
Probabilistic Inference in Physics

Giulio D'Agostini

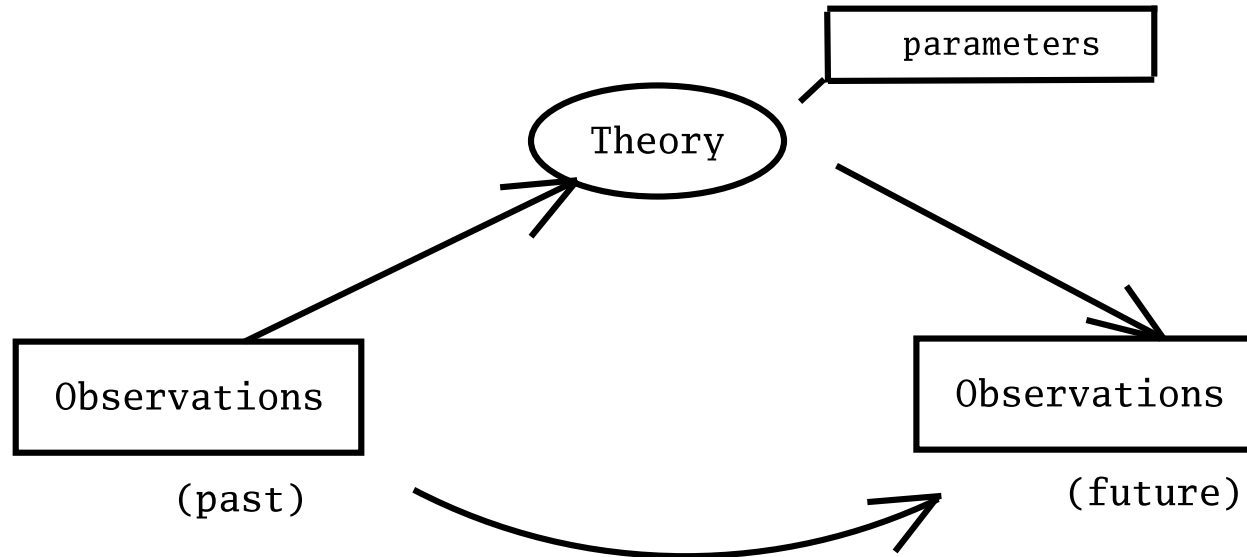
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“La théorie des probabilités n'est, au fond,
que le bon sens réduit au calcul” (Laplace)

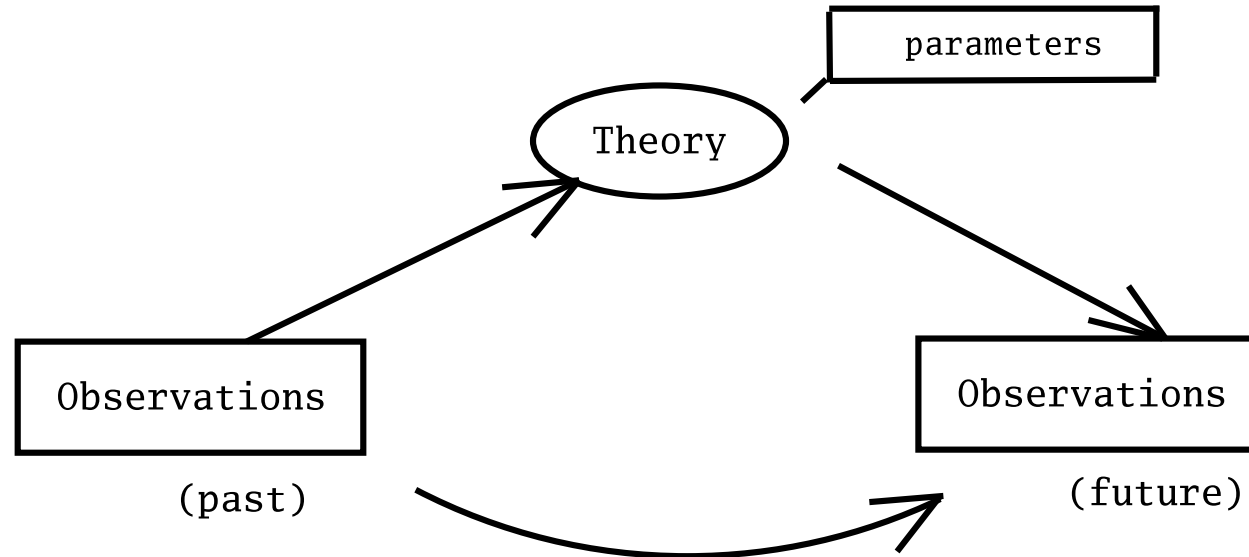
Doing Physics [Science in general]



Task of physicists:

- Describe/understand the physical world
⇒ **inference** of laws and their parameters
- Predict observations
⇒ **forecasting**

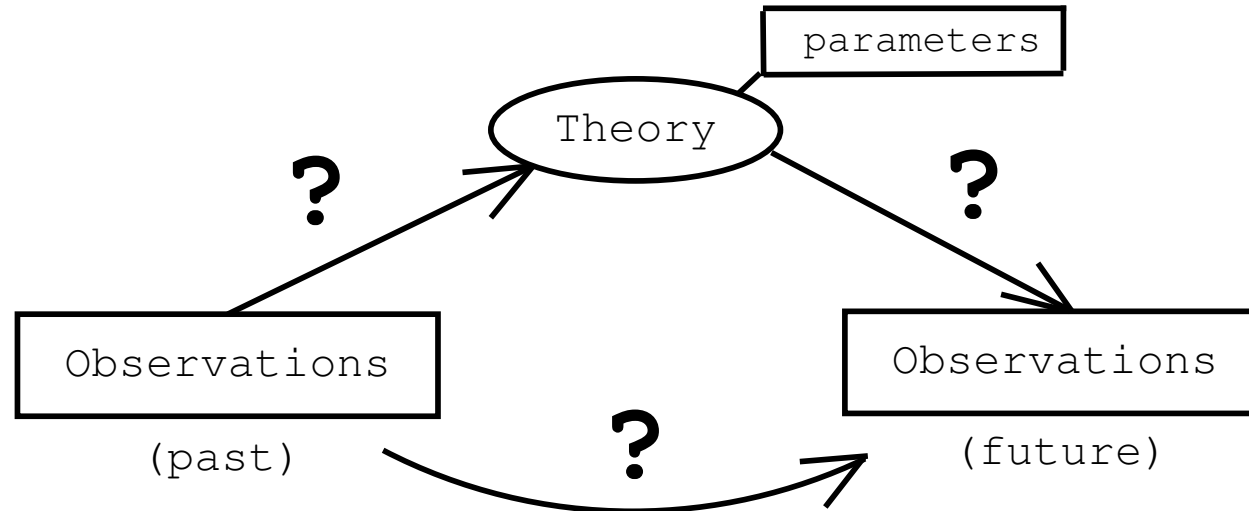
Doing Physics [Science in general]



Process

- neither automatic
- nor purely contemplative
 - 'scientific method'
 - planned experiments ('actions') ⇒ **decision.**

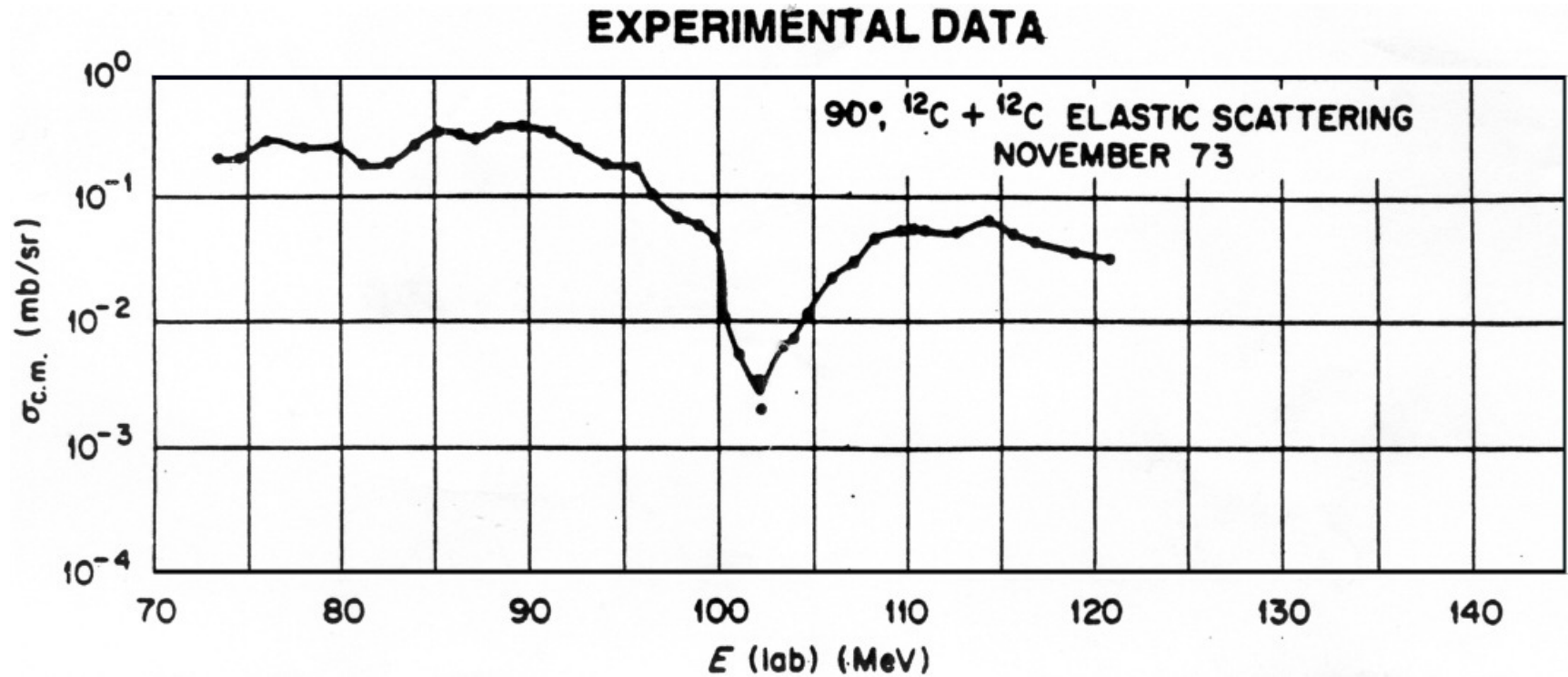
Doing Physics [Science in general]



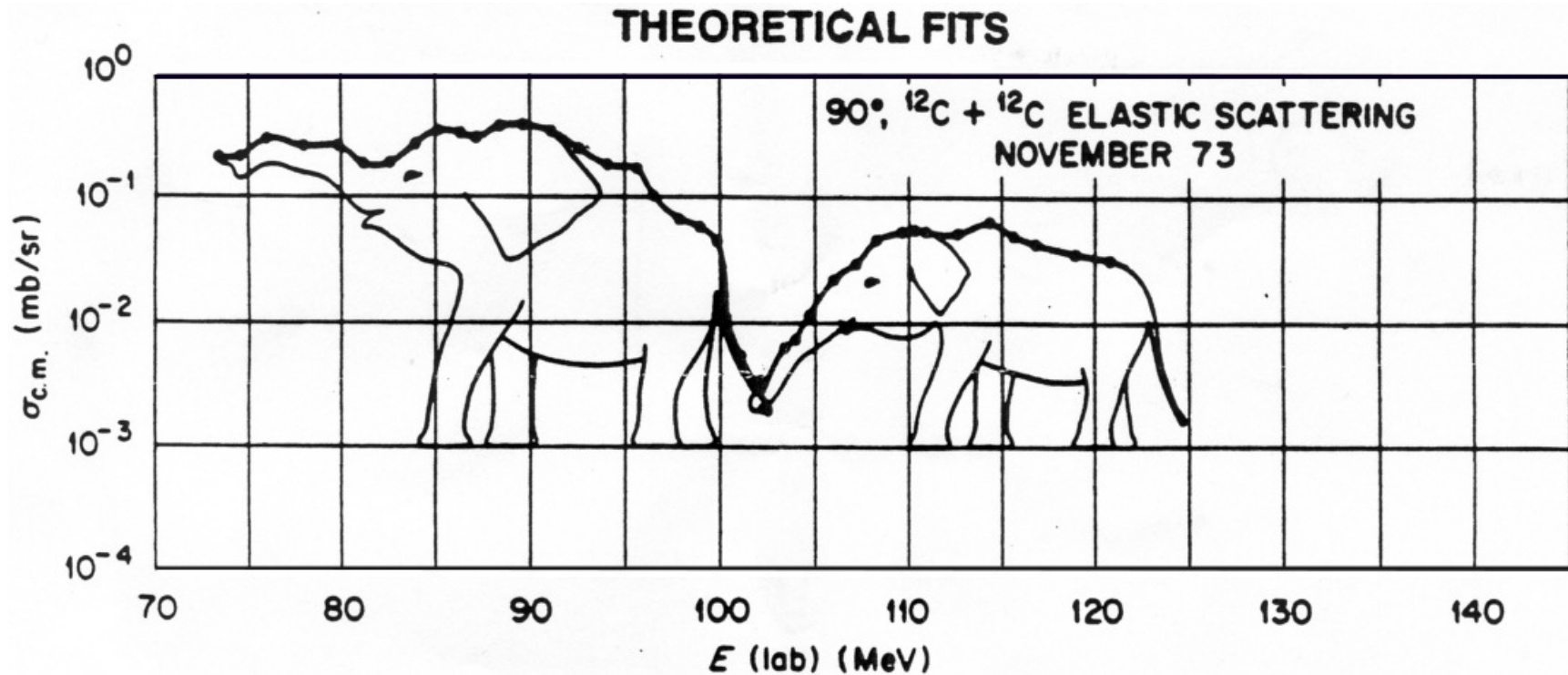
⇒ Uncertainty:

1. Given the past observations, in general we are not sure about the theory parameters (and/or the theory itself)
2. Even if we were sure about theory and parameters, there could be internal (e.g. Q.M.) or external effects (initial/boundary conditions, 'errors', etc) that make the forecasting uncertain.

