

MadNIS — MadGraph Neural Importance Sampling

Theo Heime
November 2024



UNIVERSITÄT
HEIDELBERG
ZUKUNFT
SEIT 1386

[2212.06172] TH, Winterhalder, Butter, Isaacson, Krause, Maltoni, Mattelaer, Plehn

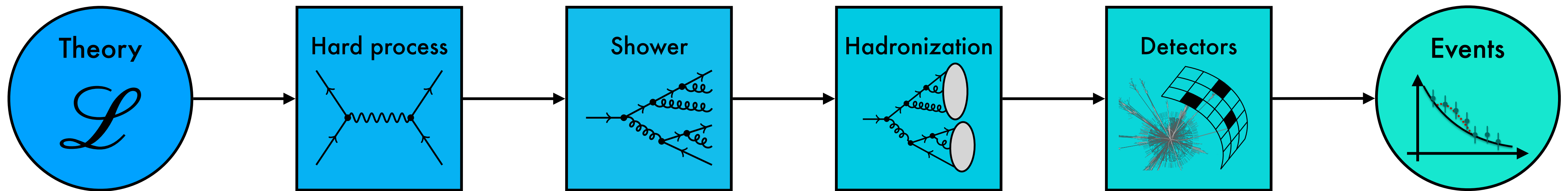
[2311.01548] TH, Huetsch, Maltoni, Mattelaer, Plehn, Winterhalder

[2408.01486] TH, Mattelaer, Plehn, Winterhalder

[2411.00942] TH, Plehn, Schmal

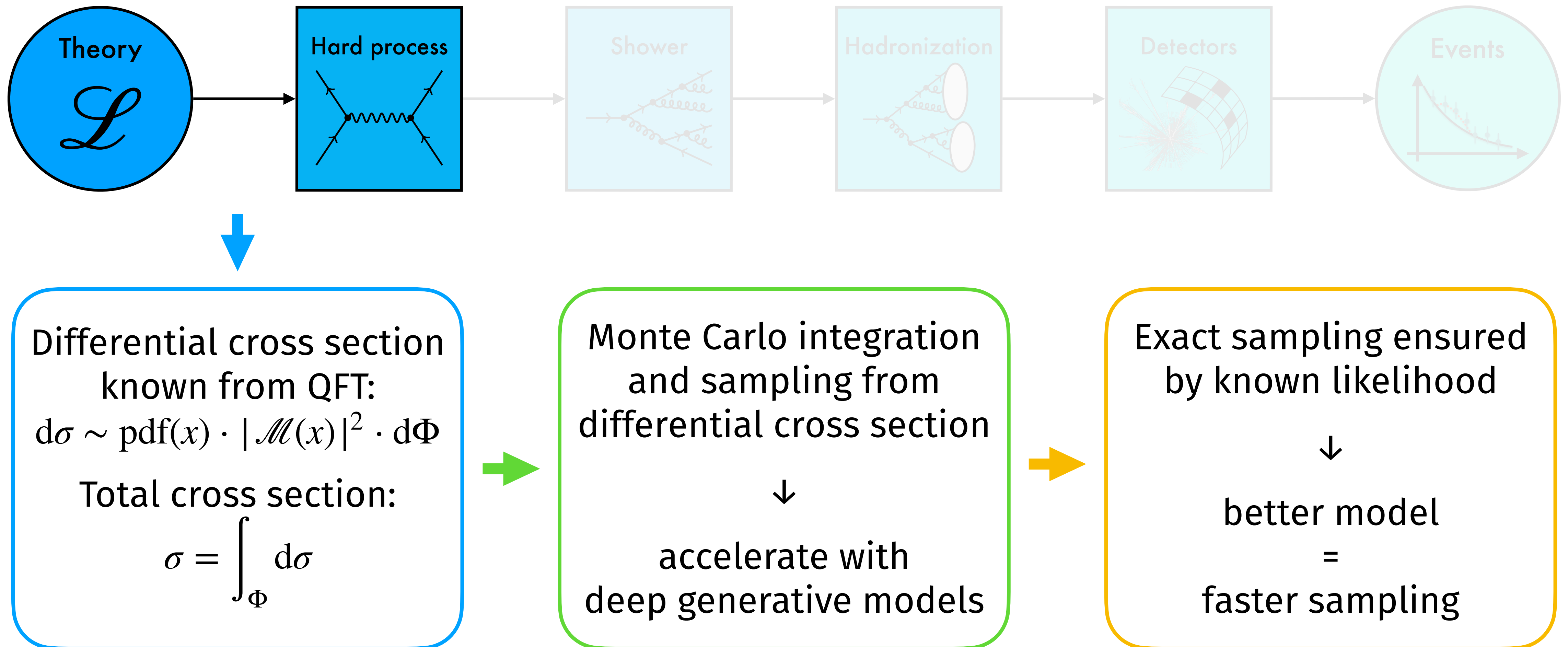
Introduction

How can we prevent MC event generation from becoming a bottleneck in future LHC runs?



Introduction

How can we prevent MC event generation from becoming a bottleneck in future LHC runs?

