

Skew-Normal Likelihood for non-Gaussian astronomical data

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The Non-Gaussian Universe Workshop

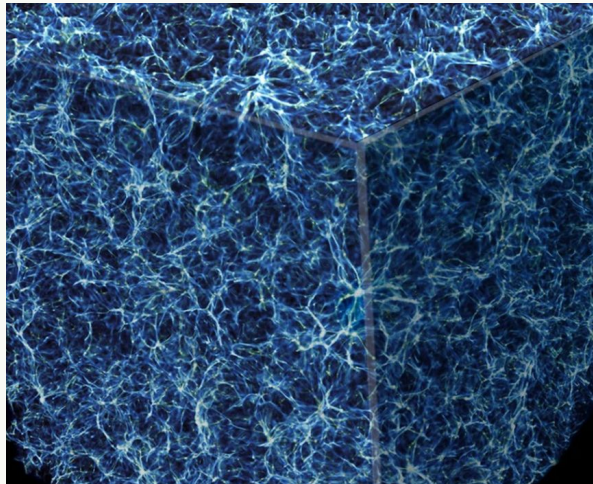
Which non-Gaussianity are we talking about?

The Underlying Field

Domain: Physical 3D Space.

Cause: Non-linear gravity, etc.

Result: Information leaks into higher-order statistics.



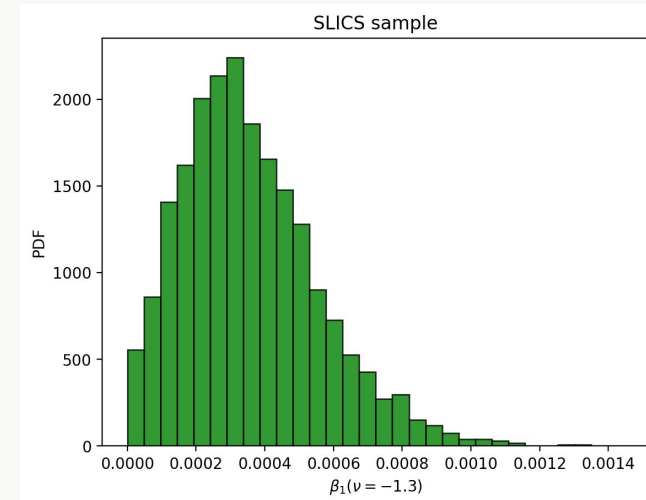
Credit: NASA, ESA, and E. Hallman (University of Colorado, Boulder)

The Likelihood

Domain: Statistical Data Vector Space.

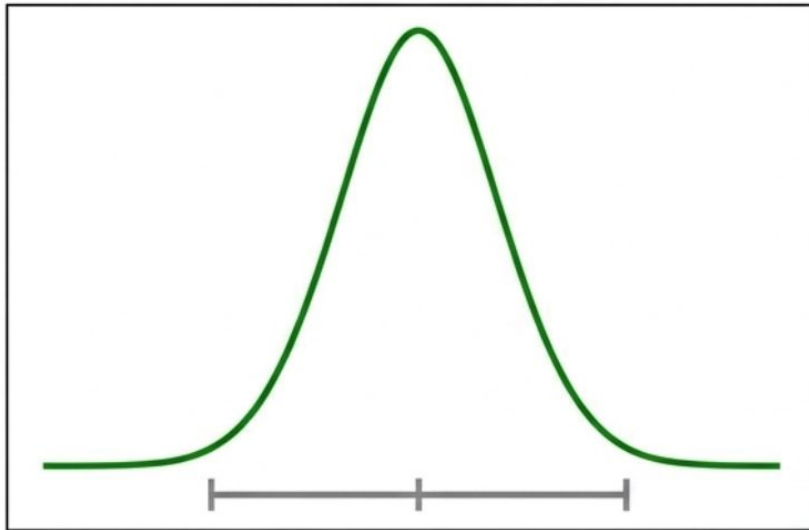
Cause: Cosmic variance, etc.

Result: The PDF of summary statistics is asymmetric (skewed). Requires non-Gaussian modeling.



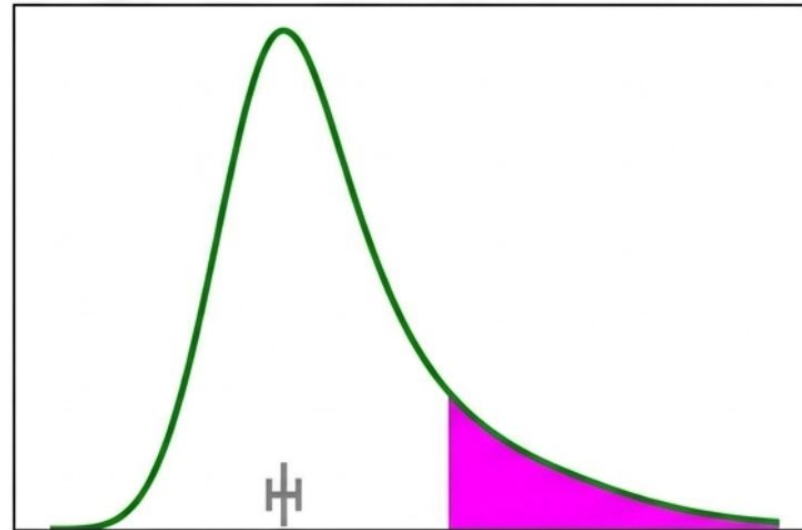
Why is it important for us?

Past Surveys



Legacy Error Margins: Gaussian assumptions fit well enough beneath the noise.

Stage-IV Surveys (Euclid, LSST)



The Precision Era: Shrinking error bars expose pronounced asymmetric tails in the true data likelihood.

