

RADIO SHAPE MEASUREMENT

JOINT ARGOS-TITAN-TOSCA WORKSHOP, CRETE

Priyamvad Tripathi

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Observatoire de la Côte d'Azur



TOSCA

Weak lensing for optical and radio surveys

TABLE OF CONTENTS

1. Introduction
2. Methodology
3. Fixed PSF
4. Variable PSF
5. Comparison with Other Works
6. Summary

INTRODUCTION



- Galaxies sampled as **discrete** points in the **Fourier** domain

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$$V(u, v, w) = \int \frac{1}{n} I(l, m) \exp[-2\pi i(ul + vm + w(n - 1))] dl dm \quad (1)$$

u, v are Fourier domain coordinates, l, m are image domain coordinates, w corresponds to the non-coplanarity of antenna pairs, and $n = \sqrt{1 - l^2 - m^2}$

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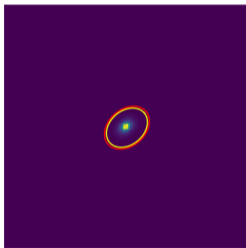
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- General radio-interferometric approach for image reconstruction is an iterative process: **Minor** and **Major** cycles
- Such a process is computationally expensive and can introduce non-linear biases [Patel et al., 2014]

EXAMPLE

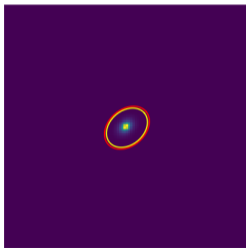


(a) x

$$\epsilon = [0.022, -0.154]$$

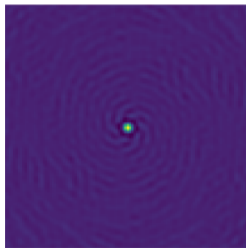
Figure 1: Example of a simulated galaxy with ellipticity $\epsilon = [0.024, -0.152]$.

EXAMPLE



(a) x

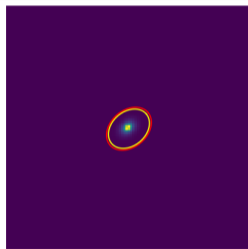
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(b) h

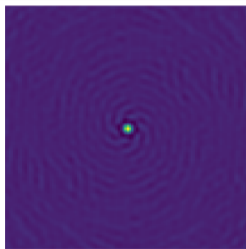
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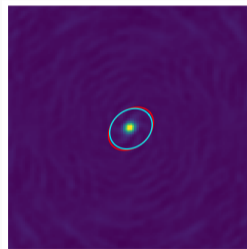


(a) x

$$\epsilon = [0.022, -0.154]$$



(b) h



(c) x^D

$$\epsilon = [0.026, -0.099]$$

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EXAMPLE

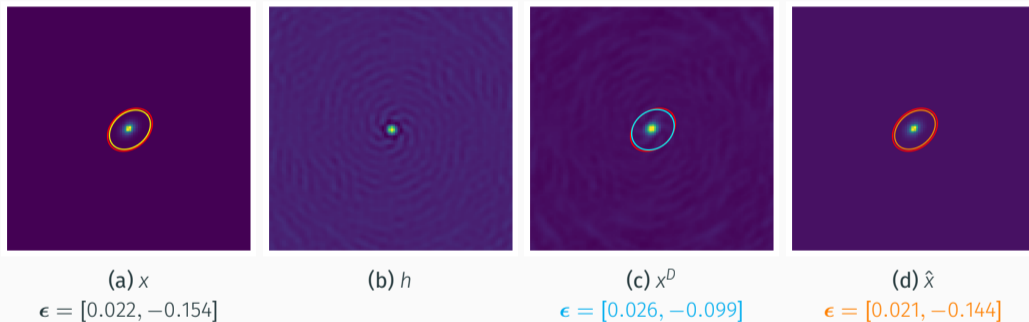


Figure 1: Example of a simulated galaxy with ellipticity $\epsilon = [0.024, -0.152]$. The images plotted from left to right are the true image x , PSF h , dirty image x^D , and reconstructed image \hat{x} .

