

24th AGATA Week

Status of the optimization of the Energy pre-processing

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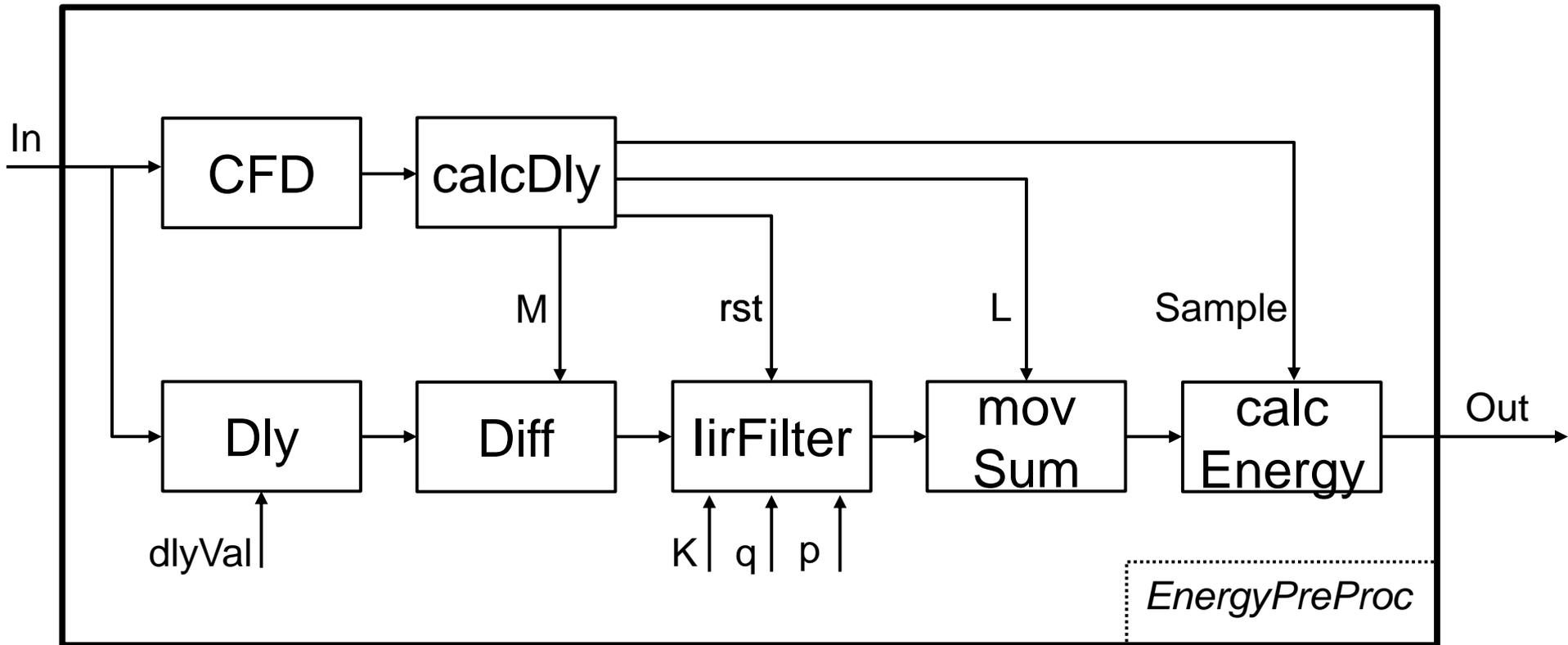
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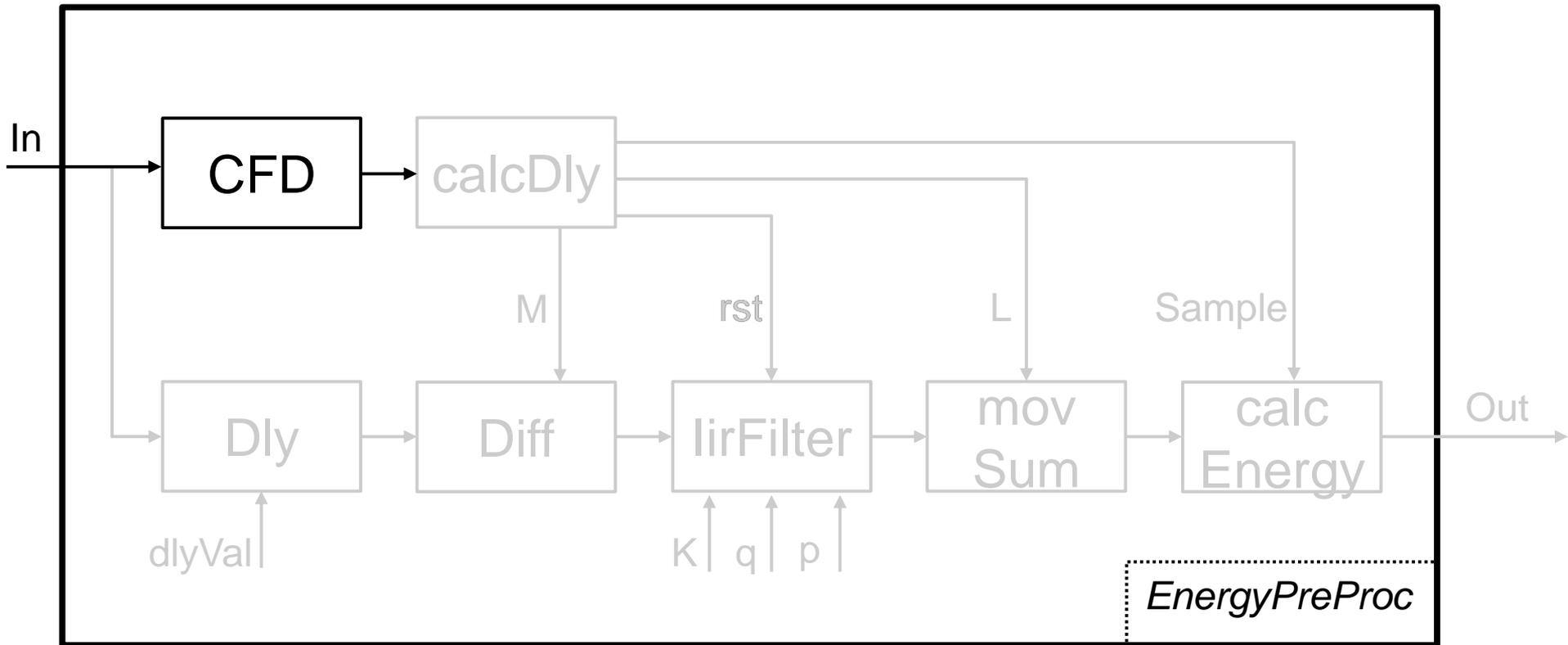
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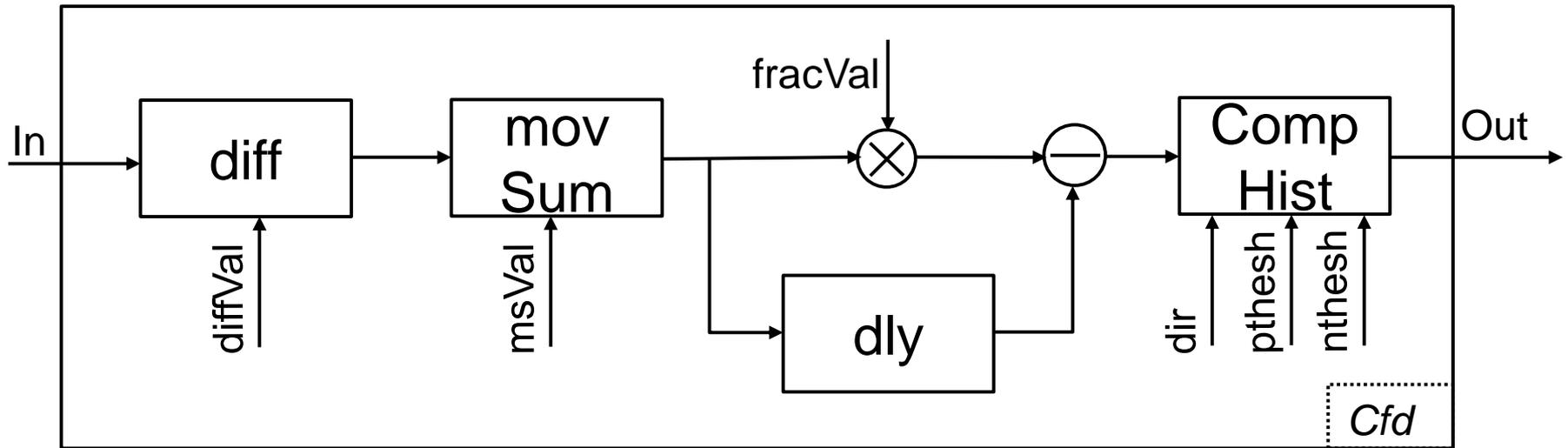
Energy pre-processing



