



# Complex scaling method for multiple particle collisions

## Introduction

#### Bound states

## • Wave function of finite size (bound to the box)

Variational method, multiple ways to discretize wave function and solve the Schrödinger eq.





#### Singularities in momentum space...

Scattering requires a much more « fine tuning » of the interactions When all bound states are OK,  $V_{NN}+V_{NNN}$  can still fail there !!! e.g. n + <sup>3</sup>H



PHYSICAL REVIEW C 70, 044002 (2004)

## Introduction

A dream: to solve scattering problem with a similar ease as bound state one (avoiding complex singularities or boundary conditions)

• Lorentz integral transform (inclusive process)

N. Barnea, V. D. Efros, W. Leidemann, and G. Orlandini, Phys. Rev. C 63, 057002 (2001)

• Complex energy method in momentum space

*E. Uzu, H. Kamada, and Y. Koike, Phys. Rev. C* **68**, 061001 (2003) *A. Deltuva and A. C. Fonseca, Phys. Rev. C* **86**, 011001(2012)

• Momentum lattice technique

O. A. Rubtsova, V. N. Pomerantsev, and V. I. Kukulin, Phys. Rev. C 79, 064602 (2009)

Continuum discretization (above break-up threshold?)

A. Kievsky, M. Viviani, and L. E. Marcucci, Phys. Rev. C 85, 014001 (2012).

Complex scaling method

B.Giraud, K.Kato and A. Ohnishi, J. of Phys. A37 (2004),11575 (passing via spectral function) Y.Suzuki, W.Horiuchi, D.Baye, PTP,123 (2010) (passing via spectral function)

<u>J. Nuttal and H. L. Cohen, Phys. Rev. 188 (1969) 1542</u>

Driven radial Schrödinger equation:  $\Psi_{i}(r) = \Psi_{i}^{in}(r) + \Psi_{i}^{sc}(r)$ 

$$\frac{\hbar^2}{2\mu} \left( -\frac{d^2}{dr^2} + \frac{l(l+1)}{r^2} + V_l(r) - k^2 \right) \Psi_l^{sc}(r) = -V_l^s(r) \Psi_l^{in}(r)$$

$$\Psi_{l}(r \rightarrow \infty) = \hat{j}_{l}(kr) + A_{l}(k)\exp(ikr - l\frac{\pi}{2})$$
  

$$\Psi_{l}(r \rightarrow \infty) = F_{l}(kr) + A_{l}(k)\exp(ikr - l\frac{\pi}{2} - \eta\ln(2kr))$$
  

$$\Psi_{l}^{in}(r) \qquad \Psi_{l}^{sc}(r \rightarrow \infty)$$

Complex scaling: 
$$r \longrightarrow re^{i\theta}$$
  

$$\frac{\hbar^2}{2\mu} \left( -\frac{d^2}{e^{2i\theta}dr^2} + \frac{l(l+1)}{e^{2i\theta}r^2} + V_l(re^{i\theta}) - k^2 \right) \widetilde{\Psi}_l^{sc}(r) = V_l^s(re^{i\theta}) \Psi_l^{in}(re^{i\theta})$$
Exp. bound by the short range pot. term  $V^s$   

$$\Psi_l^{oc}(r \longrightarrow \infty) \sim \exp(ikr) \qquad \exp(-kr\sin\theta)$$
Exp. bound if  $\theta < \pi/2$ 

$$\widetilde{H}x = b$$

Extraction of amplitudes:

- From the asymptote of the solution  $A_i(k) = \Psi_i^{\theta c}(r \to \infty) / \exp(ikre^{i\theta} + ...)$
- Using Green's theorem

 $A_{l}(k) \sim \int \Psi_{l}^{in}(re^{i\theta}) V_{l}^{s}(re^{i\theta}) (\Psi_{l}^{oc}(r) + \Psi_{l}^{in}(re^{i\theta})) e^{i\theta} dr$ 

## **Complex scaling method (Resonances)**

Analiticity of the potential, limitation of the scaling angle:

 $V(r) \sim \exp(-\mu r^n) - \exp(-\mu r^n e^{in\theta})$ 

Starts to diverge for  $\theta > \pi/(2n)$ 

M. Rittby, N. Elander and E. Brandas, Phys. Rev. A 24 (1981) 1636



Solution obtained by imposing  $\varphi(r_{max})=0$  condition at the border  $r_{max}$  of the finite grid. Using spline discretization technique.