↑ Shift to Stage-IV Precision →
←

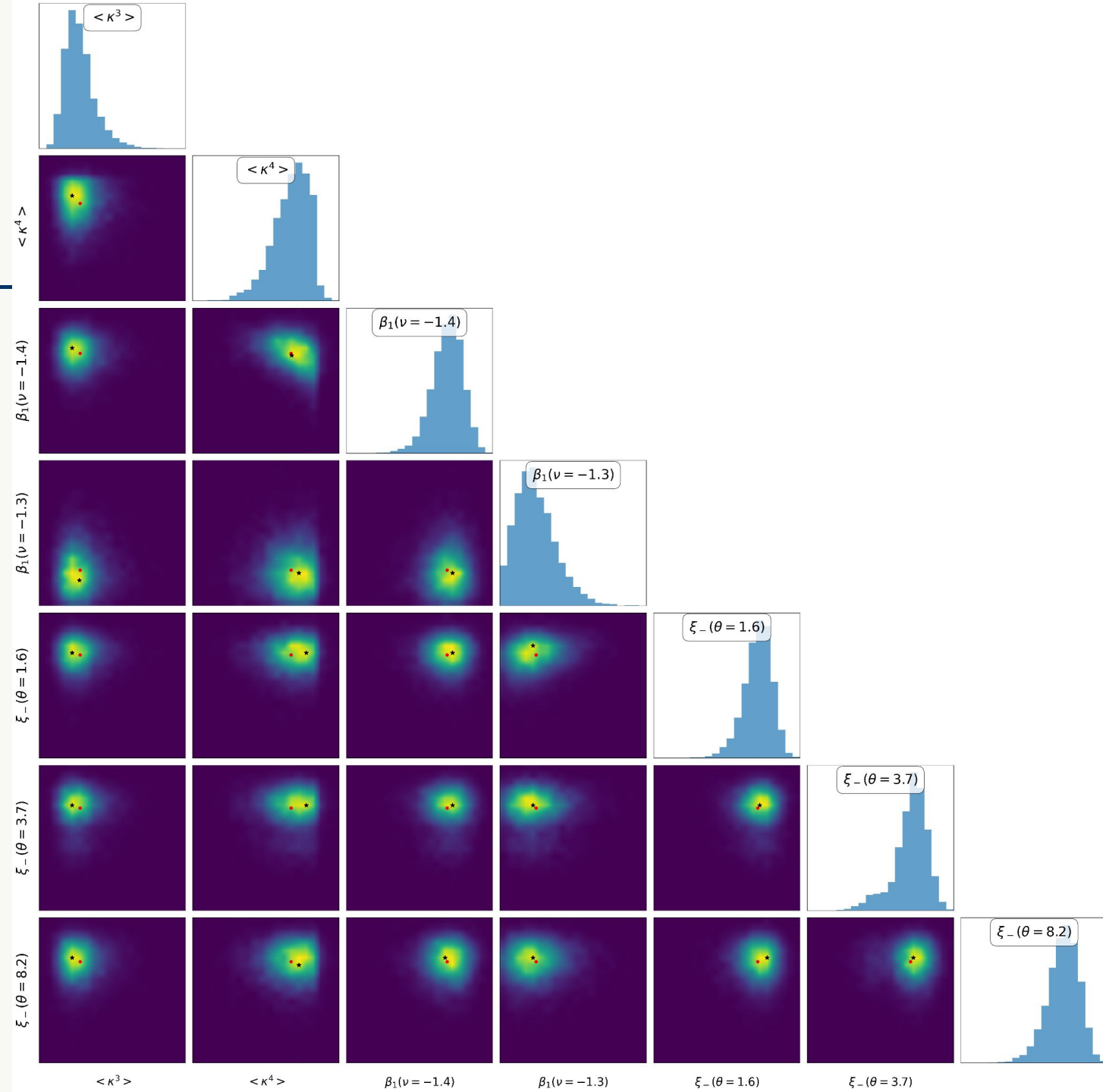
How pronounced is the non gaussianity of the likelihood in WL data?



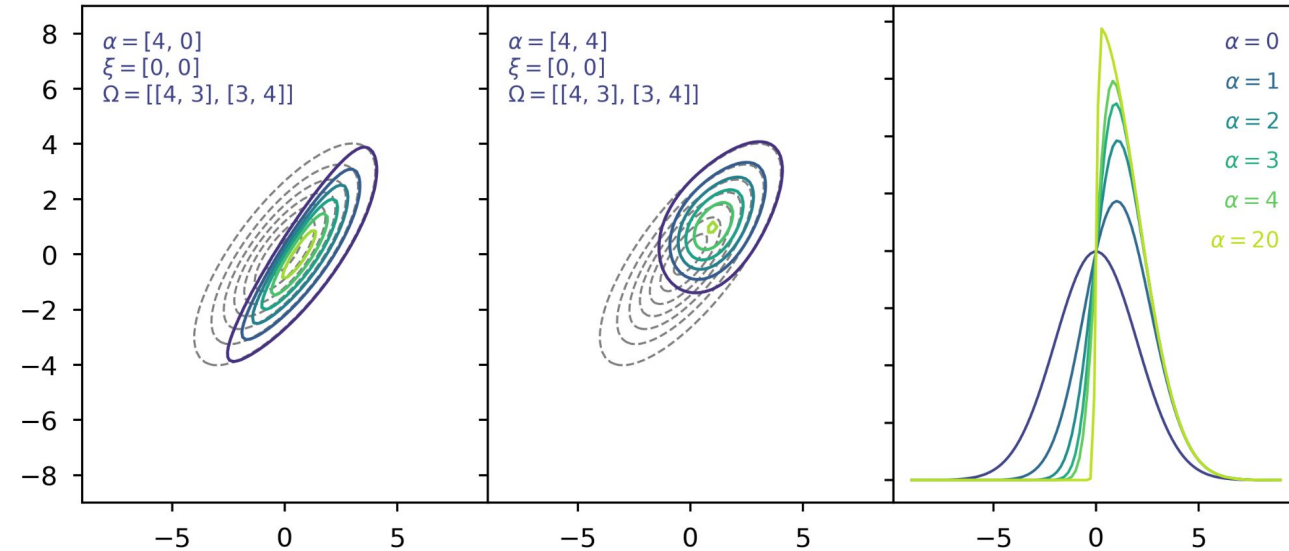
Some selected data points from SLICS simulation with high non-gaussianity



