

Statistical Physics of Assignment and Optimal Transport Problems: Some applications

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Applications of Statistical Physics to Optimal Transport Theory

- Assignment and Matching problems: balanced and unbalanced
- Optimal Transport (balanced)
- Optimal Transport (unbalanced) with variable masses
- Gromov-Wasserstein Optimal Transport

A long history...



Gaspard Monge
(1746-1818)



Erwin Schroedinger
(1887-1961)



Leonid Kantorovich
(1912-1986)



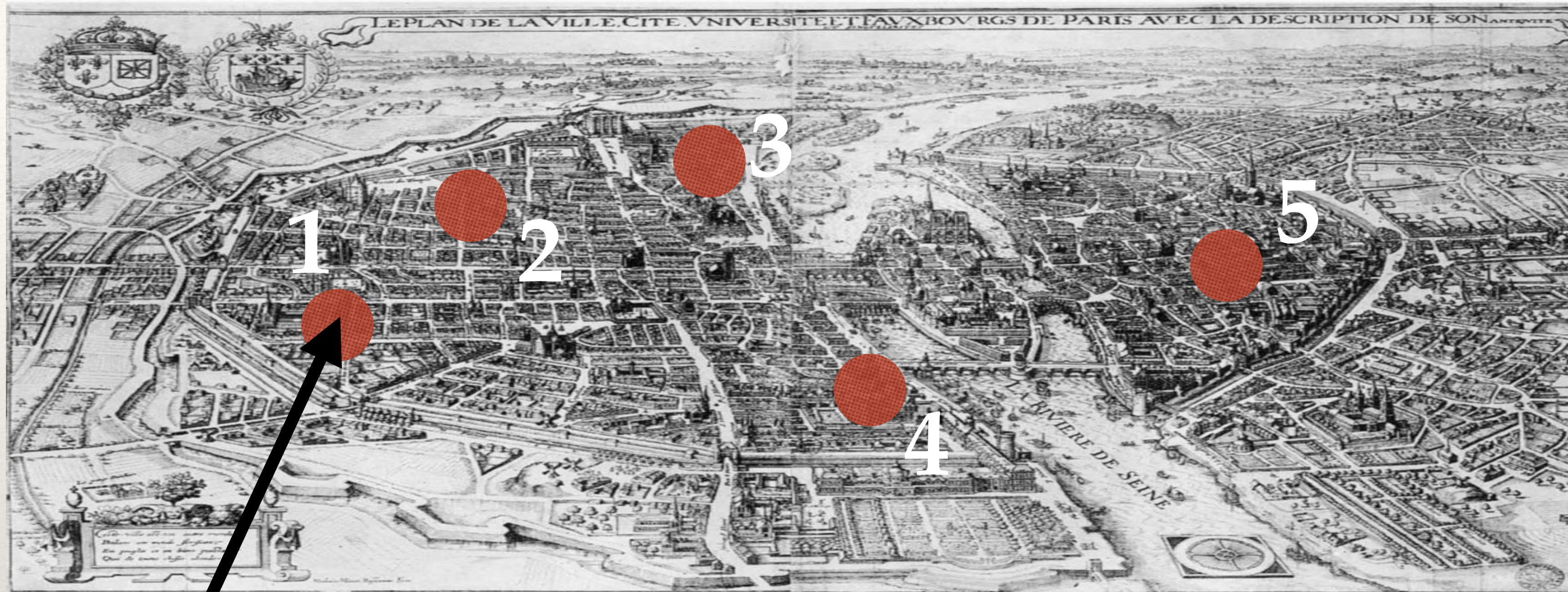
Cedric Villani



Alessio Figalli

The study of optimal transportation
and allocation of resources

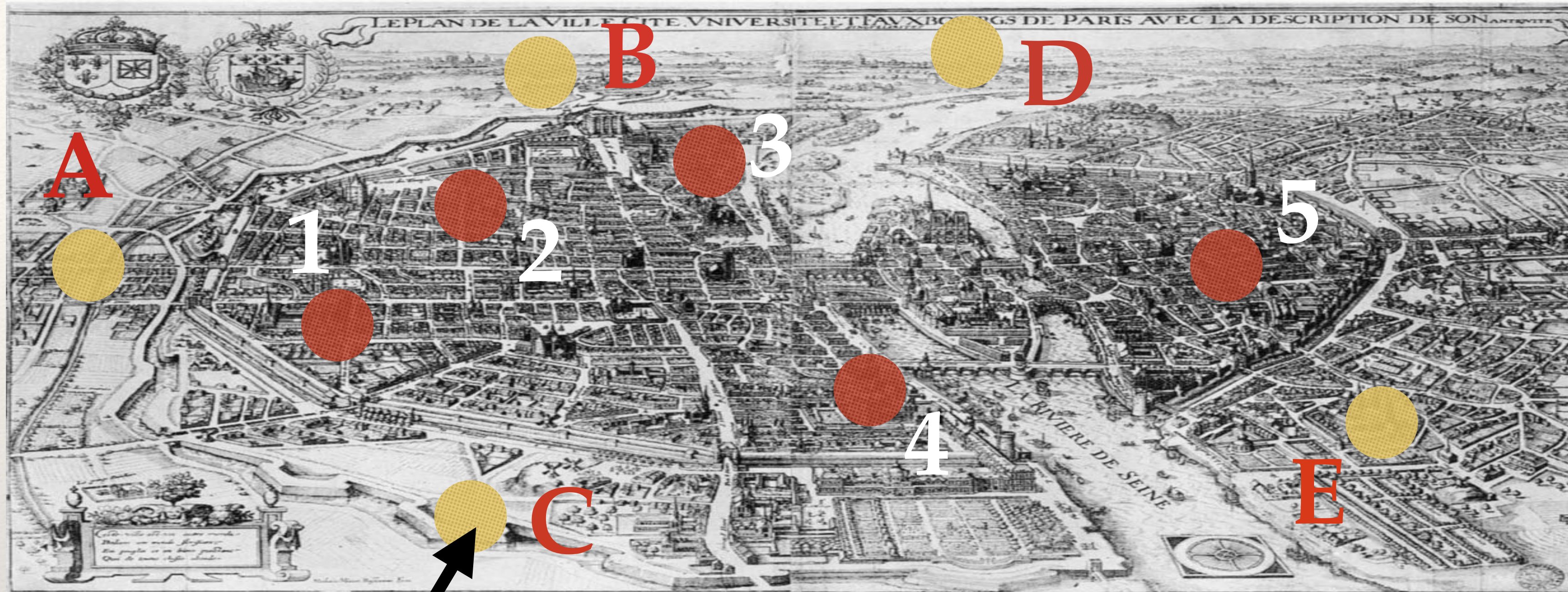
Optimal Transport (Monge): Assignment



Bakeries need flour

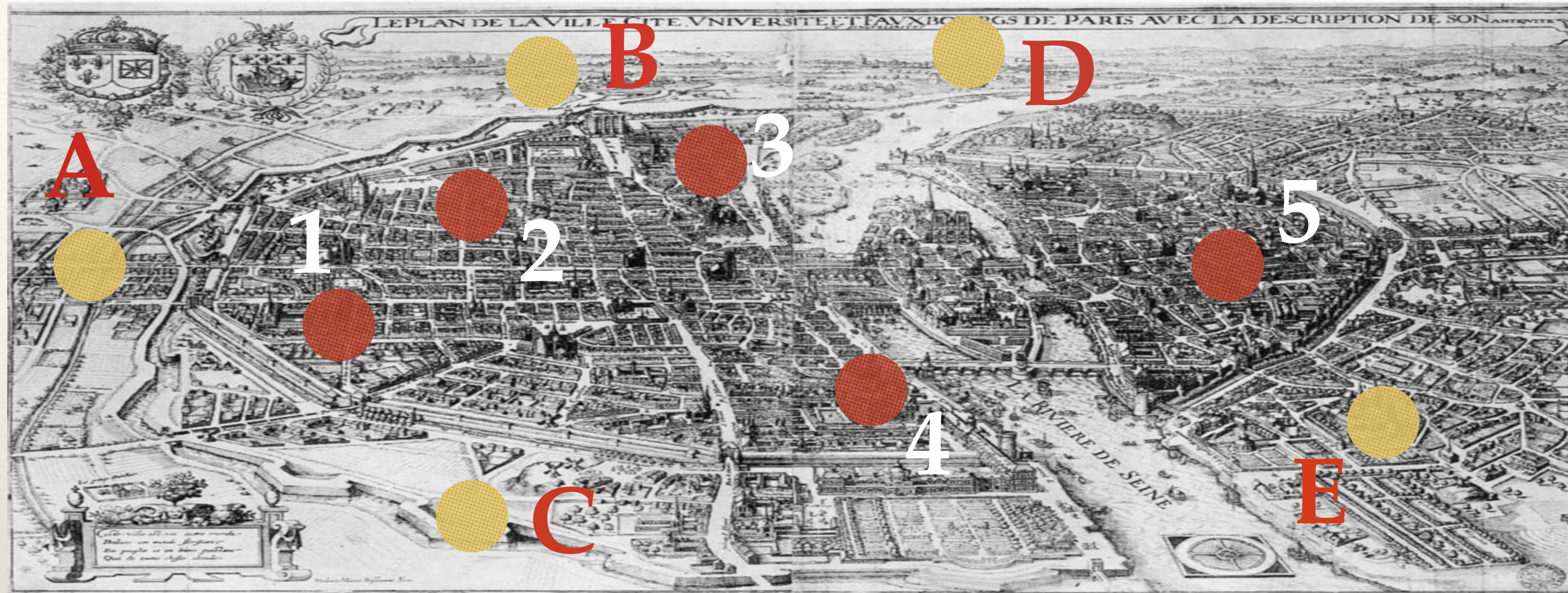
Monge, 1781

Optimal Transport: Assignment



Mills producing flour

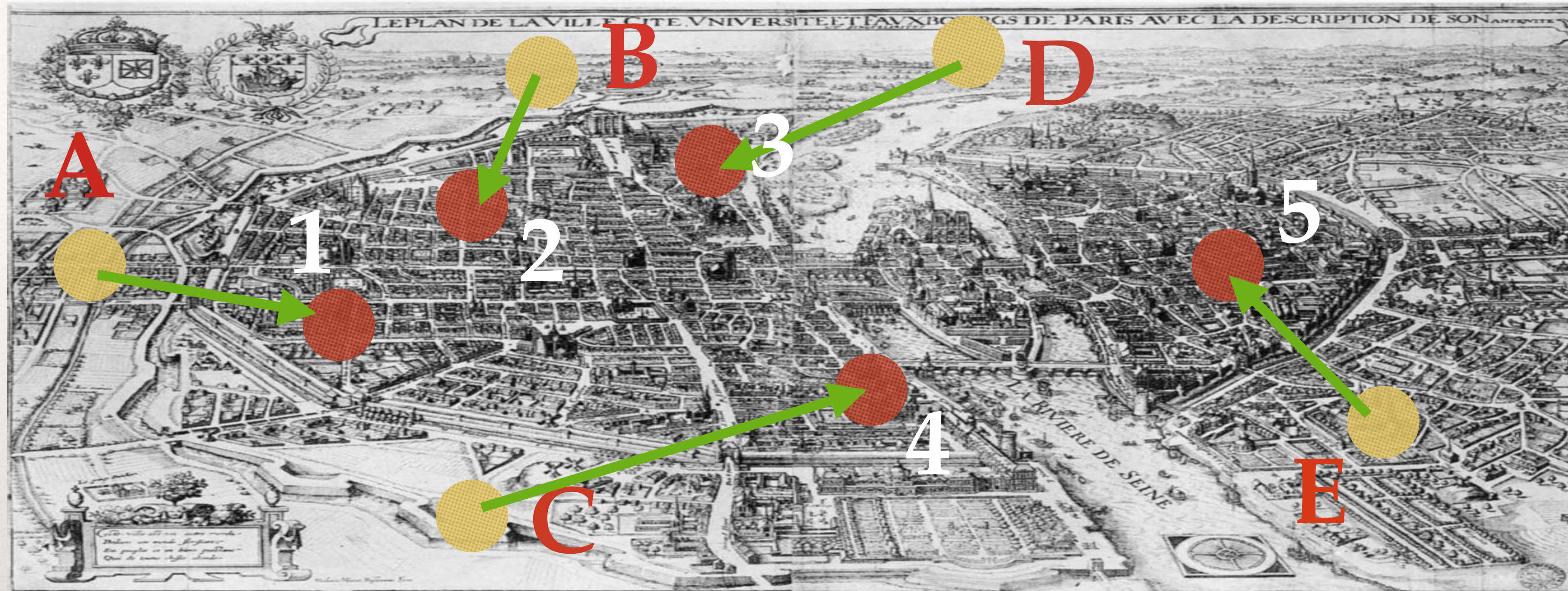
Optimal Transport: Assignment



	A	B	C	D	E
1	2	3	2,5	5	8
2	3	1,5	3	4	7,5
3	4	1,5	3,5	2	4,5
4	6	4	3	3	4
5	9	6,5	7	3	2

**Transportation Cost
From Mill (column) to Bakery (line)**

Optimal Transport: Assignment

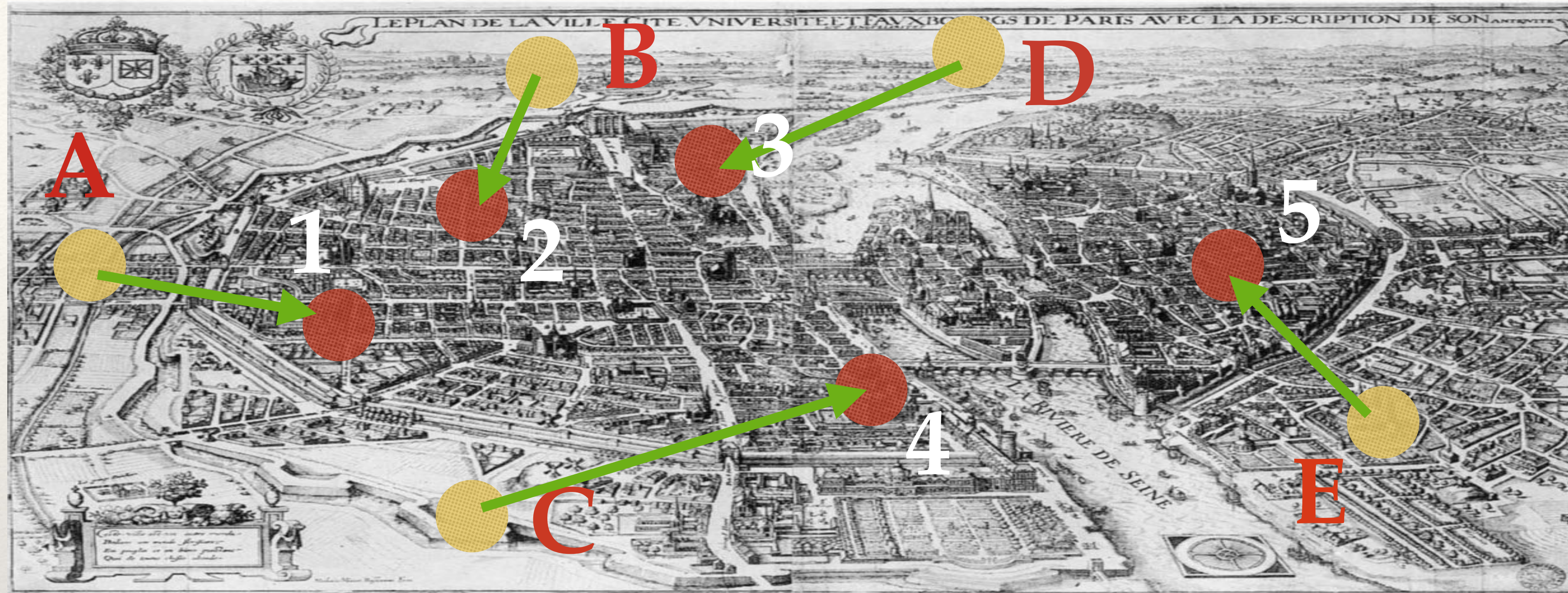


	A	B	C	D	E
1	2	3	2,5	5	8
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4	6	4	3	3	4
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How to minimise Total Transportation Cost?

