

FCC-ee Tracker Full Simulation : Detailed Vertex Digitization Studies and Outlook

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- **Context and Motivation**
- CLD Detector Concept and All Silicon tracker
- Silicon sensor digitization: Our Module *VTXDigiDetailed*
- Tracking Performance and validation against the parametric reference

❖ Motivation for a Precise Digitiser :

- **From Ideal to Real:** We need to simulate realistic detector response to validate model capabilities
- **Physics Scope:** Essential for studying detector performance in high-occupancy environments
- **Broader Integration:** To build a robust, parameter-based tool that can easily be adapted to test other detector geometries

❖ From Software R&D:

- **New *VTXdigiDetailed* Module:** Developed by IP2I team ([MR](#), officially merged) and previously presented by Jessy Daniel ([9th FCC Physics Workshop 2026](#))

❖ To Physics & Performance Validation:

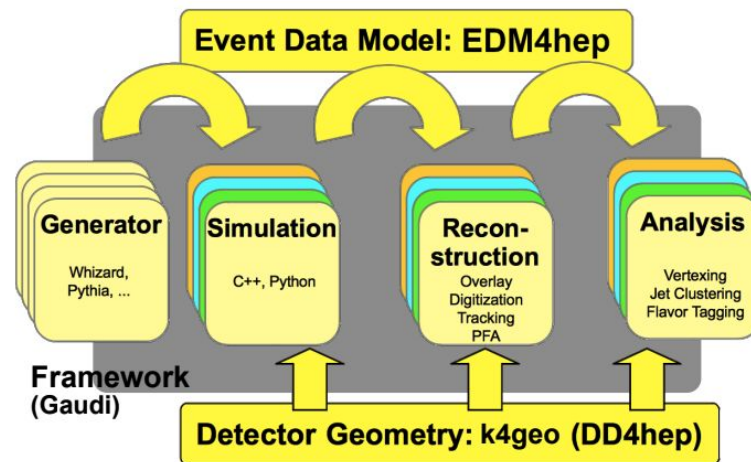
- **Objective:** Transition from idealized parametric smearing to a physics-driven response (Integrated in key4hep)
- **R&D Feedback Loop**

Towards a Turnkey Software Stack :

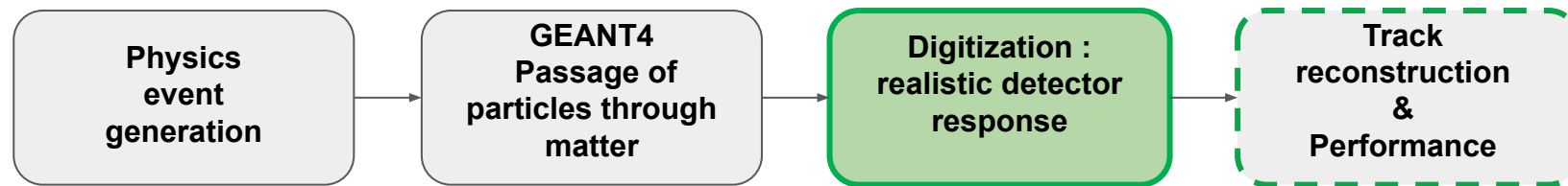
- **Software initiative** created in **2019** to optimise efforts in the context of **future colliders studies**.
⇒ Aims to **connect** and **extend** the individual packages towards a **complete data processing framework**
- ❖ **Common effort** from FCC, CLIC/ILC, EIC, CEPC, Muon Collider etc.
 - **Preserves** and **adds** existing functionality from iLCSoft, FCCSW, CPECSW...
 - **Builds on top of the experience** from LHC and **results of R&D**
- ❖ Having **common building blocks** enables **synergies** across **future collider communities**

★ Main ingredients :

- **Event data model** : EDM4hep, based on **PODIO**, **AIDA** project
- **Event processing framework** : **Gaudi**, used in LHCb, ATLAS...
- **Detector description** : **DD4hep**, **AIDA** project
- **Package Manager** : **Spack**



➤ Diagram of the full simulation chain



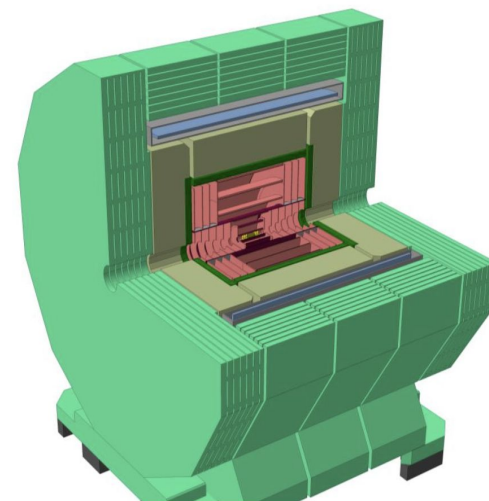
- **Digitization** translates the energy deposited in the silicon into realistic electronic signals. It is the step that determines how faithfully the simulation reproduces the real performance expected from a sensor.

★ Our work :

- **Developing the full simulation chain** - in particular by designing a detailed digitization for the silicon tracker sensors of the FCC-ee and assessing its impact on performance.

★ Why CLD ?

