

# Adaptive Sampling Optimization for Magnetic Resonance Imaging by Bayesian Experimental Design

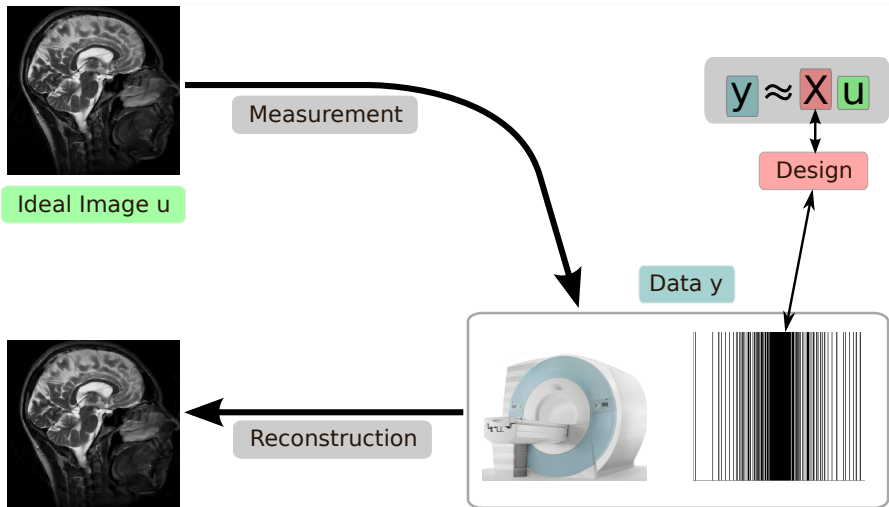
Matthias Seeger

joint work with Hannes Nickisch,  
Rolf Pohmann, Bernhard Schölkopf

Laboratory for Probabilistic Machine Learning  
Ecole Polytechnique Fédérale de Lausanne  
<http://lapmal.epfl.ch/>



# Image Reconstruction

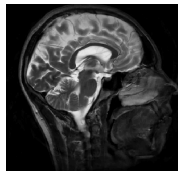


# Sampling Optimization

scan time  $\propto$   
# phase encodes

$$y \approx Xu$$

$X \leftarrow ?$



Reconstruction

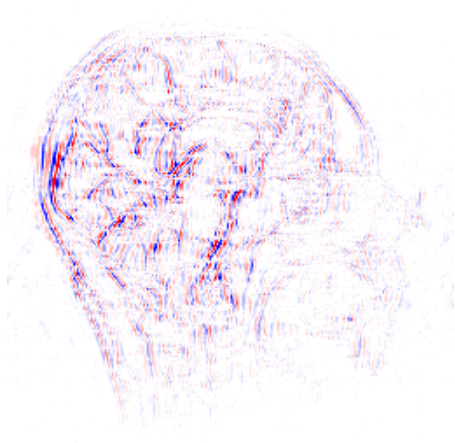
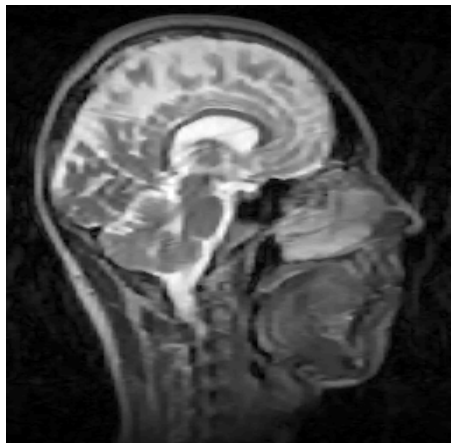


# Why Sampling Optimization?

MAP reconstruction, 1/4 Nyquist (64 encodes)

