A joint Planck and SPT-SZ measurement of CMB lensing cluster masses

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A quick introduction/reminder

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Cosmology with clusters

Mass function:

- z, M <---> cosmo
- Redshift from optical survey
- Mass from?

A quick introduction/reminder

Gravitational lensing

- **Visible light**: galaxies, 3% of total mass
- **X-rays**: hot intracluster gas, 12% of total mass
- **Gravitational lensing**: the above + dark matter (85%)
- = 100% of total mass

Lensing induced by a cluster on a background galaxy

Which source?

Two different types of sources:

- **Background galaxies**: need to find background galaxies, i.e. up to z~1
- **CMB**: the CMB is the source, i.e. up to z~1100

Mass measured with a signal to noise ratio of 1 as a function of redshift for CMB lensing

A quick introduction/reminder

Two surveys

What to do then?

- We use **Planck** et **SPT-SZ**, two complementary data sets
- First steps: **separated** analysis for each data set
	- Analysis on simulated maps
	- Apply the method to real data
- We then **combine** the Planck and SPT-SZ data sets
	- First simulation
	- Then real data

Map simulation

- **CMB**: Gaussian random field from Planck CMB power spectrum
- **Cluster lens**: Navarro-Frenk- White (NFW) density profile
- **SZ effect**: generalized NFW (GNFW) profile (Arnaud et al. 2010)
- **Instrumental point spread function** (PSF)
- **Instrumental noise**

Planck CMB TT angular power spectrum

• CMB

- CMB
- Cluster lens

- CMB
-

- CMB
-

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- CMB
- Cluster lens
- SZ effect
- Instrumental PSF
- Instrumental noise

- 100 GHz map
- No SZ effect
- No lensing

- 100 GHz map
- No SZ effect
- Lensing

Needed information

Data analysis

- **Internal Linear Combinations** (ILC), Remazeilles et al., 2011
- **Lensing estimator**, Hu & Okamoto, 2002
- **Matched filter**, Melin et al., 2015

One Planck simulation

Each point and associated error bar correspond to an **individual cluster mass measurement**, for a total of 468.

Averaging these measurements provides $\langle Mr \rangle = 0.84 \pm 0.25$, compatible with one

Comparison between Planck and SPT results…

Planck ILC maps: large scales

 $\langle Mr \rangle = 0.84 \pm 0.25$ (one simulation)

SPT ILC maps: small scales

 $\langle Mr \rangle = 0.91 \pm 0.22$ (one simulation)

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… and the combination of both

Planck: $\langle Mr \rangle = 0.84 \pm 0.25$ (one simulation)

SPT: $\langle Mr \rangle = 0.91 \pm 0.22$

Combination:

$|Mr$ = 0.88 \pm 0.17

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Real maps need to be cleaned

Points sources: replaced by gaussian field with CMB properties, continuity with vicinity **Maps not periodic:** apodisation of the maps

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Real maps need to be cleaned

Points sources: replaced by gaussian field with CMB properties, continuity with vicinity **Maps not periodic:** apodisation of the maps

Original map (zoom) and the control of the control of the Masked map

point source

Inpainting

To fill ZONE 1 with a realistic CMB compatible with ZONE 2:

- Compute the correlation function / power spectrum of the map
- Create a CMB map with it
- Adapt the new CMB map to ensure continuity

Hoffman & Ribak 1991, Benoit-Lévy et al. 2013

Combined results (real)

- The point sources are masked
- The lensing due to foregrounds is subtracted using "off" measurements

Averaging these measurements provides

 $|Mr$ = 0.92 \pm 0.19,

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Combined ILC map

- Planck brings most of the information on large scales
- SPT on small scales
- We get a better precision at $\frac{a}{b}$
all scales not only statistical \overrightarrow{H} all scales, not only statistical precision
- \rightarrow Complementarity

$$
\Sigma = \frac{1}{\sigma_{planck}^2} + \frac{1}{\sigma_{SPT}^2} = ? \frac{1}{\sigma_{combi}^2}
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Systematic effects

- The baseline analysis use a profile up to 5 x r500
- The main uncertainty is t assumption on the matte profile

 $|Mr$ = 0.92 \pm 0.19 (stat.)

Summary

- **First** CMB-lensing galaxy cluster mass measurement using a **combination** of **ground** and **space**-based surveys
- Analysis tested on simulations and applied to actual SPT-SZ and Planck data
- We measure the signal at **4.8 sigma** on real data, a significant gain with respect to measurements performed on the two individual datasets
- Small increasing trend from McMBlens with respect to Msz still to be understood
- **Correlations** between the scales observed by SPT-SZ and the scales observed by Planck **improve** the constraints on the lensing potential
- Planck data will remain a key element in CMB-lensing cluster studies for decades to come

Backup slides

Internal Linear Combinations

- **Contaminants**: SZ effect, foreground
- **Instrumental characteristics**: PSF, noise

Combine the maps at different frequencies to remove contaminants, easier when we know the recipe

\rightarrow Best lensed CMB map

$$
\begin{cases}\nm_{\nu_0}(\mathbf{k}) = \alpha_{\nu_0} s(\mathbf{k}) + \beta_{\nu_0} y_{\nu_0}(\mathbf{k}) + n_{\nu_0}(\mathbf{k}) \\
m_{\nu_1}(\mathbf{k}) = \alpha_{\nu_1} s(\mathbf{k}) + \beta_{\nu_1} y_{\nu_1}(\mathbf{k}) + n_{\nu_1}(\mathbf{k}) \\
\cdots \\
m_{\nu_5}(\mathbf{k}) = \alpha_{\nu_5} s(\mathbf{k}) + \beta_{\nu_5} y_{\nu_5}(\mathbf{k}) + n_{\nu_5}(\mathbf{k})\n\end{cases}
$$

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Lensing estimator

- The CMB k-modes (spatial frequencies, i.e. the different scales) are uncorrelated
- The CMB on our map is lensed, **inducing spatial correlations**
- Use these correlations to rebuild the lensing potential

2D-Fourier transform of the reconstructed gravitational potential (small k-modes – large scales in the middle)

Matched filter

- Compares the obtained lensing potential to a NFW profile for a given mass
- We know the NFW profile used in the simulations
- Returns the estimation of the amplitude fitting best the NFW profile. For simulations, we expect to get, in average: $\;M_{measurement}\;$

 M_{true}

 $= 1$

Planck ILC map

- For one simulated cluster
- No foreground simulated
- The map is periodic

Combined ILC map

- Better small scales than Planck only
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point source \bigstar

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Inpainting

- We want to fill ZONE 1 with a realistic CMB, compatible with ZONE 2
- We compute the correlation function / power spectrum of the map
- We create a CMB map with it

 \rightarrow We now have to adapt the new CMB map to ensure continuity

point source \bigstar

Inpainting

• The conditional probability distribution function of pixels in ZONE 1 constrained by pixels in ZONE 2 is a gaussian

$$
\mathcal{P}(p_1|Z_2) = \frac{\mathcal{P}(Z_2|p_1)\mathcal{P}(p_1)}{\mathcal{P}(Z_2)}
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• We keep the random deviations from the realization but use the mean of the PDF of the real map

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Bias in the lensing!

- Massive **foreground** objects
have a lensing effect
- Having **non periodic** maps creates another bias
- These biases **can be corrected** by "off" measurements
- \rightarrow We draw 10 **random** "off" maps **not centered on a cluster** for each "on" map and run the analysis on them
- àFinal result is **on - off**

For one "on" map, we cut 10 "off" maps in the sky map