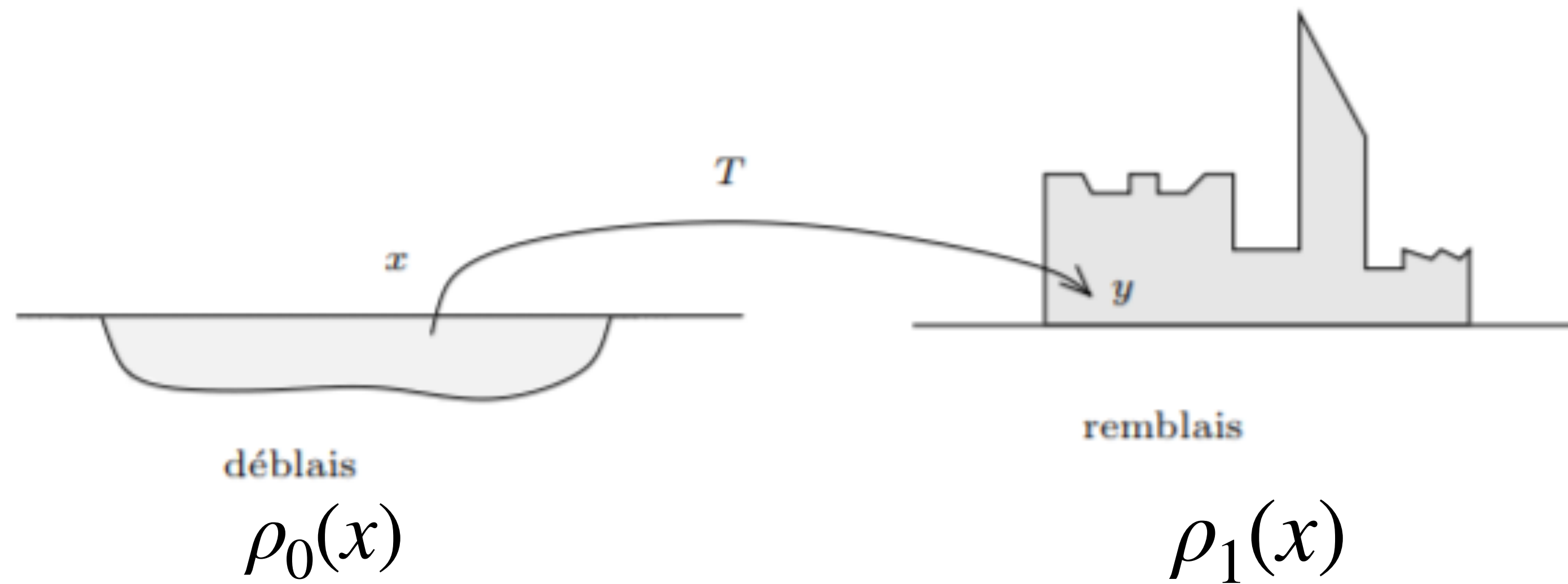
Operational research
Economics
Data Science
Physics

Optimal Transport: Assignment



	A	B	C	D	E		A	B	C	D	E	
1	2	3	2,5	5	8	1	1	0	0	0	0	= 10.5
2	3	1,5	3	4	7,5	2	0	1	0	0	0	
3	4	1,5	3,5	2	4,5	3	0	0	0	1	0	
4	6	4	3	3	4	4	0	0	1	0	0	
5	9	6,5	7	3	2	5	0	0	0	0	1	

Monge formulation: déblais et remblais



T is a **transport** of ρ_0 to ρ_1 iff

$$\forall A \subset \mathbb{R}^d \quad \int_{x \in A} \rho_1(x) dx = \int_{x \in T^{-1}(A)} \rho(x) dx$$

$$\text{Det}(\nabla T(x)) \cdot \rho_1(T(x)) = \rho_0(x)$$

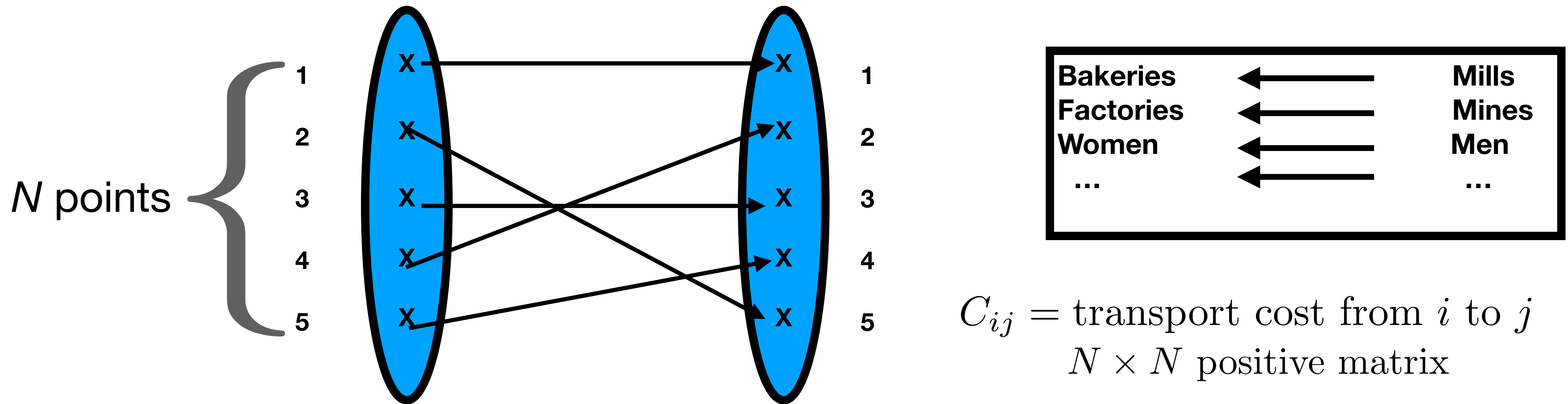
- $C(x, y) \geq 0$: cost of transporting unit mass from x to y
- Optimal transport = Monge distance

$$d(\rho_0, \rho_1) = \inf_{\{T \text{ transport}\}} \int dx C(x, T(x)) \rho_0(x)$$

- Examples :
 - Monge: $C(x, y) = |x - y|$
 - p-Wasserstein: $C(x, y) = |x - y|^p$ Wasserstein distance

Assignment = Bipartite Matching Problem = Marriage Problem.....

C.P. Bachas, 1985: pairing of defects lines in crystals



C_{ij} = transport cost from i to j
 $N \times N$ positive matrix

Assignment = Permutation
Find permutation P which minimises cost

$$C = \inf_{P \in \mathcal{S}_N} \left(\sum_{i=1}^N C_{iP(i)} \right)$$

The Hungarian Algorithm

- Published by [Harold Kuhn](#) in 1955
- Based on work by Hungarian mathematicians [Dénes König](#) and [Jenő Egerváry](#) in 1931
- In fact (2006), solved by [Jacobi](#) and published posthumously in 1890 in latin
- IDEA: Shift row values / column values to get a “simpler” cost matrix
- Complexity is of order $O(N^3)$: unpractical for large problems. Note that ≥ 3 –matching is NP-complete!
- Algorithm serial in nature and difficult to parallelize

•

Finite Temperature Assignment

- Finite temperature introduced in **combinatorial optimisation (TSP)** by Kirkpatrick in 1981, 1983
- Statistical physics of the random assignment problem by Vannimenus and Mézard (1984) and HO (1985), Mézard and Parisi (1985): Quenched average over random cost function
- The study of disordered systems in the lab, was initiated by **Cirano De Dominicis**, who performed seminal work in the theory of **Spin-Glasses**. Followed at that time by Edouard Brézin, **Claude Itzykson**, Jean Zinn-Justin, Bernard Derrida, Thomas Garel, Jean-Marc Luck...

Disordered Assignment

$$Z = \sum_{P \in \mathcal{S}_N} e^{-\beta \sum_{i=1}^N C_{iP(i)}}$$
$$U_{ij} = e^{-\beta C_{ij}}$$

Take C_{ij} as random quenched variables and introduce replicas.

With no replica symmetry breaking, infinite number of order parameters.

One obtains an integral equation for an order parameter function ϕ (MP, HO).

In the case of an exponential distribution for C_{ij} , the ground state energy has been calculated by Mézard and Parisi (1985):

$$E_0/N = \frac{\pi^2}{6}$$

$$\begin{array}{l}
 N \times N \text{ Cost Matrix } C_{ij} \\
 \text{Assignment matrix } G_{ij} \text{ with}
 \end{array}
 \left\{ \begin{array}{l}
 G_{ij} = 0 \text{ or } 1 \\
 \forall j \in \{1, \dots, N\} \quad \sum_{i=1}^N G_{ij} = 1 \\
 \forall i \in \{1, \dots, N\} \quad \sum_{j=1}^N G_{ij} = 1
 \end{array} \right.$$

$$\text{Cost Function } E = \sum_{i,j} C_{ij} G_{ij}$$

$$\text{Partition function at temperature } T = \frac{1}{\beta} \quad Z = \sum_{\text{all } C \in \mathcal{C}} e^{-\beta E(C)}$$

$$Z = \sum_{\{G_{ij}=0,1\}} \prod_{i=1}^N \delta \left(\sum_{j=1}^N G_{ij} - 1 \right) \prod_{j=1}^N \delta \left(\sum_{i=1}^N G_{ij} - 1 \right) e^{-\beta \sum_{i,j} C_{ij} G_{ij}}$$

Fourier representation of δ -functions

$$\delta\left(\sum_j G_{ij} - 1\right) = \int \frac{\beta d\lambda(i)}{2\pi} e^{i\beta\lambda(i)\left(1 - \sum_j G_{ij}\right)}$$

$$Z(\beta) = \int_{-\infty}^{+\infty} \prod_k d\lambda(k) \int_{-\infty}^{+\infty} \prod_l d\mu(l) e^{\beta\left(\sum_k i\lambda(k) + \sum_l i\mu_l\right)} \sum_{G(k,l) \in \{0,1\}} e^{-\beta \sum_{k,l} G(k,l) \left(C(k,l) + i\lambda(k) + i\mu(l)\right)}$$

Do summation over the G

$$Z(\beta) = \int_{-\infty}^{+\infty} \prod_k d\lambda(k) \int_{-\infty}^{+\infty} \prod_l d\mu_l e^{-\beta F_\beta(\boldsymbol{\lambda}, \boldsymbol{\mu})}$$

with

$$F_\beta(\boldsymbol{\lambda}, \boldsymbol{\mu}) = -\left(\sum_k i\lambda(k) + \sum_l i\mu(l)\right) - \frac{1}{\beta} \sum_{kl} \ln \left[1 + e^{-\beta(C(k,l) + i\lambda(k) + i\mu(l))}\right]$$

Duality

Saddle-Point Approximation

Change $i\lambda(k) \rightarrow \lambda(k)$ $i\mu(l) \rightarrow \mu(l)$ Saddle point is pure imaginary

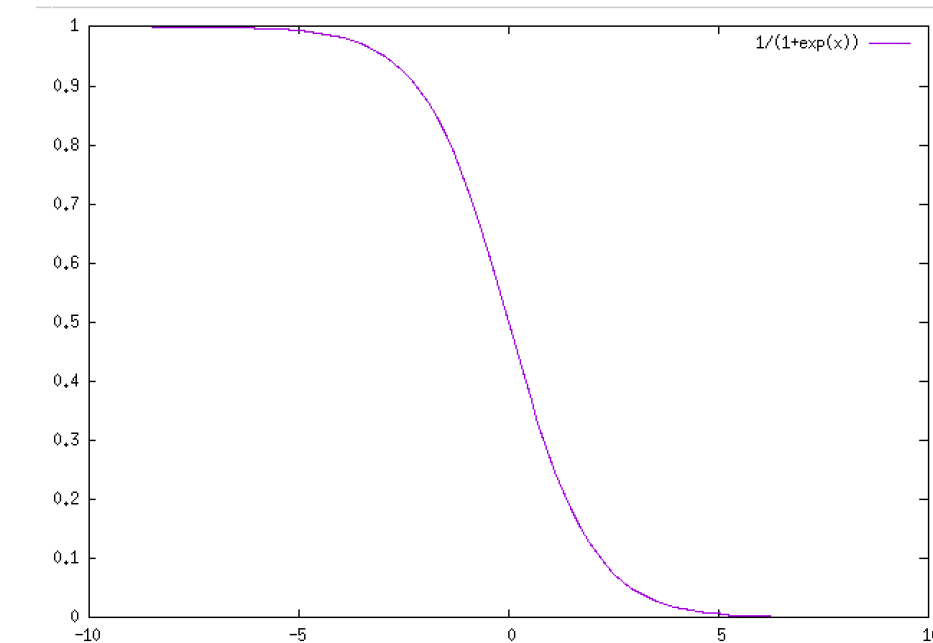
SP equations $\frac{\partial F_\beta(\boldsymbol{\lambda}, \boldsymbol{\mu})}{\partial \lambda_k} = 0$ and $\frac{\partial F_\beta(\boldsymbol{\lambda}, \boldsymbol{\mu})}{\partial \mu_l} = 0$

Define $X(k, l) = h[\beta(C_{kl} + \lambda(k) + \mu(l))]$ where $h(x) = \frac{1}{e^x + 1}$


$X(k, l) = \bar{G}(k, l)$ Thermal average of G

$$\left. \begin{aligned} \forall k, \sum_l X(k, l) &= 1 \\ \forall l, \sum_k X(k, l) &= 1 \end{aligned} \right\}$$

Set of $2N$ non-linear equations with $2N$ variables



Some properties of the SP

- The Hessian of F is negative, except for one trivial zero mode 
maximum is unique

- Free energy F  Internal energy U  as a function of T

$$F = U - TS$$

$$U = \sum_{kl} C(k, l) X(k, l)$$

Lattice gaz entropy

$$S = - \sum_{kl} (X(k, l) \ln X(k, l) + (1 - X(k, l)) \ln(1 - X(k, l)))$$

- $F^* = \lim_{\beta \rightarrow +\infty} F(\beta)$ $U^* = \lim_{\beta \rightarrow +\infty} U(\beta)$

At zero temperature, the SP free and internal energy converge to exact solutions

- Solve equations by **Newton-Raphson**. Very efficient.
- Start at high temperature and decrease temperature: **annealing procedure**.
When do we stop?
- When T decreases to zero, one may reach solutions where the $X(k, l)$ do not converge to 0 or 1: **problem is degenerate**.
- If the problem is degenerate, the entropy does not vanish at $T = 0$.
- In that case, how to obtain the optimal assignment?

Solving Degenerate Assignment Problems

- **Theorem:** if the problem is degenerate, there are ground state solutions with integer $G^*(k, l)$ with same total cost as the fractional solution (Gartner and Matousek, 2006).
- If Δ is the gap between the optimal solution and the second best solution, the optimal solution of the assignment problem with cost function

$$C'(k, l) = C(k, l) + \alpha \times \text{random}(k, l)$$

$\in [0, 1]$

with $\alpha < \frac{\Delta}{2N}$ has the same optimal assignment as the original $C(k, l)$ cost

- The randomized original problem is non degenerate.
- If all entries of $C(k, l)$ are scaled to be integer, then $\Delta \geq 1$ and it is sufficient to have

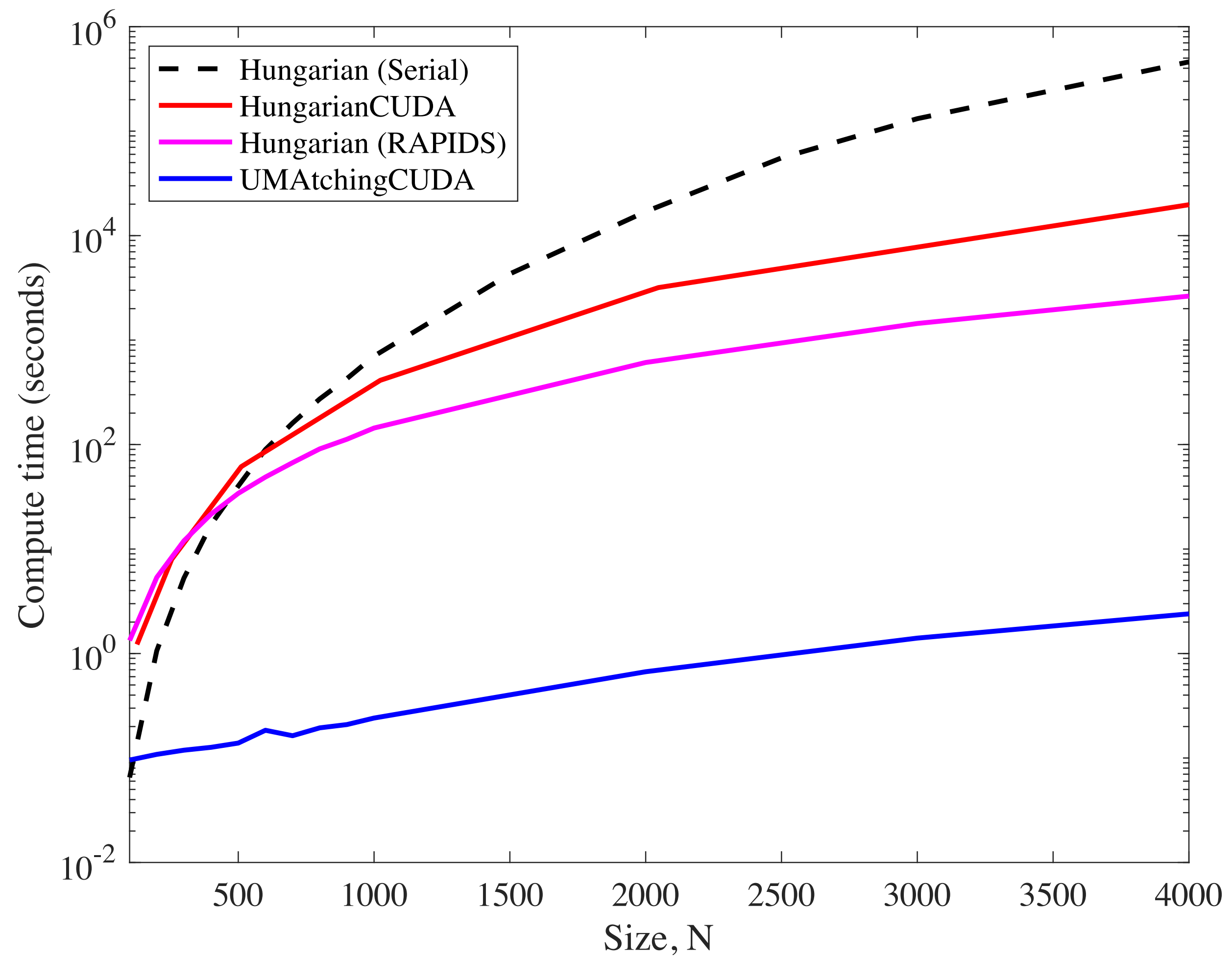
$$\alpha < \frac{1}{2N}$$

When to stop the annealing?

