

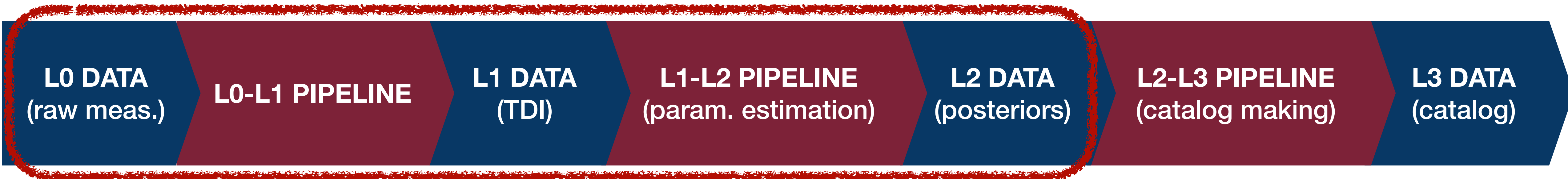
# LISA L0.5-L2 end-to-end simulation and analysis pipeline

(FMT task 4.5. Report was submitted for MAR this fall)

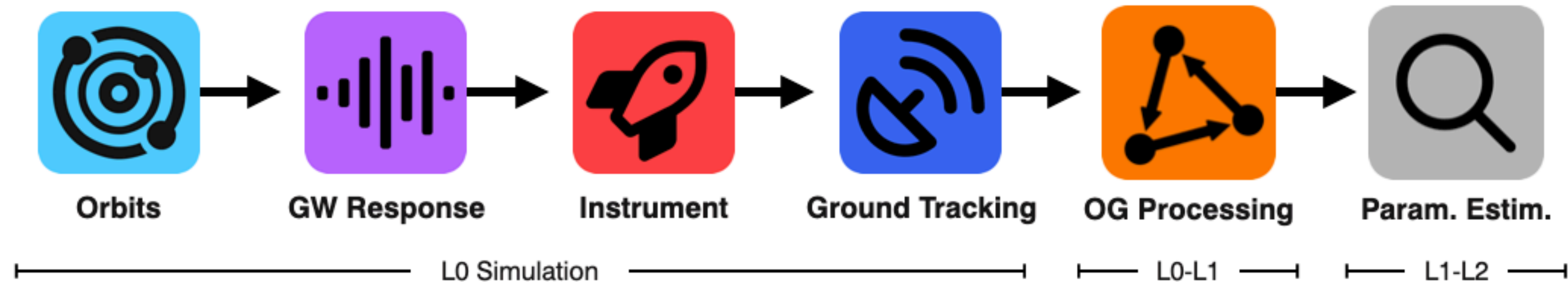
J.B. Bayle, C. Chapman-Bird, O. Hartwig, A. Hees, M. Lilley, M. Staab, G. Woan, P. Wolf

# Overview of LISA processing

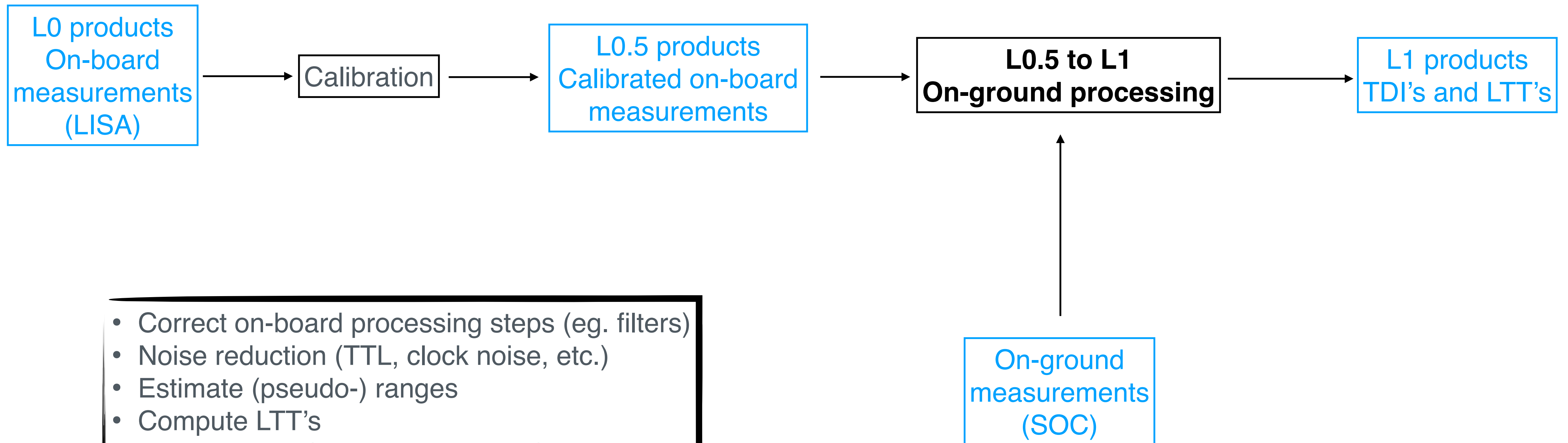
- LISA data processing and analysis sequence