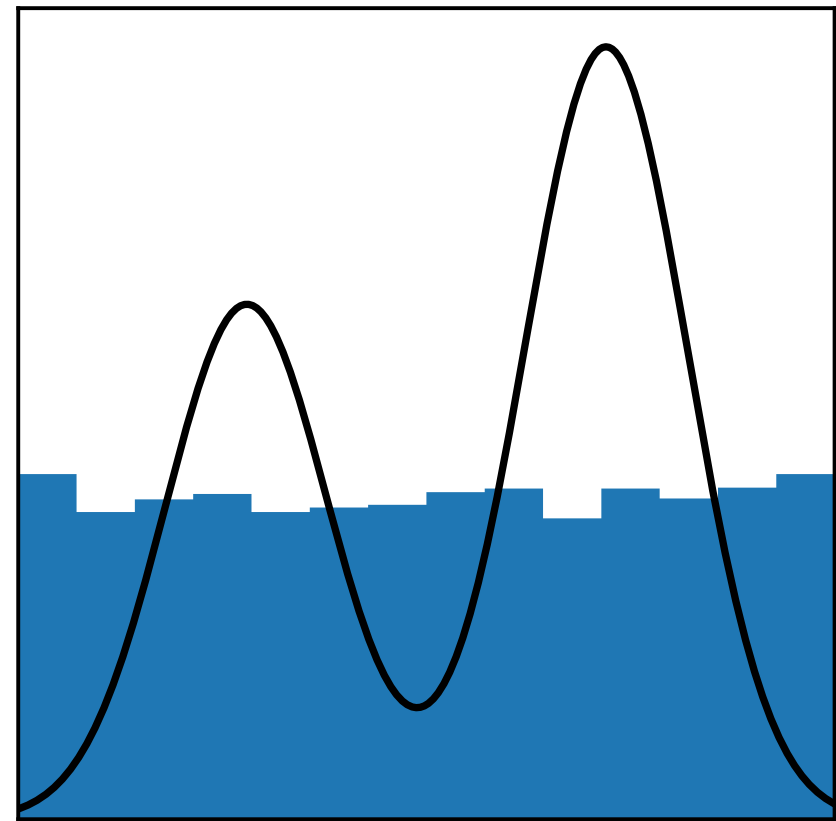


Monte Carlo integration + sampling

$$I = \int dx f(x)$$

Monte Carlo integration + sampling

$$I = \int dx f(x)$$

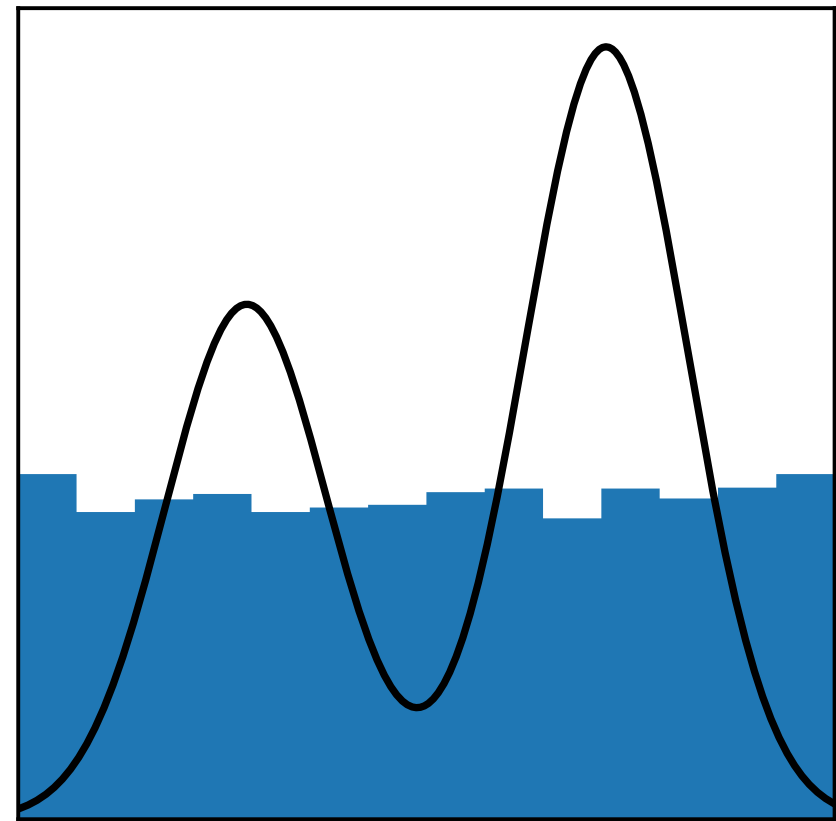


Flat sampling
inefficient

$$I = \langle f(x) \rangle_{x \sim p(x)}$$

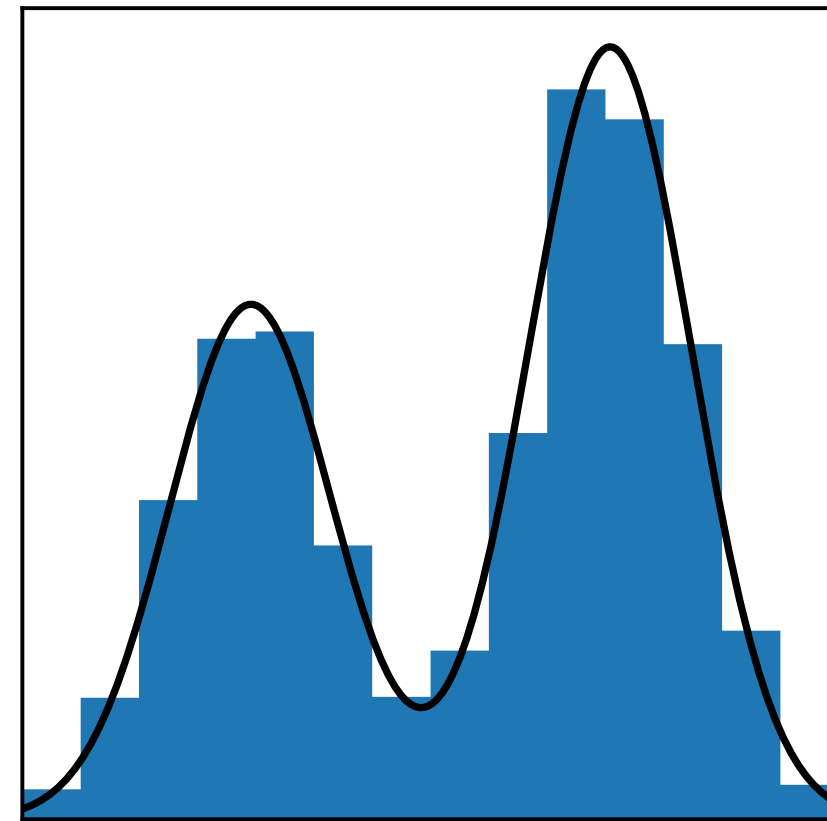
Monte Carlo integration + sampling

$$I = \int dx f(x)$$



Flat sampling
inefficient

$$I = \langle f(x) \rangle_{x \sim p(x)}$$

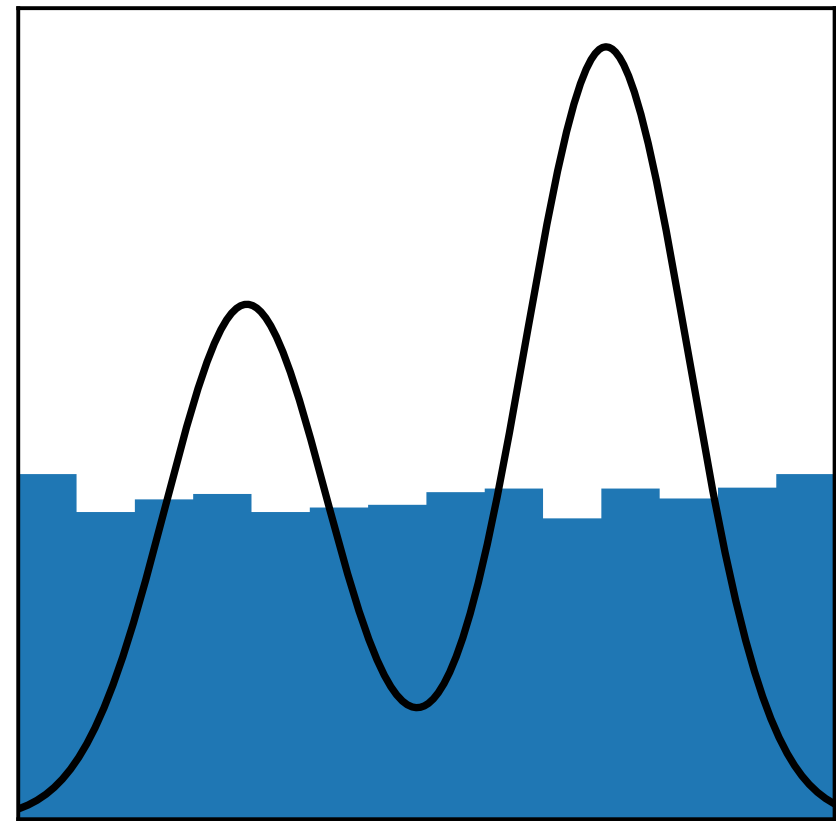


Importance sampling
Find mapping close
to integrand

$$I = \left\langle \frac{f(x)}{g(x)} \right\rangle_{x \sim g(x)}$$

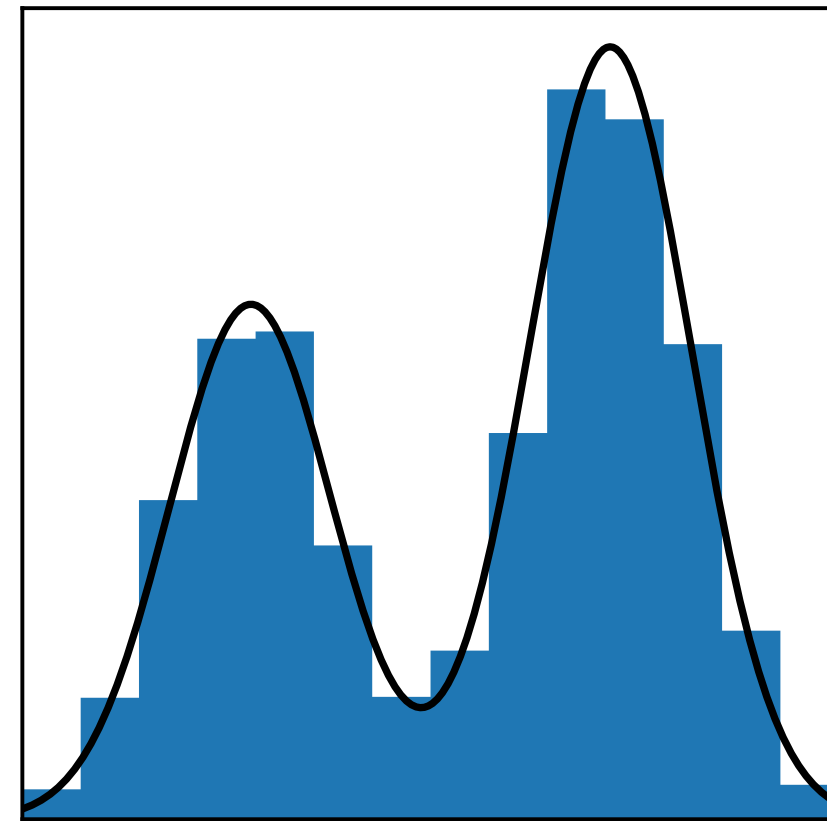
Monte Carlo integration + sampling

$$I = \int dx f(x)$$



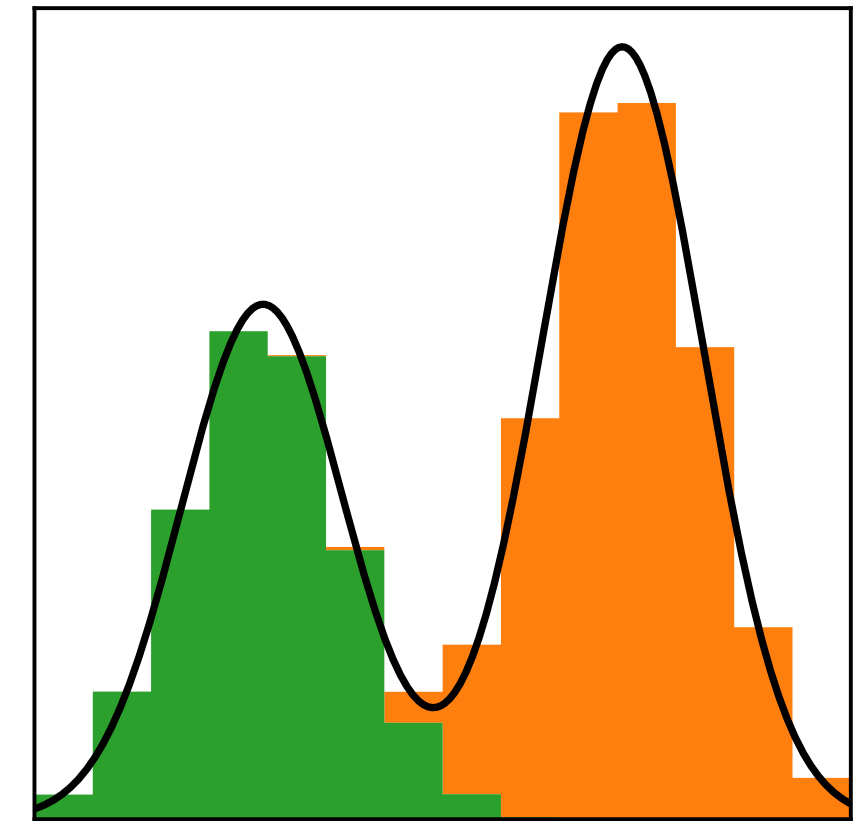
Flat sampling
inefficient

$$I = \langle f(x) \rangle_{x \sim p(x)}$$



Importance sampling
Find mapping close
to integrand

$$I = \left\langle \frac{f(x)}{g(x)} \right\rangle_{x \sim g(x)}$$



Multi-channeling
one mapping for
each channel

$$I = \sum_i \left\langle \alpha_i(x) \frac{f(x)}{g_i(x)} \right\rangle_{x \sim g_i(x)}$$

Phase space integration

How can we make event generation faster?

Efficient integration and sampling from differential cross section

$$d\sigma = \frac{1}{\text{flux}} dx_a dx_b f(x_a) f(x_b) d\Phi_n \langle |M_{\lambda,c,\dots}(p_a, p_b | p_1, \dots, p_n)|^2 \rangle$$



$$I = \sum_i \left\langle \alpha_i(x) \frac{f(x)}{g_i(x)} \right\rangle_{x \sim g_i(x)}$$

Phase space integration

How can we make event generation faster?

Efficient integration and sampling from differential cross section

$$d\sigma = \frac{1}{\text{flux}} dx_a dx_b f(x_a) f(x_b) d\Phi_n \langle |M_{\lambda,c,\dots}(p_a, p_b | p_1, \dots, p_n)|^2 \rangle$$



Integrand

MadGraph: $d\sigma/dx$

$$I = \sum_i \left\langle \alpha_i(x) \frac{f(x)}{g_i(x)} \right\rangle_{x \sim g_i(x)}$$

Phase space integration

How can we make event generation faster?

Efficient integration and sampling from differential cross section

$$d\sigma = \frac{1}{\text{flux}} dx_a dx_b f(x_a) f(x_b) d\Phi_n \langle |M_{\lambda,c,\dots}(p_a, p_b | p_1, \dots, p_n)|^2 \rangle$$



Sum over channels

MadGraph: build channels
from Feynman diagrams

Integrand

MadGraph: $d\sigma/dx$

$$I = \sum_i \left\langle \alpha_i(x) \frac{f(x)}{g_i(x)} \right\rangle_{x \sim g_i(x)}$$

Phase space integration

How can we make event generation faster?

Efficient integration and sampling from differential cross section

$$d\sigma = \frac{1}{\text{flux}} dx_a dx_b f(x_a) f(x_b) d\Phi_n \langle |M_{\lambda,c,\dots}(p_a, p_b | p_1, \dots, p_n)|^2 \rangle$$



Sum over channels

MadGraph: build channels from Feynman diagrams

$$I = \sum_i \left\langle \alpha_i(x) \frac{f(x)}{g_i(x)} \right\rangle_{x \sim g_i(x)}$$

Integrand

MadGraph: $d\sigma/dx$

Channel mappings

MadGraph: use propagators, ...
Refine with VEGAS
(factorized, histogram based importance sampling)

Phase space integration

How can we make event generation faster?

Efficient integration and sampling from differential cross section

$$d\sigma = \frac{1}{\text{flux}} dx_a dx_b f(x_a) f(x_b) d\Phi_n \langle |M_{\lambda,c,\dots}(p_a, p_b | p_1, \dots, p_n)|^2 \rangle$$



Sum over channels

MadGraph: build channels from Feynman diagrams

Integrand

MadGraph: $d\sigma/dx$

$$I = \sum_i \left\langle \alpha_i(x) \frac{f(x)}{g_i(x)} \right\rangle_{x \sim g_i(x)}$$

Channel weights

MadGraph: $\alpha_i \sim |M_i|^2$

or $\alpha_i \sim \prod |p_k^2 - m_k^2 - iM_k\Gamma_k|^{-2}$

Channel mappings

MadGraph: use propagators, ...
Refine with VEGAS
(factorized, histogram based importance sampling)

MadNIS: Neural Importance Sampling

$$I = \sum_i \left\langle \alpha_i(x) \frac{f(x)}{g_i(x)} \right\rangle_{x \sim g_i(x)}$$

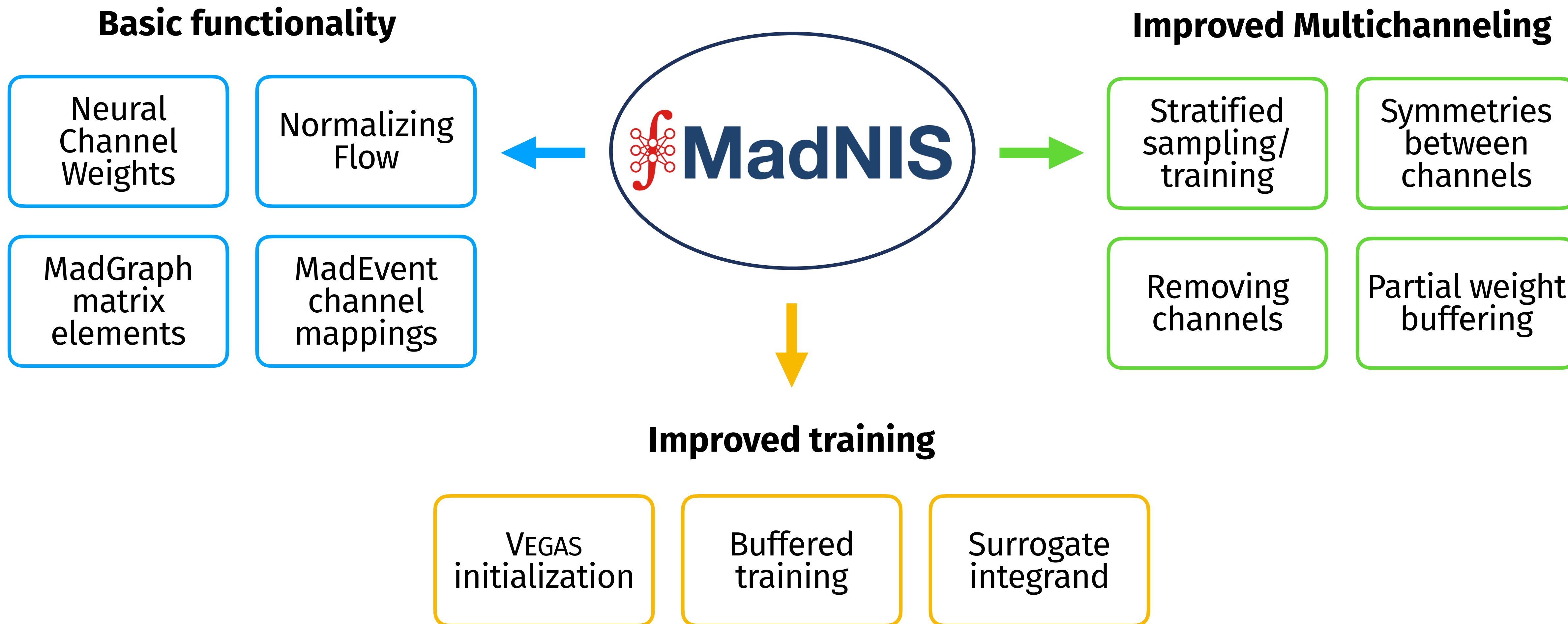
Use physics knowledge to construct channels and mappings

Normalizing Flow to
refine channel mappings

Fully connected network
to refine channel weights

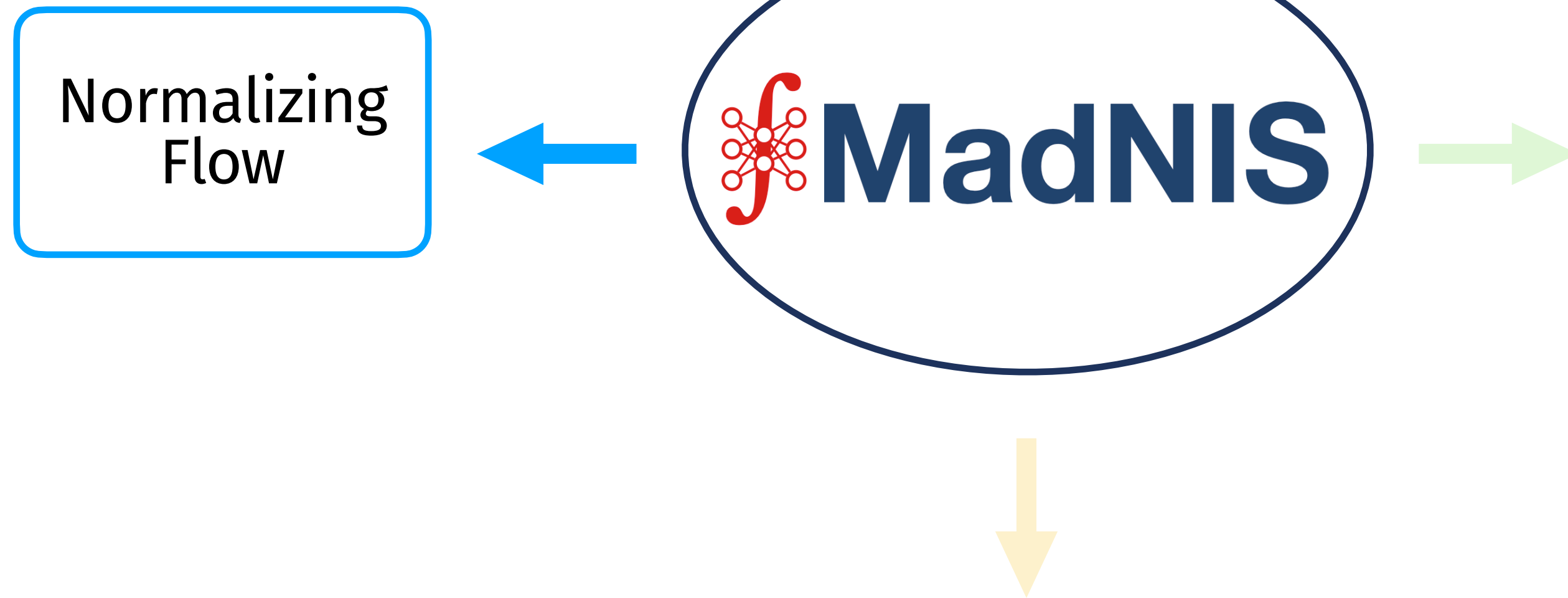
Optimize simultaneously with integral variance as loss function

