

Visualizing the internal structure of a cryptodome with cosmic ray muon radiography

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Imaging a thick target

thick →

Less muon after passing through the target

Short time →

Less muon



Exposure time should be longer



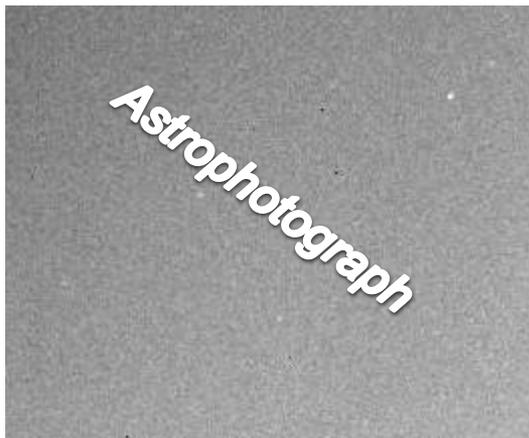
ISO3200
1 sec

Longer
Exposure
time

ISO3200
60 sec

If exposure time becomes longer noise become significant

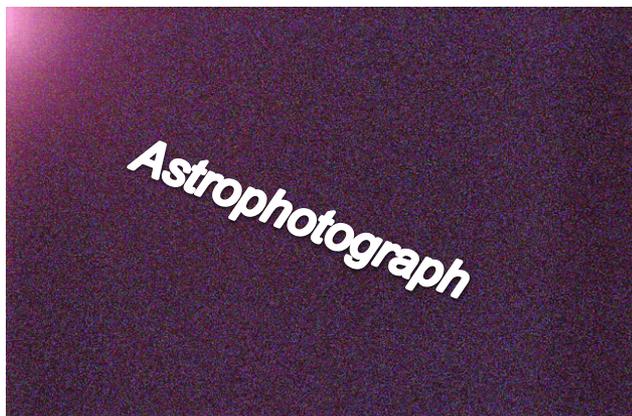
Uniform background



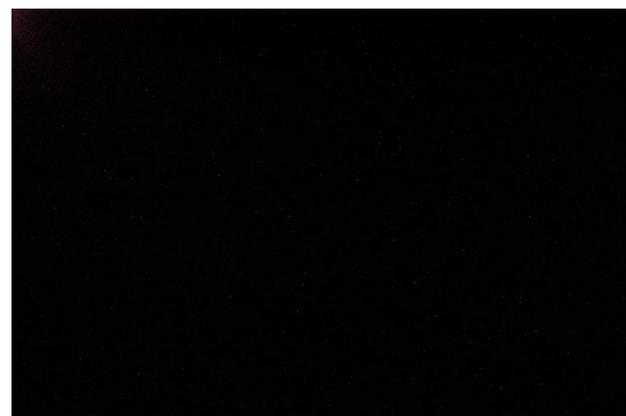
Noise
reduction →



Non-uniform background



Noise
reduction →



Sanyo Longtime exposure 180sec
ISO1600

Long time exposure 260 sec
ISO1600

When signal is sufficient

$$N > \Delta N$$

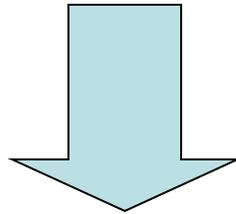
$$\sqrt{(N + \Delta N)} \sim \sqrt{N}$$

But if the target becomes thicker

$$N < \Delta N$$

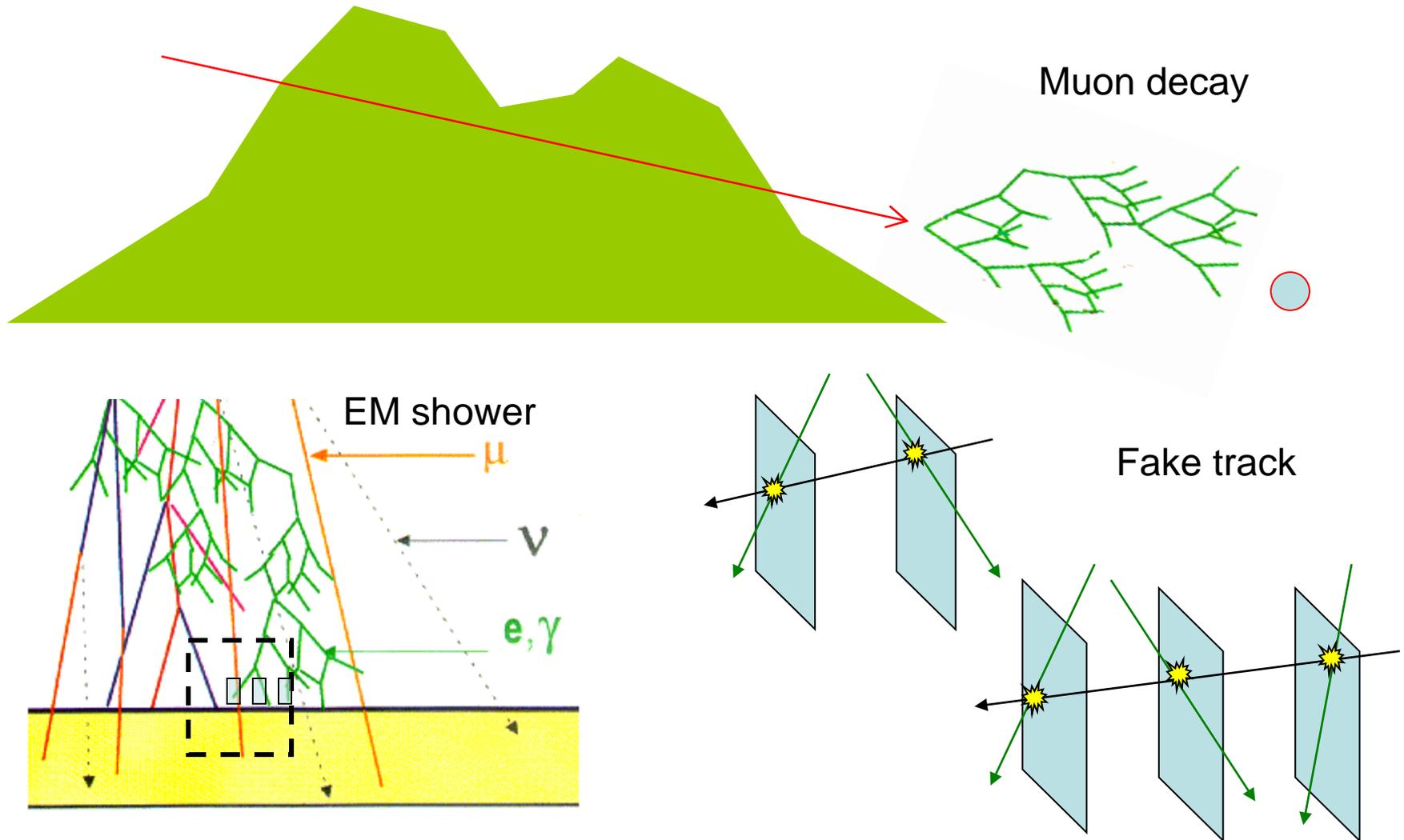
$$\sqrt{(N + \Delta N)} \sim \sqrt{\Delta N}$$

- When we reduce the noise level, weak muon can be seen
= We can shorten the observation time



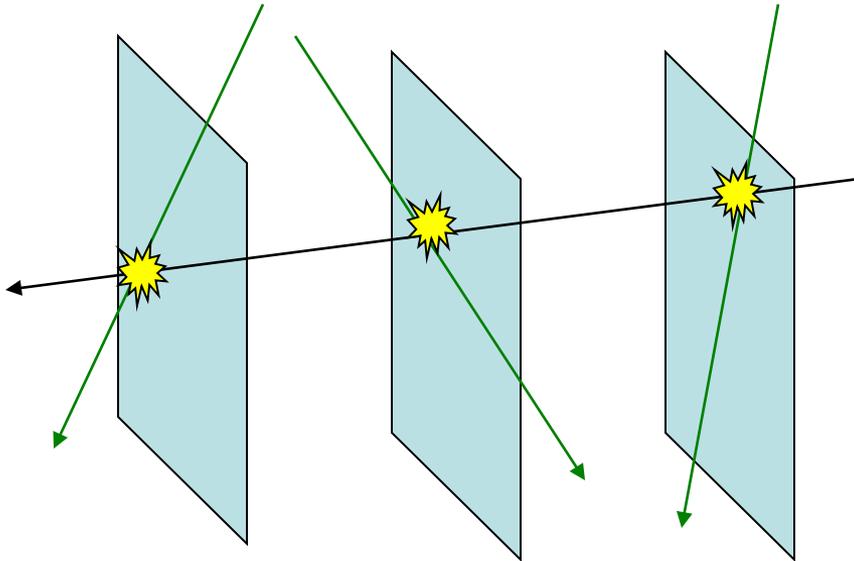
How to reduce the noise level?

