

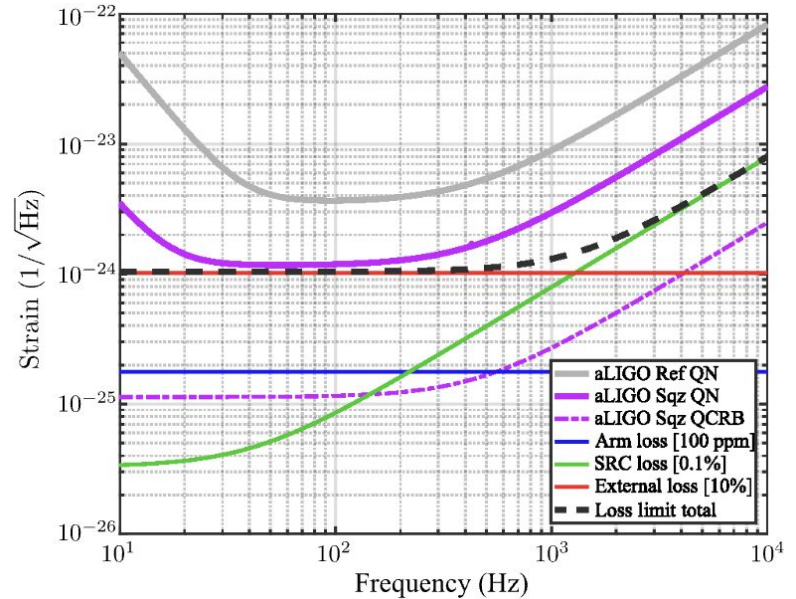
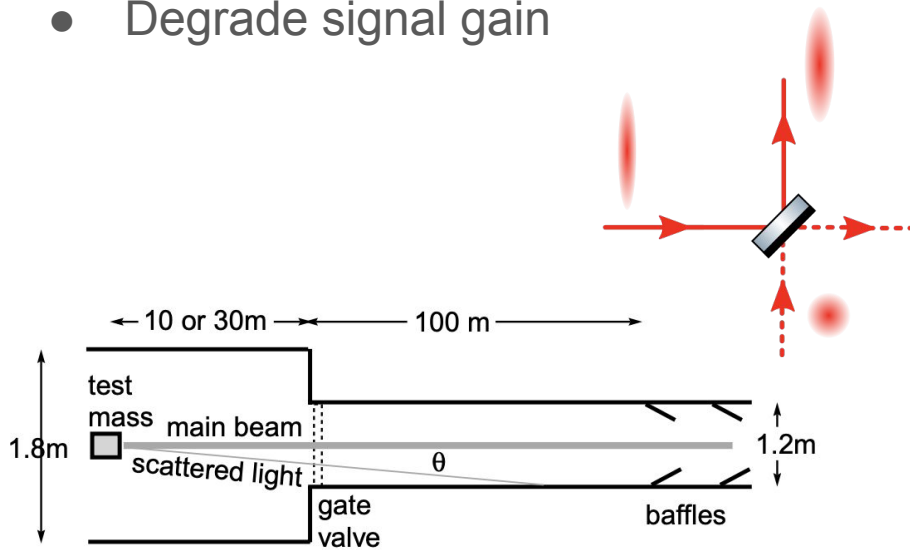
Study of the optical losses as a function of beam position on the mirrors in the filter cavity

Yuhang Zhao, Marco Vardaro, Eleonora Capocasa, Jacques Ding, Yuefan Guo, Michel Lequime, Matteo Barsuglia



Optical losses in gravitational wave detectors

- Introduce noise
- Impair noise reduction (for squeezing)
- Degrade signal gain



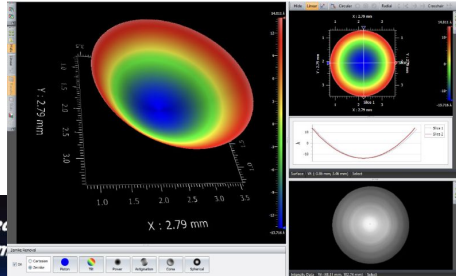
Characterization of scattering losses

Several methods can be use:

Characterize a single mirror
(During fabrication)

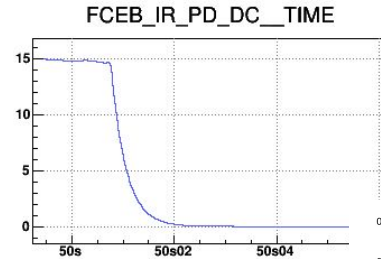


Measure surface height



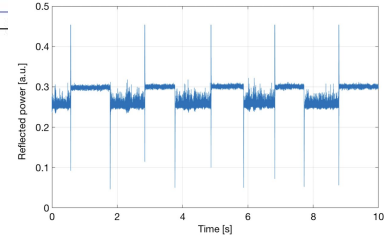
Measure scattering

Characterize a cavity
(After integration)