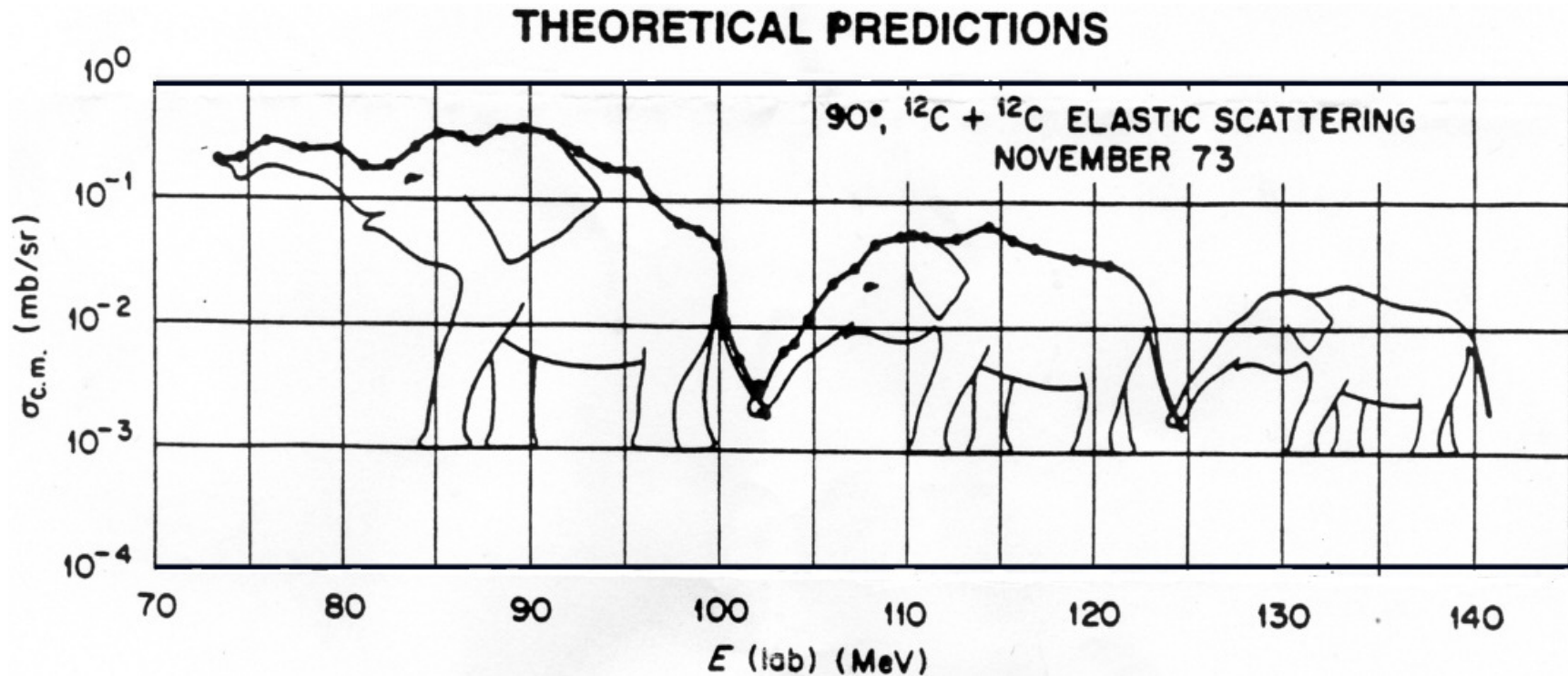
Inferential-predictive process



Inferential-predictive process

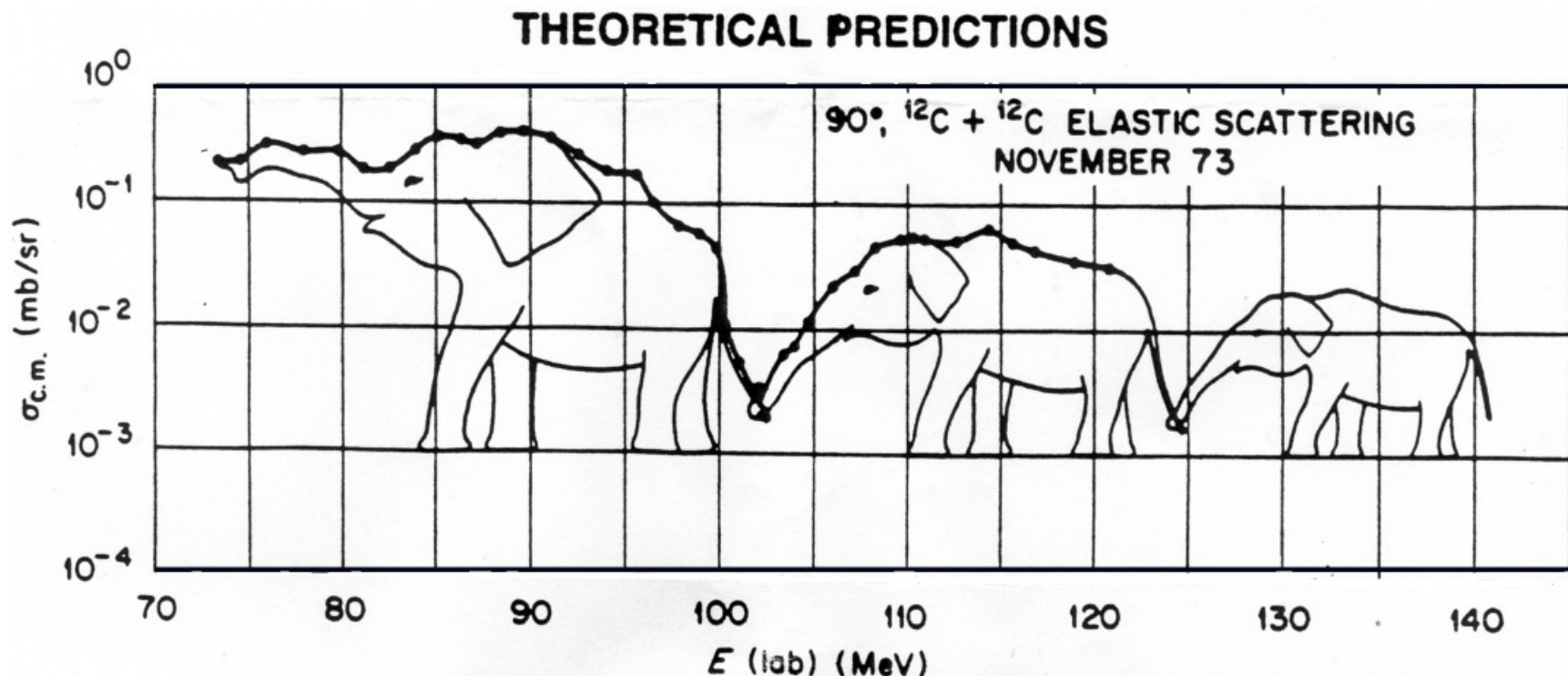


Inferential-predictive process



(S. Raman, *Science with a smile*)

Inferential-predictive process



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Even if the (*ad hoc*) model fits perfectly the data,
we do not believe the predictions
because we don't trust the model!

[Many 'good' models are *ad hoc* models!]

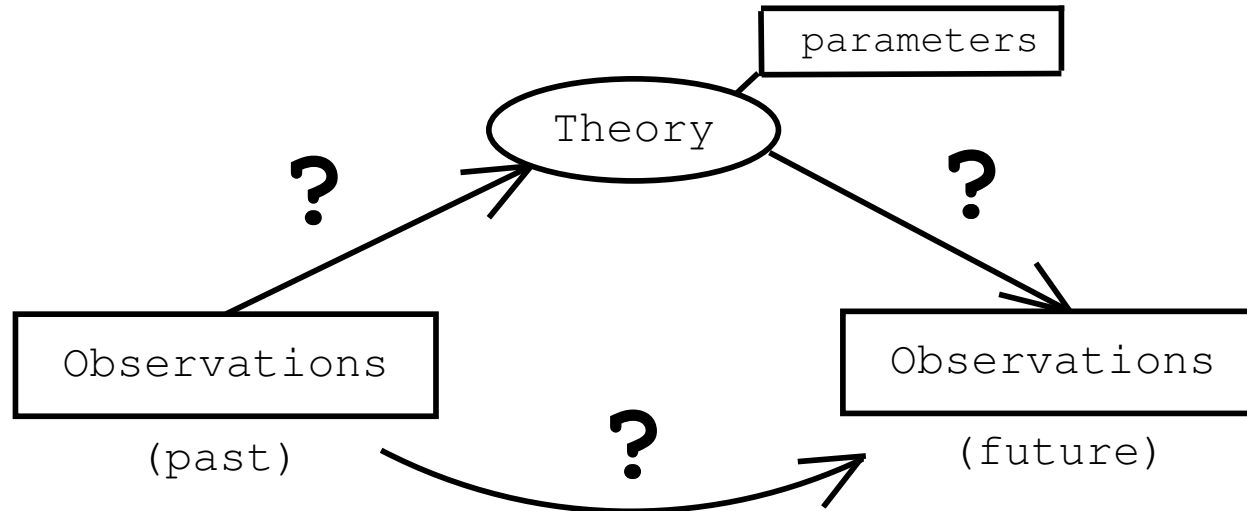
2011 IgNobel prize in Mathematics

- D. Martin of USA (who predicted the world would end in 1954)
- P. Robertson of USA (who predicted the world would end in 1982)
- E. Clare Prophet of the USA (who predicted the world would end in 1990)
- L.J. Rim of KOREA (who predicted the world would end in 1992)
- C. Mwerinde of UGANDA (who predicted the world would end in 1999)
- H. Camping of the USA (who predicted the world would end on September 6, 1994 and later predicted that the world will end on **October 21, 2011**)

2011 IgNobel prize in Mathematics

“For teaching the world to be careful when making mathematical assumptions and calculations”

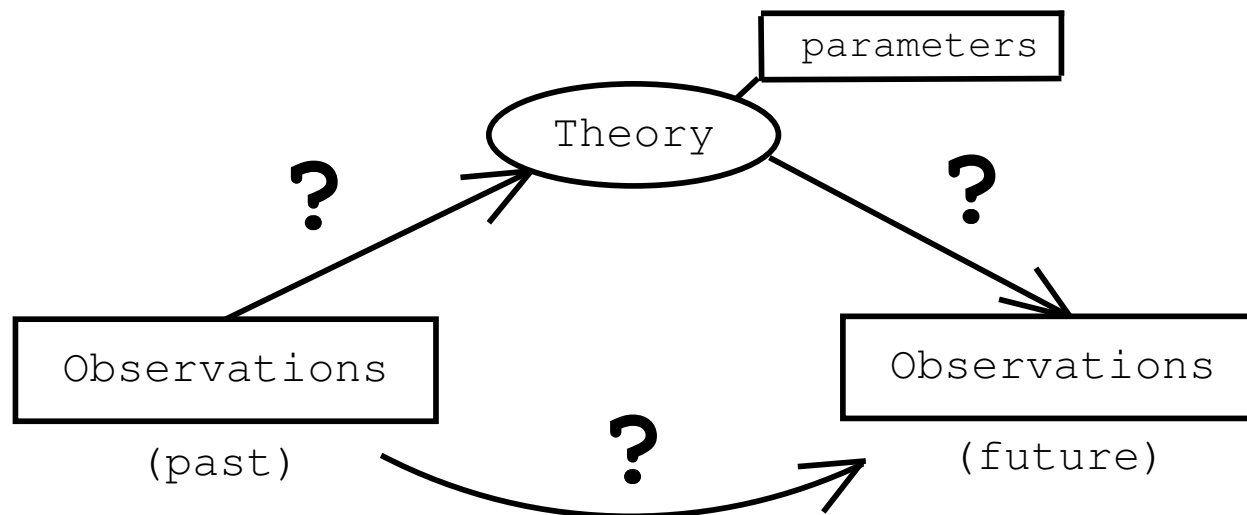
Deep source of uncertainty



Uncertainty:

Theory	— ? —>	Future observations
Past observations	— ? —>	Theory
Theory	— ? —>	Future observations

Deep source of uncertainty



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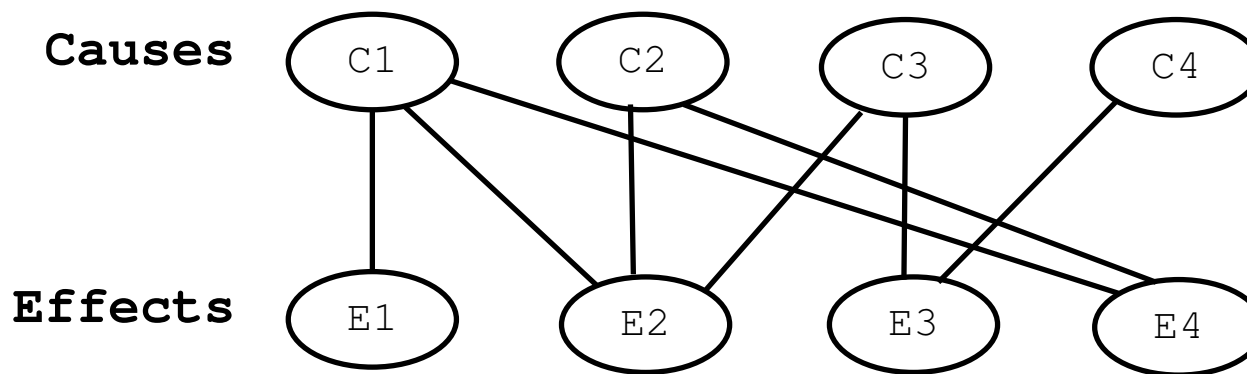
Theory — ? → Future observations
Past observations — ? → Theory
Theory — ? → Future observations

⇒ **Uncertainty about causal connections**

CAUSE ⇔ EFFECT

Causes → effects

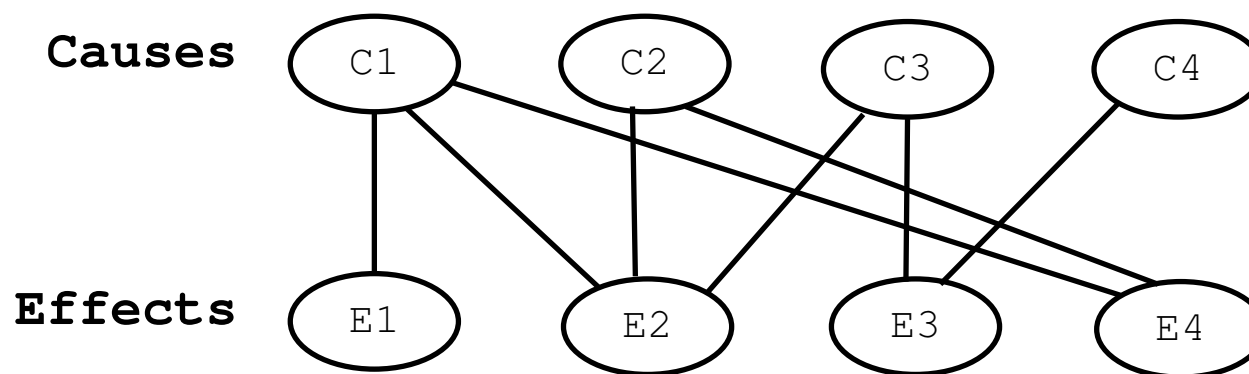
The same *apparent* cause might produce several, different effects



Given an observed effect, we are not sure about the exact cause that has produced it.

