

SMALL THINKS BIG

Transfer learning in KM3NeT/ORCA with transformers

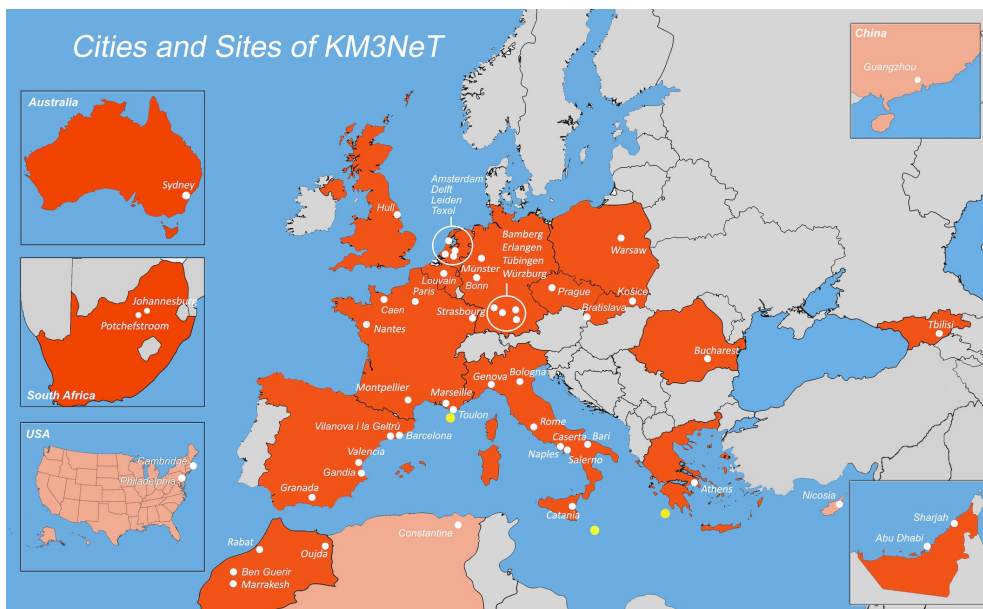
30/09/2024, Caen
Iván Mozún Mateo, Antonin Vacheret
On behalf of the KM3NeT collaboration



1. KM3NeT: neutrino telescopes
2. Need for data in large language models
3. Why transfer learning?
4. Multi-detector configuration and multi-task for KM3NeT/ORCA
5. Summary & The road ahead

KM3NeT is an **international collaboration**

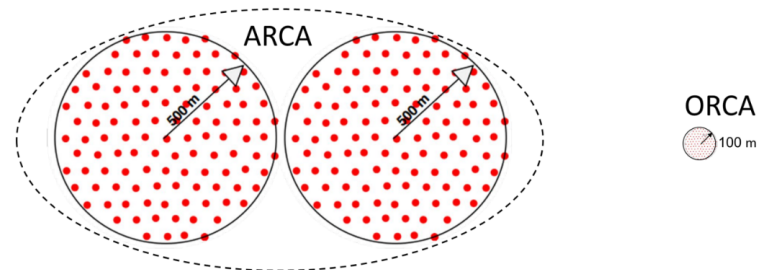
- 22 countries
- 65 partner institutes
- ~250 members



Two undersea neutrino telescopes

- **KM3NeT/ARCA**
 - Optimized for 1 TeV – 10 PeV
 - Identify high-energy neutrino sources in the Universe.
 - 36m vertical spacing and 90m horizontal spacing
- **KM3NeT/ORCA**
 - Optimized for 1 – 100 GeV
 - Determine the mass ordering of neutrinos.
 - 9m vertical spacing and 20m horizontal spacing

Currently under construction: ORCA23 (20%), ARCA28 (12%)



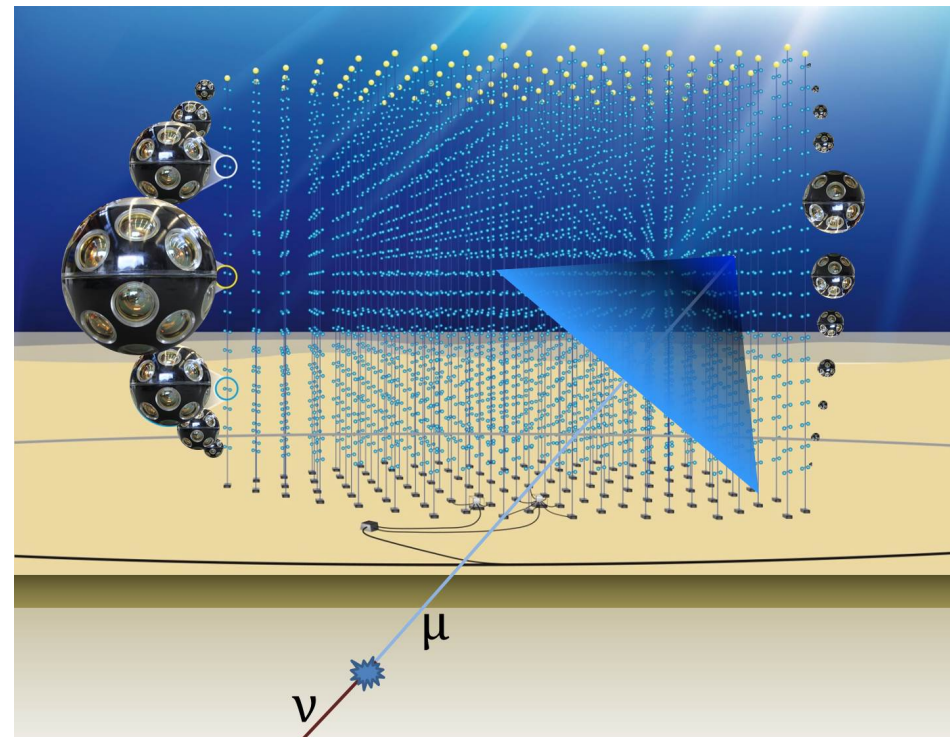
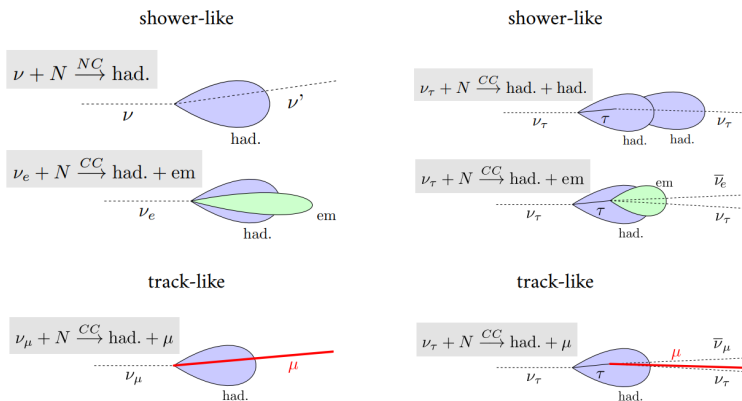
KM3NeT: neutrino telescopes

Same **technology**:

- 1 (2) building block(s) for ORCA (ARCA)
- 115 vertical detection units (DUs) per block
- 18 digital optical modules (DOMs) per DU
- 31" PMTs per DOM