SLICS: N-body sim with 7640 realizations - 25 deg² light cones and 4.8 arcsec resolution



Anatomy of the Skew-Normal Distribution



$$\text{SN}(x; \alpha, \xi, \Omega) = 2 \times N(x; \xi, \Omega) \times \Phi(\alpha \omega^{-1}(x - \xi))$$

The Base Normal

The Perturbation Factor

The Slant Parameter

Following the notation of Azzalini (1985)

What make SN a good option for using as likelihood?

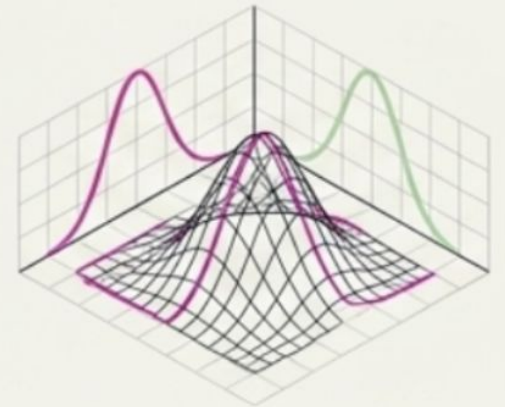
- ✓ converges to Gaussian likelihood at $\alpha = 0$
- ✓ Adding Gaussian noise is theoretically straightforward
- ✓ Theoretical form for the marginals



Exact Gaussian Convergence



Closure Under Normal Noise

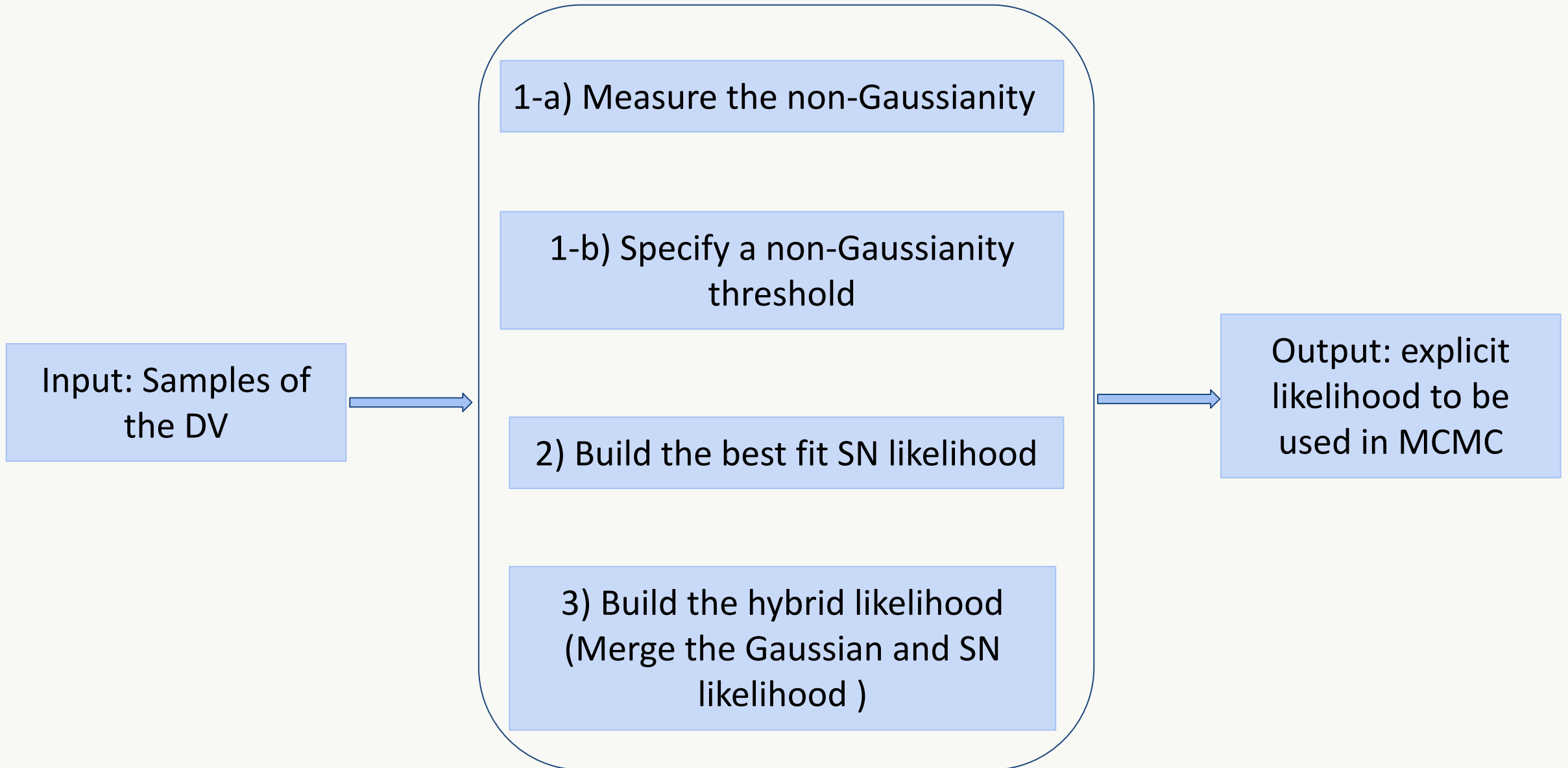


Closed-Form Marginals

Building the SN likelihood

	Method of Moments	Bayesian	Profile likelihood	The marginal method
Speed	Fast	Slow	Scalable	Fast
Scalability	Fails in extreme cases. Skeweness estimator becomes ill-conditioned while approaching the symmetric case	Expensive	The most accurate/efficient method when enough samples are provided	Not as accurate as the profile likelihood but works more reliably with small sample size

