

Introduction :

Compilation

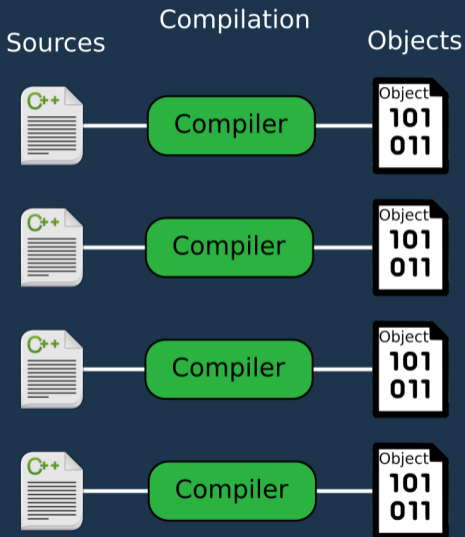
Pierre Aubert



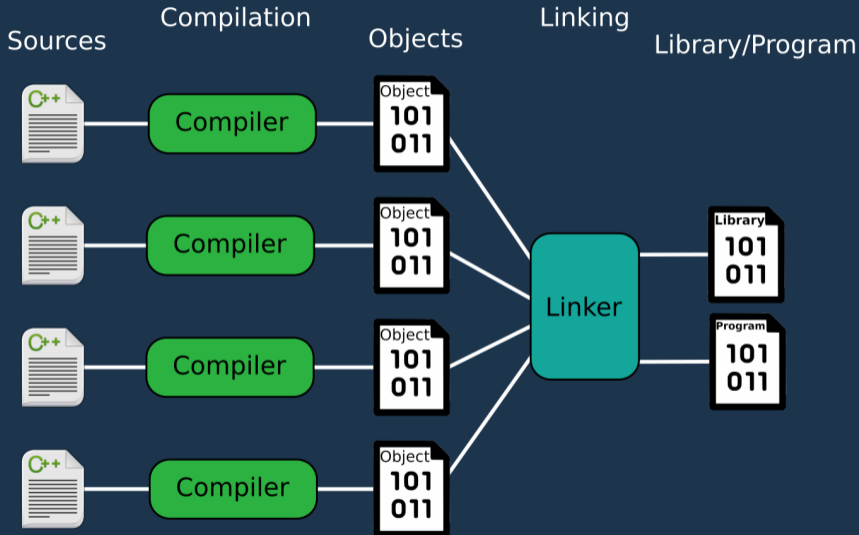
Sources



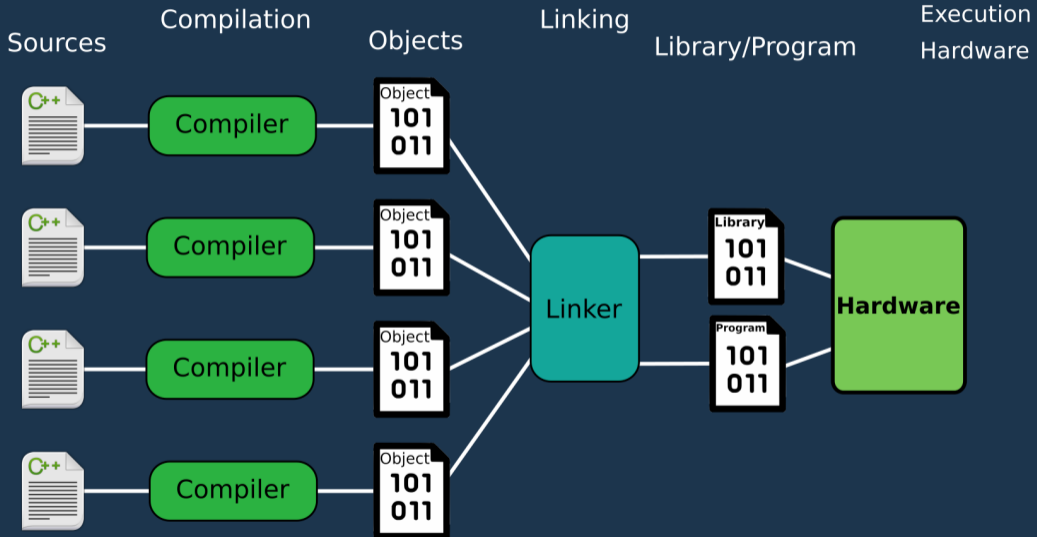
Compilation : From Text to Binary



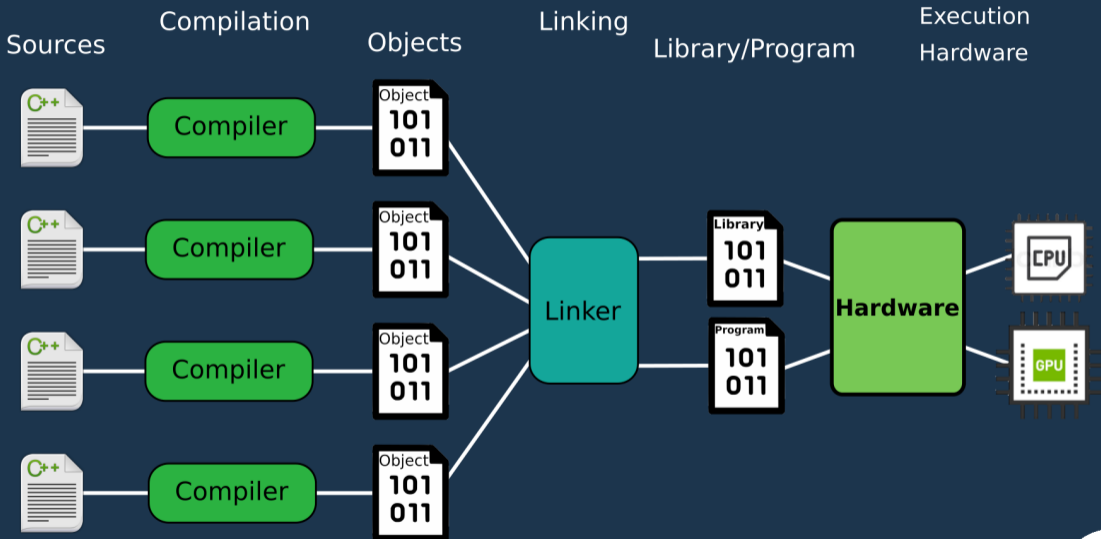
Compilation : From Text to Binary



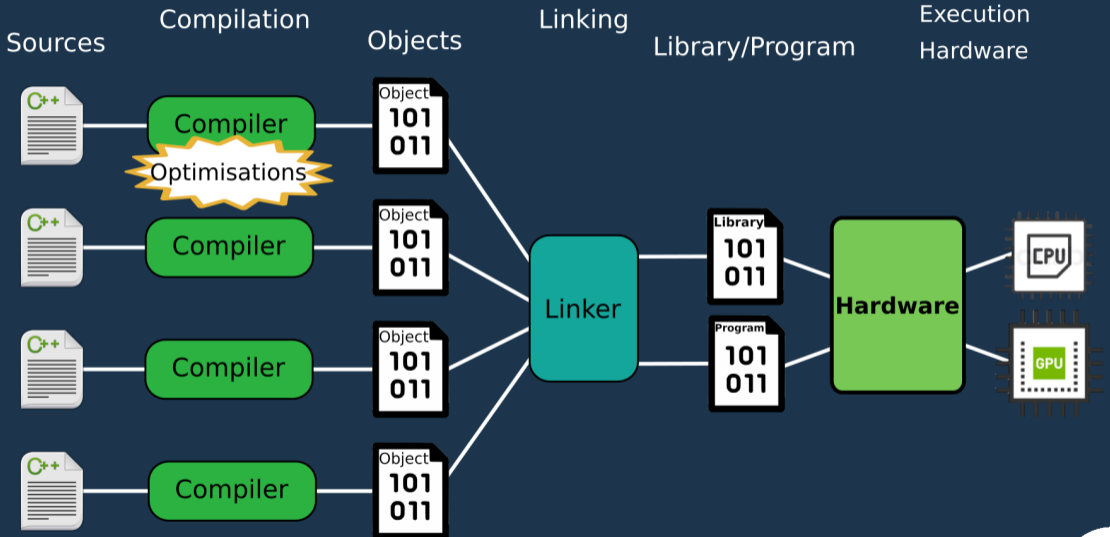
Compilation : From Text to Binary



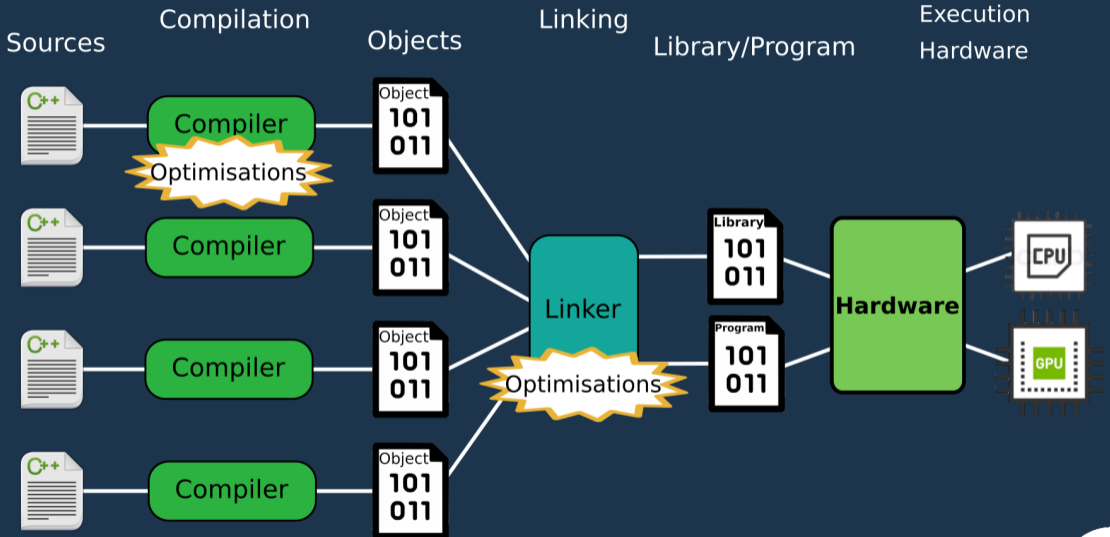
Compilation : From Text to Binary



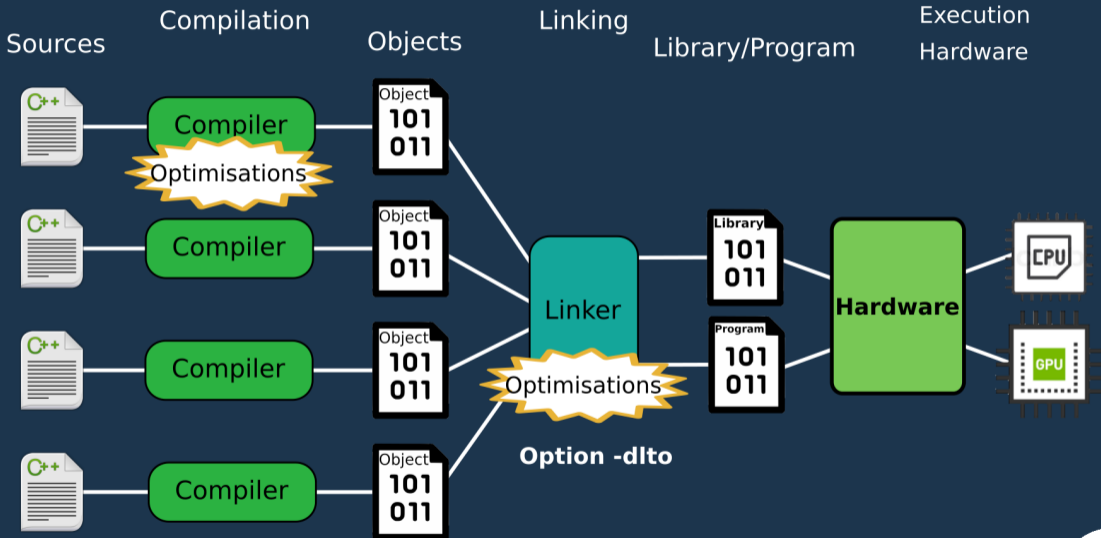
Compilation : From Text to Binary



Compilation : From Text to Binary



Compilation : From Text to Binary



Languages



Fortran

Languages



Fortran

Binaries



Languages



Compiler workflow

Languages



Front-End



Front-End

Fortran

Front-End

Middle-End

Intermediate
Representation

Binaries

Library

101
011

Program

101
011

Compiler workflow

Languages



Front-End



Front-End

Fortran

Front-End

Middle-End

Remove Comments

Intermediate Representation

Binaries

Library

101
011

Program

101
011

Compiler workflow

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Front-End



Front-End

Fortran

Front-End

Middle-End

Remove Comments

Resolve Macros

Intermediate Representation

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Intermediate Representation

Remove Comments

Resolve Macros

Remove Comments

Remove Dead Code

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Compiler workflow

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Front-End



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Fortran

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Intermediate Representation

Remove Comments

Resolve Macros

Remove Comments

Remove Dead Code

Constant Forwarding

Binaries

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Intermediate Representation

Remove Comments

Resolve Macros

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Constant Forwarding

Remove Useless Call

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Intermediate Representation



Binaries



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Intermediate Representation

Remove Comments

Resolve Macros

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Remove Dead Code

Constant Forwarding

Remove Useless Call

Remove Dead Code

Loops Analysis

Binaries

Library

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011

Program

101
011

Compiler workflow

Languages



Front-End



Front-End

Fortran

Front-End

Middle-End

Intermediate Representation

- Remove Comments
- Resolve Macros
- Remove Comments
- Remove Dead Code
- Constant Forwarding
- Remove Useless Call
- Remove Dead Code
- Loops Analysis
- Remove Dead Code

