



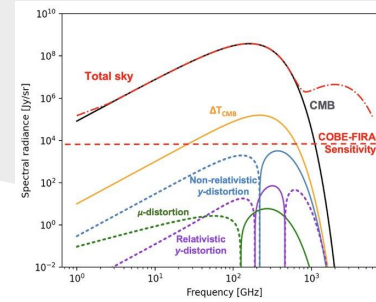
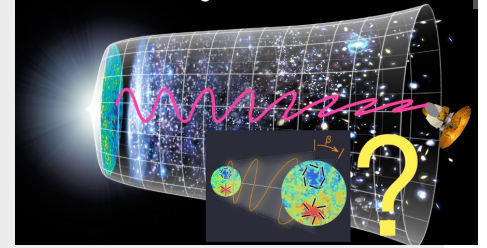
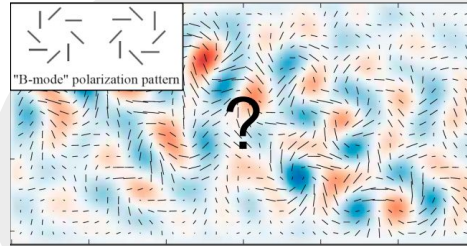
Component separation for CMB experiments

Alessandro Carones

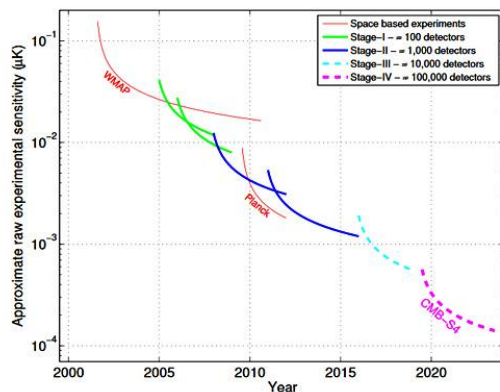
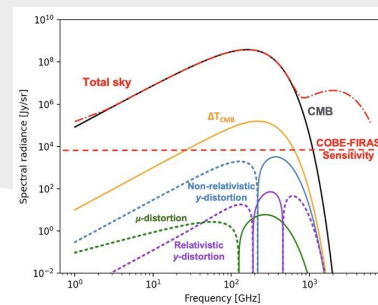
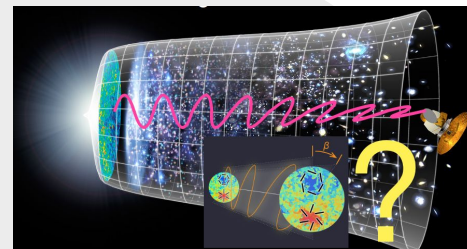
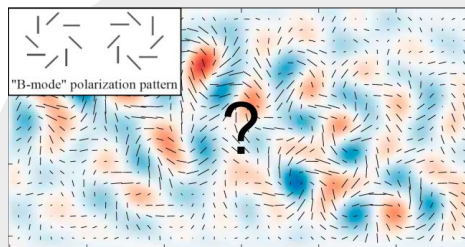


New CMB signals

1

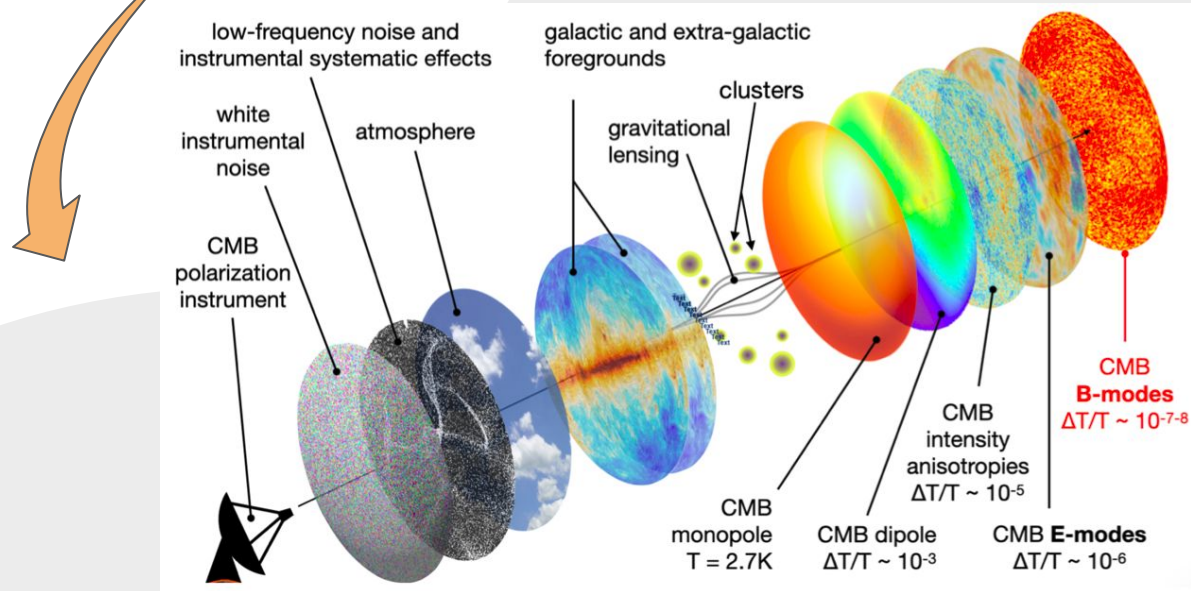


New CMB signals



Better sensitivities

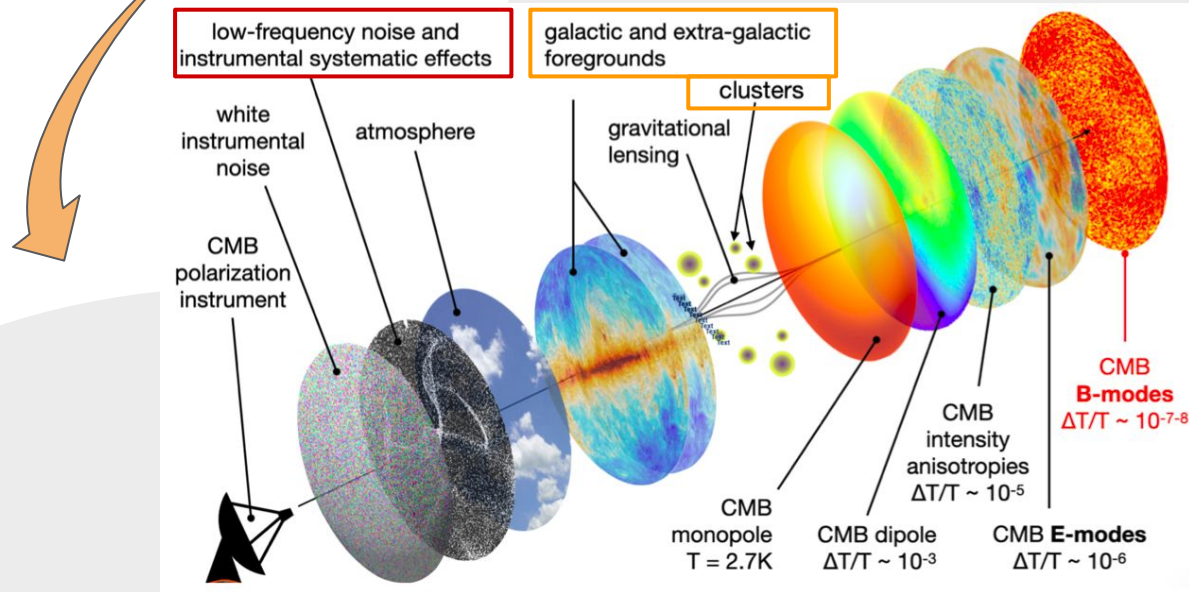
New CMB signals



Credit: J. Errard

Better sensitivities

New CMB signals



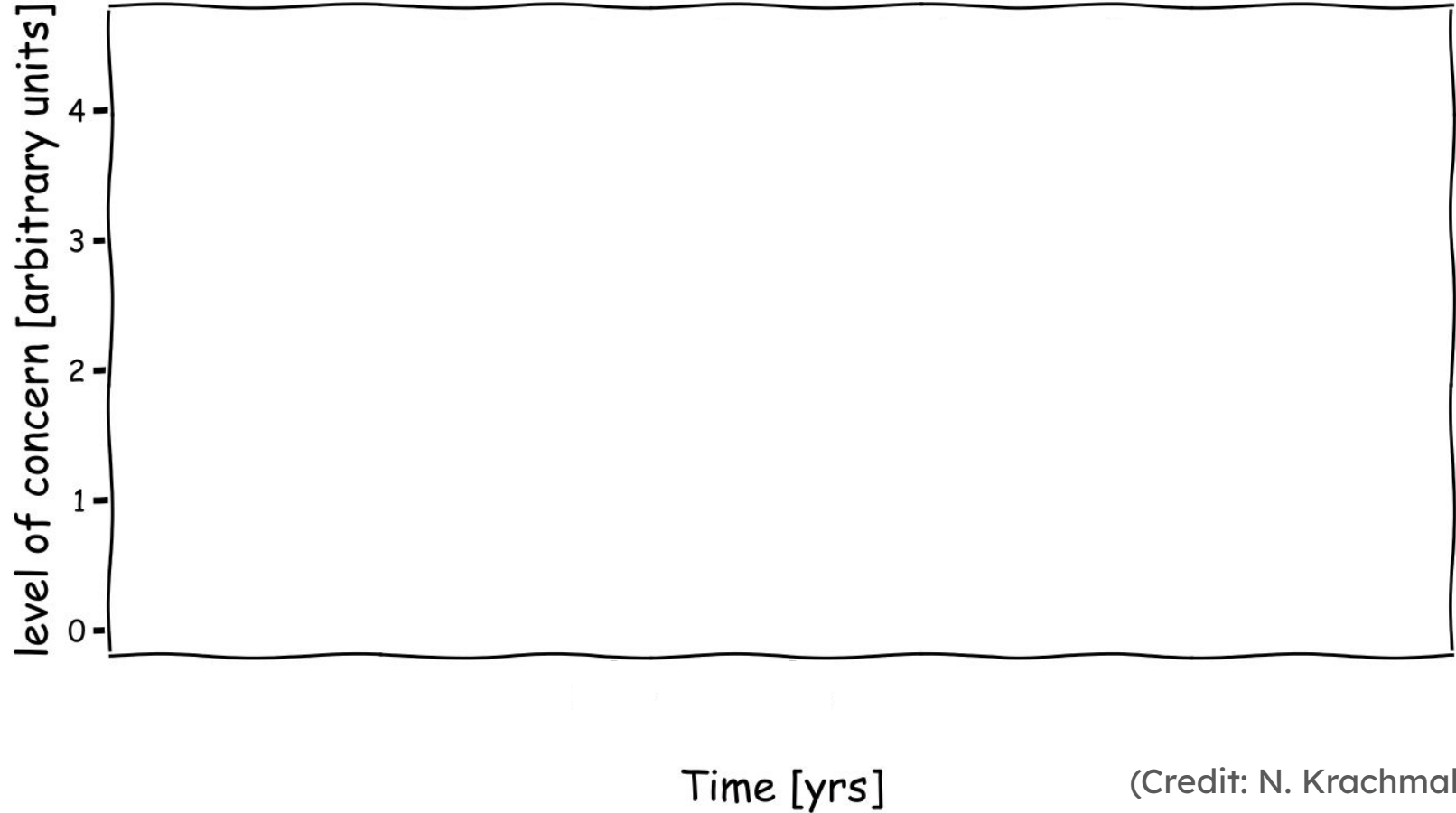
Credit: J. Errard

Better sensitivities

($\propto$ component-separation development)



FOREGROUND AWARENESS TIMELINE

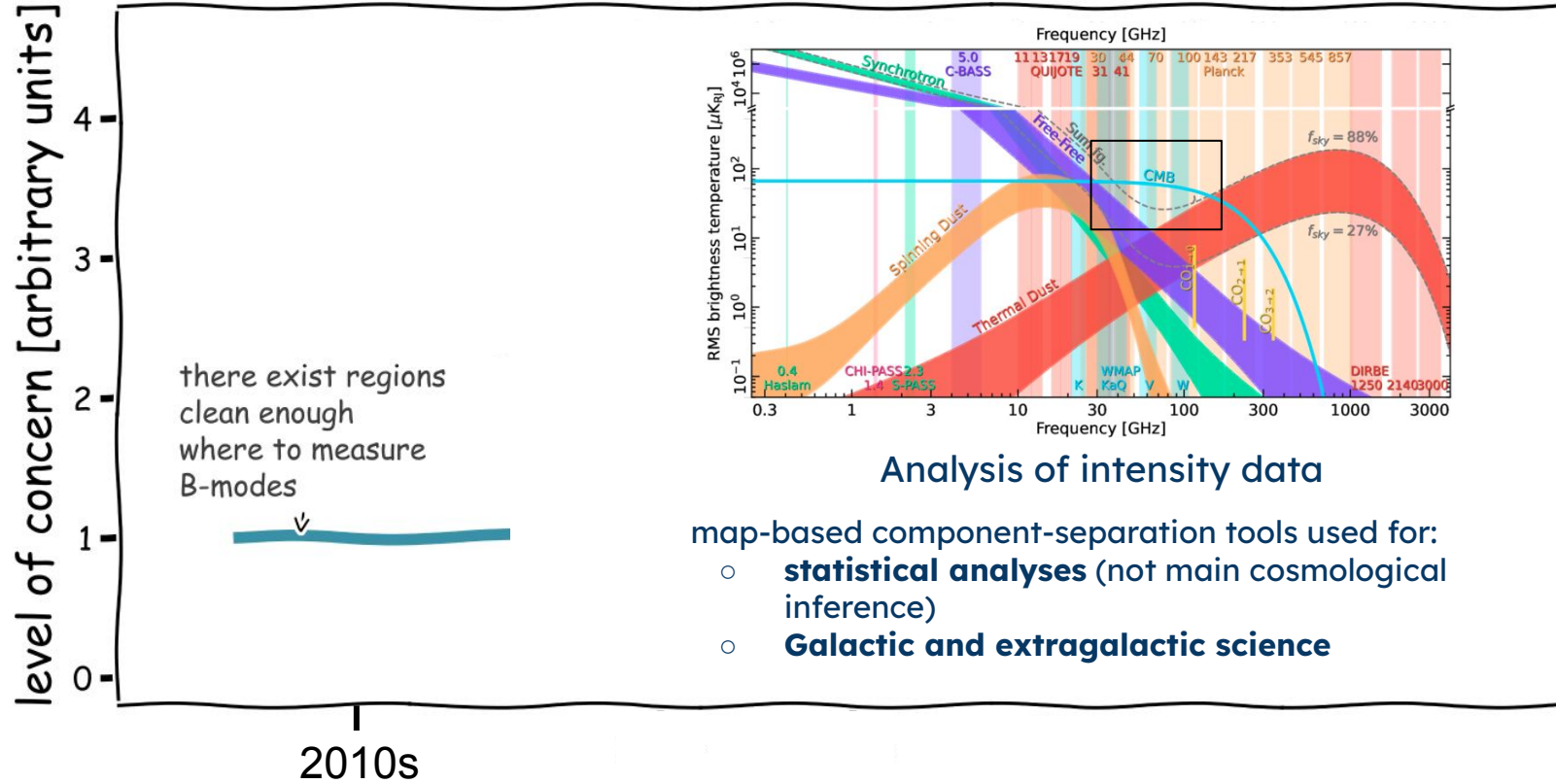


(Credit: N. Krachmalnicoff)

($\propto$ component-separation development)



