

Astronomical Video Imaging



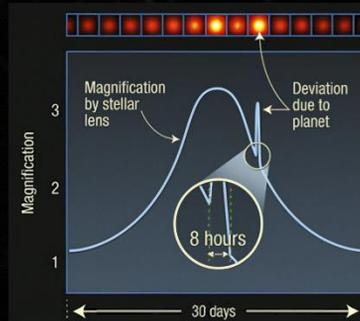
Emmanuel Bertin



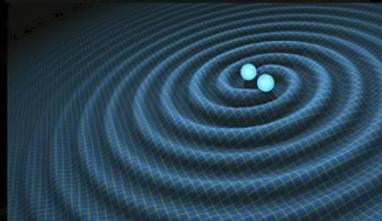
université
PARIS-SACLAY



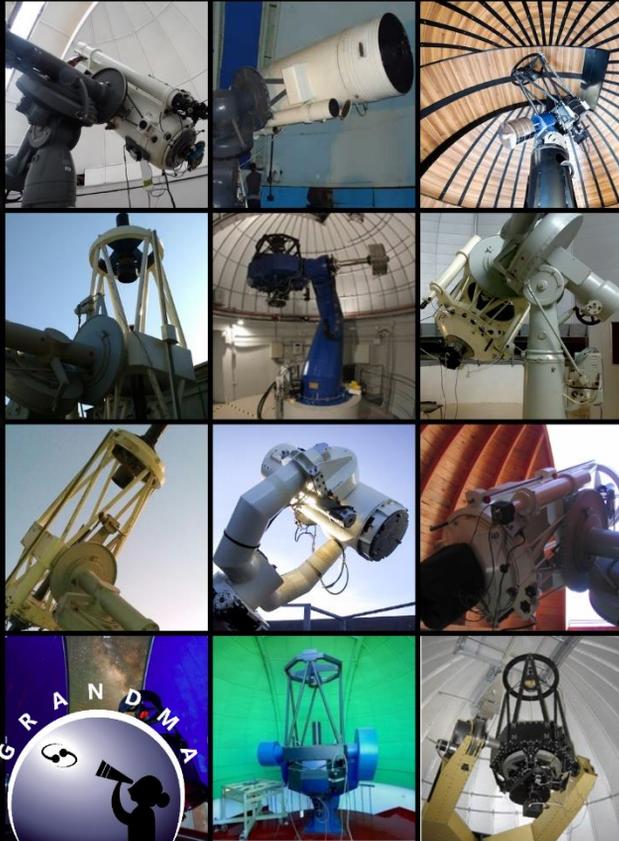
Transient astronomy



IPAC/caltech



DanceCam



- EB, S.Bialek, H.Bouy, J.-C. Cuillandre, S.Fabbro, O.Lai, J.-P. Rivet
- Funding IDEX “Cosmic-DANCe” / INSU national projects / NTCO-Create
- Leverage new technologies to improve the efficiency of (small) survey telescopes
- Time domain astronomy

Potential benefits of deep sky video imaging



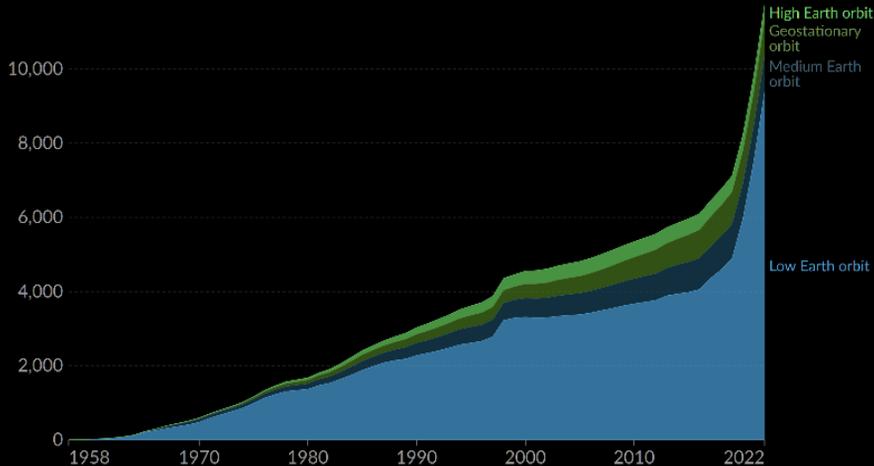
- Ultra-short readout time (Electronic shutter)
 - CCDs: 2s-80s (10-60%)
- No shutter action required
- No guiding required
- No de-rotator required
- Digital stacking
 - MegaCam: 25% of exposures are non-sidereal guided
- Real-time monitoring
 - Photometry
 - Turbulence profile
- Lucky imaging
- Mitigate the impact of temporal artifacts
- Mitigate blurring effects from the atmosphere

Satellite constellations

Number of payloads and rocket bodies in space, by orbit

Our World
in Data

Debris from launches or collisions is not counted. Objects are subtracted from the time series after they have reentered the Earth's atmosphere.



