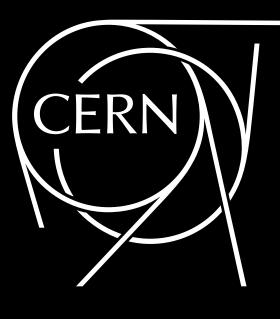
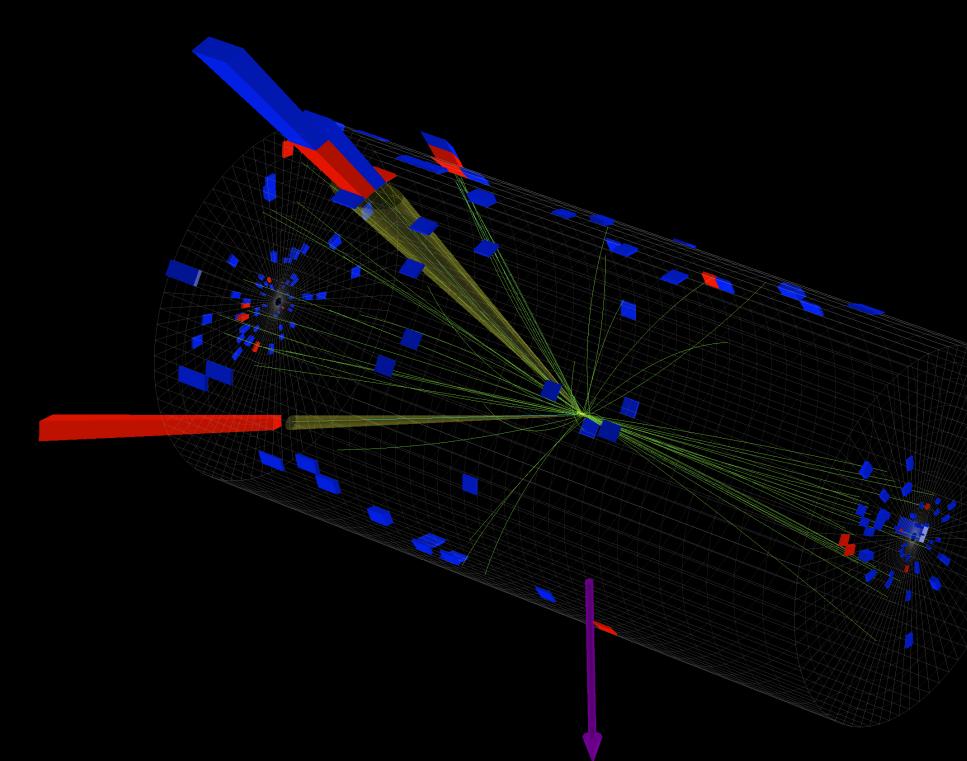
Towards a Foundation Model for Jet Physics

Huilin Qu

EPS-HEP July 10, 2025

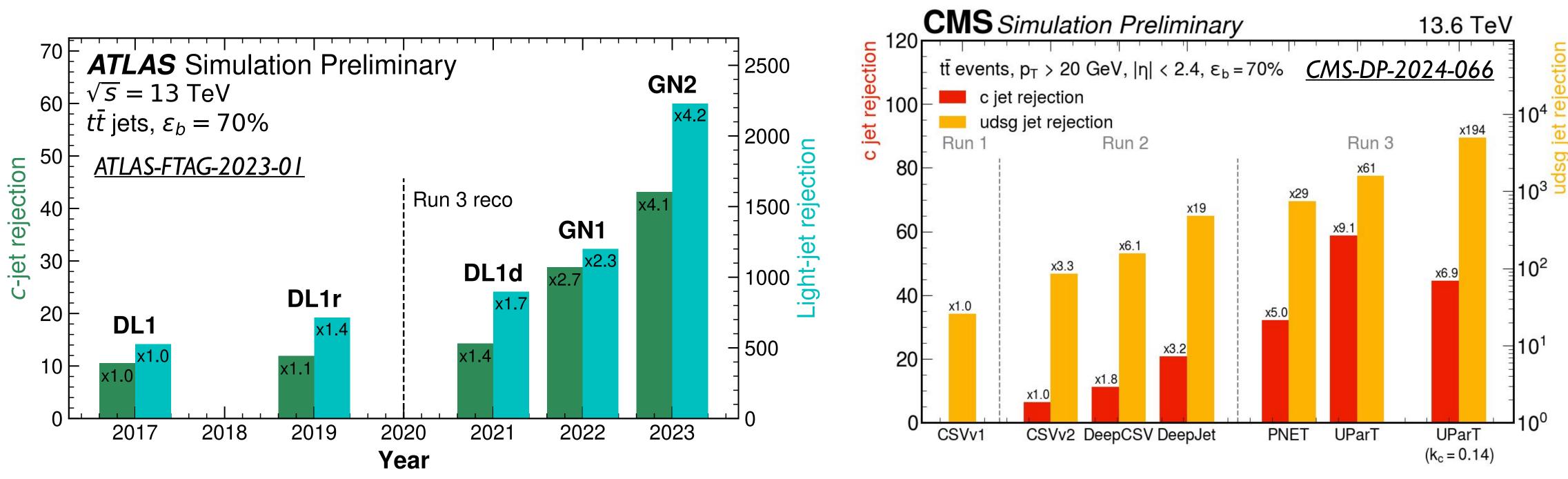




THE EVOLUTION OF JET TAGGERS

Tremendous progress in jet tagging in the past few years

more than an order of magnitude improvement in light jet rejection



A driving force – advanced machine learning (ML) techniques

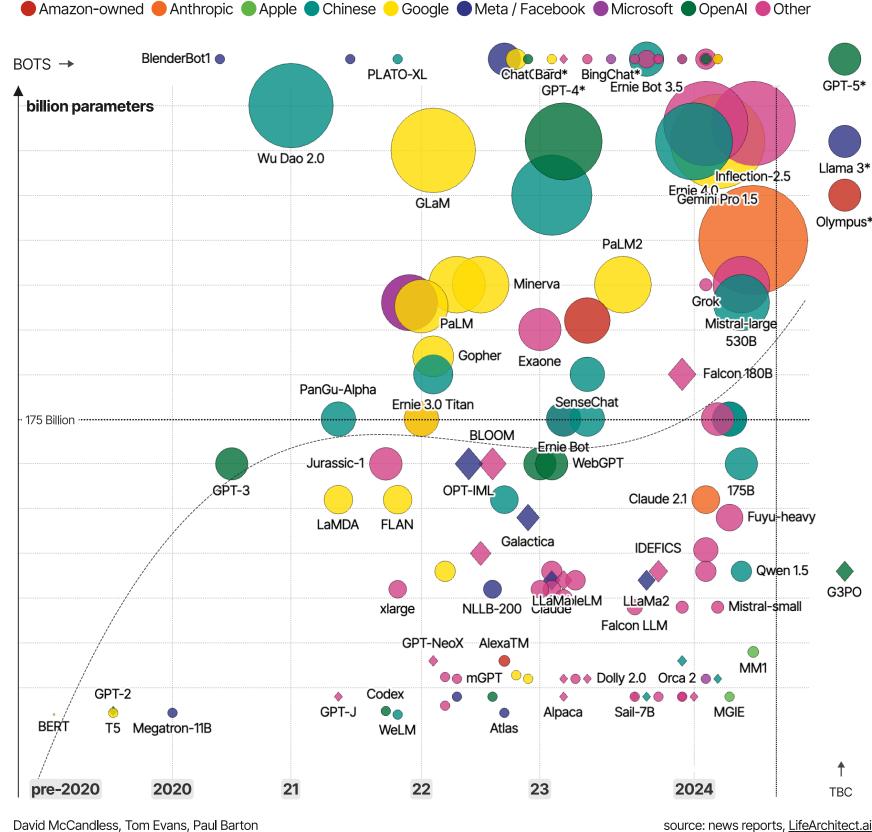








Natural language models



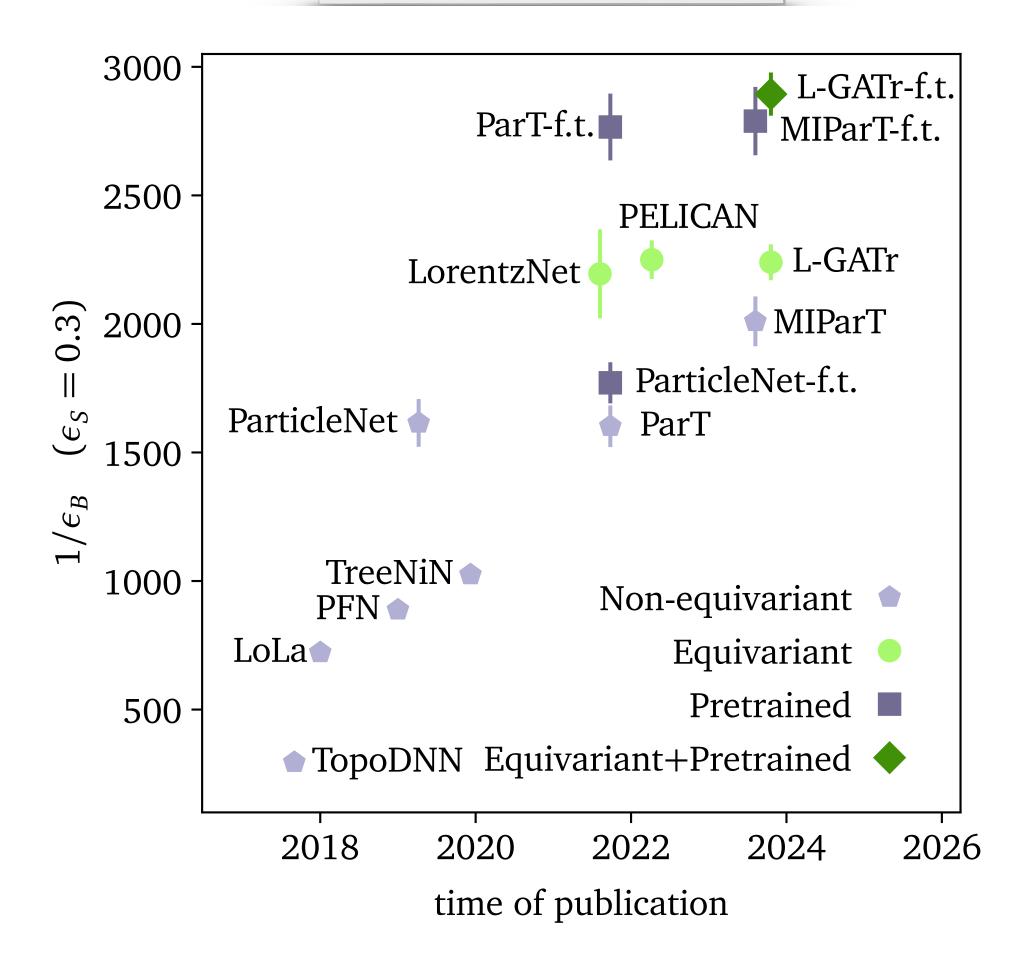
Information is Beautiful // UPDATED 20th Mar 24

source: news reports, LifeArchi * = parameters undisclosed // see the data

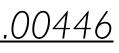
MADE WITH VIZ**SWEET**

Source: informationisbeautiful.net

HEP models (jet tagging)