Binaries



Compiler workflow

Languages



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Intermediate Representation



Binaries



Compiler workflow

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Intermediate Representation

- Remove Comments
- Resolve Macros
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- Remove Useless Call



Binaries



Compiler workflow

Languages



Front-End



Front-End

Fortran

Front-End

Middle-End

Intermediate Representation

Binaries

Remove Comments

Resolve Macros

Remove Comments

Remove Dead Code

Constant Forwarding

Remove Useless Call

Remove Dead Code

Loops Analysis

Remove Dead Code

Remove Useless Call



150-300 Steps

Library

101
011

Program

101
011

Compiler workflow

Languages



Front-End



Front-End

Fortran

Front-End

Middle-End

Intermediate Representation

- Remove Comments
- Resolve Macros
- Remove Comments
- Remove Dead Code
- Constant Forwarding
- Remove Useless Call
- Remove Dead Code
- Loops Analysis
- Remove Dead Code
- Remove Useless Call

150-300 Steps

Binaries

Back-End



Back-End



Program

```
float square(float x){  
    return x*x;  
}  
int main(){  
    float y(42.0f);  
    std::cout << square(y) << std::endl;  
    return 0;  
}
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Program

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Graph



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Graph



Update
Program
as needed

Program

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Graph



Add probes

Update
Program
as needed

Program

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Check computing instabilities

Add probes

Update Program as needed

Graph



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Graph



Check computing instabilities

Profiler
- GProf

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Graph



Check computing instabilities

Add probes

Update Program as needed

Profiler
- GProf

Unit Tests
- gcov



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Counters on lines and branches



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Graph



Check computing instabilities

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Counters on lines and branches

Optimisation

- Constant forwarding
- Inlining
- Auto-vectorization
- Auto-parallelization

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Graph



Results have to remain identical

Check computing instabilities

Add probes

Update Program as needed

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Graph



Check computing instabilities

Add probes

Update Program as needed

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Counters on lines and branches

Optimisation

- Constant forwarding
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Results have to remain identical

Need to keep a **similar** graph

Compiler intermediate representation

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Graph



Check computing instabilities

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Counters on lines and branches

Optimisation

- Constant forwarding
- Inlining
- Auto-vectorization
- Auto-parallelization

Results have to remain identical

Need to keep a **similar** graph

Some optimisations are **forbidden** by **Graph Theory**

Compilation options

<https://gcc.gnu.org/onlinedocs/gcc/Optimize-Options.html>

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 - ▶ Try to reduce compilation time, but **-Og** is better for debugging.

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- ▶ **-O2**
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- ▶ **-O3**
 - ▶ More function inlining, loop unrolling, partial vectorization...

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- ▶ **-O0** : default
 - ▶ Try to reduce compilation time, but **-Og** is better for debugging.
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- ▶ **-O2**
 - ▶ Partial function inlining, Assume strict aliasing...
- ▶ **-O3**
 - ▶ More function inlining, loop unrolling, partial vectorization...
- ▶ **-Ofast**
 - ▶ Disregard strict standards compliance. Enable **-ffast-math**, stack size is hardcoded to 32 768 bytes (borrowed from **gfortran**).
Possibly degrades the computation accuracy.


```
float square(float x){  
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}
```

↓
Constant forwarding

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```


Examples

Function inlining

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float square(float x){  
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}  
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Constant forwarding

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Function inlining

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int main(){  
»     std::cout << 42.0f*42.0f << std::endl;  
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Constant expression solving

```
int main(){  
»     std::cout << 1764.0f << std::endl;  
»     return 0;  
}
```

Examples

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Constant expression solving

```
int main(){
>>     std::cout << 1764.0f << std::endl;
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}
```

No more :

- **Function call**
- **Multiplication**
- **Variable declaration**

Loop Unrolling

Loop Unrolling

```
void hadamard(float* tabRes, const float * tabX, const float * tabY, size_t nbElement){  
    >>     for(size_t i(0lu); i < nbElement; ++i){  
    >>         >>         tabRes[i] = tabX[i]*tabY[i];  
    >>     }  
}
```

Base

Loop Unrolling

```
void hadamard(float* tabRes, const float * tabX, const float * tabY, size_t nbElement){  
    >>     for(size_t i(0lu); i < nbElement; ++i){  
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    >>     }  
}
```

Base

```
void hadamard(float* tabRes, const float * tabX, const float * tabY, size_t nbElement){  
    >>     for(size_t i(0lu); i < nbElement; i += 2lu){  
    >>         >>         tabRes[i] = tabX[i]*tabY[i];  
    >>         >>         tabRes[i + 1] = tabX[i + 1]*tabY[i + 1];  
    >>     }  
}
```

Loop unrolled 2 times

Loop Unrolling

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    >>     }  
}
```

Increase Computing in Iteration

Loop unrolled 2 times

Loop Unrolling

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        tabRes[i] = tabX[i]*tabY[i];
        tabRes[i + 1] = tabX[i + 1]*tabY[i + 1];
    }
}
```

Increase Computing in Iteration
Loop unrolled 2 times