Data source: United States Space Force (2023)

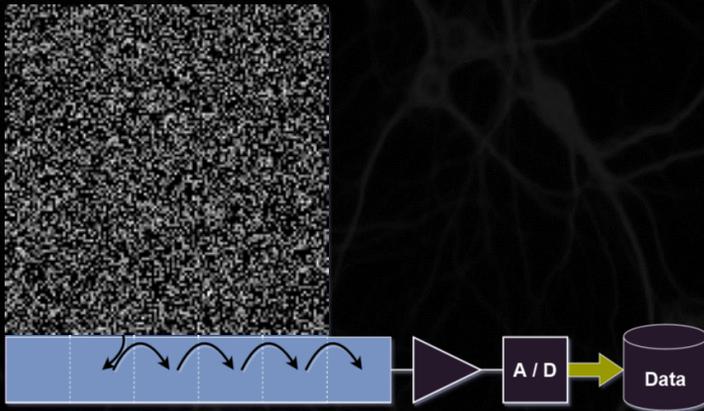
OurWorldInData.org/space-exploration-satellites | CC BY

Note: Low Earth orbit¹ is defined by a point of closest approach to Earth below 2,000 kilometers; medium Earth orbit between 2,000 and 35,586 kilometers; geostationary orbit between 35,586 and 35,986 kilometers; high Earth orbit above 35,986 kilometers.

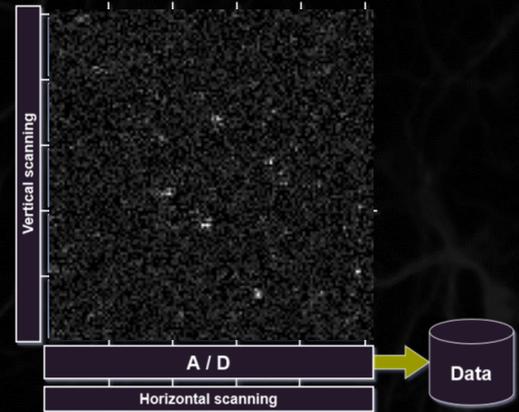
1. **Low Earth orbit:** A low Earth orbit (LEO) is an orbit around Earth with a period of 128 minutes or less (making at least 11.25 orbits per day). Most of the artificial objects in outer space are in LEO, with an altitude never more than about one-third of the radius of Earth.

CMOS vs CCD sensors

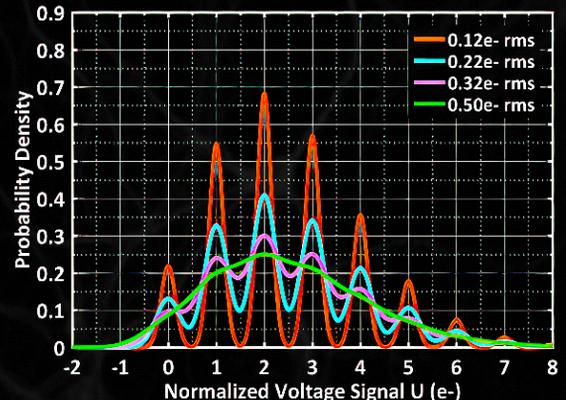
CCD



CMOS



- CMOS: charges are converted to voltage at every pixel.
- Modern CMOS detectors allow ~ 20 fps full-frame acquisition at sub- e^- readout noise.
- Suitable for contemporary science (Betoule et al. 2023).
- Readout noise and QE in the NIR steadily improving.