Structure of the likelihood pipeline



Non-Gaussianity metric

✓ SMAPE

$$y_i = (\mathbf{D}_i - \langle \mathbf{D} \rangle)^T \text{COV}^{-1} (\mathbf{D}_i - \langle \mathbf{D} \rangle)$$

$$S_i = \frac{|P_{\text{obs}}(y_i) - P_{\chi^2}(y_i)|}{|P_{\text{obs}}(y_i)| + |P_{\chi^2}(y_i)|}$$

$$S_{\text{lim}} = \langle S_{\text{obs}}^{\text{gauss}} \rangle + 2\sigma(S_{\text{obs}}^{\text{gauss}})$$

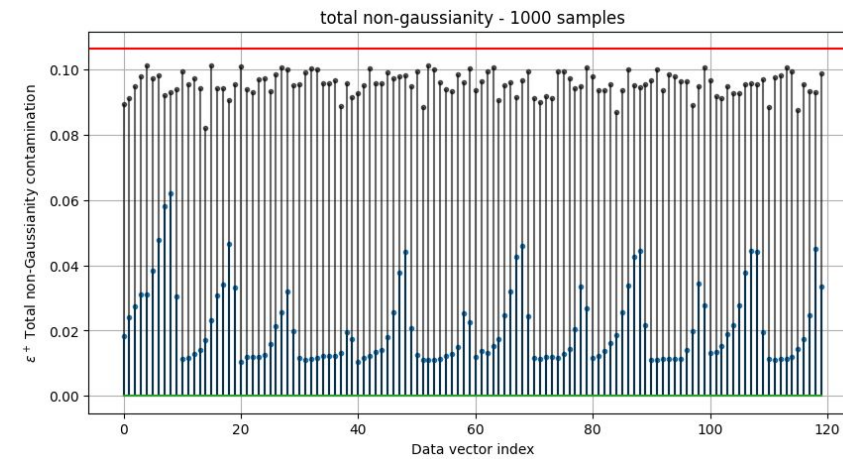
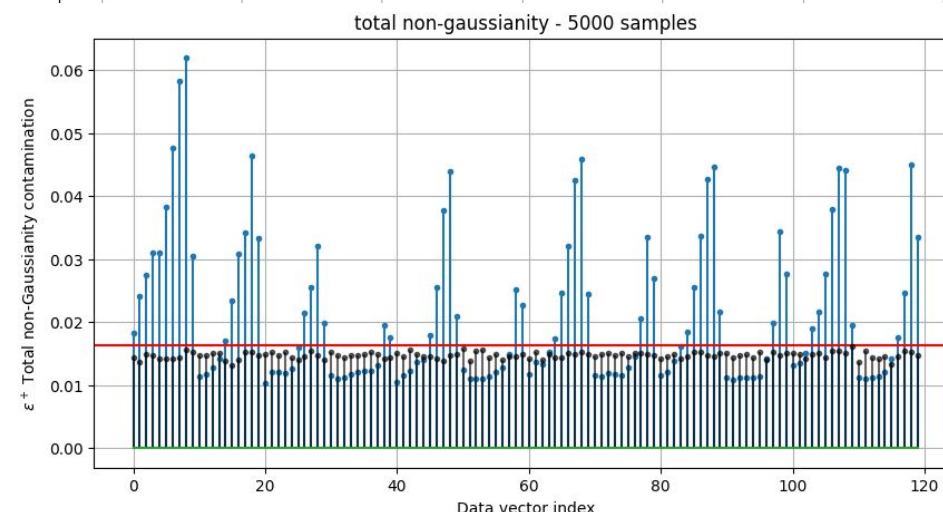
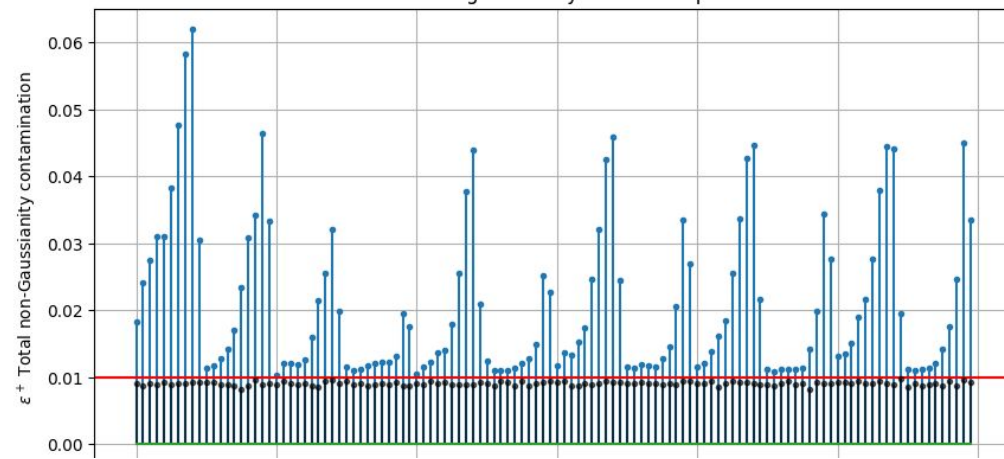
Vinciguerra et al. (2025)