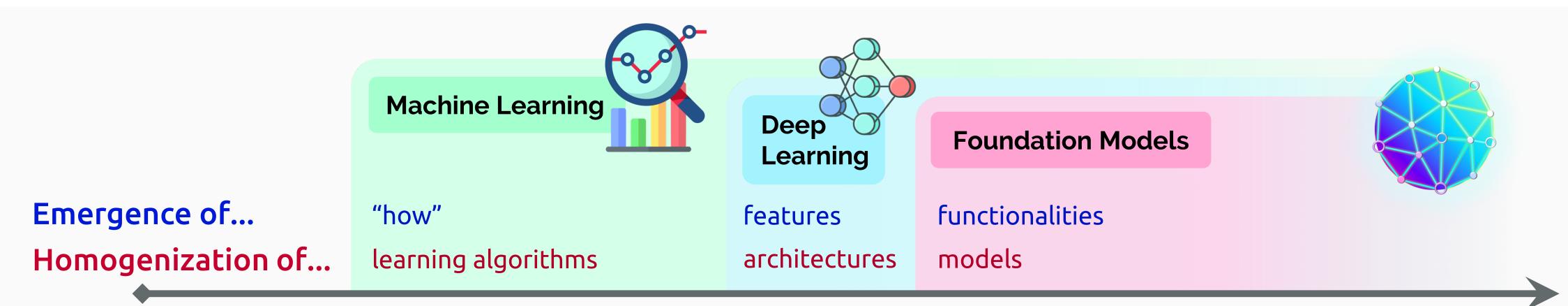


J. Brehmer, V. Bresó, P. Haan, T. Plehn, HQ, J. Spinner and J. Thaler, arXiv: 2411.00446



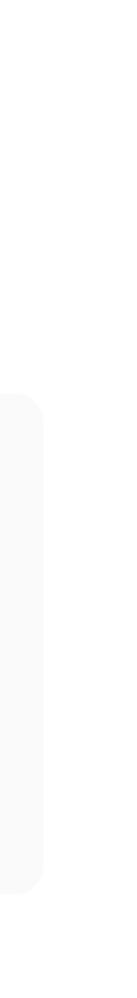


FOUNDATION MODEL



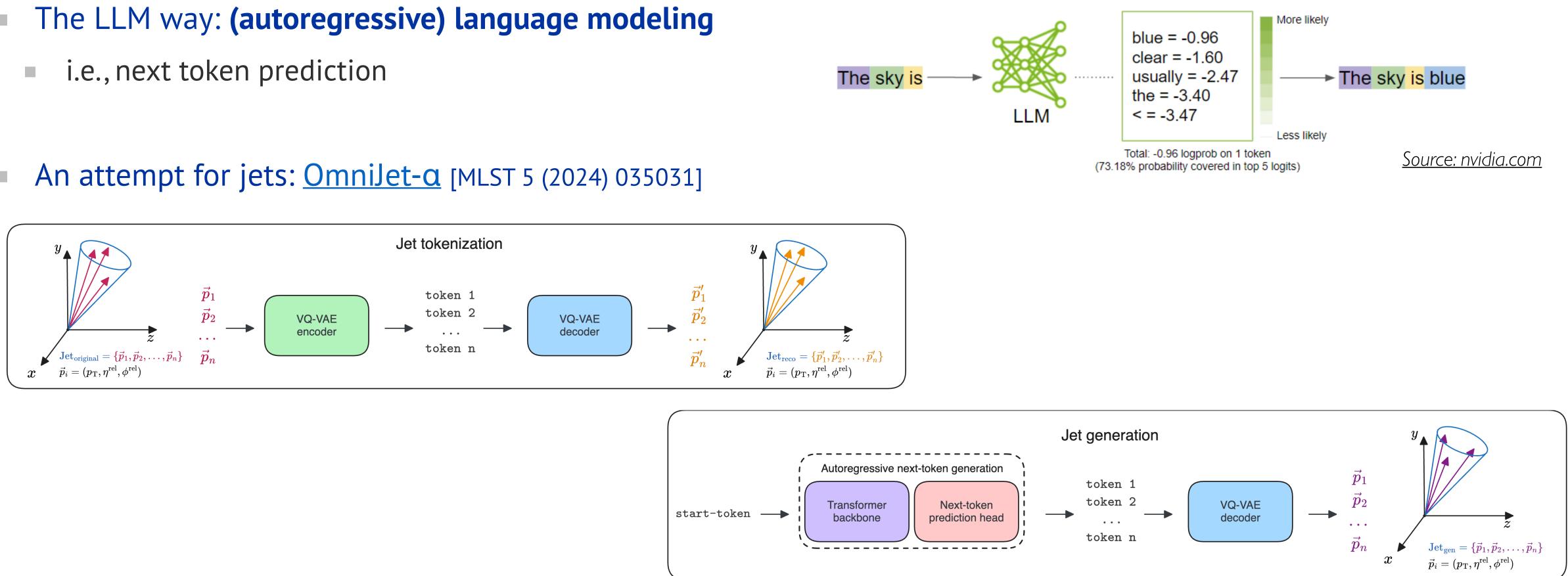
"A foundation model is any model that is trained on broad data (generally using self-supervision at scale) that can be adapted (e.g., fine-tuned) to a wide range of downstream tasks."

On the Opportunities and Risks of Foundation Models [arXiv: 2108.07258]



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SELF-SUPERVISION: NEXT TOKEN PREDICTION



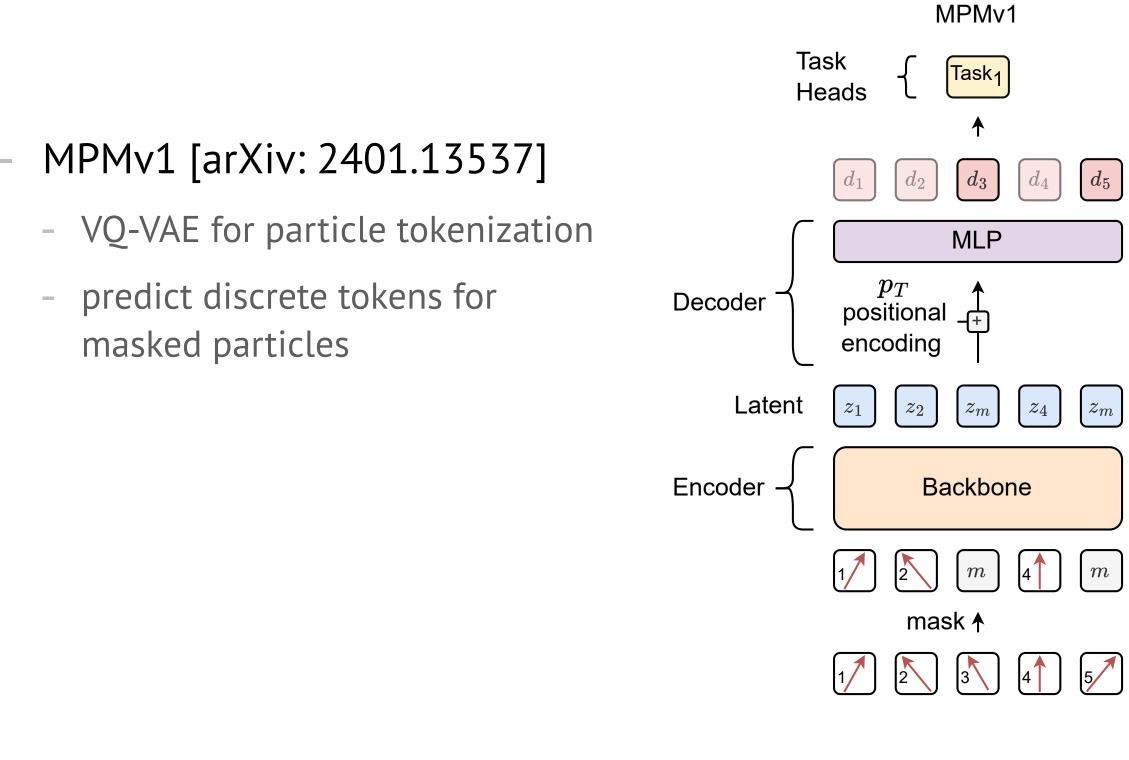
- Probably not the most natural approach:
 - requires (discrete) tokenization of high-dimensional numerical inputs

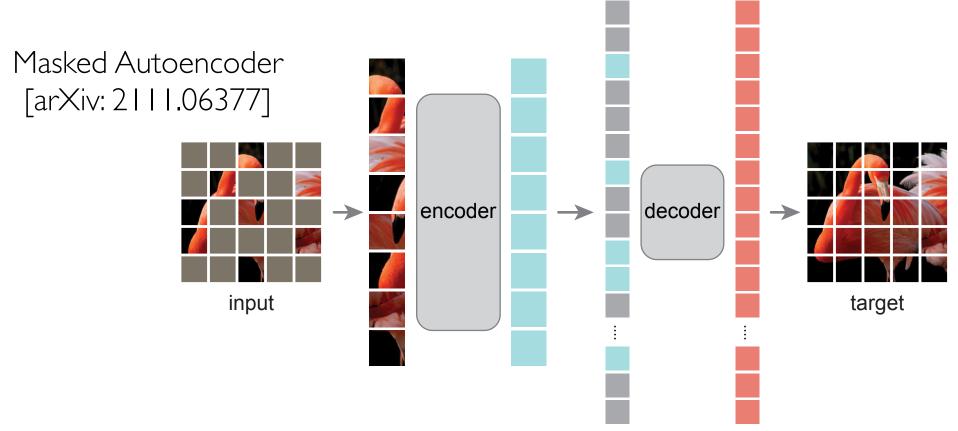
needs to impose an ordering on jet constituent particles, which are intrinsically permutation invariant



SELF-SUPERVISION: MASKED MODELING

- The CV approach: "masked modeling"
 - i.e., mask and reconstruct
- Adapted for particle physics: <u>Masked Particle Modeling</u>





$\boxed{z_4}$	z_m
e	
4	m
4	5

MPMv2				
Task ₁ Task _N				
d_1 d_2 d_3 d_4 d_5				
Transformer				
$\begin{bmatrix} z_1 \end{bmatrix} \begin{bmatrix} z_2 \end{bmatrix} \begin{bmatrix} m_1 \end{bmatrix} \begin{bmatrix} z_4 \end{bmatrix} \begin{bmatrix} m_2 \end{bmatrix}$				
pad 🕇				
$egin{array}{cccccccccccccccccccccccccccccccccccc$				
Backbone				
drop 🛧				