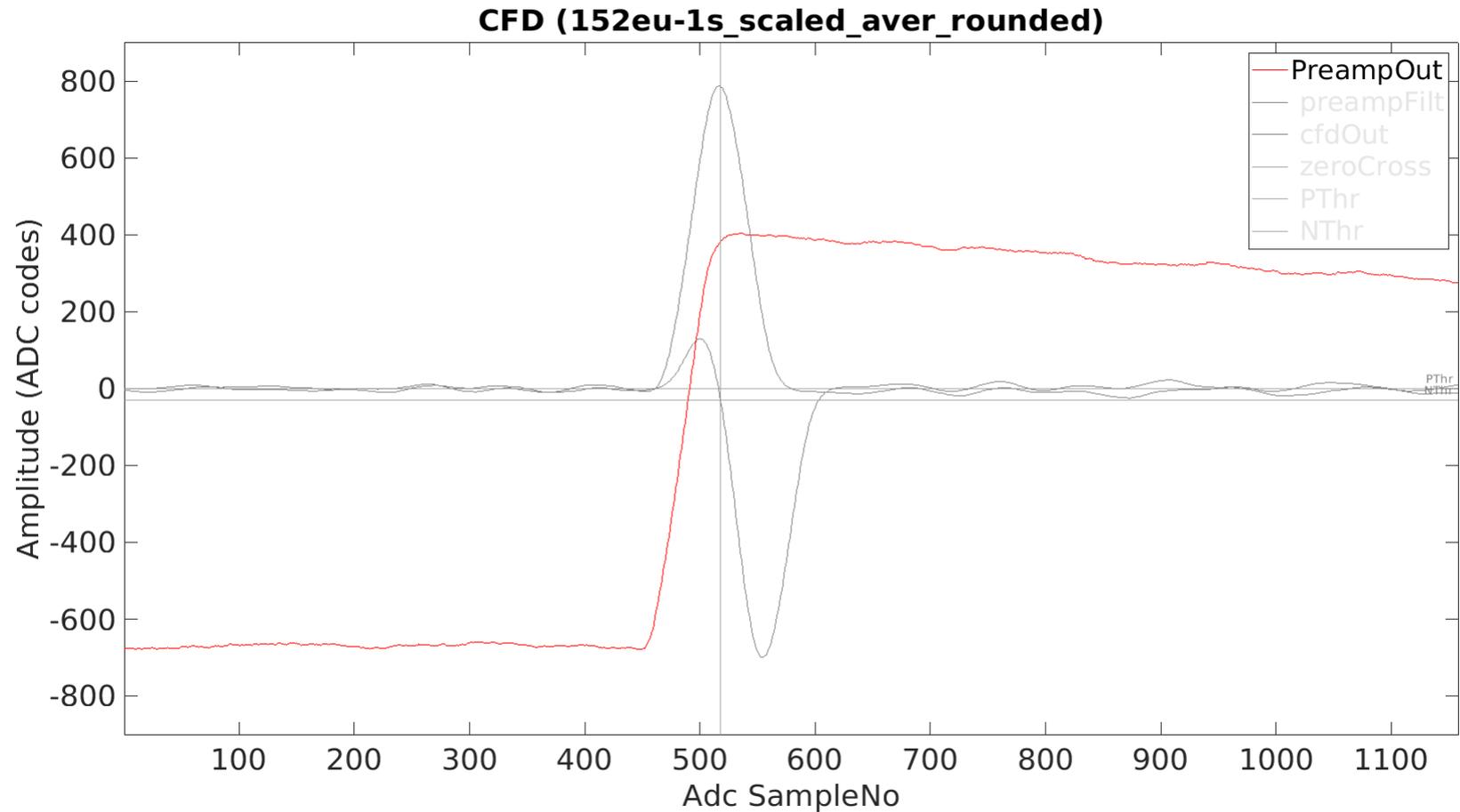
Constant Fraction Discriminator (CFD)



Constant Fraction Discriminator (CFD)



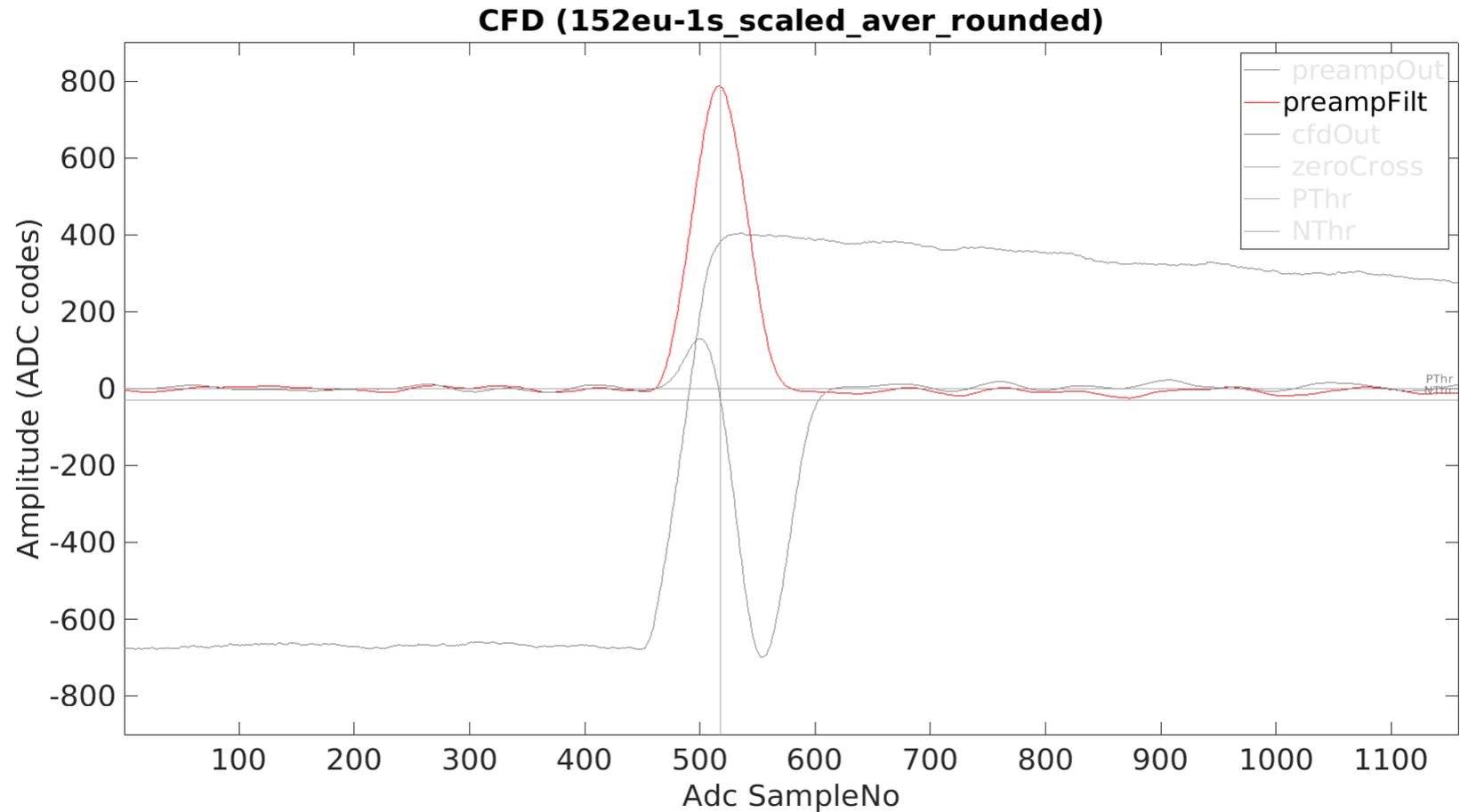
Constant Fraction Discriminator (CFD)



