

# On ghost-free massive gravity

based on: C. Deffayet, JM, G Zahariade [arXiv:1207.6338],[arXiv:1208.4493];  
JM, D. Steer ([arXiv:1310.6560], [arXiv:1405.1862]).

J Mourad

Université Paris Diderot

*mourad@apc.univ-paris7.fr*

11 June 2014

- 1 Free massive spin 2 field
- 2 Interacting massive spin 2
- 3 ghostfree massive gravity: metric formulation
- 4 Vielbein formulation
- 5 Translation invariant solutions
  - $\beta_1$  mass term
  - $\beta_3$  mass term
- 6 Conclusion

- 1 Free massive spin 2 field
- 2 Interacting massive spin 2
- 3 ghostfree massive gravity: metric formulation
- 4 Vielbein formulation
- 5 Translation invariant solutions
  - $\beta_1$  mass term
  - $\beta_3$  mass term
- 6 Conclusion

## The massless action

The Einstein-Hilbert action for  $g_{\mu\nu} = \eta_{\mu\nu} + h_{\mu\nu}$  is

$$S_0 = \frac{1}{2} \int h_{\mu\nu} \mathcal{G}^{\mu\nu}, \quad (1)$$

with

$$\begin{aligned} \mathcal{G}^{\mu\nu} &= \mathcal{R}^{\mu\nu} - \frac{1}{2} \eta^{\mu\nu} \mathcal{R}^\alpha{}_\alpha, \\ \mathcal{R}^{\mu\nu} &= \square h^{\mu\nu} - \partial^{(\mu} \partial_\alpha h^{\nu)\alpha} + \partial^\mu \partial^\nu h^\alpha{}_\alpha. \end{aligned} \quad (2)$$

The gauge symmetry  $\delta h_{\mu\nu} = \partial_{(\mu} \xi_{\nu)}$  is guaranteed by the Bianchi identity  $\partial_\mu \mathcal{G}^{\mu\nu} = 0$  and removes  $2 \times D$  dof from from the  $D(D+1)/2$  components leaving  $(D-2)(D-1)/2 - 1$  dof.

## The massive action

Addition of the most general mass term

$$S_1 = -\frac{m^2}{2} \int \left( h_{\mu\nu} h^{\mu\nu} - a (h^\alpha{}_\alpha)^2 \right) \quad (3)$$

## The massive action

Addition of the most general mass term

$$S_1 = -\frac{m^2}{2} \int \left( h_{\mu\nu} h^{\mu\nu} - a(h^\alpha{}_\alpha)^2 \right) \quad (3)$$

gives the exchange amplitude

$$T \cdot \Delta \cdot T = \frac{T \cdot T - \frac{1}{D-1}(T')^2}{\square - m^2} - \frac{(T')^2}{(D-1) \left( \square - \frac{m^2(1-aD)}{(D-2)(a-1)} \right)}, \quad (4)$$

with  $T' = T^\alpha{}_\alpha$ .

## The massive action

Addition of the most general mass term

$$S_1 = -\frac{m^2}{2} \int \left( h_{\mu\nu} h^{\mu\nu} - a(h^\alpha{}_\alpha)^2 \right) \quad (3)$$

gives the exchange amplitude

$$T.\Delta.T = \frac{T.T - \frac{1}{D-1}(T')^2}{\square - m^2} - \frac{(T')^2}{(D-1) \left( \square - \frac{m^2(1-aD)}{(D-2)(a-1)} \right)}, \quad (4)$$

with  $T' = T^\alpha{}_\alpha$ .

so the action describes a massive **spin 2 field** and a massive **scalar ghost**.

## The Fierz-Pauli action

is obtained by setting  $a = 1$ .



## The Fierz-Pauli action

is obtained by setting  $a = 1$ .

what is special about the FP action ?

## The Fierz-Pauli action

is obtained by setting  $a = 1$ .

## what is special about the FP action ?

The equations of motion

$$\mathcal{G}_{\mu\nu} = m^2(h_{\mu\nu} - a\eta_{\mu\nu}h'). \quad (5)$$

- and the Bianchi identity give

$$\partial^\mu h_{\mu\nu} - a\partial_\nu h' = 0, \quad (6)$$

## The Fierz-Pauli action

is obtained by setting  $a = 1$ .

