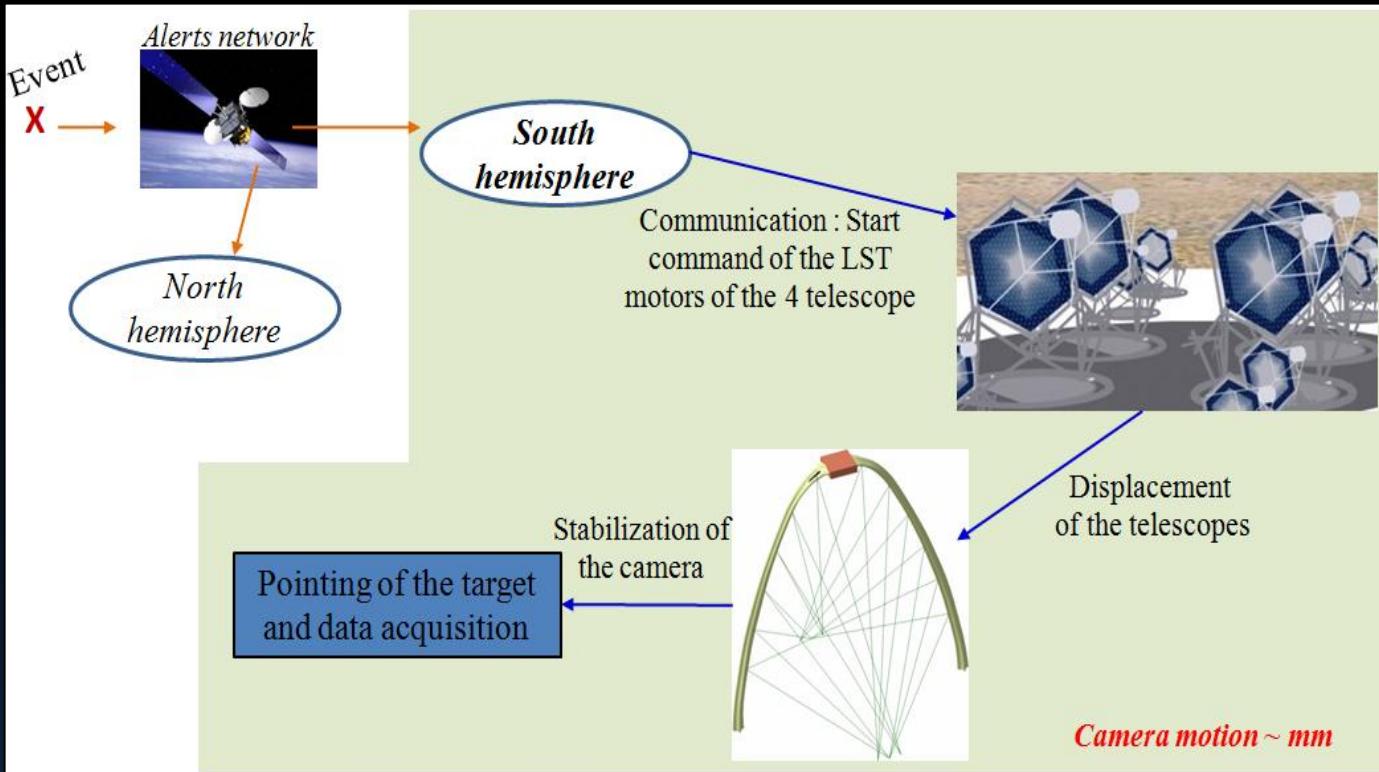


# LST au LAPP

## « Drive System »

## « Amortissement de l'arche »

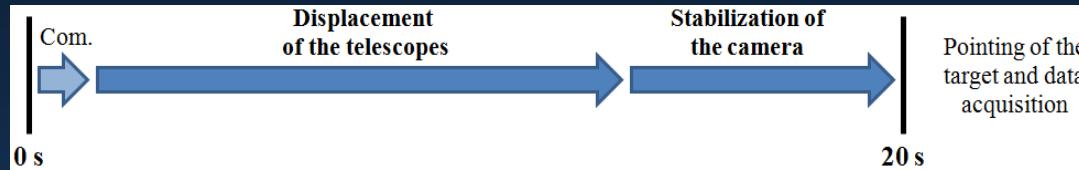
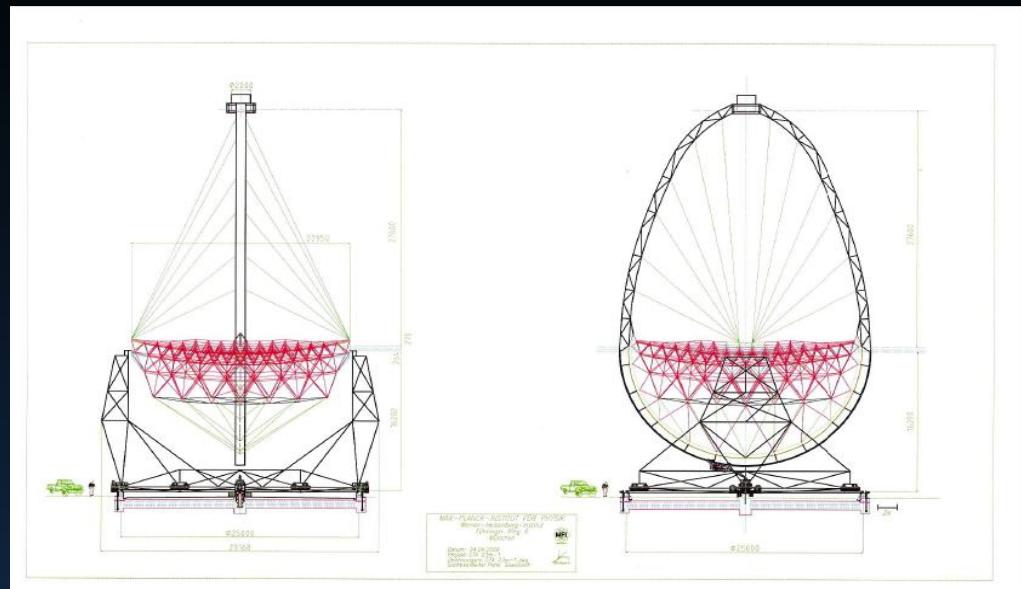
# Les contraintes



- *Weight: 50 tones*
- *Focal distance: 23 - 24 m*
- *Rotation speed (fast): 180° in 20s*
