

Kaluza-Klein truncations of gravity to two dimensions

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Based on works with G. Bossard, G. Inverso, A. Kleinschmidt and H. Samtleben

Anly workshop, April 11th 2024

d=2 ?

- d=2 gravity models are usually simpler than in higher-dimensions.

Einstein-Hilbert

$$S_{\text{EH}} \sim \int d^2x \sqrt{-g} R = \text{total derivative}$$

Simplest non-trivial models:
dilaton gravity

$$S \sim \int d^2x \sqrt{-g} [\rho R - V(\rho)]$$

$V(\rho) \propto \rho$: Jackiw-Teitelboim
model

and D=2 is the lowest possible dimension for:

- Riemann curvature
- Black holes
- Boundaries with dynamics

- There are also models which are much harder to study than in higher-dimensions...

For the past years: interested in d=2 (maximal) supergravities.

(in particular, those that arise as Kaluza-Klein truncations of ‘string theory’).

Motivation: holographic duality between string theory on AdS_2 backgrounds
and various supersymmetric matrix quantum mechanics.

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Early works:

D=5: gravity

$$\mathcal{M}_D = \mathcal{M}_d \times S^1$$

—————>

KK truncation

d=4:

gravity
+
Maxwell
+
dilaton

On the Unification Problem in Physics*

from TH. KALUZA[†]
in Königsberg

(Submitted by Mr. Einstein on December 8, 1921; s. above, p. 859.)

In the general theory of relativity, in order to characterize world events, the fundamental metric tensor $g_{\mu\nu}$ of the 4-dimensional world manifold, interpreted as the tensor potential of gravitation must be introduced separately from the electromagnetic four-potential q_μ .

The dualistic nature of gravitation and electricity still remaining here does not actually destroy the ensnaring beauty of either theory but rather affords a new challenge towards their triumph through an entirely unified picture of the world.

Kaluza 1921
Klein 1926

What is meant exactly by consistent Kaluza-Klein truncation...?

Toy model

Scalar field Φ on a D-dimensional spacetime $\mathcal{M}_D = \mathcal{M}_d \times S_1$ with coordinates $X^M = (x^\mu, y)$

Expand on a Fourier basis: $\Phi(x, y) = \sum_{n \in \mathbb{Z}} \phi_n(x) e^{i \frac{n}{R} y}$

circle radius

Dynamics: $\hat{\square} \Phi(x, y) = 0 \quad \rightarrow \quad \square \phi_n(x) - \frac{n^2}{R^2} \phi_n(x) = 0$

$\square + \partial_y^2$

Free massless scalar \rightarrow

$n = 0$: massless mode

$+ n \neq 0$: Infinite tower of massive modes with $m_n = \frac{|n|}{R}$

Consistent Kaluza-Klein truncations: only keep a finite subset of Kaluza-Klein modes that do not source the truncated ones.

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- Always possible on a circle (or torus): truncate all massive modes $\Phi(x, y) = \phi_0(x)$
- $\square \phi_n(x) \neq \phi_0(x)$ independent of the dynamics! (ensured by group theory)

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- Generally possible when internal space is a group manifold G :

Isometry of the internal metric: $\tilde{G} = G_L \times G_R$ — Keep only singlets

DeWitt 1963

Scherk, Schwarz 1979

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Consistent Kaluza-Klein truncations: only keep a finite subset of Kaluza-Klein modes that do not source the truncated ones.

Consistent Kaluza-Klein truncations are **few** and **difficult to construct**. Powerful tools:

- Allow to uplift all solutions of the lower-dimensional theory.
- Useful for holography (sphere truncations of gravity).

KK truncation of gravity on T^q

d-dimensional spacetime | q-dimensional internal space

Consider gravity on a D-dimensional manifold \mathcal{M}_D with coordinates $X^M = (x^\mu, y^m)$

and make the following **gauge choice** for the D-dimensional vielbein:

$$E_M{}^A(x) = \begin{pmatrix} e_\mu{}^\alpha & \rho^{1/q} A_\mu{}^m V_m{}^a \\ 0 & \rho^{1/q} V_m{}^a \end{pmatrix}$$

dilaton | Unimodular matrix
 $\in SL(q)$

- Breaks D-dimensional local Lorentz symmetry

$$SO(D-1, 1) \rightarrow SO(d-1, 1) \times SO(q)$$

d-dimensional Lorentz internal symmetry

- Decomposes into d-dimensional:
vielbein $e_\mu{}^\alpha$ + vectors $A_\mu{}^m$ + scalars $\rho, V_m{}^a$

Fix $\mathcal{M}_D = \mathcal{M}_d \times T^q$ and perform a KK truncation on T^q →

All fields
independent
of y^m

What are the symmetries inherited by the truncated theory?

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D-dimensional diffeomorphisms decompose into:

$$\xi^M(x, y) \xrightarrow{\text{Compatibility with } T^q.}$$

d-dimensional diffeo. :	$\xi^\mu(x, y) = \xi(x)$
internal diffeo. :	$\xi^m(x, y) = L^m(x) + \Lambda_n{}^m y^n + \lambda y^m$
	$ $ $ $ $ $
	$U(1)^q$ gauge parameter constant $SL(q)$ matrix constant rescaling

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Internal diffeomorphisms generate:

- Local abelian symmetry $U(1)^q$ $A_\mu{}^m \rightarrow A_\mu{}^m + \partial_\mu \textcolor{violet}{L}^m(x)$
- Rigid symmetry $R^+ \times SL(q)$ $A_\mu{}^m \rightarrow \lambda^{-1/q} \Lambda_n{}^m A_\mu{}^n$ $\rho \rightarrow \lambda \rho$ $V_m{}^a \rightarrow \Lambda_m{}^n V_n{}^a$

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What about the dynamics?