$L_2 = 7.38$

- Low pass: Dense sampling of low frequencies



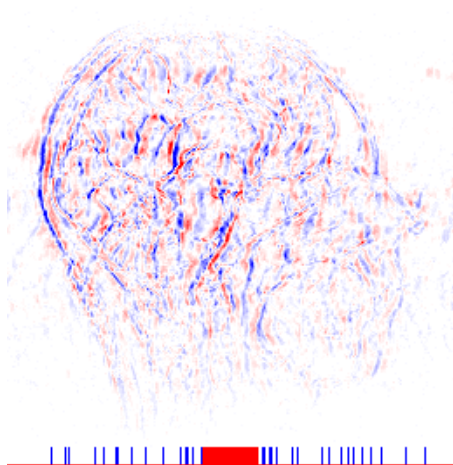
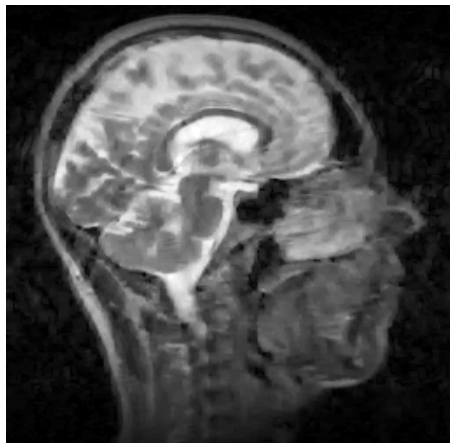
# Why Sampling Optimization?

MAP reconstruction, 1/4 Nyquist (64 encodes)

- Random (variable density)

$$L_2 = 8.12(\pm 0.53)$$

Lustig, Donoho, Pauly: MRM 58(6)



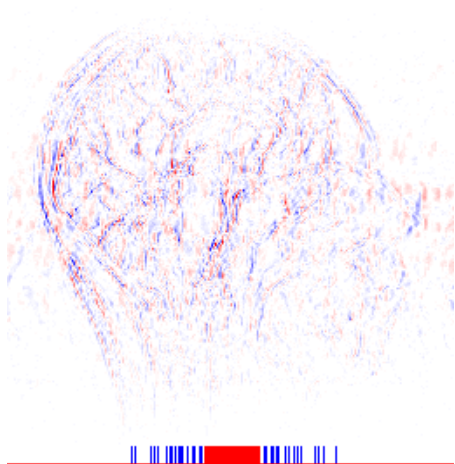
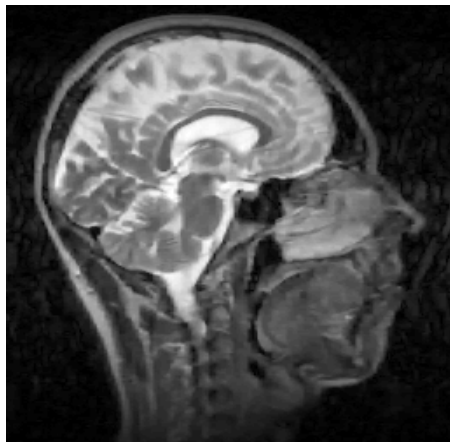
# Why Sampling Optimization?

MAP reconstruction, 1/4 Nyquist (64 encodes)

$L_2 = 5.66$

- Bayesian optimized

Seeger *et al.*, MRM 63(1)

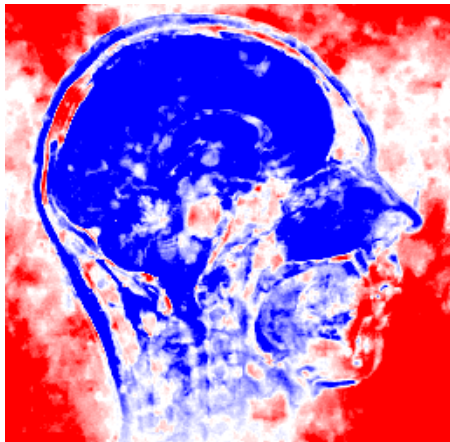
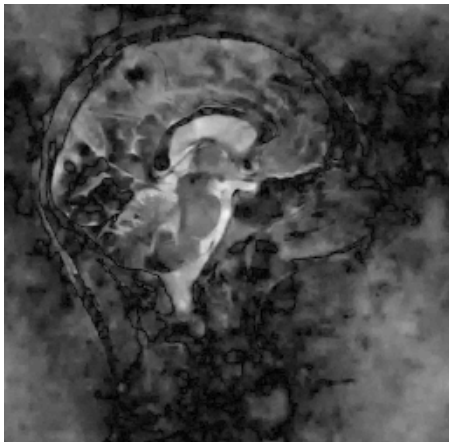