- Data simulation, processing and scientific exploitation software



# The L0.5-L1 step in brief.

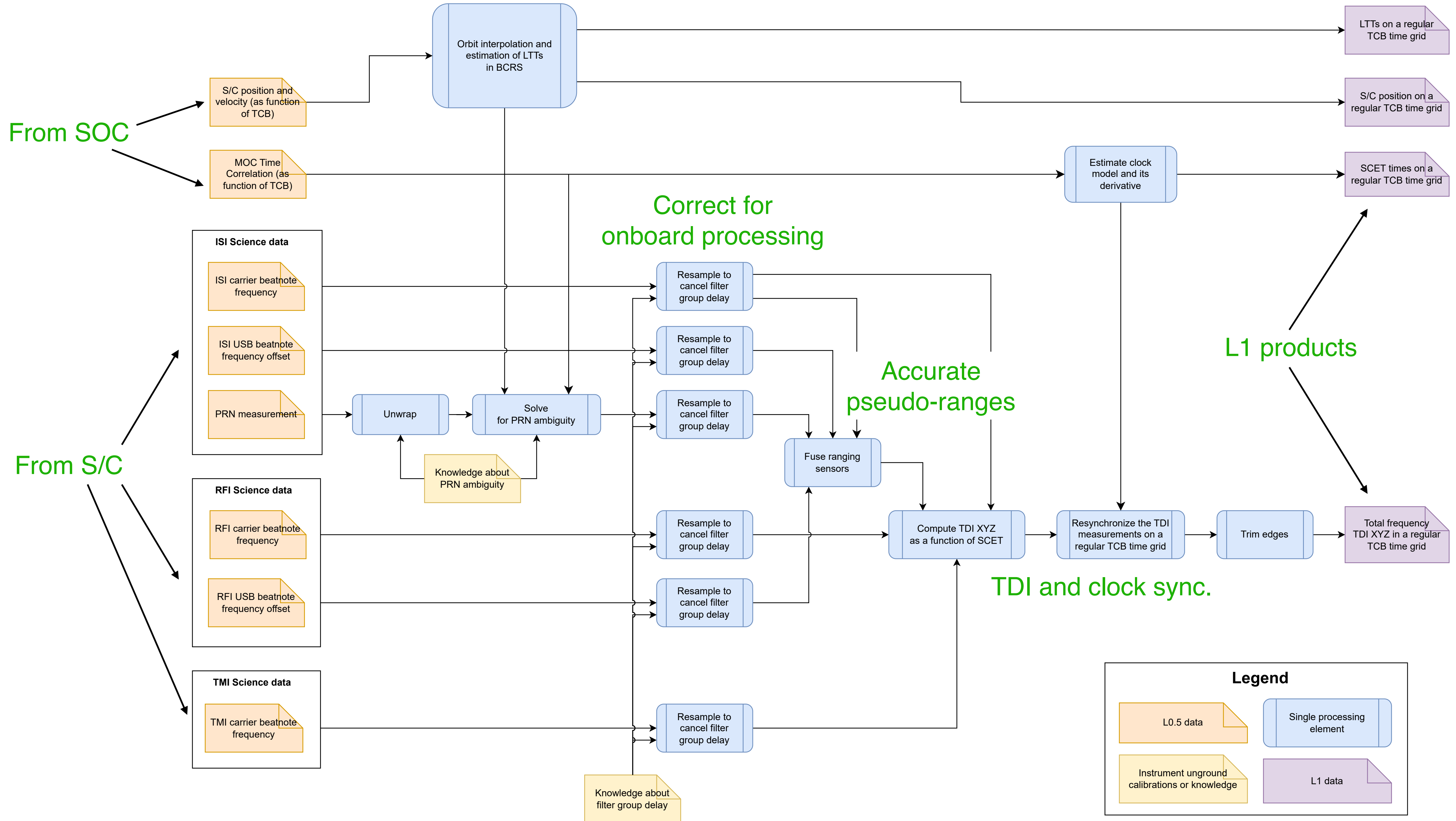


- Correct on-board processing steps (eg. filters)
- Noise reduction (TTL, clock noise, etc.)
- Estimate (pseudo-) ranges
- Compute LTT's
- TDI variables (reduce laser noise)
- Noise estimates
- Handling of gaps and glitches
- Clock synchronisation
- Etc.

# Simulation of L0.5 products

- **A single bright galactic binary**
- **Realistic time-varying unequal arm ESA LISA orbits.**
- **Ground tracking providing S/C positions and time couples.**
- **Total frequency.**
- **1 clock per S/C: different proper time, jitters and drifts**
- **ISI, RFI, TMI beatnotes, side-bands and PRN code.**
- **Instrumental noise content: laser, modulation, clock, backlink, test-mass, readout, jitter, ranging.**
- **On-board processing including filtering and decimation from 16 to 4 Hz.**
- **Laser locking and frequency planning.**
- **Simulation duration: 3 days (limited by RAM usage of lisainstrument)**

