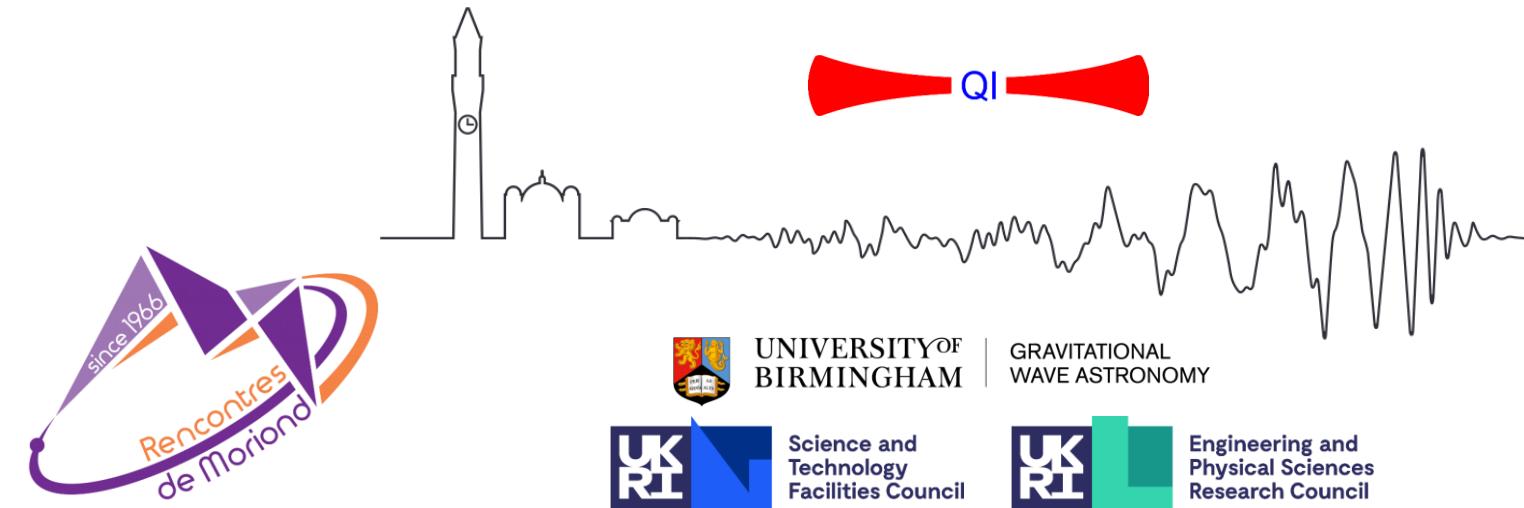


LIDA:

First results and future prospects

Joscha Heinze (speaker),

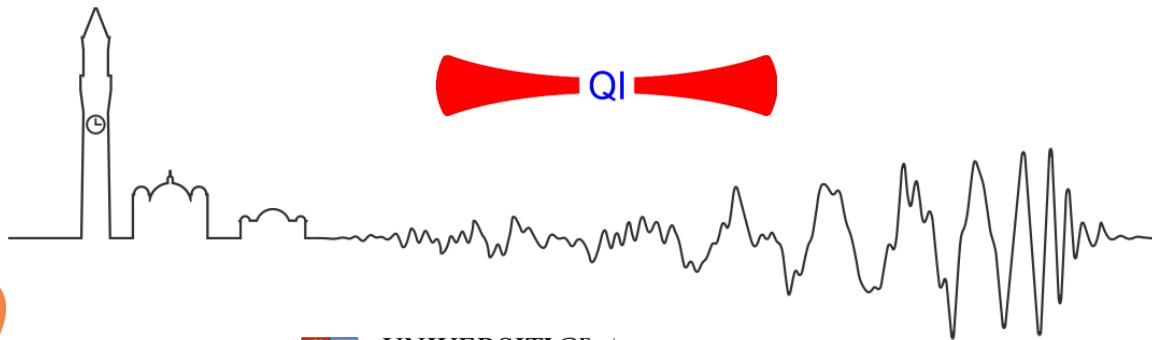
Artemiy Dmitriev, Alex Gill, Jiri Smetana, Tiangliang Yan, Vincent Boyer, and Denis Martynov



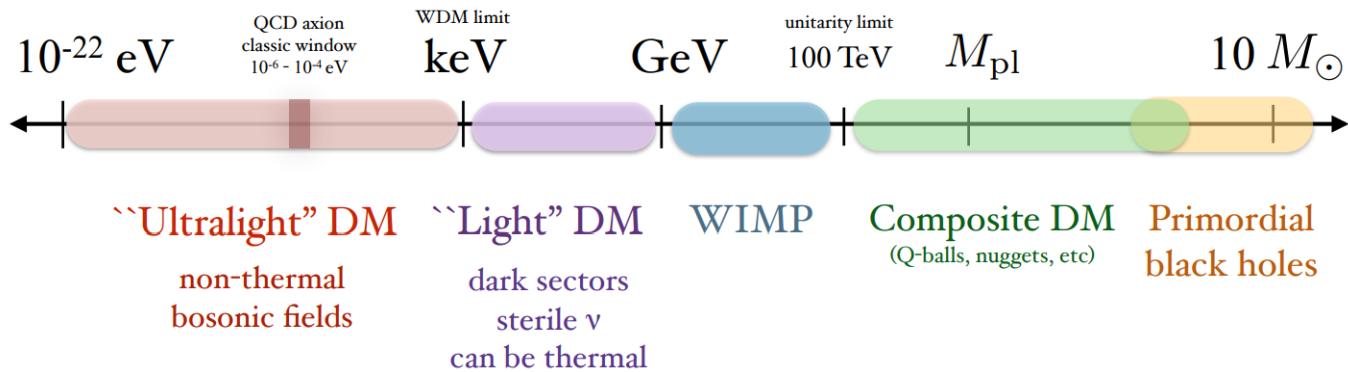
Laser-Interferometric Detector for Axions: First results and future prospects

Joscha Heinze (speaker),

Artemiy Dmitriev, Alex Gill, Jiri Smetana, Tiangliang Yan, Vincent Boyer, and Denis Martynov



Mass range



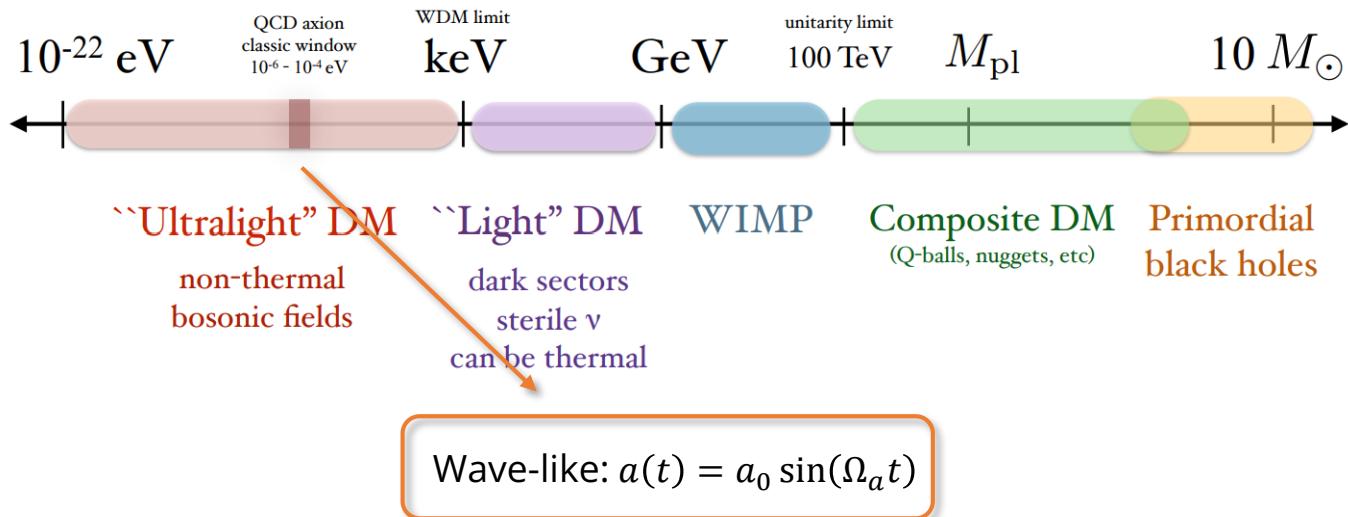
T. Lin, arXiv:1904.07915 (2019)



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Mass range



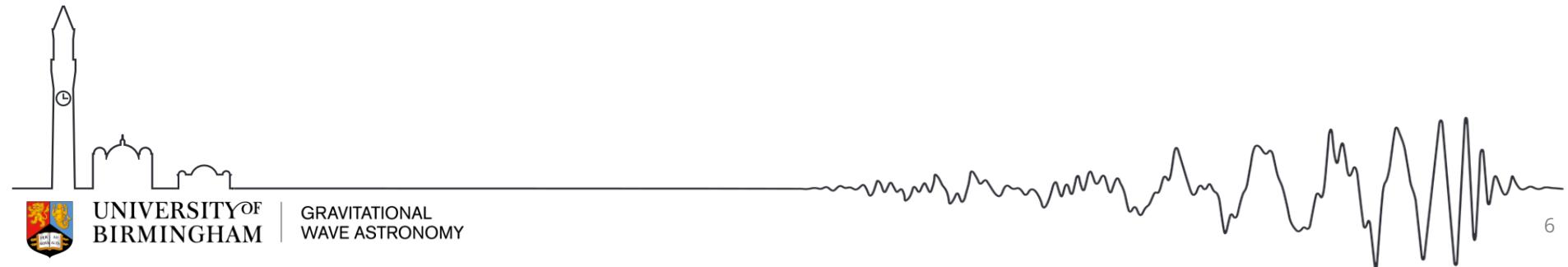
T. Lin, arXiv:1904.07915 (2019)



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Operating principle

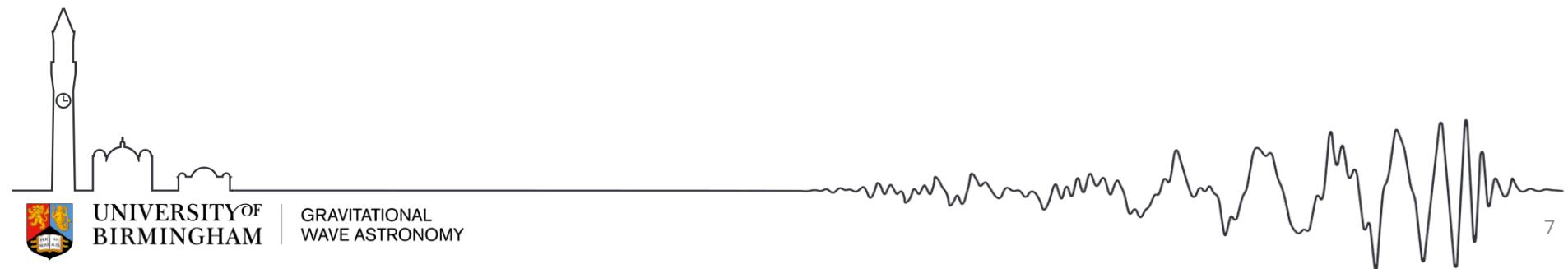


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Operating principle

- Directly detect axions and axion-like particles ($10^{-16} - 10^{-8}$ eV).



