Design of the front-end digitization electronics for a G-APD-based Cherenkov telescope camera

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FACT – Overview First G-APD Cherenkov Telescope

Full-scale camera for long-term monitoring of variable Gamma-ray sources and technology demonstration

4.5° field-of-view (0.11° per pixel), 1440 pixels Operation also under twilight/moon (background rate up to 5 GHz per pixel) Power consumption \approx 1 kW Gain stabilization to \approx 5% with feedback Installation on former HEGRA CT3 telescope at La Palma (9.2 m² mirror)

Solid light concentrators

Digitization and triggering integrated in camera

DRS4 analog pipeline chip (PSI development) Timing better than 300 ps (rms) Data transfer via Ethernet Majority-trigger logic of non-overlapping patches



Imaging Air Cherenkov Telescopes

No photons from space with wavelength shorter than UV reach ground

Direct detection only in space or on high-altitude balloons Cost implies size and weight limit Event rate very low above ≈50 GeV (Crab nebula >30 GeV: ~0.2 photons/cm²/year)

Above ≈ 60 GeV: resulting air showers attain detectable size

Detection through emitted Cherenkov light Atmosphere behaves as 27 radiation length deep calorimeter Challenge is discrimination against hadronic showers (γ/p ratio <10-4) and muons



Statistical analysis of image parameters

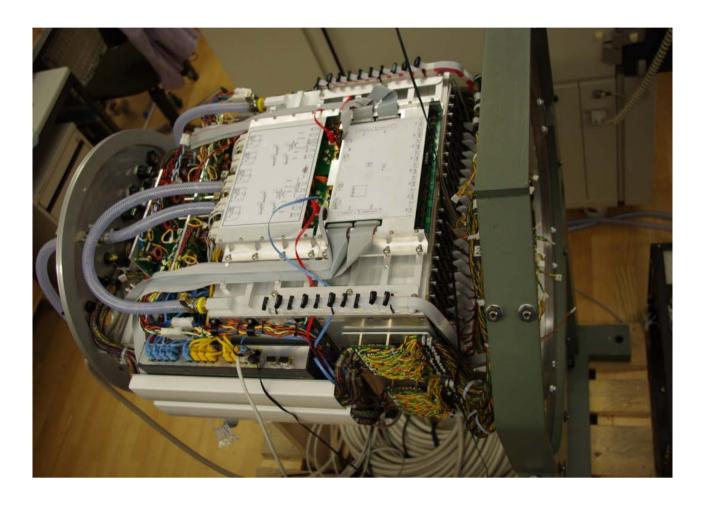
Gamma/hadron separation benefits from sub-ns time resolution

γ-ray energy ≈15% resolution for large telescope

Arrival direction (source location) ≈10 arcmin resolution

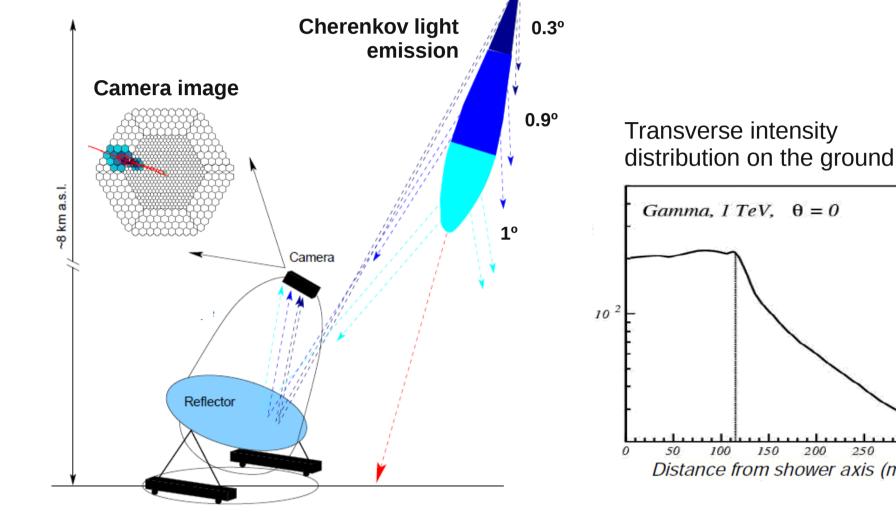
Typical camera images (MAGIC)