Possible background source



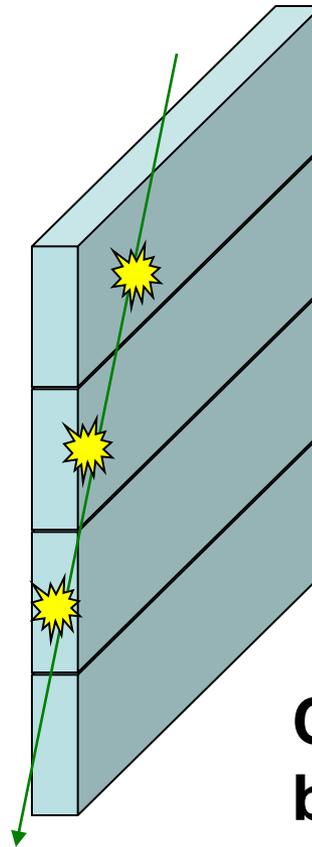
Removal of fake tracks

non-linearity cut



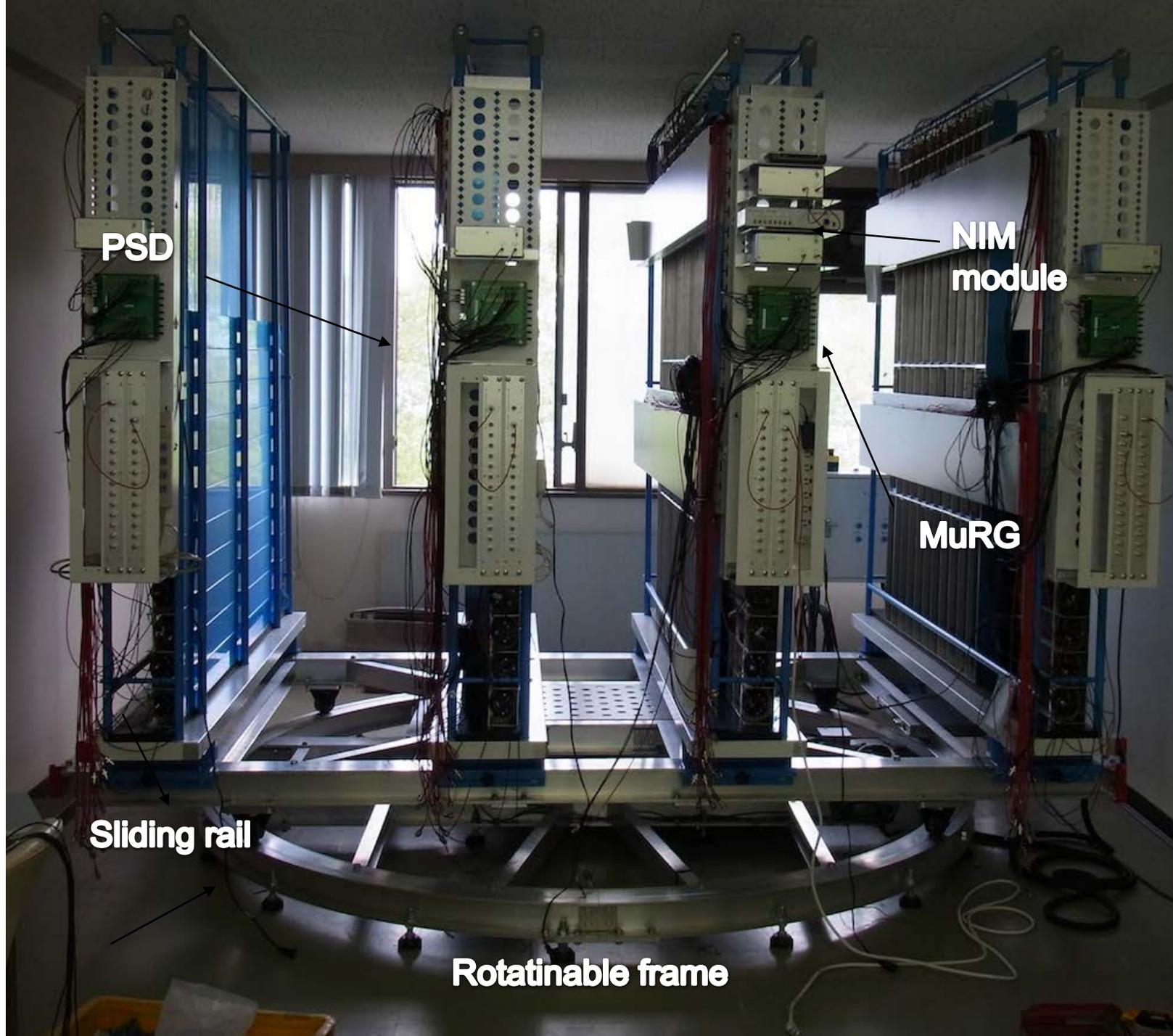
Pros: can reject events with wide range of incident angles.
Cons: cannot reject events making straight lines within the position resolution of the detector.

Multihit cut



Pros: can reject all events from vertical.
Cons: cannot reject events arriving the angle:
 $>(\text{thickness})/(\text{width})$