- If the problem is **non-degenerate**, at low enough temperature, the matrix $X(k, l)$ becomes **row-dominant**: each row contains one and only one element $> 1/2$ (since $\sum_{k,l} X(k, l) = 1$)
- Theorem: At that point, one can stop and replace in each row the dominant $X(k, l)$ by 1 and all others by 0. This is the ground state assignment $G^*(k, l)$
- If the problem is **degenerate**, make it first non-degenerate by adding the proper random noise then use above theorem.

Implementation

- Apparent computational complexity is $O(N^2)$ compared to $O(N^3)$ for Hungarian algorithm.
- Can be parallelised and run on GPU.
- Storage space required $O(N^2)$. Limit of $N=30000$ on GPU.



For $N = 4000$, computational times (in seconds):

Hungarian sequential
460000

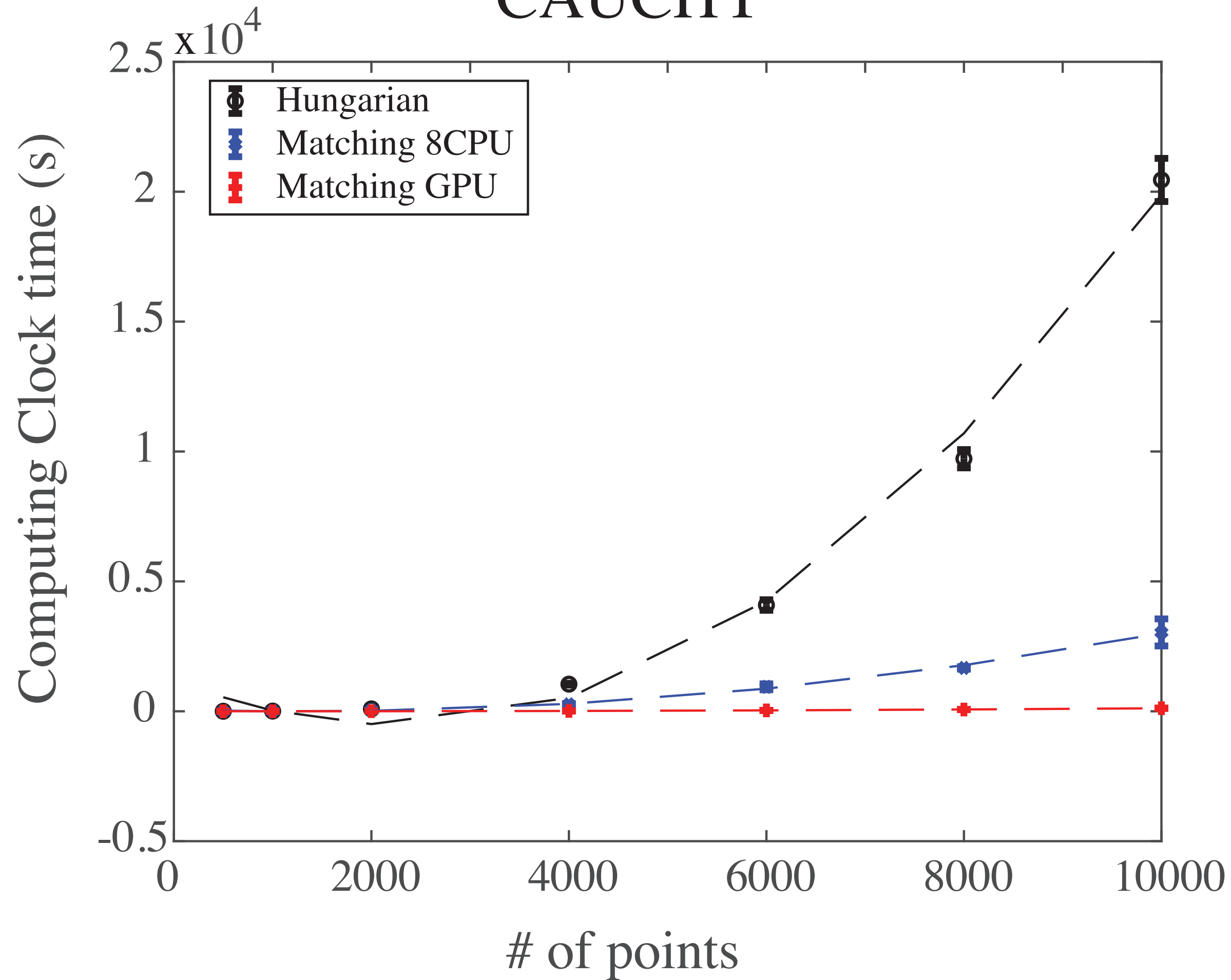
Hungarian CUDA
21590

Hungarian NVIDIA
2638

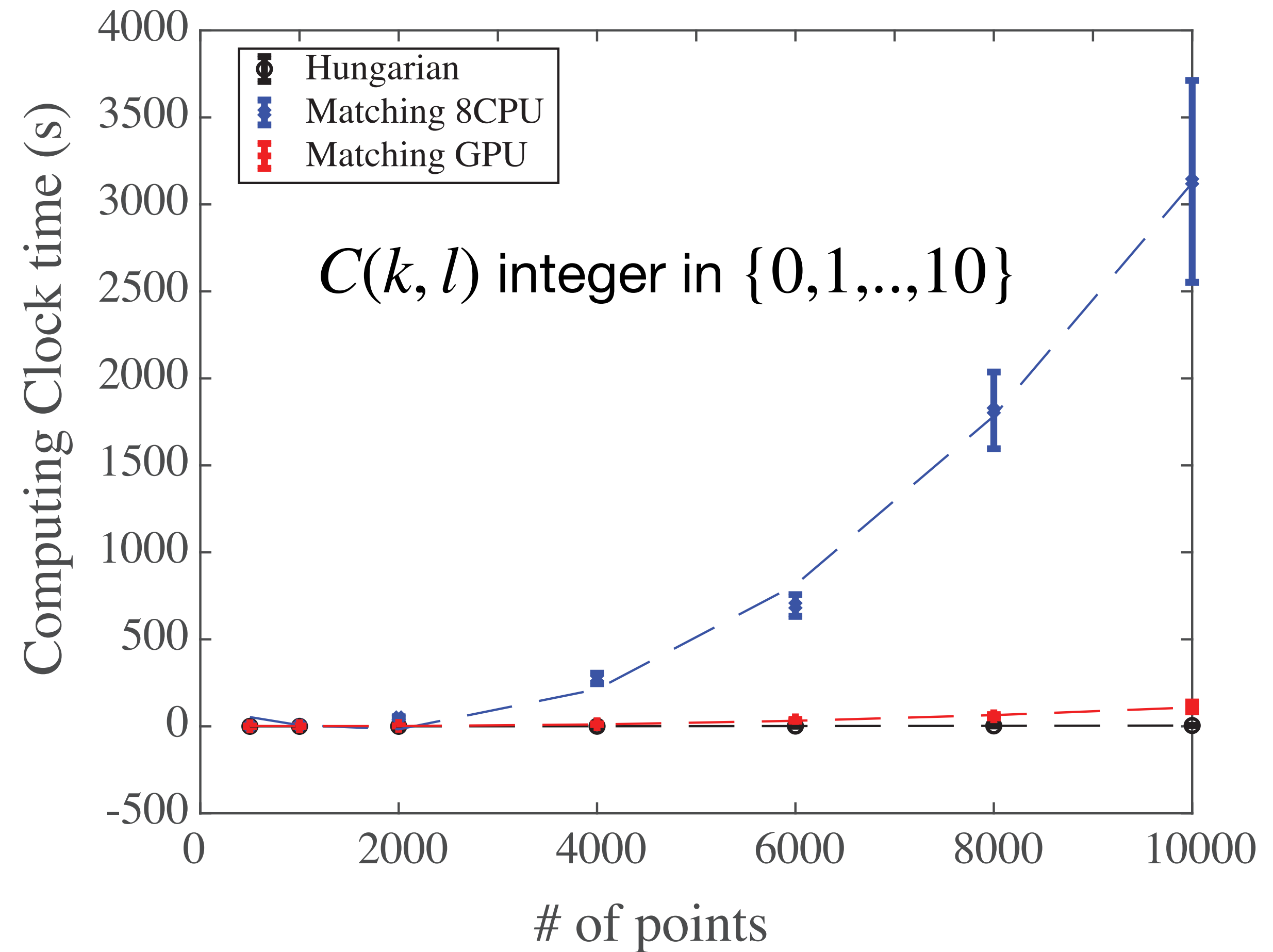
UMatchng
2.40

Test with i.i.d. random costs

CAUCHY



INTEGER

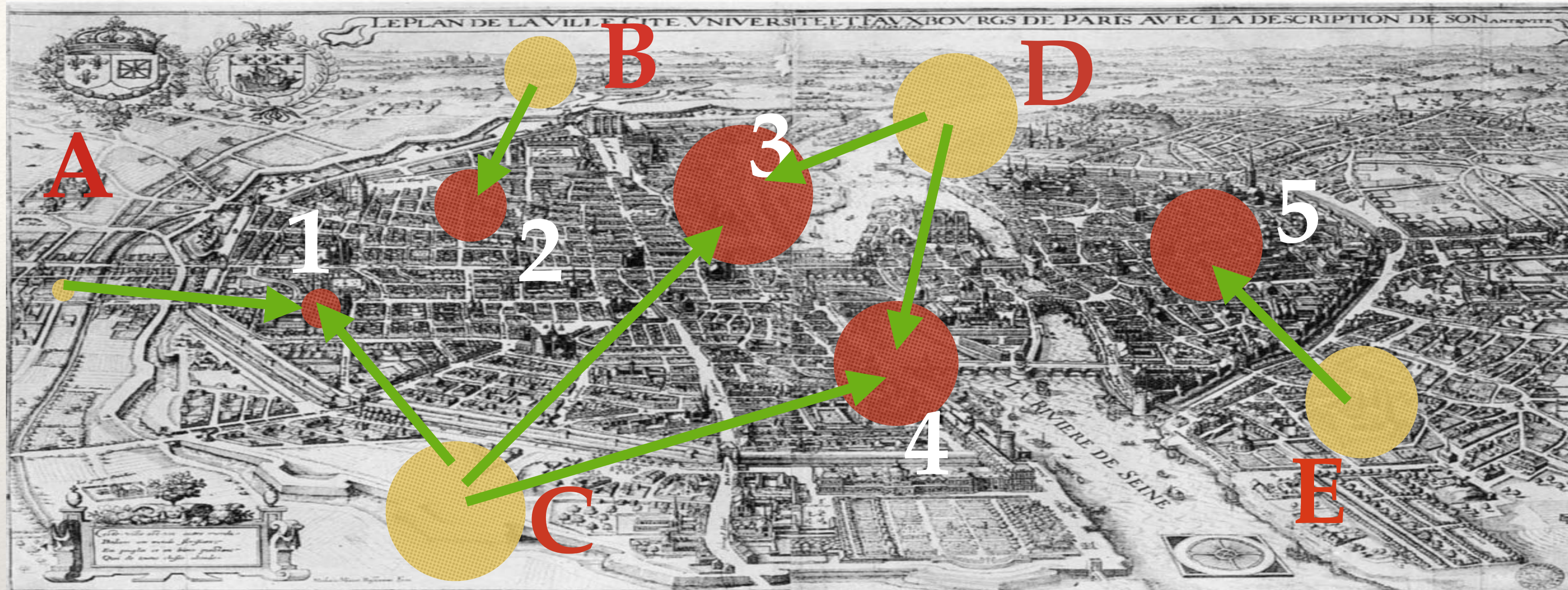


Optimal Transport: Transport Plan



	A	B	C	D	E
1	2	3	2,5	5	8
2	3	1,5	3	4	7,5
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Optimal Transport: Transport Plan



	A	B	C	D	E		A	B	C	D	E
1	2	3	2,5	5	8	1	●		●		
2	3	1,5	3	4	7,5	2		●			
3	4	1,5	3,5	2	4,5	3			●	●	
4	6	4	3	3	4	4			●	●	
5	9	6,5	7	3	2	5					●

Kantorovitch formulation: breaking the stones

$P(x, y)$ is a transport plan from ρ_0 to ρ_1 iff

$$\begin{cases} \int dy P(x, y) = \rho_0(x) \\ \int dx P(x, y) = \rho_1(y) \end{cases}$$

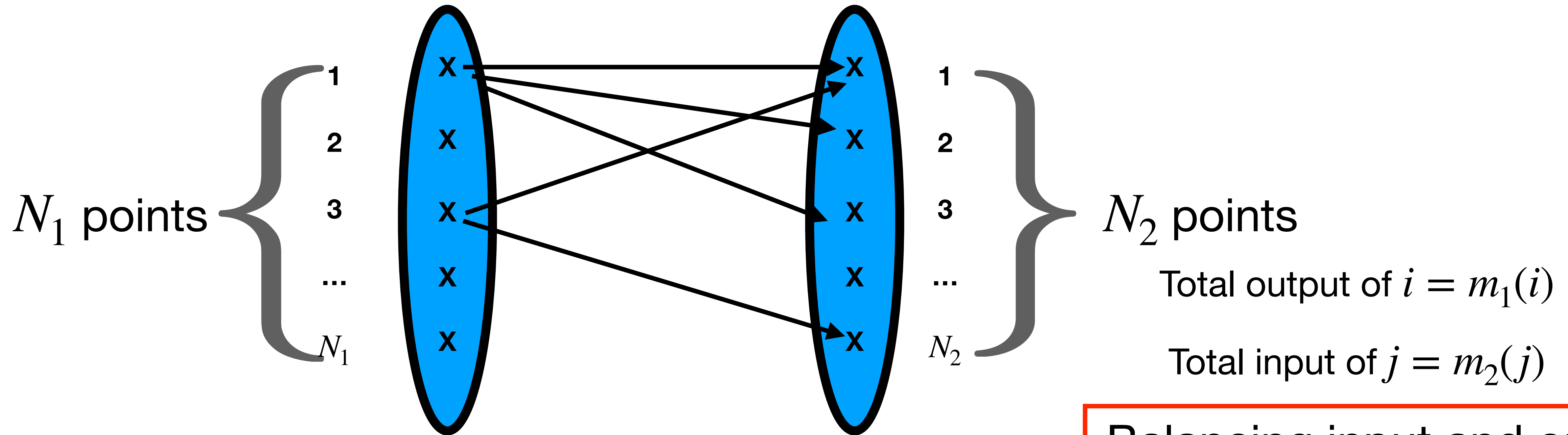
Cost function $C(x, y) \geq 0$

$$d(\rho_0, \rho_1) = \inf_{P \in \text{transport}} \int dx \int dy C(x, y) P(x, y) \quad \text{Identical to Monge distance}$$