✓ MISE (Summation)

$$\frac{1}{B} \sum_{b=1}^B [\mathcal{H}_b(s_i^{e,f}) - \mathcal{G}(0, 2)]^2 =: S_{e,f}^+$$

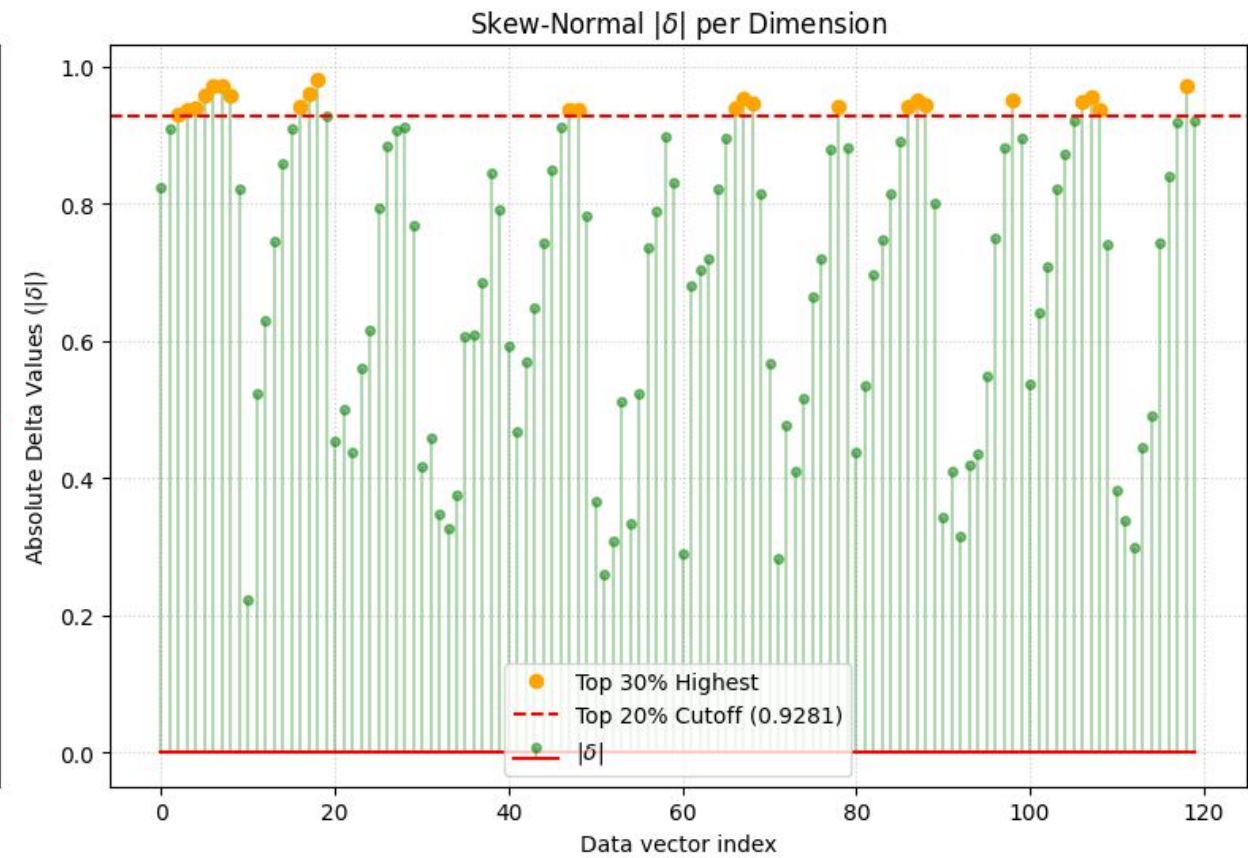
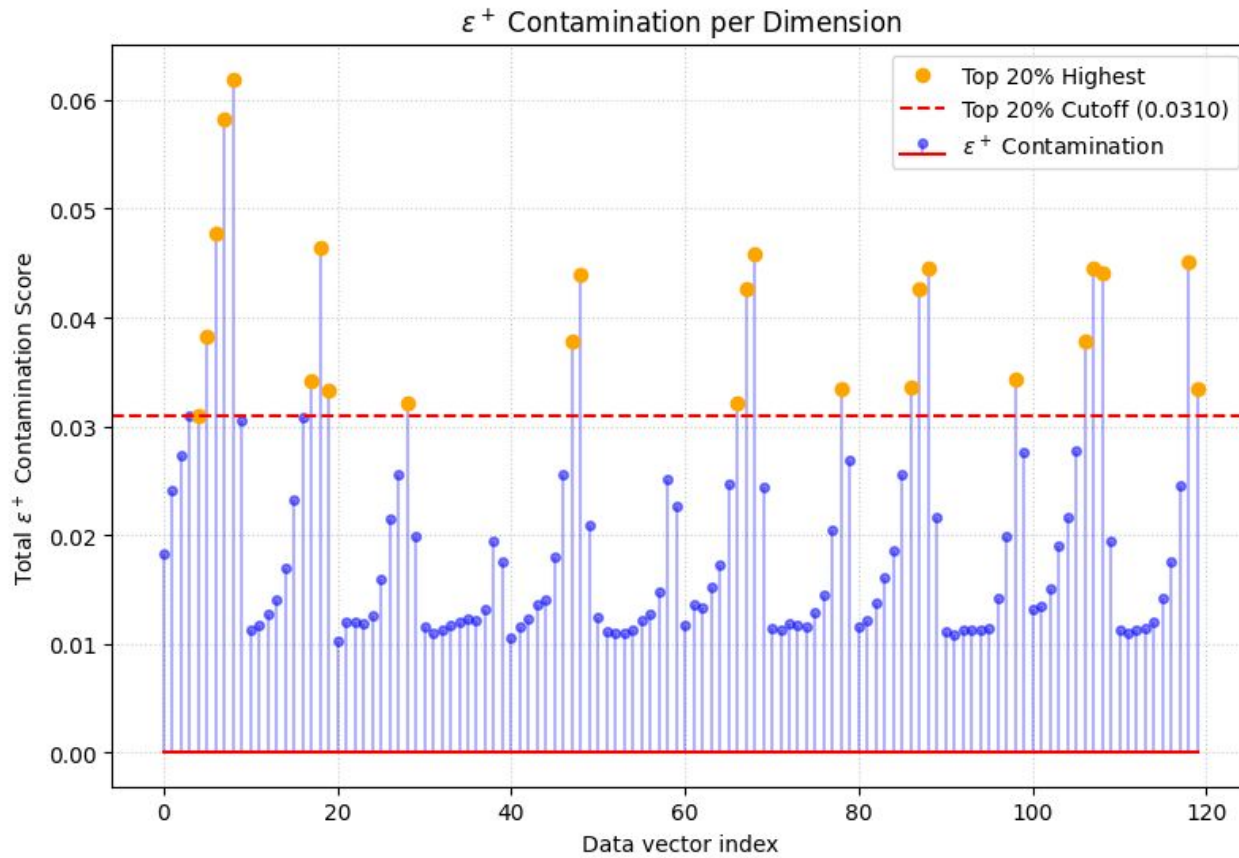
$$\epsilon_e^{\text{tot},+} = \sum_{f \neq e} S_{e,f}^+$$