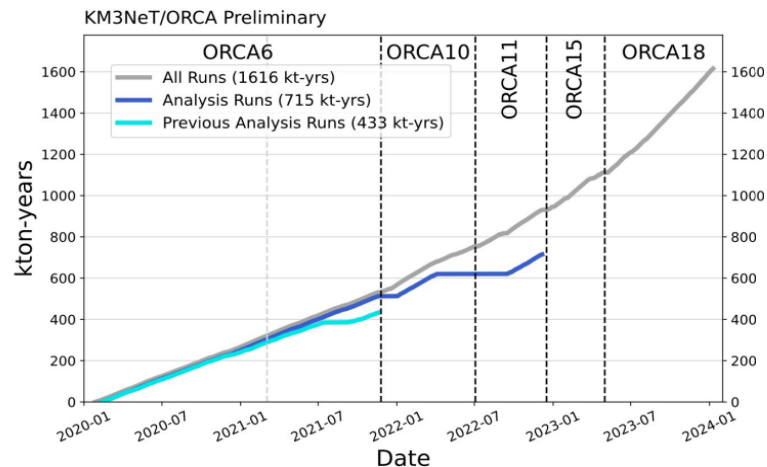
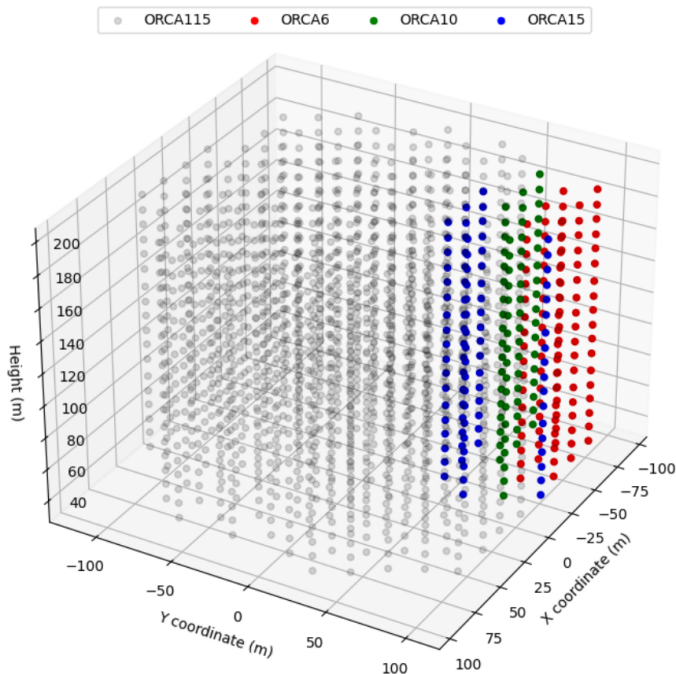
Same **detection principle**:

Light collection from Cherenkov radiation emitted by particles traveling faster than the speed of light in water



Building the detectors

KM3NeT telescopes collect, process and analyze data as they are being built.

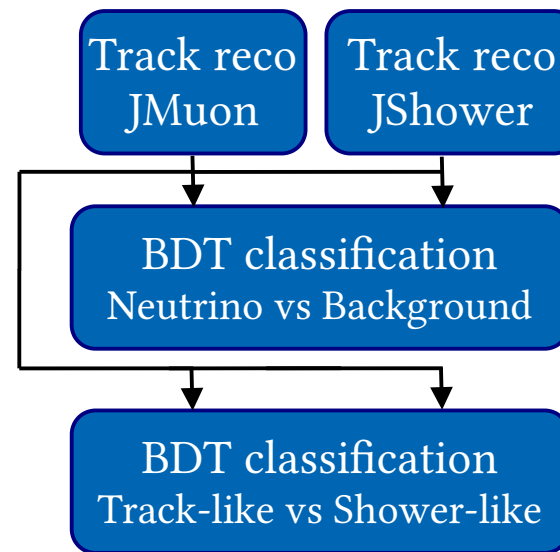
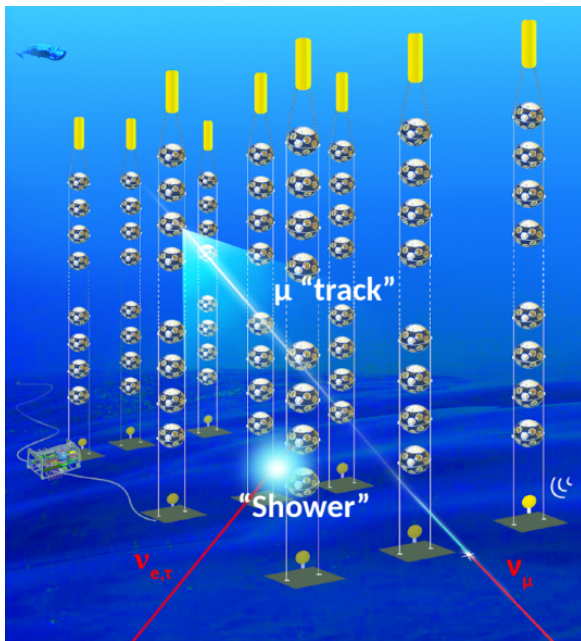


Foundation model in KM3NeT?

- learns as the detectors grow
- can handle multiple geometries
- can handle both KM3NeT/ORCA and KM3NeT/ARCA
- classification ↔ reconstruction

Reconstructing neutrino physics

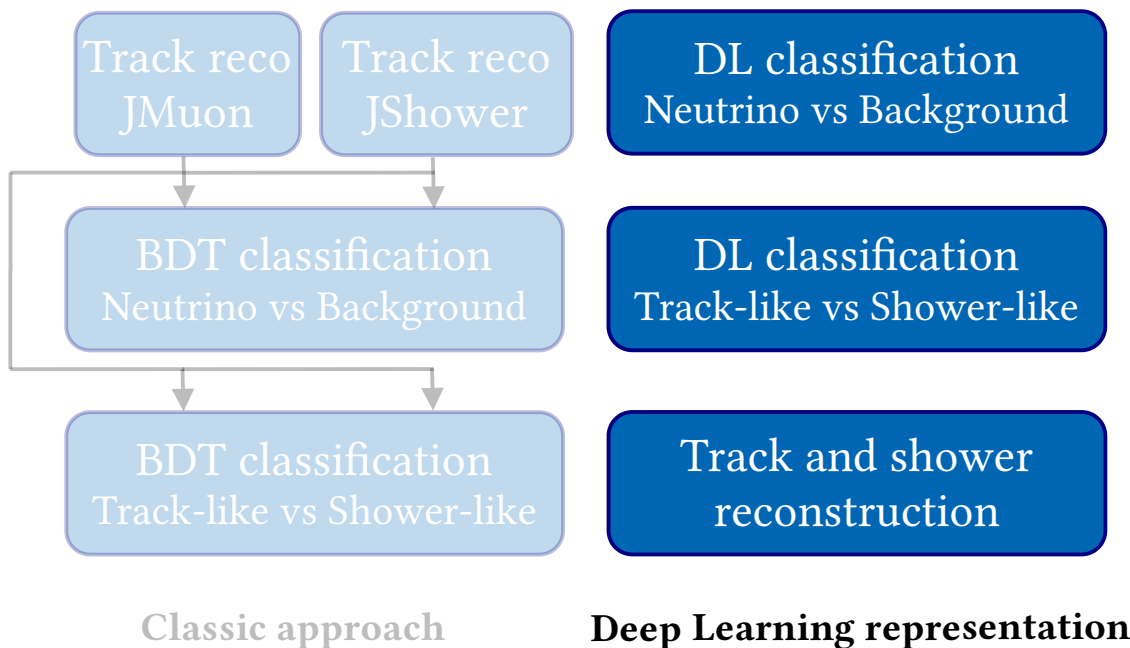
The **official KM3NeT pipeline for reconstruction and classification** relies on algorithms that are applied separately for track-like event or shower-like events. Then, simple BDTs are applied on the reconstructed variables for classification tasks.



Classic approach

Reconstructing neutrino physics

The **official KM3NeT pipeline for reconstruction and classification** relies on algorithms that are applied separately for track-like event or shower-like events. Then, simple BDTs are applied on the reconstructed variables for classification tasks.



Novel **deep learning** techniques use low-level information from the detector, i.e. light pulses to

1. Let the model decide the features to use
2. Generalise over a large input domain dimensions
3. Perform different tasks

Classification and reconstruction are performed **independently**, and for any type of event.

Large DL models needs **huge amounts of very diverse data** to generalize and interpolate, improving the performances of existing algorithms.

Various DL models tested. So far, no one is considered for official analysis.