Measure storage time

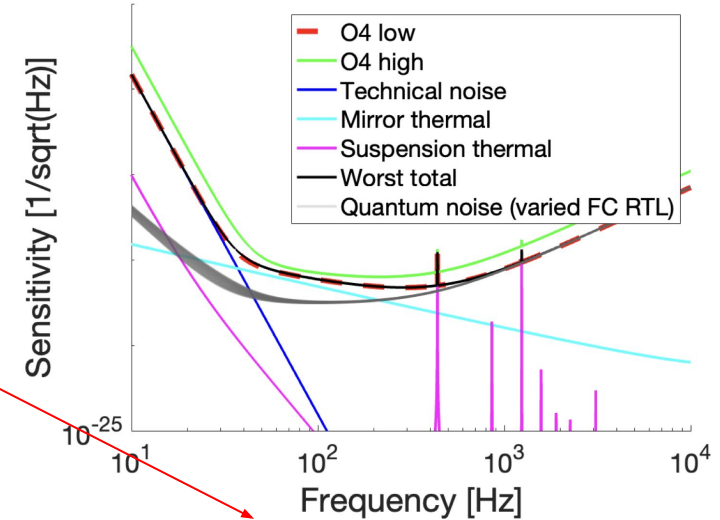
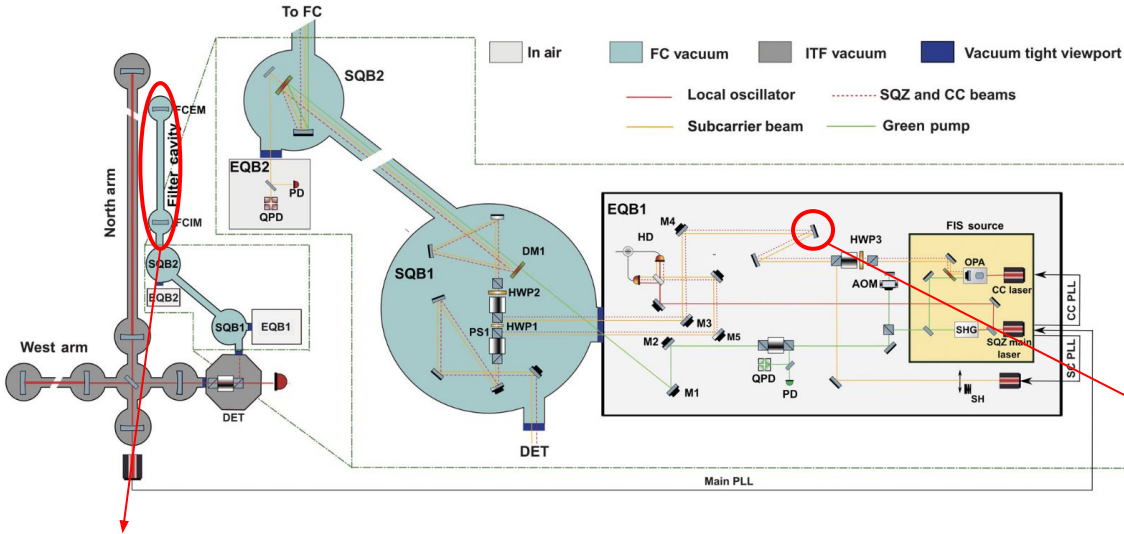
Measure cavity reflection



Losses and sensitivity of Virgo

A visible influence of filter cavity losses on sensitivity

**RTL uncertainty:
30-100 ppm**

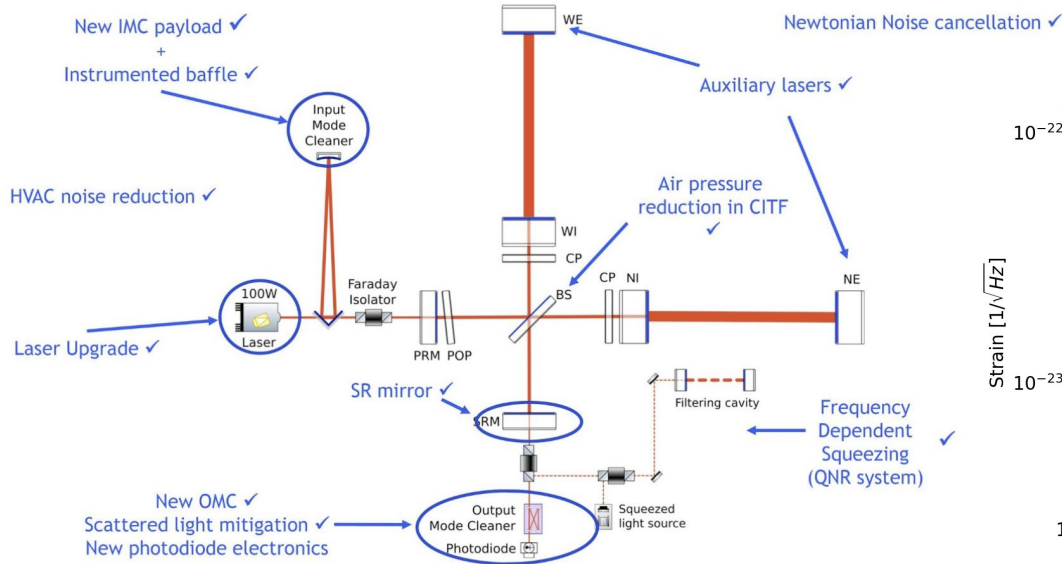


30-100 ppm has visible effect due to **light bouncing back forth between mirrors**

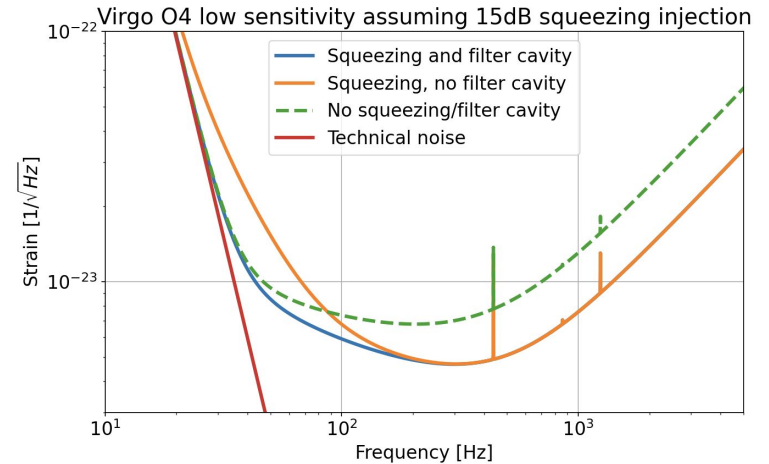
Single bounce, 30-100 ppm will not make a difference

The filter cavity in Virgo

Filter cavity is one of the upgrade for Advanced Virgo+ phase one, with the goal of broadband quantum noise reduction

