

A Fisher matrix code for population analysis of gravitational-wave events

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Huitième Assemblée Générale du GdR
Marseille, October 13

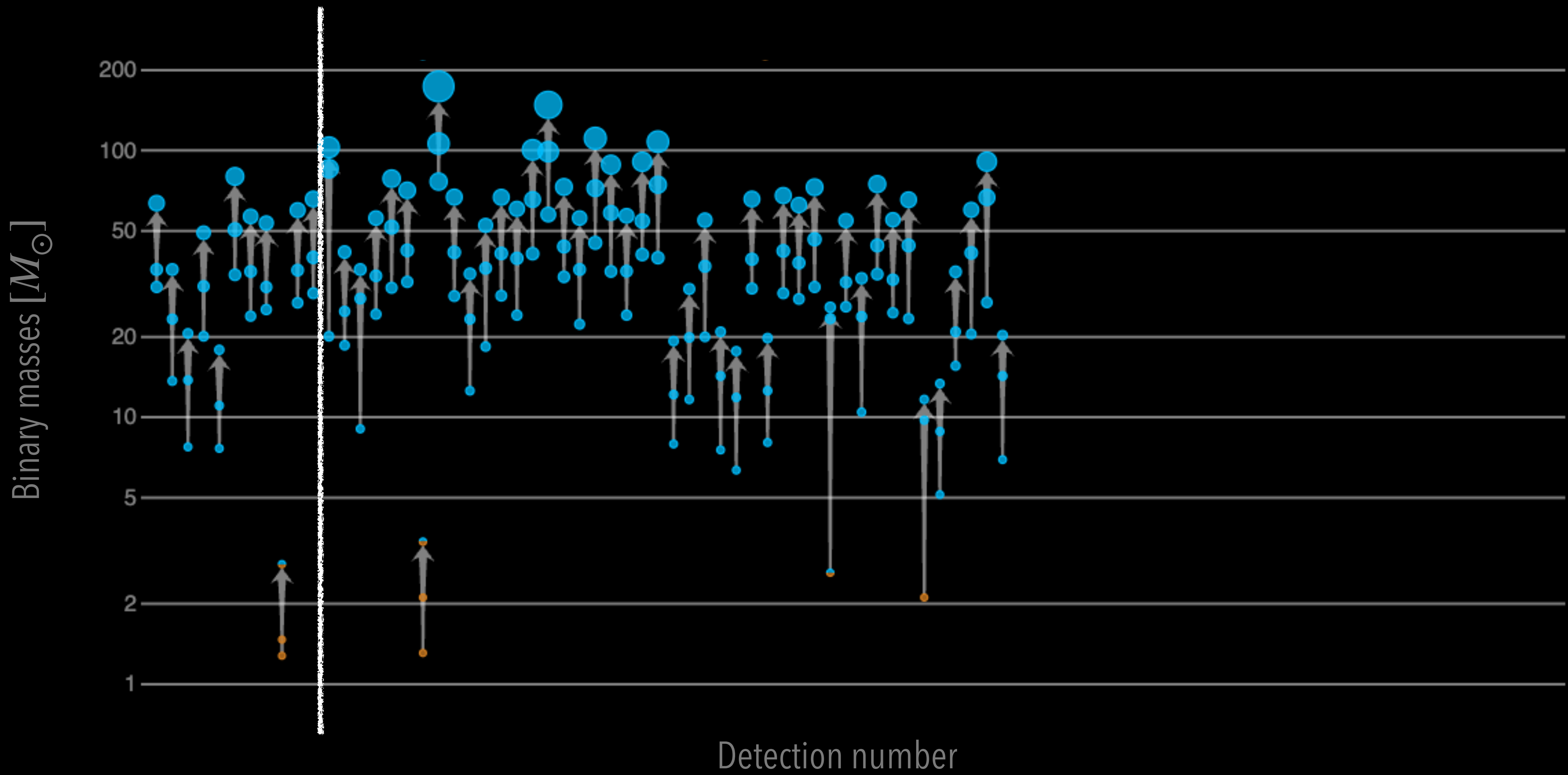
v.derenzis@campus.unimib.it

GWTC-1 (2018)



GWTC-1 (2018)

GWTC-2 (2020)

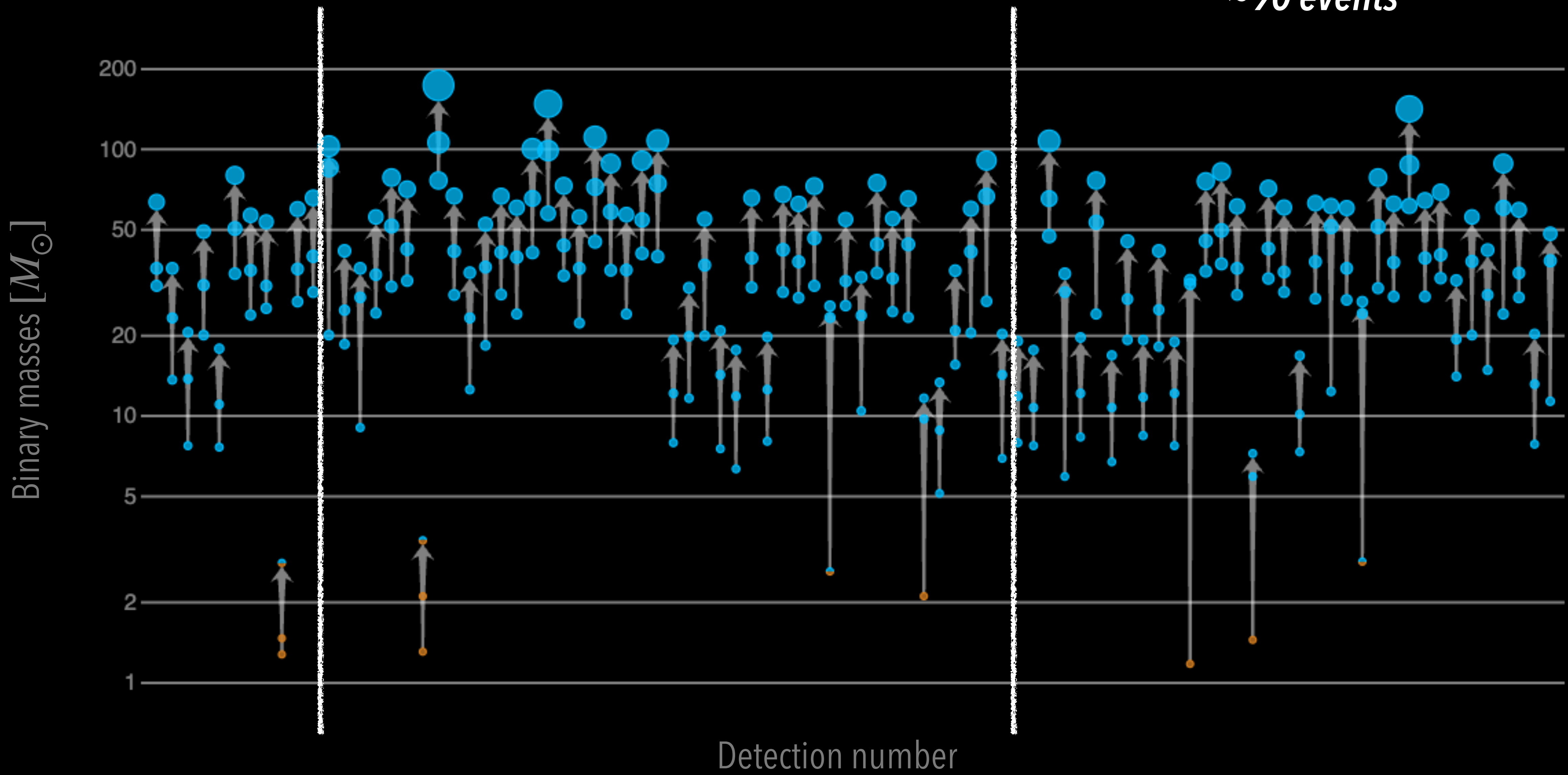


GWTC-1 (2018)

GWTC-2 (2020)

GWTC-3 (2022)

~90 events

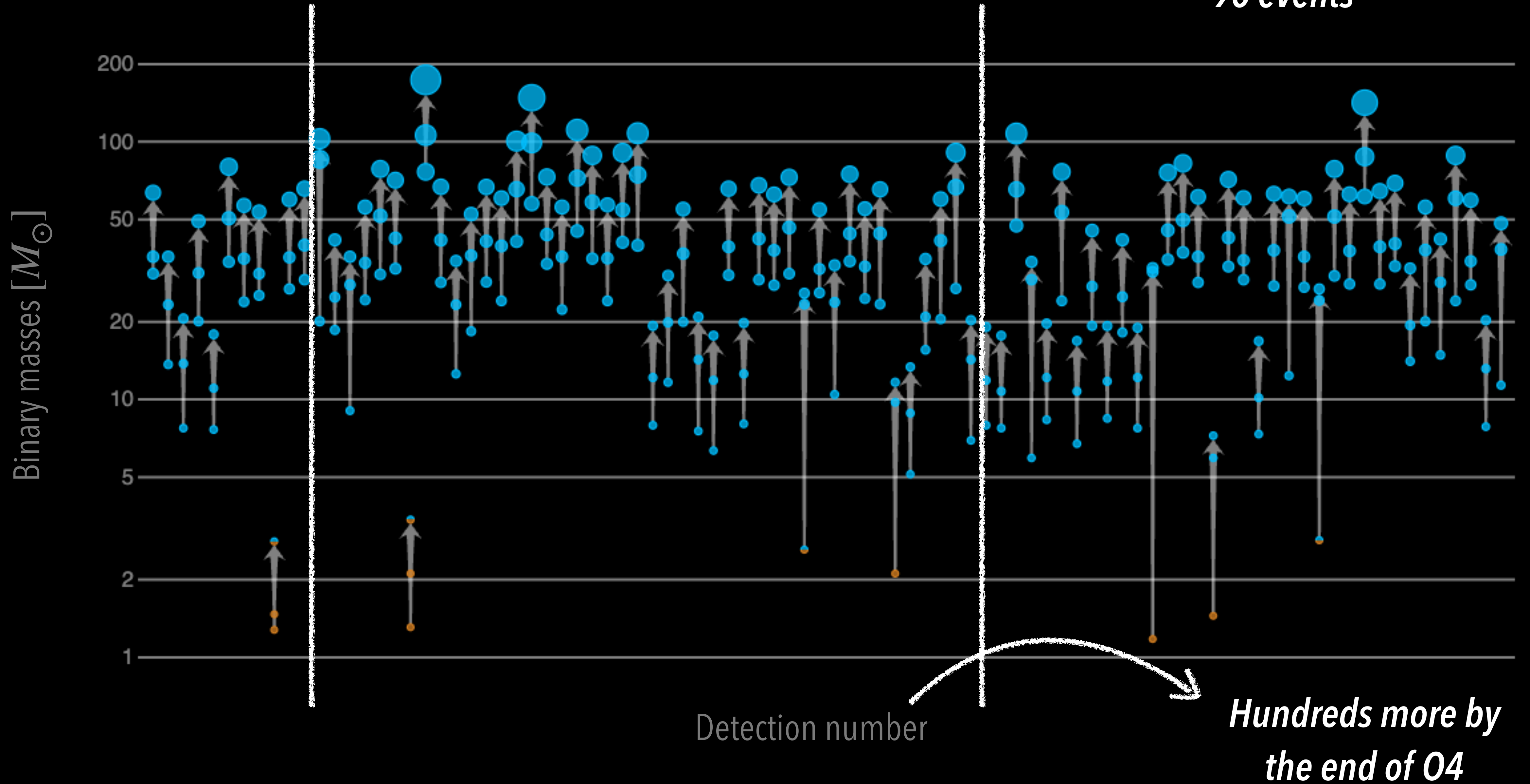


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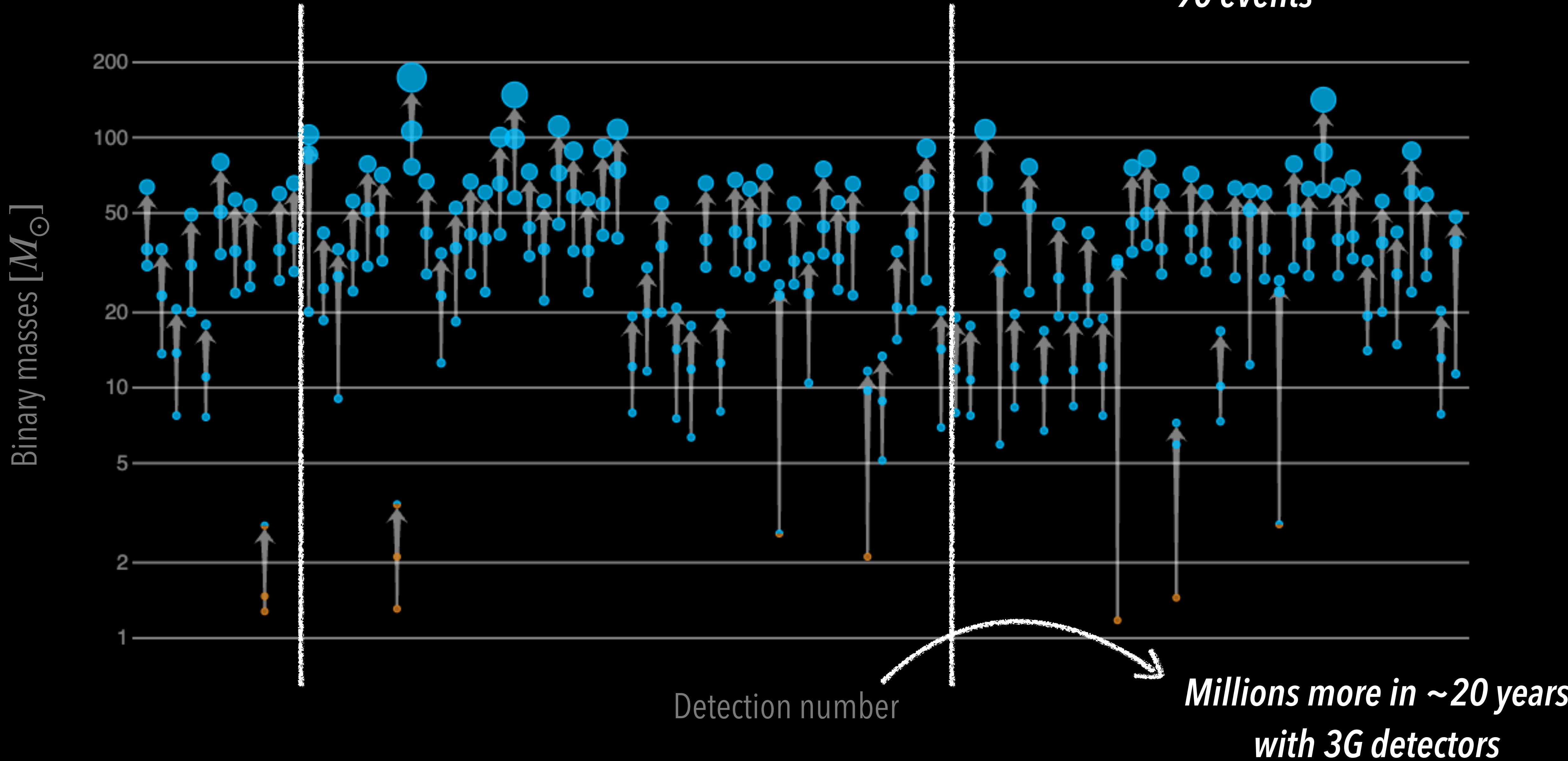


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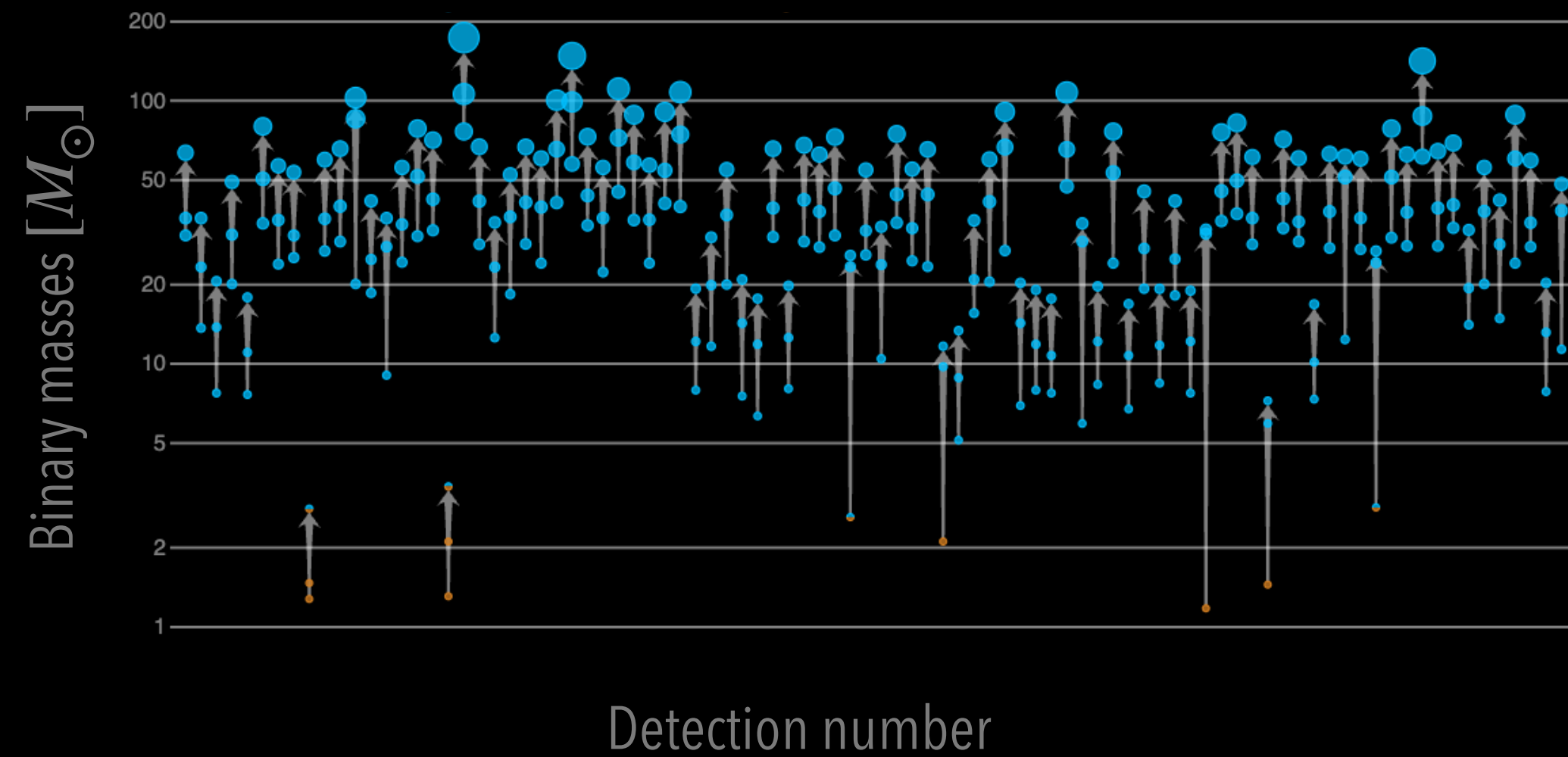
GWTC-2 (2020)

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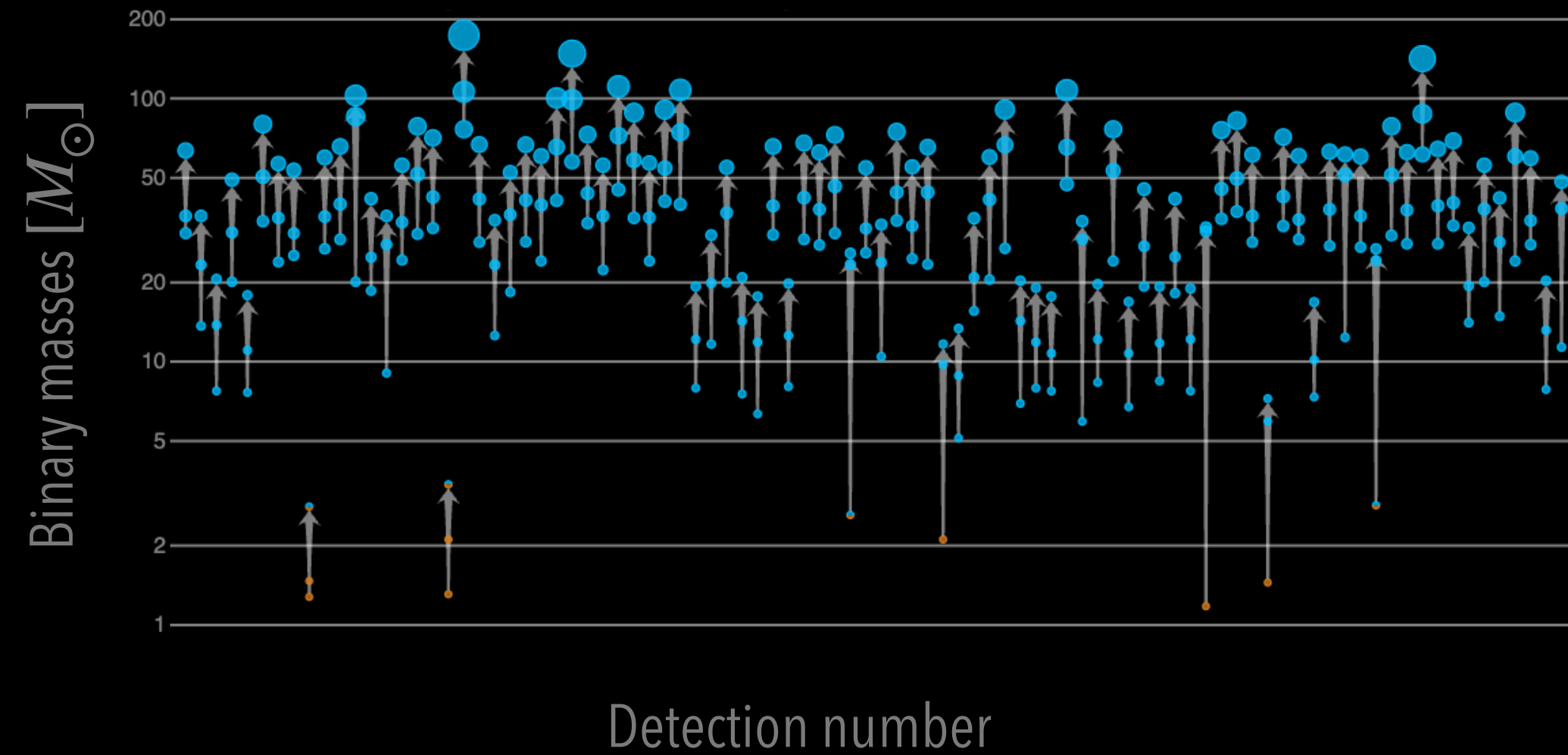


Hierarchical Bayesian analysis for population studies



- **Lowest level:**
What are the properties of **individual** GW sources?

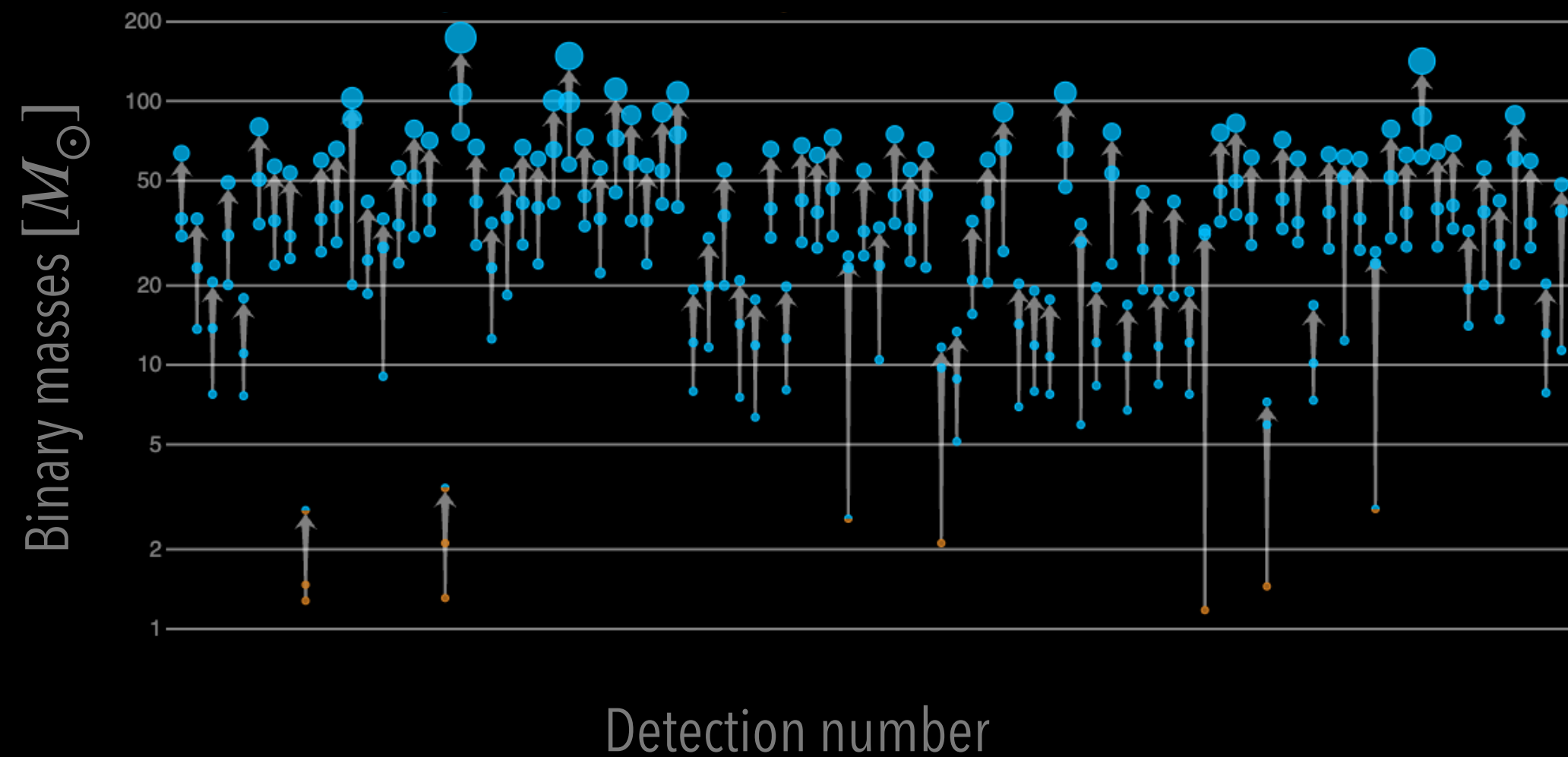
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Hierarchical Bayesian analysis for population studies



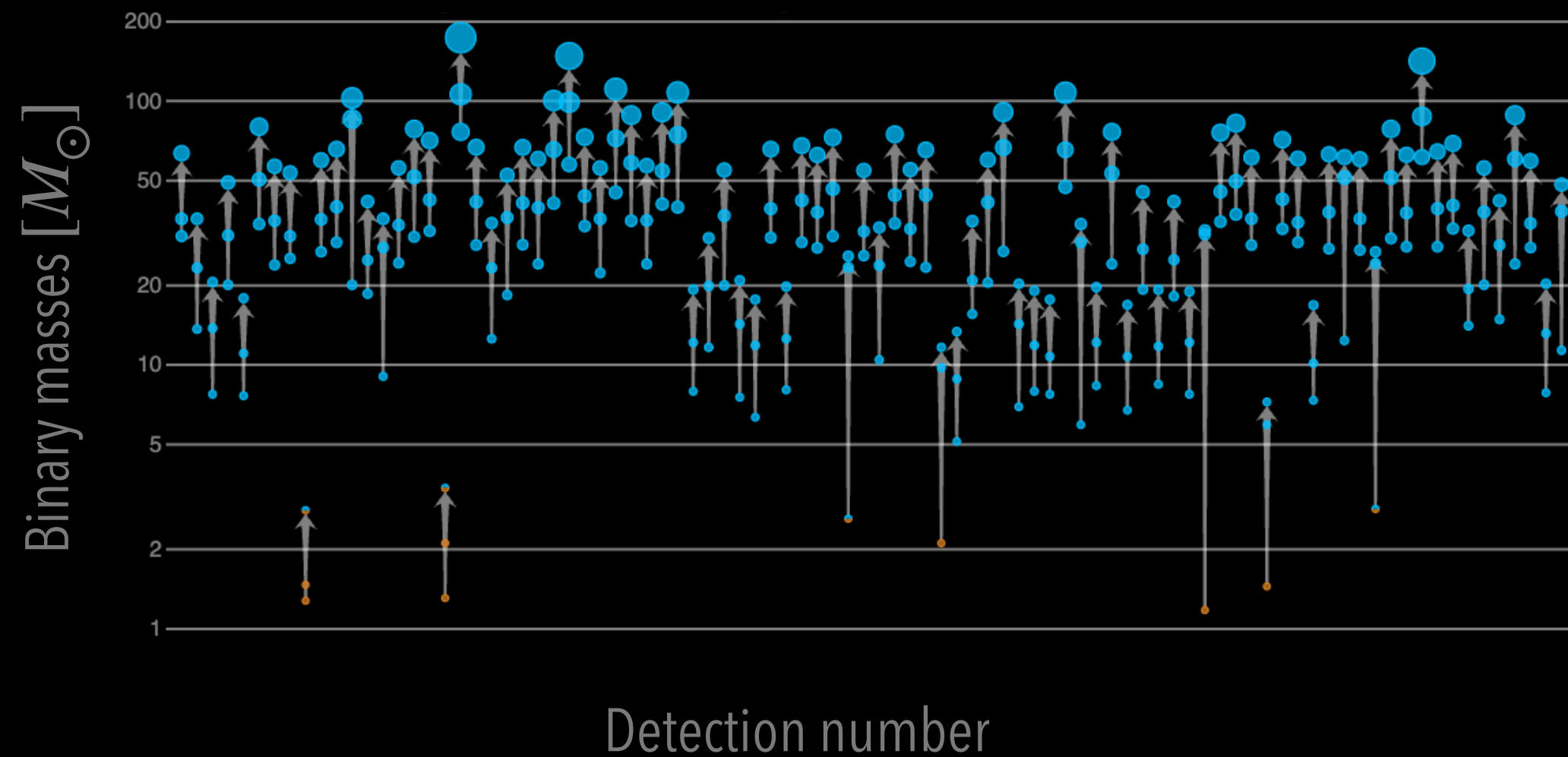
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- **Ultimate goal:** Figure out the formation pathways and population properties of compact binary systems

- how many formation channels?
- properties of each individual channel (common envelope, kicks...)
- merger rate for each channel
- many more open questions

Hierarchical Bayesian analysis for population studies



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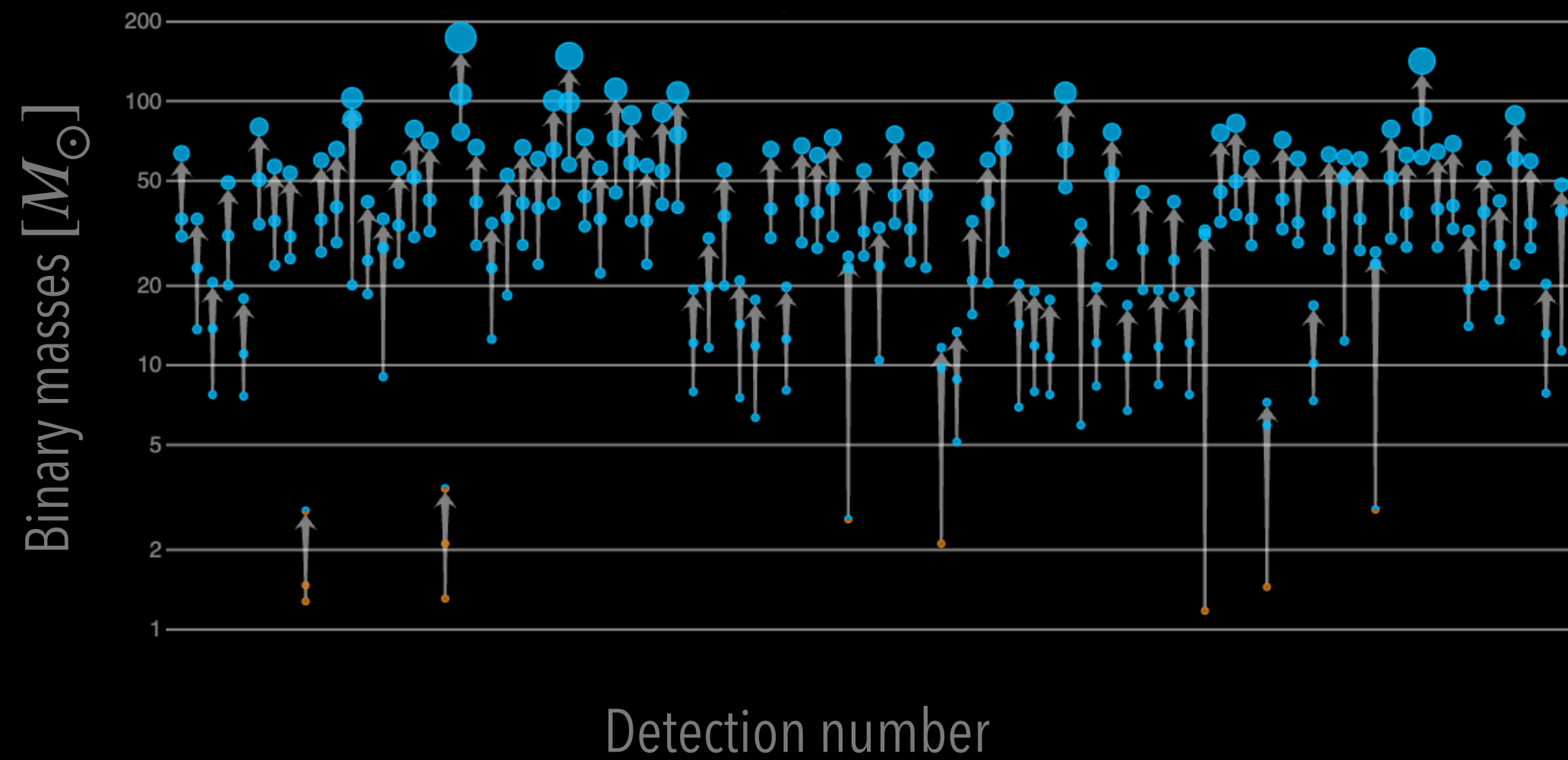
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**Hierarchical Bayesian
inference**

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Hierarchical Bayesian analysis for population studies



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$$p(\vec{\theta} | d) \propto \mathcal{L}(d | \vec{\theta}) \pi(\vec{\theta})$$