Convolutional Neural Networks

- Event reconstruction for KM3NeT/ORCA using convolutional neural networks (M. Moser, KM3NeT)
- Event Classification and Energy Reconstruction for ANTARES using Convolutional Neural Networks (N. Geißelbrecht, ANTARES)
- Deep learning reconstruction in ANTARES (J. García-Méndez et al., ANTARES)
- Dark matter search towards the Sun using Machine Learning reconstructions of single-line events in ANTARES (J. García-Méndez et al., ANTARES)

Deep Neural Networks

- Deep Neural Networks for combined neutrino energy estimate with KM3NeT/ORCA6 (S. Peña Martínez, KM3NeT)

Graph Neural Networks:

- Development of detector calibration and graph neural network-based selection and reconstruction algorithms for the measurement of oscillation parameters with KM3NeT/ORCA (D. Guderian, KM3NeT)
- Data reconstruction and classification with graph neural networks in KM3NeT/ORCA6-8 (F. Filippini et al., KM3NeT)
- Cosmic ray composition measurement using Graph Neural Networks for KM3NeT/ORCA (S. Reck, KM3NeT)
- Optimisation of energy regression with sample weights for GNNs in KM3NeT/ORCA (B. Setter, KM3NeT)
- Tau neutrino identification with Graph Neural Networks in KM3NeT/ORCA (L. Hennig, KM3NeT)

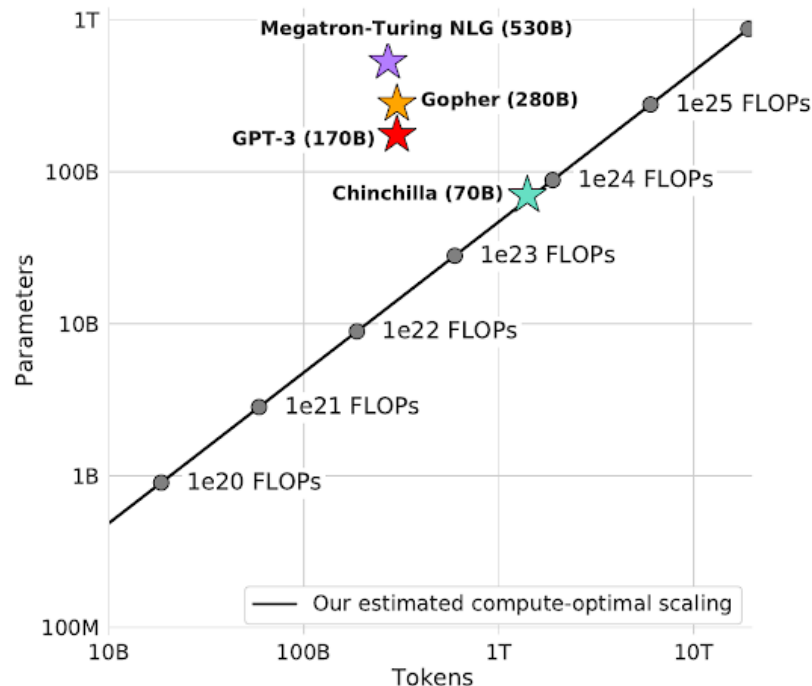
More details here: [A Comprehensive Insight into Machine Learning Techniques in KM3NeT \(J. Prado\)](#)

Neutrino telescope data is described as a set of spatial points with timing & charge information (point-cloud data), hence, most developed DL architectures are based on GNNs.

Language models are starting to overtake but...

- lot of trainable parameters
- lot of training data

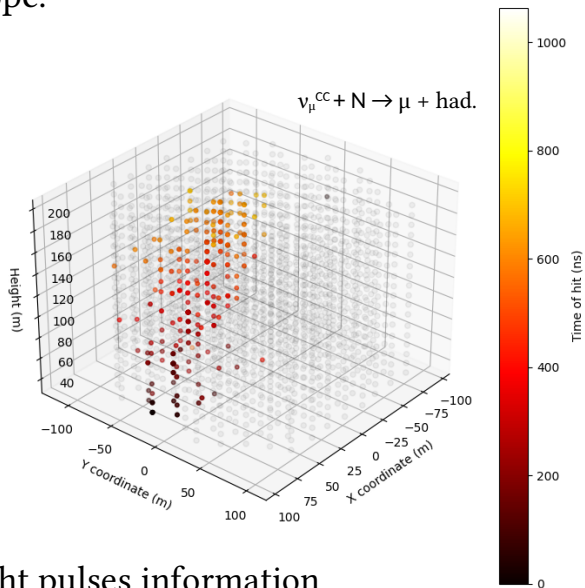
The data is too complex and requires a lot of computing resources to be produced and to encapsulate all the physics → **we must be efficient**



Scaling law for trainable parameters and tokens for large language models
arxiv.org/abs/2203.15556

Transformer architecture

The input data is the low-level hit information that composes the light pattern detected in the telescope.

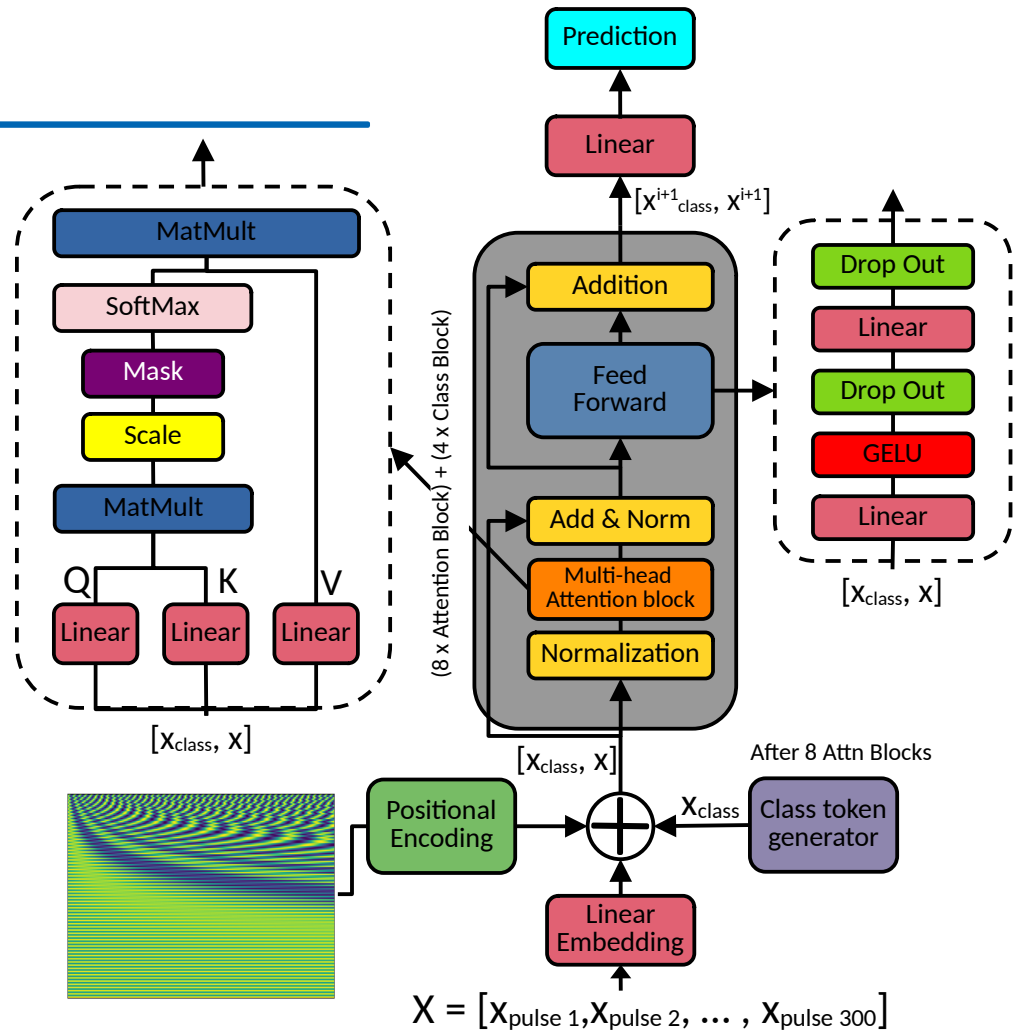


The light pulses information

$$\mathbf{X}_{\text{pulse}} = [\text{pos}_x, \text{pos}_y, \text{pos}_z, \text{dir}_x, \text{dir}_y, \text{dir}_z, \text{t}, \text{ToT}]$$

is processed in parallel by the transformer and the high-level information is extracted in the attention blocks.

Model has ~1.6M trainable parameters.