FOREGROUND AWARENESS TIMELINE

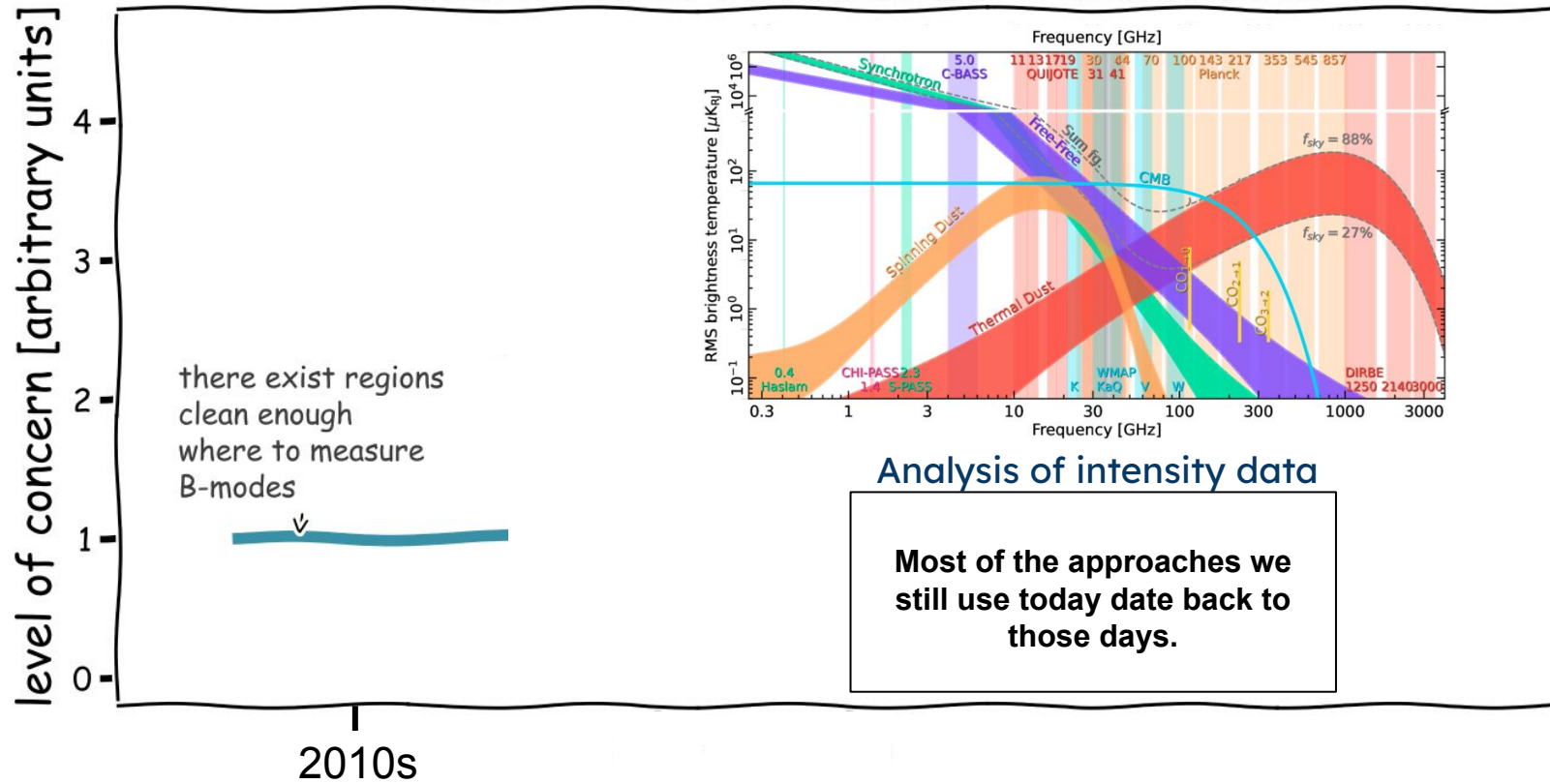


(Credit: N. Krachmalnicoff)

($\propto$ component-separation development)



FOREGROUND AWARENESS TIMELINE

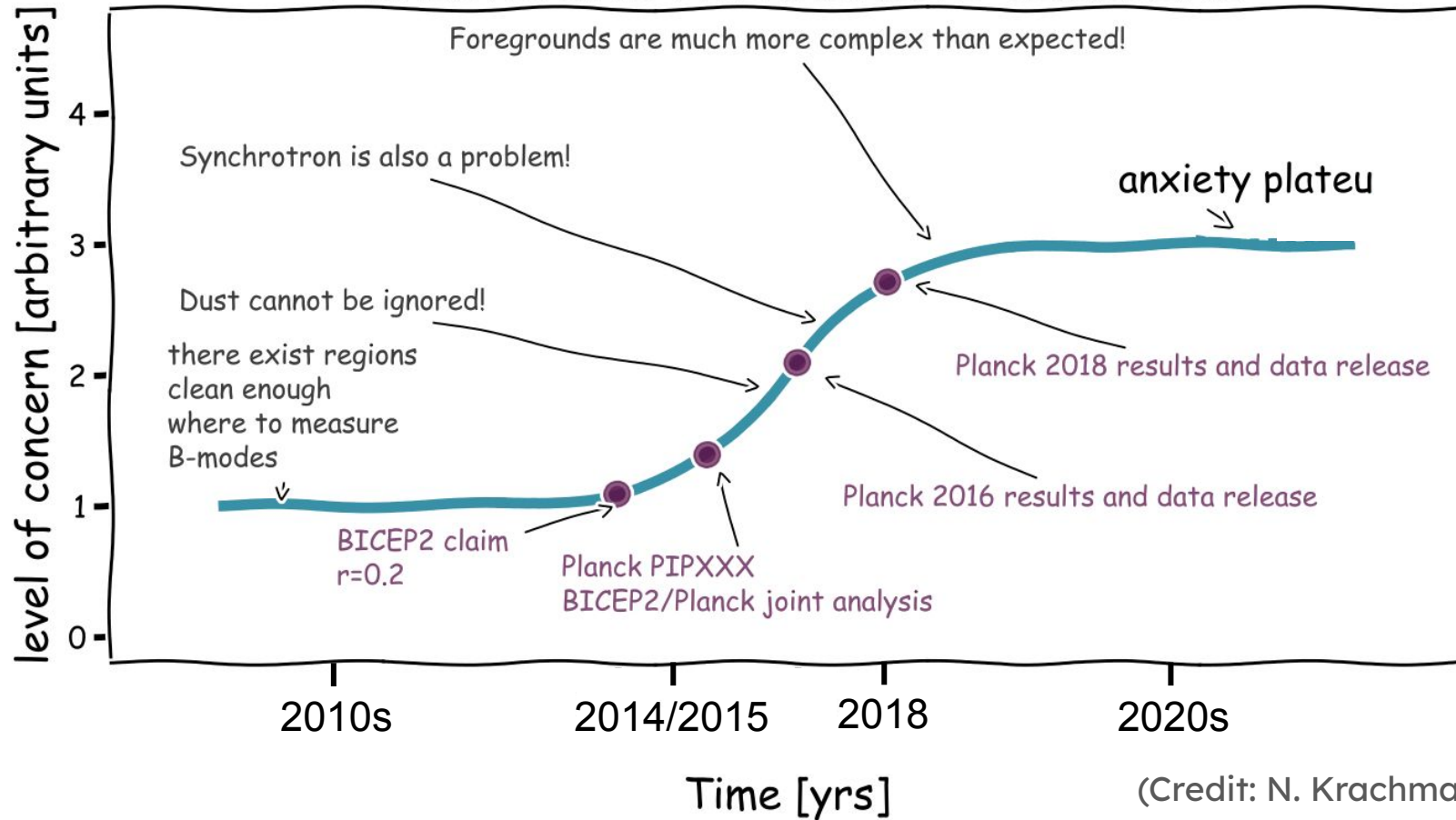


(Credit: N. Krachmalnicoff)

($\propto$ component-separation development)

2

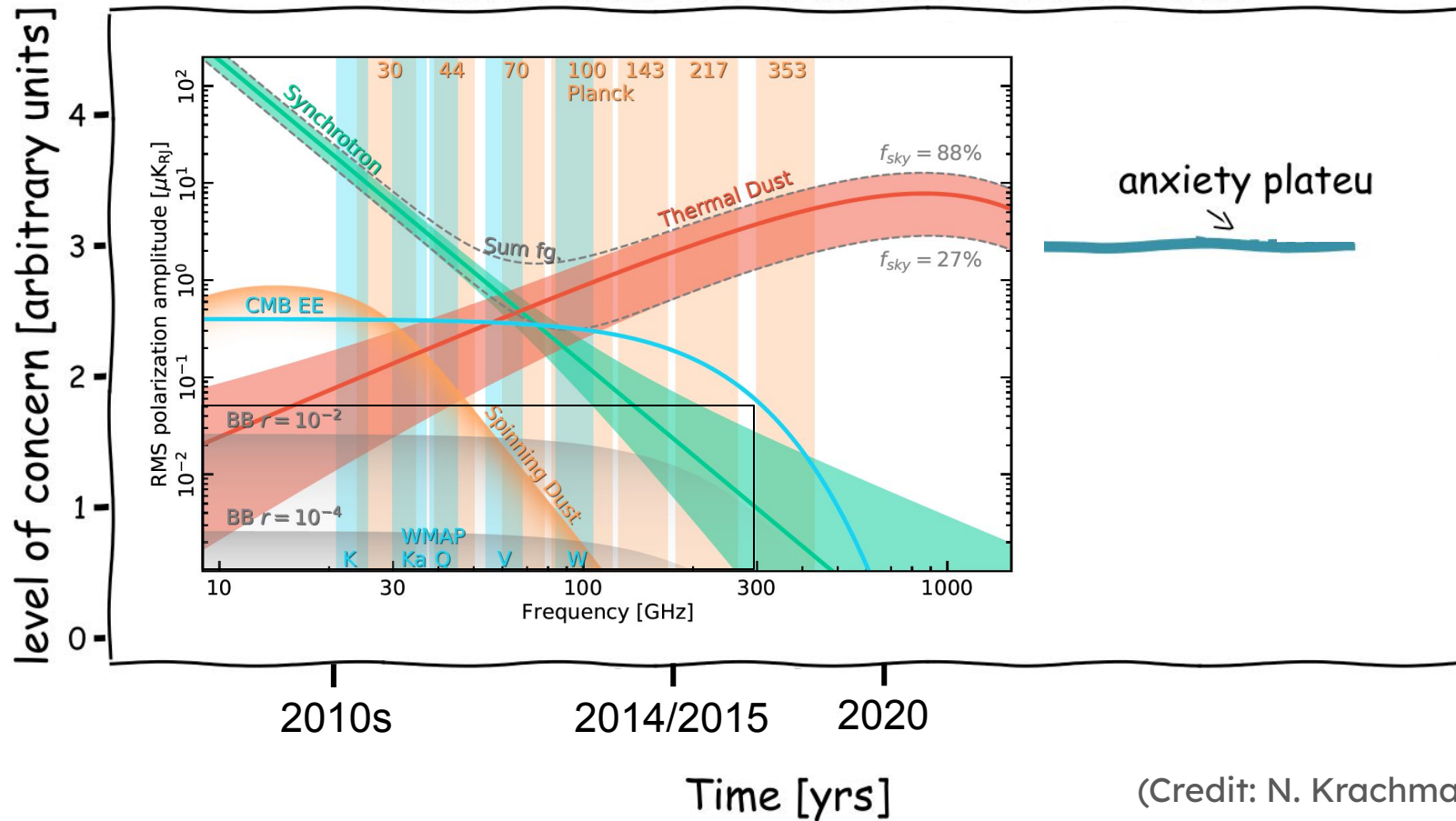
FOREGROUND AWARENESS TIMELINE



($\propto$ component-separation development)



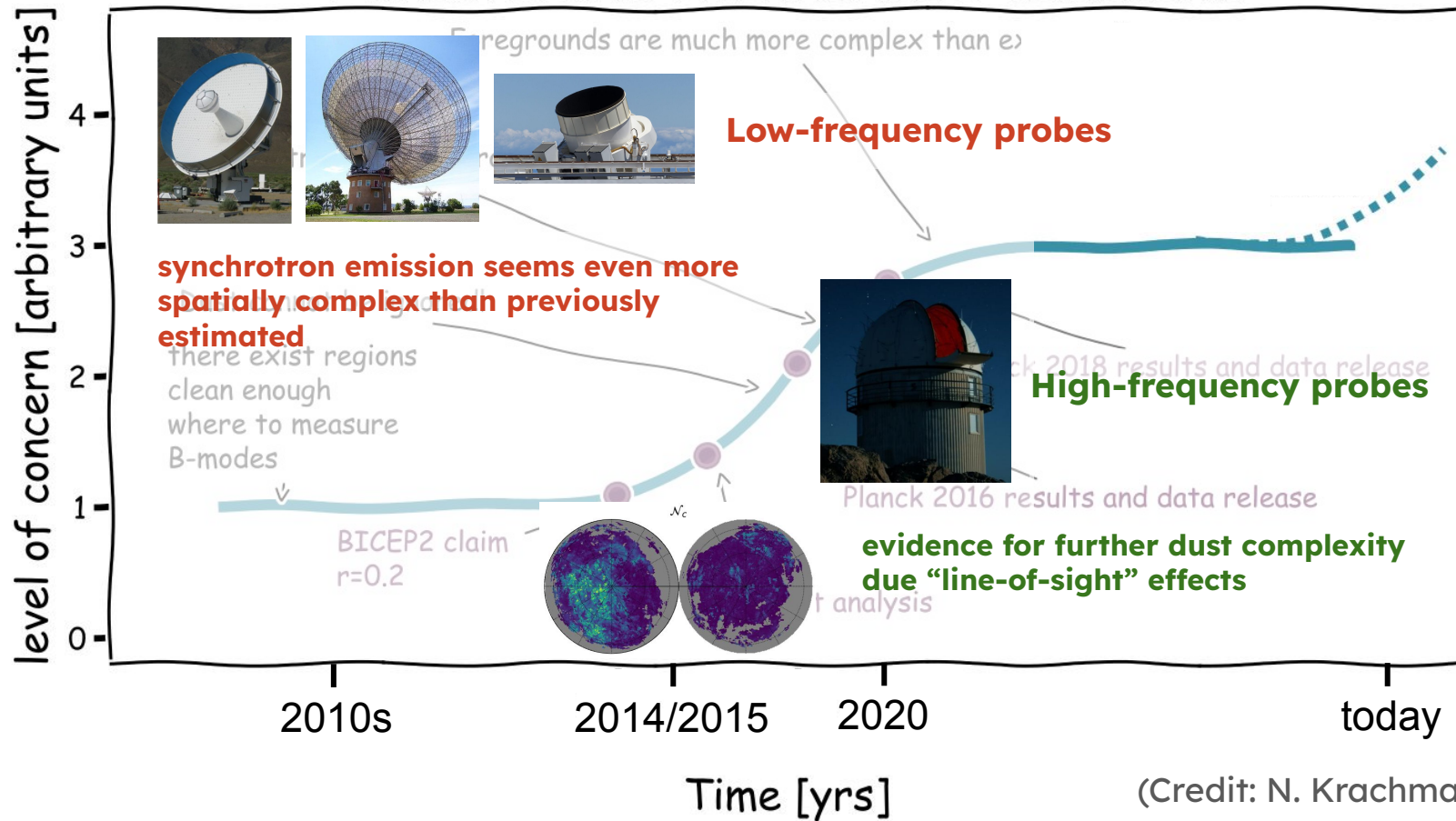
FOREGROUND AWARENESS TIMELINE



($\propto$ component-separation development)