Monge-Kantorovitch distance

$$d_p(\rho_0, \rho_1) = \inf_{P \in \text{transport}} \int dx \int dy |x - y|^p P(x, y) \quad \text{Wasserstein distance}$$

Optimal Transport



C_{ij} = transport cost from i to j

$G_{ij} \in [0,1]$ = transport plan

$N_1 \times N_2$ matrices

Find the best transport plan to minimise $\mathcal{C} = \sum_{ij} C_{ij} G_{ij}$

Balancing input and output

$$\forall i, \sum_j G_{ij} = m_1(i)$$

$$\forall j, \sum_i G_{ij} = m_2(j)$$

$$\sum_i m_1(i) = \sum_j m_2(j)$$

$N \times N$ Cost Matrix C_{ij}
 Transport plan G_{ij} with

$$\left\{ \begin{array}{l} G_{ij} \in [0, 1] \\ \forall i \in \{1, \dots, N_1\}, \sum_{j=1}^{N_2} G_{ij} = m_1(i) \\ \forall j \in \{1, \dots, N_2\}, \sum_{i=1}^{N_1} G_{ij} = m_2(j) \end{array} \right.$$

Cost Function
$$E = \sum_{i,j} C_{ij} G_{ij}$$

Partition function at temperature

$$Z(\beta) = \int_0^1 \prod_{ij} dG_{ij} \prod_{i=1}^{N_1} \delta \left(\sum_{j=1}^{N_2} G_{ij} - m_1(i) \right) \prod_{j=1}^{N_2} \delta \left(\sum_{i=1}^{N_1} G_{ij} - m_2(j) \right) e^{-\beta \sum_{ij} C_{ij} G_{ij}}$$

Optimal Transport at Finite Temperature

$$Z = \int \prod_k d\lambda_k \int \prod_l d\mu_l e^{-\beta F_{\text{eff}}(\beta, i\lambda_k, i\mu_l)}$$

$$F_{\text{eff}}(\beta, \lambda, \mu) = - \left(\sum_k \lambda_k m_1(k) + \sum_l \mu_l m_2(l) \right) - \frac{1}{\beta} \sum_{kl} \ln \left(\frac{1 - e^{-\beta(C_{kl} + \lambda_k + \mu_l)}}{\beta(C_{kl} + \lambda_k + \mu_l)} \right).$$

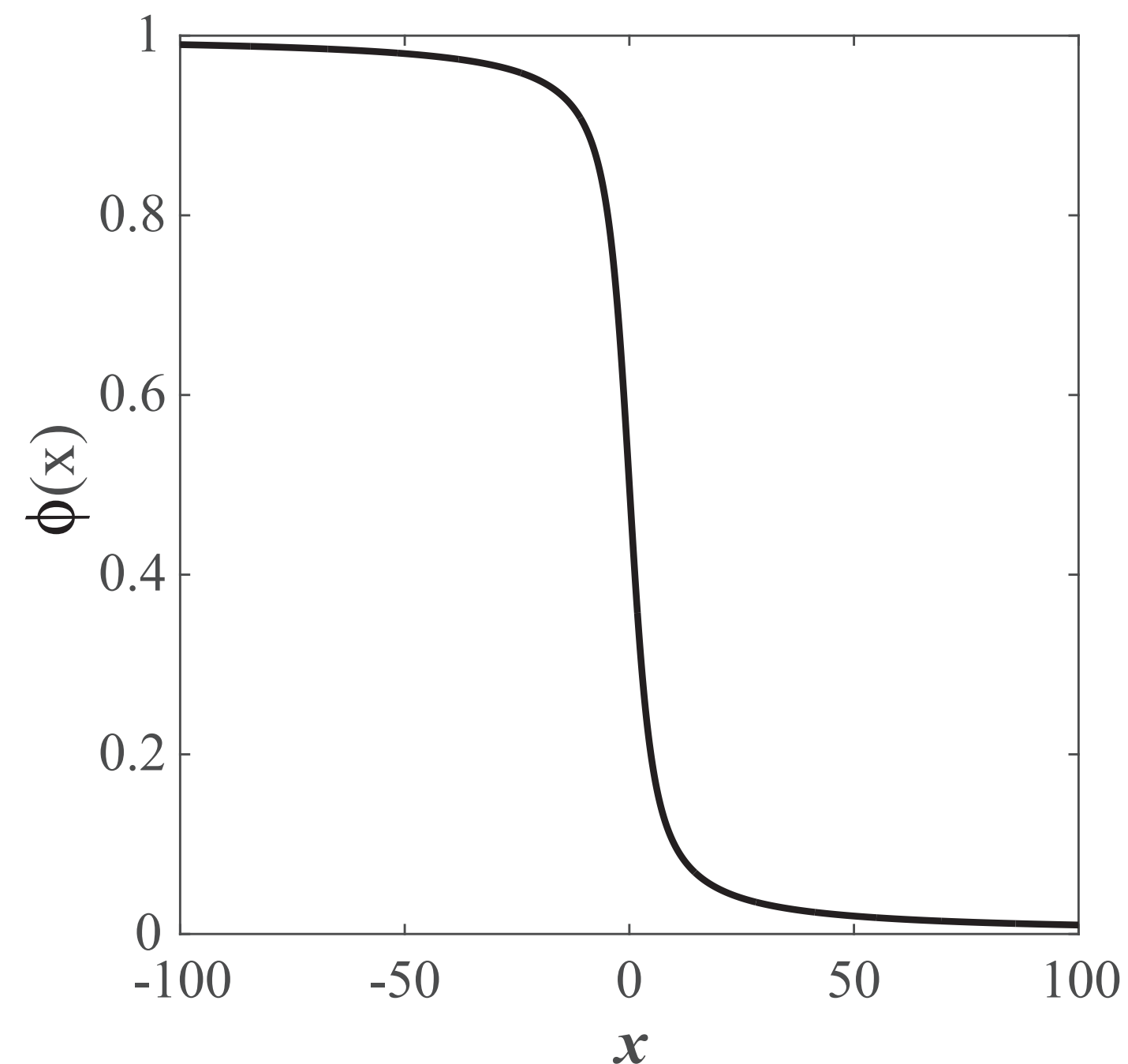
Saddle-Point Approximation

$$\frac{\partial \mathcal{F}_{\text{eff}}(\beta, i\lambda, i\mu)}{\partial \lambda_k} = 0 \quad \text{and} \quad \frac{\partial \mathcal{F}_{\text{eff}}(\beta, i\lambda, i\mu)}{\partial \mu_l} = 0.$$

$$\bar{G}_{kl} = \phi[\beta(C_{kl} + i\lambda_k + i\mu_l)]$$

$$\forall k, \quad \sum_l \bar{G}_{kl} = m_1(k),$$

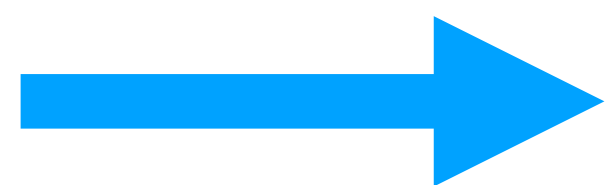
$$\forall l, \quad \sum_k \bar{G}_{kl} = m_2(l),$$



$$\phi(x) = \frac{e^{-x}}{e^{-x} - 1} + \frac{1}{x}.$$

Implementation

- Hessian of \mathcal{F}_{eff} is positive, with a trivial 0-mode (set one λ or μ to 0) so effective free energy is concave
- Solve by Newton-Raphson using a temperature annealing scheme $T \searrow 0$
- Free energy and internal energy are decreasing functions of β and converge to the optimal plan at 0 temperature
- **Triangular inequality** for the internal energy: 3 ensembles N_1, N_2, N_3 points, with $\forall (k, l) \forall j, C_{13}(k, l) \leq C_{12}(k, j) + C_{23}(j, l)$



$$U_{13} \leq U_{12} + U_{23} \quad \text{at any temperature}$$

Application - Computer Vision



Flip a coin - correct 50% of the time
Software fifteen years ago - not much better
Today - 99%

Application - Computer Vision

Dog or Muffin?

Still a challenge



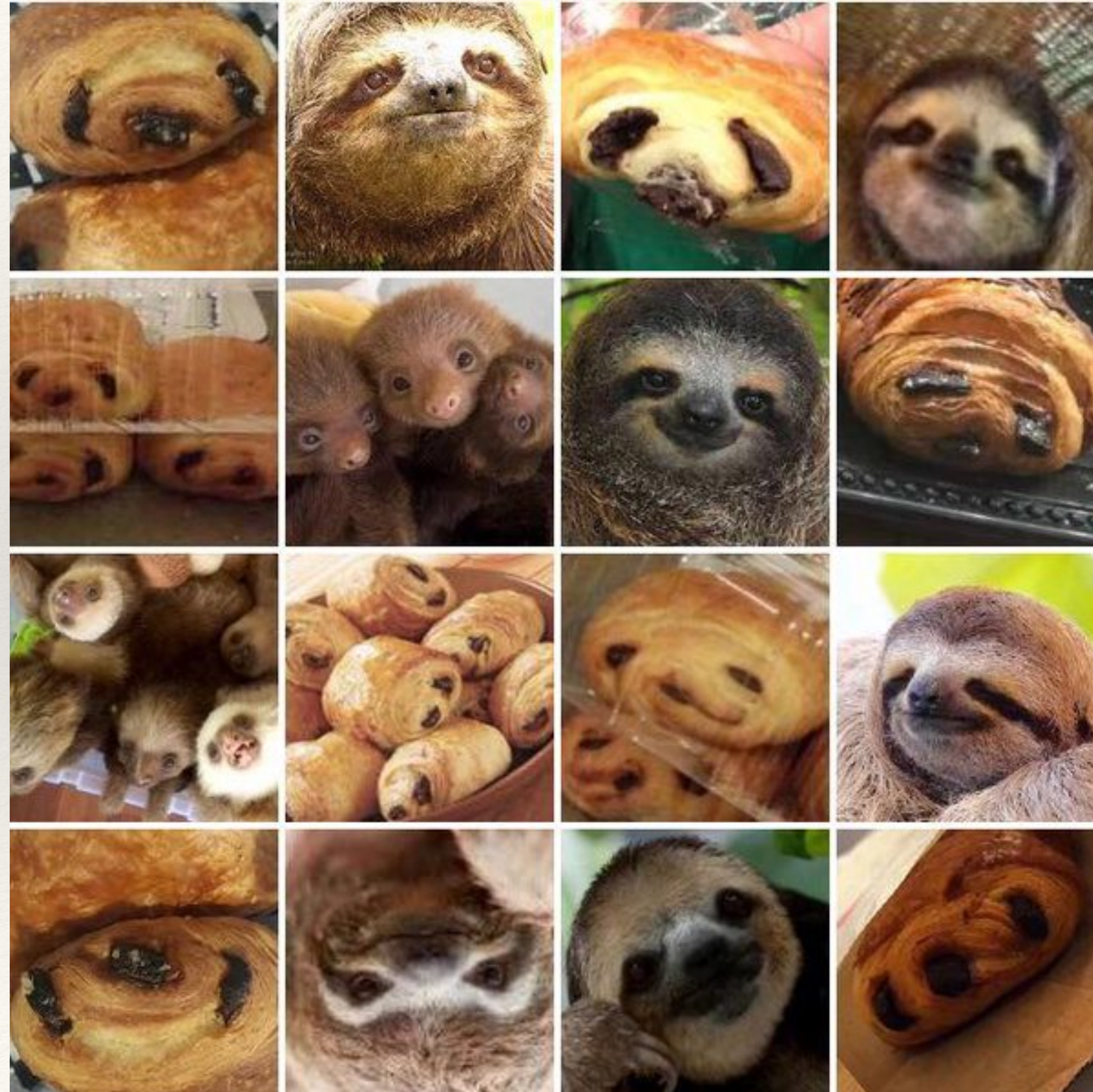
Application - Computer Vision

Puppy or Bagel?



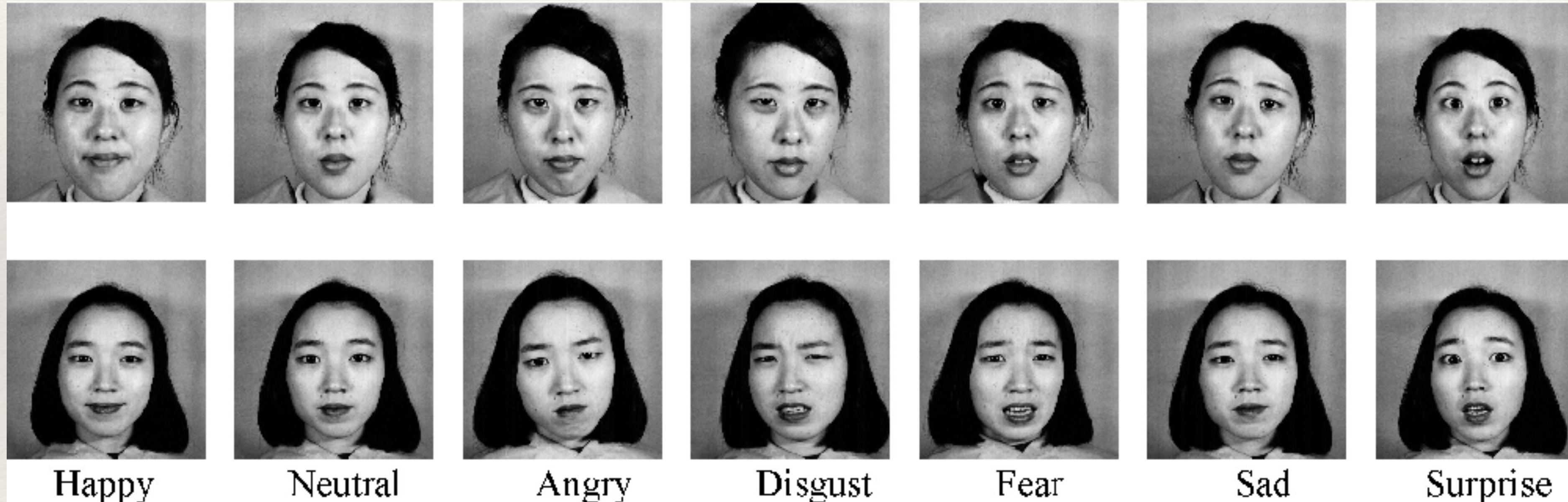
Application - Computer Vision

Pain au chocolat or Sloth ?