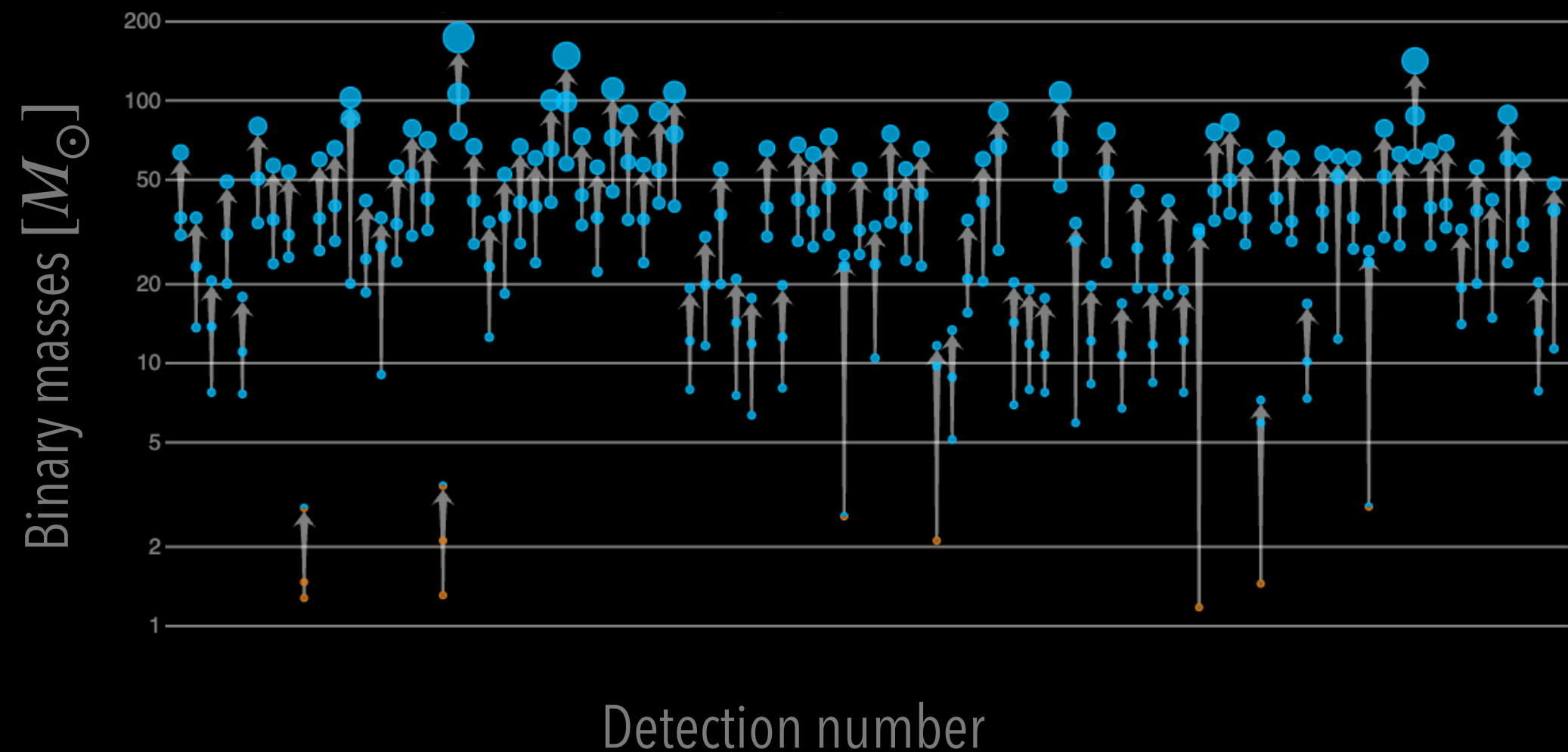
$\vec{\theta}$ = individual source parameters

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**Hierarchical Bayesian
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Hierarchical Bayesian analysis for population studies



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Single-event
likelihood

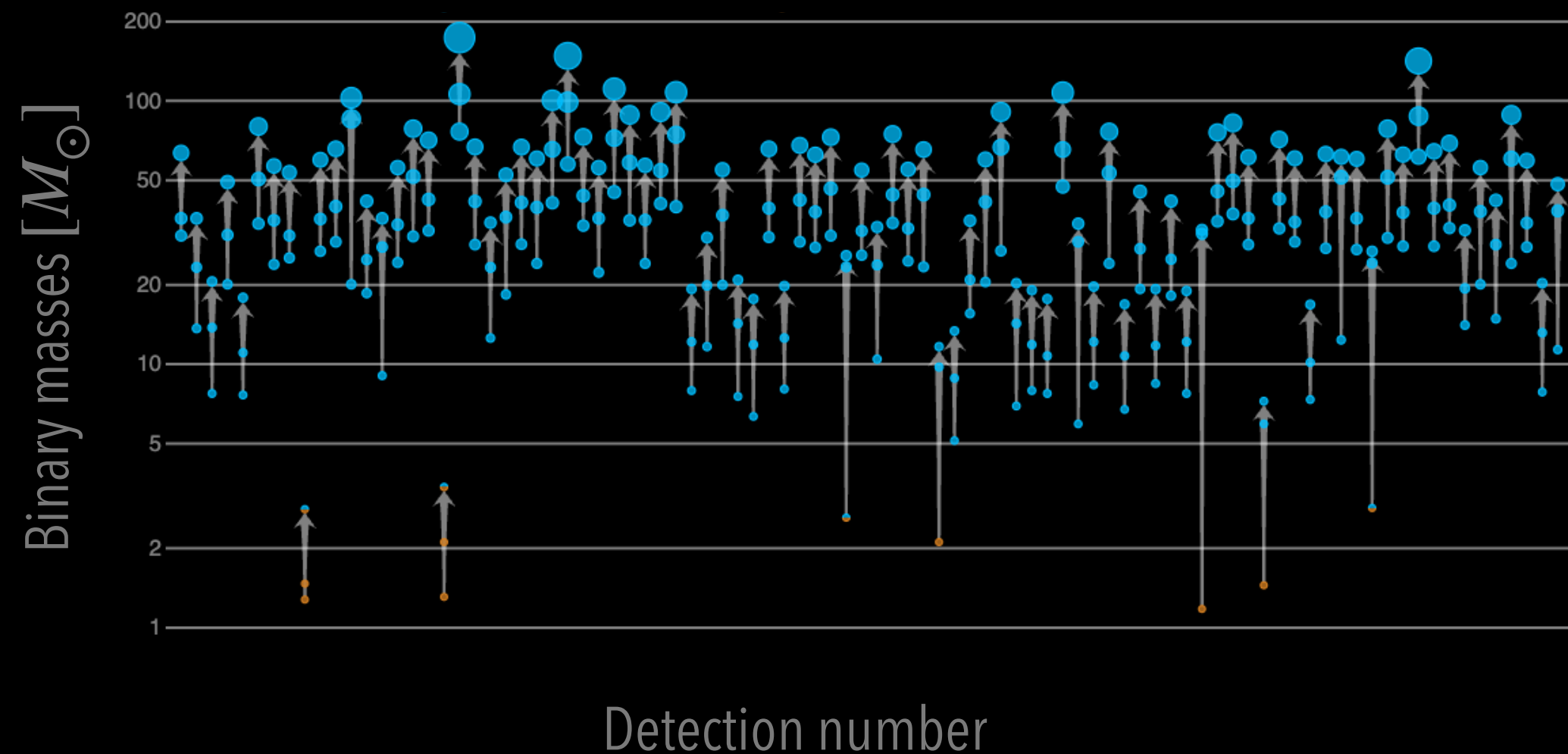
Population
model

$$p(\{d_i\} | \vec{\lambda}) = \frac{\int \mathcal{L}(d | \vec{\theta}) p(\vec{\theta} | \vec{\lambda}) d\vec{\theta}}{P_{\text{det}}(\vec{\lambda})}$$

Population Likelihood

Not all sources are
equally easy to detect

Hierarchical Bayesian analysis for population studies



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Population Likelihood

Selection effects

$$P_{\text{det}}(\vec{\lambda}) = \int P_{\text{det}}(\vec{\theta}) p(\vec{\theta} | \vec{\lambda}) d\vec{\theta}$$

Detection probability:

$$P_{\text{det}}(\vec{\theta}) = \int_{d > d_{\text{th}}} \mathcal{L}(d | \vec{\theta}) dd$$

Individual-event parameter estimation

- Bayesian inference codes (BILBY, lalsimulation, PyCBC, RIFT, DINGO...)

[Ashton et al, 2018]
[Henshaw et al, 2022]
[Dax et al, 2021]

- Fisher codes (GWfast, GWbench, GWfish)

[Iacovelli et al, 2022]
[Borhanian, 2021]
[Branchesi et al, 2023]

Population level parameter estimation

- Bayesian inference codes (GWpopulation, BILBY, deep learning codes, non-parametric models...)
- No fisher codes to make forecasts about the population properties that will be observed with 3G detectors



We are developing a user-friendly python code to estimate the parameters that characterize a population of GW events including selection effects

Population Fisher Matrix

$$(\Gamma_\lambda)_{ij} \equiv N_{\text{det}} [(\Gamma_{\text{I}})_{ij} + (\Gamma_{\text{II}})_{ij} + (\Gamma_{\text{III}})_{ij} + (\Gamma_{\text{IV}})_{ij} + (\Gamma_{\text{V}})_{ij}]$$

$$(\Gamma_{\text{I}})_{ij} = - \int \frac{\partial^2 \ln(p(\vec{\theta} | \vec{\lambda}) / P_{\text{det}}(\vec{\lambda}))}{\partial \lambda^i \partial \lambda^j} \frac{P_{\text{det}}(\vec{\theta})}{P_{\text{det}}(\vec{\lambda})} p(\vec{\theta} | \vec{\lambda}) d\vec{\theta}$$

$$(\Gamma_{\text{II}})_{ij} = \frac{1}{2} \int \frac{\partial^2 \ln \det(\Gamma + H)}{\partial \lambda^i \partial \lambda^j} \frac{P_{\text{det}}(\vec{\theta})}{P_{\text{det}}(\vec{\lambda})} p(\vec{\theta} | \vec{\lambda}) d\vec{\theta}$$

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1. Population model: $p(\vec{\theta} | \vec{\lambda})$

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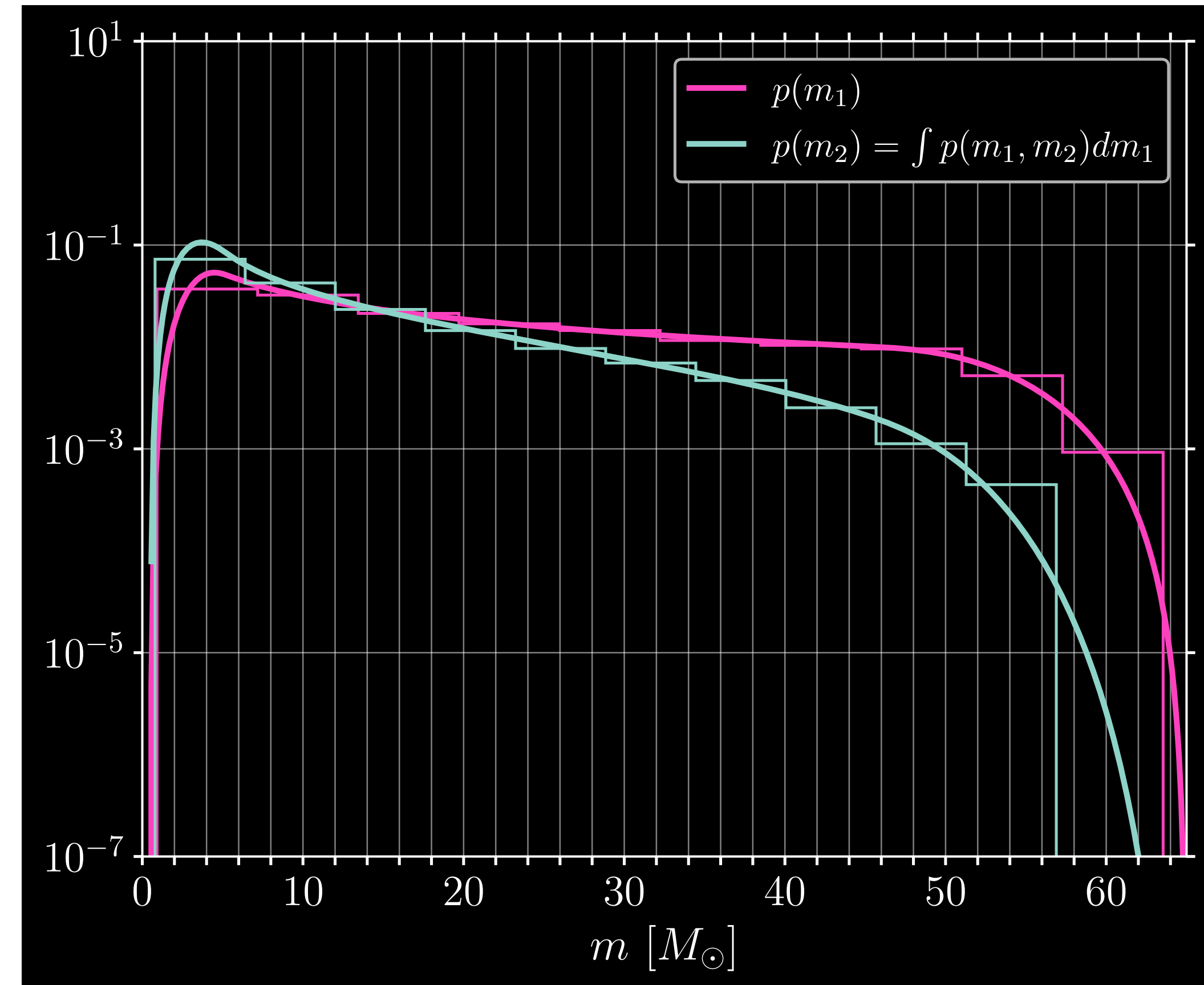
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1.

Masses: Power law?



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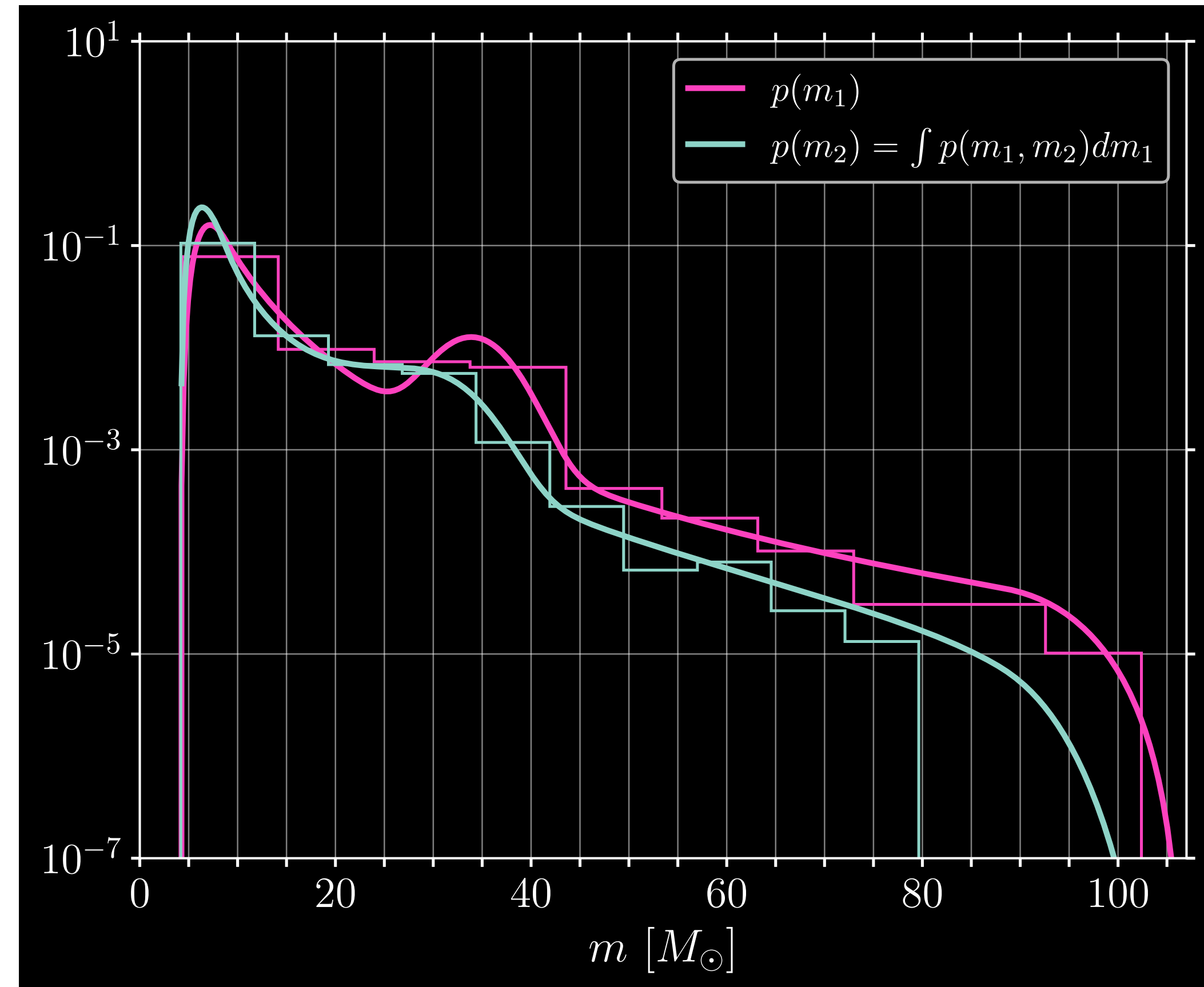
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1.

Masses: power law + peak?



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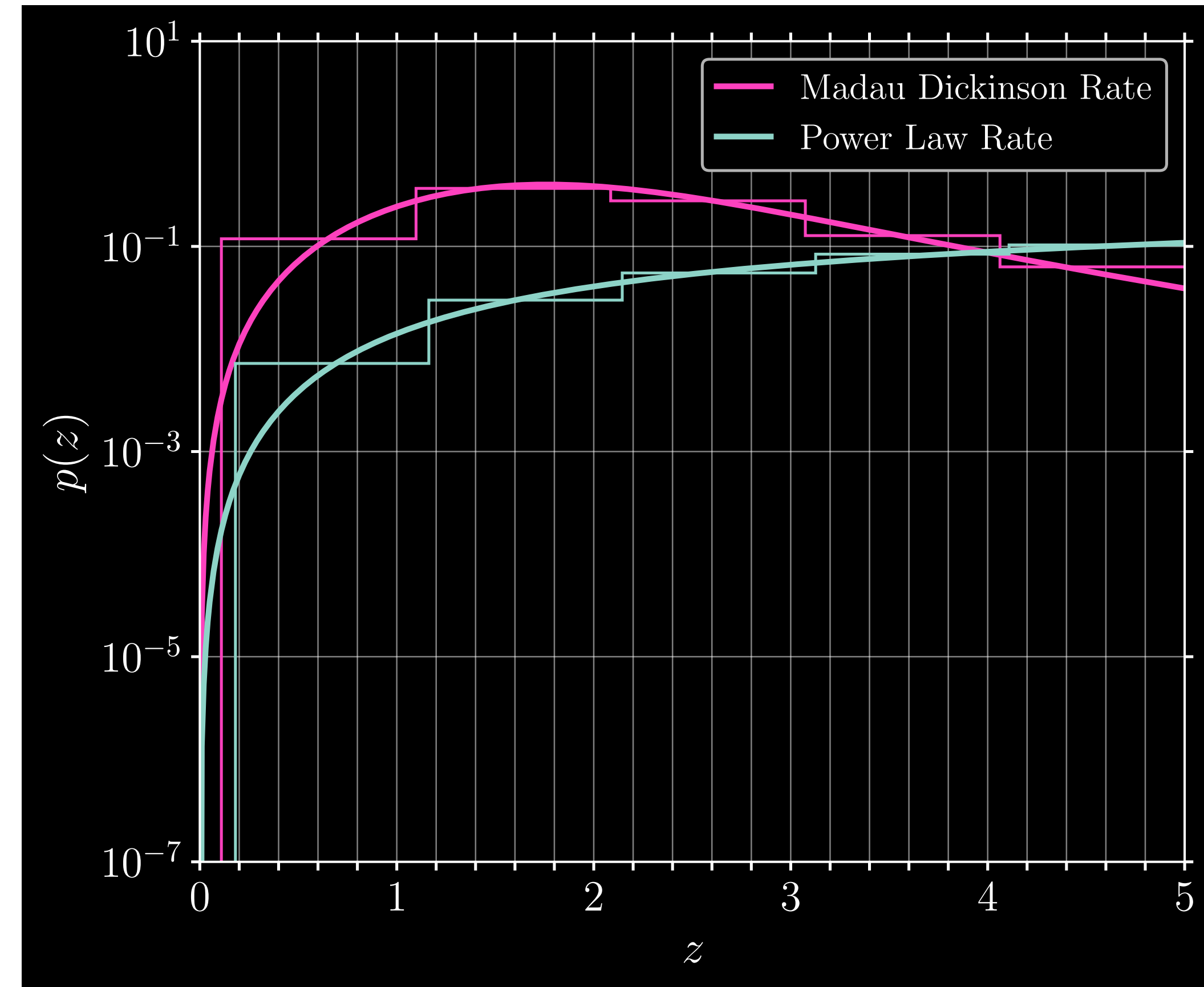
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1.

Redshift:

PL/Madau Dickinson?



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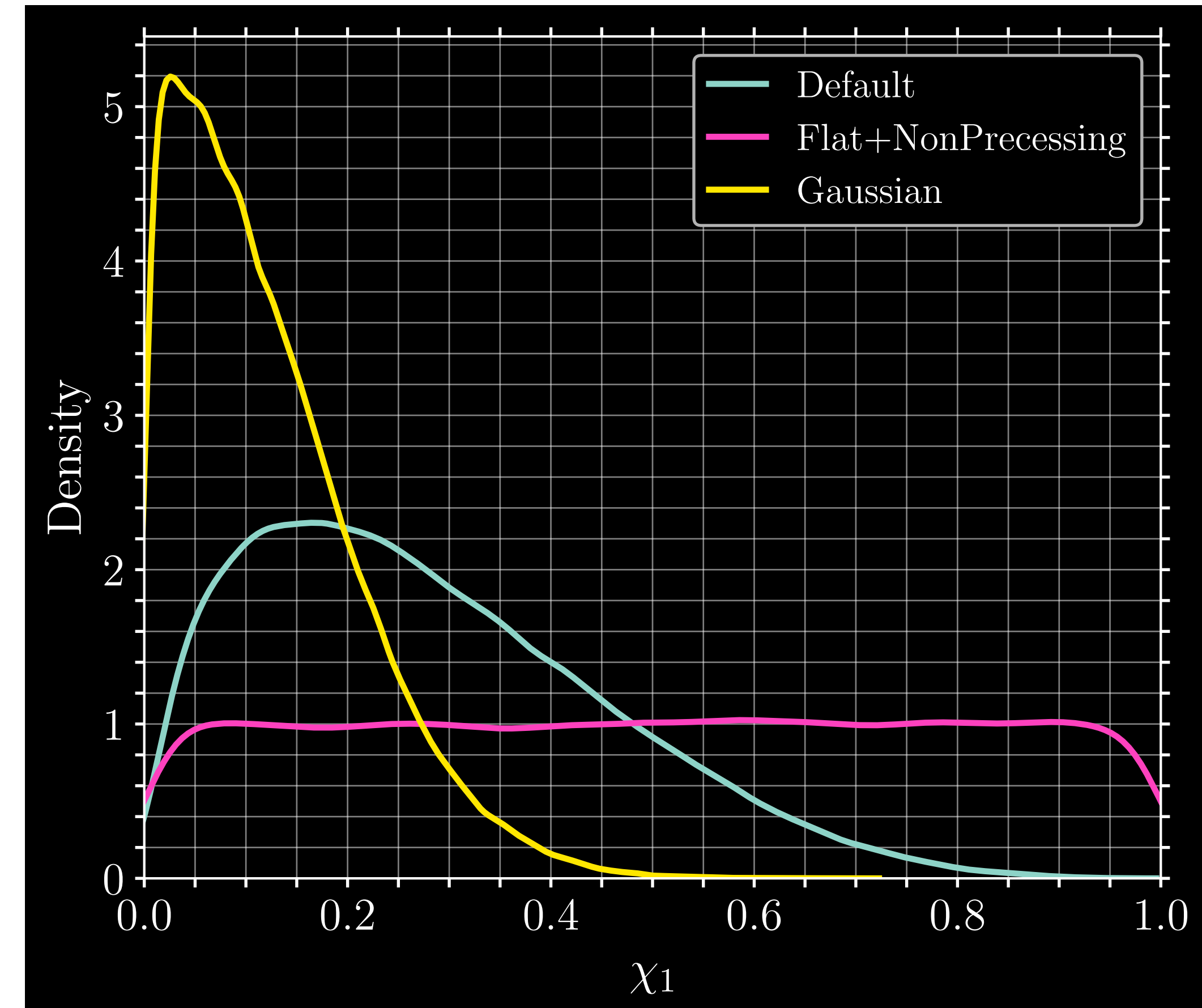
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1.

Spins:
Default/Flat, Gaussian?



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Whatever functional form
you like!
(as long as it is differentiable)

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1. Population model: $p(\vec{\theta} | \vec{\lambda})$

with its first and second derivatives

$$P_i = \frac{\partial \ln p(\vec{\theta} | \vec{\lambda})}{\partial \theta^i}$$

$$H_{ij} = - \frac{\partial^2 \ln p(\vec{\theta} | \vec{\lambda})}{\partial \theta^i \partial \theta^j}$$

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1. Population model: $p(\vec{\theta} | \vec{\lambda})$

2. Selection effects:
 $P_{\text{det}}(\vec{\lambda}) = \int P_{\text{det}}(\vec{\theta}) p(\theta | \lambda) d\vec{\theta}$

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$$(\Gamma_{\text{III}})_{ij} = - \frac{1}{2} \int \frac{\partial^2}{\partial \lambda^i \partial \lambda^j} \left[(\Gamma + H)_{kl}^{-1} \right] \Gamma_{kl} \frac{p(\vec{\theta} | \vec{\lambda})}{P_{\text{det}}(\vec{\lambda})} d\vec{\theta}$$

$$(\Gamma_{\text{IV}})_{ij} = - \int \frac{\partial^2}{\partial \lambda^i \partial \lambda^j} \left[P_k (\Gamma + H)_{kl}^{-1} \right] D_l \frac{p(\vec{\theta} | \vec{\lambda})}{P_{\text{det}}(\vec{\lambda})} d\vec{\theta}$$

$$(\Gamma_{\text{V}})_{ij} = - \frac{1}{2} \int \frac{\partial^2}{\partial \lambda^i \partial \lambda^j} \left[P_k (\Gamma + H)_{kl}^{-1} P_l \right] \frac{P_{\text{det}}(\vec{\theta})}{P_{\text{det}}(\vec{\lambda})} p(\vec{\theta} | \vec{\lambda})$$

1. Population model: $p(\vec{\theta} | \vec{\lambda})$

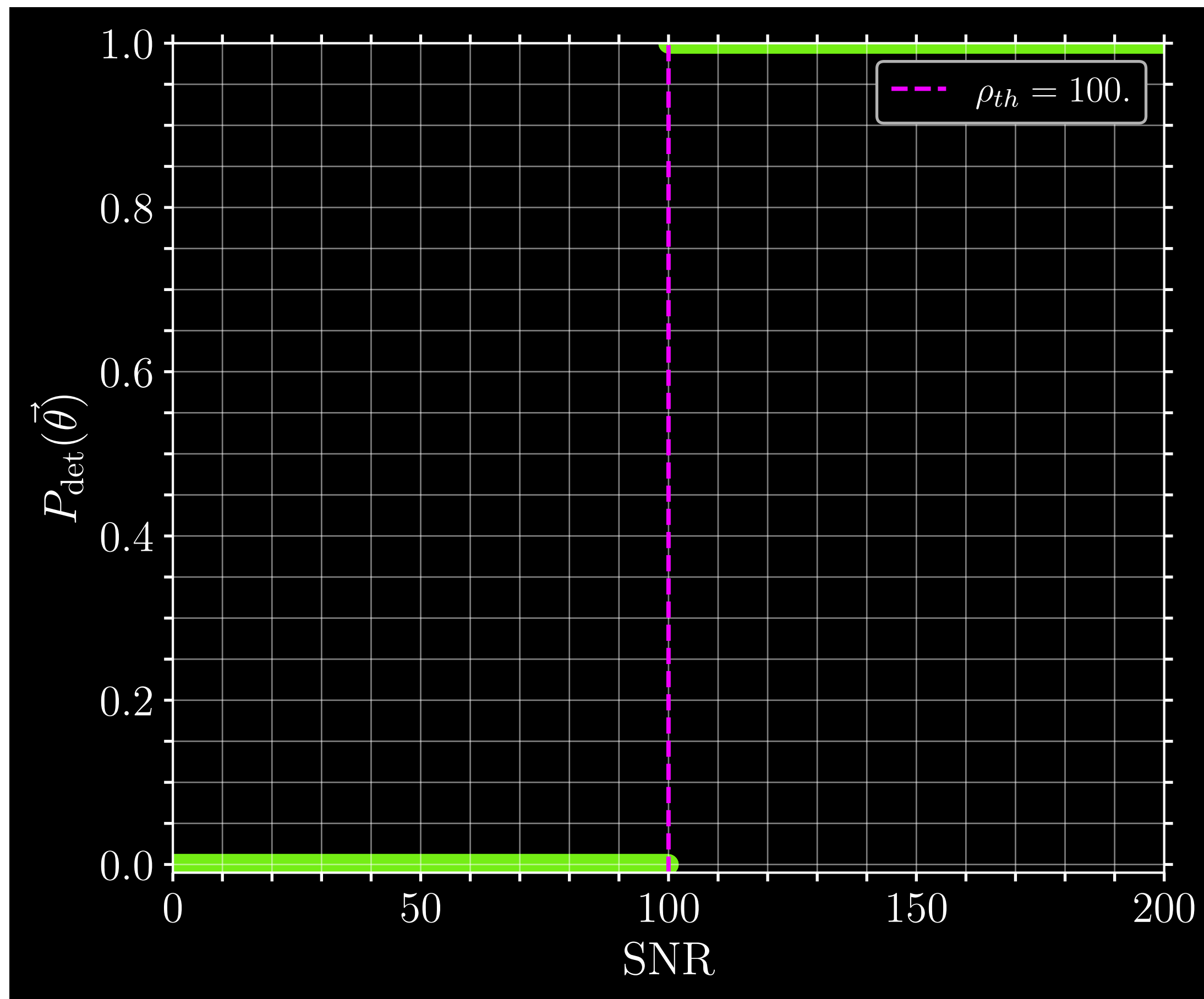
2. Selection effects:
 $P_{\text{det}}(\vec{\lambda}) = \int P_{\text{det}}(\vec{\theta}) p(\theta | \lambda) d\vec{\theta}$

3. Detection probability:
 $P_{\text{det}}(\vec{\theta}) = \int_{d > d_{th}} p(d | \vec{\theta}) d\vec{\theta}$

Population Fisher Matrix

$$(\Gamma_\lambda)_{ij} \equiv N_{\text{det}} [(\Gamma_{\text{I}})_{ij} + (\Gamma_{\text{II}})_{ij} + (\Gamma_{\text{III}})_{ij} + (\Gamma_{\text{IV}})_{ij} + (\Gamma_{\text{V}})_{ij}]$$

$$P_{\text{det}}(\vec{\theta}) = \text{Heaviside function}$$



1. Population model: $p(\vec{\theta} | \vec{\lambda})$

2. Selection effects:
$$P_{\text{det}}(\vec{\lambda}) = \int P_{\text{det}}(\vec{\theta}) p(\theta | \lambda) d\vec{\theta}$$

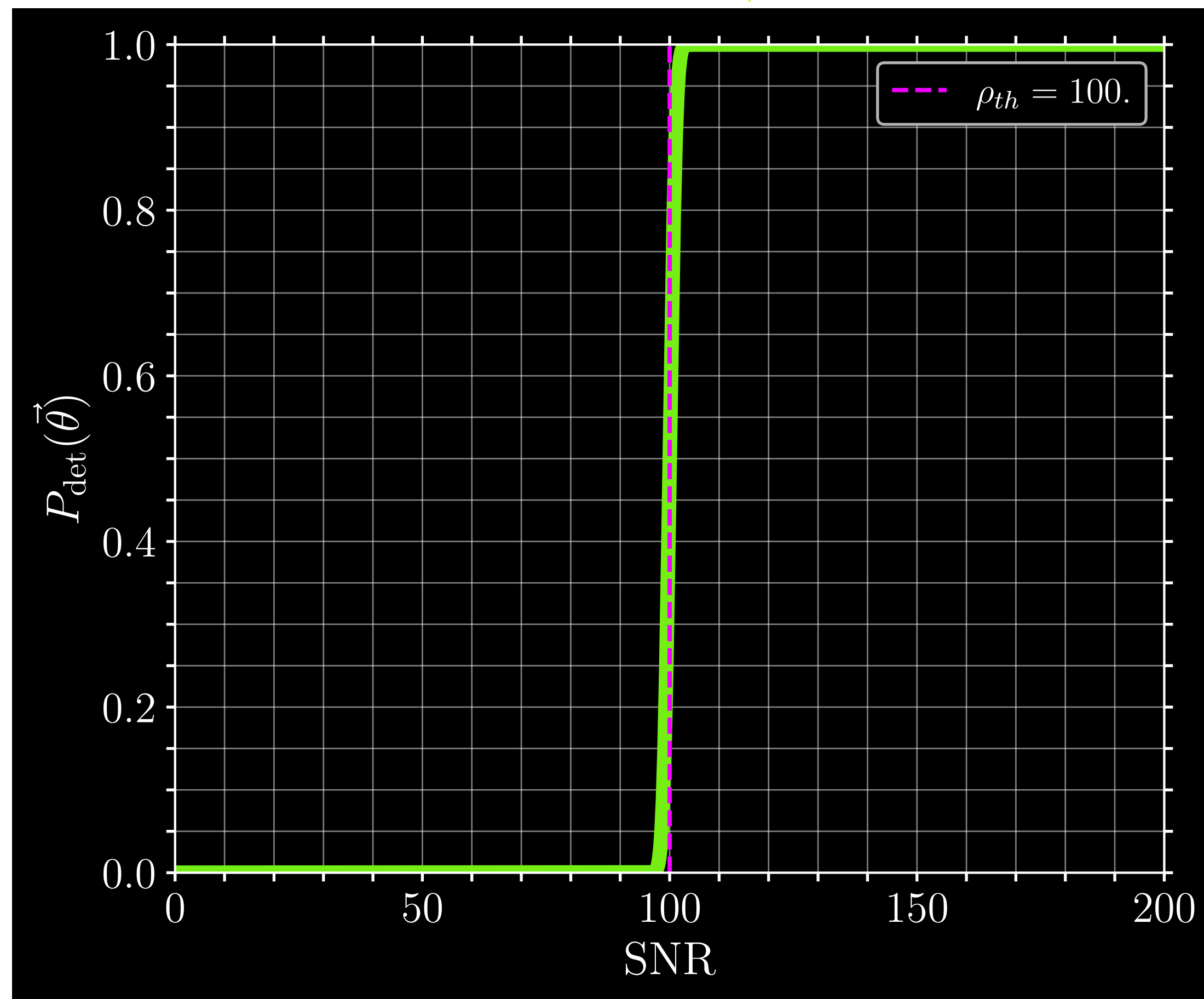
3. Detection probability:
$$P_{\text{det}}(\vec{\theta}) = \int_{d > d_{th}} p(d | \vec{\theta}) d\vec{\theta}$$

Population Fisher Matrix

$$(\Gamma_\lambda)_{ij} \equiv N_{\text{det}} [(\Gamma_{\text{I}})_{ij} + (\Gamma_{\text{II}})_{ij} + (\Gamma_{\text{III}})_{ij} + (\Gamma_{\text{IV}})_{ij} + (\Gamma_{\text{V}})_{ij}]$$

We opted for a more regular error function, i.e

$$P_{\text{det}}(\vec{\theta}) = \frac{1}{2} \text{erfc} \frac{(\rho - \rho_{\text{th}})}{\sqrt{2}\sigma}$$



1. Population model: $p(\vec{\theta} | \vec{\lambda})$

2. Selection effects:
$$P_{\text{det}}(\vec{\lambda}) = \int P_{\text{det}}(\vec{\theta}) p(\theta | \lambda) d\vec{\theta}$$