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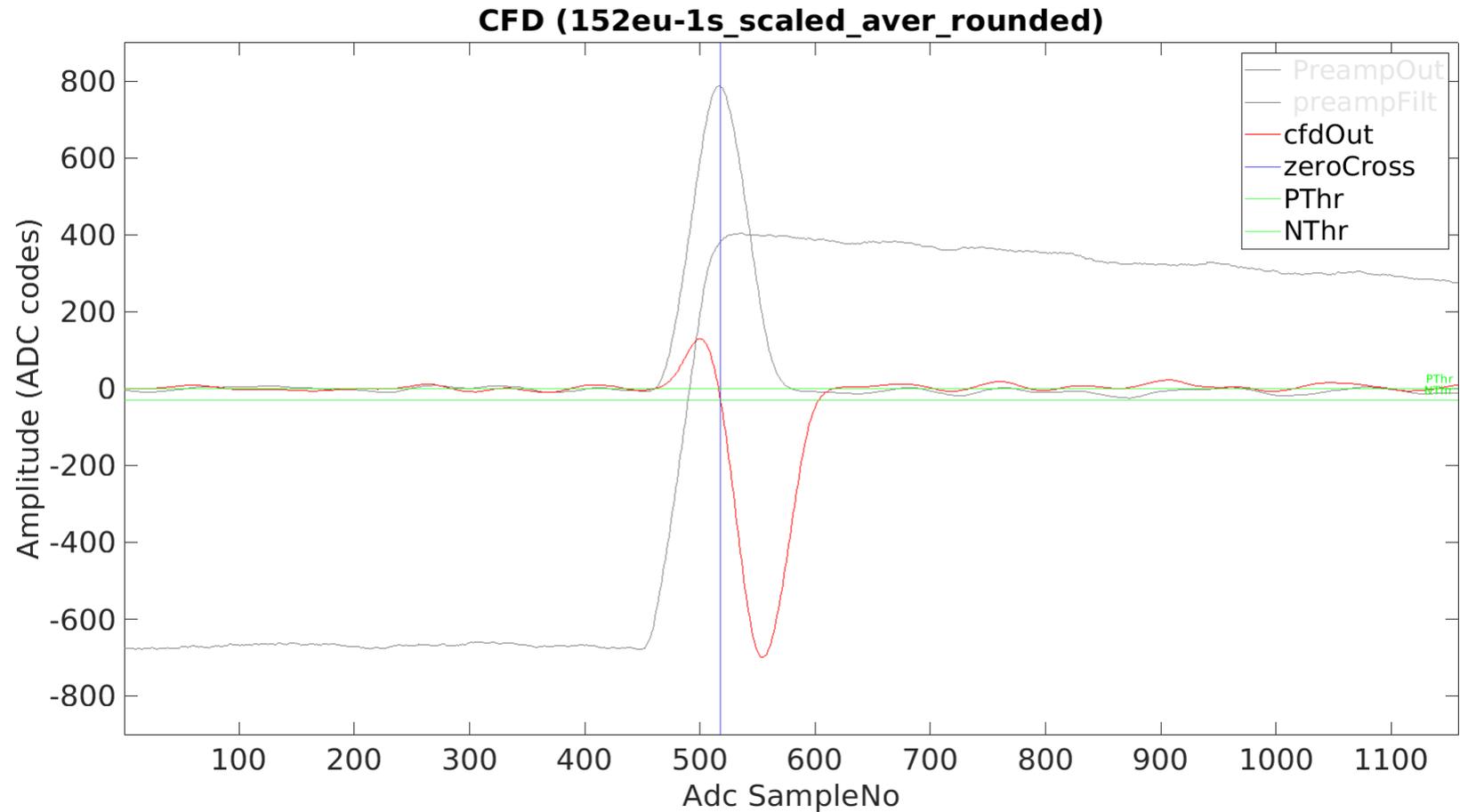
Constant Fraction Discriminator (CFD)



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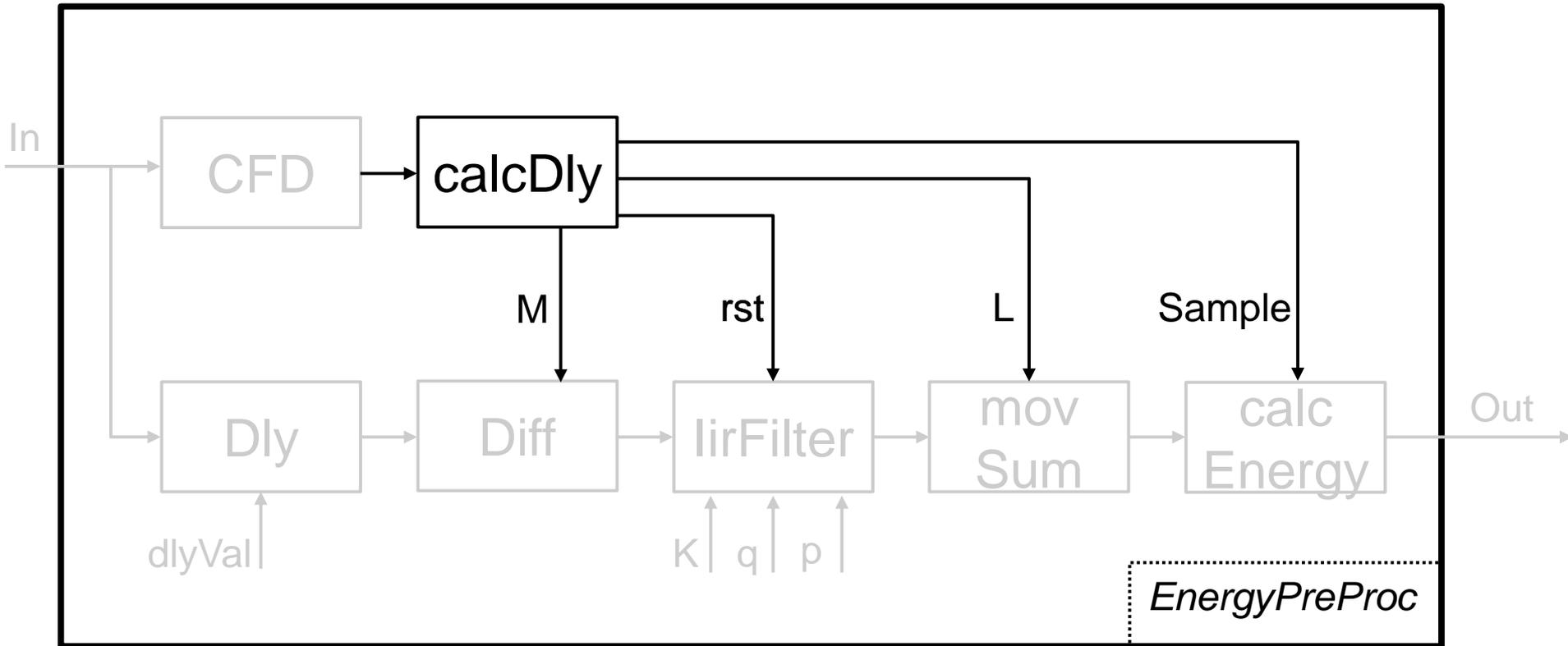
Constant Fraction Discriminator (CFD)