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Operating principle

- Directly detect axions and axion-like particles ($10^{-16} - 10^{-8}$ eV).
- Use coupling of **axions to photons**:

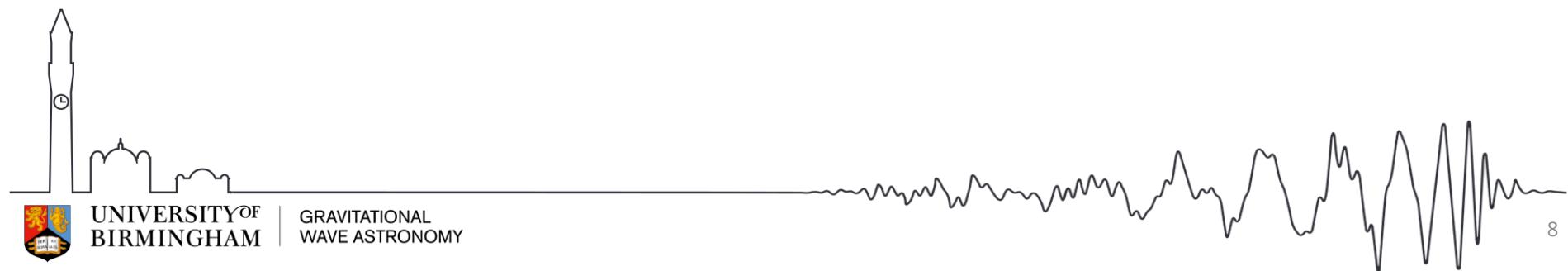
$$\mathcal{L} = \frac{g_{a\gamma}}{4} a F_{\mu\nu} \tilde{F}^{\mu\nu}$$

Lagrangian \mathcal{L}

a : axion field

$g_{a\gamma}$: coupling coefficient

F : electromagnetic field-strength tensor



Operating principle

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$$\mathcal{L} = \frac{g_{a\gamma}}{4} a F_{\mu\nu} \tilde{F}^{\mu\nu} \quad \Rightarrow \quad \frac{\partial^2 \mathbf{E}}{\partial t^2} - \nabla^2 \mathbf{E} = g_{a\gamma} \dot{a} (\nabla \times \mathbf{E})$$

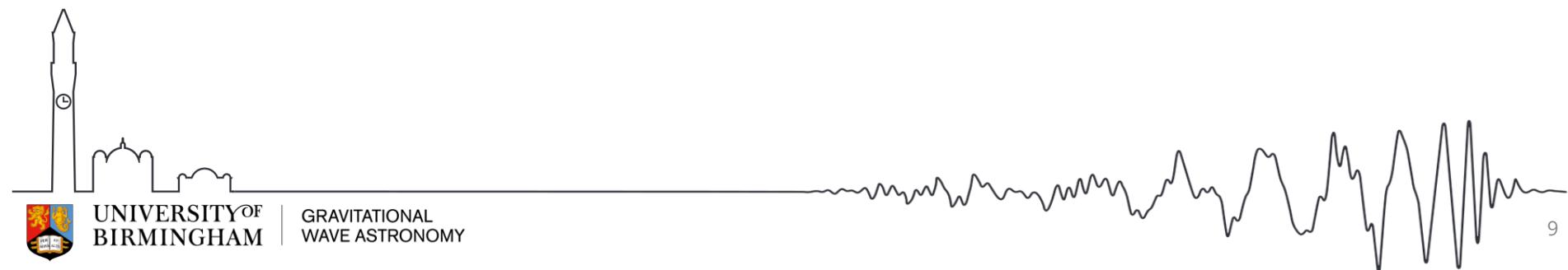
Lagrangian \mathcal{L}

a : axion field

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wave equation for electric field \mathbf{E}



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 a : axion field

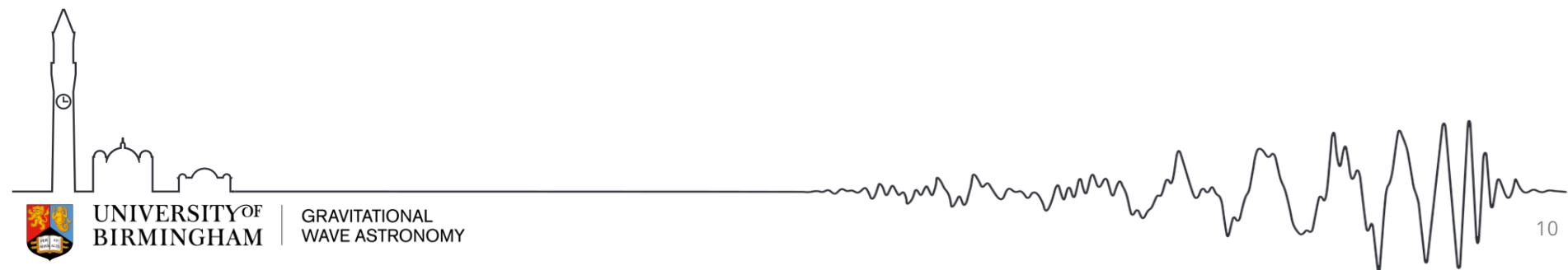
$g_{a\gamma}$: coupling coefficient
 F : electromagnetic field-strength tensor

$$\frac{\partial^2 \mathbf{E}}{\partial t^2} - \nabla^2 \mathbf{E} = g_{a\gamma} \dot{a} (\nabla \times \mathbf{E})$$

wave equation for electric field \mathbf{E}

$$\Delta\phi = g_{a\gamma} [a(t) - a(t - \tau)]$$

phase difference $\Delta\phi$ between left- and right-handed circular polarisation



Operating principle

- Directly detect axions and axion-like particles ($10^{-16} - 10^{-8}$ eV).
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Lagrangian \mathcal{L}
 a : axion field

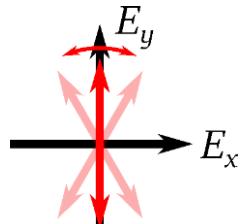
$g_{a\gamma}$: coupling coefficient
 F : electromagnetic field-strength tensor

$$\frac{\partial^2 \mathbf{E}}{\partial t^2} - \nabla^2 \mathbf{E} = g_{a\gamma} \dot{a} (\nabla \times \mathbf{E})$$

wave equation for electric field \mathbf{E}

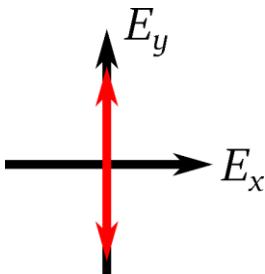
$$\Delta\phi = g_{a\gamma} [a(t) - a(t - \tau)]$$

phase difference $\Delta\phi$ between left- and right-handed circular polarisation

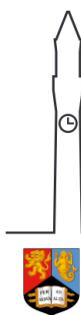


Observable effect:
 Rotation of linear polarization!

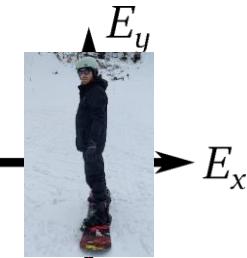
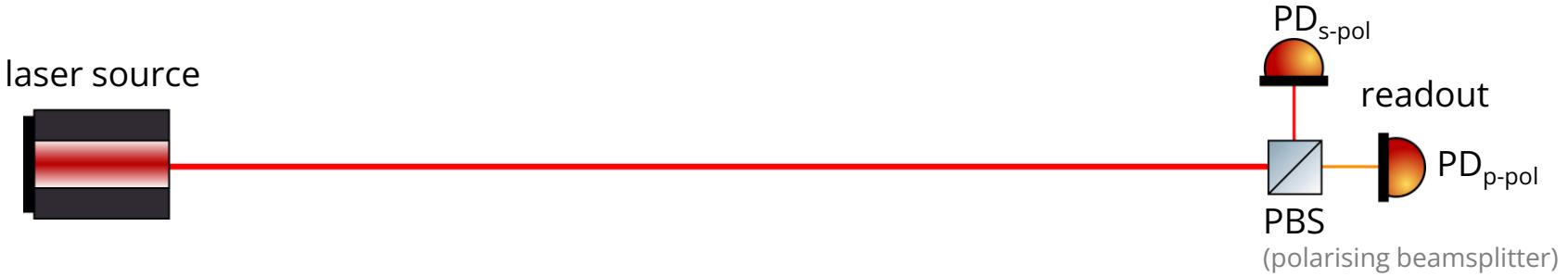
Signal generation



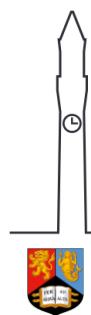
Input: linear s-polarisation.



Signal generation



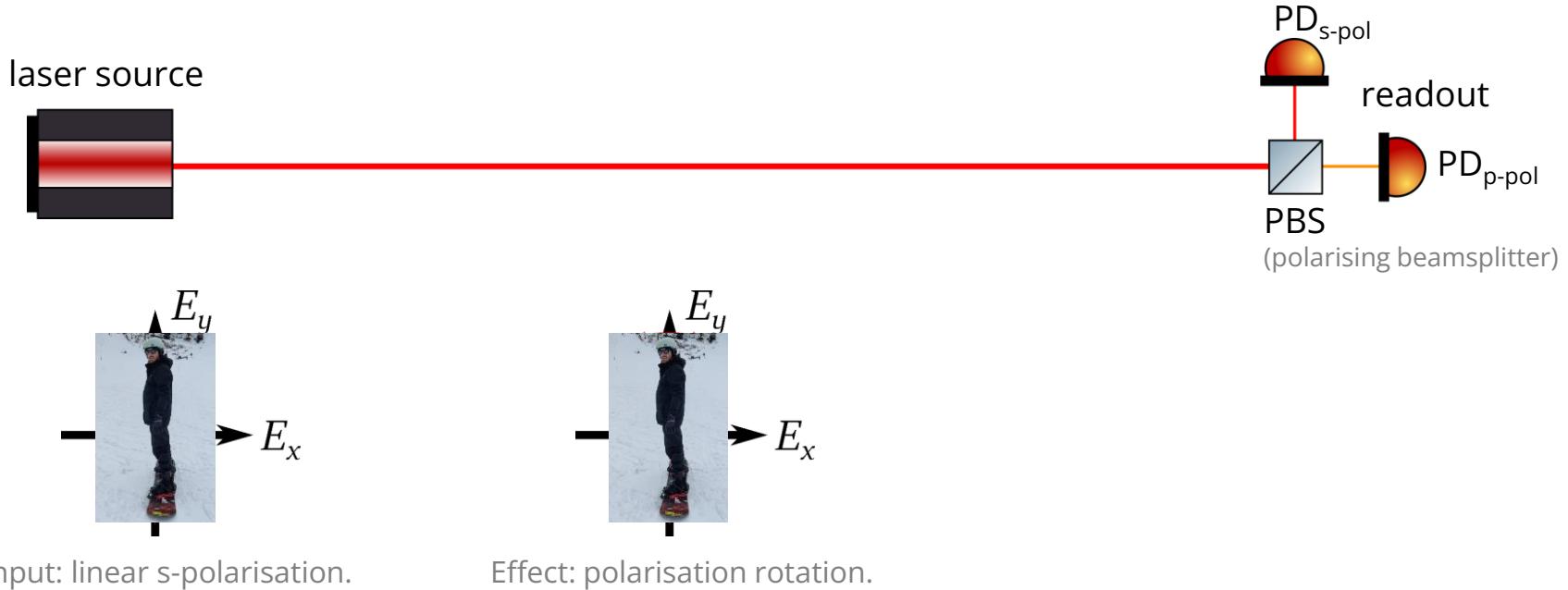
Input: linear s-polarisation.