Combination of both methods



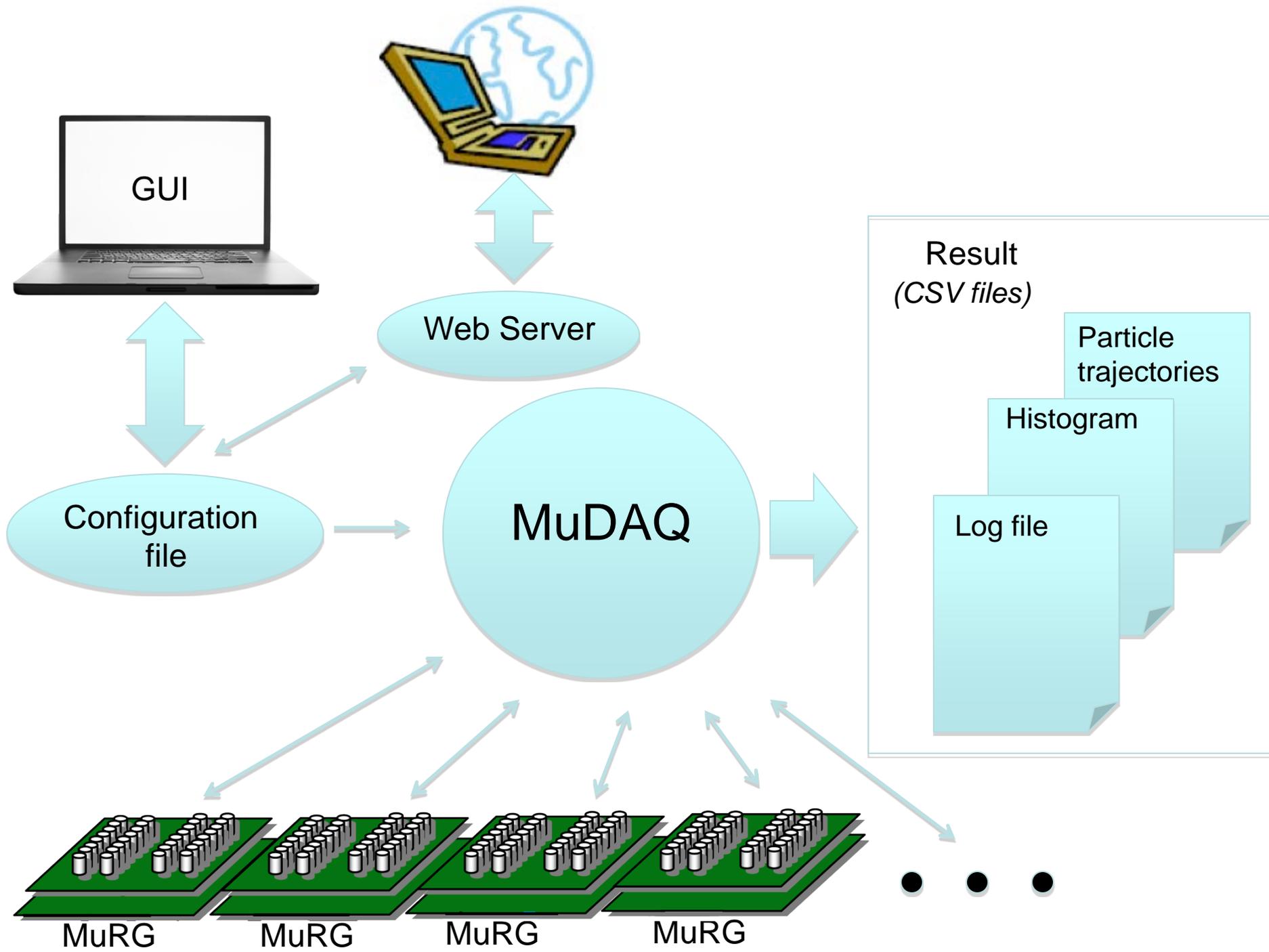
PSD

**NIM
module**

MuRG

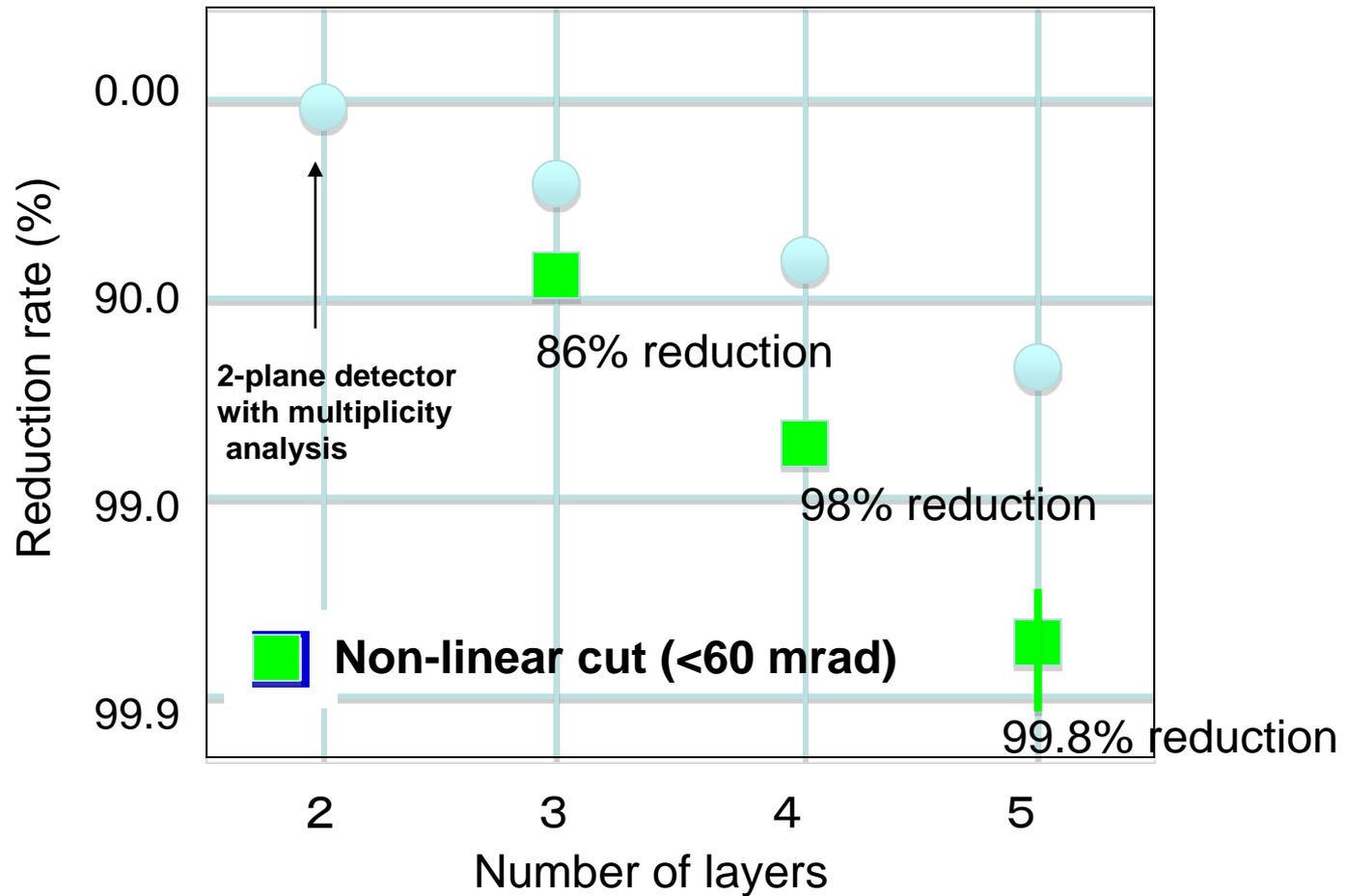
Sliding rail

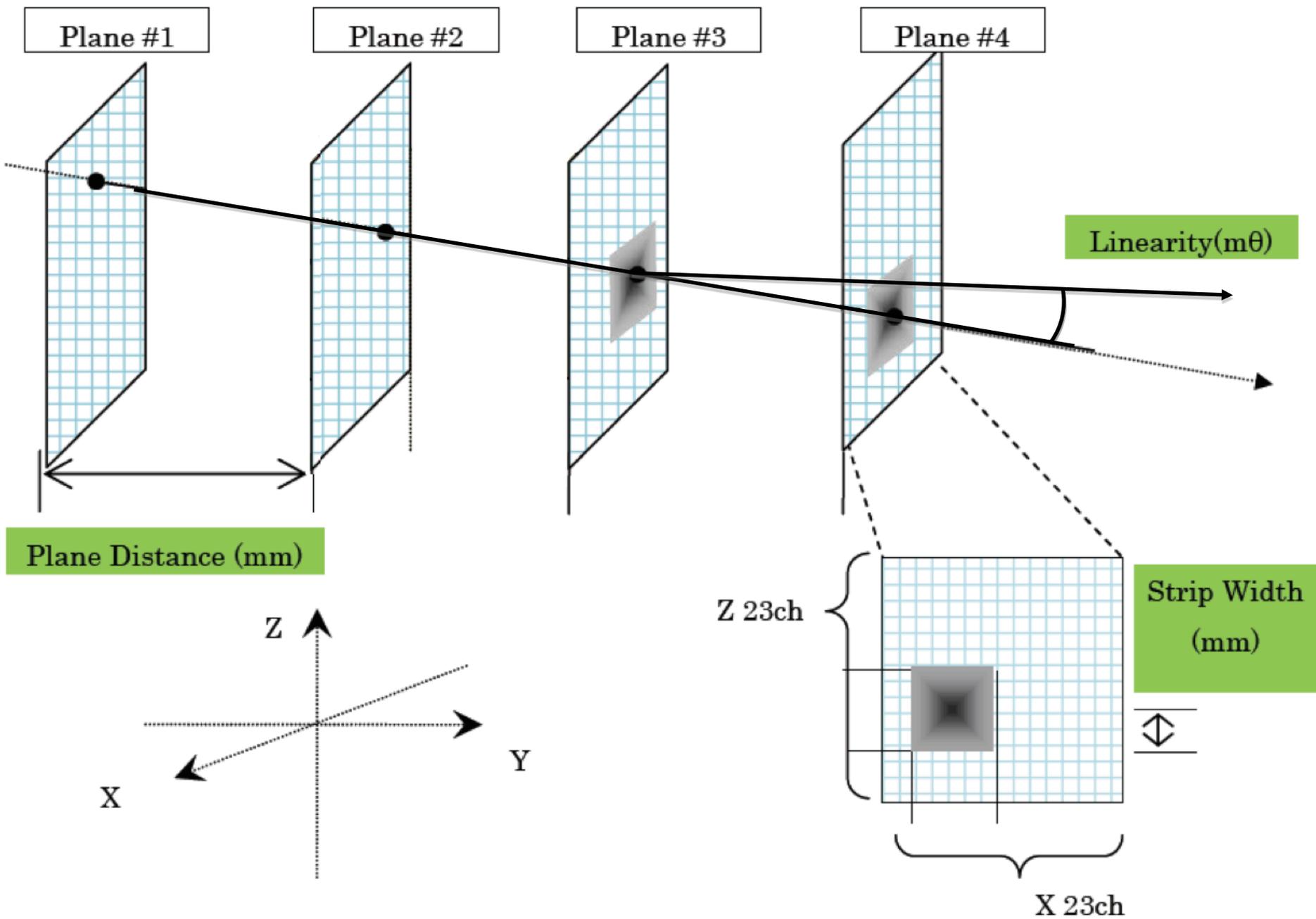
Rotatable frame



Layer number effect

1m²

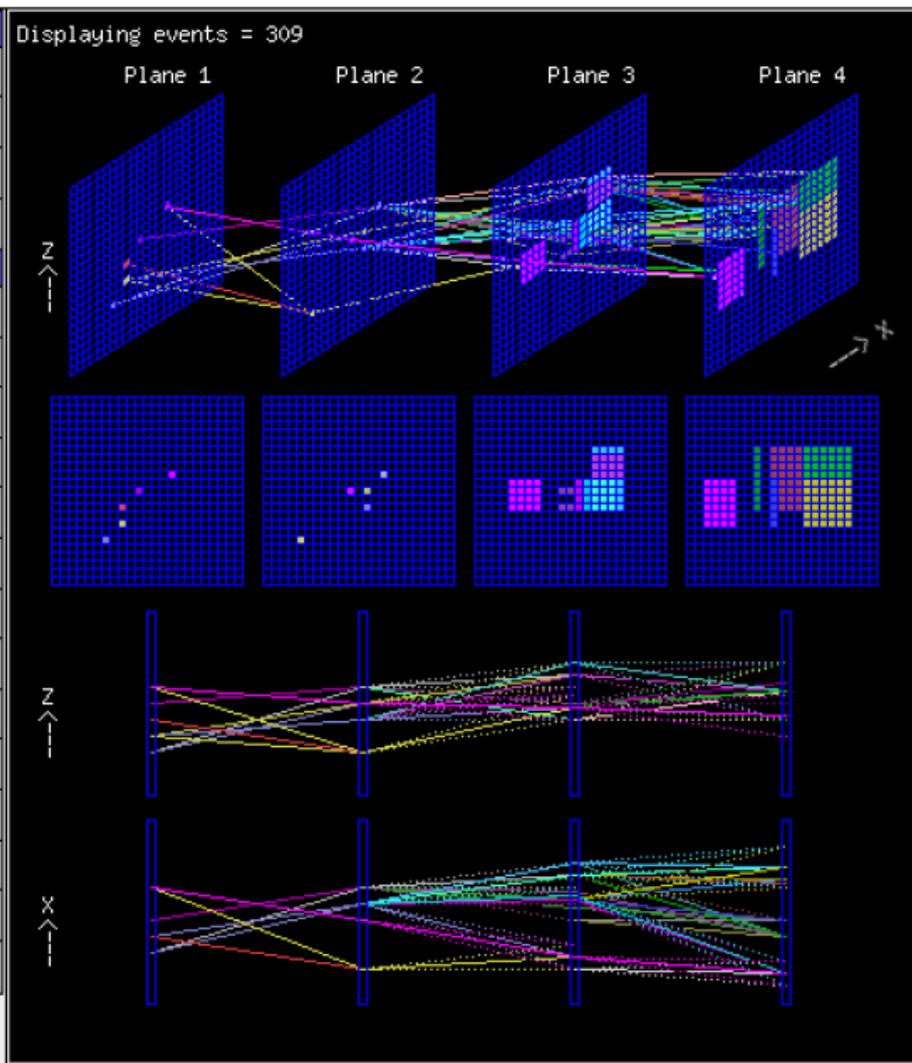




GUI Screen

Event Display for Plane 1-2-3-4

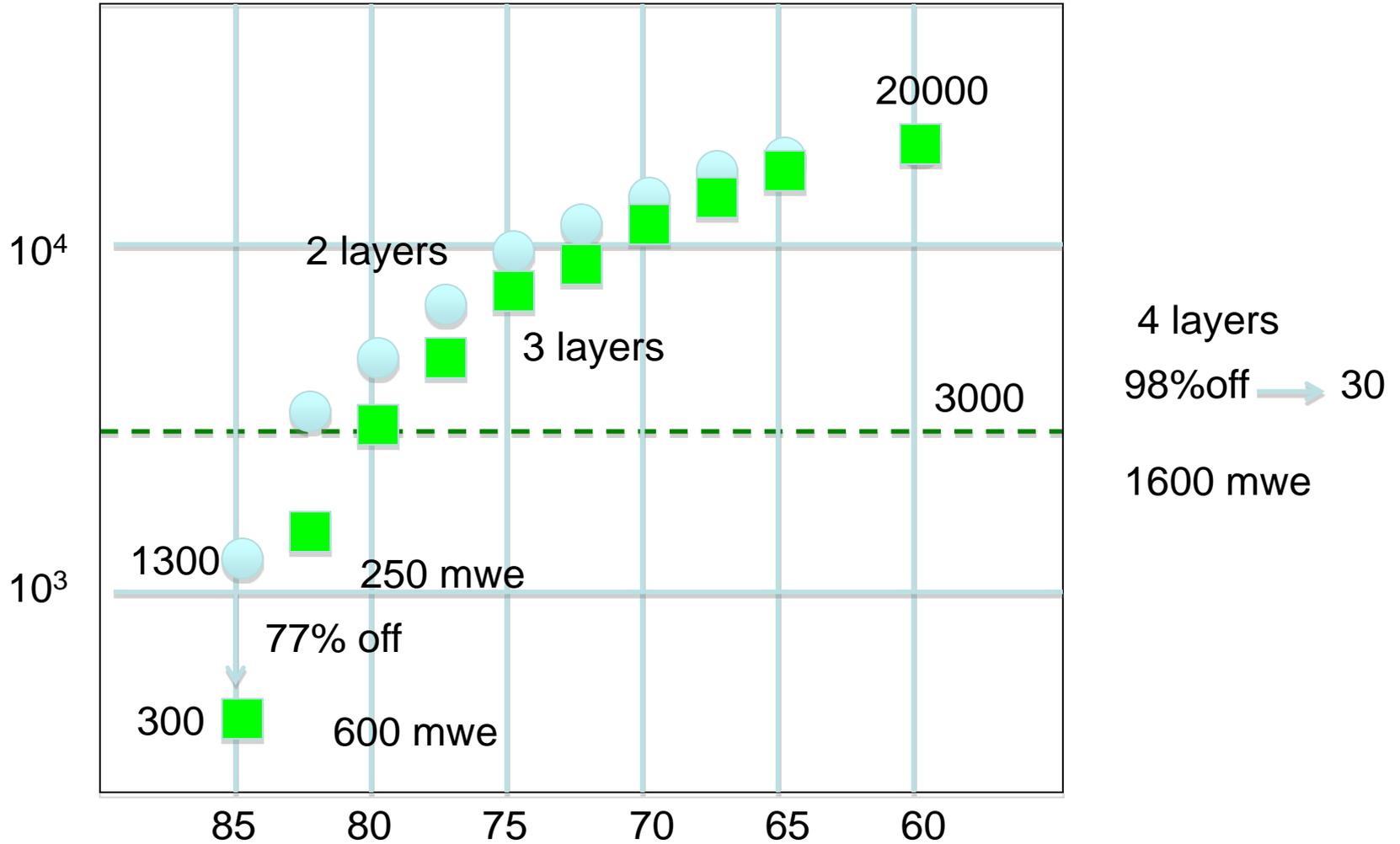
Testing Information	
Start Time	2009/10/08 16:52:48
Current Time	2009/10/08 16:56:44
Duration	0days 00:03:56
<input checked="" type="checkbox"/> update time and graphs.	10 seconds
Settings	
Plane Distance 1-2 [mm]	1000
Plane Distance 2-3 [mm]	1000
Plane Distance 3-4 [mm]	1000
Strip Width [mm]	100
Linearity [mrad]	100
Linearity(Multiplicity) [mrad]	100
Multi Plane Window [nsec]	200
Plane Window [nsec]	255
Multiplicity X [0-22]	22
Multiplicity Z [0-22]	22
Data Save Interval [hours]	1
Graph Display Events[events]	3000
Data Update Interval[sec]	5
<input type="button" value="Update Settings"/>	