3. Detection probability:
$$P_{\text{det}}(\vec{\theta}) = \int_{d > d_{\text{th}}} p(d | \vec{\theta}) d\vec{\theta}$$

Population Fisher Matrix

$$(\Gamma_\lambda)_{ij} \equiv N_{\text{det}} [(\Gamma_{\text{I}})_{ij} + (\Gamma_{\text{II}})_{ij} + (\Gamma_{\text{III}})_{ij} + (\Gamma_{\text{IV}})_{ij} + (\Gamma_{\text{V}})_{ij}]$$

$$(\Gamma_{\text{I}})_{ij} = - \int \frac{\partial^2 \ln(p(\vec{\theta} | \vec{\lambda}) P_{\text{det}}(\vec{\lambda}))}{\partial \lambda^i \partial \lambda^j} \frac{P_{\text{det}}(\vec{\theta})}{P_{\text{det}}(\vec{\lambda})} p(\vec{\theta} | \vec{\lambda})$$

$$(\Gamma_{\text{II}})_{ij} = \frac{1}{2} \int \frac{\partial^2 \ln \det(\Gamma + H)}{\partial \lambda^i \partial \lambda^j} \frac{P_{\text{det}}(\vec{\theta})}{P_{\text{det}}(\vec{\lambda})} p(\vec{\theta} | \vec{\lambda})$$

$$(\Gamma_{\text{III}})_{ij} = - \frac{1}{2} \int \frac{\partial^2}{\partial \lambda^i \partial \lambda^j} \left[(\Gamma + H)_{kl}^{-1} \right] \Gamma_{kl} \frac{p(\vec{\theta} | \vec{\lambda})}{P_{\text{det}}(\vec{\lambda})} d\vec{\theta}$$

$$(\Gamma_{\text{IV}})_{ij} = - \int \frac{\partial^2}{\partial \lambda^i \partial \lambda^j} \left[P_k (\Gamma + H)_{kl}^{-1} \right] D_l \frac{p(\vec{\theta} | \vec{\lambda})}{P_{\text{det}}(\vec{\lambda})} d\vec{\theta}$$

$$(\Gamma_{\text{V}})_{ij} = - \frac{1}{2} \int \frac{\partial^2}{\partial \lambda^i \partial \lambda^j} \left[P_k (\Gamma + H)_{kl}^{-1} P_l \right] \frac{P_{\text{det}}(\vec{\theta})}{P_{\text{det}}(\vec{\lambda})} p(\vec{\theta} | \vec{\lambda})$$

1. Population model: $p(\vec{\theta} | \vec{\lambda})$

2. Selection effects:
 $P_{\text{det}}(\vec{\lambda}) = \int P_{\text{det}}(\vec{\theta}) p(\theta | \lambda) d\vec{\theta}$

3. Detection probability:
 $P_{\text{det}}(\vec{\theta}) = \int_{d > d_{th}} p(d | \vec{\theta}) d\vec{\theta}$

with its first derivative

$$D_l = \frac{\partial P_{\text{det}}(\vec{\theta})}{\partial \theta^l}$$

Population Fisher Matrix

$$(\Gamma_\lambda)_{ij} \equiv N_{\text{det}} [(\Gamma_{\text{I}})_{ij} + (\Gamma_{\text{II}})_{ij} + (\Gamma_{\text{III}})_{ij} + (\Gamma_{\text{IV}})_{ij} + (\Gamma_{\text{V}})_{ij}]$$

$$(\Gamma_{\text{I}})_{ij} = - \int \frac{\partial^2 \ln(p(\vec{\theta} | \vec{\lambda}) P_{\text{det}}(\vec{\lambda}))}{\partial \lambda^i \partial \lambda^j} \frac{P_{\text{det}}(\vec{\theta})}{P_{\text{det}}(\vec{\lambda})} p(\vec{\theta} | \vec{\lambda})$$

$$(\Gamma_{\text{II}})_{ij} = \frac{1}{2} \int \frac{\partial^2 \ln \det(\Gamma + H)}{\partial \lambda^i \partial \lambda^j} \frac{P_{\text{det}}(\vec{\theta})}{P_{\text{det}}(\vec{\lambda})} p(\vec{\theta} | \vec{\lambda}) d\vec{\theta}$$

$$(\Gamma_{\text{III}})_{ij} = - \frac{1}{2} \int \frac{\partial^2}{\partial \lambda^i \partial \lambda^j} \left[(\Gamma + H)_{kl}^{-1} \right] \Gamma_{kl} \frac{p(\vec{\theta} | \vec{\lambda})}{P_{\text{det}}(\vec{\lambda})} d\vec{\theta}$$

$$(\Gamma_{\text{IV}})_{ij} = - \int \frac{\partial^2}{\partial \lambda^i \partial \lambda^j} \left[P_k (\Gamma + H)_{kl}^{-1} \right] D_l \frac{p(\vec{\theta} | \vec{\lambda})}{P_{\text{det}}(\vec{\lambda})} d\vec{\theta}$$

$$(\Gamma_{\text{V}})_{ij} = - \frac{1}{2} \int \frac{\partial^2}{\partial \lambda^i \partial \lambda^j} \left[P_k (\Gamma + H)_{kl}^{-1} P_l \right] \frac{P_{\text{det}}(\vec{\theta})}{P_{\text{det}}(\vec{\lambda})} p(\vec{\theta} | \vec{\lambda}) d\vec{\theta}$$

1. Population model: $p(\vec{\theta} | \vec{\lambda})$

2. Selection effects:
 $P_{\text{det}}(\vec{\lambda}) = \int P_{\text{det}}(\vec{\theta}) p(\theta | \lambda) d\vec{\theta}$

3. Detection probability:
 $P_{\text{det}}(\vec{\theta}) = \int_{d > d_{th}} p(d | \vec{\theta}) d\vec{\theta}$

4. Γ = Single event Fisher matrix with GWfast

Population Fisher Matrix

$$(\Gamma_\lambda)_{ij} \equiv N_{\text{det}} [(\Gamma_{\text{I}})_{ij} + (\Gamma_{\text{II}})_{ij} + (\Gamma_{\text{III}})_{ij} + (\Gamma_{\text{IV}})_{ij} + (\Gamma_{\text{V}})_{ij}]$$

$$(\Gamma_{\text{I}})_{ij} = - \int \frac{\partial^2 \ln(p(\vec{\theta} | \vec{\lambda}) P_{\text{det}}(\vec{\lambda}))}{\partial \lambda^i \partial \lambda^j} \frac{P_{\text{det}}(\vec{\theta})}{P_{\text{det}}(\vec{\lambda})} p(\vec{\theta} | \vec{\lambda})$$

$$(\Gamma_{\text{II}})_{ij} = \int B(\vec{\theta}) \frac{P_{\text{det}}(\vec{\theta})}{P_{\text{det}}(\vec{\lambda})} p(\vec{\theta} | \vec{\lambda}) d\vec{\theta}$$

$$(\Gamma_{\text{III}})_{ij} = \int C(\vec{\theta}) \frac{p(\vec{\theta} | \vec{\lambda})}{P_{\text{det}}(\vec{\lambda})} d\vec{\theta}$$

$$(\Gamma_{\text{IV}})_{ij} = \int D(\vec{\theta}) \frac{p(\vec{\theta} | \vec{\lambda})}{P_{\text{det}}(\vec{\lambda})} d\vec{\theta}$$

$$(\Gamma_{\text{V}})_{ij} = \int E(\vec{\theta}) \frac{P_{\text{det}}(\vec{\theta})}{P_{\text{det}}(\vec{\lambda})} p(\vec{\theta} | \vec{\lambda}) d\vec{\theta}$$

1. Population model: $p(\vec{\theta} | \vec{\lambda})$

2. Selection effects:
 $P_{\text{det}}(\vec{\lambda}) = \int P_{\text{det}}(\vec{\theta}) p(\theta | \lambda) d\vec{\theta}$

3. Detection probability:
 $P_{\text{det}}(\vec{\theta}) = \int_{d > d_{th}} p(d | \vec{\theta}) d\vec{\theta}$

4. Γ = Single event Fisher matrix with GWfast

Errors on the single-event parameters $\vec{\theta}$ enter in the last four terms!

[Iacovelli et al, 2022]

[Gair et al., 2023]

Population Fisher Matrix

$$(\Gamma_\lambda)_{ij} \equiv N_{\text{det}} [(\Gamma_{\text{I}})_{ij} + (\Gamma_{\text{II}})_{ij} + (\Gamma_{\text{III}})_{ij} + (\Gamma_{\text{IV}})_{ij} + (\Gamma_{\text{V}})_{ij}]$$

$$(\Gamma_{\text{I}})_{ij} = - \int \frac{\partial^2 \ln(p(\vec{\theta} | \vec{\lambda}) P_{\text{det}}(\vec{\lambda}))}{\partial \lambda^i \partial \lambda^j} \frac{P_{\text{det}}(\vec{\theta})}{P_{\text{det}}(\vec{\lambda})} p(\vec{\theta} | \vec{\lambda})$$

$$(\Gamma_{\text{II}})_{ij} = \int B(\vec{\theta}) \frac{P_{\text{det}}(\vec{\theta})}{P_{\text{det}}(\vec{\lambda})} p(\vec{\theta} | \vec{\lambda}) d\vec{\theta}$$

$$(\Gamma_{\text{III}})_{ij} = \int C(\vec{\theta}) \frac{p(\vec{\theta} | \vec{\lambda})}{P_{\text{det}}(\vec{\lambda})} d\vec{\theta}$$

$$(\Gamma_{\text{IV}})_{ij} = \int D(\vec{\theta}) \frac{p(\vec{\theta} | \vec{\lambda})}{P_{\text{det}}(\vec{\lambda})} d\vec{\theta}$$

$$(\Gamma_{\text{V}})_{ij} = \int E(\vec{\theta}) \frac{P_{\text{det}}(\vec{\theta})}{P_{\text{det}}(\vec{\lambda})} p(\vec{\theta} | \vec{\lambda}) d\vec{\theta}$$

1. Population model: $p(\vec{\theta} | \vec{\lambda})$

2. Selection effects:
 $P_{\text{det}}(\vec{\lambda}) = \int P_{\text{det}}(\vec{\theta}) p(\theta | \lambda) d\vec{\theta}$

3. Detection probability:
 $P_{\text{det}}(\vec{\theta}) = \int_{d > d_{th}} p(d | \vec{\theta}) d\vec{\theta}$

4. Γ = Single event Fisher matrix with GWfast

If the single-event errors are small,
 Γ_{I} is the dominant term

[Iacovelli et al, 2022]

[Gair et al., 2023]

3G forecasts

☀️ **Mass distribution = Power Law Plus Peak**

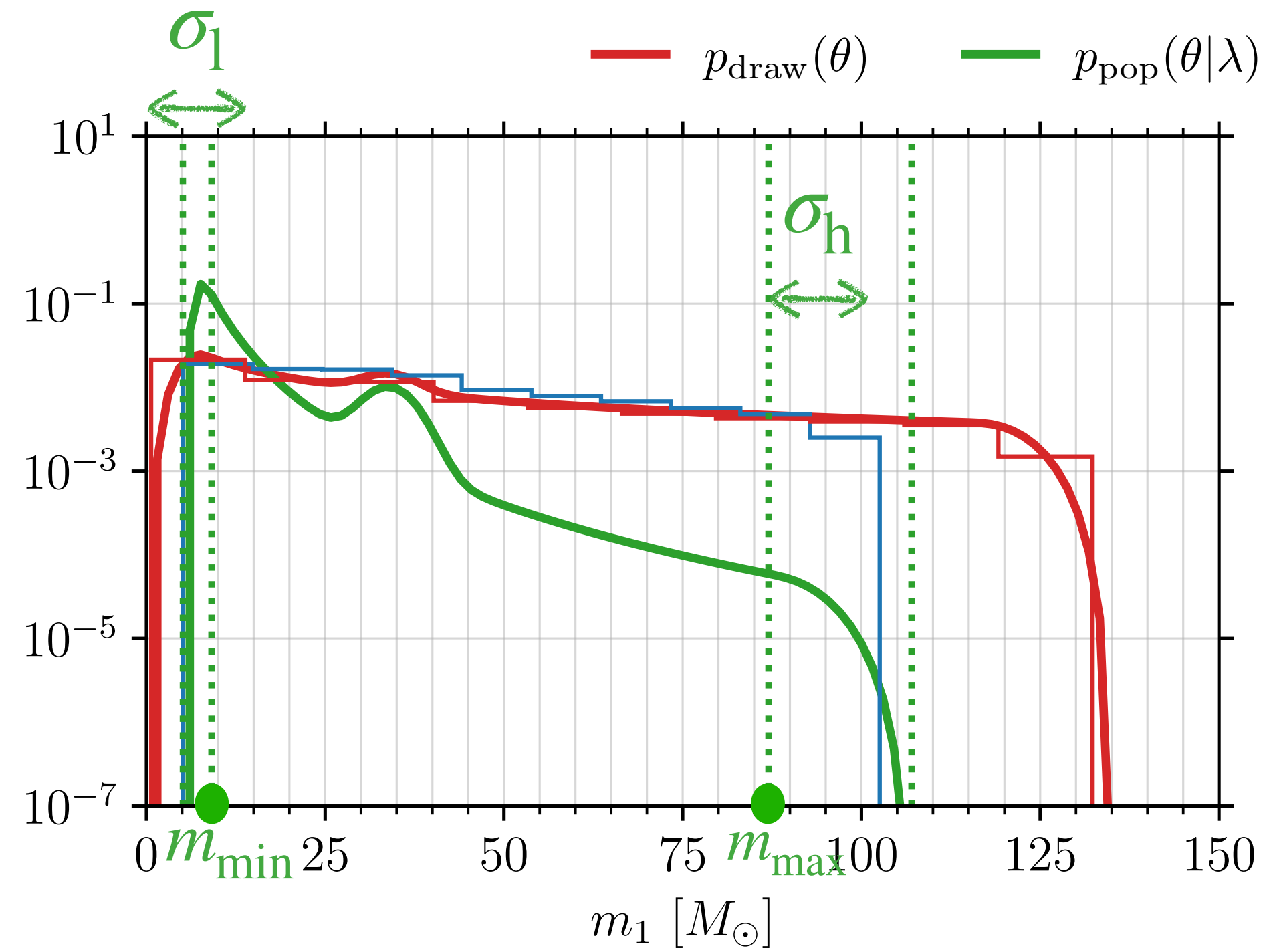
☀️ Redshift distribution = Madau Dickinson

☀️ Spin = Default distribution

☀️ Detectors: ET, ET+2CE

☀️ SNR threshold = 12

☀️ Waveform: *IMRPhenomXPHM*

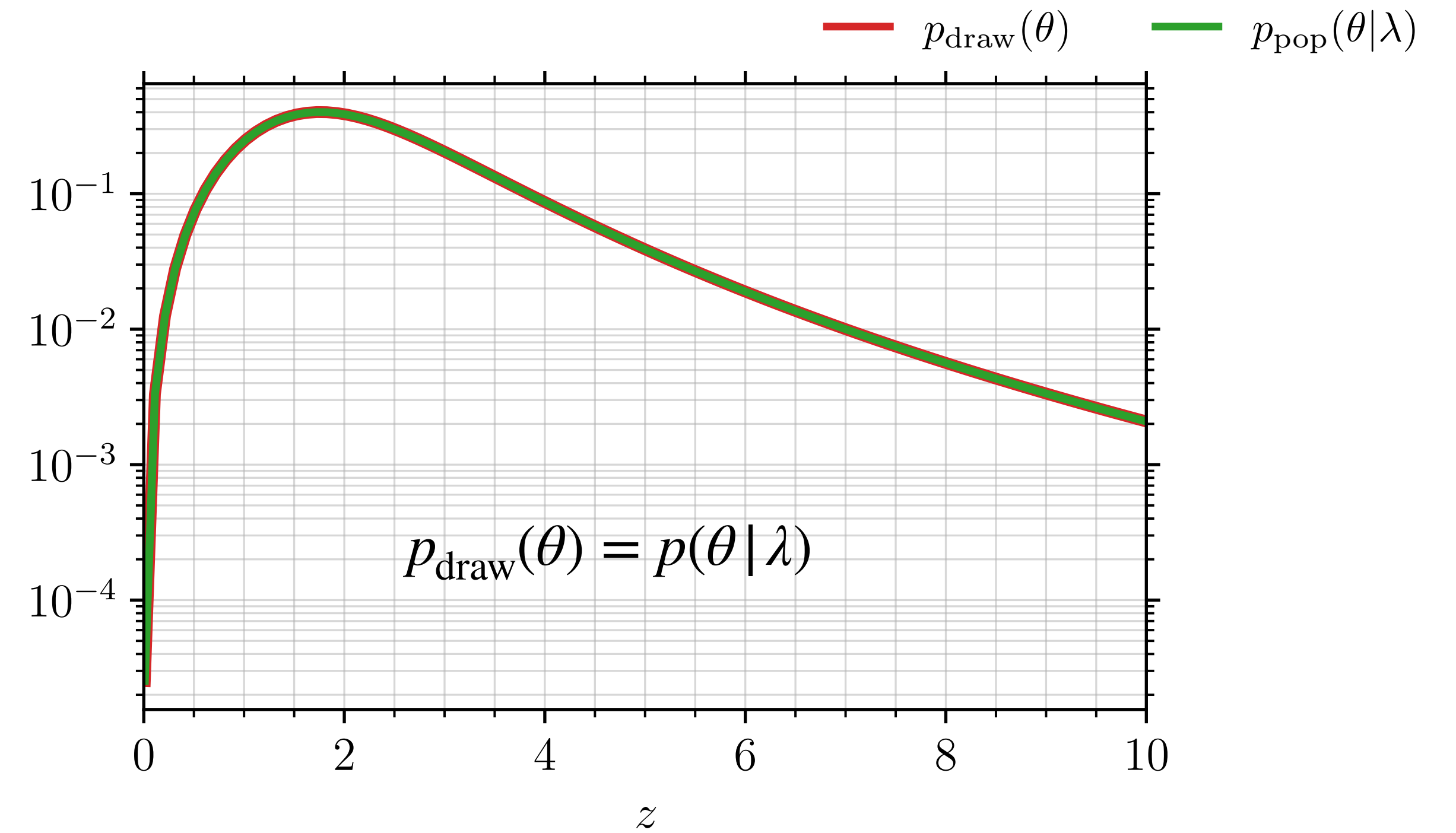


Parameter	Description	Fiducial Value
Mass model: POWER LAW PLUS PEAK		
α_m	Spectral index for the power-law of the primary mass distribution.	3.4
β_q	Spectral index for the power-law of the mass ratio distribution.	1.1
m_{min}	Minimum mass of the power-law component of the primary mass distribution.	$9.1 M_\odot$
m_{max}	Maximum mass of the power-law component of the primary mass distribution.	$87 M_\odot$
λ_p	Fraction of binary BHs in the Gaussian component.	0.039
μ_m	Mean of the Gaussian component in the primary mass distribution.	34
σ_m	Width of the Gaussian component in the primary mass distribution.	3.6
σ_l	Width of mass smoothing at the lower end of the mass distribution.	4.0
σ_h	Width of mass smoothing at the upper end of the mass distribution.	0.5

3G forecasts

- ✱ Mass distribution = Power Law Plus Peak
- ✱ **Redshift distribution = Madau Dickinson**
- ✱ Spin = Default distribution

- ✱ Detectors: ET, ET+2CE
- ✱ SNR threshold = 12
- ✱ Waveform: *IMRPhenomXPHM*



Parameter	Description	Fiducial Value
Rate model: MADAU DICKINSON		
α_z	Power-law index governing the rise of the star formation rate at low redshift.	2.7
β_z	Power-law index governing the decline of the star formation rate at high redshift.	3.0
z_p	Redshift at which the star formation rate peaks.	2.0

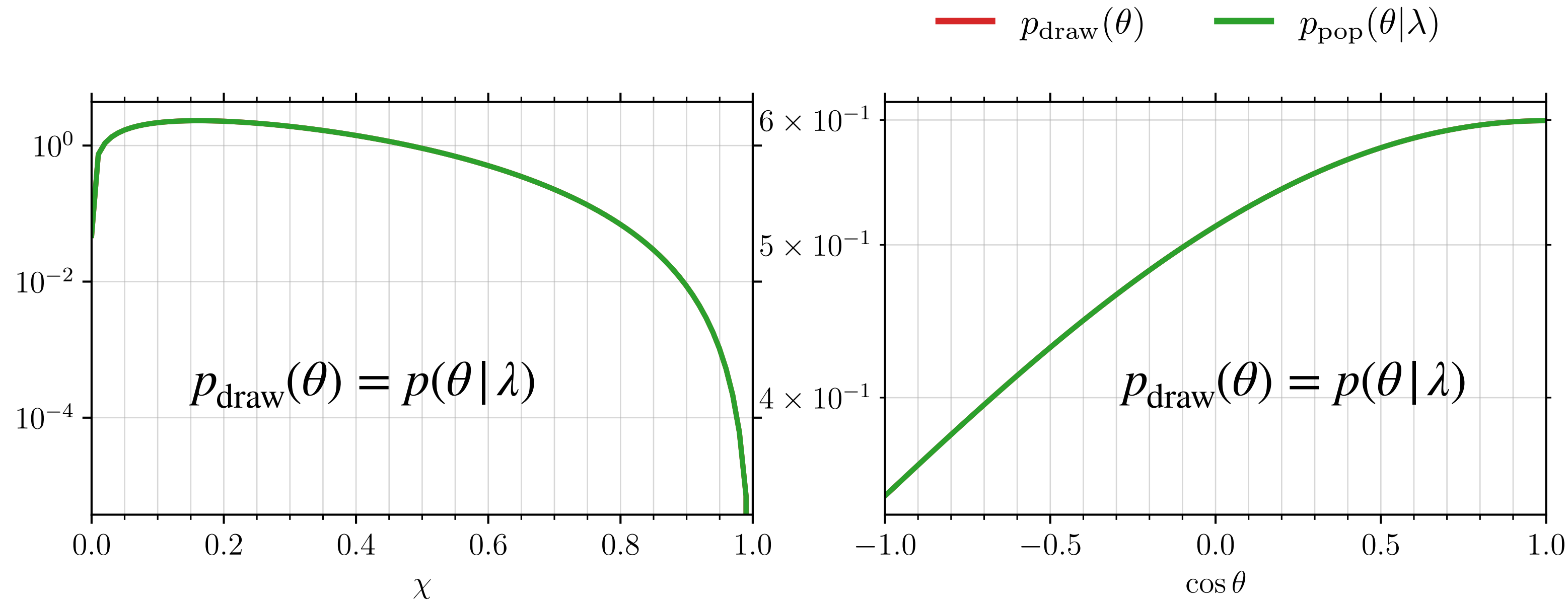
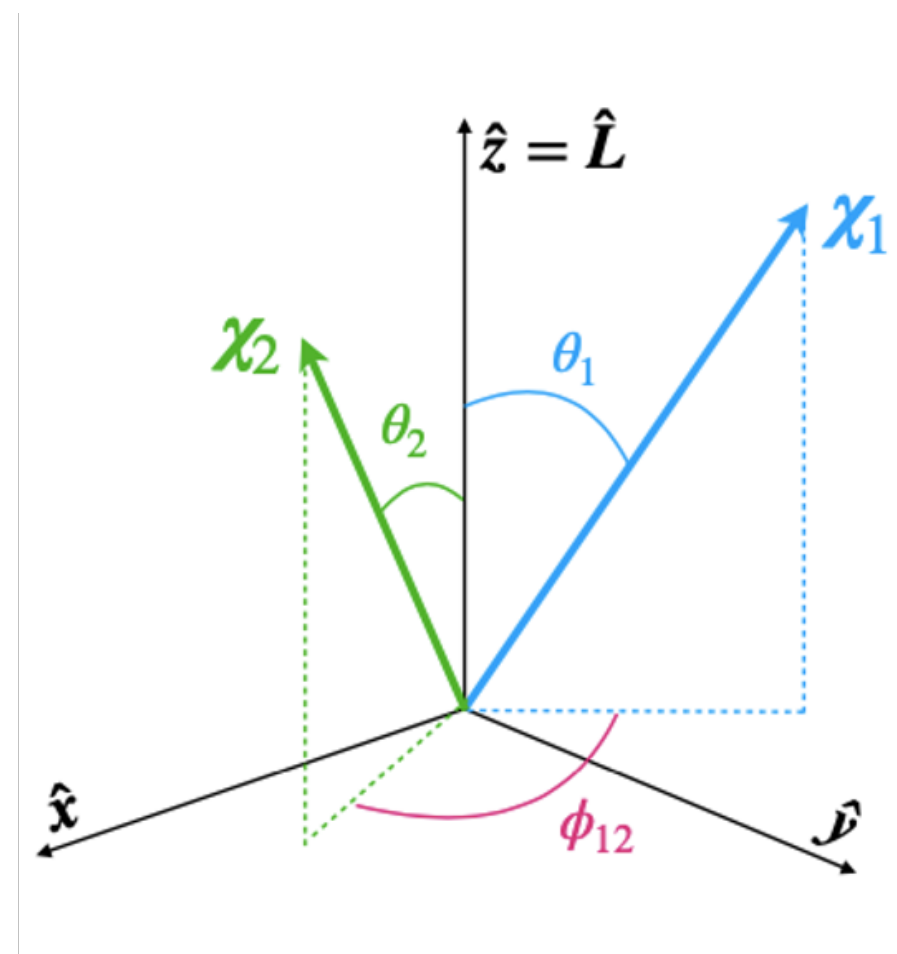
3G forecasts

- ☀ Mass distribution = Power Law Plus Peak
- ☀ Redshift distribution = Madau Dickinson
- ☀ **Spin = Default distribution**

☀ Detectors: ET, ET+2CE

☀ SNR threshold = 12

☀ Waveform: *IMRPhenomXPHM*



Parameter	Description	Fiducial Value
Spin model: DEFAULT		
α_χ	Shape parameter of the Beta distribution of the spin magnitudes.	1.6
β_χ	Shape parameter of the Beta distribution of the spin magnitudes.	4.12
ζ	Mixing fraction of mergers from the truncated Gaussian component for spin orientations.	0.66
σ_t	Width of the truncated Gaussian component for spin orientations, determining the typical spin misalignment.	1.5

Spin magnitudes $p(\chi_i | \alpha_\chi, \beta_\chi) \propto \chi_i^{\alpha-1} (1 - \chi_i)^{\beta-1}$.

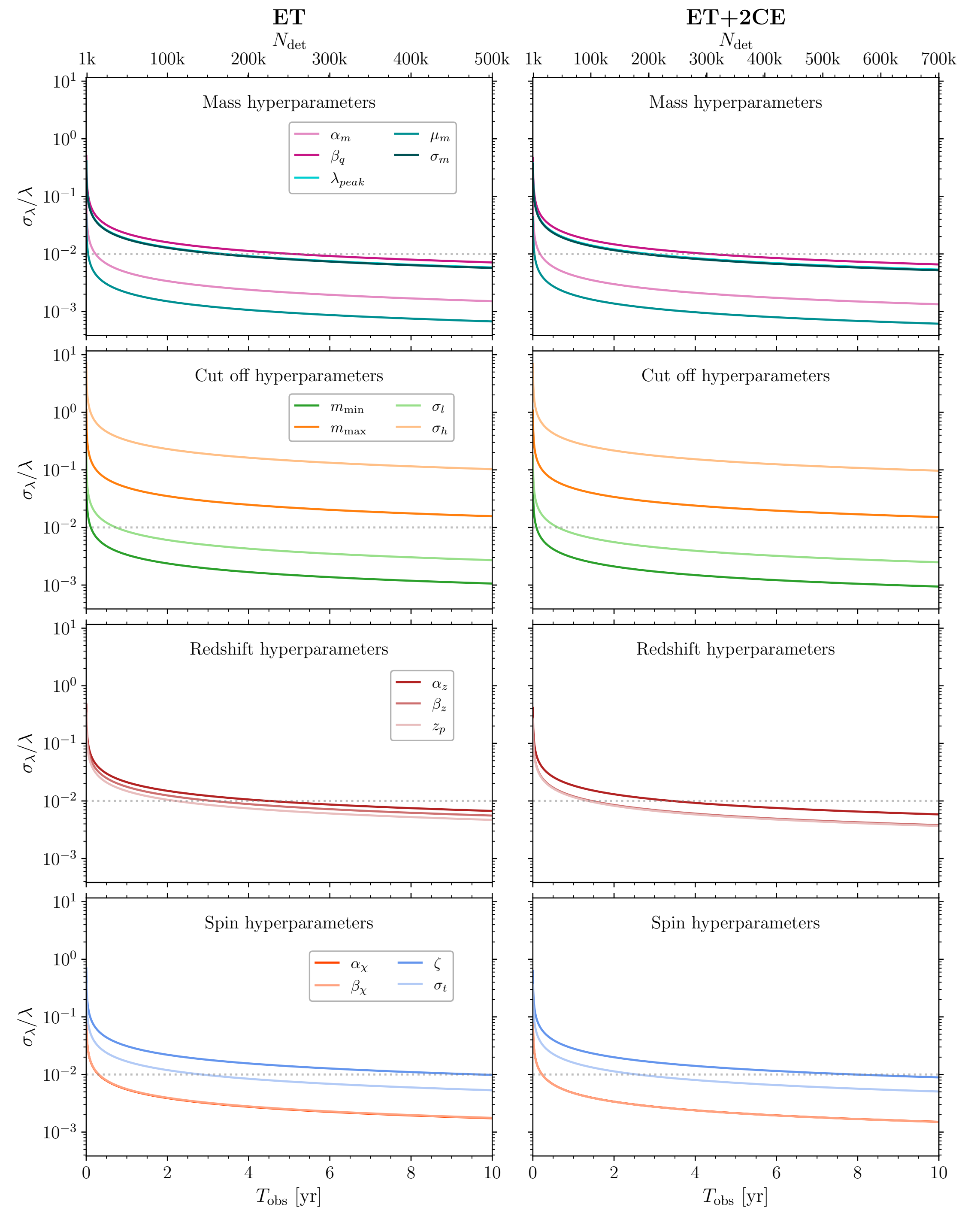
Spin tilts $p(\cos \theta_i | \zeta, \sigma_t) = \frac{1}{2} (1 - \zeta) + \zeta \mathcal{N}_{[-1,1]}(\cos \theta_i; 1, \sigma_t)$.

Population forecasts with 3G detectors

$$\frac{\sigma_\lambda}{\lambda} \propto \sigma_\lambda \propto \frac{1}{\sqrt{N}} \propto \frac{1}{\sqrt{N_{\text{det}}}} \propto \frac{1}{\sqrt{T_{\text{obs}}}}$$

Relative errors after 10 years of observation

σ_λ/λ	ET	$T_{0.01}^{ET}$	ET+2CE	$T_{0.01}^{ET+2CE}$	Fiducial Values
α_m	1.51×10^{-3}	0.2	1.34×10^{-3}	0.2	3.4
β_q	7.12×10^{-3}	5.1	6.57×10^{-3}	4.3	1.1
m_{min}	1.06×10^{-3}	0.1	9.41×10^{-4}	0.1	$9.1 M_\odot$
m_{max}	1.57×10^{-2}	>10	1.51×10^{-2}	>10	$87 M_\odot$
λ_{peak}	5.82×10^{-3}	3.4	5.35×10^{-3}	2.9	0.039
σ_l	2.71×10^{-3}	0.7	2.49×10^{-3}	0.6	4.0
σ_h	1.03×10^{-1}	>10	9.67×10^{-2}	>10	0.5
μ_m	6.74×10^{-4}	0.1	6.15×10^{-4}	0.04	34
σ_m	5.70×10^{-3}	3.3	5.19×10^{-3}	1.5	3.6
α_z	6.71×10^{-3}	4.5	5.85×10^{-3}	1.4	2.7
β_z	5.57×10^{-3}	3.1	3.81×10^{-3}	0.2	3.0
z_p	4.69×10^{-3}	2.2	3.68×10^{-3}	0.2	2.0
α_χ	1.74×10^{-3}	0.3	1.51×10^{-3}	0.2	1.6
β_χ	1.77×10^{-3}	0.3	1.50×10^{-3}	0.2	4.12
ζ_χ	9.83×10^{-3}	9.7	8.90×10^{-3}	7.9	0.66
σ_t	5.32×10^{-3}	2.8	5.06×10^{-3}	2.6	1.5



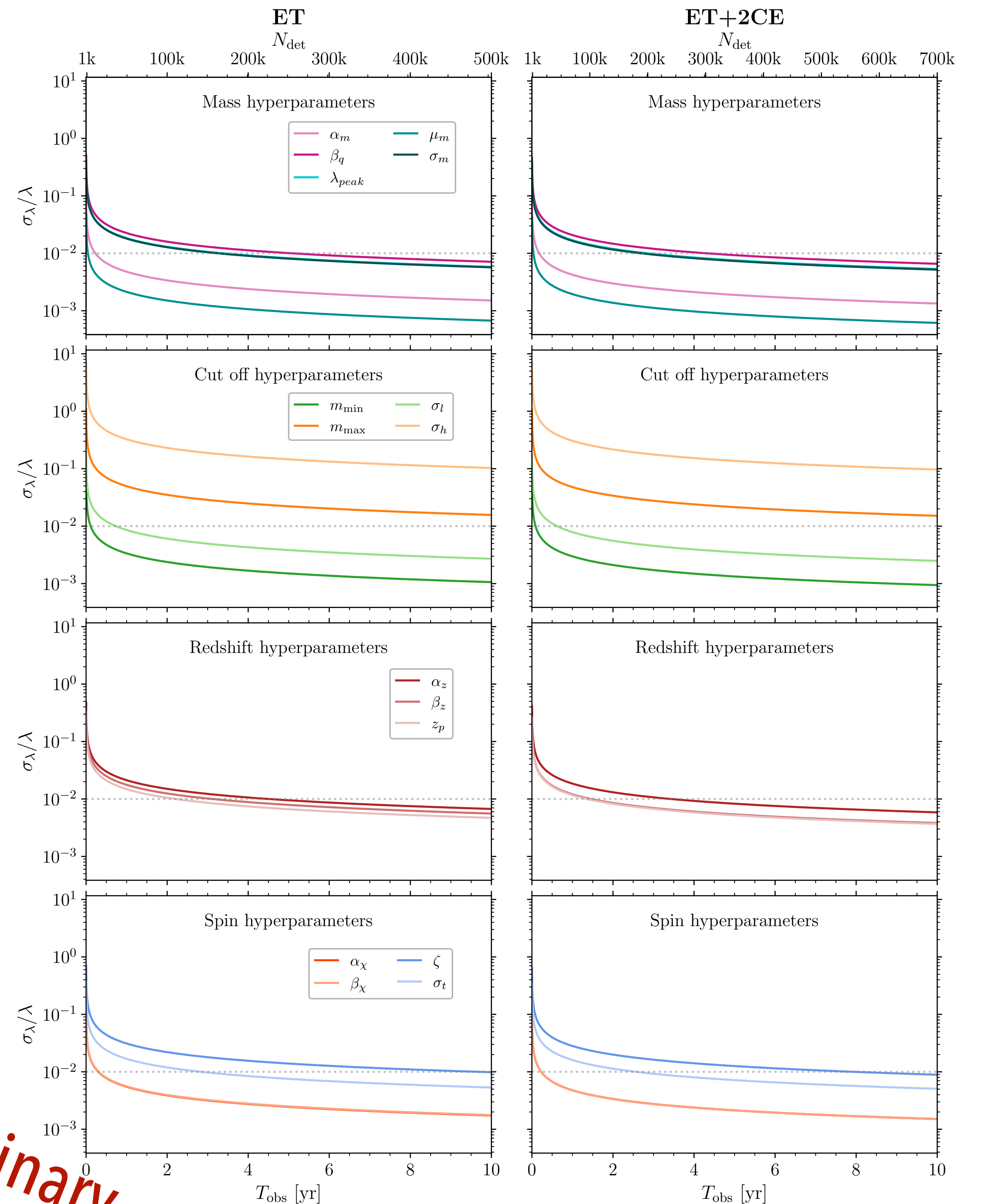
Population forecasts with 3G detectors

No big difference between ET and ET+2CE :

- Both detectors will constrain intrinsic parameters with incredible accuracy
- The scale of the problem is the number of detection
- Adding 2CE to ET introduces more distant events with lower SNR near the detection threshold

Relative errors after 10 years of observation

σ_λ/λ	ET	$T_{0.01}^{ET}$	ET+2CE	$T_{0.01}^{ET+2CE}$	Fiducial Values
α_m	1.51×10^{-3}	0.2	1.34×10^{-3}	0.2	3.4
β_q	7.12×10^{-3}	5.1	6.57×10^{-3}	4.3	1.1
m_{\min}	1.06×10^{-3}	0.1	9.41×10^{-4}	0.1	$9.1 M_\odot$
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σ_m	5.70×10^{-3}	3.3	5.19×10^{-3}	1.5	3.6
α_z	6.71×10^{-3}	4.5	5.85×10^{-3}	1.4	2.7
β_z	5.57×10^{-3}	3.1	3.81×10^{-3}	0.2	3.0
z_p	4.69×10^{-3}	2.2	3.68×10^{-3}	0.2	2.0
α_χ	1.74×10^{-3}	0.3	1.51×10^{-3}	0.2	1.6
β_χ	1.77×10^{-3}	0.3	1.50×10^{-3}	0.2	4.12
ζ_χ	9.83×10^{-3}	9.7	8.90×10^{-3}	7.9	0.66
σ_t	5.32×10^{-3}	2.8	5.06×10^{-3}	2.6	1.5

