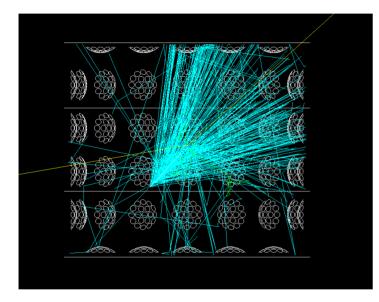
## **FITQUN AND PYFITQUN PROGRESS FOR WCTE**



Gonzalo Díaz López Neutrino group meeting 24 April 2024



### **FITQUN ALGORITHM**



Example: simulated  $\mu$ - for WCTE geometry

**Read** event hits (time, charge)

**Prefit** : use time to estimate vertex (t, **x**)

Subeventing The peak finder Hit clustering

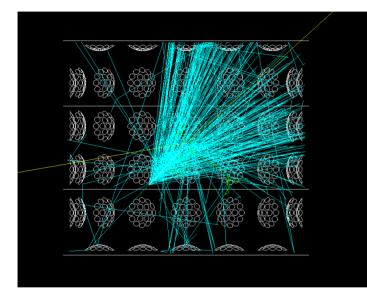
Single ring fits (t, x, p)

Multi ring fits

### **FITQUN ALGORITHM**

1

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Example: simulated  $\mu$ - for WCTE geometry

$$\mathbf{X} \equiv (\mathbf{x}, \mathbf{p})_{\mathrm{ring}}$$

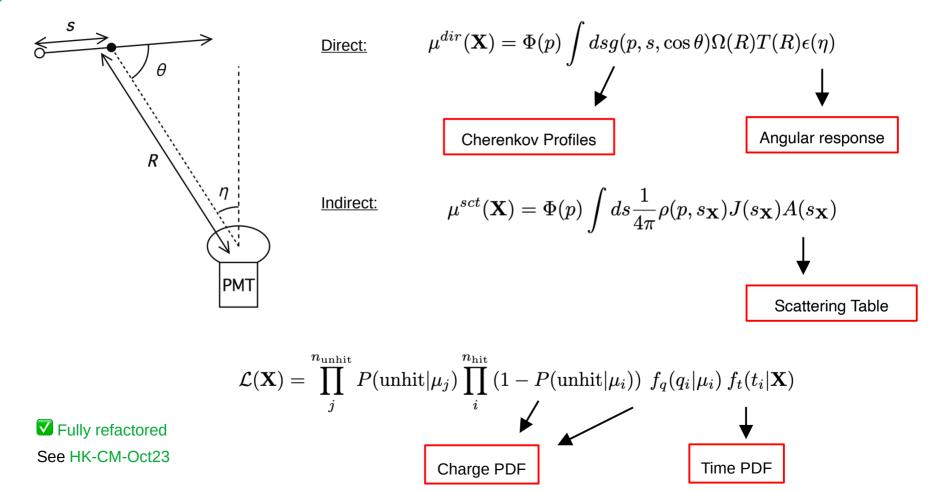
i

$$egin{aligned} \mathcal{L}(\mathbf{X}) &= \prod_{j}^{n_{ ext{unhit}}} P_j( ext{unhit}|\mathbf{X}) \prod_{i}^{n_{ ext{hit}}} \left(1 - P_i( ext{unhit}|\mathbf{X})
ight) \, f_q(q_i|\mathbf{X}) \, f_t(t_i|\mathbf{X}) \ && \mu_i \equiv \mu_i\left(\mathbf{X}
ight) \quad ext{predicted charge} \ && \mathcal{L}(\mathbf{X}) = \prod_{i}^{n_{ ext{unhit}}} P( ext{unhit}|\mu_j) \prod_{i}^{n_{ ext{hit}}} \left(1 - P( ext{unhit}|\mu_i)
ight) \, f_q(q_i|\mu_i) \, f_t(t_i|\mathbf{X}) \end{aligned}$$

