

# ML-based Particle Flow for CLD

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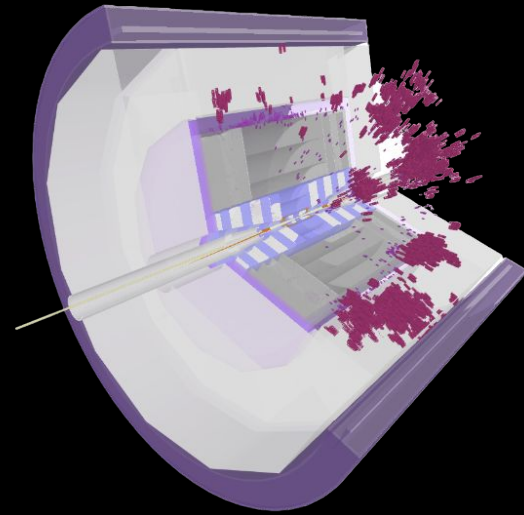
FUTURE  
CIRCULAR  
COLLIDER

**ETH** zürich

3rd ECFA Workshop, Paris, 9 October 2024

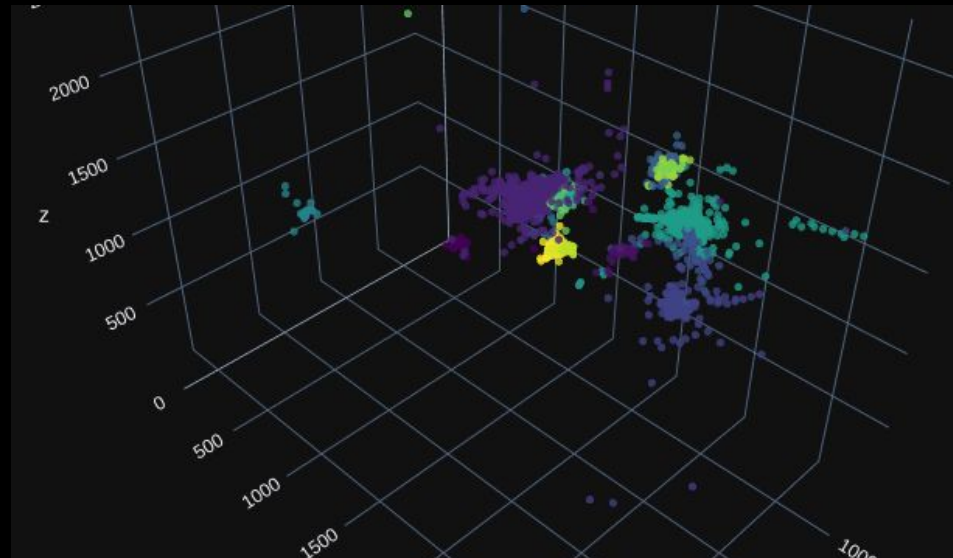
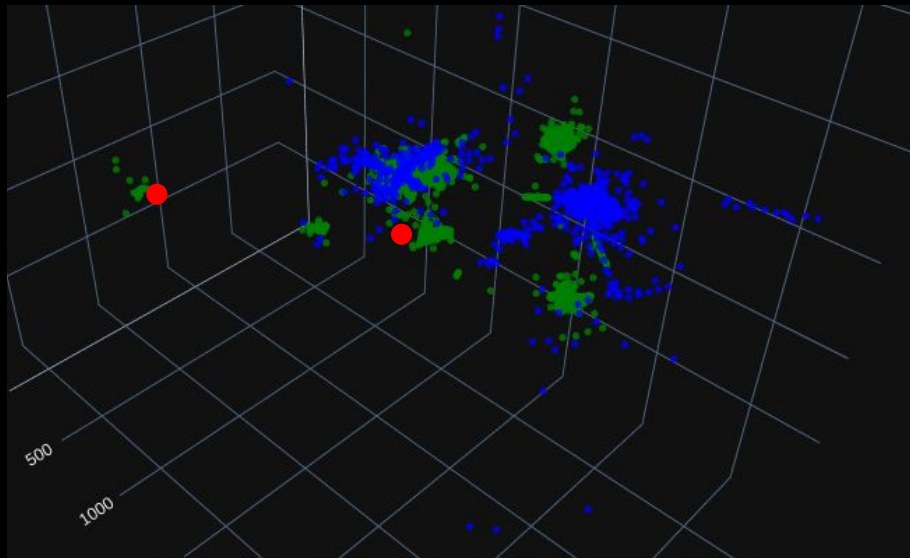
# ML-based Particle Flow