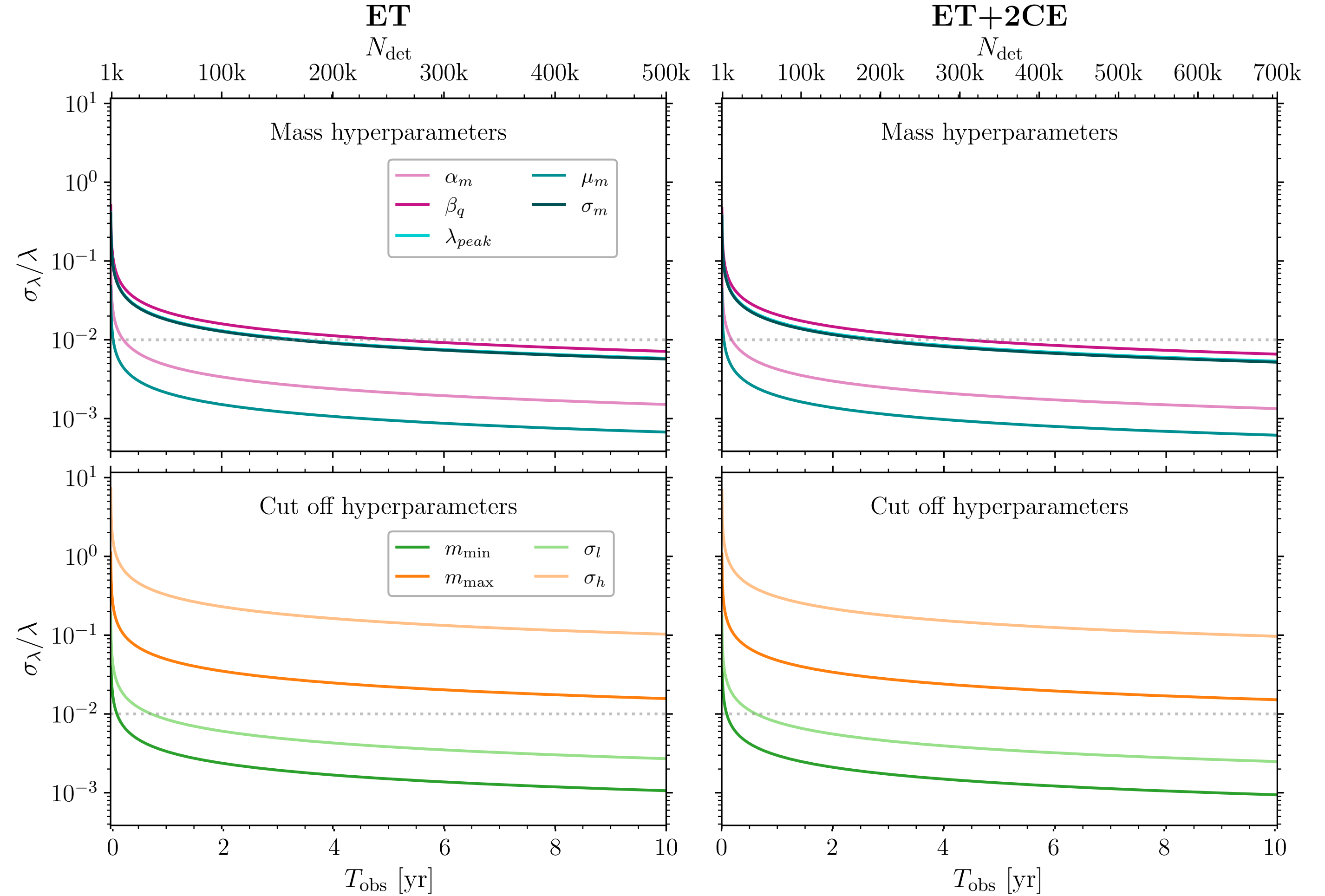


Mass hyperparameters

- * α_m, m_{\min} and μ_m are the best measured parameters
- * β_q measured with less accuracy w.r.t. α_m
- * The worst measured are σ_h and m_{\max}

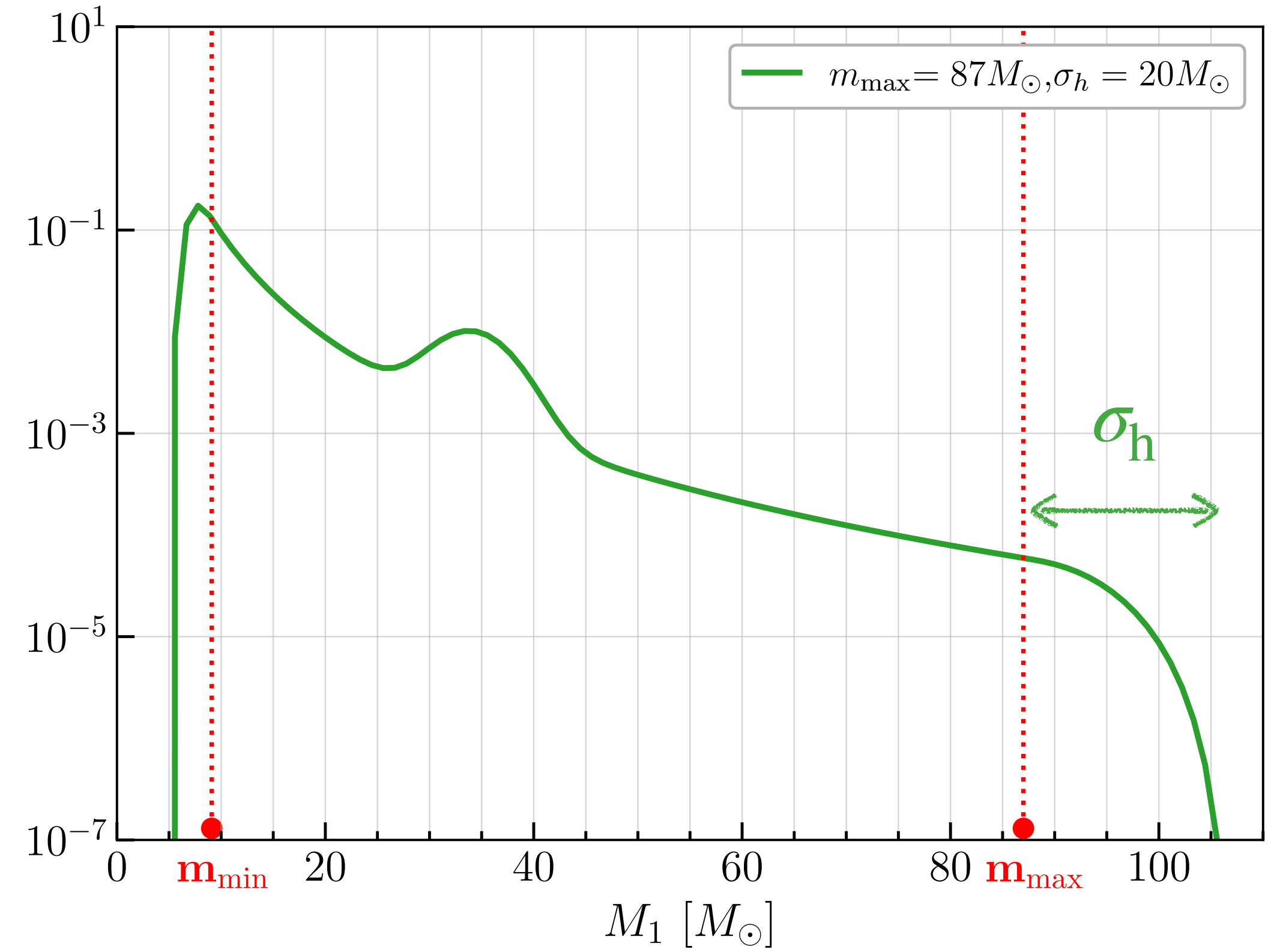
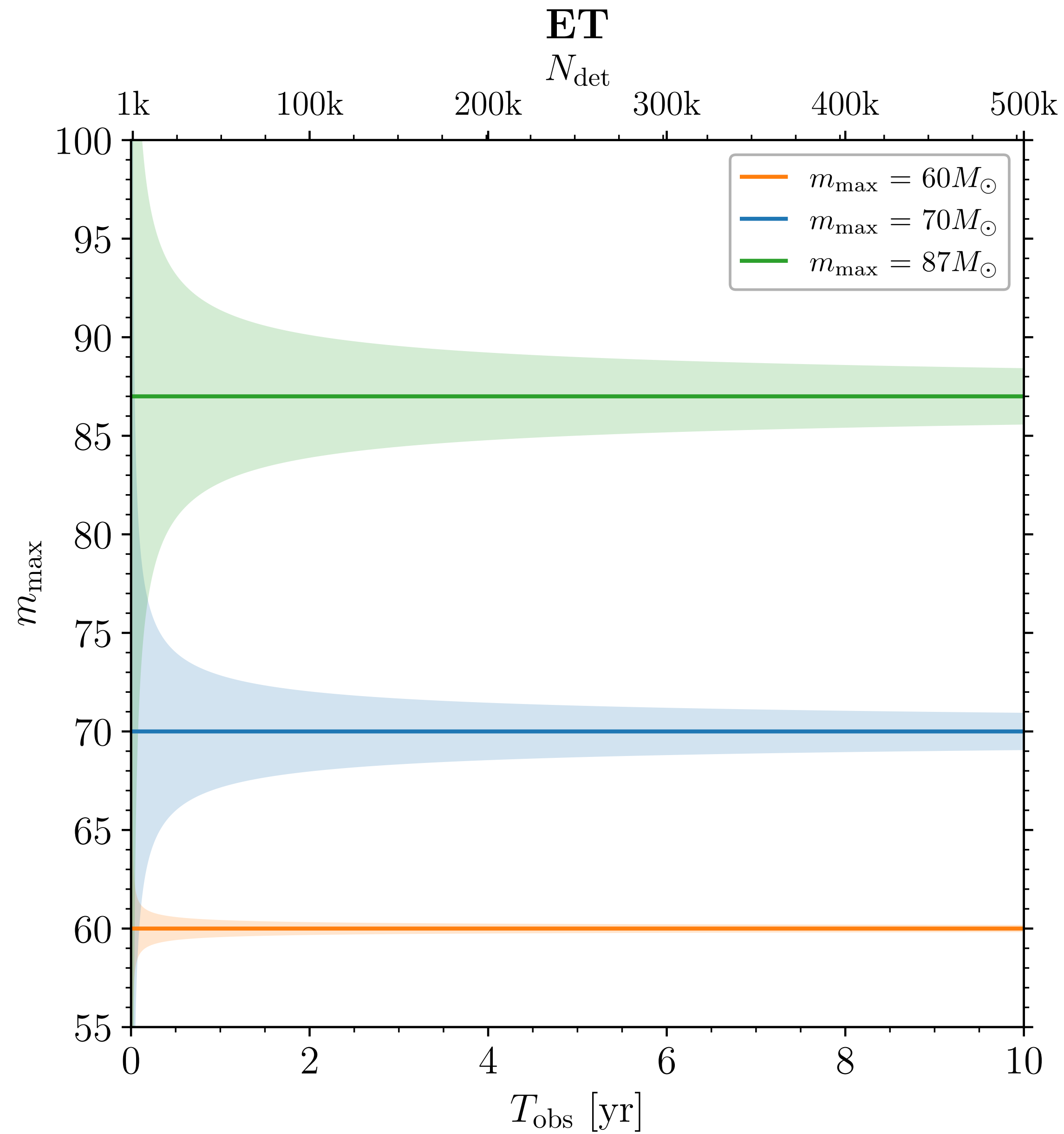
Relative errors after 10 years of observation

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m_{\max}	1.57×10^{-2}	>10	1.51×10^{-2}	>10	$87 M_\odot$
λ_{peak}	5.82×10^{-3}	3.4	5.35×10^{-3}	2.9	0.039
σ_l	2.71×10^{-3}	0.7	2.49×10^{-3}	0.6	4.0
σ_h	1.03×10^{-1}	>10	9.67×10^{-2}	>10	0.5
μ_m	6.74×10^{-4}	0.1	6.15×10^{-4}	0.04	34
σ_m	5.70×10^{-3}	3.3	5.19×10^{-3}	1.5	3.6

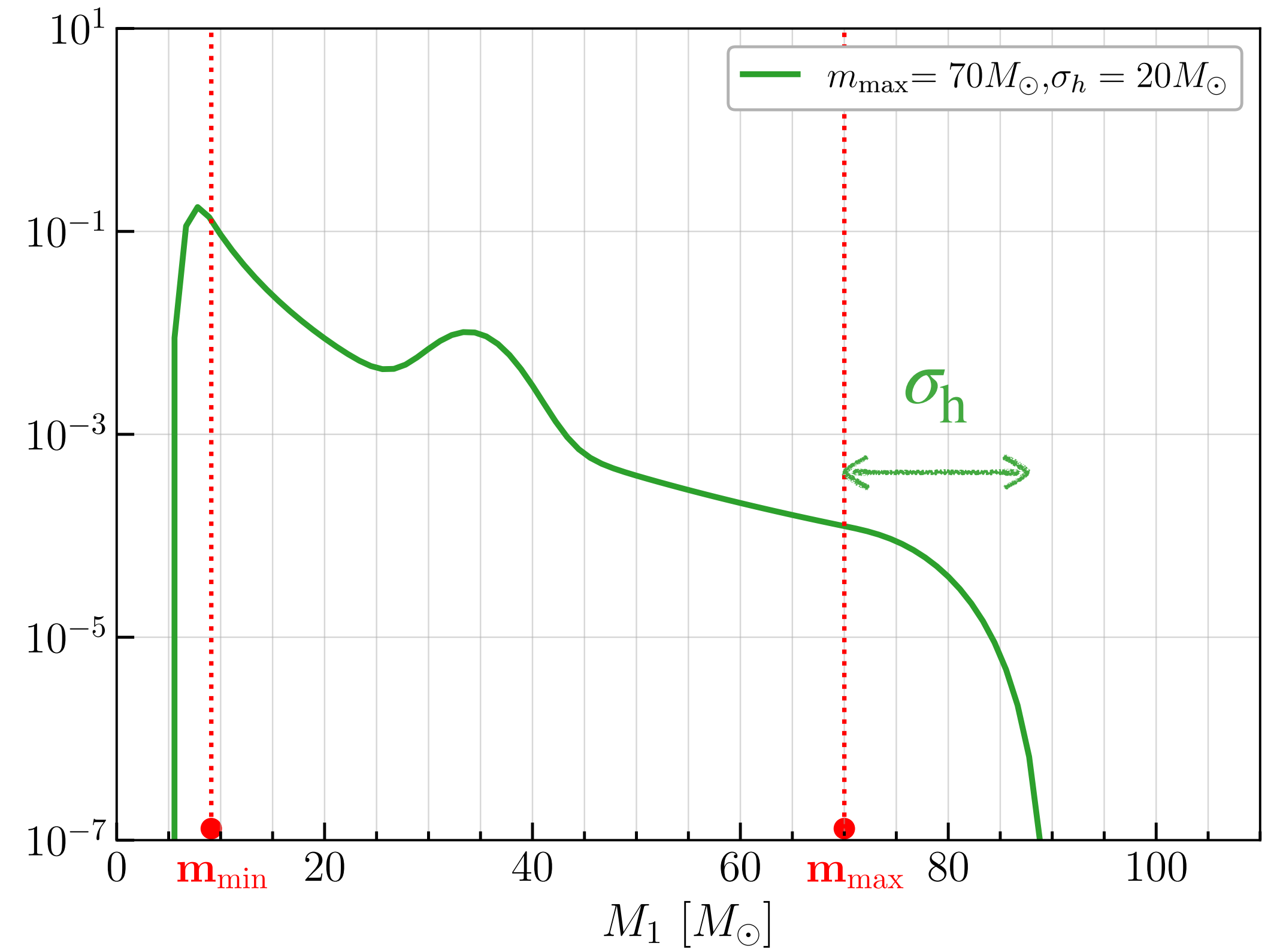
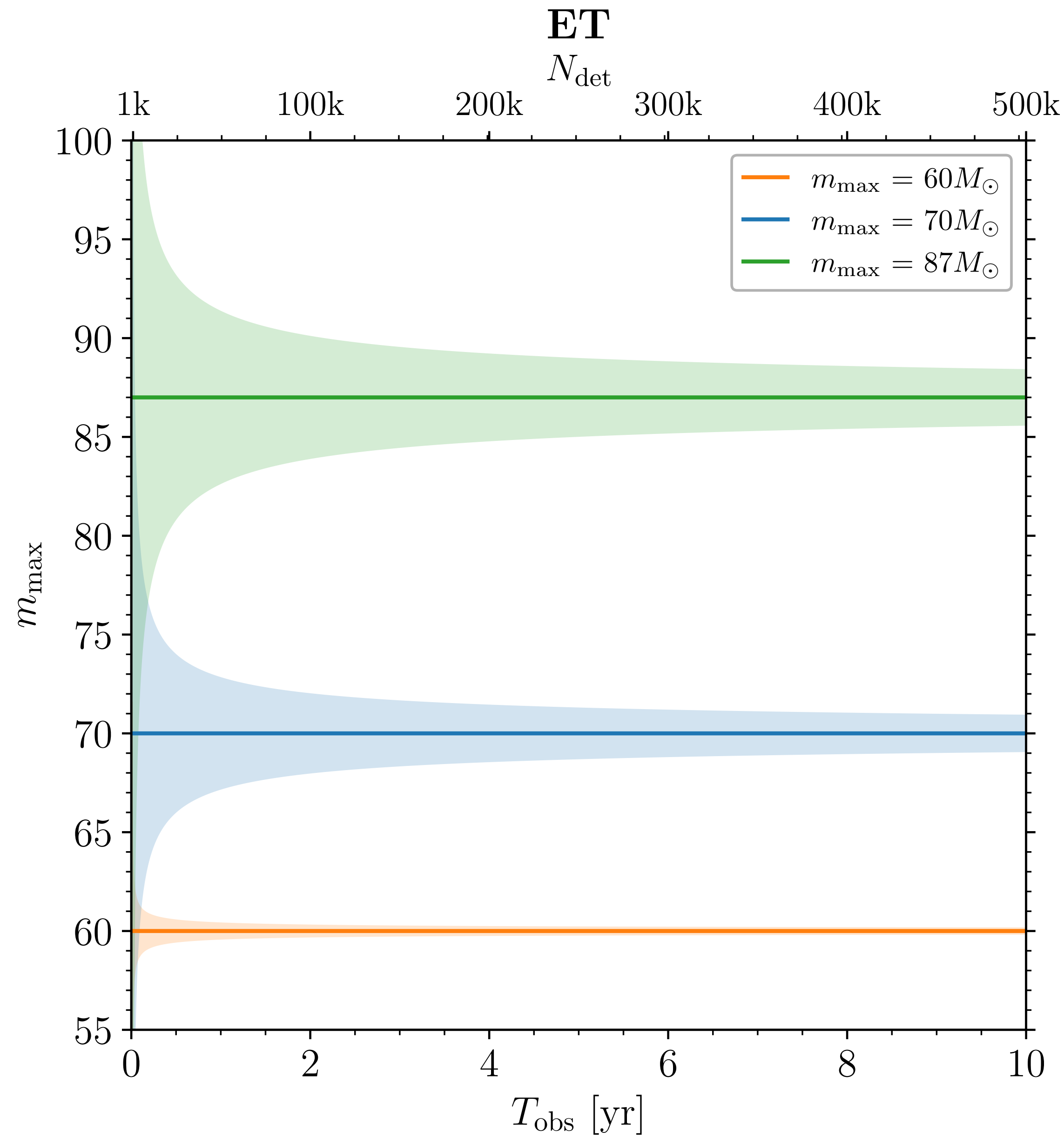


Preliminary

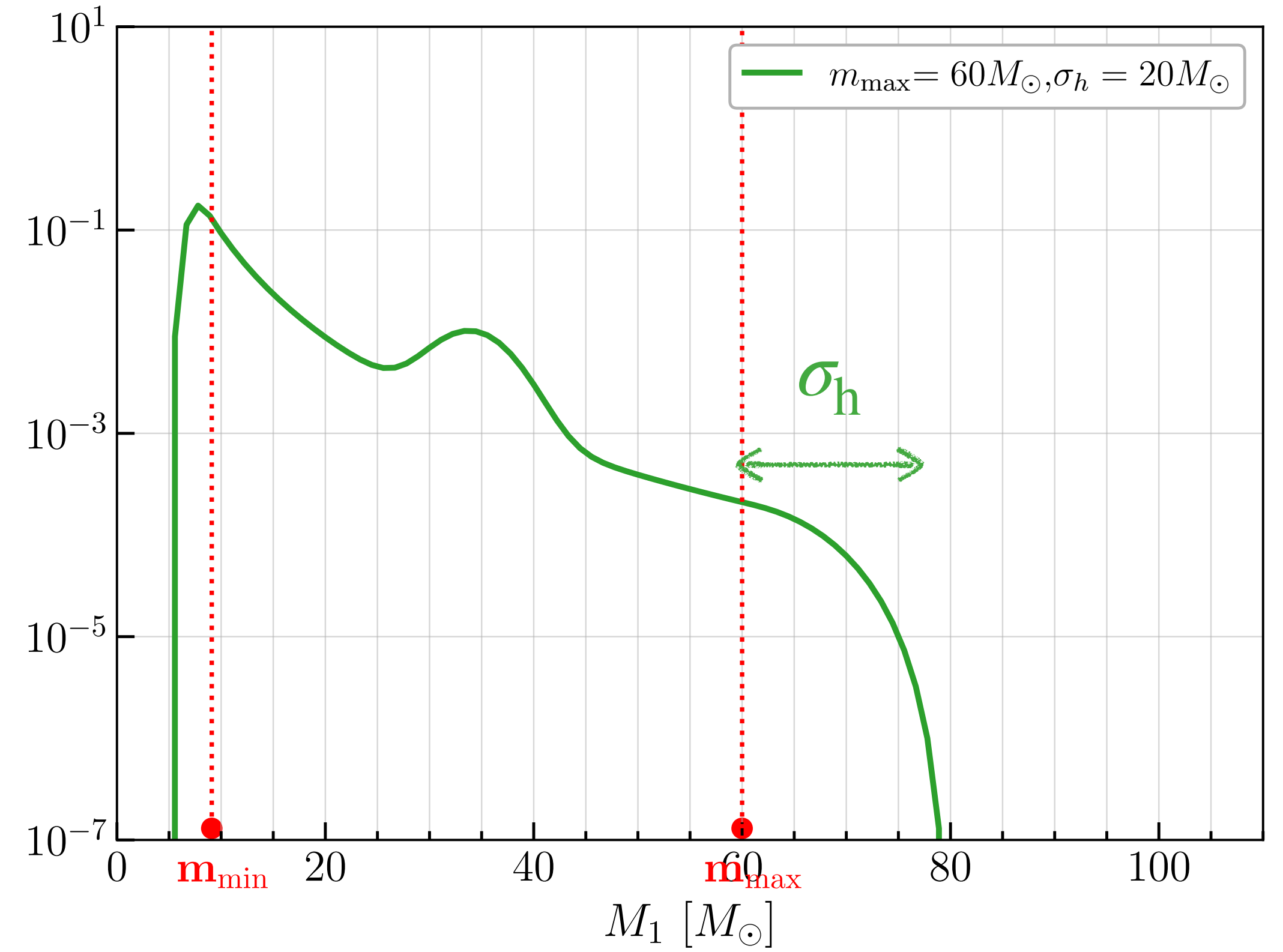
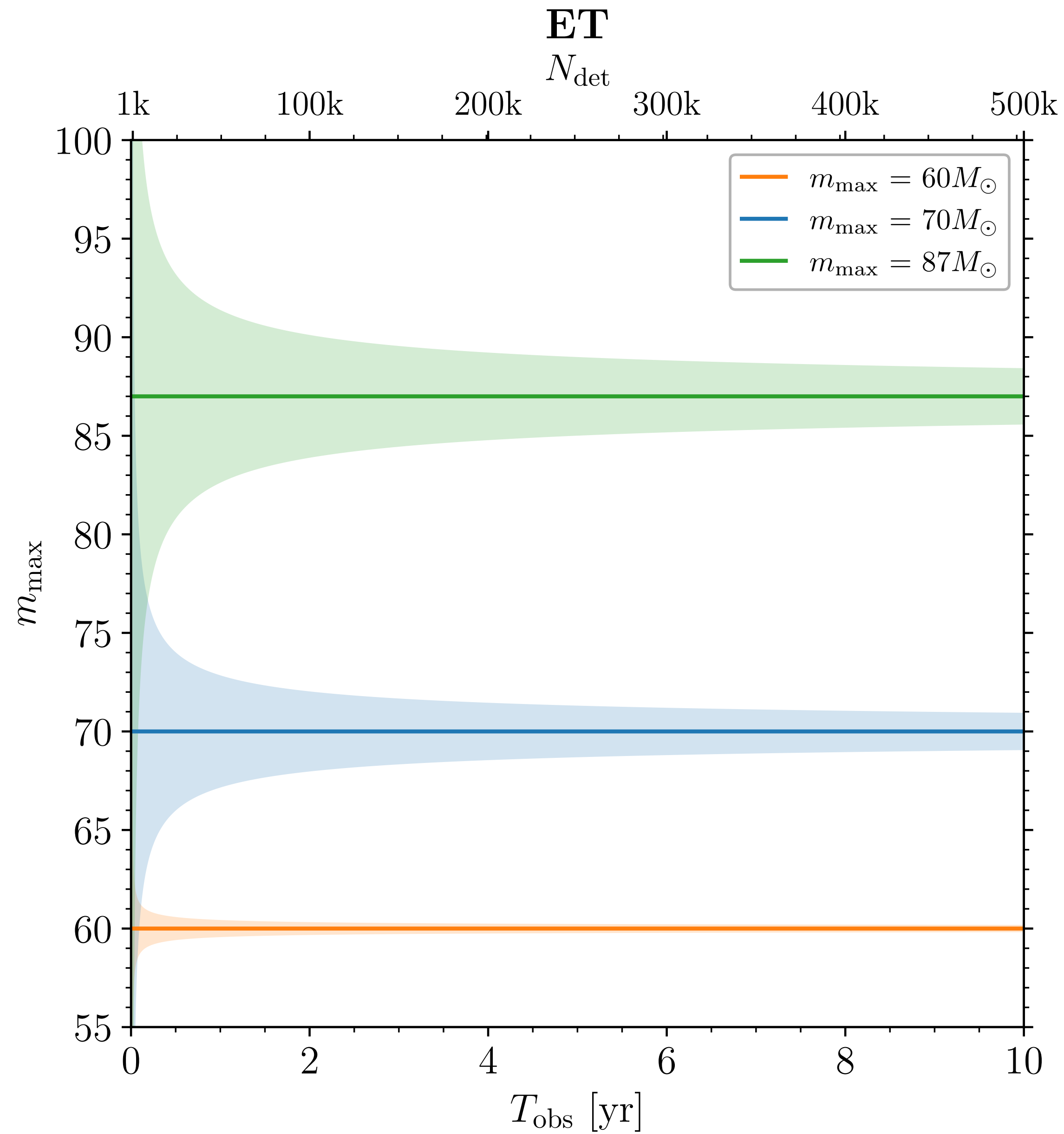
Mass hyperparameters: Variation of m_{\max}



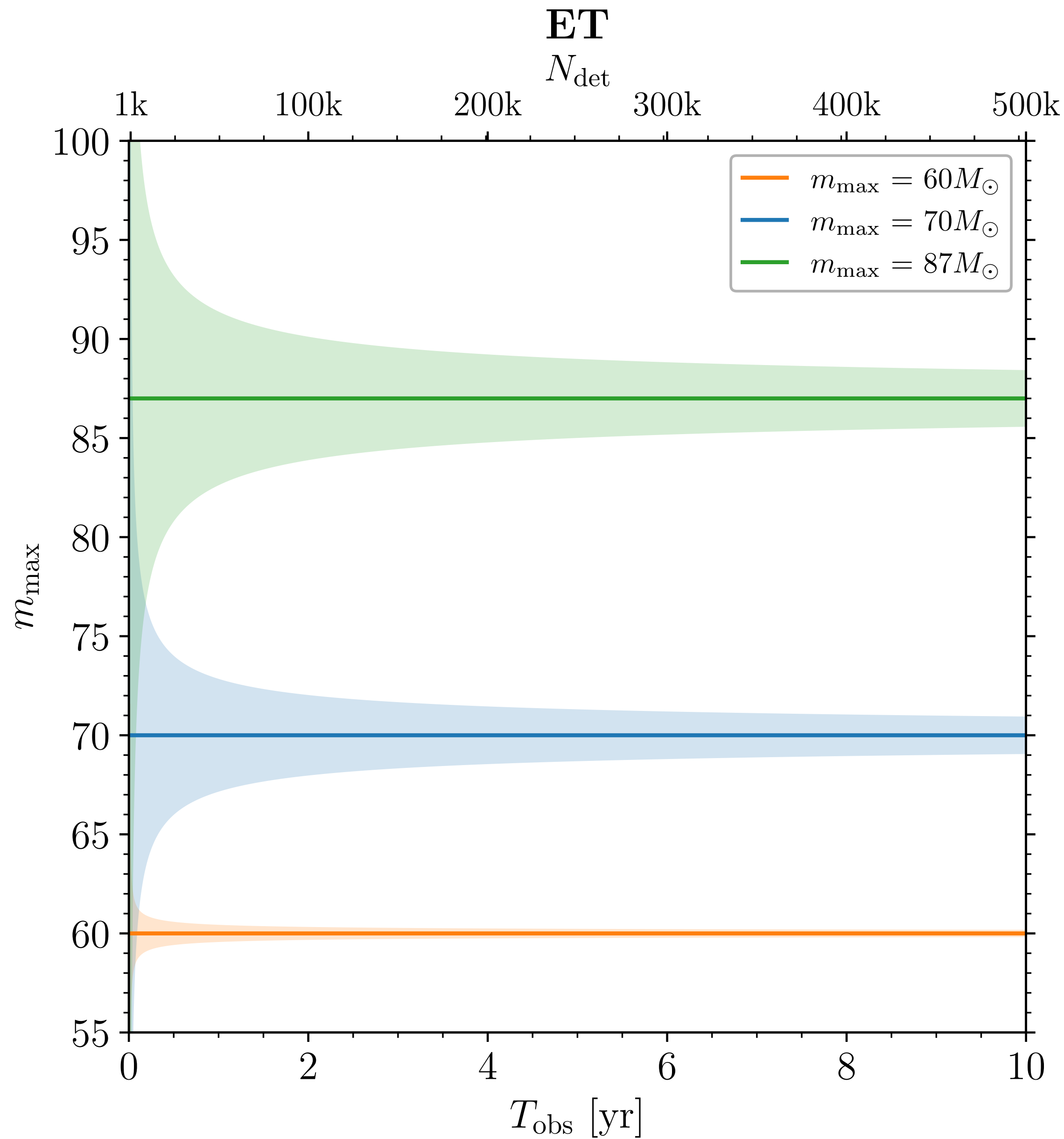
Mass hyperparameters: Variation of m_{\max}



Mass hyperparameters: Variation of m_{\max}



Mass hyperparameters: Variation of m_{\max}



Absolute errors after 10 years of observation

σ_{λ}	$m_{\max} = 60M_{\odot}$	$m_{\max} = 70M_{\odot}$	$m_{\max} = 87M_{\odot}$
α_m	2.79×10^{-3}	2.49×10^{-3}	5.14×10^{-3}
β_q	7.13×10^{-3}	8.04×10^{-3}	7.83×10^{-3}
m_{\min}	1.02×10^{-2}	9.48×10^{-3}	9.66×10^{-3}
m_{\max}	1.16×10^{-1}	8.78×10^{-1}	1.36
λ_{peak}	2.05×10^{-4}	1.88×10^{-4}	2.27×10^{-4}
σ_l	1.15×10^{-2}	1.07×10^{-2}	1.08×10^{-2}
σ_h	1.18×10^{-1}	1.31	2.06
μ_m	2.47×10^{-2}	2.51×10^{-2}	2.29×10^{-2}
σ_m	2.48×10^{-2}	2.99×10^{-2}	2.05×10^{-2}

- The errors decrease for smaller values of m_{\max}
- Correlation between σ_h and m_{\max}
- The errors on the other mass parameters remain approximately stable using different m_{\max}

Redshift hyperparameters

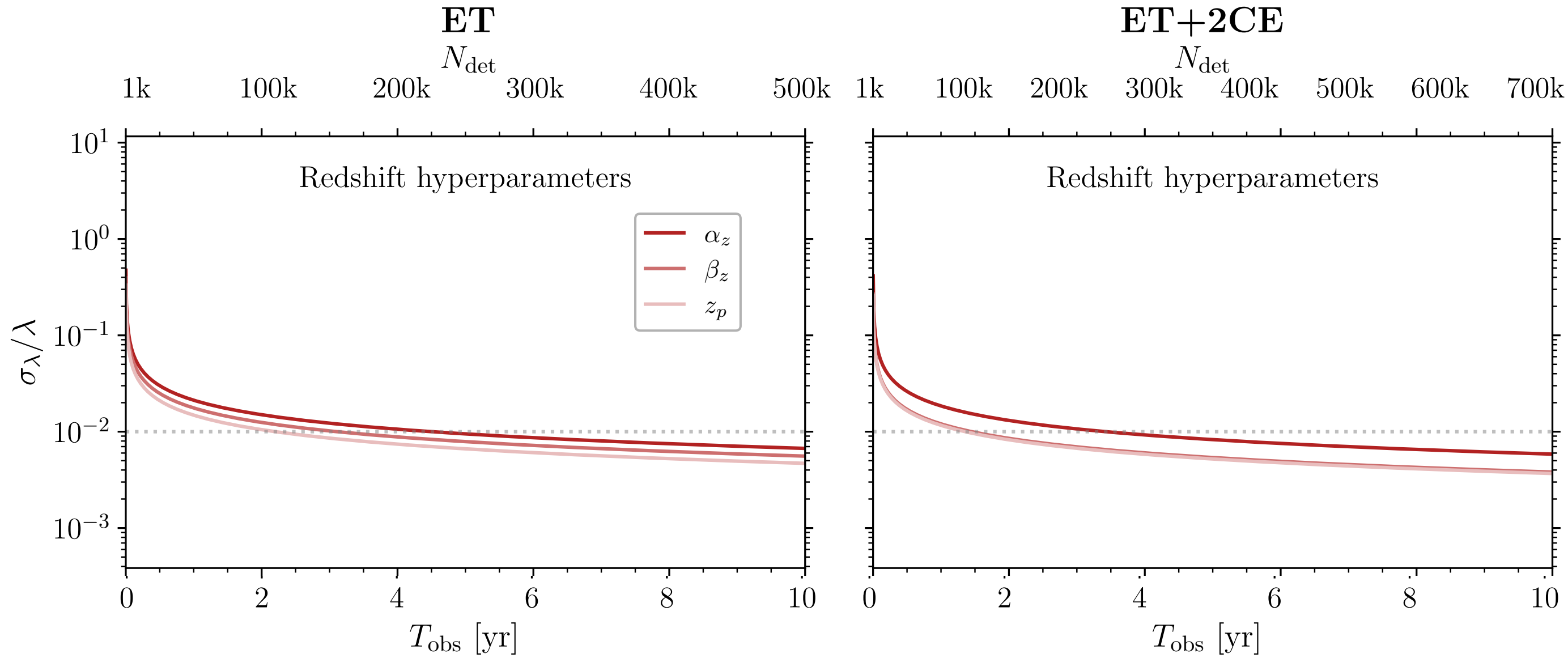
- ⊛ No big difference between ET and ET+2CE (the scale of the problem is the number of detections!)