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Delay calculation Block

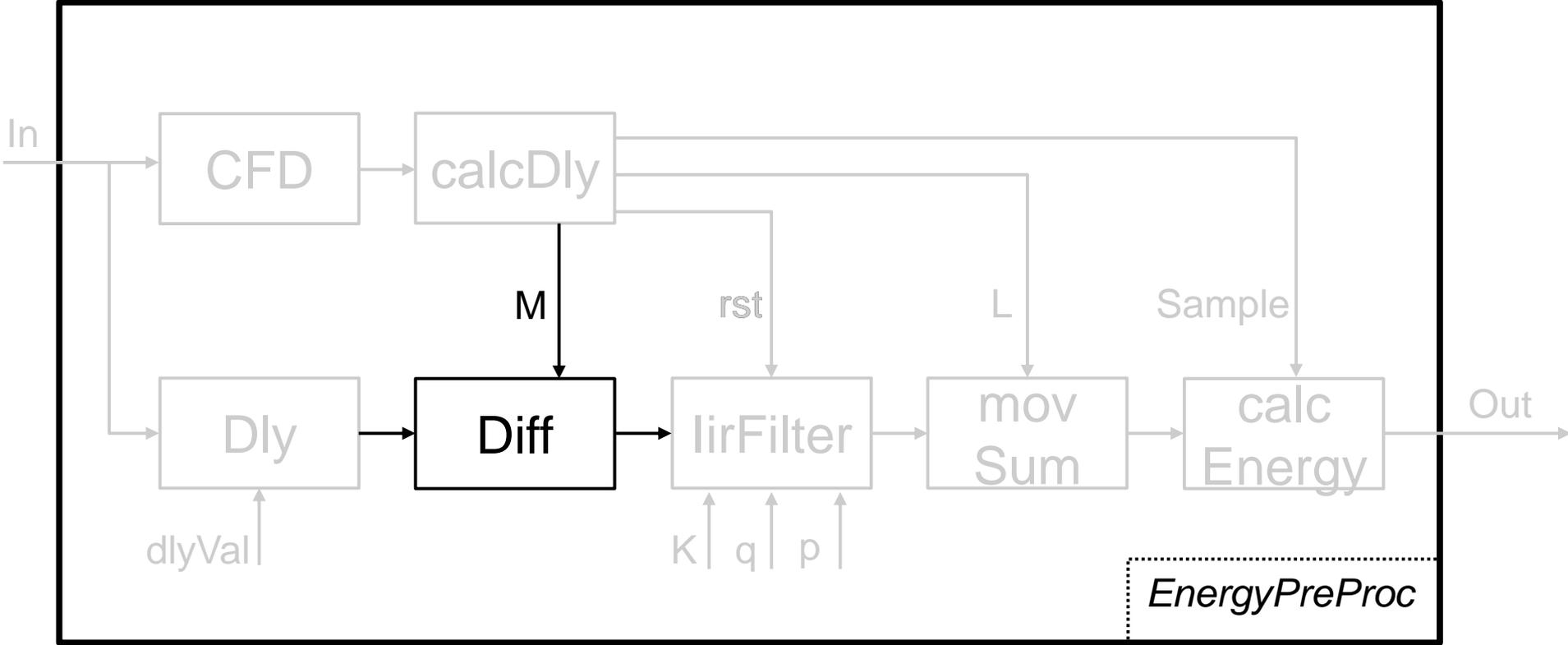


Delay calculation Block

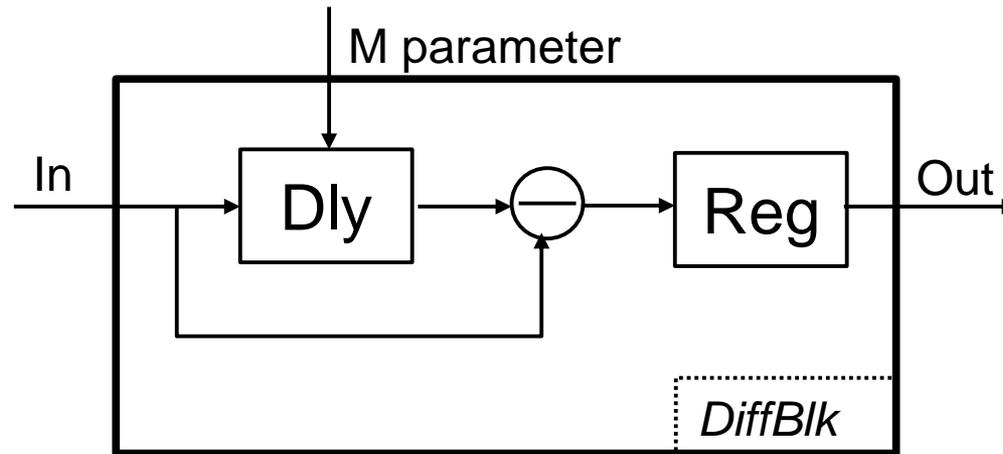
- Counts the period b/w cfd triggers (up to a max. value, set by the user).
- Compares the current period with previous one and selects the smallest one of the two.
- The smallest period is then halved and the point to loaded to the Diff Blk is also calculated.