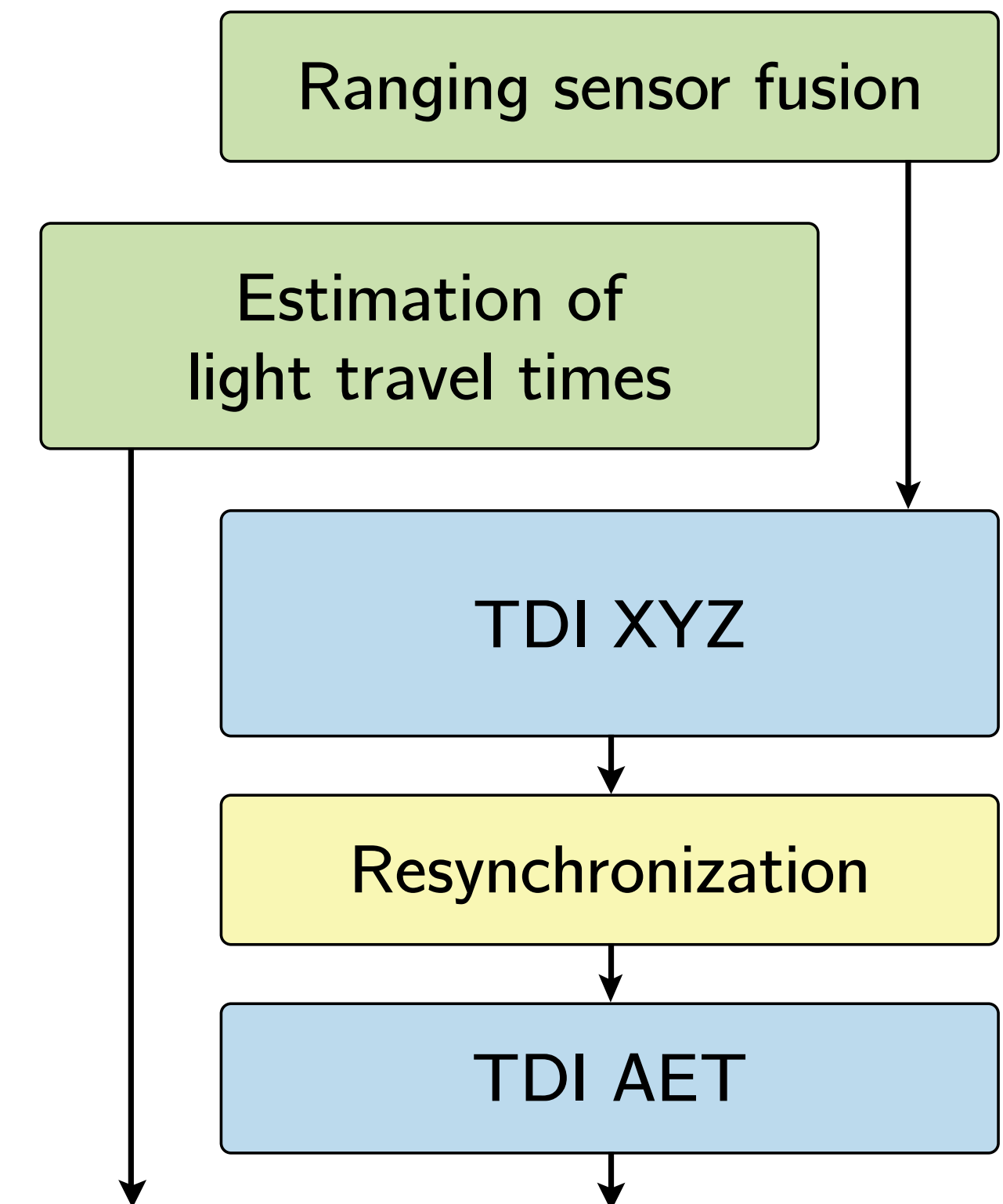
# L0.5-L1 on-ground data processing





# “TDI without clock synchronisation”

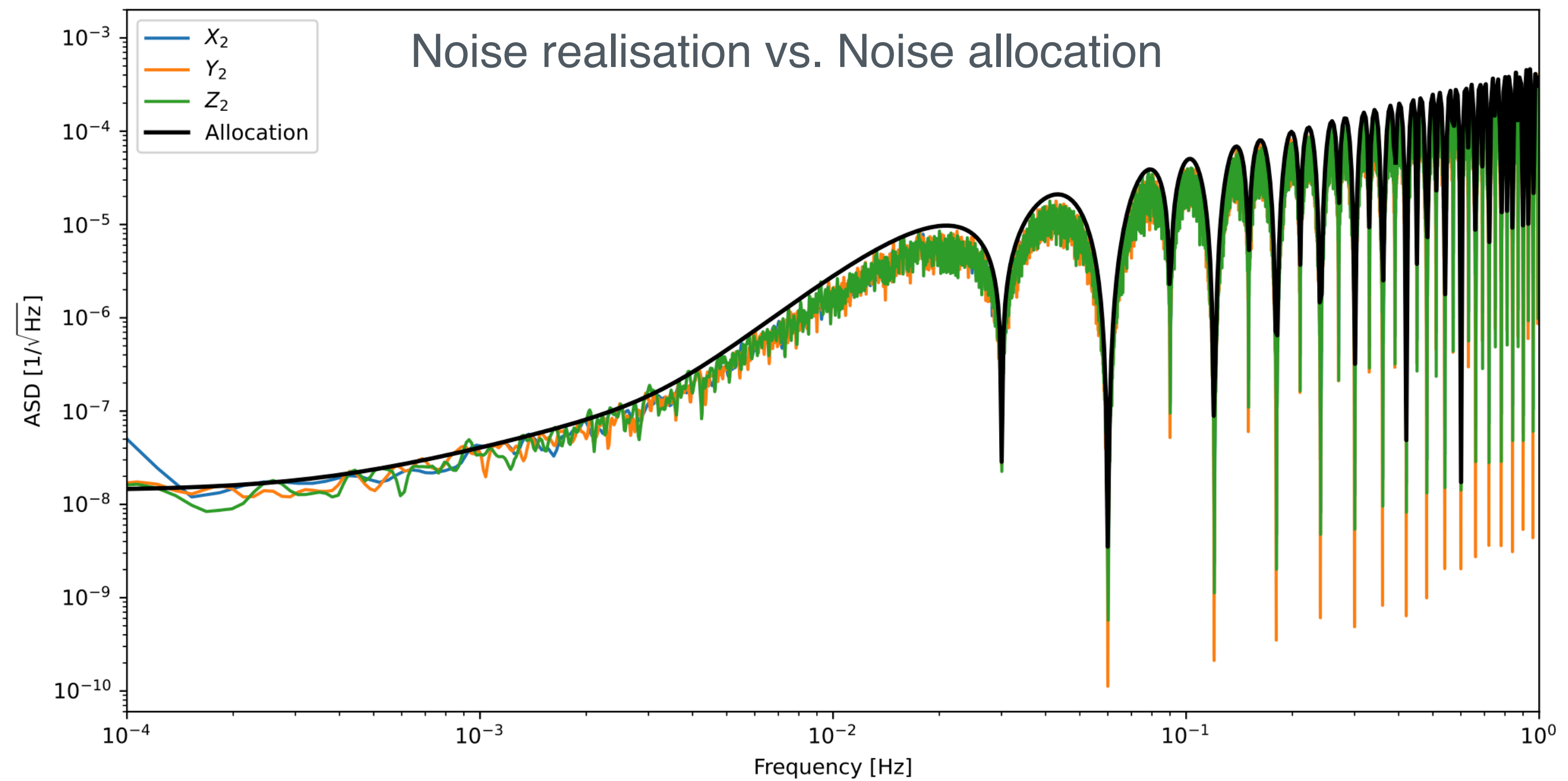
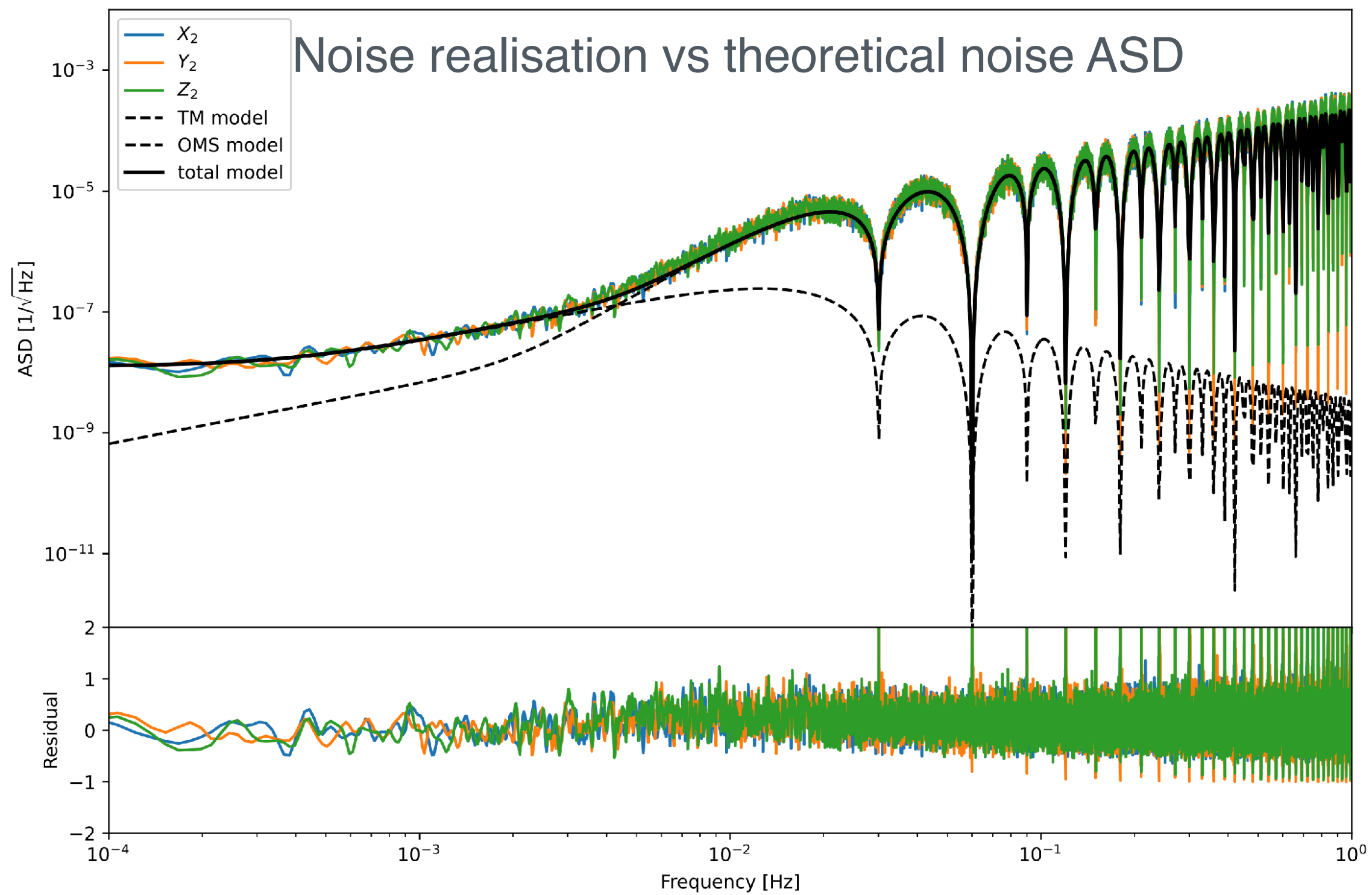
- We implement the L0.5-L1 data processing approach proposed in Hartwig et al, 2022.
- “Ranging sensor fusion” combines ground-measurements, PRN and sidebands, to provide inter-S/C pseudo-ranges sufficiently accurate for TDI.
- Light travel times in the BCRS are provided as an L1 product. They are needed for L1L2.
- Clock synchronisation to a single time frame is performed on the TDI XYZ variables. This is performed by combining the time couples with a clock model.