- *Drive tracking position: <0.005 deg*

# Les études en cours (1)

- 2 ingénieurs mécaniciens pour l' étude de l'arche et du système d'amortissement



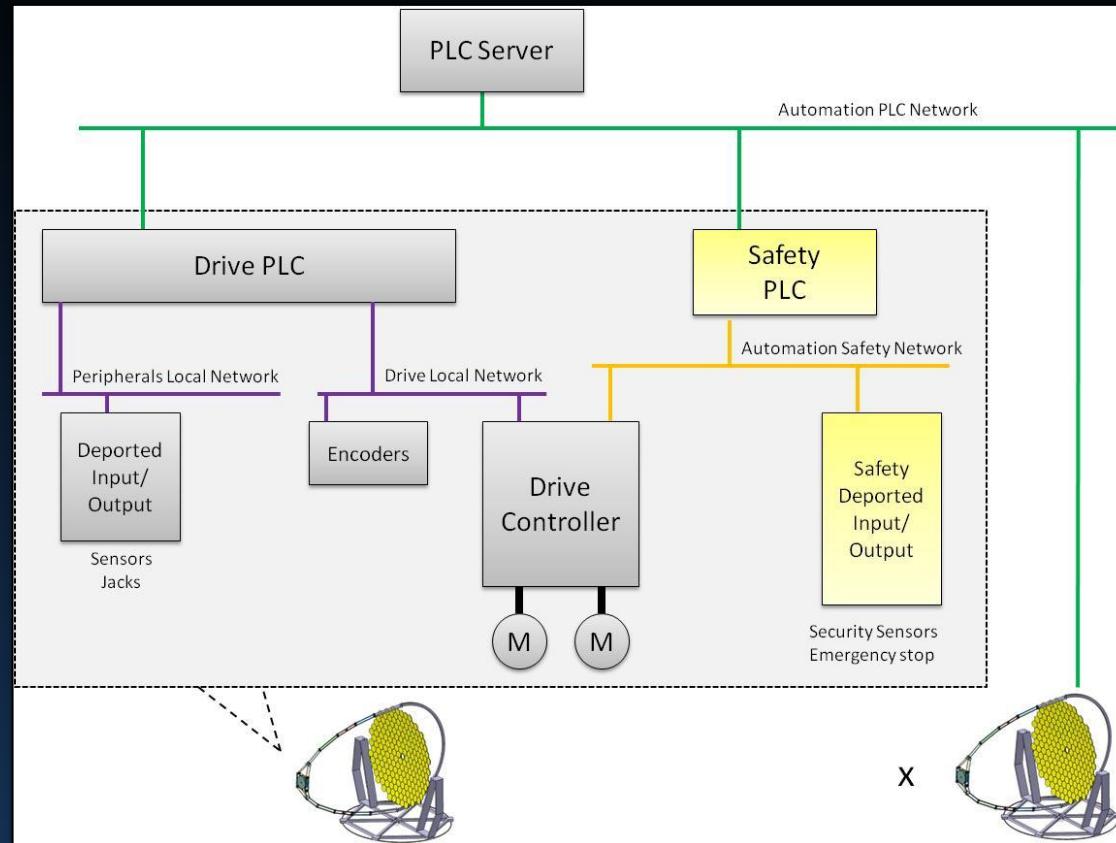
Principe d'amortissement des vibrations

Instrumenter les câbles avec  
des capteurs et actionneurs  
pour agir sur les déplacements de la  
caméra

