

# Higher Spin 6-Vertex Model and Macdonald Polynomials

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Joint work with Ferenc Balogh

# Outline

## 1 6-Vertex Model

- Definition
- Integrability
- Combinatorial point

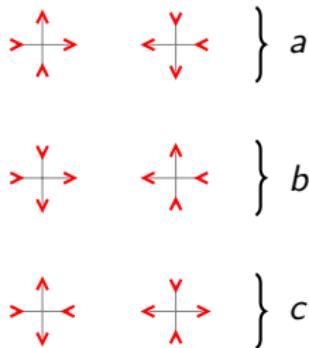
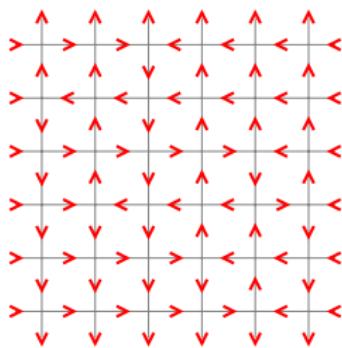
## 2 Higher Spin Generalization

- Definition and Integrability
- Partition Function

## 3 Macdonald Polynomial

- Wheel Condition
- Macdonald polynomials
- Main Result

# Definition of the 6-Vertex model

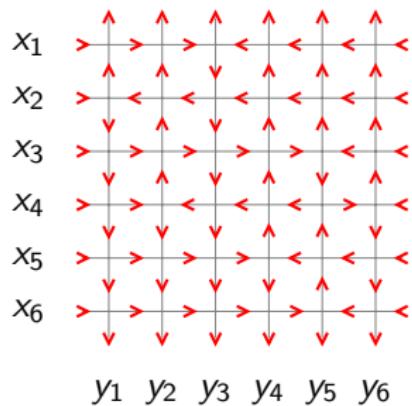


## Definition (Partition function)

The partition function is defined as usual:

$$\mathcal{Z}_n \propto \sum_{\text{configurations}} \prod_{i,j} \omega_{i,j}$$

# Definition of the 6-Vertex model



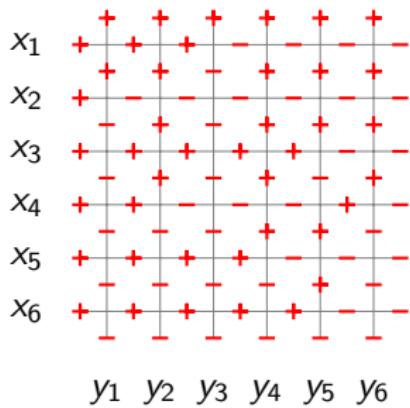
$$\left. \begin{array}{c} \text{ } \\ \text{ } \end{array} \right\} a = qx - q^{-1}y$$
$$\left. \begin{array}{c} \text{ } \\ \text{ } \end{array} \right\} b = x - y$$
$$\left. \begin{array}{c} \text{ } \\ \text{ } \end{array} \right\} c = (q - q^{-1})\sqrt{xy}$$

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$$\mathcal{Z}_n(\mathbf{x}, \mathbf{y}) \propto \sum_{\text{configurations}} \prod_{i,j} \omega_{i,j}(x_i, y_j)$$

# Definition of the 6-Vertex model



$$\left. \begin{array}{cc} + & - \\ + & - \\ + & - \end{array} \right\} a = qx - q^{-1}y$$
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# Definition of the 6-Vertex model

1	0	0	1	0	0	0
1	1	0	0	0	0	0
1	0	0	0	0	1	0
1	0	1	0	0	-1	1
1	0	0	0	1	0	0
1	0	0	0	0	1	0

$q \quad q \quad q \quad q \quad q \quad q$

$\begin{matrix} + \\ 0 \\ - \end{matrix}$

$\begin{matrix} - \\ 0 \\ + \end{matrix}$

$\left. \begin{array}{l} \\ \\ \end{array} \right\} a = q - 1$

$\begin{matrix} - \\ 0 \\ + \end{matrix}$

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$\left. \begin{array}{l} \\ \\ \end{array} \right\} b = q - 1$

$\begin{matrix} + \\ 1 \\ - \end{matrix}$

$\begin{matrix} - \\ 1 \\ + \end{matrix}$

$\left. \begin{array}{l} \\ \\ \end{array} \right\} c = q - 1$

## Definition (Partition function)

We can use it to count Alternating Sign Matrices (at  $q^3 = 1$ ):

$$\mathcal{Z}_n(\mathbf{1}, \mathbf{q}) = \#\{\text{ASM of size } n \times n\} = 1, 2, 7, 42, 429, \dots$$

# The $\check{R}$ matrix

We can build a configuration using boxes:

$$x \begin{array}{c} \uparrow \\ \square \\ \downarrow \\ y \end{array} = \begin{pmatrix} a & 0 & 0 & 0 \\ 0 & c & b & 0 \\ 0 & b & c & 0 \\ 0 & 0 & 0 & a \end{pmatrix} =: \check{R}(x, y)$$

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Then

$$\check{R}(x, y) : V_1 \otimes V_2 \rightarrow V_2 \otimes V_1$$

where  $V_i$  is the spin  $\frac{1}{2}$  representation of  $U_q(sl_2)$ .