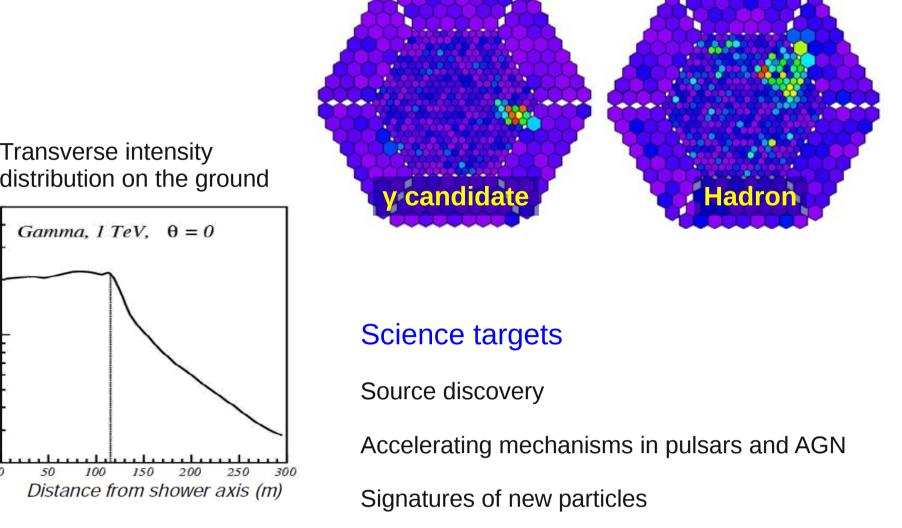


Electronics on 12-layer boards for thermal design reasons. Boards mounted to custom-build water cooled crates.

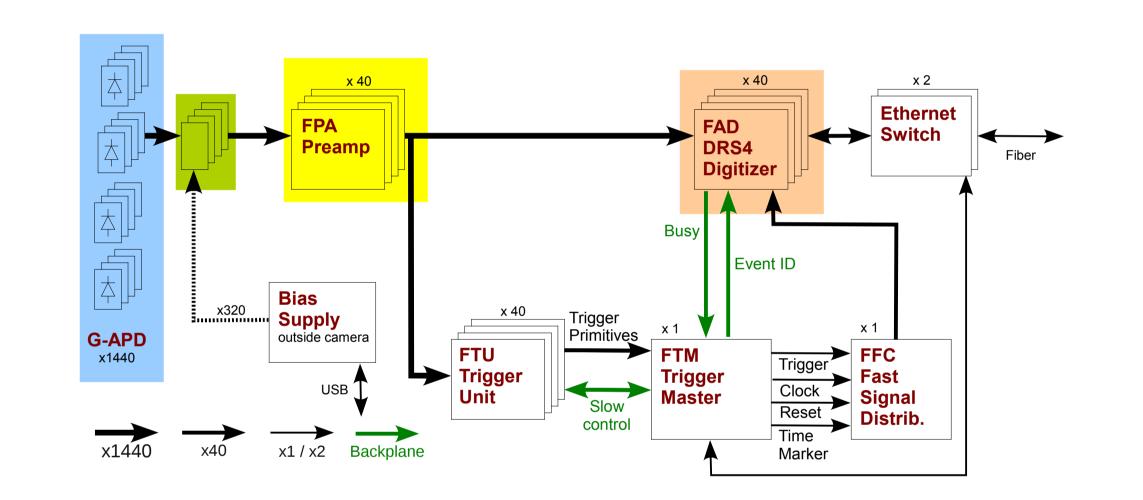
Fast digital signals routed via Cat.6 Ethernet cables Thermal interface uses Calmark Card-Loks



from: S. Commichau, PhD thesis, ETH Zürich (2007)