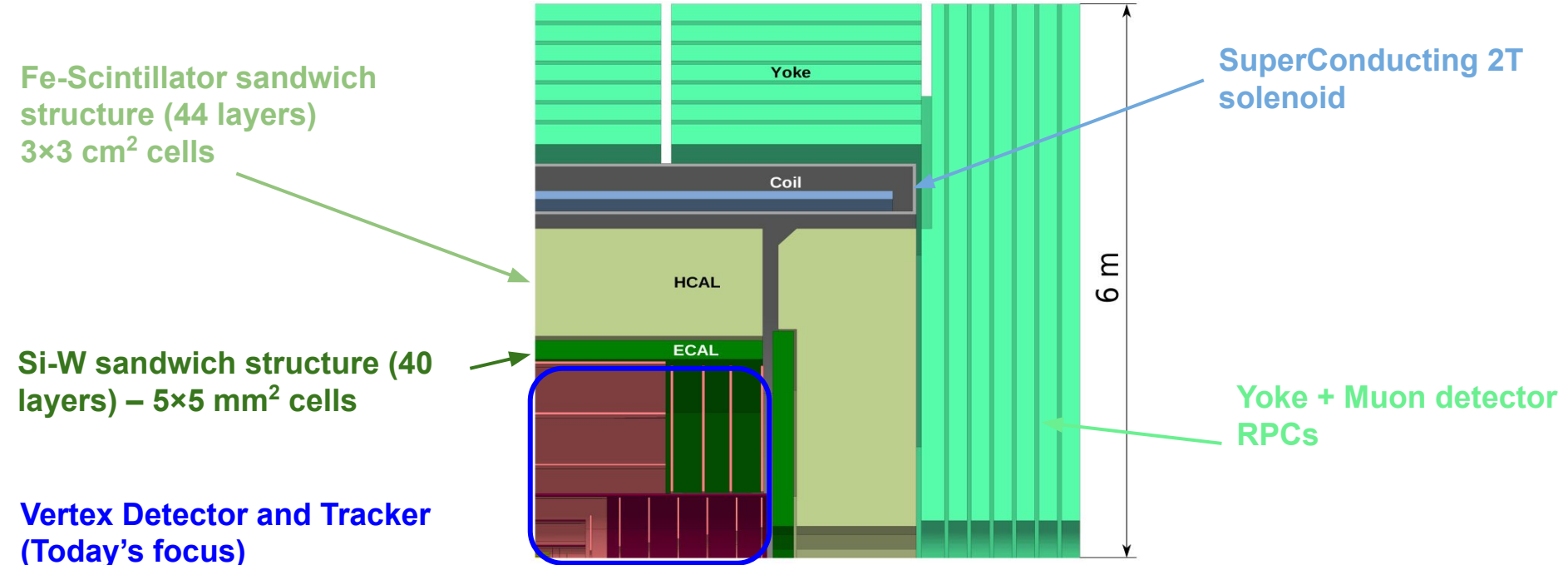
- **CLD - CLIC- like detector concept** - is built on a fully silicon tracker, which makes it a natural testbed to develop and validate our chain ⇒ but remain a detector-independent method



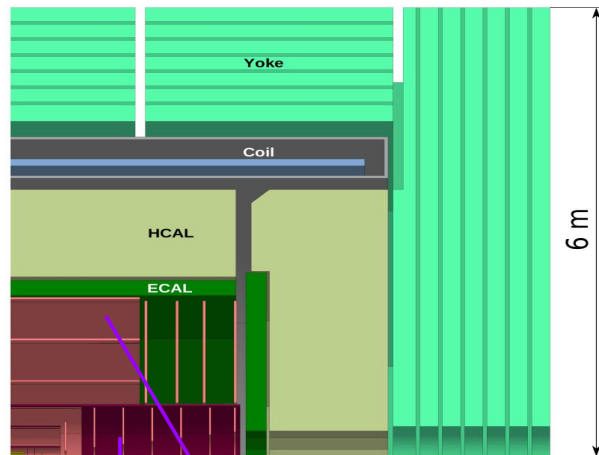
Ref : [CLD Detector Concept](#)

- Context and Motivation
- **CLD Detector Concept - All-Silicon tracker and vertex detector**
- Silicon sensor digitization: VTXDigiDetailed
- Tracking Performance and validation against the parametric reference

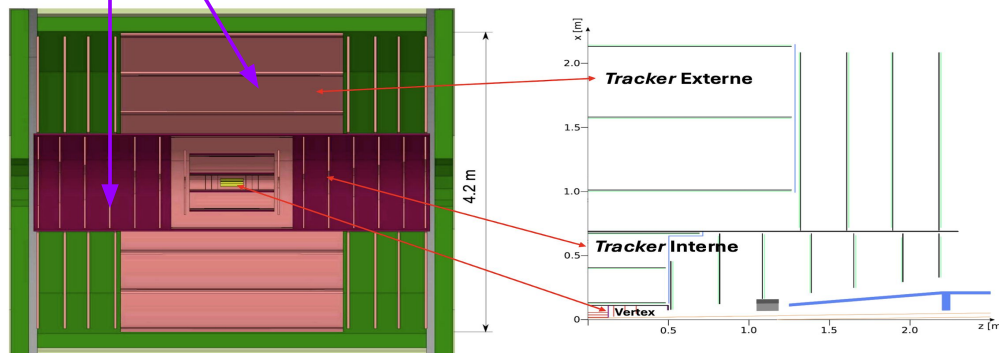
- CLD = **CLIC-like detector** = one of the detector concept for FCC-ee
- General Layout close to CMS but different technology
- **All-Silicon** Vertex detector and Tracker immersed in 2T magnetic field