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## Example

$$\check{R}(x, y) |+\textcolor{blue}{-}\rangle = c(x, y) |+\textcolor{red}{-}\rangle + b(x, y) |-\textcolor{blue}{+}\rangle$$

# Yang–Baxter equation

Identity equation:

$$\check{R}(x, y)\check{R}(y, x) = (qx - q^{-1}y)(qy - q^{-1}x)Id.$$

Yang–Baxter equation:

$$\check{R}_{2,3}(y_2, y_3)\check{R}_{1,3}(y_1, y_3)\check{R}_{1,2}(y_1, y_2) = \check{R}_{1,2}(y_1, y_2)\check{R}_{1,3}(y_1, y_3)\check{R}_{2,3}(y_2, y_3)$$

# Yang–Baxter equation

Identity equation:

$$\text{Diagram: } \begin{array}{c} \text{red} \\ \diagup \quad \diagdown \\ \text{blue} \end{array} = (qx - q^{-1}y)(qy - q^{-1}x) \begin{array}{c} \text{red} \quad \text{blue} \\ \diagup \quad \diagdown \\ \text{blue} \quad \text{red} \end{array}$$

Yang–Baxter equation:

$$\text{Diagram: } \begin{array}{c} \text{red} \quad \text{green} \\ \diagup \quad \diagdown \\ \text{green} \quad \text{red} \end{array} = \begin{array}{c} \text{green} \\ \diagup \quad \diagdown \\ \text{red} \end{array}$$

# Yang–Baxter equation

Identity equation:

$$\text{Diagram: } \begin{array}{c} \text{red curve} \\ \text{blue curve} \end{array} = (qx - q^{-1}y)(qy - q^{-1}x) \begin{array}{c} \text{red arrow} \\ \text{blue arrow} \end{array}$$

Yang–Baxter equation:

$$\text{Diagram: } \begin{array}{c} \text{red curve} \\ \text{green curve} \end{array} = \begin{array}{c} \text{green curve} \\ \text{red curve} \end{array}$$

## Example

$$\text{Diagram: } \begin{array}{c} \text{red curve} \\ \text{green curve} \end{array} = \begin{array}{c} \text{green curve} \\ \text{red curve} \end{array}$$

# Yang–Baxter equation

Identity equation:

$$\text{Diagram showing two crossing lines (red and blue) with arrows, followed by an equals sign and another diagram showing the same crossing with arrows reversed.}$$

Yang–Baxter equation:

$$\text{Diagram showing two crossing lines (red and green) with arrows, followed by an equals sign and another diagram showing the same crossing with arrows swapped.}$$

## Example

$$\begin{array}{ccc} \text{Diagram with two '+' signs above a crossing of red and green lines, and '-' below the vertical axis.} & = & \text{Diagram with two '+' signs above a crossing of green and red lines, and '-' below the vertical axis.} \end{array}$$

# Yang–Baxter equation

Identity equation:

$$\text{Diagram showing two crossing lines (red and blue) with arrows, followed by an equals sign and a product of two terms: } (qx - q^{-1}y)(qy - q^{-1}x).$$

Yang–Baxter equation:

$$\text{Diagram showing two crossing lines (red and green) with arrows, followed by an equals sign and a product of two terms: } (qx - q^{-1}y)(qy - q^{-1}x).$$

## Example

$$\begin{array}{ccc} \text{Diagram showing two crossing lines (red and green) with arrows, followed by an equals sign and a product of two terms: } & = & \text{Diagram showing two crossing lines (red and green) with arrows, followed by an equals sign and a product of two terms: } \\ \begin{array}{c} + \\ | \\ + \end{array} & & \begin{array}{c} + \\ | \\ + \end{array} \\ \begin{array}{c} + \\ | \\ - \end{array} & & \begin{array}{c} + \\ | \\ - \end{array} \end{array}$$

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Yang–Baxter equation:

$$\text{Diagram showing two crossing lines (red and green) with arrows, followed by an equals sign and a product of two terms: } (qx - q^{-1}y)(qy - q^{-1}x).$$

## Example

$$\begin{array}{c} + & + \\ \diagdown & \diagup \\ + & + \\ \diagup & \diagdown \\ + & - \end{array} = \begin{array}{c} + & + \\ \diagup & \diagdown \\ + & + \\ \diagdown & \diagup \\ - & - \end{array}$$

# Yang–Baxter equation

Identity equation:

$$\text{Diagram showing two crossing lines (red and blue) with arrows, followed by an equals sign and a product of two terms: } (qx - q^{-1}y)(qy - q^{-1}x).$$