Sellentin et al. (2017)

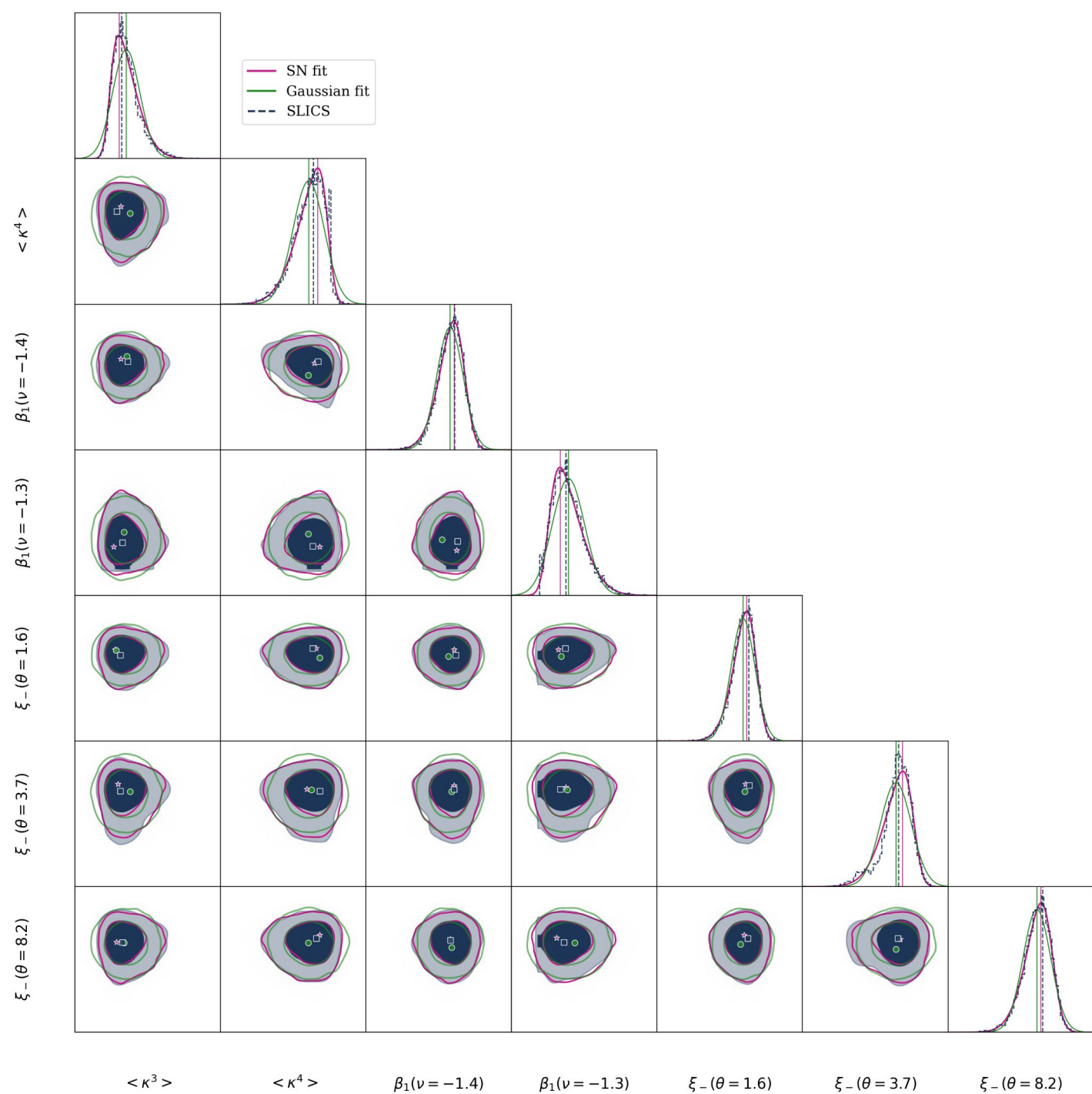


Using a different threshold for non-Gaussianity

Comparison of Non-Gaussianity Metrics per data point

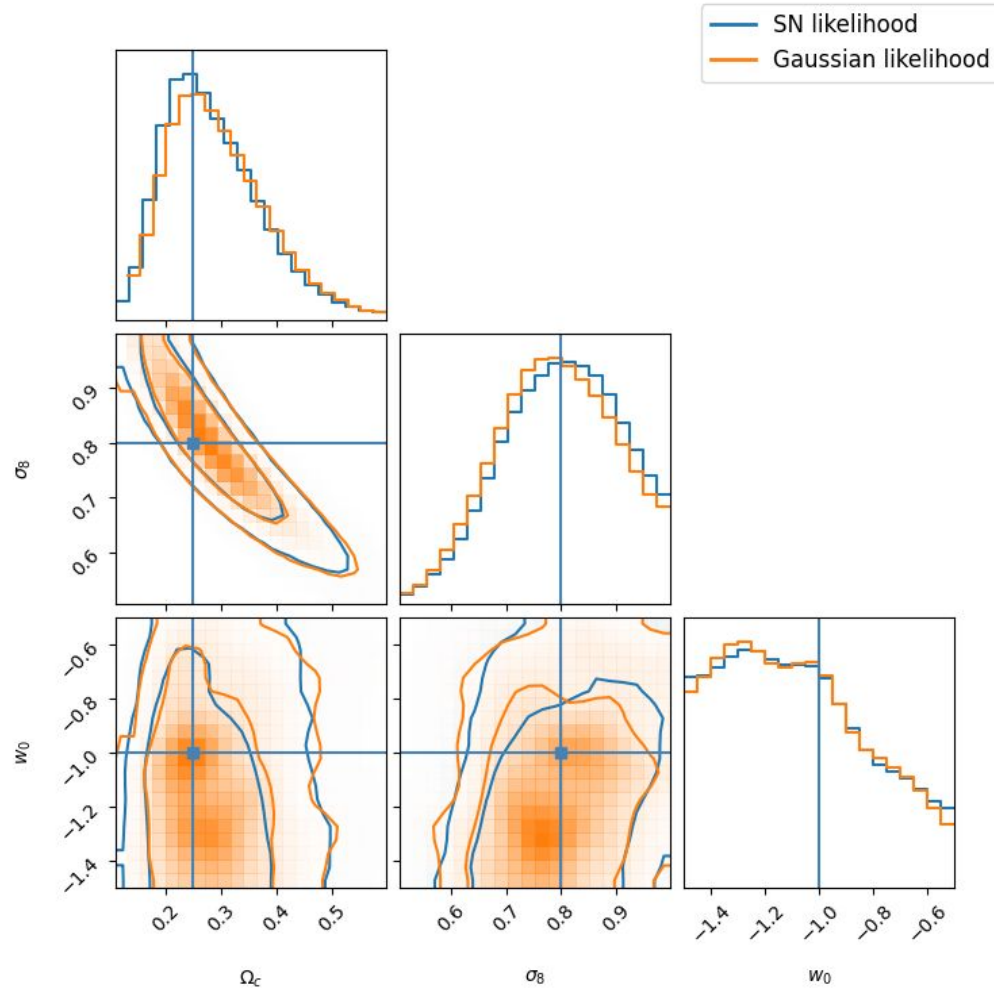


Case study: SLICS shear-2PCF

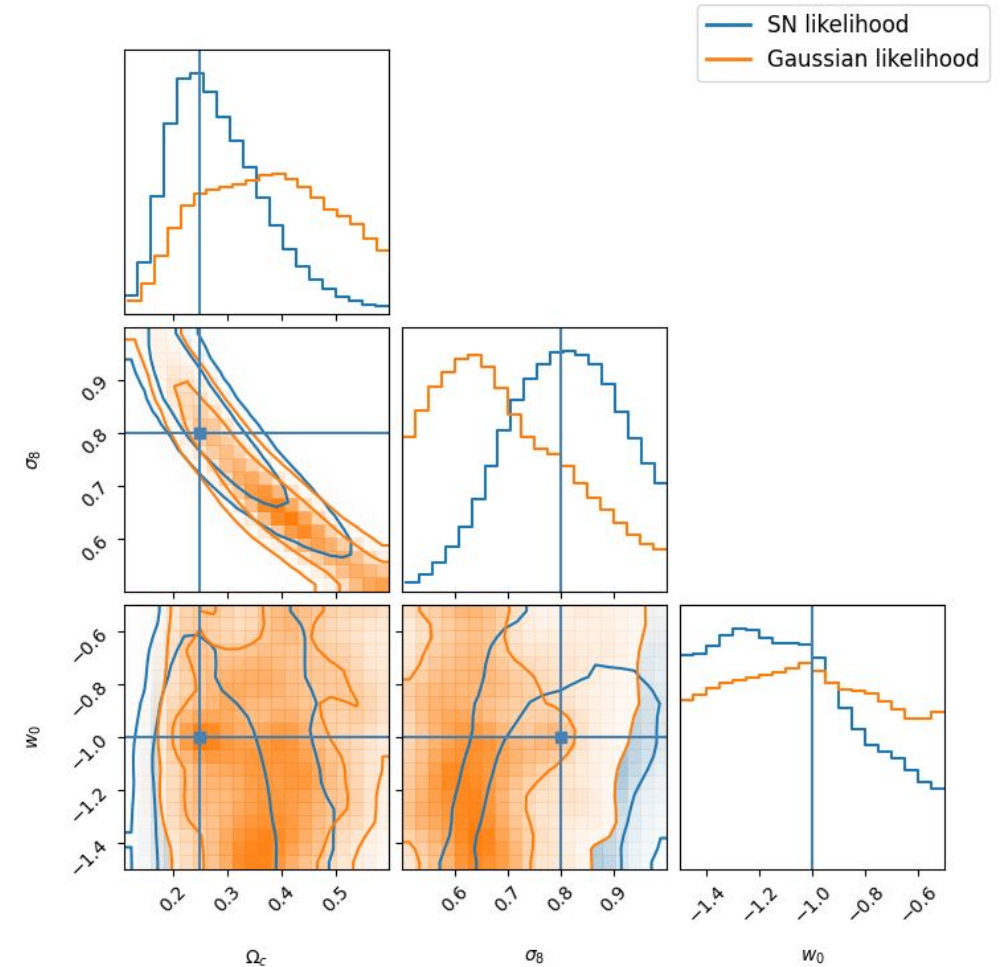


MCMC result: SLICS shear-2PCF

- ✓ All the data points included in both likelihoods: 0.1σ shift in S_8 .

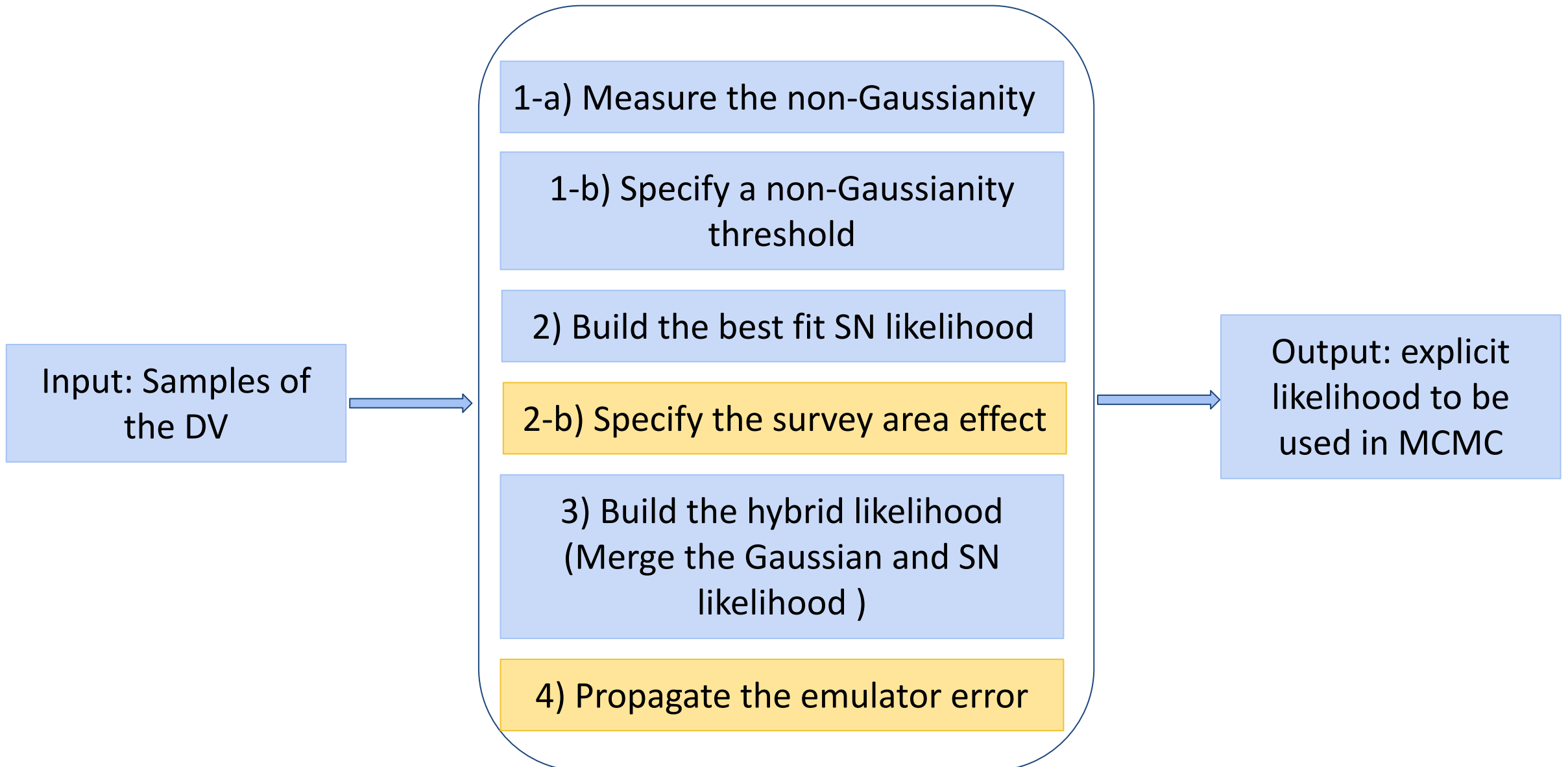


- ✓ Data points with non-Gaussian contamination have been removed in the Gaussian likelihood.



Data vector includes notomography and auto z-bins (length: 120)

Things to be done...



Conclusion

- ✓ The non-Gaussian metrics have significant details that change the valid range of the fisher forecast.
- ✓ **At the fitting level:** The skew normal likelihood fits the distribution of the data vectors better than the gaussian likelihood depending on the contamination of the data
- ✓ **At the inference level:** The skew normal likelihood can shift the S8 parameter using shear2pcf data up to 0.1σ in comparison to the Gaussian likelihood.
- ✓ If we assume that the Gaussian likelihood is not valid above a certain threshold this shift can go significantly higher and also due to the fact that we are excluding some of the non-Gaussian data points, the uncertainty of the parameters inference will expand.

Thank You!