SL(q)/SO(q) $V_m{}^a \rightarrow V_m{}^b K(x)_b{}^a$
coset space

Dynamics of KK reduced gravity

$$D = d + q$$

Gravity in D=d+q dimensions:

$$S_D = \frac{1}{\kappa_D^2} \int d^D X E R^{(D)}$$



$$S_d = \frac{1}{\kappa_d^2} \int d^d x e \rho [R^{(d)} - \frac{1}{4} \rho^{2/q} (VV^T)_{mn} F_{\mu\nu}^m F^{n\mu\nu} + \frac{q-1}{q} \rho^{-2} \partial_\mu \rho \partial^\mu \rho - \text{tr}(P_\mu P^\mu)]$$

Dynamics in d dimensions:

$$\text{d-dimensional gravity} + U(1)^q \text{ Maxwell} + \text{dilaton} + SL(q)/SO(q) \text{ sigma model}$$

$$F_{\mu\nu}^m = 2 \partial_{[\mu} A_{\nu]}^m$$

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Dynamics in d dimensions:

d-dimensional gravity + **$U(1)^q$ Maxwell** + **dilaton** + **$SL(q)/SO(q)$ sigma model**

$$F_{\mu\nu}^m = 2 \partial_{[\mu} A_{\nu]}^m$$

- Standard kinetic term for the sigma model in terms of the current: $\frac{V^{-1} \partial_\mu V = P_\mu + Q_\mu}{\in \mathfrak{sl}(q)}$

$$\text{tr}(P_\mu P^\mu) = \eta_{\alpha\beta} P_\mu^\alpha P^{\alpha\mu}$$

$\mathfrak{sl}(q)$
Cartan-Killing metric

Invariant under rigid $SL(q)$ and local $SO(q)$ transformations with parameters:

$$\Lambda \in SL(q) \quad K(x) \in SO(q)$$

$$\boxed{\begin{array}{l} V \rightarrow \Lambda V - V K(x) \\ P_\mu \rightarrow K^{-1} P_\mu K \\ Q_\mu \rightarrow K^{-1} \partial_\mu K + K^{-1} Q_\mu K \end{array}}$$

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Rigid symmetry from KK truncation on T^q : $R^+ \times SL(q)$

- ‘Free’ massless theory: *no non-abelian gauge interactions, no scalar potential.*
- Deformations can be obtained from certain KK truncations on compact manifolds.

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 → Deformations can be obtained from certain KK truncations on compact manifolds.
- *Weyl rescaling:* $e_\mu{}^\alpha \rightarrow \rho^{\frac{1}{d-2}} e_\mu{}^\alpha$

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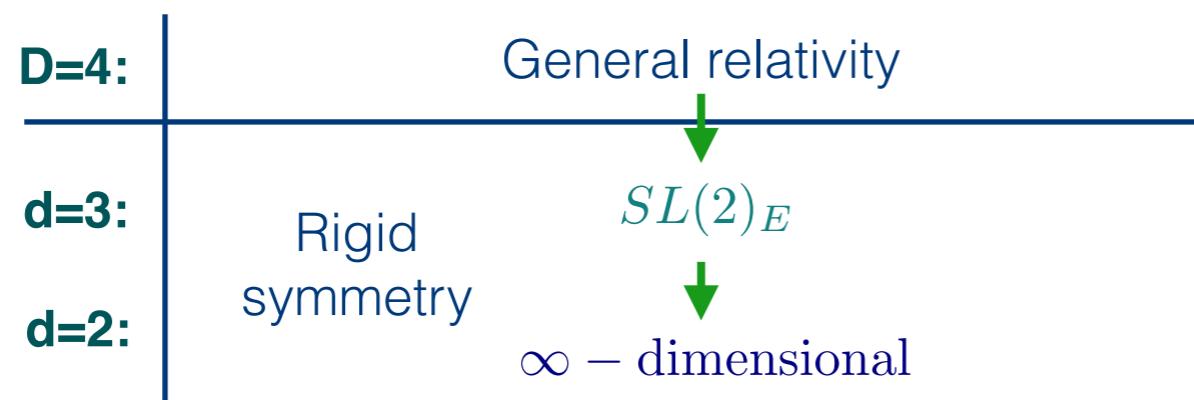
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Rigid symmetry from KK reduction on T^q :

$$R^+ \times SL(q)$$



Ehlers 1956

Geroch 1987



KK reduction of GR to d=3

$$\mathcal{M}_4 = \mathcal{M}_3 \times S^1$$

Coordinates: $X^M = (x^\mu, y)$

Following the procedure described previously, one finds:

$$\begin{array}{ccc}
 S_{\text{EH}}[E] & \xrightarrow{\text{KK truncation}} & S_{d=3} = \int d^3x e [R^{(3)} - \frac{1}{4} \varphi^4 F_{\mu\nu} F^{\mu\nu} - 2 \varphi^{-2} \partial_\mu \varphi \partial^\mu \varphi] \\
 \text{vierbein} & & = \overline{\partial_{[\mu} A_{\nu]}} \\
 E_M{}^A(x) = \begin{pmatrix} e_\mu{}^\alpha & \varphi A_\mu \\ 0 & \varphi \end{pmatrix} & & \\
 & \text{d=3 dilaton} & \\
 & & \text{d=3 gravity} + \text{Maxwell} + \text{dilaton}
 \end{array}$$