Comparing images: the Jaffe Dataset

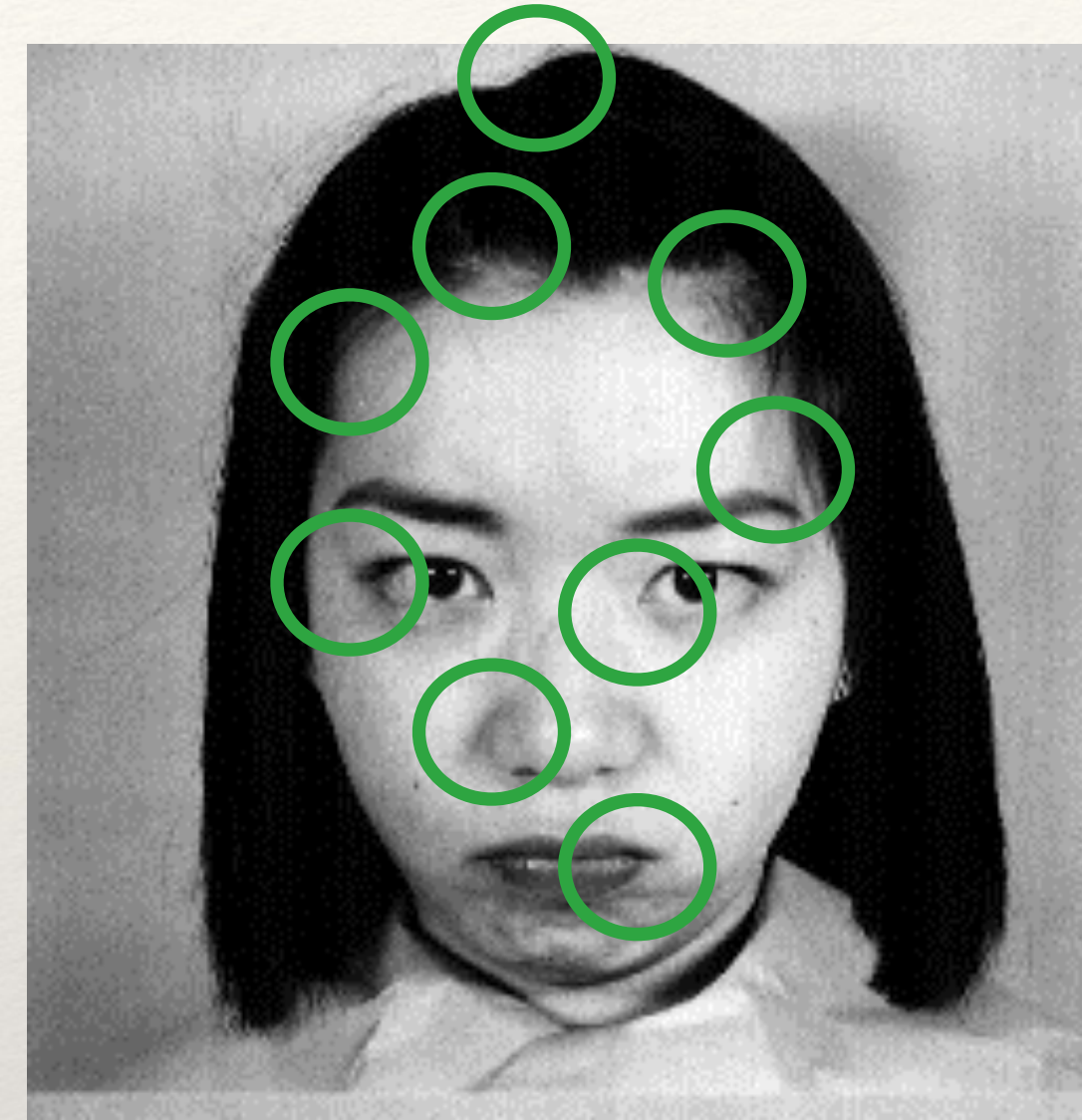
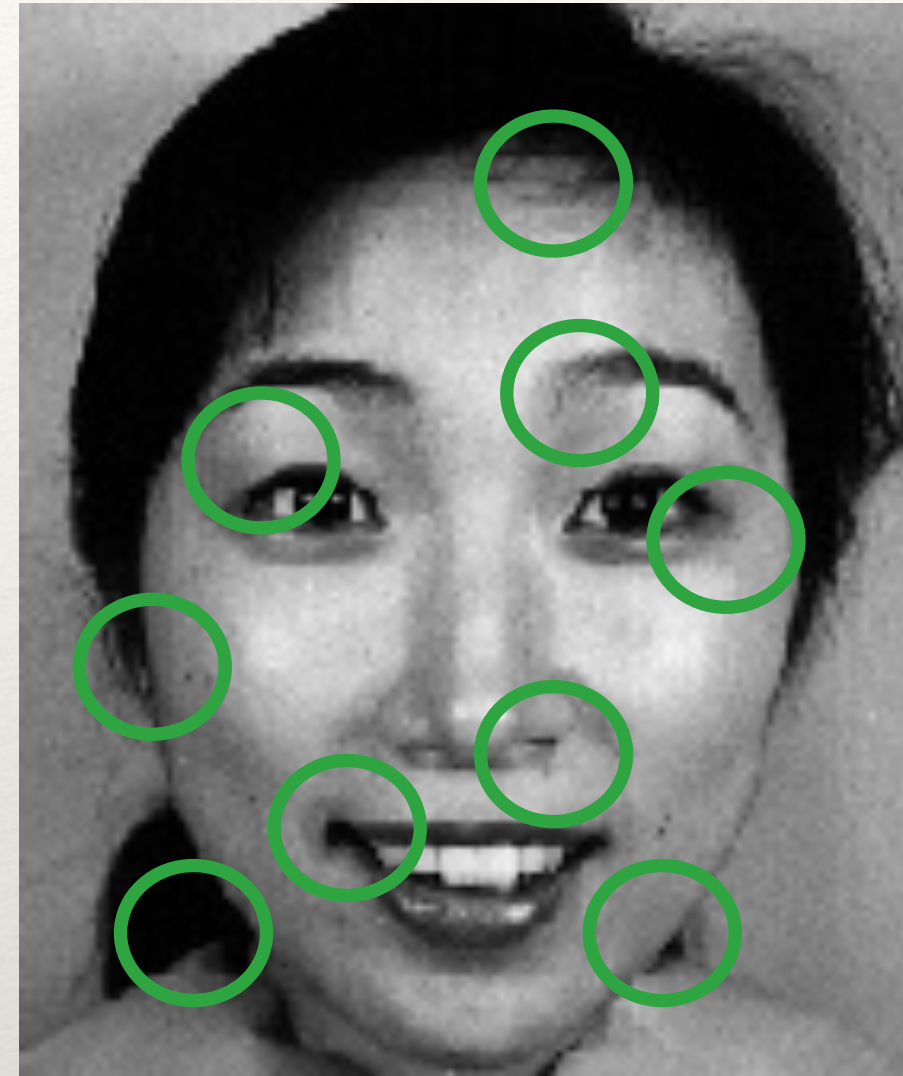
The database contains 213 images of 7 facial expressions (6 basic facial expressions + 1 neutral) posed by 10 Japanese female models.



Comparing images: the Jaffe Dataset

Comparing two images I_1 and I_2 :

a) Detect keypoints:



b) Assign mass: $1/N$

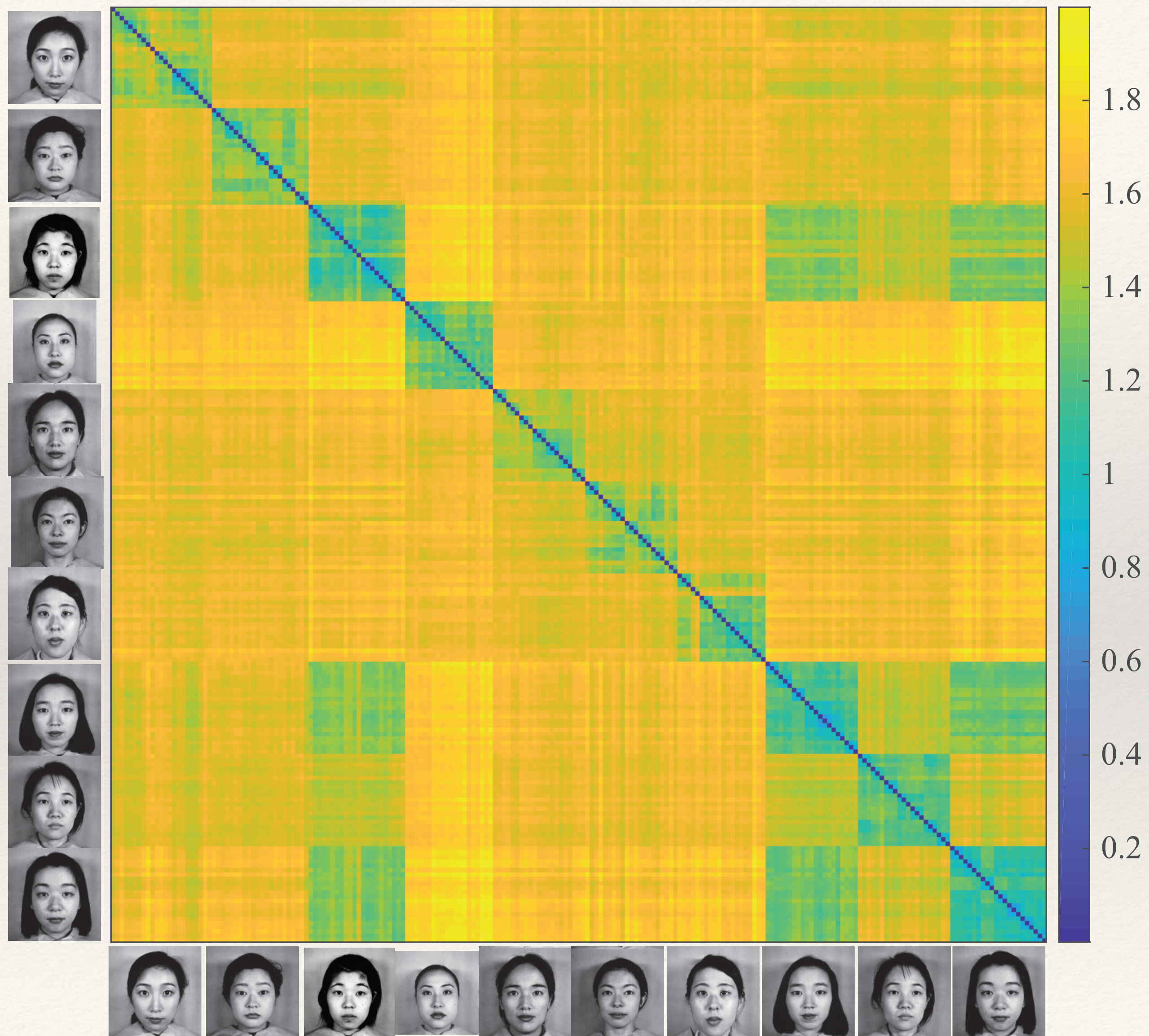
c) Assign cost matrix

- Each keypoint is characterized by a vector F of 64 "features": SURF
- For keypoint i of image 1 and j of image 2, $C(i, j) = ||F(i) - F(j)||$

d) Compute distance:

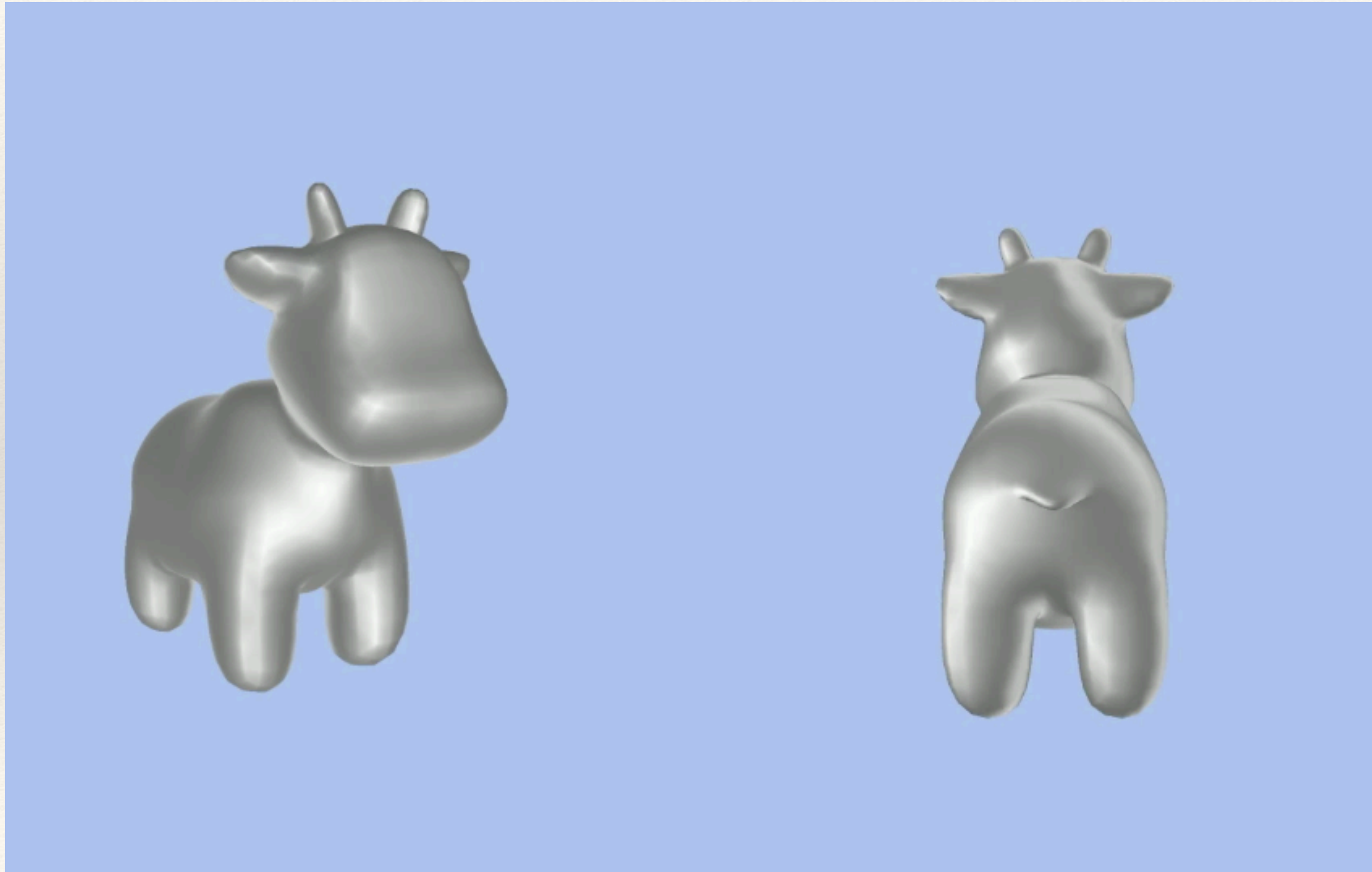
$$d(I_1, I_2) = U_{\beta}^{MF}(I_1, I_2)$$