A low orbit satellite



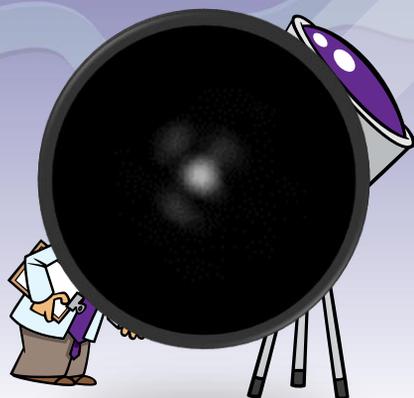
A more distant object



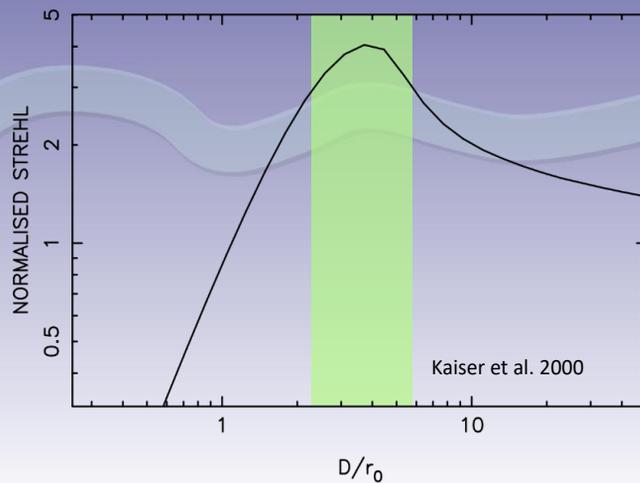
Upper layer

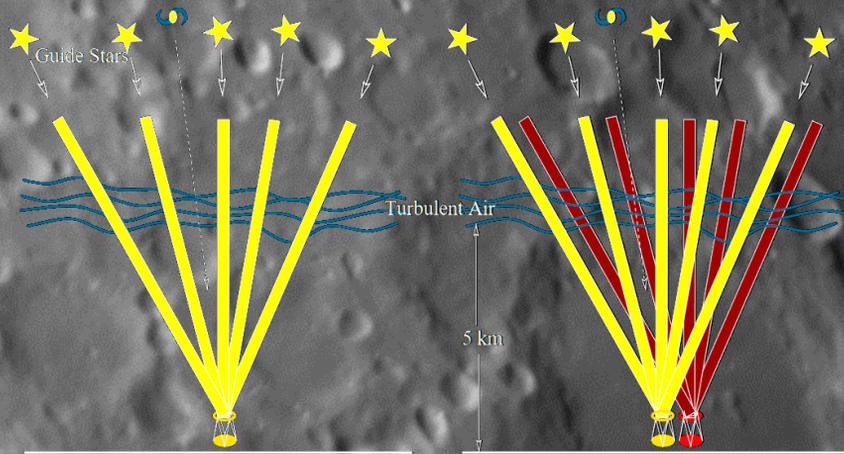
Intermediate layer

Ground layer

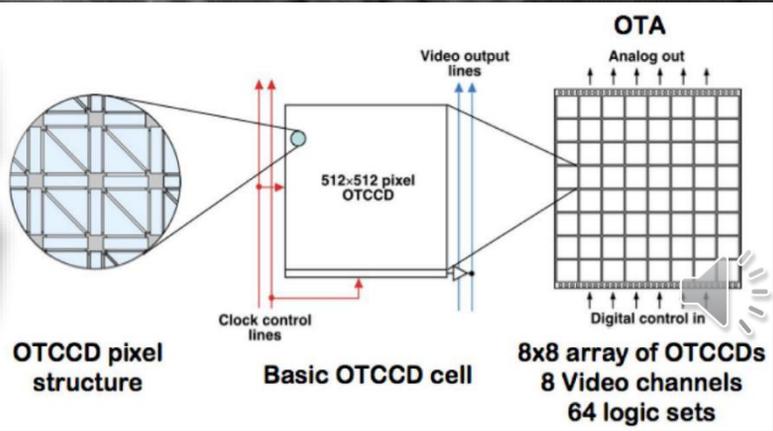


e.g., HRCam@CFHT (McLure et al. 1989)
GravityCam@NTT (MacKey et al. 2018)





Kaiser, Tonry & Luppino 2000

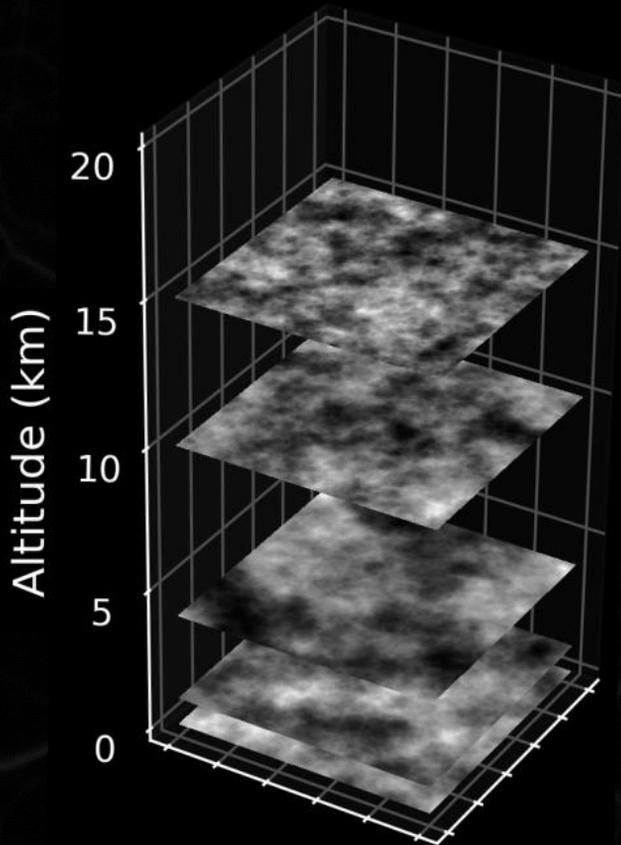


Requirements

- An excellent <1m telescope in a good observing site, with excellent wide-field correction and low obstruction ✓
- A large SCMOS camera ✓
- A high speed image acquisition system ($\sim 1\text{GB/s}$) ✓
- A good forward model