- Build PF candidates out of hits and tracks
  - Interesting problem for ML: Variable number of inputs (hits, tracks) and outputs (PF candidates)
  - Similar problems: image segmentation, tracking...
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- Dolores' talk tomorrow: **End-to-end ML-based reconstruction for FCC-ee**

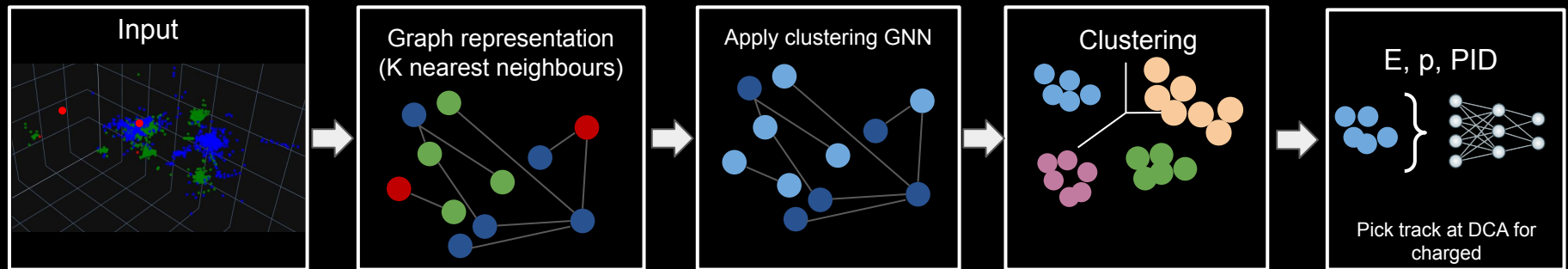


# Dataset - CLD fullsim

- fitted track
- ECAL hit
- HCAL hit



# Model



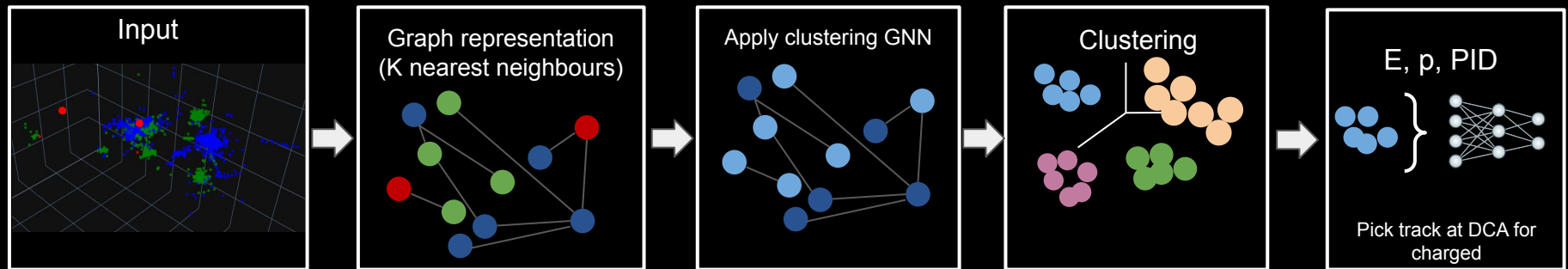
- Input: set of hits (ECAL, HCAL) + fitted tracks