Each fiTQun iteration requires the computation of the **predicted charge** 

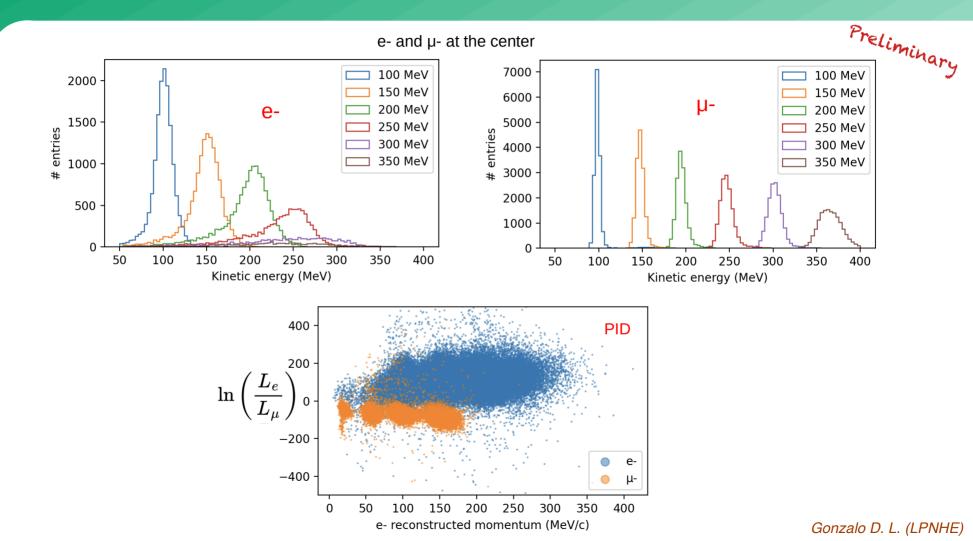
j

## **FITQUN TUNING**



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### **SOME WCTE RESULTS**



7

# **II. PYFITQUN**

### **MOTIVATION**

### PyfiTQun https://github.com/gondiaz/PyfiTQun/

- Simplify fiTQun readability using Python (early development)
- Objectives:
  - · check subalgorithms in fiTQun reconstruction (prefiting, subevent search, full fit)
  - debugging and knowing all the requirements for a future performance driven refactoring

#### Event Loop

```
event_loop_iterator = manager.event_loop_iterator()
for next_event in event_loop_iterator:
    if next_event is None: continue
    event, hits = next_event
```

#### # prefit

```
logger.info("Performing prefit...")
success, seed = likelihood_fit_seed(hits, prefit_sigma, cn, max_travel_time, radius, length, False)
event_data["prefit"] = (success, seed[:4])
if success: logger.info("Prefit successful")
else : logger.warning("Prefit not successful")
```

```
# TODO: Find subevents
```

```
# Likelihood fit
for particle in manager.particles:
```

logger.info(f"Performing likelihood fit for particle {particle}")

#### **Implemented** :

- Readers for WCSim and tuning files
- Event manager
- Prefit
- Parabolic approximation coefficients
- Predicted charges
- Likelihood function

#### **TODOs:**

- Finalize single ring fit
- Subeventing
- Multi rings

### **THE VERTEX PREFIT**

- Event reconstruction in water Cherenkov detectors is based on the pair of values (charge, time)
- Baseline reconstruction algorithm is fiTQun: (position, direction, energy, particle type)
- First step, vertex pre-fit:
  - Search for the interaction vertex (position) using only time information (triangulation)
  - Seeds multi-ring search
  - Seeds full fit
- WCTE is very small ~3x3 m<sup>2</sup>, how good it is the vertex pre-fit?

Δ No tuning needed except for the σ

Prefit minimizer:

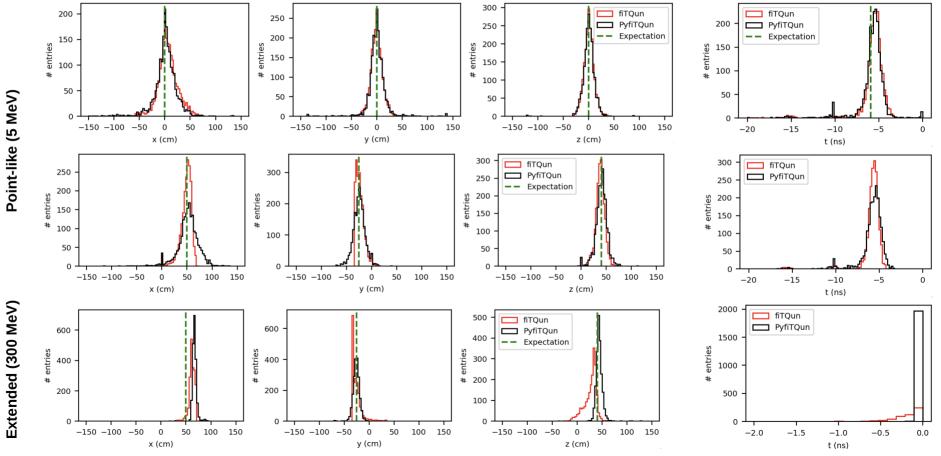
$$G(t,\mathbf{x})\equiv\sum_{h}^{n_{hits}}e^{-rac{1}{2}(T_{h}/\sigma)^{2}}$$

$$T_{h} \equiv t_{h} - t - \left\| \mathbf{R}_{h}^{\mathrm{PMT}} - \mathbf{x} \right\| / c_{n}$$