Causes → effects

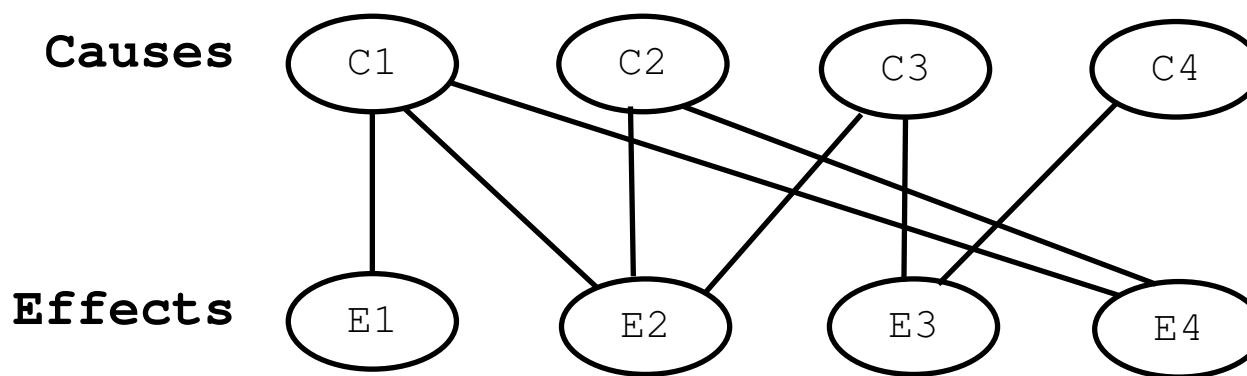
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$$E_2 \Rightarrow \{C_1, C_2, C_3\}?$$

The “essential problem” of the Sciences

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I play with a gentleman whom I do not know. He has dealt ten times, and he has turned the king up six times. What is the chance that he is a sharper? This is a problem in the probability of causes. It may be said that **it is the essential problem of the experimental method.**”

(H. Poincaré – *Science and Hypothesis*)

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(H. Poincaré – *Science and Hypothesis*)

Why physics students are not taught how to tackle this kind of problems?

Uncertainty and probability

We, as physicists, consider absolutely natural and meaningful statements of the following kind

- $P(-10 < \epsilon'/\epsilon \times 10^4 < 50) \gg P(\epsilon'/\epsilon \times 10^4 > 100)$
- $P(172 \leq m_{top}/\text{GeV} \leq 174) \approx 70\%$
- $P(M_H < 125 \text{ GeV}) > P(M_H > 125 \text{ GeV})$

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[The fact that for several people in this audience
this criticism is mysterious is a clear indication
of the confusion concerning this matter]

Doing Science in conditions of uncertainty

The constant status of uncertainty does not prevent us from doing Science (in the sense of Natural Science and not just Mathematics)

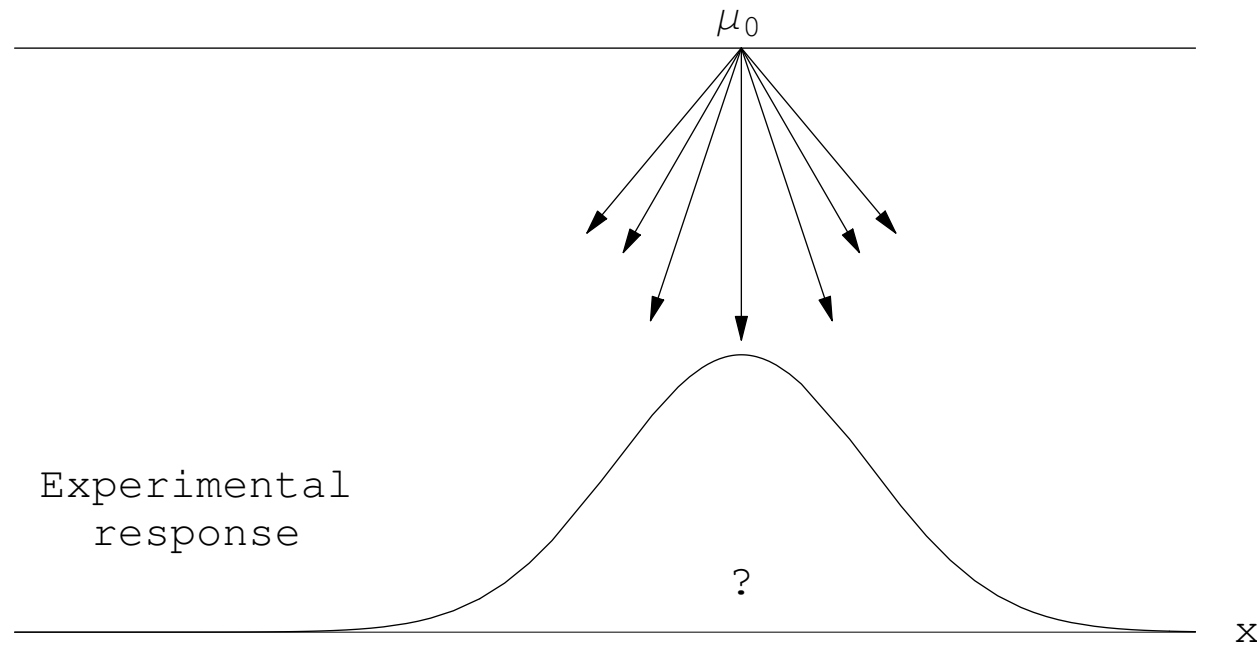
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Indeed

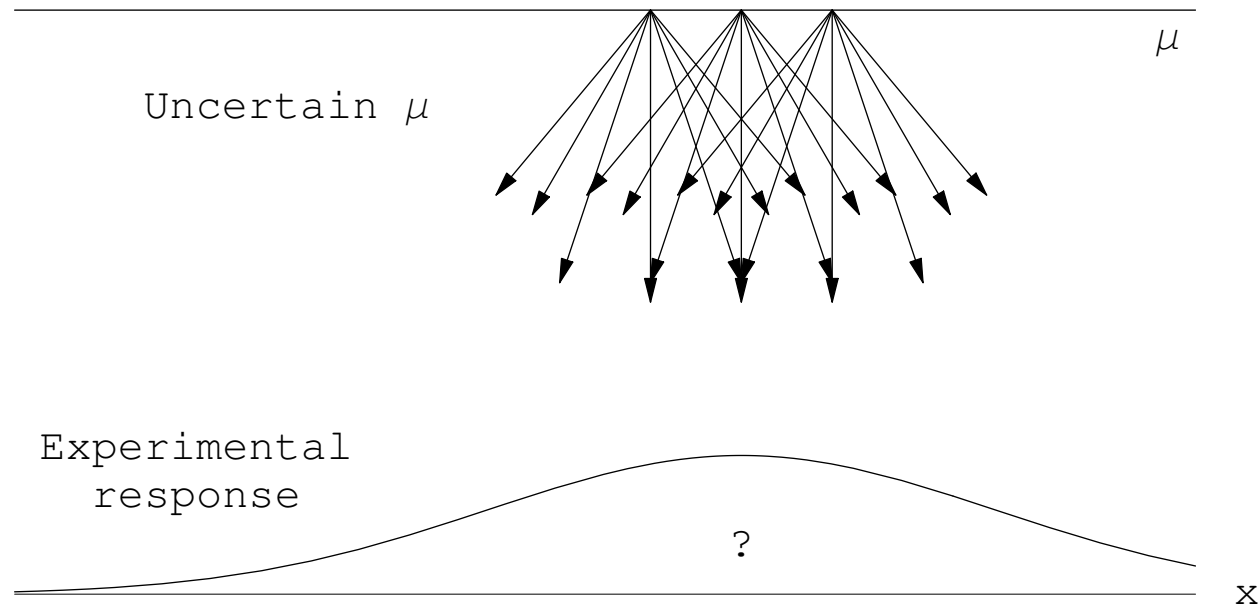
“It is scientific only to say what is more likely and what is less likely” (Feynman)

From 'true value' to observations



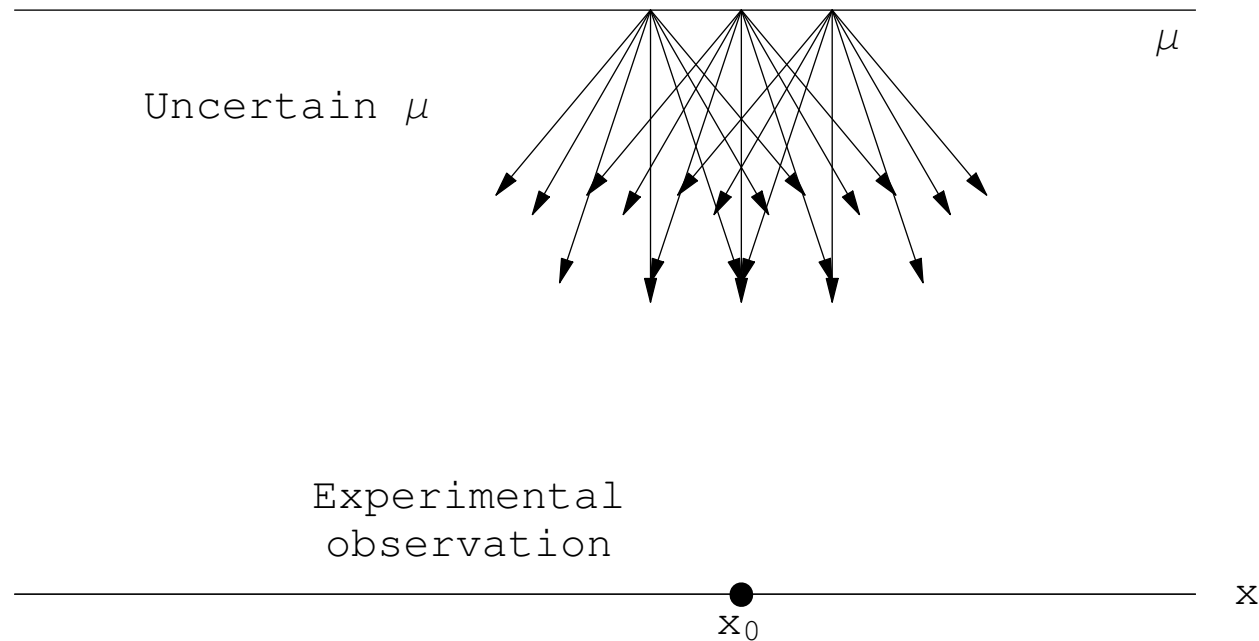
Given μ (exactly known) we are uncertain about x

From 'true value' to observations



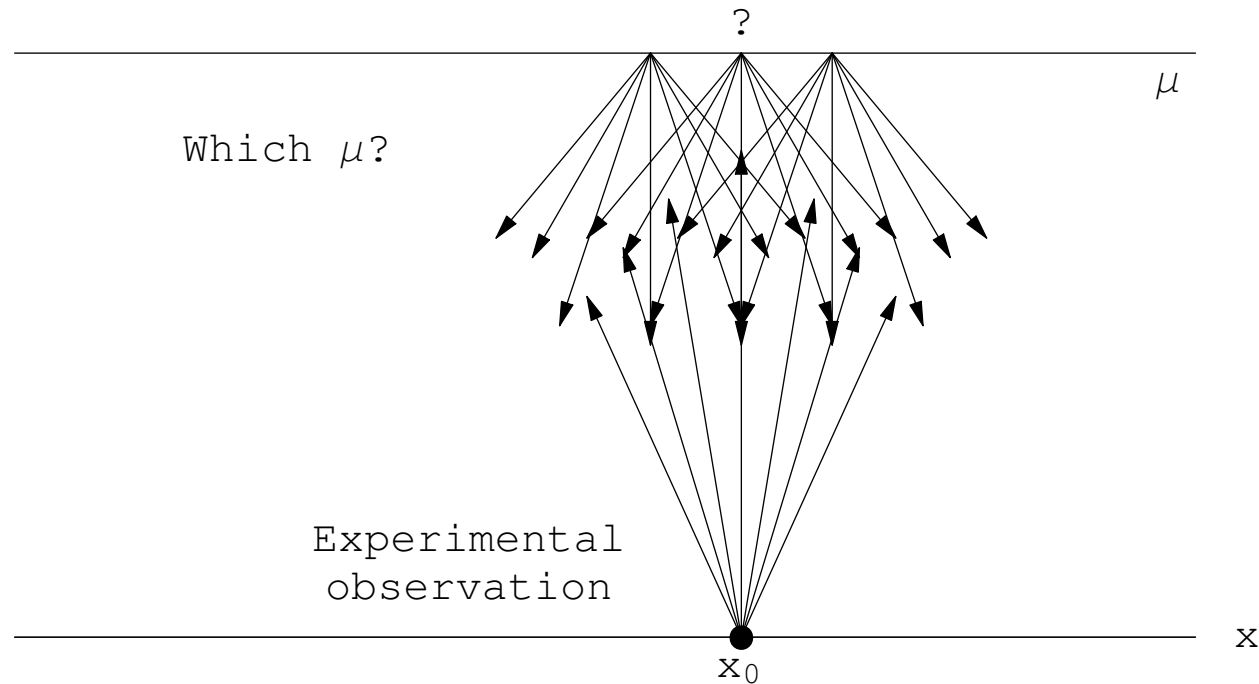
Uncertainty about μ makes us more uncertain about x