```
void hadamard(float* tabRes, const float * tabX, const float * tabY, size_t nbElement){
    for(size_t i(0lu); i < nbElement; i += 4lu){
        tabRes[i] = tabX[i]*tabY[i];
        tabRes[i + 1] = tabX[i + 1]*tabY[i + 1];
        tabRes[i + 2] = tabX[i + 2]*tabY[i + 2];
        tabRes[i + 3] = tabX[i + 3]*tabY[i + 3];
    }
}
```

Loop unrolled 4 times

Loop Unrolling

Less end loop check

Less end loop check

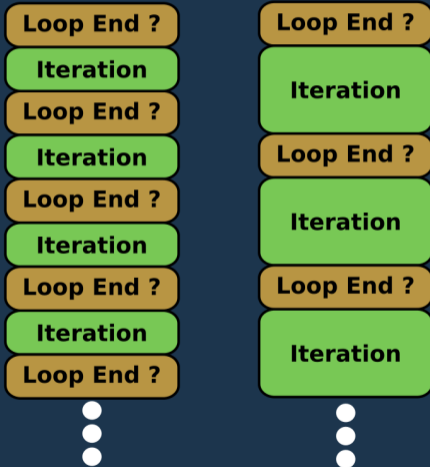
No Loop Unrolling



Loop Unrolling

Less end loop check

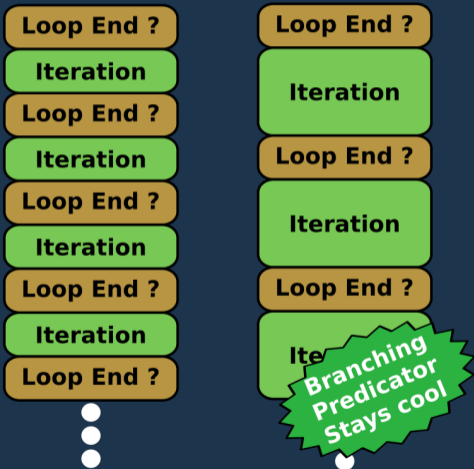
No Loop Unrolling Loop Unrolling 2x



Loop Unrolling

Less end loop check

No Loop Unrolling Loop Unrolling 2x

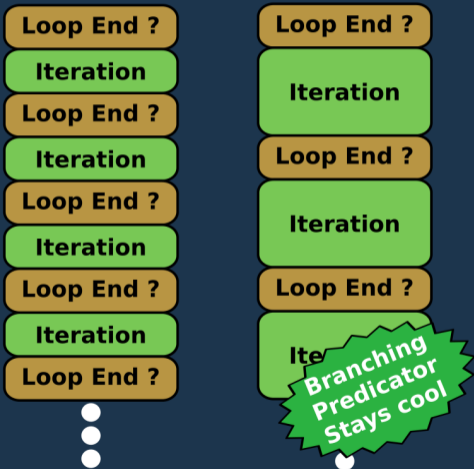


Loop Unrolling

Less end loop check

Load / Computing optimisation

No Loop Unrolling Loop Unrolling 2x



Loop Unrolling

Less end loop check

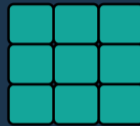
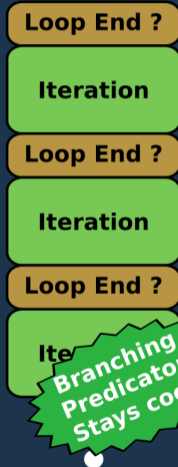
Load / Computing optimisation

No Loop Unrolling

Loop Unrolling 2x

3x3 Kernel Load

No Loop Unrolling



Branching
Predicator
Stays cool

Loop Unrolling

Less end loop check

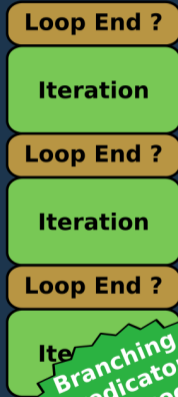
Load / Computing optimisation

No Loop Unrolling

Loop Unrolling 2x

3x3 Kernel Load

No Loop Unrolling



**Branching
Predicator
Stays cool**

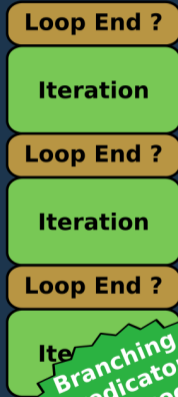


Loop Unrolling

Less end loop check

No Loop Unrolling

Loop Unrolling 2x



Branching
Predicator
Stays cool

Load / Computing optimisation

3x3 Kernel Load



Computing



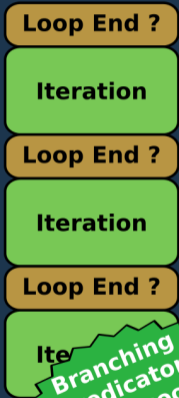
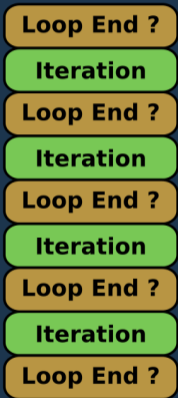
No Loop Unrolling

Loop Unrolling

Less end loop check

No Loop Unrolling

Loop Unrolling 2x



**Branching
Predicator
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Load / Computing optimisation

No Loop Unrolling

3x3 Kernel Load



Computing

Store
Result



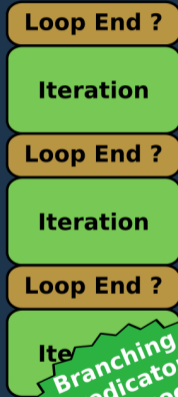
9 loads per store

Loop Unrolling

Less end loop check

No Loop Unrolling

Loop Unrolling 2x



Branching
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Load / Computing optimisation

No Loop Unrolling

3x3 Kernel Load



Computing

Store
Result



9 loads per store

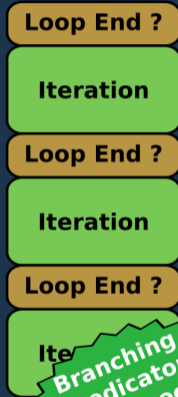
Loop Unrolling 2x

Loop Unrolling

Less end loop check

No Loop Unrolling

Loop Unrolling 2x



Branching
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Load / Computing optimisation

No Loop Unrolling

3x3 Kernel Load



Computing

Store
Result



9 loads per store

Loop Unrolling 2x

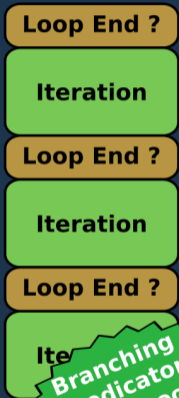


Loop Unrolling

Less end loop check

No Loop Unrolling

Loop Unrolling 2x



Branching
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Load / Computing optimisation

No Loop Unrolling

3x3 Kernel Load



Computing

Store
Result



9 loads per store

Loop Unrolling 2x

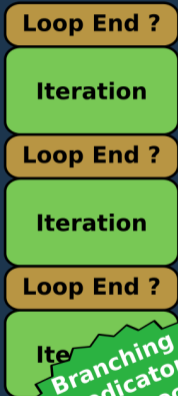


Loop Unrolling

Less end loop check

No Loop Unrolling

Loop Unrolling 2x



Branching
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Stays cool

Load / Computing optimisation

No Loop Unrolling

3x3 Kernel Load



Computing

Store
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9 loads per store

Loop Unrolling 2x



Loop Unrolling

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No Loop Unrolling

Loop Unrolling 2x



Branching
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Load / Computing optimisation

No Loop Unrolling

3x3 Kernel Load



Computing

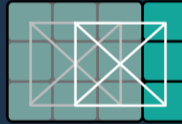
Store
Result



9 loads per store

Loop Unrolling 2x

12 loads, 2 stores



→

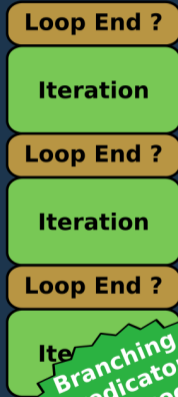


Loop Unrolling

Less end loop check

No Loop Unrolling

Loop Unrolling 2x



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Load / Computing optimisation

No Loop Unrolling

3x3 Kernel Load



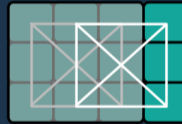
Computing

Store
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9 loads per store

Loop Unrolling 2x



→

12 loads, 2 stores



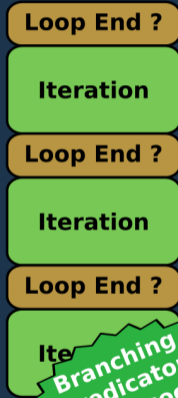
6 loads per store

Loop Unrolling

Less end loop check

No Loop Unrolling

Loop Unrolling 2x



Branching
Predicator
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Load / Computing optimisation

No Loop Unrolling

3x3 Kernel Load



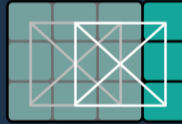
Computing

Store
Result



9 loads per store

Loop Unrolling 2x



12 loads, 2 stores



6 loads per store

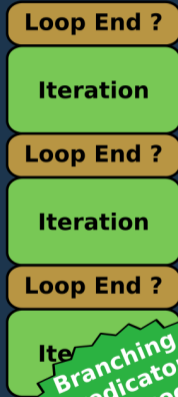
Loop Unrolling 4x

Loop Unrolling

Less end loop check

No Loop Unrolling

Loop Unrolling 2x



Branching
Predicator
Stays cool

Load / Computing optimisation

No Loop Unrolling

3x3 Kernel Load



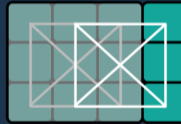
Computing

Store
Result



9 loads per store

Loop Unrolling 2x



Computing

12 loads, 2 stores



6 loads per store

Loop Unrolling 4x

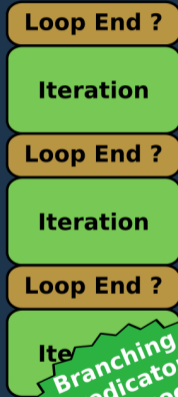


Loop Unrolling

Less end loop check

No Loop Unrolling

Loop Unrolling 2x



Branching
Predicator
Stays cool

Load / Computing optimisation

No Loop Unrolling

3x3 Kernel Load



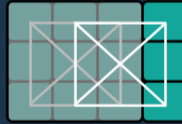
Computing

Store
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Loop Unrolling 4x

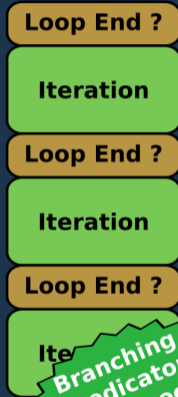


Loop Unrolling

Less end loop check

No Loop Unrolling

Loop Unrolling 2x



Branching
Predicator
Stays cool

Load / Computing optimisation

No Loop Unrolling

3x3 Kernel Load



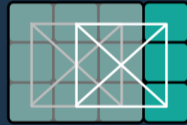
Computing

Store
Result



9 loads per store

Loop Unrolling 2x



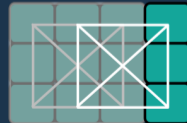
→

12 loads, 2 stores



6 loads per store

Loop Unrolling 4x

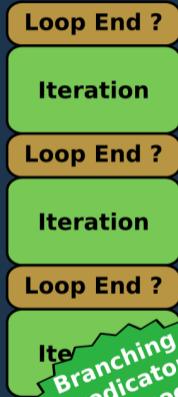


Loop Unrolling

Less end loop check

No Loop Unrolling

Loop Unrolling 2x



Branching
Predicator
Stays cool

Load / Computing optimisation

No Loop Unrolling

3x3 Kernel Load



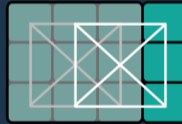
Computing

Store
Result



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Loop Unrolling 4x

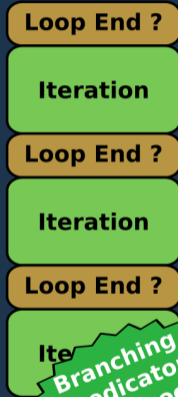


Loop Unrolling

Less end loop check

No Loop Unrolling

Loop Unrolling 2x



Branching
Predicator
Stays cool

Load / Computing optimisation

No Loop Unrolling

3x3 Kernel Load



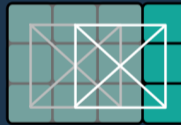
Computing

Store
Result



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Loop Unrolling 2x



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6 loads per store

Loop Unrolling 4x



Loop Unrolling

Less end loop check

No Loop Unrolling

Loop Unrolling 2x



Branching
Predicator
Stays cool

Load / Computing optimisation

No Loop Unrolling

3x3 Kernel Load



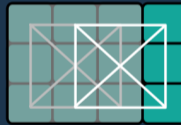
Computing

Store
Result



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Loop Unrolling 2x



Computing

12 loads, 2 stores



6 loads per store

Loop Unrolling 4x

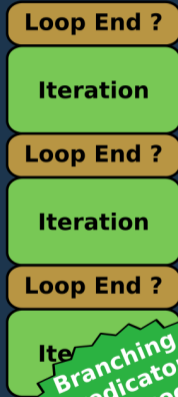


Loop Unrolling

Less end loop check

No Loop Unrolling

Loop Unrolling 2x



Branching
Predicator
Stays cool

Load / Computing optimisation

No Loop Unrolling

3x3 Kernel Load



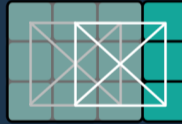
Computing

Store Result



9 loads per store

Loop Unrolling 2x



Computing

12 loads, 2 stores



6 loads per store

Loop Unrolling 4x



Computing

12 loads, 2 stores



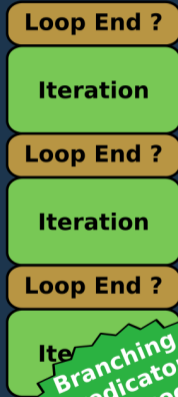
6 loads per store

Loop Unrolling

Less end loop check

No Loop Unrolling

Loop Unrolling 2x



Branching
Predicator
Stays cool

Load / Computing optimisation

No Loop Unrolling

3x3 Kernel Load



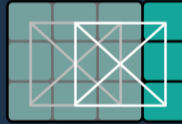
Computing

Store
Result



9 loads per store

Loop Unrolling 2x



12 loads, 2 stores



6 loads per store

Loop Unrolling 4x



18 loads, 4 stores

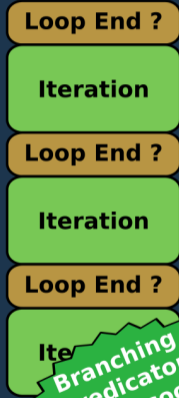
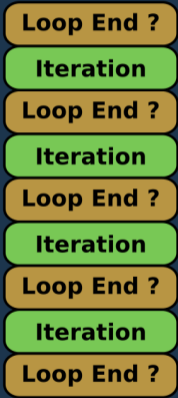


Loop Unrolling

Less end loop check

No Loop Unrolling

Loop Unrolling 2x



Load / Computing optimisation

No Loop Unrolling

3x3 Kernel Load

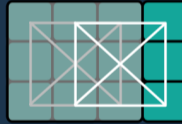


Store Result



9 loads per store

Loop Unrolling 2x



12 loads, 2 stores



6 loads per store

Loop Unrolling 4x



18 loads, 4 stores



4.5 loads per store

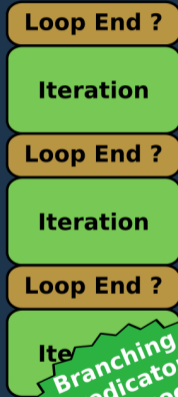
Branching
Predicator
Stays cool

Loop Unrolling

Less end loop check

No Loop Unrolling

Loop Unrolling 2x



Branching
Predicator
Stays cool

Load / Computing optimisation

No Loop Unrolling

3x3 Kernel Load



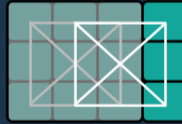
Computing

Store
Result



9 loads per store

Loop Unrolling 2x



12 loads, 2 stores

6 loads per store

Loop Unrolling 4x



18 loads, 4 stores

4.5 loads per store

Then it is a problem of number of available registers

$$a = (b + c) * (b + c)$$

Graph

$$a = (b + c) * (b + c)$$



Graph

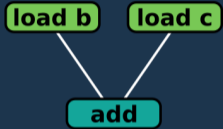
$$a = (b + c) * (b + c)$$

load b

load c

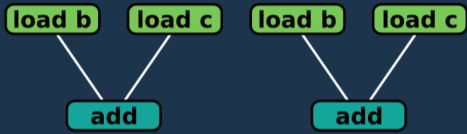
Graph

$$a = (b + c) * (b + c)$$



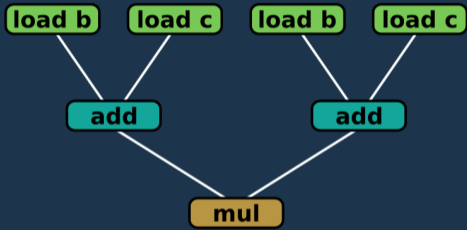
Common subexpression elimination

Graph $a = (b + c) * (b + c)$

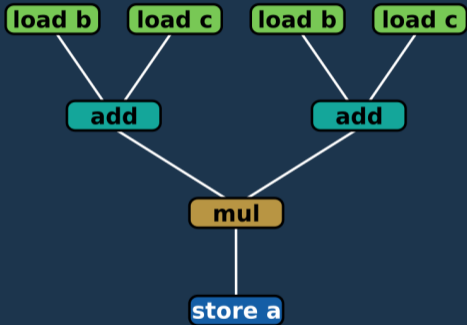


Common subexpression elimination

Graph $a = (b + c) * (b + c)$

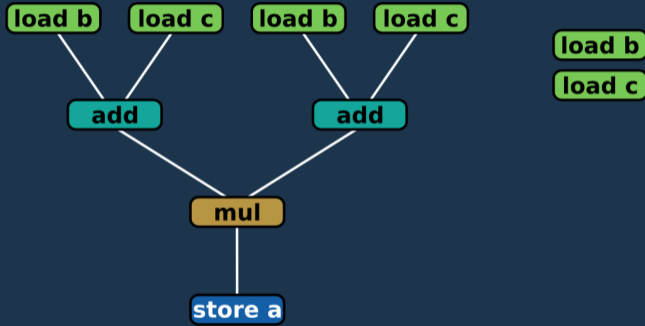


Graph $a = (b + c) * (b + c)$



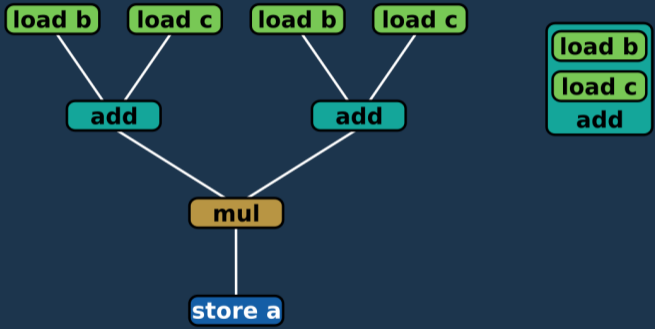
Common subexpression elimination

Graph $a = (b + c) * (b + c)$



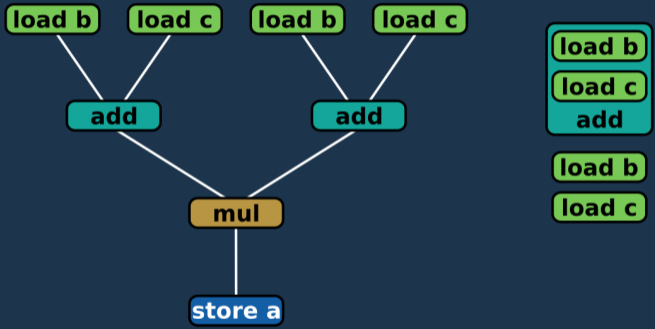
Common subexpression elimination

Graph $a = (b + c) * (b + c)$



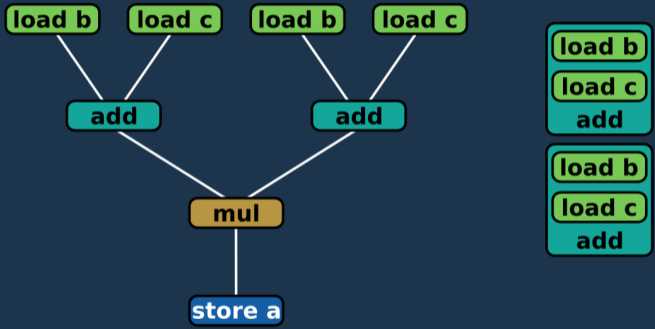
Common subexpression elimination

Graph $a = (b + c) * (b + c)$

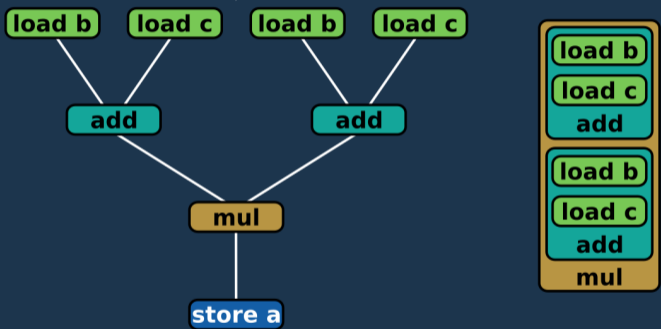


Common subexpression elimination

Graph $a = (b + c) * (b + c)$

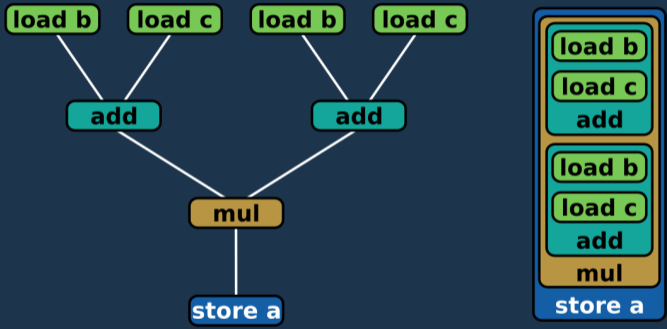


Graph $a = (b + c) * (b + c)$



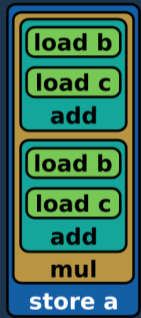
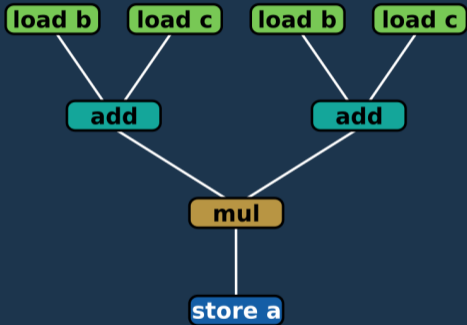
Common subexpression elimination

Graph $a = (b + c) * (b + c)$



Common subexpression elimination

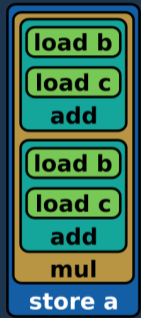
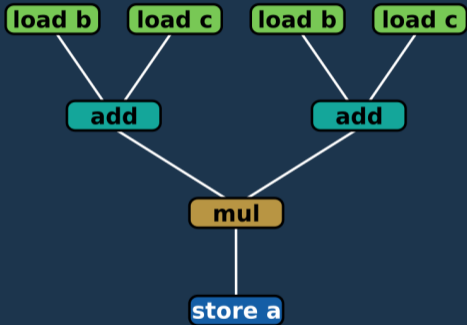
Graph $a = (b + c) * (b + c)$



Too many loads

Common subexpression elimination

Graph $a = (b + c) * (b + c)$

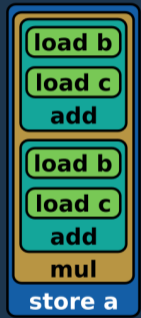
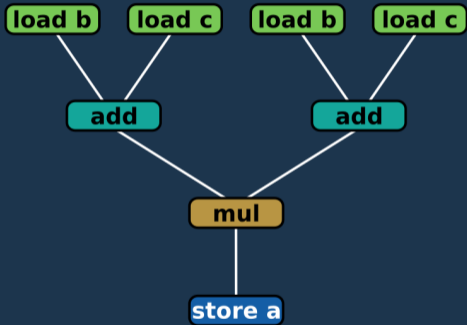


Duplicate Result of add

Too many loads

Common subexpression elimination

Graph $a = (b + c) * (b + c)$



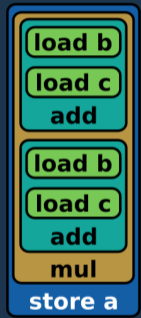
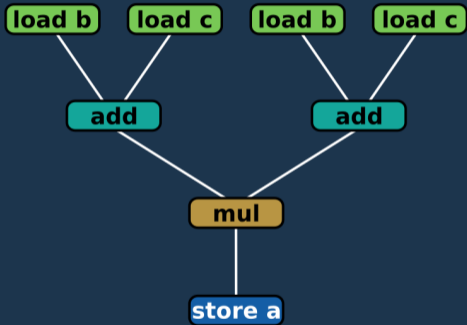
Duplicate Result of add



Too many loads

Common subexpression elimination

Graph $a = (b + c) * (b + c)$



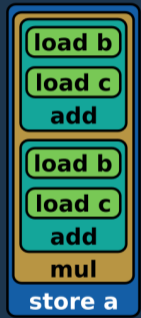
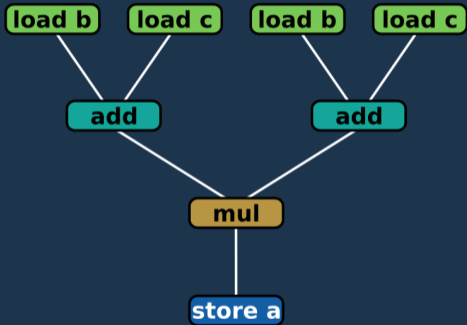
Duplicate Result of add



Too many loads

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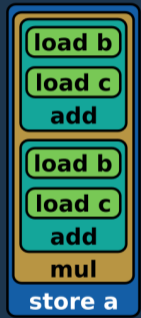
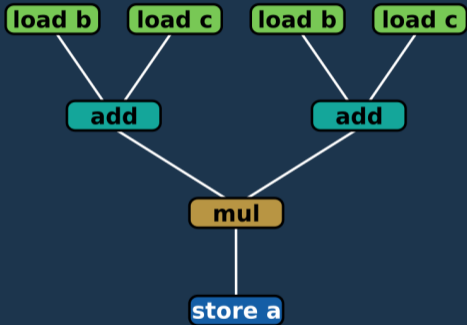
Duplicate Result of add



Too many loads

Common subexpression elimination

Graph $a = (b + c) * (b + c)$



Too many loads

Duplicate Result of add