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### **SOME WCTE RESULTS**

e- samples with horizontal direction, prefit  $\sigma = 1$  ns



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11

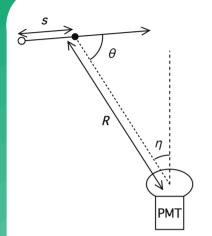
# **III. COMMENTS AND CONCLUSIONS**

### **COMMENTS AND CONCLUSIONS**

- Full refactoring of the tuning procedure
- Validation of the tuning is in progress due to differences in the cherenkov profiles
- Preliminary results on the full **fiTQun reconstruction** for WCTE
- fiTQun prefit performs well and is stable for WCTE
- Identified some improvements/fixes in C++ fiTQun:
  - Likely faster if parabolic coefficients j,k also computed in the tuning procedure
  - Is the parablic approximations actually needed? Couldn't we just tune the predicted charges?
  - Improve performace of Scattering Table computation to increase statistics
  - Indirect light not computed correctly as PMT positions are based on orientations (not valid for mPMTs)
- PyfiTQun allows to know the needed requirements of fiTQun algorithm
- PyfiTQun under development, needed to improve performance, 10 times slower
- **PyfiTQun** makes easier to include new features such as j, k tuning and analytic derivatives to minimizers
- Short term plan: implement single ring reconstruction, fully validate new tuning tools (Cherenkov Profiles)
- Long term plan: work on performance (simplify tuning and paralelization)

### BACKUP

### **UNEEDED APPROXIMATIONS**



$$egin{aligned} \mu^{dir}(p,r_0,\cos heta_0) &= \Phi(p)\int_0^{d_m(p)} dsg(p,s,\cos heta)J(s) pprox \Phi(p)(I_0j_0+I_1j_1+I_2j_2)\ &J(s) \equiv \Omega(R)T(R)\epsilon(\eta) pprox j_0+j_1s+j_2s^2 \end{aligned}$$

$$egin{aligned} \mu^{sct}(p,r_0,\cos heta_0) &= \Phi(p) \int_0^{d_m(p)} ds \int_\Omega ds rac{1}{4\pi} 
ho(p,s) J(s) A(s) &pprox \Phi(p) (K_0 k_0 + K_1 k_1 + K_2 k_2) \ && J(s) A(s) &pprox k_0 + k_1 s + k_2 s^2 \end{aligned}$$

Save computing time (they are computed in every iteration) and memory (avoid loading STable)

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Cherenkov profiles  $\mu^{dir}(r_0, \cos \theta_0) = \Phi(p) \int dsg(p, s, \cos \theta) \Omega(R) T(R) \epsilon(\eta)$ 

$$J(s) \equiv \Omega(R)T(R)\epsilon(\eta) \approx j_0 + j_1s + j_2s^2$$

$$\mu^{dir}(r_0, \cos \theta_0) = \Phi(p) \int dsg(p, s, \cos \theta) J(s)$$
  
 
$$\approx \Phi(p)(I_0 j_0 + I_1 j_1 + I_2 j_2)$$

$$I_n(p,r_0,\cos heta_0)=\int dsg(s)s^npprox \sum_{i=0}^{n_{par}}J_i(r_0,\cos heta_0)p^i$$