In d=3, the vector A_μ can be dualized into a scalar ψ via the duality equation:

$$\boxed{\varphi^4 F^{\mu\nu} = e^{-1} \epsilon^{\mu\nu\rho} \partial_\rho \psi} \quad \leftarrow \text{Integrability/consistency condition given by the vector field equation: } \partial_\mu (e \varphi^4 F^{\mu\nu}) = 0$$

The d=3 action can then be rewritten without the vector field as:

$$S_{d=3} = \int d^3x e [R^{(3)} - \frac{1}{2} \varphi^{-4} \partial_\mu \psi \partial^\mu \psi - 2 \varphi^{-2} \partial_\mu \varphi \partial^\mu \varphi]$$

Rigid symmetries: scaling \mathbb{R}^+ : $\varphi \rightarrow \lambda \varphi$
 $\psi \rightarrow \lambda^2 \psi$

+ shift $\psi \rightarrow \psi + \text{cst}$

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Rigid **symmetry enhanced** to $SL(2)_E$: scaling + shift + hidden sym. generator

Ehlers 1956

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**$SL(2)_E/SO(2)$
sigma model**

$$\begin{aligned}
 &= \int d^3x e [R^{(3)} - \text{tr}[(P_\mu P^\mu)]]
 \end{aligned}$$

current: $V^{-1} \partial_\mu V = P_\mu + Q_\mu$ with $V = \begin{pmatrix} \varphi^{-1} & 0 \\ \varphi^{-1} \psi & \varphi \end{pmatrix}$

$\in \mathfrak{sl}(2)_E$

KK reduction: from $d=3$ to $d=2$

$$\mu = 0, 1$$

$$e_\mu{}^\alpha = \text{zweibein}$$

Reducing further on S^1 leads to:

$$S_{d=2} = \int d^2x e \rho \left[R^{(2)} - \text{tr}(P_\mu P^\mu) \right]$$

dilaton	d=2	$SL(2)_E/SO(2)$
	gravity	sigma model

with the current:

$$\frac{V^{-1} \partial_\mu V}{\in \mathfrak{sl}(2)_E} = P_\mu + Q_\mu \quad | \quad \in \mathfrak{so}(2)$$

Specificities of $d=2$:

- The vector field is non-dynamical and has been integrated out.
- Constant rescaling of the zweibein is a symmetry.
→ The dilaton cannot be removed.

The action can be simplified by going to the conformal gauge:

$$S_{d=2} = \int d^2x [\partial_\mu \sigma \partial^\mu \rho - \rho \text{tr}(P_\mu P^\mu)]$$

Conformal gauge
 $e_\mu{}^\alpha = e^\sigma \delta_\mu^\alpha$

σ : conformal factor

Rigid symmetries: $SL(2)_E$ and Weyl rescaling $\sigma \rightarrow \sigma + \text{cst}$

On-shell symmetries in d=2

Consider the field equation for the coset scalars:

$$\partial_\mu (\rho V P_\mu V^{-1}) = \partial^\mu I_{(1)}^\mu = 0 \quad \xrightarrow{\text{dualisation}} \quad I_{(1)}^\mu = \rho V P^\mu V^{-1} = \epsilon^{\mu\nu} \partial_\nu Y_1 \in \mathfrak{sl}(2)$$

$$\longrightarrow I_{(2)}^\mu = (\rho \tilde{\rho} \delta_\nu^\mu + \epsilon^{\mu\lambda} \eta_{\lambda\nu} \rho^2) V P^\nu V^{-1} - \frac{1}{2} [Y_1, \partial^\mu Y_1] = \epsilon^{\mu\nu} \partial_\nu Y_2$$

$\rightarrow \cdots \rightarrow$ infinite tower of $\mathfrak{sl}(2)$ -valued dual scalar fields Y_n .

Integrability conditions given by the conservation of the currents $I_{(n)}^\mu$.

\rightarrow consistency of the tower relies on the field equation.

Infinite number of duality relations encoded in:

- a generating function known as the *linear system*

Belinsky, Zakarov 1978

Breitenlohner, Maison 1986

or equivalently

- a *twisted self-duality equation*

Julia, Nicolai 1996

Paulot 2004

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Extra rigid symmetries of the field equations:

- $Y_n \xrightarrow[\mathfrak{sl}(2)]{} Y_n + C_n$ infinite number of shifts
- $\xrightarrow{\widetilde{SL}(2)}$ loop group
- Non-linearly realised ('hidden') symmetries...



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Full on-shell symmetry
of the theory:

$\widetilde{SL(2)}$
loop group and $\sigma \rightarrow \sigma + c$
Weyl rescaling

Affine
group

central extension

- Symmetry of space of stationary axisymmetric solutions of GR.