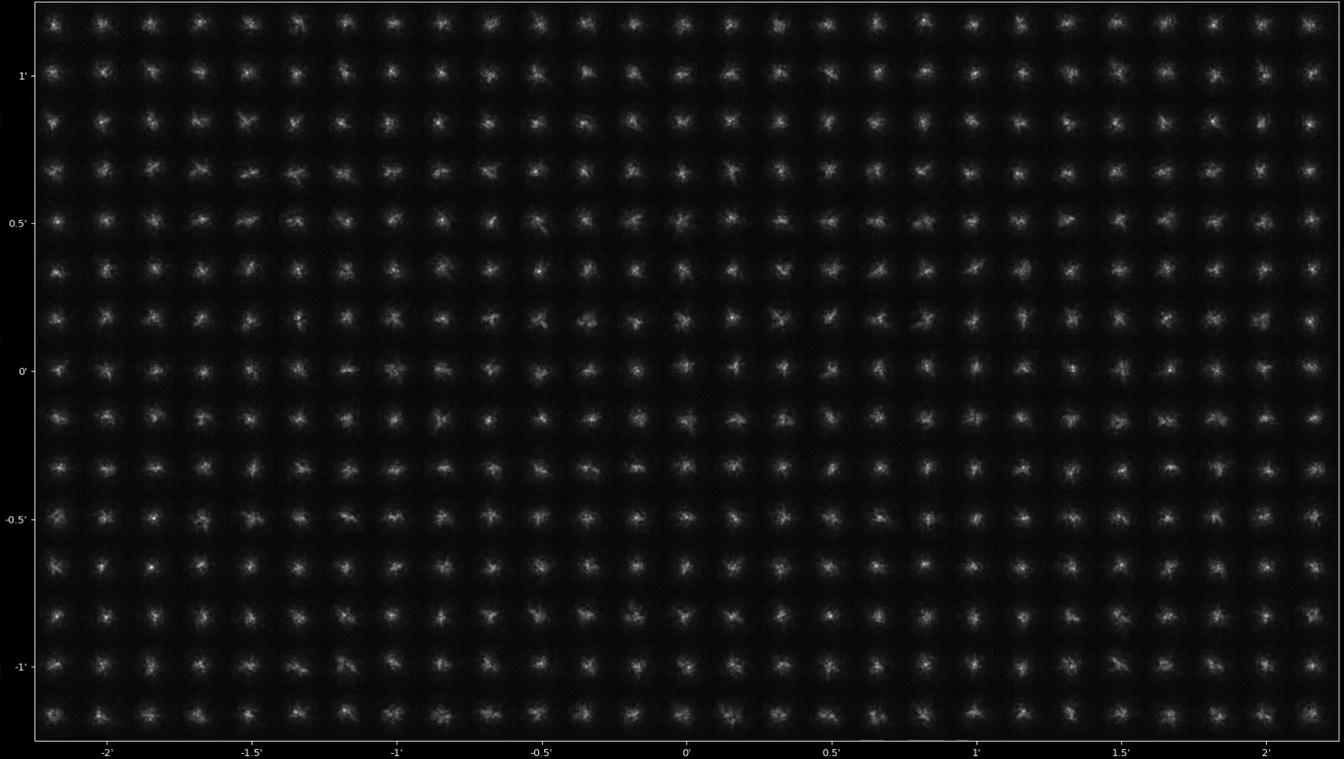
Propagation through the atmosphere



- Stochastic model with a modified von Kármán spectrum
- Frozen field approximation
- Centrimetric resolution
- Fresnel light propagation using the angular spectrum representation
 - Instrument pupil and aberrations
 - Stars twinkle!
- Implementation in PyTorch 2
 - Batch FFTs and tensor folding/unfolding
 - 10^5 PSFs/s on a fast GPU

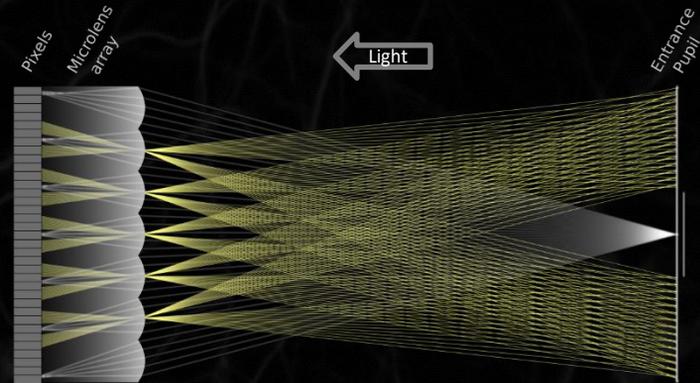
PSF rendering example

0.7" seeing over 5 turbulent layers / r band / 40" diameter / 30% obstruction

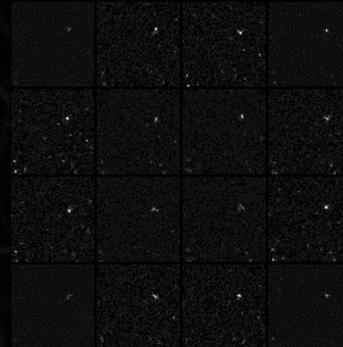
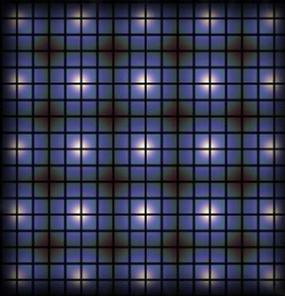


Dealing with larger pupils

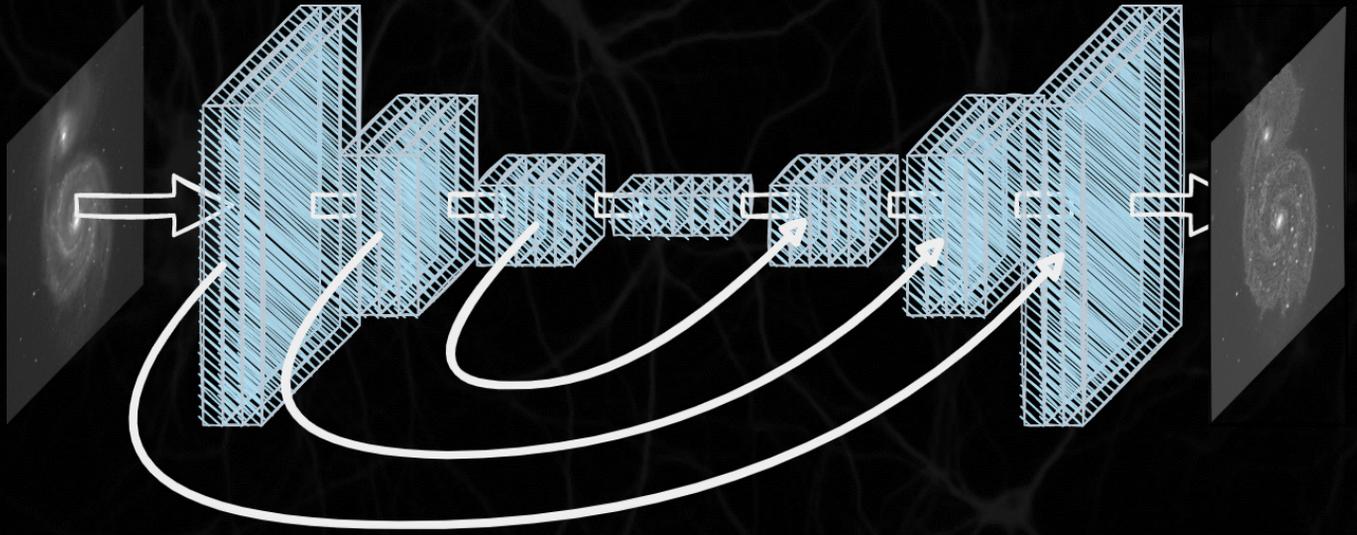
- Extend iso-kinetic area around “guide-stars”
- Pupil splitting with a light-field camera design (e.g., Ng 2006)?
 - Abbe diffraction limit for an F/4 beam:
 - $2\mu\text{m}@400\text{nm}$
 - $4\mu\text{m}@800\text{nm}$
- Or rely on holographic-like reconstruction?



