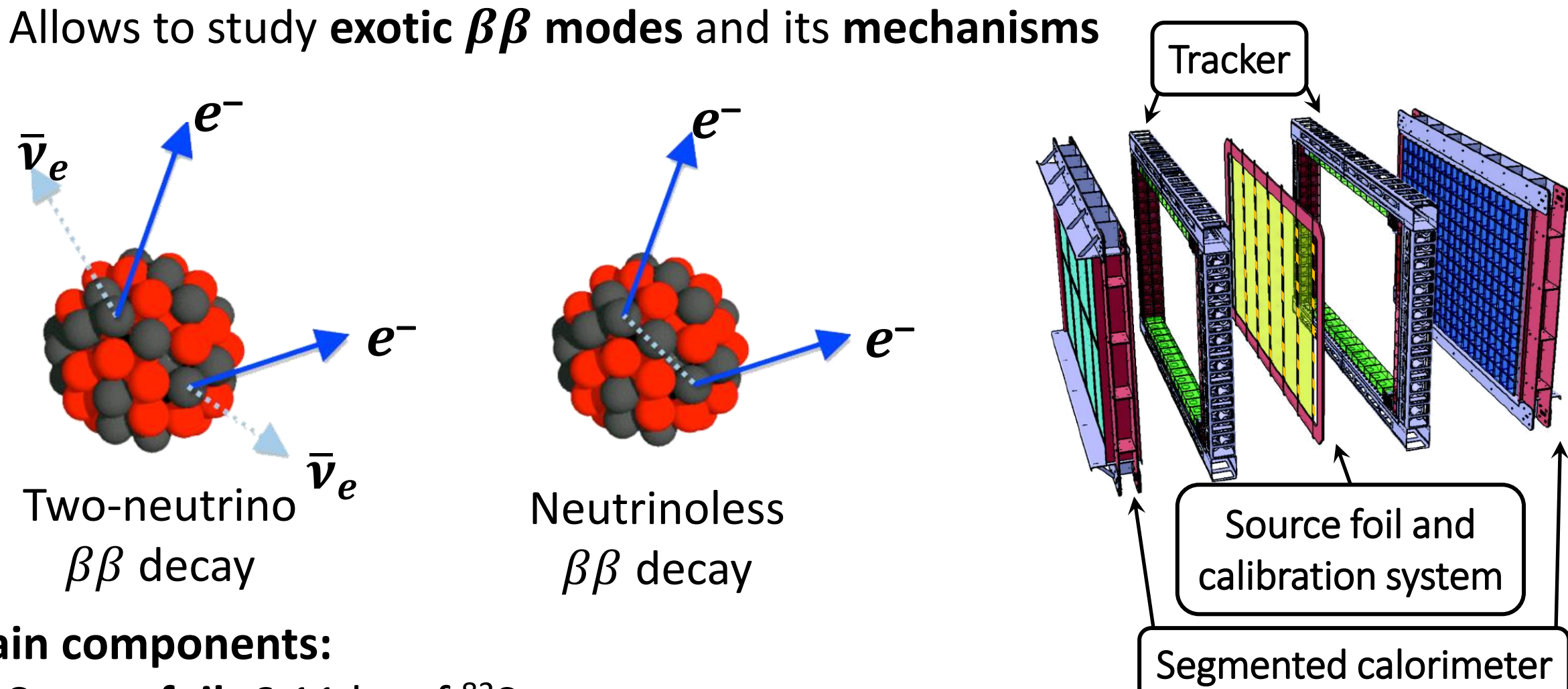




SuperNEMO detector

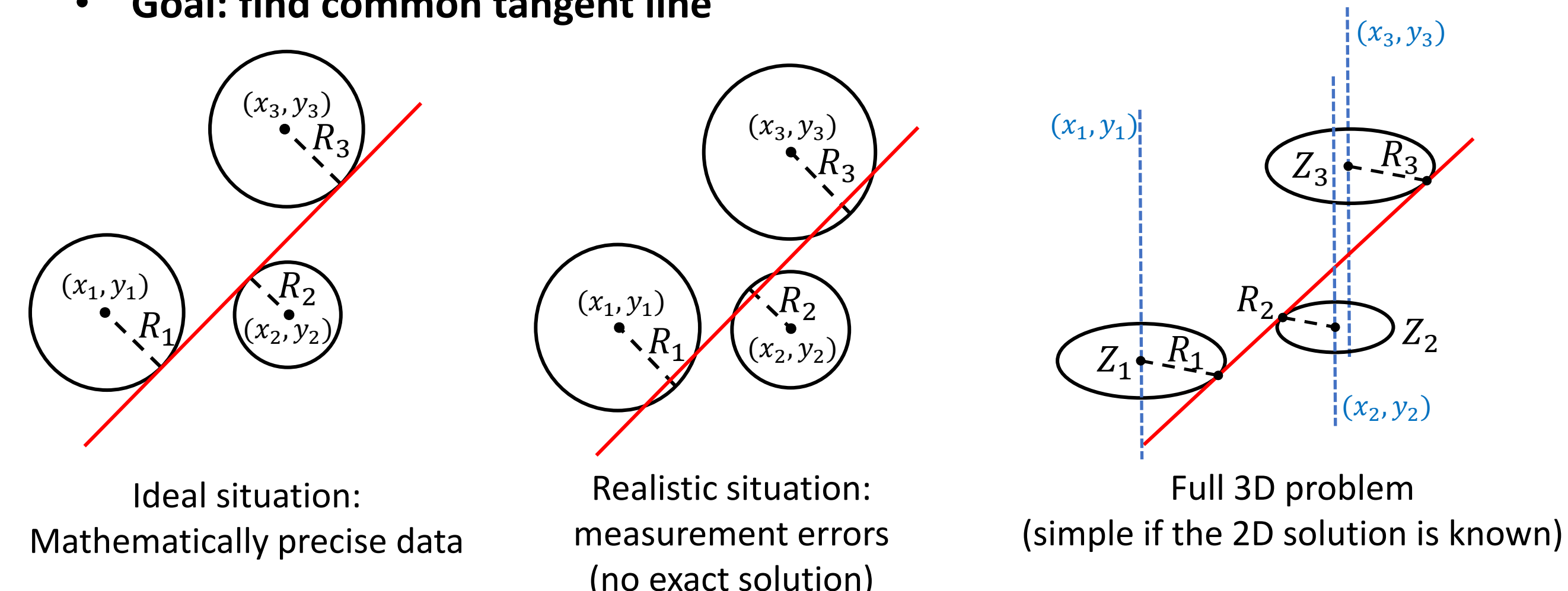
- **Powerful tool to study the physics of double beta ($\beta\beta$) decays**
- **Taking data** since April 2025
- $\beta\beta$ standard observable – sum of the two electrons' energies
- **Unique design = calorimetry + tracking:**
 - Full event topology reconstruction (decay angle, single e^- energy)
 - Allows to study **exotic $\beta\beta$ modes** and its **mechanisms**



- **Main components:**
 - **Source foil:** 6.11 kg of ^{82}Se
 - **Tracker:** multiwire chamber (2034 drift cells) → **topology**
 - **Segmented calorimeter:** 712 optical modules → **energy**
 - **^{207}Bi calibration system:** 7 x 6 grid of point-like deployable sources