Multiple tasks

- Classification and reconstruction done together
- Test the capacity of the model

Multiple detector geometries

- A single model for all detectors: ORCA115 → ORCAX
- Run-by-Run approach:
 - MC based on data to reduce discrepancies
 - **Not enough data** to train models for every detector

Efficient use of resources

- Saves time and increases performance
- The information is propagated across detectors

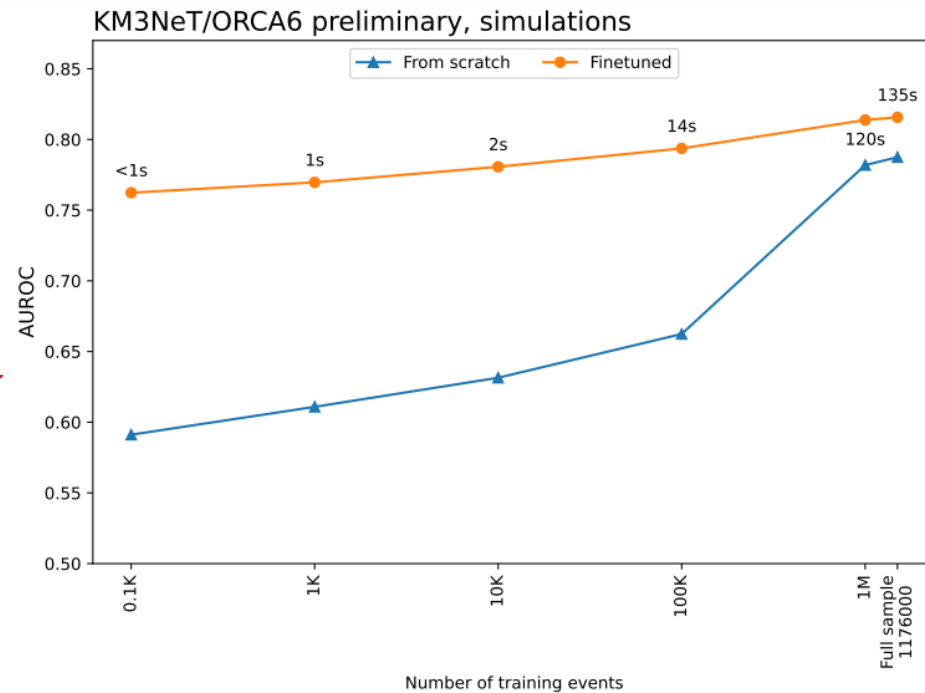


Multi-detector study

ORCA6 (Feb20 – Nov21): 4075 runs
ORCA10 (Dec21 – May22): 1889 runs
100k tracks & 100k showers

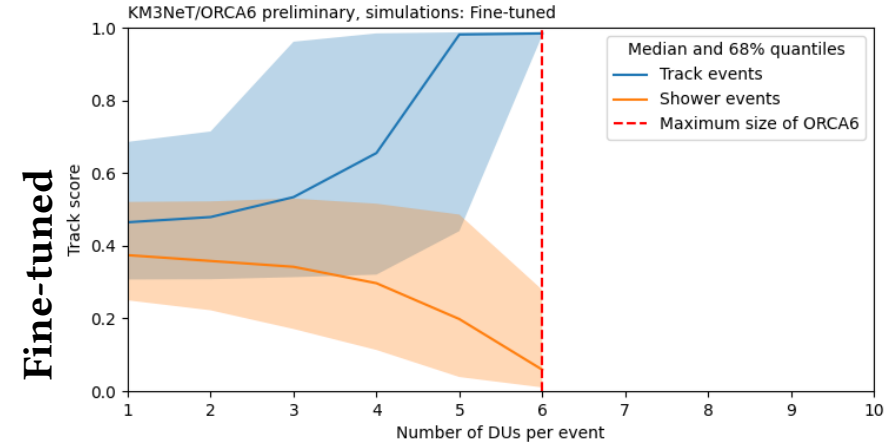
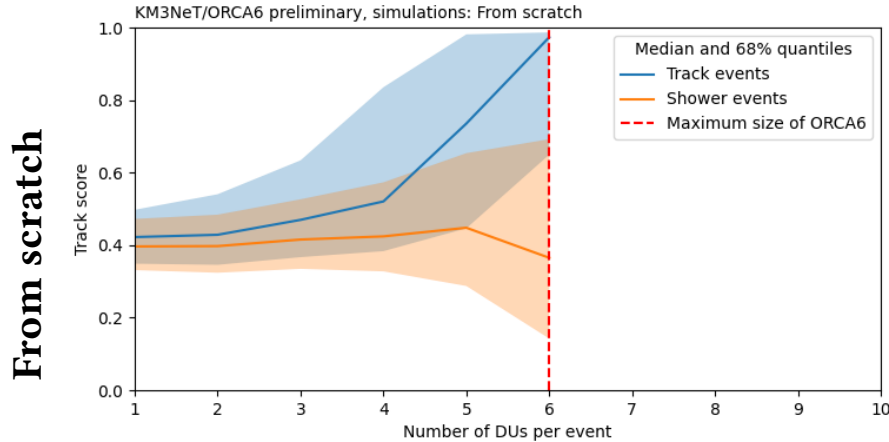
Multi-task study

ORCA115 dataset 1: track-shower
ORCA115 dataset 2: energy
850k tracks & 850k showers each



AUROC value for track-shower classification with KM3NeT/ORCA6 data.
The AUROC curves are shown as function of the training size sample.

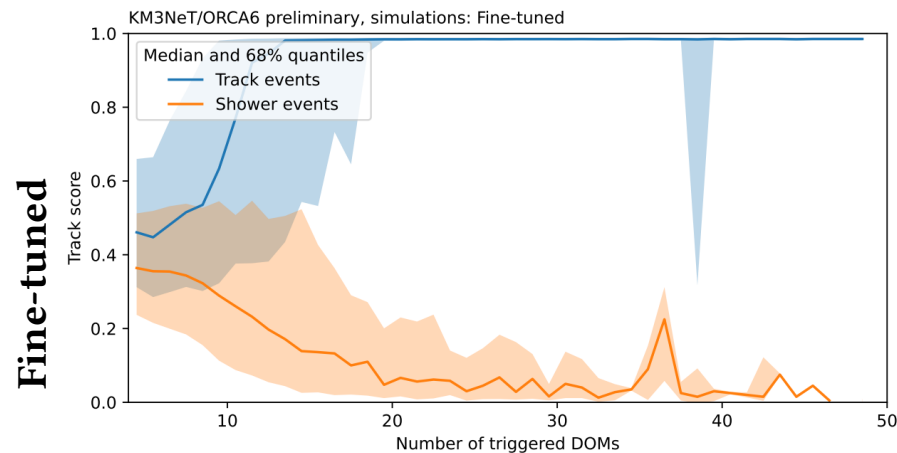
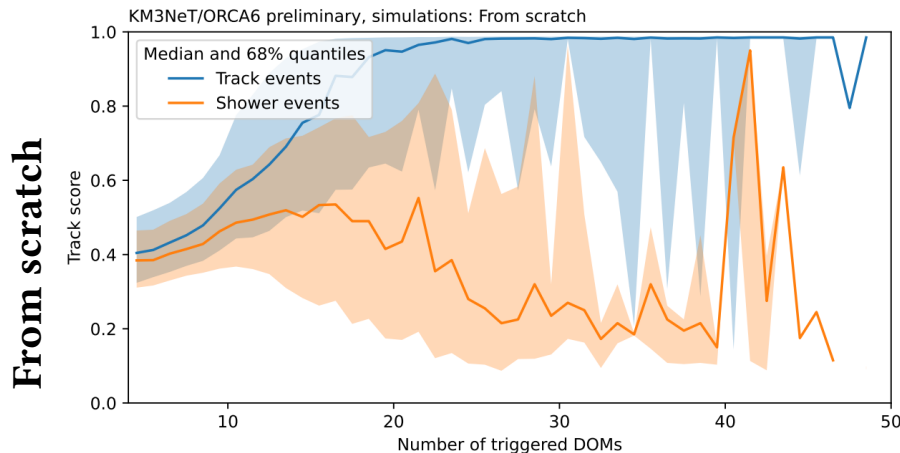
The model is able to **interpolate to non-existing DUs information** because it pre-learned the full geometry.



