# Gravitational Waves inspiral tests of General Relativity in the framework of the Einstein Telescope

Alessandro Agapito (Centre de Physique Théorique, Cosmology group) PhD supervisor: Prof. Michele Mancarella (Aix-Marseille universitè)

On behalf of:

Mr. Francesco Crescimbeni (Sapienza Università di Roma) Prof. Andrea Maselli (Gran Sasso Science Institute) Prof. Paolo Pani (Sapienza Università di Roma)









# amU Prospects for the Einstein Telescope

Theoretical and astrophysical implications

- $\Rightarrow$  **Astrophysics**: Black Holes (BHs) properties and evolution
- ⇒ Fundamental physics: Tests of General Relativity (GR)



To better investigate its capabilities we need a **Parameter Estimation** (PE) study

### **Parameter estimation for coalescing binary systems** Bayesian inference

 $\Rightarrow$  Let's assume our time-domain Gravitational Wave (GW) signal s(t) as:

s(t) = h(t) + n(t)

 $\Rightarrow$  Once s(t) is detected, we want to *infer* statistical information about the physical parameters  $\vec{\theta}$  (e.g.  $M = m_1 + m_2, \chi_i$ ) related to the GW sources, such as Binary Black Hole (BBH):

 $p(ec{ heta}|s) \propto \mathcal{L}(s|ec{ heta})\pi(ec{ heta})$ 

The **posterior**  $p(\vec{\theta}|s)$  must be stochastically sampled (e.g. MCMC methods)

The only computationally feasible way of performing PE on large populations ( $\sim 10^5$  events/yr) is based on the **Fisher Information Matrix** (FIM) approach

M. Branchesi +, JCAP, 2023, M. Maggiore +, JCAP, 2020

# amU Fisher information matrix

Approximations in the context of Bayesian analysis

 $\Rightarrow$  By writing down the likelihood  $\mathcal{L}(s|\vec{\theta})$ , we implicitly assume a **noise model**:

$$\log \mathcal{L}(s|\vec{\theta}) \propto -\frac{1}{2} \langle n|n \rangle = -\frac{1}{2} \langle s - h(\vec{\theta})|s - h(\vec{\theta}) \rangle$$

at fixed parameters  $\vec{\theta},$  and compute the FIM in the following way:

$$\Gamma_{ij} = \langle h_i | h_j 
angle \qquad,\quad h_i = \partial_i h |_{ec{ heta} = ec{ heta}_0}$$

Under the **large SNR limit**, a **stationary Gaussian noise** and a **flat prior**, the *inverse of* the FIM  $(\Gamma^{-1})$  can be approximated to the covariance matrix of the Bayesian posterior:

$$p(ec{ heta}|s) \propto \mathcal{L}(s|ec{ heta})\pi(ec{ heta}) \propto expigg[-rac{1}{2} \mathbf{\Gamma}_{ij} \,\delta heta^i\delta heta^jigg] igg| \quad, \quad \delta heta^i = heta^i - heta^i_0$$

M. Vallisneri, Phys. Rev. D, 2008

# amU Tests of GR: model-agnostic deviations

to the inspiral part of the GW phase predicted by GR

 $\Rightarrow$  The **frequency-domain waveform models**, during the *inspiral phase*, can be given as:

$$\tilde{h}(f) = A(f)e^{i\Phi_{ins}(f)}$$

in which  $\Phi_{ins}(f)$  is treated within the *Post-Newtonian (PN)* framework up to a certain *n*PN order:

$$\mathcal{O}\left[\left(\frac{\nu}{c}\right)^{2n}\right] = \mathcal{O}\left[\left(\frac{\pi GMf}{c^3}\right)^{2n/3}\right]$$

Our main aim is to introduce and constrain a **model-agnostic deviation**  $\delta \Phi(f)$ in the *inspiral part of the phase*  $\Phi_{ins}(f)$ :

 $\Phi_{ins}(f) \rightarrow \Phi_{ins}(f) + \boldsymbol{\delta \Phi(f)}$ 

N.Yunes +, Phys. Rev. D, 2016

# **Method: Adopt GWFISH to estimate errors on GW signals**

 $\Rightarrow$  Under the FIM formalism, we can easily **forecast the PE capabilities** (e.g. constraining model-agnostic  $\delta\Phi$ ) of future generation detectors

#### Input: Binary parameters

- $m_i, \chi_i, d_L, \dots (i = 1, 2)$
- GW models based on GR
- Detector type (e.g. ET, LIGO)
- New injection of a **phase** deviation through  $\delta\Phi$



# **Output: Statistical errors** $\sigma$ **by detector noise**

- on BBH parameters
- on **GR deviations**,  $\sigma_{\delta \Phi} \neq 0$  represents our statistical constrain