- Graph Transformer

- Use HDBSCAN to build clusters - PF Candidates

- Simple PID: photon/CH/NH/e
- Output: PFCandidates

# Model



- Input: set of hits (ECAL, HCAL) + fitted tracks


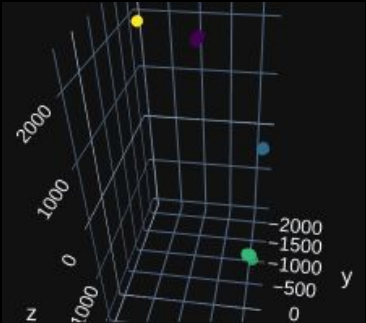
- Graph Transformer

- Use HDBscan to build clusters - PF Candidates

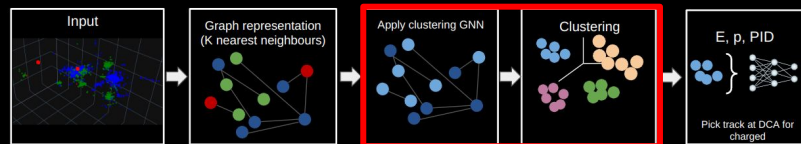
- Simple PID: photon/CH/NH/e
- Output: PFCandidates

**Similar approach for each detector! Can we avoid tuning of the Pandora parameters for each detector?**

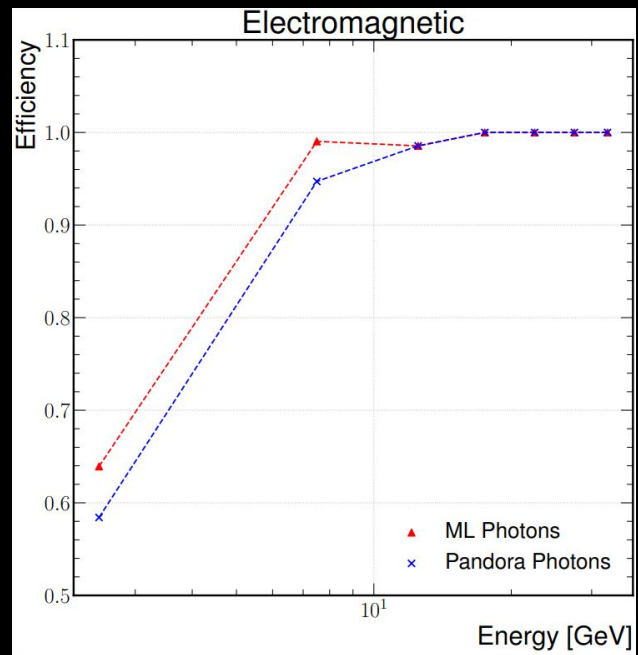
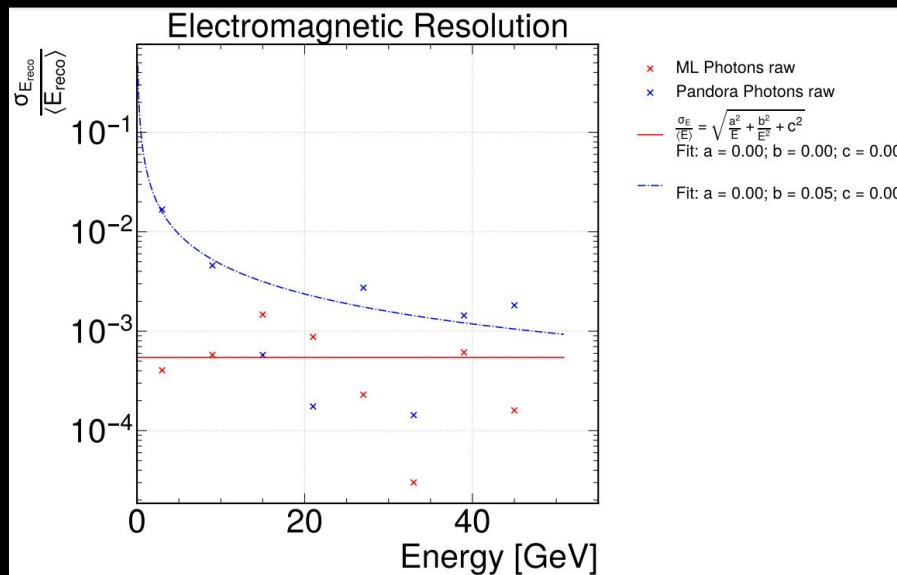
# Datasets