More details in : [CLD Detector Concept](#)



Sub-detector	Technologies	Resolution
Vertex	Pixels MAPS 25x25 μm^2	$\sim 3 \mu\text{m}$
Inner Tracker except 1st endcap	Bandes Si (pitch 50 μm) Pixels MAPS 50x50 μm^2	$\sim 7 \times 90 \mu\text{m}$ $\sim 5 \times 5 \mu\text{m}$
Outer Tracker	Bandes Si (pitch 50 μm)	$\sim 7 \times 90 \mu\text{m}$

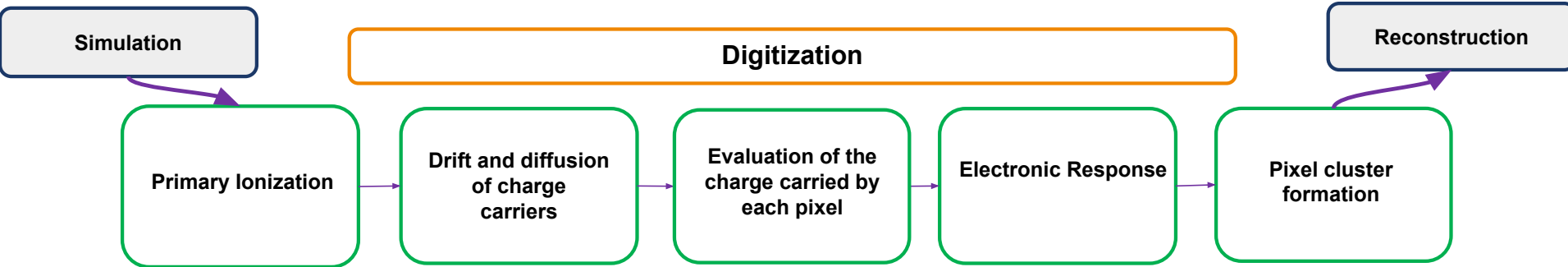


Modifications made to the vertex detector :

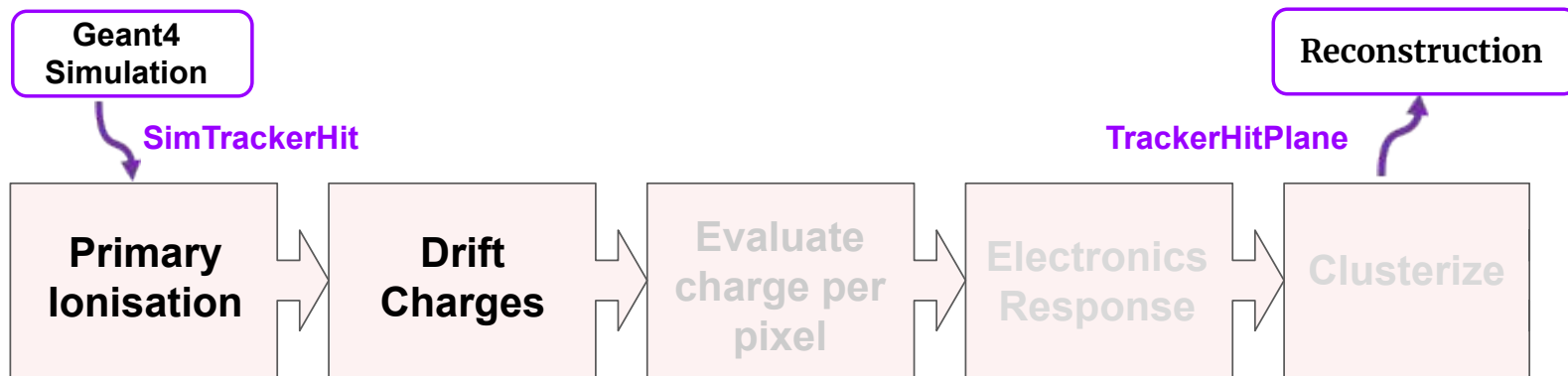
- Pixels : $25 \times 25 \mu\text{m}^2 \rightarrow 20 \times 20 \mu\text{m}^2$
(configurable in the module)
- Sensitive Layer : 50 $\mu\text{m} \rightarrow 10 \mu\text{m}$ thickness
- Goal : Represent a MAPS sensor with a greater fidelity
(Monolithic Active Pixel Sensor)