Solution obtained by imposing  $\varphi(r_{max})=0$  condition at the border  $r_{max}$  of the finite grid. Using spline discretization technique.

![](_page_7_Figure_2.jpeg)

![](_page_8_Figure_1.jpeg)

FIG. 3: (Color online) Dependence of the calculated NN  ${}^{1}S_{0}$  phaseshift using integral expression as a function of the complex rotation angle. Grid was limited to  $r_{max}=100$  fm. The upper curve correspond Coulomb-free case, the bottom one includes Coulomb.

![](_page_8_Figure_3.jpeg)

#### Faddeev eq. (particles of identical

![](_page_9_Figure_2.jpeg)

 $\left[ (E - V_3(x_3) - \hat{H}_0)F_3 - V_3(x_3)(F_1 + F_2) = 0 \right]$ 

Driven Faddeev eq.:  $F_{1} \begin{pmatrix} \mathbf{r} & \mathbf{r} \\ x_{1}, y_{1} \end{pmatrix} = F_{1}^{in} \begin{pmatrix} \mathbf{r} & \mathbf{r} \\ x_{1}, y_{1} \end{pmatrix} + F_{1}^{sc} \begin{pmatrix} \mathbf{r} & \mathbf{r} \\ F_{1}^{sc} \begin{pmatrix} \mathbf{r} & \mathbf{r} \\ x_{1}, y_{1} \end{pmatrix} + F_{1}^{sc} \begin{pmatrix} \mathbf{r} & \mathbf{r} \\ x_{1}, y_{1} \end{pmatrix} + F_{1}^{sc} \begin{pmatrix} \mathbf{r} & \mathbf{r} \\ x_{1}, y_{1} \end{pmatrix} + F_{1}^{sc} \begin{pmatrix} \mathbf{r} & \mathbf{r} \\ x_{1}, y_{1} \end{pmatrix} + F_{1}^{sc} \begin{pmatrix} \mathbf{r} & \mathbf{r} \\ x_{1}, y_{1} \end{pmatrix} + F_{1}^{sc} \begin{pmatrix} \mathbf{r} & \mathbf{r} \\ x_{1}, y_{1} \end{pmatrix} + F_{1}^{sc} \begin{pmatrix} \mathbf{r} & \mathbf{r} \\ x_{1}, y_{1} \end{pmatrix} + F_{1}^{sc} \begin{pmatrix} \mathbf{r} & \mathbf{r} \\ x_{1}, y_{1} \end{pmatrix} + F_{1}^{sc} \begin{pmatrix} \mathbf{r} & \mathbf{r} \\ x_{1}, y_{1} \end{pmatrix} + F_{1}^{sc} \begin{pmatrix} \mathbf{r} & \mathbf{r} \\ x_{1}, y_{1} \end{pmatrix} + F_{1}^{sc} \begin{pmatrix} \mathbf{r} & \mathbf{r} \\ x_{1}, y_{1} \end{pmatrix} + F_{1}^{sc} \begin{pmatrix} \mathbf{r} & \mathbf{r} \\ x_{1}, y_{1} \end{pmatrix} + F_{1}^{sc} \begin{pmatrix} \mathbf{r} & \mathbf{r} \\ x_{1}, y_{1} \end{pmatrix} + F_{1}^{sc} \begin{pmatrix} \mathbf{r} & \mathbf{r} \\ x_{1}, y_{1} \end{pmatrix} + F_{1}^{sc} \begin{pmatrix} \mathbf{r} & \mathbf{r} \\ x_{1}, y_{1} \end{pmatrix} + F_{1}^{sc} \begin{pmatrix} \mathbf{r} & \mathbf{r} \\ x_{1}, y_{1} \end{pmatrix} + F_{1}^{sc} \begin{pmatrix} \mathbf{r} & \mathbf{r} \\ x_{1}, y_{1} \end{pmatrix} + F_{1}^{sc} \begin{pmatrix} \mathbf{r} & \mathbf{r} \\ x_{1}, y_{1} \end{pmatrix} + F_{1}^{sc} \begin{pmatrix} \mathbf{r} & \mathbf{r} \\ x_{1}, y_{1} \end{pmatrix} + F_{1}^{sc} \begin{pmatrix} \mathbf{r} & \mathbf{r} \\ x_{1}, y_{1} \end{pmatrix} + F_{1}^{sc} \begin{pmatrix} \mathbf{r} & \mathbf{r} \\ x_{1}, y_{1} \end{pmatrix} + F_{1}^{sc} \begin{pmatrix} \mathbf{r} & \mathbf{r} \\ x_{1}, y_{1} \end{pmatrix} + F_{1}^{sc} \begin{pmatrix} \mathbf{r} & \mathbf{r} \\ x_{1}, y_{1} \end{pmatrix} + F_{1}^{sc} \begin{pmatrix} \mathbf{r} & \mathbf{r} \\ x_{1}, y_{1} \end{pmatrix} + F_{1}^{sc} \begin{pmatrix} \mathbf{r} & \mathbf{r} \\ x_{1}, y_{1} \end{pmatrix} + F_{1}^{sc} \begin{pmatrix} \mathbf{r} & \mathbf{r} \\ x_{1}, y_{2} \end{pmatrix} + F_{1}^{sc} \begin{pmatrix} \mathbf{r} & \mathbf{r} \\ x_{2} \end{pmatrix} + F_{1}^{sc} \begin{pmatrix} \mathbf{r} & \mathbf{r} \\ x_{1}, y_{2} \end{pmatrix} + F_{1}^{sc} \begin{pmatrix} \mathbf{r} & \mathbf{r} \\ x_{2} \end{pmatrix} + F_{1}^{sc} \begin{pmatrix} \mathbf{r} & \mathbf{r} \\ x_{2} \end{pmatrix} + F_{1}^{sc} \begin{pmatrix} \mathbf{r} & \mathbf{r} \\ x_{2} \end{pmatrix} + F_{1}^{sc} \begin{pmatrix} \mathbf{r} & \mathbf{r} \\ x_{2} \end{pmatrix} + F_{1}^{sc} \begin{pmatrix} \mathbf{r} & \mathbf{r} \\ x_{2} \end{pmatrix} + F_{1}^{sc} \begin{pmatrix} \mathbf{r} & \mathbf{r} \\ x_{2} \end{pmatrix} + F_{1}^{sc} \begin{pmatrix} \mathbf{r} & \mathbf{r} \\ x_{2} \end{pmatrix} + F_{1}^{sc} \begin{pmatrix} \mathbf{r} & \mathbf{r} \\ x_{2} \end{pmatrix} + F_{1}^{sc} \begin{pmatrix} \mathbf{r} & \mathbf{r} \\ x_{2} \end{pmatrix} + F_{1}^{sc} \begin{pmatrix} \mathbf{r} & \mathbf{r} \\ x_{2} \end{pmatrix} + F_{1}^{sc} \begin{pmatrix} \mathbf{r} & \mathbf{r} \\ x_{2} \end{pmatrix} + F_{1}^{sc} \begin{pmatrix} \mathbf{r} & \mathbf{r} \\ x_{2} \end{pmatrix} + F_{1}^{sc} \begin{pmatrix} \mathbf{r} & \mathbf{r} \\ x_{2} \end{pmatrix} + F_{1}^{sc} \begin{pmatrix} \mathbf{r} & \mathbf{r} \\ x_{2} \end{pmatrix} + F_{1}^{sc} \begin{pmatrix} \mathbf{r} & \mathbf{r} \\ x_{2} \end{pmatrix} + F_{1}^{sc} \begin{pmatrix} \mathbf{r} & \mathbf{r} \\ x_{2} \end{pmatrix} + F_{1}^{sc} \begin{pmatrix} \mathbf{r} & \mathbf{r} \\ x_{2} \end{pmatrix} + F_{1}^{sc} \begin{pmatrix} \mathbf{r} & \mathbf{r} \\ x_{2} \end{pmatrix} + F_{1}^{sc} \begin{pmatrix} \mathbf{r} & \mathbf{$ 