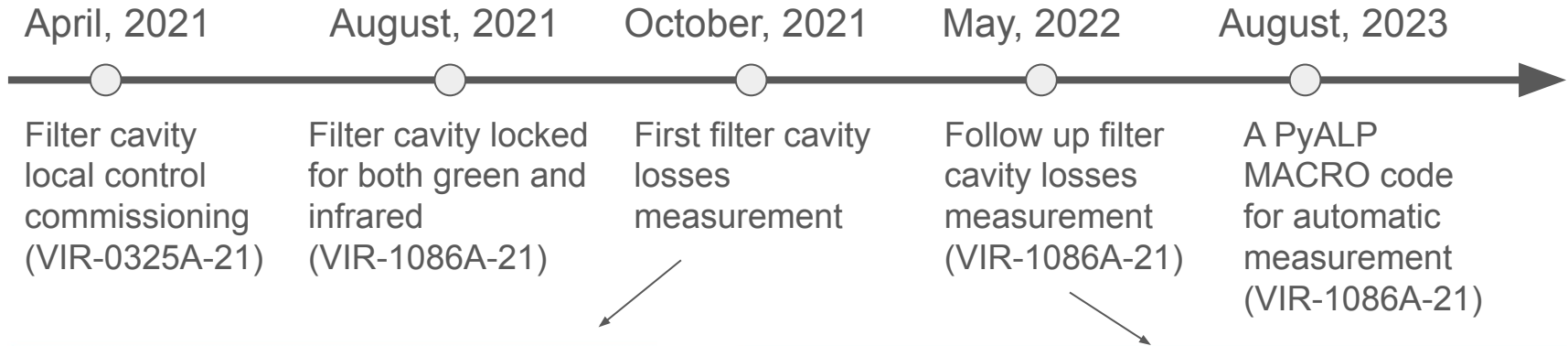


PHASE I OF THE UPGRADES TO ADVANCED VIRGO + COMPLETED
May 5, 2021



The filter cavity construction and characterization history

During filter cavity commissioning, **very different optical losses are measured**



AdV-SGD (FDS commissioning)

[guo, vardaro](#) - 20:46 Tuesday 05 October 2021 (53392) 📧 📄

Filter cavity round trip losses measurement with EQB2 PD

AdV-SGD (FDS commissioning)

[Zhao, Msihid, Ding, Guo, Grimaldi, Capocasa](#) - 11:29 Tuesday 24 May 2022 (55947) 📧 📄

Comment to IR loss budget (55651)