Relative errors after 10 years of observation

σ_λ/λ	ET	$T_{0.01}^{ET}$	ET+2CE	$T_{0.01}^{ET+2CE}$
α_z	6.71×10^{-3}	4.5	5.85×10^{-3}	1.4
β_z	5.57×10^{-3}	3.1	3.81×10^{-3}	0.2
z_p	4.69×10^{-3}	2.2	3.68×10^{-3}	0.2



A network of well-separated interferometers has better sky localization capabilities, resulting in an improved distance (and thus redshift) determination



Preliminary

Spin hyperparameters

Preliminary

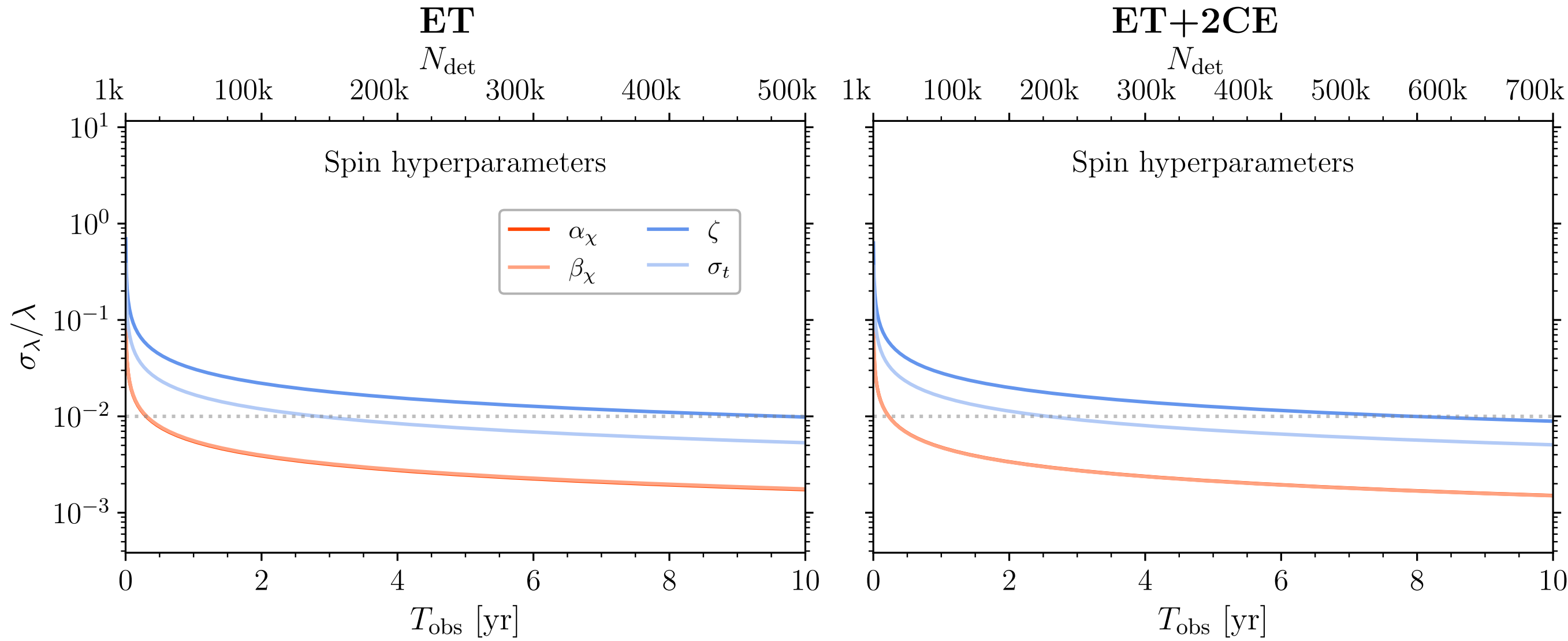
- ✱ No big difference between ET and ET+2CE (the scale of the problem is the number of detections!)

Relative errors after 10 years of observation

σ_{λ}/λ	ET	$T_{0.01}^{ET}$	ET+2CE	$T_{0.01}^{ET+2CE}$
α_{χ}	1.74×10^{-3}	0.3	1.51×10^{-3}	0.2
β_{χ}	1.77×10^{-3}	0.3	1.50×10^{-3}	0.2
ζ_{χ}	9.83×10^{-3}	9.7	8.90×10^{-3}	7.9
σ_t	5.32×10^{-3}	2.8	5.06×10^{-3}	2.6



- Difficulty in reconstructing spin directions even with the accuracy of 3G instruments.
- Single event errors are no more irrelevant for spins



Spin magnitudes

$$p(\chi_i | \alpha_{\chi}, \beta_{\chi}) \propto \chi_i^{\alpha-1} (1 - \chi_i)^{\beta-1}.$$

Spin tilts

$$p(\cos \theta_i | \zeta, \sigma_t) = \frac{1}{2} (1 - \zeta) + \zeta \mathcal{N}_{[-1,1]}(\cos \theta_i; 1, \sigma_t).$$

Conclusions

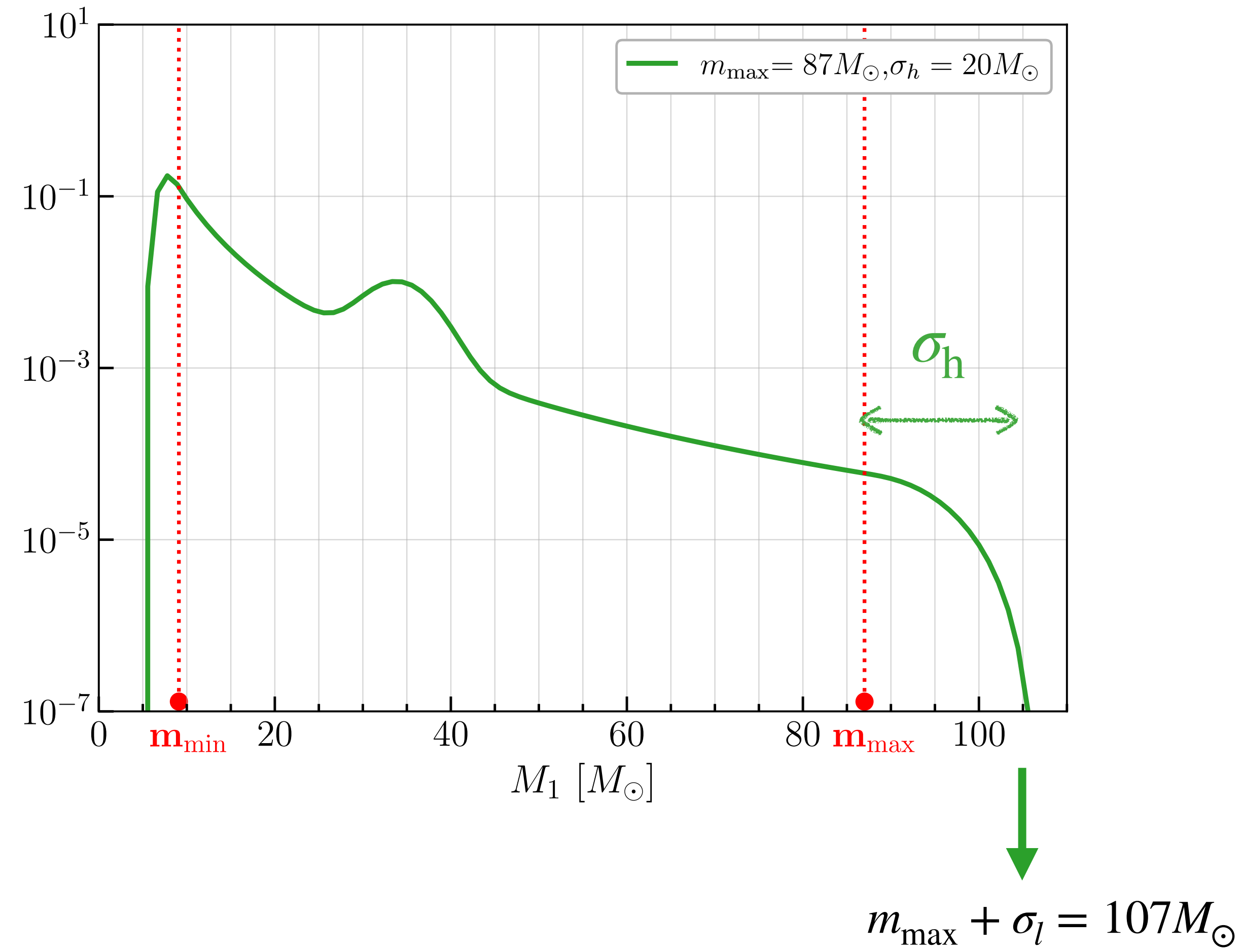
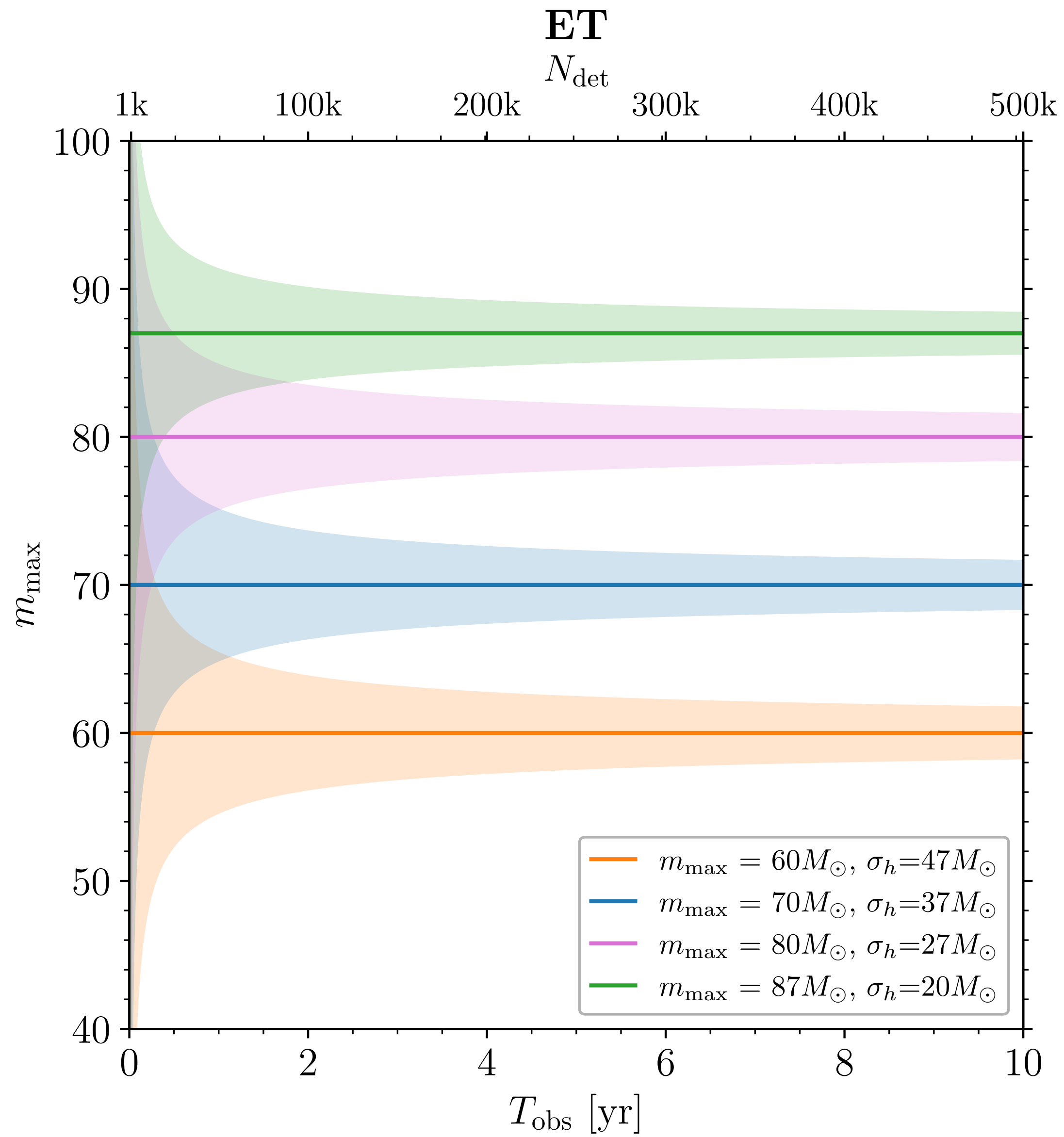
- ❑ We developed a (not yet public) Fisher code for population analysis with selection effects that enable the use of parametric (differentiable) models.
- ❑ Our forecast show the outstanding constraining power of 3G detectors
- ❑ After just a few years of observation, these detectors are projected to constrain hyperparameters with percent-level accuracy

Future work

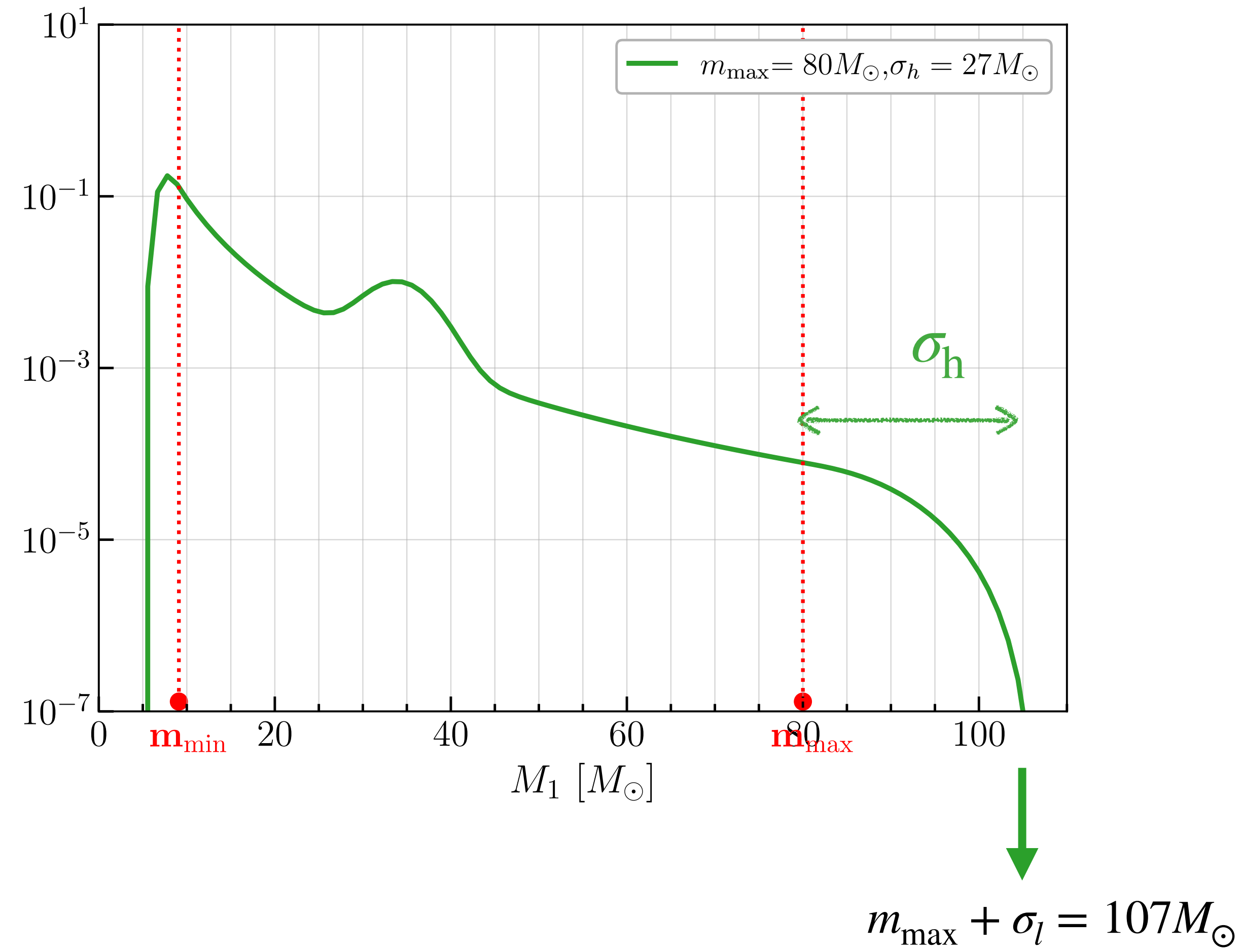
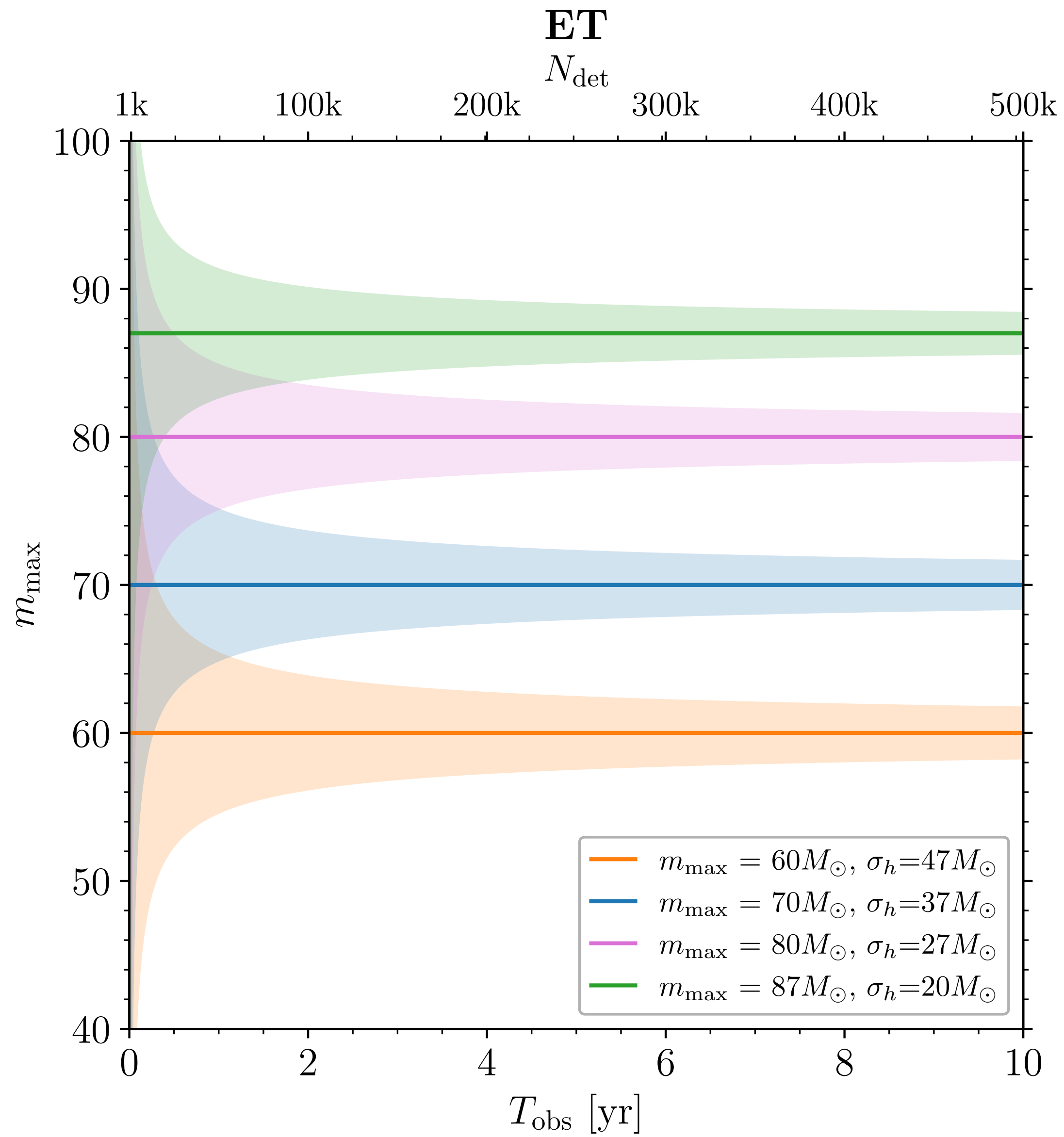
- ❑ Exploring the correlations between parameters
- ❑ Adding cosmology
- ❑ Perform hierarchical test of GR
- ❑ Other ideas?

Back up slides

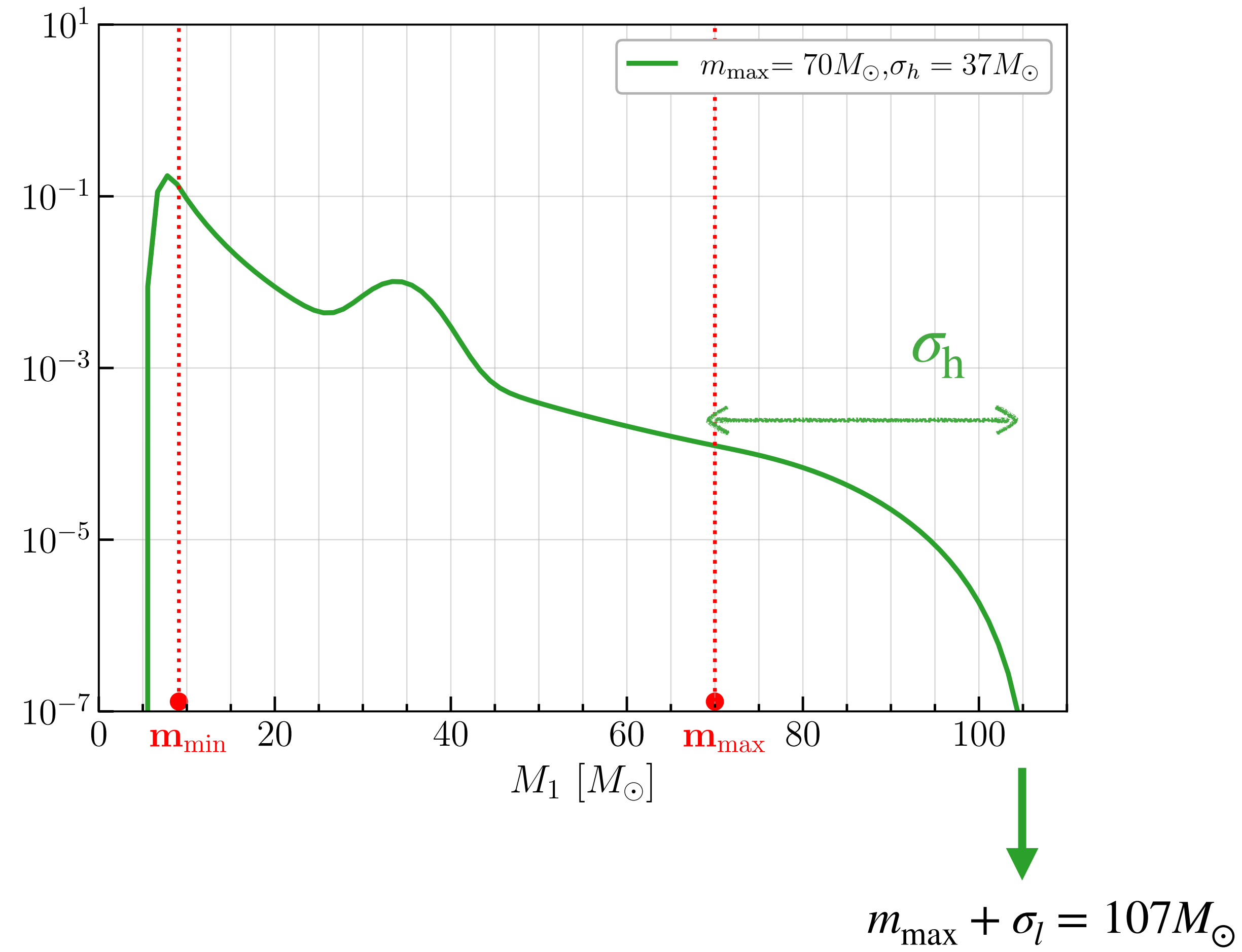
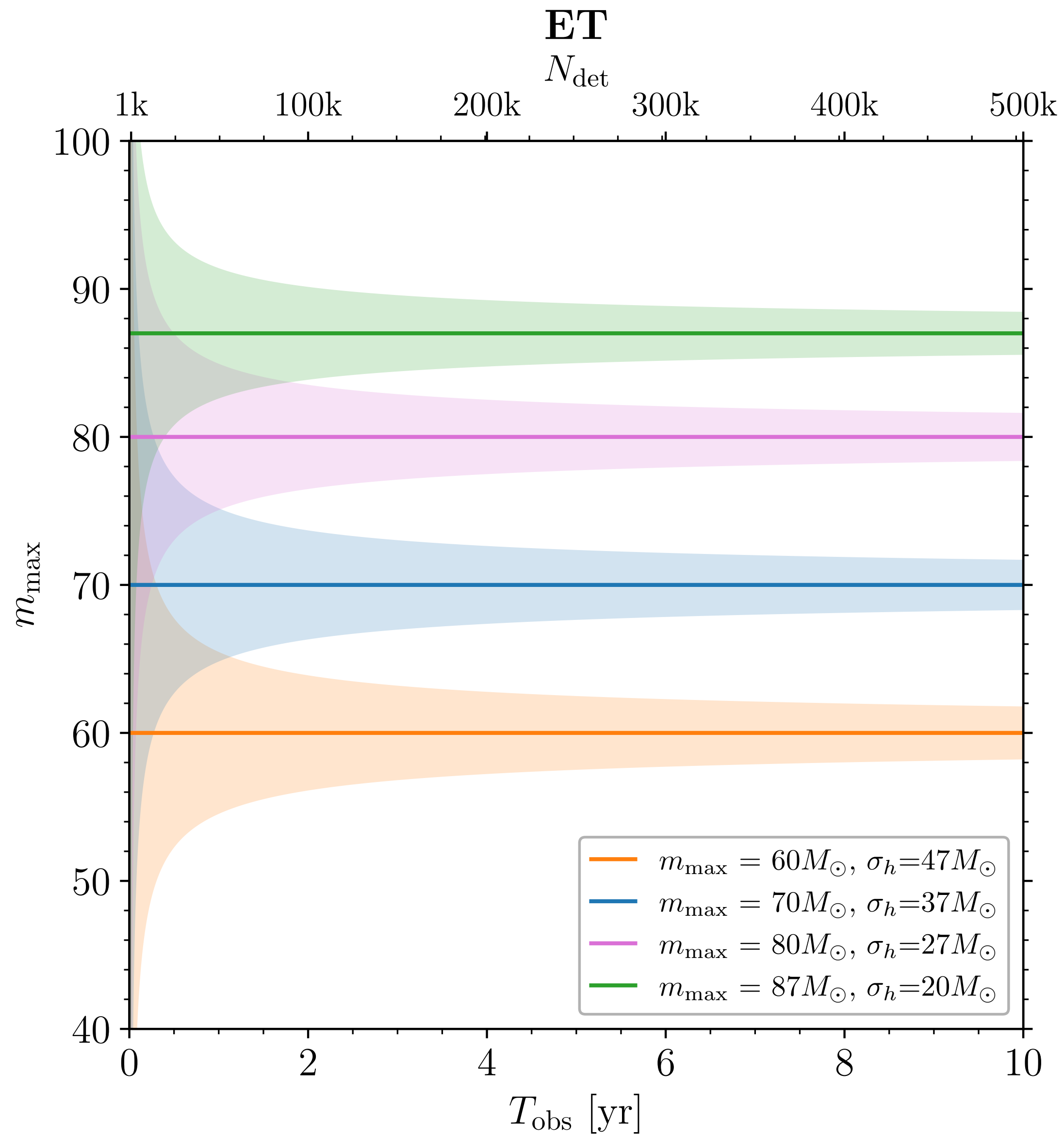
Mass hyperparameters: Variation of m_{\max} and σ_h



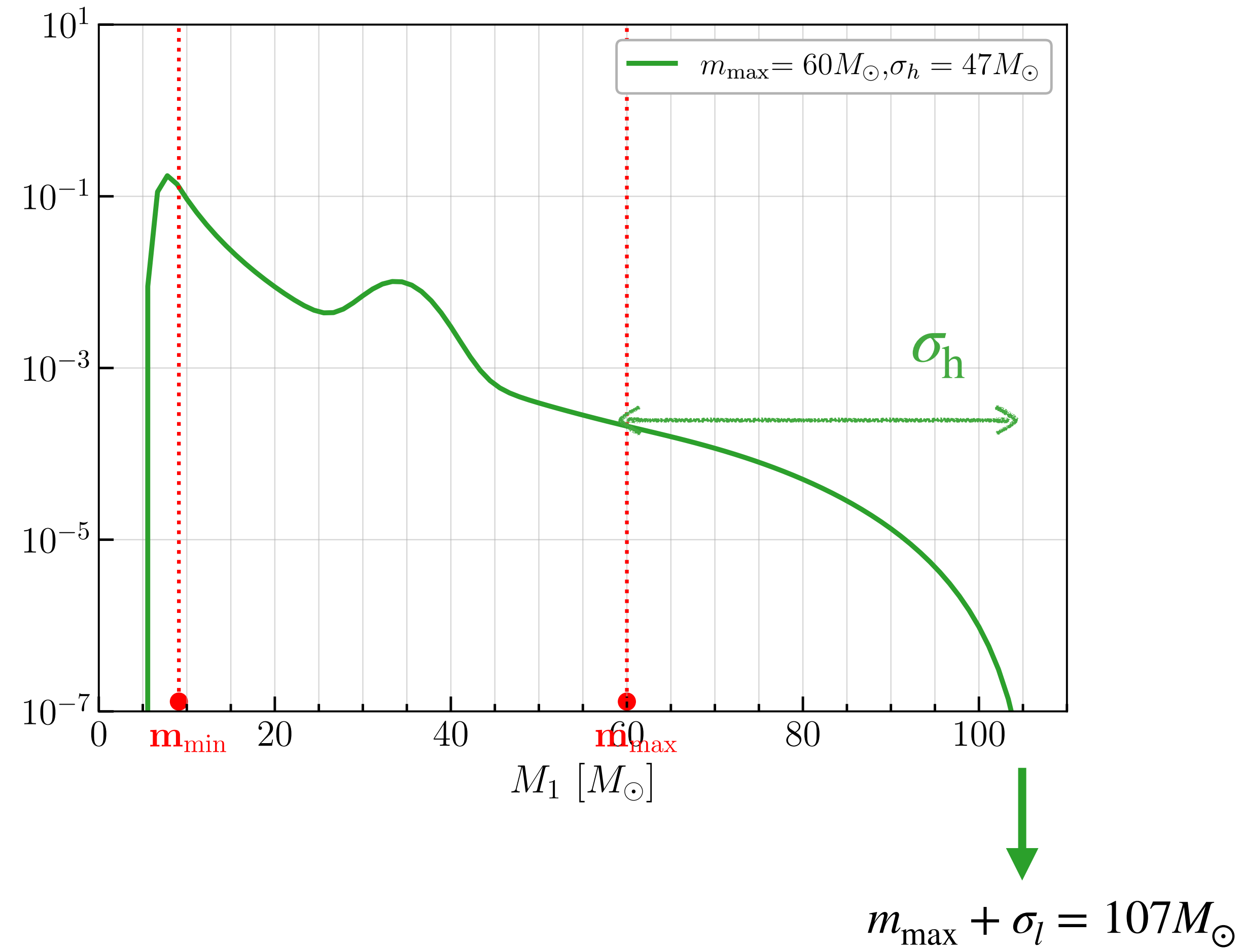
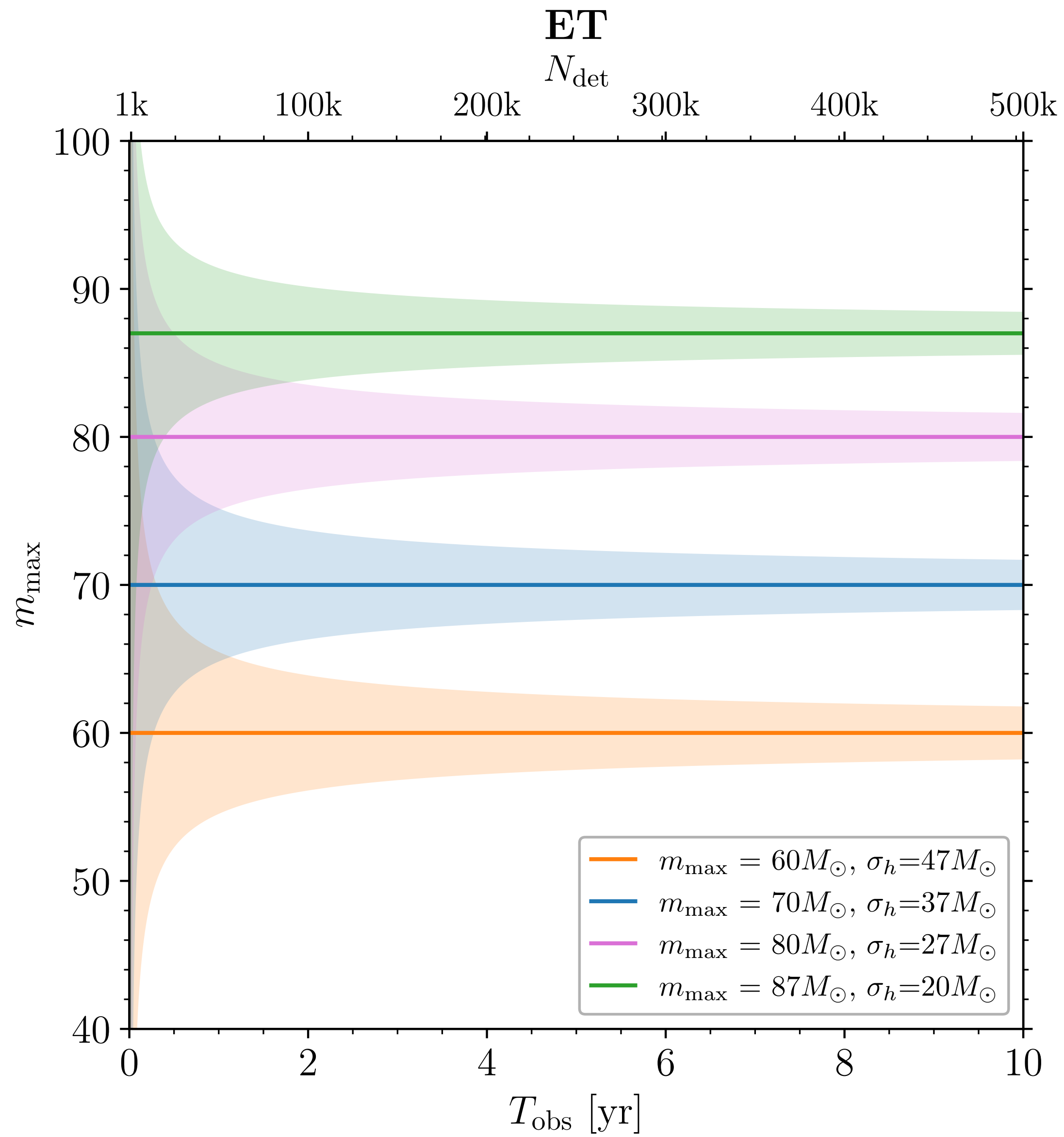
Mass hyperparameters: Variation of m_{\max} and σ_h