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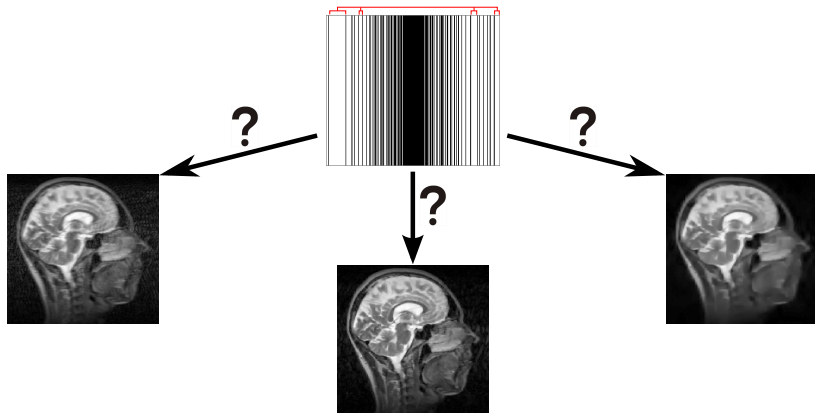
MAP reconstruction, 1/4 Nyquist (64 encodes)

$L_2 = 46.48(\pm 8.01)$

- Uniformly random Fourier coefficients



# Reconstruction is Ill Posed



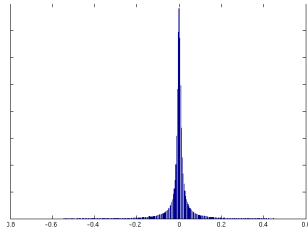
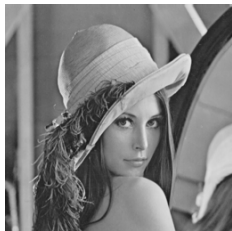


# Image Statistics

Whatever images are ...

they are not Gaussian!

- Image gradient super-Gaussian (“sparse”)

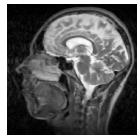
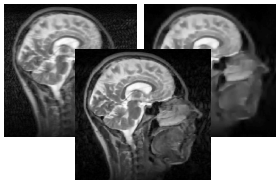


Use **sparsity** prior distribution  $P(\mathbf{u})$

# Posterior Distribution

- Likelihood  $P(\mathbf{y}|\mathbf{u})$ : Data fit
- Prior  $P(\mathbf{u})$ : Signal properties
- Posterior distribution  $P(\mathbf{u}|\mathbf{y})$ :  
Consistent information summary

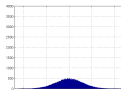
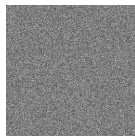
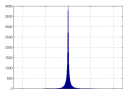
$$P(\mathbf{y}|\mathbf{u})$$



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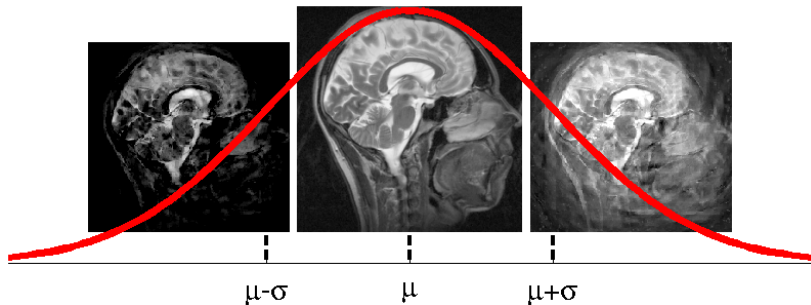
$$P(\mathbf{y}|\mathbf{u}) \times P(\mathbf{u})$$