Differential Block



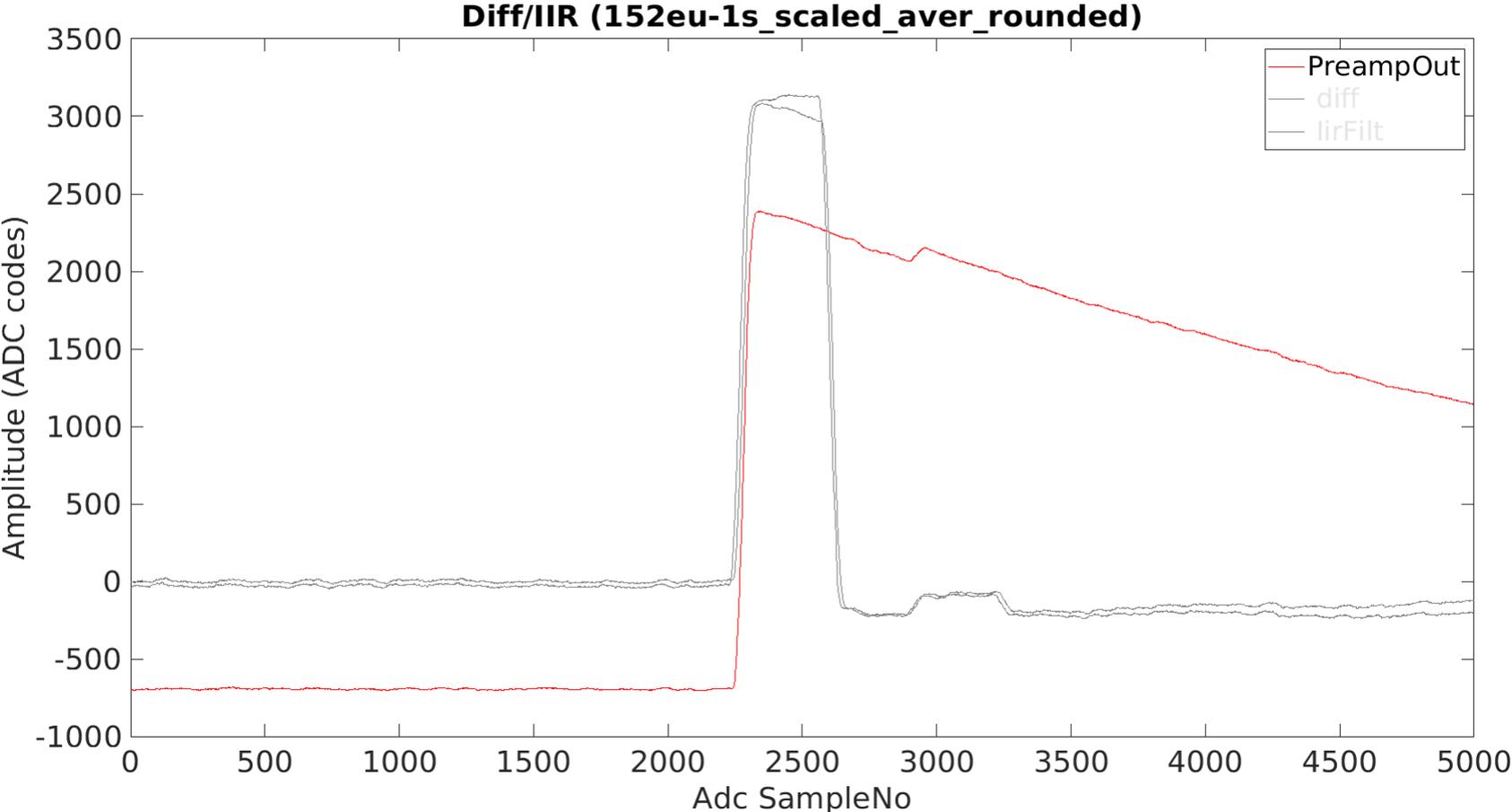
Differential Block



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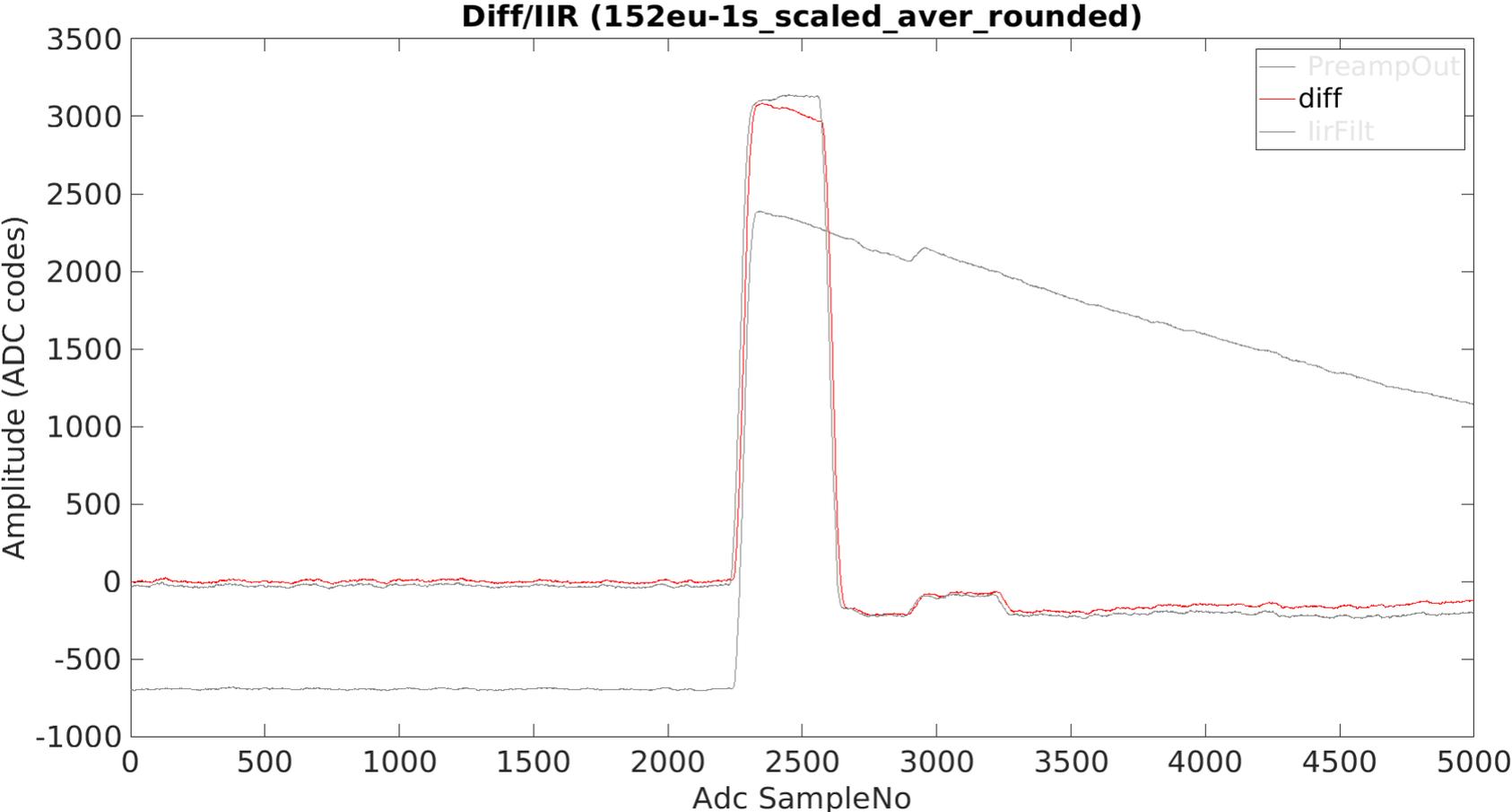
Differential Block