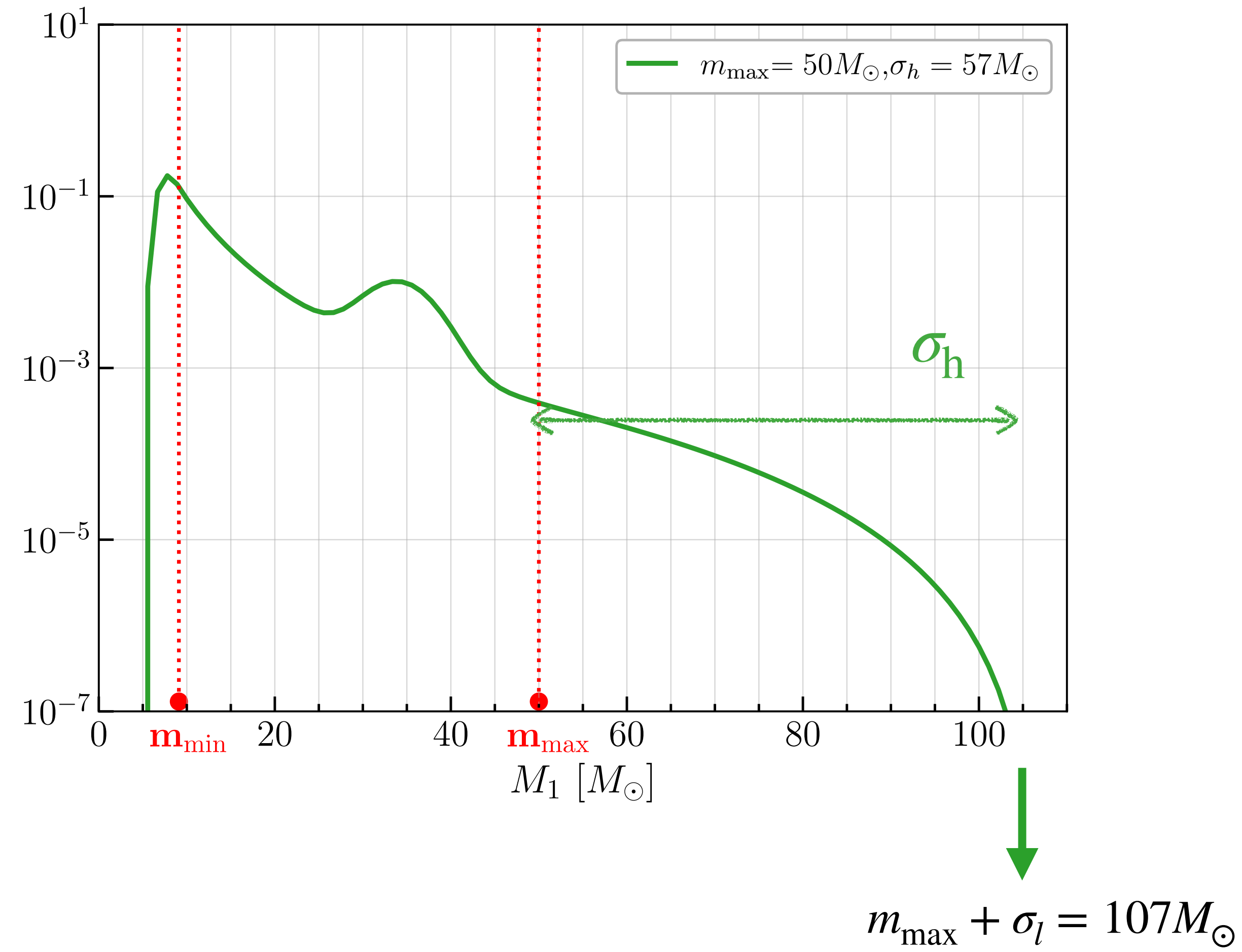
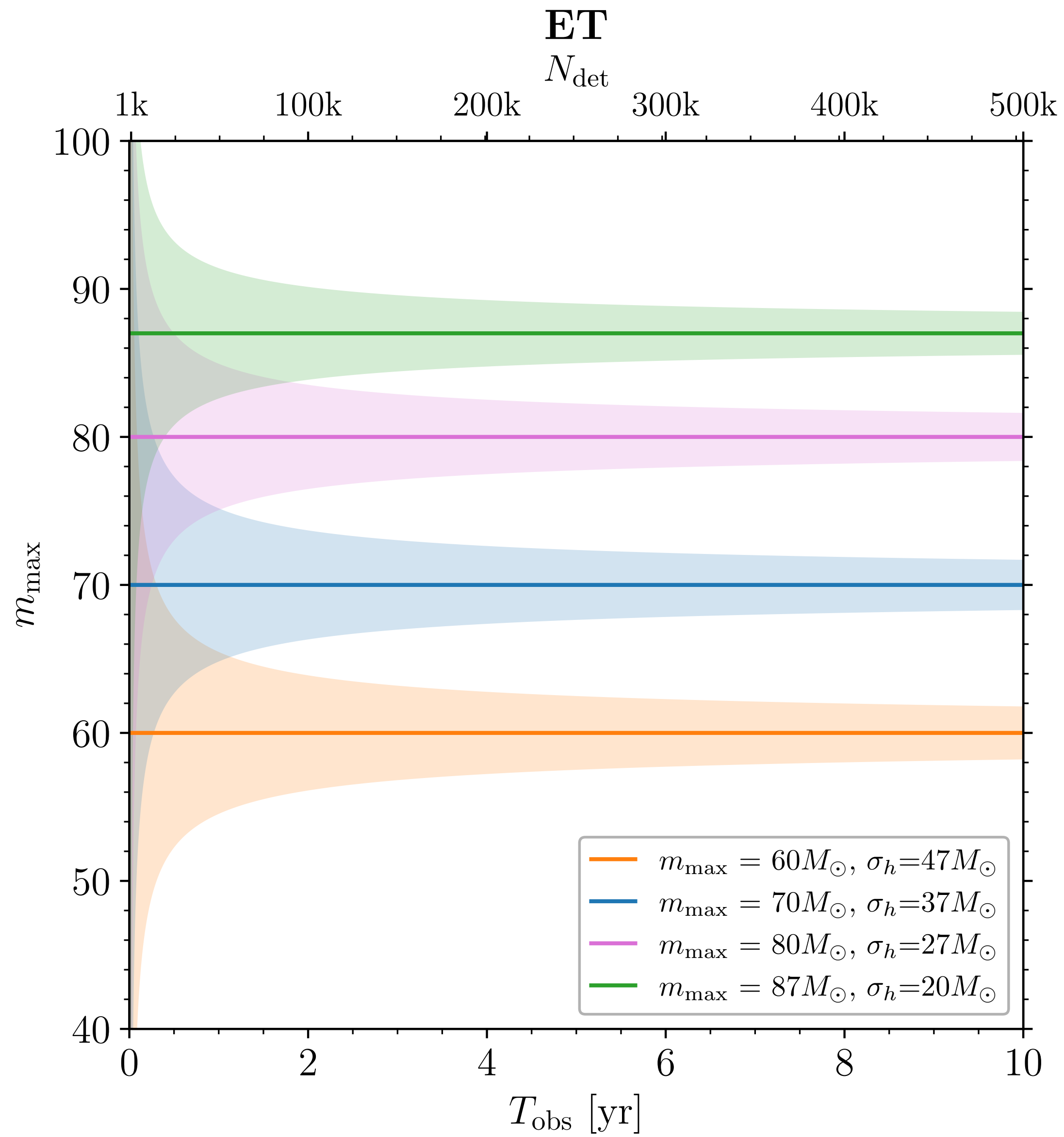
Mass hyperparameters: Variation of m_{\max} and σ_h



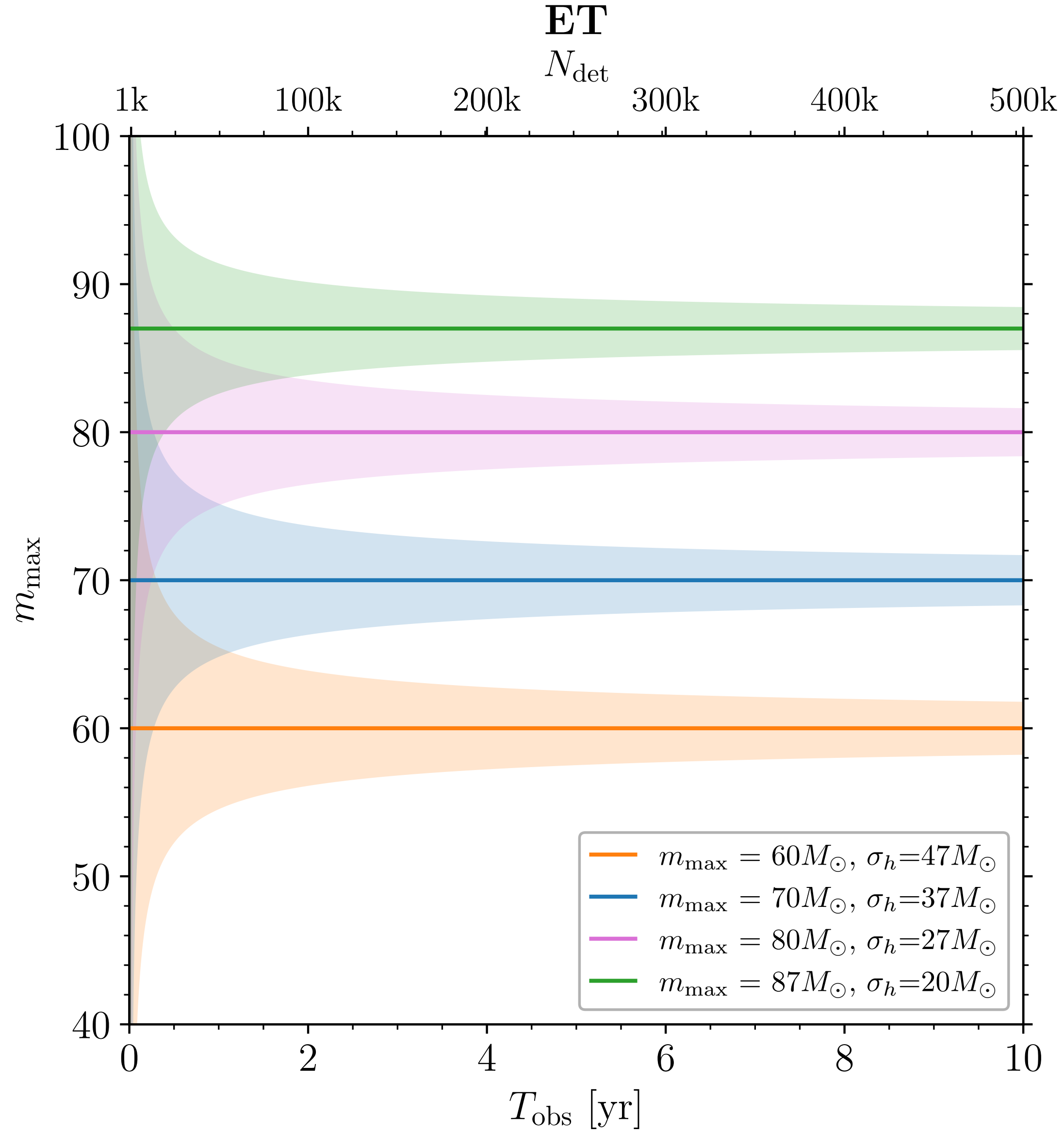
Mass hyperparameters: Variation of m_{\max} and σ_h



Mass hyperparameters: Variation of m_{\max} and σ_h



Mass hyperparameters: Variation of m_{\max} and σ_h



σ_{λ}	$m_{\max} = 60M_{\odot}$	$m_{\max} = 70M_{\odot}$	$m_{\max} = 80M_{\odot}$	$m_{\max} = 87M_{\odot}$
α_m	5.59×10^{-3}	5.40×10^{-3}	5.27×10^{-3}	5.14×10^{-3}
β_q	8.15×10^{-3}	8.12×10^{-3}	8.11×10^{-3}	7.83×10^{-3}
m_{\min}	9.38×10^{-3}	9.29×10^{-3}	9.23×10^{-3}	9.66×10^{-3}
m_{\max}	1.70	1.61	1.53	1.36
λ_{peak}	2.35×10^{-4}	2.35×10^{-4}	2.35×10^{-4}	2.27×10^{-4}
σ_l	1.03×10^{-2}	1.02×10^{-2}	1.02×10^{-2}	1.08×10^{-2}
σ_h	2.64	2.45	2.30	2.06
μ_m	2.40×10^{-2}	2.40×10^{-2}	2.39×10^{-2}	2.40×10^{-2}
σ_m	2.15×10^{-2}	2.14×10^{-2}	2.13×10^{-2}	2.05×10^{-2}

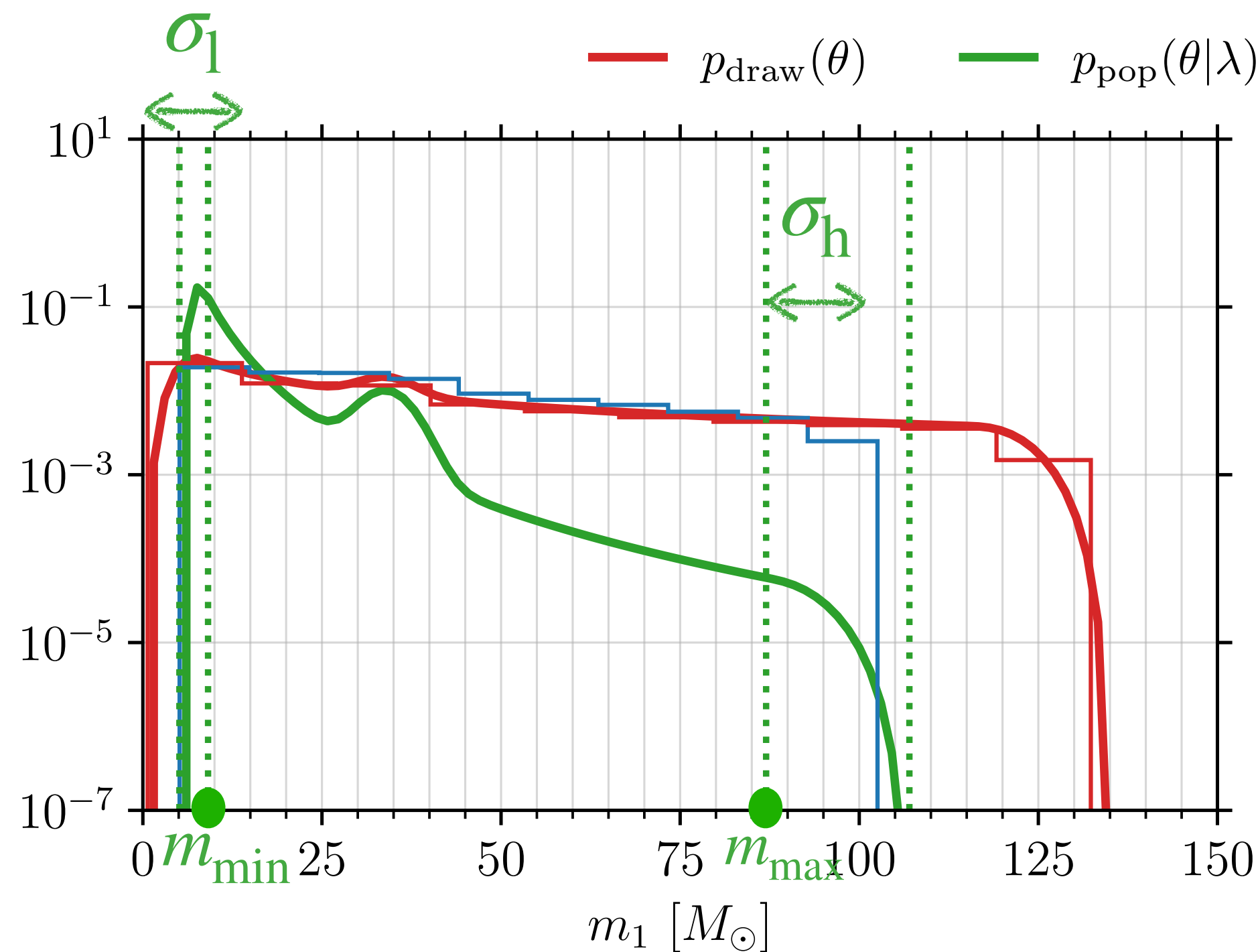
- The errors increase for smaller values of m_{\max}

Monte Carlo integration

We approximate the equation for $\Gamma_I, \Gamma_{II}, \Gamma_{III}, \Gamma_{IV}, \Gamma_V$ with Monte Carlo integrals

$$I(\lambda) = \int X(\theta, \lambda) p_{\text{draw}}(\theta) d\theta \simeq \frac{1}{N_{\text{draw}}} \sum_i^{N_{\text{draw}}} X(\theta_i, \lambda)$$

Mass distribution $p_{\text{pop}}(\theta | \lambda)$ = Power Law Plus Peak



Fiducial values for $p_{\text{draw}}(\theta)$

$$\alpha_m = \beta_q = 0.7$$

$$\sigma_1 = 8.7 M_{\odot} \quad \sigma_h = 20 M_{\odot}$$

$$m_{\text{min}} = 9.1 M_{\odot} \quad m_{\text{max}} = 115 M_{\odot}$$

Fiducial values for $p_{\text{pop}}(\theta | \lambda)$

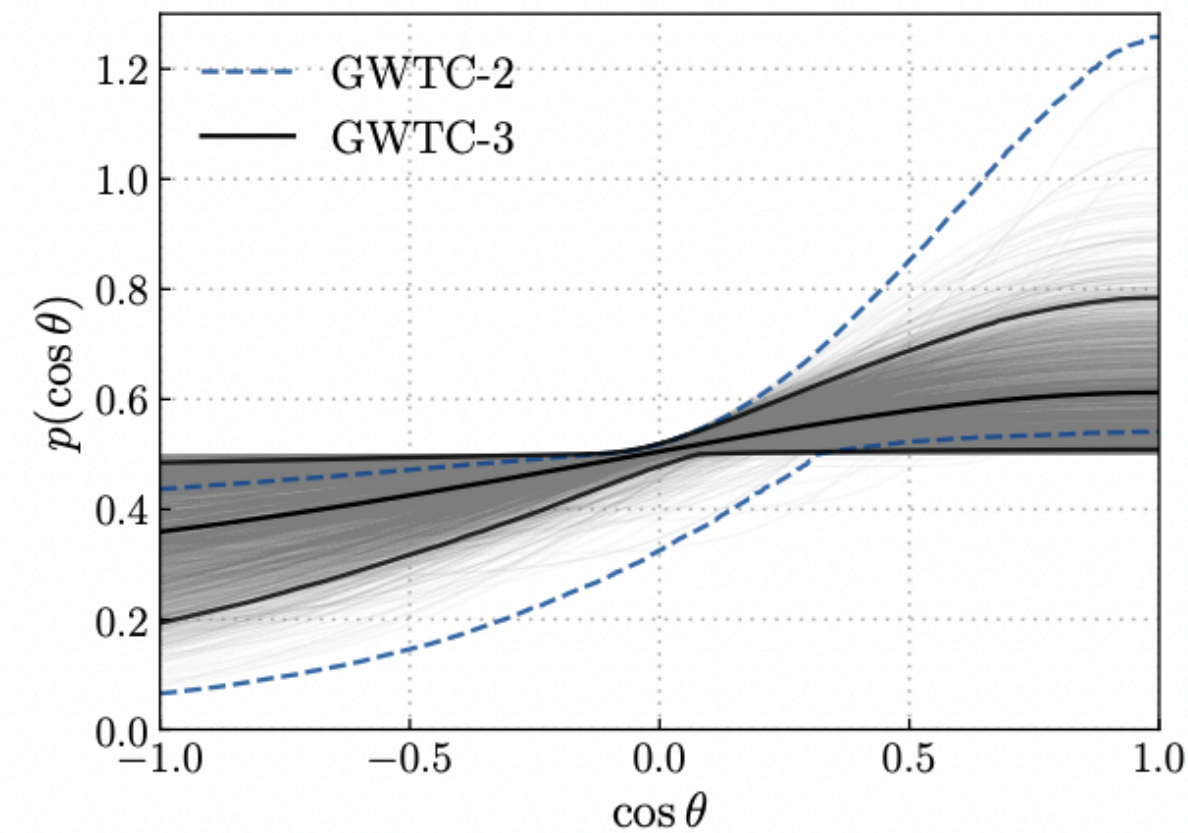
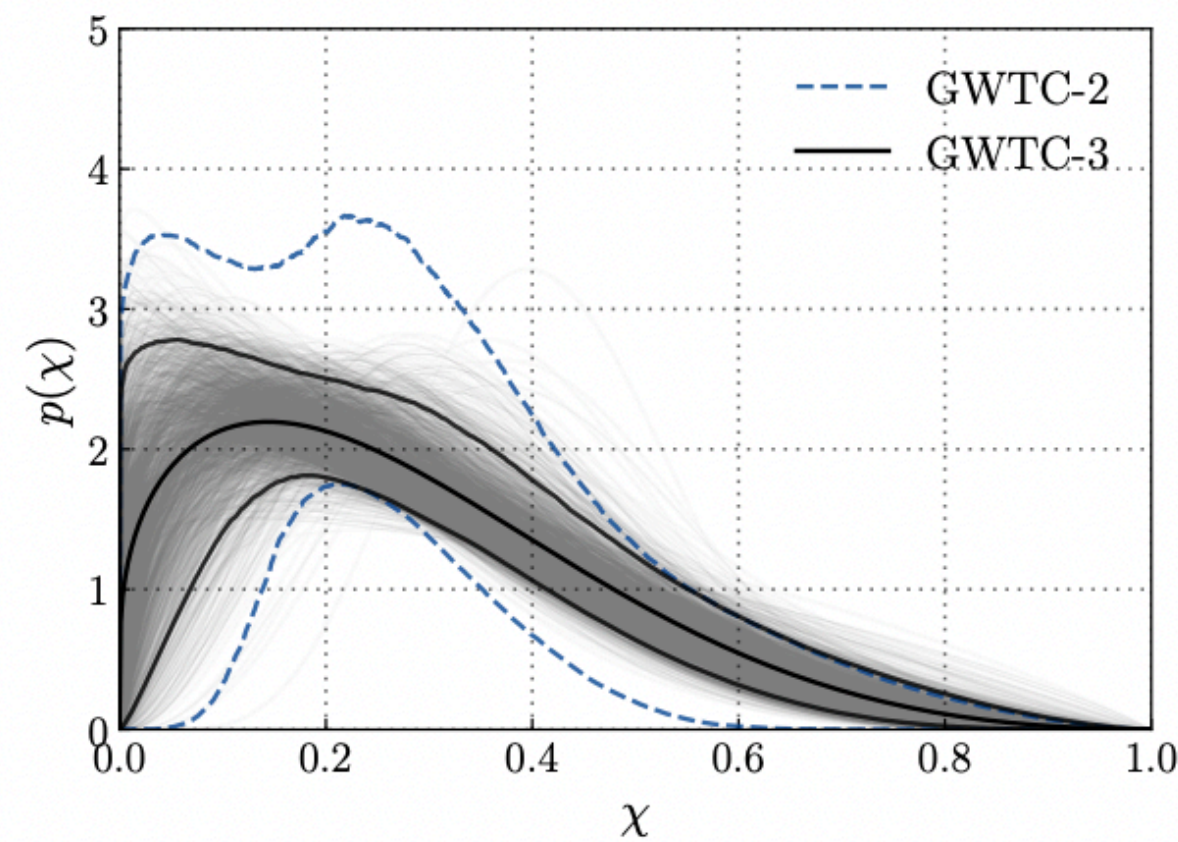
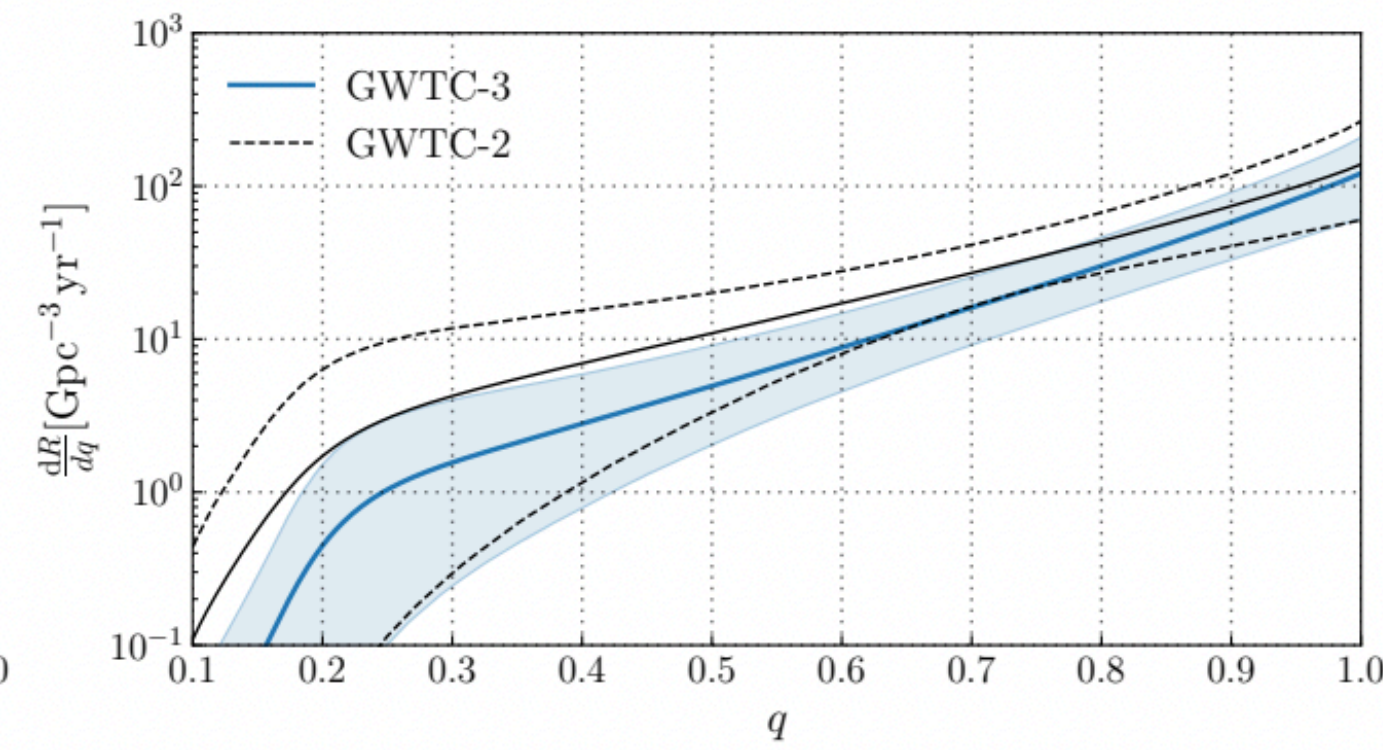
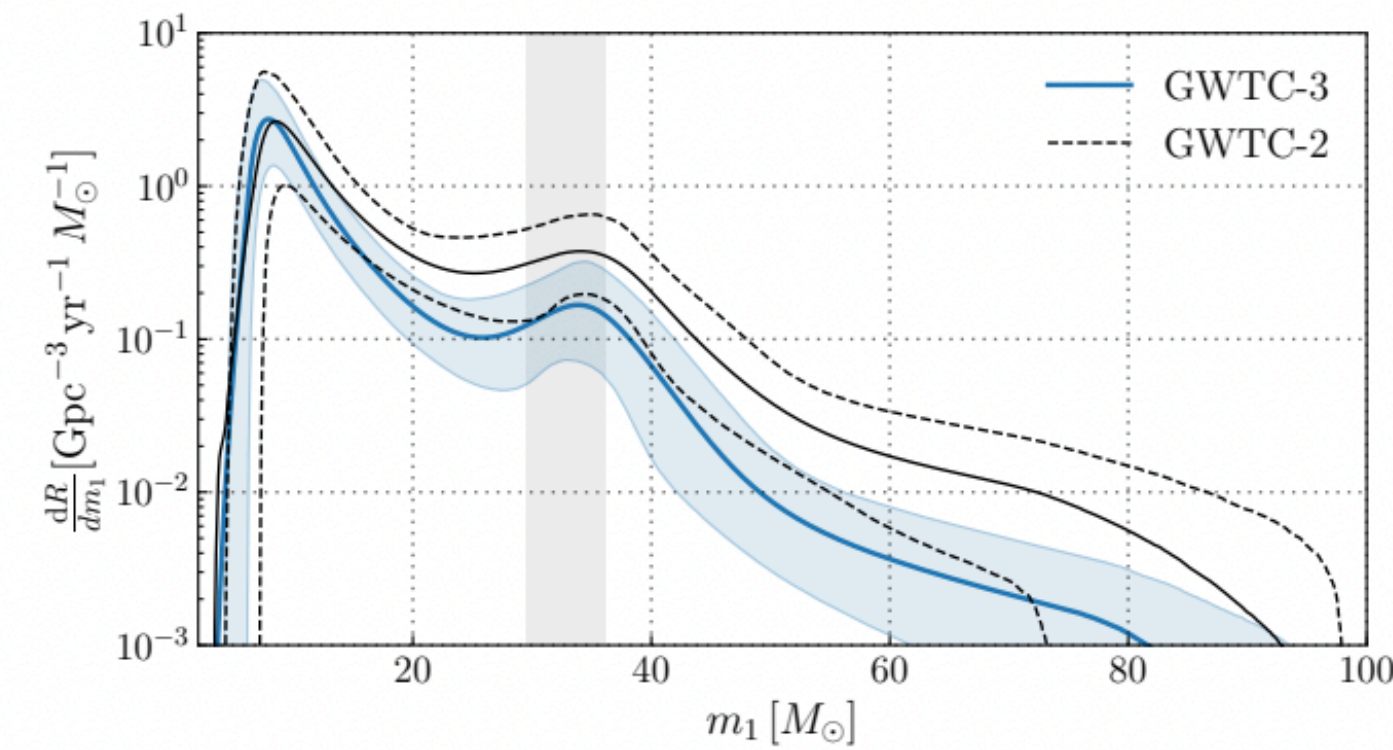
$$\alpha_m = 3.4 \quad \beta_q = 1.1$$

$$\sigma_1 = 5 M_{\odot} \quad \sigma_h = 20 M_{\odot}$$

$$m_{\text{min}} = 9.1 M_{\odot} \quad m_{\text{max}} = 87 M_{\odot}$$

Astrophysical implications

What's the formation, evolution, and distribution of BBHs in the universe?



- ✱ Lower mass end at $\sim 10M_\odot \rightarrow$ Field binaries
- ✱ $m_{\text{max}} \simeq 90M_\odot \rightarrow$ Hierarchical mergers in dense environments
- ✱ Peak at $\sim 34M_\odot \rightarrow$ Support for PISN mass gap between $\sim [40, 60]M_\odot$

- ✱ Low (but non-zero) spin magnitudes
- ✱ Mixture of aligned and misaligned spins
- ✱ Weak precession

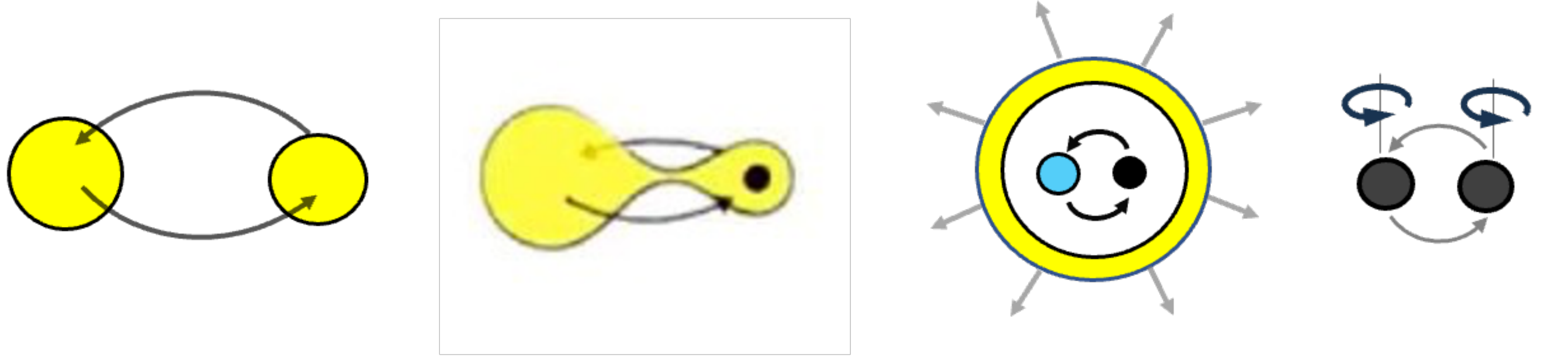


Mix of BBH formation channels (dynamical and isolated)

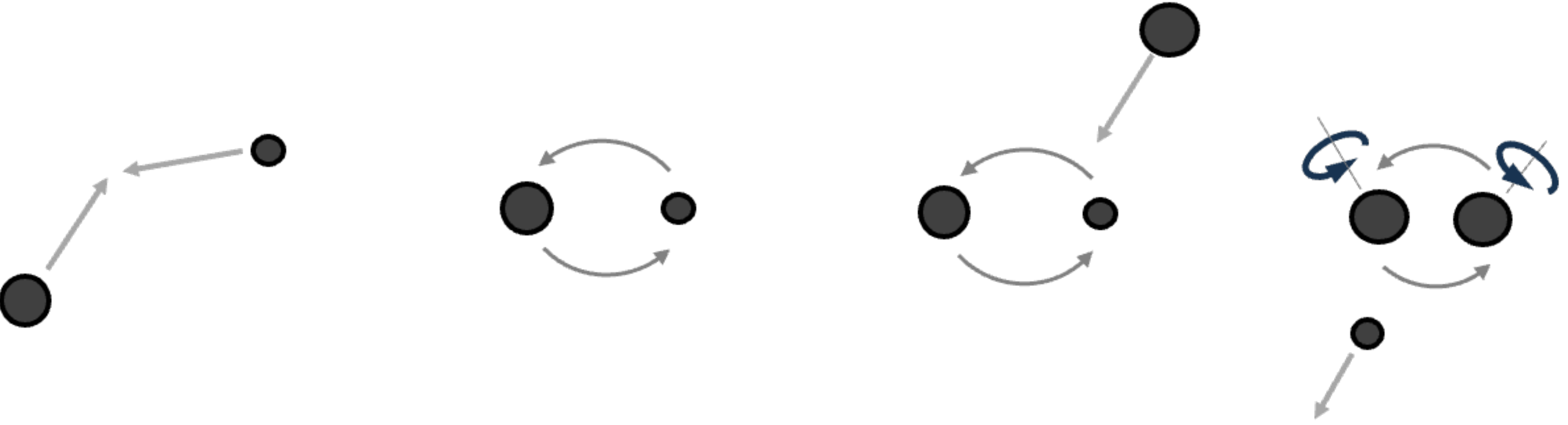
Astrophysical implications: spin distribution

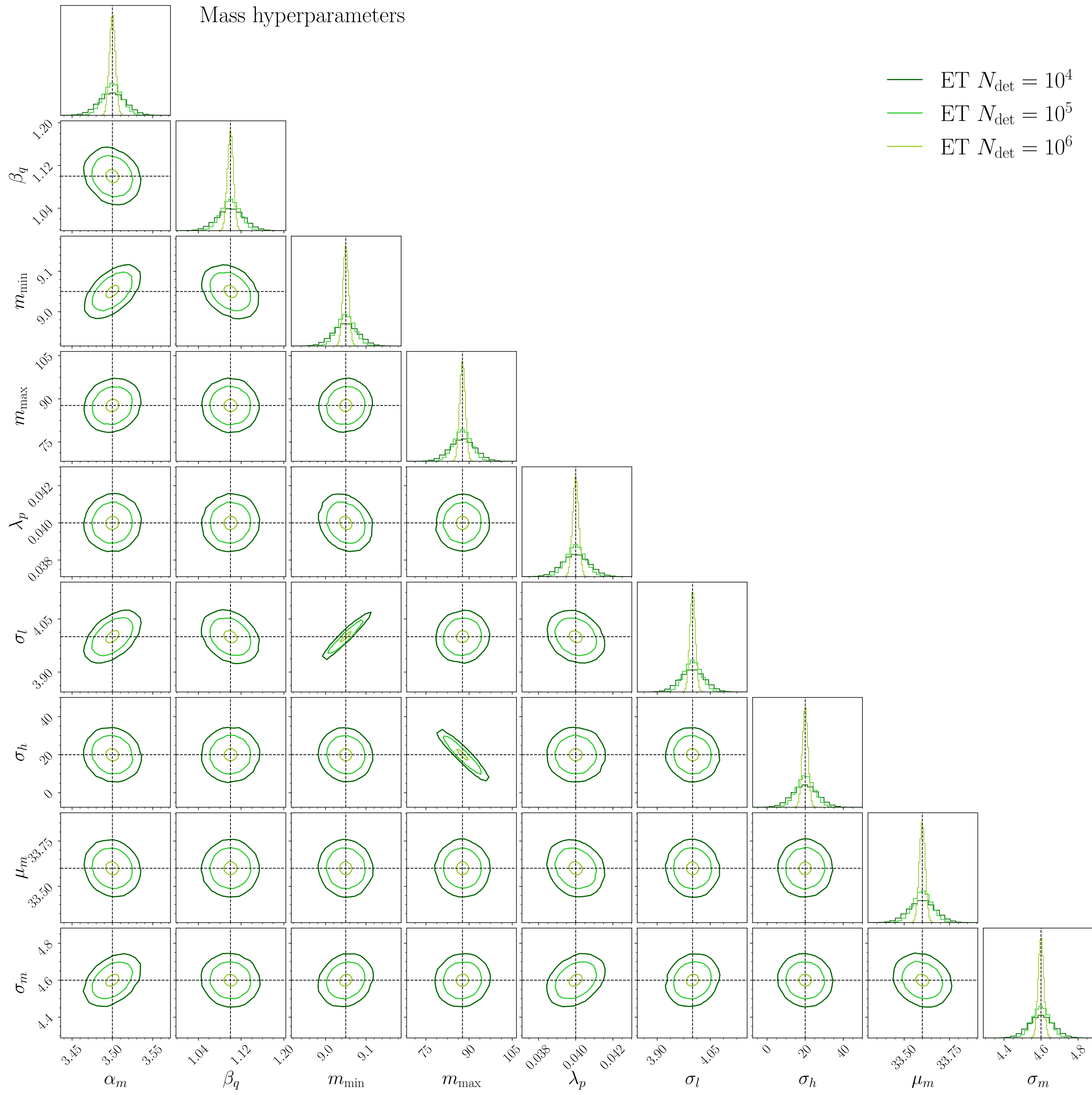
The directions of the BH spins are believed to be clean tracers of the astrophysical formation pathway