# Posterior Distribution

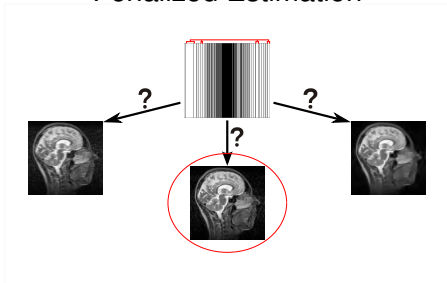
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Consistent information summary

$$P(\mathbf{u}|\mathbf{y}) = \frac{P(\mathbf{y}|\mathbf{u}) \times P(\mathbf{u})}{P(\mathbf{y})}$$



# Estimation and Bayesian Decision Making

## Penalized Estimation

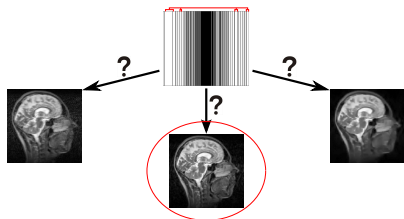


$$\hat{\mathbf{u}} = \operatorname{argmax} P(\mathbf{y}|\mathbf{u})P(\mathbf{u})$$

- Single best guess  $\hat{\mathbf{u}}$
- Massive recent progress

# Estimation and Bayesian Decision Making

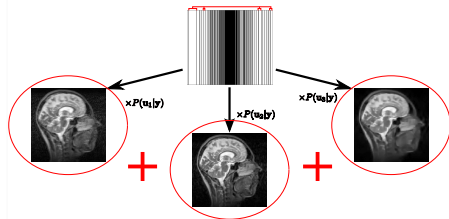
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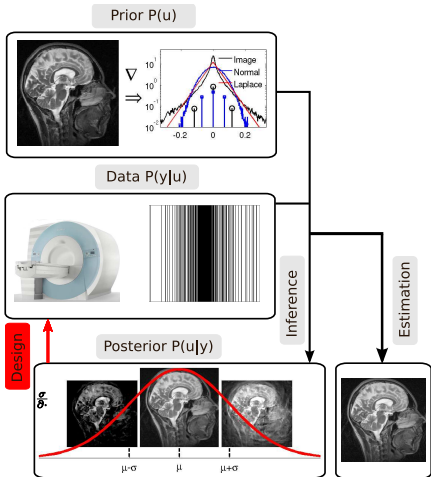
## Bayesian Inference



$$P(\mathbf{u}|\mathbf{y}) = \frac{P(\mathbf{y}|\mathbf{u})P(\mathbf{u})}{P(\mathbf{y})}$$

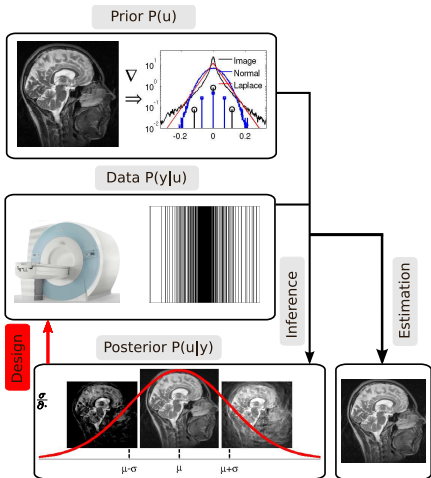
- Quantify your uncertainty
- Optimal decision making

# Bayesian Experimental Design

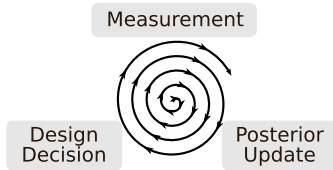


- Posterior: **Uncertainty** in reconstruction
- Experimental design: Find poorly determined directions
- Sequential search with interjacent partial measurements