### Scattering table

$$\mu^{sct}(\vec{\mathbf{x}},\vec{\mathbf{p}}) = \Phi(p) \int ds \frac{1}{4\pi} \rho(p,s_{\vec{\mathbf{x}},\vec{\mathbf{p}}}) J(s_{\vec{\mathbf{x}},\vec{\mathbf{p}}}) A(s_{\vec{\mathbf{x}},\vec{\mathbf{p}}}) ds_{\vec{\mathbf{x}},\vec{\mathbf{p}}} ds_{\vec{\mathbf{x}},\vec{\mathbf{p}}}} ds_{\vec{\mathbf{x}},\vec{\mathbf{p}}} ds_{\vec{\mathbf{x}},\vec{\mathbf{p}}}} ds_{\vec{\mathbf{x}},\vec{\mathbf{p}}} ds_{\vec{\mathbf{x}},\vec{\mathbf{p}}} ds_{\vec{\mathbf{x}},\vec{\mathbf{p}}}} ds_{\vec{\mathbf{x}},\vec{\mathbf{p}}} ds_{\vec{\mathbf{x}},\vec{\mathbf{p}}} ds_{\vec{\mathbf{x}},\vec{\mathbf{p}}} ds_{\vec{\mathbf{x}},\vec{\mathbf{p}}} ds_{\vec{\mathbf{x}},\vec{\mathbf{p}}}} ds_{\vec{\mathbf{x}},\vec{\mathbf{p}}} ds_{\vec{\mathbf{x}},\vec{\mathbf{p}}}} ds_{\vec{\mathbf{x}},\vec{\mathbf{p}}} ds_{\vec{\mathbf{x}},\vec{\mathbf{p}}} ds_{\vec{\mathbf{x}},\vec{\mathbf{p}}} ds_{\vec{\mathbf{x}},\vec{\mathbf{p}}} ds_{\vec{\mathbf{x}},\vec{\mathbf{p}}} ds_{\vec{\mathbf{x}},\vec{\mathbf{p}}} ds_{\vec{\mathbf{x}},\vec{\mathbf{p}}} ds_{\vec{\mathbf{x}},\vec{\mathbf{p}}} ds_{\vec{\mathbf{x}},\vec{\mathbf{p}}} ds_{\vec{\mathbf{x}},\vec{\mathbf{x}},\vec{\mathbf{p}}} ds_{\vec{\mathbf{x}},\vec{\mathbf{x}},\vec{\mathbf{x}},\vec{\mathbf{p}}} ds_{\vec{\mathbf{x}},\vec{\mathbf{x}},\vec{\mathbf{p}}} ds_{\vec{\mathbf{x}},\vec{\mathbf{x}},\vec{\mathbf{p}}} ds_{\vec{\mathbf{x}},\vec{\mathbf{x}},\vec{\mathbf{p}}} ds_{\vec{\mathbf{x}},\vec{\mathbf{p}}} ds_{\vec{\mathbf{x}},\vec{\mathbf{p}}} ds_{\vec{\mathbf{x}},\vec{\mathbf{p}}} ds_{\vec{\mathbf{x}},\vec{\mathbf{p}}} ds_{\vec{\mathbf{x}},\vec{\mathbf{p}}} ds_{\vec{\mathbf{x}},\vec{\mathbf{p}}} ds_{\vec{\mathbf{x}},\vec{\mathbf{p}}}} ds_{\vec{\mathbf{x}},\vec{\mathbf{p}}} ds_{\vec{\mathbf{x}},\vec{\mathbf{p}}} ds_{\vec{\mathbf{x}},\vec{\mathbf{p}}} ds_{\vec{\mathbf{x}},\vec{\mathbf{p}}} ds_{\vec{\mathbf{x}},\vec{\mathbf{p}}}} ds_{\vec{\mathbf{x}},\vec{\mathbf{p}}} ds_{\vec{\mathbf{x}},\vec{\mathbf{p}}}} ds_{\vec{\mathbf{x}},\vec{\mathbf{p}}} ds_{\vec{\mathbf{x}},\vec{\mathbf{p}}}} d$$

$$ho(p,s)\equiv\int g(p,s,\cos heta)d\Omega$$

$$A(z_s, R_s; z_{ ext{PMT}} | R_{ ext{PMT}}, \phi; z_d, heta) = rac{d\mu^{sct}}{d\mu^{dir, iso}}$$

 $\label{eq:posterior} \begin{array}{l} \mbox{Charge PDF} \\ P({\rm unhit}|\mu) \approx (1+a_1\mu+a_2\mu^2+a_3\mu^3)e^{-\mu} \end{array}$ 

$$f_q(q|\mu)\cong\sum_{i=0}^{n_{pars}}a_i(q)\mu^i$$

$$\label{eq:time_pdf} \begin{array}{l} \mbox{Time PDF}\\ t_h^{res} = t_h - t - s_{mid}/c - |\mathbf{R}_h^{\rm PMT} - \mathbf{x} - s_{mid}\mathbf{d}|/c_n \end{array}$$

$$f_t(t_h^{res}) = w f_t^{dir}(t_h^{res}) + (1-w) f_t^{sct}(t_h^{res})$$

$$w = \frac{1 - e^{-\mu^{dir}}}{1 - e^{-\mu^{dir}} e^{-\mu^{sct}}}$$

Direct:

$$(\mu,\sigma)(p,\mu^{dir}) = \sum_{i=0}^{n_{gauss}} a_i(p) \; \mu^{dir}$$
 $a_i(p) = \sum_{j=0}^{n_{pars}} b_{ij} \; p^j$ 

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