... and back: Inferring a true value



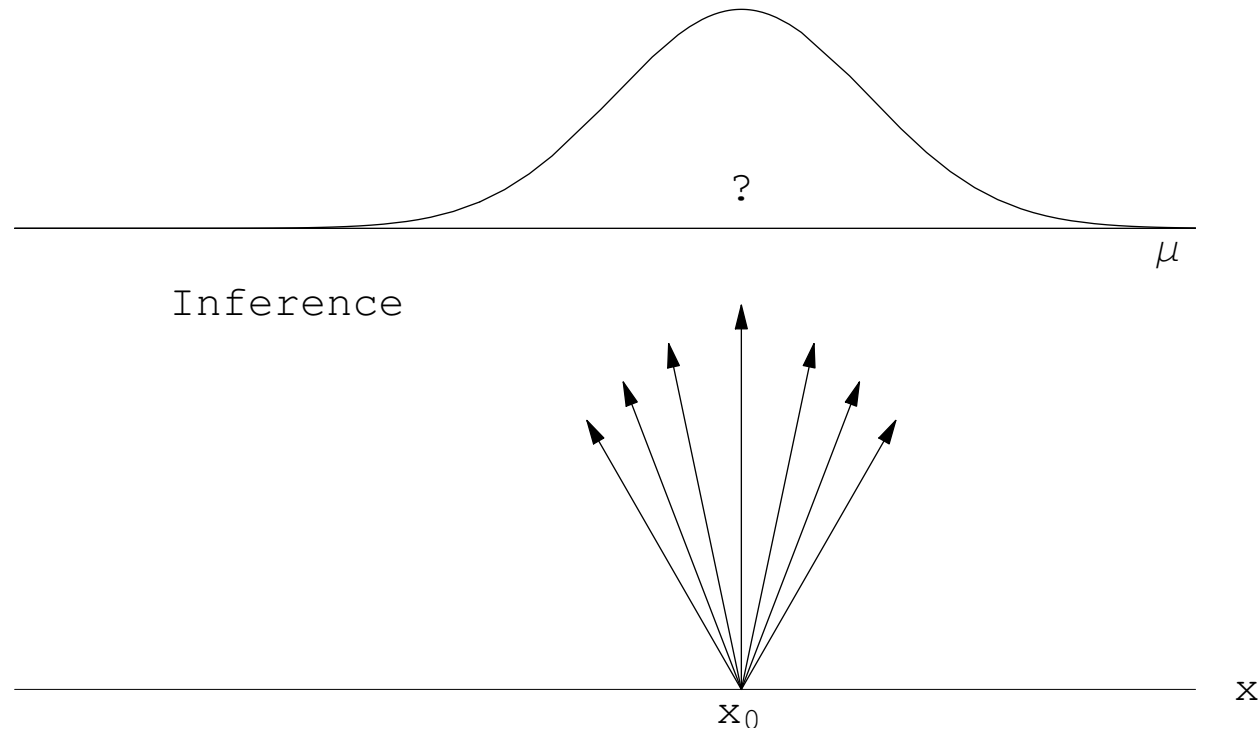
The observed data is certain: \rightarrow 'true value' uncertain.

... and back: Inferring a true value



Where does the observed value of x comes from?

... and back: Inferring a true value



We are now uncertain about μ , given x .

A very simple experiment

Let's make an experiment

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- Here
- Now

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For simplicity

- μ can assume only six possibilities:

$0, 1, \dots, 5$

- x is binary:

$0, 1$

[(1, 2); Black/White; Yes/Not; ...]

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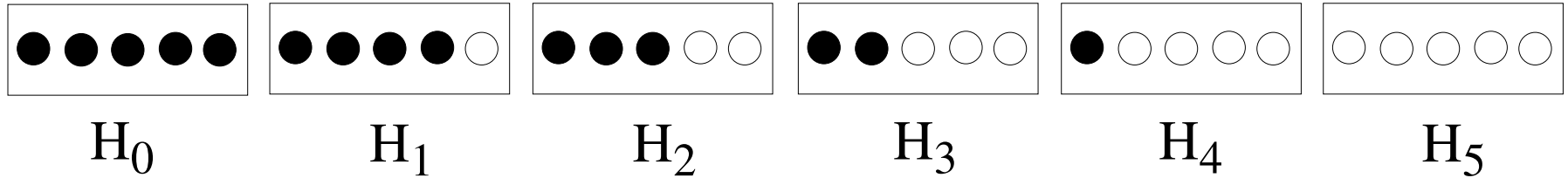
- x is binary:

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$[(1, 2); \text{Black/White}; \text{Yes/Not}; \dots]$

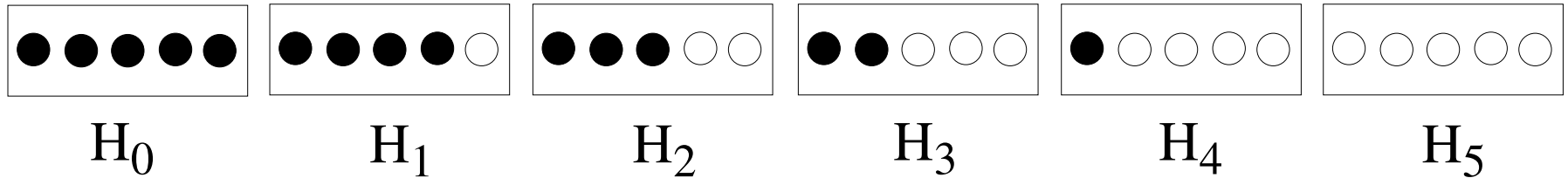
\Rightarrow Later we shall make μ continuous.

Which box? Which ball?



Let us take randomly one of the boxes.

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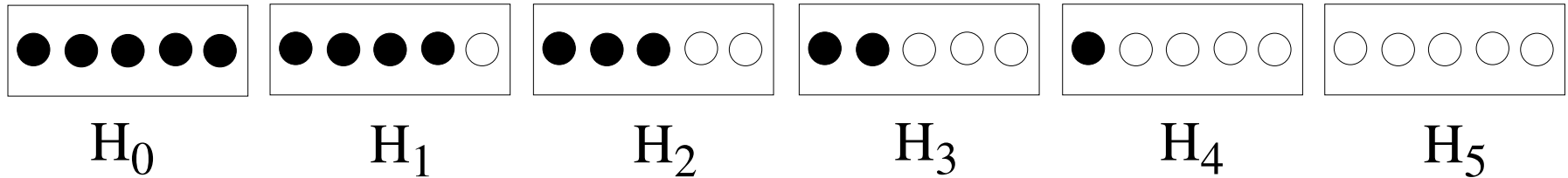
We are in a state of uncertainty concerning several *events*, the most important of which correspond to the following questions:

- (a) Which box have we chosen, H_0, H_1, \dots, H_5 ?
- (b) If we extract randomly a ball from the chosen box, will we observe a white ($E_W \equiv E_1$) or black ($E_B \equiv E_2$) ball?

Our certainties:

$$\bigcup_{j=0}^5 H_j = \Omega$$
$$\bigcup_{i=1}^2 E_i = \Omega.$$

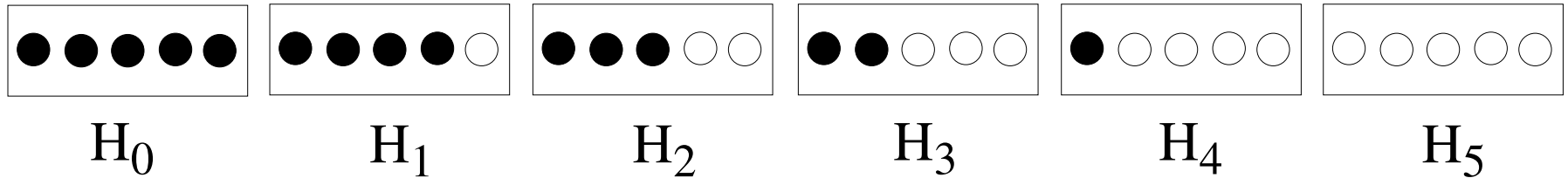
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Let us take randomly one of the boxes.

- What happens after we have extracted one ball and looked its color?
 - Intuitively feel *how to roughly change* our opinion about
 - the possible cause
 - a future observation

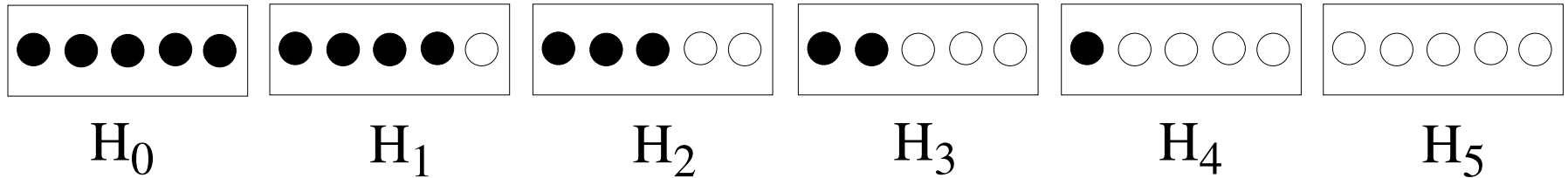
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 - Intuitively feel *how to roughly change* our opinion about
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 - a future observation
 - Can we do it *quantitatively*, in an ‘objective way’?
- And after a sequence of extractions?

The toy inferential experiment

The aim of the experiment will be to **guess** the content of the box **without looking inside it**, only extracting a ball, record its color and reintroducing in the box

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This toy experiment is conceptually very close to what we do in Physics

⇒ try to guess what we cannot see (the electron mass, a branching ratio, etc)

... from what we can see (somehow) with our senses.

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The rule of the game is that **we are not allowed to watch inside the box!** (As **we cannot open a neutrino and 'read' its properties**, unlike we read the MAC address of a network interface.)

Where is probability?

We all agree that the **experimental results change**

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Where is the probability?

Certainly not *in* the box!

Subjective nature of probability

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Probability depends on **the status of information of the *subject*** who evaluates it.

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$$P(E) \longrightarrow P(E | I_s)$$

where I_s is the information available to *subject* s .

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⇒ **How much we believe something**

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→ ‘Degree of belief’ ←

Beliefs and 'coherent' bets

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“The usual touchstone, whether that which someone asserts is merely his persuasion – or at least his subjective conviction, that is, his firm belief – is betting. It often happens that someone propounds his views with such positive and uncompromising assurance that he seems to have entirely set aside all thought of possible error. A bet disconcerts him. Sometimes it turns out that he has a conviction which can be estimated at a value of one ducat, but not of ten. For he is very willing to venture one ducat, but when it is a question of ten he becomes aware, as he had not previously been, that it may very well be that he is in error.” (Kant)

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 - you state the **odds** according on your beliefs;
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“His [Bouvard] calculations give him the mass of Saturn as 3,512th part of that of the sun. Applying my probabilistic formulae to these observations, I find that the **odds are 11,000 to 1** that the error in this result is not a hundredth of its value.” (Laplace)

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$$\rightarrow P(3477 \leq M_{Sun}/M_{Sat} \leq 3547 | I(\text{Laplace})) = 99.99\%$$

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- It does not imply one has to be 95% confident on something!
- If you do so you are going to make a bad bet!

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For more on the subject

see <http://arxiv.org/abs/1112.3620>

and references therein.

Unifying role of subjective probability

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- Probability statements all have the same meaning no matter to what they refer and how the number has been evaluated.
 - $P(\text{Rain next Saturday in Hamburg}) = 68\%$
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They all convey unambiguously the same confidence on something.

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 - You might agree or disagree, but at least You know what this person has in his mind. (NOT TRUE with “C.L.’s”!)
 - If a person has these beliefs and he/she has the chance to win a rich prize bound to one of these events, he/she is **indifferent to the choice**.
-

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We can talk very naturally about
probabilities of true values!

Probability Vs “probability”...

Errors on ratios of small numbers of events

F. James^(*) and M. Roos

Nucl. Phys. **B172** (1980) 475

(http://ccdb4fs.kek.jp/cgi-bin/img_index?8101205)

When the result of the measurement of a physical quantity is published as $R=R_0 \pm \sigma_0$ without further explanation, it is implied that R is a Gaussian-distributed measurement with mean R_0 and variance σ_0^2 . This allows one to calculate various confidence intervals of given "probability", i.e. the "probability" P that the true value of R is within a given interval. P is given by the area under the corresponding part of the Gaussian curve, and is the basis of well-known rules-of-thumb such as "the probability of exceeding two standard deviations is 5%".

(*) Influential CERN 'frequentistic guru' of HEP community

Mathematics of beliefs

The good news:

The basic laws of degrees of belief are the same we get from the inventory of favorable and possible cases, or from events occurred in the past.

[Details skipped...]

Basic rules of probability

1. $0 \leq P(A | I) \leq 1$
2. $P(\Omega | I) = 1$
3. $P(A \cup B | I) = P(A | I) + P(B | I)$ [if $P(A \cap B | I) = \emptyset$]
4. $P(A \cap B | I) = P(A | B, I) \cdot P(B | I) = P(B | A, I) \cdot P(A | I)$

Remember that probability is always conditional probability!

I is the background condition (related to information ' I'_s ')

→ usually implicit (we only care of 're-conditioning')

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Note: 4. does not define conditional probability.
(Probability is always conditional probability!)

Mathematics of beliefs

An even better news:

The fourth basic rule
can be fully exploited!