Overview

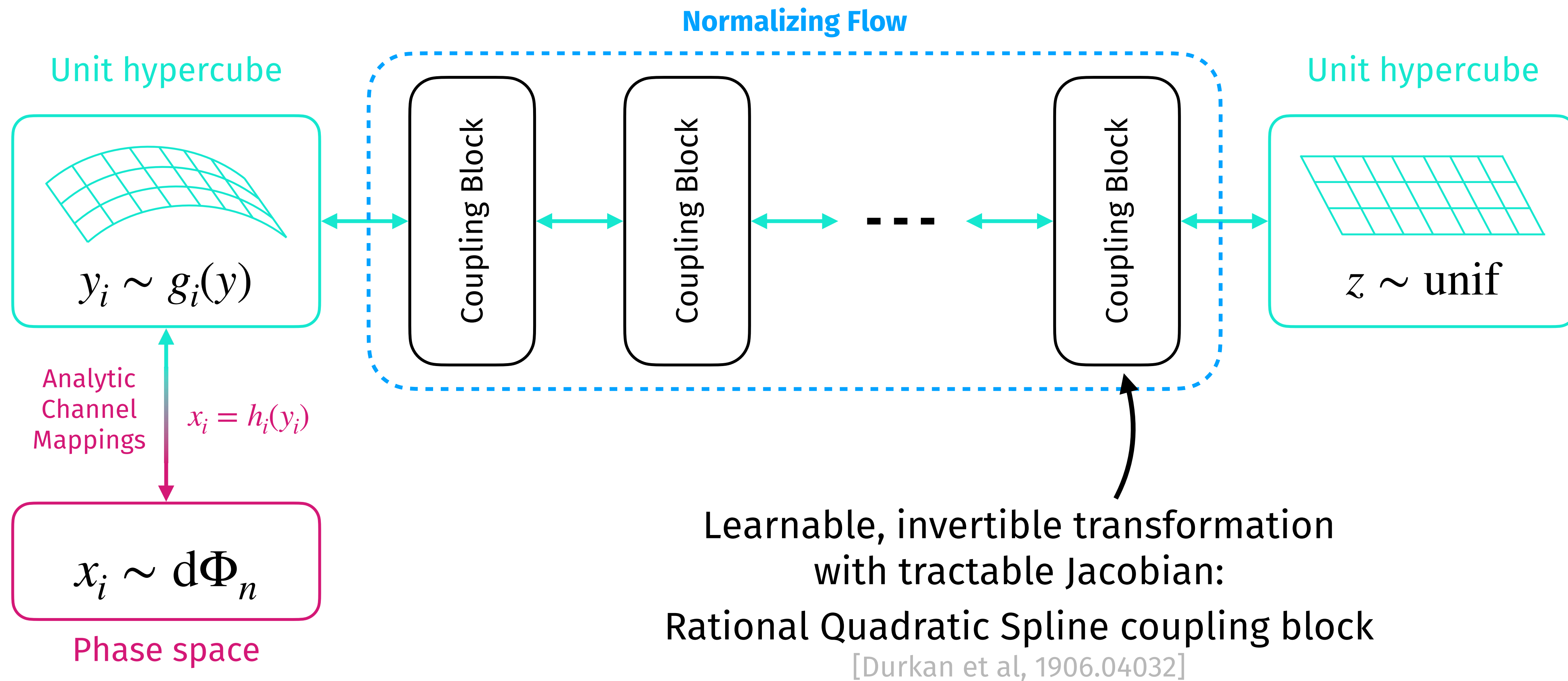


Overview

Basic functionality

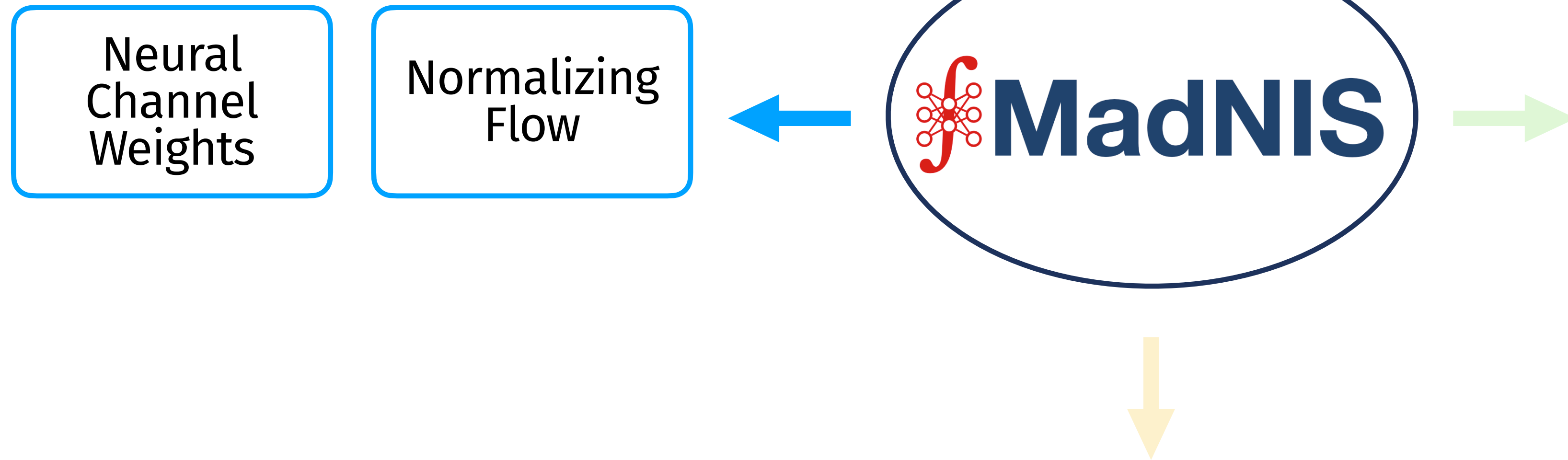


Neural Importance Sampling

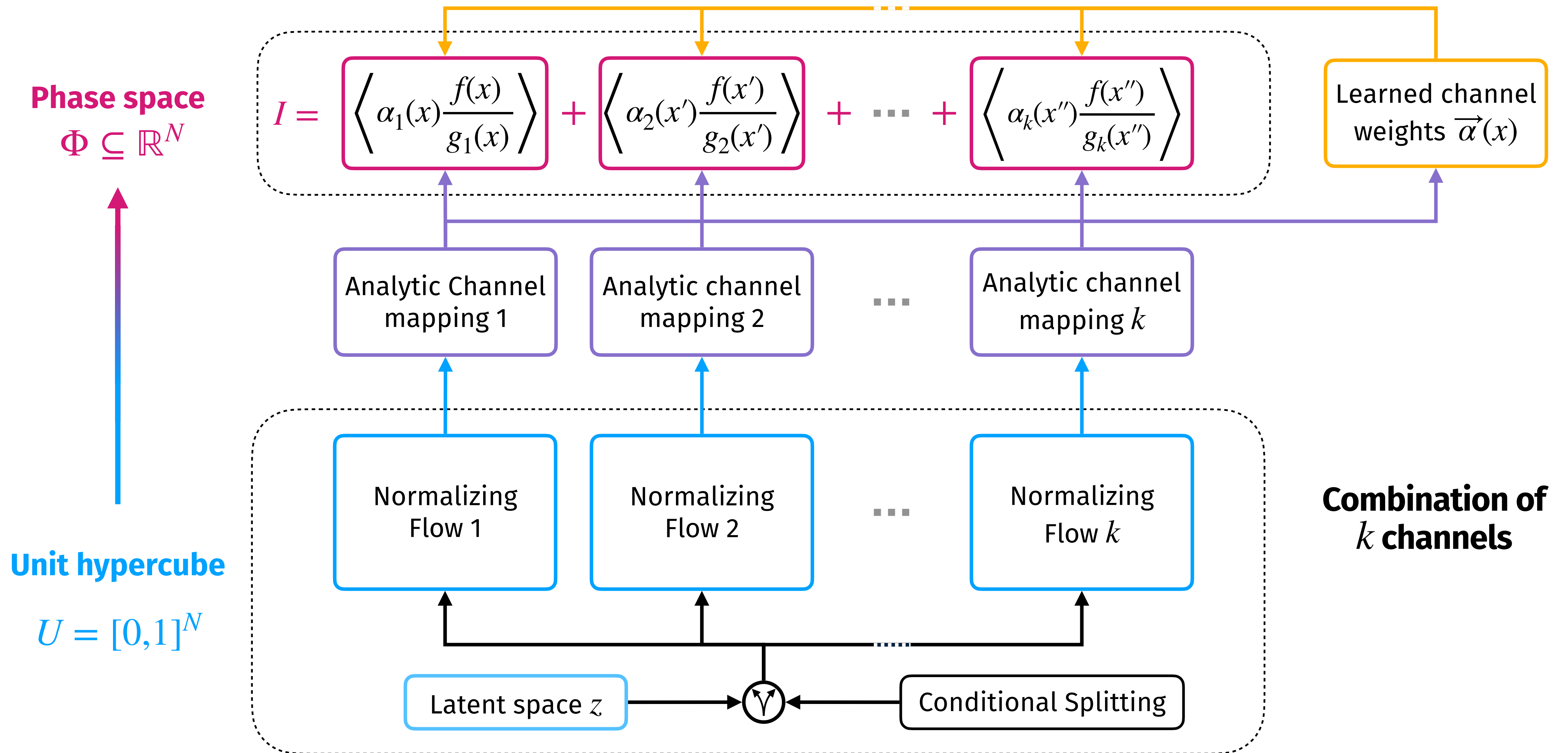


Overview

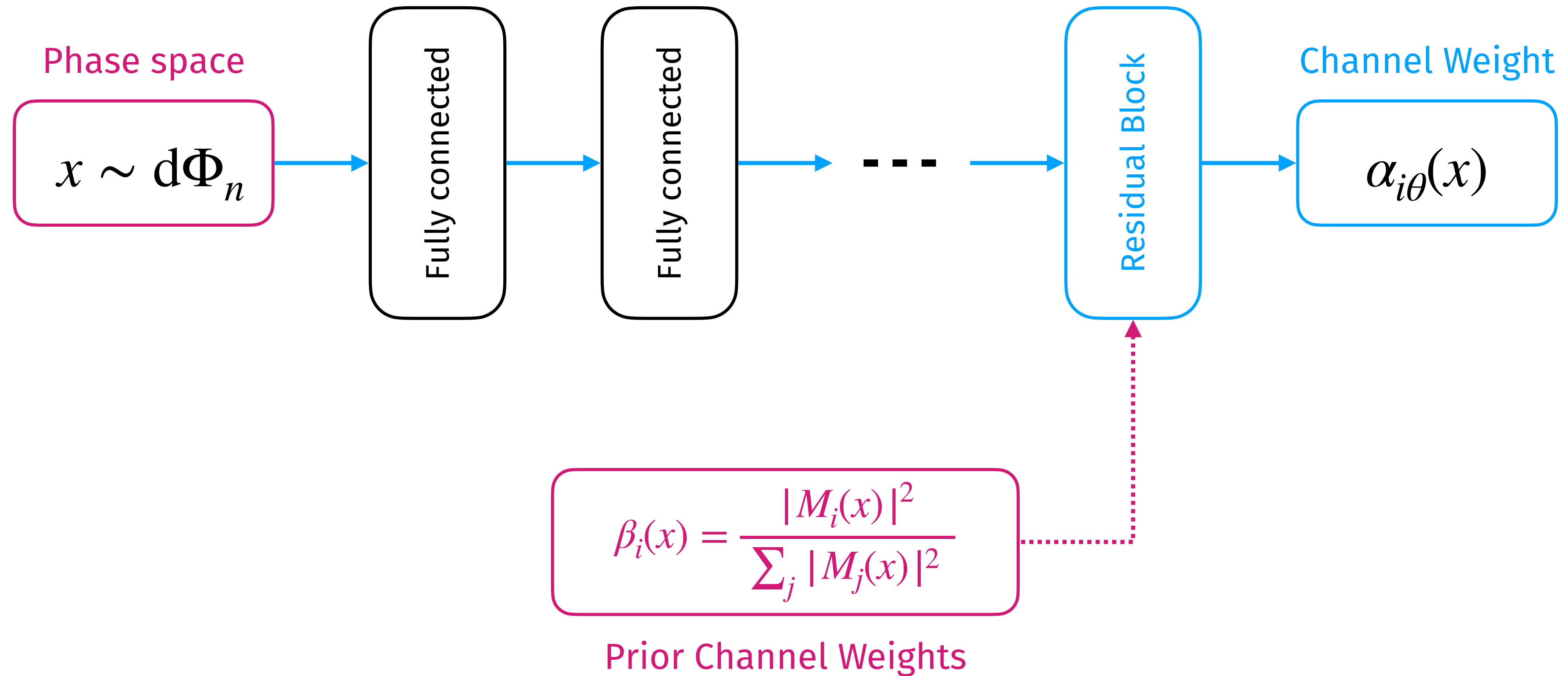
Basic functionality



MADNIS: Neural Importance Sampling



Neural Channel Weights



Loss function

Training objective:
Minimize total variance

$$\sigma_{\text{tot}}^2 = N \sum_i \frac{\sigma_i^2}{N_i} \quad \text{with}$$

$$\sigma_i^2 = \text{Var} \left(\alpha_i(x) \frac{f(x)}{g_i(x)} \right)_{x \sim g_i(x)}$$

Optimal MC weights depend on N_i



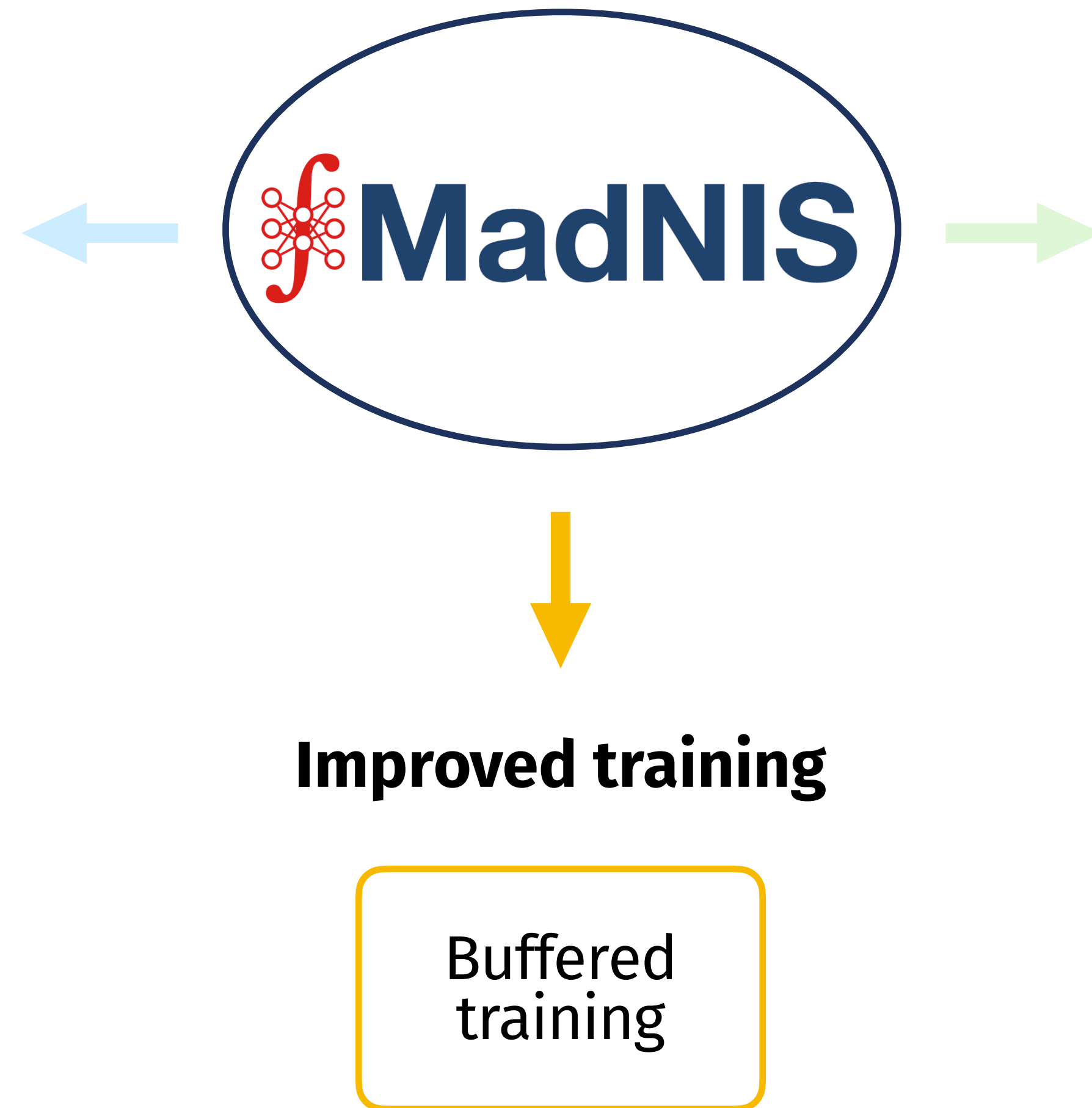
assume choice of N_i during training:
use stratified sampling