# Bayesian Experimental Design



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# Main Message

- Compressive sampling for anatomical MRI?  
Needs **design optimization**.  
Random sampling plus  $\ell_1$  magic suboptimal.
- Design optimization:  
Decision making (about  $\mathbf{X}$ ) under uncertainty (about  $\mathbf{u}$ ).  
Needs **Bayesian inference** beyond MAP estimation.
- Bayesian inference? You must be kidding!
  - MCMC: Undirected random walks, not based on optimization
  - Many orders of magnitude slower than estimation (gap increasing)

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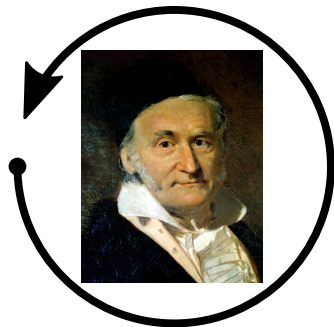
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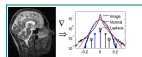
- Variational Bayesian inference:
  - Convex optimization
  - Driven by MAP (least squares) estimation



=

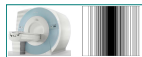


# Sparse Linear Image Model

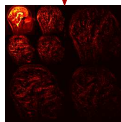


$$P(\mathbf{u}) \propto \prod_{i=1}^q t_i(s_i) =$$

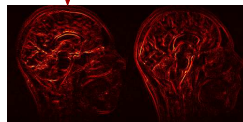
$$e^{-\tau_w \|\mathbf{B}_w \mathbf{u}\|_1} \times e^{-\tau_{tv} \|\mathbf{B}_{tv} \mathbf{u}\|_1}, \quad \mathbf{s} = \mathbf{B}\mathbf{u}$$



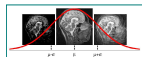
$$P(\mathbf{y}|\mathbf{u}) = \mathcal{N}(\mathbf{y}|\mathbf{X}\mathbf{u}, \sigma^2\mathbf{I})$$



wavelet

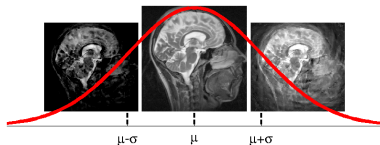


gradient



$$P(\mathbf{u}|\mathbf{y}) \propto P(\mathbf{u})P(\mathbf{y}|\mathbf{u})$$

# Variational Bayesian Inference

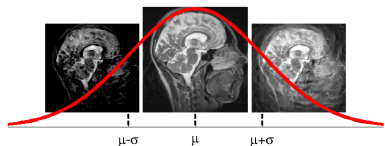


$$P(\mathbf{u}|\mathbf{y}) = \frac{P(\mathbf{y}|\mathbf{u}) \times P(\mathbf{u})}{P(\mathbf{y})}$$

## Variational Inference Approximation

- Write intractable integration as (intractable) optimization
- Relax to tractable optimization problem

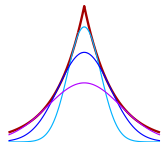
# Variational Bayesian Inference



$$P(\mathbf{u}|\mathbf{y}) = \frac{P(\mathbf{y}|\mathbf{u}) \times P(\mathbf{u})}{P(\mathbf{y})}$$

- **Variational Relaxation:** Bound the master function

$$\underbrace{-\log P(\mathbf{y}) = -\log \int P(\mathbf{u}, \mathbf{y}) d\mathbf{u}}_{\text{Moment generating function}} \leq \min_{\gamma} \min_{\mathbf{u}} \phi(\mathbf{u}, \gamma)$$

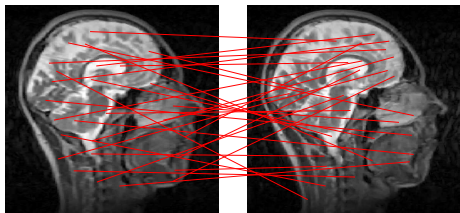


- Approximate posterior  $P(\mathbf{u}|\mathbf{y})$  by Gaussian
- Integration  $\Rightarrow$  Convex optimization