## what is special about the FP action ?

The equations of motion

$$\mathcal{G}_{\mu\nu} = m^2(h_{\mu\nu} - a\eta_{\mu\nu}h'). \quad (5)$$

- and the Bianchi identity give

$$\partial^\mu h_{\mu\nu} - a\partial_\nu h' = 0, \quad (6)$$

This removes a vectorial dof.

- the trace of the equation

$$\frac{2-D}{2}\mathcal{R} = m^2(1-aD)h', \quad (7)$$

- Using the vectorial constraint in  $\mathcal{R} = 2(\square h' - \partial^\mu \partial^\nu h_{\mu\nu})$  gives

$$\mathcal{R} = 2(1-a)\square h' \quad (8)$$

- the trace of the equation

$$\frac{2-D}{2}\mathcal{R} = m^2(1-aD)h', \quad (7)$$

- Using the vectorial constraint in  $\mathcal{R} = 2(\square h' - \partial^\mu \partial^\nu h_{\mu\nu})$  gives

$$\mathcal{R} = 2(1-a)\square h' \quad (8)$$

so the trace becomes

$$(2-D)(1-a)\square h' - m^2(1-aD)h' = 0. \quad (9)$$

- the trace of the equation

$$\frac{2-D}{2}\mathcal{R} = m^2(1-aD)h', \quad (7)$$

- Using the vectorial constraint in  $\mathcal{R} = 2(\square h' - \partial^\mu \partial^\nu h_{\mu\nu})$  gives

$$\mathcal{R} = 2(1-a)\square h' \quad (8)$$

so the trace becomes

$$(2-D)(1-a)\square h' - m^2(1-aD)h' = 0. \quad (9)$$

So only for  $a = 1$  we have  $\mathcal{R} = 0$  and consequently  $h' = 0$ .

# Outline

- 1 Free massive spin 2 field
- 2 Interacting massive spin 2
- 3 ghostfree massive gravity: metric formulation
- 4 Vielbein formulation
- 5 Translation invariant solutions
  - $\beta_1$  mass term
  - $\beta_3$  mass term
- 6 Conclusion

# Interacting massive spin 2 field

Fierz-Pauli theory can be non linearly completed by considering actions

$$S_{g,m} = M_g^2 \int d^4x \sqrt{-g} [R(g) - m^2 V(\mathcal{M})], \quad (10)$$

- $V$  is a scalar function of  $\mathcal{M}^\mu{}_\nu = g^{\mu\sigma} f_{\sigma\nu}$ ,
- the theory contains, besides the dynamical metric  $g_{\mu\nu}$ , a non dynamical metric  $f_{\mu\nu}$  usually considered to be flat.



# Interacting massive spin 2 field

Fierz-Pauli theory can be non linearly completed by considering actions

$$S_{g,m} = M_g^2 \int d^4x \sqrt{-g} [R(g) - m^2 V(\mathcal{M})], \quad (10)$$

- $V$  is a scalar function of  $\mathcal{M}^\mu{}_\nu = g^{\mu\sigma} f_{\sigma\nu}$ ,
- the theory contains, besides the dynamical metric  $g_{\mu\nu}$ , a non dynamical metric  $f_{\mu\nu}$  usually considered to be flat.
- $V$  should be chosen such that
  - (i) when  $f_{\mu\nu}$  is taken to be  $\eta_{\mu\nu}$ ,  $g_{\mu\nu} = \eta_{\mu\nu}$  is a solution of the field equations,
  - (ii) when expanded at quadratic order around this flat background, the action (10) has the Fierz-Pauli form .

There are infinitely many functions  $V$  that satisfy these requirements.

the equations of motion

$$G_{\mu\nu}(g) = T_{\mu\nu}(g, f), \quad (11)$$

the equations of motion

$$G_{\mu\nu}(g) = T_{\mu\nu}(g, f), \quad (11)$$

give the vectorial constraint

$$\nabla^\mu T_{\mu\nu}(g, f) = 0 \quad (12)$$

It removes a vectorial dof,

the equations of motion

$$G_{\mu\nu}(g) = T_{\mu\nu}(g, f), \quad (11)$$

give the vectorial constraint

$$\nabla^\mu T_{\mu\nu}(g, f) = 0 \quad (12)$$

It removes a vectorial dof, the scalar is not removed (Boulware-Deser ghost).