10-15 particle gun	$K_S \rightarrow \pi^0 \pi^0 \rightarrow 4 \gamma$
<p data-bbox="65 299 606 342"><math>E \sim [0.5, 50] \text{ GeV}</math>, from (0,0,0)</p> <p data-bbox="65 349 212 386"><math>\Delta r = 0.5</math></p> <p data-bbox="65 397 367 441"><math>p, n, K_L, \pi^\pm, e^\pm, \gamma</math></p>	<p data-bbox="680 299 993 342"><math>E \sim [0.5, 50] \text{ GeV}</math></p> <p data-bbox="680 349 1205 386">Displaced vertex; <math>c\tau \sim 2.6 \text{ cm}</math></p>
	

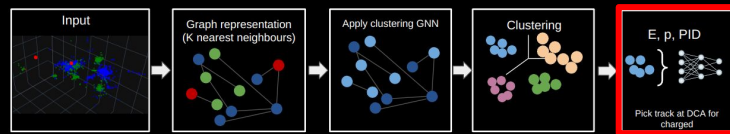
# Results: clustering



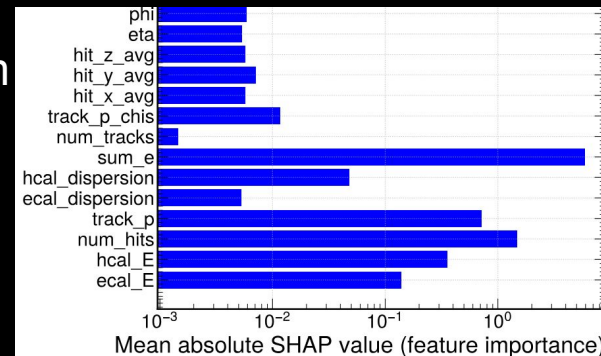
- Improved efficiency of clustering on the 10-15 particles dataset



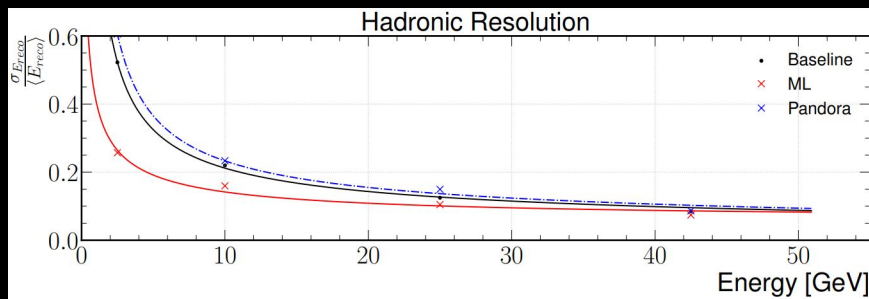
# Results: energy correction



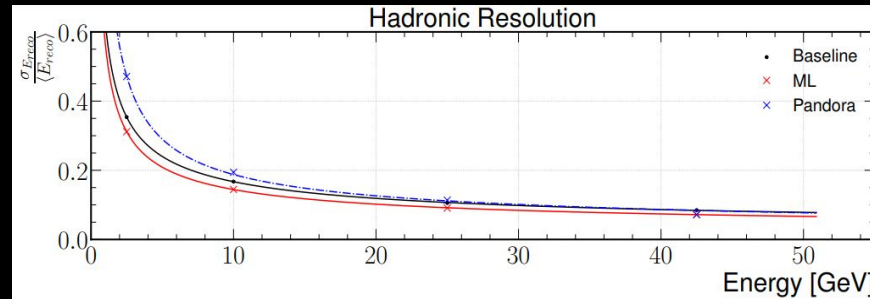
- Better clustering, energy correction for neutral hadrons leads to better mass resolution
- Key: high-level features (% energy in ECAL/HCAL; sum of  $E_{\text{hits}}$ ) complementing the complex shower geometry information extracted by the GNN
- Better clustering is key - sum of the hits the most important feature