Comparing images: the Jaffe Dataset

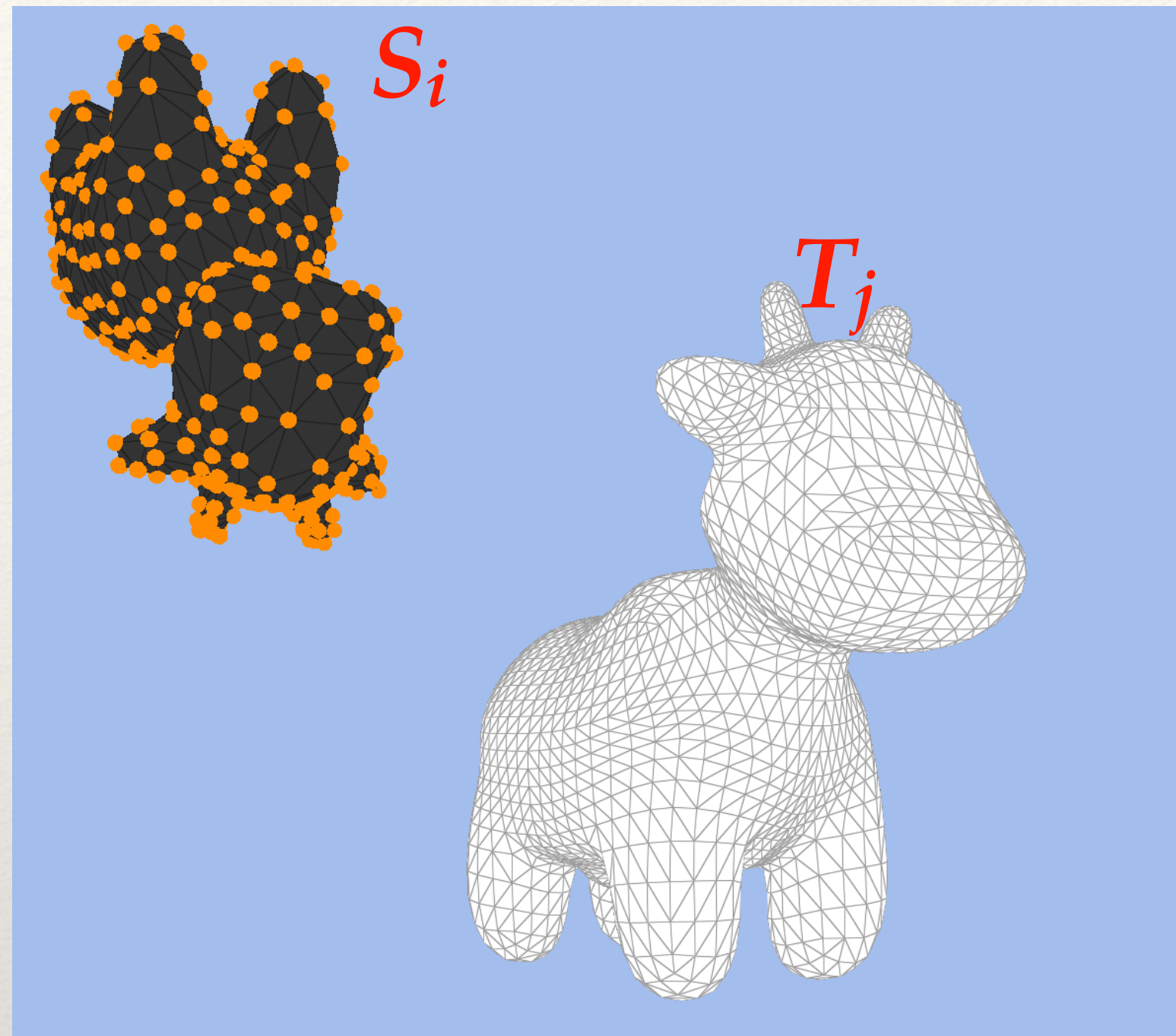


Comparing 3D shapes with OT

SPOT



Comparing 3d shapes



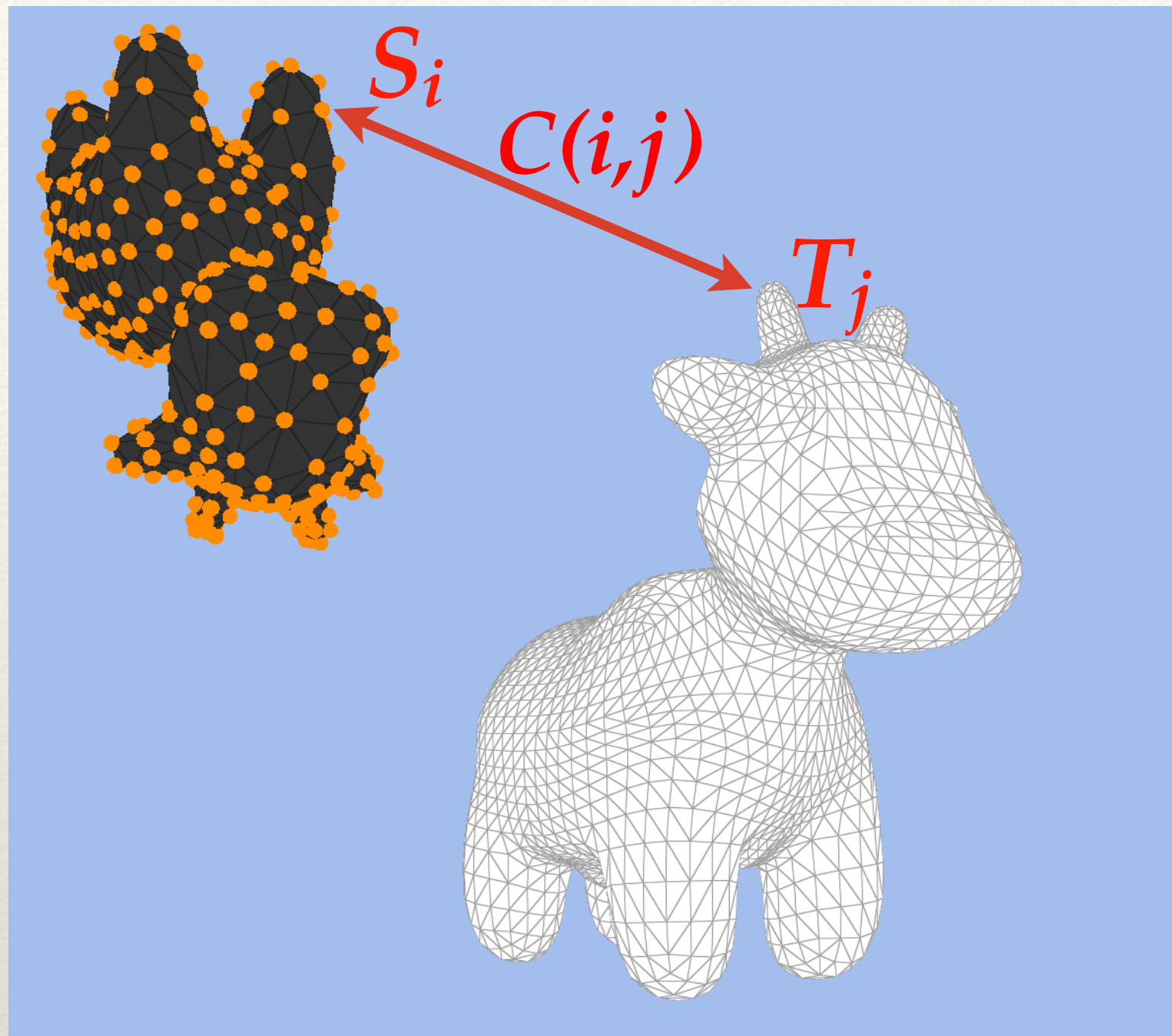
$$S = \{S_i\}_{i \in [1, N]}$$

$$m_1(i) = \frac{1}{N}$$

$$T = \{T_j\}_{j \in [1, M]}$$

$$m_2(j) = \frac{1}{M}$$

Comparing shapes



$$S = \{S_i\}_{i \in [1, N]}$$

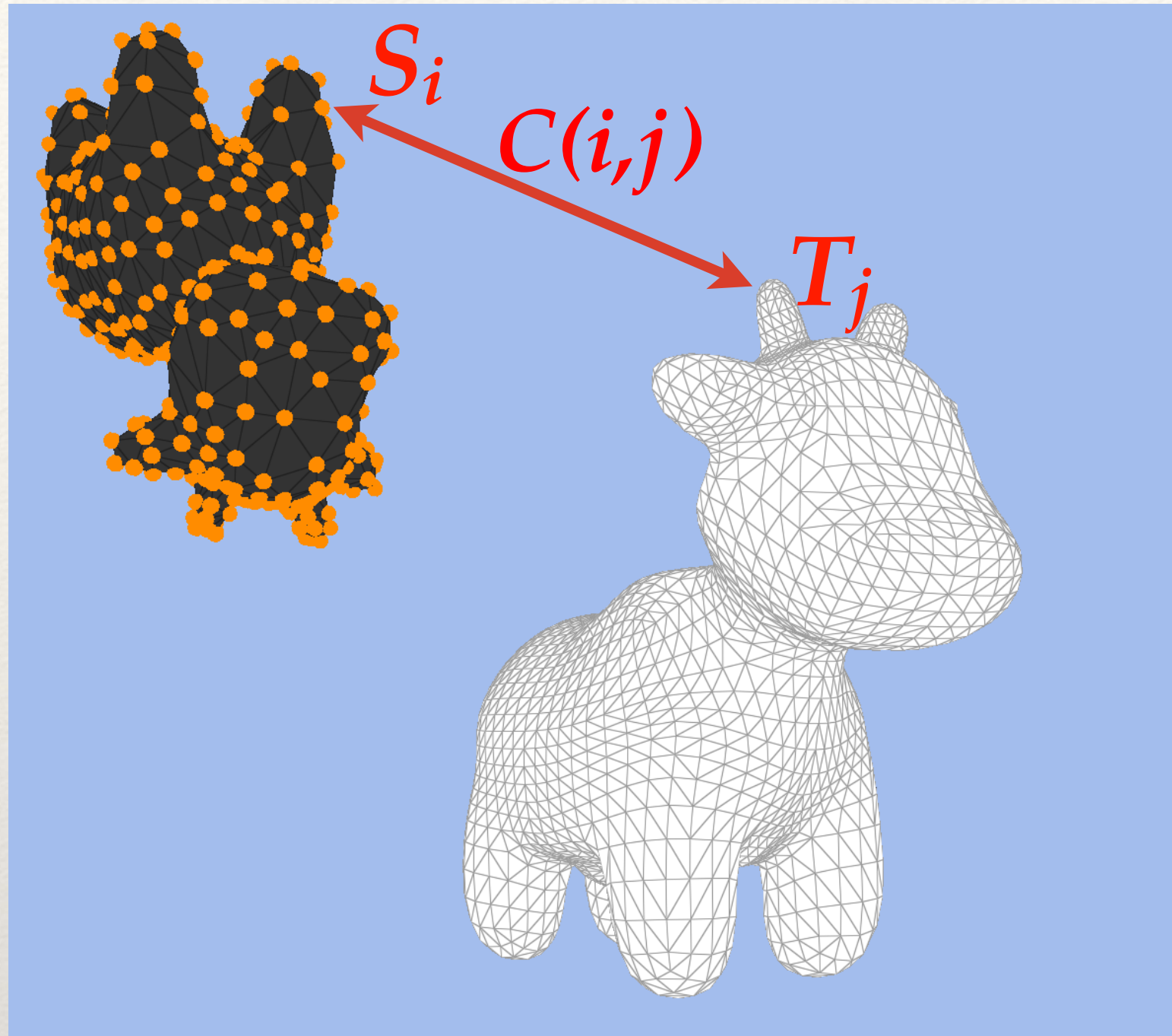
$$m_1(i) = \frac{1}{N}$$

$$T = \{T_j\}_{j \in [1, M]}$$

$$m_2(j) = \frac{1}{M}$$

$$C(i, j) = \text{dist}(S_i, T_j)$$

Comparing shapes



$$S = \{S_i\}_{i \in [1, N]}$$

$$m_1(i) = \frac{1}{N}$$

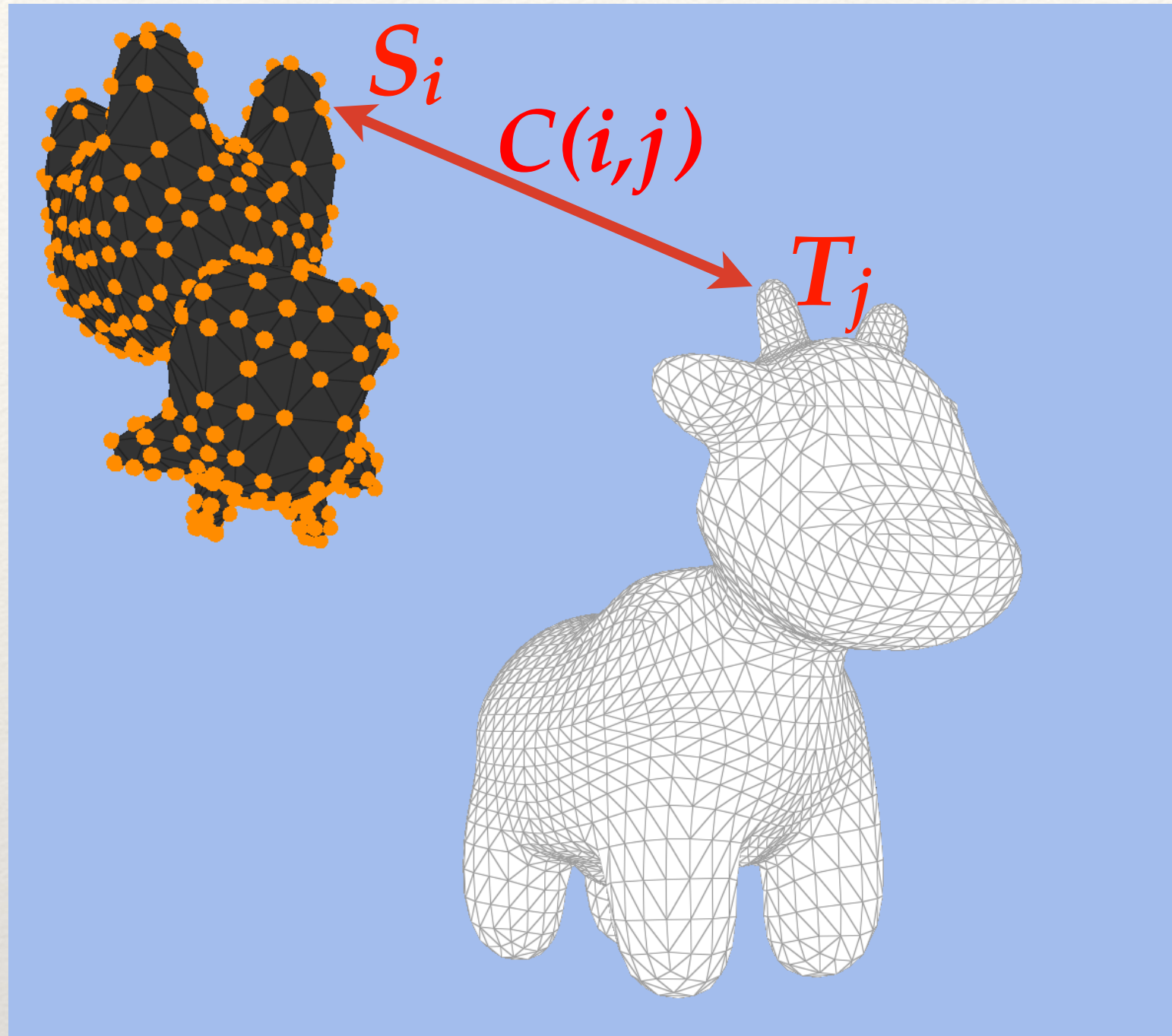
$$T = \{T_j\}_{j \in [1, M]}$$

$$m_2(j) = \frac{1}{M}$$

$$C(i, j) = \text{dist}(S_i, T_j)$$

$$d_{OT}(S, T) = \min_G \sum_i \sum_j C(i, j) G(i, j)$$

Comparing shapes



$$S = \{S_i\}_{i \in [1,N]}$$

$$m_1(i) = \frac{1}{N}$$

$$T = \{T_j\}_{j \in [1,M]}$$

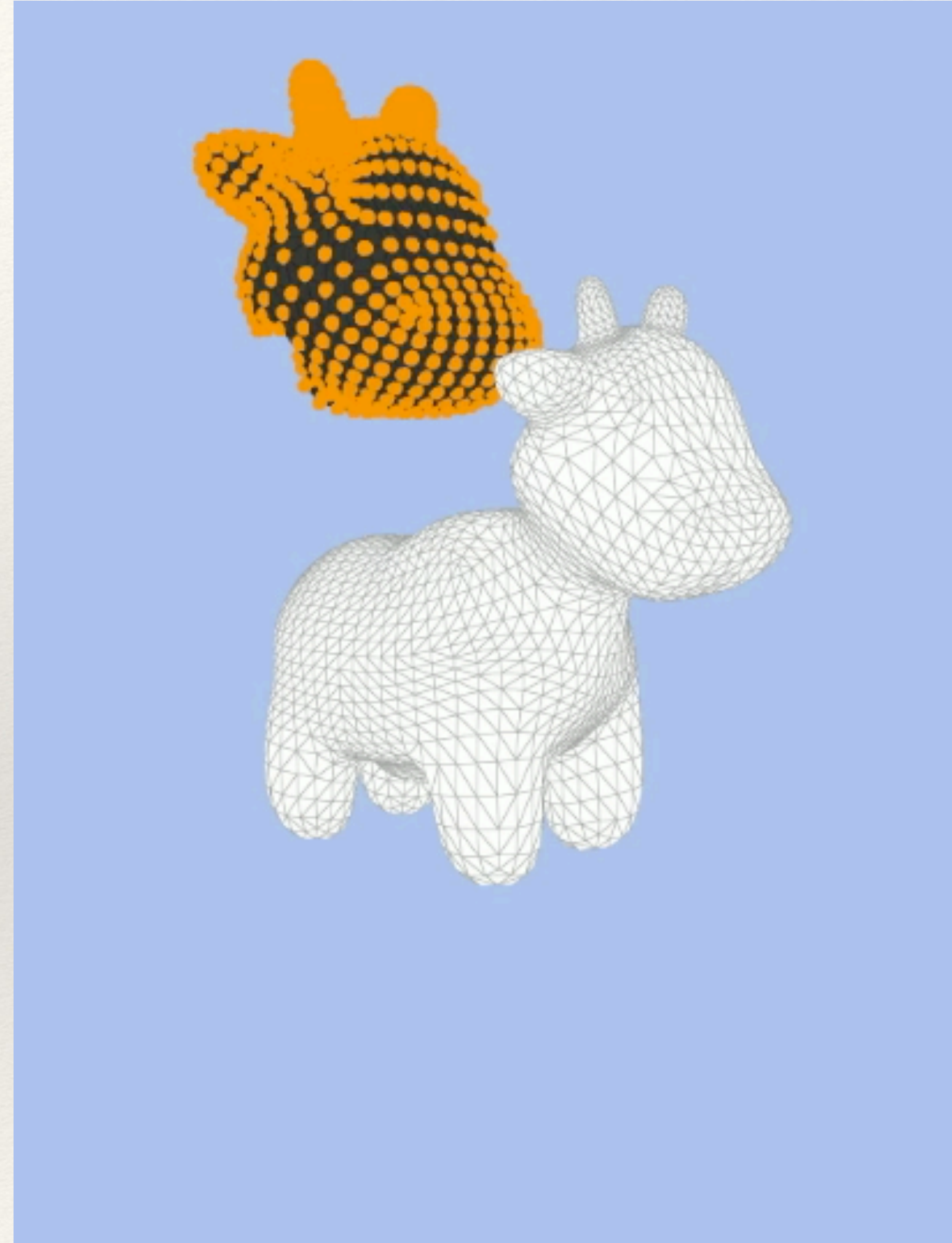
$$m_2(j) = \frac{1}{M}$$

$$C(i, j) = \text{dist}(S_i, T_j)$$

$$d_{OT}(S, T) = \min_G \sum_i \sum_j C(i, j) G(i, j)$$

$$d(S, T) = \min_R d_{OT}(R(S), T) = \min_R \left(\min_G \sum_i \sum_j C_R(i, j) G(i, j) \right)$$

Comparing shapes: Problem!