2

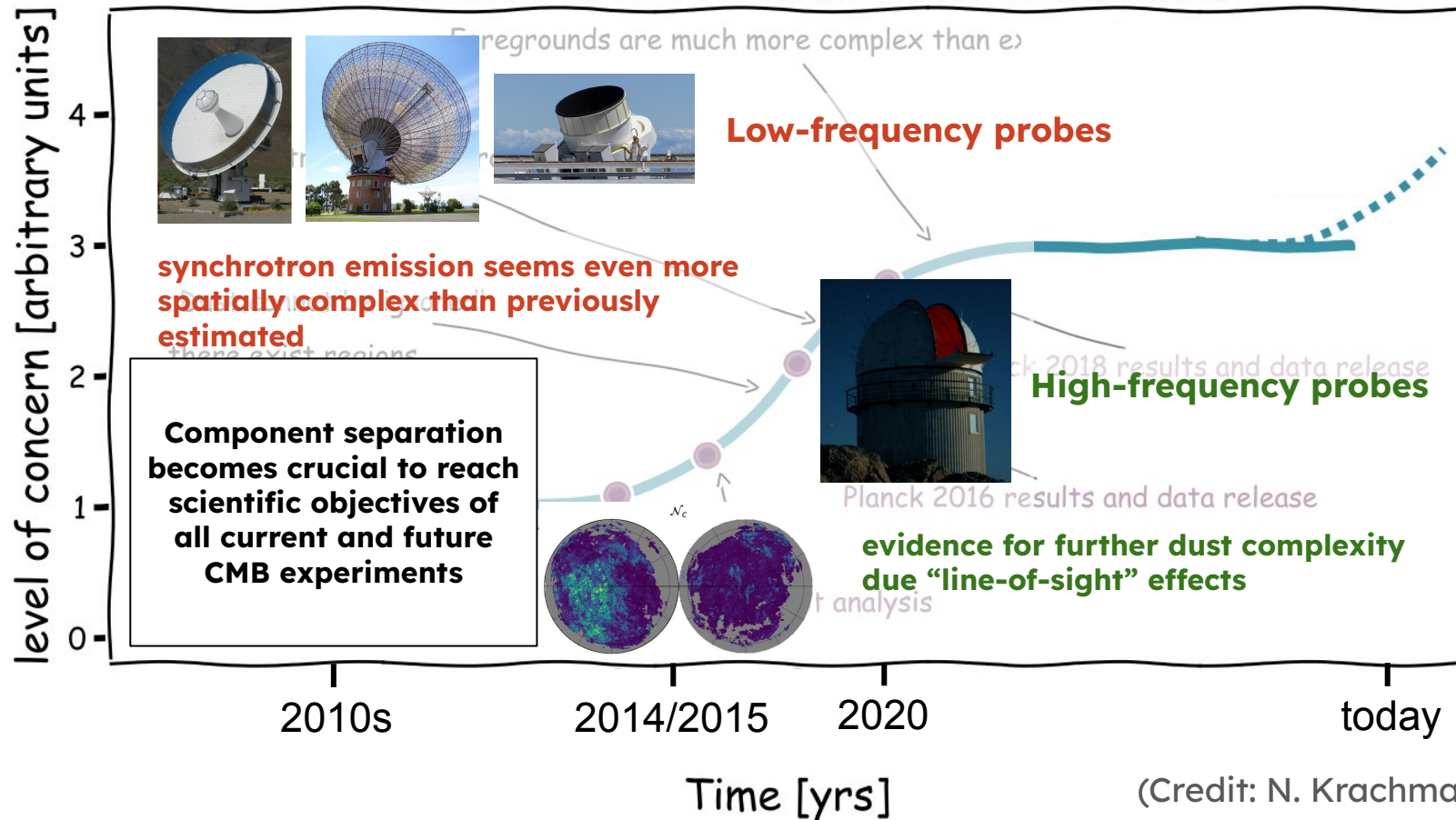
FOREGROUND AWARENESS TIMELINE



($\propto$ component-separation development)

2

FOREGROUND AWARENESS TIMELINE

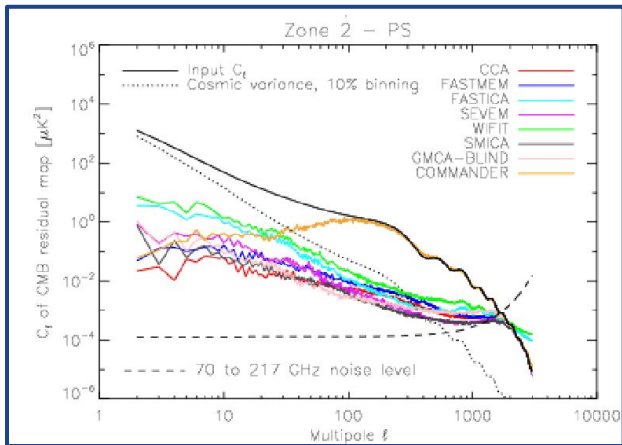


Component-separation wishlist

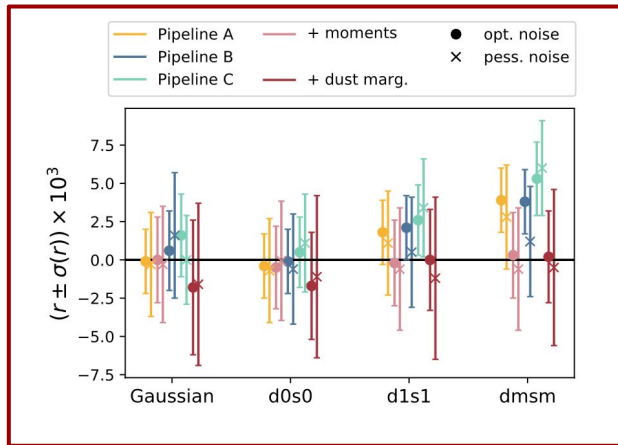
1. Being able to deal with foreground:
 - a. projected spatial complexity
 - b. spectral complexity
2. Absorb instrumental modelling/mitigate calibration systematics
3. Develop robustness tests - diagnostic of goodness of component separation
4. Reach the targeted sensitivity for scientific observables

CMB experiments wishlist

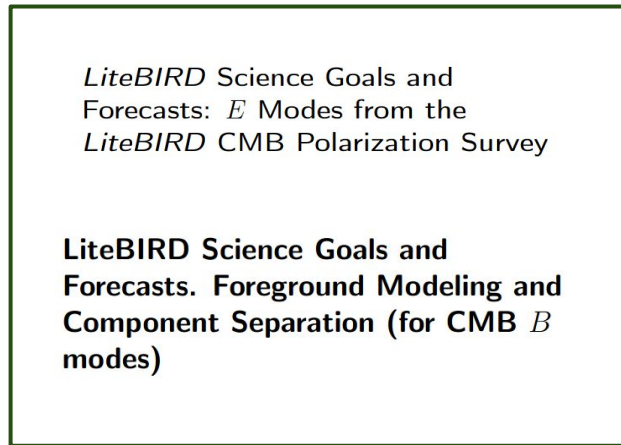
3



 **Planck**
[ Leach+ (2008)]



Simons Observatory
[ Wolz+ (2023)]



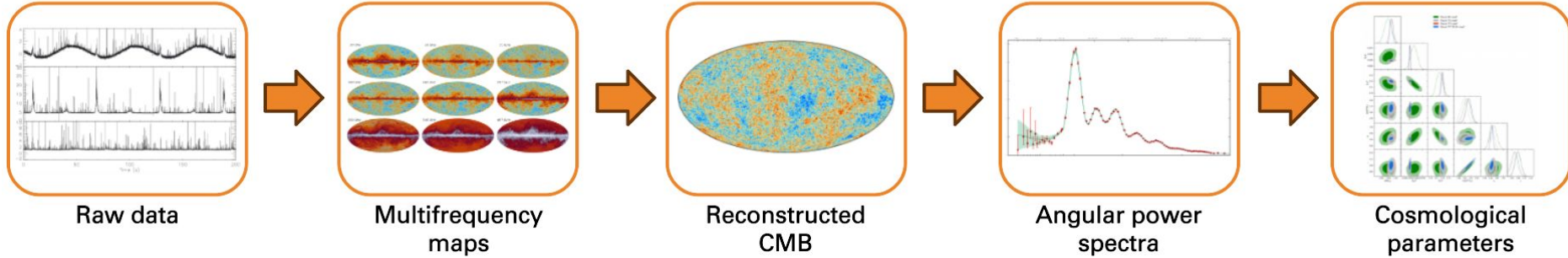
LiteBIRD
[ LB Coll. (in prep.)]

- Applying multiple (different) component separation pipelines
- Having additional strategies to mitigate potential foreground and systematic biases

will allow to validate any potential detection of new observables

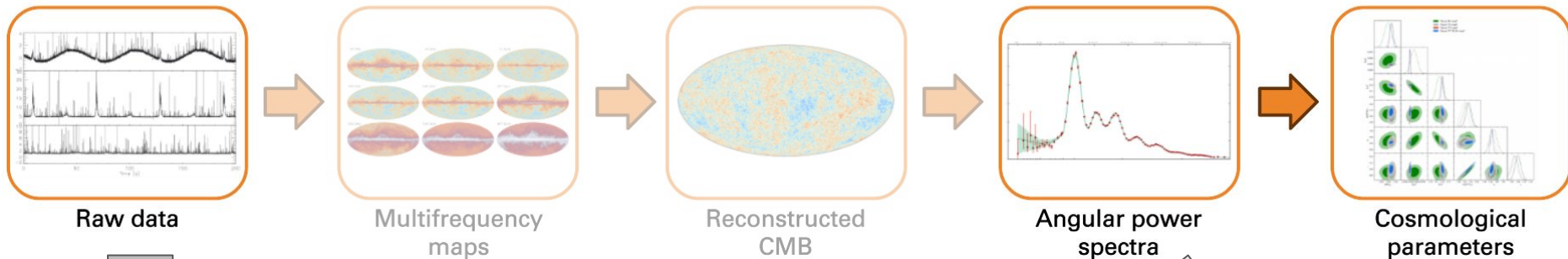
Component-separation basis

4



Component-separation from TODs

4



Integration of map-making, component separation and power spectrum estimation in a unified framework

data model

$$d_{j,t} = g_{j,t} \mathbf{P}_{tp,j} \left[\mathbf{B}_{pp',j}^{\text{symm}} \sum_c \mathbf{M}_c(\beta_{p'}, \Delta_{bp}^j) \mathbf{a}_{p'}^c + \mathbf{B}_{pp',j}^{\text{asymm}} (s_{j,t}^{\text{orb}} + s_{j,t}^{\text{fsl}}) \right] + n_{j,t}^{\text{corr}} + n_{j,t}^{\text{w}}$$

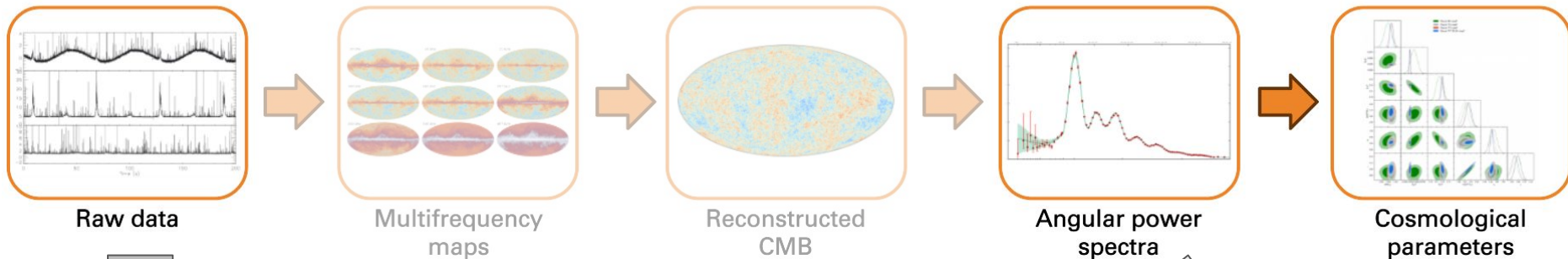
common
component-separation
parameters

$$\begin{aligned} g &\leftarrow P(g \mid d, \xi_n, \Delta_{bp}, \mathbf{a}, \beta, C_\ell) \\ n_{\text{corr}} &\leftarrow P(n_{\text{corr}} \mid d, g, \xi_n, \Delta_{bp}, \mathbf{a}, \beta, C_\ell) \\ \xi_n &\leftarrow P(\xi_n \mid d, g, n_{\text{corr}}, \Delta_{bp}, \mathbf{a}, \beta, C_\ell) \\ \Delta_{bp} &\leftarrow P(\Delta_{bp} \mid d, g, n_{\text{corr}}, \xi_n, \mathbf{a}, \beta, C_\ell) \\ \beta &\leftarrow P(\beta \mid d, g, n_{\text{corr}}, \xi_n, \Delta_{bp}, C_\ell) \\ \mathbf{a} &\leftarrow P(\mathbf{a} \mid d, g, n_{\text{corr}}, \xi_n, \Delta_{bp}, \beta, C_\ell) \\ C_\ell &\leftarrow P(C_\ell \mid d, g, n_{\text{corr}}, \xi_n, \Delta_{bp}, \mathbf{a}, \beta), \end{aligned}$$

Gibbs sampling

Component-separation from TODs

4



Integration of map-making, component separation and power spectrum estimation in a unified framework

data model

$$d_{j,t} = g_{j,t} \mathbf{P}_{tp,j} \left[\mathbf{B}_{pp',j}^{\text{symm}} \sum_c \mathbf{M}_{c,j} (\beta_{p'} \Delta_{bp}^j a_{p'}^c + \mathbf{B}_{pp',j}^{\text{asymm}} (s_{j,t}^{\text{orb}} + s_{j,t}^{\text{fsl}})) \right] + n_{j,t}^{\text{corr}} + n_{j,t}^{\text{w}}$$

common
component-separation
parameters

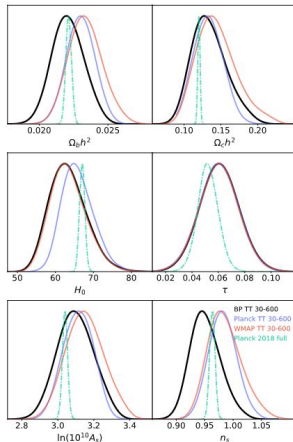
Extends a philosophy already adopted in latest Planck analyses (SRoll, NPIPE):
using astrophysical information to help calibrating data and mitigating systematics

Component-separation from TODs

5

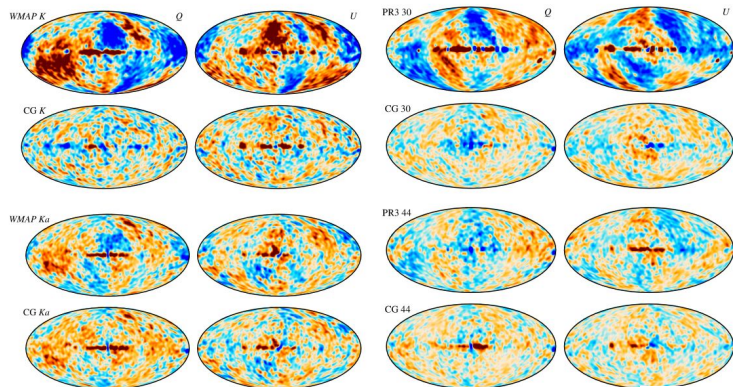
[ Paradiso+ (2022)]

End-to-end error propagation
(both in cosmological parameters
and foreground modelling)



**Robust mitigation of
systematic effects**

(actual component separation
less impacted by instrument systematics)

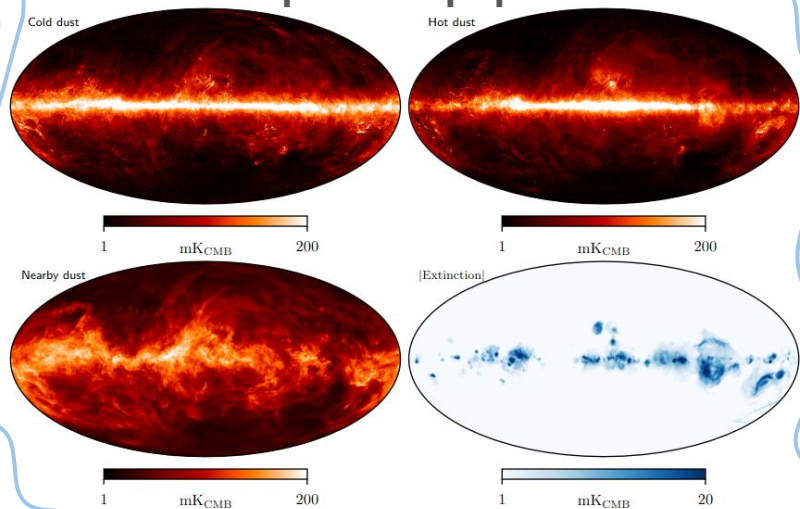


[ Watts+ (2022)]