4m-class

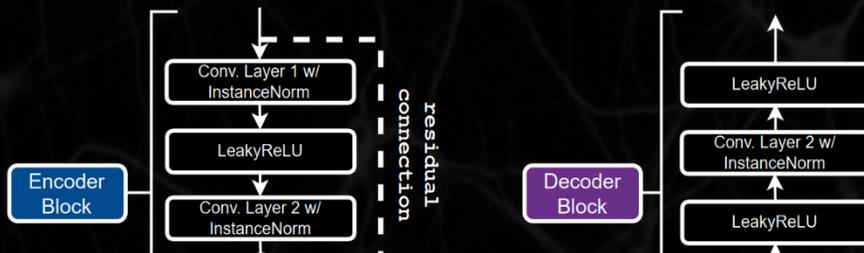
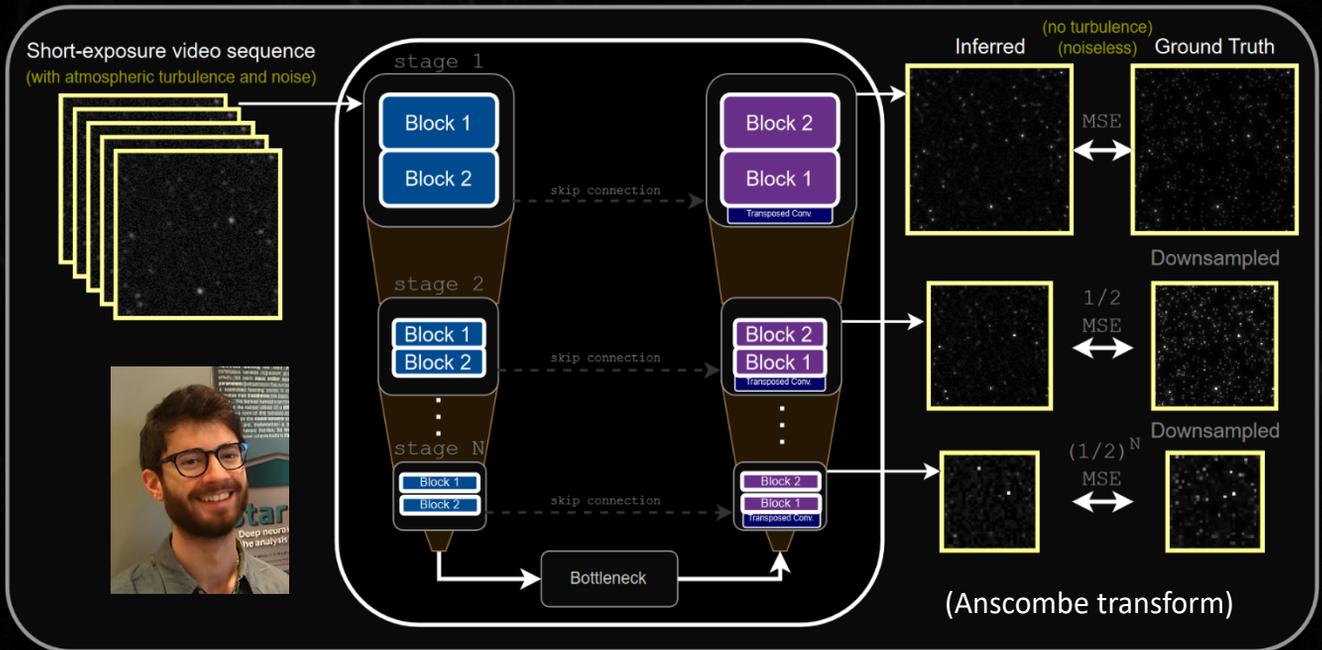