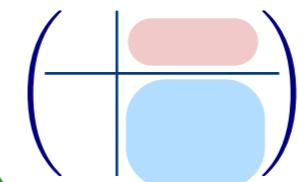
Geroch 1987

Always two paths to d=2

D=2+q:

Gravity

$$T^{q-1}$$



d=3: $R^+ \times SL(q-1)$ symmetry

Dualisation of the $(d-1)$ KK vectors
into scalars $\implies SL(q)_E$ symmetry

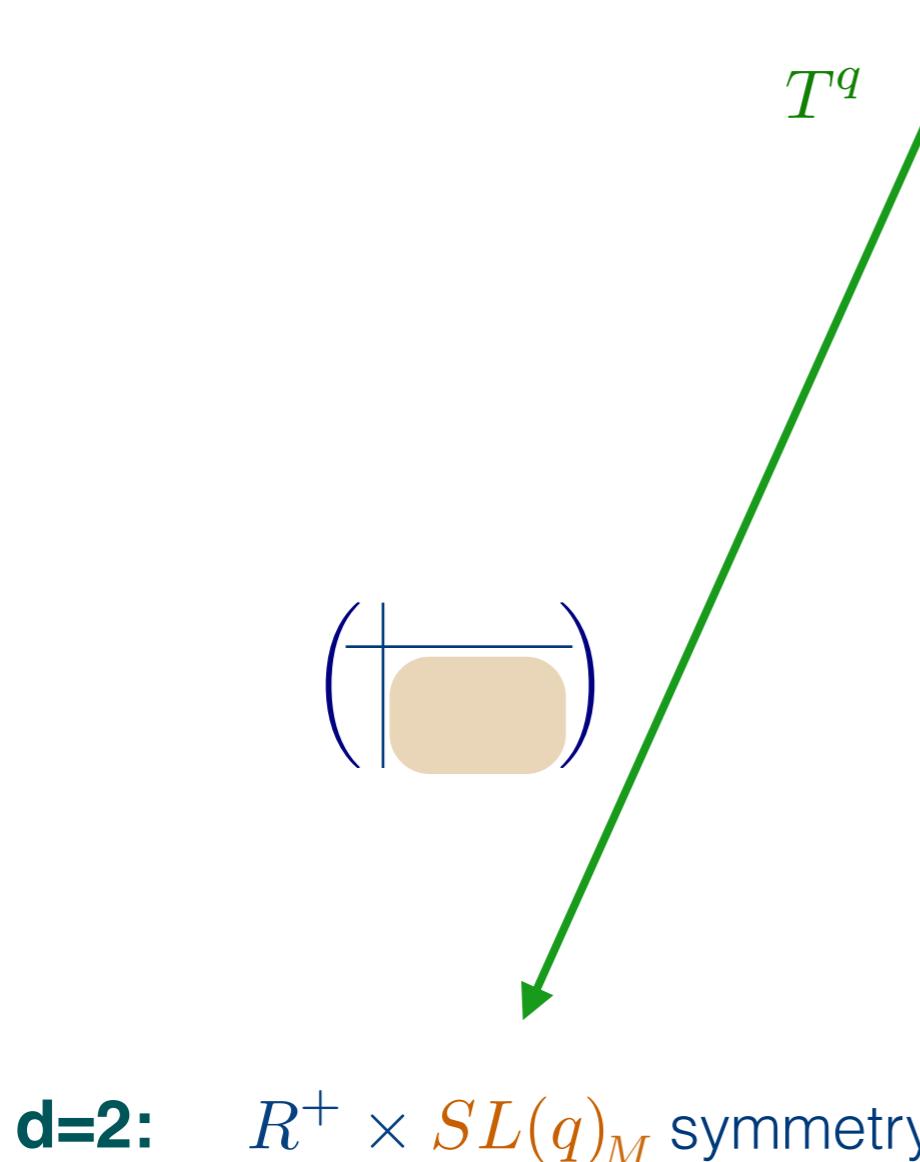
$$\downarrow S^1$$

d=2:

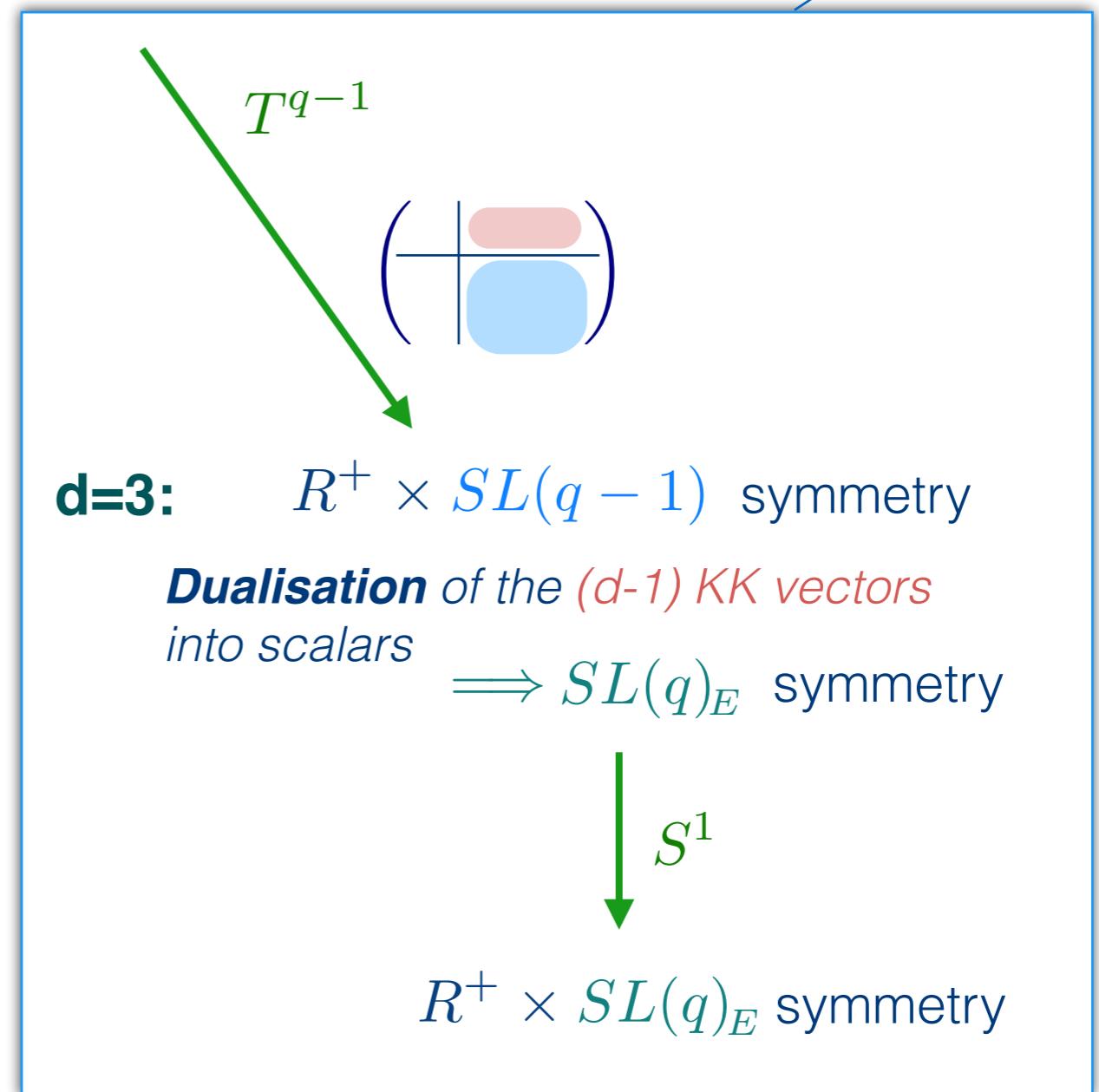
$R^+ \times SL(q)_E$ symmetry

Always two paths to d=2

D=2+q:

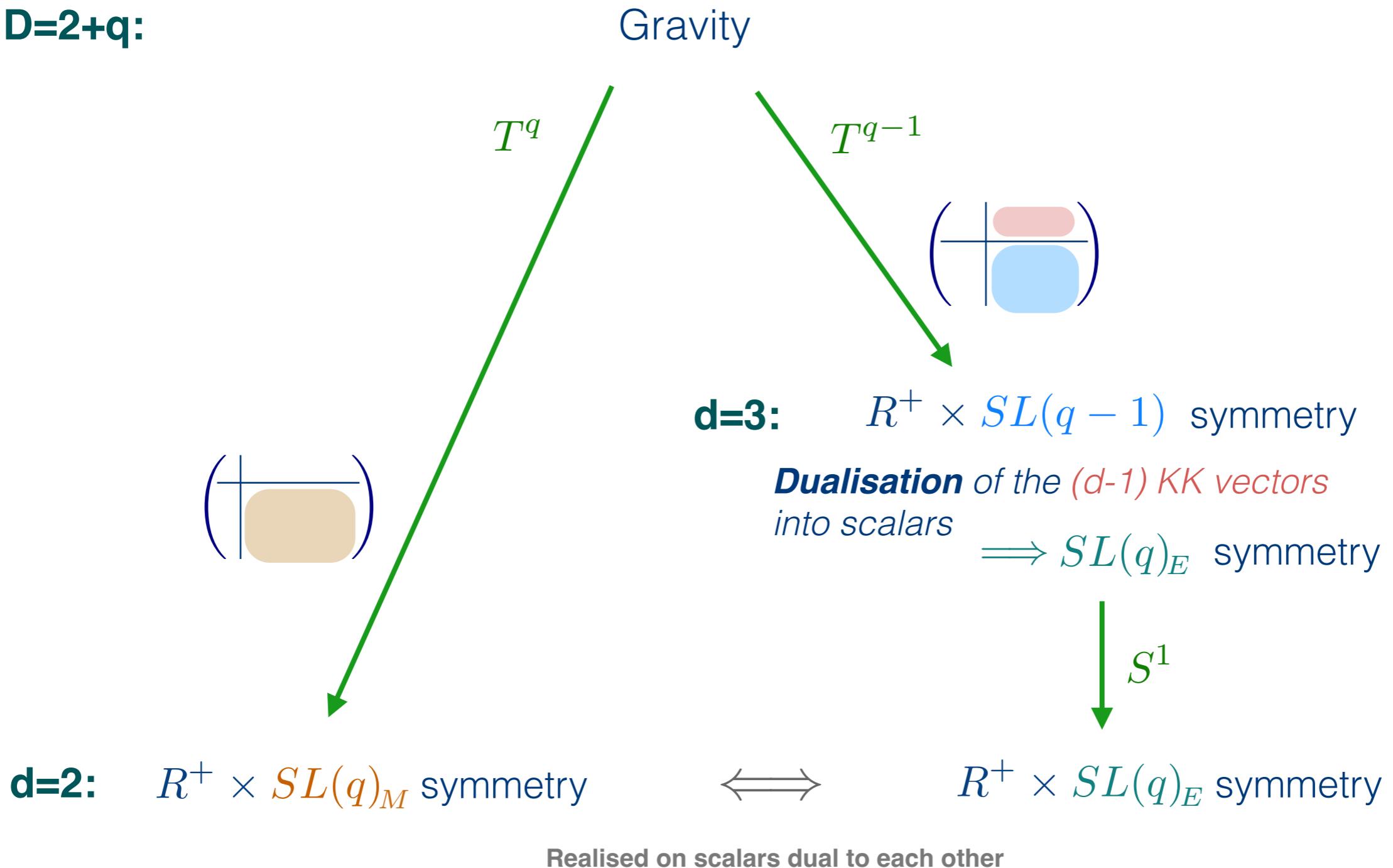


Gravity



Always two paths to d=2

D=2+q:



Two (on-shell) equivalent versions of the D=2 theory

Realising the two $SL(q)$ simultaneously requires an infinite number of dual scalars

$$"SL(q)_M \times SL(q)_E = \widetilde{SL(q)}" \text{ loop group}$$

Consistent sphere truncations

Necessary condition:

$$SO(q+1) \subset \mathcal{G}$$

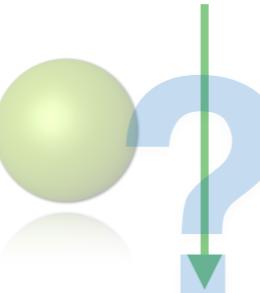
→ Requires symmetry enhancement of \mathcal{G} .

Cvetic, Gibbons, Lü, Pope 2003

D:

Gravity theory

S^q



d=D-q:

Theory with
 $SO(q+1)$ gauge
symmetry

T^q

Theory with
rigid symmetry \mathcal{G}

Only rare examples: must start from matter-coupled gravity

Consistent sphere truncations

Necessary condition:

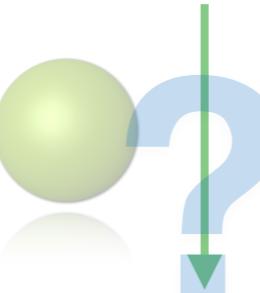
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Gravity theory

S^q



d=D-q:

Theory with
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Theory with
rigid symmetry \mathcal{G}

Only rare examples: must start from matter-coupled gravity

D=10

Gravity + 3-form



S^7

d=5

Gravity + $SO(8)$ YM + scalars

Maximal SUSY context:

$AdS_4 \times S^7$



M2-branes

De Wit, Nicolai 1980's

Prototypical examples
of AdS/CFT

Consistent sphere truncations

Necessary condition:

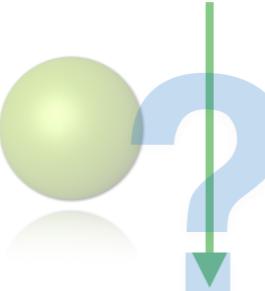
$$SO(q+1) \subset \mathcal{G}$$

→ Requires symmetry enhancement of \mathcal{G} .

D:

Gravity theory

$$S^q$$



d=D-q:

Theory with
 $SO(q+1)$ gauge
symmetry

$$T^q$$

Theory with
rigid symmetry \mathcal{G}

Only rare examples: must start from matter-coupled gravity

D=11

Gravity + 3-form



$$S^4$$

d=7

Gravity + $SO(5)$ YM + scalars + ...

Maximal SUSY context:

$$AdS_4 \times S^7$$



M2-branes

$$AdS_7 \times S^4$$



M5-branes

Consistent sphere truncations

Necessary condition:

$$SO(q+1) \subset \mathcal{G}$$

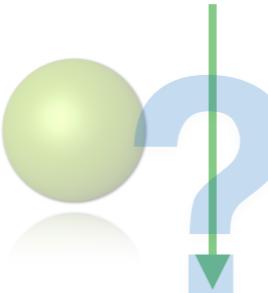
→ Requires symmetry enhancement of \mathcal{G} .

D:

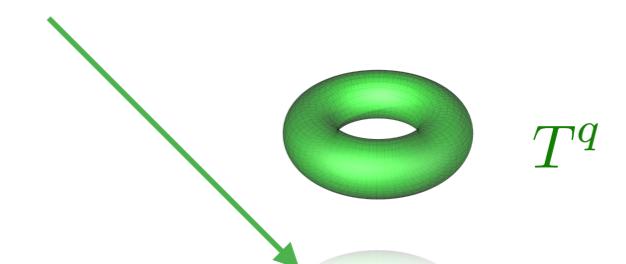
d=D-q:

Gravity theory

S^q



Theory with
 $SO(q+1)$ gauge
symmetry



Theory with
rigid symmetry \mathcal{G}

Only rare examples: must start from matter-coupled gravity

D=11

Gravity + 5-form



S^5

d=4

Gravity + $SO(6)$ YM + scalars

Maximal SUSY context:

$AdS_4 \times S^7$



M2-branes

$AdS_7 \times S^4$



M5-branes

$AdS_5 \times S^5$



D3-branes

Consistent sphere truncations

Necessary condition:

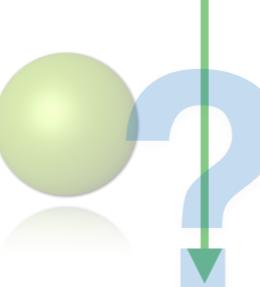
$$SO(q+1) \subset \mathcal{G}$$

→ Requires symmetry enhancement of \mathcal{G} .