 $\begin{cases} (E - V_1(x_1) - \hat{H}_0)F_1^{sc} - V_1(x_1)(F_2^{sc} + F_3^{sc}) = 0\\ (E - V_2(x_2) - \hat{H}_0)F_2^{sc} - V_2(x_2)(F_1^{sc} + F_3^{sc}) = V_2(x_2)F_1^{in}\\ (E - V_3(x_3) - \hat{H}_0)F_3^{sc} - V_3(x_3)(F_1^{sc} + F_2^{sc}) = V_3(x_3)F_1^{in} \end{cases}$ 

![](_page_10_Figure_1.jpeg)

Driven Faddeev eq.:  $F_{1}(\stackrel{\mathbf{r}}{x_{1}}, \stackrel{\mathbf{r}}{y_{1}}) = F_{1}^{in}(\stackrel{\mathbf{r}}{x_{1}}, \stackrel{\mathbf{r}}{y_{1}}) + F_{1}^{sc}(\stackrel{\mathbf{r}}{x_{1}}, \stackrel{\mathbf{r}}{y_{1}})$  $F_{1}^{in}(\overset{\mathbf{r}}{x_{1}},\overset{\mathbf{r}}{y_{1}}) = f_{1}^{l_{x}}(x_{1})\hat{j}_{l_{y}}(qy_{1})\left\{Y_{l_{x}}(\hat{x})\otimes Y_{l_{y}}(\hat{y})\right\}_{IM}$ 

Outgoing wave  $F_1^{sc}(x_1^r e^{i\theta}, y_1^r e^{i\theta})$  becomes exponentially bound:

• 2-body plane out. waves

 $\sim \exp(-k_{bs}x)\exp(-qy\sin\theta)$   $k_{bs} = \sqrt{\frac{m}{h^2}}|B_{bs}|; q = \sqrt{\frac{2m}{3h^2}}E_{lab}$ 

• 3-body break-up out. wave

$$\sim \exp(-K\rho\sin\theta) \qquad K = \sqrt{\frac{m}{h^2}\left(\frac{2}{3}E_{lab} - B_{bs}\right)}; \ \rho = \sqrt{x^2 + y^2}$$

![](_page_11_Figure_1.jpeg)

![](_page_12_Figure_1.jpeg)

#### **Solution: Faddeev equations+PW decomposition+spline discretization of xy**

R. Lazauskas, PhD thesis, Université Joseph Fourier Grenoble (2003)

R. Lazauskas and J. Carbonell, Phys. Rev. C 84 (2011), 034002

TABLE III: Neutron-deuteron scattering phaseshift and inelasticity parameter as a function of the complex rotation angle compared with benchmark results of [23, 24]. Our calculations has been performed by setting  $y_{max}=100$  fm.