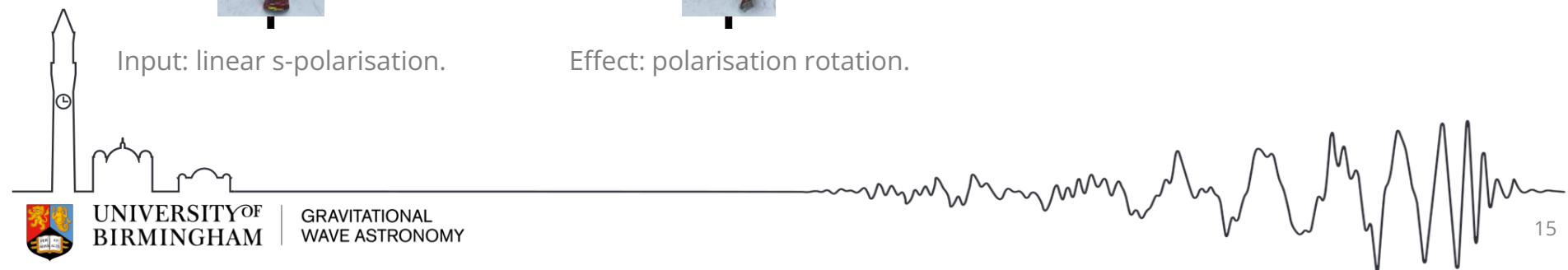
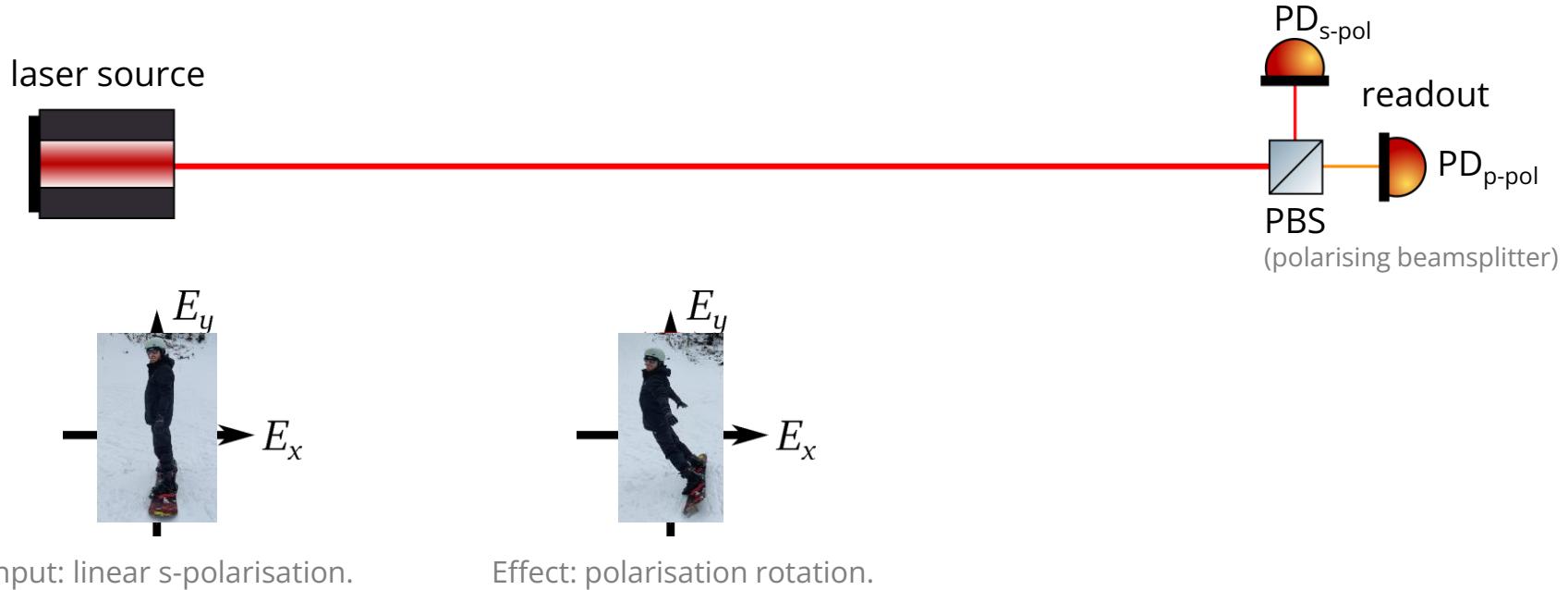
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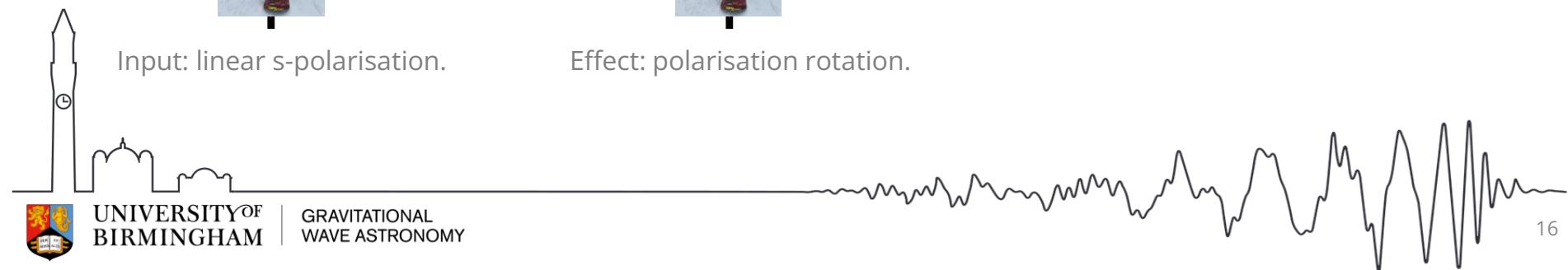
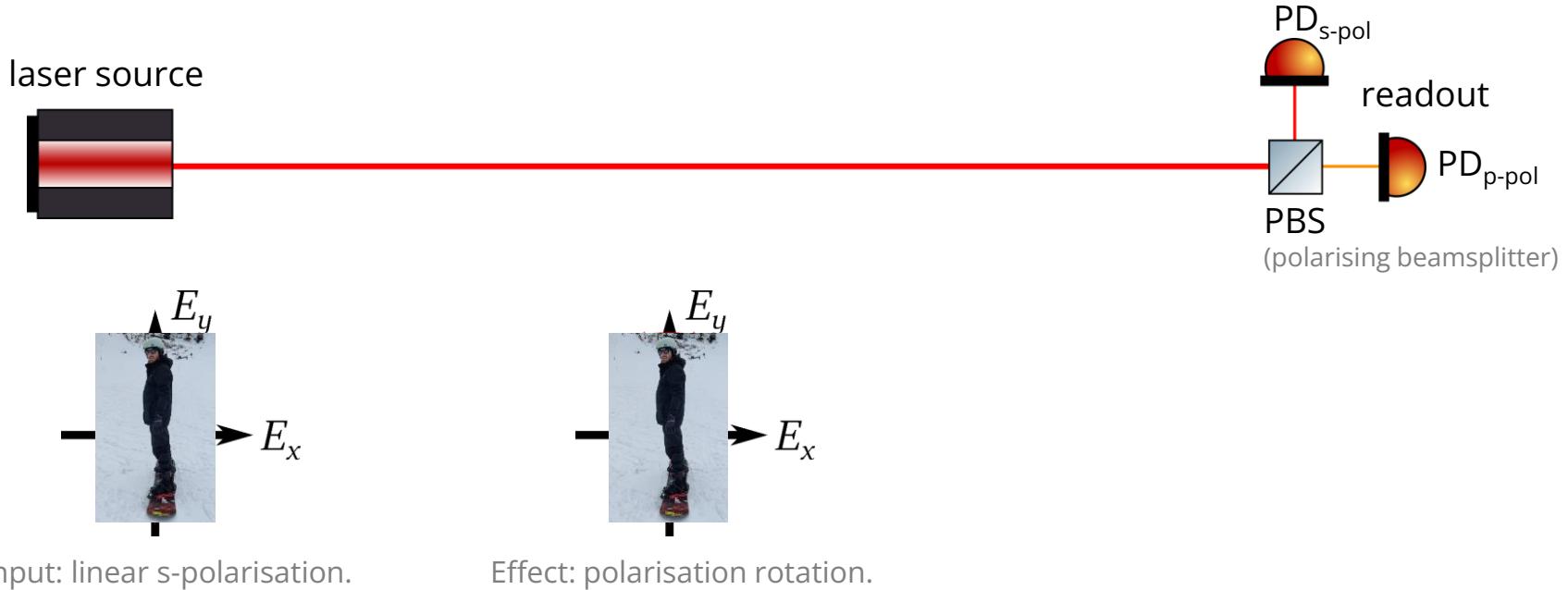
Signal generation