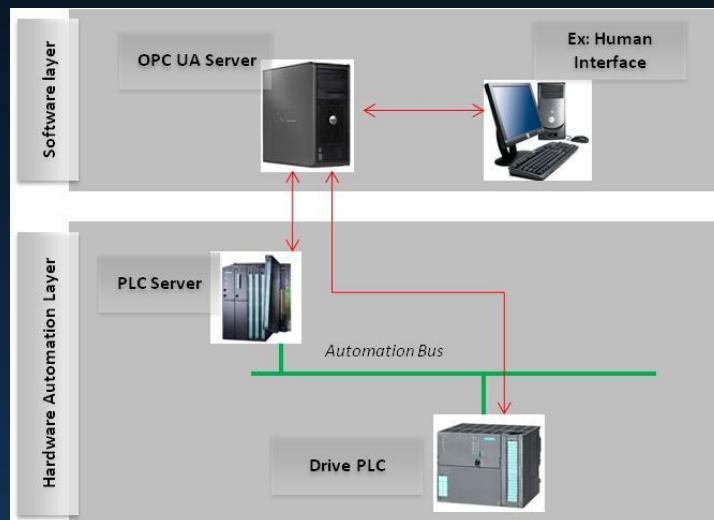
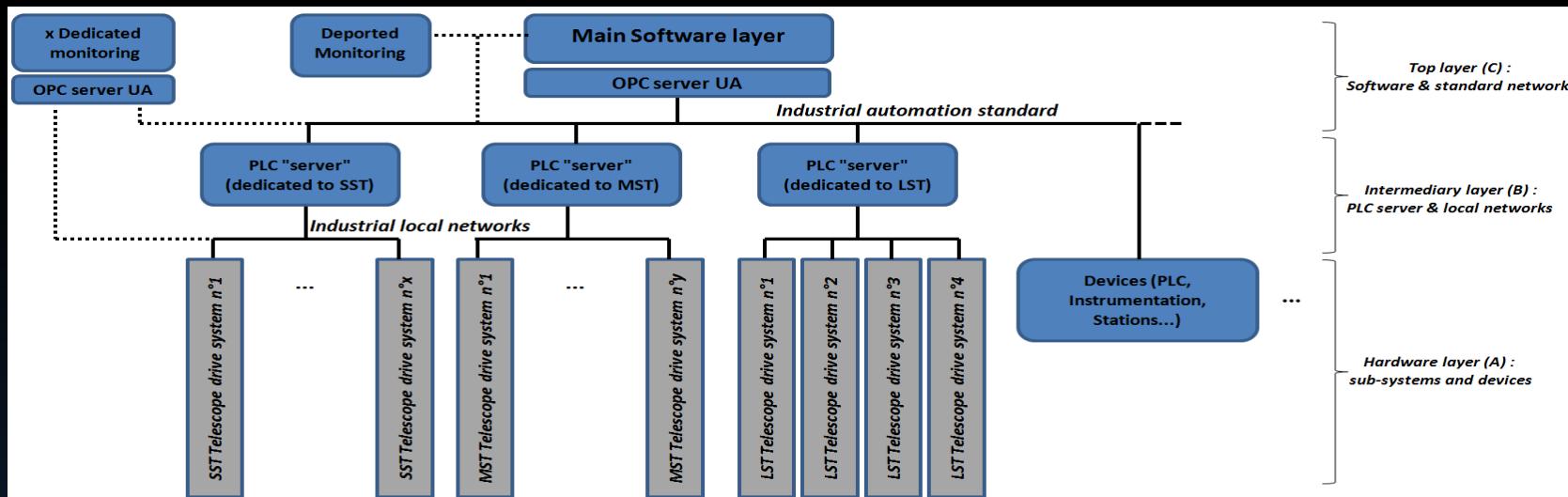