Yang–Baxter equation:

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## Example

$$\begin{array}{c} + & & + \\ & \diagdown & \diagup \\ + & & + \\ & \diagup & \diagdown \\ + & & - \end{array} = \begin{array}{c} + & & + \\ & \diagup & \diagdown \\ + & & + \\ & \diagdown & \diagup \\ - & & - \end{array}$$

# Yang–Baxter equation

Identity equation:

$$\text{Diagram showing two crossing red arrows} = (qx - q^{-1}y)(qy - q^{-1}x) \text{ Diagram showing two crossing blue arrows}$$

Yang–Baxter equation:

$$\text{Diagram showing two crossing red and green arrows} = \text{Diagram showing two crossing green and red arrows}$$

## Example

$$\begin{array}{c} + & & + \\ & \diagdown \text{red} & \diagup \text{green} \\ + & + & + \\ & \diagup \text{green} & \diagdown \text{red} \\ + & & - \\ & \diagup \text{blue} & \diagdown \text{blue} \\ - & & \end{array} = \begin{array}{c} + & & + \\ & \diagup \text{green} & \diagdown \text{red} \\ + & + & + \\ & \diagup \text{red} & \diagdown \text{green} \\ + & & - \\ & \diagup \text{blue} & \diagdown \text{blue} \\ - & & \end{array}$$

# Yang–Baxter equation

Identity equation:

$$\text{Diagram showing two crossing lines (red and blue) with arrows, followed by an equals sign and the expression } (qx - q^{-1}y)(qy - q^{-1}x) \text{ with two arrows pointing right.}$$

Yang–Baxter equation:

$$\text{Diagram showing two crossing lines (red and green) with arrows, followed by an equals sign and the expression } (qx - q^{-1}y)(qy - q^{-1}x) \text{ with two arrows pointing right.}$$

## Example

$$\begin{array}{c} + \\ + \end{array} \times \begin{array}{c} + \\ + \end{array} = \begin{array}{c} + \\ + \end{array} + \begin{array}{c} + \\ - \end{array}$$

Diagram illustrating the Yang-Baxter equation for a 6-vertex model. The left side shows a vertex with four edges: top-left (green, up-right), top-right (red, up-right), bottom-left (green, down-right), and bottom-right (blue, down-right). The right side shows the sum of two terms. The first term has edges: top (green, up-right), middle-left (green, up-right), middle-right (red, up-right), bottom (blue, down-right). The second term has edges: top (green, up-right), middle-left (green, up-right), middle-right (red, up-right), bottom (blue, down-right).

# Yang–Baxter equation

Identity equation:

$$\text{Diagram showing two crossing lines (red and blue) with arrows, followed by an equals sign and a product of two terms: } (qx - q^{-1}y)(qy - q^{-1}x).$$

Yang–Baxter equation:

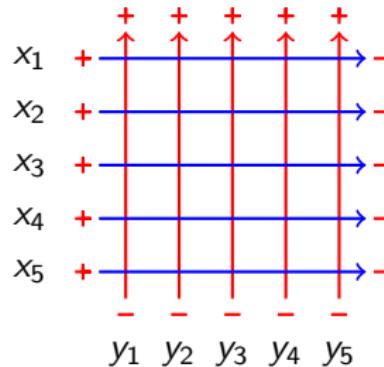
$$\text{Diagram showing two crossing lines (red and green) with arrows, followed by an equals sign and a product of two terms: } \text{Diagram with red and green lines crossing} = \text{Diagram with red and green lines crossing}.$$

## Example

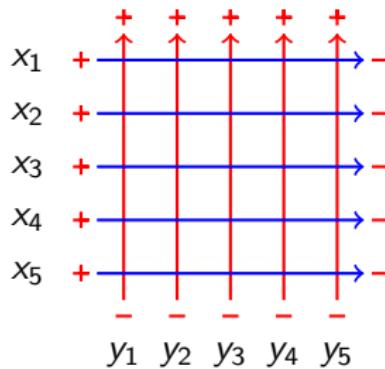
$$\begin{array}{ccc} \text{Diagram with red and green lines crossing} & = & \text{Diagram with red and green lines crossing} + \text{Diagram with red and green lines crossing} \\ \text{with signs} & & \text{with signs} \end{array}$$

$$a(x, y)a(y, z)c(x, z) = c(y, z)a(x, z)c(x, y) + b(y, z)c(x, z)b(x, y)$$

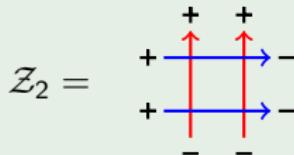
# The partition function



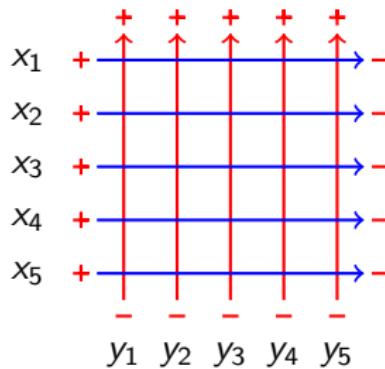
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Example ( $n = 2$ )