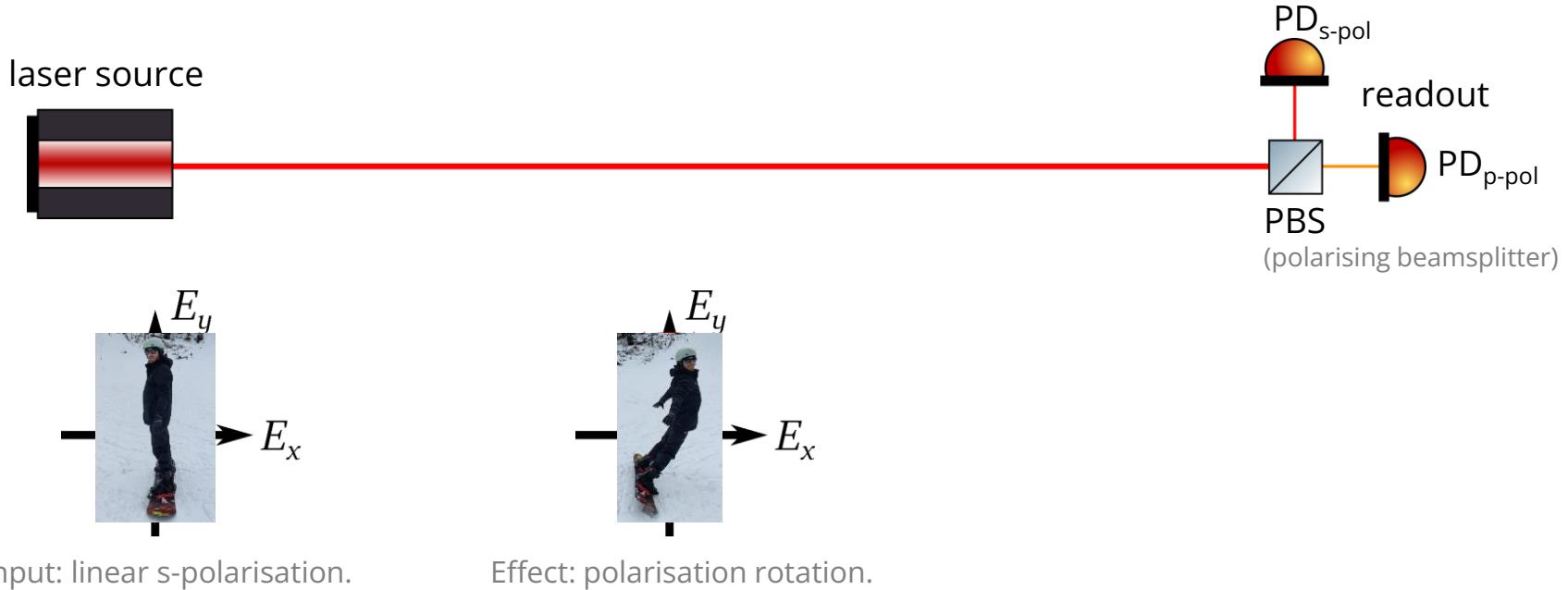
Signal generation



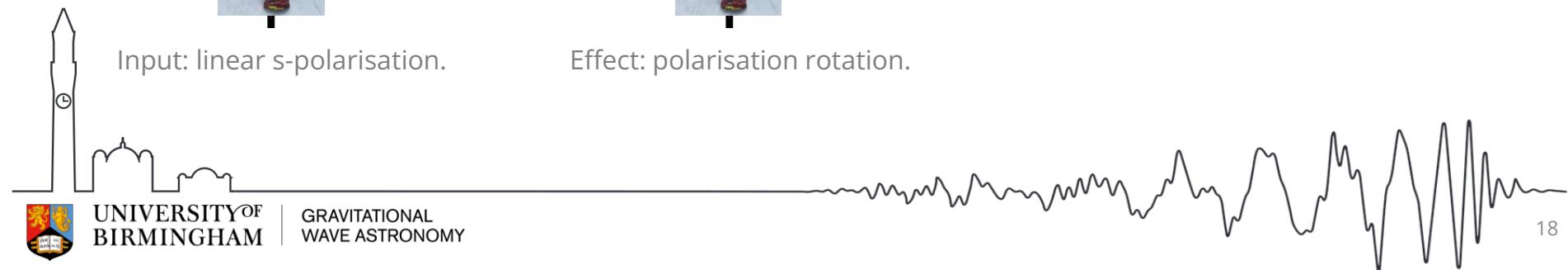
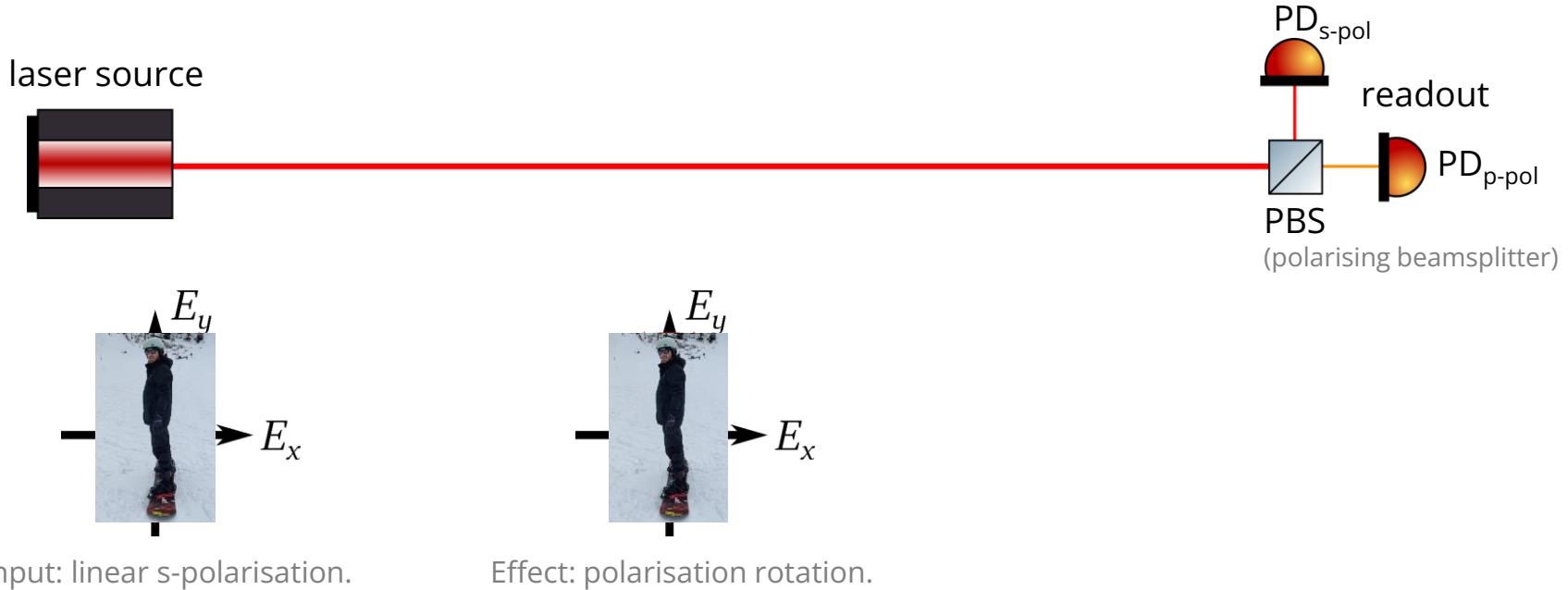
Signal generation



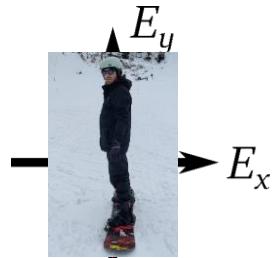
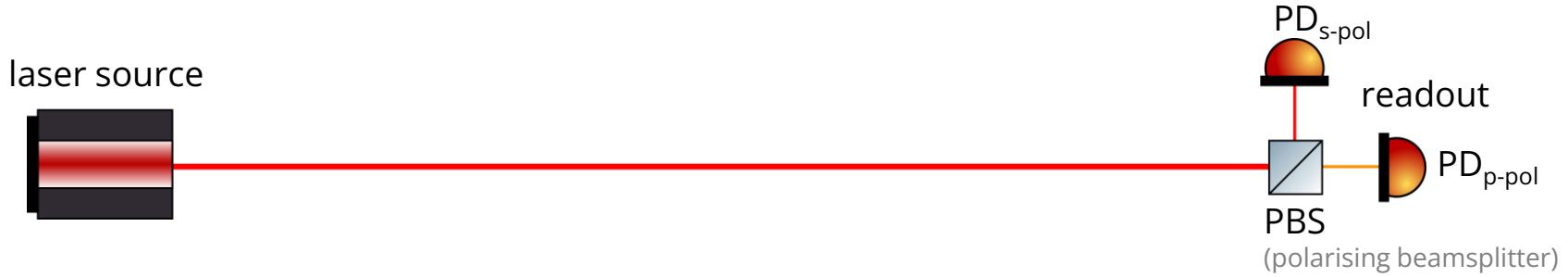
Signal generation



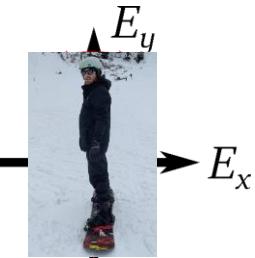
Signal generation



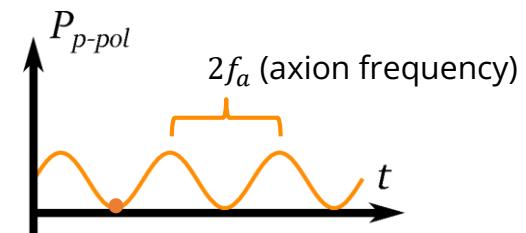
Signal generation



Input: linear s-polarisation.

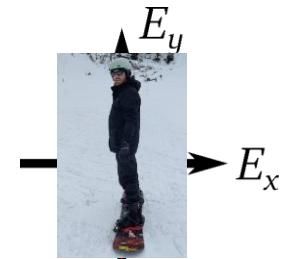


Effect: polarisation rotation.

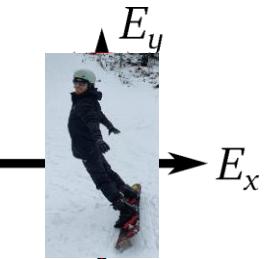


Output: signal in p-polarisation.

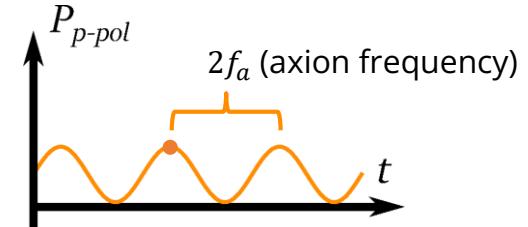
Signal generation



Input: linear s-polarisation.



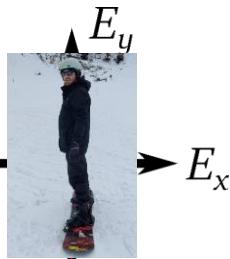
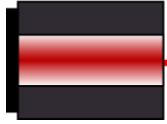
Effect: polarisation rotation.



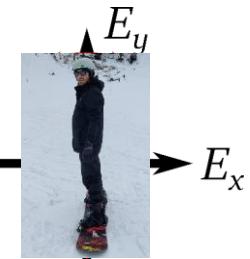
Output: signal in p-polarisation.

Signal generation

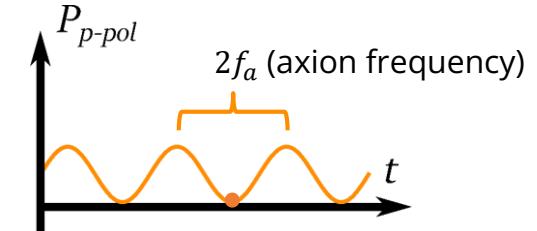
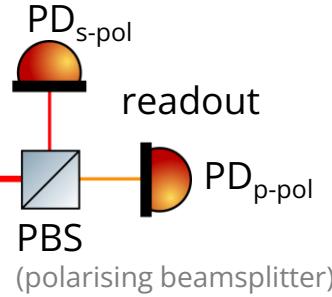
laser source



Input: linear s-polarisation.

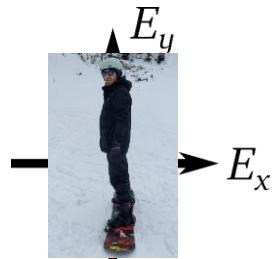


Effect: polarisation rotation.

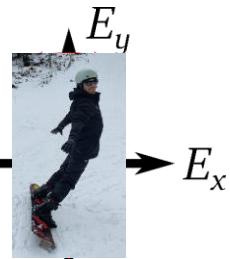


Output: signal in p-polarisation.

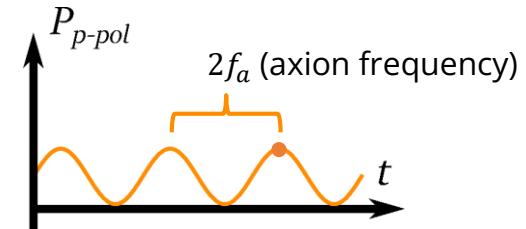
Signal generation



Input: linear s-polarisation.



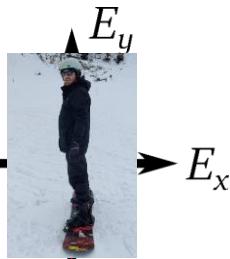
Effect: polarisation rotation.



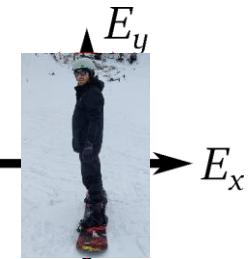
Output: signal in p-polarisation.

Signal generation

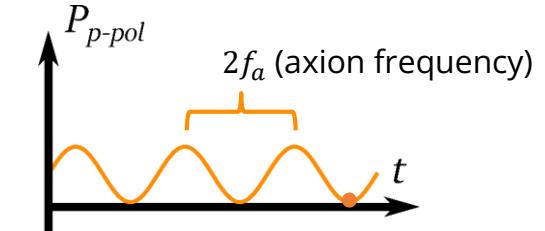
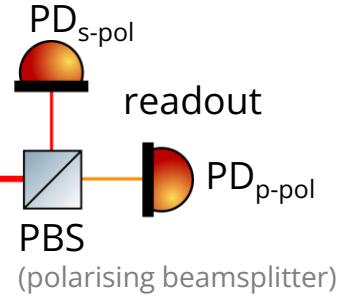
laser source



Input: linear s-polarisation.

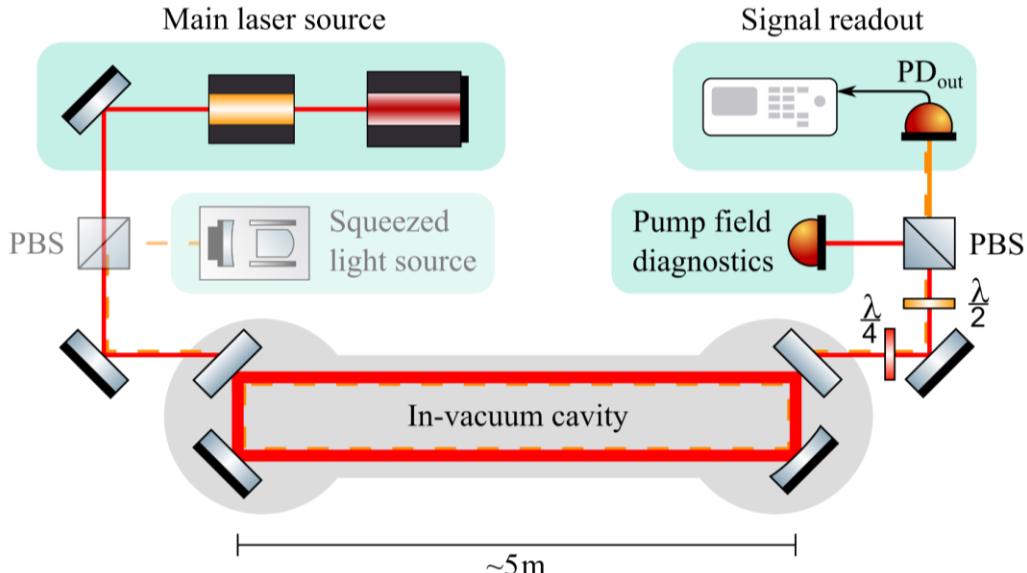


Effect: polarisation rotation.



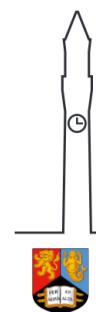
Output: signal in p-polarisation.