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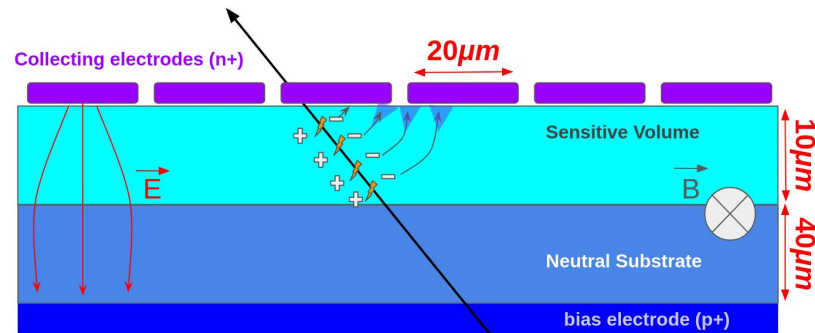
- ❖ **Sensor response** (*VTXDigiDetailed module*, developed at IP2I) :



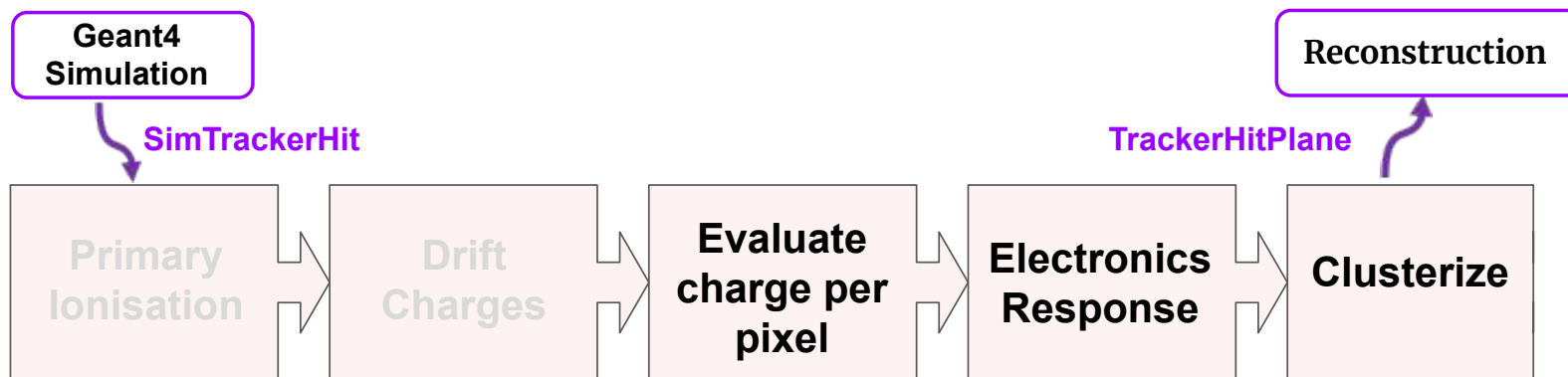
- ★ **Generic & reusable:** one module → all silicon subdetectors (VT, IT, OT, barrel & endcap)
- ★ **Fully steerable:** pixel pitch, threshold, smearing etc. in the config file - no recompilation
- ★ **Geometry-aware:** thickness & sensor dimensions read directly from DD4hep → automatically follows geometry updates



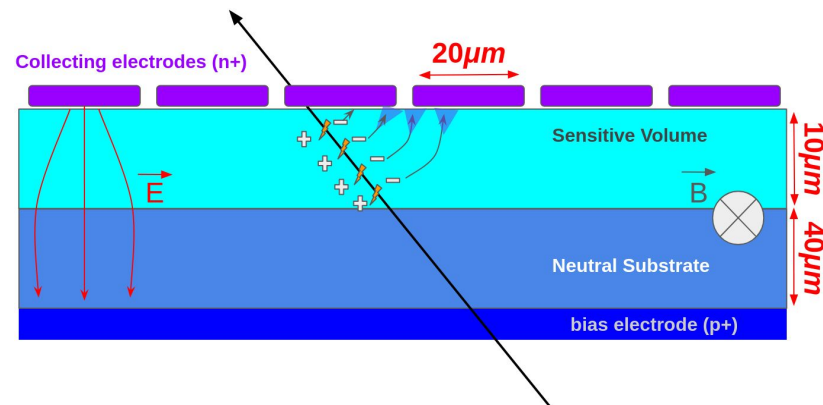
- ❖ Geant4 gives the path of the particle, the deposited energy, and hit position and time
 - The path of the particle is divided into **segments**
 - The energy deposited is divided uniformly into each segment and converted into **number of electrons**
- ❖ Drift each charge in the depletion area according to magnetic and electric fields + Consider thermal diffusion
 - Drift from **Lorentz Angle** and **E field** considered **uniform**
 - Thermal diffusion is considering by creating a **charge cloud**



* Thanks to Jessy Daniel's **Merge Request** and already presented in previous talks (ie, [9th FCC Physcis Workshop 2026](#))