Caveat:

having a *complete* and *robust* model
of instrument and sky

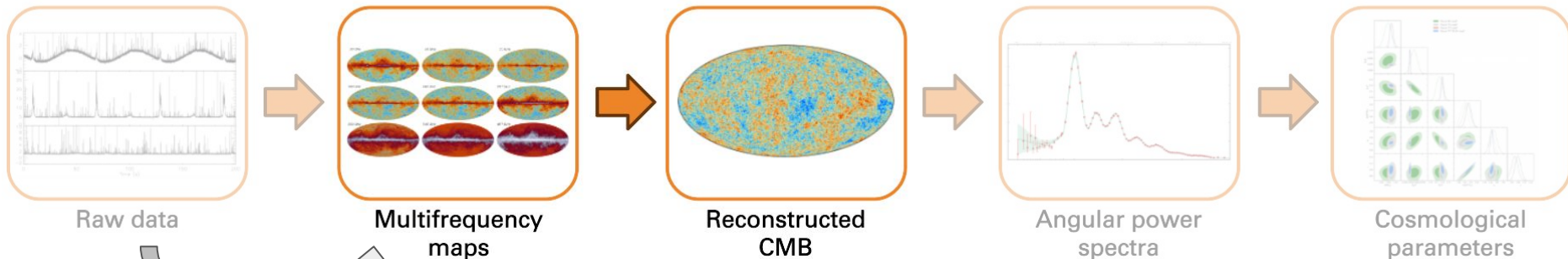
**Evidence for
multiple dust populations**



[ Gjerløw+ (2022)]

Component-separation basis

6



Map-based approaches:

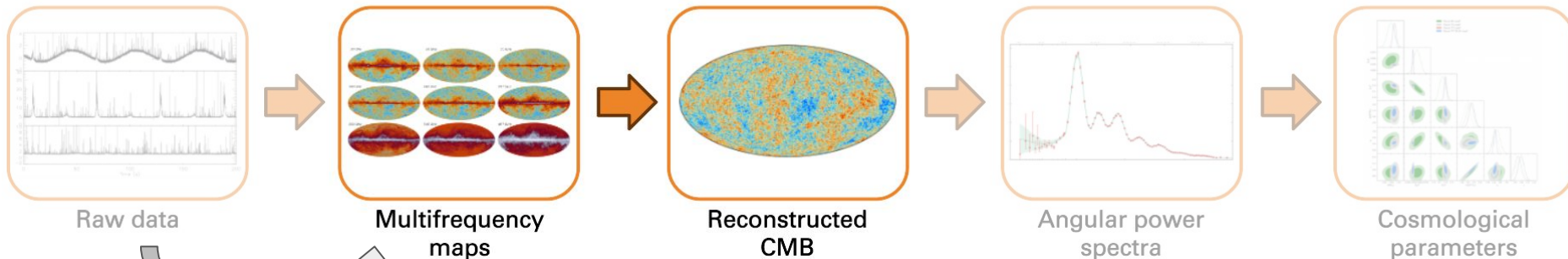
$$\boxed{m_\nu(\hat{n})} = \text{beam convolution} * \left(\sum_c \underbrace{A(\beta_c, \Delta_\nu)}_{\text{spectral parameters}} \underbrace{s_c(\hat{n})}_{\text{sky signals}} \right) + \underbrace{n(\hat{n})}_{\text{noise}}$$

The equation describes the map-making process. The left side is the frequency map $m_\nu(\hat{n})$. The right side is the sum of the beam convolution (indicated by a green arrow) of the mixing matrix $A(\beta_c, \Delta_\nu)$ (indicated by a purple arrow) and the sky signals $s_c(\hat{n})$ (indicated by a pink arrow). The mixing matrix A is a function of the spectral parameters β_c (indicated by a purple arrow) and the bandpass parameters Δ_ν (indicated by a brown arrow). The noise $n(\hat{n})$ is added to the result.

Algorithms differ in
how and how many components they recover

Component-separation basis

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via standard
mapmaking
algorithms

Map-based approaches:

$$\text{frequency maps } m_\nu(\hat{n}) = B * \left(\sum_c \text{Mixing matrix } A(\beta_c, \Delta_\nu) \text{ sky signals } s_c(\hat{n}) \right) + \text{noise } n(\hat{n})$$

Parametric

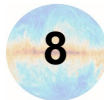
create a model $\tilde{m}_\nu(\theta)$ and fit it to data

global chi-square minimization

$$\chi^2(\hat{n}) = \sum_\nu \left(\frac{m_\nu(\hat{n}) - \tilde{m}_\nu(\hat{n})}{\sigma_\nu(\hat{n})} \right)^2$$

[ Eriksen+ (2004),
Stompor+ (2009),
de la Hoz+ (2020)]

Parametric approach



global chi-square minimization

$$\chi^2(\hat{n}) = \sum_{\nu} \left(\frac{m_{\nu}(\hat{n}) - \tilde{m}_{\nu}(\hat{n})}{\sigma_{\nu}(\hat{n})} \right)^2$$

baseline:

just fit sky components

$$\theta = \{\beta_c, s_c\}$$

Algorithm	Methodology
Commander (Eriksen+, 2024)	Gibbs sampling
FGBuster (Stompor+, 2009)	Spectral Likelihood
B-seCRET (de la Hoz+, 2020)	MCMC sampling

Parametric approach

8

global chi-square minimization

$$\chi^2(\hat{n}) = \sum_{\nu} \left(\frac{m_{\nu}(\hat{n}) - \tilde{m}_{\nu}(\hat{n})}{\sigma_{\nu}(\hat{n})} \right)^2$$

baseline:

just fit sky components

$$\theta = \{\beta_c, s_c\}$$

extended:

include parameters for instrumental effects

$$\theta = \{\beta_c, s_c\} \cup \{B, \Delta_{\nu}\}$$

Fit can be affected by
instrument systematics

[ Eriksen+ (2004),
Verges+ (2021),
de la Hoz+ (2020),
Jost+ (2023)]

Parametric approach

8

global chi-square minimization

$$\chi^2(\hat{n}) = \sum_{\nu} \left(\frac{m_{\nu}(\hat{n}) - \tilde{m}_{\nu}(\hat{n})}{\sigma_{\nu}(\hat{n})} \right)^2$$

baseline:

just fit sky components

$$\theta = \{\beta_c, s_c\}$$

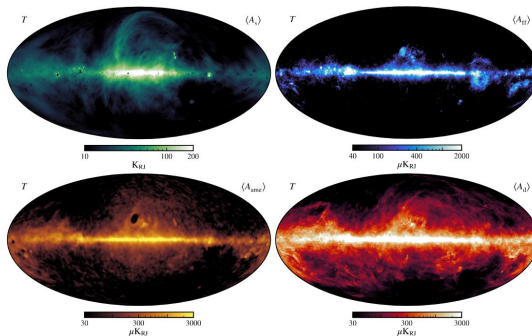
extended:

include parameters for instrumental effects

$$\theta = \{\beta_c, s_c\} \cup \{B, \Delta_{\nu}\}$$

Advantages:

- Easily absorb instrument calibration errors
- Provide estimation at the same time of all sky components



Parametric approach

8

global chi-square minimization

baseline:

just fit sky components

$$\theta = \{\beta_c, s_c\}$$

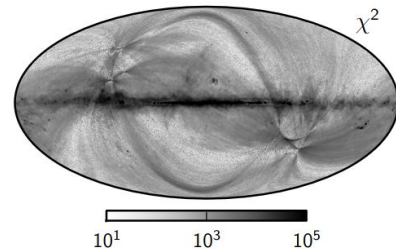
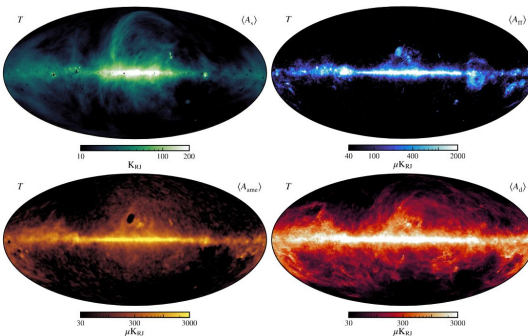
extended:

include parameters for instrumental effects

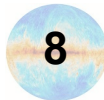
$$\theta = \{\beta_c, s_c\} \cup \{B, \Delta_\nu\}$$

Advantages:

- Easily absorb instrument calibration errors
- Provide estimation at the same time of all sky components
- Chi-square maps: first robustness test



Parametric approach



global chi-square minimization

$$\chi^2(\hat{n}) = \sum_{\nu} \left(\frac{m_{\nu}(\hat{n}) - \tilde{m}_{\nu}(\hat{n})}{\sigma_{\nu}(\hat{n})} \right)^2$$

baseline:

just fit sky components

$$\theta = \{\beta_c, s_c\}$$

Assumptions:

- Emission model for each sky component

Parametric approach

8

global chi-square minimization

baseline:

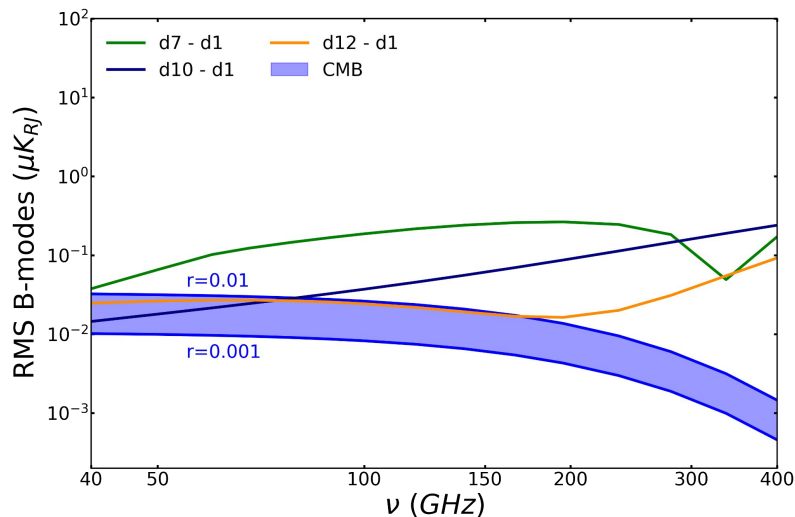
just fit sky components

$$\theta = \{\beta_c, s_c\}$$

$$\chi^2(\hat{n}) = \sum_{\nu} \left(\frac{m_{\nu}(\hat{n}) - \tilde{m}_{\nu}(\hat{n})}{\sigma_{\nu}(\hat{n})} \right)^2$$

Assumptions:

- Emission model for each sky component



**Susceptible to the
assumptions underlying the
sky model**

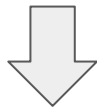
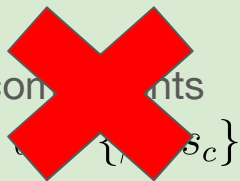
Parametric approach

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global chi-square minimization

baseline:

just fit sky components



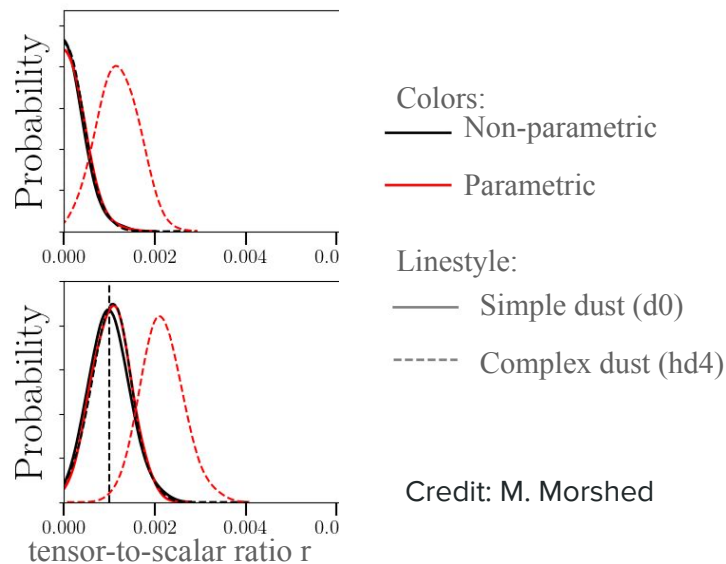
baseline+: MICMAC

Simplify model assumptions in the mixing matrix

$$\theta = \{A_{ik}^f, s_{\text{CMB}}\}$$

 Leloup+ (2023),
Morshed+ (2024)]

$$\chi^2(\hat{n}) = \sum_{\nu} \left(\frac{m_{\nu}(\hat{n}) - \tilde{m}_{\nu}(\hat{n})}{\sigma_{\nu}(\hat{n})} \right)^2$$



Parametric approach

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global chi-square minimization

$$\chi^2(\hat{n}) = \sum_{\nu} \left(\frac{m_{\nu}(\hat{n}) - \tilde{m}_{\nu}(\hat{n})}{\sigma_{\nu}(\hat{n})} \right)^2$$

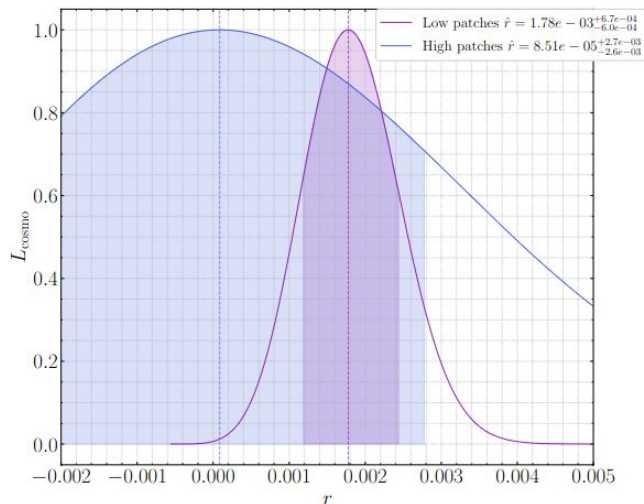
baseline:

just fit sky components

$$\theta = \{\beta_c, s_c\}$$

Limitations:

- Number of fitted spectral parameters coming from trade-off between residual bias and overall sensitivity



[ Kabalan+ (2026)]

Parametric approach

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global chi-square minimization

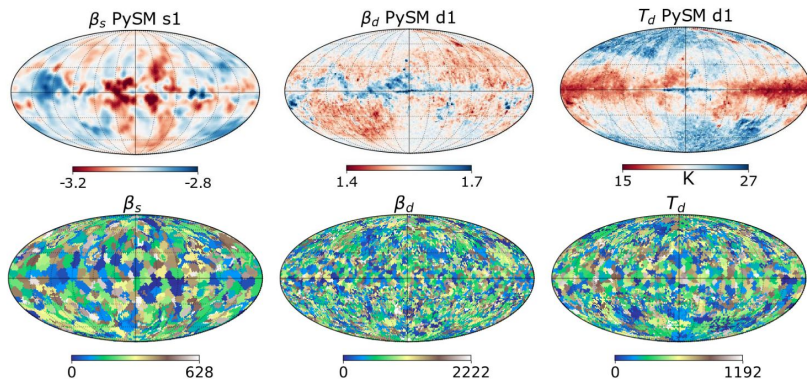
baseline:

just fit sky components

$$\theta = \{\beta_c, s_c\}$$

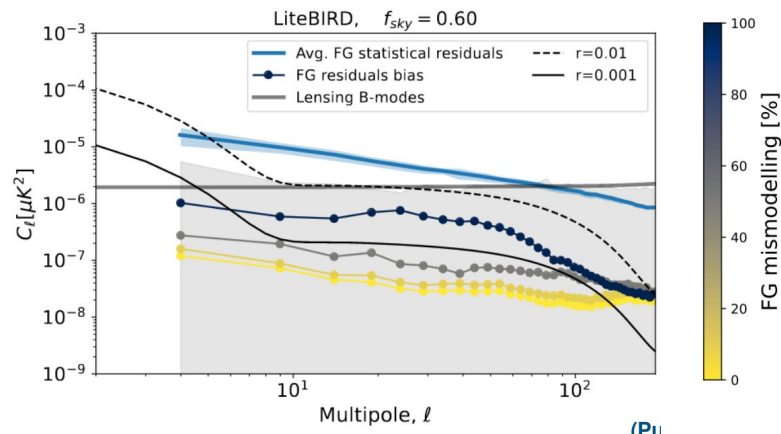


[ Puglisi+ (2022)]