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The fourth basic rule
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(Liberated by a **curious ideology** that forbids its use)

A simple, powerful formula

$$\mathbb{P}(A|B) = \frac{\mathbb{P}(B|A) \mathbb{P}(A)}{\mathbb{P}(B)}$$

A simple, powerful formula

$$P(A | B | I) P(B | I) = P(B | A, I) P(A | I)$$

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Take the courage to use it!

A simple, powerful formula

$$\mathbb{P}(A|B) = \frac{\mathbb{P}(B|A) \mathbb{P}(A)}{\mathbb{P}(B)}$$

It's easy if you try...!

Laplace's "Bayes Theorem"

“The greater the probability of an observed event given any one of a number of causes to which that event may be attributed, the greater the likelihood of that cause {given that event}.

$$P(C_i | E) \propto P(E | C_i)$$

Laplace's "Bayes Theorem"

“The greater the probability of an observed event given any one of a number of causes to which that event may be attributed, the greater the likelihood of that cause {given that event}. The probability of the existence of any one of these causes {given the event} is thus a fraction whose numerator is the probability of the event given the cause, and whose denominator is the sum of similar probabilities, summed over all causes.

$$P(C_i | E) = \frac{P(E | C_i)}{\sum_j P(E | C_j)}$$

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$$P(C_i | E) = \frac{P(E | C_i) P(C_i)}{\sum_j P(E | C_j) P(C_j)}$$

“This is the **fundamental principle (*)** of that branch of the analysis of chance that consists of reasoning *a posteriori* **from events to causes**”

(*) In his “Philosophical essay” Laplace calls ‘principles’ the ‘fondamental rules’.

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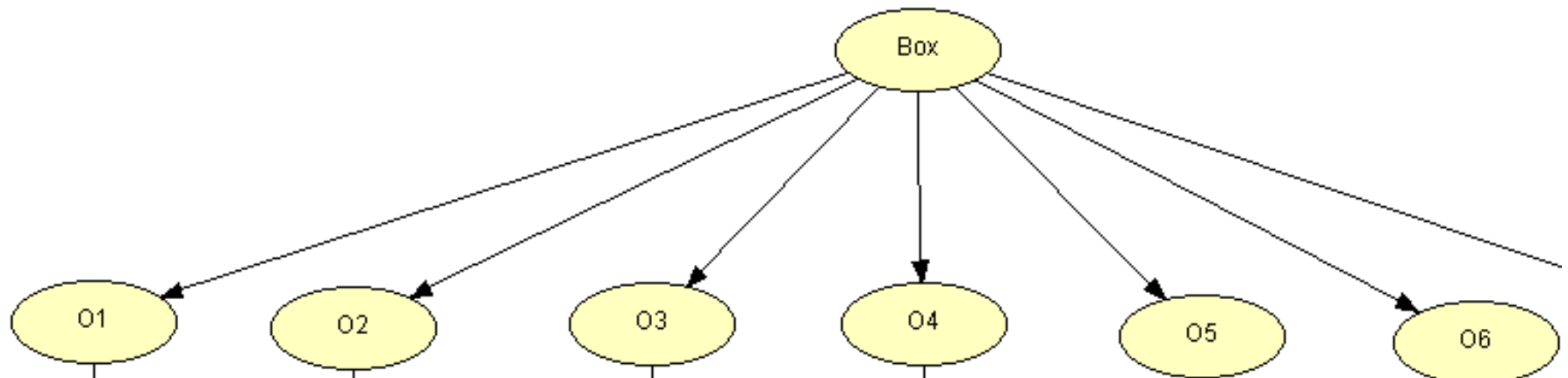
Note: denominator is just a normalization factor.

$$\Rightarrow P(C_i | E) \propto P(E | C_i) P(C_i)$$

Most convenient way to remember Bayes theorem

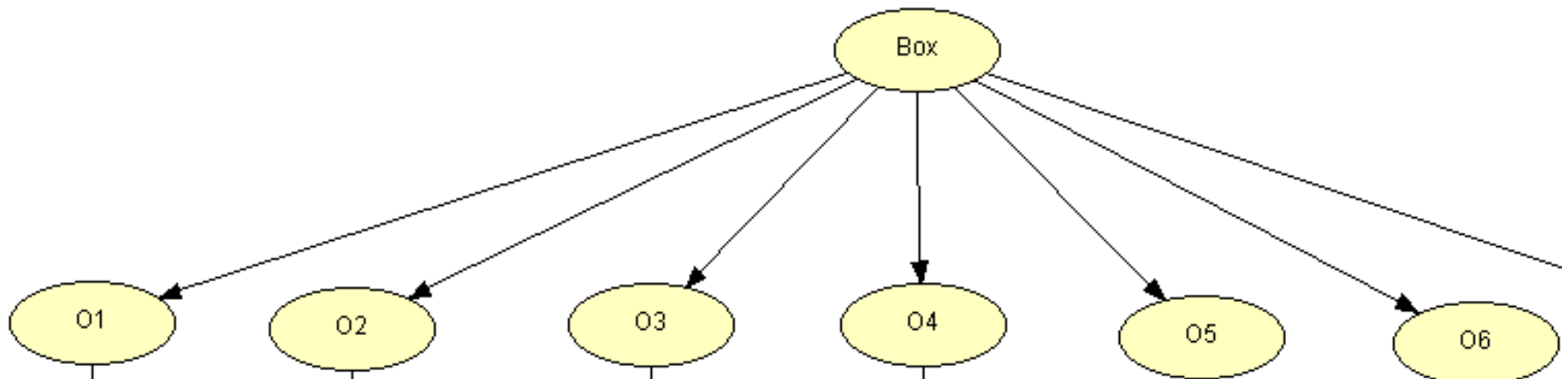
Cause-effect representation

box content \rightarrow observed color



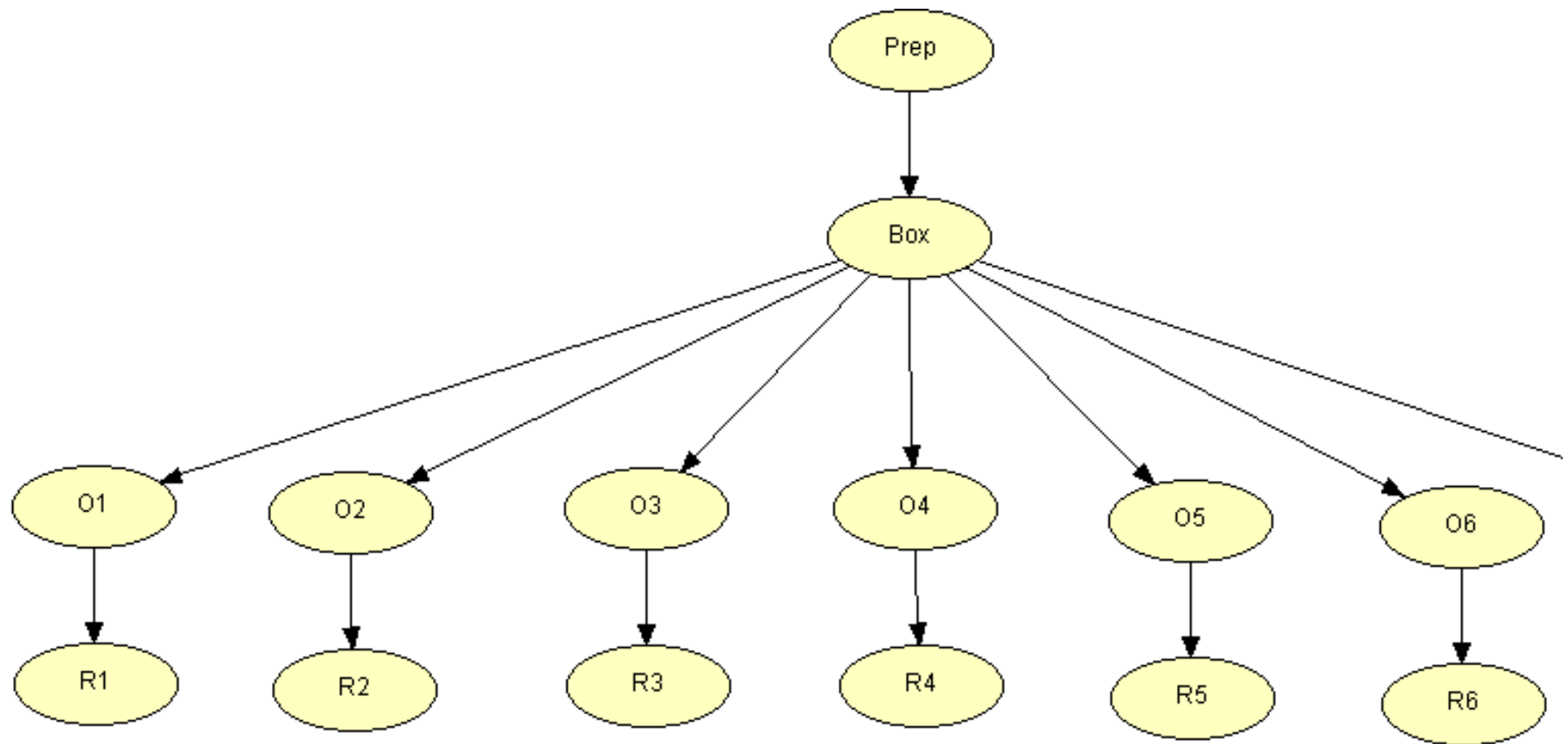
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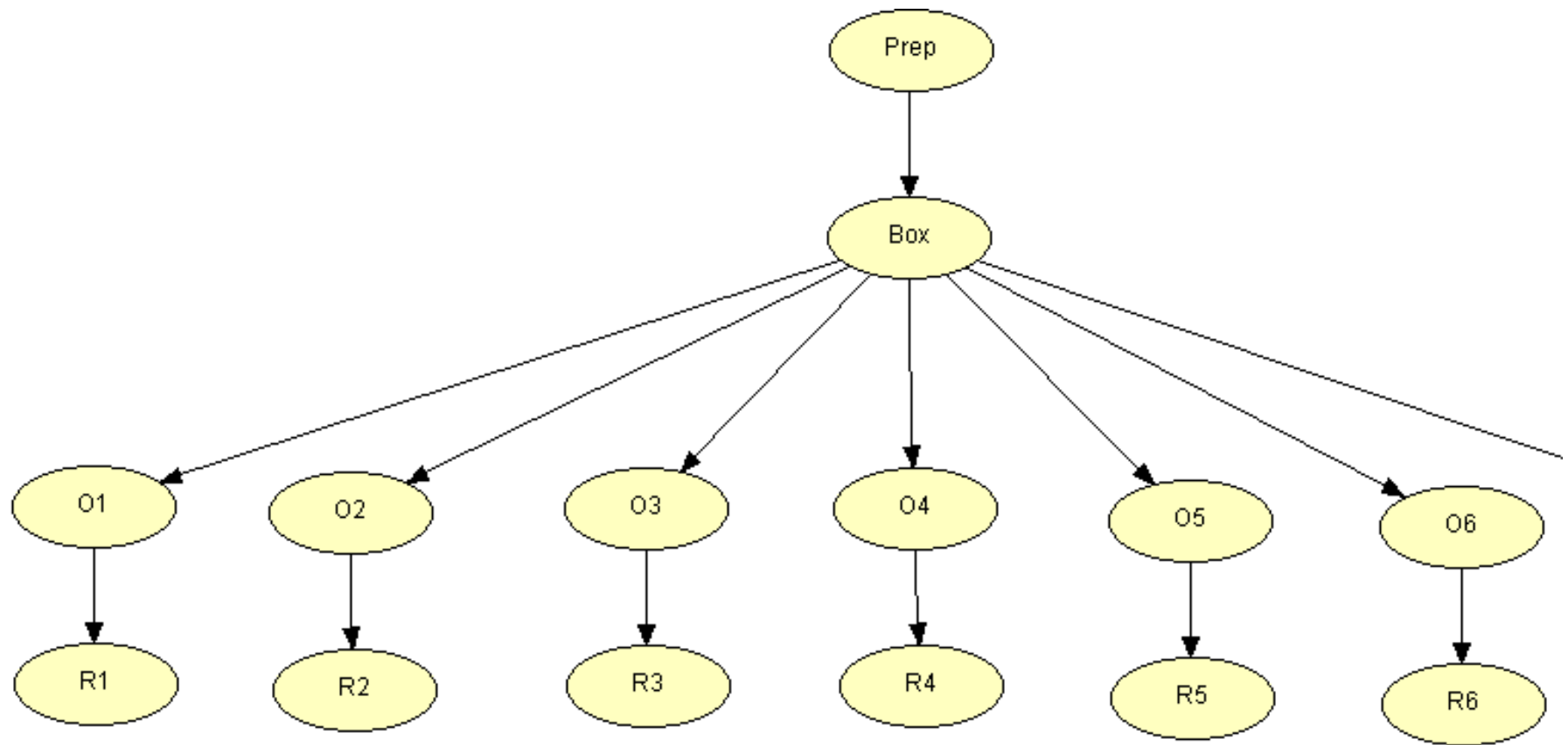


An effect might be the cause of another effect \Rightarrow

A network of causes and effects



A network of causes and effects



and so on...

⇒ Physics applications

Inferring 'proportions'

Let's turn the toy experiment to a 'serious' physics case:

- Inferring H_j is the same as inferring the proportion of white balls:

$$H_j \longleftrightarrow j \longleftrightarrow p = \frac{j}{5}$$

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$$n : 6 \rightarrow \infty$$

$\Rightarrow p$ continuous in $[0, 1]$

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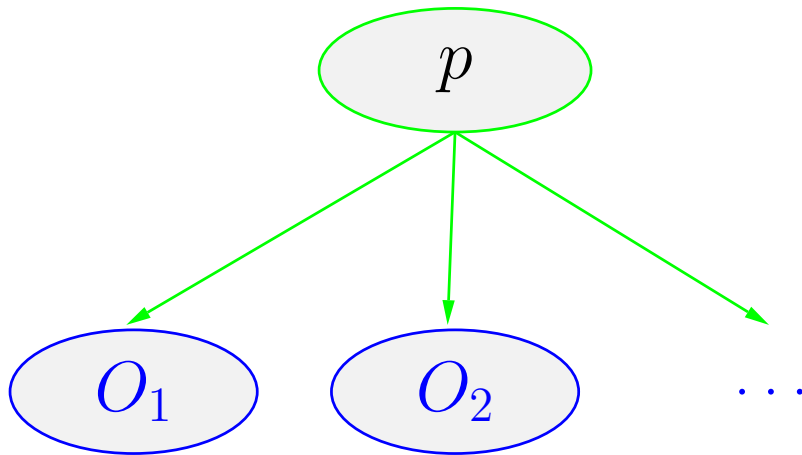
⇒ p continuous in $[0, 1]$

- Generalize White/Black → Success/Failure

⇒ efficiencies, branching ratios, . . .