# amU Model-agnostic tests of the multipolar structure

arising with quadratic and cubic spin terms in the GW modified inspiral phase

We introduce **model-agnostic deviations** in the dominant spin-induced *quadrupole* moment scalar  $M_2 = -\kappa m^3 \chi^2$  through:

$$\kappa_i^{GR} = 1 \rightarrow \kappa_i = 1 + \delta \kappa_i$$

for each component i = 1, 2 of the coalescing binary

 $\Rightarrow$  We want to constrain the symmetric combination  $\delta \kappa_s = \frac{\delta \kappa_1 + \delta \kappa_2}{2}$  entering the inspiral part of the GW modified phase:

$$\delta \Phi = \delta \Phi(\pmb{\delta \kappa_s})$$

and test the Kerr BHs multipolar structure predicted by 'no-hair theorems'

N.V. Krishnendu +, 2019

# amU Results: statistical errors on different simulated events

Constraining quadrupolar deviations entering the GW modified inspiral phase



ET constraints can improve by more than an order of magnitude compared to future LVK

# amU Model-agnostic tests of tidal effects

altering the inspiral part of the GW phase starting at 5PN

We introduce an inspiral phase deviation produced by possible tidal effects:

$$\delta\Phi(f) = -rac{117}{256\eta} \mathbf{\Lambda} \left(rac{\pi GMf}{c^3}
ight)^{5/3} \hspace{0.5cm}, \hspace{0.5cm} \eta = rac{m_1 m_2}{M^2}$$

where  $\Lambda$  is the weighted tidal deformability of the compact binary

 $\Rightarrow We want to constrain \Lambda and possible deviations$ (e.g exotic compact objects) from its GR value:

$$\Lambda^{GR} = 0$$

associated with a Kerr BH binary

M. Maggiore +, Oxford University Press, 2018

# amU Results: statistical errors on different simulated events

Constraining possible tidal deviations entering the GW modified inspiral phase



ET constraints can improve by more than an order of magnitude compared to future LVK



### **Conclusions**

- We generalized GWFISH to predict statistical errors on  $\delta\kappa_s$  and  $\Lambda$
- We have shown that **ET will improve statistical constraints** on  $\delta \kappa_s$  and  $\Lambda$  by more than an order of magnitude compared to predicted future LIGO O5
- We have tested the validity of the FIM approach making a **fully Bayesian comparison**

### **Possible outcomes**

- The investigation on possible causes of **false GR violations** (*Gupta +, 2024*)
- The implementation and test of generic priors in GWFISH (Dupletsa +, 2024)
- The development of an entire **CBC population analysis** (*Mancarella +, 2022*)

#### Thanks for the attention!



► Back-up slides

# amU Gravitational Waves: a brief introduction

Emission by Compact Binary Coalescing (CBC) systems during the inspiral phase



Inspiral phase main approximations

- Slow-motion condition
- Weak-field sources

Analytical treatment of the emitted Gravitational Wave (GW) **frequency** and **amplitude** of the two wave *polarizations*  $h_{+,\times}$ 

# Gravitational Waves: observations



M. Coleman +, Nature, 2019

We are able to measure the time-domain GW **strain** as:

$$h = h_+F_+ + h_ imes F_ imes \simeq rac{\Delta L}{L}$$

But the signal is buried in the **detector noise** affecting the *sensitivity* and *frequency bandwidth* 

# Significant improvements are expected by future third-generation interferometers such as the Einstein Telescope

## Science with Einstein Telescope Sensitivity curves

 $\rightarrow$  Each detector is composed by two interferometers, "xylophone" configuration:

### Predicted noise Amplitude Spectral Density



## Improved sensitivity

- High-frequency (HF)
- Low-frequency (LF) cryogenic
- Up to **one order** of magnitude **better** respect to predicted Advanced LIGO O5 (*C. Cahillane et al. Galaxies, 2022*)

Noise ASD of a **single nested detector**, but we have more than one...

## Science with Einstein Telescope Detector geometries

→ Two possible underground detector networks, **triangular** *vs* **separated 2L-shaped**:

#### Scheme of the two geometries



# Triangular configuration

- "Null-stream"
- $SNR \propto 1.5 L$

# 2L-shaped configuration

- Parallel vs misalligned
- $SNR \propto 1.4 L$

# **EXAMPLE TERMS** Fisher Information Matrix

 $\rightarrow$  Let's assume our **time-domain GW signal** s(t) as:

 $s(t) = h_0(t) + n_0(t)$ 

where  $h_0(t) = h(\vec{\theta}_0, t)$  is the signal with expected parameters  $\vec{\theta}_0$  and  $n_0(t)$  is a stationary Gaussian noise  $\rightarrow$  Let's define a **weighted-noise inner product**  $\langle \cdot | \cdot \rangle$  between two time-domain signals as:

$$\langle a|b
angle = 4 \Re \int_0^\infty rac{ ilde{a}^*(f) ilde{b}(f)}{S_n(f)} df$$

where the tilde denotes the Fourier transform and  $S_n(f)$  is the one-sided noise PSD