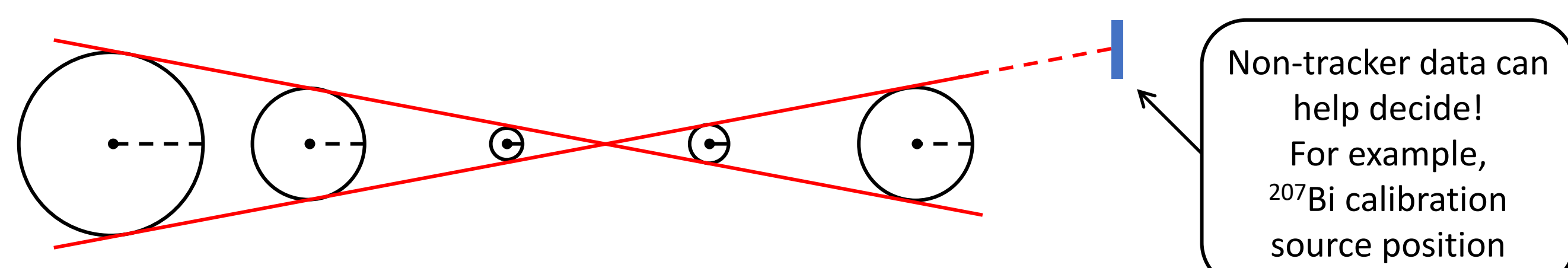
Track reconstruction problems

- Magnetic field currently turned off → **straight line trajectories**
- The problem is in 3D, but the difficult part is in the horizontal plane:
 - 3 exemplary tracker hits = 3 triggered anode wires (x_i, y_i) and 3 measured distances $R_i = 3$ circles
 - **Goal: find common tangent line**



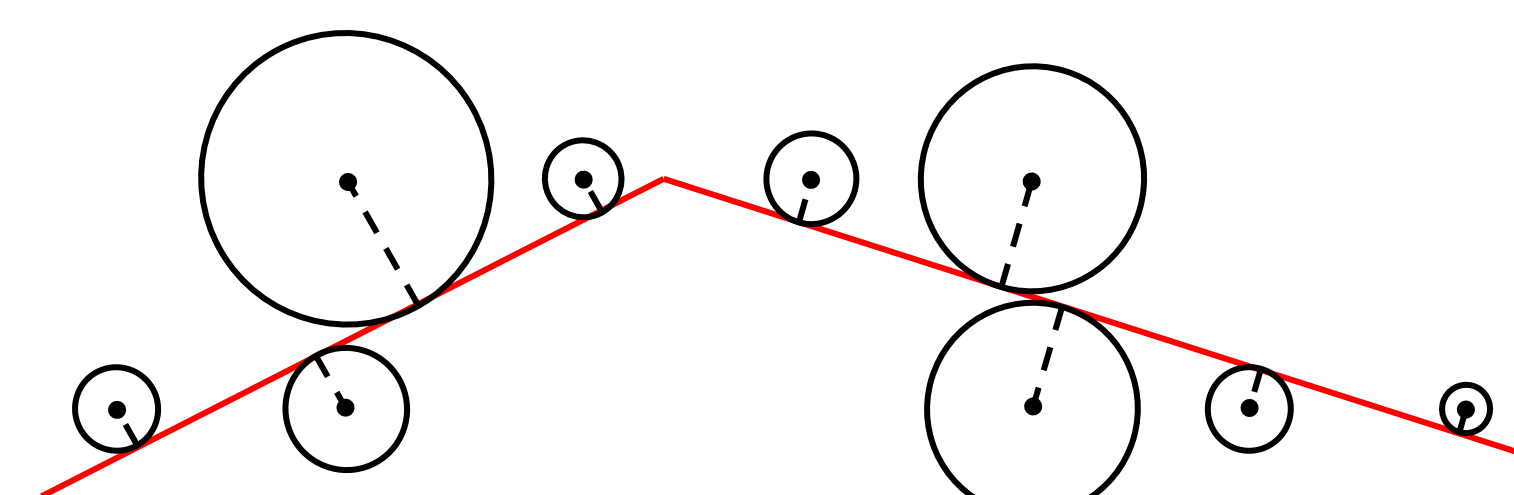
Problem of ambiguity – which track is real?

- Tracker hits aligned on a line → **mirror symmetry** = 2 equal solutions
- Impossible to decide based on tracker data only → **We need both solutions!**
- Different possible orientations of the symmetry line