METHODOLOGY

IMAGE FEATURE EXTRACTION

- We used an $E(2)$ equivariant convolutional neural network (CNN) [Weiler and Cesa, 2019] for our feature extraction layer

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- Equivariance is enforced in the structure by using convolution kernels expressed in a steerable basis of the $E(2)$ group:

$$k(\mathbf{x}|\mathbf{w}) = \sum_{\ell=1}^8 w_{\ell}(r) Y_{\ell}(\alpha) \quad (2)$$

where $\mathbf{x} = (r, \alpha)$, $Y_{\ell}(\alpha) = e^{i\ell\alpha}$ are the basis vectors and the kernel weights $w_{\ell}(r)$ have a radial symmetry.

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- Produces a vector feature map that is equivariant to the actions of the $E(2)$ group:

$$C_{E(2)}[G(\hat{\mathbf{x}})] = G[C_{E(2)}(\hat{\mathbf{x}})] \quad (3)$$

- **Population Model:** Star-Forming Galaxies (SFGs) catalogue from the Tiered-Radio Extragalactic Continuum Simulation (T- RECS) [Bonaldi et al., 2018]
- Isolated galaxies with galaxy center at antenna pointing: 128×128 pixels

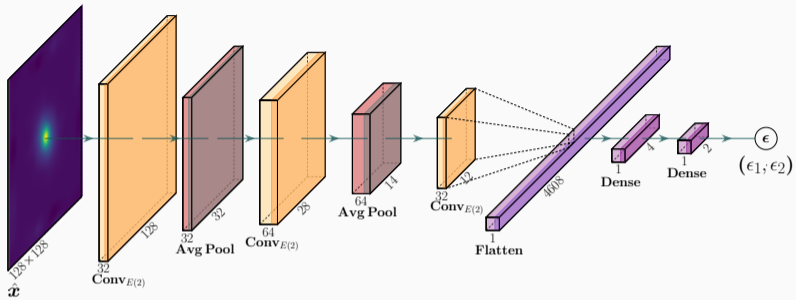
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- Visibilities based on SKA-MID configuration: 197 antennas, 936144 unique visibility positions
- Perturb the visibilities with noise sampled from $\mathcal{N}(0, (\sigma/20)^2)$

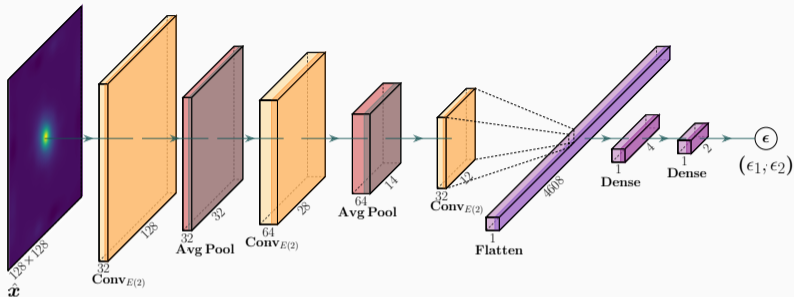
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- PSF h is then deconvolved from the dirty image using MS-Clean to get reconstructed image \hat{x}

FIXED PSF



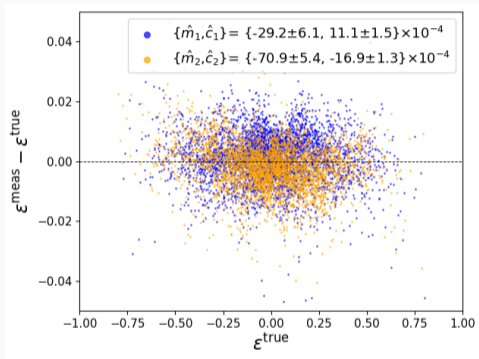




- 20,000 galaxies with varying size and intrinsic ellipticity

$$\hat{\theta}_{\text{eq}} = \underset{\theta_{\text{eq}}}{\text{argmin}} \mathbb{E}_{(\hat{x}, \epsilon^{\text{true}})} [\|N_{\theta_{\text{eq}}}(\hat{x}) - \epsilon^{\text{true}}\|^2] \quad (4)$$