$$N_i = N \frac{\sigma_i}{\sum_k \sigma_k}$$

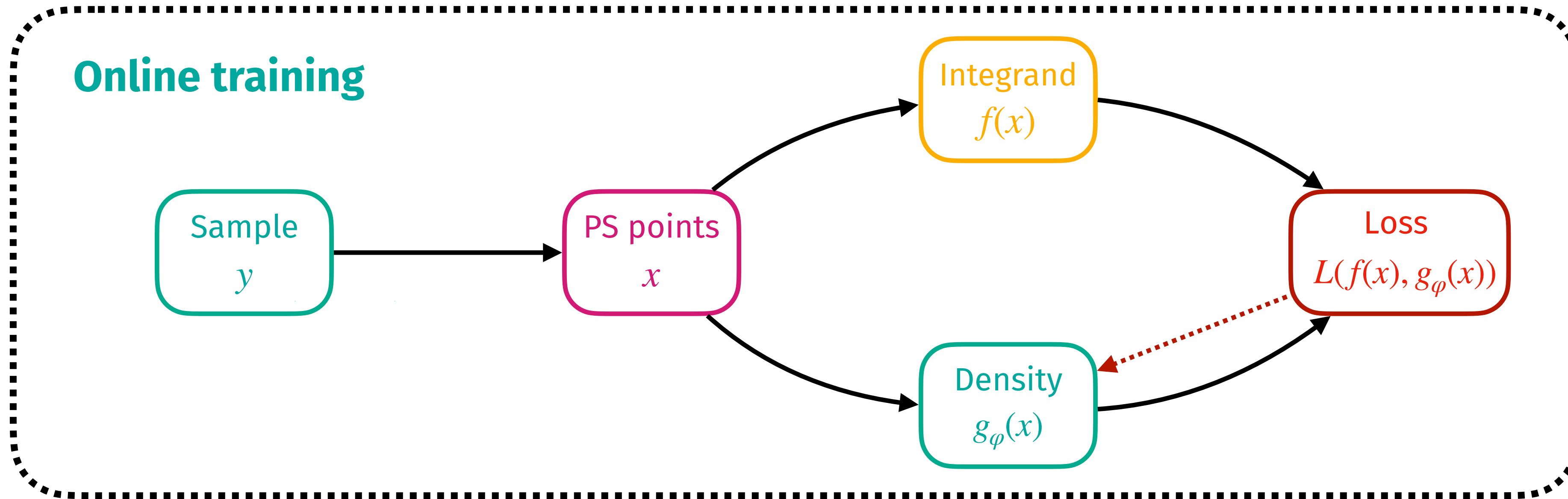
MadNIS loss function

$$\mathcal{L} = \sigma_{\text{tot}}^2 = \sum_{i,k} \sigma_i \sigma_k$$

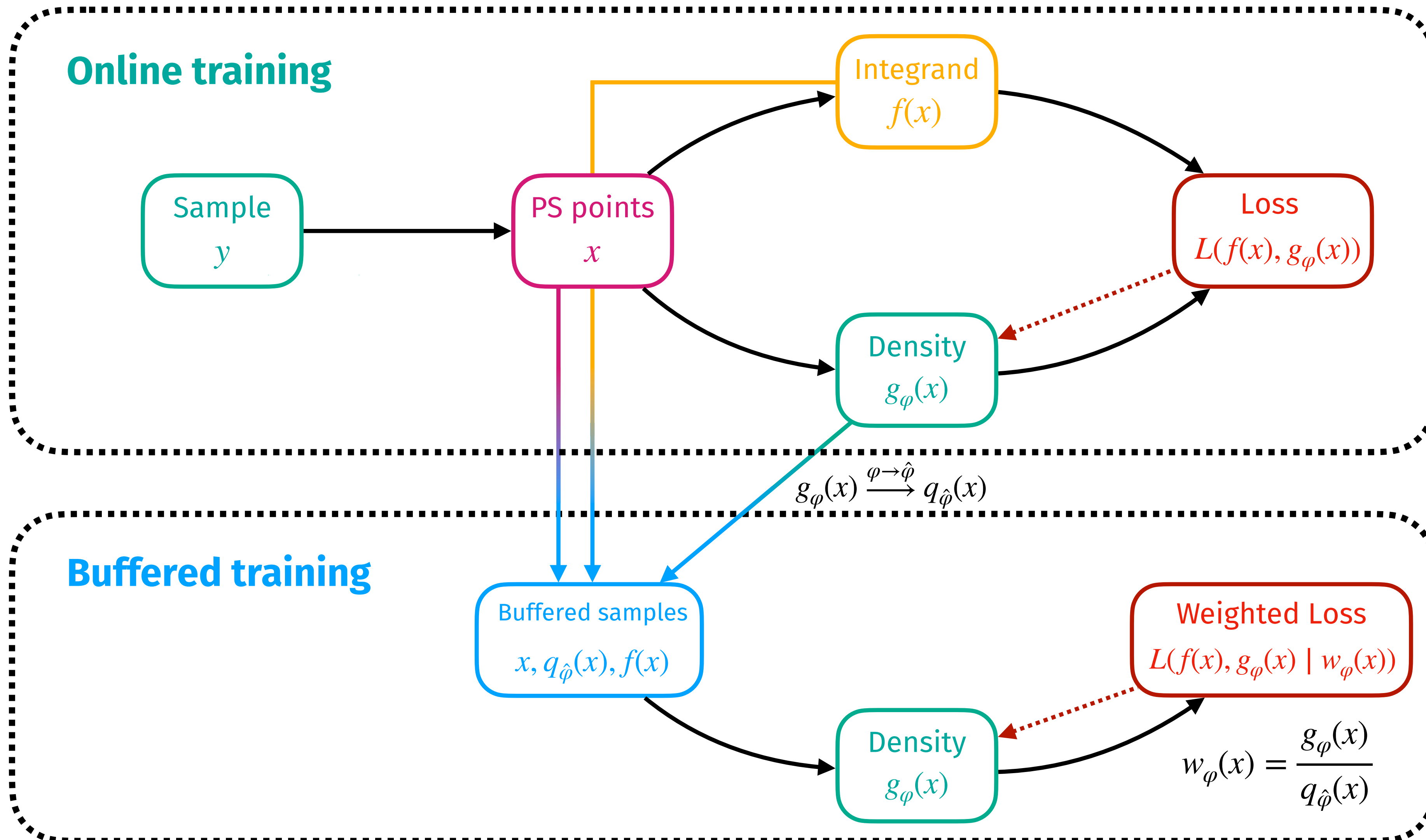
Overview



Buffered Training



Buffered Training



Buffered Training

Training algorithm

generate new samples, train on them,
save samples



train on saved samples n times

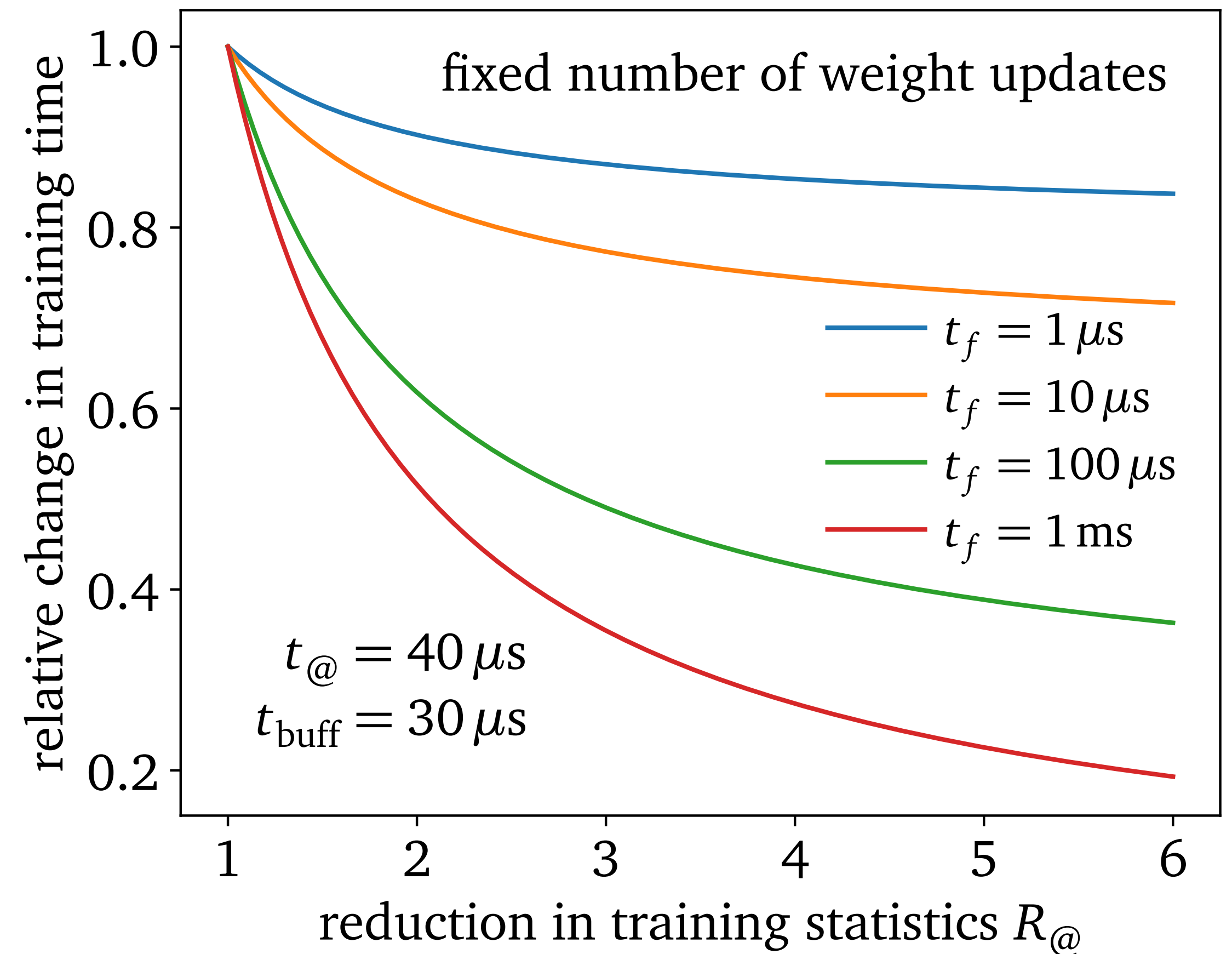


repeat

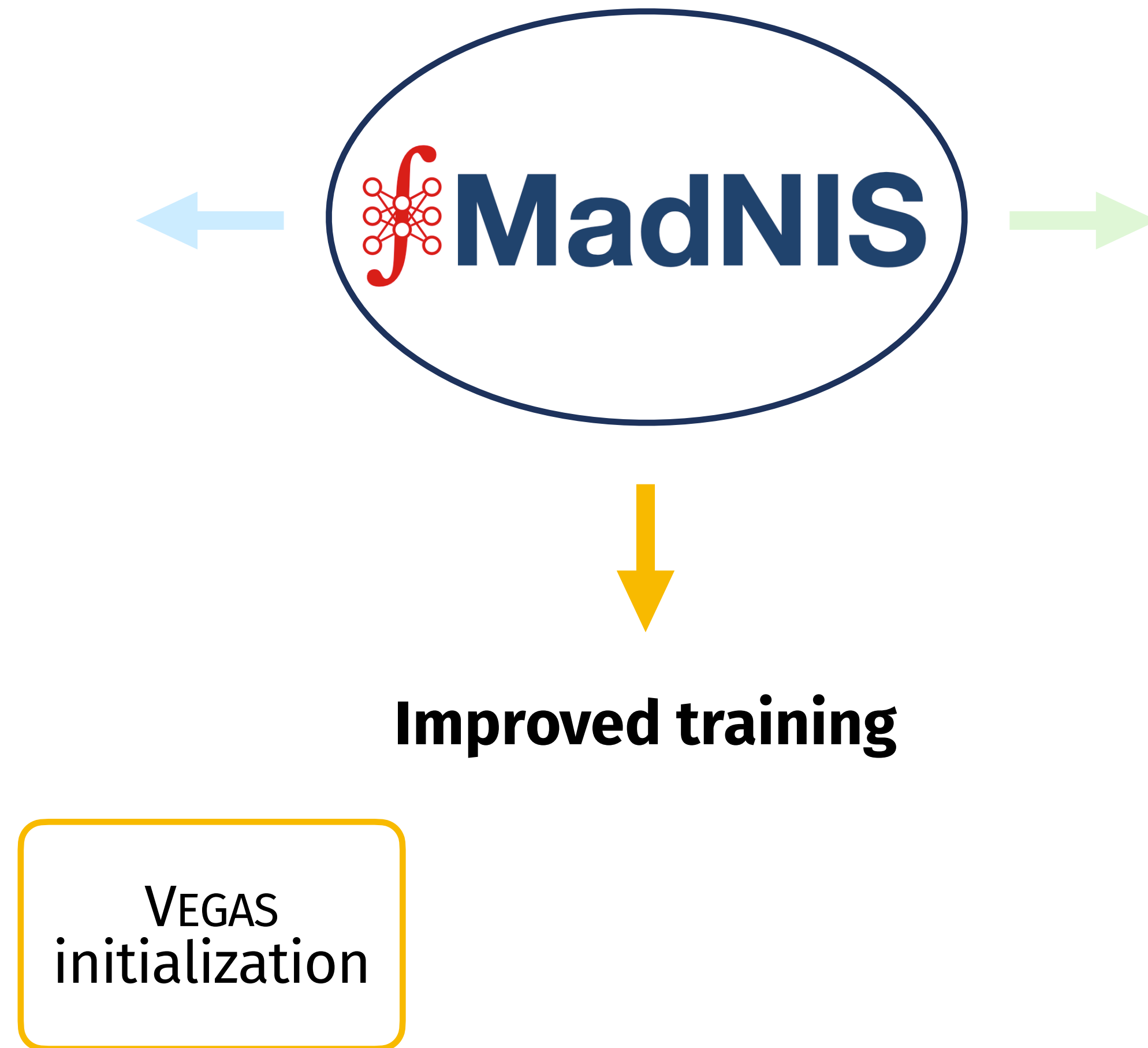


Reduction in training statistics by

$$R_{@} = n + 1$$



Overview



VEGAS Initialization

	VEGAS	Flow
Training	Fast	Slow
Correlations	No	Yes



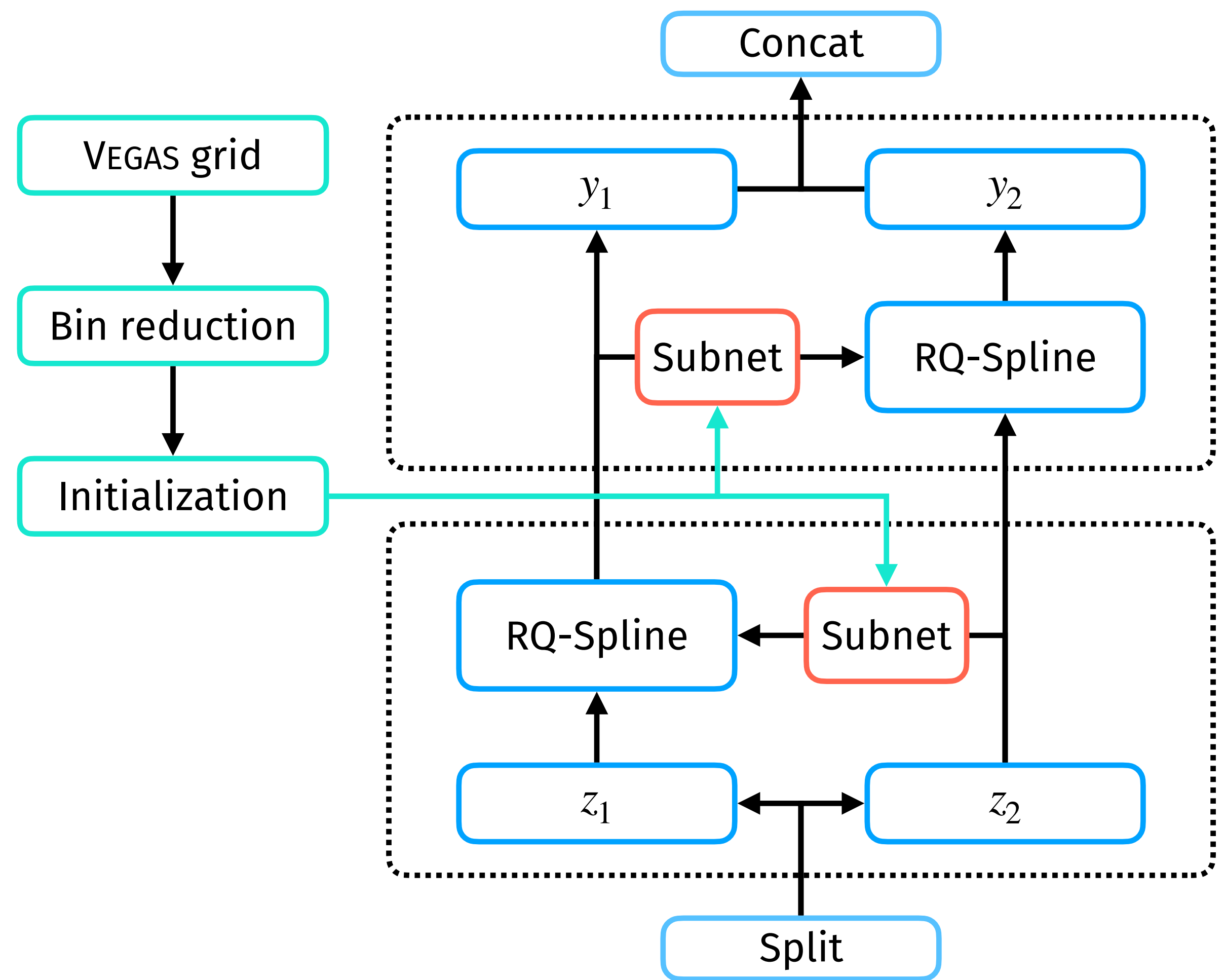
Combine advantages:
Pre-trained VEGAS grid as
starting point for flow training