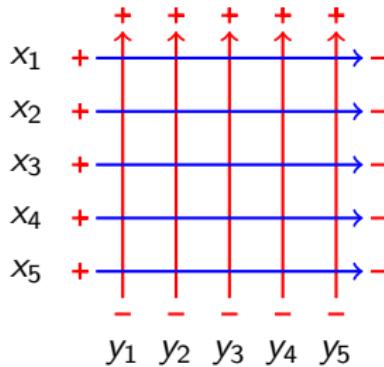
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Example ( $n = 2$ )

$$\mathcal{Z}_2 = \begin{array}{c} + \\ + \\ + \\ - \\ - \end{array} + \begin{array}{c} + \\ - \\ + \\ + \\ - \end{array}$$

# The partition function



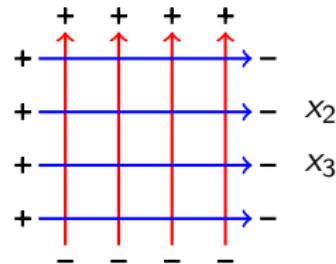
Example ( $n = 2$ )

$$\mathcal{Z}_2 = \begin{array}{c} + \\ + \\ + \\ - \\ - \end{array} + \begin{array}{c} + \\ - \\ + \\ + \\ - \end{array}$$

$$c(x_2, y_1)a(x_2, y_2)a(x_1, y_1)c(x_1, y_2) + b(x_2, y_1)c(x_2, y_2)c(x_1, y_1)b(x_1, y_2)$$

# Properties of the partition function

Symmetry in  $x$  and  $y$ . Proved using Yang–Baxter equation:



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Symmetry in  $x$  and  $y$ . Proved using Yang–Baxter equation:

$$\frac{1}{qx_2 - q^{-1}x_3}$$

The diagram illustrates the Yang-Baxter equation for the 6-vertex model. It shows four horizontal lines labeled  $x_3$  and  $x_2$ . Red vertical arrows point upwards on the left and downwards on the right. Blue horizontal arrows point right on the top and left on the bottom. A blue curve connects the second and third lines from the left, crossing them.

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The diagram illustrates the Yang-Baxter equation for the 6-vertex model. It shows four horizontal red lines labeled with '+' at the top and '-' at the bottom. A blue line labeled  $x_3$  crosses from the second line down to the third line. Another blue line labeled  $x_2$  crosses from the third line down to the second line. The crossing points are connected by a curved blue line.

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Symmetry in  $x$  and  $y$ . Proved using Yang–Baxter equation:

$$\frac{1}{qx_2 - q^{-1}x_3}$$

The diagram illustrates the Yang-Baxter equation for the 6-vertex model. It shows four horizontal lines with arrows pointing right. The top line has four '+' signs above it. The bottom line has four '-' signs below it. Between them are two red lines with '+' signs above them. The middle red line has a wavy crossing over the bottom line. To the right of the lines, there are labels  $x_3$  and  $x_2$ .

# Properties of the partition function

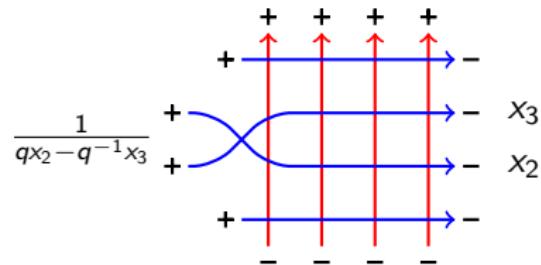
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The diagram illustrates the Yang-Baxter equation for the 6-vertex model. It shows four horizontal red lines with '+' signs at the top and '-' signs at the bottom. Two blue lines cross these: one from the left to the right labeled  $x_3$ , and another from the right to the left labeled  $x_2$ . Arrows indicate the direction of flow for each line.

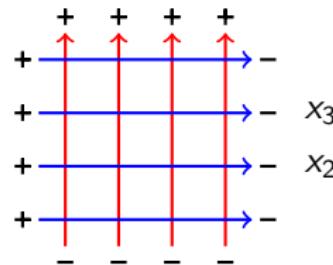
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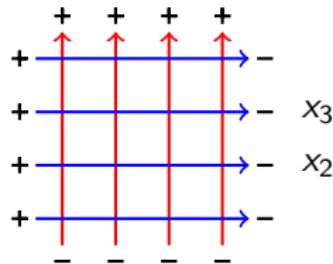
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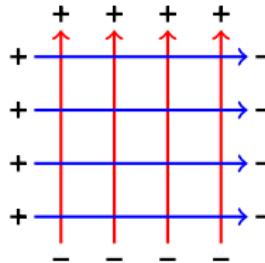