the equations of motion

$$G_{\mu\nu}(g) = T_{\mu\nu}(g, f), \quad (11)$$

give the vectorial constraint

$$\nabla^\mu T_{\mu\nu}(g, f) = 0 \quad (12)$$

It removes a vectorial dof, the scalar is not removed (Boulware-Deser ghost).

until the work of de Rham, Gabadadze and Tolley (dRGT) (2010)

# Outline

- 1 Free massive spin 2 field
- 2 Interacting massive spin 2
- 3 ghostfree massive gravity: metric formulation
- 4 Vielbein formulation
- 5 Translation invariant solutions
  - $\beta_1$  mass term
  - $\beta_3$  mass term
- 6 Conclusion

For a matrix  $X$  define  $F_k$  as

$$F_k(X) = \frac{1}{k!} X^{a_1}_{[a_1} \dots X^{a_k}_{a_k]}, \quad (13)$$

For a matrix  $X$  define  $F_k$  as

$$F_k(X) = \frac{1}{k!} X^{a_1}_{[a_1} \dots X^{a_k}_{a_k]}, \quad (13)$$

The dRGT action

$$S = M_P^2 \int d^4x \sqrt{-g} \left[ R - m^2 \sum_{k=0}^{k=4} \beta_k F_k \left( \sqrt{g^{-1}f} \right) \right]. \quad (14)$$



For a matrix  $X$  define  $F_k$  as

$$F_k(X) = \frac{1}{k!} X^{a_1}{}_{[a_1} \dots X^{a_k}{}_{a_k]}, \quad (13)$$

## The dRGT action

$$S = M_P^2 \int d^4x \sqrt{-g} \left[ R - m^2 \sum_{k=0}^{k=4} \beta_k F_k \left( \sqrt{g^{-1}f} \right) \right]. \quad (14)$$

- The mass term depends on the matrix square root  $\gamma$

$$\gamma^\mu{}_\sigma \gamma^\sigma{}_\nu = g^{\mu\sigma} f_{\sigma\nu}, \quad (15)$$

- proved to be ghostfree in the decoupling limit.

- 1 Free massive spin 2 field
- 2 Interacting massive spin 2
- 3 ghostfree massive gravity: metric formulation
- 4 Vielbein formulation**
- 5 Translation invariant solutions
  - $\beta_1$  mass term
  - $\beta_3$  mass term
- 6 Conclusion

# Ghostfree massive gravity- The moving frame formulation

In terms of dynamical one-forms  $\theta^A$  and non-dynamical  $\ell^A$ , the dRGT action reads

$$S[\theta^A] = \frac{1}{2} \int \Omega^{AB} \wedge \theta_{AB}^* + \sum_{n=0}^{D-1} \beta_n \int \ell^{A_1} \wedge \dots \wedge \ell^{A_n} \wedge \theta_{A_1 \dots A_n}^*, \quad (16)$$

where

$$\theta_{A_1 \dots A_n}^* \equiv \frac{1}{(D-n)!} \epsilon_{A_1 \dots A_D} \theta^{A_{n+1}} \wedge \dots \wedge \theta^{A_D} \quad (17)$$

Hinterbichler and Rosen (2012), Deffayet, JM, Zahariade (2013)

# Ghostfree massive gravity- The moving frame formulation

In terms of dynamical one-forms  $\theta^A$  and non-dynamical  $\ell^A$ , the dRGT action reads

$$S[\theta^A] = \frac{1}{2} \int \Omega^{AB} \wedge \theta_{AB}^* + \sum_{n=0}^{D-1} \beta_n \int \ell^{A_1} \wedge \dots \wedge \ell^{A_n} \wedge \theta_{A_1 \dots A_n}^*, \quad (16)$$

where

$$\theta_{A_1 \dots A_n}^* \equiv \frac{1}{(D-n)!} \epsilon_{A_1 \dots A_D} \theta^{A_{n+1}} \wedge \dots \wedge \theta^{A_D} \quad (17)$$

Hinterbichler and Rosen (2012), Deffayet, JM, Zahariade (2013)