Limitations:

- Number of fitted spectral parameters coming from trade-off between residual bias and overall sensitivity



Parametric approach

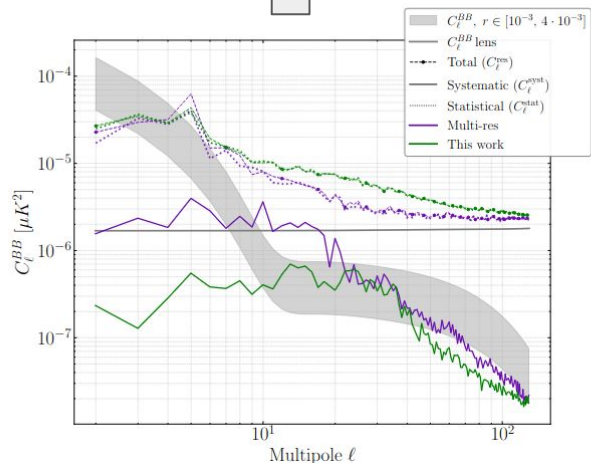
12

global chi-square minimization

baseline:

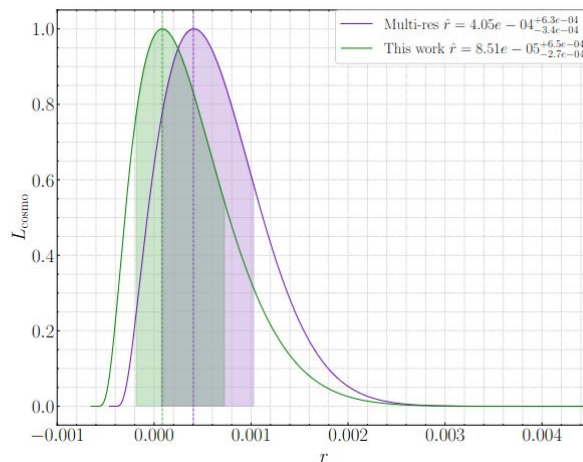
just fit sky components

$$\theta = \{\beta_c, s_c\}$$



Limitations:

- Number of fitted spectral parameters coming from trade-off between residual bias and overall sensitivity



Parametric approach

13

global chi-square minimization

$$\chi^2(\hat{n}) = \sum_{\nu} \left(\frac{m_{\nu}(\hat{n}) - \tilde{m}_{\nu}(\hat{n})}{\sigma_{\nu}(\hat{n})} \right)^2$$

baseline:

just fit sky components

$$\theta = \{\beta_c, s_c\}$$

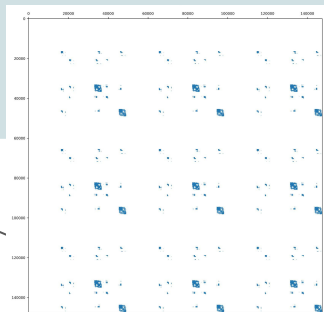


baseline++:

Including TOD filtering (ground-based experiments) into the data model

$$\mathbf{d} = \mathcal{O}\mathbf{A}\mathbf{s} + \mathbf{n}$$

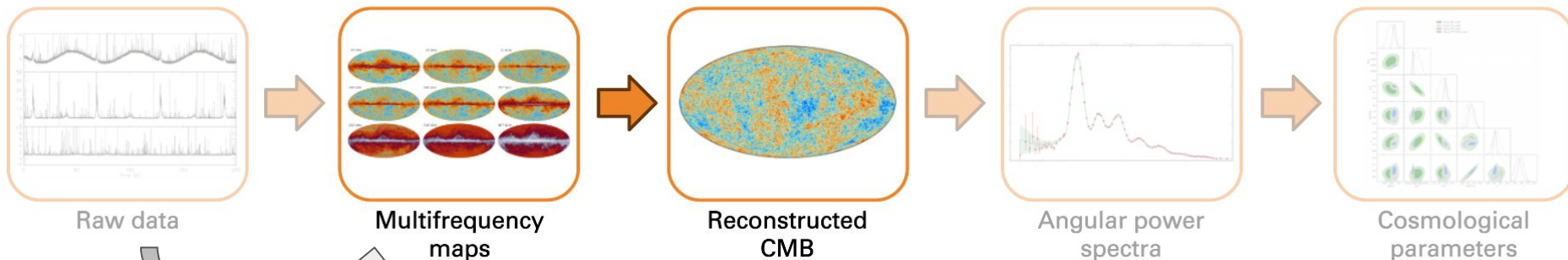
[See Baptiste's talk]



Observation matrix $\mathcal{O}$ accounts for all (linear) effects of TODs filtering at the map level

Component-separation basis

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Map-based approaches:

$$\text{frequency maps } m_\nu(\hat{n}) = \mathbf{B} * \left(\sum_c \text{Mixing matrix } \mathbf{A}(\beta_c, \Delta_\nu) \text{ sky signals } s_c(\hat{n}) \right) + \text{noise } n(\hat{n})$$

Blind (ILC)

combine your data and minimize variance of contaminants: $\hat{s}_{\text{ILC}}(\hat{n}) = \sum_\nu w_\nu(\hat{n}) m_\nu(\hat{n})$

global variance minimization

$$\text{Var}(\hat{s}_{\text{ILC}}) = \text{Var}(s_{\text{CMB}}) + w_\nu (F + N)_{\nu\nu'} w_{\nu'}$$

Blind (ILC) approach

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global variance minimization

baseline:

applying the formalism in different
sub-bases: pixel, harmonic, wavelets

for CMB reconstruction:

$$\sum_{\nu} w_{\nu} A_{\nu}^{\text{CMB}} = 1$$
$$\min_w \text{Var} \left[\sum_{\nu} w_{\nu} d_{\nu} \right]$$
$$\mathbf{w} = [\mathbf{A}_{\text{CMB}}^T \mathbf{C}^{-1} \mathbf{A}_{\text{CMB}}]^{-1} \mathbf{A}_{\text{CMB}}^T \mathbf{C}^{-1}$$

data covariance

$$\text{Var}(\hat{s}_{\text{ILC}}) = \text{Var}(s_{\text{CMB}}) + w_{\nu}(F + N)_{\nu\nu'} w_{\nu'}$$

Assumptions:

- Components are statistically independent
- The SED of the component to be reconstructed must be known

Advantages:

- Simple implementation
- No affected by sky mismodelling

Blind (ILC) approach

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global variance minimization

[ Remazeilles+ (2011), Planck Collab. (2016)]

Generalized ILC:

Use statistical and spatial information to blindly deproject components with known statistical and SED properties (CMB, noise, CIB) and reconstruct components with unknown SEDs

$$\text{Var}(\hat{s}_{\text{ILC}}) = \text{Var}(s_{\text{CMB}}) + w_{\nu}(F + N)_{\nu\nu'} w_{\nu'}$$

Assumptions:

- Components are statistically independent
- The SED of the component to be reconstructed must be known

Blind (ILC) approach

17

global variance minimization

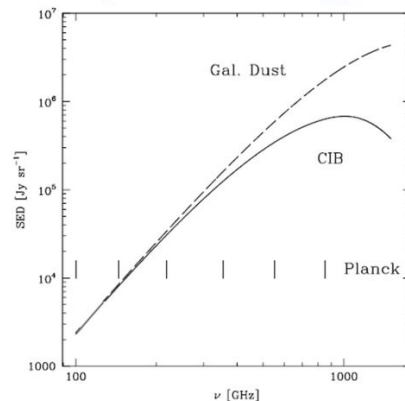
[ Remazeilles+ (2011), Planck Collab.

Generalized ILC:

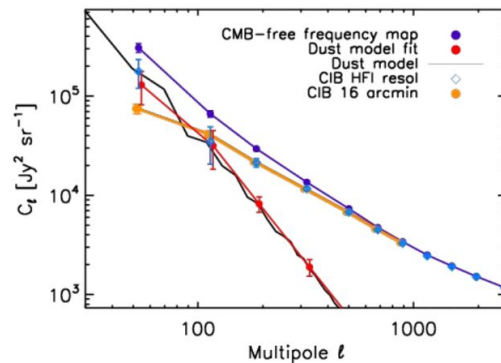
Use statistical and spatial information to blindly deproject components with known statistical and SED properties (CMB, noise, CIB) and reconstruct components with unknown SEDs

$$\text{Var}(\hat{s}_{\text{ILC}}) = \text{Var}(s_{\text{CMB}}) + w_{\nu}(F + N)_{\nu\nu'} w_{\nu'}$$

Thermal dust and CIB have similar spectral signatures (modified blackbody)



Thermal dust and CIB have different angular power spectrum



Blind (ILC) approach

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global variance minimization

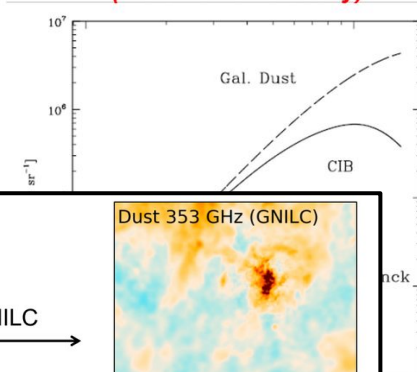
[Remazeilles+ (2011), Planck Collab.

Generalized ILC:

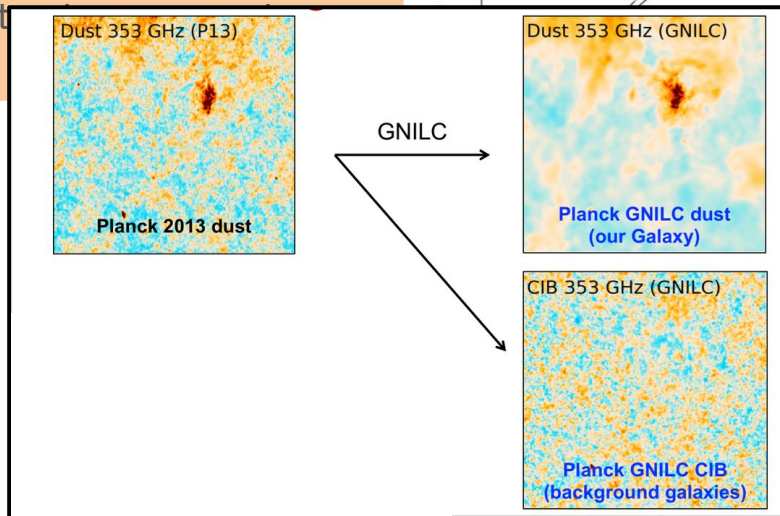
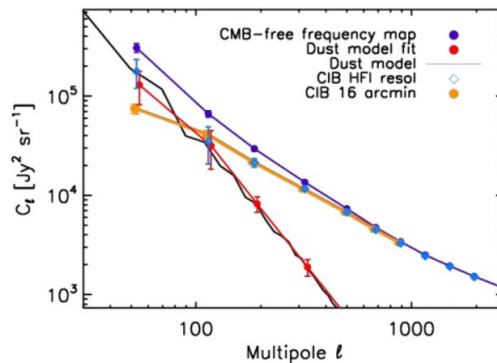
Use statistical and spatial information to blindly deproject components with known statistical and SED properties (CMB, noise, CIB) and reconstruct with unknown SEDs

$$\text{Var}(\hat{s}_{\text{ILC}}) = \text{Var}(s_{\text{CMB}}) + w_{\nu}(F + N)_{\nu\nu'} w_{\nu'}$$

Thermal dust and CIB have similar spectral signatures (modified blackbody)



Thermal dust and CIB have different angular power spectrum



Blind (ILC) approach

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global variance minimization

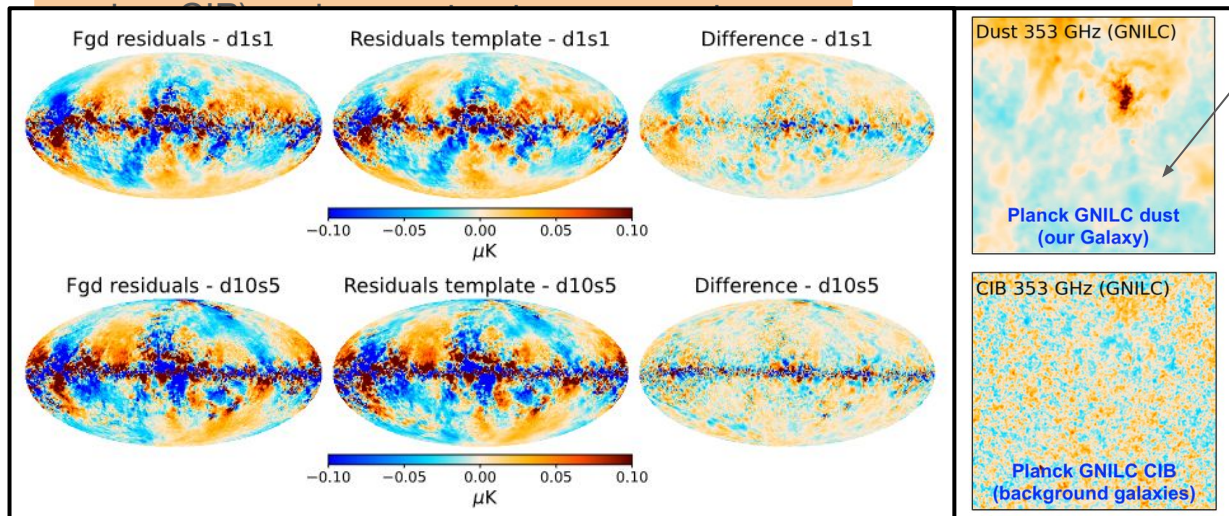
$$\text{Var}(\hat{s}_{\text{ILC}}) = \text{Var}(s_{\text{CMB}}) + w_{\nu}(F + N)_{\nu\nu'} w_{\nu'}$$

[ Remazeilles+ (2011), Planck Collab.