Detector design

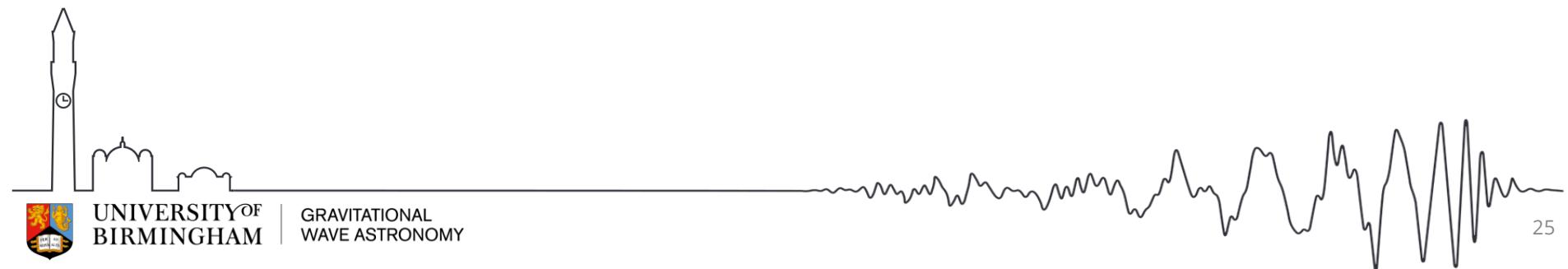


Tabletop demonstration:

- **200 kW** intra-cavity power to enhance signal
- **5 m** baseline to increase interaction time
- vacuum system
- **6 months** integration time for larger signal-to-noise ratio
- **squeezed light** to reduce quantum noise by up to 10 dB



Status and first results

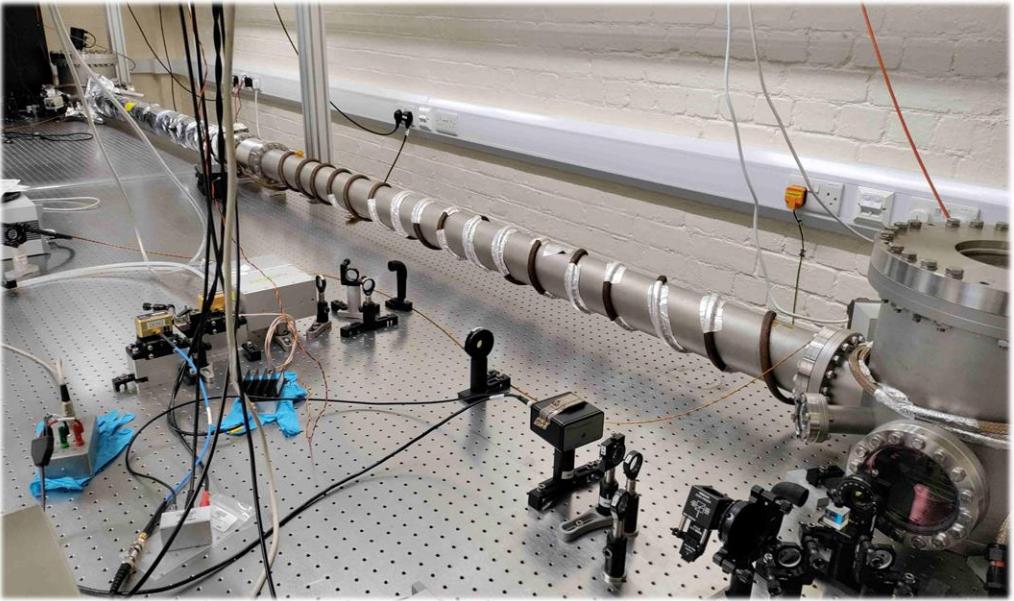


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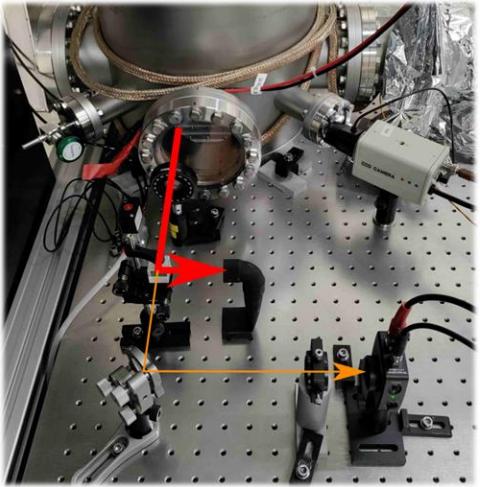
LIDA in the lab

✓ 5 m long vacuum system!

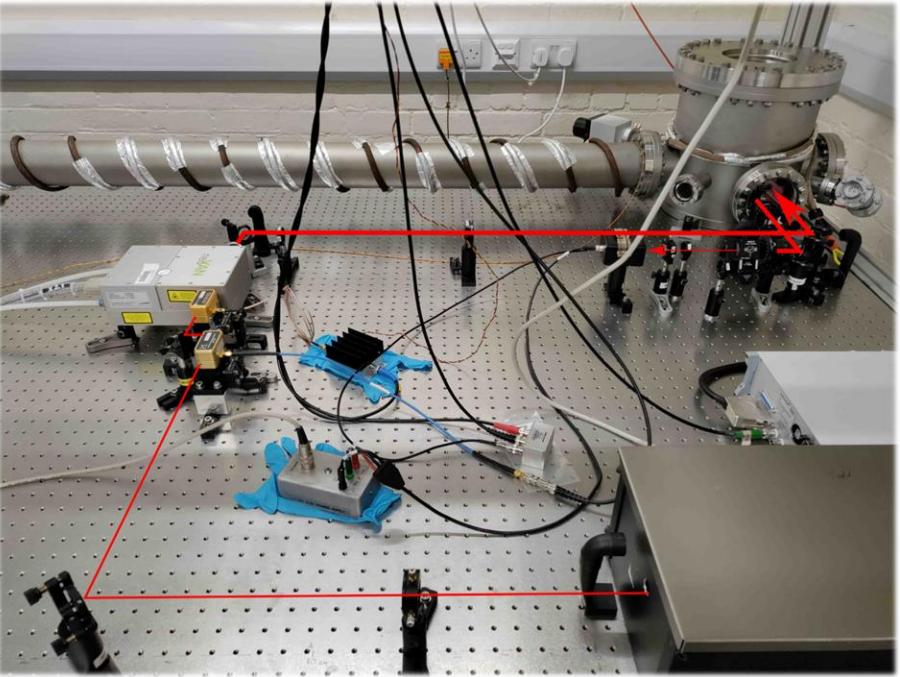


LIDA in the lab

- ✓ 5 m long vacuum system!
- ✓ Input and readout setup!



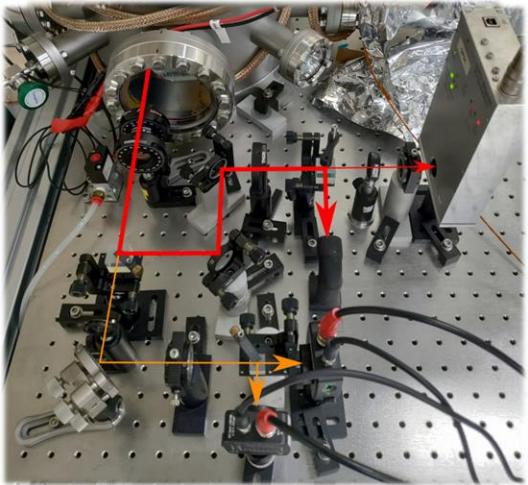
Readout



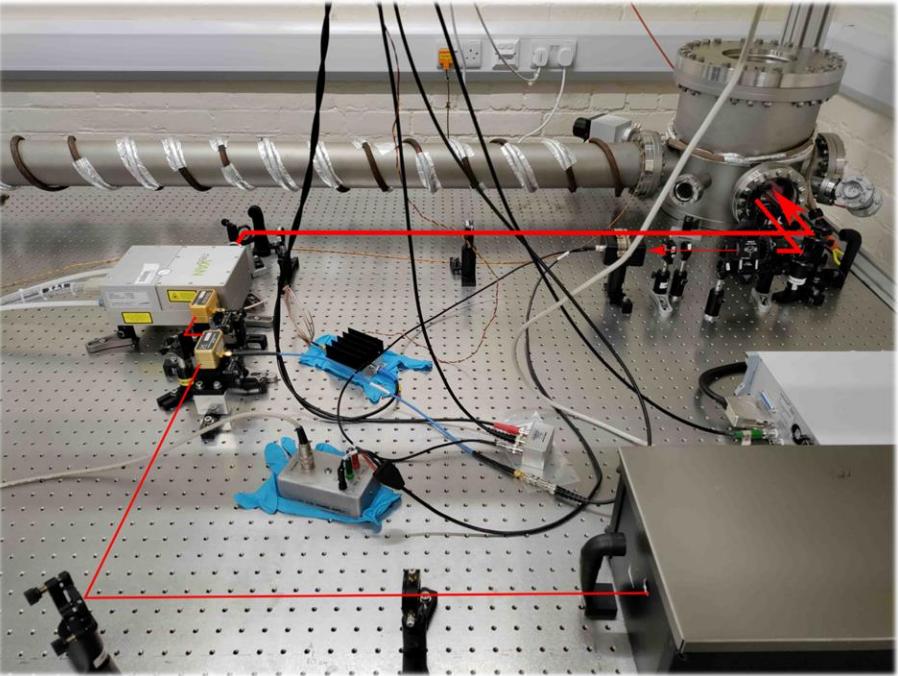
Input

LIDA in the lab

- ✓ 5 m long vacuum system!
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Readout



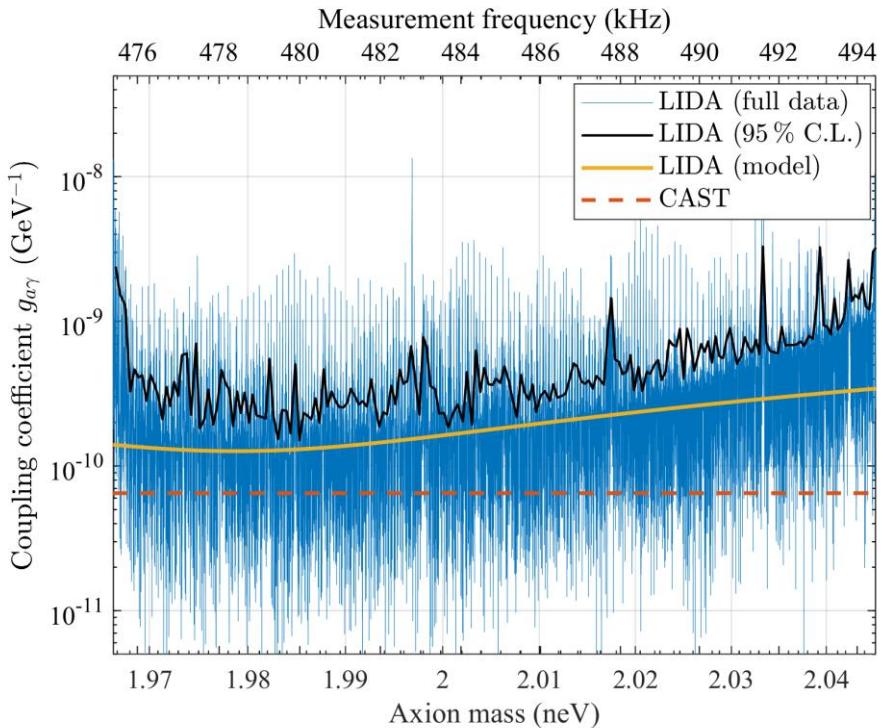
Input



1st science run

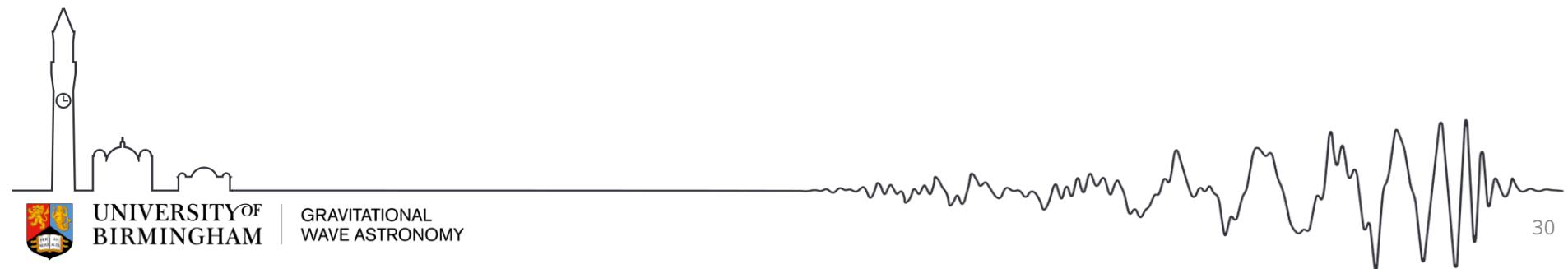
	First run
Input pump power	12 W
Intra-cavity power	118 kW
Measurement time	85 h
Squeezing level	—
Detuning	478 kHz