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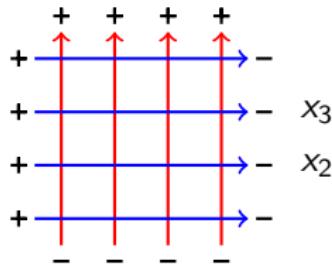


Korepin's recursion relation. At  $y_1 = q^2 x_1$ ,  $a(x_1, y_1) = 0$ , then:

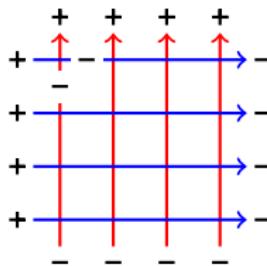


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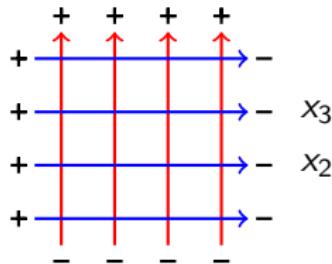


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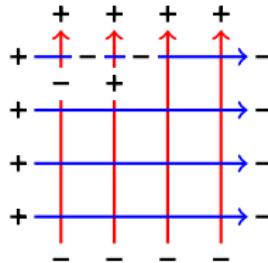


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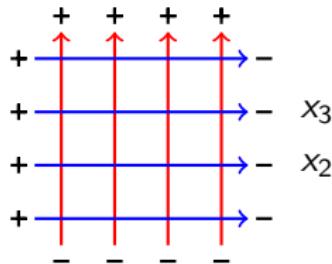


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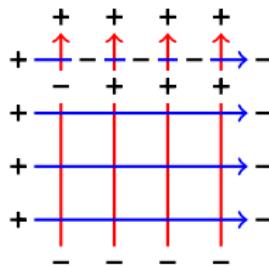


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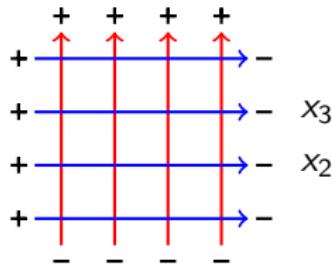


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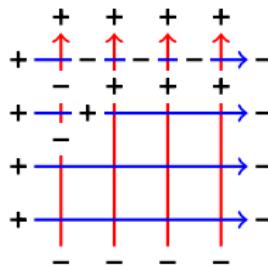


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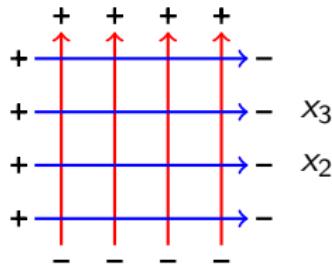


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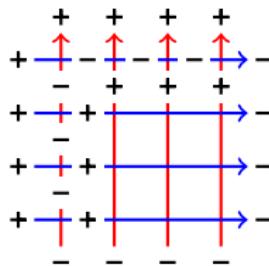


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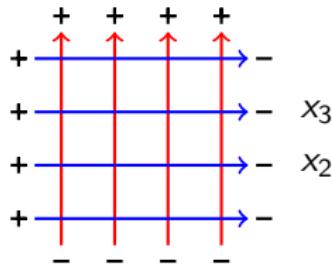


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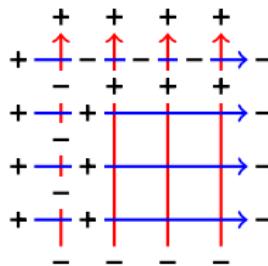


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Korepin's recursion relation. At  $y_1 = q^2 x_1$ ,  $a(x_1, y_1) = 0$ , then:



$$\mathcal{Z}_n|_{y_1=q^2x_1} \propto \prod_{i \neq 1} (y_i - x_1)(x_i - y_1)\sqrt{x_1 y_1} \mathcal{Z}_{n-1}$$

# Properties of the partition function

A weight  $c(x_i, y_j)$  appears an odd number of times at each row and column. Normalize

$$\frac{\mathcal{Z}_n(\mathbf{x}, \mathbf{y})}{\prod_i \sqrt{x_i y_i}} \rightarrow \mathcal{Z}_n(\mathbf{x}, \mathbf{y})$$

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## Properties

- *Satisfies the Korepin's recursion relation;*
- *A homogeneous polynomial;*
- *Has total degree  $n(n - 1)$ ;*
- *Has partial degree at each variable of  $n - 1$*
- *Is symmetric in  $\mathbf{x}$  and  $\mathbf{y}$ .*

# Explicit formula for the partition function

Using Korepin's recursion relation, Izergin showed that:

$$\mathcal{Z}_n(\mathbf{x}, \mathbf{y}) = (\text{Pre-factor}) \det \left| \frac{1}{(x_i - qy_j)(qx_i - y_j)} \right|_{i,j}$$