	3°	$4^{\circ}$	$5^{\circ}$	6°	7.5°	$10^{\circ}$	12.5°	Ref. [23, 24
			nd d	loublet at $E_{lab}$	=14.1 MeV			•
$\operatorname{Re}(\delta)$	105.00	105.43	105.50	105.50	105.50	105.49	105.48	105.49
$\eta$	0.4559	0.4638	0.4653	0.4654	0.4653	0.4650	0.4649	0.4649
			nd	doublet at $E_{la}$	b=42  MeV			
$\operatorname{Re}(\delta)$	41.71	41.63	41.55	41.51	41.45	41.04		41.35
$\eta$	0.5017	0.5015	0.5014	0.5014	0.5015	0.5048		0.5022
			nd q	$ uartet at E_{lab} $	=14.1 MeV			
$\operatorname{Re}(\delta)$	68.47	68.90	68.97	68.97	68.97	68.97	68.97	68.95
$\eta$	0.9661	0.9762	0.9782	0.9784	0.9783	0.9782	0.9780	0.9782
			nd	quartet at $E_{la}$	$_{b}=42 \text{ MeV}$			
$\operatorname{Re}(\delta)$	37.83	37.80	37.77	37.77	37.74	38.06	-	37.71
$\eta$	0.9038	0.9034	0.9032	0.9030	0.9029	0.8980	-	0.9033

Ref.[23] J. L. Friar et al.:, Phys. Rev. C 51 (1995) 2356. Ref.[24] A. Deltuva, A. C. Fonseca et al.:,, Phys. Rev. C 71 (2005) 064003.

	3°	$4^{\circ}$	5°	6°	7.5°	10°	12.5°	Ref. [24]
			pd do	ublet at $E_{lab} =$	$14.1  \mathrm{MeV}$			
$\operatorname{Re}(\delta)$	108.46	108.43	108.43	108.43	108.43	108.43	108.42	108.41[3]
$\eta$	0.5003	0.4993	0.4990	0.4988	0.4986	0.4984	0.4981	0.4983[1]
			pd de	oublet at $E_{lab}$ =	=42  MeV			
$\operatorname{Re}(\delta)$	43.98	43.92	43.87	43.82	43.78	44.83	-	43.68[2]
$\eta$	0.5066	0.5060	0.5056	0.5054	0.5052	0.5488	-	0.5056
			pd qu	artet at $E_{lab}=$	14.1 MeV			
$\operatorname{Re}(\delta)$	72.70	72.65	72.65	72.64	72.64	72.63	72.62	72.60
$\eta$	0.9842	0.9827	0.9826	0.9826	0.9826	0.9828	0.9829	0.9795[1]
			թժ գւ	uartet at $E_{lab}$ =	=42  MeV			
$\operatorname{Re}(\delta)$	40.13	40.11	40.08	40.07	40.05	40.35	-	39.96[1]
$\eta$	0.9052	0.9044	0.9039	0.9036	0.9034	0.9026	-	0.9046

TABLE IV: Proton-deuteron scattering phaseshift and inelasticity parameter as a function of the complex rotation angle  $\theta$  compared with benchmark values of [24]. Our calculations has been performed by setting  $y_{max}=150$  fm.

Ref.[24] A. Deltuva, A. C. Fonseca et al.:, Phys. Rev. C 71 (2005) 064003.

TABLE V: Neutron-deuteron  ${}^{3}S_{1}$  break-up amplitude calculated at  $E_{lab}=42$  MeV as a function of the break-up angle  $\vartheta$ .

	0°	10°	20°	30°	40°	50°	60°	70°	80°	90°
This work $Re(^{3}S_{1})$	1.49[-2]	8.84[-4]	-3.40[-2]	-3.33[-2]	7.70[-2]	2.52[-1]	4.47[-1]	6.47[-1]	6.30[-1]	-1.62[-1]
This work $Im(^{3}S_{1})$	1.69[0]	1.74[0]	1.87[0]	1.92[0]	1.80[0]	1.68[0]	1.70[0]	1.96[0]	2.23[0]	3.17[0]
Ref. [23] $Re({}^{3}S_{1})$	1.48[-2]	9.22[-4]	-3.21[-2]	-3.09[-2]	7.70[-2]	2.52[-1]	4.51[-1]	6.53[-1]	6.93[-1]	1.05[-1]
Ref. [23] $Im({}^{3}S_{1})$	1.69[0]	1.74[0]	1.87[0]	1.92[0]	1.80[0]	1.67[0]	1.70[0]	1.95[0]	2.52[0]	3.06[0]

Ref.[23] J. L. Friar et al.:, Phys. Rev. C 51 (1995) 2356.