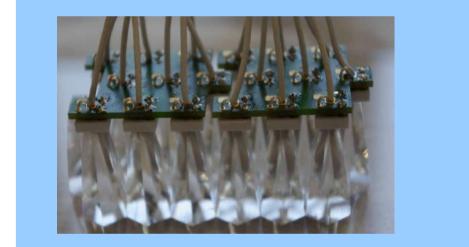
Electronics Block Diagram



Light Sensor

Geiger-mode Avalanche Photo-diode

Hamamatsu S10362-33-50C MPPC

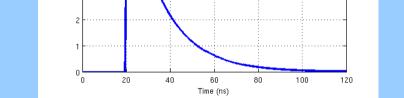






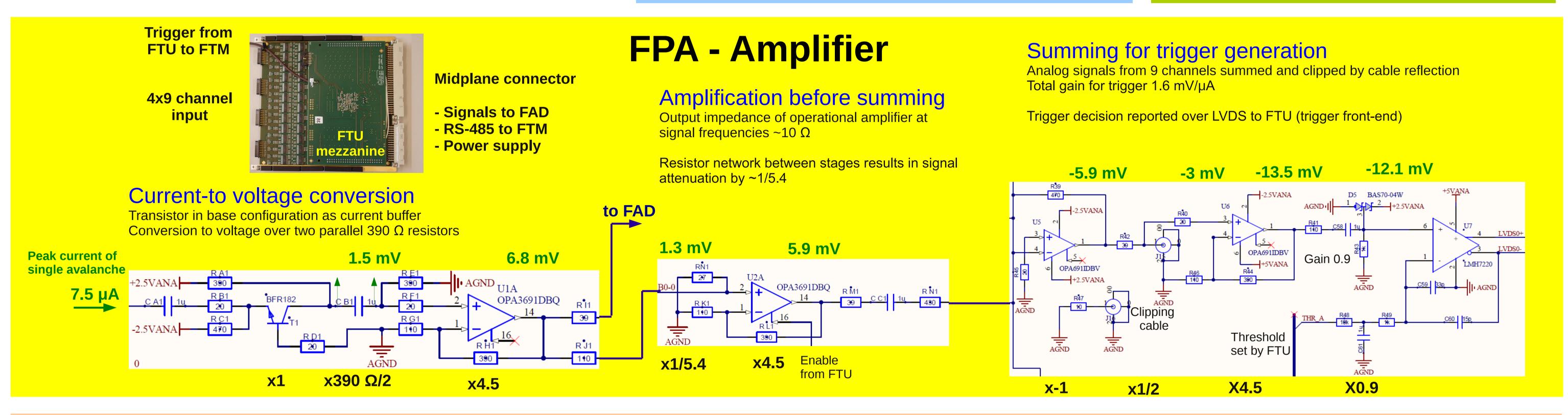
320 channel bias supply





Single avalanche pulse shape

0-90 V USB interface Custom developed



Single-ended to differential conversion

Signal attenuated by resistors and input/output impedance between FPA and FAD by ~0.5 Converter set to gain 2

6.8 mV

FAD - Digitization

DRS4 analog pipeline chip

Developed at PSI, Switzerland (http://drs.web.psi.ch/). Chip integration follows PSI VME mezzanine design