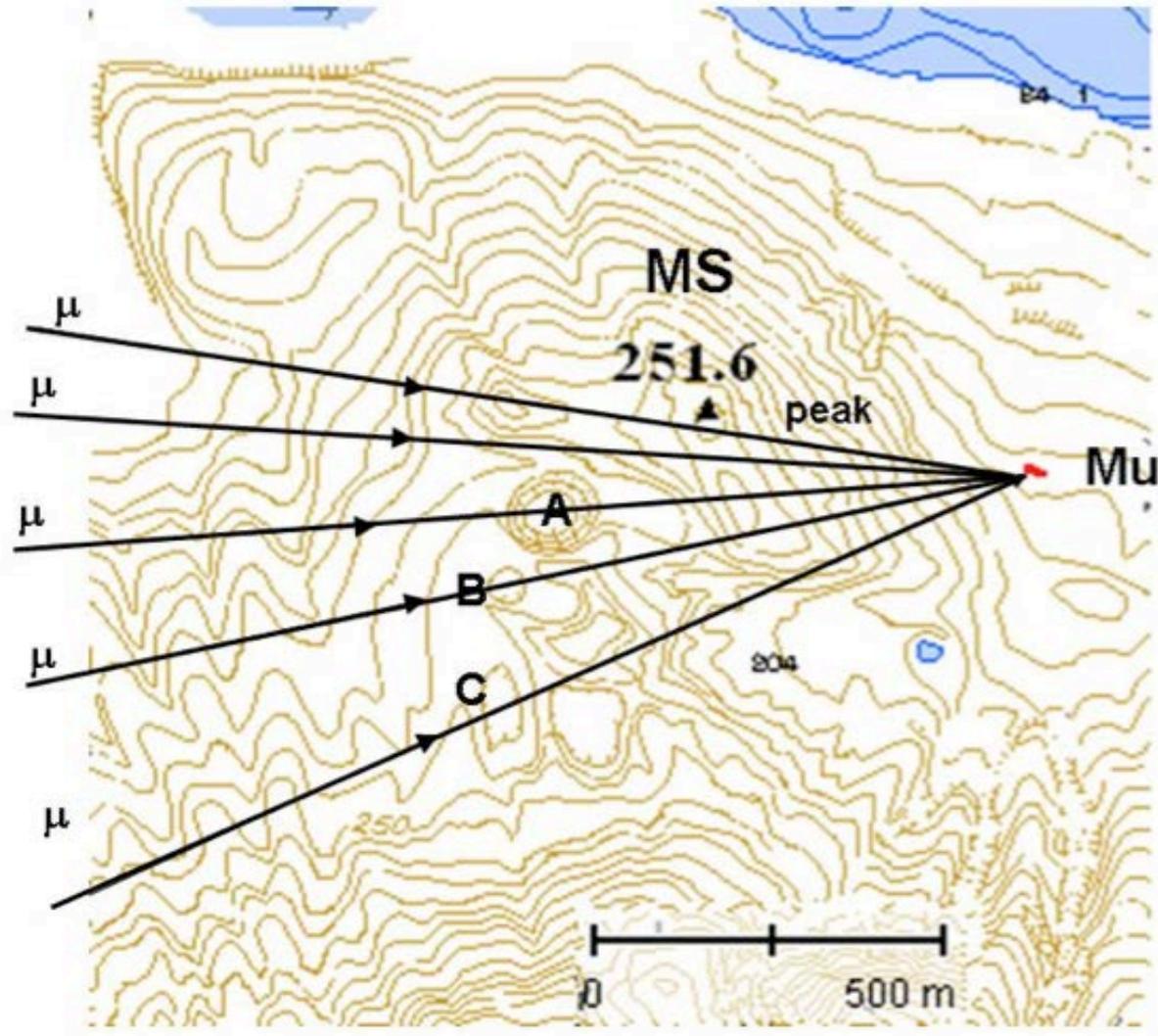
Test Experiment

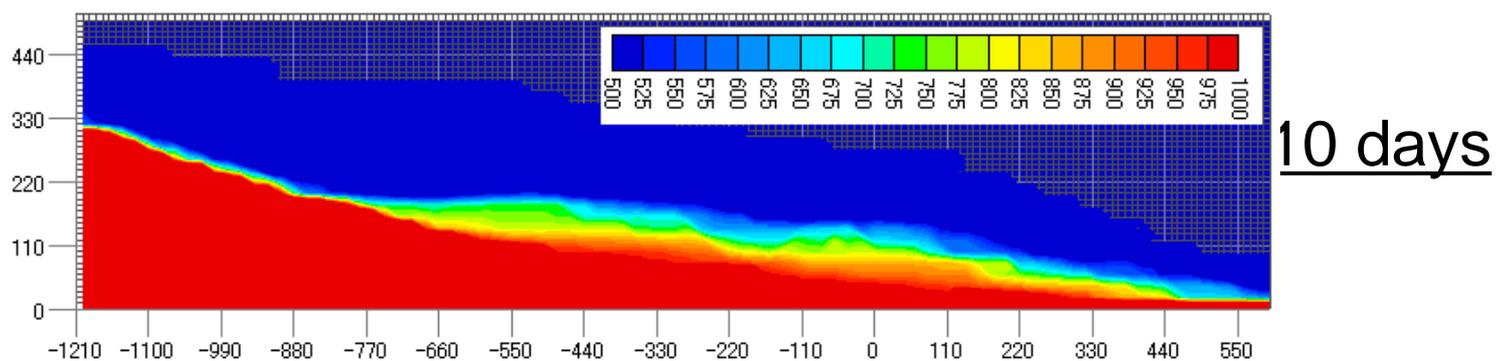
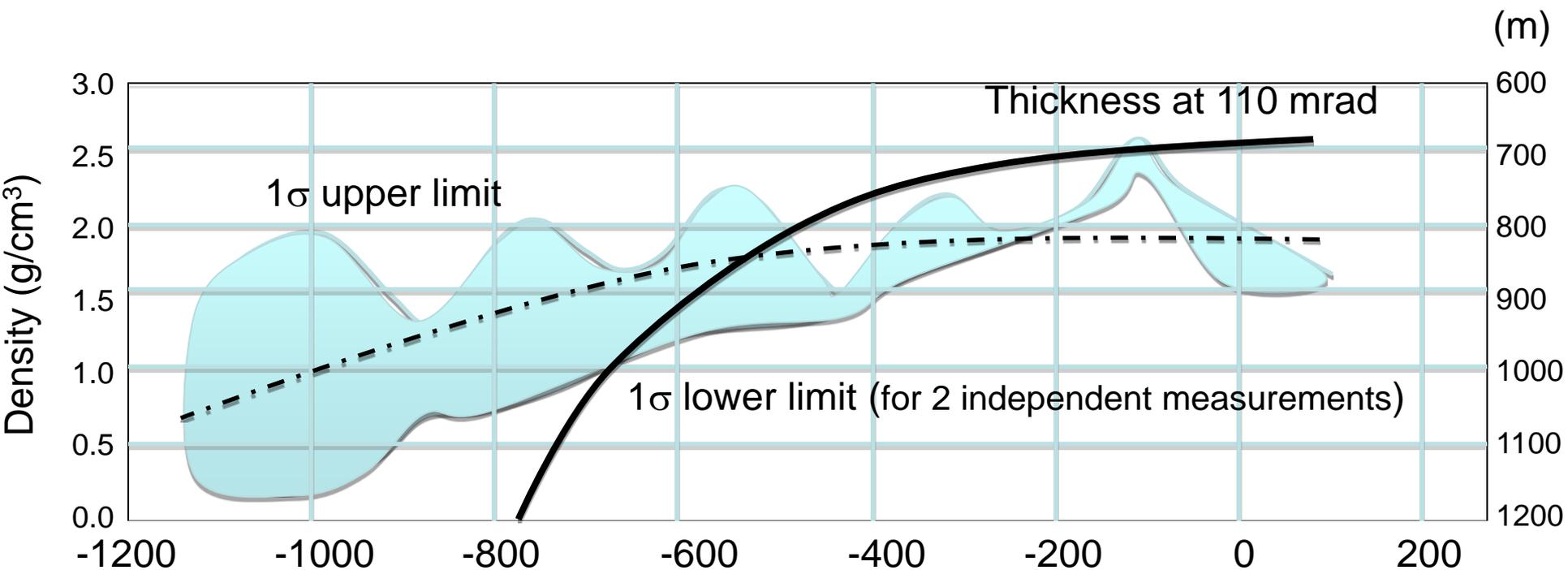


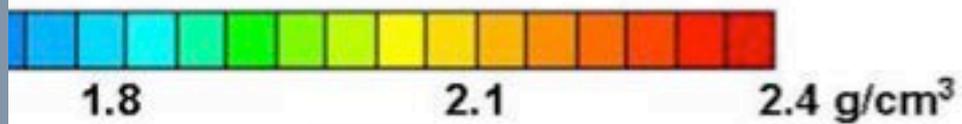
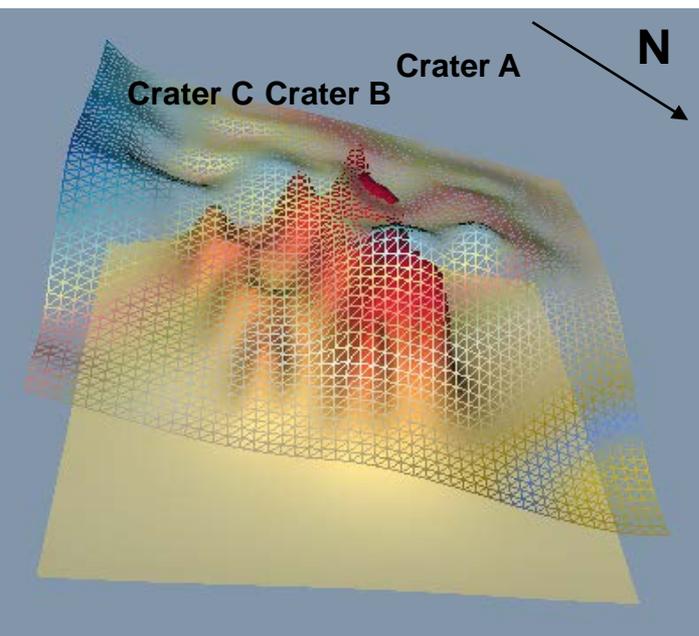
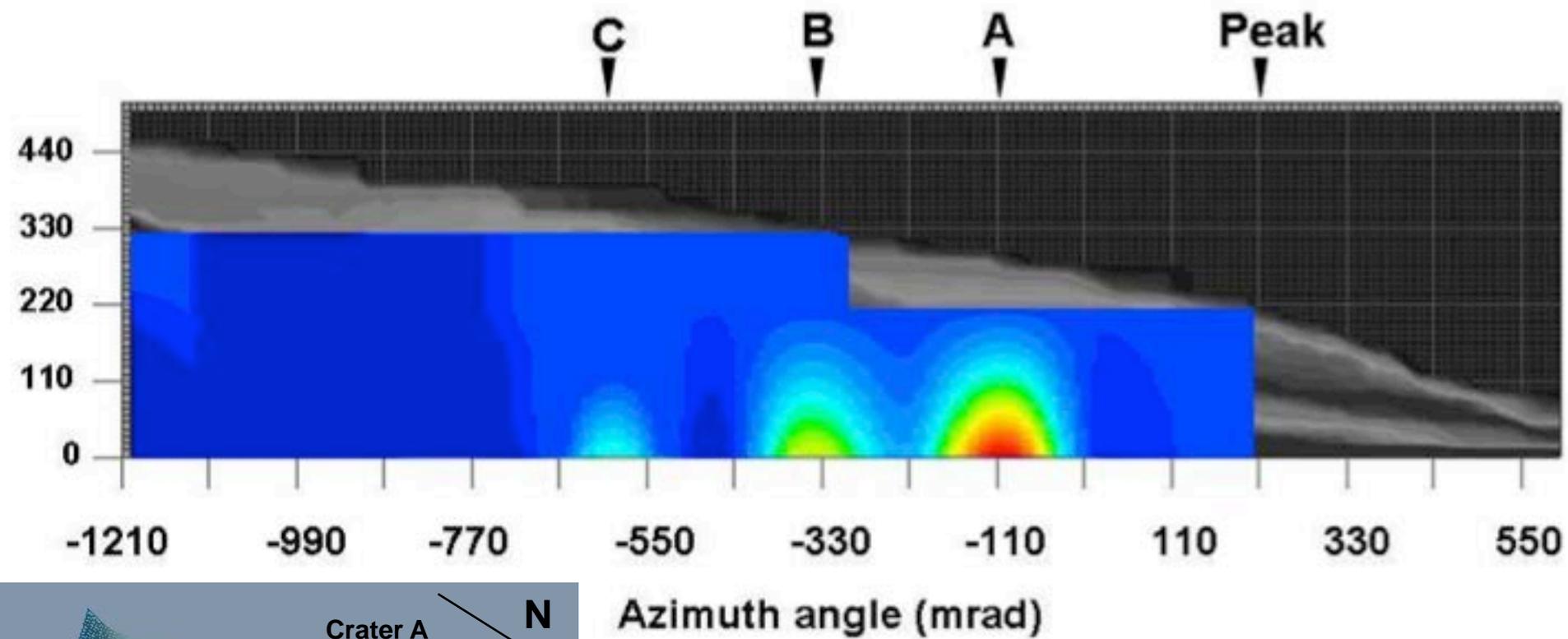
Test result