Generalized ILC:

Use statistical and spatial information to blindly deproject components with known statistical and SED properties (CMB,

CMB and noise
are also deprojected



GILC denoising can be used to predict spatial distribution of foreground residuals after component separation

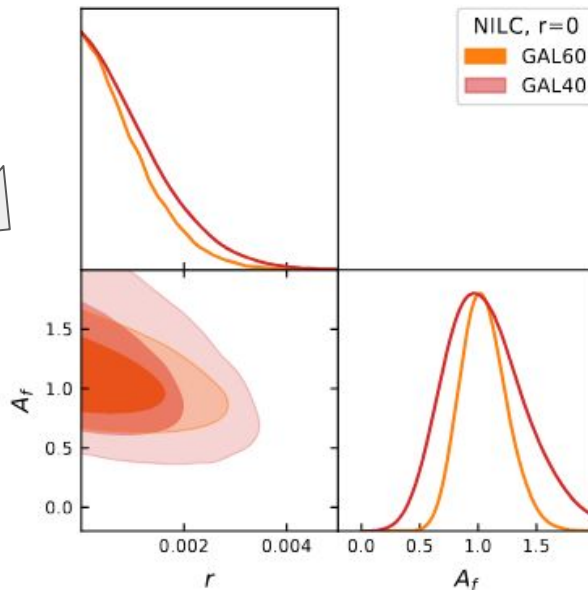
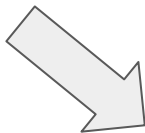
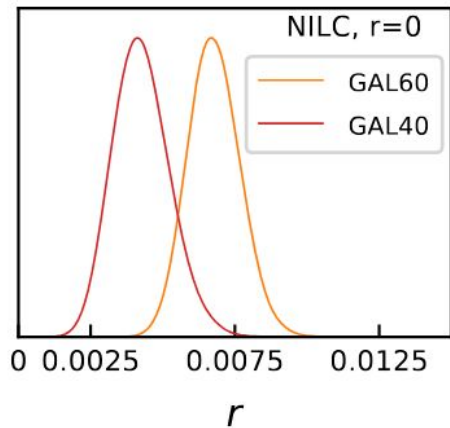
[ Carones (2025)]

Blind (ILC) approach

18

global variance minimization

$$\text{Var}(\hat{s}_{\text{ILC}}) = \text{Var}(s_{\text{CMB}}) + w_{\nu}(F + N)_{\nu\nu'} w_{\nu'}$$



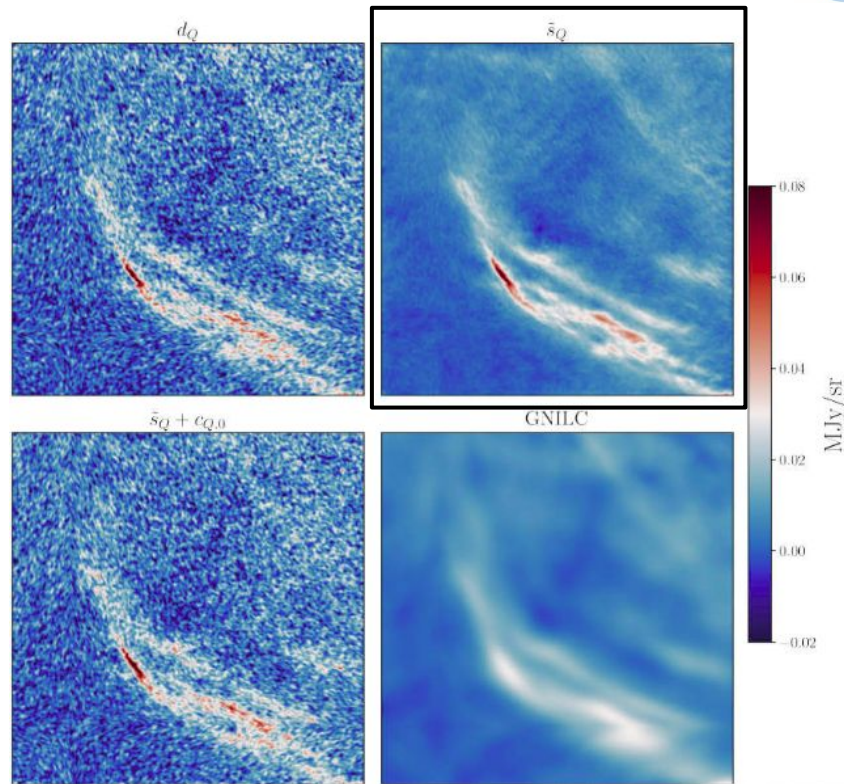
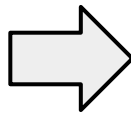
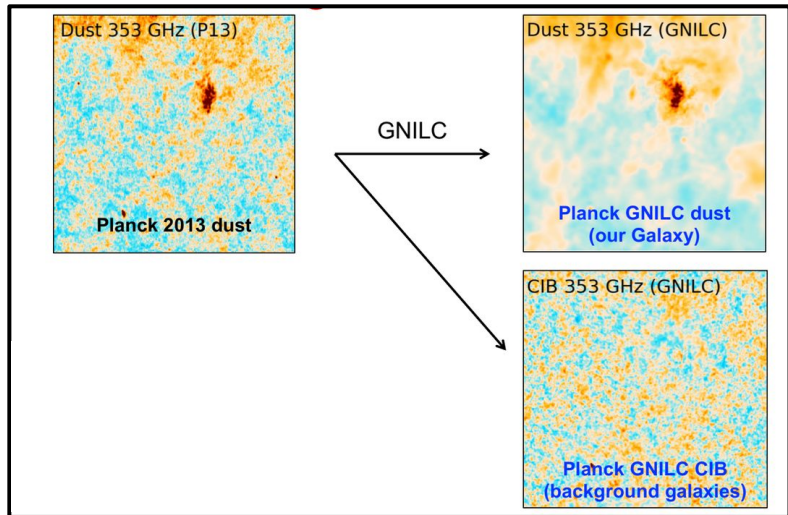
GILC denoising can be used to predict spatial distribution of foreground residuals after component separation

[ Carones (2025)]

Statistical deprojection

[ Tsouros+ (2026)]

19



[ Remazeilles+ (2011), Planck Collab. (2016)]

$$\begin{aligned}
 S_1(\lambda_1) &\equiv \langle |x \star \psi^{\lambda_1}| \rangle \\
 S_2(\lambda_1) &\equiv \langle |x \star \psi^{\lambda_1}|^2 \rangle \\
 S_3(\lambda_1, \lambda_2) &\equiv \frac{\text{Cov}[x \star \psi^{\lambda_2}, |x \star \psi^{\lambda_1}| \star \psi^{\lambda_2}]}{\sqrt{\langle |x \star \psi^{\lambda_1}|^2 \rangle} \sqrt{\langle |x \star \psi^{\lambda_2}|^2 \rangle}} \\
 S_4(\lambda_1, \lambda_2, \lambda_3) &\equiv \frac{\text{Cov}[|x \star \psi^{\lambda_1}| \star \psi^{\lambda_3}, |x \star \psi^{\lambda_2}| \star \psi^{\lambda_3}]}{\sqrt{\langle |x \star \psi^{\lambda_1}|^2 \rangle} \sqrt{\langle |x \star \psi^{\lambda_2}|^2 \rangle}}
 \end{aligned}$$

Enhanced reconstruction of foregrounds signal exploiting higher-order statistical information (no assumption on foreground properties again) by means of WST

Blind (ILC) approach

20

global variance minimization

baseline:

applying the formalism in different sub-bases: pixel, harmonic, wavelets

for CMB reconstruction:

$$\sum_{\nu} w_{\nu} A_{\nu}^{\text{CMB}} = 1$$

$$\min_w \text{Var} \left[\sum_{\nu} w_{\nu} d_{\nu} \right]$$

$$\mathbf{w} = [\mathbf{A}_{\text{CMB}}^T \mathbf{C}^{-1} \mathbf{A}_{\text{CMB}}]^{-1} \mathbf{A}_{\text{CMB}}^T \mathbf{C}^{-1}$$

$$\text{Var}(\hat{s}_{\text{ILC}}) = \text{Var}(s_{\text{CMB}}) + w_{\nu}(F + N)_{\nu\nu'} w_{\nu'}$$

Limitations:

- Complex spatial variations may limit effectiveness of these methods
- Just one component can be reconstructed each time and no control on removal of components
- If impacted by systematics, it is not trivial to implement mitigation strategies at the component-separation level

Blind (ILC) approach

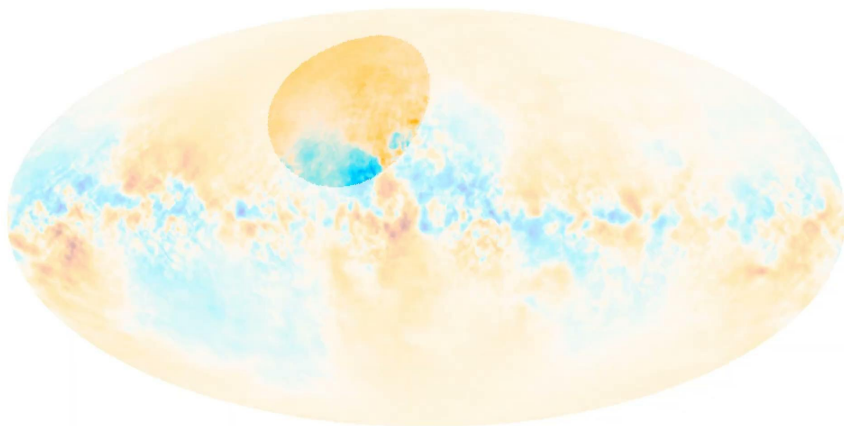
20

global variance minimization

baseline:

applying the formalism in different
sub-bases: pixel, harmonic, wavelets

$$\mathbf{w} = [\mathbf{A}_{\text{CMB}}^T \mathbf{C}^{-1} \mathbf{A}_{\text{CMB}}]^{-1} \mathbf{A}_{\text{CMB}}^T \mathbf{C}^{-1}$$



$$\text{Var}(\hat{s}_{\text{ILC}}) = \text{Var}(s_{\text{CMB}}) + w_{\nu}(F + N)_{\nu\nu'} w_{\nu'}$$

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$$\text{Var}(\hat{s}_{\text{ILC}}) = \text{Var}(s_{\text{CMB}}) + w_{\nu}(F + N)_{\nu\nu'} w_{\nu'}$$

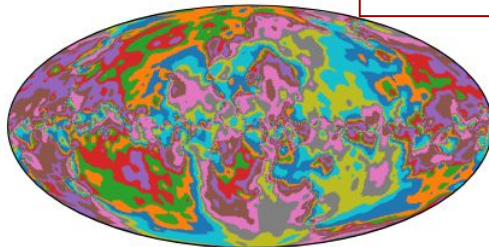
Limitations:

- Complex spatial variations may limit effectiveness of these methods

New approach for covariance computation.
It adapts to foreground properties

[📖 Carones+ (2023)]

Blind spectral
foreground tracer



Blind (ILC) approach

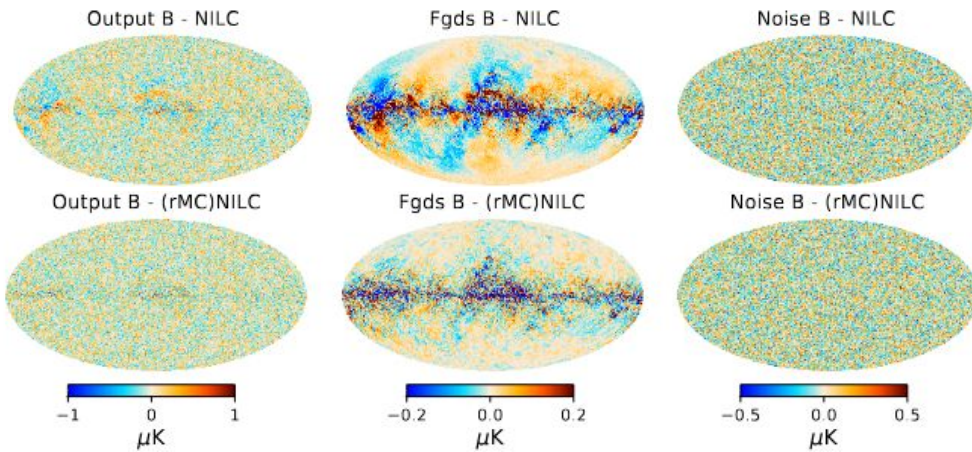
20

global variance minimization

baseline:

applying the formalism in different
sub-bases: pixel, harmonic, wavelets

significant reduction of residuals at large scales



$$\text{Var}(\hat{s}_{\text{ILC}}) = \text{Var}(s_{\text{CMB}}) + w_{\nu}(F + N)_{\nu\nu'} w_{\nu'}$$

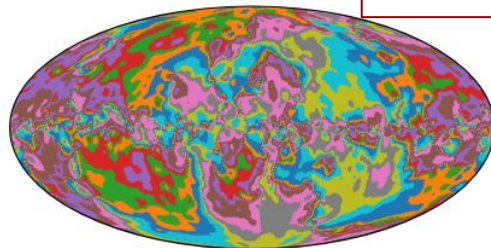
Limitations:

- Complex spatial variations may limit effectiveness of these methods

New approach for covariance computation.
It adapts to foreground properties

[ Carones+ (2023)]

Blind spectral
foreground tracer



Blind (ILC) approach

16

global variance minimization

[ Remazeilles+ (2011)]

constrained ILC:

constrain ILC weights to deproject undesired components or keep more than one sky component (all with known SEDs)

$$\mathbf{w}_{\text{cILC}} = \mathbf{e}^T [\mathbf{A}^T \mathbf{C}^{-1} \mathbf{A}]^{-1} \mathbf{A}^T \mathbf{C}^{-1}$$

deprojection
coefficients

SEDs of all
components of
interest

full deprojection:

$$\mathbf{e} = (1 \ 0 \ 0 \ . \ .)$$

full reconstruction:

$$\mathbf{e} = (1 \ 1 \ 1 \ . \ .)$$

$$\text{Var}(\hat{s}_{\text{ILC}}) = \text{Var}(s_{\text{CMB}}) + w_{\nu}(F + N)_{\nu\nu'} w_{\nu'}$$

Limitations:

- Complex spatial variations may limit effectiveness of these methods
- Just one component can be reconstructed each time and no control on removal of components
- If impacted by systematics, it is not trivial to implement mitigation strategies at the component-separation level

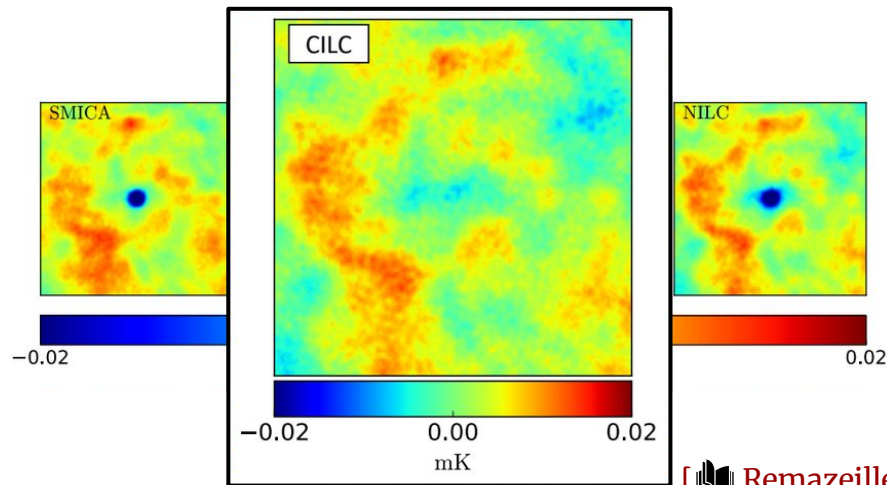
Blind (ILC) approach

16

constrained ILC:

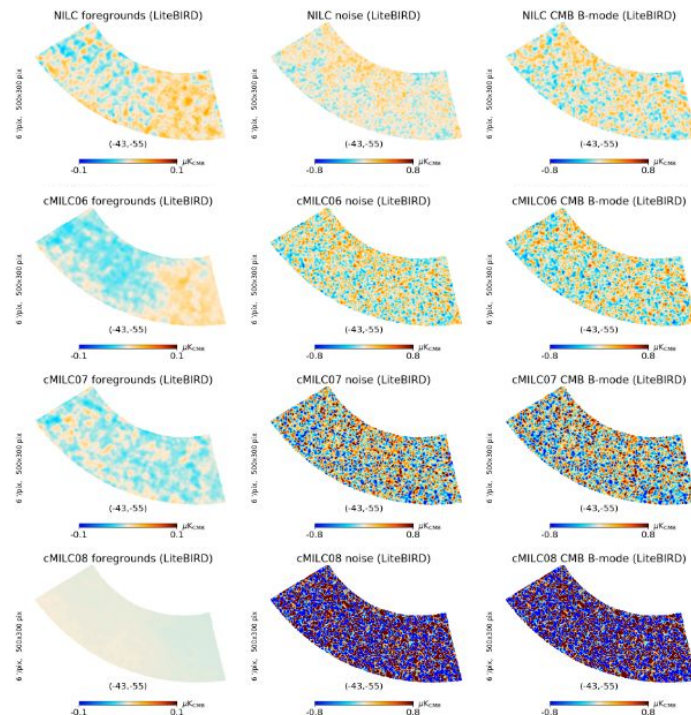
$$\mathbf{w}_{\text{cILC}} = e^T [A^T C^{-1} A]^{-1} A^T C^{-1}$$