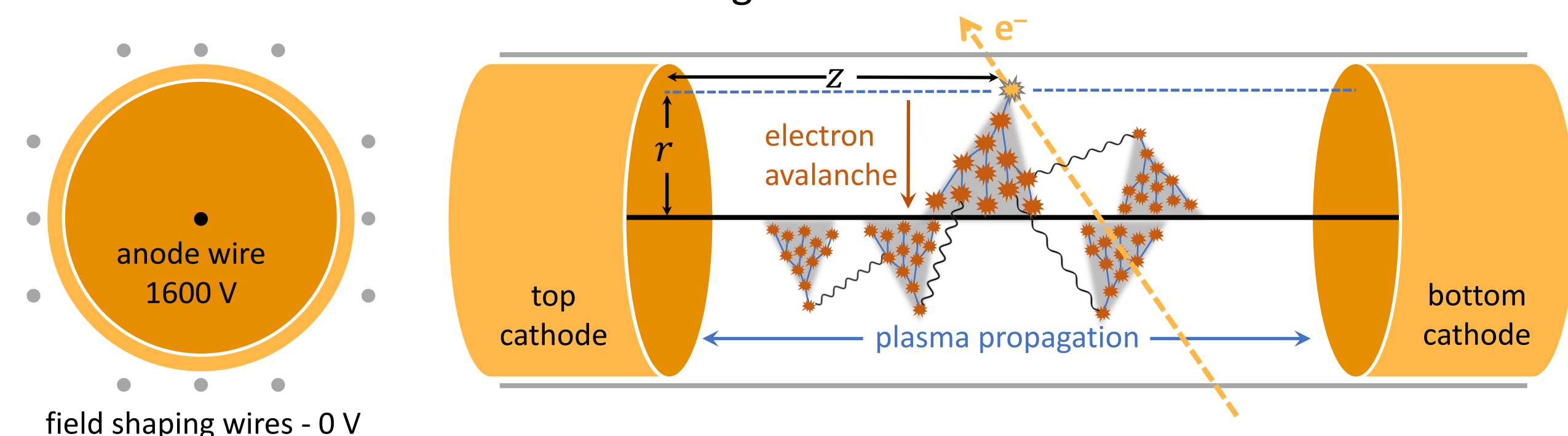
Problem of kinked trajectories

- Sudden change in direction of the particle → **kinked trajectory** (polyline model)
- How do we distinguish between two straight tracks and one kinked track?



Tracker cell

- 44 x 44 x 3030 mm³ drift cell in Geiger mode

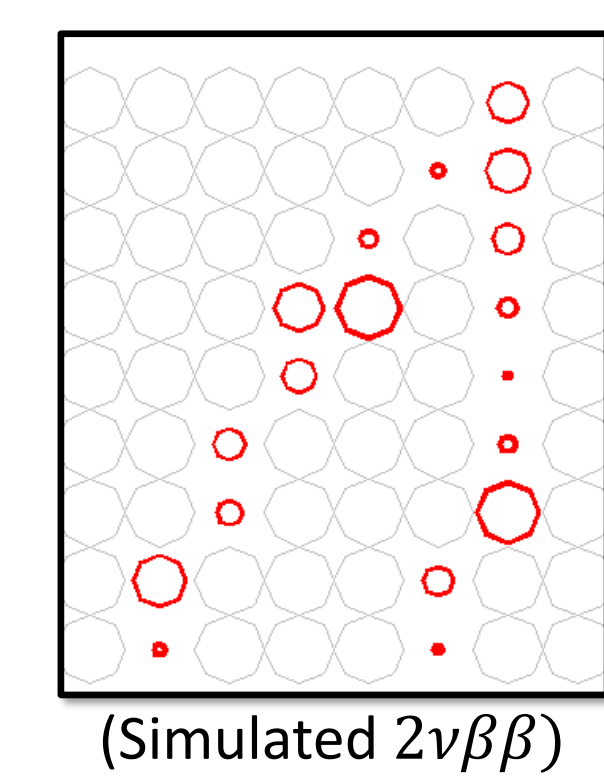


- Measures position of a passing charged particle:
 - Electron avalanche → Distance to anode wire (r)
 - Plasma propagation → Vertical position (z)