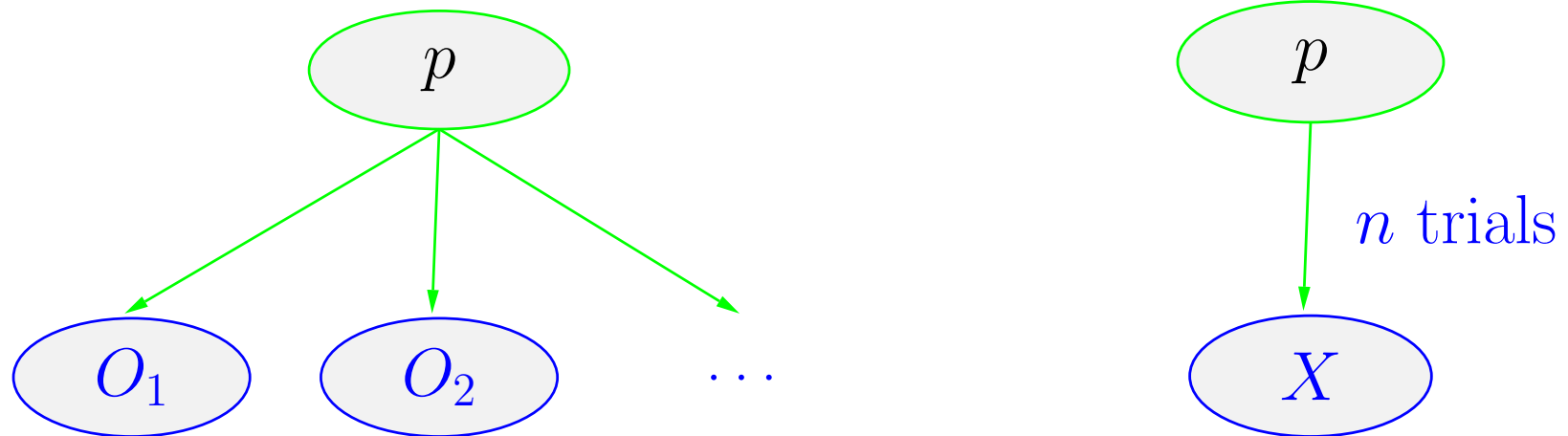
Inferring Bernoulli's trial parameter p

Making several independent trials *assuming* the same p



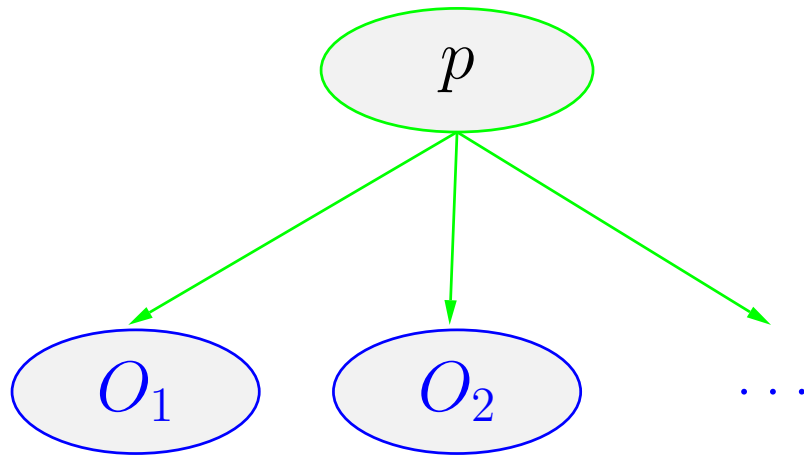
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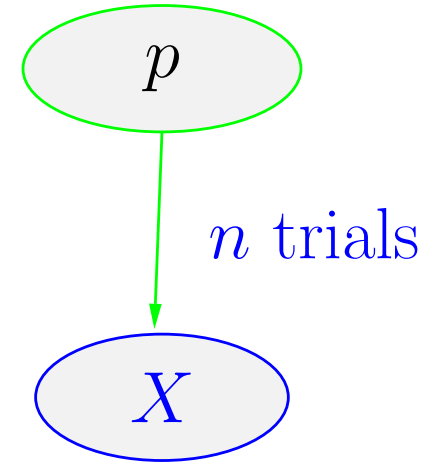


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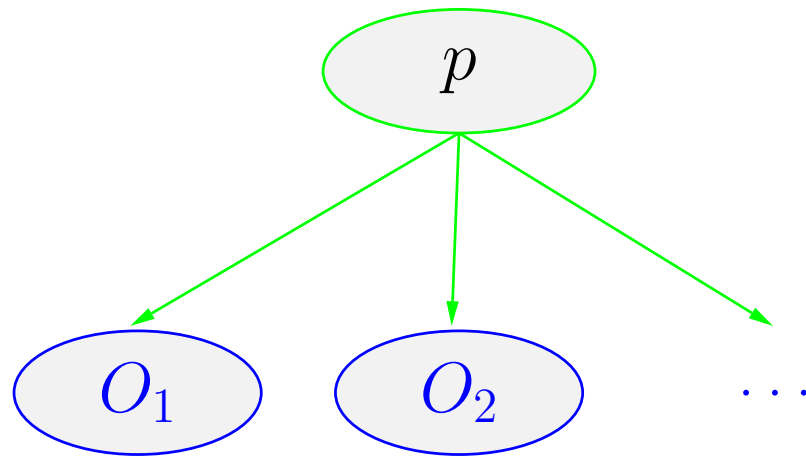
“independent Bernoulli trials”



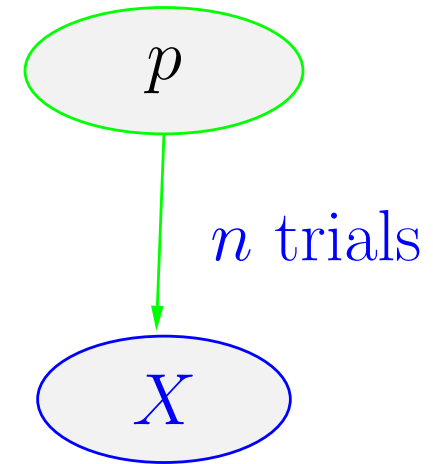
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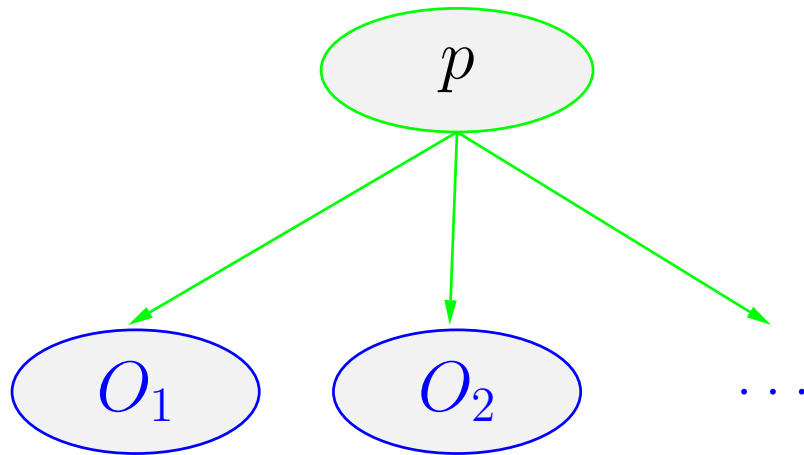


“binomial distribution”

⇒ In the light of the experimental information
there will be values of p we shall believe more,
and others we shall believe less.

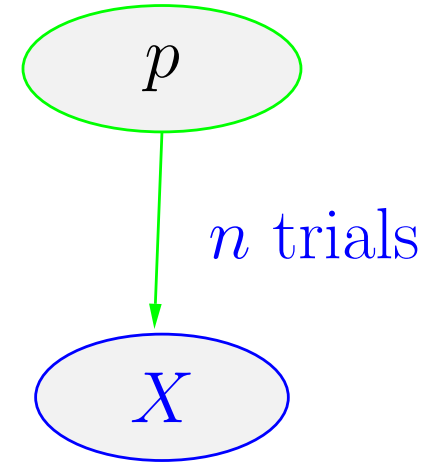
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“independent Bernoulli trials”

$$P(p_i | O_1, O_2, \dots)$$
$$f(p | O_1, O_2, \dots)$$

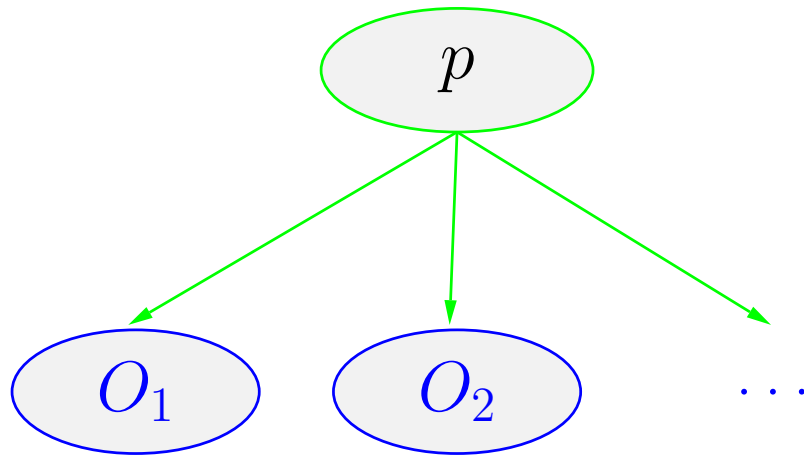


“binomial distribution”

$$P(p_i | X, n)$$
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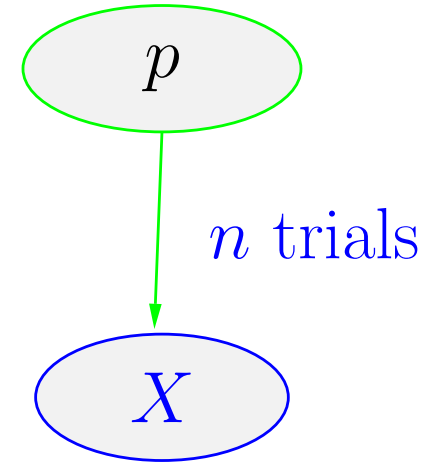
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$$P(p_i | O_1, O_2, \dots)$$
$$f(p | O_1, O_2, \dots)$$

$$\propto f(O_1, O_2, \dots | p) \cdot f_0(p)$$



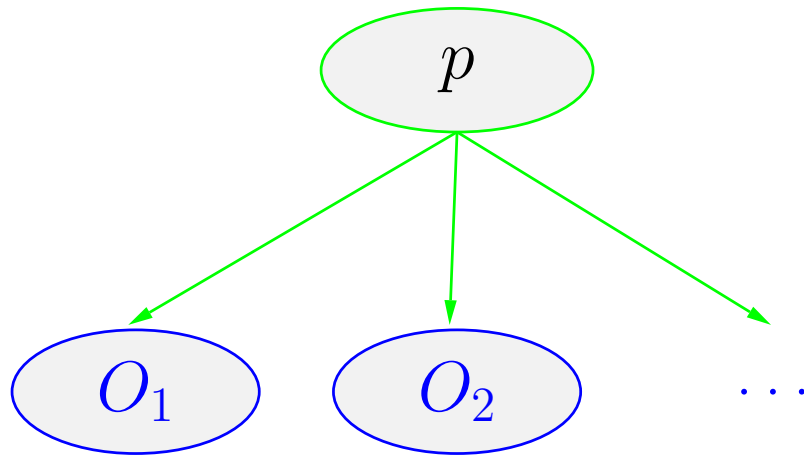
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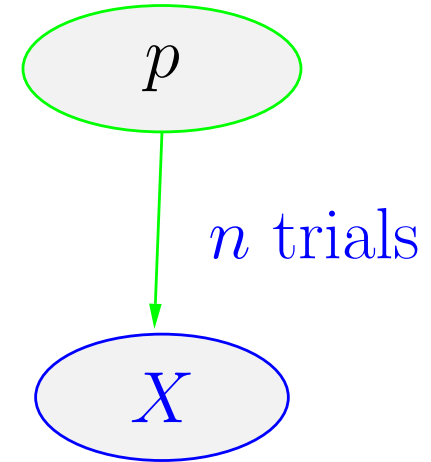
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$$P(p_i | X, n)$$
$$f(p | X, n)$$

Are the two inferences the same?
(not obvious in principle)