```
void hadamard_product(float * vecRes, const float * vecX, const float * vecY, size_t nbElement){  
»     for(size_t i(0lu); i < nbElement; ++i){  
»         »     vecRes[i] = vecX[i]*vecY[i];  
»     }  
}
```



```

void evaluateHadamardProduct(size_t nbElement, size_t nbRepetition){
    //On déclare nos tableaux et on les initialise :
    float* vecX = (float*)std::malloc(sizeof(float)*nbElement);
    float* vecY = (float*)std::malloc(sizeof(float)*nbElement);
    float* vecRes = (float*)std::malloc(sizeof(float)*nbElement);

    for(size_t i(0lu); i < nbElement; ++i){
        vecX[i] = i*32lu%17lu;
        vecY[i] = i*57lu%31lu;
    }
    size_t fullNbElement(nbElement*nbRepetition);
    //Stating the timer
    HiPeTime beginTime = phoenix_getTime();
    //Let's call the kernel several times
    for(size_t i(0lu); i < nbRepetition; ++i){
        hadamard_product(vecRes, vecX, vecY, nbElement);
    }
    //Stop the timer
    NanoSecs elapsedTime(phoenix_getTime() - beginTime);
    double ellapsedTimeNs(elapsedTime.count()/((double)nbRepetition));
    double timePerElement = ellapsedTimeNs/((double)nbElement), timeErrorPerElement(0.0), ellapsedTimeErrorNs(0.0);

    std::cout << "Hadamard product naive ptr : nbElement = " << fullNbElement << ", timePerElement = " << timePerElement << " ns/el ± "
    << timeErrorPerElement << ", ellapsedTime = " << ellapsedTimeNs << " ns ± " << ellapsedTimeErrorNs << std::endl;
    std::cerr << nbElement << "\t" << timePerElement << "\t" << ellapsedTimeNs << "\t" << timeErrorPerElement << "\t" <<
    ellapsedTimeErrorNs << std::endl;

    std::free(vecX);
    std::free(vecY);
    std::free(vecRes);
}
    
```

```

void evaluateHadamardProduct(size_t nbElement, size_t nbRepetition){
    //{On déclare nos tableaux et on les initialise :
    float* vecX = (float*)std::malloc(sizeof(float)*nbElement);
    float *vecY = (float*)std::malloc(sizeof(float)*nbElement);
    float *vecRes = (float*)std::malloc(sizeof(float)*nbElement);

    for(size_t i(0lu); i < nbElement; ++i){
        vecX[i] = i*32lu%17lu;
        vecY[i] = i*57lu%31lu;
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    }
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    NanoSecs elapsedTime(phoenix_getTime() - beginTime);
    double ellapsedTimeNs(elapsedTime.count()/((double)nbRepetition));
    double timePerElement = ellapsedTimeNs/((double)nbElement), timeErrorPerElement(0.0), ellapsedTimeErrorNs(0.0);

    std::cout << "Hadamard product naive ptr : nbElement = " << fullNbElement << ", timePerElement = " << timePerElement << " ns/el ± "
    << timeErrorPerElement << ", elapsedTime = " << ellapsedTimeNs << " ns ± " << ellapsedTimeErrorNs << std::endl;
    std::cerr << nbElement << "\t" << timePerElement << "\t" << ellapsedTimeNs << "\t" << timeErrorPerElement << "\t" <<
    ellapsedTimeErrorNs << std::endl;

    std::free(vecX);
    std::free(vecY);
    std::free(vecRes);
}
    
```

Allocation

Implementation

```

void evaluateHadamardProduct(size_t nbElement, size_t nbRepetition){
    //{On déclare nos tableaux et on les initialise :
    float* vecX = (float*)std::malloc(sizeof(float)*nbElement);
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    float* vecRes = (float*)std::malloc(sizeof(float)*nbElement);

    for(size_t i(0lu); i < nbElement; ++i){
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    }
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    }
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    double timePerElement = ellapsedTimeNs/((double)nbElement), timeErrorPerElement(0.0), ellapsedTimeErrorNs(0.0);