D:

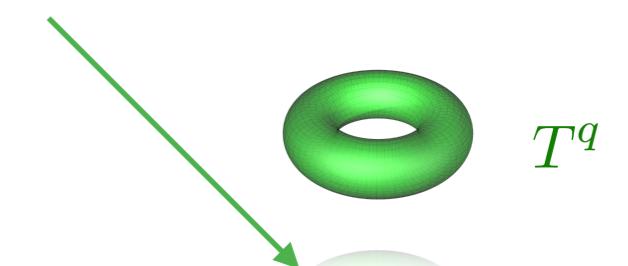
Gravity theory

S^q



d=D-q:

Theory with
 $SO(q+1)$ gauge
symmetry



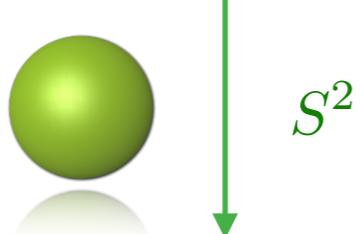
Theory with
rigid symmetry \mathcal{G}

Only rare examples: must start from matter-coupled gravity

D:

Gravity + Maxwell + dilaton

$$D \neq 4$$



d=D-2: Gravity + $SO(3)$ YM + scalars

+ 2 other
examples

Cvetic, Lü, Pope 2000

Consistent sphere truncations

Necessary condition:

$$SO(q+1) \subset \mathcal{G}$$

→ Requires symmetry enhancement of \mathcal{G} .

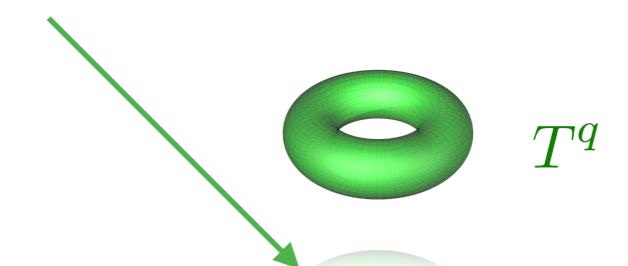
D:

Gravity theory



d=D-q:

Theory with
 $SO(q+1)$ gauge
symmetry



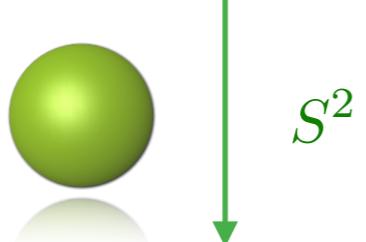
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rigid symmetry \mathcal{G}

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D:

Gravity + Maxwell + dilaton

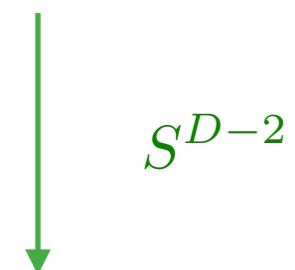
$$D \neq 4$$



d=D-2: Gravity + $SO(3)$ YM + scalars

D:

Gravity + Maxwell + dilaton



d=2: Gravity + $SO(D-1)$ YM + scalars

Consistent sphere truncations

Necessary condition:

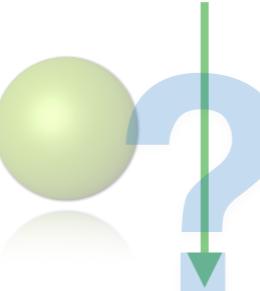
$$SO(q+1) \subset \mathcal{G}$$

→ Requires symmetry enhancement of \mathcal{G} .

D:

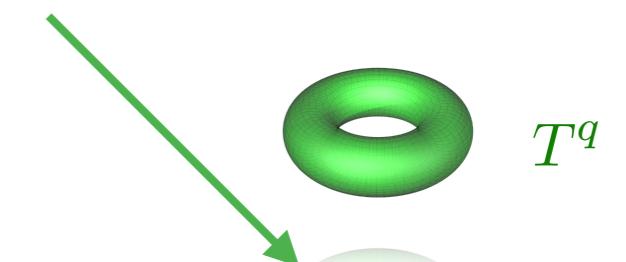
Gravity theory

$$S^q$$



d=D-q:

Theory with
 $SO(q+1)$ gauge
symmetry



Theory with
rigid symmetry \mathcal{G}

Only rare examples: must start from matter-coupled gravity

D+1:

Gravity



$$S^1$$

D:

Gravity + Maxwell + dilaton

$$D \neq 4$$



$$S^2$$

d=D-2: Gravity + $SO(3)$ YM + scalars

D+1:

Gravity



$$S^1$$

D:

Gravity + Maxwell + dilaton



$$S^{D-2}$$

d=2: Gravity + $SO(D-1)$ YM + scalars

Consistent sphere truncations

Necessary condition:

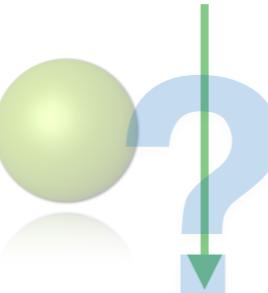
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Gravity theory

S^q



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D+1:

Gravity

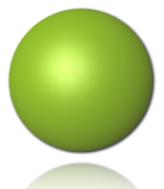


S^1

D:

Gravity + Maxwell + dilaton

$D \neq 4$



S^2

d=D-2: Gravity + $SO(3)$ YM + scalars

Group manifold
reduction on
 $SU(2) \simeq S^3$

Cvetic, Gibbons, Lü, Pope 2003

Consistent sphere truncations

Necessary condition:

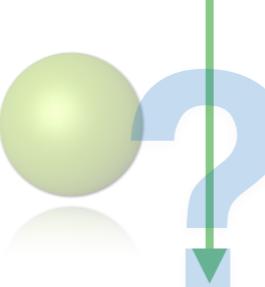
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→ Requires symmetry enhancement of \mathcal{G} .