# Decoupling by Concavity

$$-\log \int P(\mathbf{u}, \mathbf{y}) d\mathbf{u} \leq \min_{\gamma} \min_{\mathbf{u}} \phi(\mathbf{u}, \gamma)$$

- Dependencies in posterior  $P(\mathbf{u}|\mathbf{y})$   
 $\Rightarrow$  Difficult **couplings** in criterion  $\phi$
- Critically coupled part is **concave**
- Upper bound by tangent plane

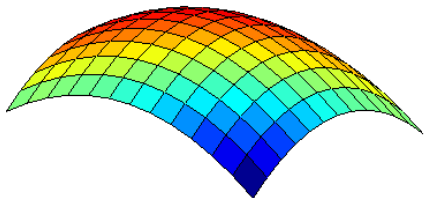




# Decoupling by Concavity

$$-\log \int P(\mathbf{u}, \mathbf{y}) d\mathbf{u} \leq \min_{\gamma} \min_{\mathbf{u}} \phi(\mathbf{u}, \gamma)$$

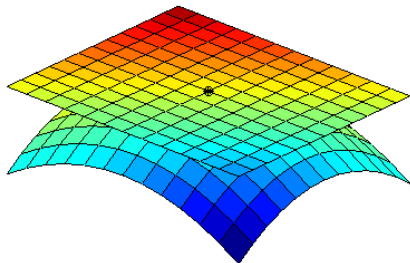
- Dependencies in posterior  $P(\mathbf{u}|\mathbf{y})$   
⇒ Difficult **couplings** in criterion  $\phi$
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# Decoupling by Concavity

$$-\log \int P(\mathbf{u}, \mathbf{y}) d\mathbf{u} \leq \min_{\gamma} \min_{\mathbf{u}} \phi(\mathbf{u}, \gamma) = \underbrace{\min_{\mathbf{z}} \min_{\gamma} \min_{\mathbf{u}} \phi_{\mathbf{z}}(\mathbf{u}, \gamma)}_{\text{Decoupled problem}}$$

- Dependencies in posterior  $P(\mathbf{u}|\mathbf{y})$   
 $\Rightarrow$  Difficult **couplings** in criterion  $\phi$
- Critically coupled part is **concave**
- Upper bound by tangent plane



# Double Loop Algorithm

$$\min_{\mathbf{u}} (\min_{\gamma} \phi_{\mathbf{z}}(\mathbf{u}, \gamma))$$

## Double loop algorithm

- Inner loop optimization:  $\min_{\gamma} \min_{\mathbf{u}} \phi_{\mathbf{z}}(\mathbf{u}, \gamma)$
- Outer loop update:  $\min_{\mathbf{z}} \phi_{\mathbf{z}}(\mathbf{u}, \gamma)$

# Double Loop Algorithm

$$\min_{\mathbf{u}} (\min_{\gamma} \phi_{\mathbf{z}}(\mathbf{u}, \gamma)) = \min_{\mathbf{u}} \|\mathbf{y} - \mathbf{X}\mathbf{u}\|^2 + \mathcal{R}_{\mathbf{z}}(\mathbf{u})$$

## Double loop algorithm

- Inner loop optimization:  $\min_{\gamma} \min_{\mathbf{u}} \phi_{\mathbf{z}}(\mathbf{u}, \gamma)$   
**Penalized Least Squares**
- Outer loop update:  $\min_{\mathbf{z}} \phi_{\mathbf{z}}(\mathbf{u}, \gamma)$

# Double Loop Algorithm

$$\min_{\mathbf{z}} \phi_{\mathbf{z}}(\mathbf{u}, \gamma)$$

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# Double Loop Algorithm

$$\text{Tangent plane : } \mathbf{z} \leftarrow \nabla_{\gamma^{-1}} \phi_{\Pi}(\gamma^{-1}) = \text{diag}(\mathbf{B}\mathbf{A}^{-1}\mathbf{B}^T)$$

$$\mathbf{A} = \sigma^{-2}\mathbf{X}^T\mathbf{X} + \mathbf{B}^T(\text{diag } \gamma)^{-1}\mathbf{B}$$