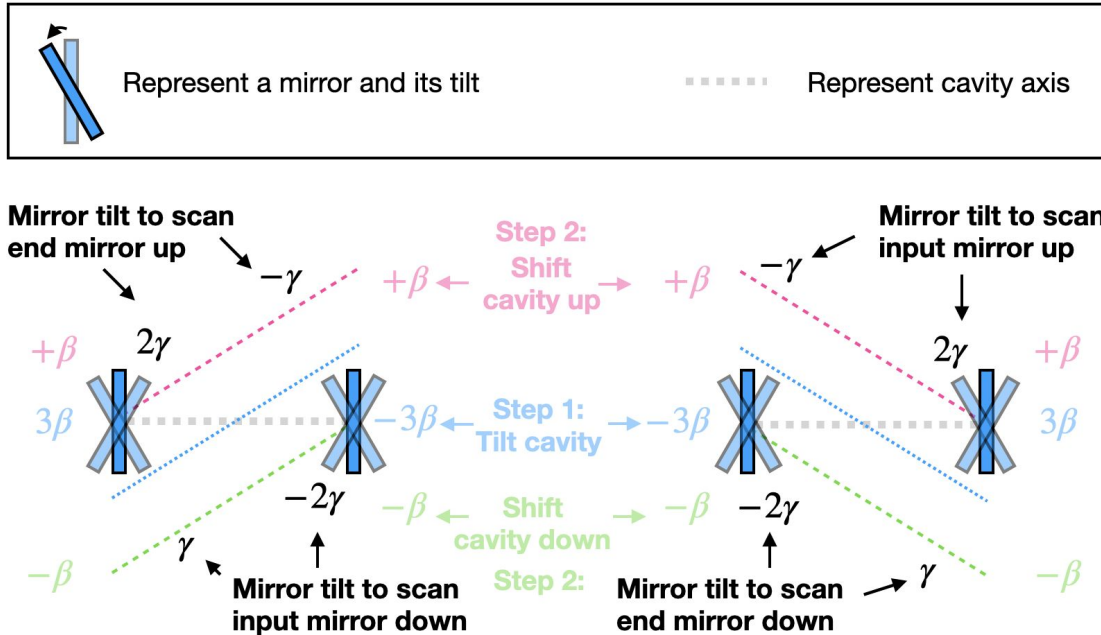
About 31 ppm



About 89 ppm

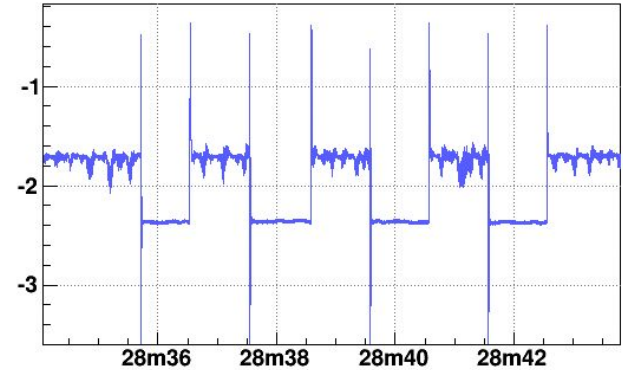
Measurement methodology

1. Scan mirrors separately



2. Measure losses

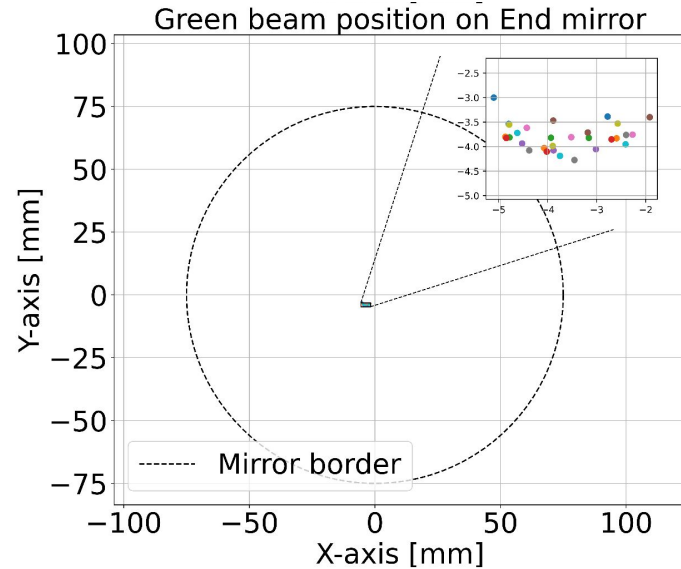
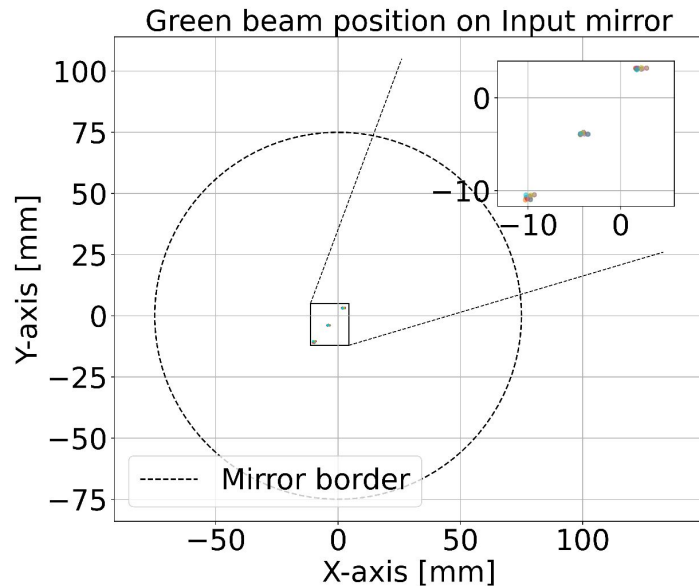
EQB2_IR_PD_DC__TIME



1382383732.0531 Oct26 2023 19:28:34 UTC

Study of the repeatability

Losses measurements were performed for three points during ten days



Losses measurements

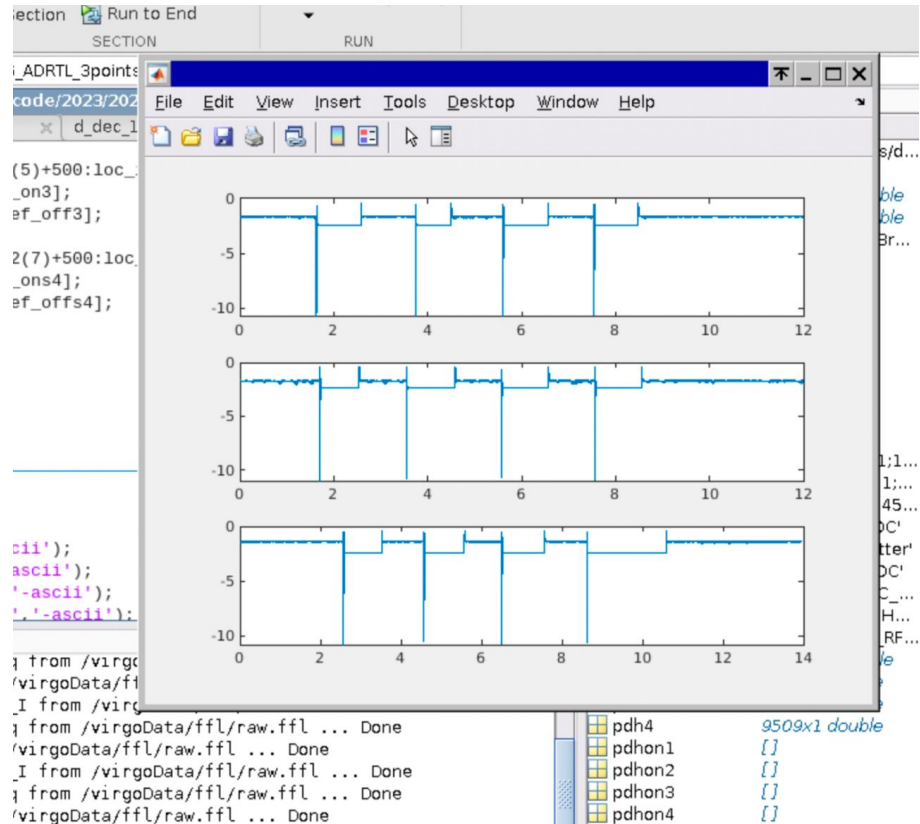
- Usual technique reported in **Phys. Rev. D 98, 022010**

$$L \sim \frac{T_1}{2} \frac{1 - R_{\text{cav}}}{1 + R_{\text{cav}}} = \frac{T_1}{2} \frac{1 - P_{\text{res}}/P_{\text{in}}}{1 + P_{\text{res}}/P_{\text{in}}}$$