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    << timeErrorPerElement << ", elapsedTime = " << ellapsedTimeNs << " ns ± " << ellapsedTimeErrorNs << std::endl;
    std::cerr << nbElement << "\t" << timePerElement << "\t" << ellapsedTimeNs << "\t" << timeErrorPerElement << "\t" <<
    ellapsedTimeErrorNs << std::endl;

    std::free(vecX);
    std::free(vecY);
    std::free(vecRes);
}
    
```

Allocation

Initialisation

Implementation

```

void evaluateHadamardProduct(size_t nbElement, size_t nbRepetition){
    //{On déclare nos tableaux et on les initialise :
    float* vecX = (float*)std::malloc(sizeof(float)*nbElement);
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    for(size_t i(0lu); i < nbElement; ++i){
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        vecY[i] = i*57lu%31lu;
    }
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    //Let's call the kernel several times
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    }
    //Stop the timer
    NanoSecs elapsedTime(phoenix_getTime() - beginTime);
    double ellapsedTimeNs(elapsedTime.count()/((double)nbRepetition));
    double timePerElement = ellapsedTimeNs/((double)nbElement), timeErrorPerElement(0.0), ellapsedTimeErrorNs(0.0);

    std::cout << "Hadamard product naive ptr : nbElement = " << fullNbElement << ", timePerElement = " << timePerElement << " ns/el ± "
    << timeErrorPerElement << ", ellapsedTime = " << ellapsedTimeNs << " ns ± " << ellapsedTimeErrorNs << std::endl;
    std::cerr << nbElement << "\t" << timePerElement << "\t" << ellapsedTimeNs << "\t" << timeErrorPerElement << "\t" <<
    ellapsedTimeErrorNs << std::endl;

    std::free(vecX);
    std::free(vecY);
    std::free(vecRes);
}
    
```

Allocation

Initialisation

Start Chrono

Implementation

```

void evaluateHadamardProduct(size_t nbElement, size_t nbRepetition){
    //On déclare nos tableaux et on les initialise :
    float* vecX = (float*)std::malloc(sizeof(float)*nbElement);
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    for(size_t i(0lu); i < nbElement; ++i){
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    double ellapsedTimeNs(elapsedTime.count()/((double)nbRepetition));
    double timePerElement = ellapsedTimeNs/((double)nbElement), timeErrorPerElement(0.0), ellapsedTimeErrorNs(0.0);

    std::cout << "Hadamard product naive ptr : nbElement = " << fullNbElement << ", timePerElement = " << timePerElement << " ns/el ± "
    << timeErrorPerElement << ", ellapsedTime = " << ellapsedTimeNs << " ns ± " << ellapsedTimeErrorNs << std::endl;
    std::cerr << nbElement << "\t" << timePerElement << "\t" << ellapsedTimeNs << "\t" << timeErrorPerElement << "\t" <<
    ellapsedTimeErrorNs << std::endl;

    std::free(vecX);
    std::free(vecY);
    std::free(vecRes);
}
    
```

Allocation

Initialisation

Start Chrono

Performance Evaluation

Implementation

```

void evaluateHadamardProduct(size_t nbElement, size_t nbRepetition){
    //On déclare nos tableaux et on les initialise :
    float* vecX = (float*)std::malloc(sizeof(float)*nbElement);
    float* vecY = (float*)std::malloc(sizeof(float)*nbElement);
    float* vecRes = (float*)std::malloc(sizeof(float)*nbElement);

    for(size_t i(0lu); i < nbElement; ++i){
        vecX[i] = i*32lu%17lu;
        vecY[i] = i*57lu%31lu;
    }
    size_t fullNbElement(nbElement*nbRepetition);
    //Starting the timer
    HiPeTime beginTime = phoenix_getTime();
    //Let's call the kernel several times
    for(size_t i(0lu); i < nbRepetition; ++i){
        hadamard_product(vecRes, vecX, vecY, nbElement);
    }
    //Stop the timer
    NanoSecs elapsedTime(phoenix_getTime() - beginTime);
    double ellapsedTimeNs(elapsedTime.count()/((double)nbRepetition));
    double timePerElement = ellapsedTimeNs/((double)nbElement), timeErrorPerElement(0.0), ellapsedTimeErrorNs(0.0);

    std::cout << "Hadamard product naive ptr : nbElement = " << fullNbElement << ", timePerElement = " << timePerElement << " ns/el ± "
    << timeErrorPerElement << ", ellapsedTime = " << ellapsedTimeNs << " ns ± " << ellapsedTimeErrorNs << std::endl;
    std::cerr << nbElement << "\t" << timePerElement << "\t" << ellapsedTimeNs << "\t" << timeErrorPerElement << "\t" <<
    ellapsedTimeErrorNs << std::endl;

    std::free(vecX);
    std::free(vecY);
    std::free(vecRes);
}
    
```

Allocation

Initialisation

Start Chrono

Performance Evaluation

Stop Chrono

Implementation

```

void evaluateHadamardProduct(size_t nbElement, size_t nbRepetition){
    //On déclare nos tableaux et on les initialise :
    float* vecX = (float*)std::malloc(sizeof(float)*nbElement);
    float* vecY = (float*)std::malloc(sizeof(float)*nbElement);
    float* vecRes = (float*)std::malloc(sizeof(float)*nbElement);

    for(size_t i(0lu); i < nbElement; ++i){
        vecX[i] = i*32lu%17lu;
        vecY[i] = i*57lu%31lu;
    }
    size_t fullNbElement(nbElement*nbRepetition);
    //Starting the timer
    HiPeTime beginTime = phoenix_getTime();
    //Let's call the kernel several times
    for(size_t i(0lu); i < nbRepetition; ++i){
        hadamard_product(vecRes, vecX, vecY, nbElement);
    }
    //Stop the timer
    NanoSecs elapsedTime(phoenix_getTime() - beginTime);
    double ellapsedTimeNs(elapsedTime.count()/((double)nbRepetition));
    double timePerElement = ellapsedTimeNs/((double)nbElement), timeErrorPerElement(0.0), ellapsedTimeErrorNs(0.0);

    std::cout << "Hadamard product naive ptr : nbElement = " << fullNbElement << ", timePerElement = " << timePerElement << " ns/el ± "
    << timeErrorPerElement << ", ellapsedTime = " << ellapsedTimeNs << " ns ± " << ellapsedTimeErrorNs << std::endl;
    std::cerr << nbElement << "\t" << timePerElement << "\t" << ellapsedTimeNs << "\t" << timeErrorPerElement << "\t" <<
    ellapsedTimeErrorNs << std::endl;

    std::free(vecX);
    std::free(vecY);
    std::free(vecRes);
}
    
```

Allocation

Initialisation

Start Chrono

Performance Evaluation

Stop Chrono

Time Computation

Implementation

```

void evaluateHadamardProduct(size_t nbElement, size_t nbRepetition){
    //On déclare nos tableaux et on les initialise :
    float* vecX = (float*)std::malloc(sizeof(float)*nbElement);
    float* vecY = (float*)std::malloc(sizeof(float)*nbElement);
    float* vecRes = (float*)std::malloc(sizeof(float)*nbElement);

    for(size_t i(0lu); i < nbElement; ++i){
        vecX[i] = i*32lu%17lu;
        vecY[i] = i*57lu%31lu;
    }
    size_t fullNbElement(nbElement*nbRepetition);
    //Starting the timer
    HiPeTime beginTime = phoenix_getTime();
    //Let's call the kernel several times
    for(size_t i(0lu); i < nbRepetition; ++i){
        hadamard_product(vecRes, vecX, vecY, nbElement);
    }
    //Stop the timer
    NanoSecs elapsedTime(phoenix_getTime() - beginTime);
    double ellapsedTimeNs(elapsedTime.count()/((double)nbRepetition));
    double timePerElement = ellapsedTimeNs/((double)nbElement), timeErrorPerElement(0.0), ellapsedTimeErrorNs(0.0);

    std::cout << "Hadamard product naive ptr : nbElement = " << fullNbElement << ", timePerElement = " << timePerElement << " ns/el ± "
    << timeErrorPerElement << ", ellapsedTime = " << ellapsedTimeNs << " ns ± " << ellapsedTimeErrorNs << std::endl;
    std::cerr << nbElement << "\t" << timePerElement << "\t" << ellapsedTimeNs << "\t" << timeErrorPerElement << "\t" <<
    ellapsedTimeErrorNs << std::endl;

    std::free(vecX);
    std::free(vecY);
    std::free(vecRes);
}
    
```

Allocation

Initialisation

Start Chrono

Performance Evaluation

Stop Chrono

Time Computation

Print Results

Implementation

```

void evaluateHadamardProduct(size_t nbElement, size_t nbRepetition){
    //On déclare nos tableaux et on les initialise :
    float* vecX = (float*)std::malloc(sizeof(float)*nbElement);
    float* vecY = (float*)std::malloc(sizeof(float)*nbElement);
    float* vecRes = (float*)std::malloc(sizeof(float)*nbElement);

    for(size_t i(0lu); i < nbElement; ++i){
        vecX[i] = i*32lu%17lu;
        vecY[i] = i*57lu%31lu;
    }
    size_t fullNbElement(nbElement*nbRepetition);
    //Starting the timer
    HiPeTime beginTime = phoenix_getTime();
    //Let's call the kernel several times
    for(size_t i(0lu); i < nbRepetition; ++i){
        hadamard_product(vecRes, vecX, vecY, nbElement);
    }
    //Stop the timer
    NanoSecs elapsedTime(phoenix_getTime() - beginTime);
    double ellapsedTimeNs(elapsedTime.count()/((double)nbRepetition));
    double timePerElement = ellapsedTimeNs/((double)nbElement), timeErrorPerElement(0.0), ellapsedTimeErrorNs(0.0);

    std::cout << "Hadamard product naive ptr : nbElement = " << fullNbElement << ", timePerElement = " << timePerElement << " ns/el ± "
    << timeErrorPerElement << ", elapsedTime = " << ellapsedTimeNs << " ns ± " << ellapsedTimeErrorNs << std::endl;
    std::cerr << nbElement << "\t" << timePerElement << "\t" << ellapsedTimeNs << "\t" << timeErrorPerElement << "\t" <<
    ellapsedTimeErrorNs << std::endl;