D:

Gravity theory

S^q



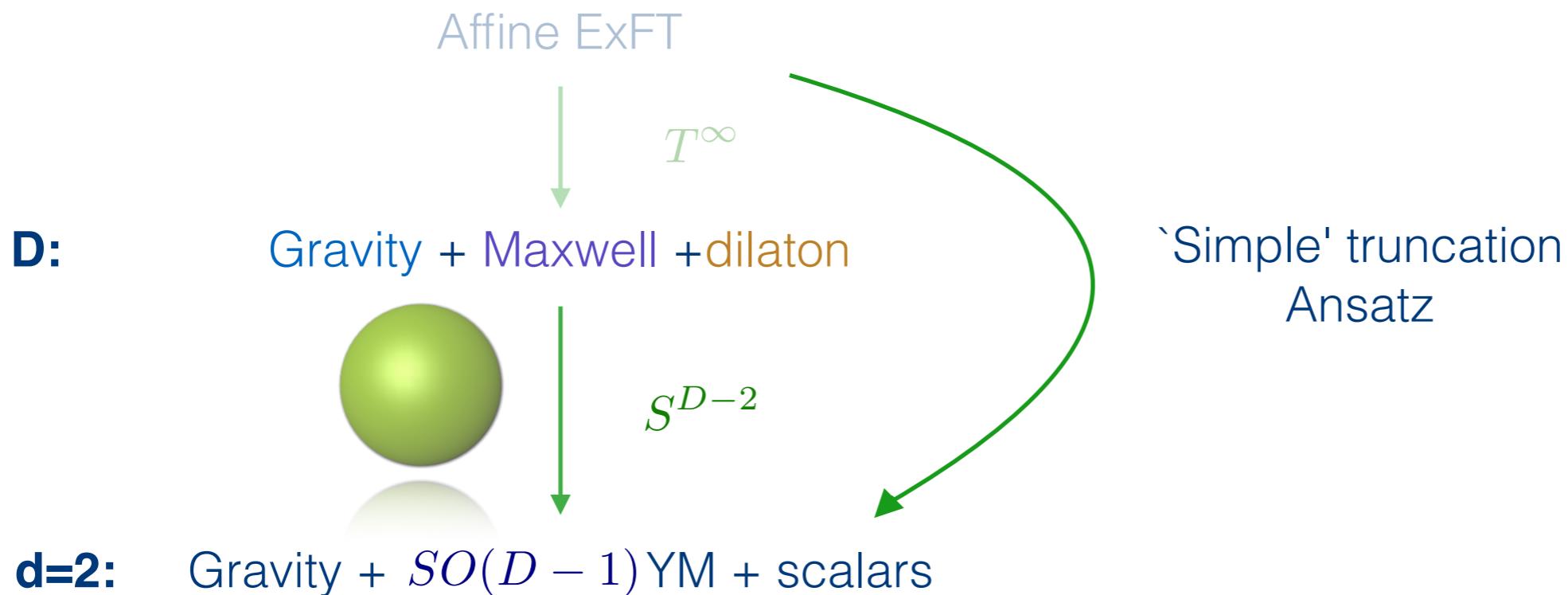
d=D-q:

Theory with
 $SO(q+1)$ gauge
symmetry

T^q

Theory with
rigid symmetry \mathcal{G}

Only rare examples: must start from matter-coupled gravity



Consistent sphere truncations

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D:

Gravity theory

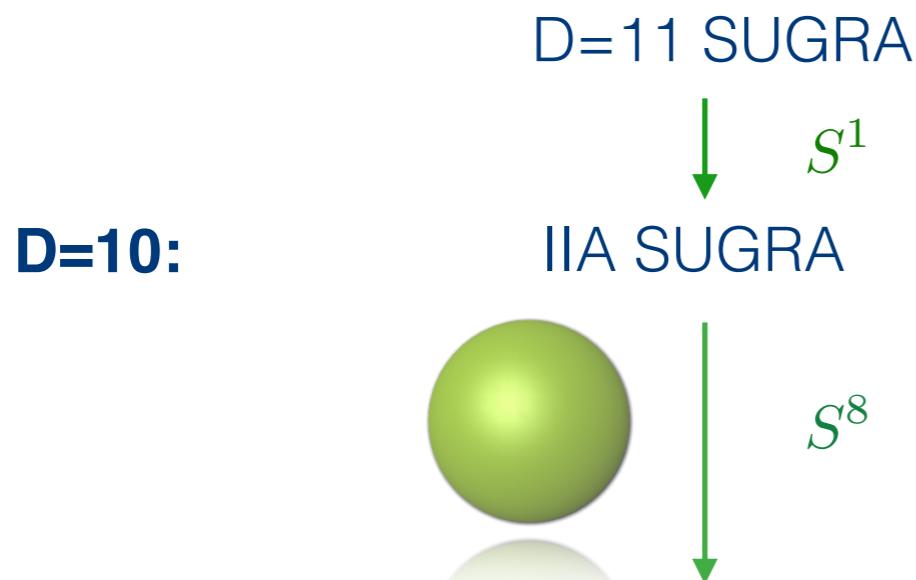


d=D-q:

Theory with
 $SO(q+1)$ gauge
symmetry

Theory with
rigid symmetry \mathcal{G}

Only rare examples: must start from matter-coupled gravity



Maximal SUSY context:

‘ $AdS_2 \times S^8$ ’ \longleftrightarrow D0-branes

Holographic description of
BFSS matrix quantum mechanics

Bossard, Ciceri, Inverso, Kleinschmidt, Samtleben 2021

Bossard, Ciceri, Inverso, Kleinschmidt 2023

Thank you for your attention

and

congratulations Anamaria.