# Les études en cours (2)

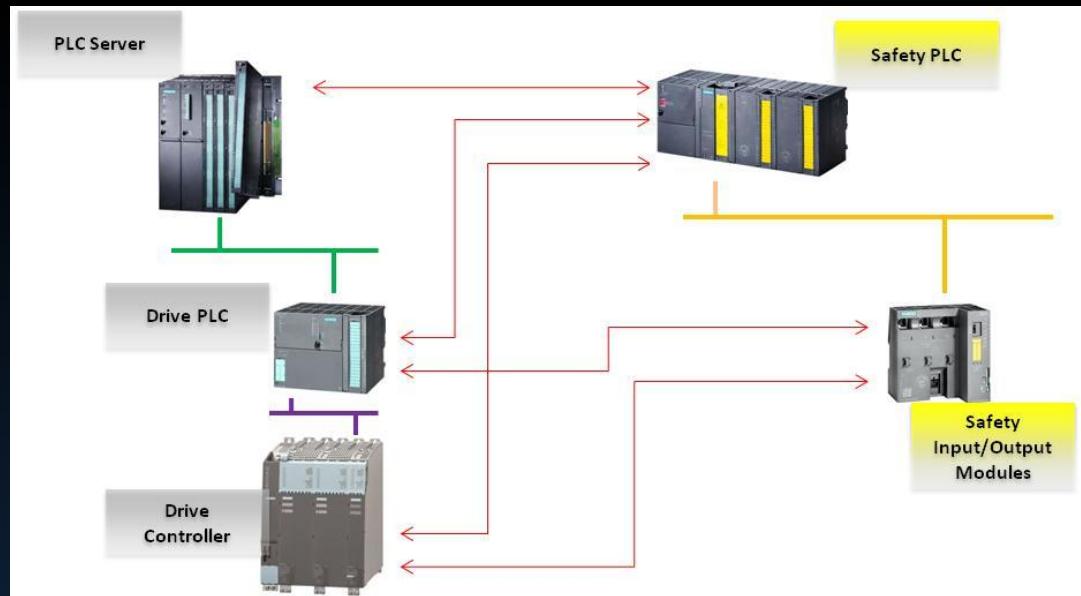
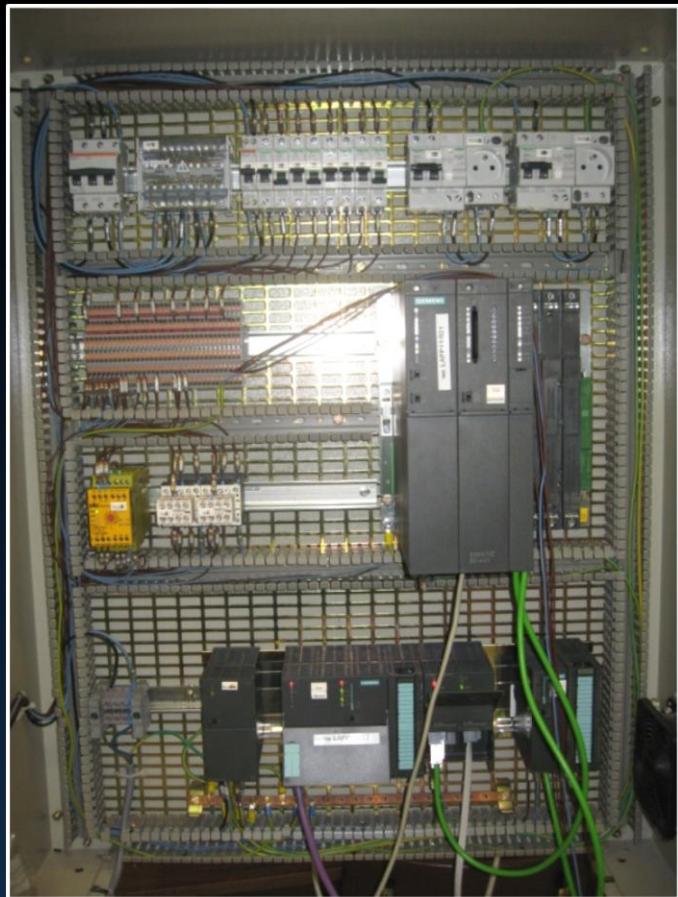
- 2 ingénieurs « Automatien » pour l' étude du « Drive System »



# Architecture



# Banc Test au LAPP



Evaluation of communications between all automation components.

# Array Drive System : Work in progress

- Test bench on PLC (currently “Siemens”) and field bus organization to meet a cost effective PLC and network architecture vs. expected performance (i.e. 20” for 90 deg elevation and 180 deg rotation)
- Telescopes layout => network topology
  - ✓ Data transmission
  - ✓ PCL logical & physical organization
    - Hierarchical vs Star Architecture depending mainly on the reaction time



- Network availability => link redundancy, reaction times
- Data flow prioritization => bandwidth reservation, synchronization, RealTime