- We considered the estimation the uncoupled power due to mismatch, sidebands

$$R_{\text{cav}} = \frac{R_{\text{cav}}^\gamma - \gamma}{(1 - \gamma)}$$

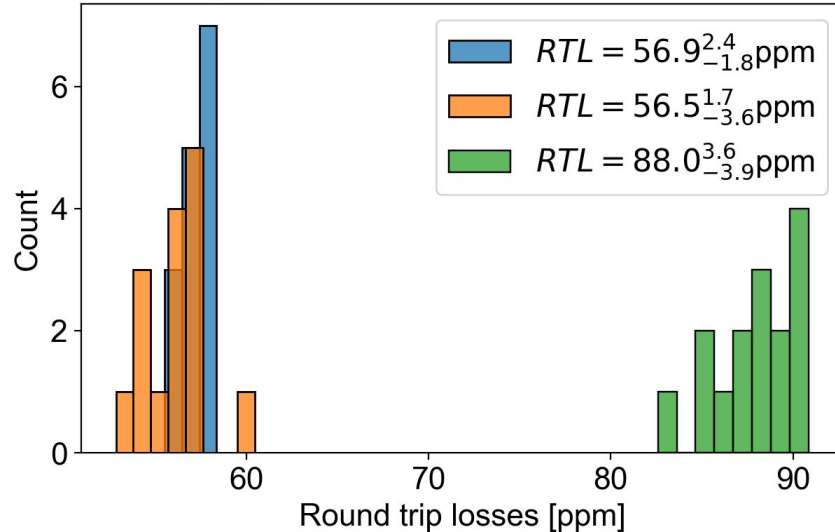
- Effect of a small clipping on the measurement is not relevant



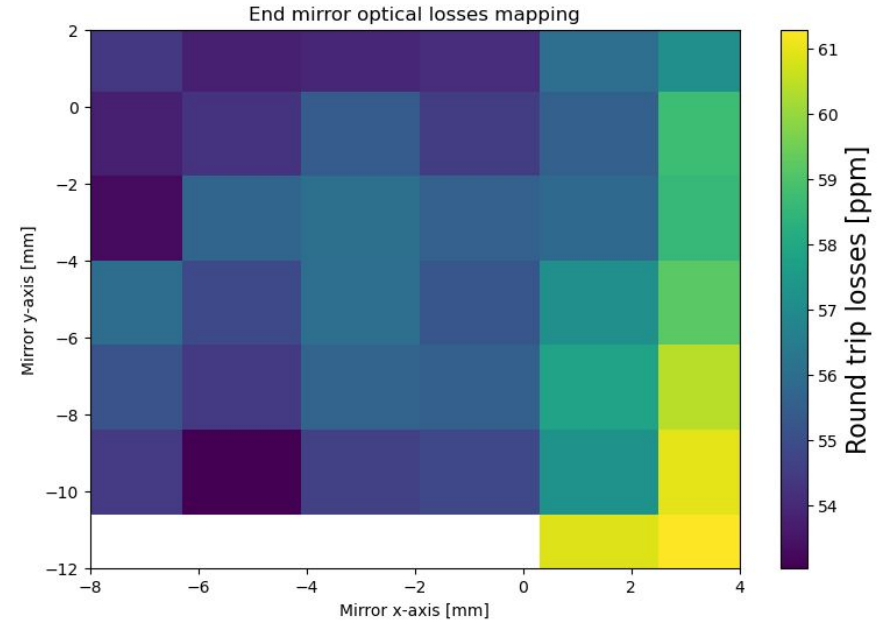
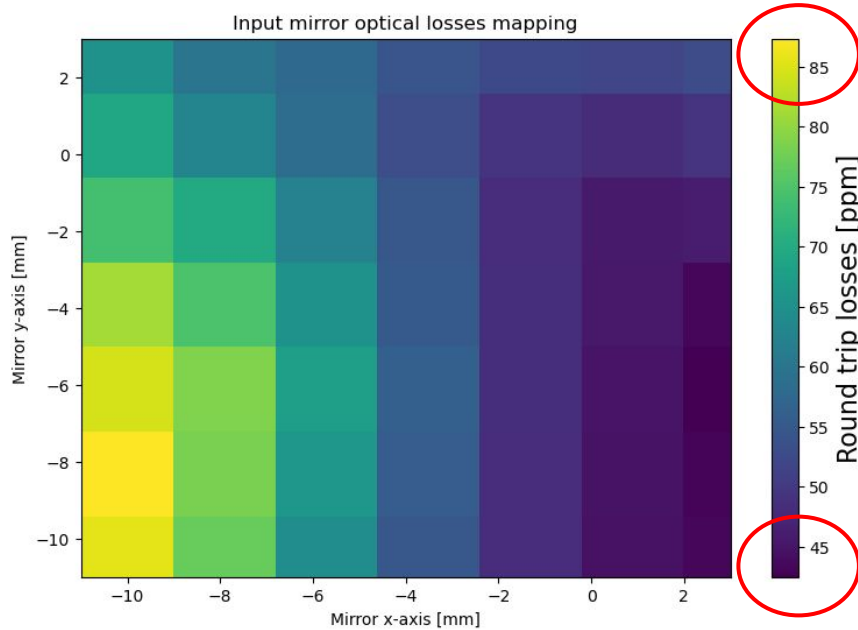
The repeatability of measurements

A ten-days characterization proves the repeatability of our result

On-off measurements of three different positions on filter cavity input mirror from 1 Dec to 11 Dec 2023



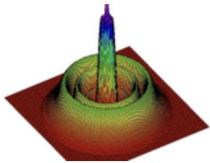
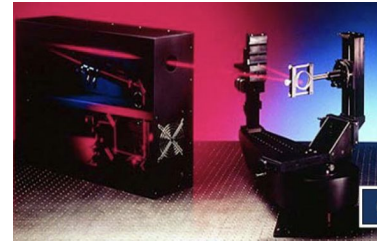
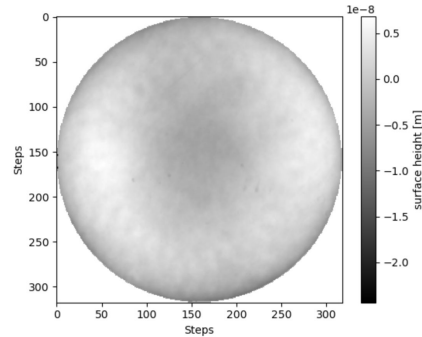
A losses map for input and end mirrors



Estimation of optical losses

Mirror characterizations before cavity integration is very useful for predicting the total losses that can be achieved in an optical cavity