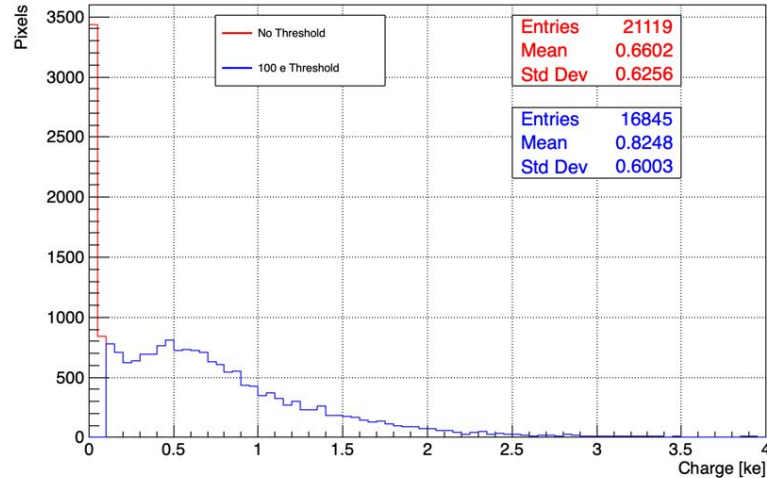
- ❖ Deduce the **energy deposited** in each pixel/strip
- ❖ Consider **electronic response** (Only Threshold for now) :
- ❖ **Clusterization**
 - Get the central position of the clusters with a weighted average
- ❖ Return a TrackerHitPlane to reconstruction containing per hit :
 - Position + uncertainty
 - Time + uncertainty
 - Total recorded energy



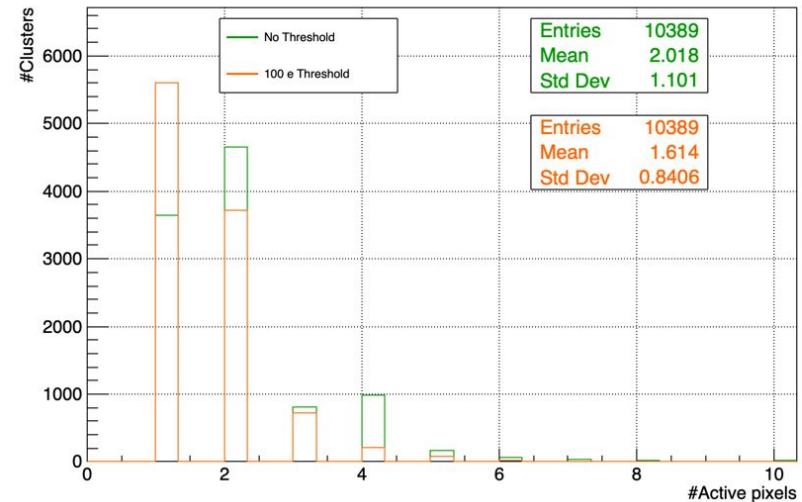
Some results: Pixel and Cluster

- A test have been runned with **2000 muons generated with a 10 GeV energy**
 - Test the energy per pixel and the number of pixels per cluster : example of VTX Barrel.
 - Before Threshold : **$\sim 66 \text{ e-}/\mu\text{m}$** , consistent with expectation ([2011 JINST 6 P06013](#))
 - Number of pixels reduced by **20% by threshold**
 - Number of clusters **stays stable**

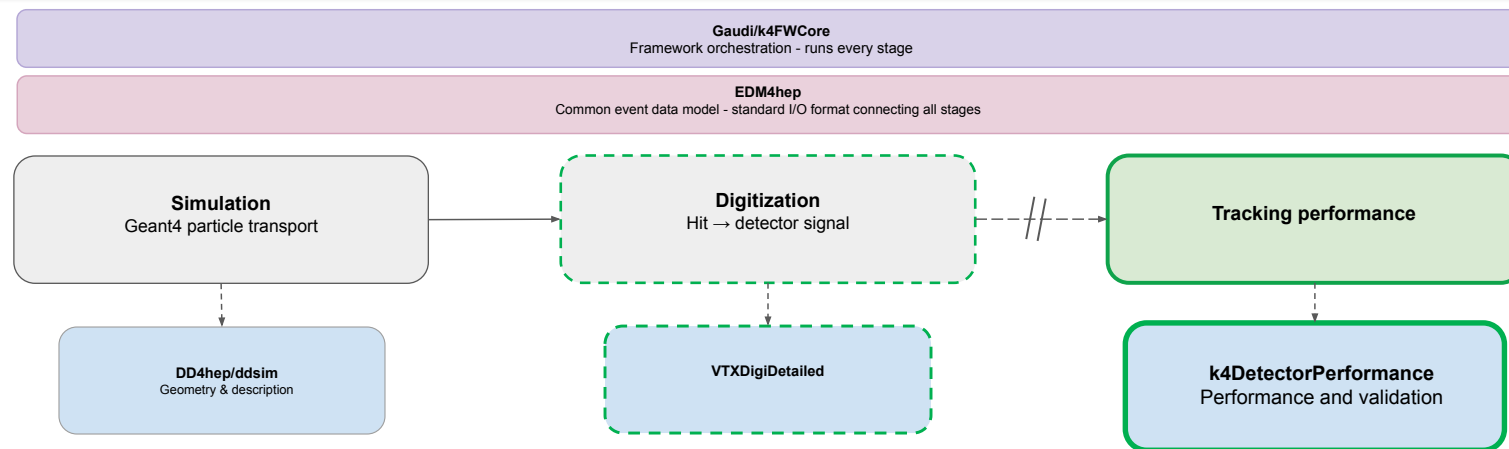
Charge per pixel for VTXBarrel



Number of pixels per cluster for VTXBarrel



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❖ k4DetPerformance - Inherited validation framework

- Tracking performance suite from [G. Sadowski \(IPHC IN2P3\)](#) PhD Thesis. Runs on the Key4hep stack