NORMAL VS EQUIVARIANT NETWORK

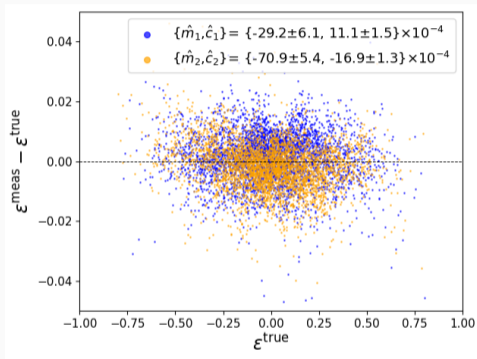


(a) Traditional Network

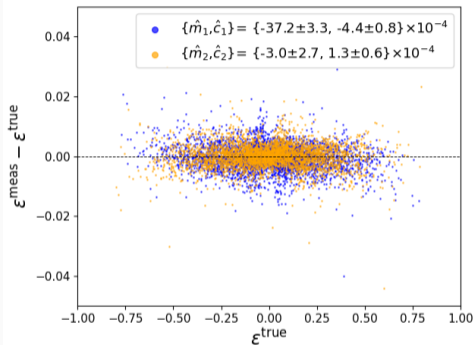
Figure 2: Comparison of $\Delta\epsilon$ vs ϵ^{true} . The two components $\Delta\epsilon_1$ and $\Delta\epsilon_2$ are plotted in blue and orange respectively. The legend indicates the linear bias in ellipticity measurement:

$$\Delta\epsilon_i = m_i \epsilon_i^{\text{true}} + c_i$$

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(b) Equivariant Network

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VARIABLE PSF

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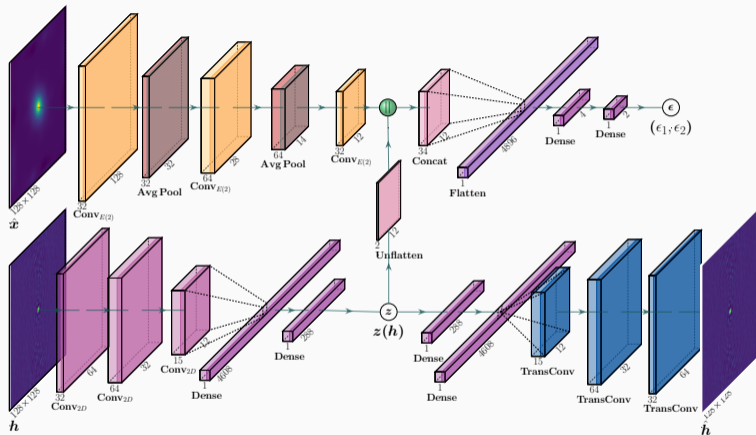
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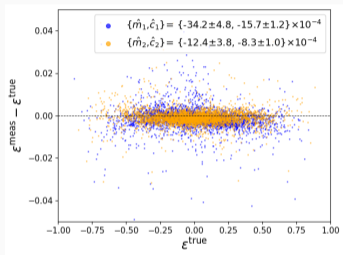
$$\{\hat{\theta}_E, \hat{\theta}_D\} = \underset{\{\theta_E, \theta_D\}}{\operatorname{argmin}} \mathbb{E}_h [\|h - \hat{h}_{\theta_D}[\mathbf{z}_{\theta_E}(h)]\|^2] \quad (5)$$

where \hat{h}_{θ_D} is the output from the decoder, \mathbf{z}_{θ_E} is the output from the encoder and $\{\theta_E, \theta_D\}$ the encoder-decoder architecture parameters.