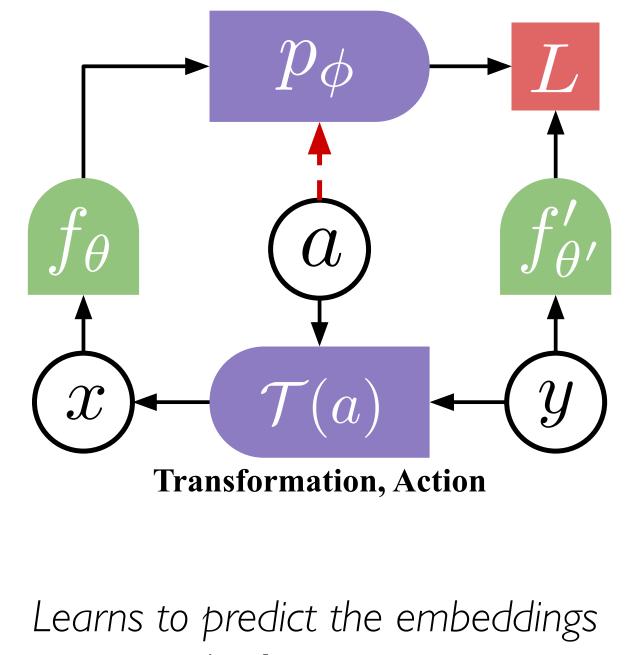
- MPMv2 [arXiv: 2409.12589]
 - no need for discrete tokenization
 - multiple reconstruction tasks:
 - PID prediction
 - direct regression
 - conditional generative tasks (via CNF / CFM)

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JOINT-EMBEDDING PREDICTIVE ARCHITECTURE

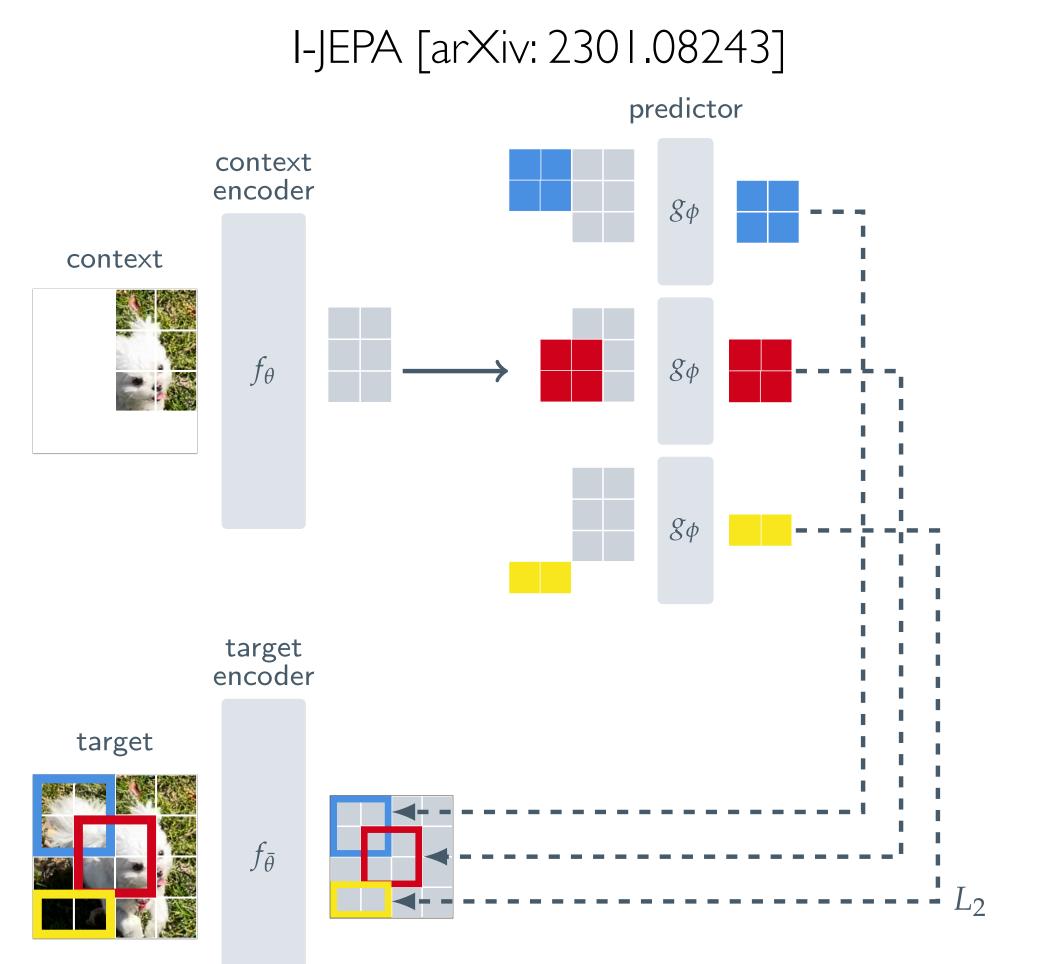


Predictor/World Model



in the **latent** space. A path towards "World Models".

arXiv: 2403.00504

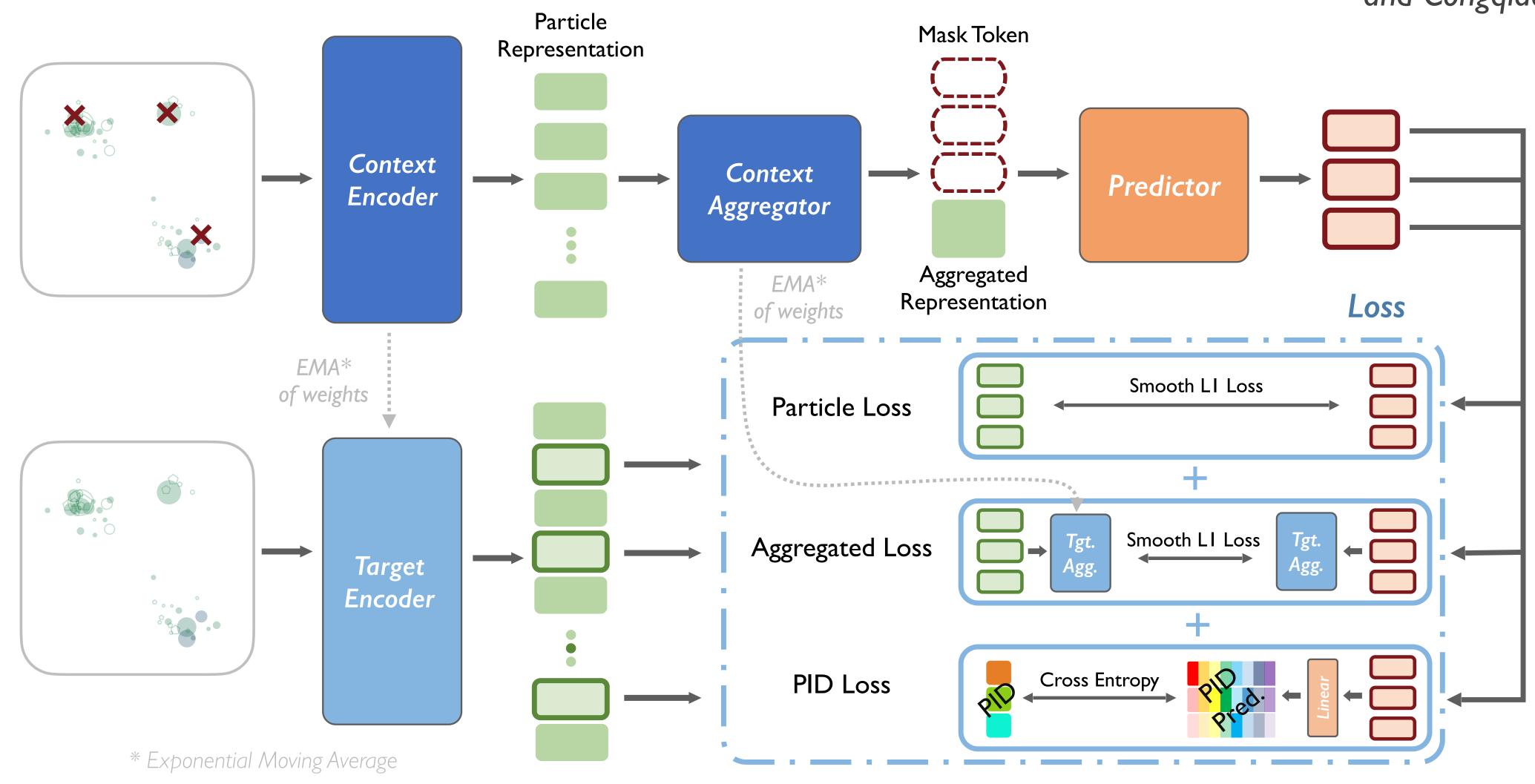


... predicts the embeddings of masked image patches in a (learned) latent space.





INTRODUCING P-JEPA



Work in progress with Qibin Liu, Shudong Wang and Congqiao Li

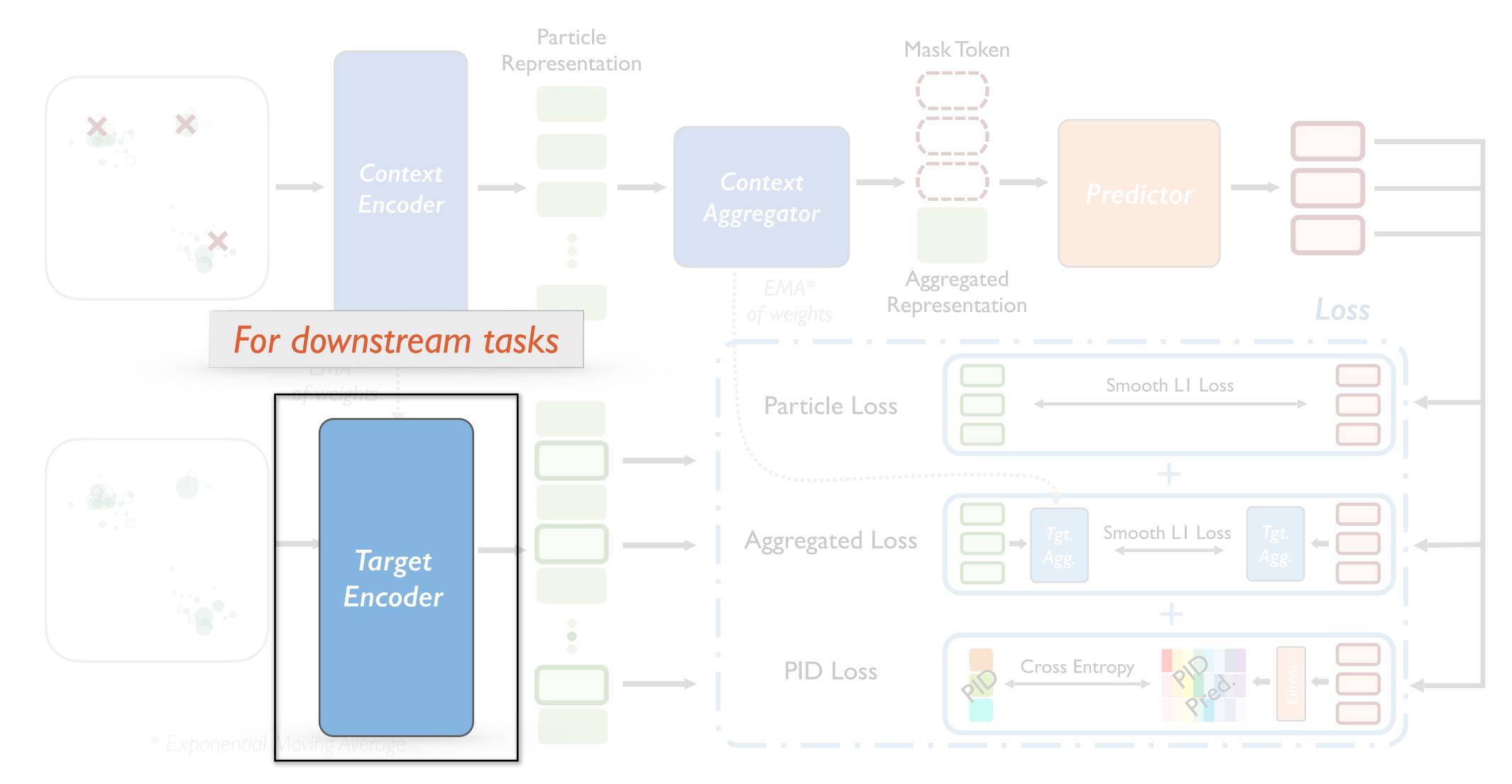
See also: "J-JEPA" [S. Katel, H. Li, Z. Zhao, F. Mokhtar, J. Duarte and R. Kansal, arXiv: 2412.05333], "HEP-JEPA" []. Bardhan, R. Agrawal, A. Tilak, C. Neeraj and S. Mitra, <u>arXiv: 2502.03933</u>]