Peak sensitivity: $1.51 \times 10^{-10} \text{ GeV}^{-1}$
 Avg sensitivity: $3.2 \times 10^{-10} \text{ GeV}^{-1}$



Published: J Heinze, et. al., arXiv:2307.01365 (Accepted by PRL)

Prospects for LIDA

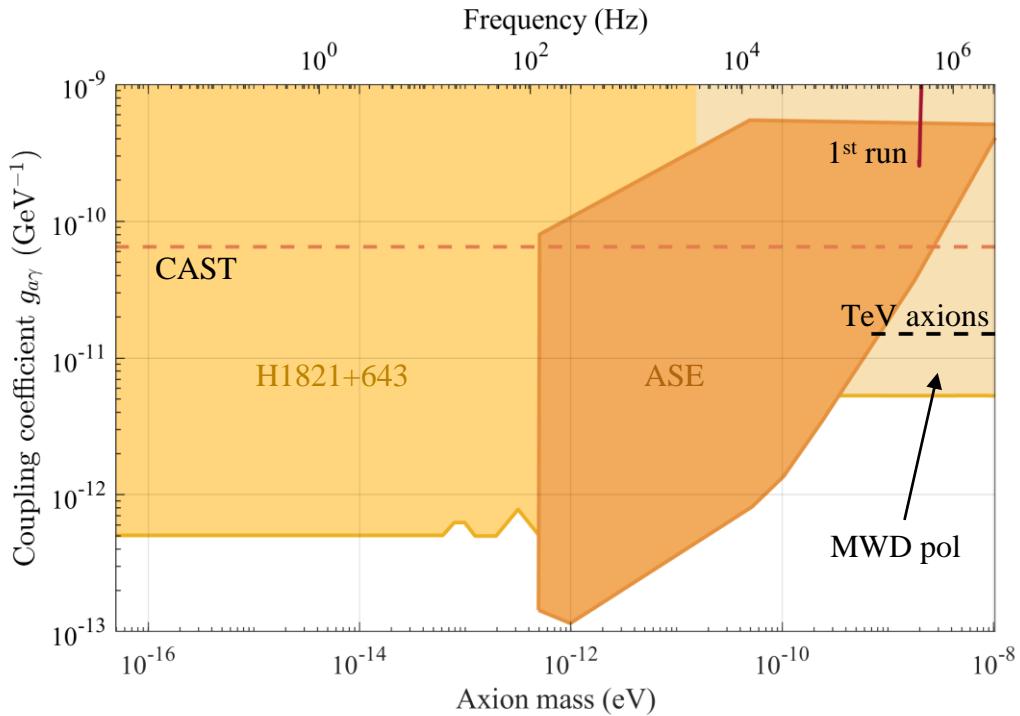


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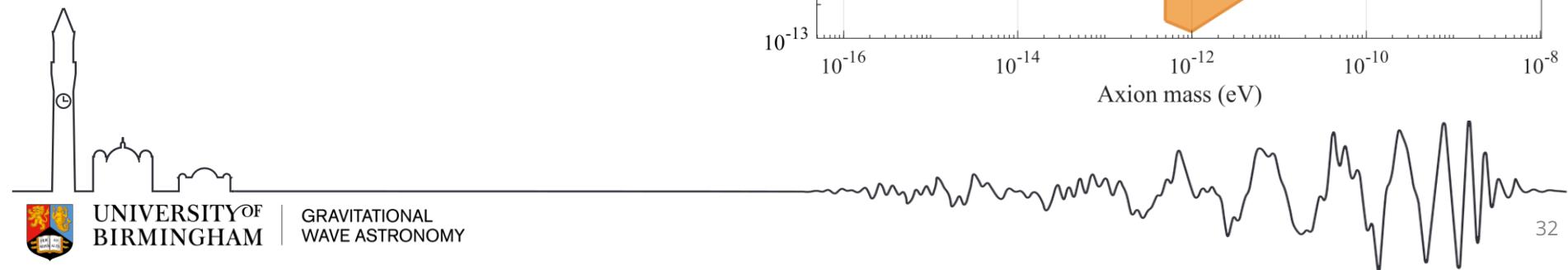
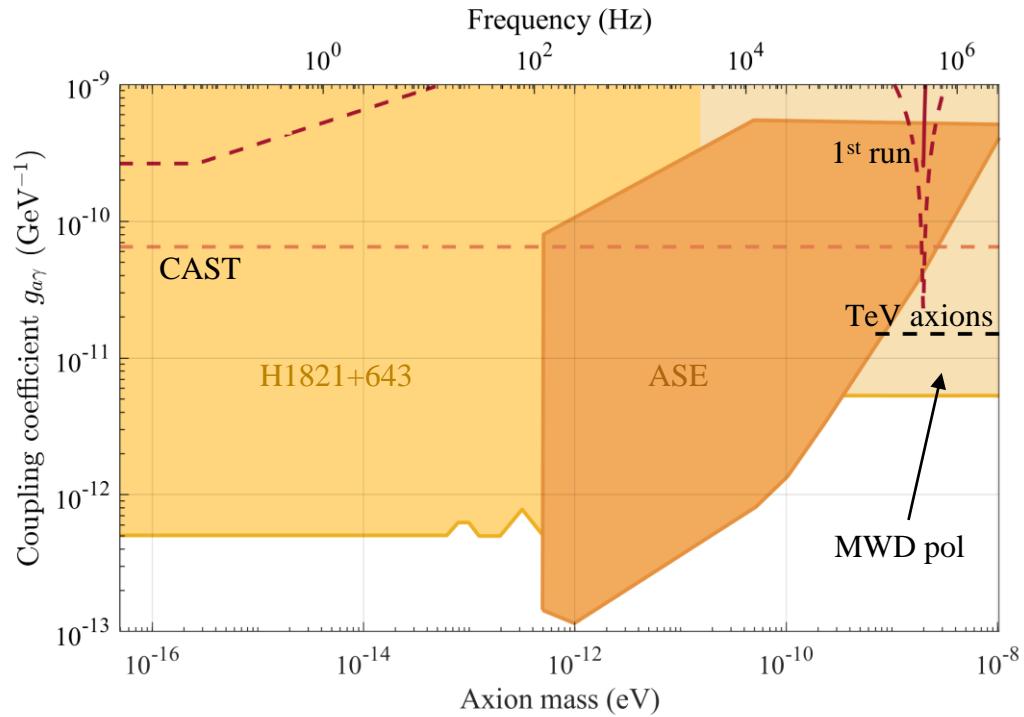
Prospects for LIDA

	First run	Next run
Intra-cavity power (kW)	118	?
Measurement time	85 h	?
Squeezing level (dB)	—	?
Detuning	478 kHz	?



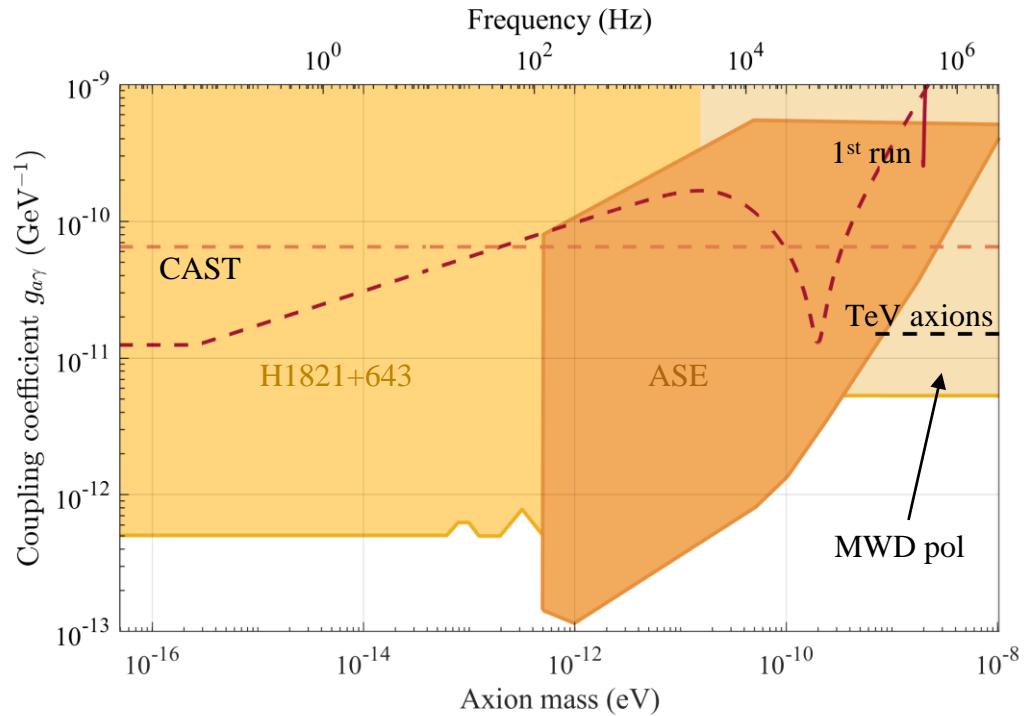
Prospects for LIDA

	First run	Next run
Intra-cavity power (kW)	118	200
Measurement time	85 h	6 months
Squeezing level (dB)	—	10 dB
Detuning	478 kHz	478 kHz



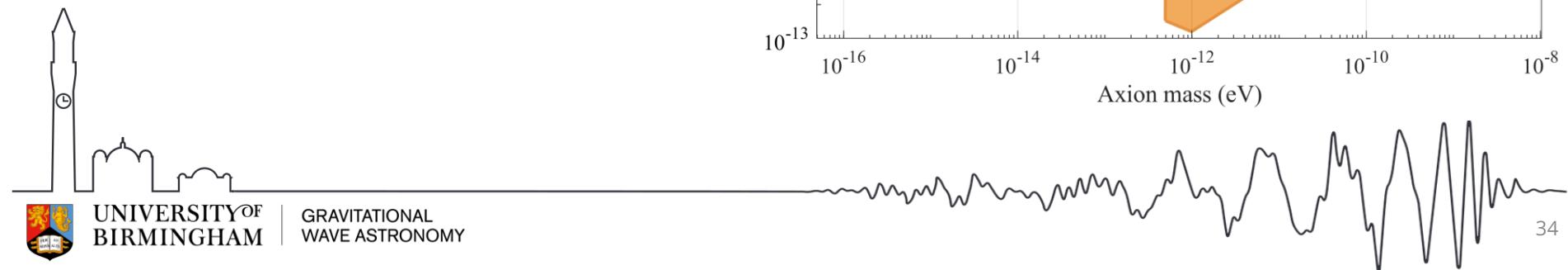
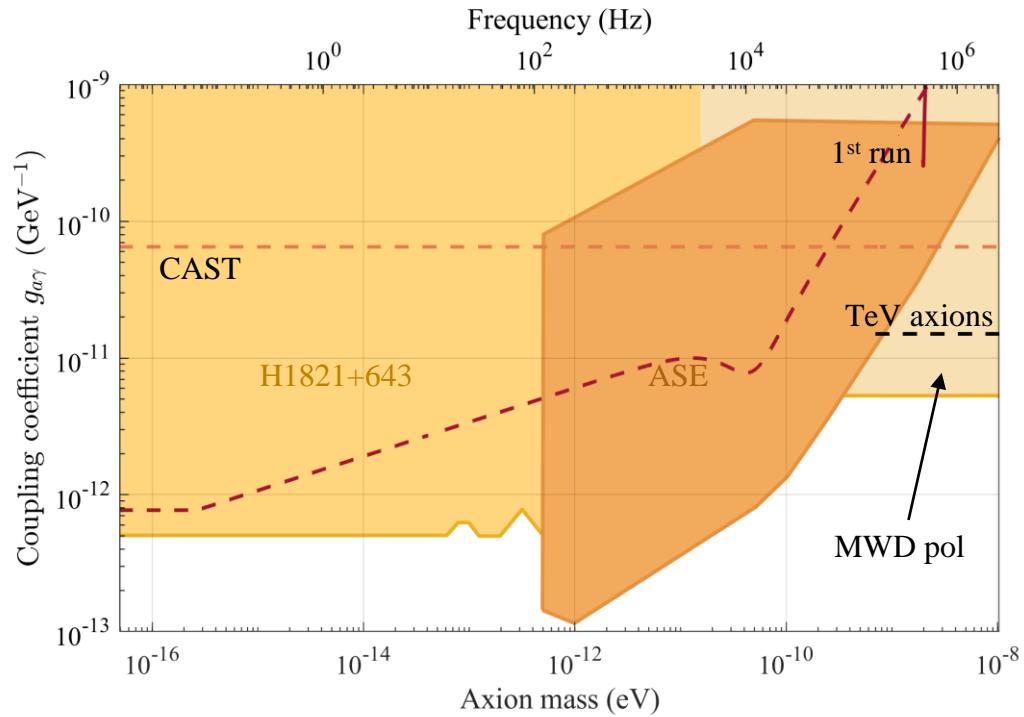
Prospects for LIDA