OT with variable masses

Minimize

$$U(G, m_1, m_2) = \sum_i \sum_j C(i, j) G(i, j)$$

under the constraints:

$$G_{ij} \geq 0$$

$$\sum_j G(i, j) = m_1(i) \quad \forall i$$

$$\sum_i G(i, j) = m_2(j) \quad \forall j$$

OT with variable masses

Minimize

$$U(G, m_1, m_2) = \sum_i \sum_j C(i, j) G(i, j)$$

under the constraints:

$$G_{ij} \geq 0$$

$$\sum_j G(i, j) = m_1(i) \quad \forall i \quad m_1(i) \geq 0$$

$$\sum_i G(i, j) = m_2(j) \quad \forall j \quad m_2(j) \geq 0$$

$$\sum_i \sum_j G(i, j) = 1$$

OT with variable masses

Minimize

$$U(G, m_1, m_2) = \sum_i \sum_j C(i, j) G(i, j) + \alpha_1 \sum_i m_1(i)^2 + \alpha_2 \sum_j m_2(j)^2$$

under the constraints:

$$G_{ij} \geq 0$$

$$\sum_j G(i, j) = m_1(i) \quad \forall i$$

$$\sum_i G(i, j) = m_2(j) \quad \forall j$$

$$\sum_i \sum_j G(i, j) = 1$$

$$\begin{aligned}
Z_\beta(S_1, S_2) &= \int_0^1 \prod_{kl} dG(k, l) \int_{-\infty}^{+\infty} \prod_k dm_1(k) \int_{-\infty}^{+\infty} \prod_l dm_2(l) e^{-\beta \left(\sum_{kl} C(k, l) G(k, l) + \sum_k \alpha_1(k) m_1^2(k) + \sum_l \alpha_2(l) m_2^2(l) \right)} \\
&\times \int_{-\infty}^{+\infty} \prod_k d\lambda(k) e^{-i\beta\lambda(k) \left(\sum_l G(k, l) - m_1(k) \right)} \int_{-\infty}^{+\infty} \prod_l d\mu(l) e^{-i\beta\mu(l) \left(\sum_k G(k, l) - m_2(l) \right)} \\
&\times \int_{-\infty}^{+\infty} e^{-i\beta x \left(\sum_{kl} G(k, l) - 1 \right)} dx
\end{aligned}$$

OT with variable masses

Effective free energy:

$$F_\beta(\lambda, \mu, x) = -x - \frac{1}{4\alpha_1} \sum_k \lambda_k^2 - \frac{1}{4\alpha_2} \sum_l \mu_l^2 - \frac{1}{\beta} \sum_{kl} \ln \left[\frac{1 - e^{-\beta(C(k,l) + \lambda(k) + \mu(l))}}{\beta(C(k,l) + \lambda(k) + \mu(l))} \right]$$

Saddle Point Approximation:

$$\left\{ \begin{array}{l} \bar{G}(k, l) = \phi(\beta(C(k, l) + \lambda(k) + \mu(l))) \\ \sum_l \bar{G}(k, l) = \frac{\lambda_k}{2\alpha_1} \quad \forall k \\ \sum_k \bar{G}(k, l) = \frac{\mu_l}{2\alpha_2} \quad \forall l \\ \sum_{k,l} G(k, l) = 1 \end{array} \right. \quad \text{where} \quad \phi(x) = \frac{e^{-x}}{e^{-x} - 1} + \frac{1}{x}$$

OT with variable masses

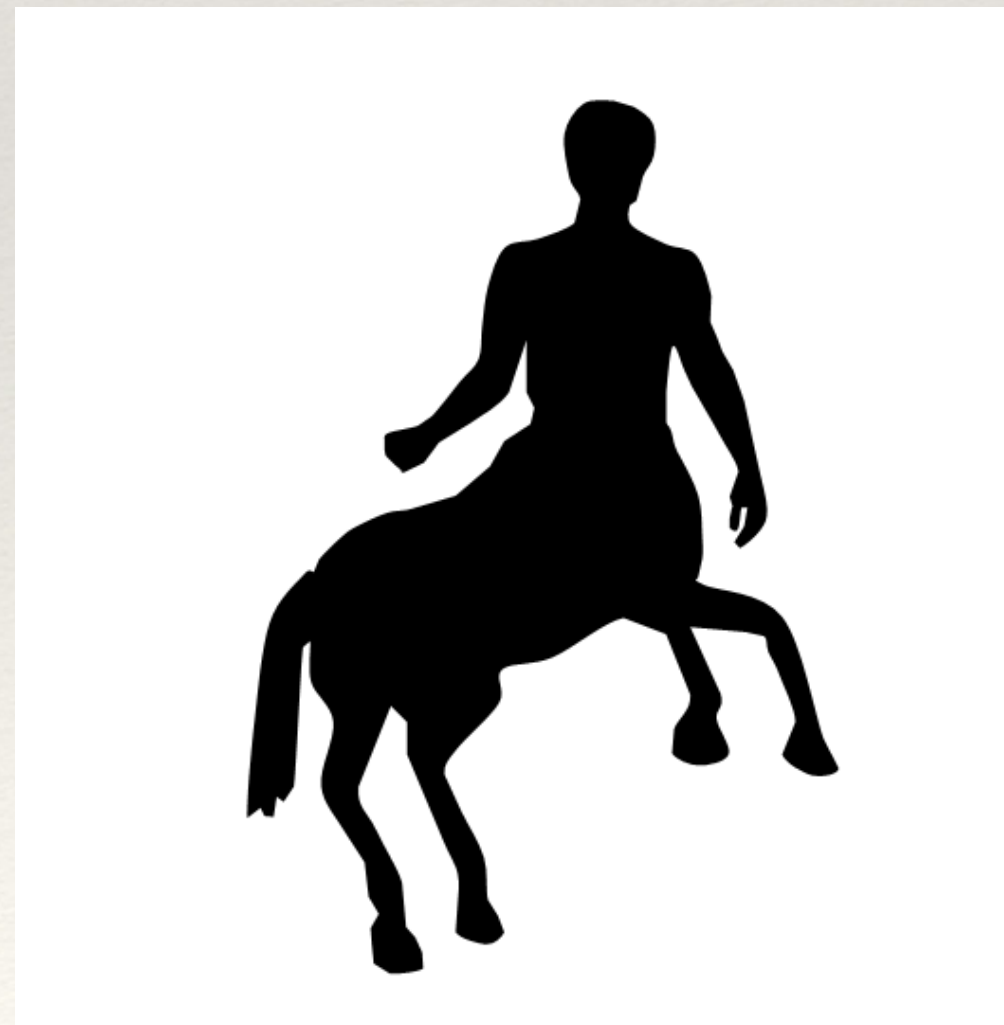
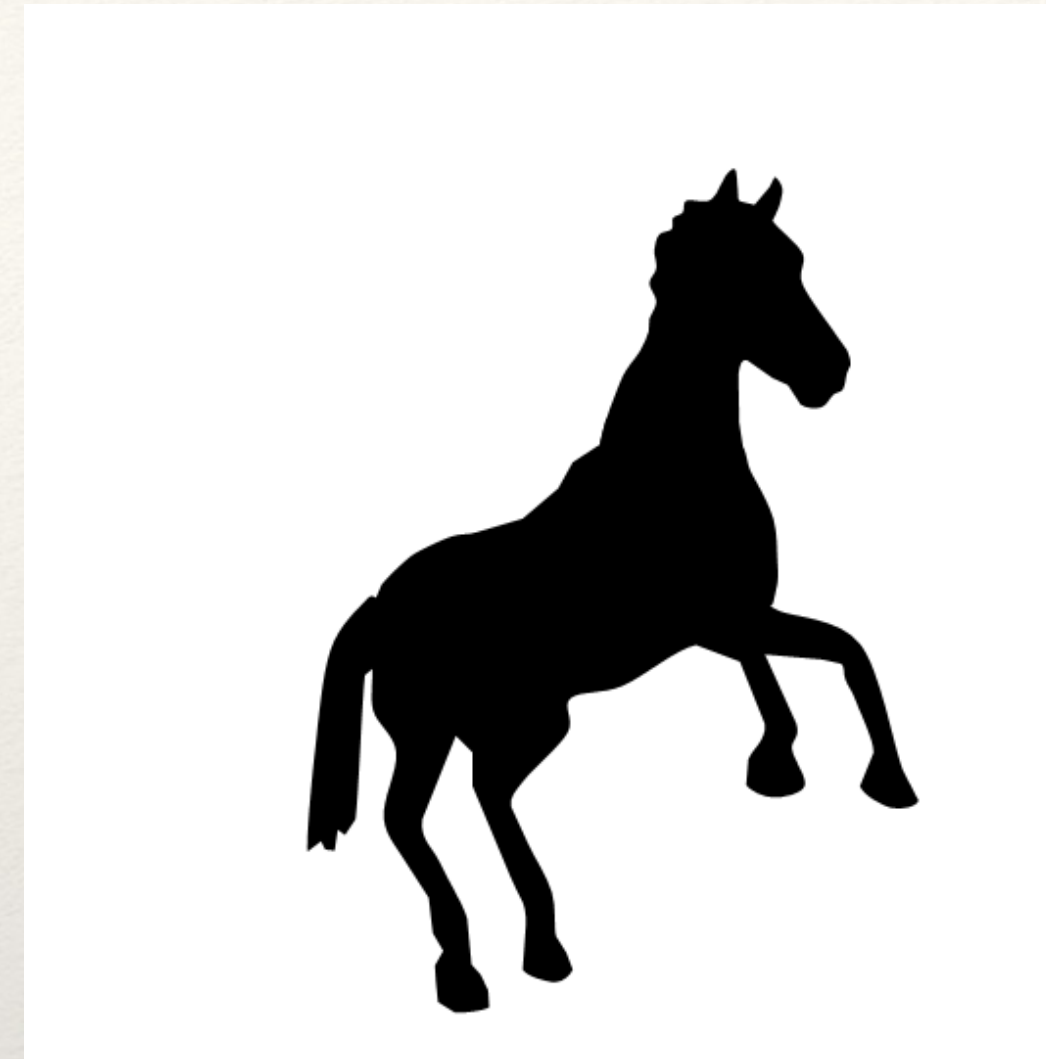
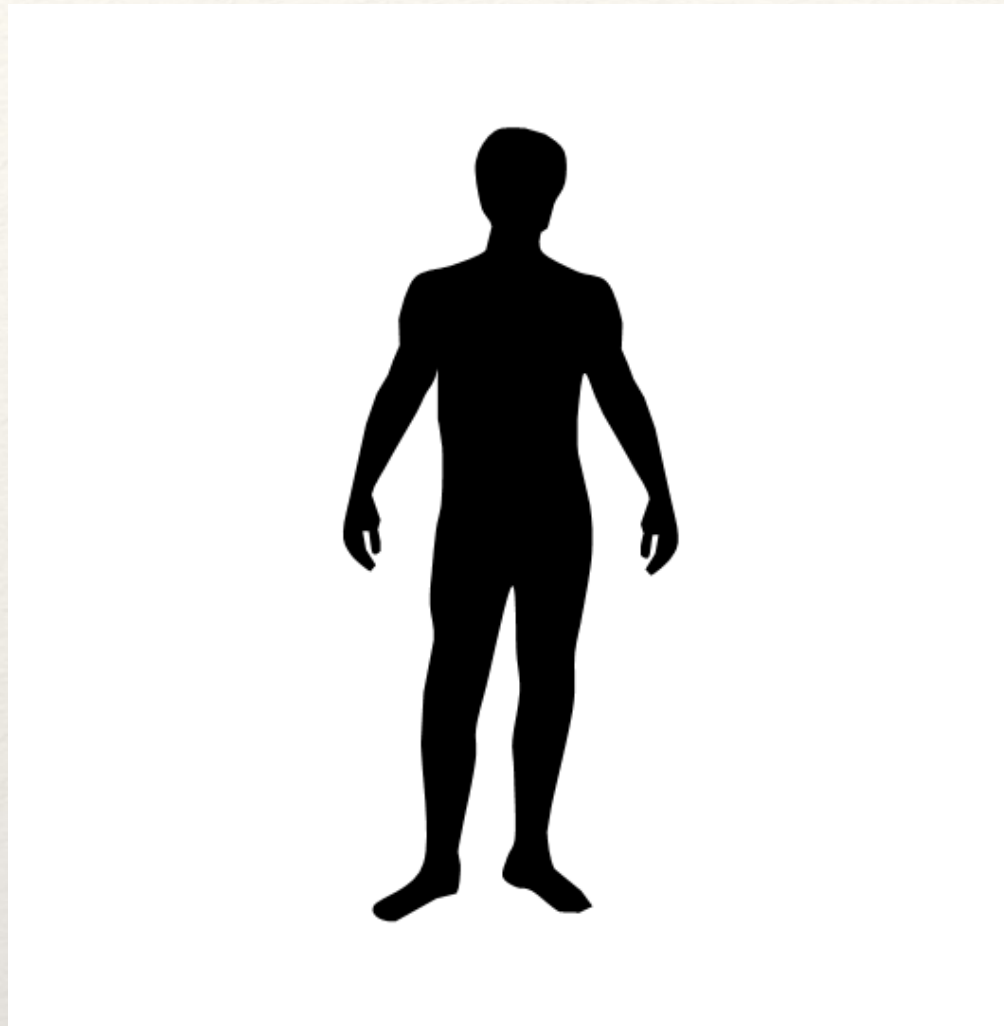


