



ID de Contribution: 11

Type: Non spécifié

## Improving photo-z with FORS2 data

*mercredi 13 décembre 2023 17:20 (20 minutes)*

In the interest of improving photo-z estimation with template fitting methods, data from observations with FORS2 has been used to generate templates to be used in LEPHARE-like code. An in-house estimator enables access to the whole posterior distribution of redshift and aims to help us understand how to generate / select the best templates, and how to extract the closest point-estimate to the true redshift.

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**Classification de Session:** Science talks