INTRODUCING P-JEPA



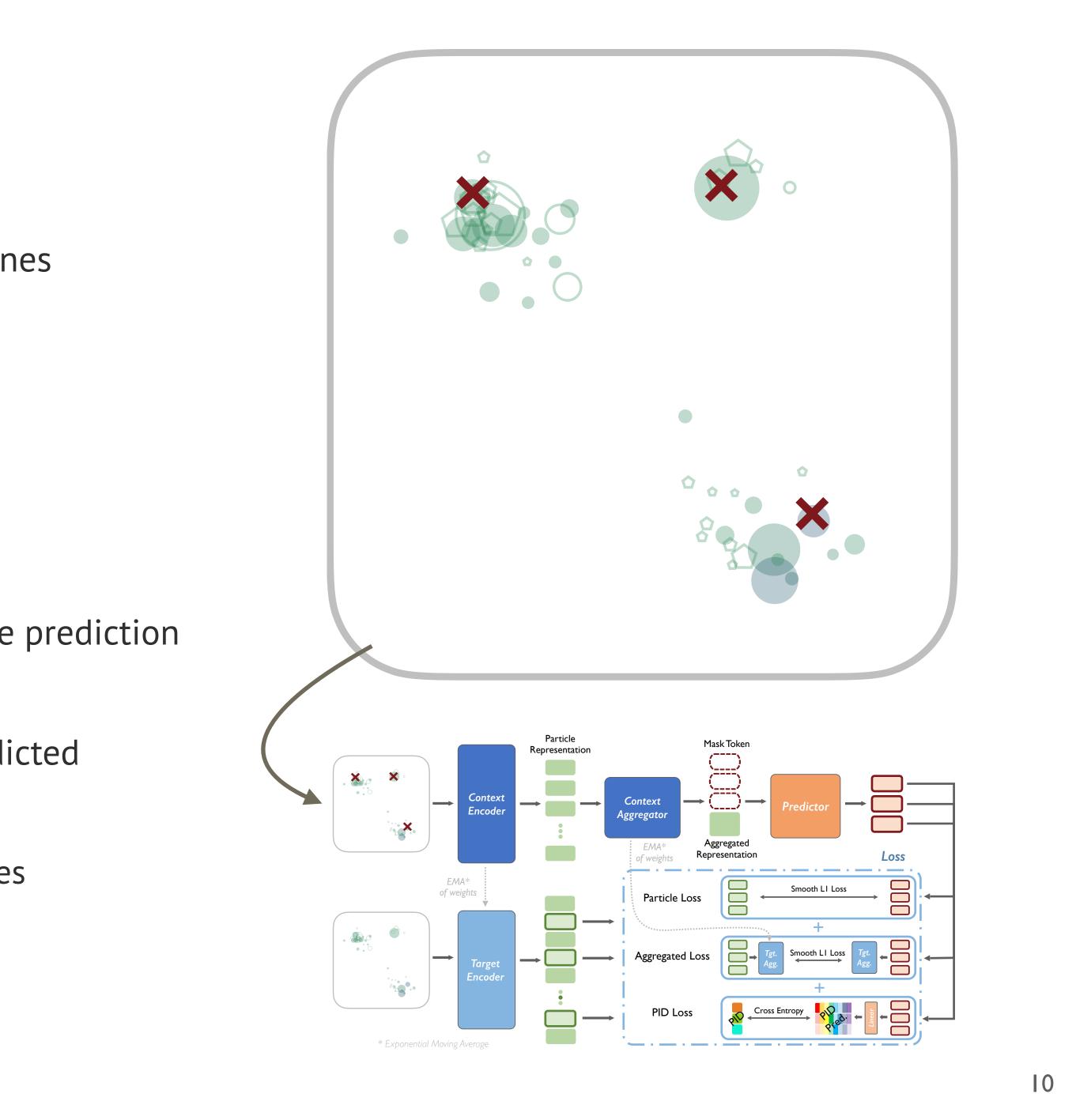




PARTICLE MASKING

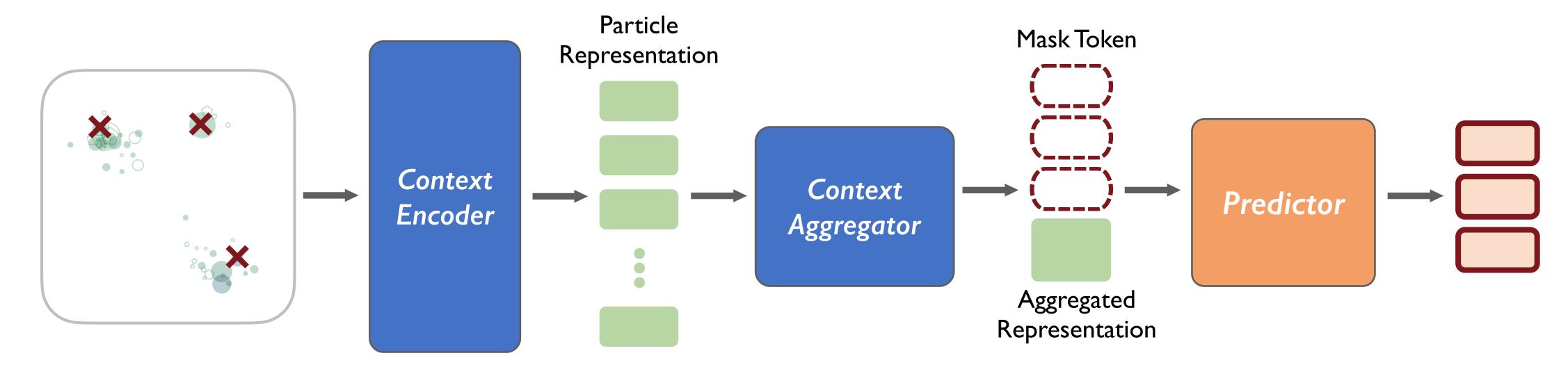
- The pre-training task in a nutshell:
 - predict the masked particles from the remaining ones
 - ... but in the latent space

- Masking strategy:
 - randomly mask 30–50% of the particles in a jet
 - the remaining particles serve as the context for the prediction
 - ==> input to the context encoder & predictor
 - the masked particles become the target to be predicted
 - ==> NOT seen by the context encoder & predictor
 - ==> the loss is computed only for the target particles



CONTEXT ENCODER AND PREDICTOR

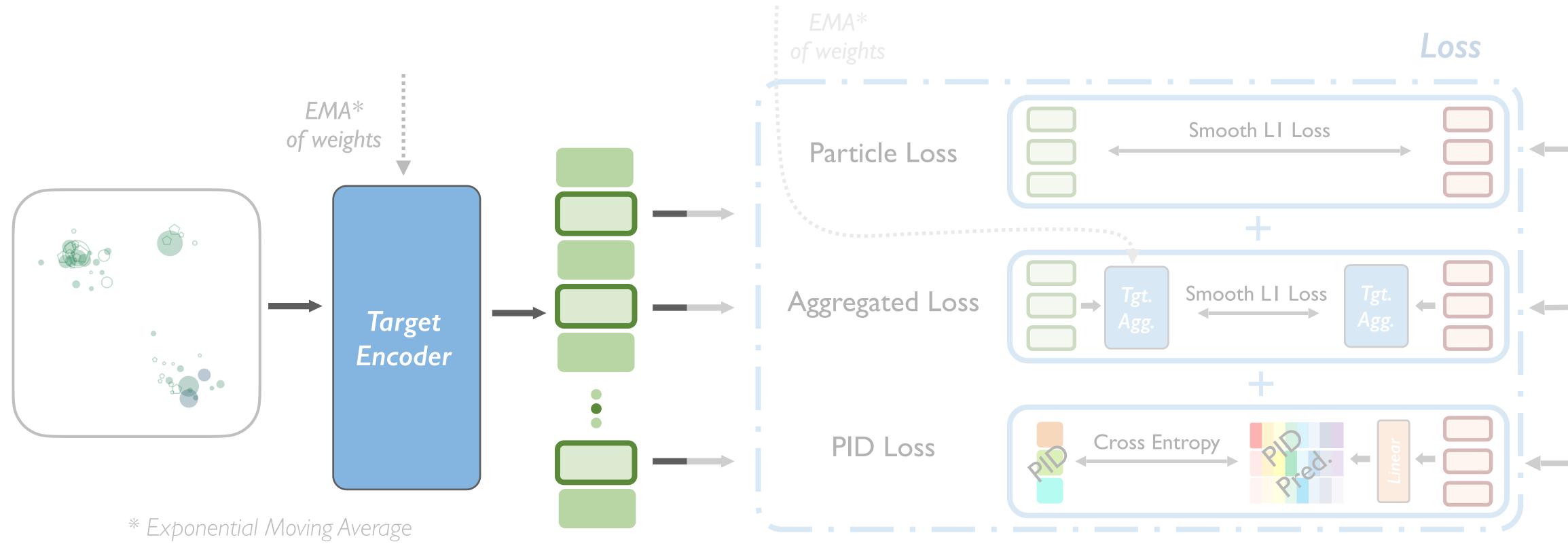
- Context encoder
 - a larger Particle Transformer (w/ pairwise features)
- Context aggregator
 - aggregates all context particles into a single token
- Predictor
 - plain Transformer, smaller than encoder
 - predicts the masked particles from the aggregated representation + mask tokens w/ pos. emb.