neutrons



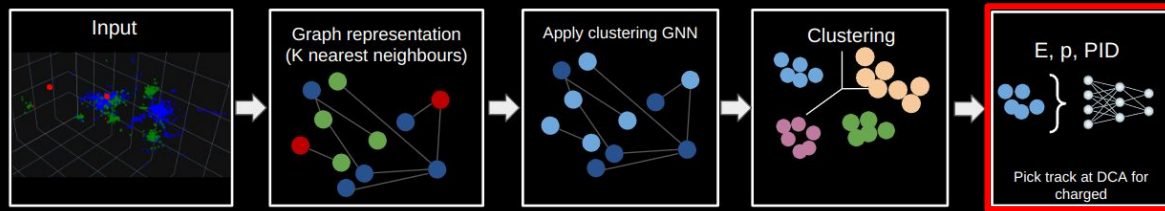
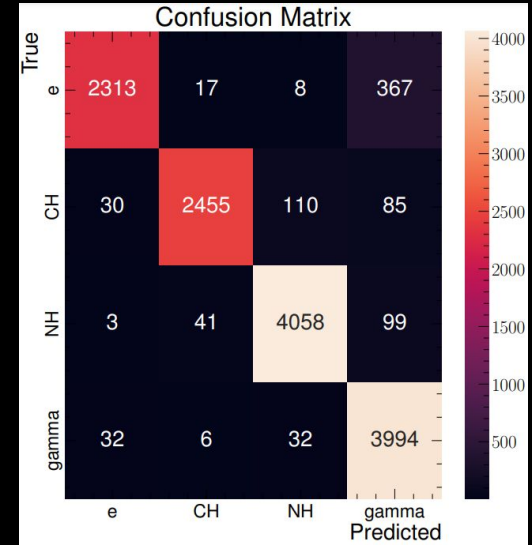
$K_L$





# Results: PID

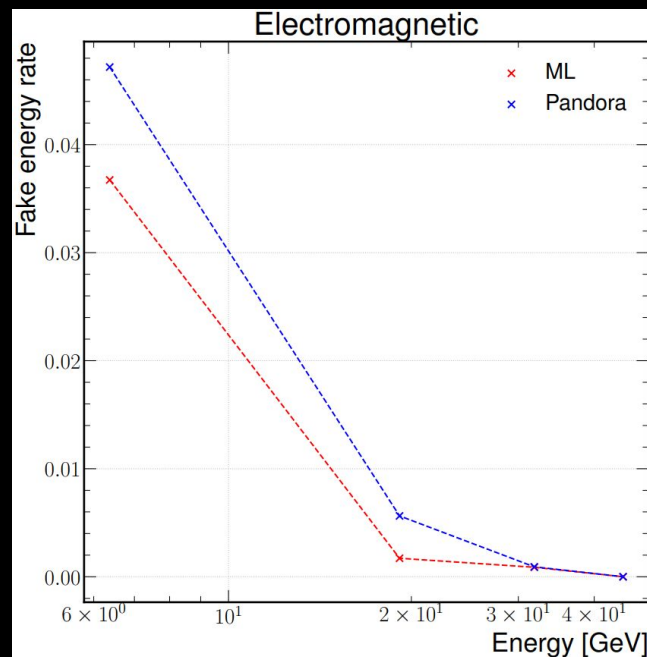
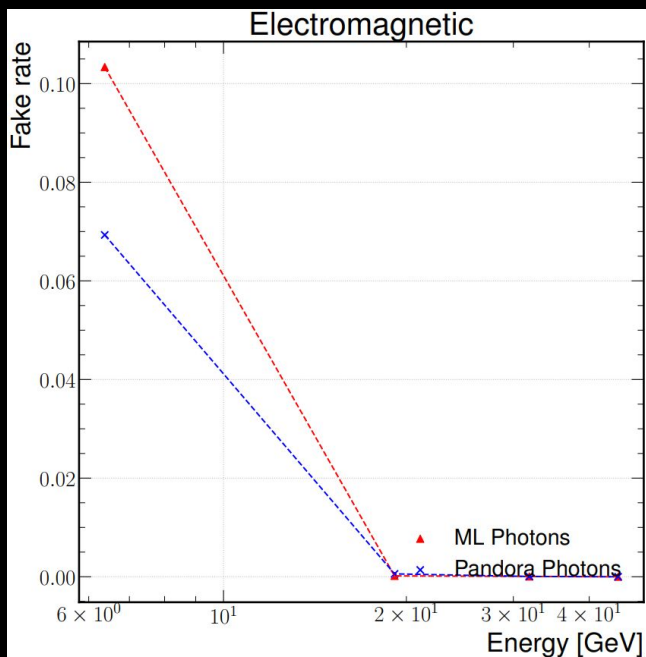
- Simplified PID: electron, CH (assign pion mass), NH (assign neutron mass), photon
- Predict unit vector  $p/|p|$  + energy correction + PID
- Separate model heads for charged (containing a track) and neutral (containing no track) particles
- All classes in both heads (to account for errors in clustering)