Tracker hit = circle tangent to the track

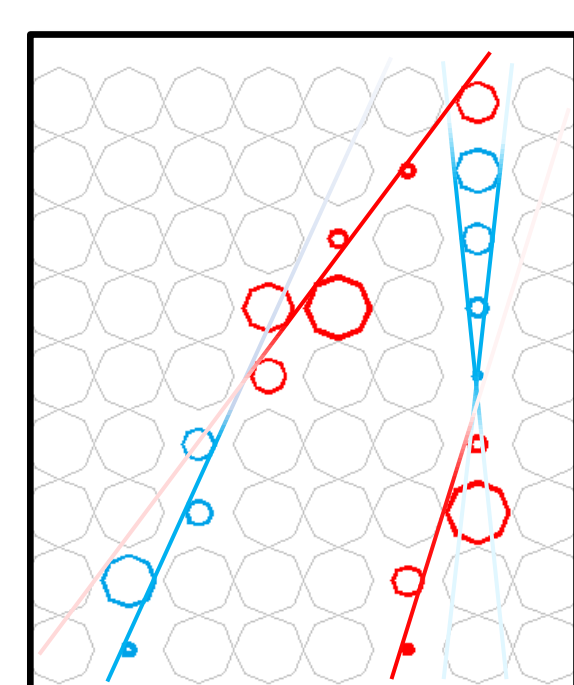
Cimrman Reconstruction Module

Input tracker data → Clustered data → Fitted linear parts → Polyline trajectories



Clustering phase

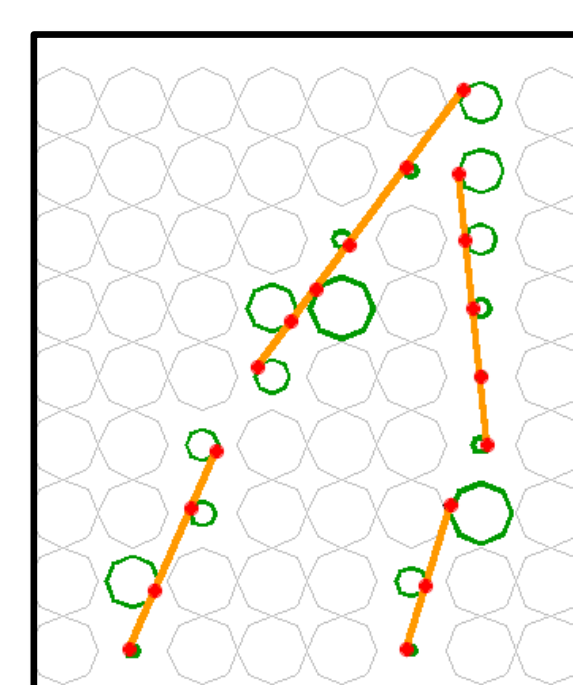
- Iteratively switching between:
1. Spatial separation of hits → optimization (uses local characteristics)
 2. Legendre transform method → 2D line fit estimates (uses global characteristics)



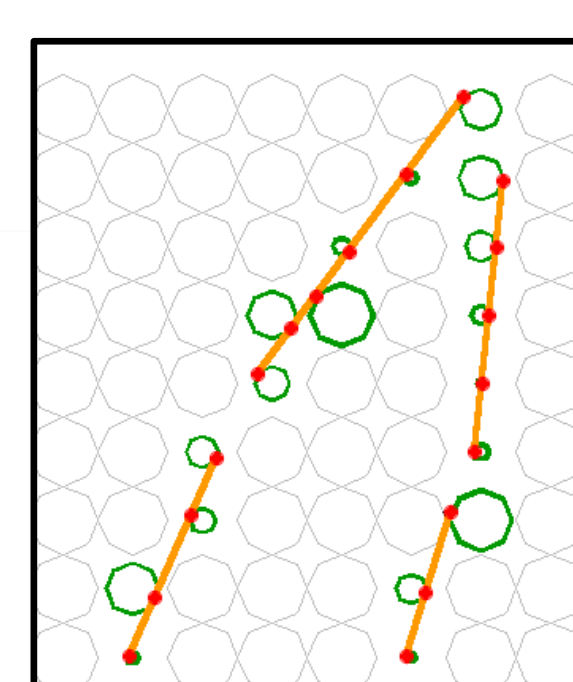
(4 clusters found, 5 line fits estimated)

Fitting phase

1. Maximum likelihood fits of identified clusters → Precise 3D line fits
2. Detection of ambiguities → mirroring 3D line fits
3. Combining ambiguities into alternative solutions