	Context Encoder + Aggregator	Predictor
Embed Dims	(5 2,5 2,5 2)	192
Pair Embed Dims	(64, 64, 64)	/
Num Heads	8	6
Num Blocks	16	4
Num Class Blocks	2	/
Num Params	76M	2.6M

TARGET ENCODER

- A target encoder is used to derive the particle embeddings in the latent space for loss computation
 - processes the complete set of particles in a jet (i.e., context + target)
 - then only the embeddings of the target particles are picked up for loss computation
 - updated by "copying" the weights from the context encoder (via exponential moving average)



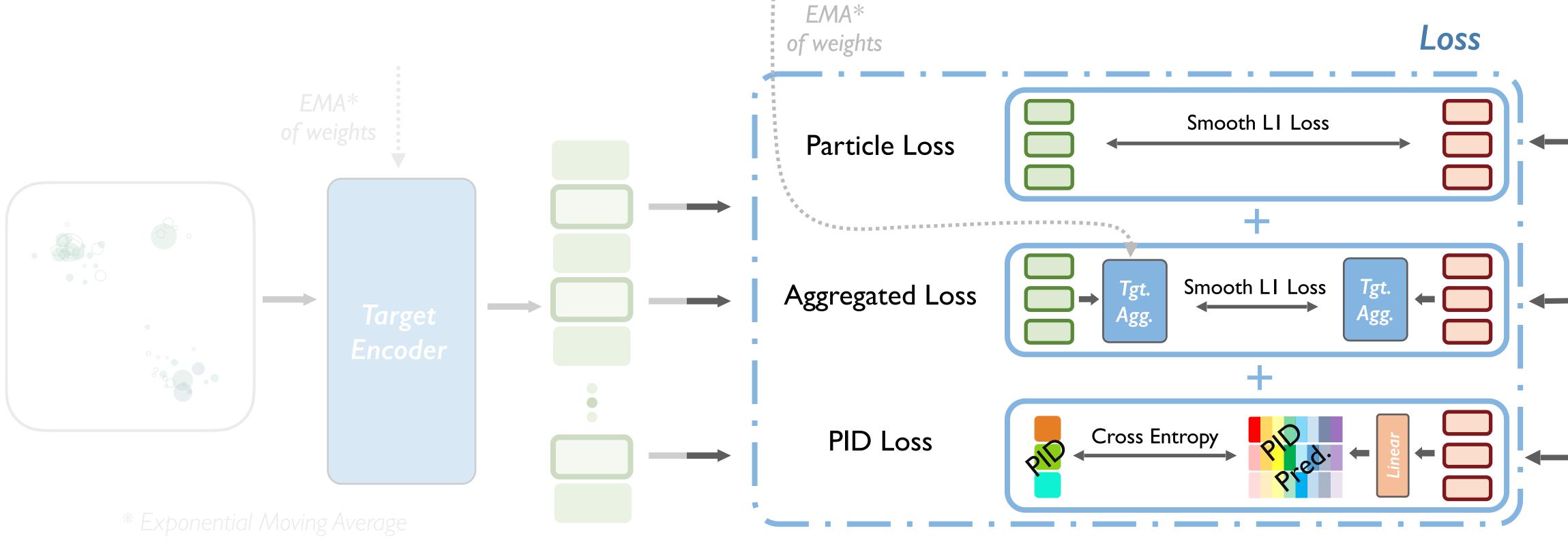




PRE-TRAINING LOSS

Loss = Particle Loss + Aggregated Loss + PID loss

- Particle Loss: smooth L1 loss between the predicted embeddings and those from target encoder

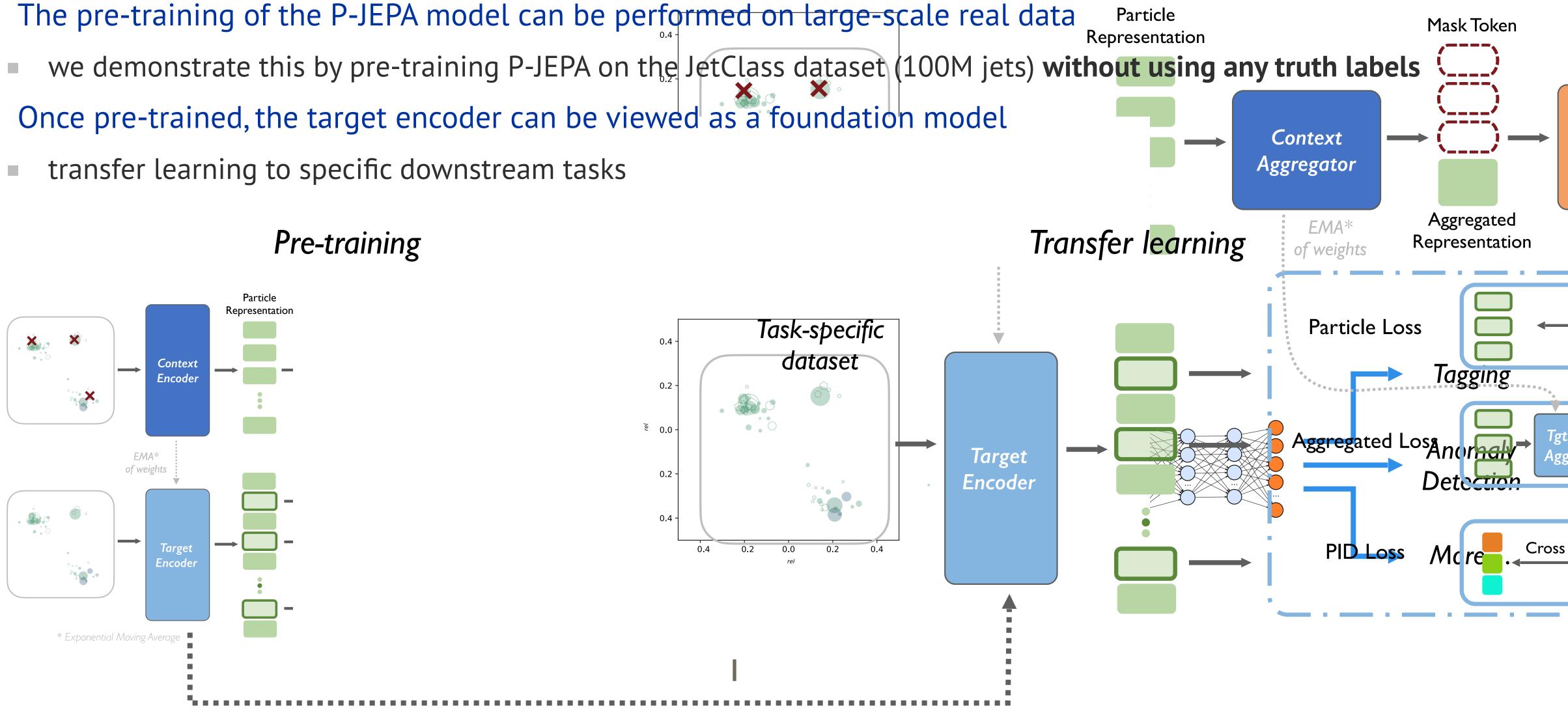


Aggregated Loss: computed on the aggregated representations of target particles using the target aggregator PID Loss: auxiliary task to predict the reconstructed PID of each masked particle from the predicted embeddings





PRE-TRAIN

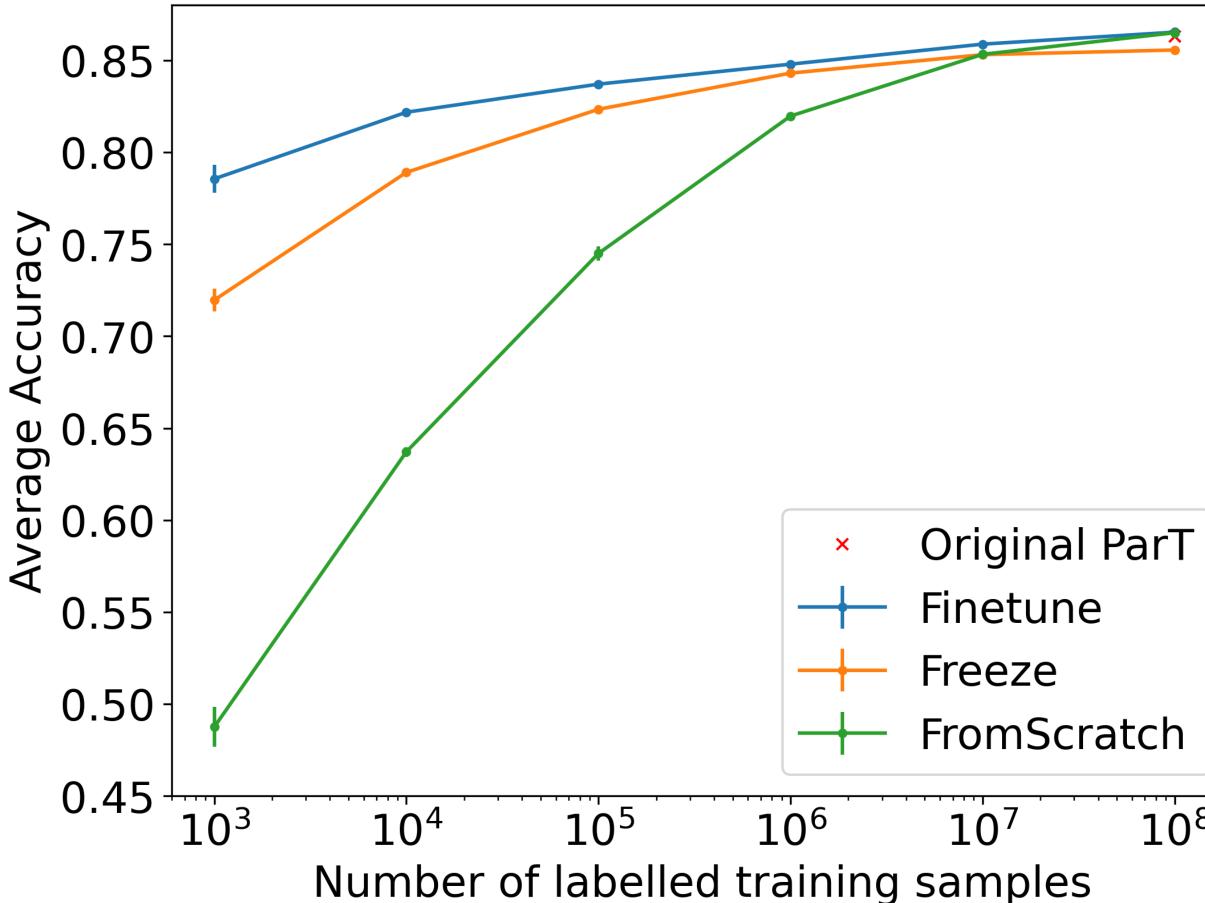


NING

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TRANSFER LEARNING: JET TAGGING

Benchmark: 10-class jet classification on JetClass





Encoder allowed to be slightly updated when trained with labelled jets for tagging

Freeze:

Encoder fixed when trained with labelled jets for tagging

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FromScratch:

Same network architecture, but trained with labelled jets starting from randomly initialized weights