Graphical models

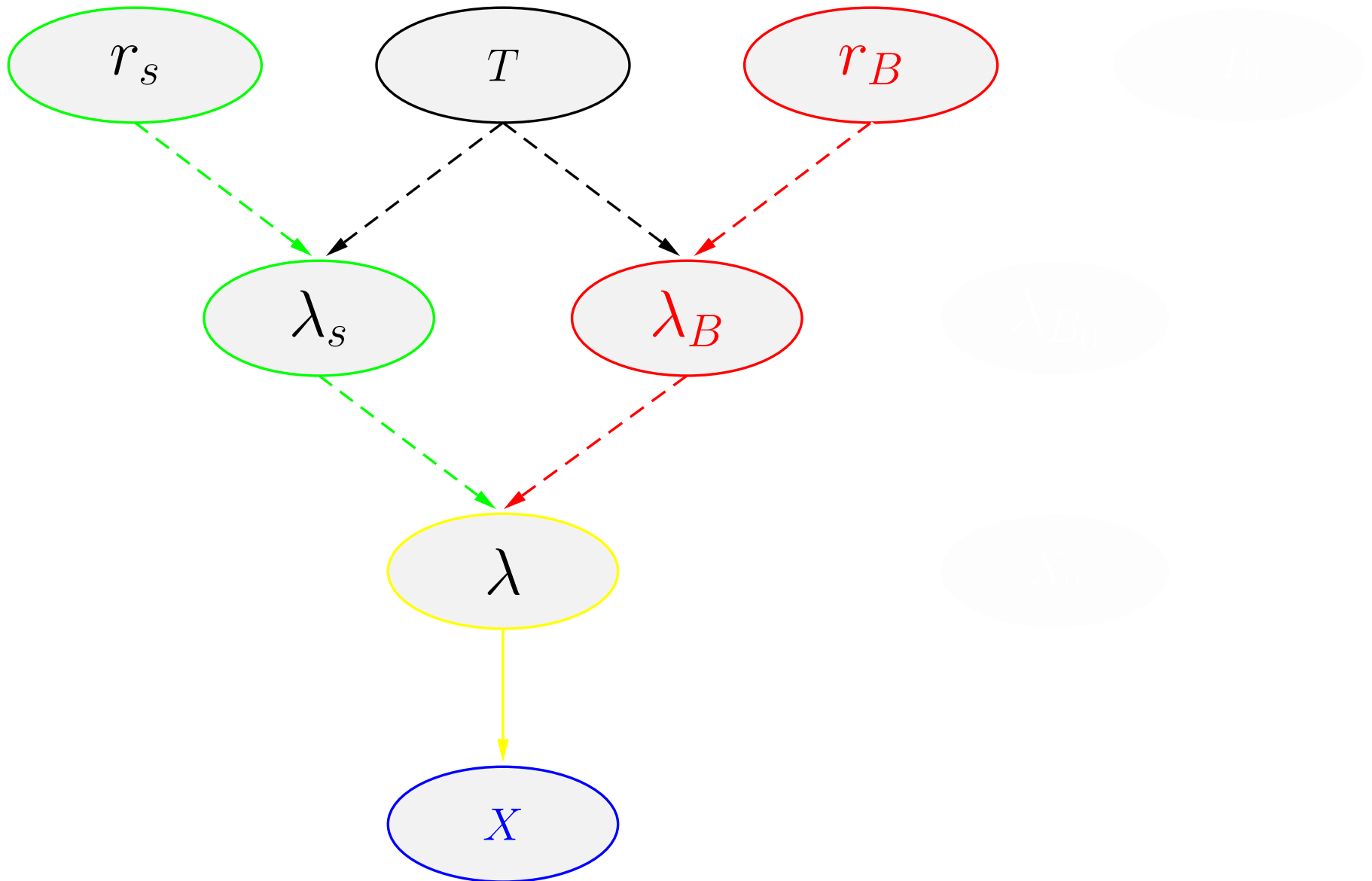
Before analysing in some detail this case let's make an overview of other important cases in physics

Graphical models

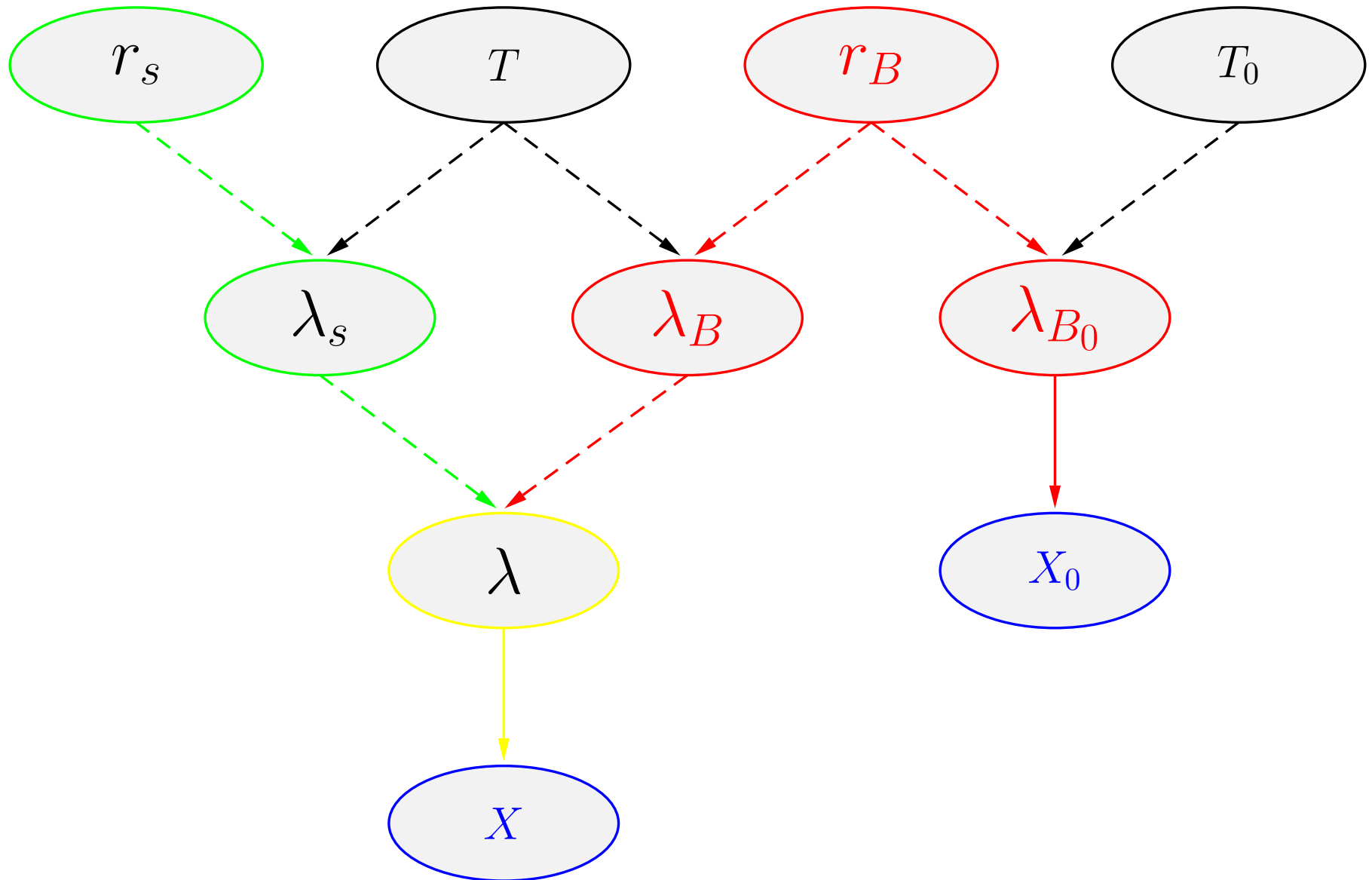
Before analysing in some detail this case let's make an overview of other important cases in physics

⇒ Nowadays, thanks to progresses in mathematics and computing, **drawing the problem as a 'belief network'** is more than 1/2 step towards its solution!

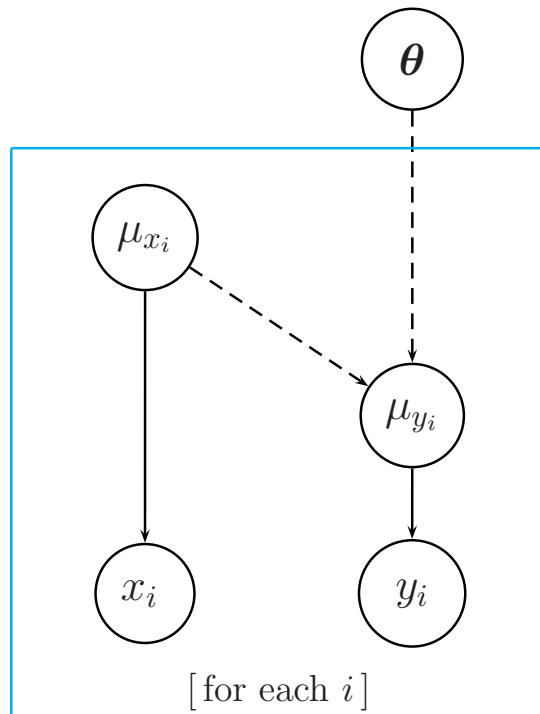
Signal and background



Signal and background



A different way to view fit issues



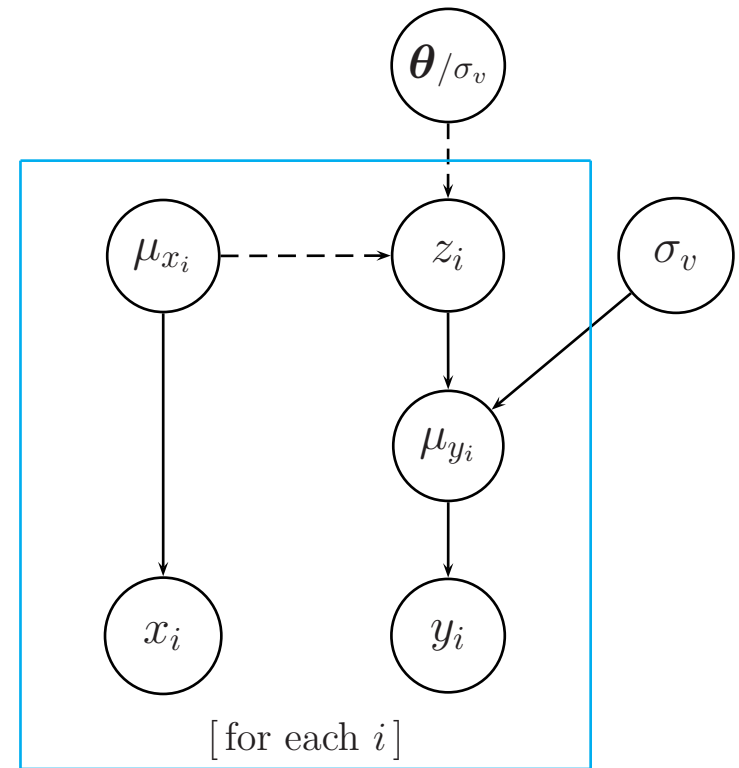
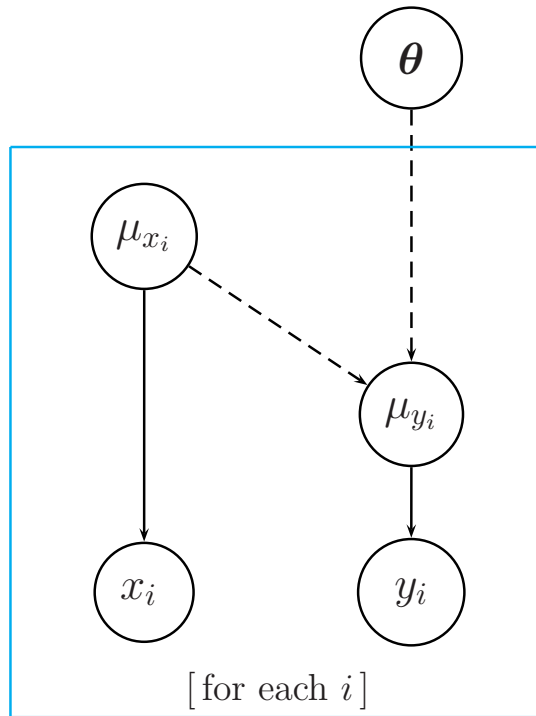
Deterministic link μ_x 's to μ_y 's

Probabilistic links $\mu_x \rightarrow x, \mu_y \rightarrow y$

(errors on both axes!)

\Rightarrow aim of fit: $\{x, y\} \rightarrow \theta$

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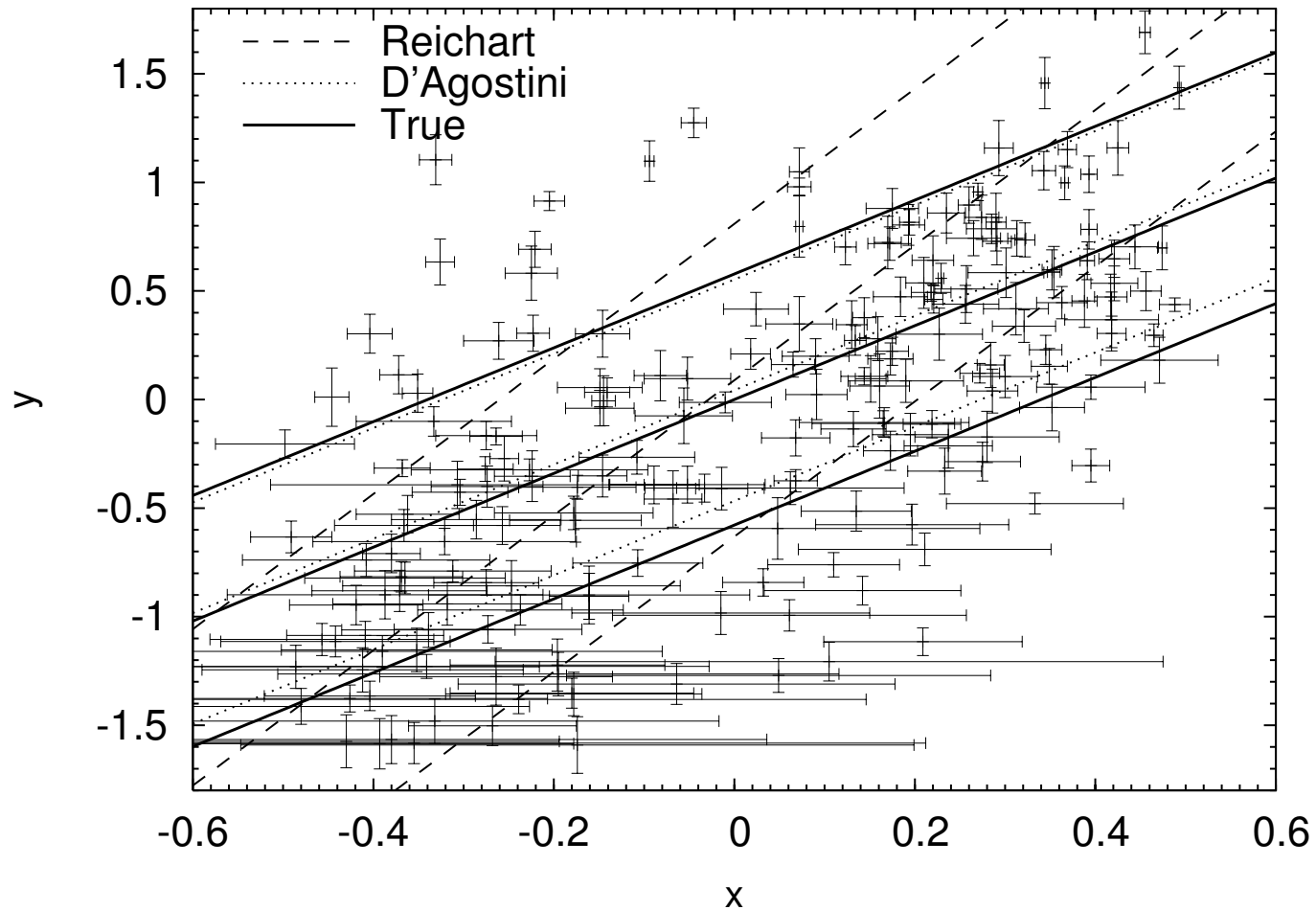
\Rightarrow aim of fit: $\{x, y\} \rightarrow \theta$