Track-shower classification:

- Limited data: 200k events for a detector with 6 lines is not enough to do a proper separation
- Performance: fine-tuned model works way better than the scratch one
- High dependence on event geometry: not enough discrimination with few lines

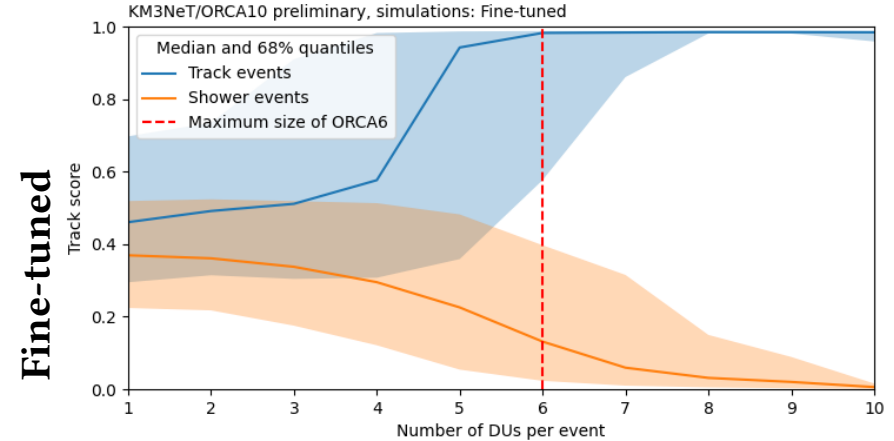
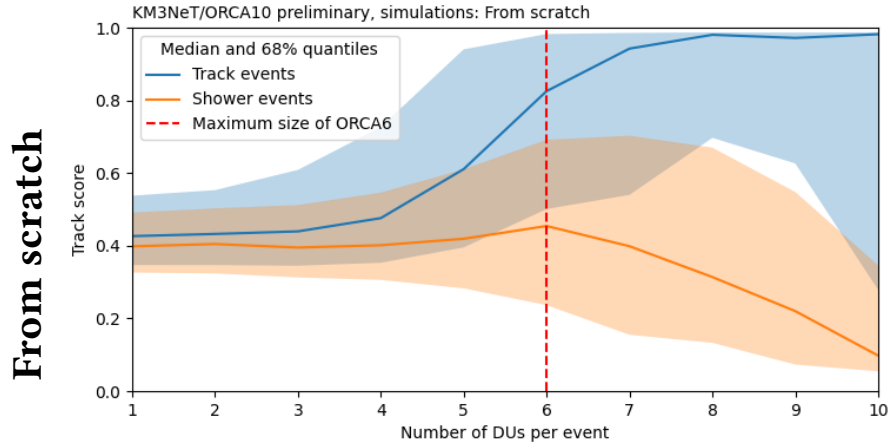
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Track-shower classification:

- Limited data: 200k events for a detector with 6 lines is not enough to do a proper separation
- Performance: fine-tuned achieves separation in events with above 10 triggered DOMs
- Peak at ~40 triggered DOMs: fine-tuned model compensates the low statistics

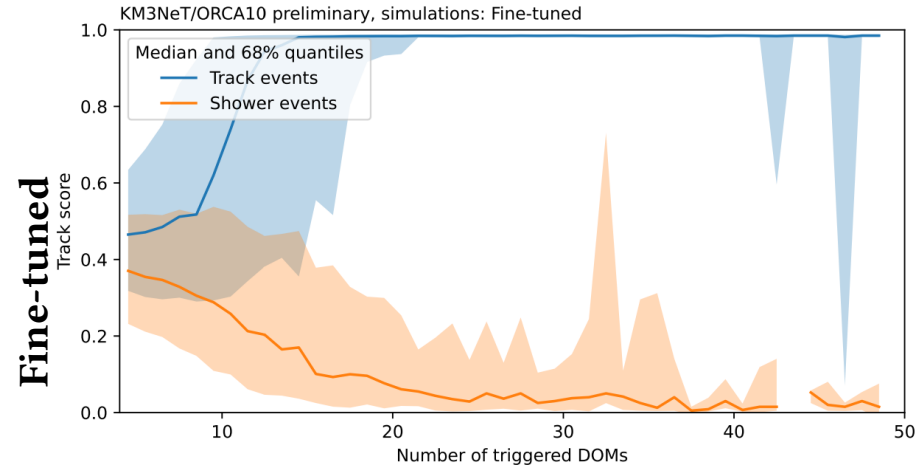
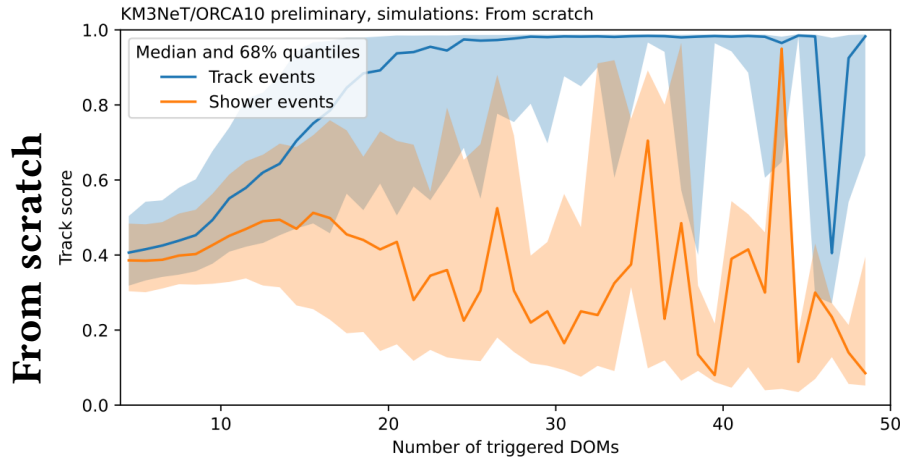
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Track-shower classification:

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- Performance: fine-tuned model works way better than the scratch one
- High dependence on event geometry: not enough discrimination with few lines
- **Major improvement with increasing detector size ↔ better event containment**

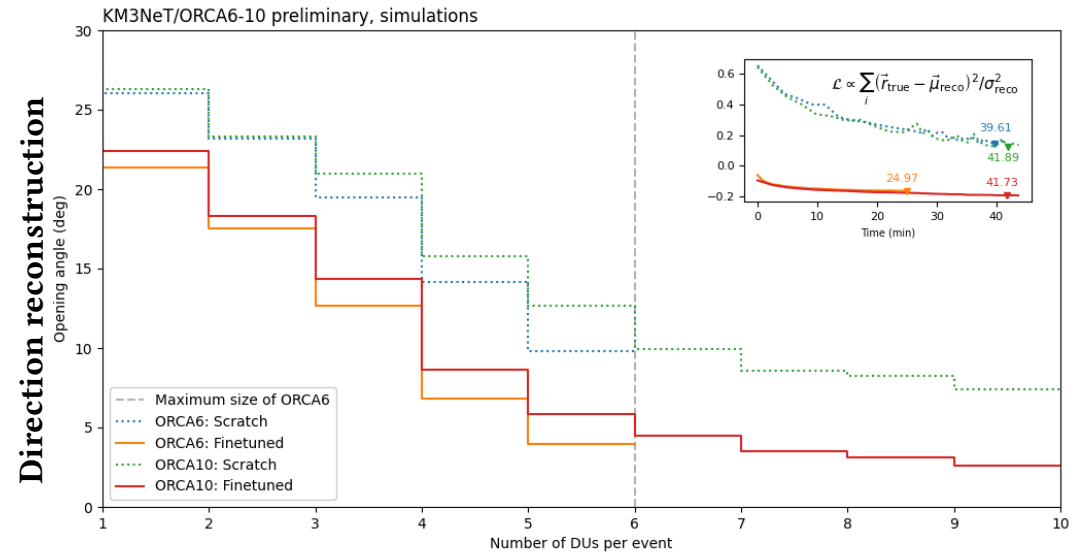
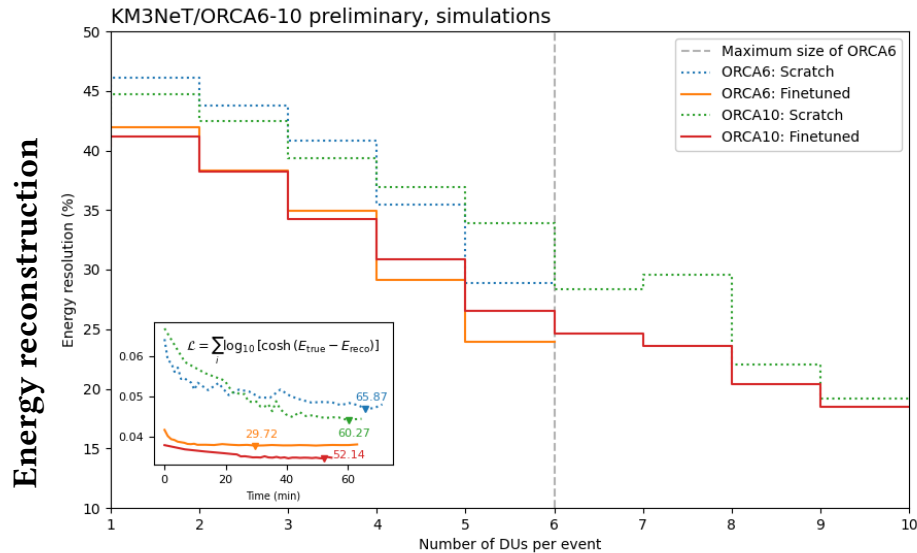
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Track-shower classification:

- Limited data: 200k events for a detector with 6 lines is not enough to do a proper separation
- Performance: fine-tuned achieves separation in events with above 10 triggered DOMs
- Multiple peaks: fine-tuned model compensates the low statistics

The model is able to **interpolate to non-existing DUs information** because it pre-learned the full geometry.



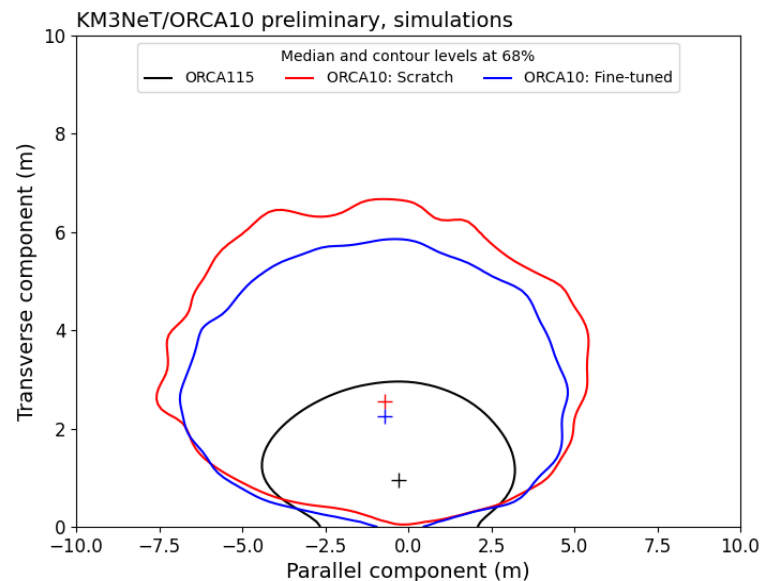
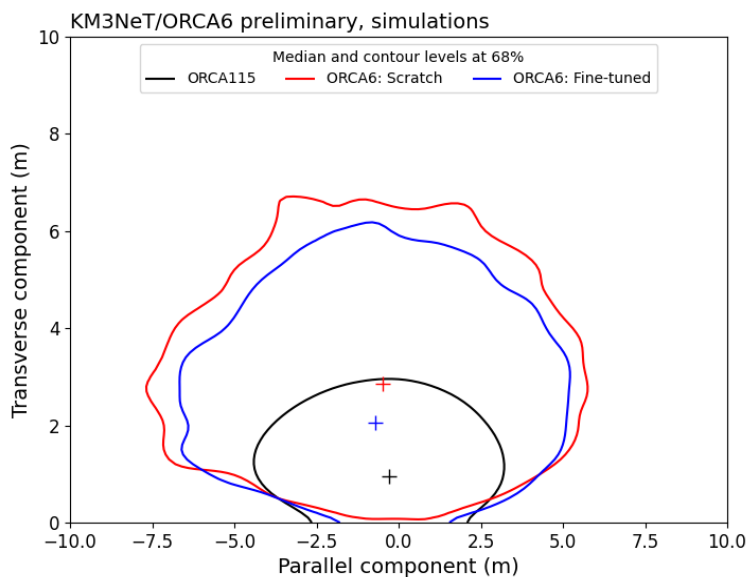
Energy and direction reconstruction:

- Loss curves reveal fine-tuning's performance boost
- Similar resolution in energy reconstruction, but in less time!
- Direction reconstruction improved significantly

Interaction reconstruction vertex:

- The hardest task
- Dynamic detector coordinates from RbR approach
- Small fiducial volume burdens the reconstruction

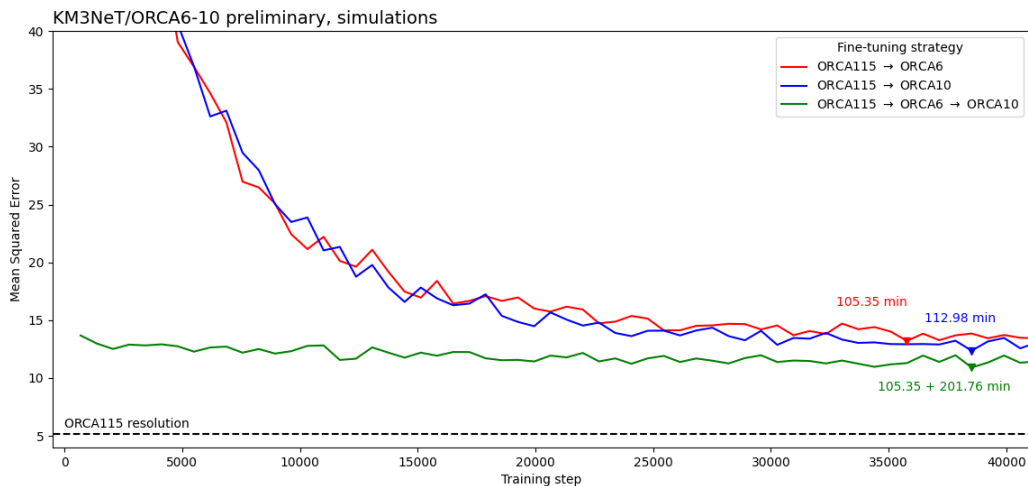
Better data representation?
Build a latent space to effectively accommodate dynamic coordinates and detector conditions & geometries



Interaction vertex reconstruction at KM3NeT/ORCA6 (left) and KM3NeT/ORCA10 (right) projected over the neutrino direction for 1-100 GeV atmospheric neutrinos.

Interaction reconstruction vertex:

- The hardest task
- Dynamic detector coordinates from rbr approach
- Small fiducial volume burdens the reconstruction

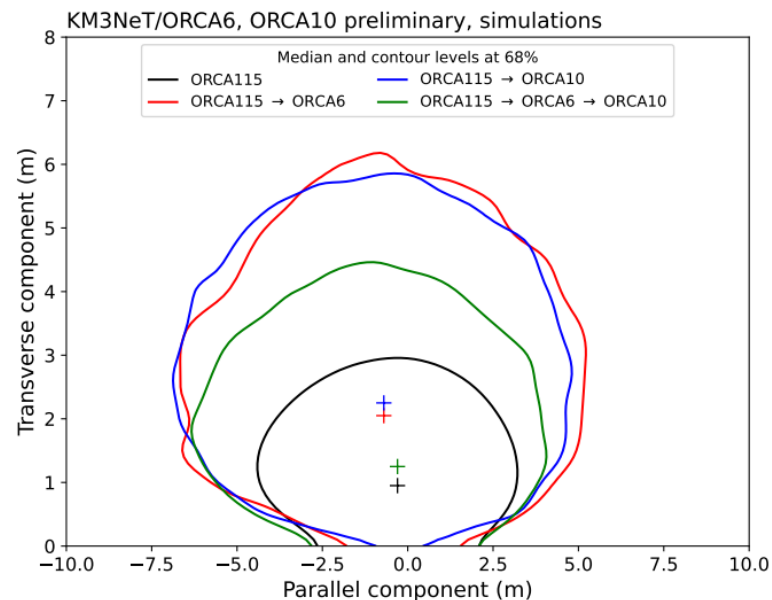


From big to small...