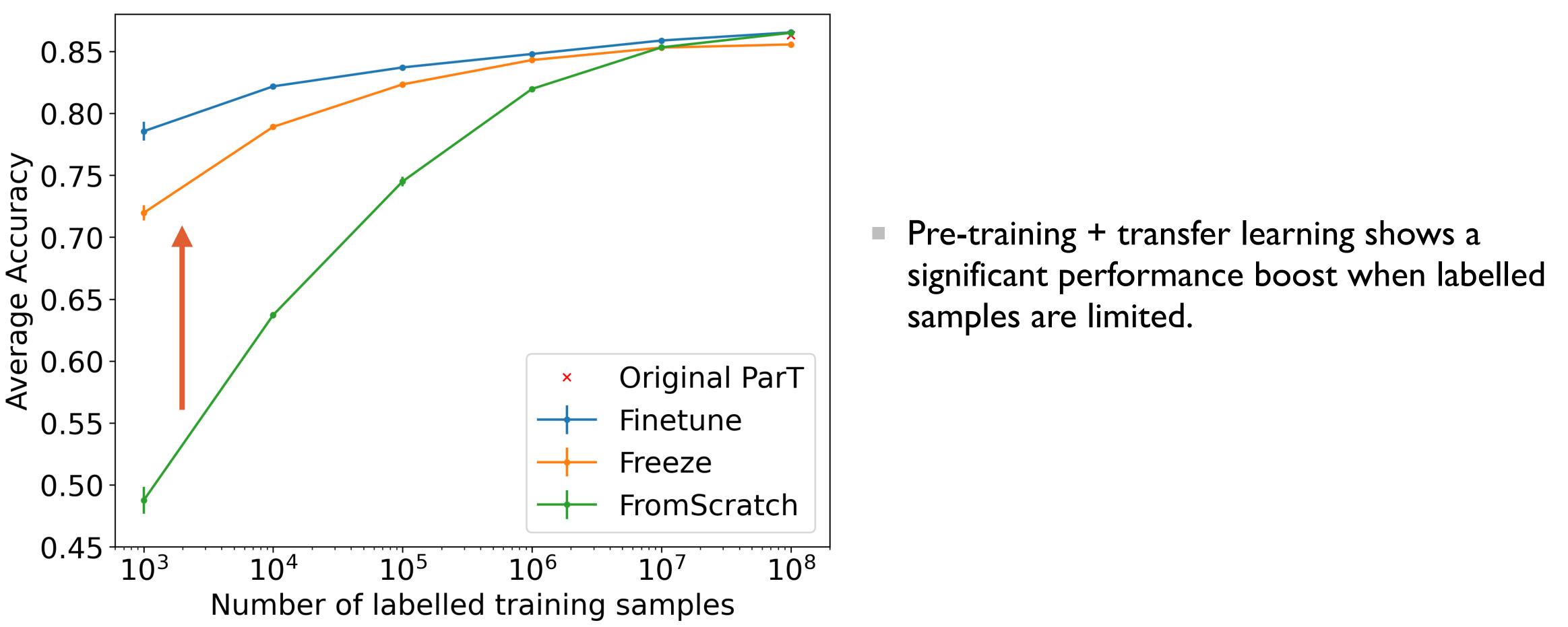






TRANSFER LEARNING: JET TAGGING

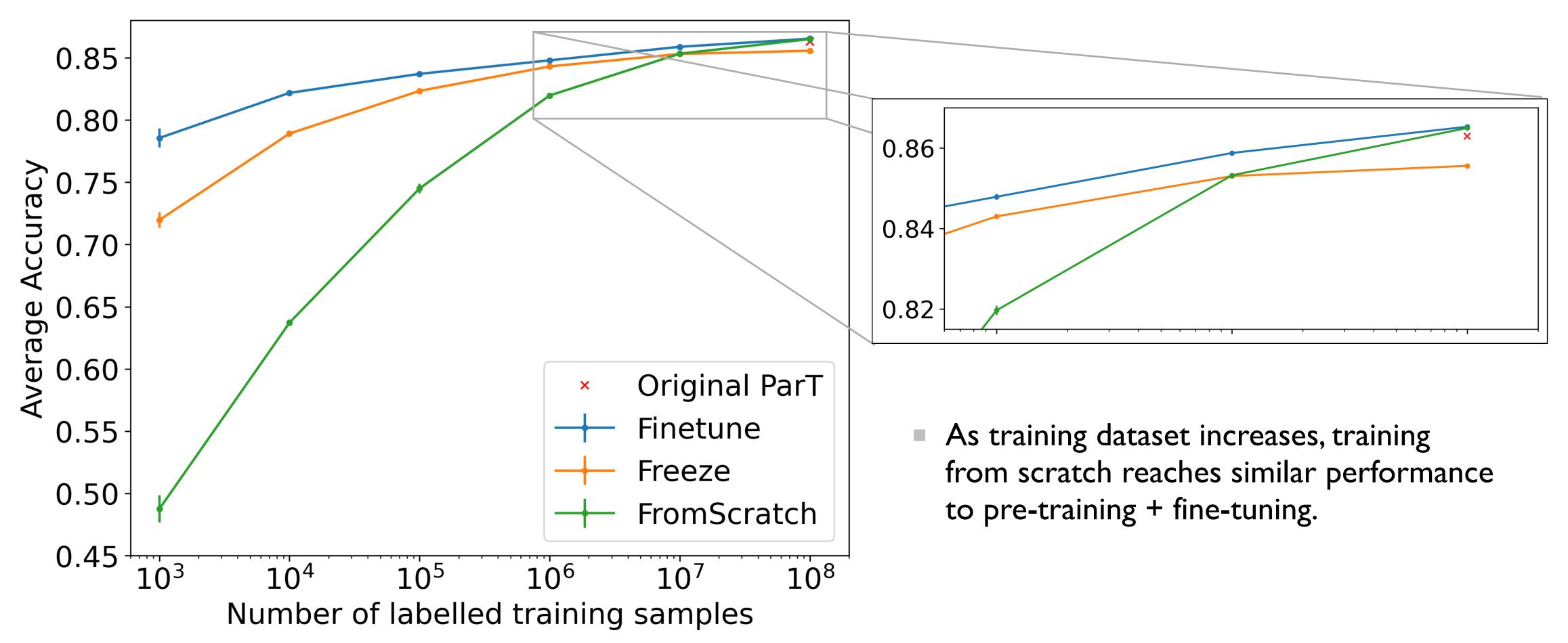
Benchmark: 10-class jet classification on JetClass





TRANSFER LEARNING: JET TAGGING

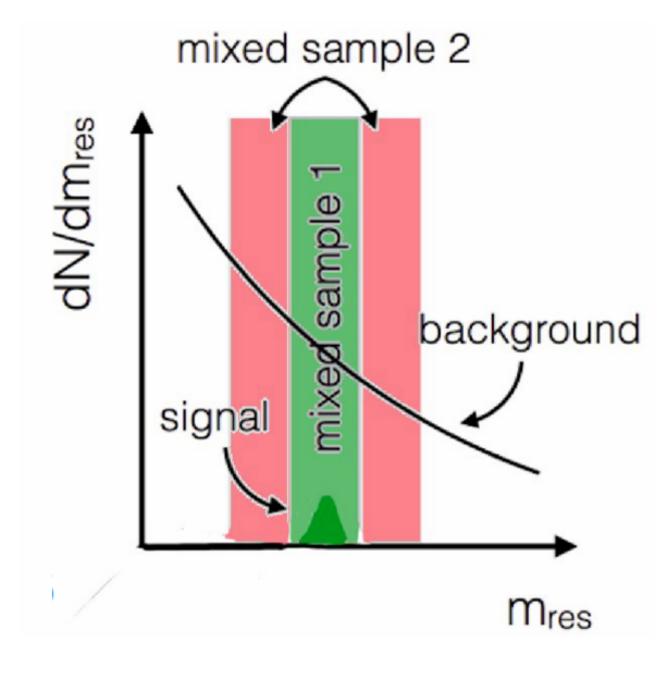
Benchmark: 10-class jet classification on JetClass







- Anomaly Detection (AD): model-agnostic search for new physics signals
- A classic paradigm for AD: <u>CWoLa</u> (classification without labels)
 - trains a classifier to distinguish two mixed samples
 - e.g., mass window (signal enriched) vs mass sideband (background enriched)
 - the classifier is effectively a signal vs background discriminator, thus can be used to enhance signal purity
 - allows to detect unknown signals purely from data



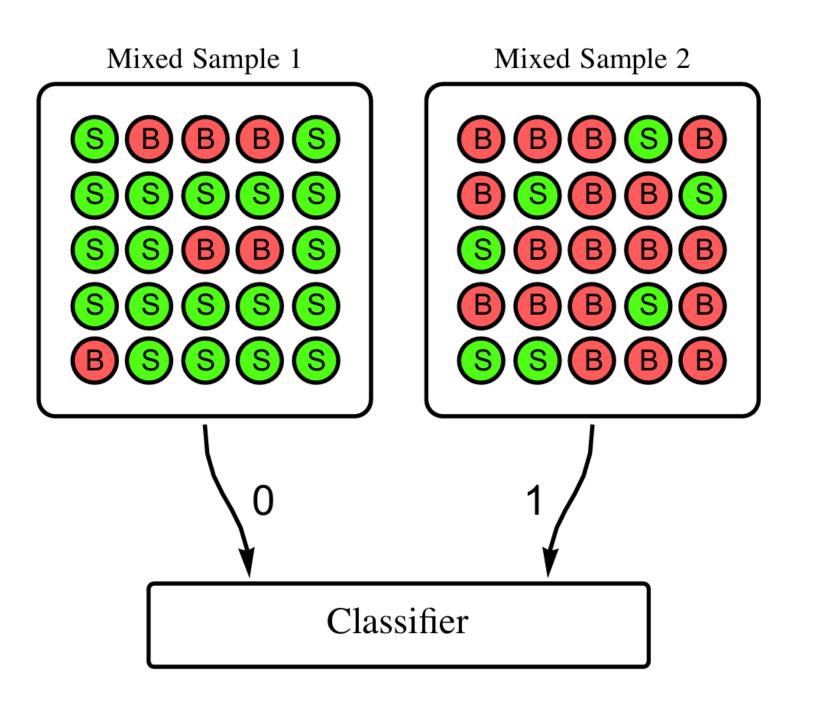
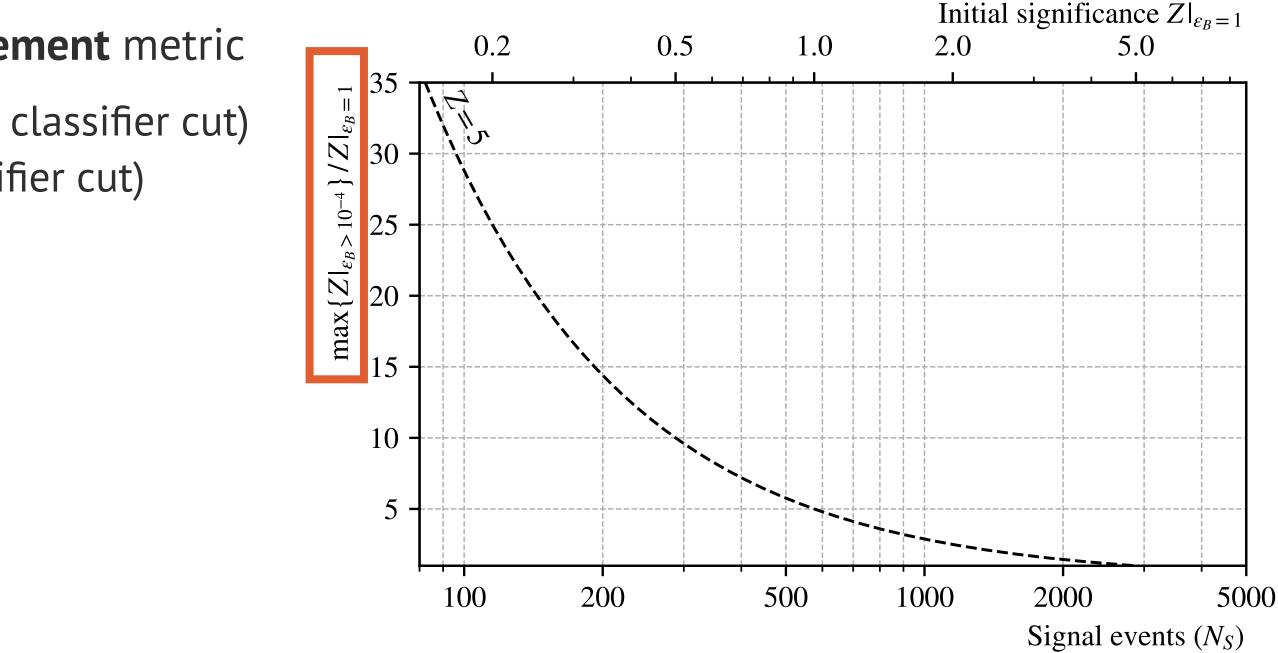