The Fisher Information Matrix (FIM) is defined as:

$$\Gamma_{ij} = -\langle \partial_i \partial_j \log P(s|\vec{\theta}) \rangle_n \Big|_{\vec{\theta} = \vec{\theta}_0} \Big| \text{ where } \partial_i = \frac{\partial}{\partial \theta_i}$$

and  $\langle \cdot \cdot \rangle_n$  is a noise average with fixed  $\vec{\theta}$  and  $P(s|\vec{\theta})$  is the likelihood for a data realization s(t) conditioned on  $\vec{\theta}$ 



 $\rightarrow$  For each  $k^{th}$  single detector of the network we can compute the FIM and the SNR:

• 
$$\Gamma_{ij}^k = (h_i^k | h_j^k)$$
 •  $SNR_k = \sqrt{(h^k | h^k)}$ 

 $\rightarrow$  For the **entire network** of *n* detector we can compute:

• 
$$\Gamma_{ij} = \sum_{k=1}^{n} \Gamma_{ij}^{k}$$
 •  $SNR = \sqrt{\sum_{k=1}^{n} SNR_{k}^{2}}$ 

The variance  $\sigma_i^2$  of the  $i^{th}$  parameter & the sky localization area  $\Delta\Omega_{90\%}$  are:

$$\sigma_i^2 = \Gamma_{ii}^{-1} \Delta \Omega_{90\%} = -2\pi \ln\left(\frac{1}{10}\right) |\sin\theta| \sqrt{\left(\Gamma_{\theta\theta}^{-1}\right) \left(\Gamma_{\phi\phi}^{-1}\right) - \left(\Gamma_{\phi\theta}^{-1}\right)^2}$$

# **GWFISH: an overview** Flowchart of the functioning of modules and directories





$$\Phi_{ins}(x) = \phi_c - \frac{3}{128\eta} \sum_{n=0}^{7} \left[ \varphi_n + \varphi_n^{(l)} \ln \left( x^{3/2} \right) \right] x^{(n-5)/2} \quad , \quad x = \left( \frac{\pi GMf}{c^3} \right)^{2/3}$$





$$\Phi(f) = \Phi_{ins} \ \theta(f - f_{ins}) + \theta(f - f_{ins}) \ \Phi_{int} \ \theta(f - f_{int}) + \ \Phi_{MR} \ \theta(f - f_{MR})$$



### Multipolar structure of a Kerr BH Spin-induced multipolar moments

 $\Rightarrow$  In a specific class of coordinate systems called "Asymptotically Cartesian and Mass Centered" (ACMC), the metric is given by:

$$ds^{2} = -(1 - c_{00}) dt^{2} + (1 + c_{00}) dx_{i}^{2} + c_{0i} dt dx_{i}$$

where  $c_{00}$  admits a spherical harmonic decomposition in terms of the *mass multipole* moments  $M_{\ell m}$ , while  $c_{0i}$  is decomposed in terms of the *current multipole moments*  $S_{\ell m}$ .

 $\Rightarrow$  All the multipole moments of a Kerr BH can be uniquely determined by two parameters, its mass *m* and spin  $\chi$ :

$$M_{\ell}^{\rm BH} + iS_{\ell}^{\rm BH} = m^{\ell+1} \left( i\chi \right)^{\ell}$$

# amU Results: errors on multiple simulated events

Implications for possible GR deviations entering the GW modified phase

 $\Rightarrow$  **GR deviations** are detectable in  $\sigma_{\delta\lambda_s}$  and are **agnostic** to modified theories



- 5 different simulated events with the same spins ( $\chi_1 = 0, 5, \chi_2 = 0, 4$ ) mass ratio ( $m_1/m_2 = 3$ ) and luminosity distance ( $d_L = 400 \ Mpc$ )
- ET property of **reducing the correlations** among parameters

#### ET constraints can improve by more than an order of magnitude compared to future LVK

### **Tidal properties of a Kerr BH** Weighted tidal deformability

 $\Rightarrow$  The linear response of vacuum Kerr BHs to external static perturbations is predicted to be:  $\tilde{\lambda}_{\ell}^{BH} = 0$ ,  $M_{ij} = -\tilde{\lambda}\mathcal{E}_{ij}$ 

where  $M_{ij}$  is the *tidal-induced quadrupole moment* and  $\mathcal{E}_{ij}$  is the *quadrupole tidal field*. Considering higher multipole contributions, the procedure can be extended to generic  $\ell \neq 2$ .

 $\Rightarrow \text{ We can define the dimensionless tidal Love numbers } k_{\ell} \propto \tilde{\lambda}_{\ell}/m^{2\ell+1}. \text{ For instance, in the Neutron Star case, } k_2 = \frac{3}{2} \frac{G\tilde{\lambda}_2}{R^5} \text{ from which we can define } \Lambda = \frac{2}{3} k_2 \left(\frac{Gm}{Rc^2}\right)^{-5}. \text{ In general, it is useful to introduce the weighted tidal deformability as:} \\ \Lambda = \frac{16}{13} \frac{(m_1 + 12m_2)m_1^4\Lambda_1 + (m_2 + 12m_1)m_2^4\Lambda_2}{(m_1 + m_2)^5}$