Track-truth matching

- Reco tracks associated to true “MC” (simulated) particles via shared hits

Track parameters

- For the five perigee/helix parameters :
 - a. Curvature Ω
 - b. Azimuthal Angle φ_0
 - c. Impact Parameter d_0
 - d. Z - position z_0
 - e. Slope $\tan\lambda$

Residuals

- For each fitted track, the residual is $\Delta = \text{reco} - \text{true}$
- the resolution is its width $\sigma(\Delta)$ extracted per (θ, p) configuration

- ❖ **Objective** : Quantify the benefit of a realistic digitization (VTXDigiDetailed) on tracking performance, *via* a direct comparison with the parametric Gaussian-smearing baseline

➤ **Two digitization models compared:**

Baseline (reference) - Gaussian Smearing

- Hit position smeared according to a Gaussian of fixed width
- Fast, but less realistic

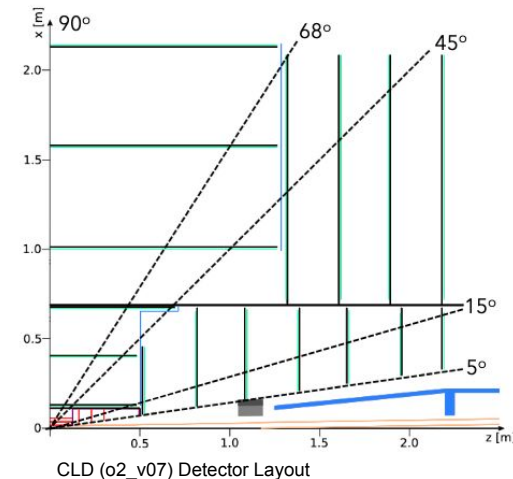
Detailed digitizer (our model) - VTXDigiDetailed

- Accounts for the fine effects of the particle-matter interaction: creation, transport and diffusion of charge carriers
- More computationally expensive, but more realistic

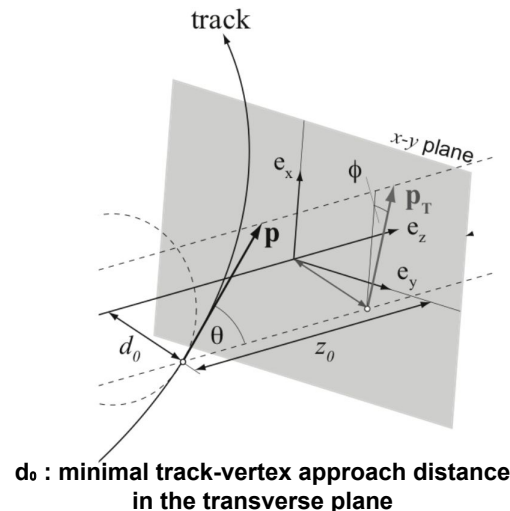
➤ **Analysis chain** (built on *TrackerPerformanceScripts*, inherited from [G. Sadowski \(IPHC IN2P3\)](#)) :

- Particle-gun scan: polar angle $\theta \in [10^\circ, 90^\circ]$ and momentum $p \in [1, 100]$ GeV, **2000 single muons per (θ, p) point.**
- Resolutions are extracted from the width of the Gaussian fit
- detailed-vs-parametric overlay **with ratio panel** + theoretical resolution curves

➔ **Result: resolution vs (θ, p) , detailed vs parametric**, quantifying where realistic digitization matters.