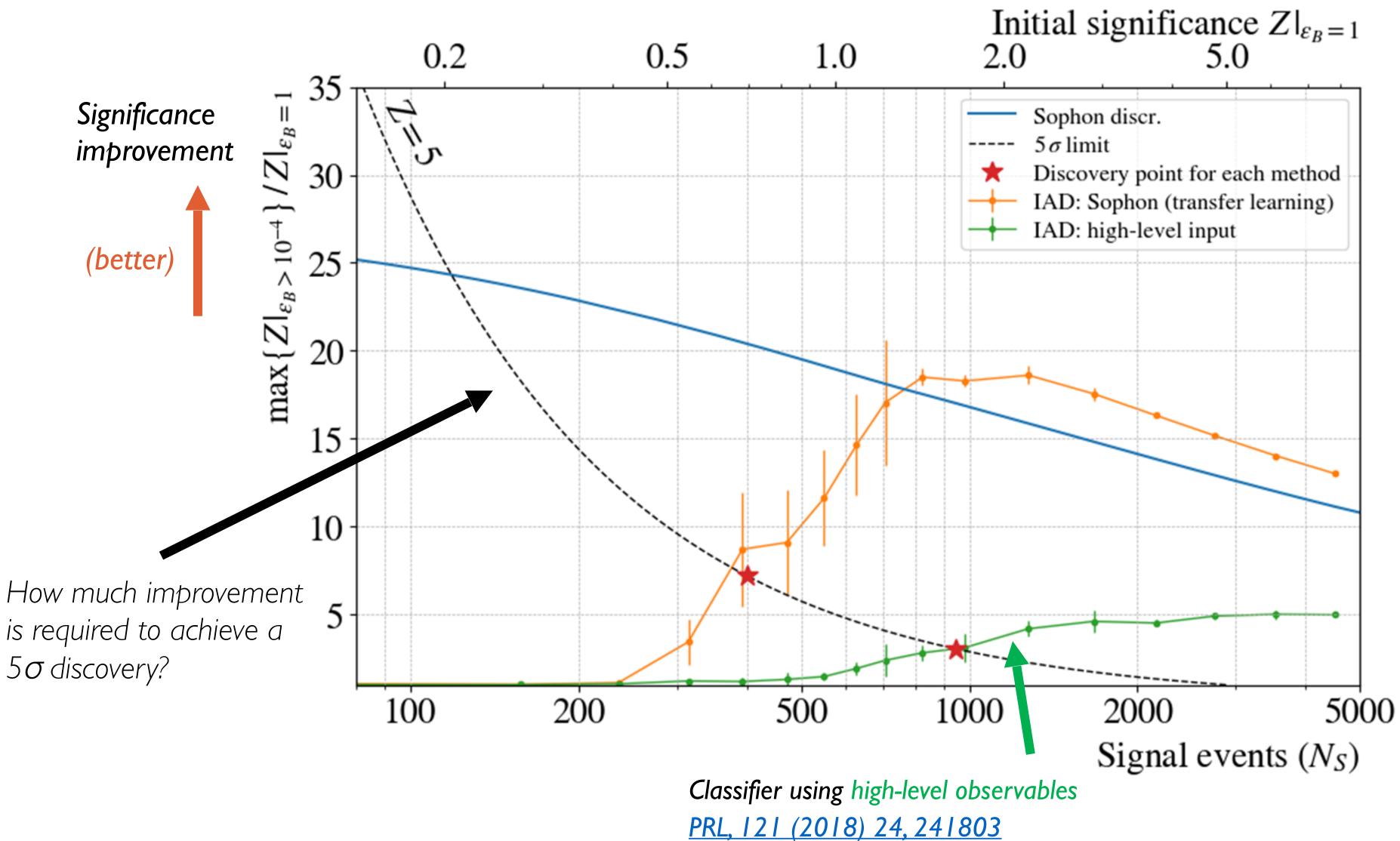
Figure Credit

- Traditionally AD was performed using only high-level features (e.g., jet mass, substructures) as inputs
- Machine-learned representations captures richer information of a jet, thus can improve the performance of AD see e.g., the "Sophon" approach [arXiv: 2405.12972]
- We benchmark the P-JEPA extracted features using the IAD [arXiv:2210.14924] framework
 - idealized setup for the mixed samples: **background only** vs **background + signal**
 - background in the two mixed samples are drawn from the same distribution, no need to worry about e.g., mass dependency and interpolation into the mass window etc.
 - performance evaluated by the **significance improvement** metric
 - i.e., **ratio** of the *maximal* significance (at an optimal classifier cut) over the *initial* significance (i.e., inclusive w/o classifier cut)