Deep learning approach: U-Net regressors



e.g., Ronneberger et al. 2015

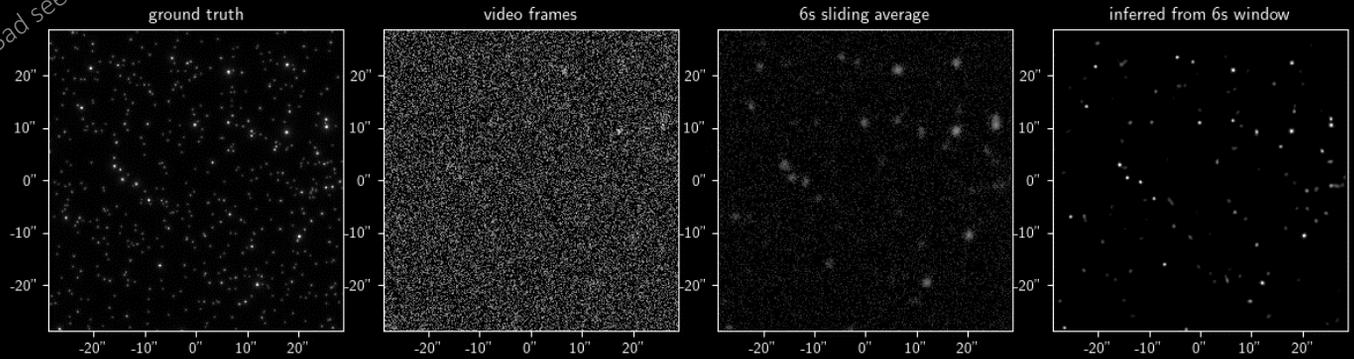
DanceNet



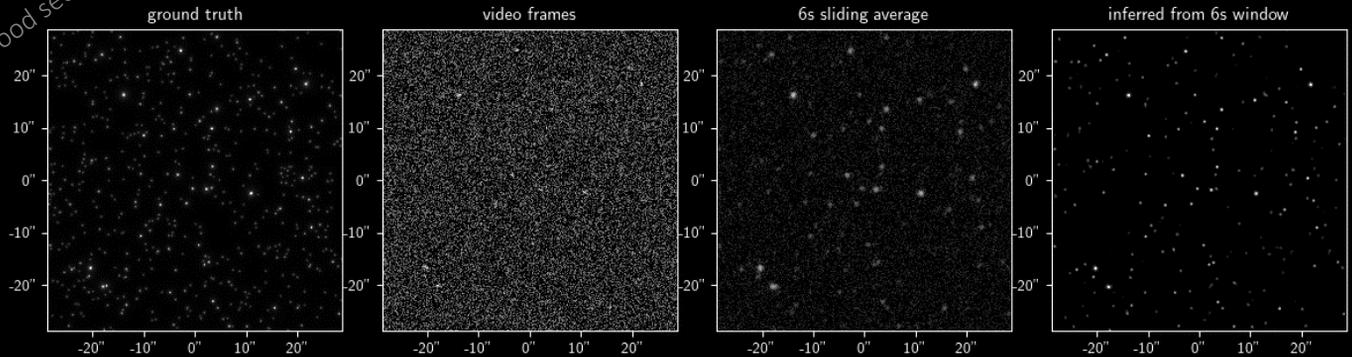
Isensee+ 2021

Inference test results

Bad seeing



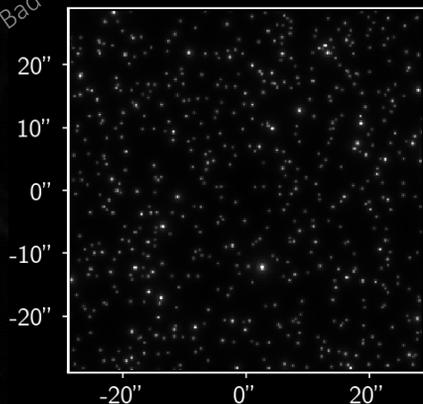
Good seeing



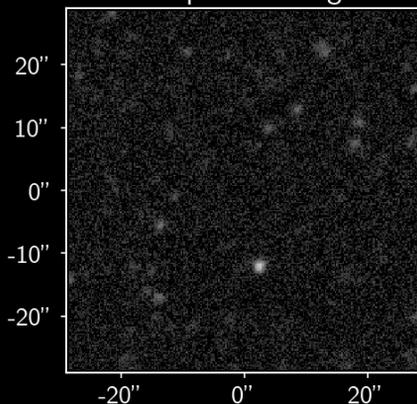
Inference test results (stacked)