# L1-L2: source parameter estimation

- We attempt to recover 5 of 8 parameters of a single GB (sky localisation and  $\dot{f}$  fixed)
- Noise model: test mass acceleration noise and OMS noise, Gaussian and stationary.
- We use a Gaussian likelihood function in the Fourier domain.
- The TDI templates are computed with an adapted version of `fastGB` [Cornish+07] in the equal arms approximation
- We use `nessai` [Williams21] a nested sampling combined with ML techniques

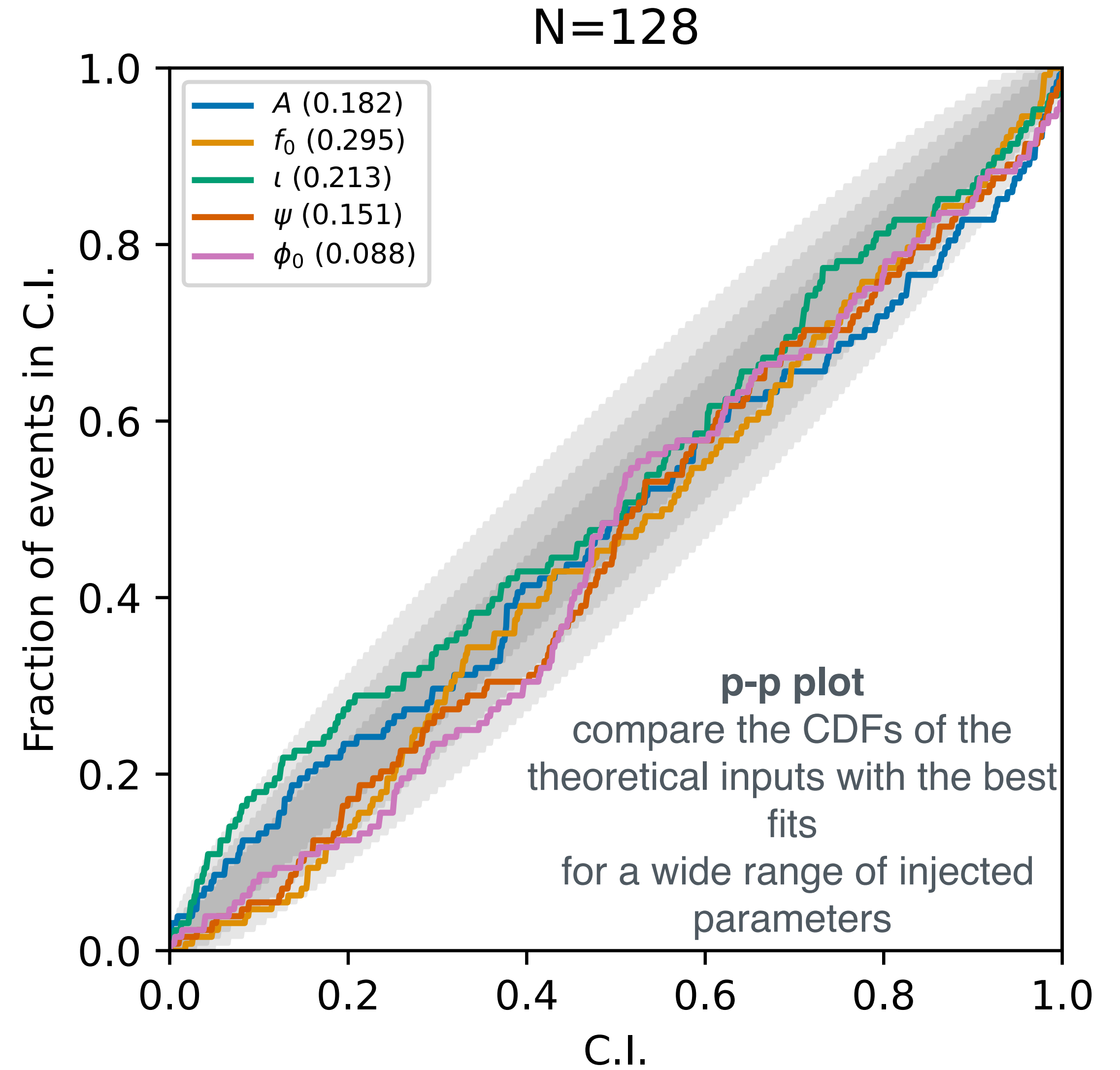
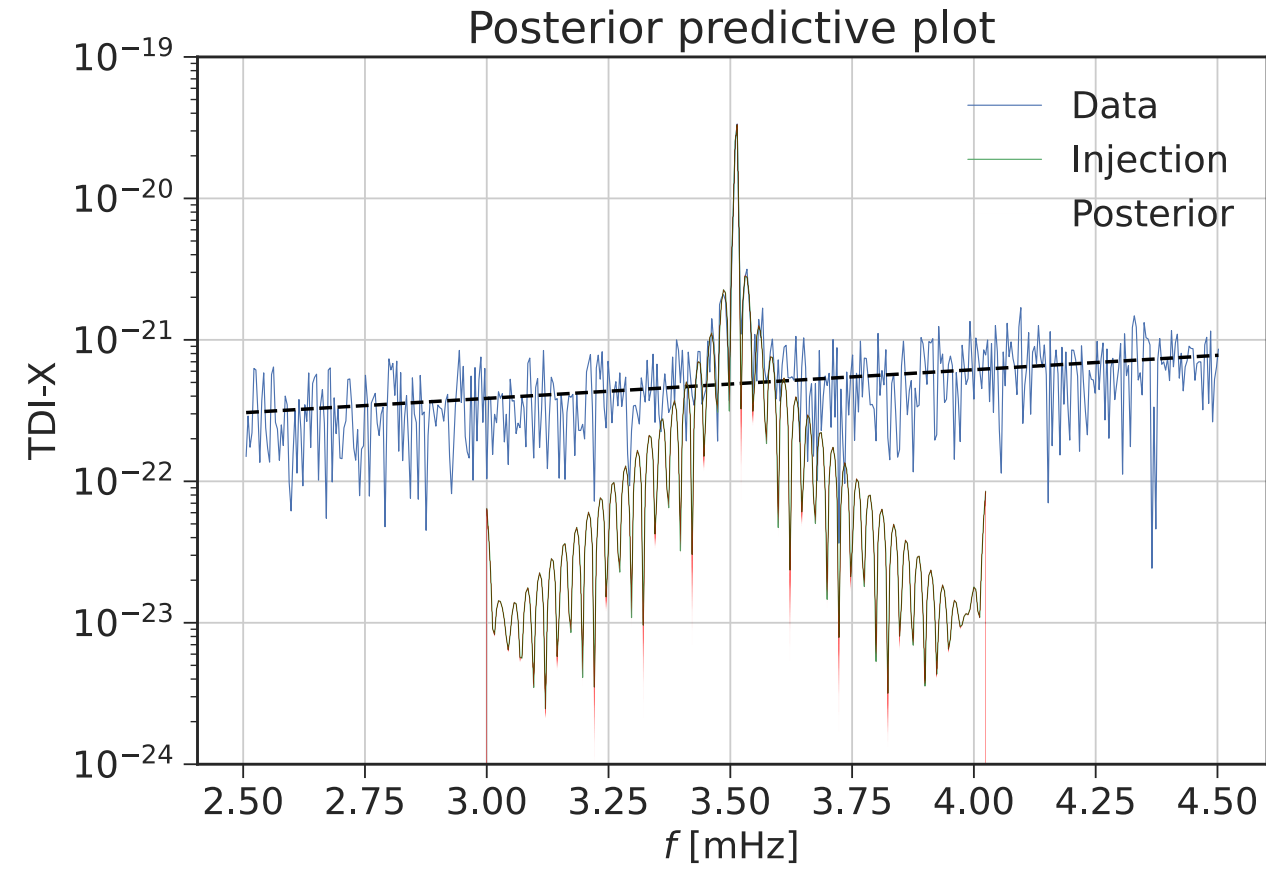
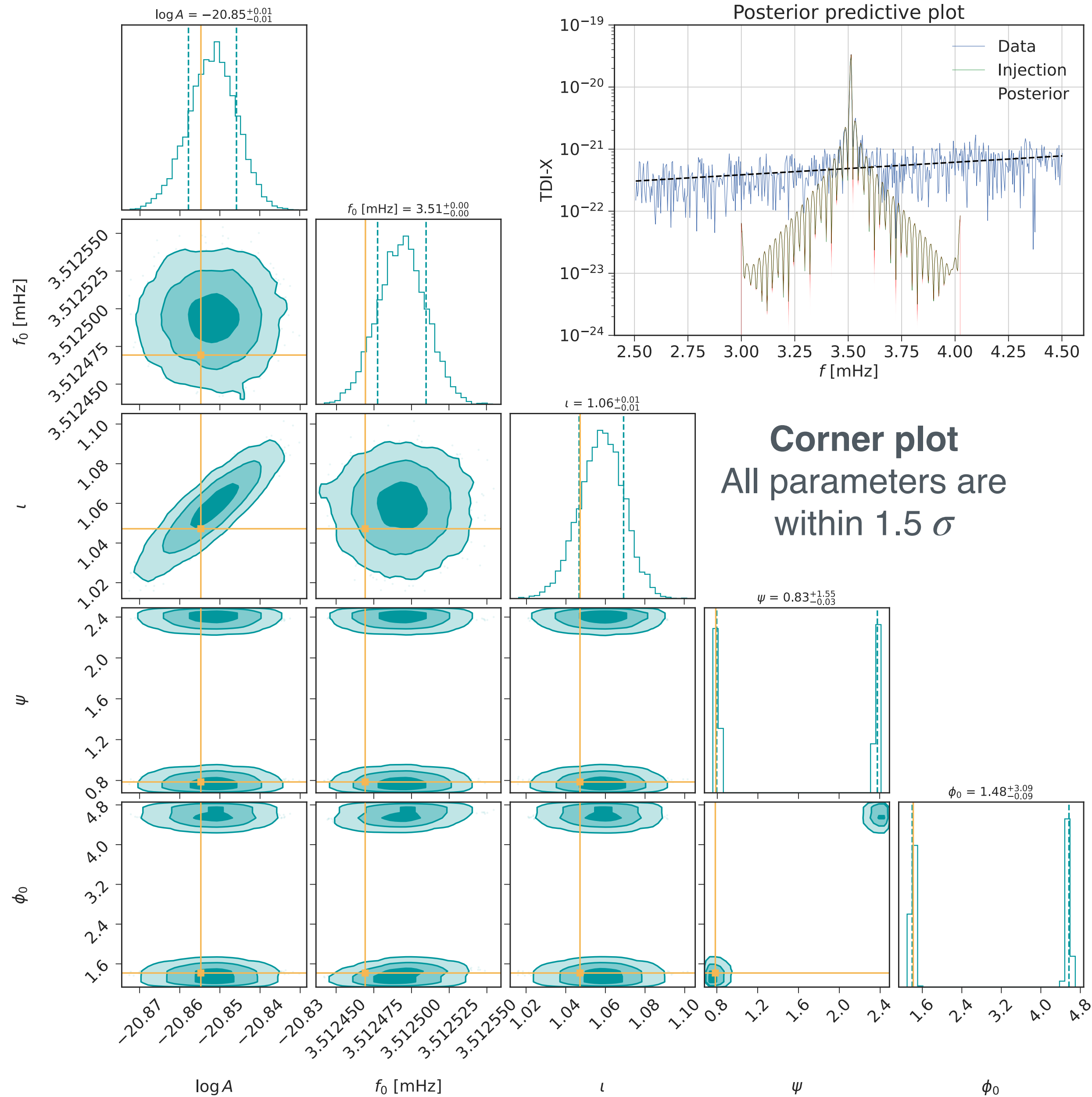
# Instrumental noise consistency check



- TM and OMS agree with theoretical expectations
- The overall noise stays allocation
- No unpleasant surprise.



# Source reconstruction



# To come...

- More realistic orbit reconstruction
- TTL correction
- Improving the interpolation schemes used in TDI
- Other types of sources
- More realistic noise
- Longer simulations
- Gaps and glitches
- Debug/improve/refine L0.5-L1 and enhance interactions with L1-L2 actors.
- Integration into LDC