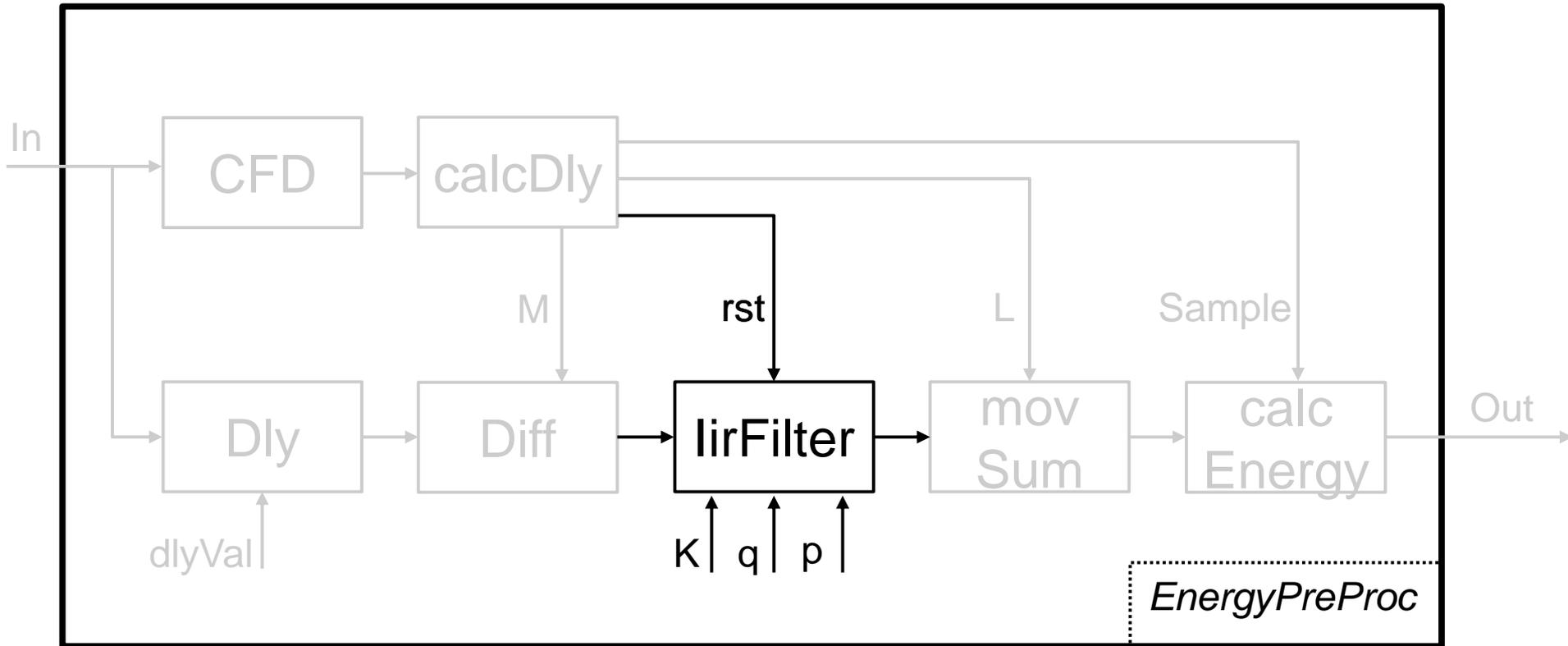
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Differential Block



IIR Filter



IIR Filter

- A more general approach is to estimate the transfer function of the pre-amplifier output using higher order models.
- Then calculate the inverse transfer function.
- Convert the inverse transfer function to the z^{-1} domain.
- So for a 3rd order model:

$$H(z) = \frac{Y(z)}{X(z)} = \frac{b_0 + b_1z^{-1} + b_2z^{-2}}{1 + a_1z^{-1} + a_2z^{-2}}$$

- The above transfer function can then be implemented as an Infinite Impulse Response (IIR) filter [Ref.2].



Transfer function Factorization

So for a 3rd order model, transfer function is:

$$H(z) = \frac{Y(z)}{X(z)} = \frac{b_0 + b_1z^{-1} + b_2z^{-2}}{1 + a_1z^{-1} + a_2z^{-2}}$$

Factorise above transfer function to:

$$H(z) = \frac{Y(z)}{X(z)} = K \frac{(1 - q_0z^{-1})(1 - q_1z^{-1})(1 - q_2z^{-1})}{(1 - p_0z^{-1})(1 - p_1z^{-1})(1 - p_2z^{-1})}$$

K = gain

q = zeros

p = poles

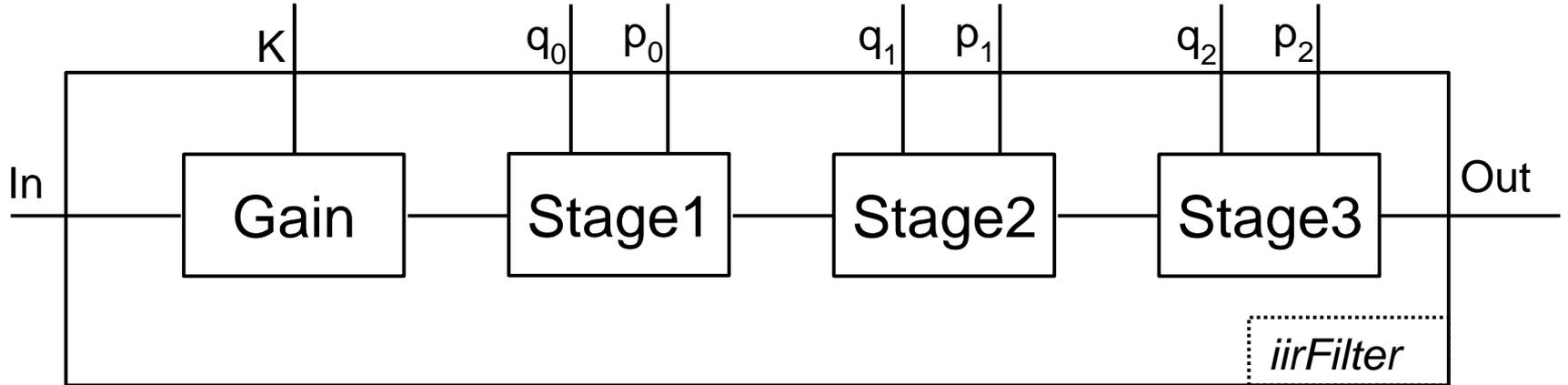


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Implementation

Cascade of first order filters:



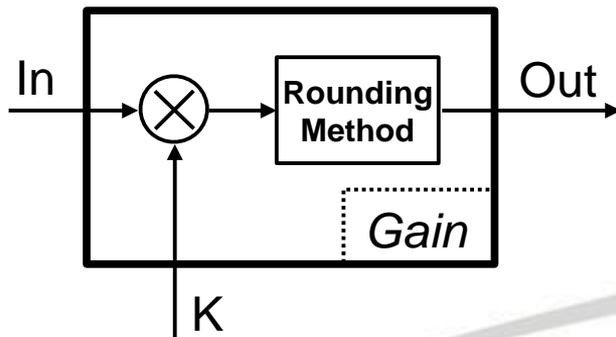
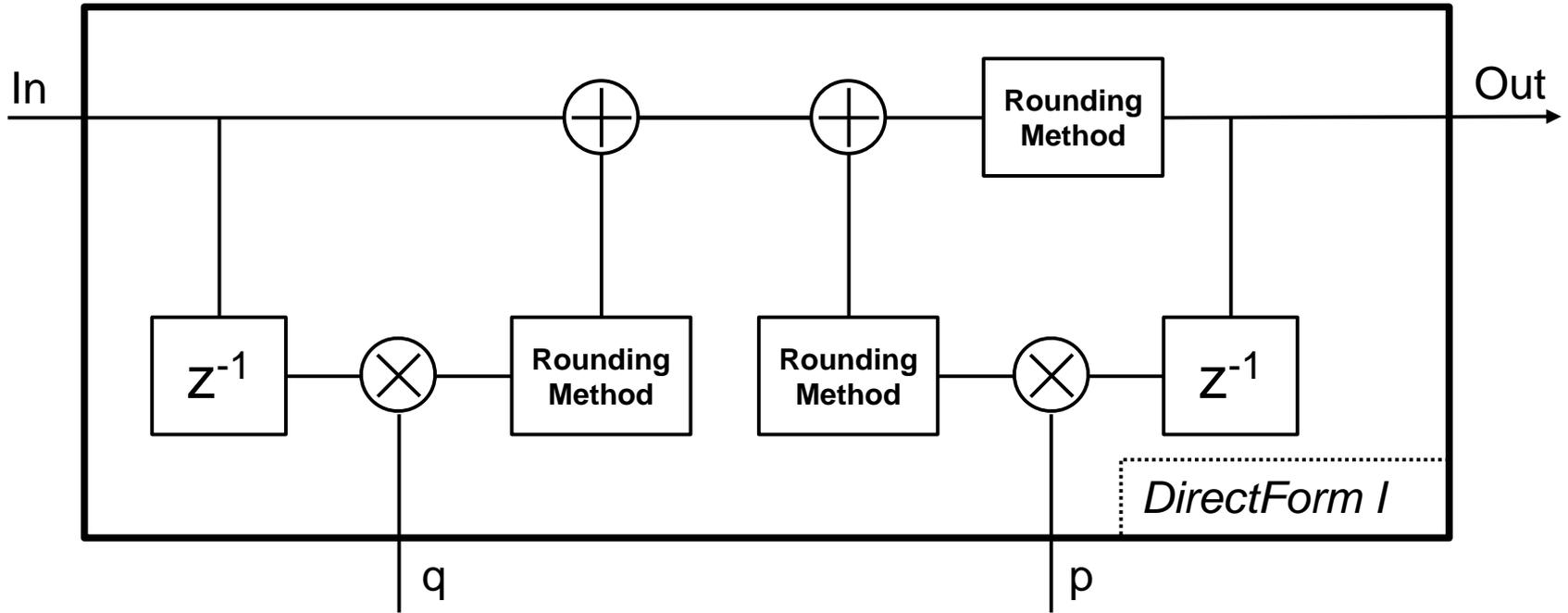
$K = \text{gain}$
 $q = \text{zeros}$
 $p = \text{poles}$