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# A Schur polynomial

Set  $q = e^{\frac{2i\pi}{3}}$ , the so-called combinatorial point.

$$Y_n = \{n-1, n-1, n-2, n-2, \dots, 1, 1, 0, 0\}$$

# A Schur polynomial

Set  $q = e^{\frac{2i\pi}{3}}$ , the so-called combinatorial point.

$$Y_4 = \begin{array}{c} \text{A Young diagram consisting of 4 rows of boxes. Row 1 has 4 boxes. Row 2 has 3 boxes. Row 3 has 2 boxes. Row 4 has 1 box. The boxes are arranged in a staircase pattern from top-left to bottom-right.} \\ | \\ \square \quad \square \quad \square \quad \square \\ \square \quad \square \quad \square \\ \square \quad \square \\ \square \end{array}$$

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It turns out that:

$$\mathcal{Z}_n(\mathbf{x}, \mathbf{y}) = S_{Y_n}(\mathbf{x}, \mathbf{y})$$

## Definition (Schur polynomial)

Let  $\lambda = \{\lambda_1, \dots, \lambda_N\}$ , then the Schur polynomial is given by:

$$S_\lambda(\mathbf{z}) = \frac{\det \left| z_i^{N+\lambda_j-j} \right|_{i,j}}{\det \left| z_i^{N-j} \right|_{i,j}}$$

# Higher Spin Generalization

We can build a higher spin version, of the model:

$$\check{R}^{(\ell)}(x, y) : V_1^{(\ell)} \otimes V_2^{(\ell)} \rightarrow V_2^{(\ell)} \otimes V_1^{(\ell)}$$

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$x_2$	$\ell$							0
$x_3$	$\ell$							0
$x_4$	$\ell$							0
$x_5$	$\ell$							0
$x_6$	$\ell$							0
	0	0	0	0	0	0	0	
	$y_1$	$y_2$	$y_3$	$y_4$	$y_5$	$y_6$		

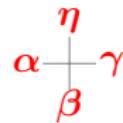
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$$\alpha + \beta = \gamma + \eta$$

# Fusion

We can get  $V^{(\ell)}$  by projecting the product  $V^{(1)} \otimes \dots \otimes V^{(1)}$ .

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$$|2\rangle = |0\rangle \otimes |1\rangle \otimes |1\rangle + |1\rangle \otimes |0\rangle \otimes |1\rangle + |1\rangle \otimes |1\rangle \otimes |0\rangle$$

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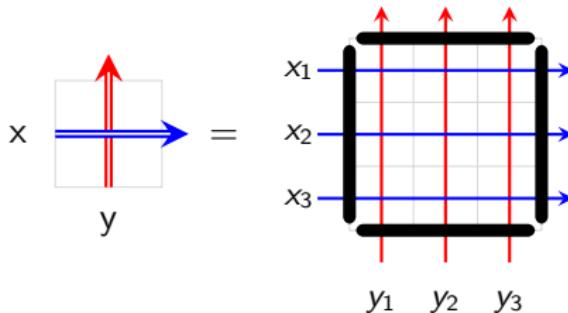
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$$\begin{array}{ccc} x & \xrightarrow{\quad \text{Diagram} \quad} & q^2 x \\ \text{Diagram: } \begin{array}{|c|} \hline \text{x} \\ \hline \text{y} \\ \hline \end{array} & = & \begin{array}{c} \text{Diagram: } \begin{array}{|c|c|c|c|} \hline & \text{x} & & \\ \hline & \text{y} & q^2 y & q^4 y \\ \hline \end{array} & =: \check{R}^{(\ell)}(x, y) \end{array} \\ & & q^4 x \end{array}$$

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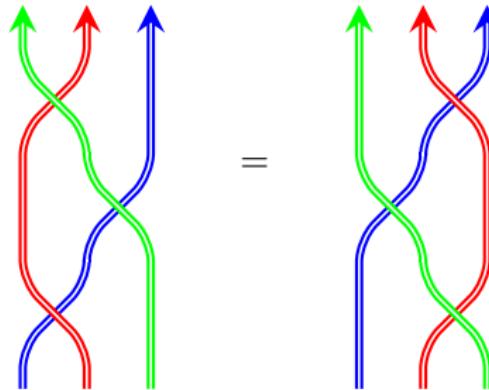
$y \quad q^2 y \quad q^4 y$

# Yang-Baxter equation

Identity equation:

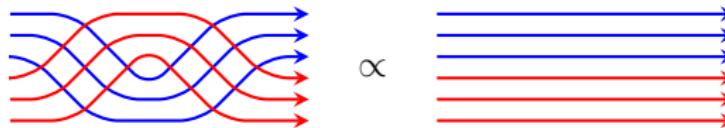


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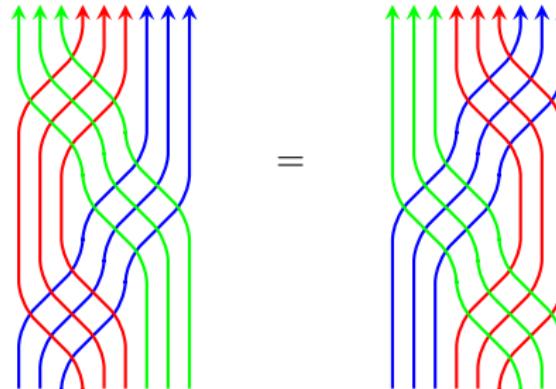


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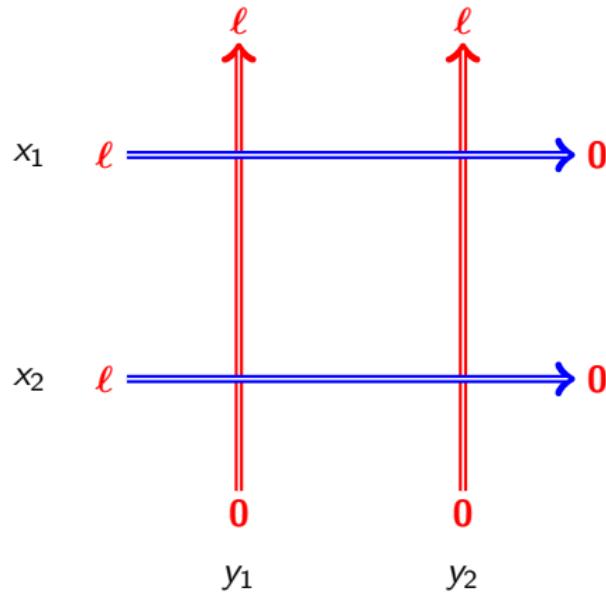


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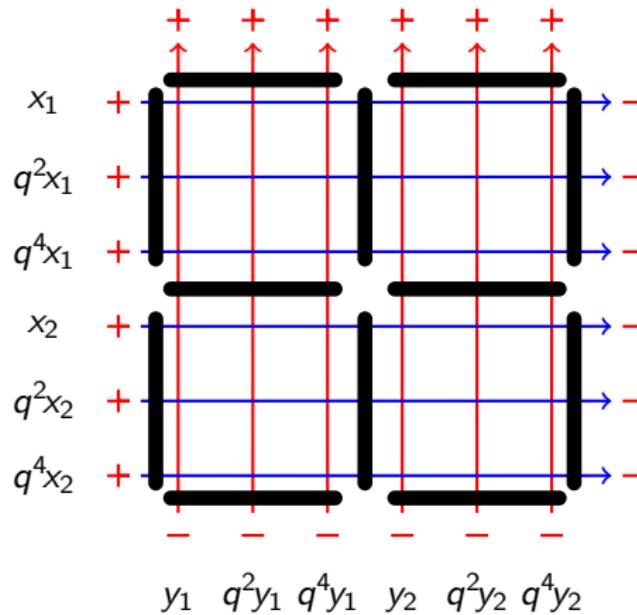
# The Partition Function

We construct the partition function in the same way:



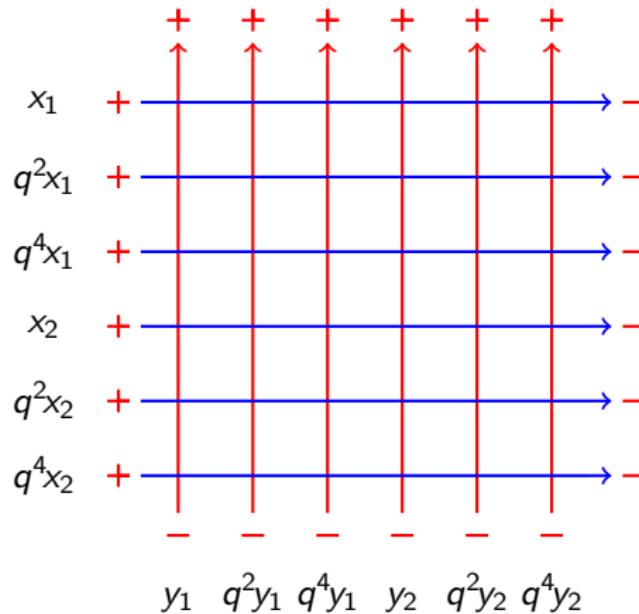
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# An Explicit Formula for the Partition Function

Let

$$\begin{aligned}\bar{\mathbf{x}} &= \{x_1, q^2 x_1, \dots, q^{2\ell-2} x_1, \dots, x_n, q^2 x_n, \dots, q^{2\ell-2} x_n\} \\ \bar{\mathbf{y}} &= \{y_1, q^2 y_1, \dots, q^{2\ell-2} y_1, \dots, y_n, q^2 y_n, \dots, q^{2\ell-2} y_n\}\end{aligned}$$