# What about fake rate?

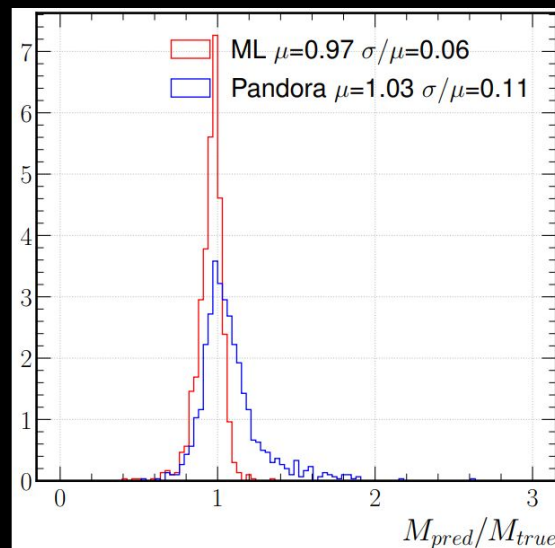
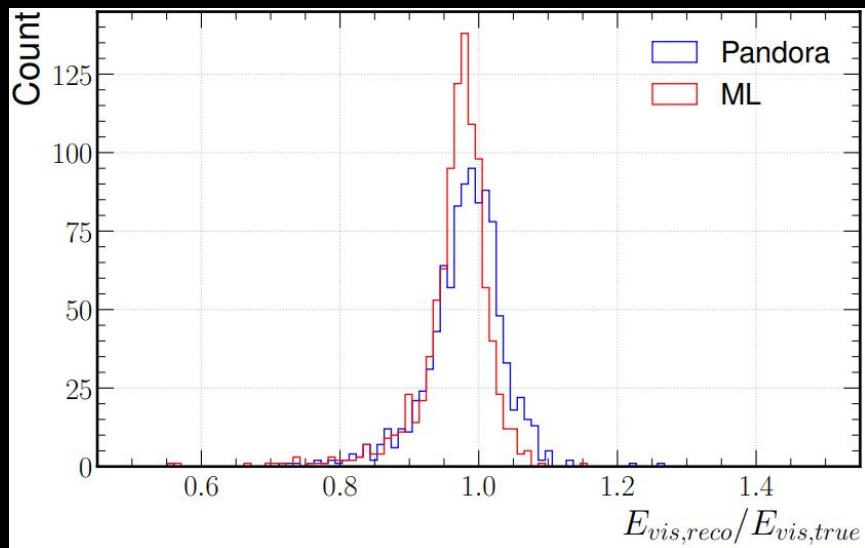
- Lots of fakes!
- But: less energy stored in them