VEGAS Initialization

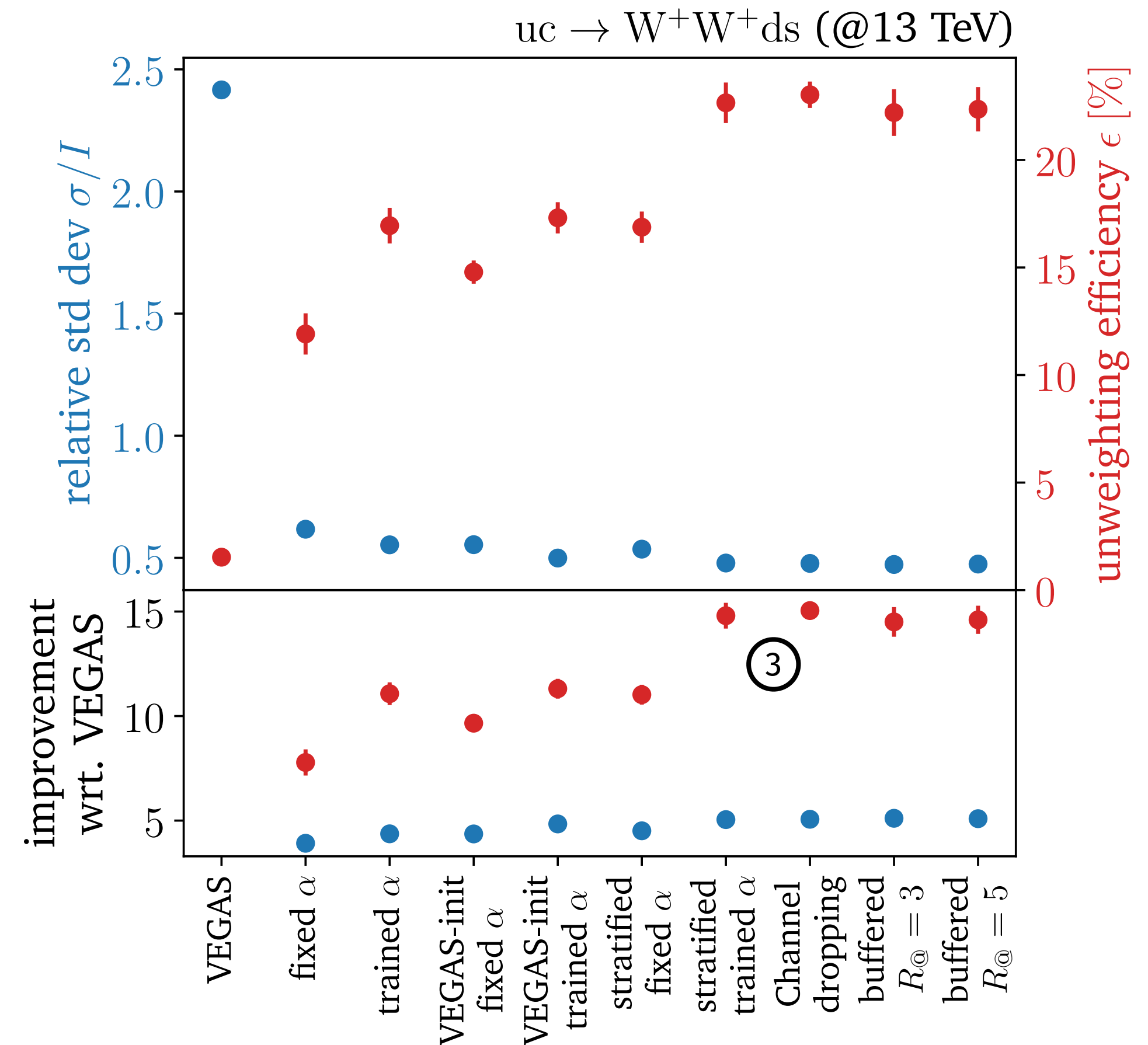
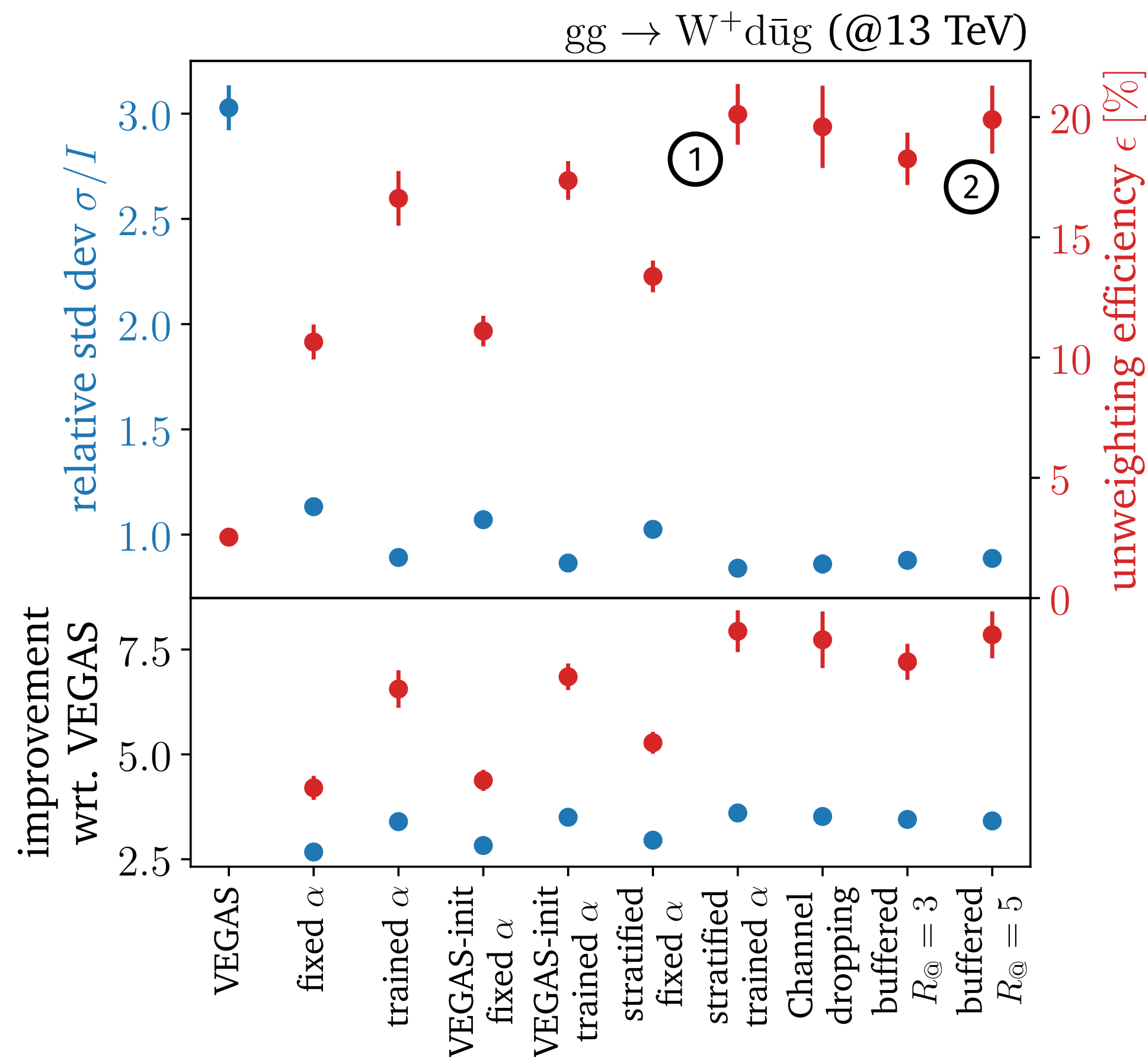
	VEGAS	Flow
Training	Fast	Slow
Correlations	No	Yes



Combine advantages:
Pre-trained VEGAS grid as
starting point for flow training

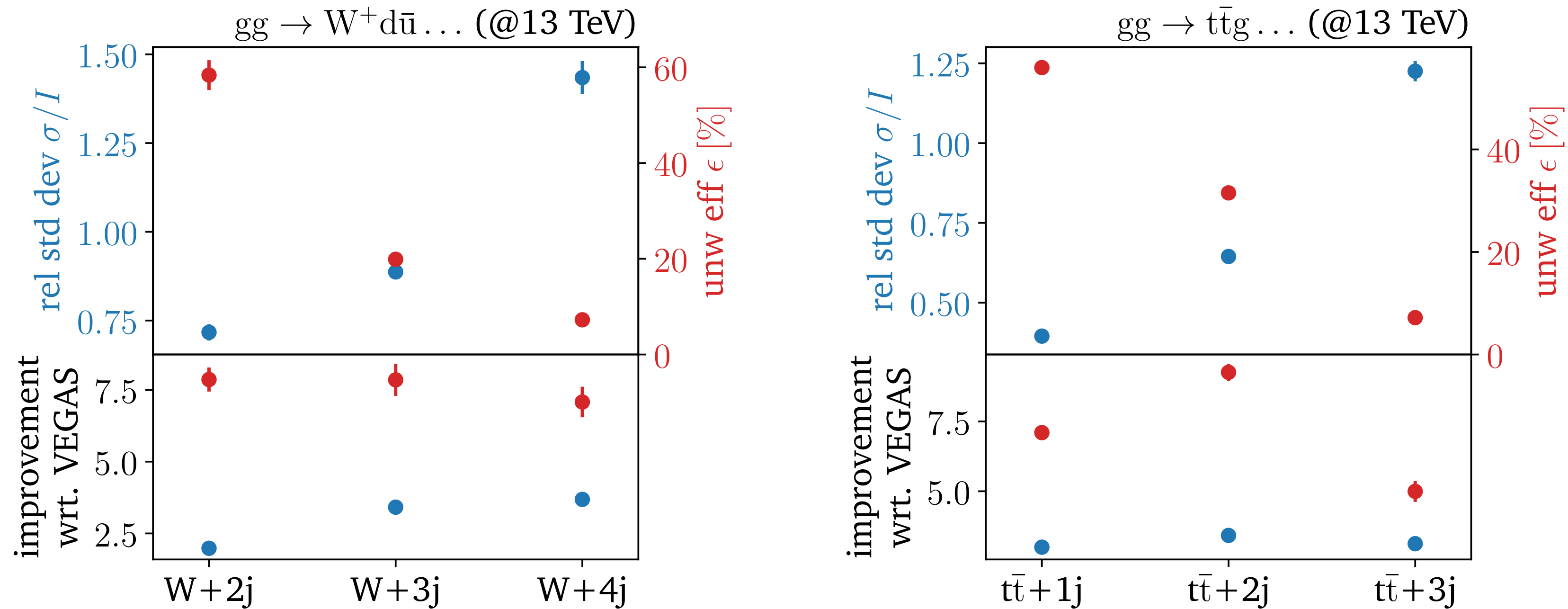


LHC processes



1. Excellent results by combining all improvements!
2. Same performance with buffered training
3. Even larger improvements for process with large interference terms

Scaling with multiplicity

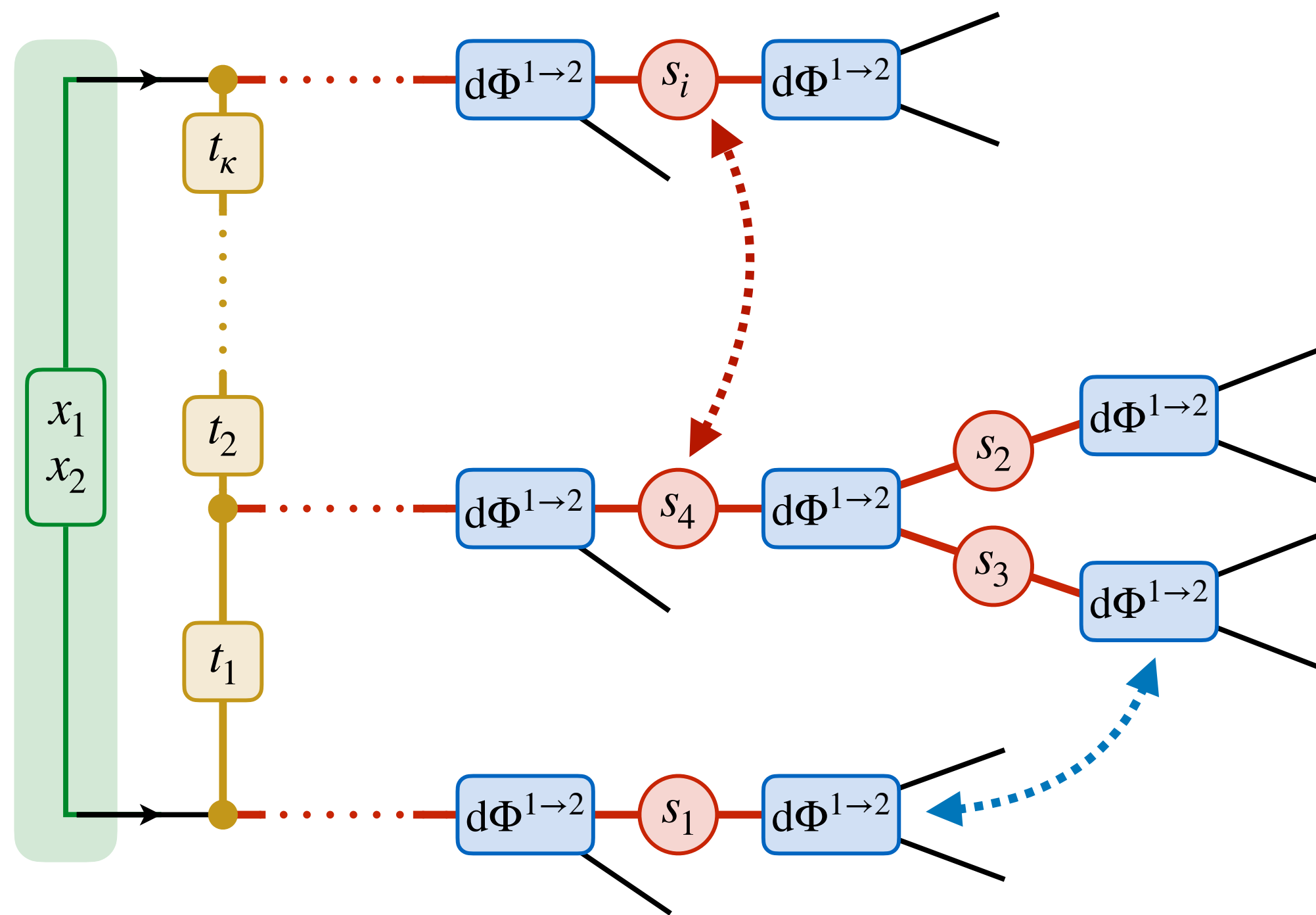


$gg \rightarrow W^+ d \bar{u} g g$
 384 channels, 108 symm.
 7x better than VEGAS

$gg \rightarrow t \bar{t} g g g$
 945 channels, 119 symm.
 5x better than VEGAS

Large improvements compared to VEGAS even
 for high multiplicities and many channels!

Differentiable MadNIS-Lite

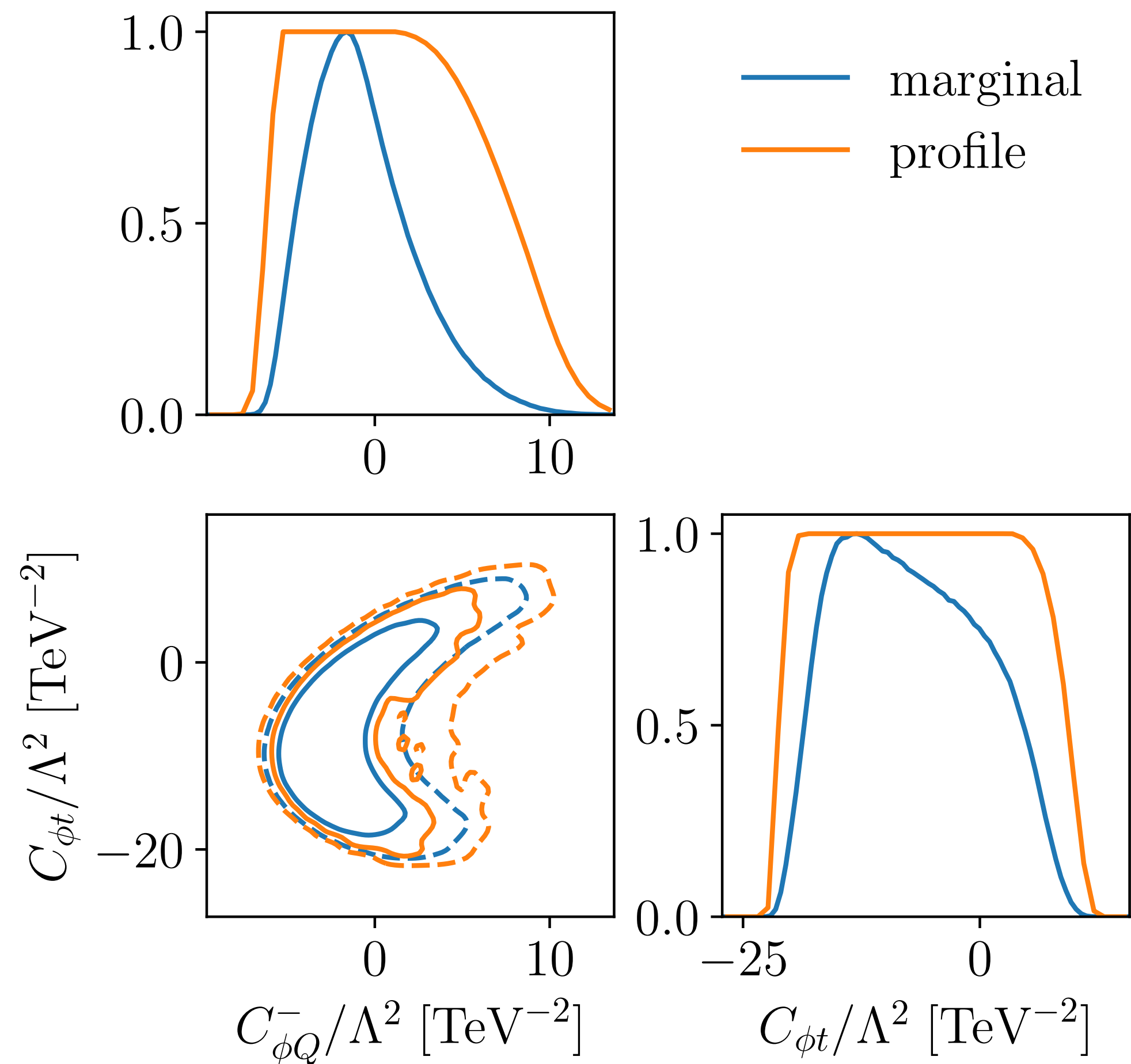



Differentiable MadNIS-Lite [2408.01486]

TH, Olivier Mattelaer, Tilman Plehn,
Ramon Winterhalder

- Build PS mappings from Feynman diagrams
→ implemented in PyTorch
→ **Fully differentiable** and **invertible**
- Build in small trainable components, with parameters shared between
→ all components of same type
→ all channels
- Learn physics of PS mappings
→ **interpretability**
→ **train on n jets, generate $n+1$ jets**