    std::free(vecX);
    std::free(vecY);
    std::free(vecRes);
}
    
```

Allocation

Initialisation

Start Chrono

Performance Evaluation

Stop Chrono

Time Computation

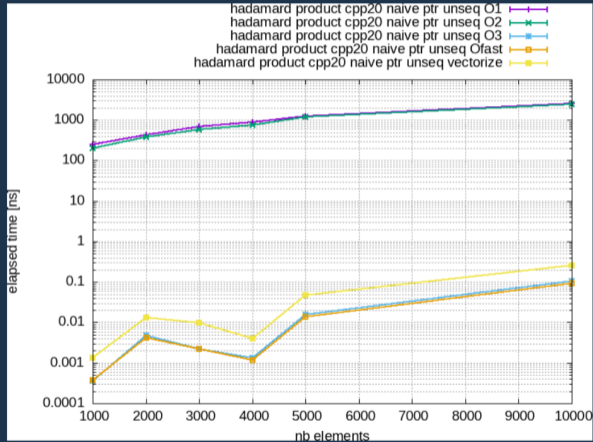
Print Results

Deallocation

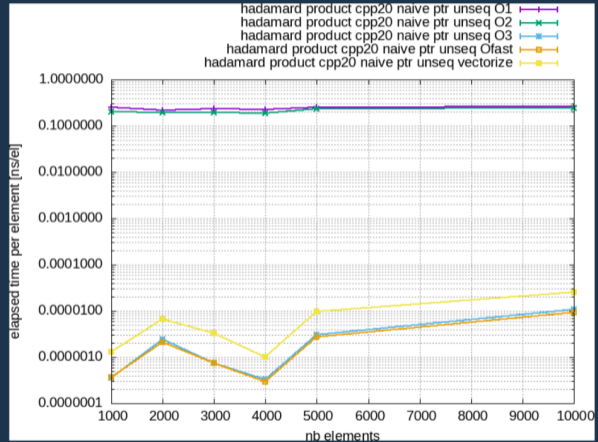
```
int main(int argc, char** argv){  
  » evaluateHadamardProduct(1000lu, 1000000lu);  
  » evaluateHadamardProduct(2000lu, 500000lu);  
  » evaluateHadamardProduct(3000lu, 300000lu);  
  » evaluateHadamardProduct(4000lu, 250000lu);  
  » evaluateHadamardProduct(5000lu, 200000lu);  
  » evaluateHadamardProduct(10000lu, 100000lu);  
  » return 0;  
}
```

Performance G++11

Total time

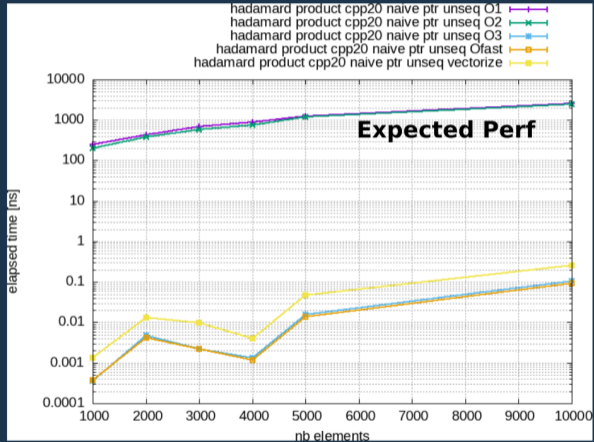


Time per element

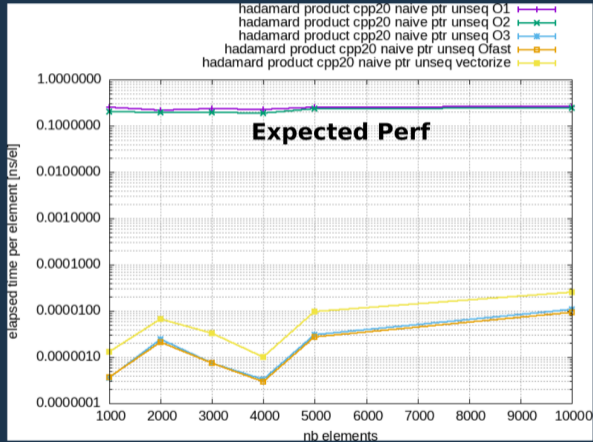


Performance G++11

Total time

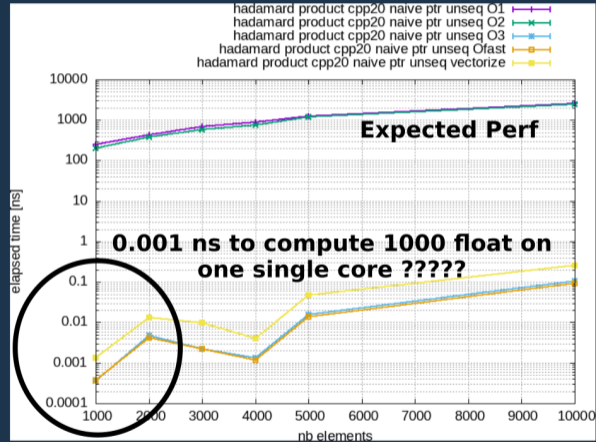


Time per element

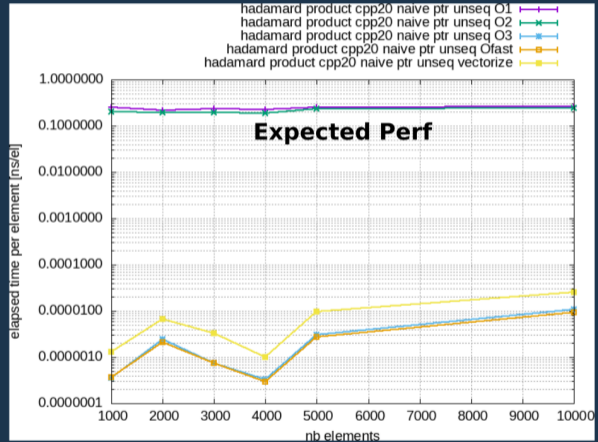


Performance G++11

Total time

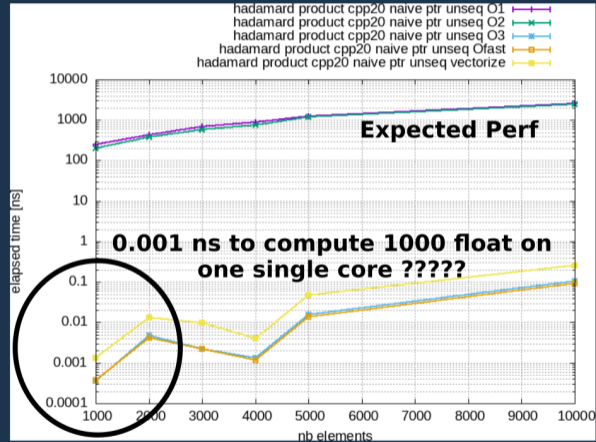


Time per element

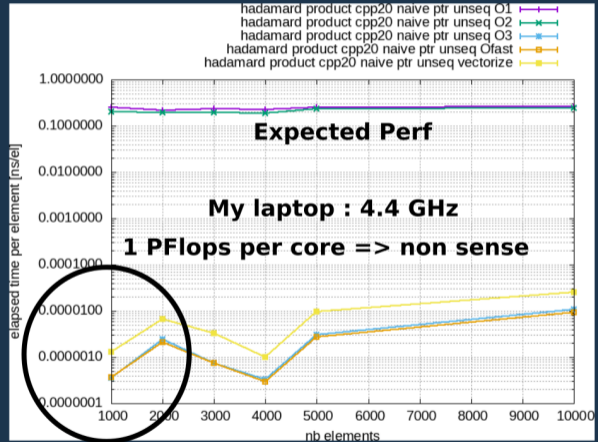


Performance G++11

Total time

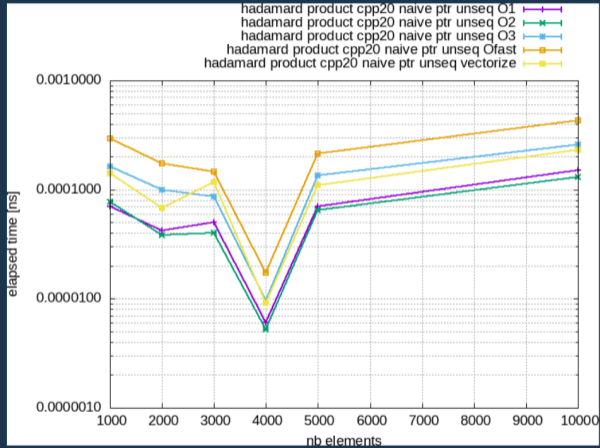


Time per element

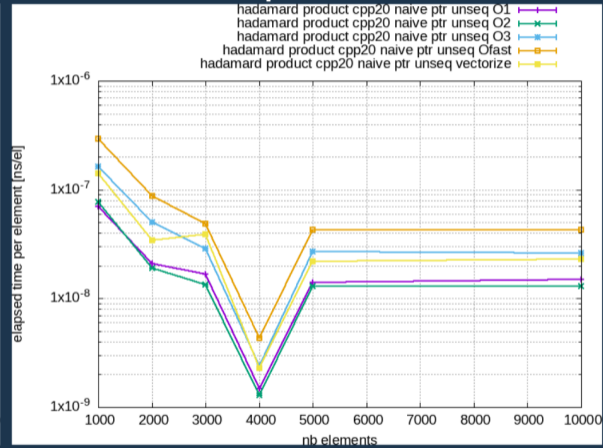


Performance Clang++14

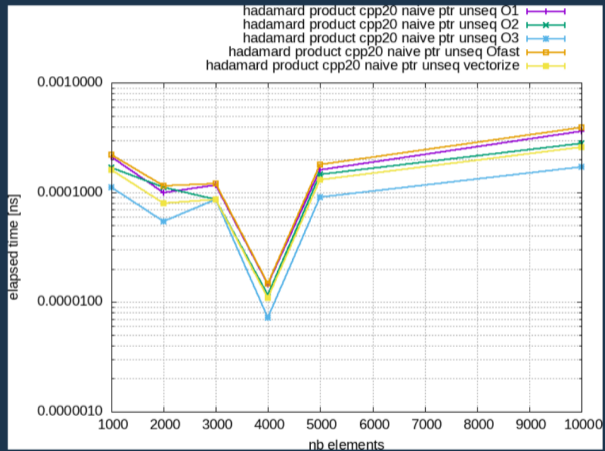
Total time



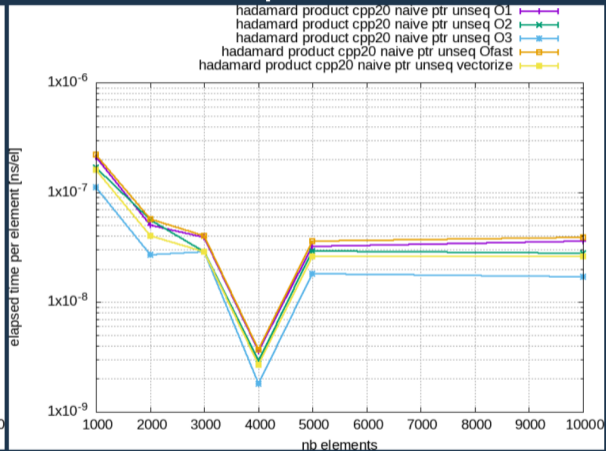
Time per element



Total time



Time per element




```

void evaluateHadamardProduct(size_t nbElement, size_t nbRepetition){
    //On déclare nos tableaux et on les initialise :
    float* vecX = (float*)std::malloc(sizeof(float)*nbElement);
    float* vecY = (float*)std::malloc(sizeof(float)*nbElement);
    float* vecRes = (float*)std::malloc(sizeof(float)*nbElement);

    for(size_t i(0lu); i < nbElement; ++i){
        vecX[i] = i*32lu%17lu;
        vecY[i] = i*57lu%31lu;
    }
    size_t fullNbElement(nbElement*nbRepetition);
    //Stating the timer
    HiPeTime beginTime = phoenix_getTime();
    //Let's call the kernel several times
    for(size_t i(0lu); i < nbRepetition; ++i){
        hadamard_product(vecRes, vecX, vecY, nbElement);
    }
    //Stop the timer
    NanoSecs elapsedTime(phoenix_getTime() - beginTime);
    double ellapsedTimeNs(elapsedTime.count()/((double)nbRepetition));
    double timePerElement = ellapsedTimeNs/((double)nbElement), timeErrorPerElement(0.0), ellapsedTimeErrorNs(0.0);

    std::cout << "Hadamard product naive ptr : nbElement = "<<fullNbElement<<", timePerElement = " << timePerElement << " ns/el ±
    "<<timeErrorPerElement<<", elapsedTime = " << ellapsedTimeNs << " ns ± "<<ellapsedTimeErrorNs << std::endl;
    std::cerr << nbElement << "\t" << timePerElement << "\t" << ellapsedTimeNs << "\t" << timeErrorPerElement << "\t" <<
    ellapsedTimeErrorNs << std::endl;

    std::free(vecX);
    std::free(vecY);
    std::free(vecRes);
}

```

```

void evaluateHadamardProduct(size_t nbElement, size_t nbRepetition){
    //On déclare nos tableaux et on les initialise :
    float* vecX = (float*)std::malloc(sizeof(float)*nbElement);
    float* vecY = (float*)std::malloc(sizeof(float)*nbElement);
    float* vecRes = (float*)std::malloc(sizeof(float)*nbElement);

    for(size_t i(0lu); i < nbElement; ++i){
        vecX[i] = i*32lu%17lu;
        vecY[i] = i*57lu%31lu;
    }
    size_t fullNbElement(nbElement*nbRepetition);
    //Stating the timer
    HiPeTime beginTime = phoenix_getTime();
    //Let's call the kernel several times
    for(size_t i(0lu); i < nbRepetition; ++i){
        hadamard_product(vecRes, vecX, vecY, nbElement);
    }
    //Stop the timer
    NanoSecs elapsedTime(phoenix_getTime() - beginTime);
    double ellapsedTimeNs(elapsedTime.count()/((double)nbRepetition));
    double timePerElement = ellapsedTimeNs/((double)nbElement), timeErrorPerElement(0.0), ellapsedTimeErrorNs(0.0);

    std::cout << "Hadamard product naive ptr : nbElement = " << fullNbElement << ", timePerElement = " << timePerElement << " ns/el ± "
    << timeErrorPerElement << ", ellapsedTime = " << ellapsedTimeNs << " ns ± " << ellapsedTimeErrorNs << std::endl;
    std::cerr << nbElement << "\t" << timePerElement << "\t" << ellapsedTimeNs << "\t" << timeErrorPerElement << "\t" <<
    ellapsedTimeErrorNs << std::endl;

    std::free(vecX);
    std::free(vecY);
    std::free(vecRes);
}
    
```

```

void evaluateHadamardProduct(size_t nbElement, size_t nbRepetition){
    //On déclare nos tableaux et on les initialise :
    float* vecX = (float*)std::malloc(sizeof(float)*nbElement);
    float* vecY = (float*)std::malloc(sizeof(float)*nbElement);
    float* vecRes = (float*)std::malloc(sizeof(float)*nbElement);

    for(size_t i(0lu); i < nbElement; ++i){
        vecX[i] = i*32lu%17lu;
        vecY[i] = i*57lu%31lu;
    }
    size_t fullNbElement(nbElement*nbRepetition);
    //Stating the timer
    HiPeTime beginTime = phoenix_getTime();
    //Let's call the kernel several times
    for(size_t i(0lu); i < nbRepetition; ++i){
        hadamard_product(vecRes, vecX, vecY, nbElement);
    }
    //Stop the timer
    NanoSecs elapsedTime(phoenix_getTime() - beginTime);
    double ellapsedTimeNs(elapsedTime.count()/((double)nbRepetition));
    double timePerElement = ellapsedTimeNs/((double)nbElement), timeErrorPerElement(0.0), ellapsedTimeErrorNs(0.0);

    std::cout << "Hadamard product naive ptr : nbElement = " << fullNbElement << ", timePerElement = " << timePerElement << " ns/el ± "
    << timeErrorPerElement << ", ellapsedTime = " << ellapsedTimeNs << " ns ± " << ellapsedTimeErrorNs << std::endl;
    std::cerr << nbElement << "\t" << timePerElement << "\t" << ellapsedTimeNs << "\t" << timeErrorPerElement << "\t" <<
    ellapsedTimeErrorNs << std::endl;