Fake energy rate = E of fakes / Total E



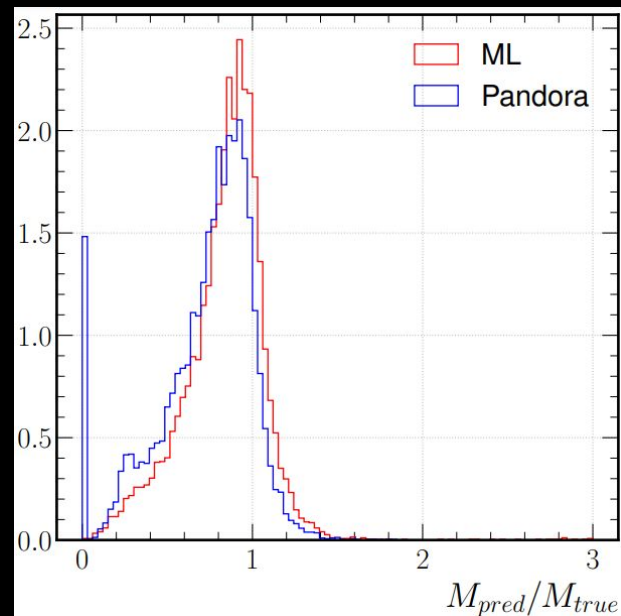
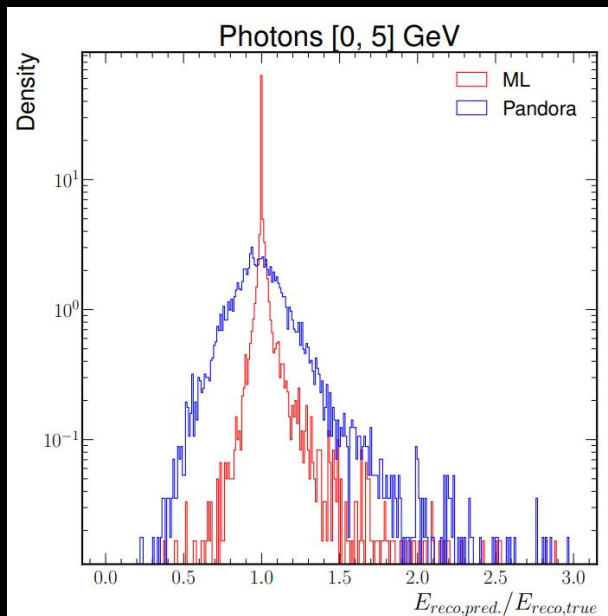
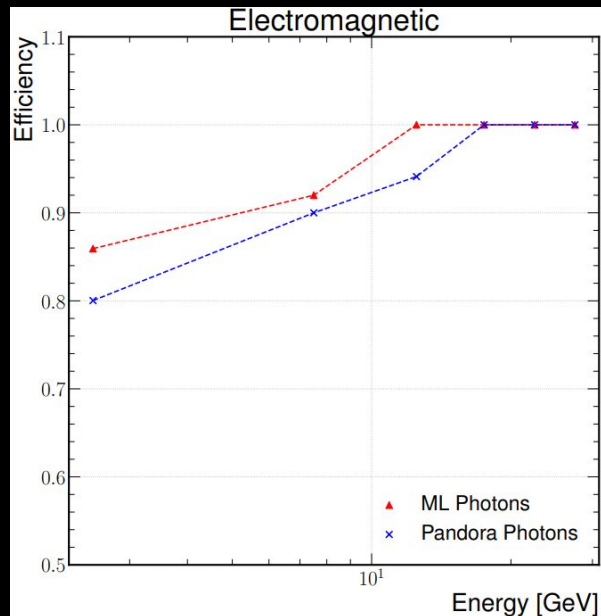
# Results - 10-15 particles dataset

- Better clustering efficiency, energy correction for neutrals leads to better invariant mass resolution (here, particles species are present equally in the same quantity - not the case for physics events!)



# Results: $K_S \rightarrow \pi^0 \pi^0$

- Not feasible to do direction regression - weighted average of the hits from (0,0,0) is a better solution - similar to Pandora