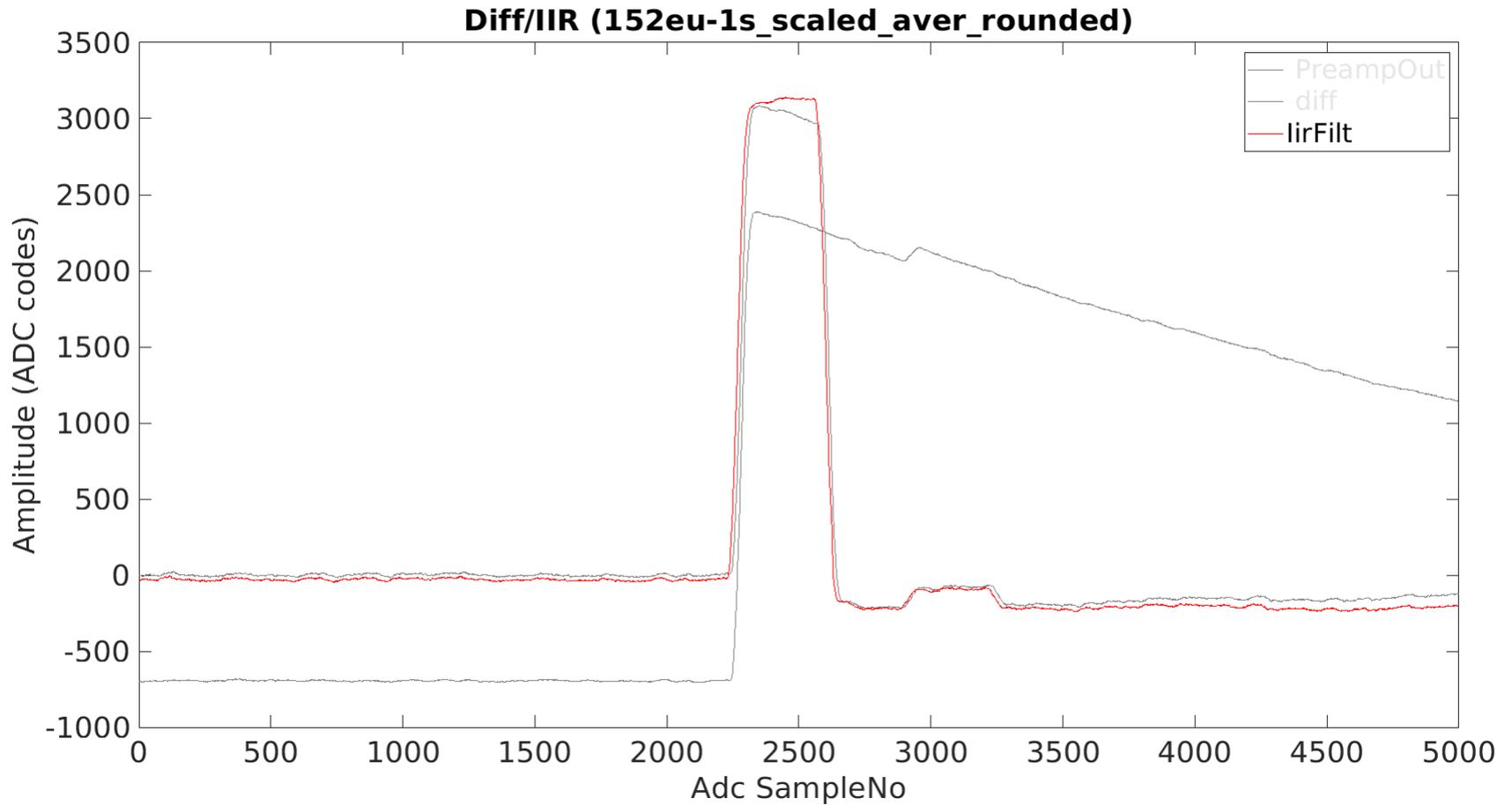
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Direct form I