- Small angle scattering
- Large angle scattering
- Middle angle scattering



OSCAR

Versione 3.30.0.0 (3,29 MB) da Jerome Degallaix

An optical FFT code to simulate Fabry Perot cavities with arbitrary mirror profiles

<https://github.com/Jerome-LMA/oscar>

© 2010



Mirror characterization at low spatial frequency

The mirror surface was characterized with Zygo interferometer with a resolution $\sim 0.3\text{mm}$. This map was used in Oscar to predict small angle scattering losses



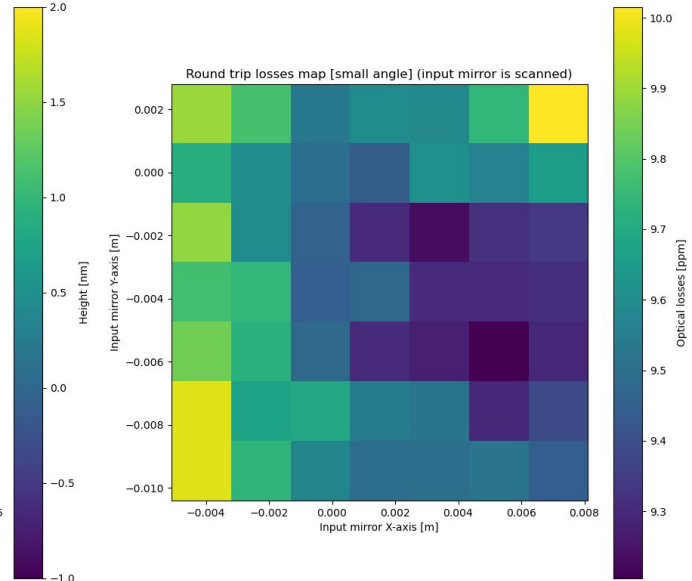
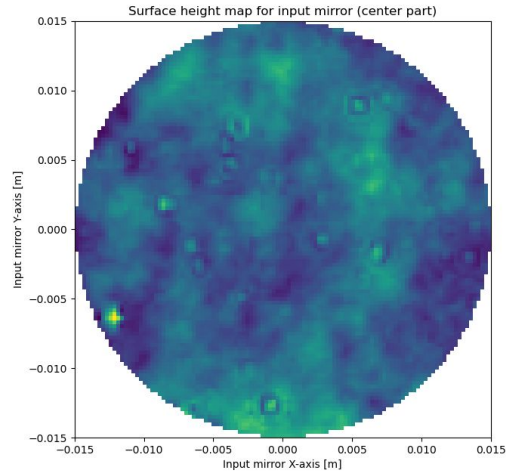
OSCAR

