Recent progress of the long-wave infrared instrument for atmosphere monitoring within the StarDICE experiment

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- 1. Why using an infrared thermal camera?
- 2. Goals
- 3. Radiometric calibration
- 4. Overview of first observations

Definitions and notations

- **LWIR :** Long-Wave Infrared band ~ 7 14 μ m
- Radiance : radiant flux emitted, reflected, transmitted, or received by a surface, per unit solid angle per unit projected area = L in W/m²/sr
- **Spatial noise :** standard deviation of a single complete image
- **Temporal noise :** standard deviation of a single pixel value on consecutive images for a supposed constant scene radiance
- **Cloud optical depth τ** : measure of the attenuation of light due to cloud particles along a given path
- **Radiometric** ⇒ LWIR thermal camera (sky measurements)
- **Photometric** ⇒ UV-VIS-NIR w/ CCD camera (stars measurements)

1. Why using an infrared thermal camera ?

• 1.1 "Gray" extinction as a limiting systematic

$$F_{SD} = \int_{\lambda} S_{\star}(\lambda) \times R_{SD}(\lambda) \times \overline{T_{atm}(\lambda)} \times t_{exp,SD} \times A_{mirror,SD} \times \frac{\lambda d\lambda}{hc}$$

$$T^{atm}(alt,az,t;\lambda) = \overline{T_{gray}} e^{-z(alt) \cdot \tau_{aerosol}(alt,az,t;\lambda)}$$

$$\times (1.0 - C_{mol}(BP(t)/BP_0)A_{mols}(z(alt);\lambda))$$

$$\times (1.0 - \sqrt{C_{mol}BP(t)}/BP_0A_{mola}(z(alt);\lambda))$$

$$\times (1.0 - C_{M_2O}(alt,az,t)A_{H_2O}(z(alt);\lambda)).$$

- Empirical wavelength-independent "gray" normalization T_{gray} is fitted for each observation (Burke et al. 2010) → insufficient as calibration is limited by a rapidly changing conditions with moving and evolving cloud cover
- Given by spectra + local measurements + radiative transfer simulations

Encyclopedia of the clouds? 2555-0950] Environment What's happ

• 1.2 What is causing "gray" extinction ?

Ice crystals and water droplets in clouds :

- Produce shadows that appear as "gray" in UV-VIS-NIR (independent of wavelength) ⇒
 decrease in atmosphere transmission ⇒ decrease in stellar source flux
- Produce thermal emission ⇒ increase in radiance / brightness temperature



I.3 Effect on UV-VIS-NIR photometry and LWIR radiance

→ Measuring the sky radiance in LWIR band appears as a potential solution



I.4 Description of the instrument

- 640 x 512 pixels <u>uncooled</u> <u>microbolometers</u> focal plane array
- Large FOV = 10.4 x 8.3 deg
- 8.33 Hz imaging rate \Rightarrow ~ 80 GB/night
- Radiometrically calibrated radiance images in radiances W/m²/sr





Does definitely not work like a photon counting sensor !

I.5 Infrared instrument installed @ OHP





2. Goals

2.1 Short-term goal(s)

- Identify spectro/-photometric exposures affected by gray extinction / clouds
 - → classification, cloud structure detection / image segmentation
 - → flag them and remove them from the analysis

Infrared Radiometric Image Classification and Segmentation of Cloud Structure Using Deep-learning Framework for Ground-based Infrared Thermal Camera Observations

K. Sommer, <u>W. Kabalan</u>, R. Brunet *In prep.*

Atmosphere Measurement Techniques, European Geosciences Union (AMT Copernicus)



Ground-based

infrared image

Binary classifier

Input

2.2 Long-term goal(s)

• Correct photometry for spurious variations

 \rightarrow find a method to produce the quantitative metric T_{gray}

→ comparisons with simulations: sky background radiance removal to derive the gray extinction component

→ joint-analysis with other data: observed spectrum, lidar, AERONET to fit the atmosphere



Calibrated Radiance W m⁻² sr⁻¹ Residual Radiance





OD >> 3 OD > 3 OD < 3 OD < 1 Clear

Cloud Optical Depth

Source: Nugent et al. 2009



Discrepancy: calibration ? simulation ? both ? → work in progress

3. Radiometric calibration

3.1 Motivation

• Why calibrating the camera ?