	First run	Next run
Intra-cavity power (kW)	118	200
Measurement time	85 h	6 months
Squeezing level (dB)	—	10 dB
Detuning	478 kHz	48 kHz



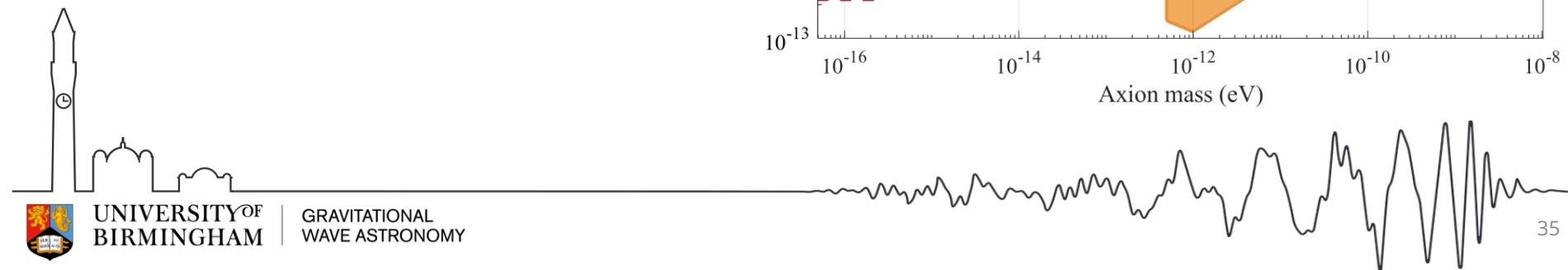
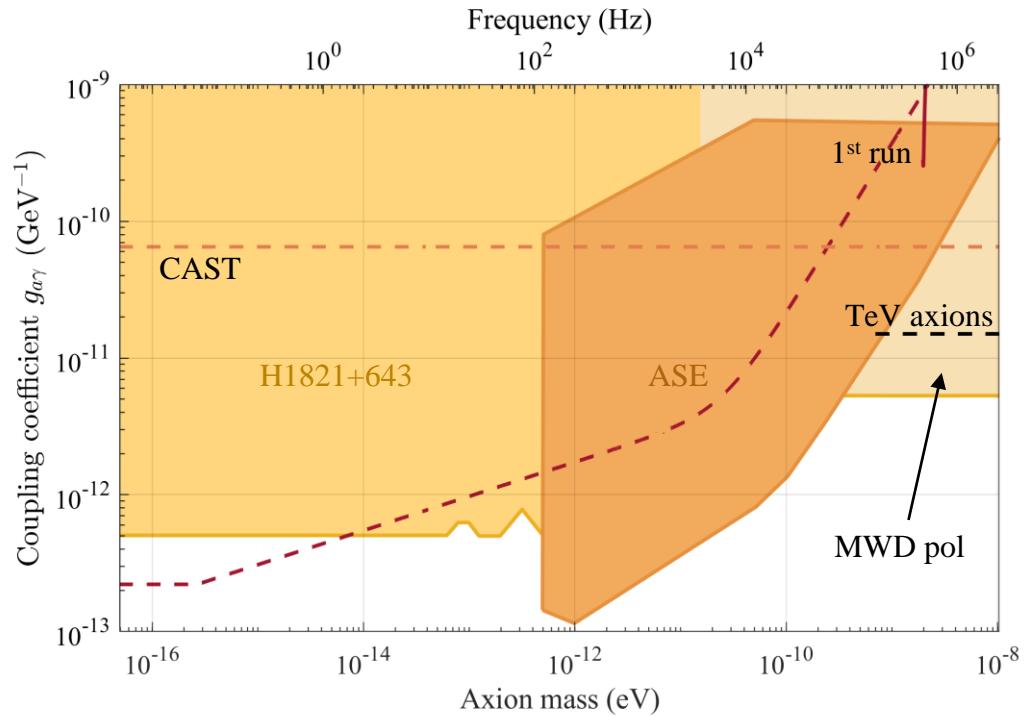
Prospects for LIDA

	First run	Next run
Intra-cavity power (kW)	118	200
Measurement time	85 h	6 months
Squeezing level (dB)	—	10 dB
Detuning	478 kHz	10 kHz



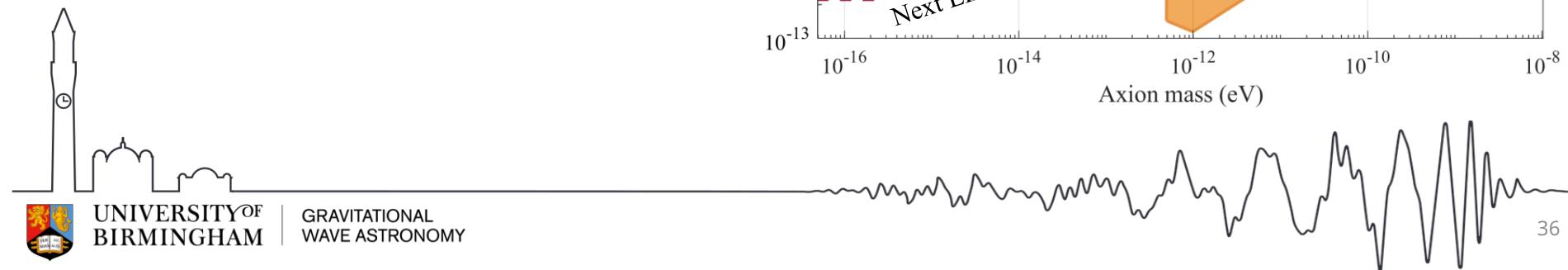
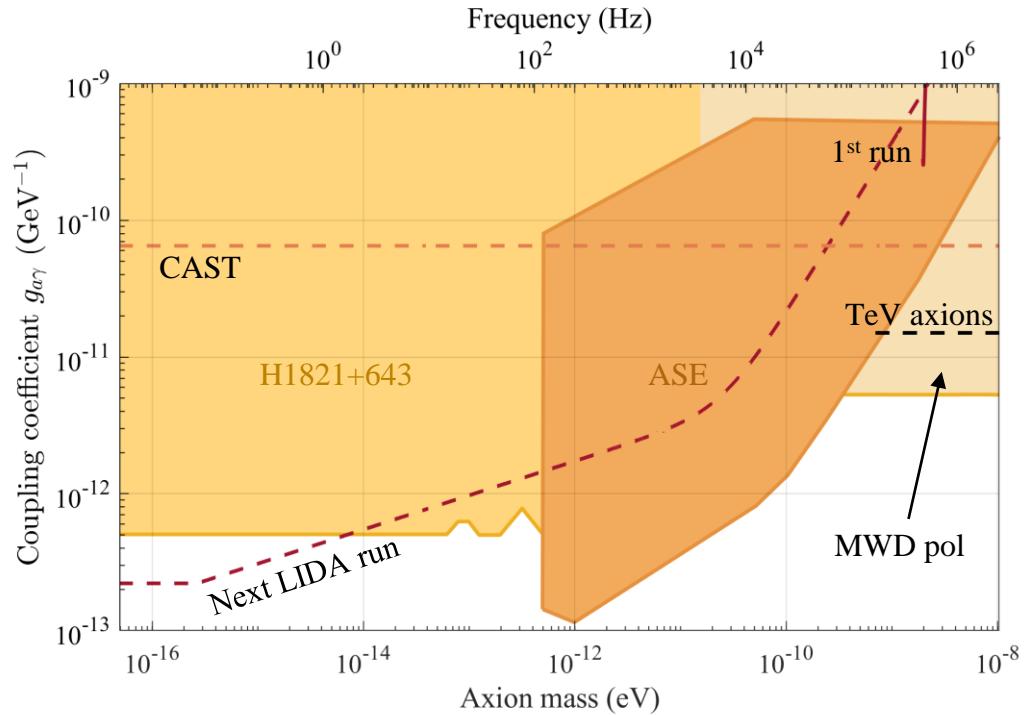
Prospects for LIDA

	First run	Next run
Intra-cavity power (kW)	118	200
Measurement time	85 h	6 months
Squeezing level (dB)	—	10 dB
Detuning	478 kHz	0 kHz

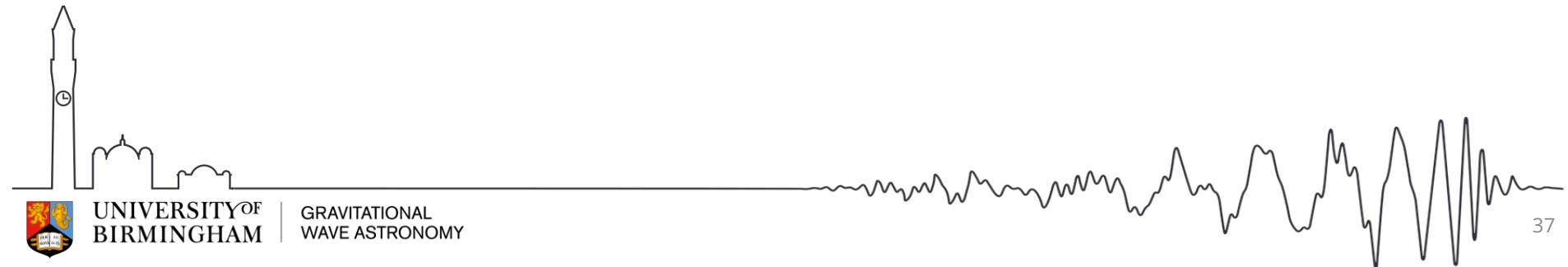


Prospects for LIDA

	First run	Next run
Intra-cavity power (kW)	118	200
Measurement time	85 h	6 months
Squeezing level (dB)	—	10 dB
Detuning	478 kHz	0 kHz



Proposal for GEO600



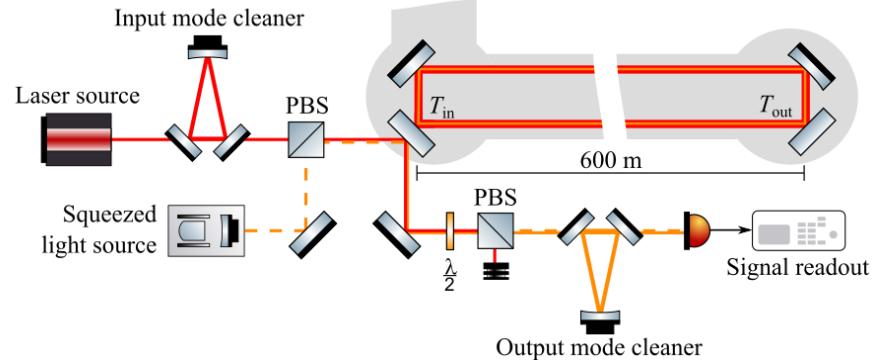
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GEO600 → DarkGEO