Isolated formation channel:
preferentially aligned spins
(non precessing binaries)



Dynamical formation channel:
isotropically oriented spins
(misalignment → spin precession)





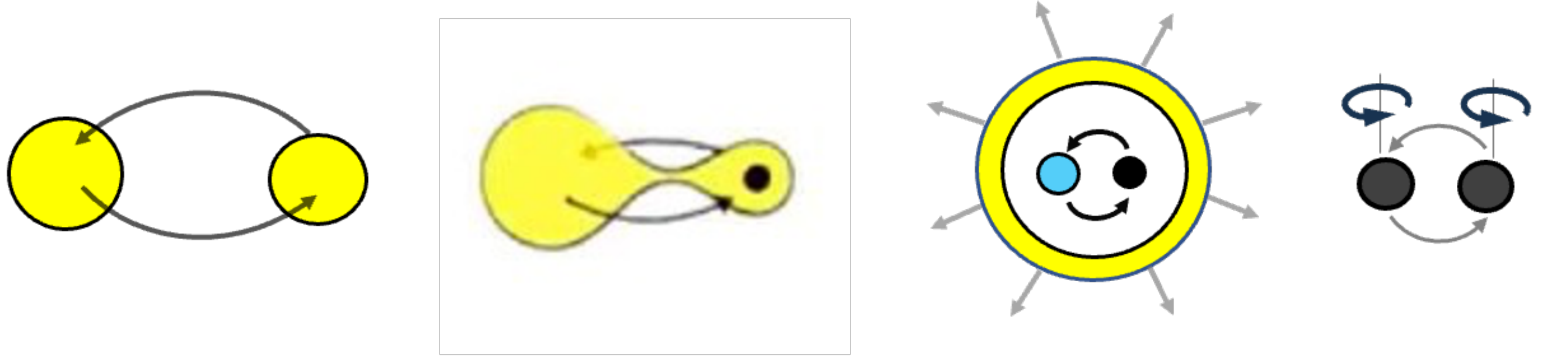
Mass hyperparameters: correlations

- ☼ Positive correlation between σ_l and m_{\min}
- ☼ Positive correlation between m_{\min} and α_m
- ☼ Positive correlation between m_{\min} and λ_{peak}
- ☼ Negative correlation between σ_h and m_{\max}

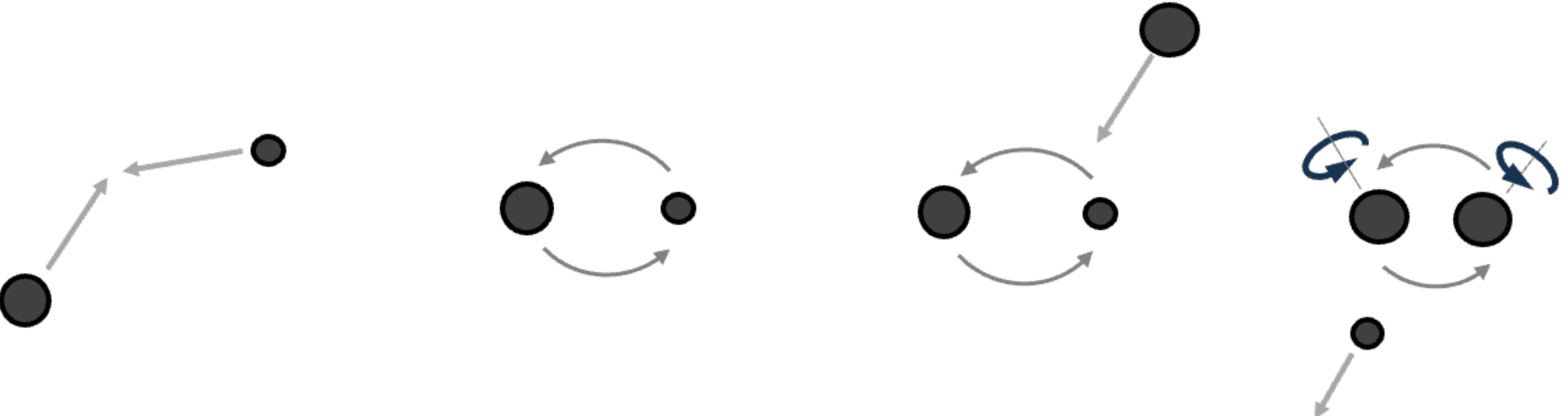
Astrophysical implications: spin distribution

The directions of the BH spins are believed to be clean tracers of the astrophysical formation pathway

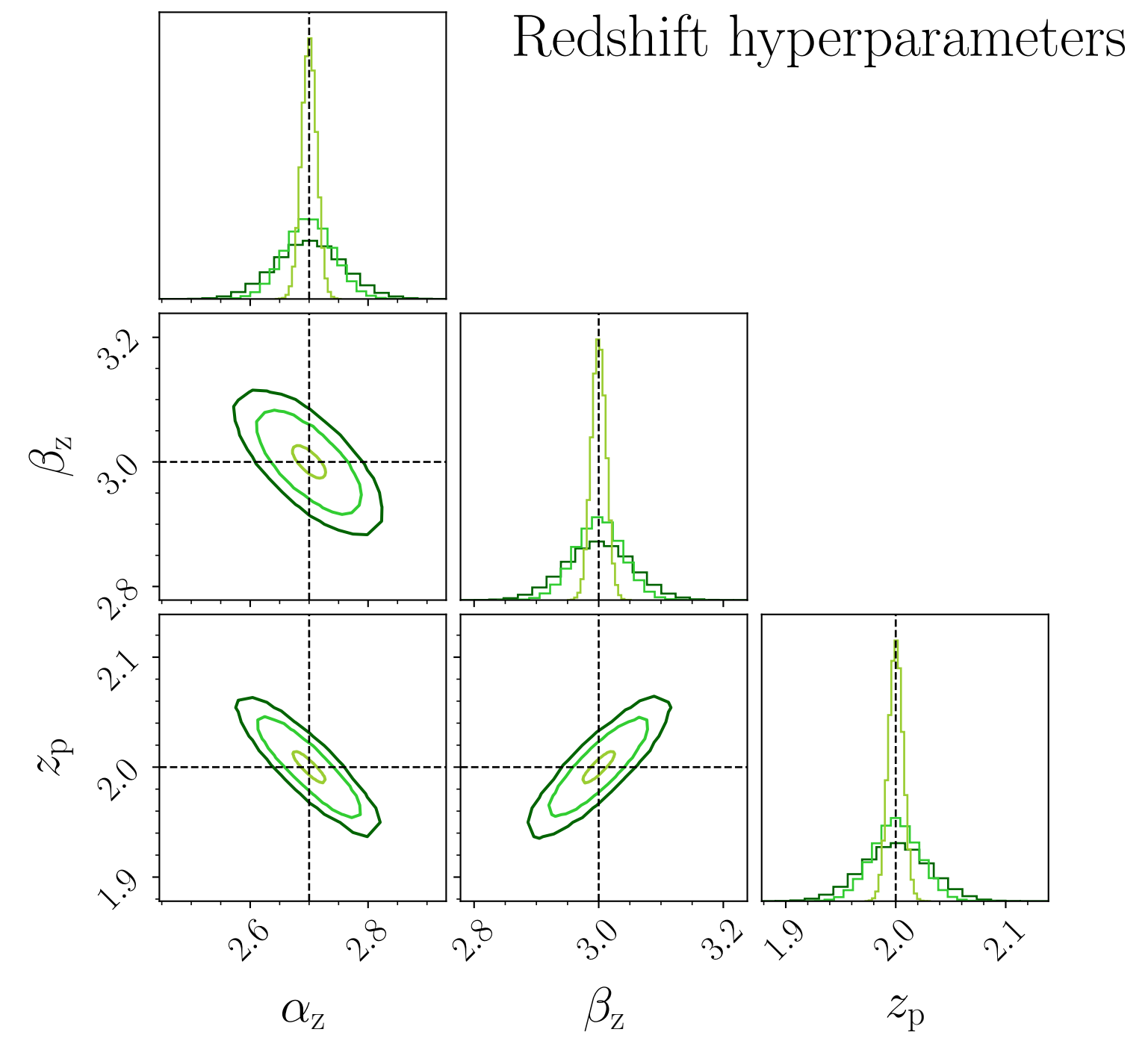
Isolated formation channel:
preferentially aligned spins
(non precessing binaries)



Dynamical formation channel:
isotropically oriented spins
(misalignment → spin precession)

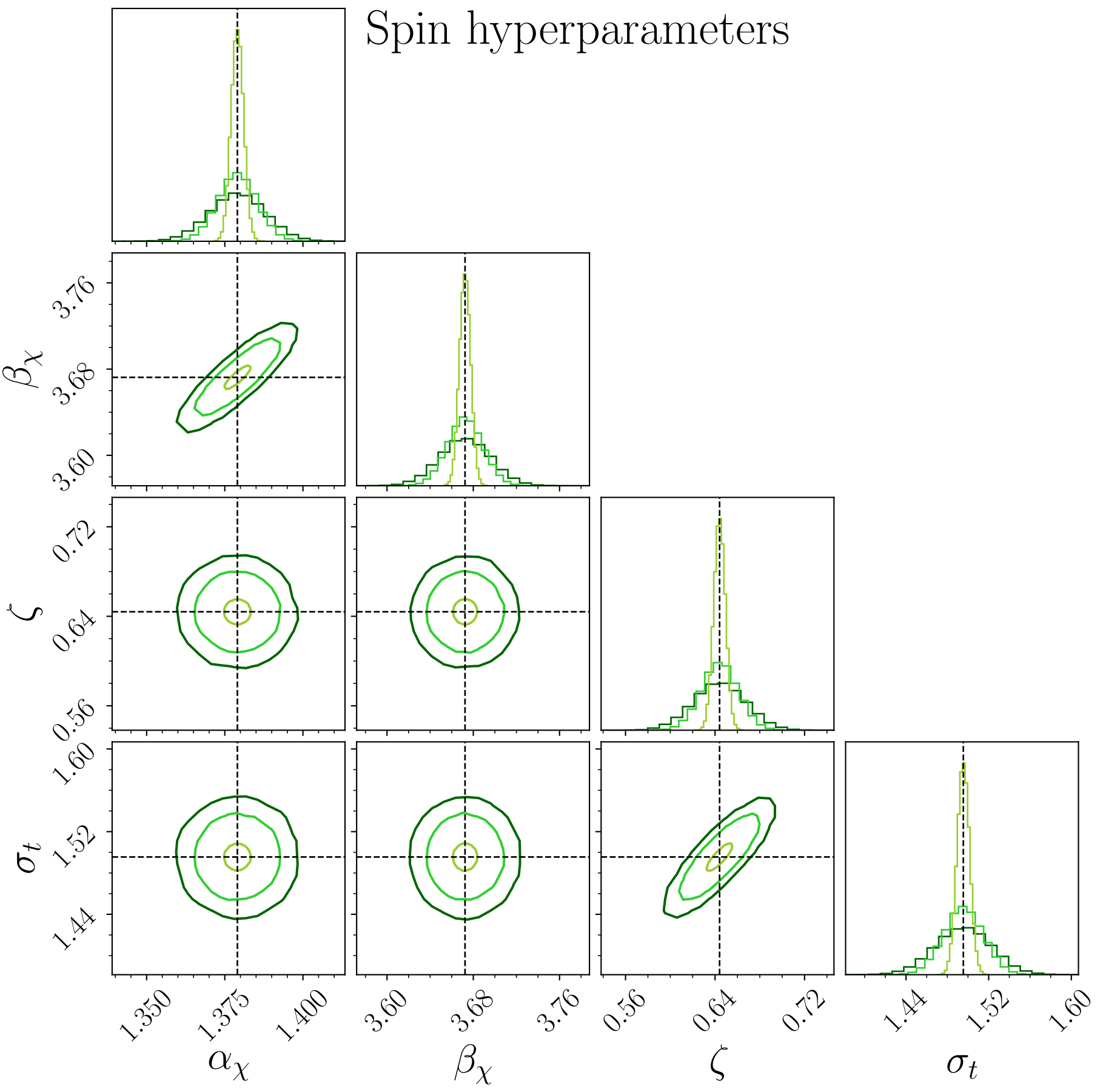


Redshift hyperparameters: correlations



Preliminary

Spin hyperparameters: correlations



Preliminary

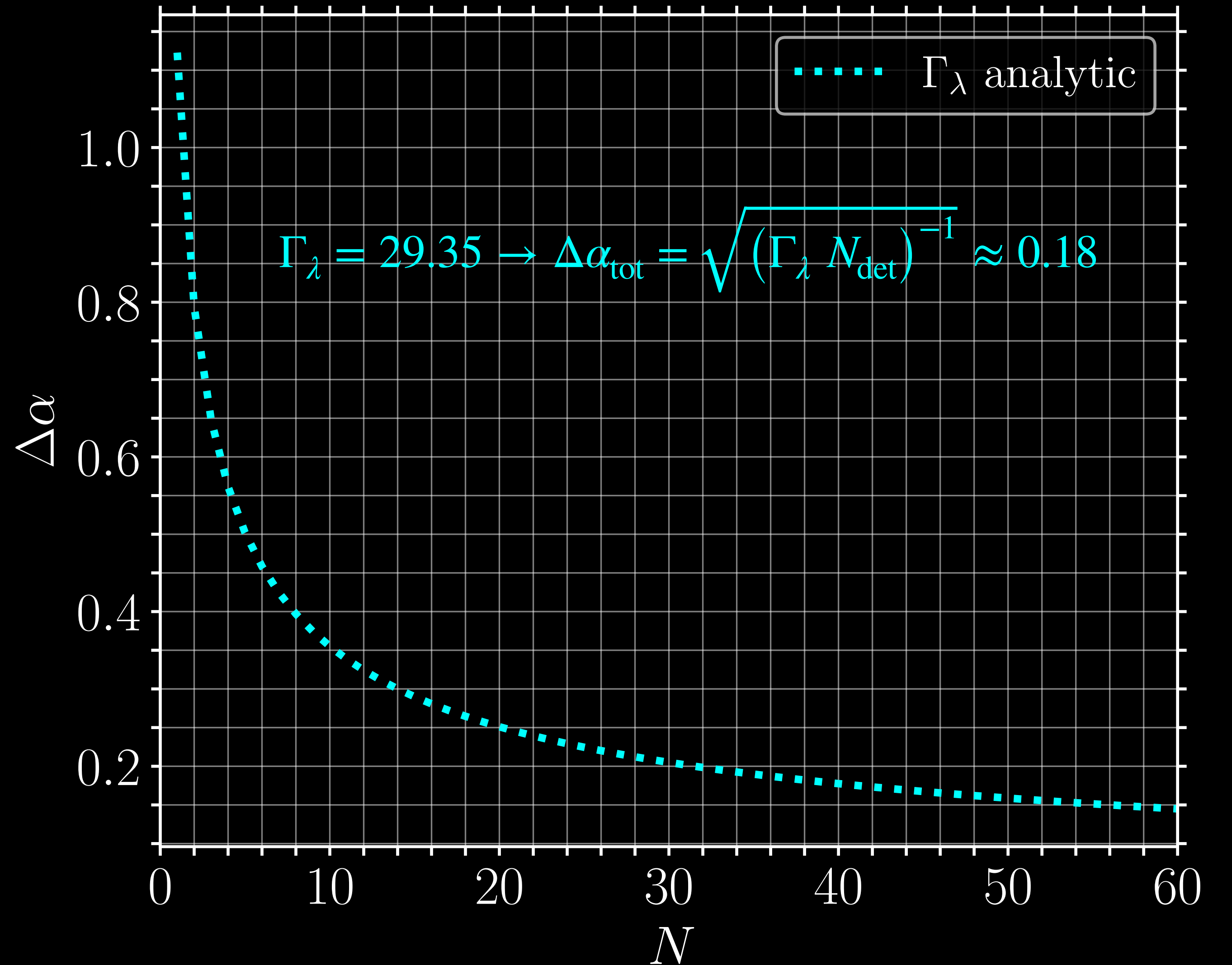
Power law of SMBHs with 1 parameter and 1 hyperparameter

[Gair et al. (2023) MNRAS 519 2736]

$$p(M_1 | \alpha) = \frac{\alpha}{M_{\max}^\alpha - M_{\min}^\alpha} M_1^{\alpha-1}$$

- ★ 1 parameter $\theta = M_1$
- ★ 1 hyperparameter $\lambda = \alpha$ with $\alpha_{\text{true}} \approx 0$
- ★ $M_{\min} = 10^4 M_\odot$
- ★ $M_{\max} = 10^7 M_\odot$

- ★ $d_{th} = 5 \times 10^5 M_\odot$
- ★ $\Gamma = \frac{1}{\sigma^2}$ with $\sigma = 0.1$
- ★ $N_{\text{obs}} = 100$
- ★ $N_{\text{det}} = 39$



Power law of SMBHs with 1 parameter and 1 hyperparameter

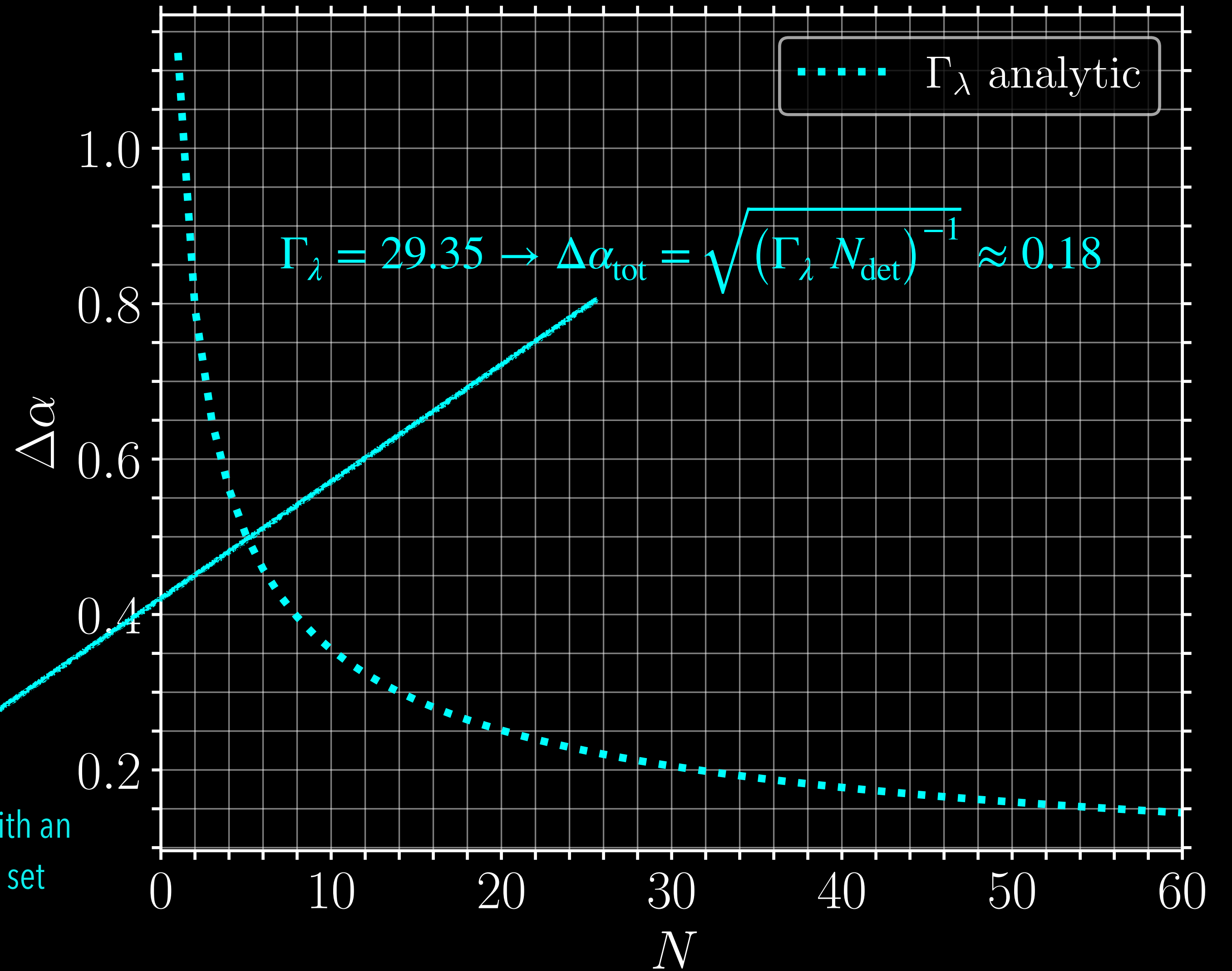
[Gair et al. (2023) MNRAS 519 2736]

$$p(M_1 | \alpha) = \frac{\alpha}{M_{\max}^\alpha - M_{\min}^\alpha} M_1^{\alpha-1}$$

- ★ 1 parameter $\theta = M_1$
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- ★ $N_{\text{det}} = 39$

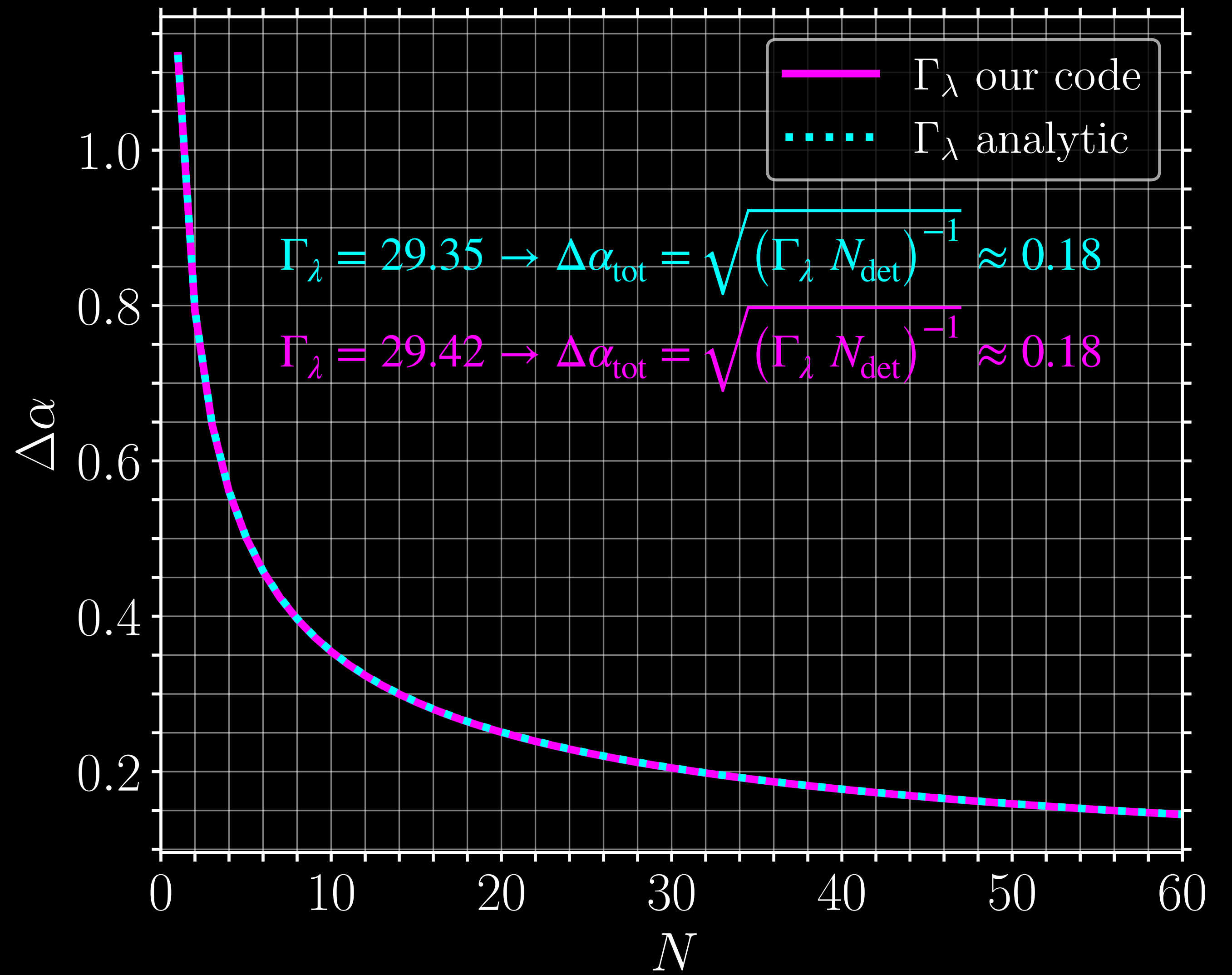
Fisher predictions were validated with an MCMC analysis for the same data set



$$p(M_1 | \alpha) = \frac{\alpha}{M_{\max}^\alpha - M_{\min}^\alpha} M_1^{\alpha-1}$$

- ★ 1 parameter $\theta = M_1$
- ★ 1 hyperparameter $\lambda = \alpha$ with $\alpha_{\text{true}} \approx 0$
- ★ $M_{\min} = 10^4 M_\odot$
- ★ $M_{\max} = 10^7 M_\odot$

- ★ $d_{th} = 5 \times 10^5 M_\odot$
- ★ $\Gamma = \frac{1}{\sigma^2}$ with $\sigma = 0.1$
- ★ $N_{\text{obs}} = 100$
- ★ $N_{\text{det}} = 39$



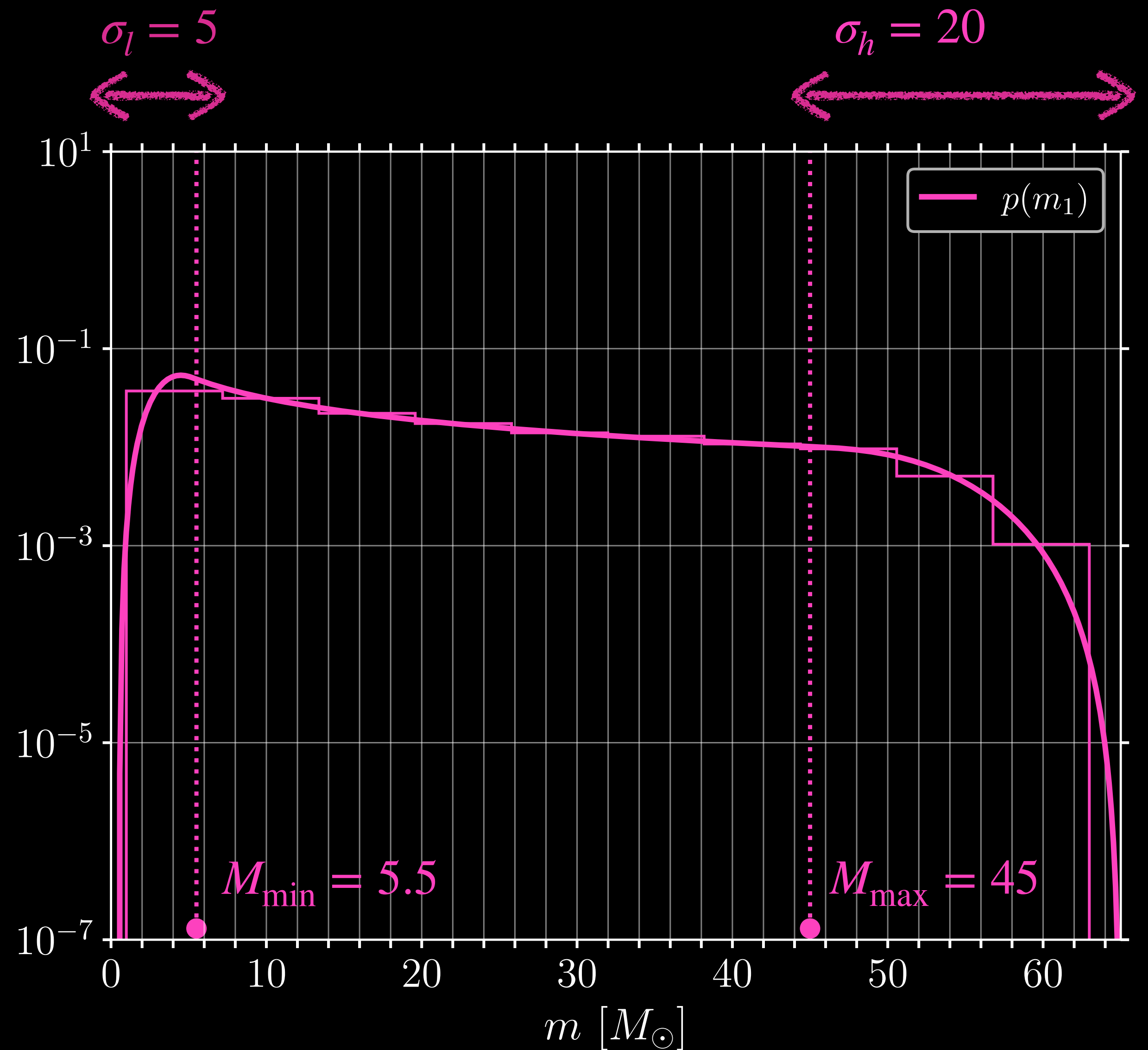
Power Law (PL) mass function with smoothing

$$p(M_1 | \vec{\lambda}) \propto M_1^{-\alpha} S(M_1, M_{\min}, \sigma_l, M_{\max}, \sigma_h)$$

$$p(M_2 | M_1, \vec{\lambda}) \propto M_2^\beta S(M_2, M_{\min}, \sigma_l, M_{\max}, \sigma_h)$$

6 hyperparameter $\vec{\lambda}$:

- α : Spectral index for the PL of the primary mass distribution ($\alpha_{\text{true}} = 0.75$)
- β : Spectral index for the PL of the mass ratio distribution ($\beta_{\text{true}} = 0.1$)
- M_{\max}, M_{\min} : Maximum and minimum mass of the PL component of the primary mass distribution
- σ_h, σ_l : Width of the smoothing component at the upper and lower edge of the mass distribution