Test measurement part 2



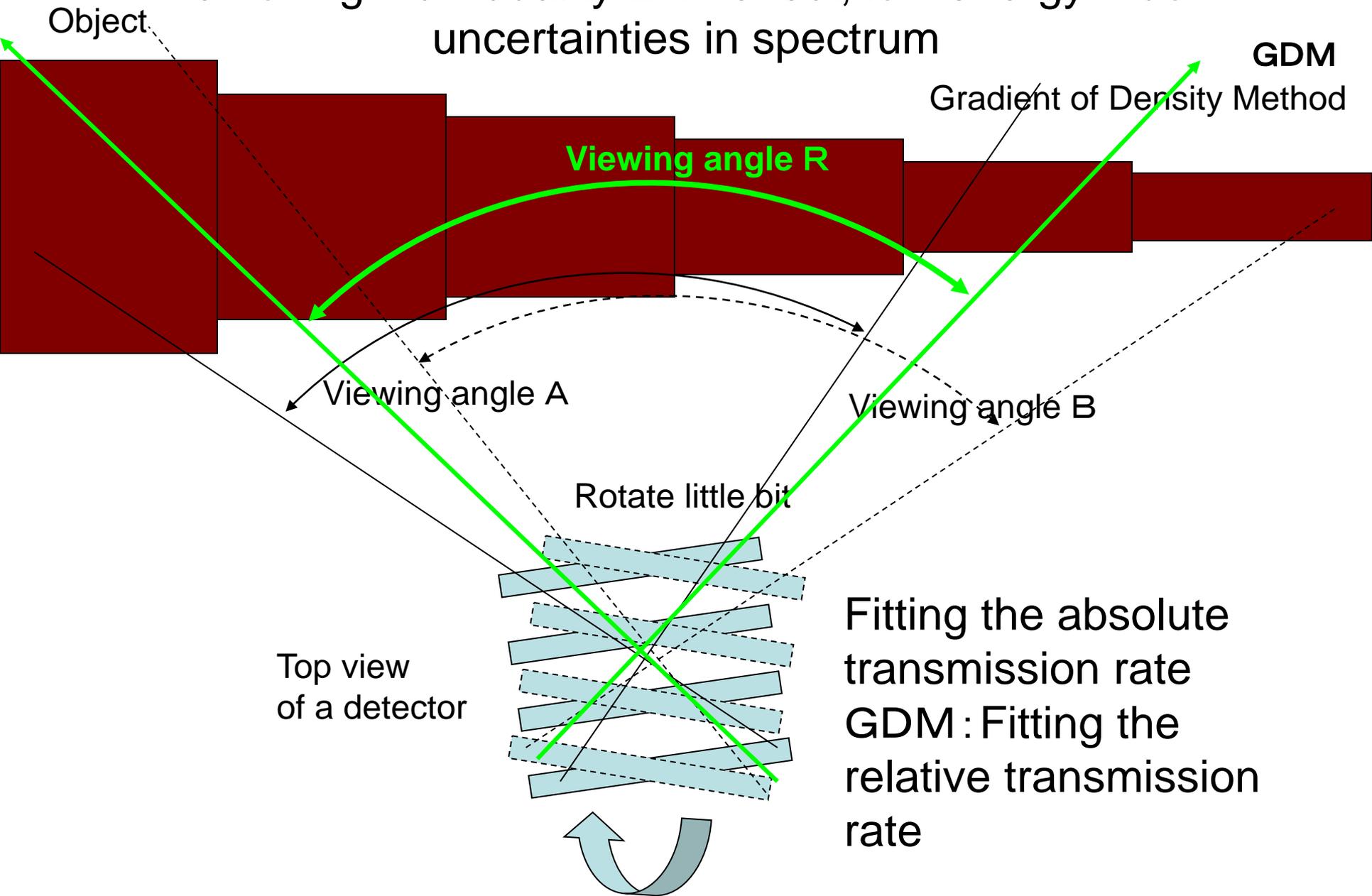




Conclusion

- Multi-layered PSD system worked well.
- Meij-shinzan lava dome was imaged within 10 days.
- This can be shortened to 5 with a full detector.

Removing individuality E-W effect, low energy muon uncertainties in spectrum



Object

GDM

Gradient of Density Method

Viewing angle R

Viewing angle A

Viewing angle B

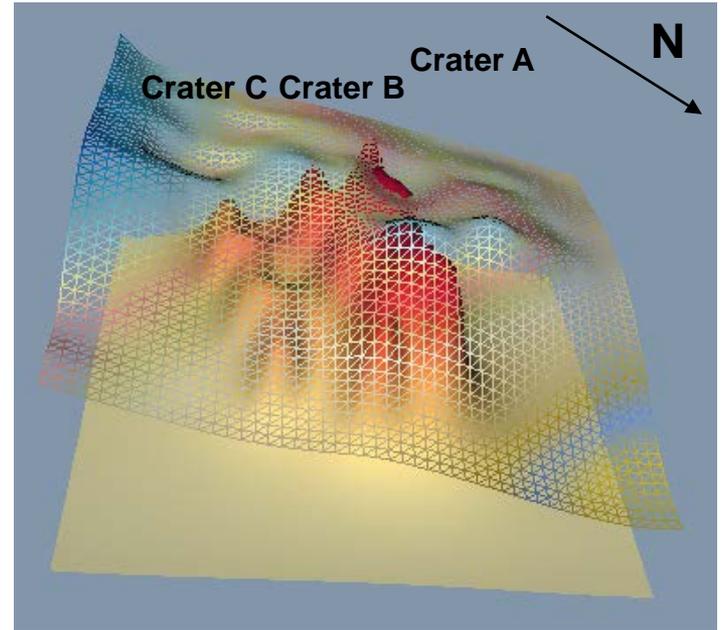
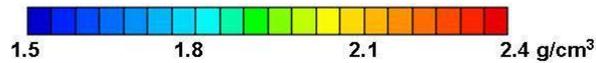
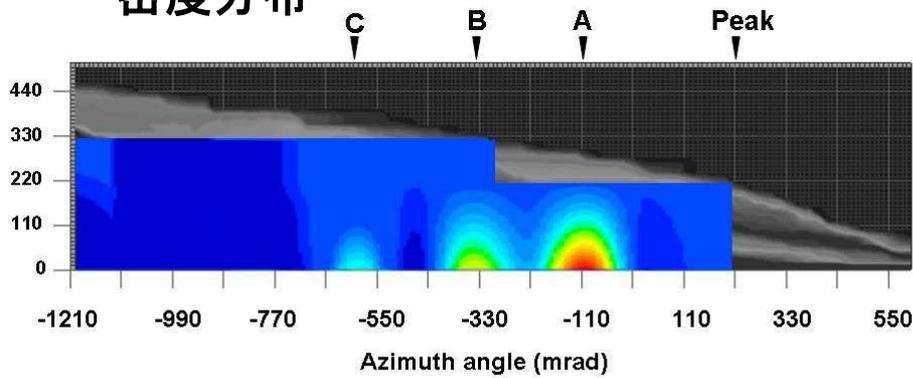
Rotate little bit

Top view
of a detector

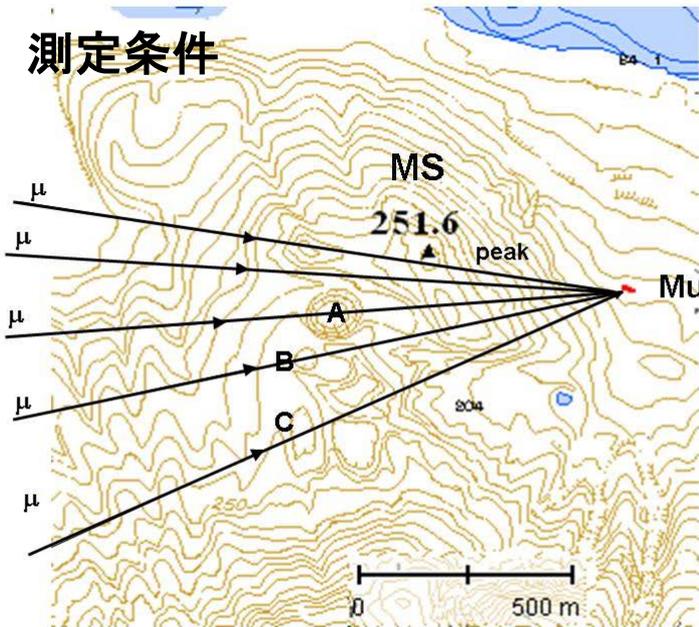
Fitting the absolute
transmission rate
GDM: Fitting the
relative transmission
rate