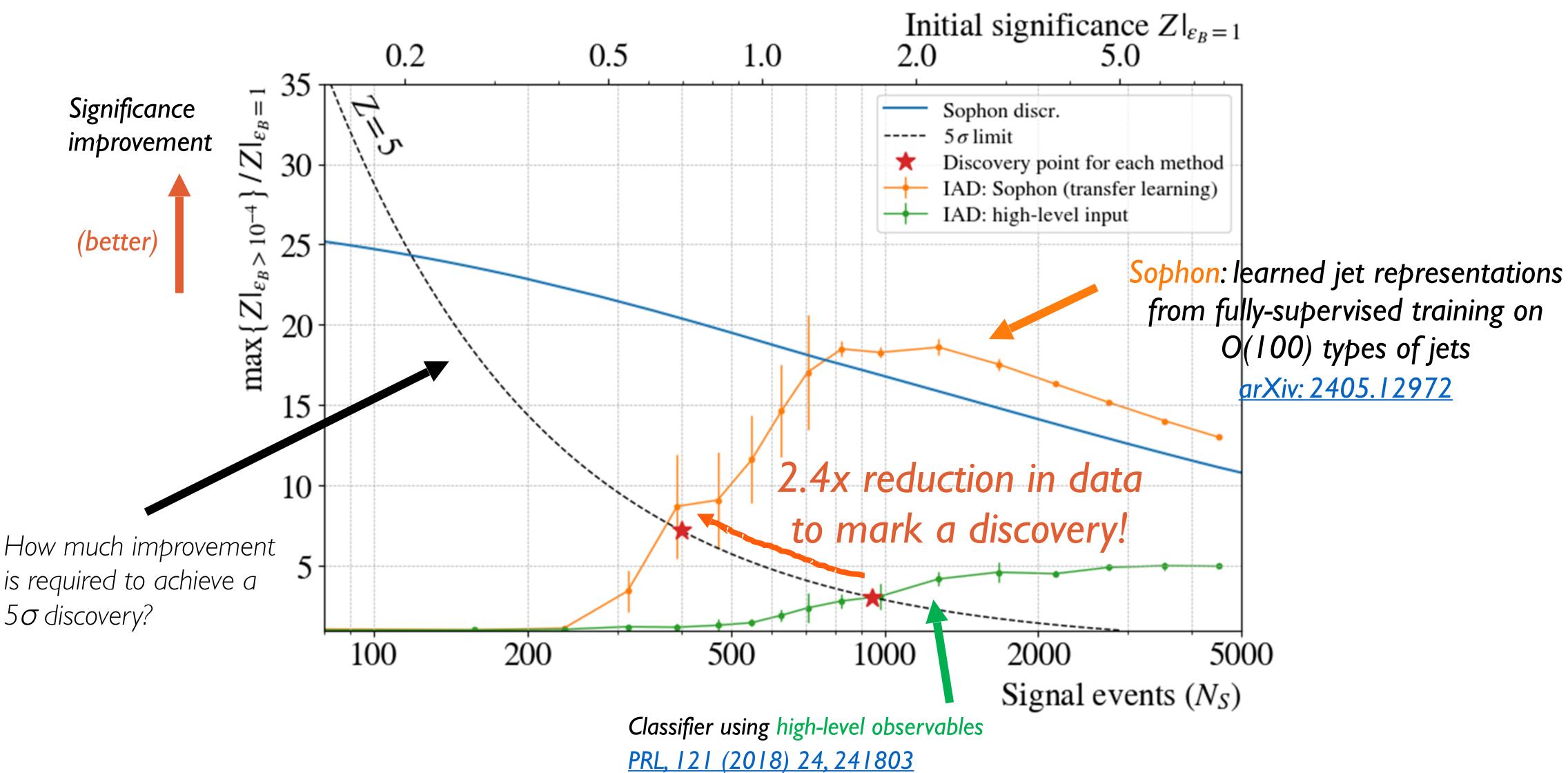




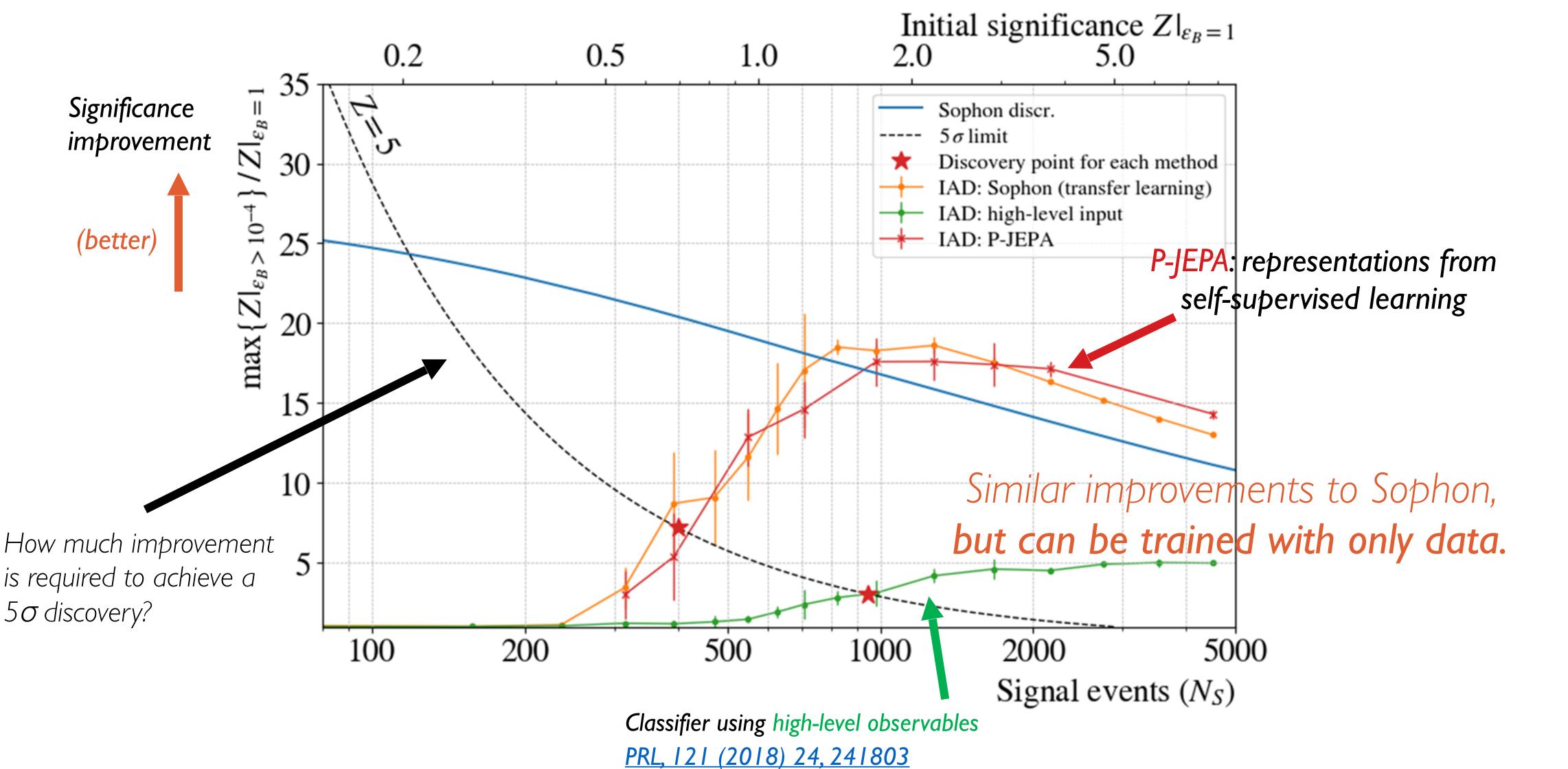










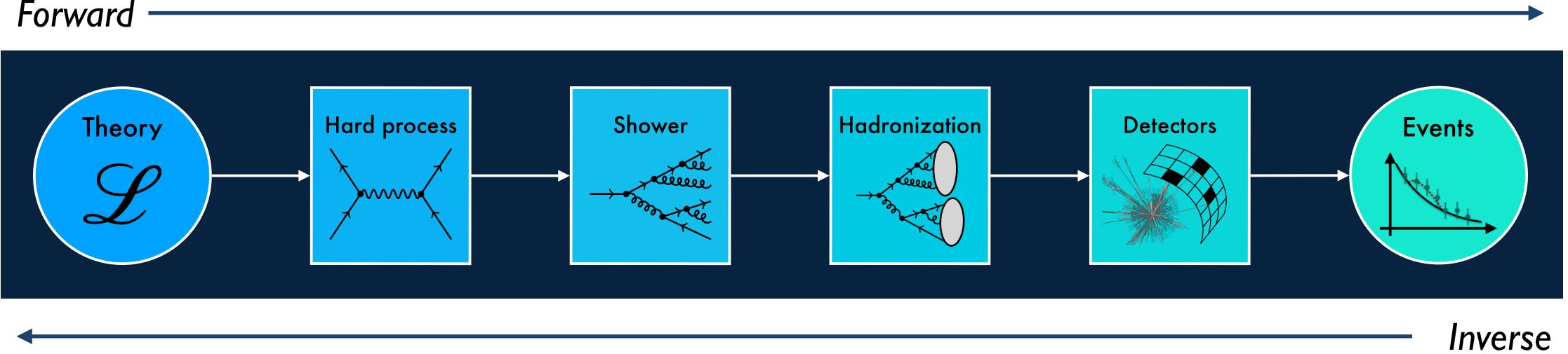




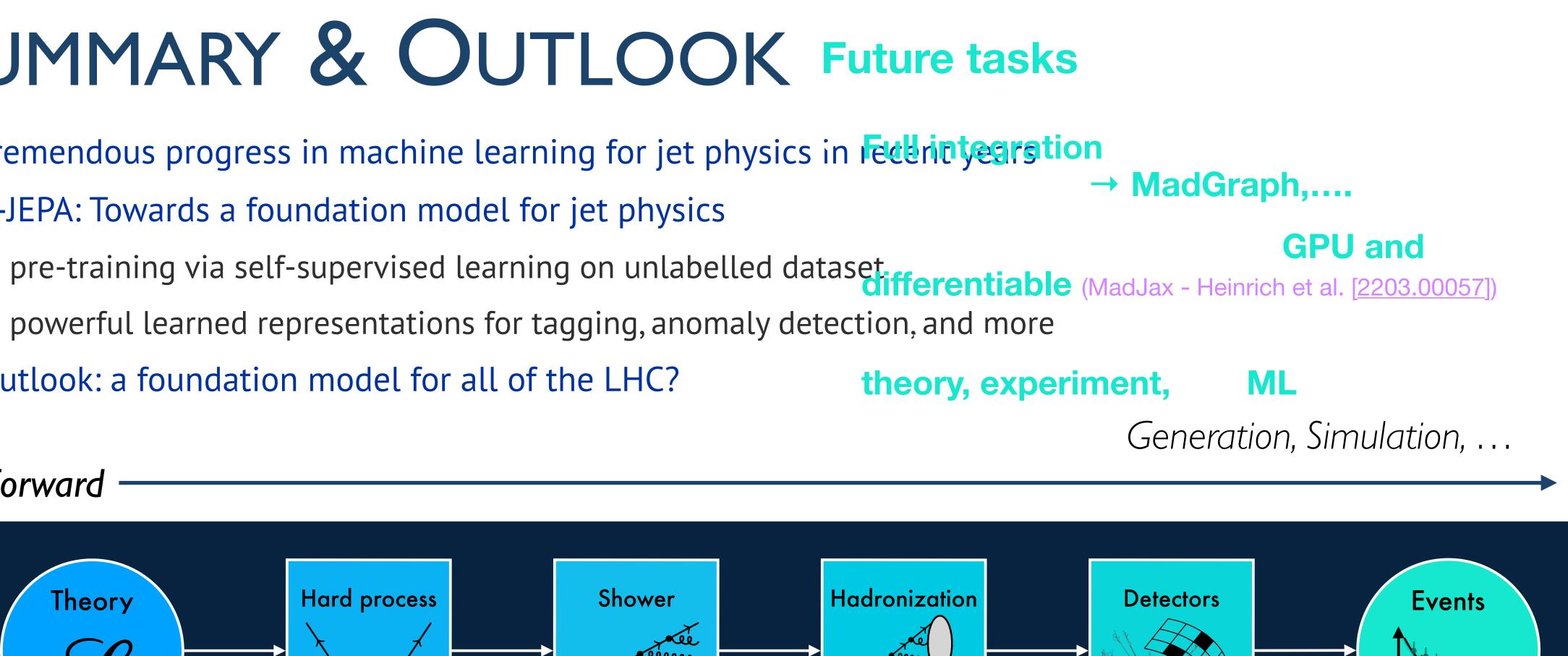
SUMMARY & OUTLOOK Future tasks

- Tremendous progress in machine learning for jet physics in rederingeration
- P-JEPA: Towards a foundation model for jet physics

 - powerful learned representations for tagging, anomaly detection, and more
- Outlook: a foundation model for all of the LHC?



Reconstruction, Unfolding, ...



Credits: <u>R.Winterhalder</u>

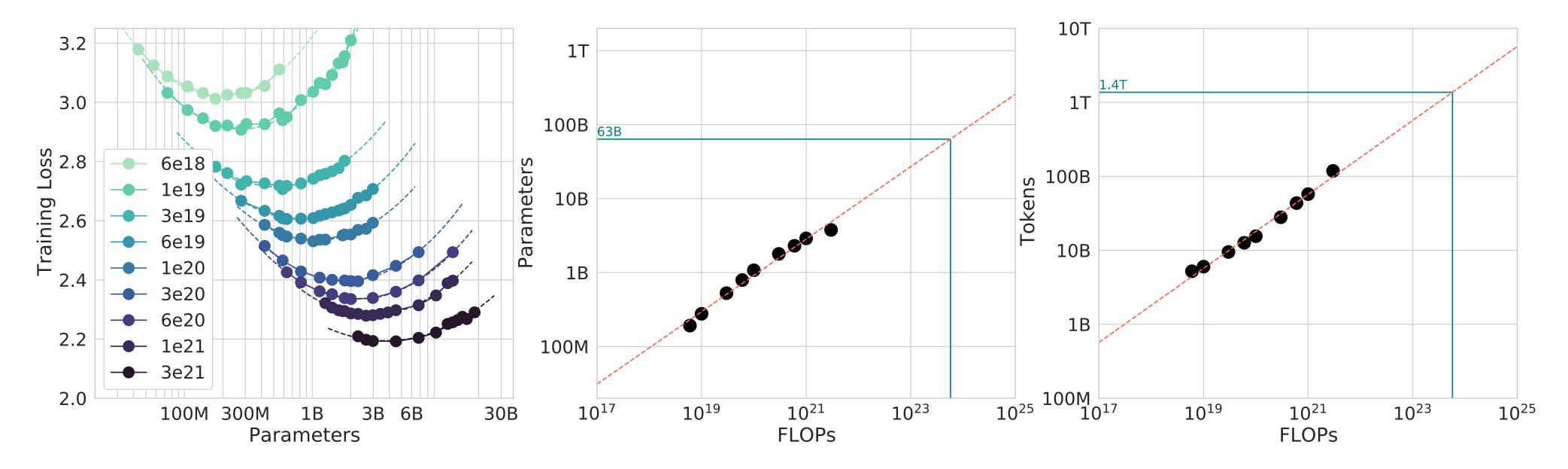






SCALING LAW

- For language models neural scaling law [arXiv: 2001.08361, 2203.15556]



- compute budget
- Would be interesting to see the scaling law for jets but very computation intensive...

How far can we push the performance with bigger models, larger datasets, and more computing power?

empirical power law scaling of the loss as a function of the compute (C), dataset size (D) and model parameters (N) once established, can be extrapolated to determine the best dataset size & parameter combination under a fixed