MadNIS technology for SFitter



- Apply neural importance sampling to SFitter likelihood 
- Combined SMEFT fit in Higgs and Top sector
→ 42 Wilson coefficients
→ ~500 datapoints from various analyses
- **Efficient profiling and marginalization**
→ before: days on CPU cluster
→ now: **a few hours on a single GPU**

Profile likelihood on ML steroids [\[2411.00942\]](#)

TH, Tilman Plehn, Nikita Schmal

MadNIS technology for SFitter

- Apply neural importance sampling to SFitter likelihood
- Combined SMEFT fit in Higgs and Top sector
→ 42 Wilson coefficients
→ ~500 datapoints from various analyses
- **Efficient profiling and marginalization**
→ before: days on CPU cluster
→ now: **a few hours on a single GPU**

Profile likelihood on ML steroids [\[2411.00942\]](#)
TH, Tilman Plehn, Nikita Schmal

Outlook

Release of MadNIS package

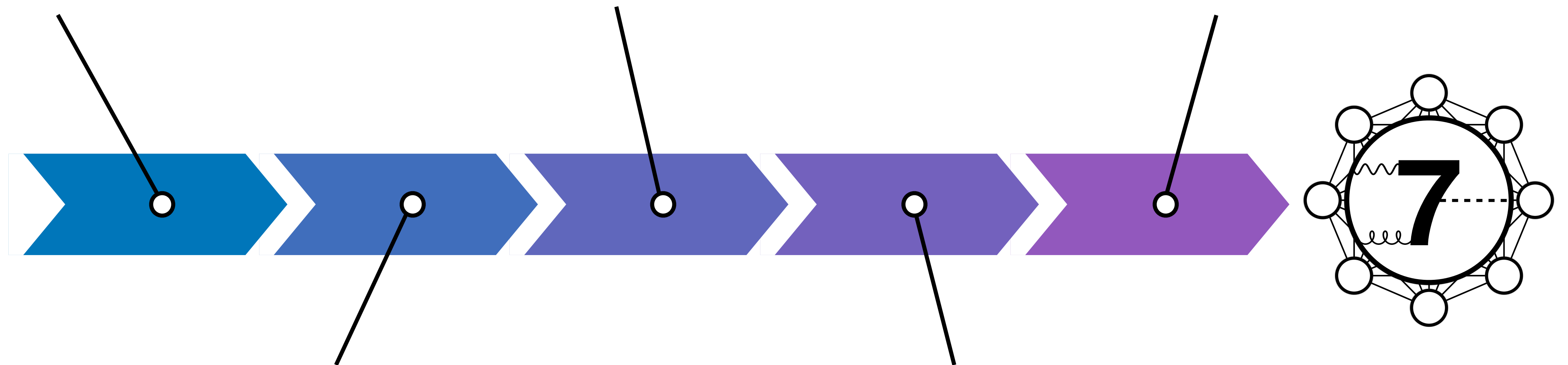
- python library
 - easy install with 'pip install'
- **December 2024**

New MadEvent7

- fully vectorized mappings
- multiple backends (c++, cuda, python,...)

Release of MadGraph7

- rigorous testing
- reliable default settings dep. on hardware/process/...



Fully integrate into MG5aMC

- multiple partonic processes
- optimized API
- merge with MG@GPU

MadNIS@NLO

- subtraction-aware sampling
- fast ML amplitudes (NLO)

Appendix

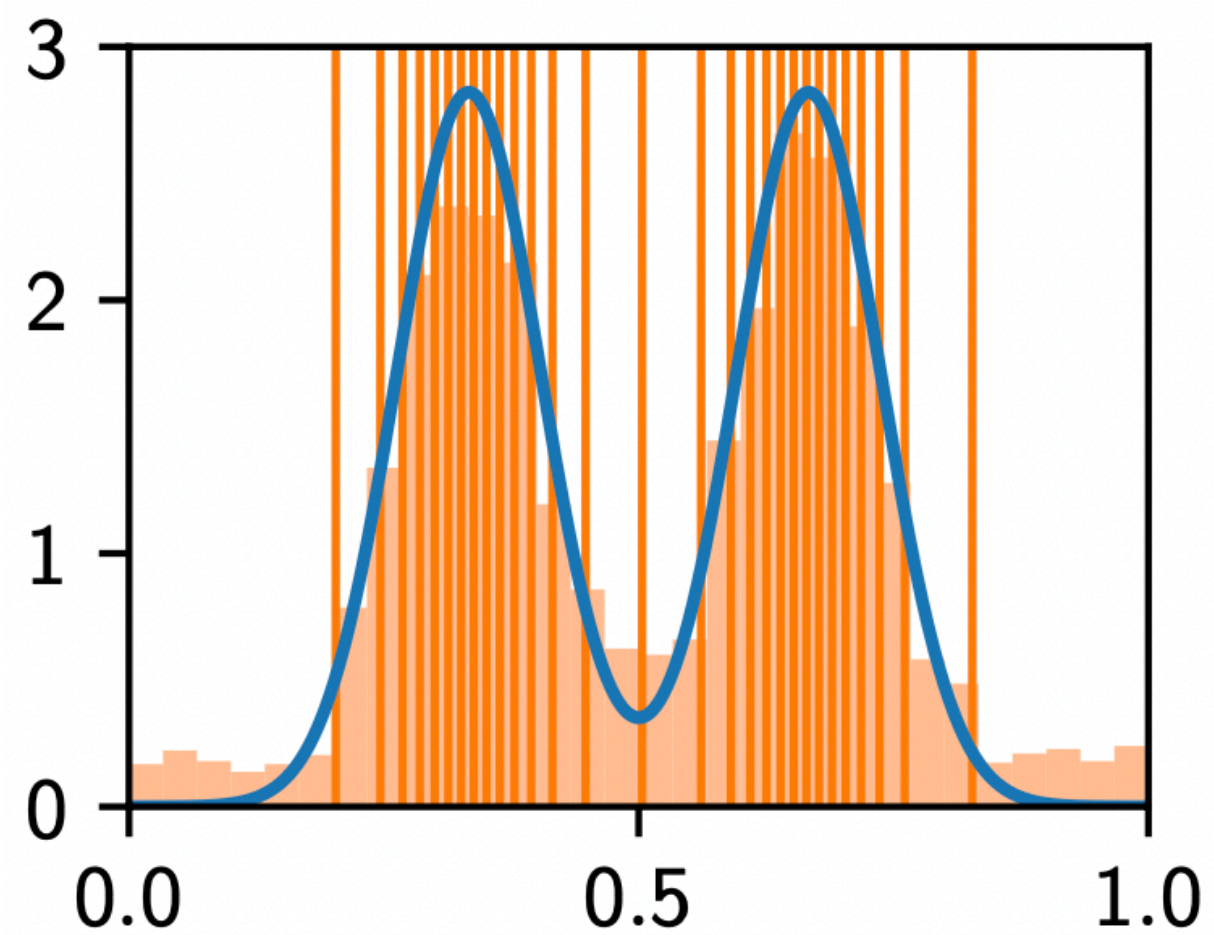
VEGAS algorithm

Factorize probability

$$p(x) = p(x_1) \cdots p(x_n)$$



Fit bins with equal probability
and varying width



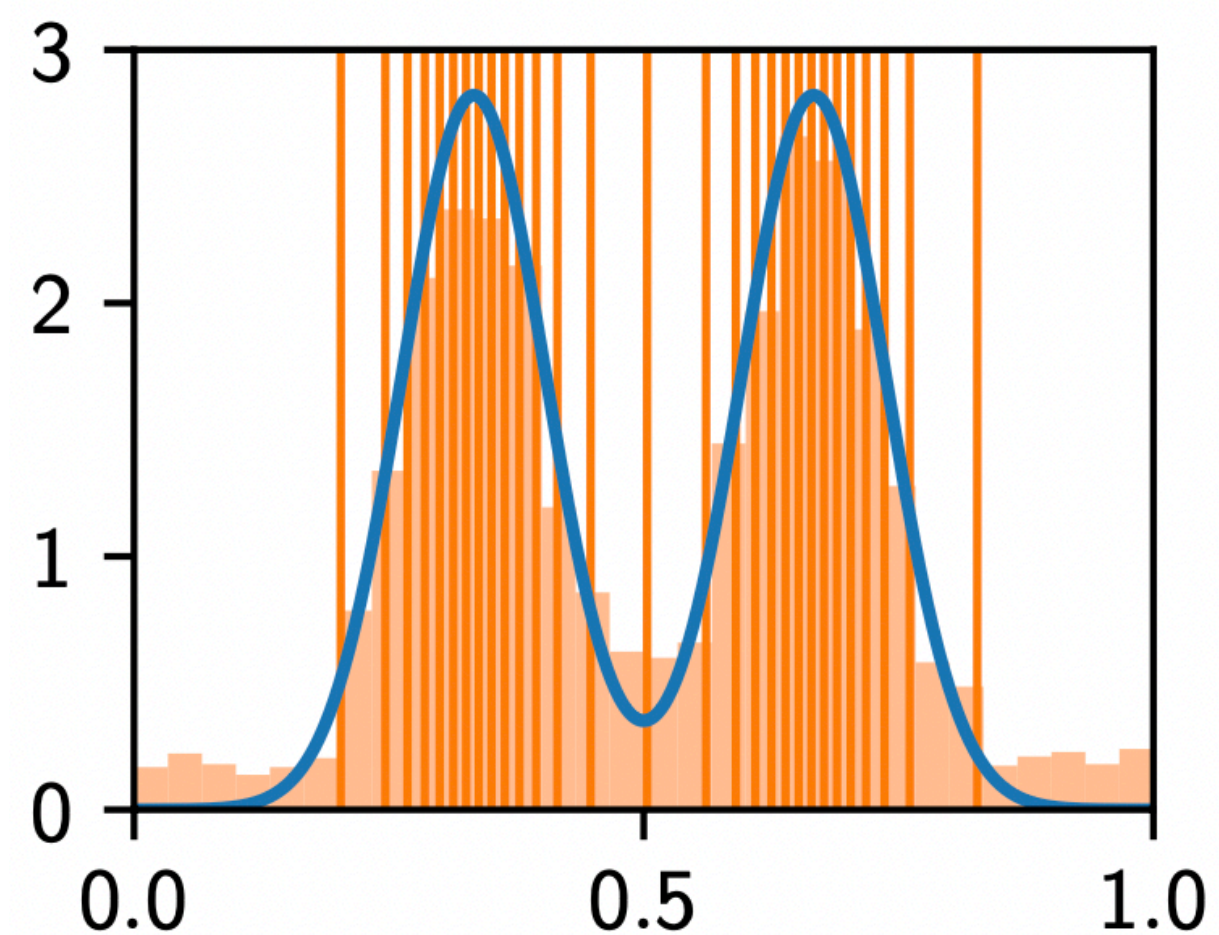
VEGAS algorithm

Factorize probability

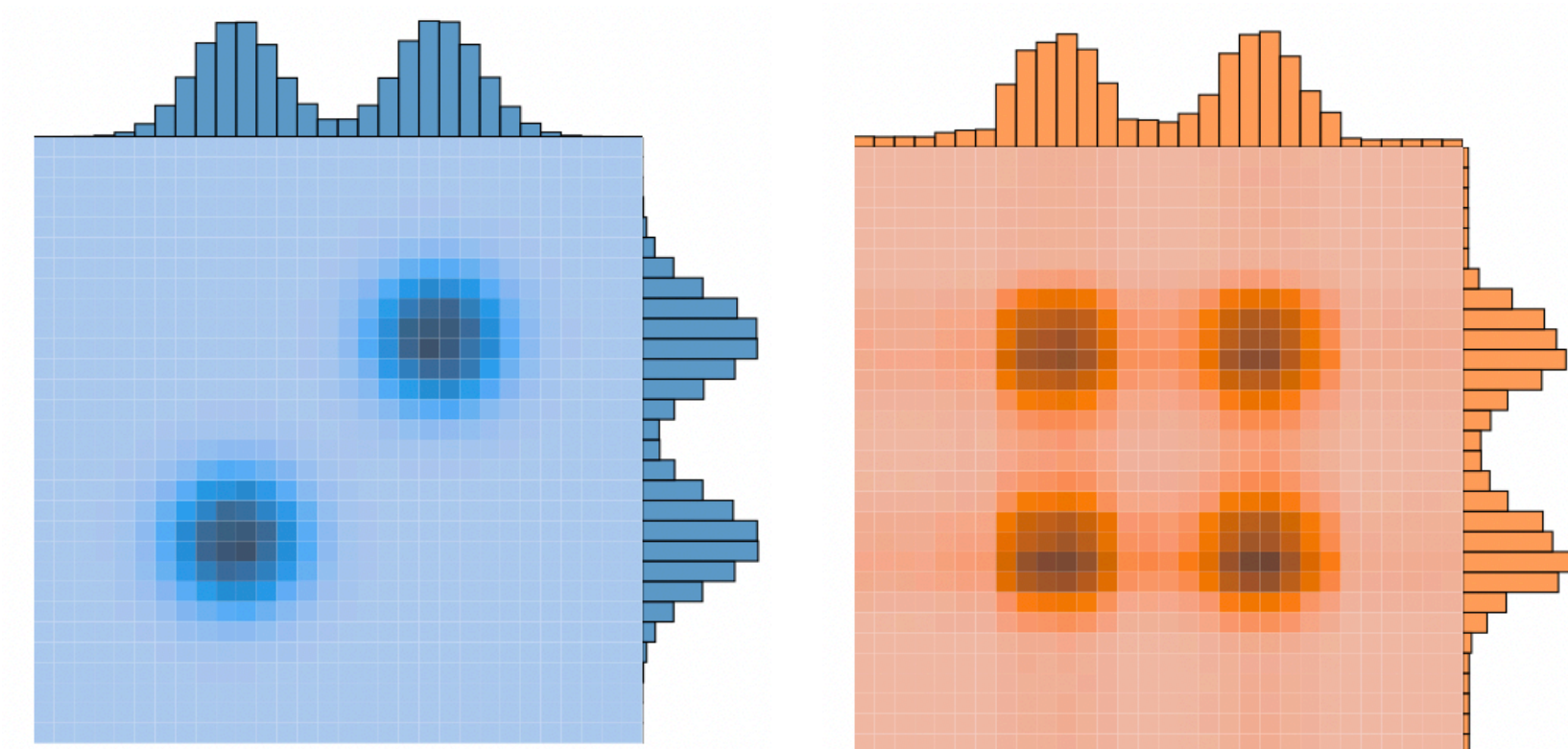
$$p(x) = p(x_1) \cdots p(x_n)$$



Fit bins with equal probability
and varying width



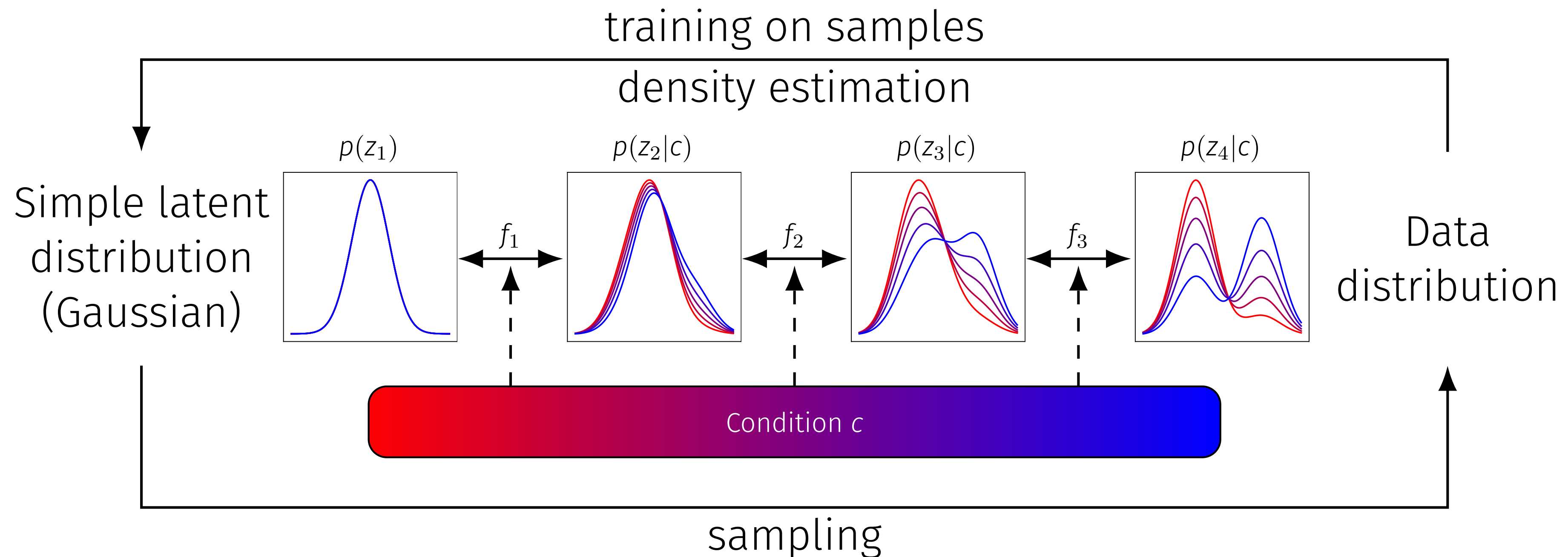
- ⊕ Computationally cheap
- ⊖ High-dim and rich peaking functions
→ slow convergence
- ⊖ Peaks not aligned with grid axes
→ phantom peaks