NETWORK STRUCTURE

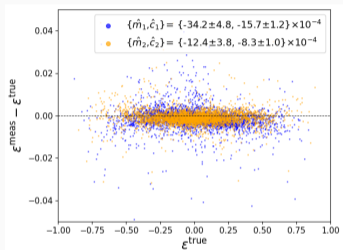


20,000 galaxies/PSF pairs with varying size and intrinsic ellipticity

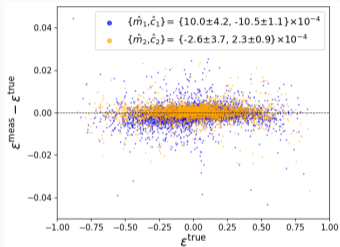


(a) Reconstructed Images: 1000
MS-Clean cycles

Figure 3

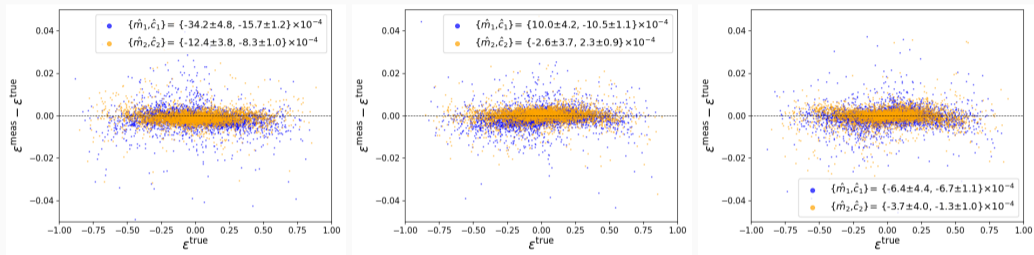


(a) Reconstructed Images: 1000
MS-Clean cycles



(b) Reconstructed Images: 500
MS-Clean cycles

Figure 3



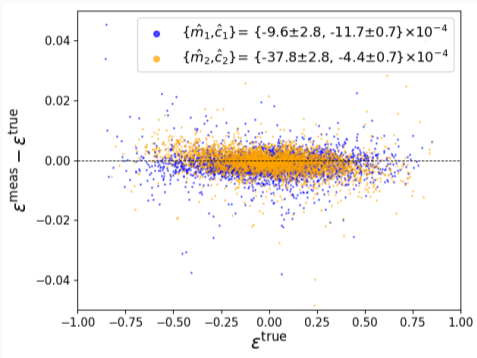
(a) Reconstructed Images: 1000 MS-Clean cycles

(b) Reconstructed Images: 500 MS-Clean cycles

(c) Dirty Images

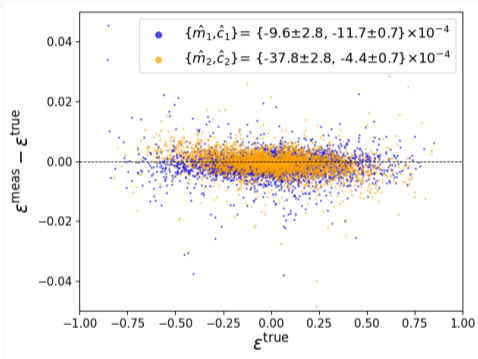
Figure 3

Figure 4: Galaxies following a **Sérsic brightness profile**: $I(r) = I_0 \exp[-(\frac{r}{r_0})^{\frac{1}{n}}]$ with index n drawn from $\mathcal{U}(1, 4)$

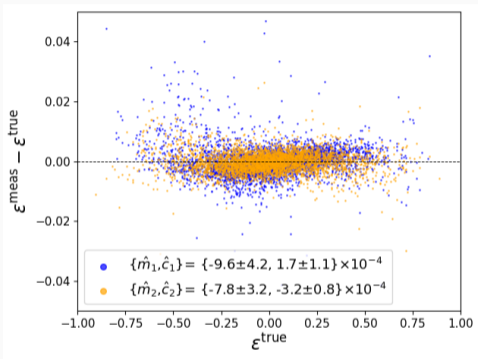


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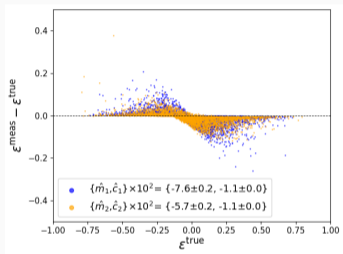
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COMPARISON WITH OTHER WORKS

- Tikhonov solution: $\tilde{x} = (H^T H + \lambda \Gamma^T \Gamma)^{-1} H^T x^D$ where H corresponds to the PSF operator, Γ corresponds to Tikhonov linear filter and λ is the regularisation weight.
- A UNET architecture is then trained to learn the mapping b/w the Tikhonov output and the true image.
- The network is trained to minimize the following loss function: $l(\hat{x}) = \|\hat{x} - x\|^2 + \gamma M(\hat{x})$
- $M(\hat{x}) = \sum_{i=1}^6 \omega_i \langle \hat{x} - x, u_i \rangle$ is a shape constraint with $\{\omega_i\}$ and $\{u_i\}$ are constant scalar weights and images respectively