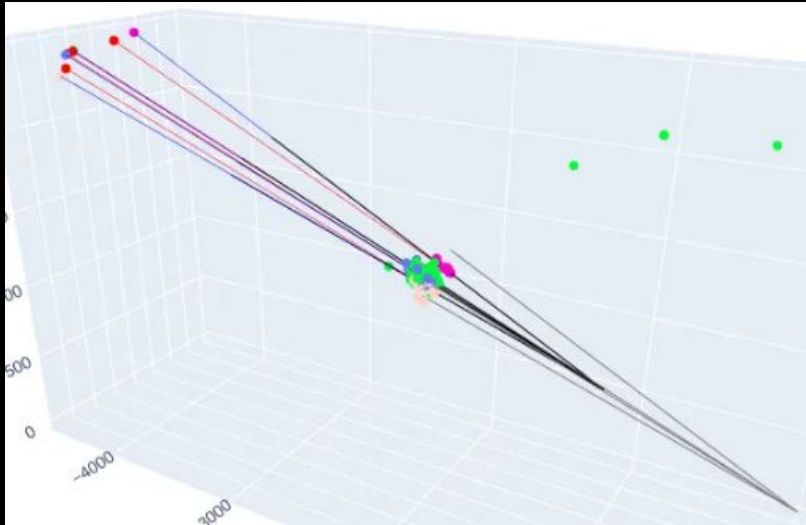
# Future work

- Demonstrate the model on physics events
- Improve angular resolution with ML
- Integrate MLPF into FCC software



# $K_S \rightarrow \pi^0 \pi^0$ dataset

- Still highly collimated photons



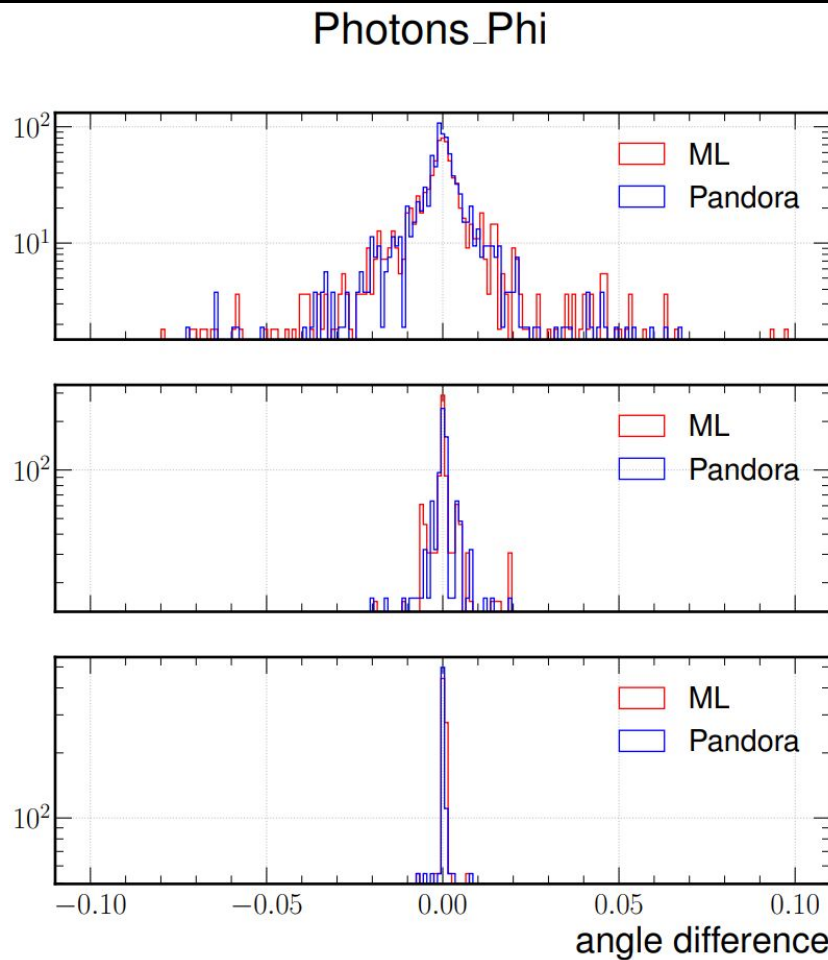
# Angular resolution ( $K_S$ dataset)

- Weighted average

[0,5] GeV

[5,15] GeV

[15,50] GeV





# Angular resolution ( $K_S$ dataset)

- Weighted average

[0,5] GeV

[5,15] GeV

[15,50] GeV