明治新山の測定結果

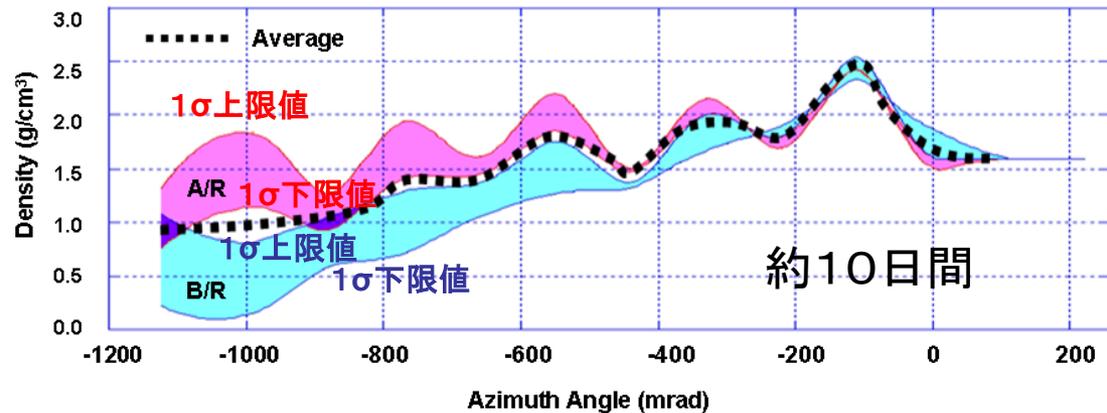
密度分布



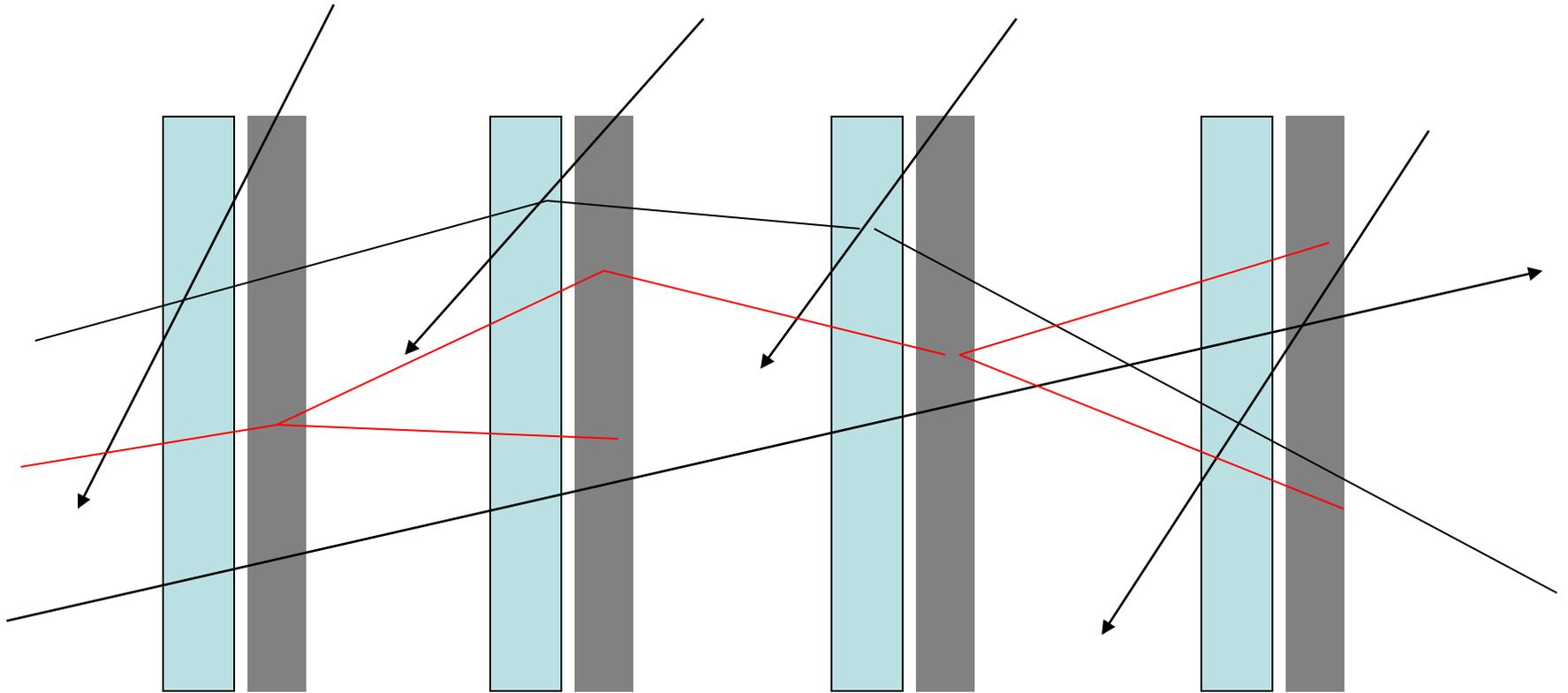
測定条件



導出密度の確証度



原理



線形性の要求

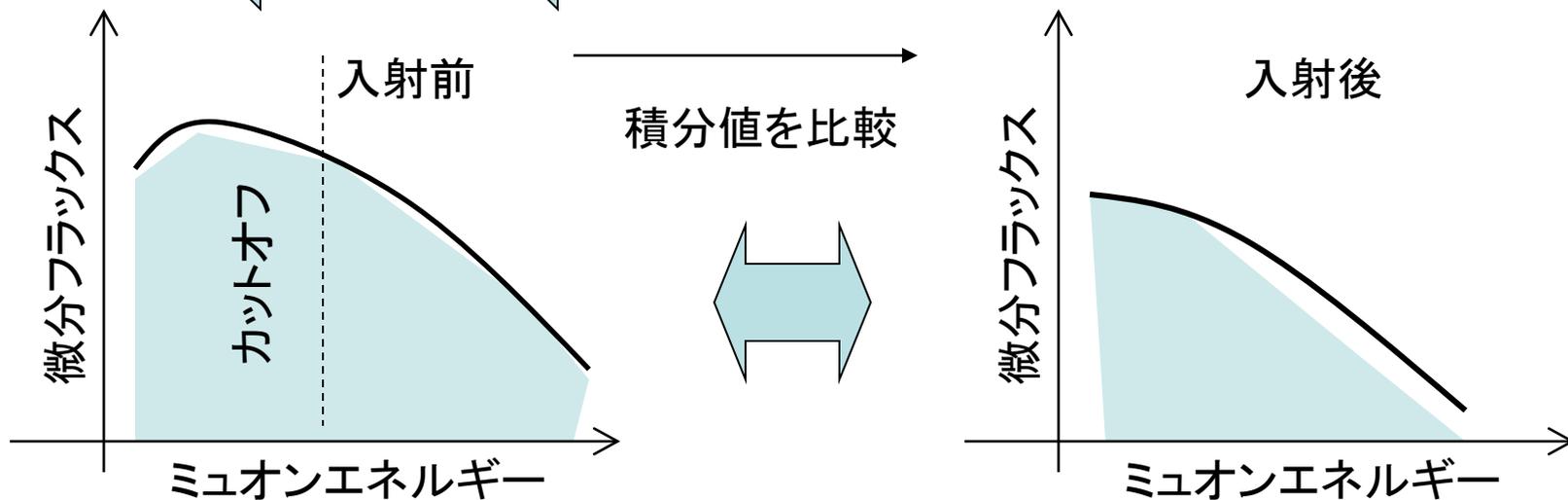
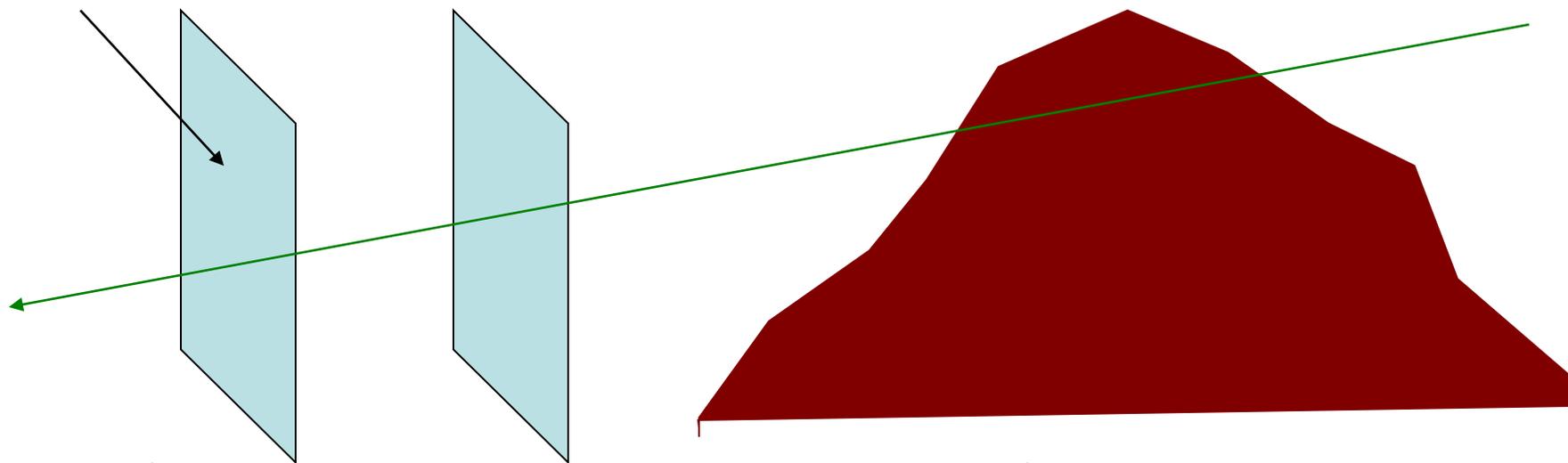
十分な厚さの散乱体による吸収・散乱