    std::free(vecX);
    std::free(vecY);
    std::free(vecRes);
}
    
```

**Result of
computation is
not used**

```

void evaluateHadamardProduct(size_t nbElement, size_t nbRepetition){
    //On déclare nos tableaux et on les initialise :
    float* vecX = (float*)std::malloc(sizeof(float)*nbElement);
    float *vecY = (float*)std::malloc(sizeof(float)*nbElement);
    float *vecRes = (float*)std::malloc(sizeof(float)*nbElement);

    for(size_t i(0lu); i < nbElement; ++i){
        vecX[i] = i*32lu%17lu;
        vecY[i] = i*57lu%31lu;
    }
    size_t fullNbElement(nbElement*nbRepetition);
    //Stating the timer
    HiPeTime beginTime = phoenix_getTime();
    //Let's call the kernel several times
    for(size_t i(0lu); i < nbRepetition; ++i){
        hadamard_product(vecRes, vecX, vecY, nbElement);
    }
    //Stop the timer
    NanoSecs elapsedTime(phoenix_getTime() - beginTime);
    double ellapsedTimeNs(elapsedTime.count()/((double)nbRepetition));
    double timePerElement = ellapsedTimeNs/((double)nbElement), timeErrorPerElement(0.0), ellapsedTimeErrorNs(0.0);

    std::cout << "Hadamard product naive ptr : nbElement = " << fullNbElement << ", timePerElement = " << timePerElement << " ns/el ± "
    << timeErrorPerElement << ", elapsedTime = " << ellapsedTimeNs << " ns ± " << ellapsedTimeErrorNs << std::endl;
    std::cerr << nbElement << "\t" << timePerElement << "\t" << ellapsedTimeNs << "\t" << timeErrorPerElement << "\t" <<
    ellapsedTimeErrorNs << std::endl;

    std::free(vecX);
    std::free(vecY);
    std::free(vecRes);
}

```

```

void evaluateHadamardProduct(size_t nbElement, size_t nbRepetition){
    //On déclare nos tableaux et on les initialise :
    float* vecX = (float*)std::malloc(sizeof(float)*nbElement);
    float *vecY = (float*)std::malloc(sizeof(float)*nbElement);
    float *vecRes = (float*)std::malloc(sizeof(float)*nbElement);

    for(size_t i(0lu); i < nbElement; ++i){
        vecX[i] = i*32lu%17lu;
        vecY[i] = i*57lu%31lu;
    }
    size_t fullNbElement(nbElement*nbRepetition);
    //Stating the timer
    HiPeTime beginTime = phoenix_getTime();
    //Let's call the kernel several times
    for(size_t i(0lu); i < nbRepetition; ++i)
        hadamard_product(vecRes, vecX, vecY, nbElement,
    }
    //Stop the timer
    NanoSecs elapsedTime(phoenix_getTime() - beginTime);
    double ellapsedTimeNs(elapsedTime.count()/((double)nbRepetition));
    double timePerElement = ellapsedTimeNs/((double)nbElement), timeErrorPerElement(0.0), ellapsedTimeErrorNs(0.0);

    std::cout << "Hadamard product naive ptr : nbElement = " << fullNbElement << ", timePerElement = " << timePerElement << " ns/el ± "
    << timeErrorPerElement << ", ellapsedTime = " << ellapsedTimeNs << " ns ± " << ellapsedTimeErrorNs << std::endl;
    std::cerr << nbElement << "\t" << timePerElement << "\t" << ellapsedTimeNs << "\t" << timeErrorPerElement << "\t" <<
    ellapsedTimeErrorNs << std::endl;

    std::free(vecX);
    std::free(vecY);
    std::free(vecRes);
}
    
```

Useless loop

```

void evaluateHadamardProduct(size_t nbElement, size_t nbRepetition){
    //On déclare nos tableaux et on les initialise :
    float* vecX = (float*)std::malloc(sizeof(float)*nbElement);
    float *vecY = (float*)std::malloc(sizeof(float)*nbElement);
    float *vecRes = (float*)std::malloc(sizeof(float)*nbElement);

    for(size_t i(0lu); i < nbElement; ++i){
        vecX[i] = i*32lu%17lu;
        vecY[i] = i*57lu%31lu;
    }
    size_t fullNbElement(nbElement*nbRepetition);
    //Stating the timer
    HiPeTime beginTime = phoenix_getTime();
    //Let's call the kernel several times
    for(size_t i(0lu); i < nbRepetition; ++i){
        hadamard_product(vecRes, vecX, vecY, nbElement);
    }
    //Stop the timer
    NanoSecs elapsedTime(phoenix_getTime() - beginTime);
    double ellapsedTimeNs(elapsedTime.count()/((double)nbRepetition));
    double timePerElement = ellapsedTimeNs/((double)nbElement), timeErrorPerElement(0.0), ellapsedTimeErrorNs(0.0);

    std::cout << "Hadamard product naive ptr : nbElement = " << fullNbElement << ", timePerElement = " << timePerElement << " ns/el ± "
    << timeErrorPerElement << ", ellapsedTime = " << ellapsedTimeNs << " ns ± " << ellapsedTimeErrorNs << std::endl;
    std::cerr << nbElement << "\t" << timePerElement << "\t" << ellapsedTimeNs << "\t" << timeErrorPerElement << "\t" <<
    ellapsedTimeErrorNs << std::endl;

    std::free(vecX);
    std::free(vecY);
    std::free(vecRes);
}

```

```

void evaluateHadamardProduct(size_t nbElement, size_t nbRepetition){
    //On déclare nos tableaux et on les initialise :
    float* vecX = (float*)std::malloc(sizeof(float)*nbElement);
    float* vecY = (float*)std::malloc(sizeof(float)*nbElement);
    float* vecRes = (float*)std::malloc(sizeof(float)*nbElement);

    for(size_t i(0); i < nbElement; ++i){
        vecX[i] = i*32lu%17lu;
        vecY[i] = i*57lu%31lu;
    }
    size_t fullNbElement(nbElement*nbRepetition);
    //Stating the timer
    HiPeTime beginTime = phoenix_getTime();
    //Let's call the kernel several times
    for(size_t i(0); i < nbRepetition; ++i){
        hadamard_product(vecRes, vecX, vecY, nbElement);
    }
    //Stop the timer
    NanoSecs elapsedTime(phoenix_getTime() - beginTime);
    double ellapsedTimeNs(elapsedTime.count()/((double)nbRepetition));
    double timePerElement = ellapsedTimeNs/((double)nbElement), timeErrorPerElement(0.0), ellapsedTimeErrorNs(0.0);

    std::cout << "Hadamard product naive ptr : nbElement = " << fullNbElement << ", timePerElement = " << timePerElement << " ns/el ± "
    << timeErrorPerElement << ", ellapsedTime = " << ellapsedTimeNs << " ns ± " << ellapsedTimeErrorNs << std::endl;
    std::cerr << nbElement << "\t" << timePerElement << "\t" << ellapsedTimeNs << "\t" << timeErrorPerElement << "\t" <<
    ellapsedTimeErrorNs << std::endl;

    std::free(vecX);
    std::free(vecY);
    std::free(vecRes);
}

```

Variables set but not used

```

void evaluateHadamardProduct(size_t nbElement, size_t nbRepetition){
    //On déclare nos tableaux et on les initialise :
    float* vecX = (float*)std::malloc(sizeof(float)*nbElement);
    float* vecY = (float*)std::malloc(sizeof(float)*nbElement);
    float* vecRes = (float*)std::malloc(sizeof(float)*nbElement);

    for(size_t i(0lu); i < nbElement; ++i){
        vecX[i] = i*22+17;
        vecY[i] = i*57+31;
    }
    size_t fullNbElement(nbElement*nbRepetition);
    //Stating the timer
    HiPeTime beginTime = phoenix_getTime();
    //Let's call the kernel several times
    for(size_t i(0lu); i < nbRepetition; ++i){
        hadamard_product(vecRes, vecX, vecY, nbElement);
    }
    //Stop the timer
    NanoSecs elapsedTime(phoenix_getTime() - beginTime);
    double ellapsedTimeNs(elapsedTime.count()/((double)nbRepetition));
    double timePerElement = ellapsedTimeNs/((double)nbElement), timeErrorPerElement(0.0), ellapsedTimeErrorNs(0.0);

    std::cout << "Hadamard product naive ptr : nbElement = " << fullNbElement << ", timePerElement = " << timePerElement << " ns/el ± "
    << timeErrorPerElement << ", elapsedTime = " << ellapsedTimeNs << " ns ± " << ellapsedTimeErrorNs << std::endl;
    std::cerr << nbElement << "\t" << timePerElement << "\t" << ellapsedTimeNs << "\t" << timeErrorPerElement << "\t" <<
    ellapsedTimeErrorNs << std::endl;

    std::free(vecX);
    std::free(vecY);
    std::free(vecRes);
}

```



```

void evaluateHadamardProduct(size_t nbElement, size_t nbRepetition){
    //On déclare nos tableaux et on les initialise :
    float *vecX = (float *)std::malloc(sizeof(float)*nbElement);
    float *vecY = (float *)std::malloc(sizeof(float)*nbElement);
    float *vecRes = (float *)std::malloc(sizeof(float)*nbElement);

    for(size_t i(0lu); i < nbElement; ++i){
        vecX[i] = i*22+17;
        vecY[i] = i*57+31;
    }
    size_t fullNbElement(nbElement*nbRepetition);
    //Stating the timer
    HiPeTime beginTime = phoenix_getTime();
    //Let's call the kernel several times
    for(size_t i(0lu); i < nbRepetition; ++i){
        hadamard_product(vecRes, vecX, vecY, nbElement);
    }
    //Stop the timer
    NanoSecs elapsedTime(phoenix_getTime() - beginTime);
    double ellapsedTimeNs(elapsedTime.count()/((double)nbRepetition));
    double timePerElement = ellapsedTimeNs/((double)nbElement), timeErrorPerElement(0.0), ellapsedTimeErrorNs(0.0);

    std::cout << "Hadamard product naive ptr : nbElement = " << fullNbElement << ", timePerElement = " << timePerElement << " ns/el ± "
    << timeErrorPerElement << ", ellapsedTime = " << ellapsedTimeNs << " ns ± " << ellapsedTimeErrorNs << std::endl;
    std::cerr << nbElement << "\t" << timePerElement << "\t" << ellapsedTimeNs << "\t" << timeErrorPerElement << "\t" <<
    ellapsedTimeErrorNs << std::endl;

    std::free(vecX);
    std::free(vecY);
    std::free(vecRes);
}
    
```

Useless loop

```

void evaluateHadamardProduct(size_t nbElement, size_t nbRepetition){
    //On déclare nos tableaux et on les initialise :
    float* vecX = (float*)std::malloc(sizeof(float)*nbElement);
    float* vecY = (float*)std::malloc(sizeof(float)*nbElement);
    float* vecRes = (float*)std::malloc(sizeof(float)*nbElement);

    for(size_t i(0); i < nbElement; ++i){
        vecX[i] = 22 + 17i;
        vecY[i] = 57 + 31i;
    }

    size_t fullNbElement(nbElement*nbRepetition);
    //Starting the timer
    HiPeTime beginTime = phoenix_getTime();
    //Let's call the kernel several times
    for(size_t i(0); i < nbRepetition; ++i){
        hadamard_product(vecRes, vecX, vecY, nbElement);
    }

    //Stop the timer
    NanoSecs elapsedTime(phoenix_getTime() - beginTime);
    double ellapsedTimeNs(elapsedTime.count()/((double)nbRepetition));
    double timePerElement = ellapsedTimeNs/((double)nbElement), timeErrorPerElement(0.0), ellapsedTimeErrorNs(0.0);

    std::cout << "Hadamard product naive ptr : nbElement = " << fullNbElement << ", timePerElement = " << timePerElement << " ns/el ± "
    << timeErrorPerElement << ", elapsedTime = " << ellapsedTimeNs << " ns ± " << ellapsedTimeErrorNs << std::endl;
    std::cerr << nbElement << "\t" << timePerElement << "\t" << ellapsedTimeNs << "\t" << timeErrorPerElement << "\t" <<
    ellapsedTimeErrorNs << std::endl;

    std::free(vecX);
    std::free(vecY);
    std::free(vecRes);
}
    
```

```

void evaluateHadamardProduct(size_t nbElement, size_t nbRepetition){
    //On déclare nos tableaux et on les initialise :
    float *vecX = (float *)std::malloc(sizeof(float)*nbElement);
    float *vecY = (float *)std::malloc(sizeof(float)*nbElement);
    float *vecRes = (float *)std::malloc(sizeof(float)*nbElement);

    for(size_t i(0); i < nbElement; ++i){
        vecX[i] = 1.22 + 171;
        vecY[i] = 1.67 + 311;
    }

    size_t fullNbElement(nbElement*nbRepetition);
    //Stating the timer
    HiPeTime beginTime = phoenix_getTime();
    //Let's call the kernel several times
    for(size_t i(0); i < nbRepetition; ++i){
        hadamard_product(vecRes, vecX, vecY, nbElement);
    }