- Correct for camera gain and offset drifts
- Compare nights between each other
- Compare to simulations of sky radiance to evaluate the background level (e.g. libRadTran radiative transfer code)



3.2 Method

• How?

- Acquire data with a controlled thermal source (e.g. blackbody surface with known temperature and emissivity)
- Put the camera at different ambient temperatures inside a controlled area
- $\circ~$ Fit a set of calibration parameters θ of the model L_{model} on the expected scene radiance L_{scene}

$$-2ln(\mathcal{L}) = \chi^2 = [L_{scene} - L_{mod}(\theta)]^T \cdot C^{-1} \cdot [L_{scene} - L_{mod}(\theta)]$$
$$L_{scene} = \epsilon_{BB} \times L_{BB} + (1 - \epsilon_{BB}) \times L_{AMB}$$
$$L_{mod} \equiv f(\theta, S, T_{FPA})$$

1 set of fitted parameters θ per pixel \Rightarrow 327,680 regressions

• 3.3 Experiments @ IJC-Lab

With Sylvie Dagoret-Campagne and Marc Moniez in December 2022

Control-command Climatic chamber setup for ATLAS ITK experiment

+300k images for multiple camera and low blackbody temperature setpoints





3.4 Preliminary results

Pixel temporal noise = \pm 0.067 (stat.) \pm 0.042 (syst.) $\Rightarrow \pm$ 0.080 (total) W/m²/sr

* Best calibration found in the literature : \pm 0.36 W/m²/sr (Nugent, 2008, PhD)







4. Overview of first observations

4.1 Quick look : a lot of things happen in 4h of imaging...



• 4.2 Night movie animation



https://drive.google.com/fi le/d/1ddrEleWxekYS38Ot JoGE9FtJotc97m1M/view ?usp=sharing

4.3 Pre-processing for DR0 (1/2)

- For each *ugrizG* exposure
 ⇒ N_{obs} infrared images
- Difficult to process all the individual images for analysis
- Statistics : spatial & temporal mean + std of the complete image and the StarDICE FOV
- For now :
 - ~ 80 GB to process per night
 - ~ 1 hours of processing per night on 40-cores server



4.3 Pre-processing for DR0 (2/2)

\rightarrow Image / cloud structure evolution with time is key



4.4 Preliminary analysis on BD+28 4111 for one night (1/2)



4.4 Preliminary analysis on BD+28 4111 for one night (2/2)

-12.25

-12.00

-11.75

-11.50

-11.25

DATE-OBS = 2023_09_11 | N_{exp} = 109 | Filter = g | Airmass = 1.037 ± 0.002

Linear ODR fit

g-band data

= 0.613 ± 0.011

 $\beta = -21.817 \pm 0.189$

- Strong correlation between magnitude and radiance
- Linear dependence as a first approximation:

$$m_i = \alpha \times L_{i,*} + \beta$$

instrumental magnitude [mag] -11.00With current -28 4211 -10.75uncertainty -10.50estimation (stat.+syst.) per pixel -10.25from calibration : 15.5 17.5 15.0 16.0 16.5 17.0 18.0 18.5 19.0 Mean radiance of StarDICE FOV $[W.m^{-2}.sr^{-1}]$

$$\sigma(m_i) = \alpha \times \sigma(L_{i,*}) \approx 0.043 \,\mathrm{mag}$$

19.5

Lower is dimmer

Next steps

• Software:

- Complete the final stages of automating the pre-processing pipeline.
- Anticipate an increase of data flux.
- Correct for some issues regarding the control-command of the dome position affecting IR images + post-processing
- Calibration :
 - Finalize the calibration data analysis \rightarrow publication
- Analysis :
 - Thorough IR and photometry analysis → robust metric for gray extinction.
 - Comparisons with libradtran simulations.
 - Combination of IR and UV-VIS-NIR data for atmosphere fitting.
 - Collaborate with OHP for atmosphere data leveraging lidar, AERONET, and more.



Summary

- Datasets from StarDICE pre-survey first nights look promising
 - Already +940k images ~ 750 GB
 - \circ ~ 10 nights
- Remote observations of IR instrument @ OHP
- Excellent SNR → low spatial and temporal noise on calibrated images
- Linear dependence between star flux magnitude and IR radiance is confirmed