The two actions coincide if

$$e^{A\mu} \ell^B_{\mu} - e^{B\mu} \ell^A_{\mu} = 0 \quad (18)$$

and we set

$$\gamma^{\mu}_{\nu} = e_A^{\mu} \ell^A_{\nu} \quad (19)$$

# Ghostfree massive gravity- The moving frame formulation

The equations of motion

$$G_A = t_A , \quad (20)$$

or equivalently  $G_{AB} = t_{AB}$ , with

$$t_A \equiv \sum_{n=0}^{D-1} \beta_n \ell^{A_1} \wedge \dots \wedge \ell^{A_n} \wedge \theta_{AA_1 \dots A_n}^* \equiv t_A{}^B \theta_B^* \quad (21)$$

# Ghostfree massive gravity- The moving frame formulation

The equations of motion

$$G_A = t_A , \quad (20)$$

or equivalently  $G_{AB} = t_{AB}$ , with

$$t_A \equiv \sum_{n=0}^{D-1} \beta_n \ell^{A_1} \wedge \dots \wedge \ell^{A_n} \wedge \theta_{AA_1 \dots A_n}^* \equiv t_A{}^B \theta_B^* \quad (21)$$

- diffeomorphism invariance of the Einstein-Hilbert term implies the Bianchi identity

$$\mathcal{D}G_A = 0 = \mathcal{D}t_A \quad (22)$$

# Ghostfree massive gravity- The moving frame formulation

The equations of motion

$$G_A = t_A , \quad (20)$$

or equivalently  $G_{AB} = t_{AB}$ , with

$$t_A \equiv \sum_{n=0}^{D-1} \beta_n \ell^{A_1} \wedge \dots \wedge \ell^{A_n} \wedge \theta_{AA_1 \dots A_n}^* \equiv t_A{}^B \theta_B^* \quad (21)$$

- diffeomorphism invariance of the Einstein-Hilbert term implies the Bianchi identity

$$\mathcal{D}G_A = 0 = \mathcal{D}t_A \quad (22)$$

- Lorentz invariance imposes

$$G_{[AB]} = 0 = t_{[AB]} . \quad (23)$$

- In many (but not all cases), this gives  $e^{A\mu} \ell^B{}_\mu - e^{B\mu} \ell^A{}_\mu = 0$

## The scalar constraint ?

a "trace" of the equations of motion

$$m^A G_A = m^A t_A, \quad (24)$$

gives a scalar constraint if  $m^A G_A$  has no second order derivatives.



## The scalar constraint ?

a "trace" of the equations of motion

$$m^A G_A = m^A t_A, \quad (24)$$

gives a scalar constraint if  $m^A G_A$  has no second order derivatives.

This is the case for  $\beta_1$  and  $\beta_2$

## The scalar constraint ?

a "trace" of the equations of motion

$$m^A G_A = m^A t_A, \quad (24)$$

gives a scalar constraint if  $m^A G_A$  has no second order derivatives.

This is the case for  $\beta_1$  and  $\beta_2$

$$G_A = d\sigma_A + \tau_A, \quad \sigma_A = -\frac{1}{2}\omega^{BC}\theta_{ABC}^* \quad (25)$$

$$\tau_A = \frac{1}{2}\omega^B{}_{[A}\omega^{CD}\theta_{C]BD}^*. \quad (26)$$

the vectorial constraint  $\mathcal{D}t_A = 0$  implies  $\theta^A\sigma_A = 0$  and  $\ell^A\sigma_A = 0$ .

C. Deffayet, G. Zahariade, JM (2013)

# Outline

- 1 Free massive spin 2 field
- 2 Interacting massive spin 2
- 3 ghostfree massive gravity: metric formulation
- 4 Vielbein formulation
- 5 Translation invariant solutions**
  - $\beta_1$  mass term
  - $\beta_3$  mass term
- 6 Conclusion

## translation invariant solutions

In the linear FP theory, they are the Plane waves in the rest frame.

They capture the degrees of freedom.

A simplified hamiltonian framework, with exact (or numerical) solutions.

## translation invariant solutions

In the linear FP theory, they are the Plane waves in the rest frame.

They capture the degrees of freedom.

A simplified hamiltonian framework, with exact (or numerical) solutions.

They also generalise the Bianchi I solutions of GR.

# translation invariant solutions

In the linear FP theory, they are the Plane waves in the rest frame.

They capture the degrees of freedom.

A simplified hamiltonian framework, with exact (or numerical) solutions.