## Double loop algorithm

- Inner loop optimization:  $\min_{\gamma} \min_{\mathbf{u}} \phi_{\mathbf{z}}(\mathbf{u}, \gamma)$   
**Penalized Least Squares**
- Outer loop update:  $\min_{\mathbf{z}} \phi_{\mathbf{z}}(\mathbf{u}, \gamma)$   
**Gaussian (Co)Variances**

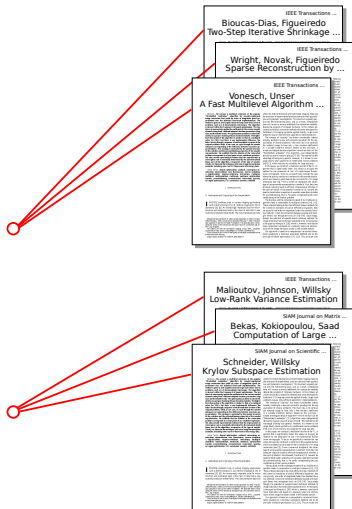
# Standing on Shoulders

Approximate  
Bayesian Inference



Penalized  
Estimation

Gaussian Model  
(Co)Variances



# Optimizing Cartesian MRI

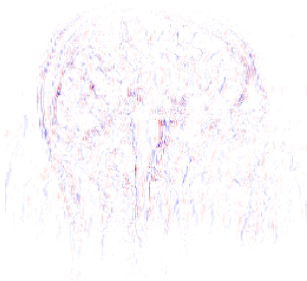
Bayes Optim.



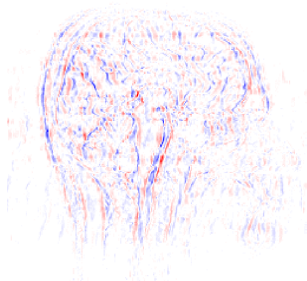
VD Random



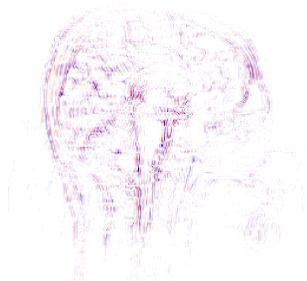
Low Pass



Seeger *et.al.*, MRM 63(1), 2010



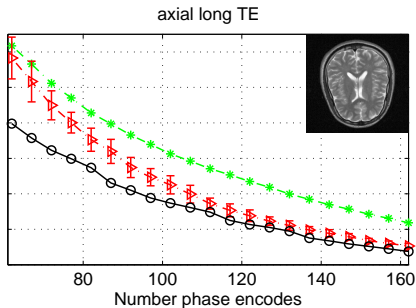
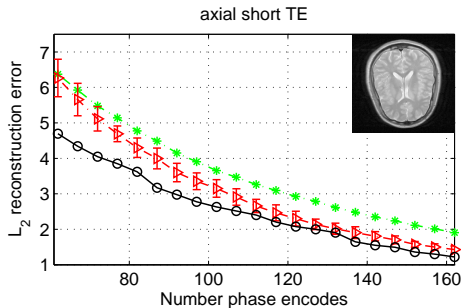
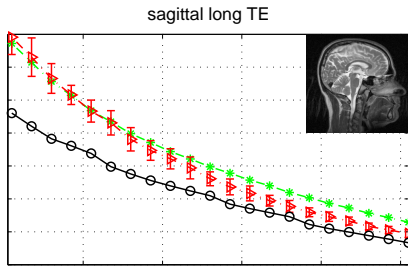
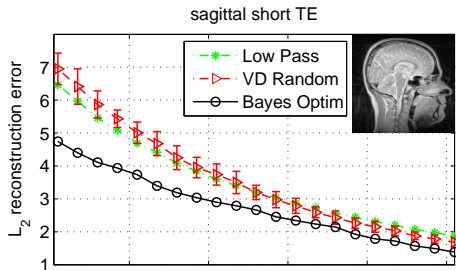
Lustig, Donoho, Pauli, MRM 58(6), 2007