Extra spread

of the data points

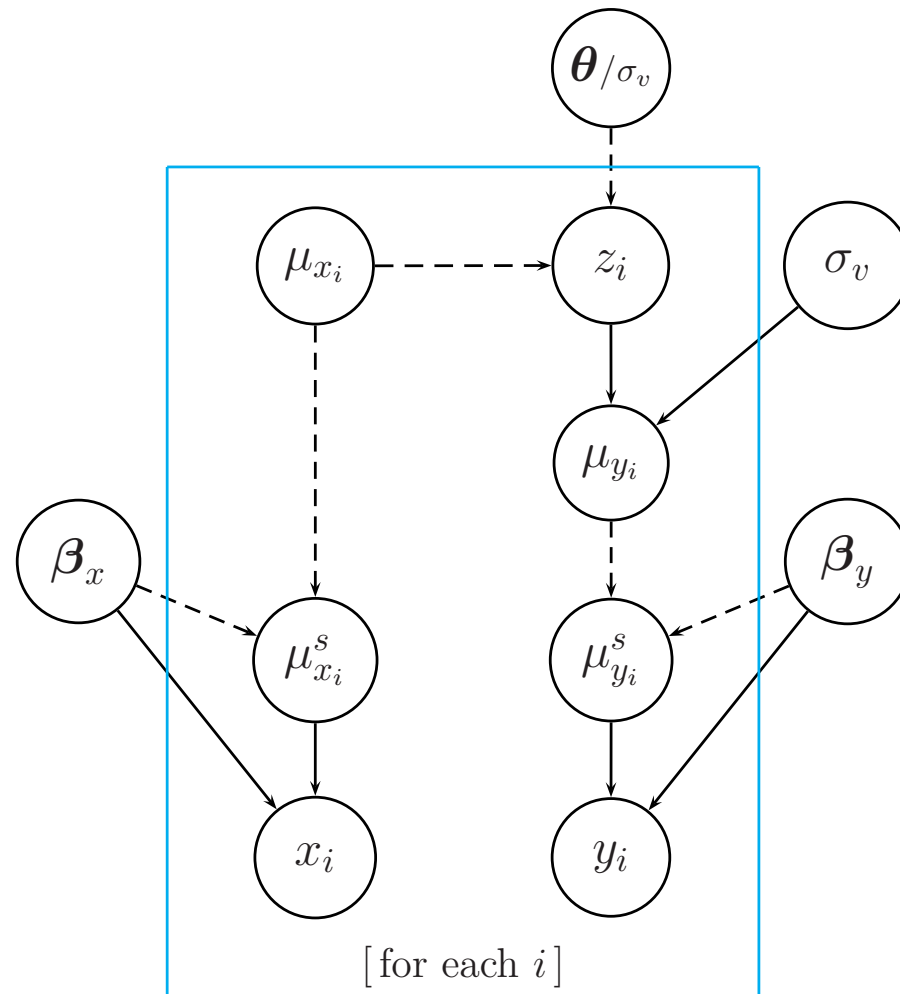
A different way to view fit issues

A physics case (from Gamma ray burts):



(Guidorzi et al., 2006)

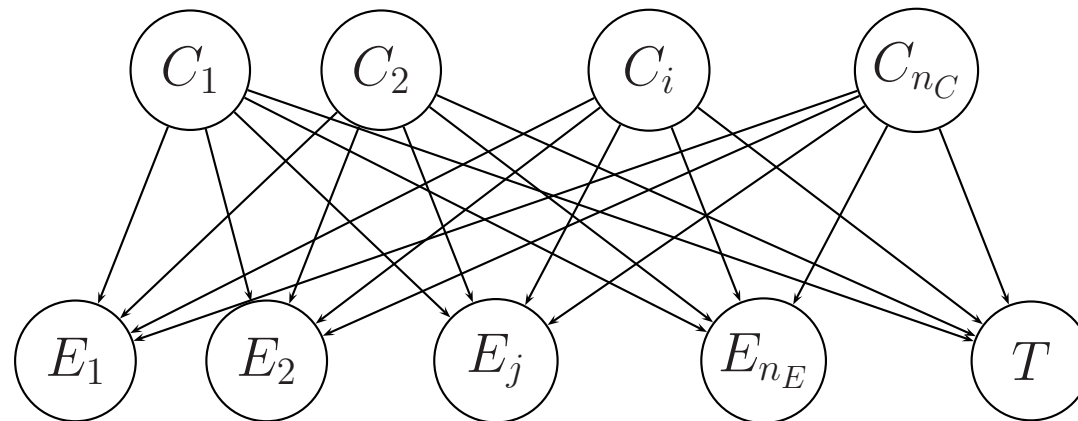
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Adding systematics

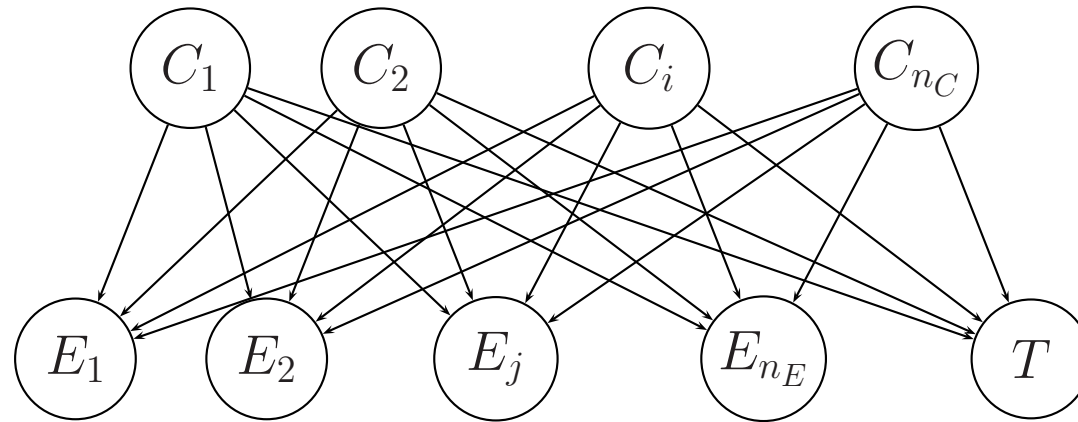
Unfolding a discretized spectrum

Probabilistic links: Cause-bins \leftrightarrow effect-bins

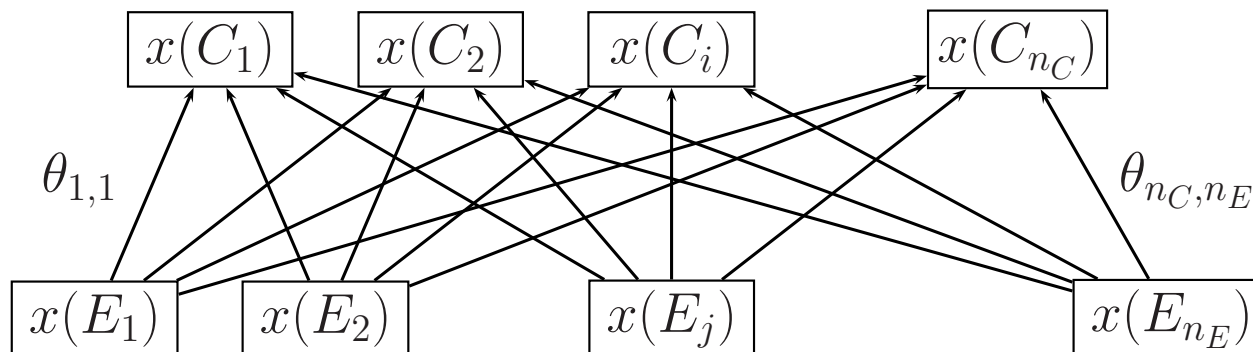


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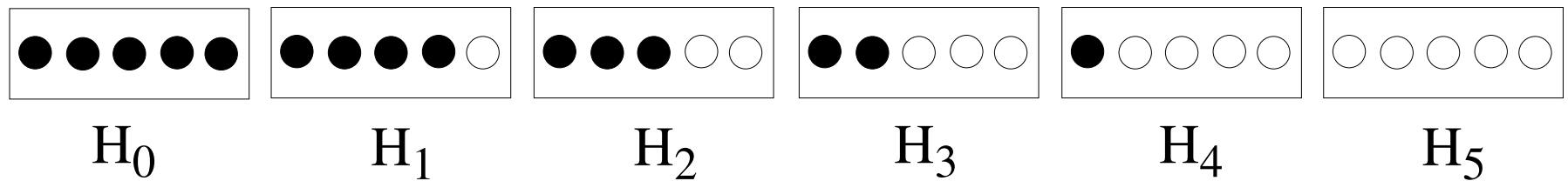
Probabilistic links: Cause-bins \leftrightarrow effect-bins



Sharing the observed events among the cause-bins



Application to the six box problem



Remind:

- $E_1 = \text{White}$
- $E_2 = \text{Black}$

Collecting the pieces of information we need

Our tool:

$$P(H_j | E_i, I) = \frac{P(E_i | H_j, I)}{P(E_i | I)} P(H_j | I)$$

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Our **prior** belief about H_j

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Probability of E_i under a well defined hypothesis H_j
It corresponds to the 'response of the apparatus in measurements.

→ **likelihood** (traditional, rather confusing name!)

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→ How much we are confident that E_i will occur.

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We can rewrite it as

$$P(E_i | I) = \sum_j P(E_i | H_j, I) \cdot P(H_j | I)$$

We are ready

Now that we have set up our formalism, let's play a little

- analyse real data
- some simulations

Then

- $H_j \longleftrightarrow j \longleftrightarrow p_j$
- extending p to a continuum:
⇒ Bayes' billiard
(prototype for all questions related to efficiencies,
branching ratios)
- On the meaning of p

Bayes' billiard

This is the original problem in the theory of chances solved by Thomas Bayes in late '700:

- imagine you roll a ball at random on a billiard;
- you mark the relative position of the ball along the billiard's length (l/L) and remove the ball
- then you roll at random other balls
 - write down if it stopped left or right of the first ball;
 - remove it and go on with n balls.
- Somebody has to guess the position of the first ball knowing only how many balls stopped left and how many stopped right

Bayes' billiard and Bernoulli trials

It is easy to recognize the analogy:

- Left/Right \rightarrow Success/Failure
- if Left \leftrightarrow Success:
 - $l/L \leftrightarrow p$ of binomial (Bernoulli trials)

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...

$$f(p | \#S, \#F) \propto p^{\#S} (1 - p)^{\#F} = p^{\#S} (1 - p)^{(1 - \#s)}$$

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$$f(p | \#S, \#F) \propto p^{\#S} (1 - p)^{\#F} = p^{\#S} (1 - p)^{(1-\#s)}$$

$$f(p | x, n) \propto p^x (1 - p)^{(n-x)} \quad [x = \#S]$$

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The main difficulty with probability is that since ever it has embedded two different meanings:

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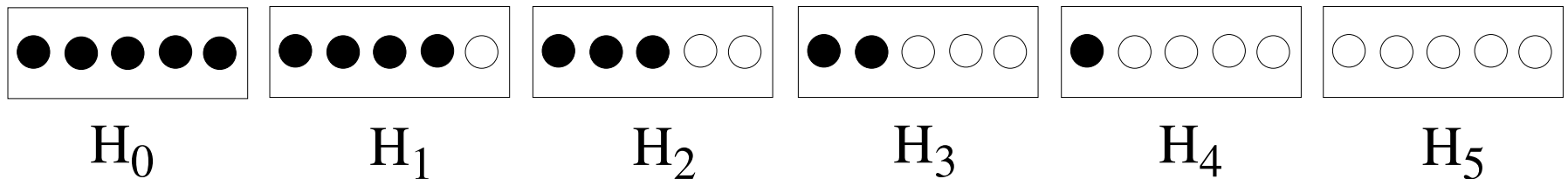
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The six box model can help to make the question clear.



Degree of belief Vs 'propension'

- There is no problem to interpret the **proportion** p of white balls as a **propensity** of a box to yield white balls.

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- If, under this assumption, we imagine a great number of trials, we expect a relative frequency of white equal to $P(W | p)$ [**Bernoulli's Theorem**]:

$$" \lim_{n \rightarrow \infty} f_n(W | p) " = P(W | p) = p$$

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There is no need to adhere to the frequentistic ideology to say this

Degree of belief Vs ‘propension’

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Instead, “probability is the limit of frequency for $n \rightarrow \infty$ ” is not more than an empty statement.

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Probability theory (in Laplace’s sense) allows to **attach probabilities to whatever we feel uncertain about!**

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- Other important parameters are related to background, systematics, 'etc.' [arguments not covered here]

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(Diffidate chi vi promette di far germogliar zecchini nel Campo dei Miracoli!)

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- Mistrust all results that sound as 'confidence', 'probability' etc about physics quantities, if they are obtained by methods that do not contemplate 'beliefs'.

The End

FINE