TSZ deprojection



[Remazeilles+ (2011)]

trade-off between
residual bias and variance



[Remazeilles+ (2021)]

deprojection of
foreground moments

Blind (ILC) approach

16

constrained ILC:

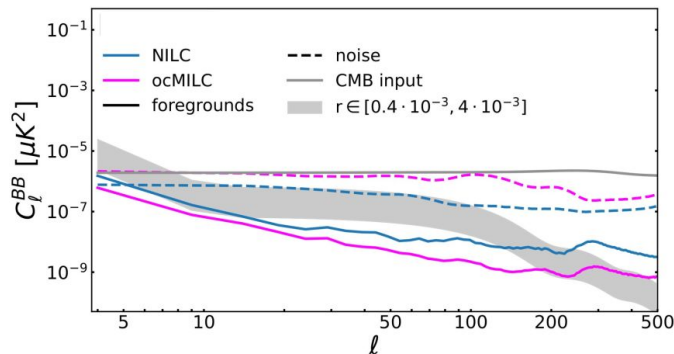
$$\mathbf{w}_{\text{cILC}} = e^T [A^T C^{-1} A]^{-1} A^T C^{-1}$$

optimizing deprojection

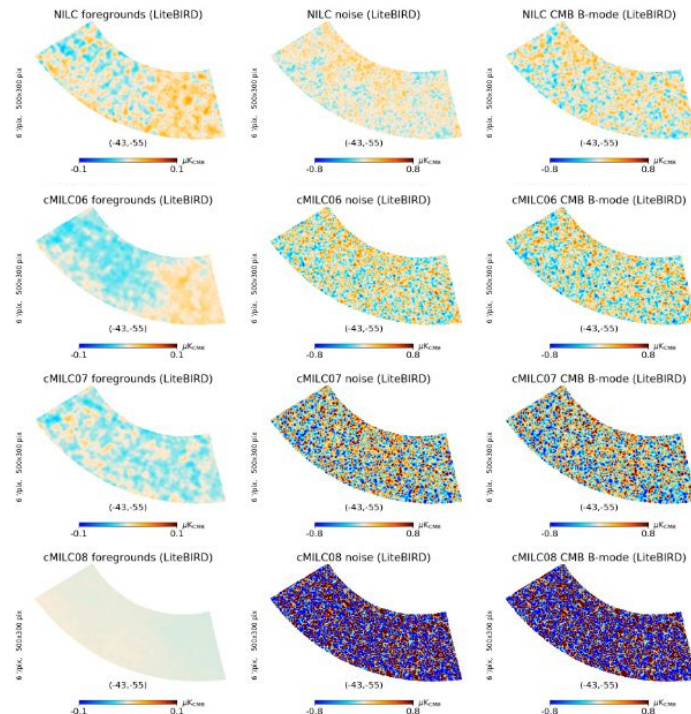
Full optimisation of:

- number of moments to deproject
- set of moments to deproject
- values of dust pivot spectral indices
- deprojection coefficients:

$$\begin{cases} \omega^j \cdot A^{\text{CMB}} = 1 \\ \omega^j \cdot f_1 = \epsilon_1 \\ \omega^j \cdot f_2 = \epsilon_2 \\ \cdot \\ \omega^j \cdot f_{m_{\text{fgds}}} = \epsilon_{m_{\text{fgds}}} \end{cases}$$



trade-off between
residual bias and variance



deprojection of
foreground moments



<https://github.com/alecarones/broom>

BROOM: Blind Reconstruction Of Observables in the Microwaves

BROOM is a Python package for blind component separation and Cosmic Microwave Background (CMB) data analysis.

Installation

You can install the base package using:

```
pip install cmbroom
```



Realistic simulations
of any CMB experiment

Angular power spectrum
computation

Component separation
reconstruction of signals with :

- known SEDs (ILCs)
- unknowns SEDs (GILCs)

CMB Foregrounds.....

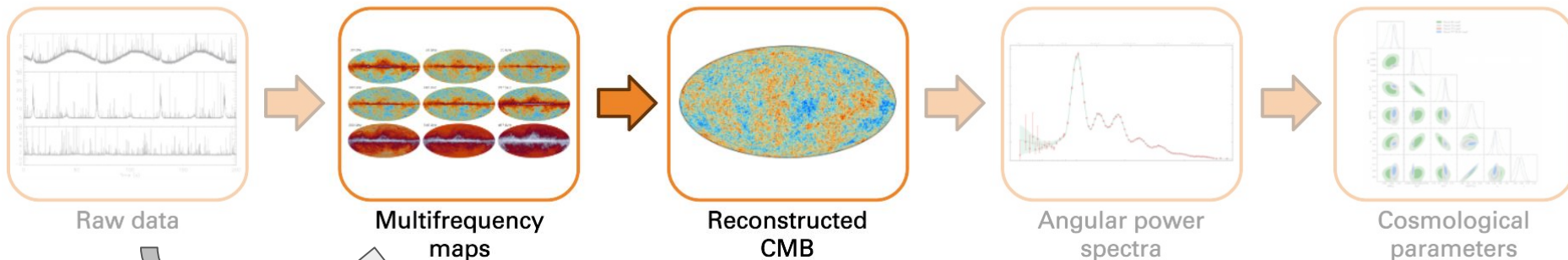
- diagnostic
- residuals reconstruction

[ Carones+ (2026)]

Skip Ad ►

Component-separation basis

21

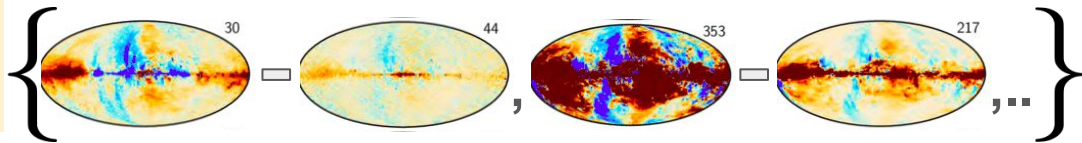


via standard
mapmaking
algorithms

Map-based approaches:

Blind (template-fitting)
global variance minimization

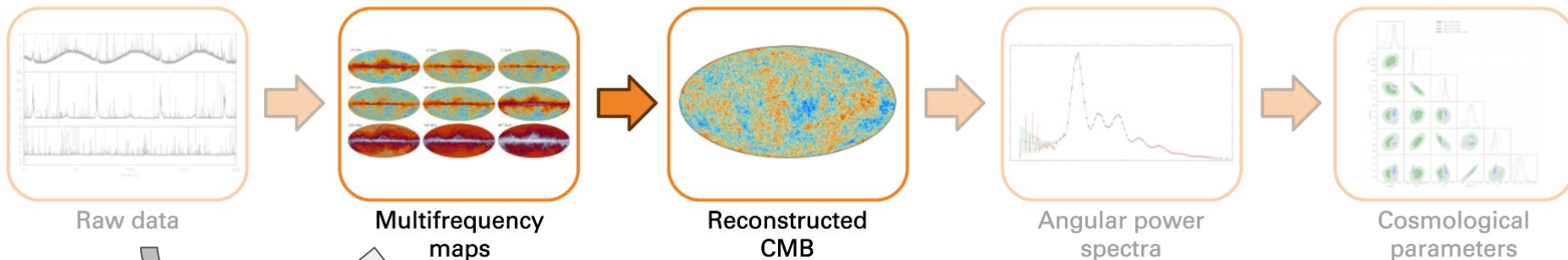
Foreground templates:



$$\tilde{s}_{\nu}^{\text{ITF}}(\hat{n}) = m_{\nu}(\hat{n}) - \sum_i \alpha_{\nu}^i(\hat{n}) t_i(\hat{n}) \quad \longleftarrow \quad \underset{\alpha}{\operatorname{argmin}} \langle (\tilde{s}_{\nu}^{\text{ITF}})^2 \rangle$$

Component-separation basis

21



via standard
mapmaking
algorithms

Map-based approaches:

Blind (template-fitting)
global variance minimization

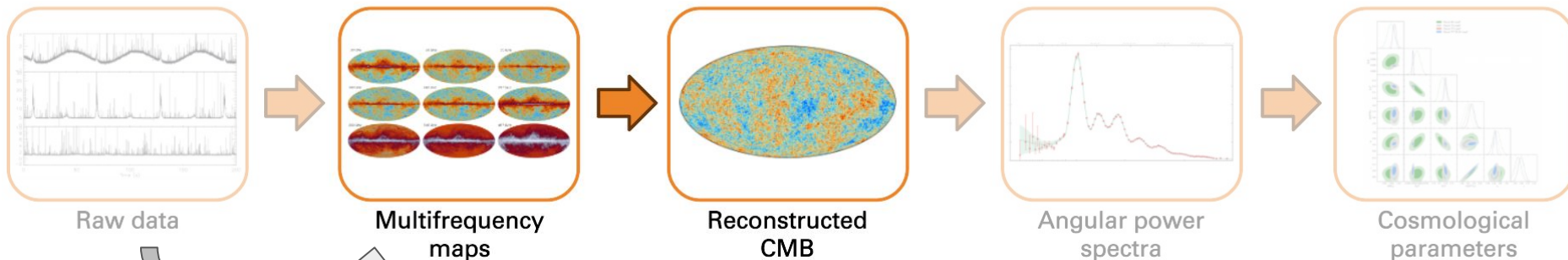
Advantages:

- Robust against spectral mismodelling
- Provide CMB maps at multiple frequencies!!!!

$$\tilde{s}_{\nu}^{\text{ITF}}(\hat{n}) = m_{\nu}(\hat{n}) - \sum_i \alpha_{\nu}^i(\hat{n}) t_i(\hat{n}) \quad \longleftarrow \quad \underset{\alpha}{\operatorname{argmin}} \langle (\tilde{s}_{\nu}^{\text{ITF}})^2 \rangle$$

Component-separation basis

21



via standard
mapmaking
algorithms

Map-based approaches:

Blind (template-fitting)
global variance minimization

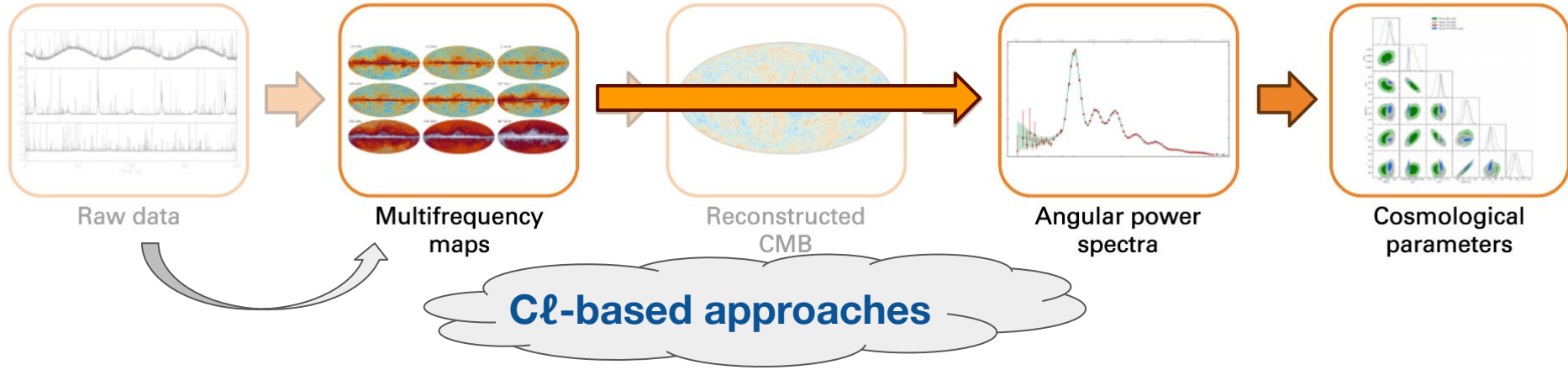
$$\tilde{s}_{\nu}^{\text{ITF}}(\hat{n}) = m_{\nu}(\hat{n}) - \sum_i \alpha_{\nu}^i(\hat{n}) t_i(\hat{n})$$

Limitations:

- Complex spatial variations may limit effectiveness of these methods
- If impacted by systematics, it is not trivial to implement mitigation strategies at the component-separation level

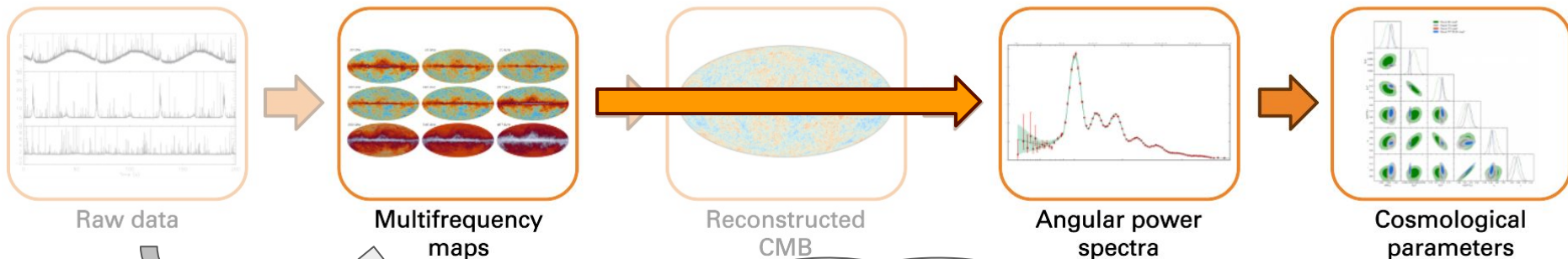
Component-separation basis

22



Component-separation basis

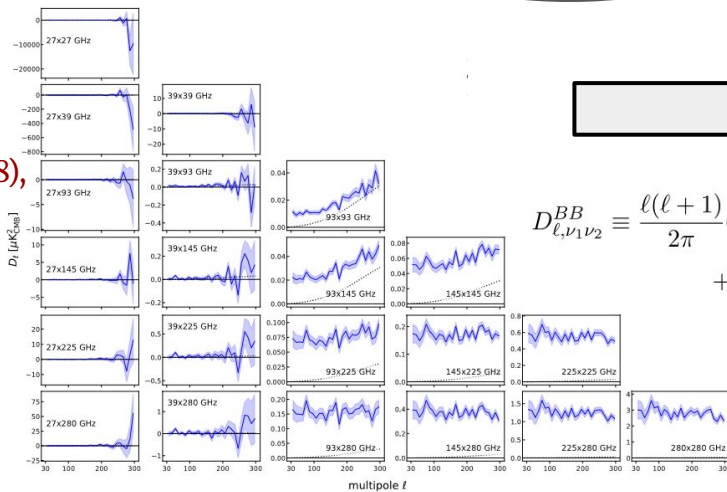
22



Cℓ-based approaches

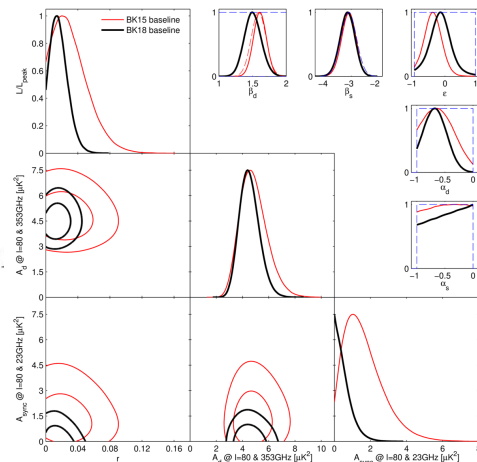
Parametric

[BK Collab. (2016, 2018),
Abitbol+ (2021),
Azzoni+ (2021),
Vacher+ (2022),
Vinzl+ (in prep.)]