Common MRI practice



# Experimental Results: Test Set Errors



# Bayesian Technology for Imaging

## MRI applications other than sampling optimization

- Autocalibrating parallel MRI (plus  $k$ -space optimization) by robust Bayesian blind deconvolution
- Robust joint estimation / calibration:  
 $B_0$  field map, relaxation, motion, . . .
- Parallel transmit: Optimizing spokes design
- Dynamic / 3D MRI:  
Graphical models, belief propagation to factorize computations

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## Generic framework beyond magnetic resonance imaging

- You can do penalized estimation efficiently?  
You can do variational Bayesian inference!

# Conclusions

- Modern nonlinear image reconstruction:  
Better images through robust low-level prior knowledge
- $k$ -space optimization makes the difference:
  - Specific to reconstruction method
  - Specific to signal class (natural/MR images)
- Nonlinear Bayesian sampling optimization:  
General, goal-directed alternative to randomized trial-and-error
- Driven by scalable variational inference
  - Decoupling speeds up optimization dramatically
  - Penalized estimation technology inside

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# Collaborators

- Hannes Nickisch (now Philips Research, Hamburg)
- Rolf Pohmann, Bernhard Schölkopf (MPI Tübingen)

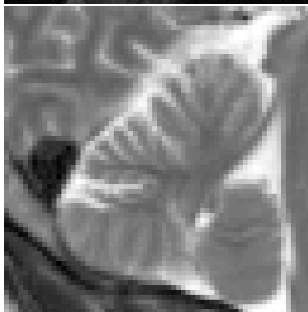
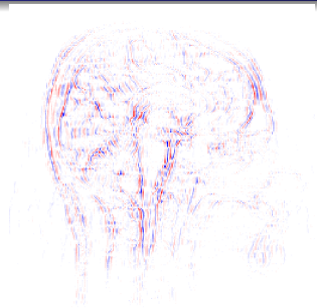
## Matlab Code

<http://www.mloss.org/software/view/269/>

## More Information

[http://lapmal.epfl.ch/proj/ed\\_mri/index.shtml](http://lapmal.epfl.ch/proj/ed_mri/index.shtml)

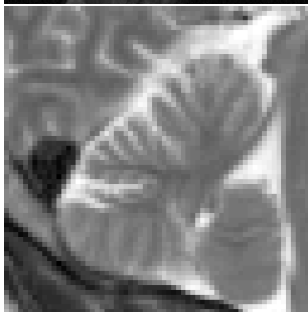
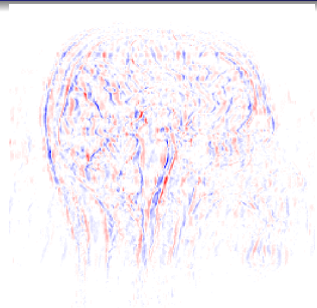
# Experimental Results: 1/4 Nyquist



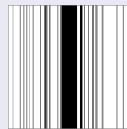
Low Pass

$\ell_2 = 8.0319$

# Experimental Results: 1/4 Nyquist

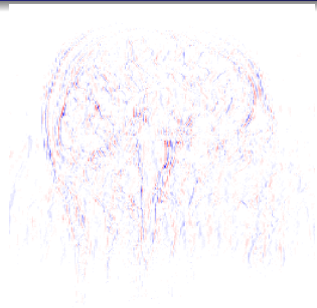
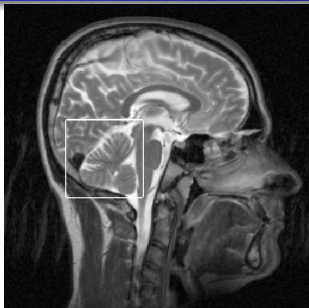


VD Random

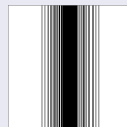


$$\ell_2 = 8.8056$$

# Experimental Results: 1/4 Nyquist



Bayes Optim.



$$\ell_2 = 6.0635$$