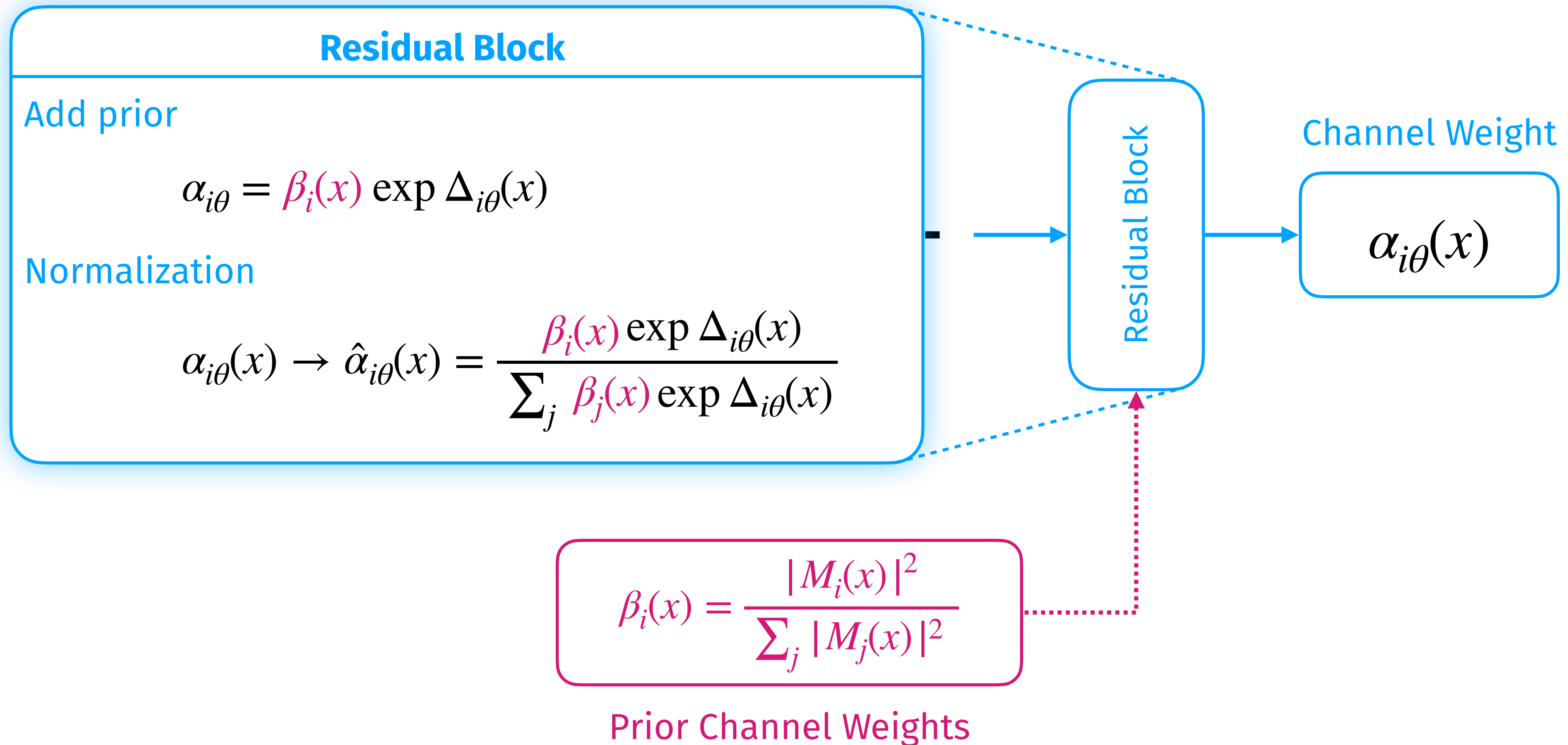
Normalizing Flows

Chain of **invertible, learnable** transformations with **exact likelihood** from change of variables formula

$$\log p(z_n | c) = \log p(z_1) + \log \det \frac{\partial z_1(z_n; c)}{\partial z_n}$$



Neural Channel Weights



Improved Multichanneling

Use symmetries

Groups of channels only **differ by permutations** of final state momenta



use **common flows** and combine in loss function

Stratified training

Channels have different contributions to the total variance



more samples for channels with **higher variance** during training

Channel dropping

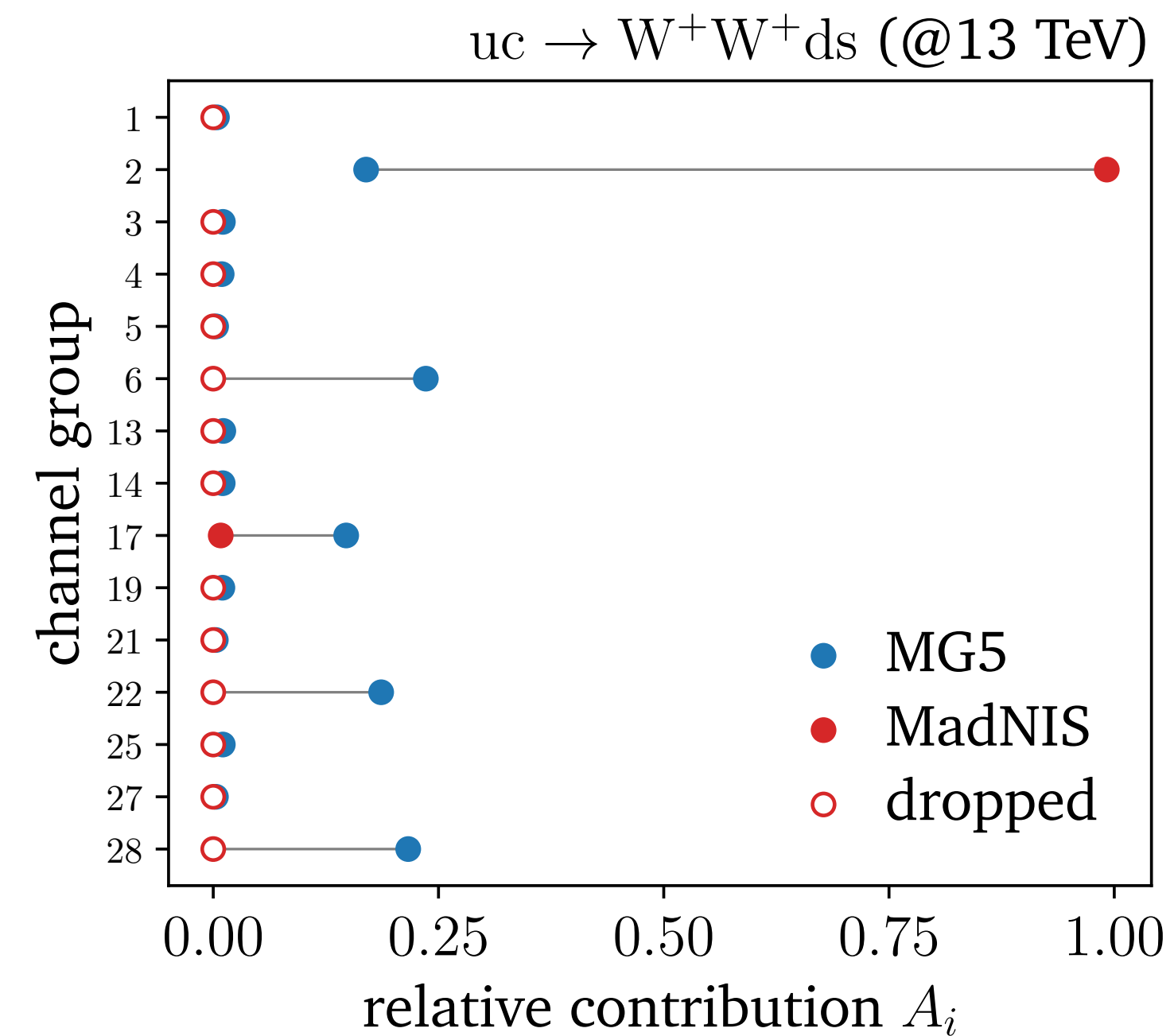
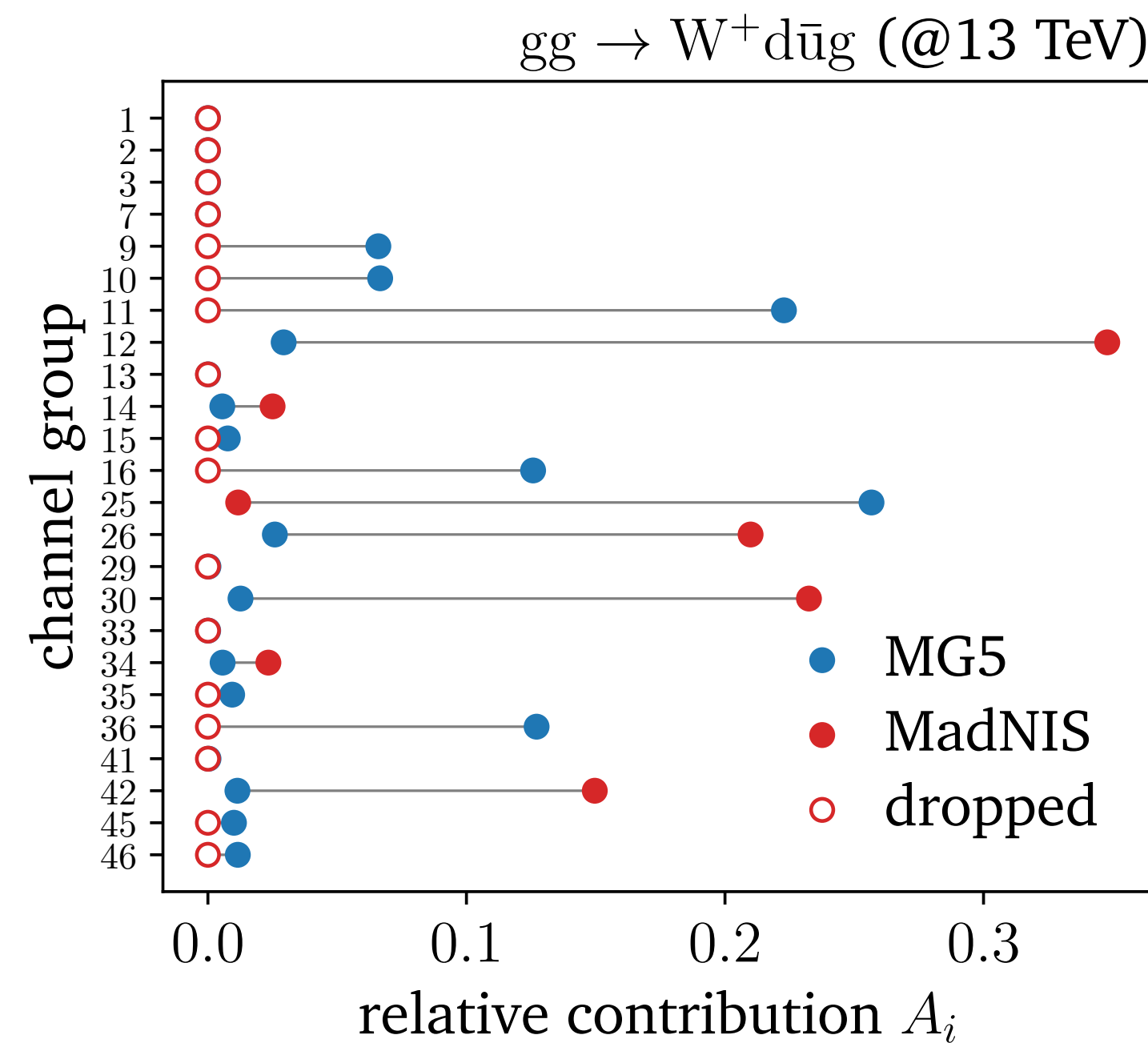
MadNIS often **reduces contribution** of some channels to total integral



remove insignificant channels from the training completely

Reduced complexity
Improved stability

Learned channel weights



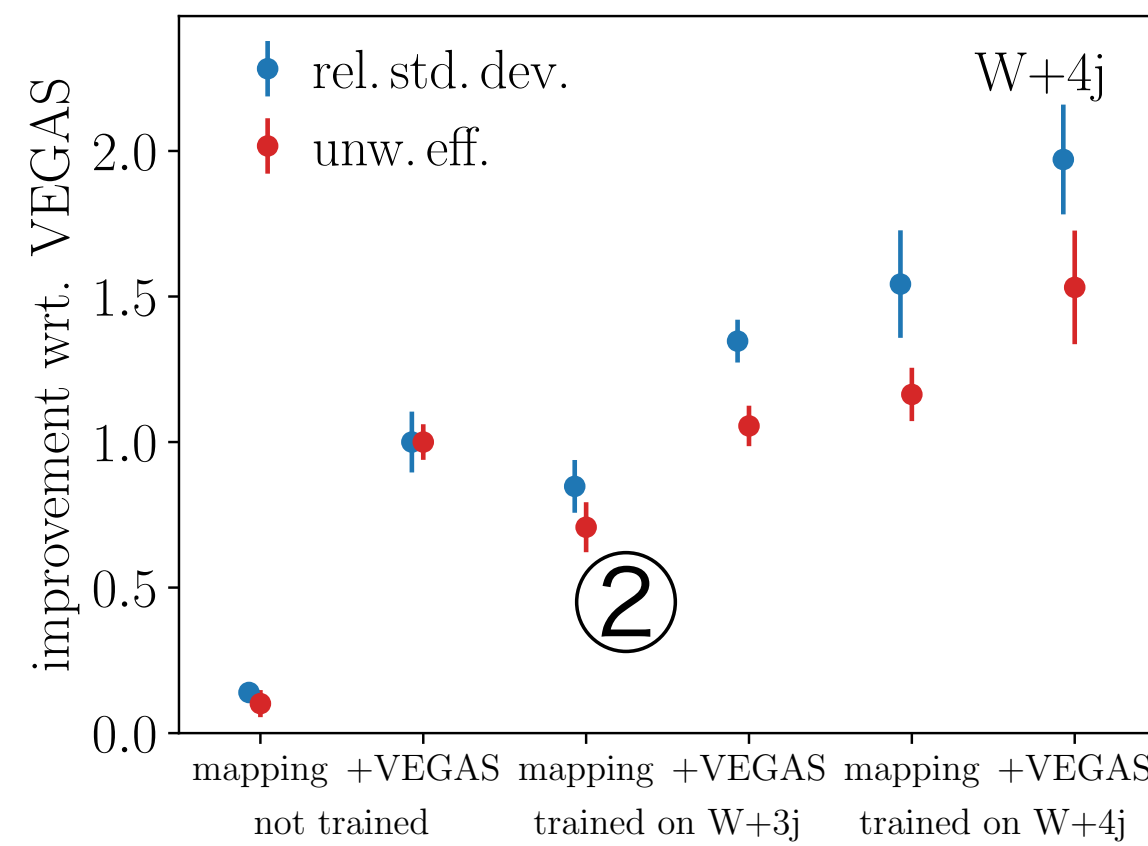
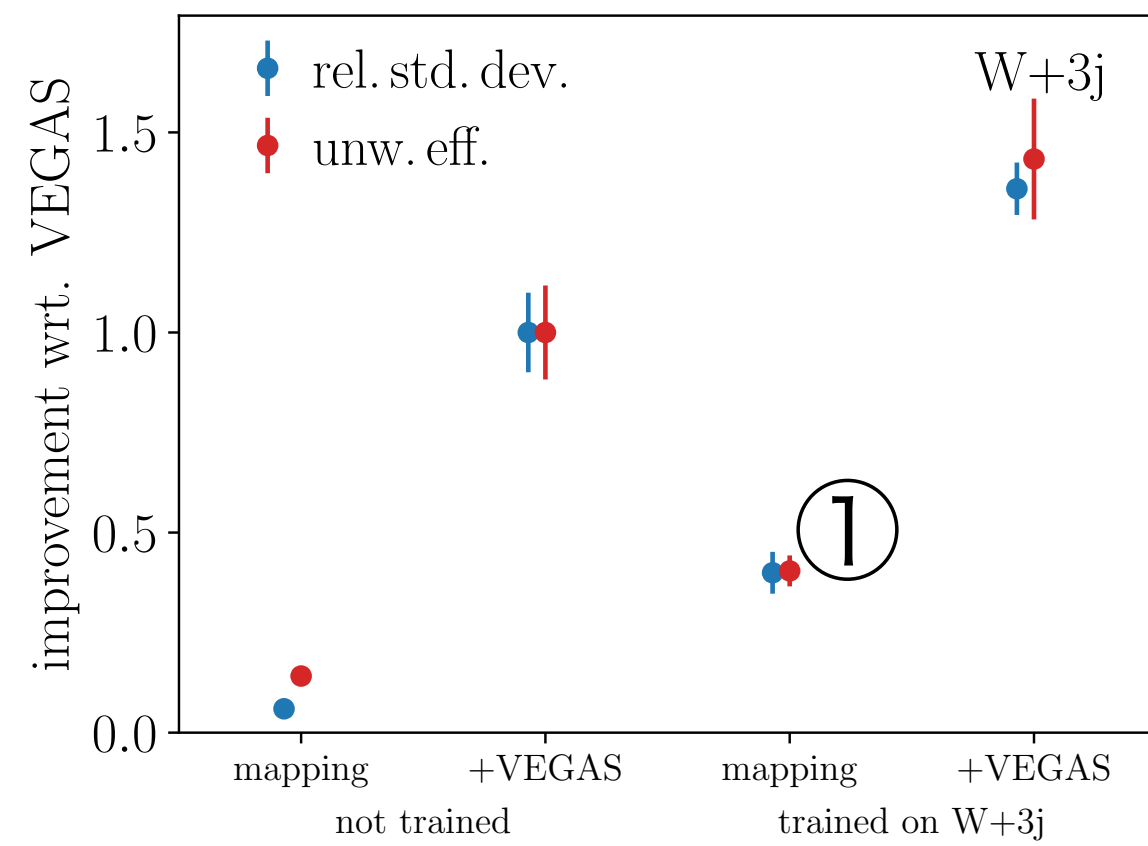
MadNIS often sends weight of many channels to 0