Version 3.30.0

An optical FFT

<https://github.com>

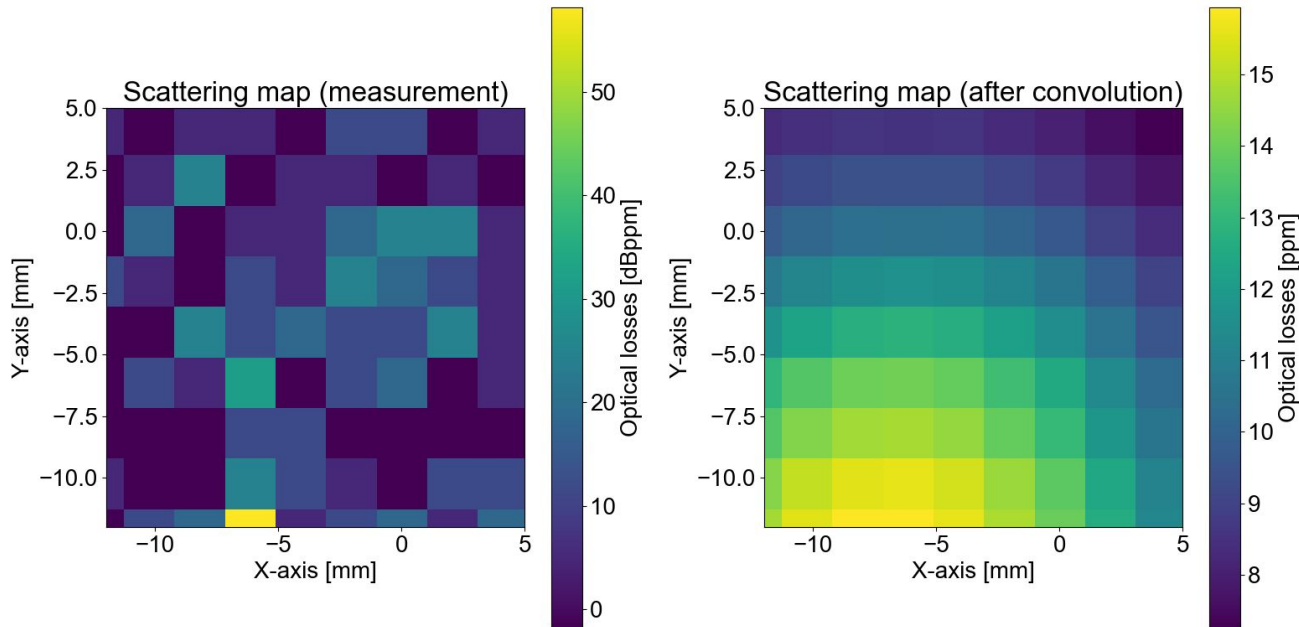
© 2018-2020



Mirror characterization at high frequencies

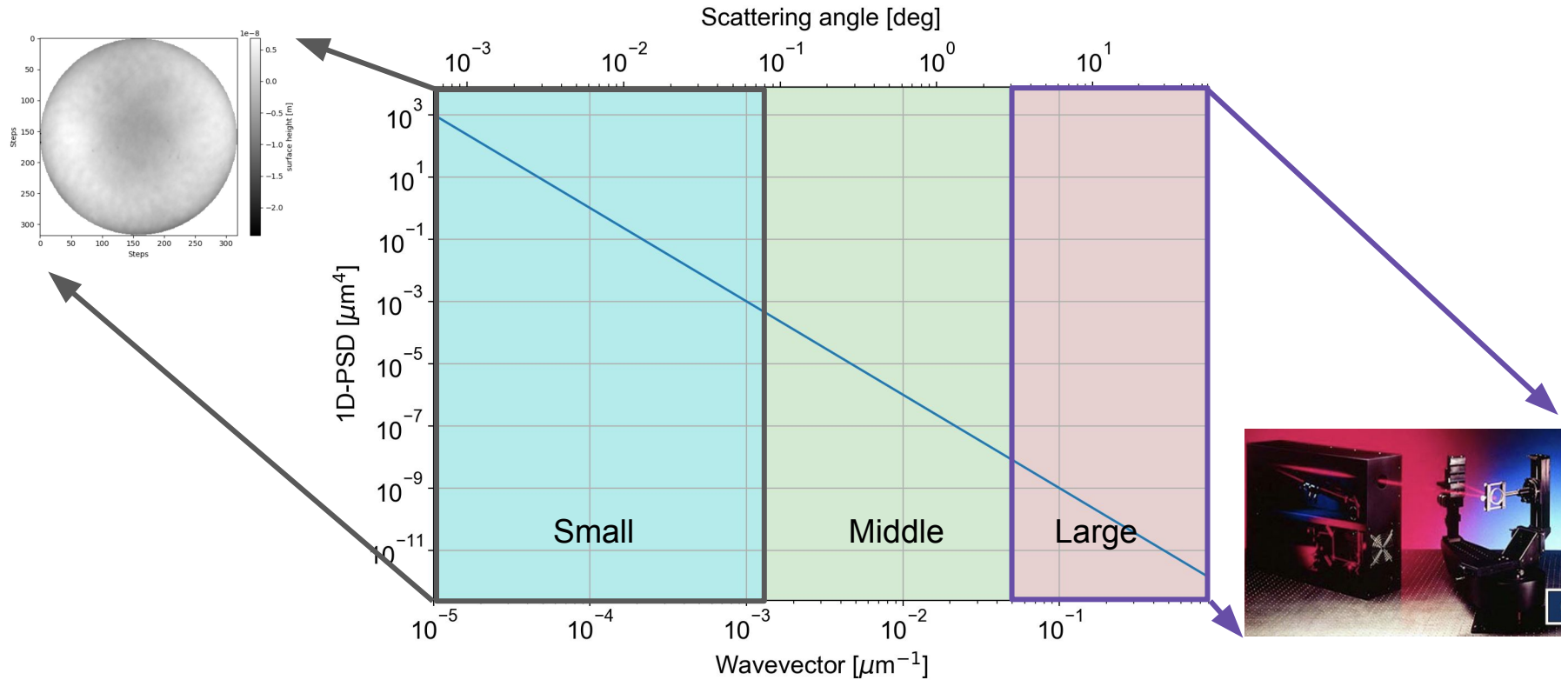


A scatterometer was used for measuring scattered light larger than 3 degree



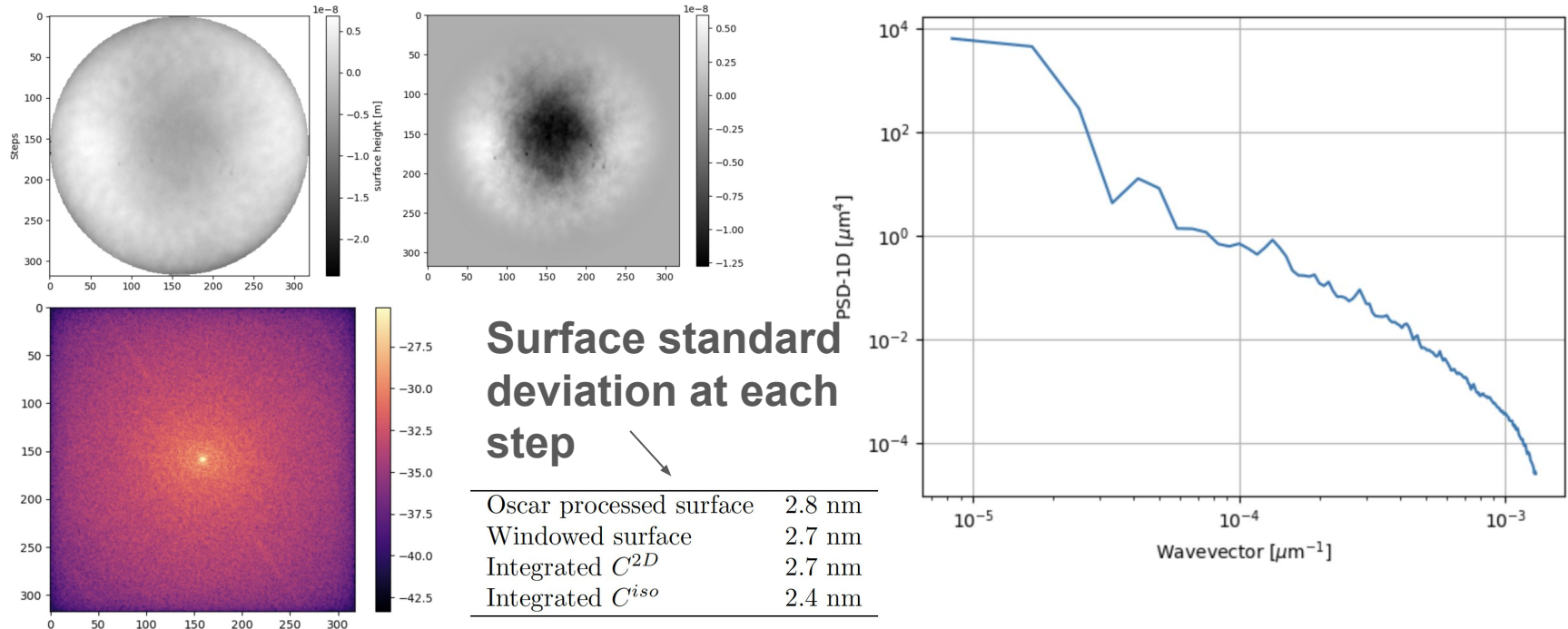
Remark: due to time limitation, angular resolved scattered was not measured for each pixel