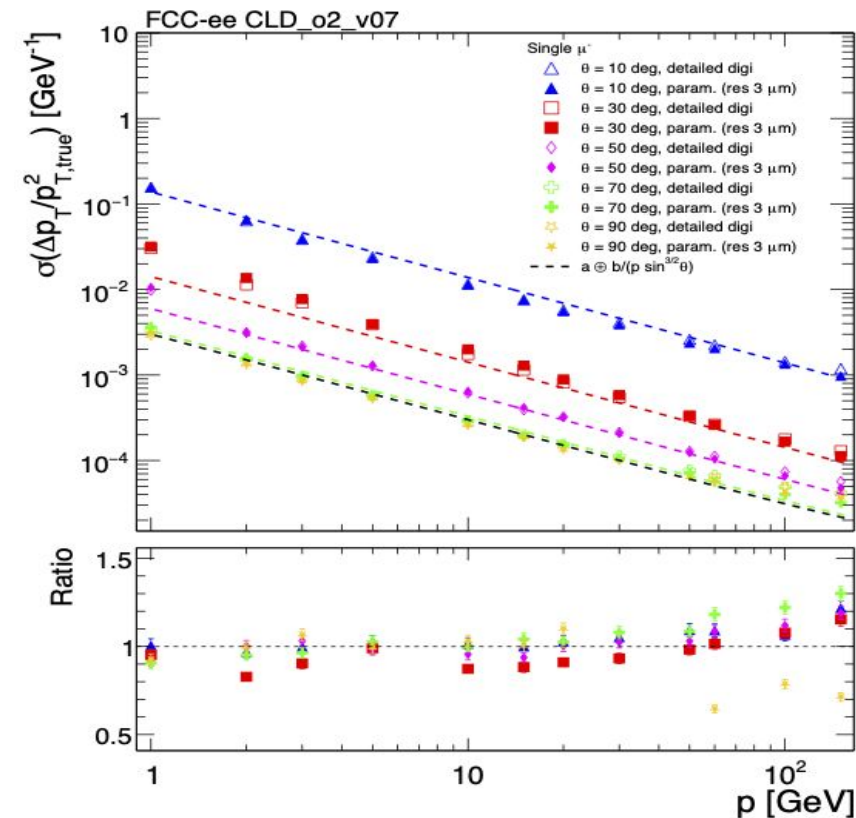


- ❖ Lower panel — Detailed VTXDigiDetailed / Baseline ratio



- **Good agreement** of the detailed module with the analytical reference
- **Discrepancy between the 2 module as expected:** our module reproduces realistic sensor effects that the baseline module idealizes

Values and formula are taken from [CLD Detector Concept](#) ref. paper



- Momentum resolution is driven by two components: multiple scattering and single-point measurement.

$$\sigma\left(\frac{\Delta p_T}{p_T^2}\right) = \underbrace{a}_{\text{multiple scattering}} \oplus \frac{\underbrace{b}_{\text{single-point measurement}}}{p \sin^{3/2} \theta}$$

- The spatial resolution provided by pixel clusters does not significantly impact the momentum curvature measurement.

⇒ **Conclusion: Detailed and parametric overlap as expected**

Values and formula are taken from [CLD Detector Concept](#) ref. paper

Summary :

- Co-development of a realistic, **fully parameterizable** digitization module for silicon sensors
- A simulation and performance evaluation chain that is **operational** and **validated on the CLD tracker**
- Performance is **consistent** with expectations across all tracking observables, validating our digitizer and **available in Key4Hep for the whole FCC community**

Next steps :

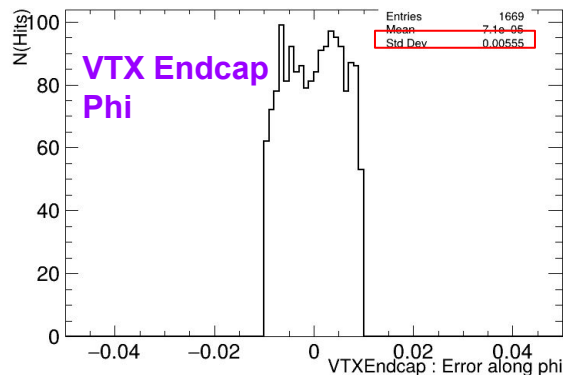
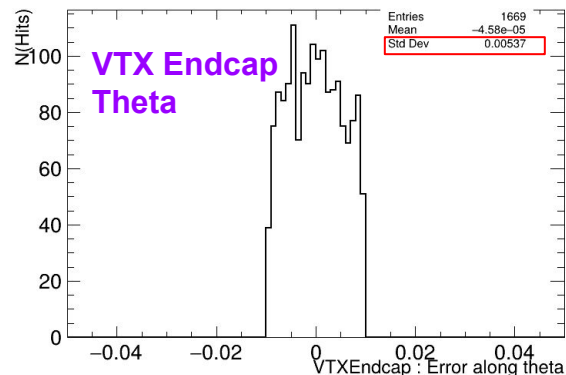
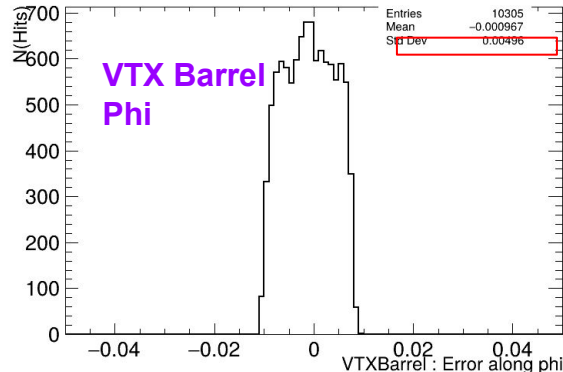
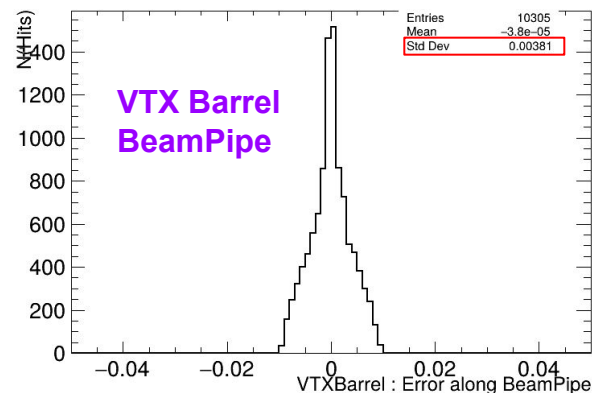
- **Generalize** the chain : other particle types, other detector concepts (ALFA)
- **Broaden** the physics scope: integration of beam-induced background (work in progress)
- **Prepare for the physics**: exploit this framework for tracker sensitive channels such as long-lived particles (**LLPs**)



Thanks for your attention !

