

CITS deserté **t**érieure

Speeding PSA with half-precision and GPU

Roméo MOLINA Vincent LAFAGE

IJCLab, CNRS/IN2P3 & Université Paris-Saclay, Orsay, France

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Using low precisions is promising

Low precision increasingly supported by hardware

Great benefits:

- ▶ Reduced **storage**, data movement, and communications
- ▶ Reduced energy consumption $(5 \times$ with fp16, $9 \times$ with bfloat16)
- ▶ Increased **speed** (16× on A100 from fp32 to fp16/bfloat16)

Floating-point arithmetic

Floating-point computation \neq mathematical evaluation

- rounding $a \oplus b \neq a + b$
- no more associativity $(a \oplus b) \oplus c \neq a \oplus (b \oplus c)$

Consequences:

- invalid results
- non reproducibility
- performance issue (useless iterations)

Some limitations to the low precisions: (= low resolution)

- Low accuracy
- **•** Narrow range

⇒ **multiplication: good ; substraction : bad**

Discrete Stochastic Arithmetic (DSA)

- each operation executed 3 times with a random rounding mode
- number of correct digits in the results estimated using Student's test with the confidence level 95 %
- \bullet operations executed synchronously
	- ⇒ detection of numerical instabilities (ex: if (A>B) with A-B numerical noise)
	- ⇒ optimization of stopping criteria to avoid useless iterations

Assess the accuracy

- \bullet implements stochastic arithmetic for $C/C++$ or Fortran codes
- all operators and mathematical functions overloaded ⇒ little code rewriting
- support for MPI, OpenMP, GPU, vectorised codes
- **•** supports emulated ou native half precision
- o one CADNA execution: accuracy of any result, complete list of instabilities

CADNA cost

- \bullet memory: $\times 4$
- run time $\approx \times 10$

CADNA **validates** fp32 **results**

- PSA performed natively in fp32
- minimum search in a 504-dimensional space … as in 56 time steps times 9 segments
- risk to accumulate catastrophic cancellations

$$
\chi = \sum_{s,t} \left| S_{s,t}^{\text{mes}} - S_{s,t}^{\text{ref}} \right|^{p=0.3}
$$

requires instrumentation to assess the accuracy results

⇒ code sensitive to perturbations?

- \bullet but 0.02% of points matched differently between fp64 and original fp32 version
- \bullet only $0.02\,\%$ between CADNA version and original version
- ⇒ Satisfactory original fullgrid PSA results!

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Turn it into half computation (CPU)

- \bullet emulated fp16
- 7.76% differences between original fp32 and fp16 version
- \bullet too much?
- need to find another way to exploit low precision

Mix several precisions in the same code with the goal of

- **•** Getting the performance benefits of low precisions
- While preserving the accuracy and stability of high precision
- ⇒ **Why does it make sense to make the precision vary?**
- Because not all computations are equally "important"! Example:

 64 bits Unimportant bits

 $+ b$

Mixed precision algorithms

Mix several precisions in the same code with the goal of

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 \overline{a} $+\ b$ $\frac{64 \text{ bits}}{1}$ **Unimportant bits**
Unimportant bits

Coarse in half, fine in float

- first step in half
- second step in float
- 8.55% differences with fullgrid fp32 version
- \bullet under the same conditions, half-half produces $14.04\,\%$ differences!

Figure: Distances between points found by the full grid fp32 algorithm and alternative methods

- we already saw vectorised version on CPU
- we also tried emulated fp16 on CPU
- ⇒ first, extract a minimum, standalone version of PSA on CPU https://gitlab.com/romeomolina/psa-test-env.git
- ⇒ then, turn to modern C++ conventions
	- ▶ const
	- ▶ auto
	- ▶ constexpr

- code should bind neatly to GPU as concurrency is clearly expressed
- moving it on GPUs to exploit fp16 half-precision hardware we will show our CUDA implementation, to keep using CADNA
- CUDA *vs* OpenACC / OpenMP : better performance,
- …less portability (NVidia only),
- …more coding effort


```
_global__void gpu_samp_loop(float* hitSegAmp, float* corSegAmp, float* baseAmp, int* baseGrid<br>
, float* chi2, int numPts){<br>
//contexpr auto baseScale*RESCALE; // scaling signals to data, including<br>
expansion factor for m
                 const int iCore = 36;
const int netChSeg = 34;
const int jPts = blockIdx.x * blockDim.x + threadIdx.x;
                if(jPts < numPts){
                                const float *baseTrace1 = baseAmp + jPts*LOOP_SAMP*TCHAN + netChSeg*LOOP_SAMP;
const float *baseTrace2 = baseAmp + jPts*LOOP_SAMP*TCHAN + iCore*LOOP_SAMP;
                                float chi2_local = 0.0f;<br>for(auto nn = 0U; nn < LOOP_SAMP; nn++) {<br>for(auto f_type fdiff = hitSegAmp[nn] - baseScale * baseTrace1[nn];
                                              chi2_local += exp2f(log2f(fabs(fdiff))*chiExponent);
                                }
for(auto nn = 0U; nn < LOOP_SAMP; nn++) {
f_type fdiff = corSegAmp[nn] - baseScale * baseTrace2[nn];
chi2_local += exp2f(log2f(fabs(fdiff))*chiExponent);
                                }
chi2[jPts] = chi2_local;
               }
}
```


Points identified within 5mm of those found by reference (FGS-FP32 without the LUT executed in CPU %)

sample of 5342 events with energies ranging from $15\,\mathrm{keV}$ to $5\,\mathrm{MeV}$

Room for improvement

- CPU experiments on an Intel® Core™ i9-11950H Processor with 8 cores at 2.6GHz with 24MB cache
- GPU experiments on a NVIDIA RTX A2000 with 3328 CUDA cores and 4GB memory.
- \Rightarrow increase the occupancy of the GPU cores, suggesting a possible acceleration up to a factor $\times 15$ on larger GPUs
- GPU fp16 really bear fruits with tensor cores…Can we express the computation as a matrix product?

Conclusion

- low precision is beneficial (speed, energy, storage)
- accuracy control is mandatory
- CADNA is well designed to do so
- mixed-precision is a way to benefit from low precision while keeping good accuracy
- PSA on GPU (CUDA)
- similar results between uniform precision and mixed precision for PSA

To improve optimisation of PSA:

- more events should be put simultaneously on the GPU to really benefit of GPU
- have the coarse/fine grid size vary
- have a hierarchy of intermediate grids
- … address PrePSA