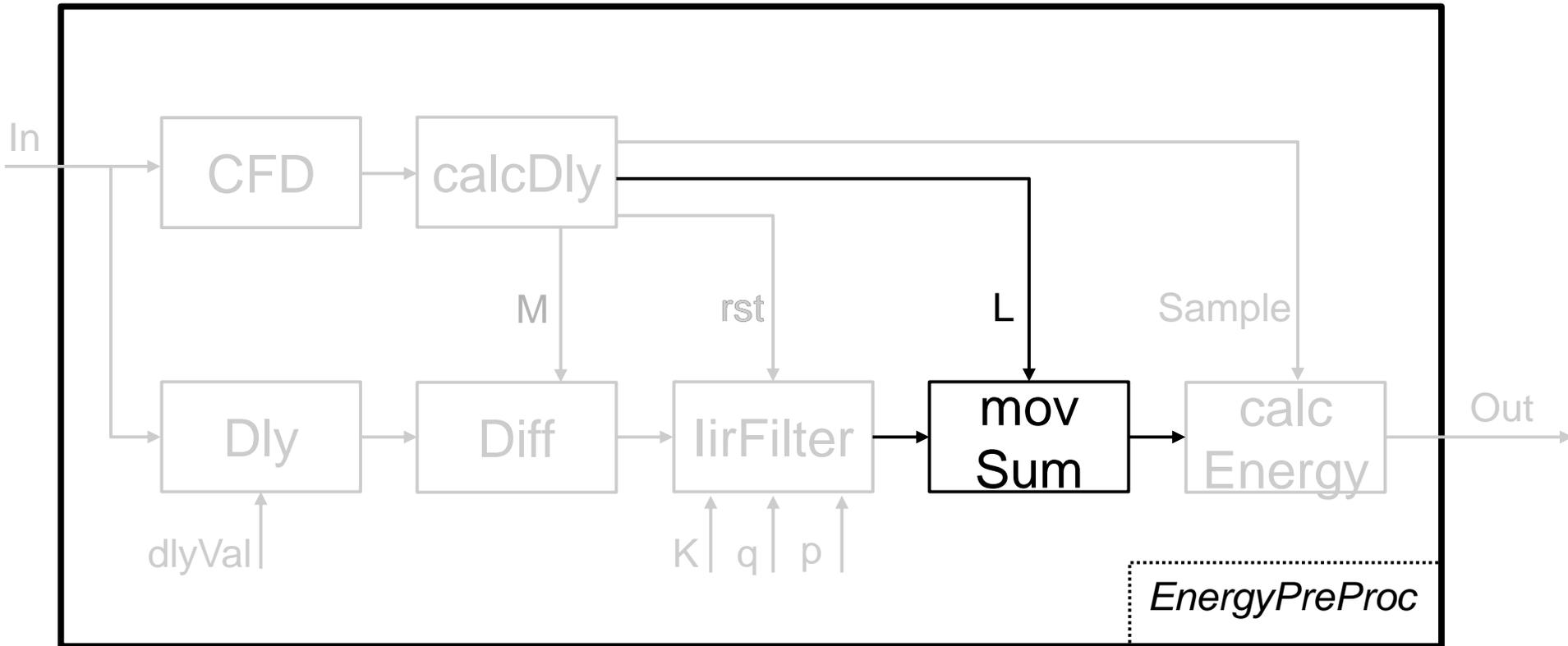
IIR Filter



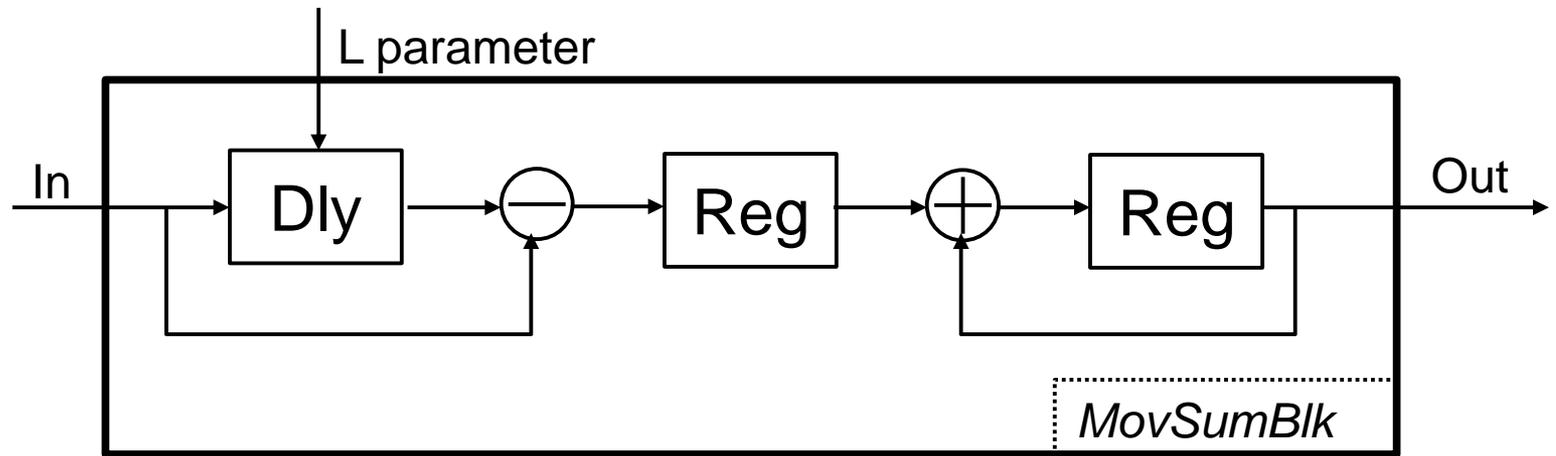
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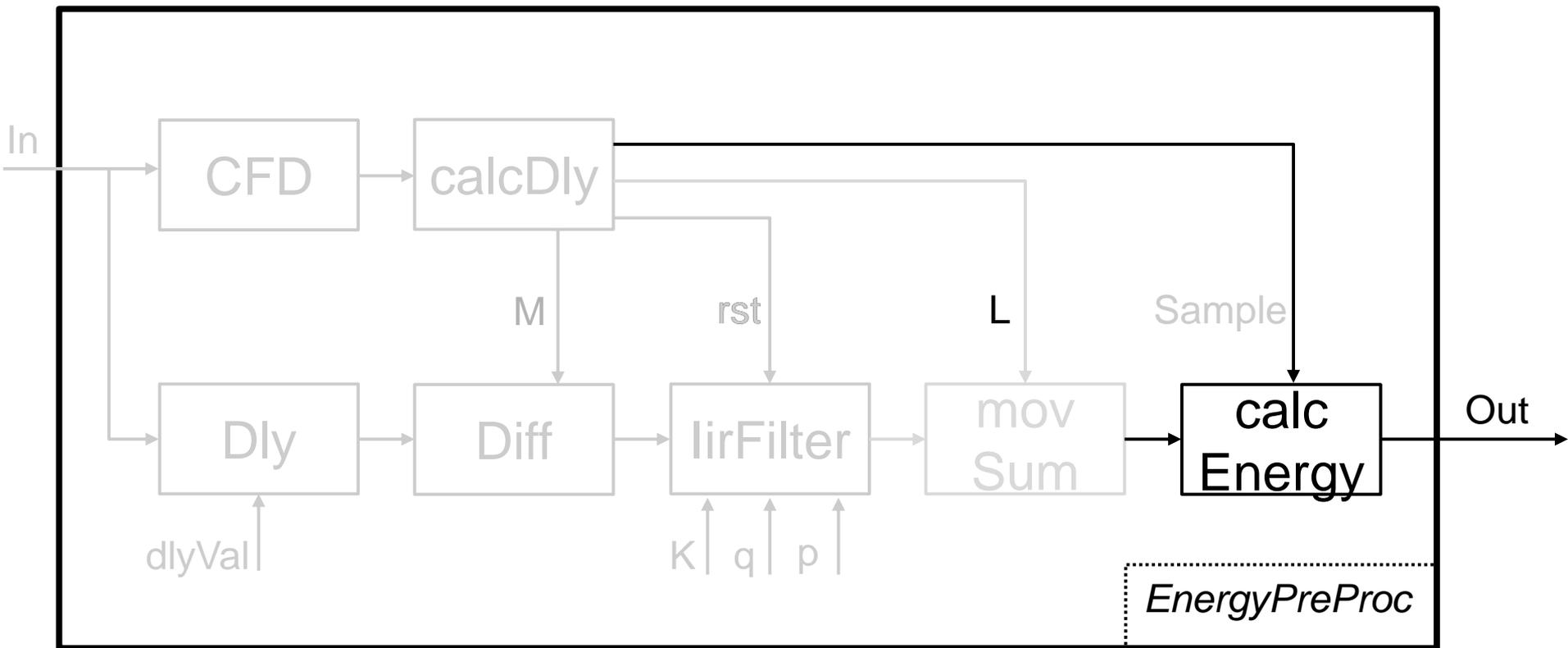
Moving Sum Block



Moving Sum Block



Energy Calc



ToDo

- Adjust the Moving Average (L) parameters depending on the duration of events and calculate the energy.
- Baseline restoration.
- Require longer traces from detectors, with multiple events per core/segment trace.



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References

1. EnergyProcessing.pdf, courtesy of Emmanuel Clement.
2. P.Födisch et al., “Digital high-pass filter deconvolution by means of an infinite impulse response filter”, Nuclear Instruments and Methods in Physics Research Section A, 2016.



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