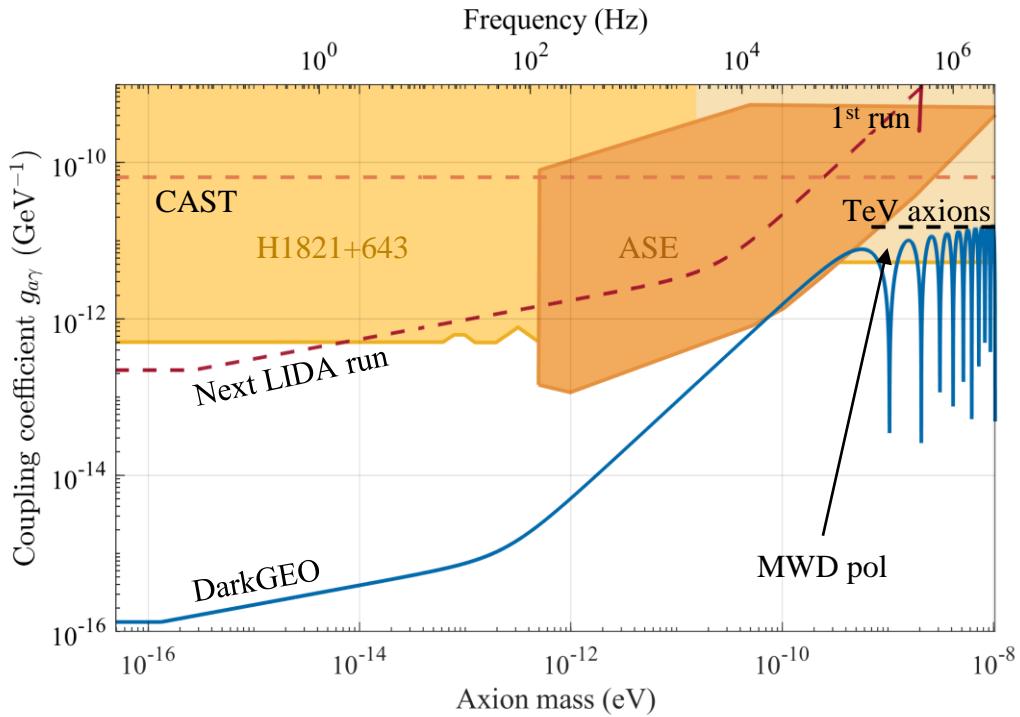
GEO600: close to Hanover, Germany (credit: geo600.org)



Published: J Heinze, et. al., arXiv:2401.11907 (2024)

DarkGEO prospects

	First LIDA	Next LIDA	DarkGEO
Power (kW)	118	200	10,000
Meas time	85 h	6 months	1 year
Squeezing (dB)	—	10 dB	10 dB
Detuning	478 kHz	0 kHz	0 kHz

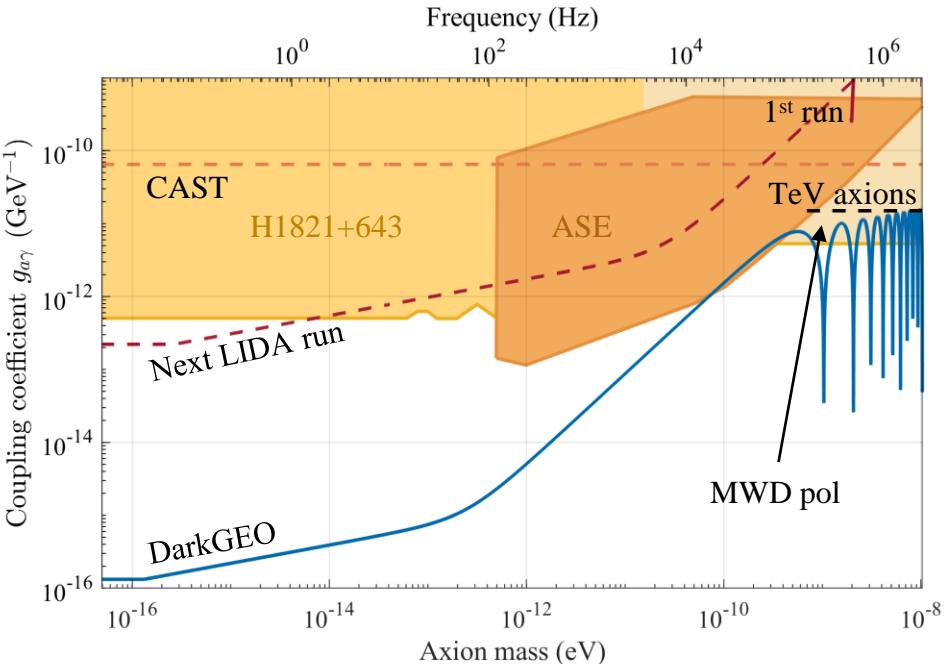


Published: J Heinze, et. al., arXiv:2401.11907 (2024)

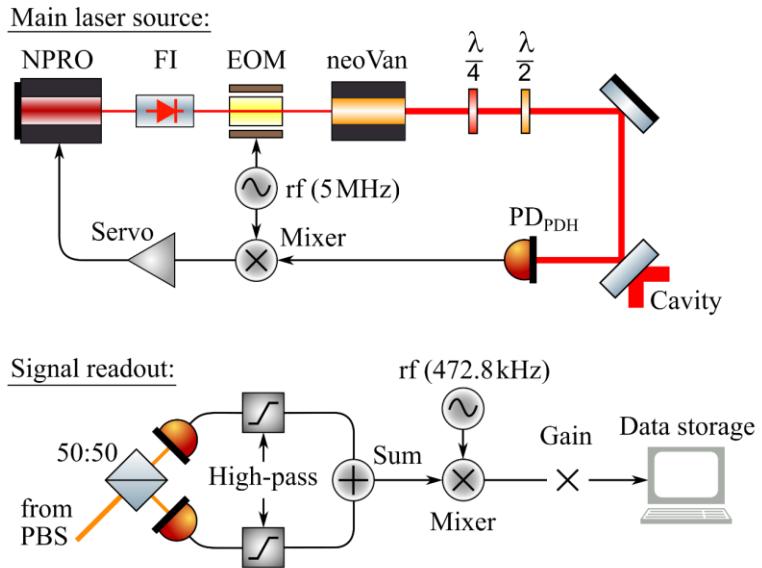
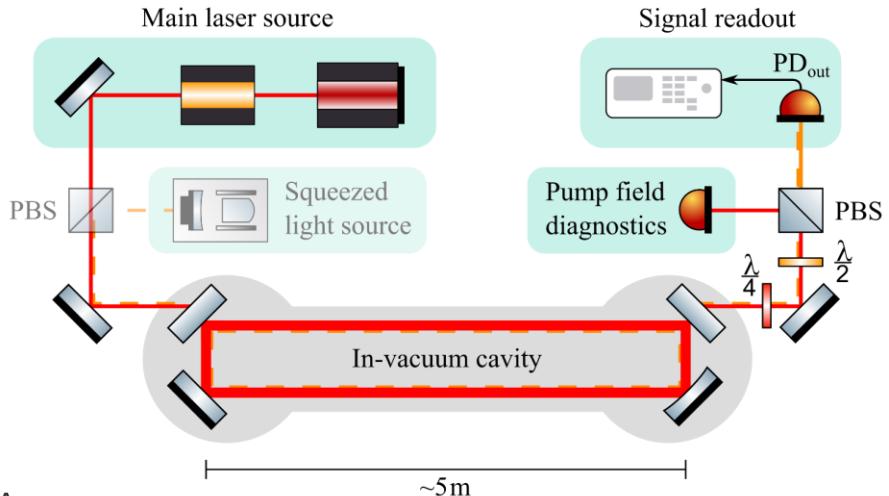


Summary

- LIDA is a **laser-interferometric detector for axions** sensitive to a rotation of linear polarisation!
- First science run yielded very **promising results**, paper submitted!
- **Prospects** to even probe unexplored regions in the next observing run at lower axion masses!
- **Challenge** to reduce detuning!
- **DarkGEO** could further boost the sensitivity by several orders of magnitude, paper in preparation!



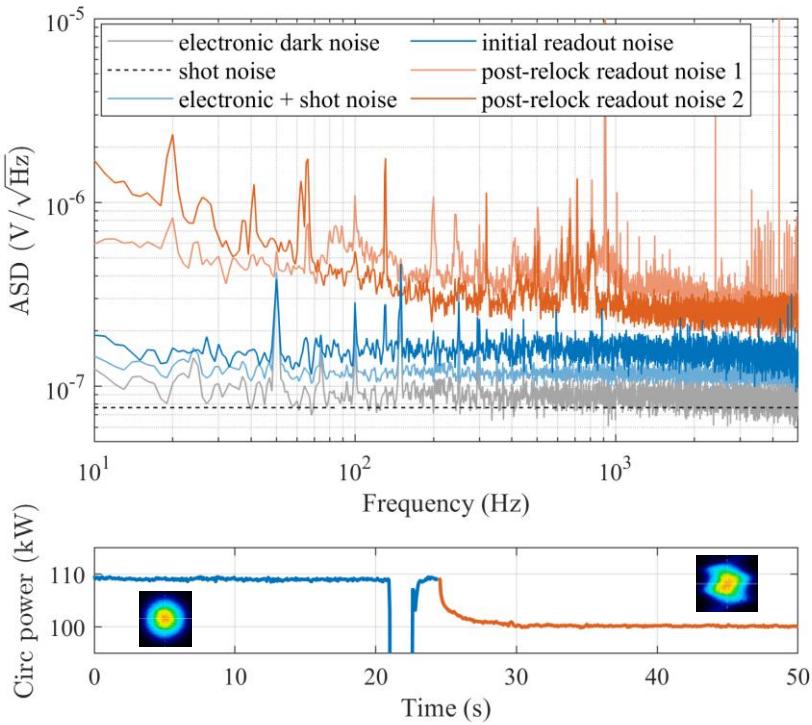
More detailed setup



EOM: electro-optic modulator, NPRO: non-planar ring oscillator, PBS: polarising beamsplitter,
PD: photodetector, PDH: Pound-Drever-Hall, rf: radio-frequency generator



High-power effects



At high circulating power:

If disturbed, the cavity often changes “state” correlating with

- a reduction in circulating power,
- a distortion of the transmitted field,
- higher readout noise.



GEO600 → DarkGEO



GEO600: close to Hanover, Germany (credit: geo600.org)



Parameter (DarkGEO-I)	Value	Unit
Wavelength	1064	nm
Cavity roundtrip length	1.2	km
Input coupler transmissivity, T_{in}	20	ppm
Output coupler transmissivity, T_{out}	1	ppm
Cavity roundtrip loss, l_{rt}	20	ppm
Laser input power	210	W
Intra-cavity power, $P_{\text{m,cav}}$	10	MW
Measurement time, T_{meas}	1	year
Main laser field polarisation	vertical	
Signal field polarisation	horizontal	
Parameter (DarkGEO-II/III)	Value	Unit
Wavelength	1064	nm
Cavity roundtrip length	1.2	km
Input coupler transmissivity, $T_{\text{m,in}}$	45	ppm
Output coupler transmissivity, $T_{\text{m,out}}$	1	ppb
Input coupler transmissivity, $T_{\text{sig,in}}$	3000	ppm
Output coupler transmissivity, $T_{\text{sig,out}}$	2.5	ppm
Cavity roundtrip loss, l_{rt}	45	ppm
Laser input power	460	W
Intra-cavity power, $P_{\text{m,cav}}$	10	MW
Effective squeezing level	10	dB
Measurement time, T_{meas}	1	year
Detuning, β	0.13 (scanned)	
Main laser field polarisation	vertical	
Signal field polarisation	horizontal	