Backup Slides

- Test the distance between the real hit and digitized one, example of Vertex Tracker :

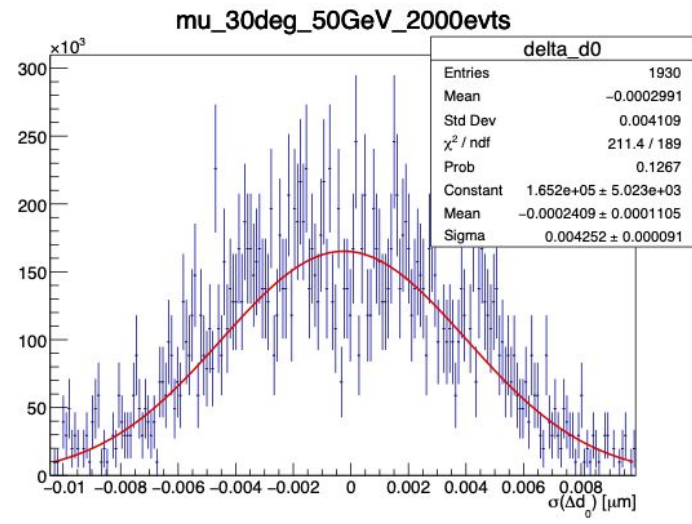


→ **Barrel** : Single hit resolution of $\sim 3.8\mu\text{m}$ along beampipe and $\sim 5.0\mu\text{m}$ orthogonal → **Do not reach the $3\mu\text{m}$ goal**

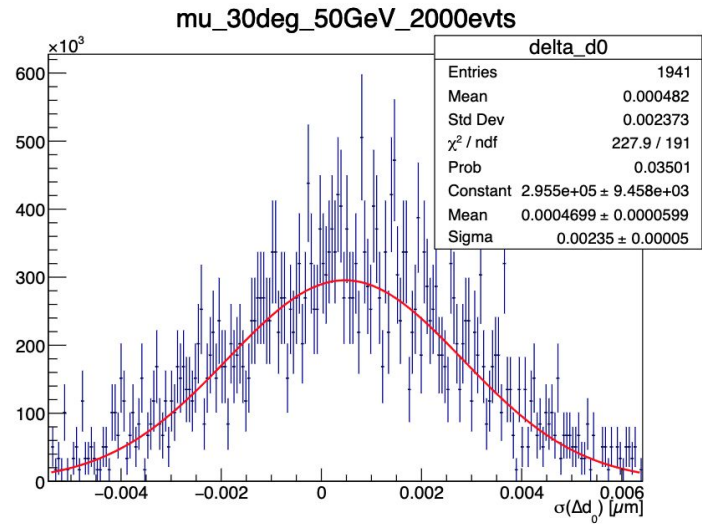
→ A shift of $\sim 1\mu\text{m}$ along ϕ = **Compatible with charge drift in magnetic field !**

→ **Encap** : $\sim 5.5\mu\text{m}$ single hit resolution → **Do not reach the $3\mu\text{m}$ goal**

- ❖ Analysis Framework : [TrackerPerformanceScripts](#) (*Standalone / Non-Gaudi*) and adapted from [G. Sadowski's PhD work](#)
 - Match reconstructed tracks directly to simulated (true) particles.
- ❖ Resolution Definitions & Fits : Extracted from the width (sigma) of a Gaussian fit



2k - muon - 30° - 50 GeV - Detailed (new) module



2k - muon - 30° - 50 GeV - Parametric module

❖ **Momentum resolution**

- The relative momentum resolution combines two terms:
- **a - multiple scattering**, plateau at low momentum, set by material budget x/X_0
 - **b - single-point measurement term** $\propto \sigma_{r\phi}$ the point error, the lever arm $1/L^2$, the field $1/B$ and the number of layers **N** (geometry-fixed)

$$\sigma\left(\frac{\Delta p_T}{p_T^2}\right) = a \oplus \frac{b}{p \sin^{3/2} \theta}$$

- **Why both digitizers agree as expected:** the digitizers enter only via $\sigma_{r\phi}$ in b, suppressed by **average numbers of N layers** and **L²**
- **detailed and parametric overlap**

θ (°)	a	b
10	7.4×10^{-5}	0.010
30	1.8×10^{-5}	0.005
50	9.2×10^{-6}	0.004
70	8.3×10^{-6}	0.003
89	8.6×10^{-6}	0.003

❖ **Transverse impact parameter resolution**

$$\sigma(d_0) = \sqrt{a^2 + \frac{b^2 \cdot \text{GeV}^2}{p^2 \sin^3(\theta)}}$$

- **a $\approx$ 5 μ m**
- **b $\approx$ 15 μ m**

Values and formula are taken from [CLD Detector Concept](#) ref. paper

1. Michael BENEDIKT. *Future Circular Collider Feasibility Study report Volume 1 : Physics and Experiments*. Rapp. Tech. CERN Document Server, mars 2025. DOI : 10.17181/CERN.9DKX.TDH9
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6. Gaëlle Sadowski. « k4DetPerformance: A Framework for Tracking Performance Studies in Full Simulation Environments ». In : The Third ECFA workshop. Paris. 2024. url : https://indico.in2p3.fr/event/32629/contributions/142944/attachments/87747/132482/k4DetPerf_poster_GaëlleSadowski.pdf