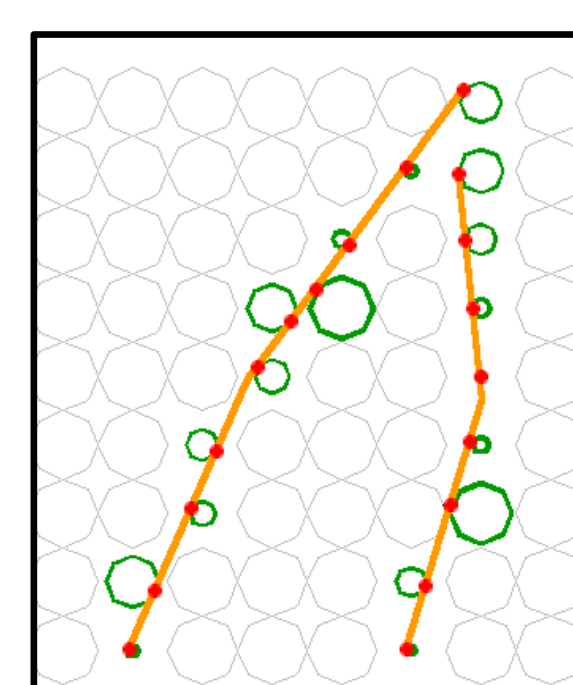
Solution 1



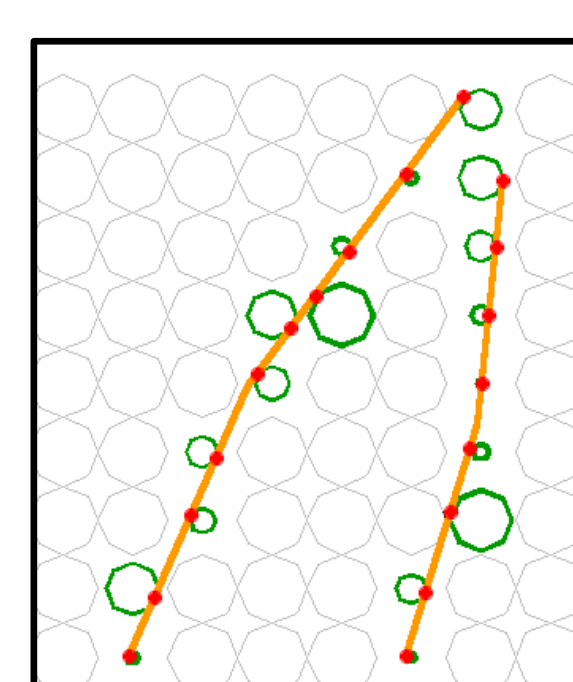
Solution 2

Connection phase

1. Connecting linear segments into polyline trajectories based on:
 - vertical distance
 - horizontal distance
 - kink angle
 - kink position
 - etc.
2. Additional refinements of clustering and fitting decisions based on the trajectory shape

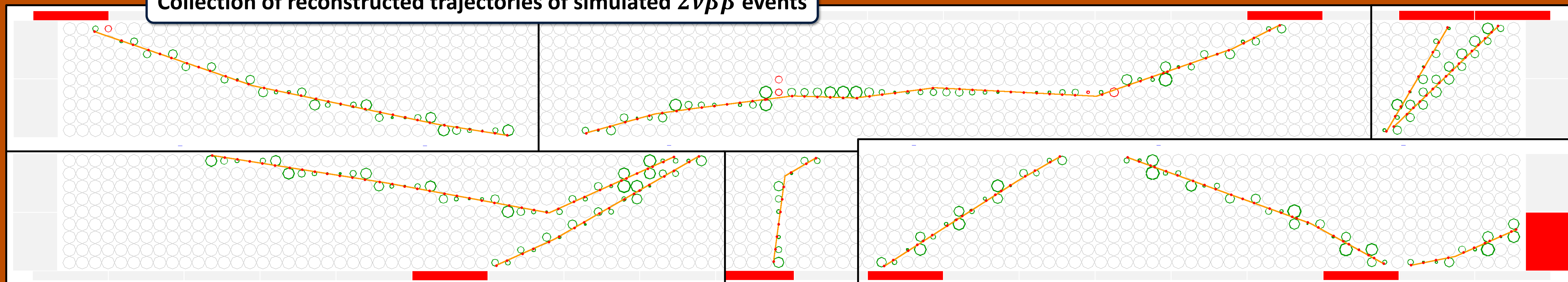


Solution 1



Solution 2

Collection of reconstructed trajectories of simulated $2\nu\beta\beta$ events



This contribution was supported with the grant No. 24-101805.