Loss estimation from mirror characterization after fabrication



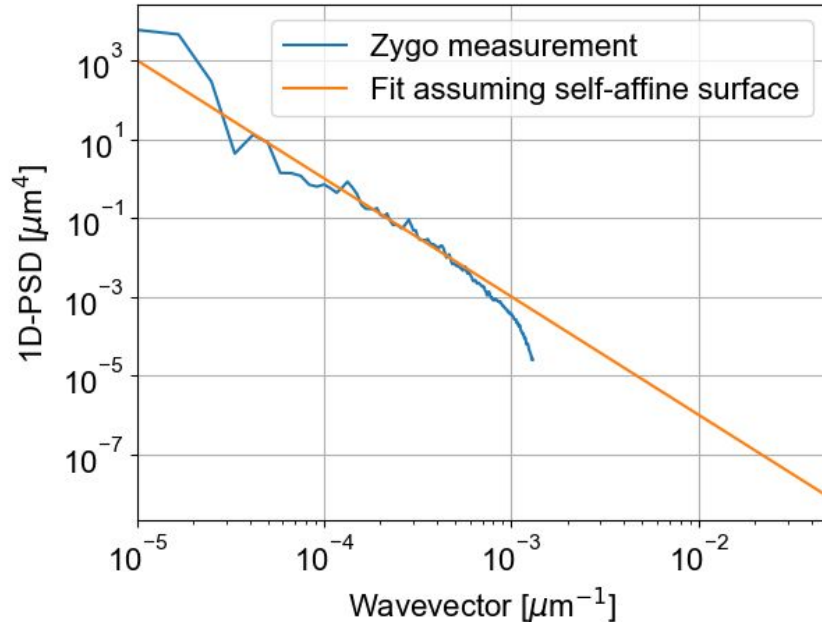
Acquire 1D-PSD

Remove offset/tilt/radius of curvature > apply window > get 2D PSD > get 1D PSD



Extend 1D PSD and estimate middle angle scattering

Assuming the mirror surface is self-affine, we made a fit of the 1D-PSD



Equation to integrate 1D-PSD

$$\sigma_{\text{middle}}^2 = 2\pi \int_{f_{\text{max-map}}}^{f_{\text{min-CASI}}} C^{\text{iso}}(f) f df$$

Equation to calculate scattering

$$TIS = \left(\frac{4\pi\sigma}{\lambda}\right)^2$$

0.7 ppm losses are estimated for middle angle scattering

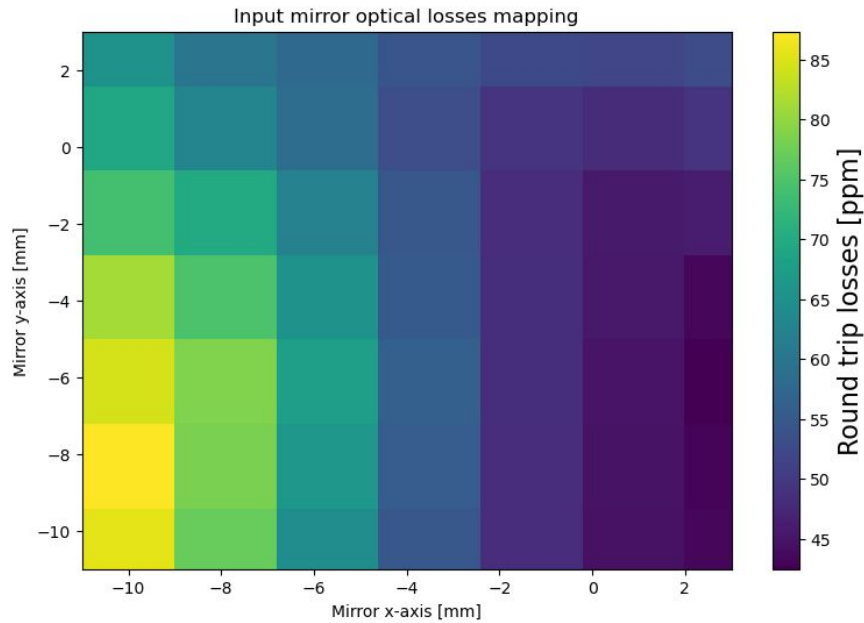


TABLE III. Estimated losses from mirrors characterization before cavity integration

Small angle scattering	10 ppm
Middle angle scattering	0.7 ppm
Large angle scattering	15-24 ppm
End mirror transmission	3.9 ppm
Absorption and clipping	< 1 ppm
Total	29.6-38.6 ppm

Summary

- Optical losses reduction is crucial for achieving the ambitious sensitivity goal of GW detectors
- Using Virgo filter cavity hardware, we have developed a methodology to characterize optical losses on cavity mirrors separately
- The optical losses varies from 42 to 87 ppm on the input mirror, but 53 to 61 ppm on the end mirror
- The lowest measured losses are comparable with what expected from mirror characterization before filter cavity integration, and **representing smallest optical losses for 300 meter scale filter cavity**
- This work has been summarized in a paper (VIR-0372A-24) which is going to be submitted to a journal

Next step

- The input mirror losses inhomogeneity may come from contamination -> potential cleaning could be scheduled in the near future
- Middle angle scattering could be larger than our estimation from the surface roughness due to point defects (need to consider it more carefully)
- The optical losses could be measured also for 532nm, such measurement would be interesting for understanding scattered light as a function of wavelength
- Other methods of measuring optical losses were used in this work but not reported since we have some unknown systematic errors, a future instrument upgrade would solve this issue
- The large angle scattering measurement with each pixel angularly resolved would provide more precise estimation