Bad seeing

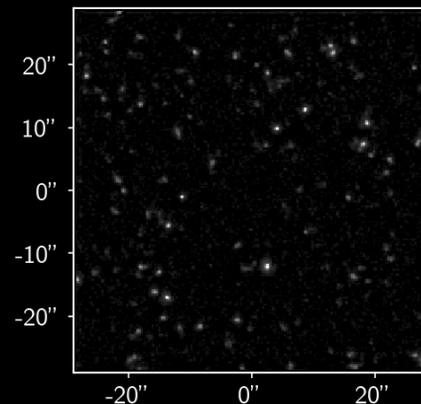
Ground Truth



Temporal Average

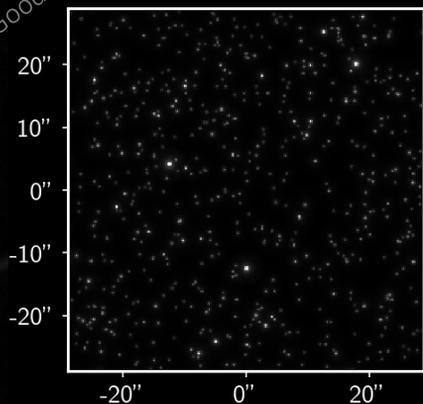


Inferred

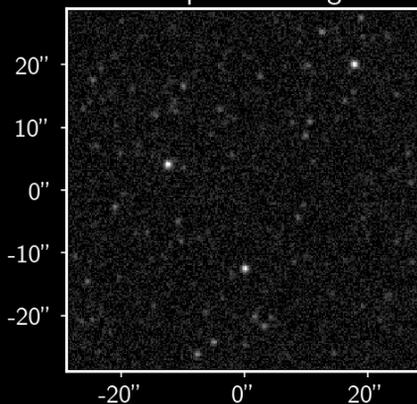


Good seeing

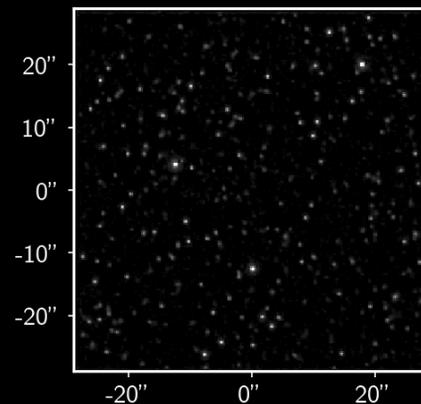
Ground Truth



Temporal Average

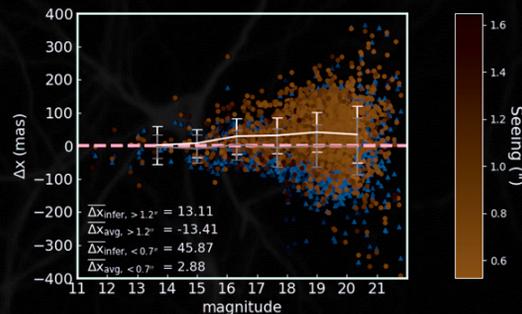
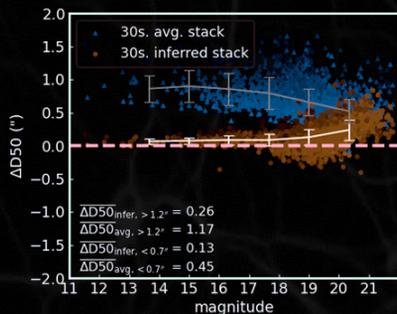
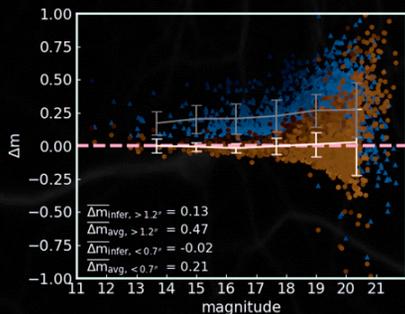
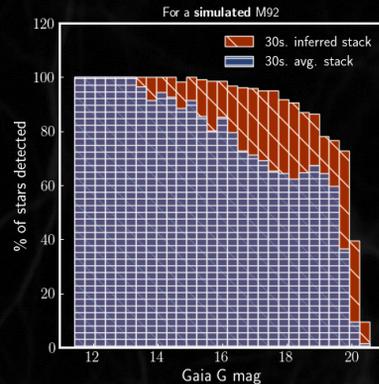
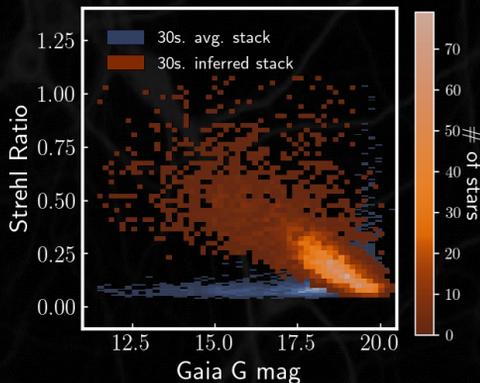
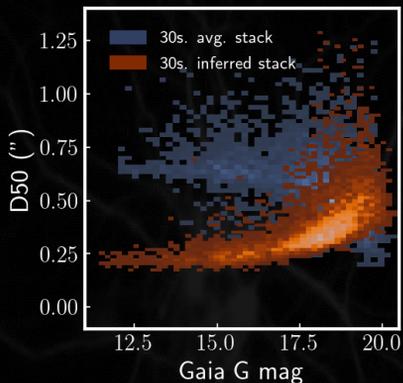