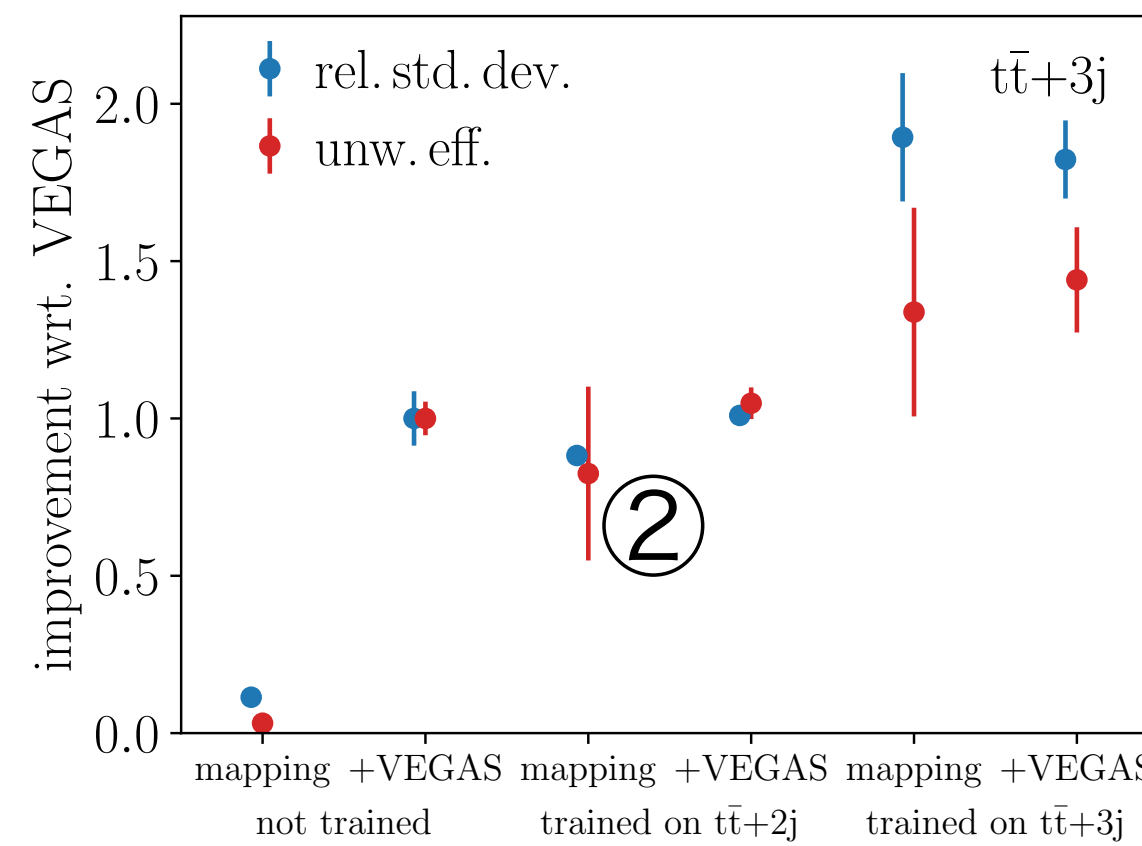
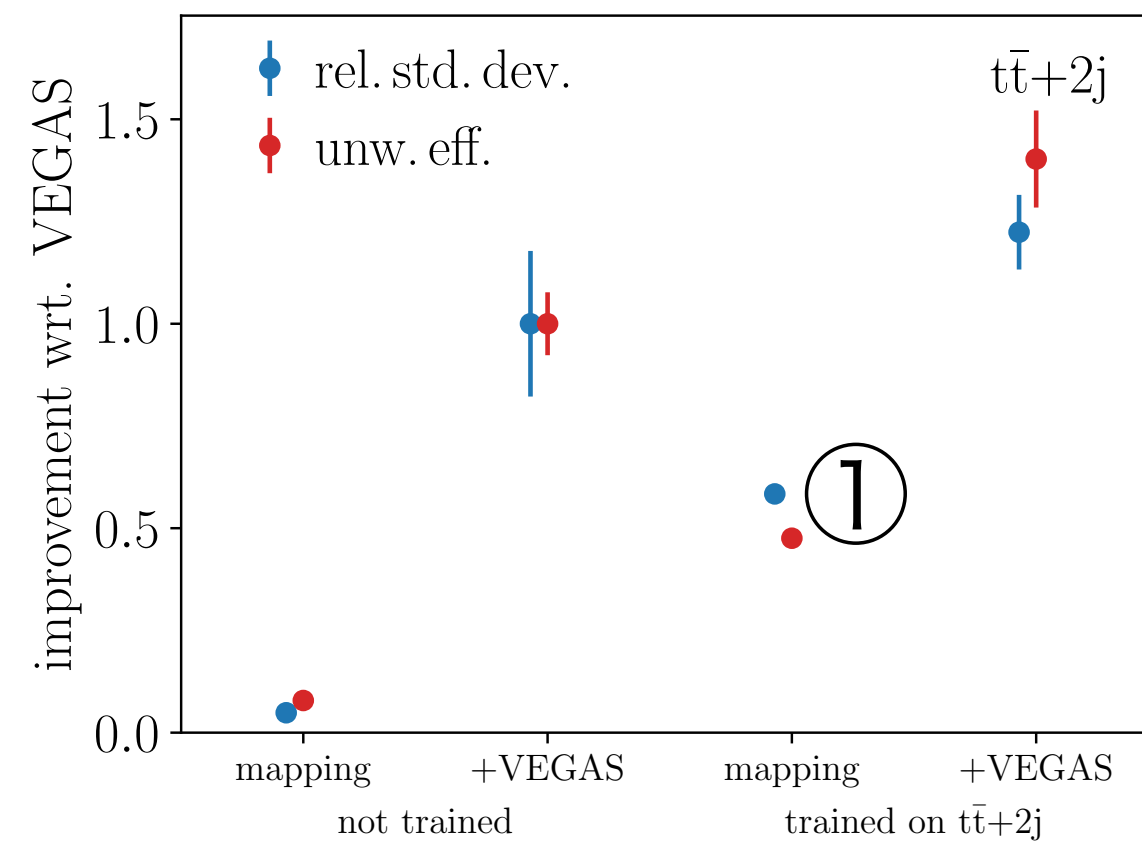
dropping channels makes training and event generation more stable and efficient

Performance

W+jets



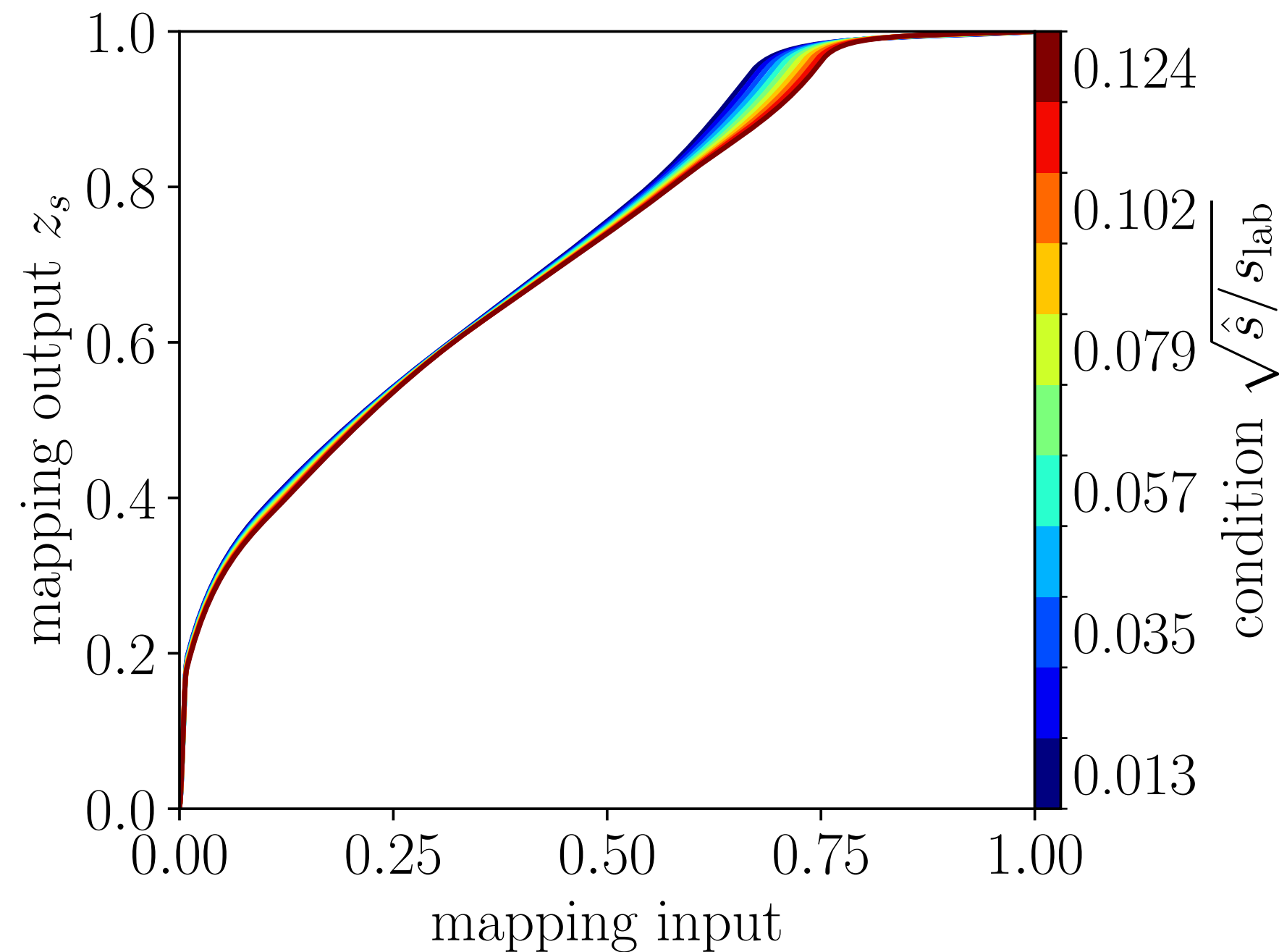
t \bar{t} +jets



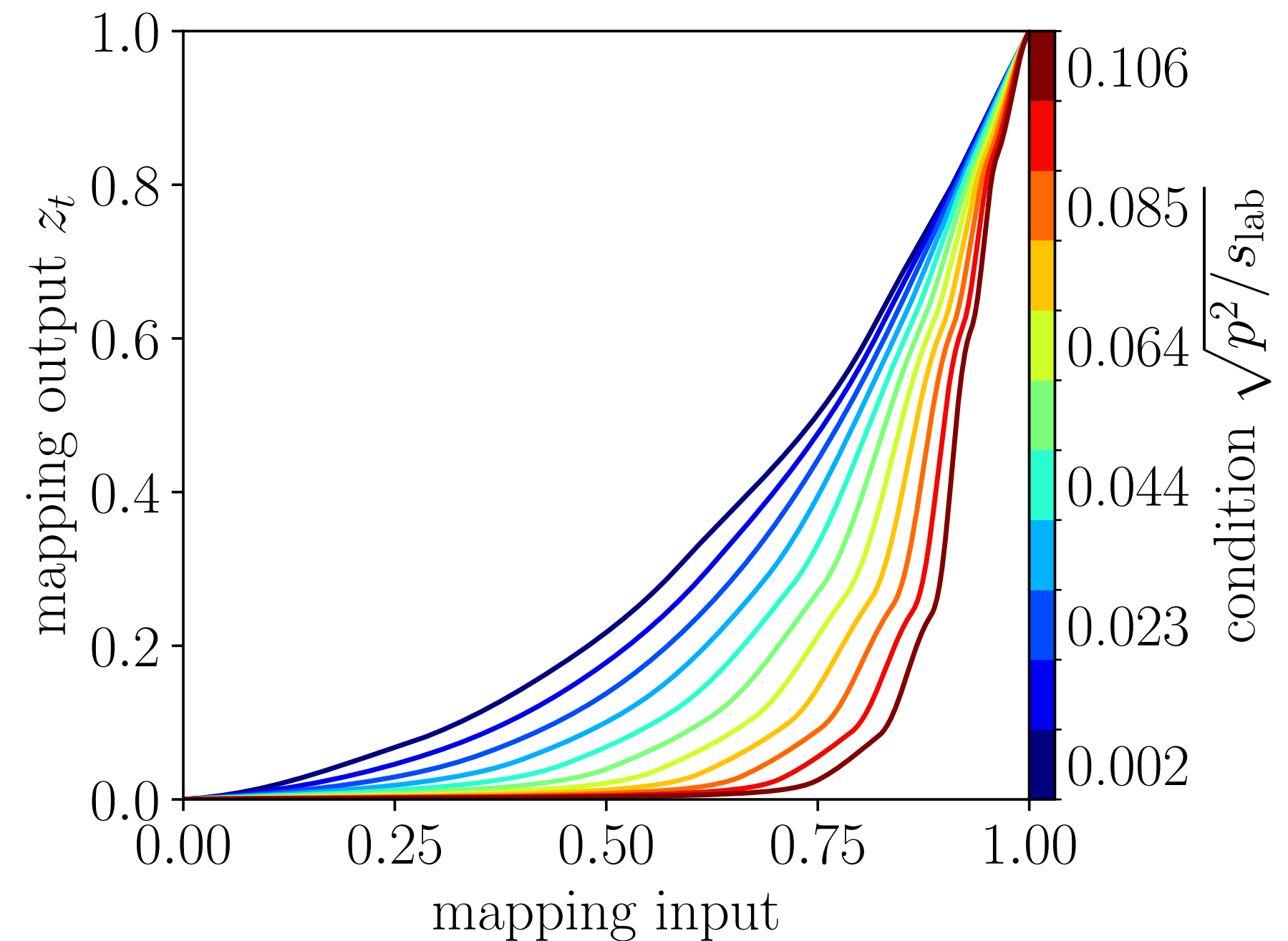
- good performance even though no channel-specific training ①
- **trained for n jets, used for n+1 jets**
→ performance like VEGAS ②
→ cheap training
- further improvements for VEGAS trained on top of MadNIS-Lite

Interpretability

Massless propagator
s-invariant



2→2 scattering
t-invariant



- s-invariant: small energy-dependence, easily learned by VEGAS, still room for improvement in underlying mapping
- t-invariant: large dependence on p^2