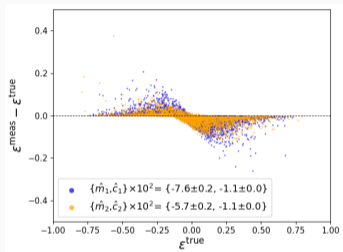
COMPARISON WITH SHAPENET



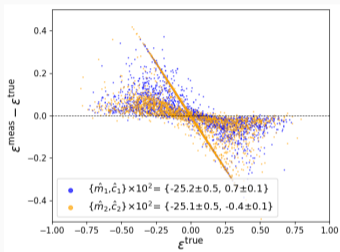
(a) $x^D = x * h + n$

Figure 5

COMPARISON WITH SHAPENET



(a) $X^D = x * h + n$



(b) $X^D = f(x, h, w, D/G, \text{vis})$

Figure 5

COMPARISON WITH SHAPENET

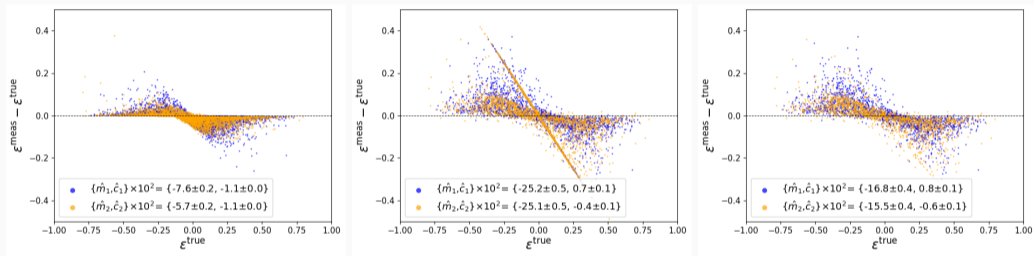
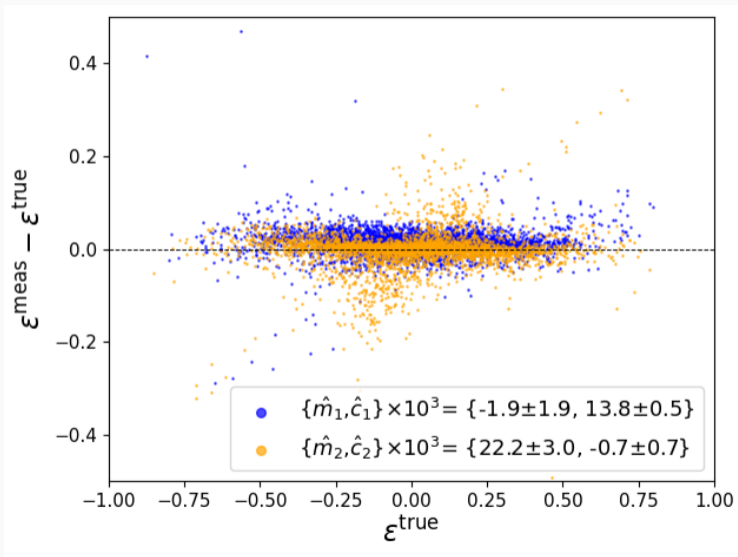


Figure 5

- Reconstruct image by deconvolving the PSF from the dirty image and estimate ellipticity ϵ_k^{calc}
- In the residual image, inject model sources with the same size and flux properties, but known ellipticity $\epsilon_i^{\text{inp}} = \{0, \pm 0.2375, \pm 0.475, \pm 0.7125, \pm 0.95\}$
- Simulate visibilities \Rightarrow Dirty Image \Rightarrow Reconstructed Image \Rightarrow Measure ellipticity ϵ^{obs}
- Fit second order 2D polynomial $b_k(\epsilon_1^{\text{inp}}, \epsilon_2^{\text{inp}}) = \epsilon_1^{\text{obs}} - \epsilon_1^{\text{inp}}$
- Calibrate observed ellipticities using $\epsilon_{1,k}^{\text{SC}} = \epsilon_{1,k}^{\text{calc}} - b_k(\epsilon_{1,k}^{\text{calc}}, \epsilon_{2,k}^{\text{calc}})$
- Repeat for ϵ_2

COMPARISON WITH SUPERCLASS



SUMMARY

Table 1: Linear Bias in Ellipticity estimates (at the order of 10^{-3})