多重イベント解析による除去

従来のミュオンラジオグラフィ

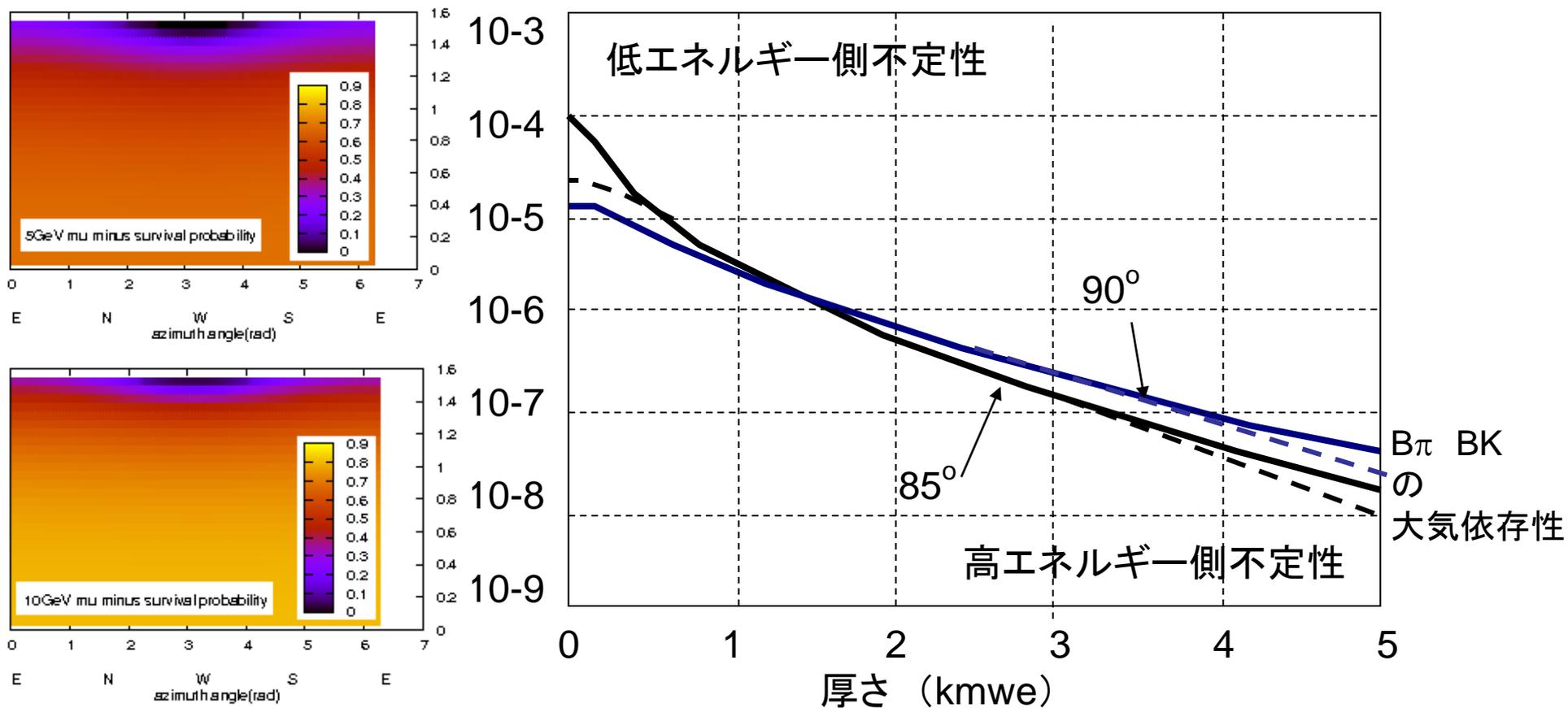
Tanaka et al. 2003

位置敏感型検出器

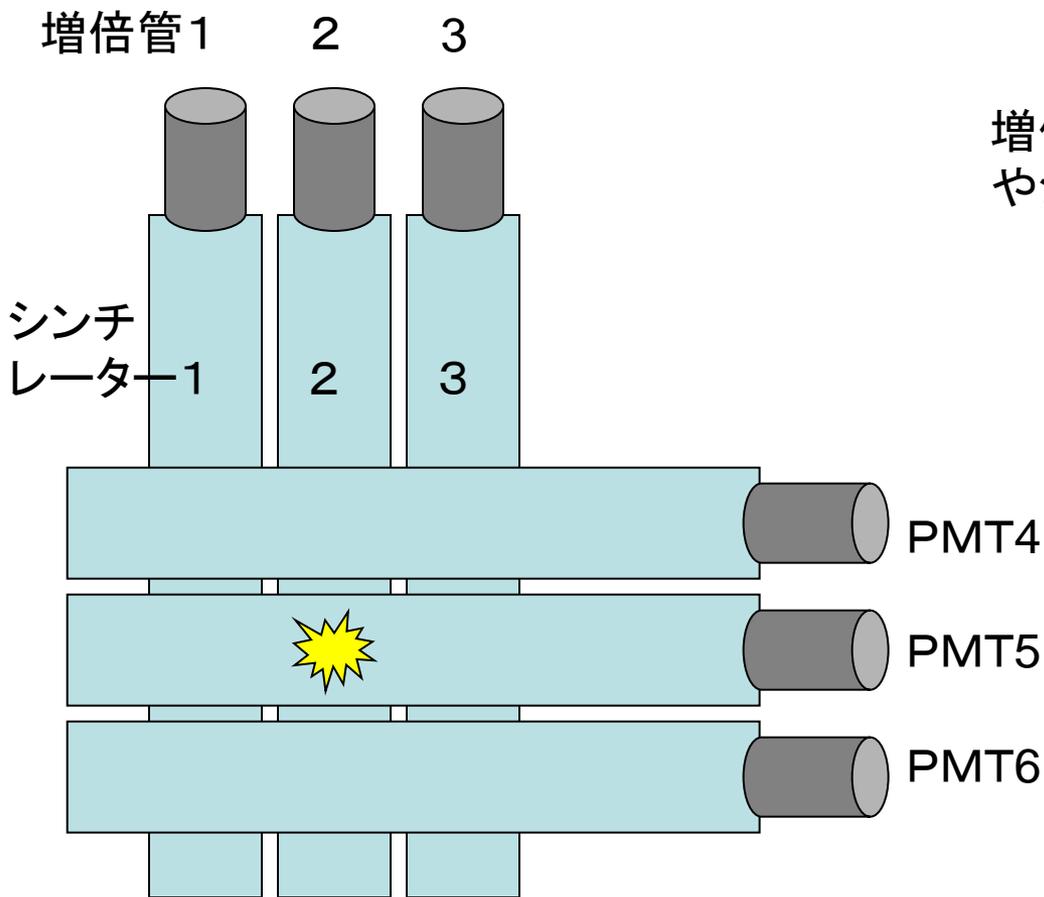


火山体のミュオンラジオグラフィーの Intrinsicな問題

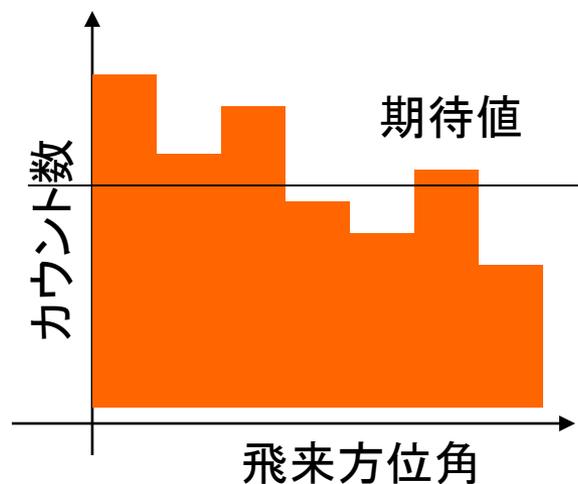
ミュオン微分フラックスのモデルに依存する。



検出器の個性による非一様バックグラウンド (デジカメの出カアンプの熱ノイズに相当)



増倍管
やシンチレーターの個性は一つ一つ違う。



従来は違う仰角の方位角分布で
規格化 = 多分不十分

今後の課題

- 厚くなるに従い導出密度が低くなる
 - 厚くなるに従いSN比が落ちる。
 - 検出器の枚数を増やす
- 現在のスペックは60%
 - 検出器をフルスペックに
 - 10日間の測定時間が6日間に
- GDM解析アルゴリズムの自動化
 - 誰でもボタン一つで密度分布をマッピング

EM成分による一様バックグラウンド（デジカメのダークノイズに相当）