## **Complex scaling method** (3-body system with optical pot.)

![](_page_16_Figure_1.jpeg)

R. Lazauskas, J. Carbonell

## 4-body system

![](_page_17_Figure_1.jpeg)

Solution: FY equations+PW decomposition+spline discretization of xyz R. Lazauskas, PhD thesis, Université Joseph Fourier Grenoble (2003)

## **4-nucleon system**

#### $n+^{3}H$ (T=1) scattering with MT I-III potential

![](_page_18_Figure_2.jpeg)

## 4-nucleon system

### $n+^{3}H$ (*T*=1) scattering with MT I-III potential

E <sub>lab</sub>	MT I-III (this work)			INOY (Deltuva)			Exp.	
(MeV)	$\sigma_{e}(mb)$	$\sigma_{b}$ (mb)	$\sigma_t$ (mb)	$\sigma_{e}(mb)$	$\sigma_{b}$ (mb)	σ <sub>t</sub> (mb)	$\sigma_t$ (mb)	
14.4	922	11	933	928	19	947	978 ± 70	
18.0	690	25	715	697	41	738	750 ± 60	
22.1	512	38	550	536	61	597	620 ± 24	

## NCSM application?

Deuteron binding energy calculation compared with np scattering calculation at 20 MeV for  ${}^{3}S_{1}$  wave

![](_page_20_Figure_2.jpeg)

Similar convergence (only less regular) as for the weakly bound state calculations
Results for the soft potentials converge much faster

## Method summary

Trivial boundary conditions.

Full information: elastic, inelastic and break-up amplitudes obtained after minimal modification of the bound state code

✤ Valid for any exponentially bound interaction, possible to include Coulomb. Inclusion of Coulomb for A>2 systems requires small improvable approximation - neglecting the action of the polarization terms on incoming wave.

⊖ Problem solved in complex arithmetics.

 $\bigcirc$  Potential must be analytical and remain short range after complex scaling (sets upper limit on  $\theta$ )

 $\bigcirc$  Additional limitation on  $\theta$  for A>2 problem (sets upper limit on  $\theta$ , this angle reduces when increasing scattering energy)

Hamiltonian is not Hermitian anymore. It is more costly to ensure unitarity of the S-matrix. Nevertheless phases are obtained very accurately, convergence of inelasticity parameters if they are small (or close to 1) is slower.
 Difficulty to treat close to the threshold region (some of outgoing waves convergence)

#### slowly)

## Conclusion

- Complex scaling method is efficient tool to solve bound, resonant as well as continuum states problem without explicit treatment of the boundary conditions
- Scattering problem might be solved using bound state methods in complex arithmetic (almost by any config. space bound state technique and require very limited effort)
- Simple extension of the formalism to many-body scattering case
- Reliable results are already obtained for 3-body and 4-body elastic and breakup scattering, including long-range and optical potentials

## **4-nucleon system**

## " $p+^{3}H$ " (*T*=0) scattering with MT I-III potential, (by ignoring Coulomb) E<sub>cm</sub>=30. MeV

 $E_{cm}$ =20.5 MeV

		δ (°)	η
L=0	S=0	-56.6	0.650
	S=1	68.8	0.947
L=1	S=0	-85.3	0.945
	S=1	64.9	0.886
L=2	S=0	47.1	0.678
	S=1	1.09	0.896

		δ (°)	η
L=0	S=0	-81.0	0.618
	S=1	56.9	0.882
L=1	S=0	78.9	0.918
	S=1	52.8	0.843
L=2	S=0	44.7	0.720
	S=1	4.49	0.851

J<sup>π</sup>=0<sup>+</sup>

E <sub>cm</sub> (MeV)	MT I-III (thi	s work)	Yamaguchi (	Uzu)
	δ (°)	η	δ (°)	η
7.3	-4.46	0.988	-5.51	0.899
20.5	-56.6	0.650	-61.7	0.746