They also generalise the Bianchi I solutions of GR.

$$e_{00} = -N, \quad e_{0i} = -Nn_i, \quad e_{ij} = \pi_{ij} - Nn_in_j, \quad (27)$$

and

$$\theta^{00} = -\left(\frac{1}{N} - \zeta^{ij}n_in_j\right), \quad \theta^{0i} = -\zeta^{ij}n_j, \quad \theta^{ij} = \zeta^{ij}. \quad (28)$$

the  $D(D+1)/2$  variables all depend on  $t$ ,  $\zeta = \pi^{-1}$ .

$$ds^2 = -\frac{1}{N^2} dt^2 + (\zeta^2)_{ij} dx^i dx^j \equiv -dT^2 + (B^{-1})_{ij} dx^i dx^j$$

## Bianchi

$$C_1 \equiv \text{tr}(\dot{B}B^{-1}) = 0 \quad (29)$$

## Hamiltonian

$$n_i = 0, \quad C_2 \equiv -\text{tr}(\dot{B}B^{-1})^2 + 8m^2 \text{tr}(1 - \pi) = 0. \quad (30)$$

## Equations of motion

$$-\partial_T(\dot{B}B^{-1}) = 2m^2 [\pi + 2\text{tr}(1 - \pi) - N] \quad (31)$$

## The lapse

The trace of the equations

$$N = 1 - \frac{2D - 3}{D - 1} \text{tr}(\pi - 1). \quad (32)$$



## The lapse

The trace of the equations

$$N = 1 - \frac{2D - 3}{D - 1} \text{tr}(\pi - 1). \quad (32)$$

## Linearised limit $\pi = 1 + h$

$$\text{tr}(\dot{h}) = 0, \quad \text{tr}(h) = 0, \quad N = 1. \quad (33)$$

$$\ddot{h} + m^2 h = 0. \quad (34)$$

## The lapse

The trace of the equations

$$N = 1 - \frac{2D - 3}{D - 1} \text{tr}(\pi - 1). \quad (32)$$

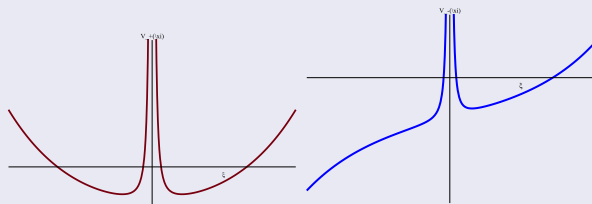
## Linearised limit $\pi = 1 + h$

$$\text{tr}(\dot{h}) = 0, \quad \text{tr}(h) = 0, \quad N = 1. \quad (33)$$

$$\ddot{h} + m^2 h = 0. \quad (34)$$

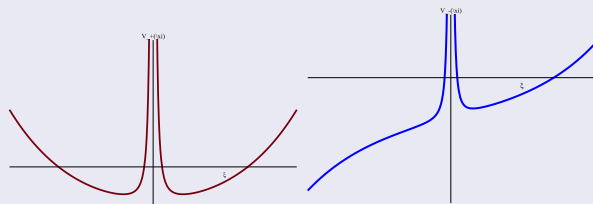
- well posed initial value problem and  $N \geq 0$ .
- sectors of solutions depending on signature of  $\pi$ , negative implies effective potential unbounded from below.

## effective potential in 3D for positive and negative determinant

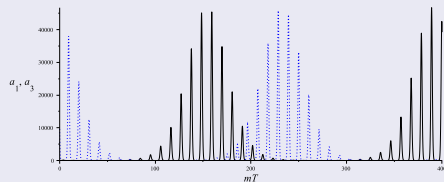


# $\beta_1$ mass term

## effective potential in 3D for positive and negative determinant



## numerical solution in the 4D diagonal case



## Bianchi

$$C_1 \equiv \text{tr} \dot{\zeta} = 0. \quad (35)$$

## Hamiltonian

$$n_i = 0, \quad C_2 \equiv \left( \text{tr}(\dot{B}B^{-1}) \right)^2 - \text{tr} \left( (\dot{B}B^{-1})^2 \right) + 8m^2(1 - \det \pi) = 0. \quad (36)$$

## Equations of motion

$$\begin{aligned}
 & -\partial_T(\dot{B}B^{-1}) + \partial_T \text{tr}(\dot{B}B^{-1}) + \frac{1}{2}(\dot{B}B^{-1})\text{tr}(\dot{B}B^{-1}) \\
 & - \frac{1}{4} \left[ \left( \text{tr}(\dot{B}B^{-1}) \right)^2 + \text{tr} \left( (\dot{B}B^{-1})^2 \right) \right] = -2m^2 [\zeta(N \det \pi) - 1], \quad (37)
 \end{aligned}$$

### The lapse

- is not obtained from the trace of the eom.
- From the eom get  $\ddot{\zeta}$  then use  $\text{tr}\dot{\zeta} = 0$  to obtain  $N$ .