Caradoc, Foda and Kitanine showed that:

$$\mathcal{Z}_{n,\ell}(\mathbf{x}, \mathbf{y}) = (\text{Pre-factor}) \det \left| \frac{1}{(\bar{x}_i - q\bar{y}_j)(q\bar{x}_i - \bar{y}_j)} \right|_{i,j}^{\ell n \times \ell n}$$

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## Properties

- *Satisfies a weaker recursion relation;*
- *A homogeneous polynomial;*
- *Has total degree  $\ell n(n - 1)$ ;*
- *Has partial degree at each variable of  $\ell(n - 1)$ ;*
- *Is symmetric in  $\mathbf{x}$  and  $\mathbf{y}$ .*

# Wheel Condition

When  $q^{2\ell+1} = 1$ , the partition function satisfies the wheel condition:

## Definition (Wheel condition)

A polynomial  $P(\mathbf{z})$  satisfies the wheel condition if:

$$P(\mathbf{z}) = 0 \quad \text{if } z_k = q^{1+2s_2} z_j = q^{2+2s_1+2s_2} z_i$$

for all  $s_1, s_2 \in \mathbb{N}_0$  such that  $s_1 + s_2 \leq \ell - 1$  and for any choice  $i < j < k$ .

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We call this point  $q^{2\ell+1} = 1$ , the combinatorial point.

# Wheel condition - an example

## Example ( $\ell = 2$ )

Impose  $q^5 = 1$ . It means that the polynomial vanishes whenever:

$$z_k = qz_j = q^2 z_i \quad z_k = q^3 z_j = q^4 z_i \quad z_k = qz_j = q^4 z_i$$

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The following polynomial satisfies the wheel condition:

$$P(z_1, \dots, z_{2n}) = \prod_{1 \leq i < j \leq n} (qz_i - z_j)(q^3 z_i - z_j) \prod_{n < i < j \leq 2n} (qz_i - z_j)(q^3 z_i - z_j)$$

# Symmetric polynomials - different basis

Let  $\lambda = \{\lambda_1, \dots, \lambda_N\}$ , such that  $\lambda_i \geq \lambda_{i+1}$ .

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$$m_\lambda = \mathcal{S} \left( z_1^{\lambda_1} z_2^{\lambda_1} \cdots z_N^{\lambda_N} \right)$$

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$$m_{\{1,1,0\}} = z_1 z_2 + z_1 z_3 + z_2 z_3$$

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$$p_{\{1,1,0\}} = (z_1 + z_2 + z_3)^2 = z_1^2 + z_2^2 + z_3^2 + 2(z_1 z_2 + z_1 z_3 + z_2 z_3)$$

# Macdonald polynomials

Define an inner product by:

$$\langle p_\lambda(\mathbf{z}), p_\mu(\mathbf{z}) \rangle_{\tilde{q}, t} = z_\mu \delta_{\lambda\mu} \prod_i \frac{1 - \tilde{q}^{\mu_i}}{1 - t^{\mu_i}}$$

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The Macdonald polynomials are defined by the Gram–Schmidt process:

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$$P_\lambda(\mathbf{z}; \tilde{q}, t) = m_\lambda(\mathbf{z}) + \sum_{\mu \prec \lambda} c_{\lambda, \mu}(\tilde{q}, t) m_\mu(\mathbf{z})$$

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## Theorem (Jimbo, Miwa, Feigin and Mukhin)

*The symmetric polynomials obeying to the wheel condition are spanned by the Macdonald polynomials  $P_\lambda$  (with  $\tilde{q} = q^2$  and  $t = q$ ), such that:*

$$\lambda_i - \lambda_{i+2} \geq \ell$$

# The Partition Function as a Macdonald Polynomial

Fix the number of boxes to  $\ell n(n - 1)$ , then we have no choice.

$$Y_{n,\ell} = \{\ell(n - 1), \ell(n - 1), \ell(n - 2), \ell(n - 2), \dots, \ell, \ell, 0, 0\}$$

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## Theorem (Main result)

*At the combinatorial point, the partition function is the Macdonald polynomial:*

$$\mathcal{Z}_{n,\ell}(\mathbf{x}, \mathbf{y}) \propto P_{Y_{n,\ell}}(\mathbf{x}, \mathbf{y}; q^2, q)$$

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### Corollary (Symmetry)

The partition function is a fully symmetric homogeneous polynomial.

# Open questions

- The 6–Vertex model is in bijection with Alternating Sign Matrices.
  - Can this generalization lead us to nice combinatorics?
  - What about the homogeneous limit?
- Wheel conditions and determinants.
  - Can we obtain different wheel conditions, with similar methods?
  - And the same wheel condition but higher degree?
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