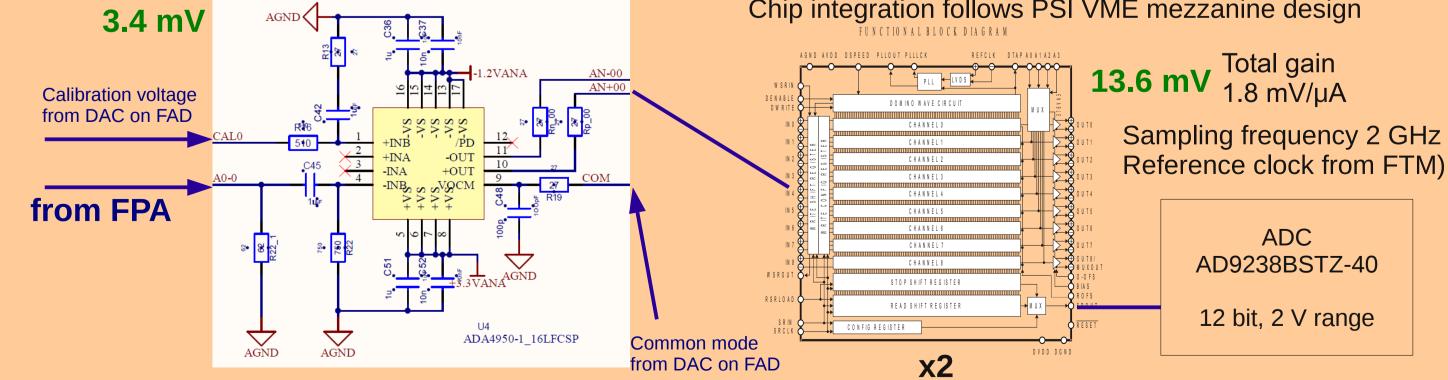
Digital control

Midplane connector

- Signals from FPA

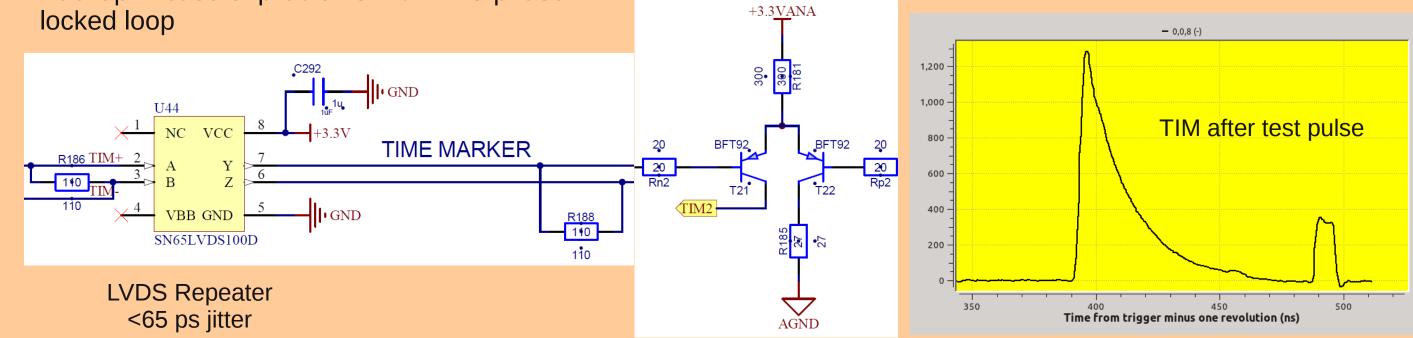


J-TAG Ethernet



High precision time marker

Time marker (TIM) generated by FTM, transported differentially over category 6 Ethernet cables Backup in case of problems with DRS phase



FPGA Xilinx XC3SD3400A-4FGG676C

50 MHz frequency Stops DRS sampling when triggered Informs trigger master (FTM) when unable to accept triggers Controls DRS4 and ADC (generates clocks) Sets DAC on FAD (input common mode, calibration, output offset) Receives event number over RS485 from FTM Interfaces with Wiznet chip Measures reference clock Reads temperature sensors

Measured throughput

FADctrl/Board00/RateHz(0

1024 | 100

(10 FAD boards)

RO

6- Apr 2011 12:52:46 to 6- Apr 2011 12:54:47

~60 MByte/sec

Trigger rate with 100 bins

region-of-interest ~700 Hz

Data transfer

Ethernet interface with Wiznet W5300 chip (100 Mbit/s)

8 TCP/IP sockets used cyclically for sending event data Socket 0 for receiving command

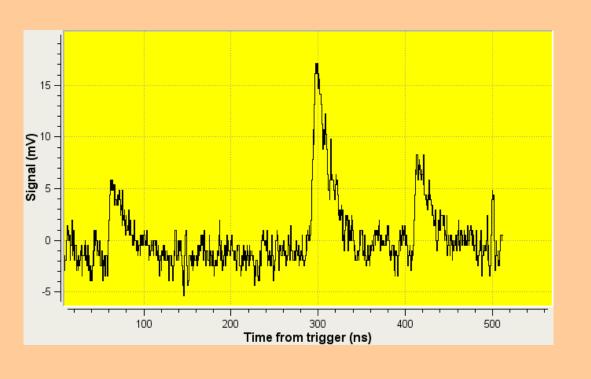
FAD boards connected to two Gigabit switches (D-Link DGS-1224T), data transfer to counting house over fibers (Huber+Suhner MO104)

- RS-485 to FTM - Power supply



G-APD dark counts digitized with FAD

Double avalanche generated by optical cross-talk Noise after DRS4 calibration 1.5-2 mV rms



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