Inferred



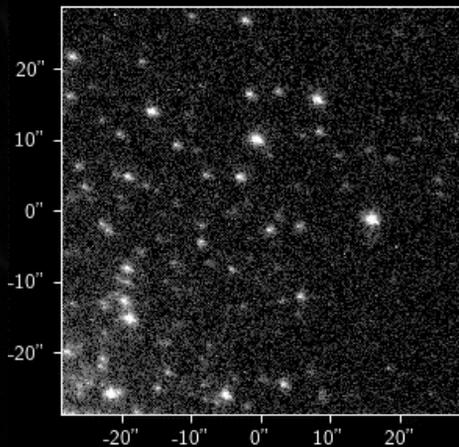
Validation on synthetic data

For a simulated M92

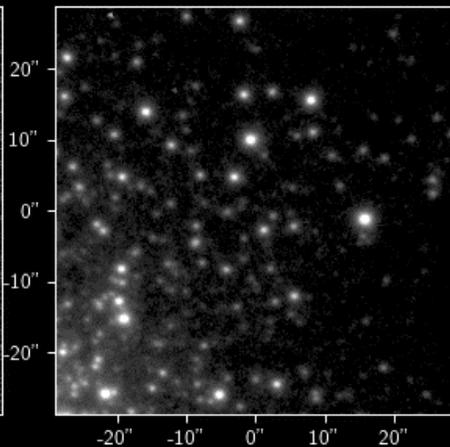


Real data

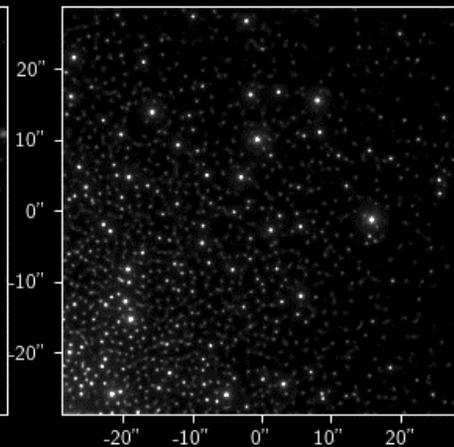
video frames



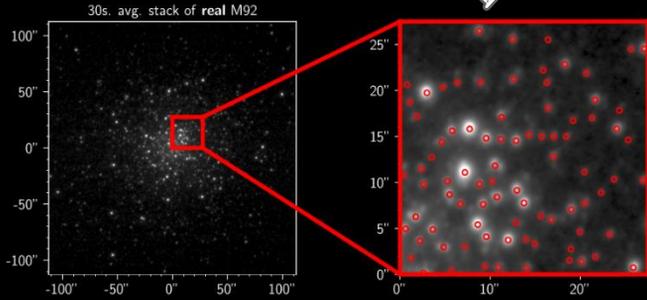
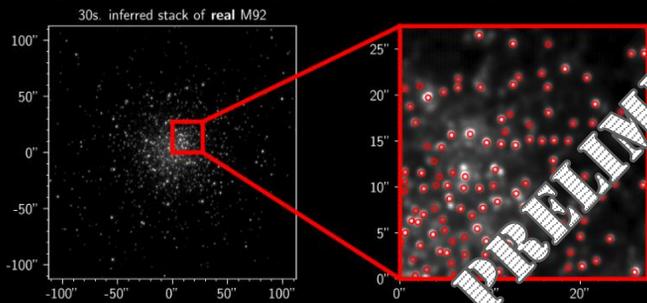
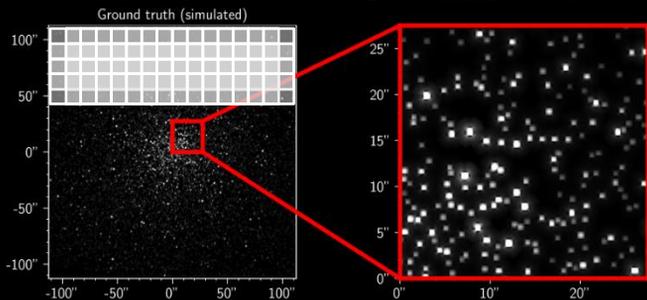
6s sliding average



inferred from 6s window

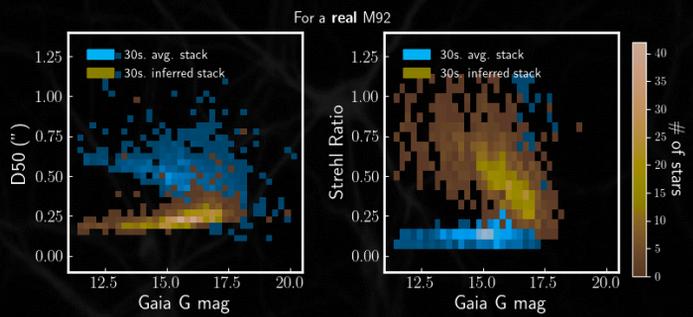
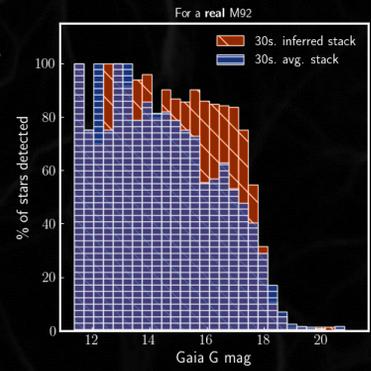


Real data



Sliding Hann window
(Pielawski & Wählby 2020)

PRELIMINARY



Lessons learned

- High cadence (video) imaging carries a lot of potential for wide-field imaging
 - Hardware performance steadily improving
 - Data storage still an issue
- A forward modeling approach with deep learning appears to be a viable solution to mitigate the effects of atmospheric turbulence
 - Already beneficial in crowded star fields
 - More generative models?
 - Extend angular and temporal reach
 - External priors?
 - Manage transient artifacts
 - Atmospheric turbulence tomography?
- Combine with GLAO?

Conclusion

- High cadence (video) imaging has the potential to solve a number of issues in astronomical wide-field imaging
- “Classical” Deep Learning models such as U-Nets already have the ability to tackle wide-field imaging problems that involve the time dimension
 - E.g., tiled image sequences
 - Performance may be limited by the angular and temporal reach of the neural network inputs
 - Can be used on a large variety of data without transfer learning
 - Forward modeling is key: knowledge of the physical and instrumental processes
 - GPUs required to reach the required data rate
 - It can be advantageous to integrate the forward modeling process directly within the ML framework
 - Generate samples on the fly
 - Benefit from batch processing, GPU acceleration and JIT compilation of Python code
 - ML frameworks integrate nicely in existing (Python) pipelines and mature enough to be used in production
 - Uncertainties can be modelled by sampling the posterior distribution (at least approximately)
 - Still computationally prohibitive in most cases
- Visualization critical for qualitative assessment of performance
 - Must be interactive and remote-capable

Thank you

Extra slides

Comparison with blind deconvolution