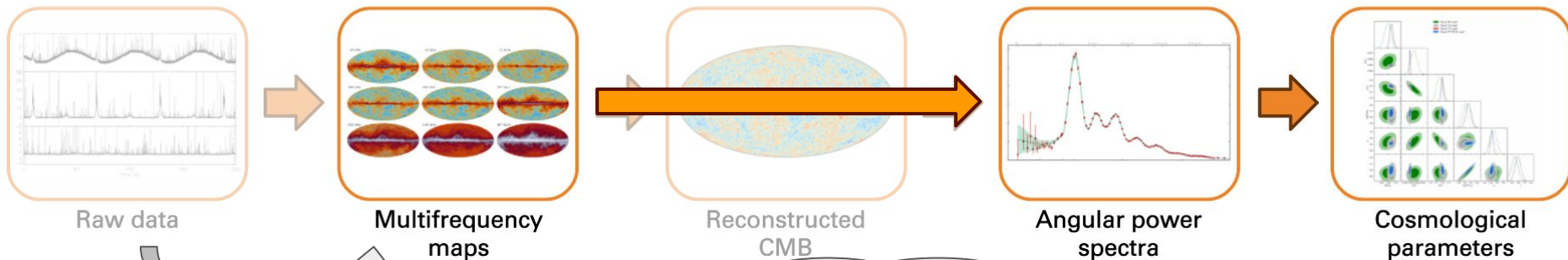
model

$$D_{\ell, \nu_1 \nu_2}^{BB} \equiv \frac{\ell(\ell+1)}{2\pi} C_{\ell, \nu_1 \nu_2}^{BB} = r \cdot D_{\ell, \text{prim}}^{BB} + D_{\ell, \text{lens}}^{BB} + D_{\ell, \nu_1 \nu_2}^{\text{dust}} + D_{\ell, \nu_1 \nu_2}^{\text{sync}} + D_{\ell, \nu_1 \nu_2}^{\text{dust} \times \text{sync}}$$



Component-separation basis

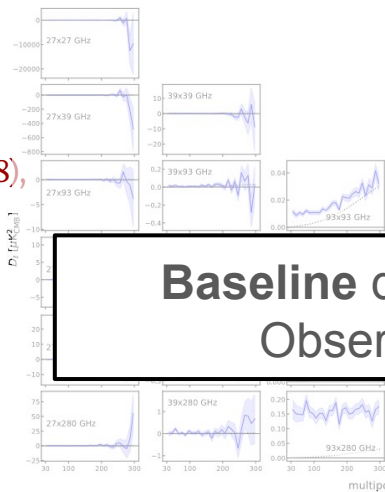
22



$C\ell$ -based approaches

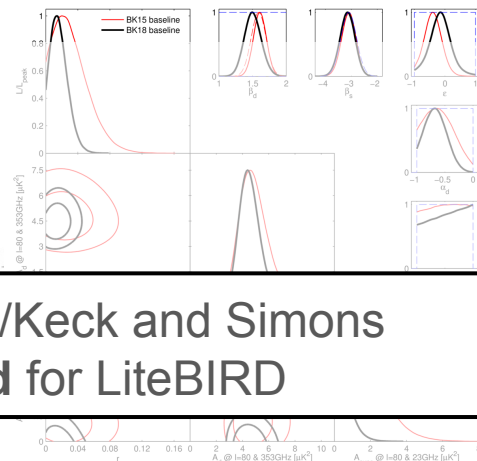
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Azzoni+ (2021),
Vacher+ (2022),
Vinzl+ (in prep.)]



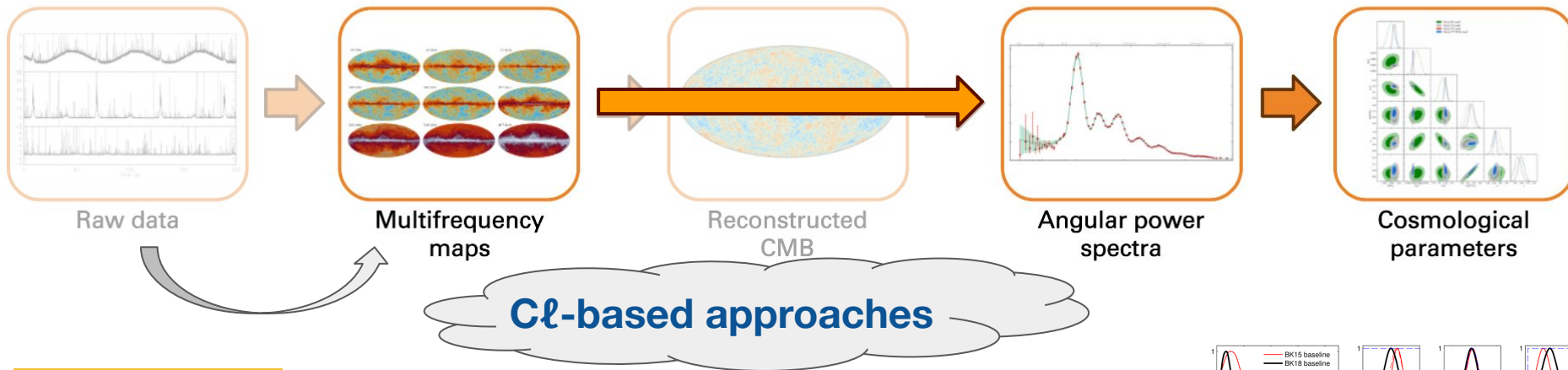
$$D_{\ell}^{BB} \equiv \frac{\ell(\ell+1)}{2\pi} C_{\ell}^{BB} = r \cdot D_{\ell}^{BB} + D_{\ell}^{BB} + \dots$$

Baseline data-analysis pipeline for BICEP/Keck and Simons Observatory - tested and augmented for LiteBIRD



Component-separation basis

22



Parametric

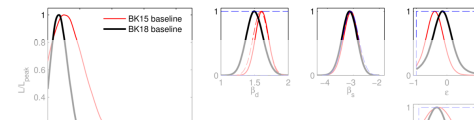
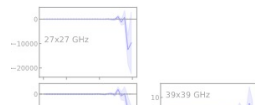
Advantages:

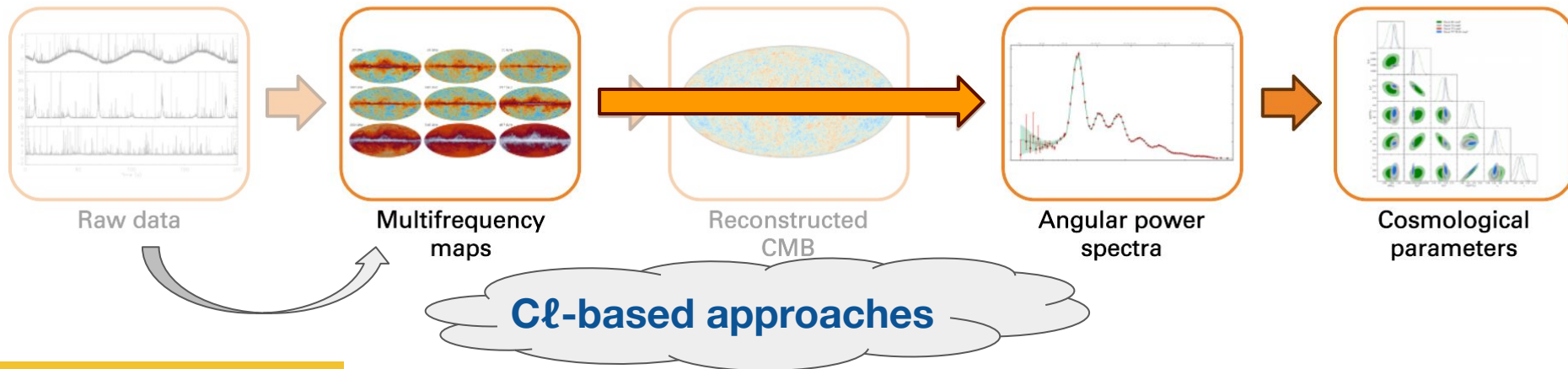
- Simpler implementation than map-based
- Simpler foreground modeling and handling
- Simpler correction for TOD filtering and systematics

- discard spatial (directional) information

Limitations:

- No cleaned CMB maps:
 - no map-based robustness tests
 - no statistical inference





Non-parametric

Spectral Matching Independent Component Analysis (SMICA)

Multi-frequency spectra:

$$\mathbf{R}(\ell) = \mathbf{A}_{\text{CMB}} \mathbf{A}_{\text{CMB}}^\dagger C(\ell) + \mathbf{F} \mathbf{P}_s(\ell) \mathbf{F}^\dagger + \mathbf{R}_n(\ell)$$

[See Viet's talk]

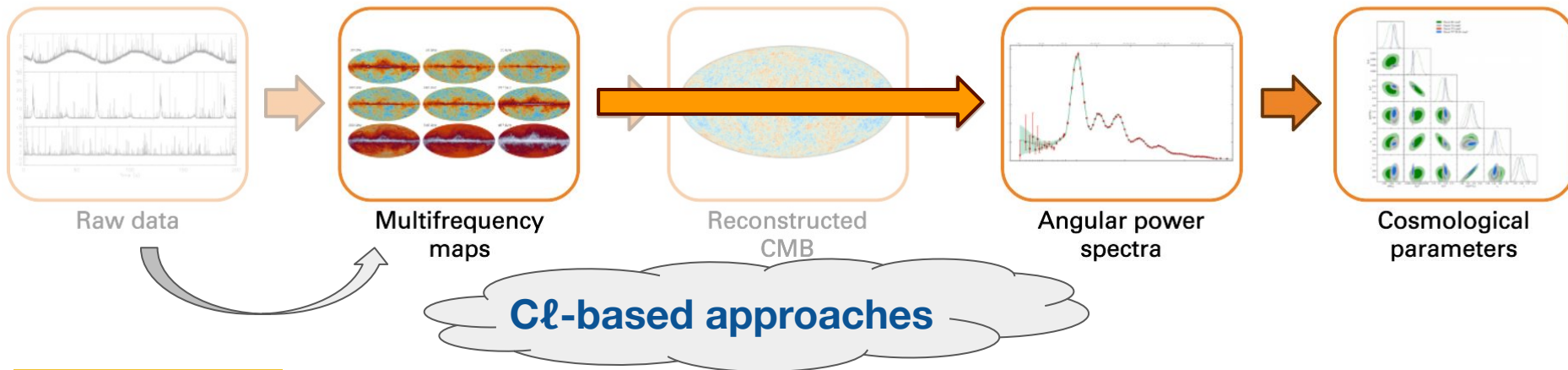
Free parameters

$$\theta = (C(\ell), \mathbf{F}, \mathbf{P}(\ell), \text{diag}(\mathbf{R}_n(\ell)))$$

found by minimizing:

$$\phi(\theta) = \sum_{\ell} \frac{2\ell + 1}{2} \left[\text{Tr}(\hat{R} \mathbf{R}^{-1}(\theta)) - \log \det(\hat{R} \mathbf{R}^{-1}(\theta)) - n \right]$$

[ Delabrouille+ (2003),
Cardoso+ (2008),
Tran+ (in prep)]

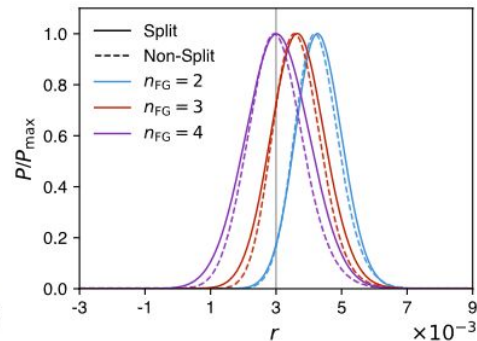
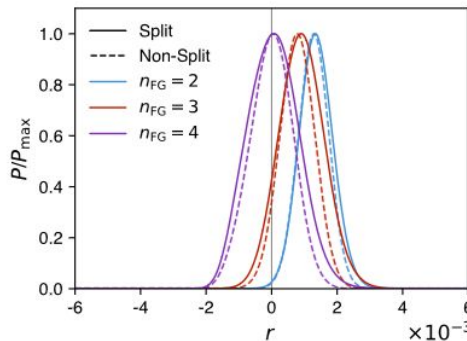
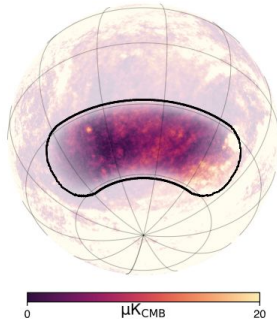


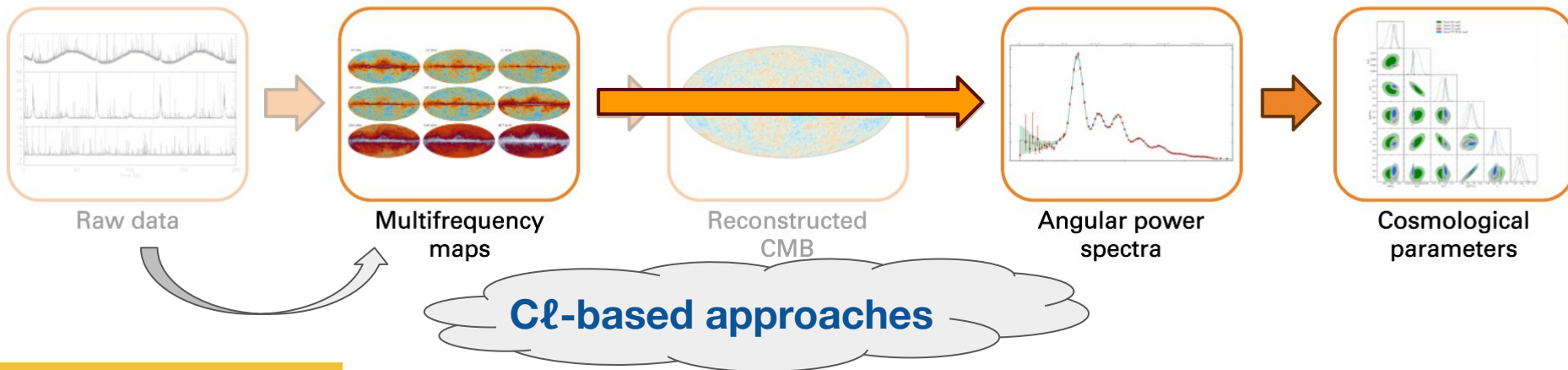
Blind

Spectral Matching Independent Component Analysis (SMICA)
 “medium complexity”

[Steier+ (2025)]

CMB-S4-like





Non-parametric

Spectral Matching Independent Component Analysis (SMICA)

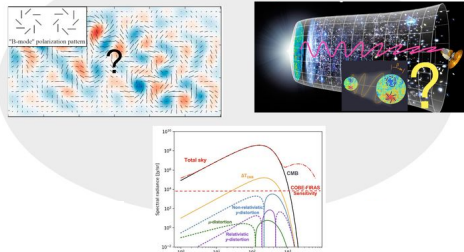
Advantages:

- Robust against sky components mismodelling
- Corrections against TOD filtering and instrumental systematics is easy

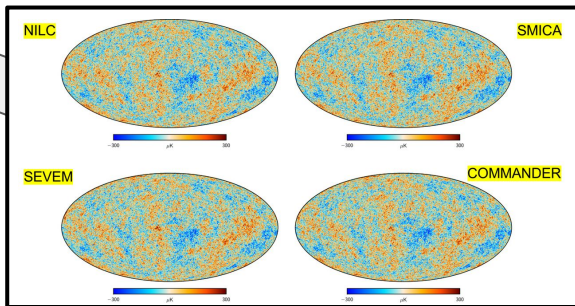
- discard spatial (directional) information

Summary

New CMB signals



compelling scientific targets ahead of us



Inheriting huge methodological developments from past experiments



1. Being able to deal with foreground:
 - a. projected spatial complexity
 - b. spectral complexity
2. Absorb instrumental modelling/mitigate calibration systematics
3. Develop robustness tests - diagnostic of goodness of component separation
4. Reach the targeted sensitivity for scientific observables