ORCA115 → ORCA6, ORCA10, etc.

...and vice versa

ORCA115 → ORCA6 → ORCA10 → etc.

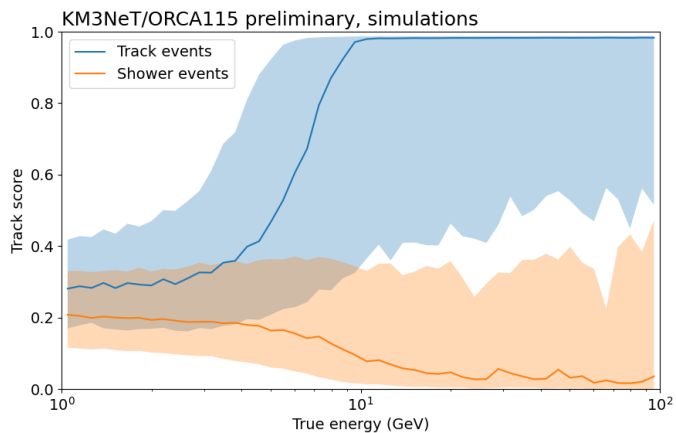


We need to propagate the knowledge between detectors!

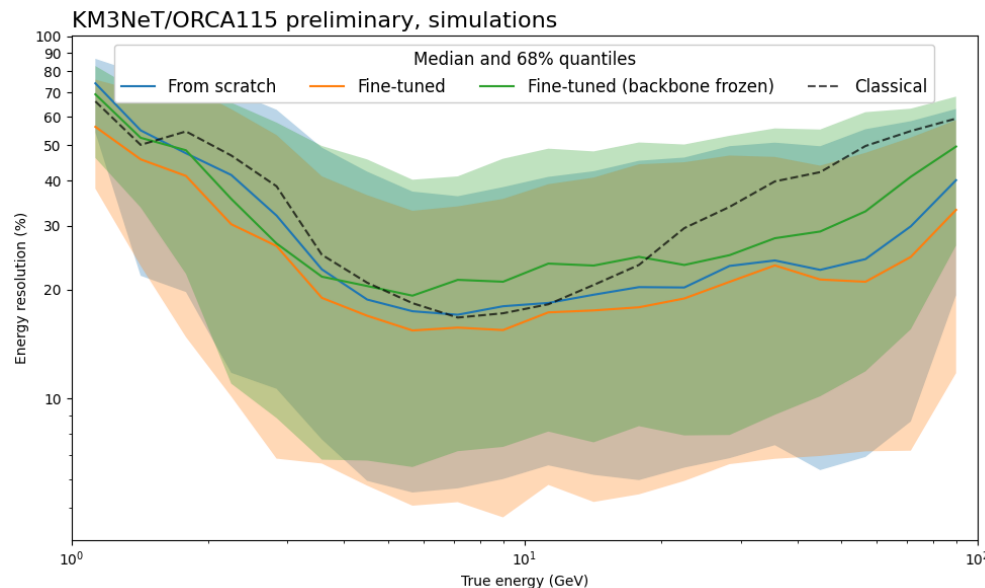
Classification to energy reconstruction

- A model that can handle multiple tasks
- A dataset 1 unrelated to dataset 2 (different detectors or water properties or atmospheric muons), helps a model into performing another task and makes it more robust

Multi-task study
ORCA115 dataset 1: track-shower
ORCA115 dataset 2: energy
850k tracks & 850k showers each



Track-score in function of neutrino energy in KM3NeT/ORCA115 for **dataset 1**

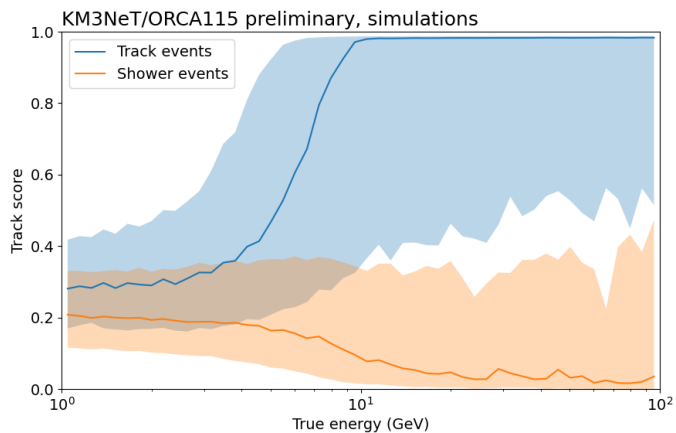


Energy resolution in function of neutrino energy in KM3NeT/ORCA115 for tracks from **dataset 2**

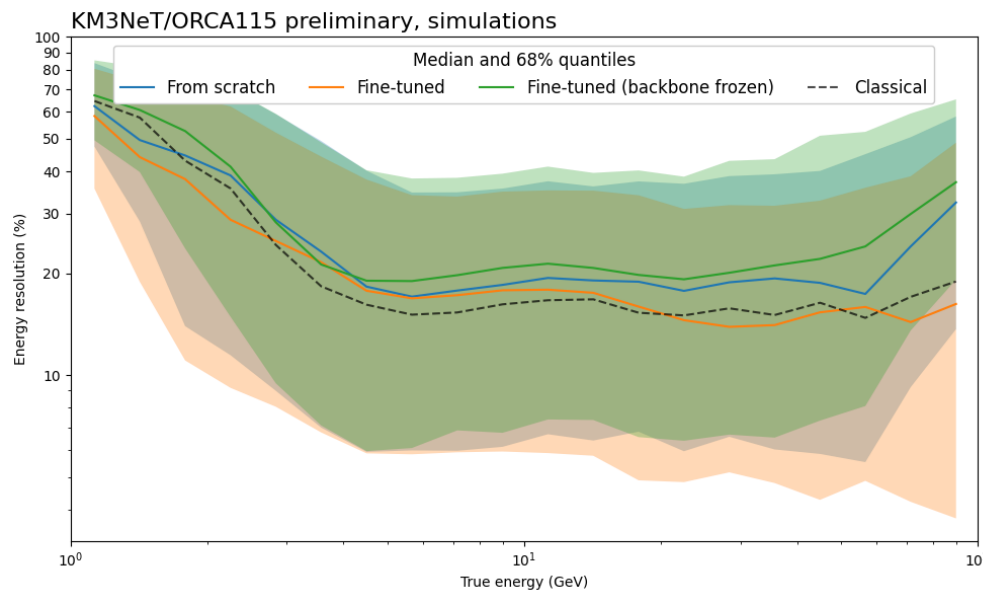
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Track-score in function of neutrino energy in KM3NeT/ORCA115 for **dataset 1**

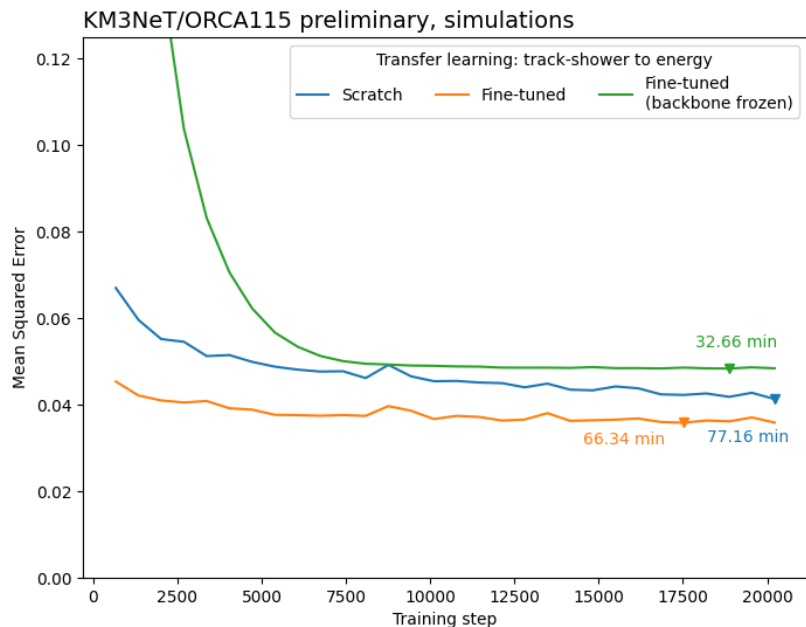


Energy resolution in function of neutrino energy in KM3NeT/ORCA115 for showers from **dataset 2**

Classification to energy reconstruction

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Fine-tuned model shows **faster convergence and efficiency**.