| | | m_1 | c_1 | m_2 | c_2 |
|--------------|------------------|----------------------------------|----------------------------------|----------------------------------|----------------------------------|
| Fixed PSF | Trad Net | 2.9 ± 0.6 | 1.1 ± 0.2 | 7.1 ± 0.5 | -1.7 ± 0.1 |
| | Eq Net | 3.7 ± 0.3 | -0.4 ± 0.1 | -0.3 ± 0.2 | 0.1 ± 0.1 |
| Variable PSF | Recon 500 | 1.0 ± 0.4 | -1.1 ± 0.1 | -0.3 ± 0.4 | 0.2 ± 0.1 |
| | Recon 1000 | -3.4 ± 0.5 | -1.6 ± 0.1 | -1.2 ± 0.4 | -0.8 ± 0.1 |
| | Dirty | -0.6 ± 0.4 | -0.7 ± 0.1 | -0.4 ± 0.4 | -0.1 ± 0.1 |
| | Shapenet Decon | 76.1 ± 2.0 | -11.3 ± 0.1 | 57.3 ± 2.1 | -11.1 ± 0.0 |
| | SuperCLASS Calib | 1.9 ± 1.9 | 13.8 ± 0.5 | 22.2 ± 3.0 | -0.7 ± 0.7 |
| Sersic Gal | Recon | 1.0 ± 0.3 | -1.2 ± 0.1 | -3.8 ± 0.3 | -0.4 ± 0.1 |
| | Dirty | -1.0 ± 0.4 | 0.2 ± 0.1 | -0.8 ± 0.3 | -0.3 ± 0.1 |

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CONCLUSION

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- Can work with galaxies with different intensity profiles

THANK YOU FOR YOUR TIME

Table 2: Comparison of MAE: $\frac{1}{N_{\text{obj}}} \sum_{n=1}^{N_{\text{obj}}} |\Delta \epsilon_i^n|$

| | MAE ϵ_1 (ϵ_2) | N_{obj} |
|---------------------------------|--------------------------------------|------------------|
| ShapeNet Paper | $7.34 (7.70) \times 10^{-2}$ | 3000 |
| Case I | $2.37 (2.69) \times 10^{-2}$ | 3810 |
| Case II | $7.11 (7.02) \times 10^{-2}$ | 3247 |
| Fiducial Network (Recon Images) | $3.82 (2.74) \times 10^{-3}$ | 3993 |
| Fiducial Network (Dirty Images) | $4.16 (3.59) \times 10^{-3}$ | 3993 |

- Works using visibilities
- Galaxy brightness profile: $I(r) = I_0 \exp(-r/\alpha)$,
- Transformation matrix \mathbf{A} with ellipticity parameters $\mathbf{e} = (e_1, e_2)$ such that:

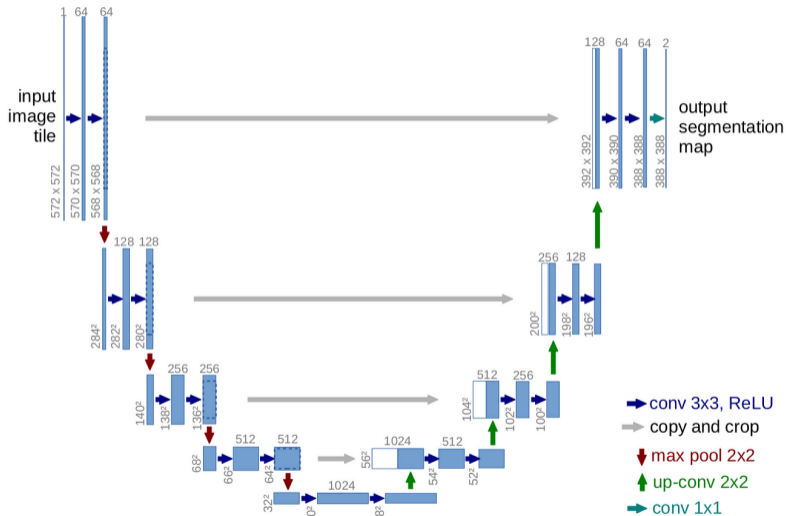
$$\begin{pmatrix} l_r \\ m_r \end{pmatrix} = \mathbf{A}\mathbf{x} = \begin{pmatrix} 1 - e_1 & -e_2 \\ -e_2 & 1 + e_1 \end{pmatrix} \times \begin{pmatrix} l \\ m \end{pmatrix}$$



- Observed visibility due to a galaxy at point $\mathbf{k} = (u, v)$ can be given by:

$$V_s(u, v) = \frac{2\pi\alpha^2 I_0}{|\mathbf{A}|(1 + 4\pi^2\alpha^2|\mathbf{A}^{-\top}\mathbf{k}|)^{3/2}} \times \exp 2\pi i \mathbf{k}^\top \mathbf{x}_0 \quad (6)$$





- Perform a Bayesian marginalization of the likelihood over I_0 , α and source centroid position $\mathbf{x}_0 = (l_0, m_0) \Rightarrow P(\mathbf{A}|D)$

UNET ARCHITECTURE



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