## The lapse

- is not obtained from the trace of the eom.
- From the eom get  $\ddot{\zeta}$  then use  $\text{tr}\dot{\zeta} = 0$  to obtain  $N$ .

For  $\pi = \text{diag}(e^\delta, \dots, e^\delta, e^\Delta)$

$$c = \text{tr}\zeta = (D - 2)e^{-\delta} + e^{-\Delta}. \quad (38)$$

$$N = \frac{c e^{-(D-2)\delta} [(D - 3)e^{(D-2)\delta} - 2c(D - 3) + 2(D - 2)^2 e^{-\delta}]}{(e^{-\delta} - e^{-\delta_*})^2 (D - 2)^2 (D - 1)^2}. \quad (39)$$

with

$$e^{-\delta_*} = \frac{c(D - 3)}{(D - 2)(D - 1)}. \quad (40)$$

## The lapse

- is not obtained from the trace of the eom.
- From the eom get  $\ddot{\zeta}$  then use  $\text{tr}\dot{\zeta} = 0$  to obtain  $N$ .

For  $\pi = \text{diag}(e^\delta, \dots, e^\delta, e^\Delta)$

$$c = \text{tr}\zeta = (D-2)e^{-\delta} + e^{-\Delta}. \quad (38)$$

$$N = \frac{c e^{-(D-2)\delta} [(D-3)e^{(D-2)\delta} - 2c(D-3) + 2(D-2)^2 e^{-\delta}]}{(e^{-\delta} - e^{-\delta_*})^2 (D-2)^2 (D-1)^2}. \quad (39)$$

with

$$e^{-\delta_*} = \frac{c(D-3)}{(D-2)(D-1)}. \quad (40)$$

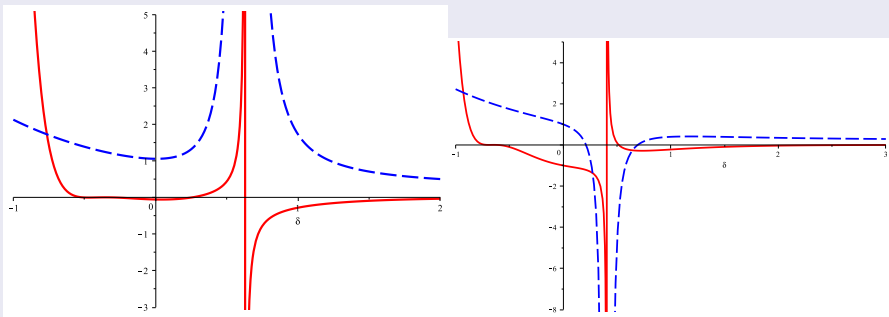
If  $c > c_{\text{crit}}$  with

$$c_{\text{crit}} = \frac{D-1}{2^{1/(D-1)}} \left( \frac{D-2}{D-3} \right)^{\frac{D-2}{D-1}} \quad (41)$$

$N$  changes sign and the evolution is singular at a finite time.



## $V$ and $N$



The potential  $V(\delta)$  (red, solid lines) and  $N(\delta)$  (blue dashed lines) in  $D = 4$  dimensions for which  $c_{\text{crit}} \simeq 3.78$ . LH panel:  $c = 3.3 < c_{\text{crit}}$ ; RH panel  $c = 4 > c_{\text{crit}}$ .

# Outline

- 1 Free massive spin 2 field
- 2 Interacting massive spin 2
- 3 ghostfree massive gravity: metric formulation
- 4 Vielbein formulation
- 5 Translation invariant solutions
  - $\beta_1$  mass term
  - $\beta_3$  mass term
- 6 Conclusion

- Ghostfree massive gravity in the moving frame formulation :
  - no square roots
  - Constraints easy to obtain ( $\beta_1$  and  $\beta_2$ ).
- Classical instabilities in some sectors of the solutions  $\beta_1$
- Singular time evolution for  $\beta_3$
- More tests for  $\beta_1$ .