Freezing the backbone has a **trade-off** between training speed-up and accuracy → suboptimal feature representation

Overall, the three cases achieve show improvements with respect to classical reconstruction methods.

Transfer Learning in multiple-detectors

- Transformers are particularly effective to deal with small detectors and very limited data
- Further optimization is needed in vertex reconstruction

Transfer Learning for multi-task

- Speeds up training and boosts model robustness
- Leverages knowledge from different tasks

The road ahead

- **From simulations to data:** ensure consistency and accuracy when transitioning to real detector data
- **Robustness tests & uncertainties:** validate model reliability across different conditions and detectors
- Estimate improvements as the detector grows to optimize **scalability**
- Develop common benchmark with state-of-the-art models
- Implement any deep learning reconstruction in the official data processing pipeline
- Start testing generative models with neutrino telescope data

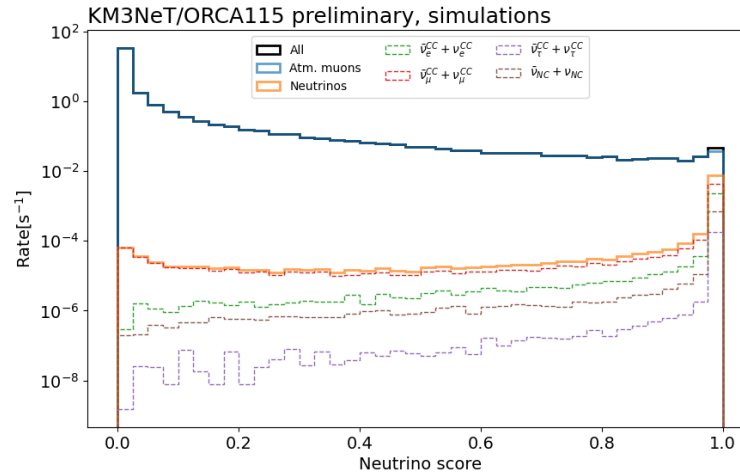
Motivation: the transformer is a language model

- KM3NeT/ORCA115 is the final detector, having all the possible neutrino physics encapsulated
- We can think of other configurations as similar languages to learn
- The information about KM3NeT/ORCA115 is used to understand our current detector

DL classification
Neutrino vs Background

DL classification
Track-like vs Shower-like

Track and shower
reconstruction



Event rate for neutrino score (0 for atmospheric muons, 1 for neutrinos).

Purpose: reject background data (atm. muon) from neutrino signal.

Atmospheric muons are more energetic, having their starting & ending points in most of the cases, out of the fiducial volume.

The model easily isolates **neutrino events** as they are mostly **fully contained** in the detector.

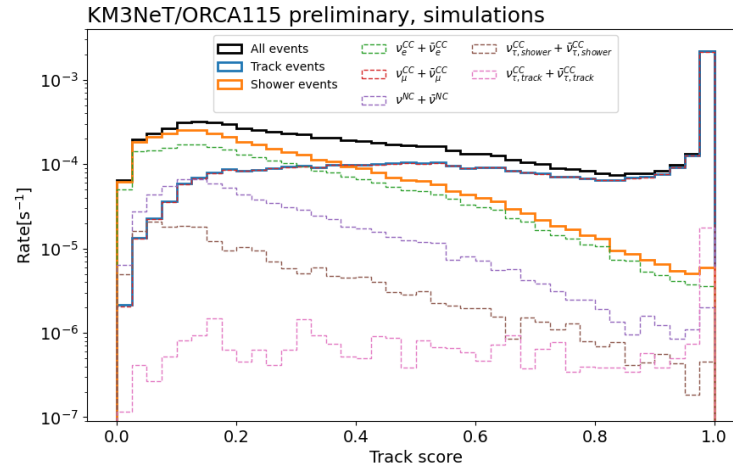
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DL classification
Neutrino vs Background

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Track-like vs Shower-like

Track and shower
reconstruction



Event rate for track score (0 for showers, 1 for tracks) for 1-100 GeV atmospheric neutrinos.

Purpose: separate the two neutrino event topologies, track-like and shower-like.

Enough separation power below 10 GeV (AUROC = 0.82)

High separation power above 10 GeV (AUROC = 0.91).

Low energy events do not contain enough pulses to properly separate these two categories

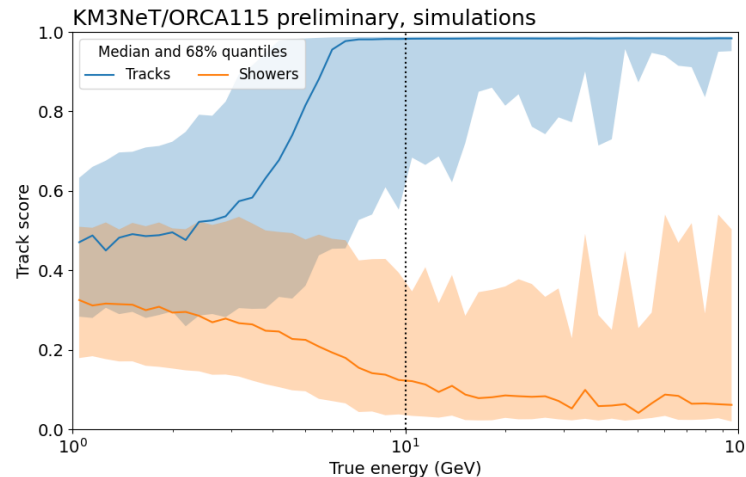
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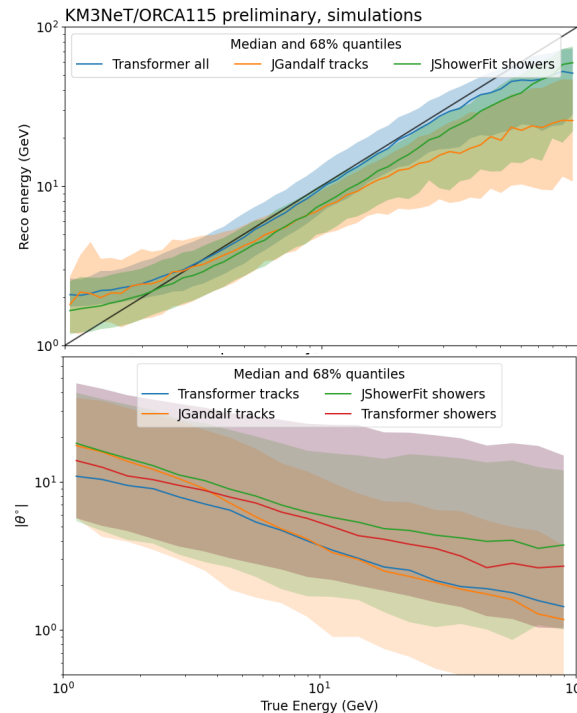
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DL classification
Neutrino vs Background

DL classification
Track-like vs Shower-like

Track and shower
reconstruction



True and reconstructed neutrino energy and zenith angle
Resolution for 1-100 GeV atmospheric neutrinos.

Purpose: reconstruct neutrino energy and neutrino direction.

Reconstruction done simultaneously for both track-like and shower-like events.

Saturation at high energies due to event containment.

Underestimation at low energies due to limited number of pulses.