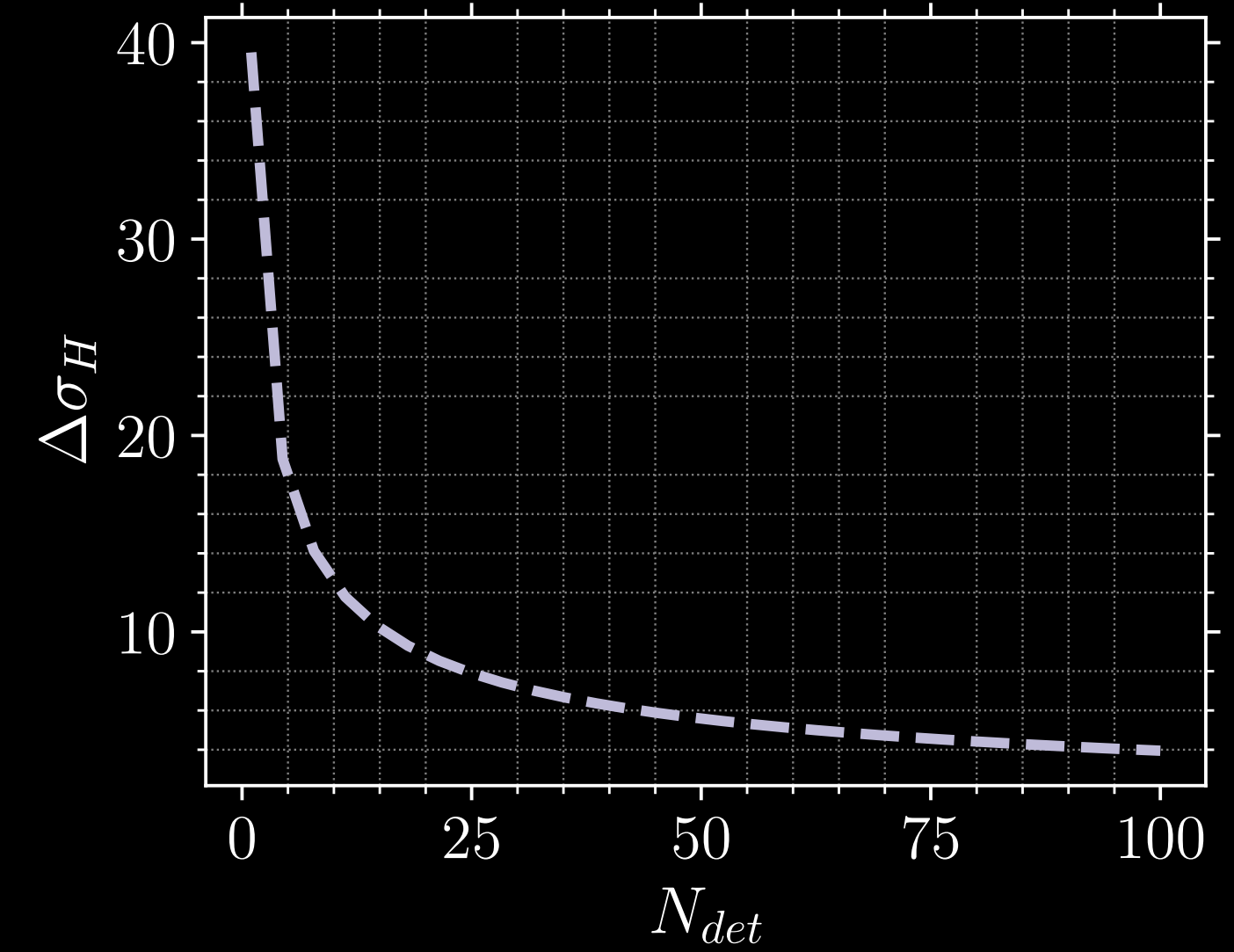
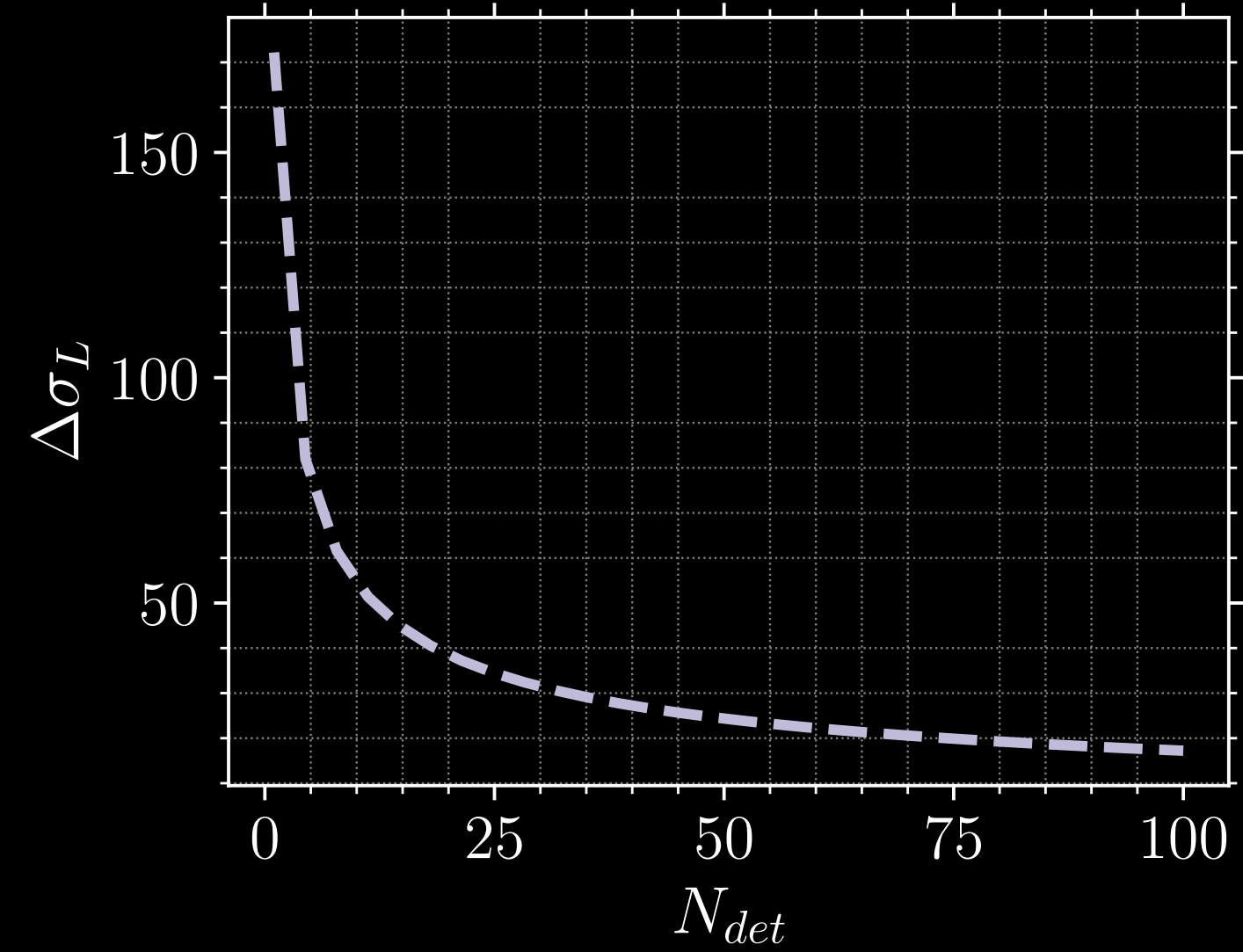
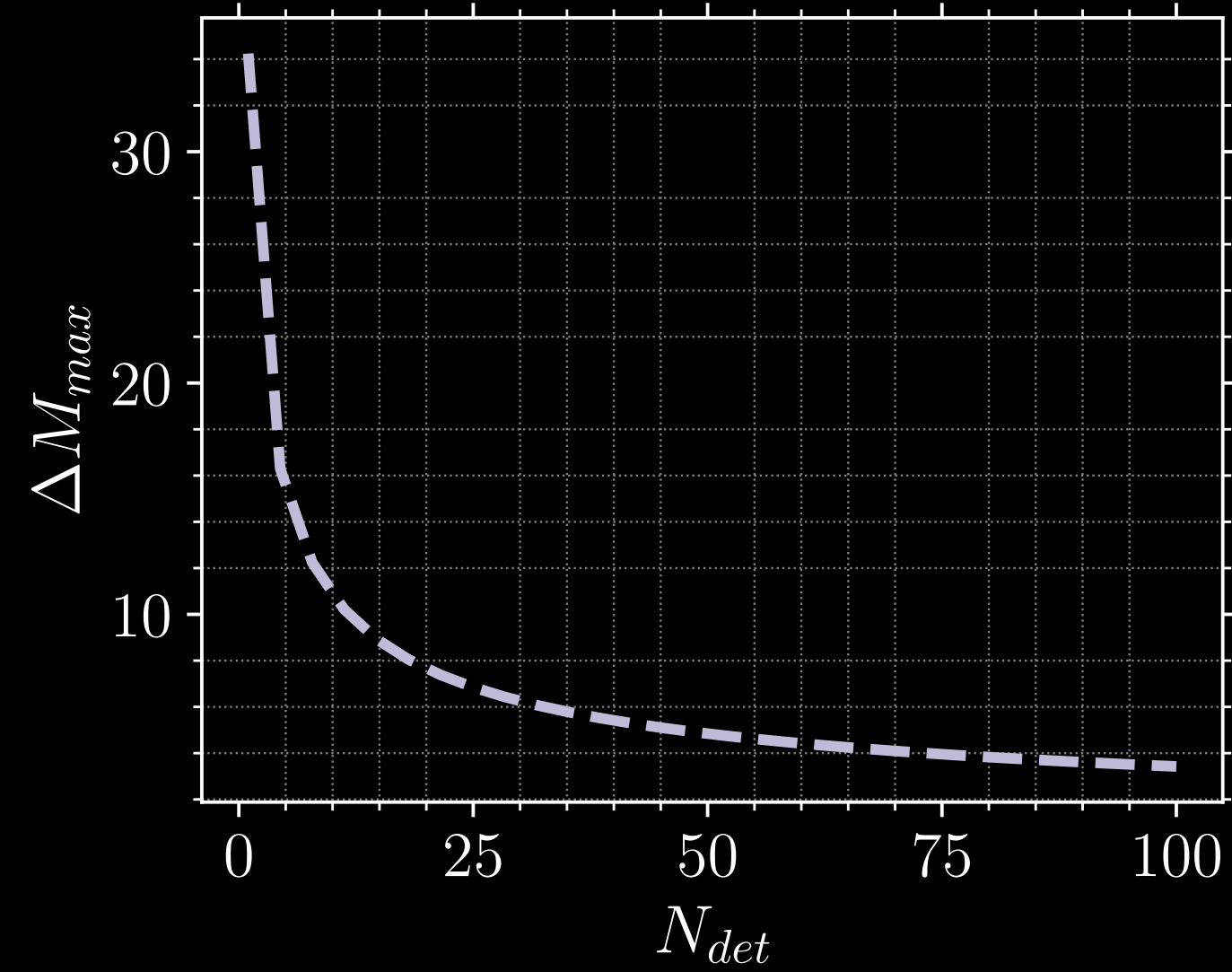
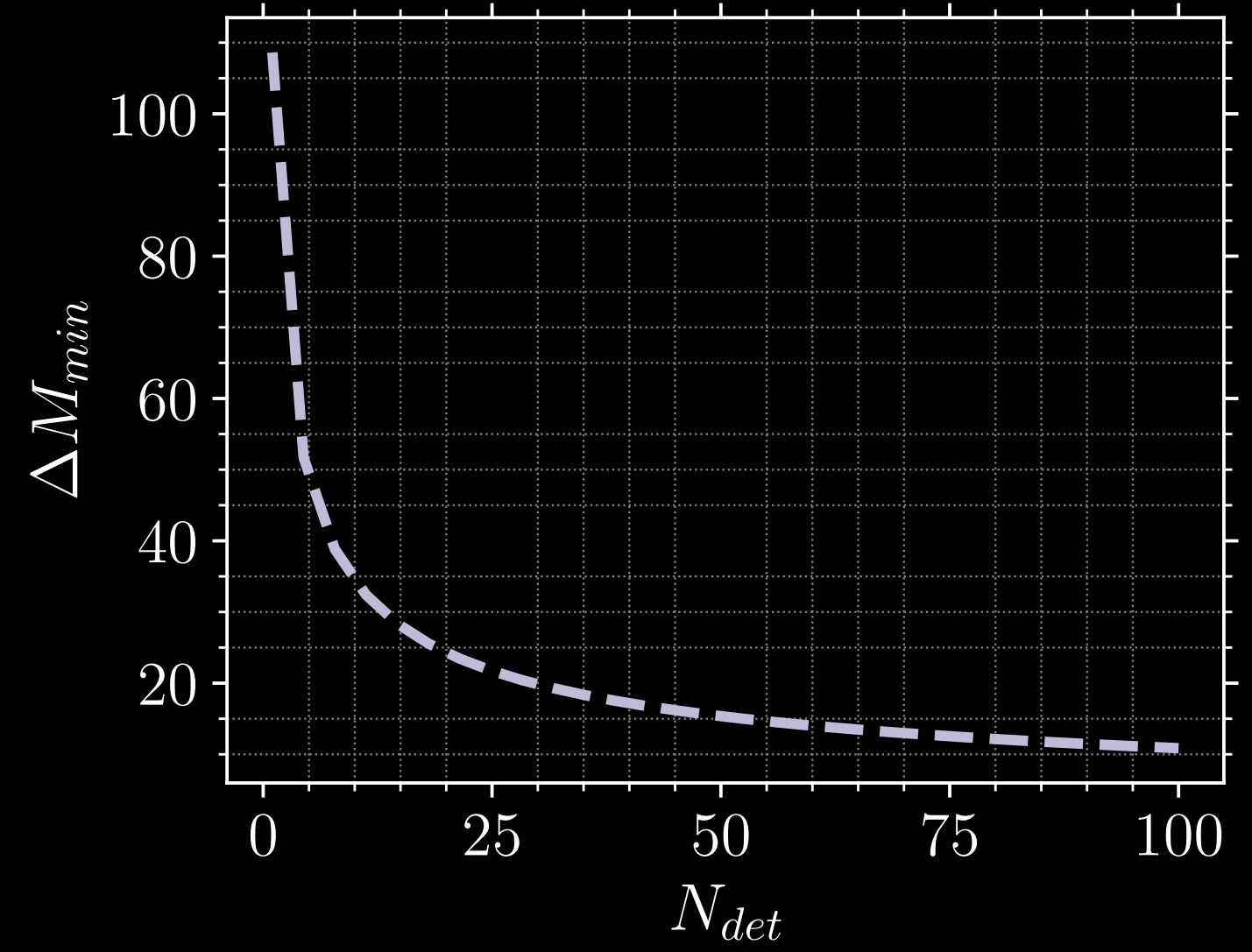
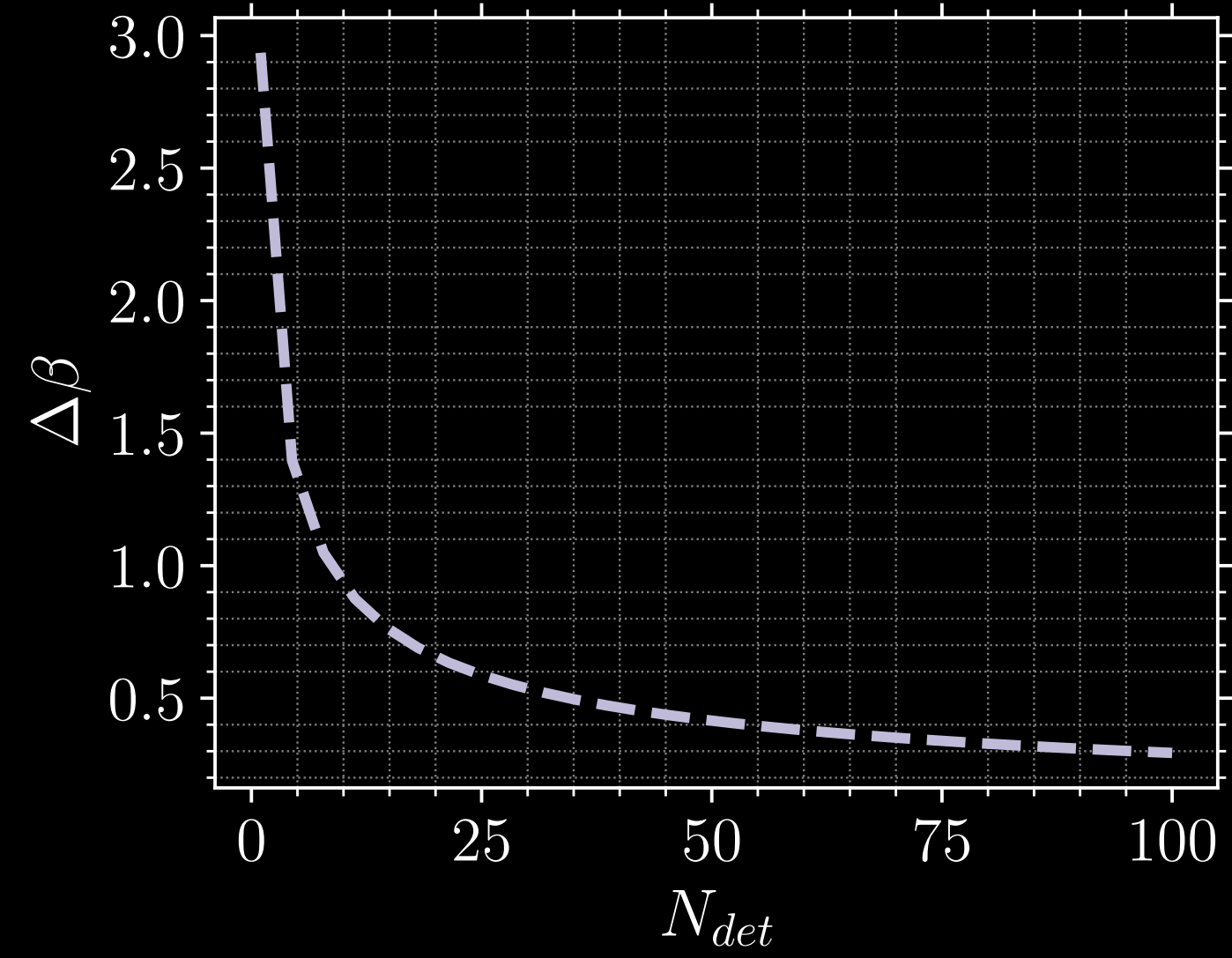
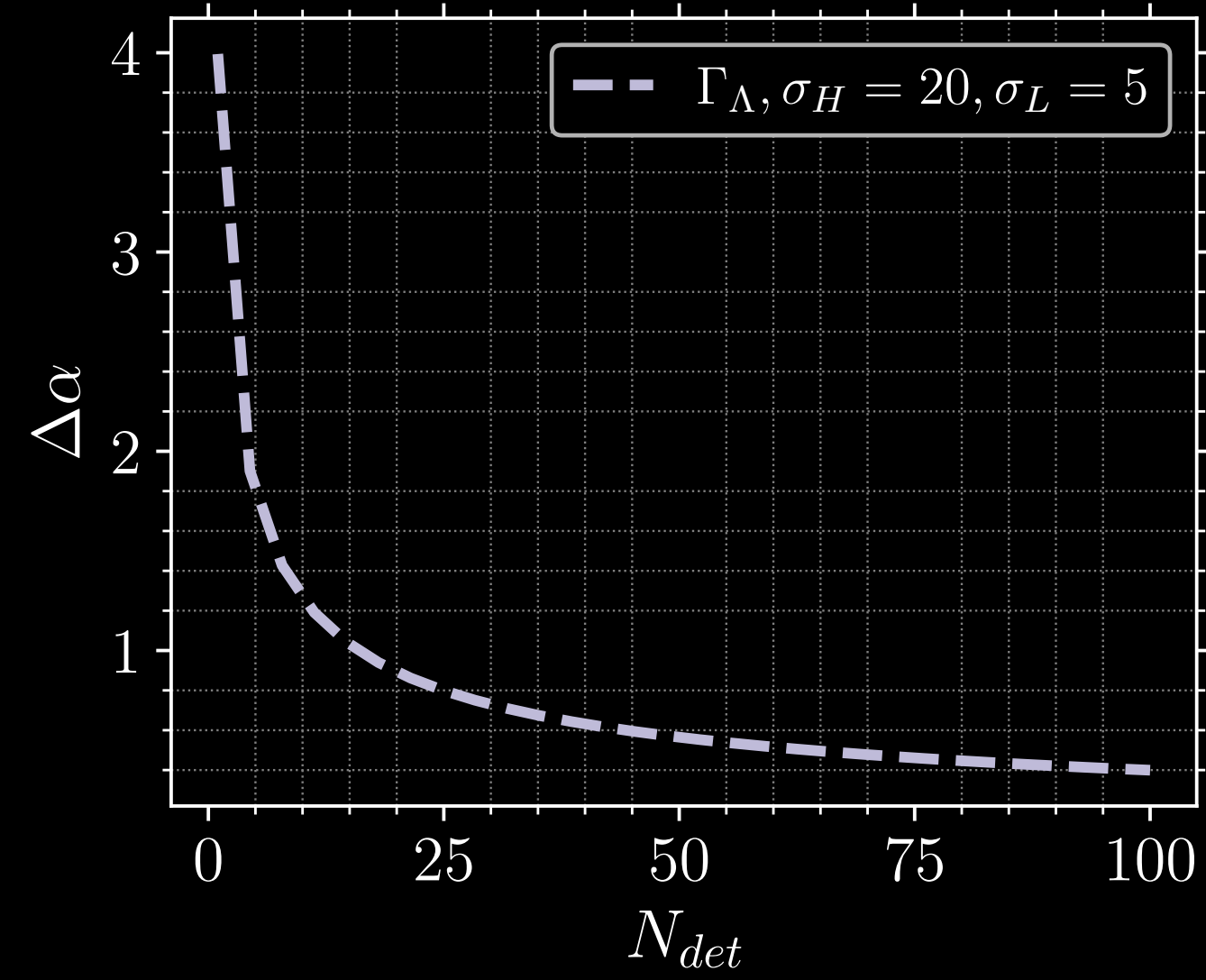


O4 sensitivity curve

IMRPhenomHM waveform model

$\rho_{\text{th}=20}$

PowerLaw mass function with smoothing



Population model with 2 parameters and 2 hyperparameters

$$p(M_1 | \alpha) = \frac{\alpha}{M_{\max}^\alpha - M_{\min}^\alpha} M_1^{\alpha-1}$$

$$p(M_2 | \beta, M_1) \sim \left(\frac{M_2}{M_1}\right)^\beta$$

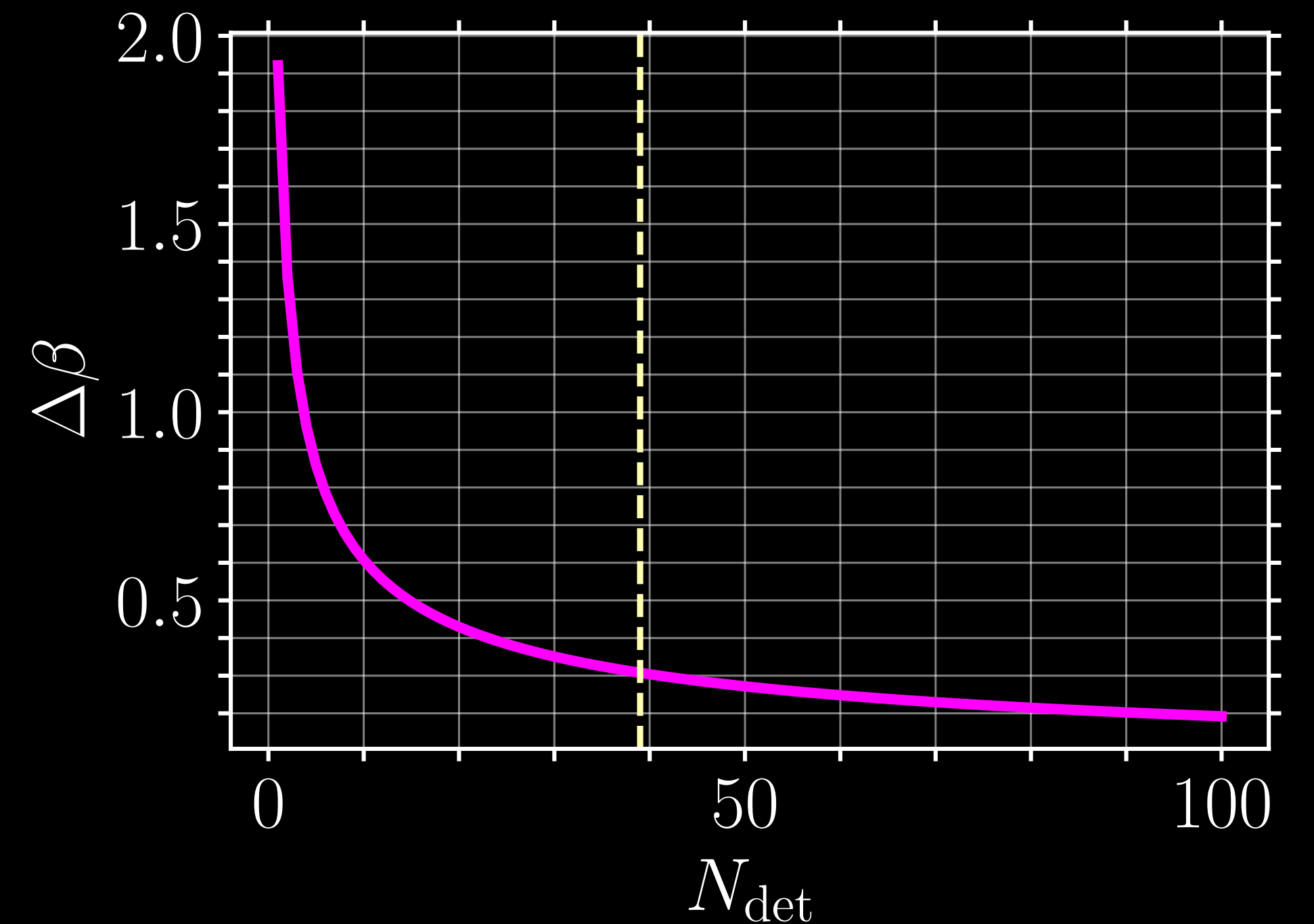
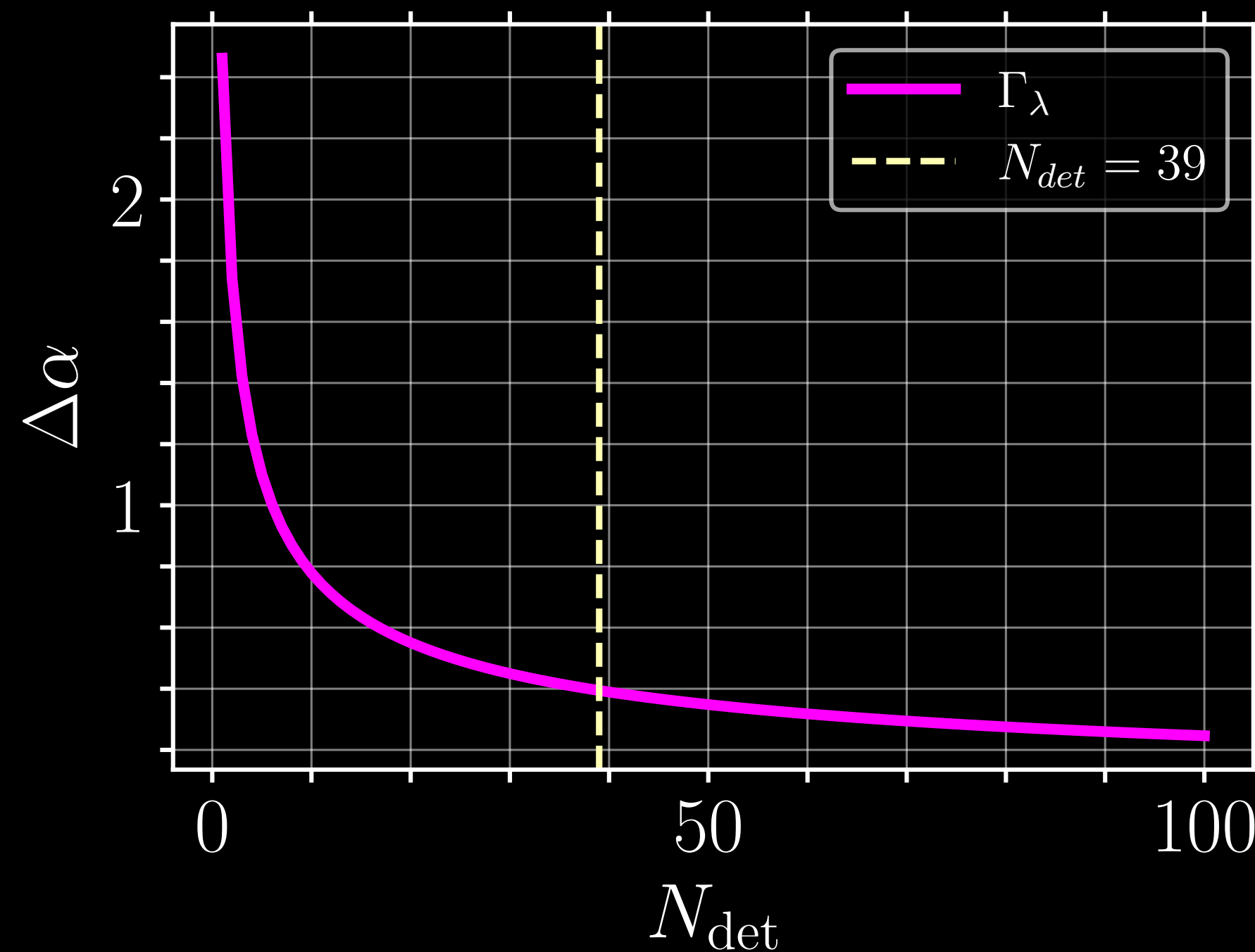
★ 2 parameters $\vec{\theta} = \{M_1, M_2\}$

★ 2 hyperparameters $\vec{\lambda} = \{\alpha, \beta\}$ with $\alpha_{\text{true}} \approx 0$ and $\beta_{\text{true}} \approx 1.1$
(Spectral indexes for the PL of the primary (mass ratio) distributions)

★ Ndet=39

$$\Delta\alpha_{\text{tot}} = \sqrt{(\Gamma_\lambda N_{\text{det}})^{-1}} \approx 0.39$$

$$\Delta\beta_{\text{tot}} = \sqrt{(\Gamma_\lambda N_{\text{det}})^{-1}} \approx 0.31$$



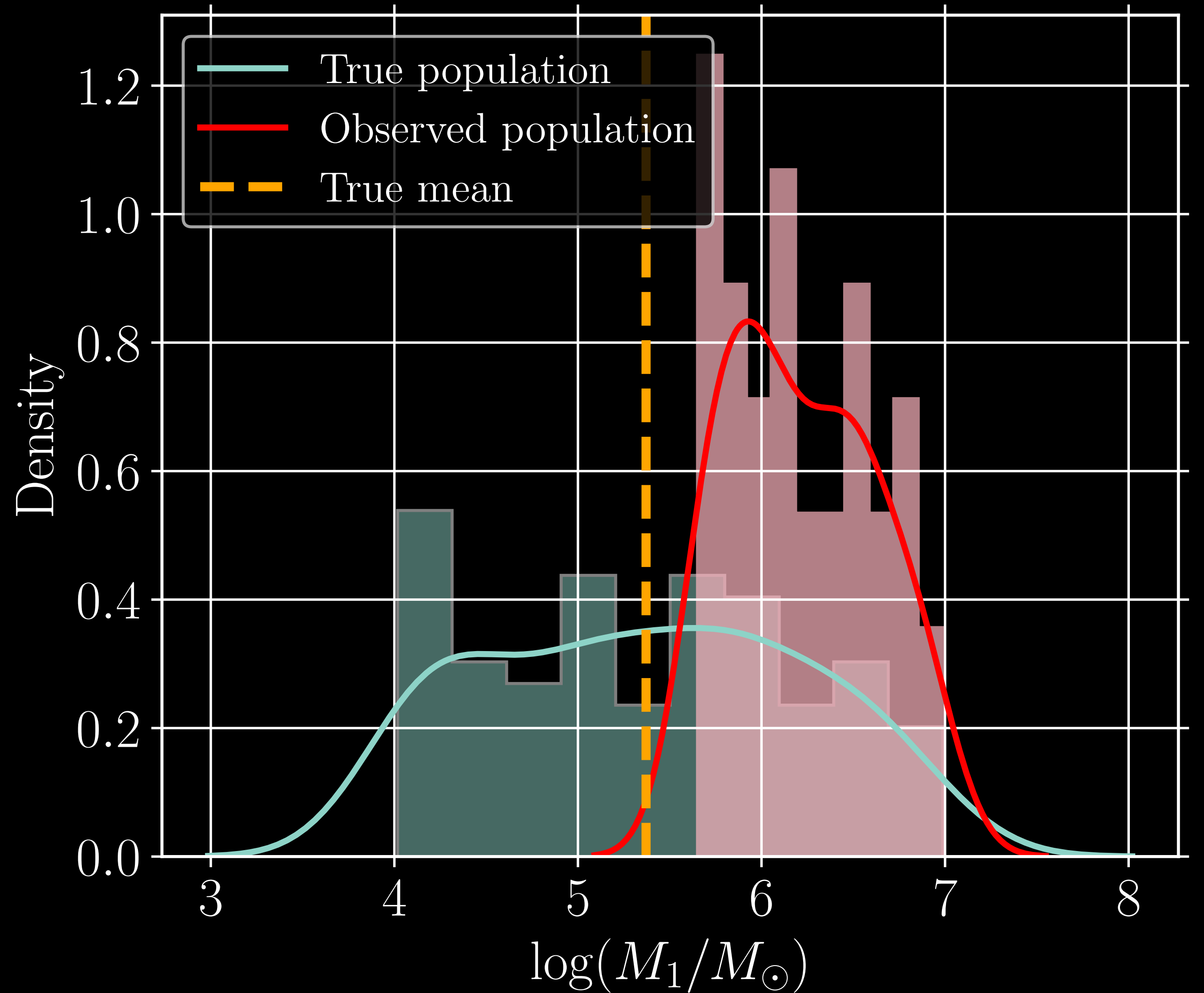
Population model with 1 parameter and 1 hyperparameter

[Gair et al. (2023) MNRAS 519 2736]

$$p(M_1 | \alpha) = \frac{\alpha}{M_{\max}^\alpha - M_{\min}^\alpha} M_1^{\alpha-1}$$

- ★ 1 parameter $\theta = M_1$
- ★ 1 hyperparameter $\lambda = \alpha$ with $\alpha_{\text{true}} \approx 0$
- ★ $M_{\min} = 10^4 M_\odot$
- ★ $M_{\max} = 10^7 M_\odot$

- ★ $d_{th} = 5 \times 10^5 M_\odot$
- ★ $\Gamma = \frac{1}{\sigma^2}$ with $\sigma = 0.1$
- ★ $N_{\text{obs}} = 100$
- ★ $N_{\text{det}} = 39$



Population model with 1 parameter and 1 hyperparameter

[Gair et al. (2023) MNRAS 519 2736]

$$p(M_1 | \alpha) = \frac{\alpha}{M_{\max}^\alpha - M_{\min}^\alpha} M_1^{\alpha-1}$$

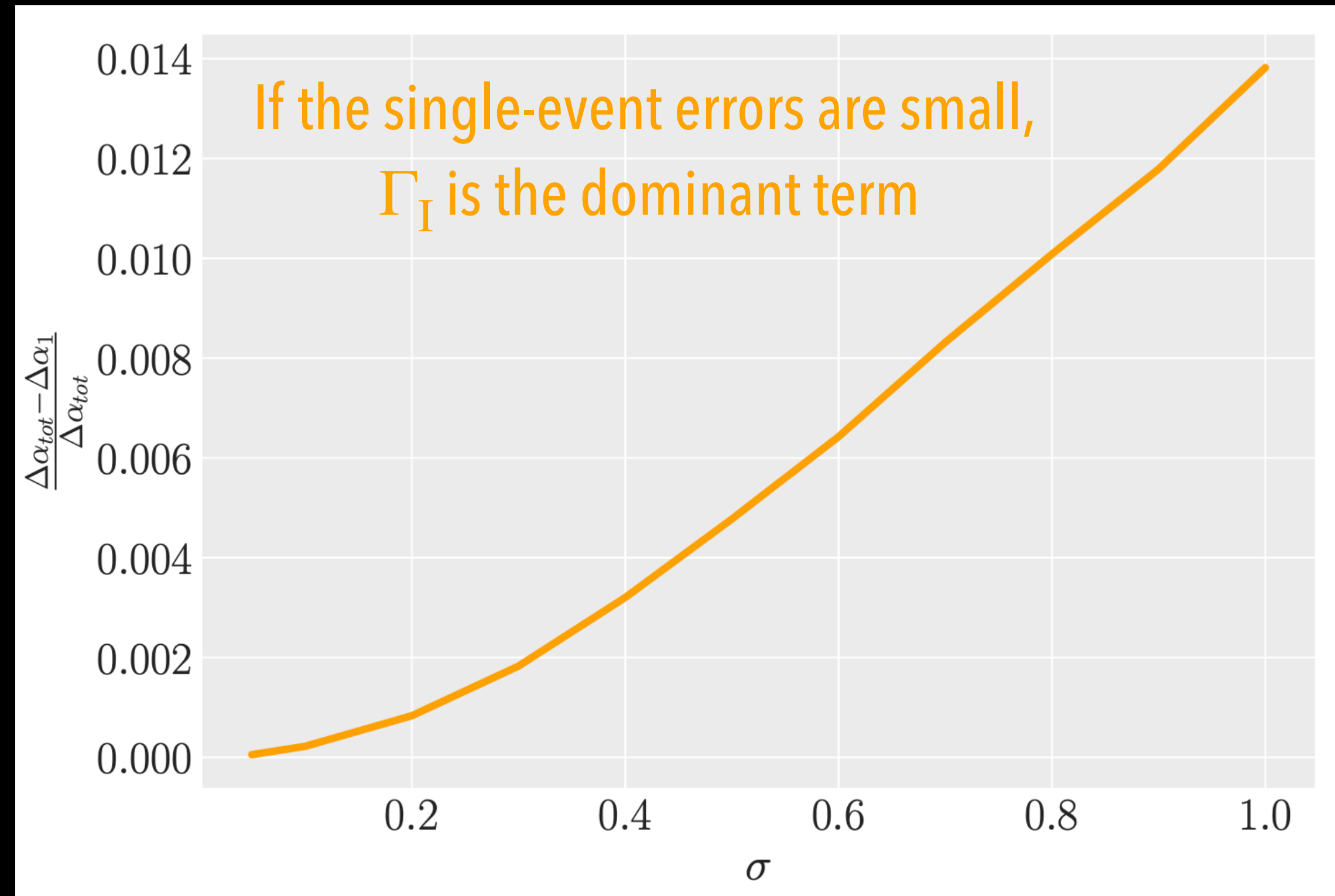
$$\Gamma_\lambda = 29.35 \rightarrow \Delta\alpha_{\text{tot}} = \sqrt{(\Gamma_\lambda N_{\text{det}})^{-1}} \approx 0.18$$

$$\Gamma_I = 29.36 \rightarrow \Delta\alpha_I = \sqrt{(\Gamma_I N_{\text{det}})^{-1}} \approx 0.18$$

$$\Gamma_{\text{II}} + \Gamma_{\text{III}} + \Gamma_{\text{IV}} + \Gamma_{\text{V}} \approx 10^{-13}$$

- ★ 1 parameter $\theta = M_1$
- ★ 1 hyperparameter $\lambda = \alpha$ with $\alpha_{\text{true}} \approx 0$
- ★ $M_{\min} = 10^4 M_\odot$
- ★ $M_{\max} = 10^7 M_\odot$

- ★ $d_{\text{th}} = 5 \times 10^5 M_\odot$
- ★ $\Gamma = \frac{1}{\sigma^2}$ with $\sigma = 0.1$
- ★ $N_{\text{obs}} = 100$
- ★ $N_{\text{det}} = 39$



Population model with 2 parameter and 2 hyperparameter

- ★ 2 parameter $\vec{\theta} = \{M_1, M_2\}$
- ★ 2 hyperparameter $\vec{\lambda} = \{\alpha, \beta\}$ with $\alpha_{\text{true}} \approx 0$ and $\beta_{\text{true}} \approx 1.1$
- ★ $N_{\text{det}}=39$

$$\Delta\alpha_{\text{tot}} = \sqrt{(\Gamma_{\lambda} N_{\text{det}})^{-1}} \approx 0.39$$

$$\Delta\alpha_{\text{I}} = \sqrt{(\Gamma_{\text{I}} N_{\text{det}})^{-1}} \approx 0.23$$

$$\Delta\beta_{\text{tot}} = \sqrt{(\Gamma_{\lambda} N_{\text{det}})^{-1}} \approx 0.31$$

$$\Delta\beta_{\text{I}} = \sqrt{(\Gamma_{\text{I}} N_{\text{det}})^{-1}} \approx 0.18$$