    //Stop the timer
    NanoSecs elapsedTime(phoenix_getTime() - beginTime);
    double ellapsedTimeNs(elapsedTime.count()/((double)nbRepetition));
    double timePerElement = ellapsedTimeNs/((double)nbElement), timeErrorPerElement(0.0), ellapsedTimeErrorNs(0.0);
    std::cout << "Hadamard product naive ptr : nbElement = " << fullNbElement << ", timePerElement = " << timePerElement << " ns/el ± "
    << timeErrorPerElement << ", elapsedTime = " << ellapsedTimeNs << " ns ± " << ellapsedTimeErrorNs << std::endl;
    std::cerr << nbElement << "\t" << timePerElement << "\t" << ellapsedTimeNs << "\t" << timeErrorPerElement << "\t" <<
    ellapsedTimeErrorNs << std::endl;

    std::free(vecX);
    std::free(vecY);
    std::free(vecRes);
}
    
```

Stop next to Start

```

void evaluateHadamardProduct(size_t nbElement, size_t nbRepetition){
    //On déclare nos tableaux et on les initialise :
    float vecX = (float *)std::malloc(sizeof(float)*nbElement);
    float vecY = (float *)std::malloc(sizeof(float)*nbElement);
    float vecRes = (float *)std::malloc(sizeof(float)*nbElement);

    for(size_t i(0); i < nbElement; ++i)
        vecX[i] = i*22+171;
        vecY[i] = i*67+311;

    size_t fullNbElement(nbElement*nbRepetition);
    //Stating the timer
    HiPeTime beginTime = phoenix_getTime();
    //Let's call the kernel several times
    for(size_t i(0); i < nbRepetition; ++i){
        hadamard_product(vecRes, vecX, vecY, nbElement);
    }
    //Stop the timer
    NanoSecs elapsedTime(phoenix_getTime() - beginTime);
    double ellapsedTimeNs(elapsedTime.count()/((double)nbRepetition));
    double timePerElement = ellapsedTimeNs/((double)nbElement), timeErrorPerElement(0.0), ellapsedTimeErrorNs(0.0);
    std::cout << "Hadamard product naive ptr : nbElement = " << fullNbElement << ", timePerElement = " << timePerElement << " ns/el ± "
    << timeErrorPerElement << ", elapsedTime = " << ellapsedTimeNs << " ns ± " << ellapsedTimeErrorNs << std::endl;
    std::cerr << nbElement << "\t" << timePerElement << "\t" << ellapsedTimeNs << "\t" << timeErrorPerElement << "\t" <<
    ellapsedTimeErrorNs << std::endl;

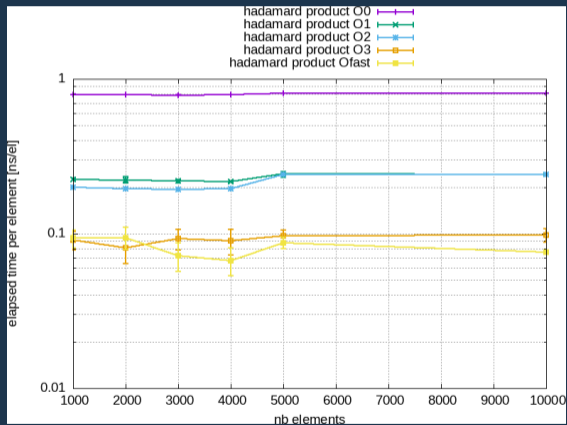
    std::free(vecX);
    std::free(vecY);
    std::free(vecRes);
}
    
```

Stop next to Start

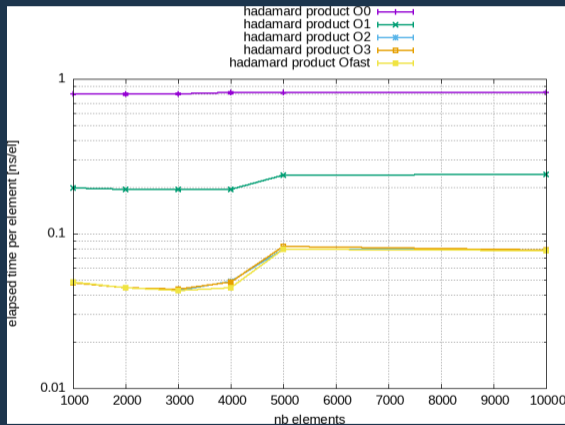
This happens because kernel is in the same file
Avoid problem if the result of the computation is used
No Problem with std::vector

The Hadamard product : Basic Options

G++ 11

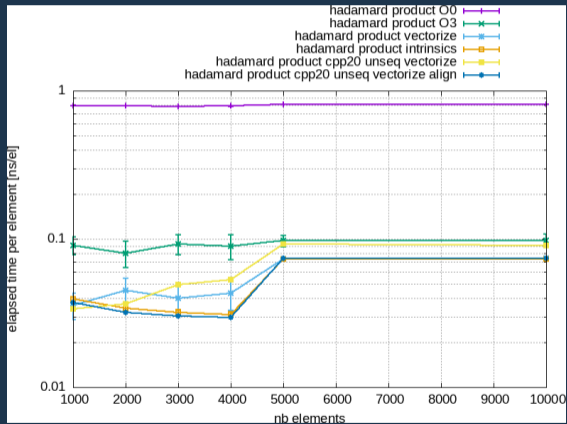


CLang++ 14

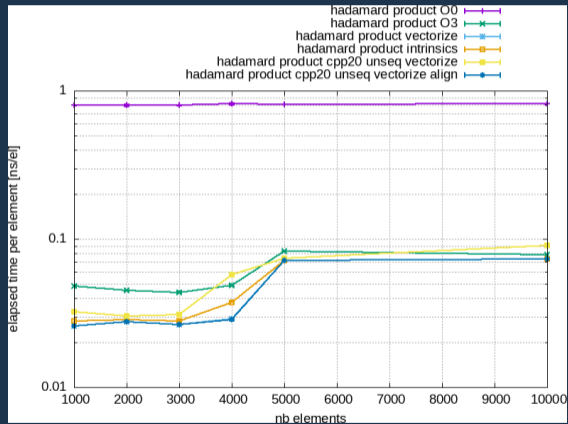


The Hadamard product : Vectorization

G++ 11



CLang++ 14



Performance Test Reminder

Are we measuring what we think we are measuring ?

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Are we measuring what we think we are measuring ?

A performance test evaluates :

Performance Test Reminder

Are we measuring what we think we are measuring ?

A performance test evaluates :

With a given **method**

Performance Test Reminder

Are we measuring what we think we are measuring ?

A performance test evaluates :

With a given **method**

With a more or less **precise chrono**

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More or less **representative** of the problem

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On a **computer**

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Cleverly determined or not

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Compiled

On a **computer**

With a **dataset**

During an **elapsed time**

On an **Operating System**

With a more or less **precise chrono**

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With a more or less **precise chrono**

Of more or less **quality**

More or less **relevant**

With more or less **usefull flags**

More or less **efficient**

With more or less **shared ressources**

More or less **representative** of the problem

Cleverly determined or not

More or less **horrible** to use

Compiler

**Very difficult
to develop**

Compiler



Certification and compilers testing

Very difficult
to develop

Compiler

Certification
Needed



Very difficult
to develop

Compiler

Certification
Needed



CSmith

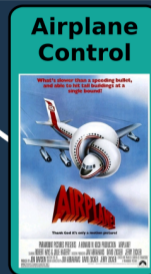
<https://github.com/csmith-project/csmith>

Certification and compilers testing

Very difficult
to develop

Compiler

Certification
Needed

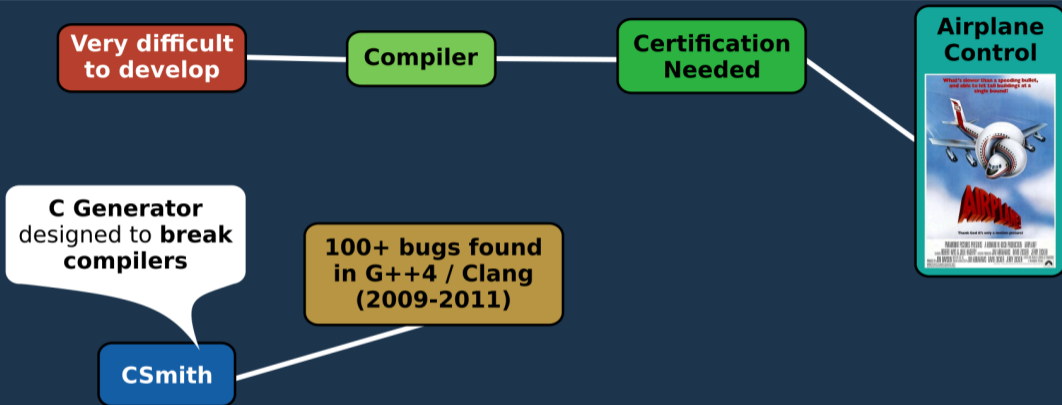


C Generator
designed to **break**
compilers

CSmith

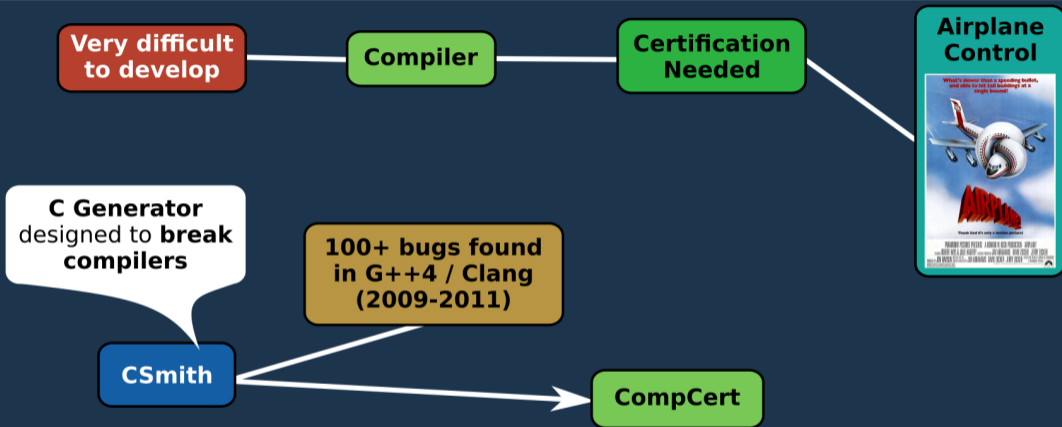
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Certification and compilers testing



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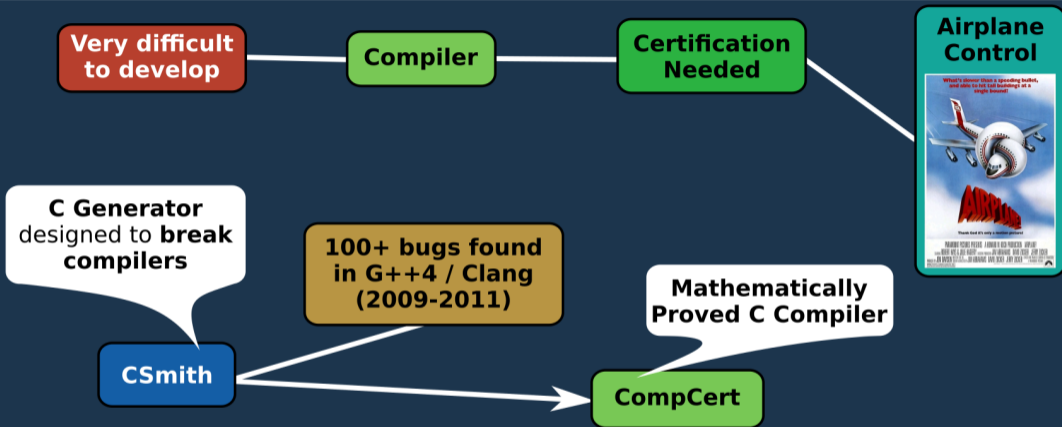
Certification and compilers testing



<https://github.com/csmith-project/csmith>

<https://compcert.org/>

Certification and compilers testing



<https://github.com/csmith-project/csmith>

<https://compcert.org/>

Conclusion



Conclusion



- Use **both** compilers
- Test **compilation options**
- Check with **Maqao** and **Valgrind**
- Check with **Performance Tests (MicroBenchmark)**