Image comparisons

Fixed masses

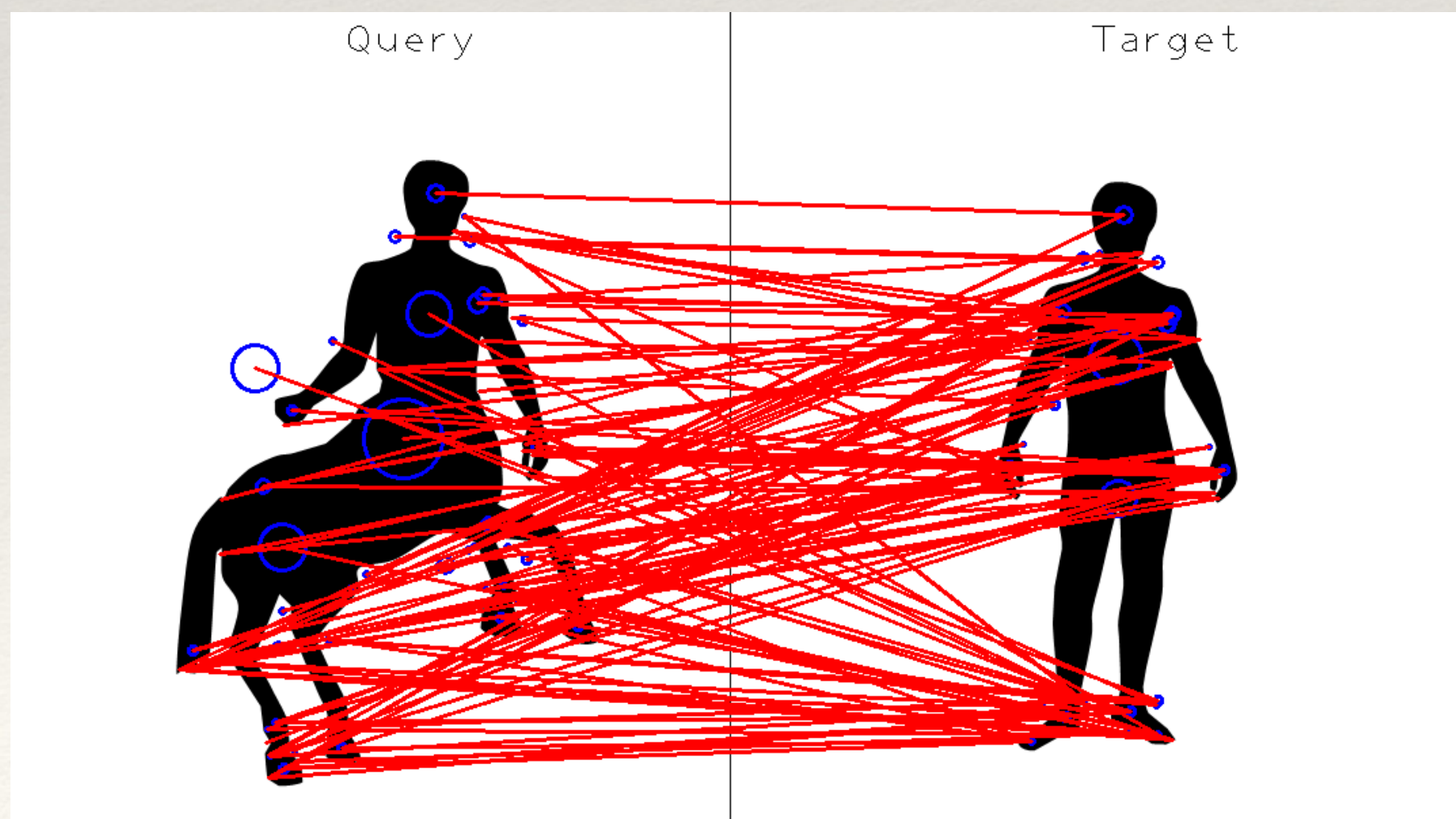
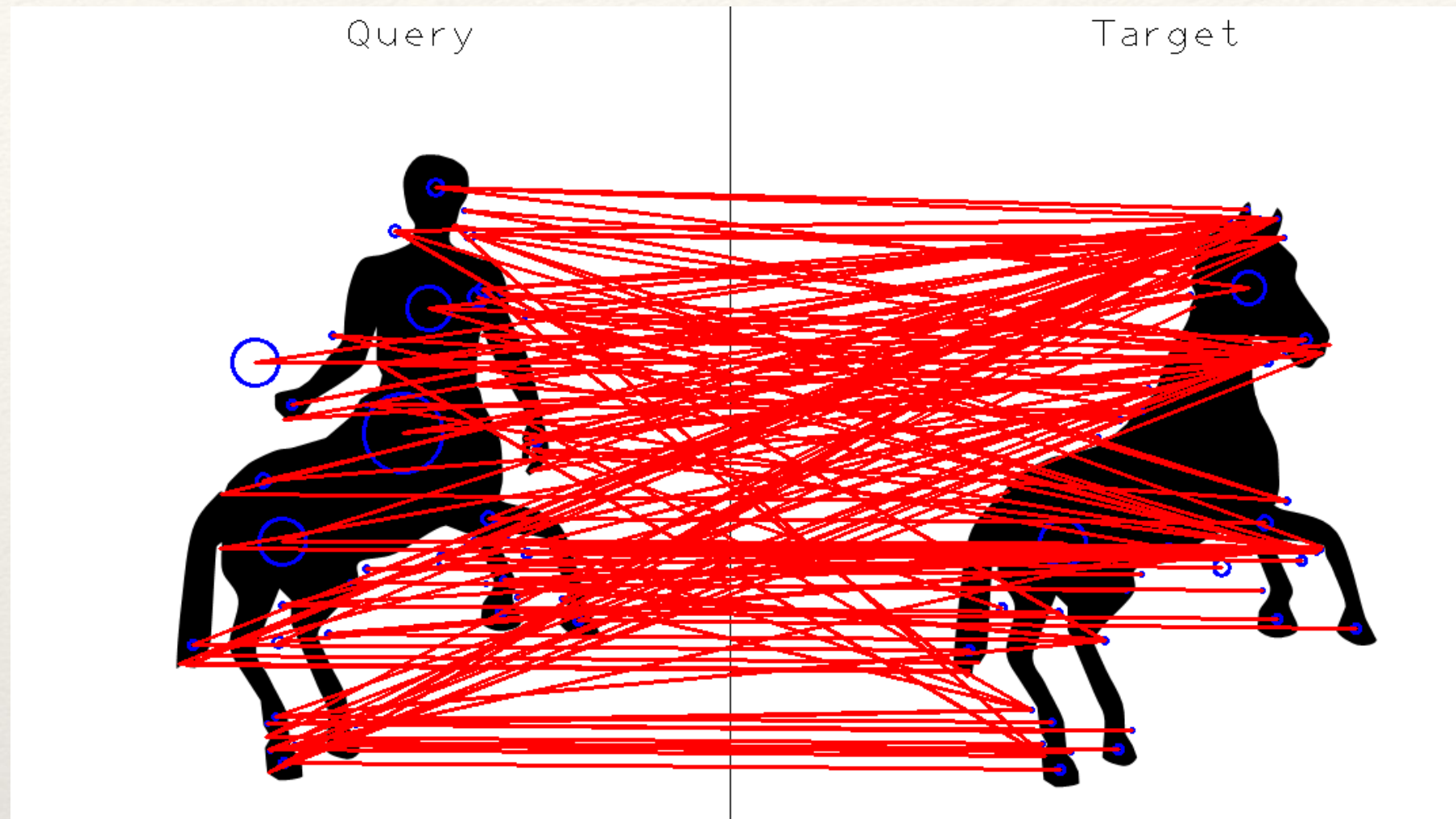
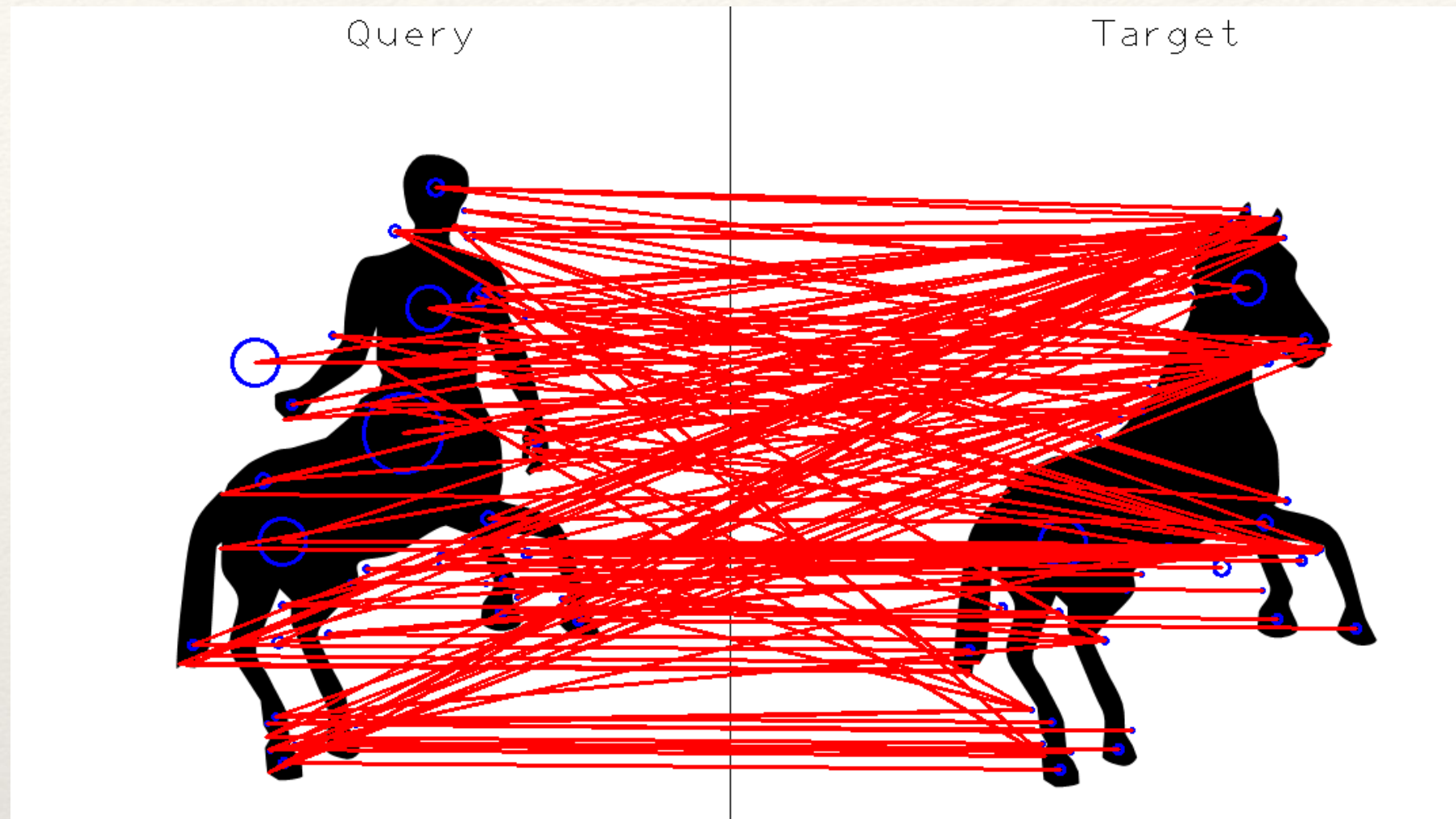
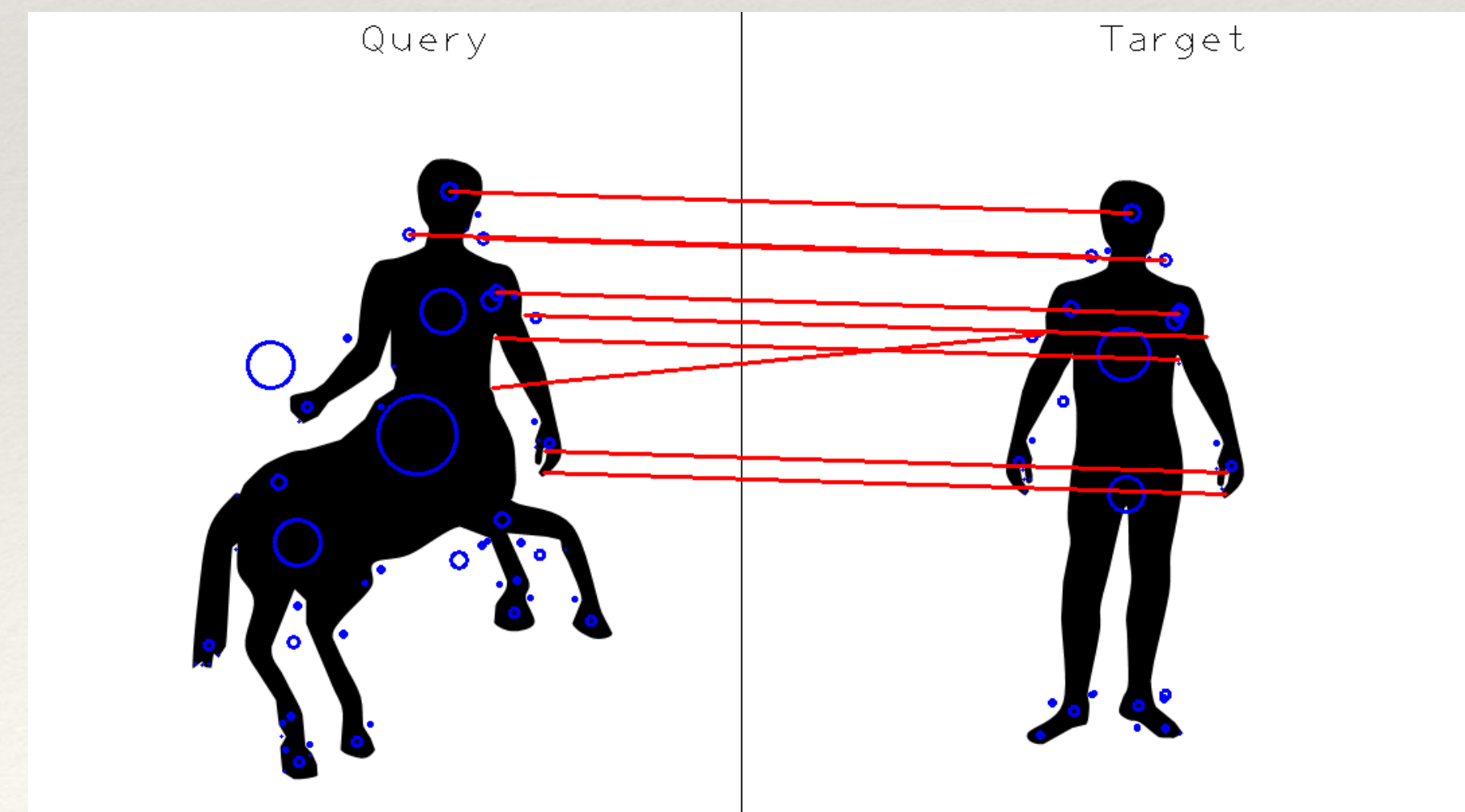
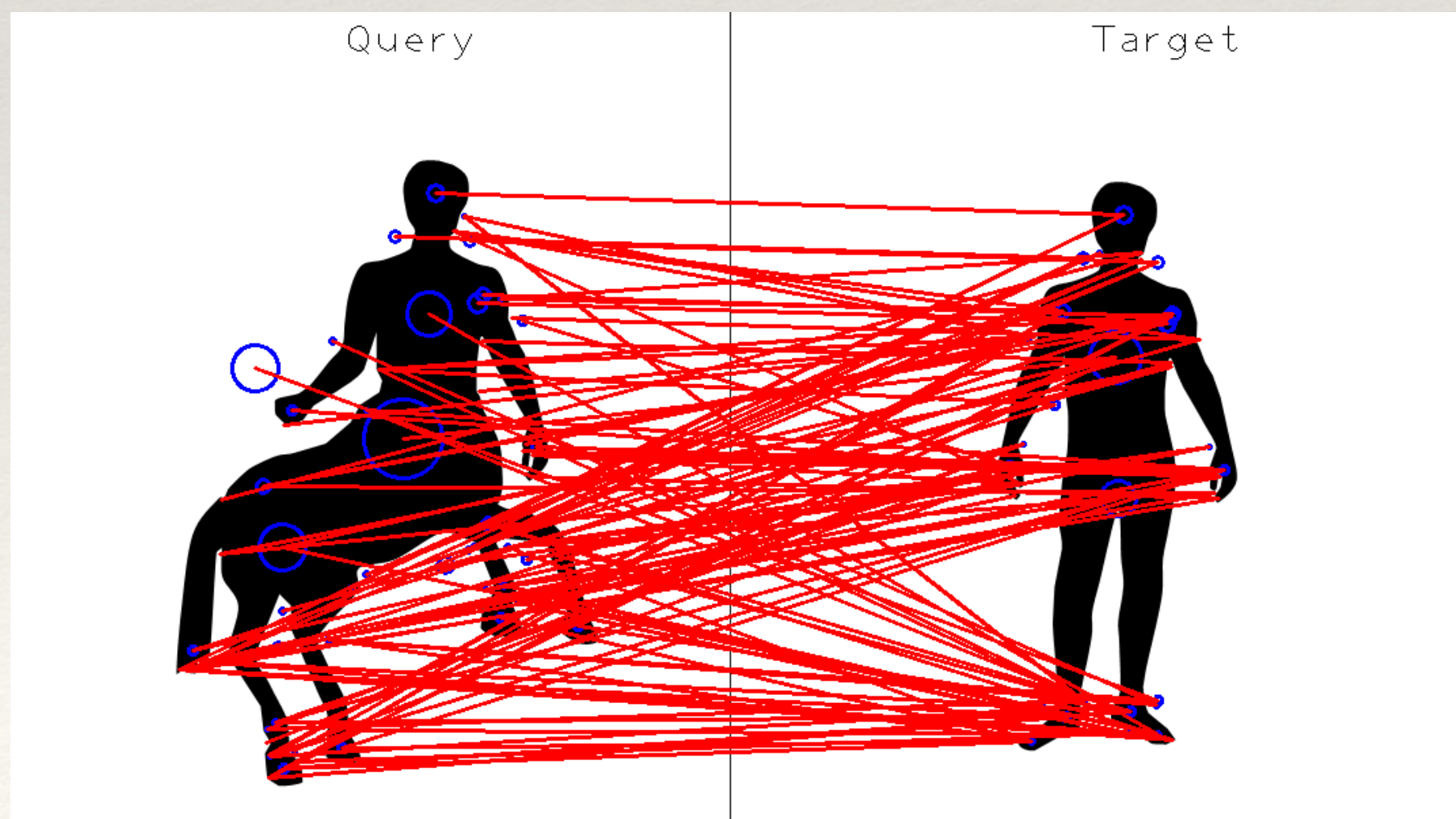
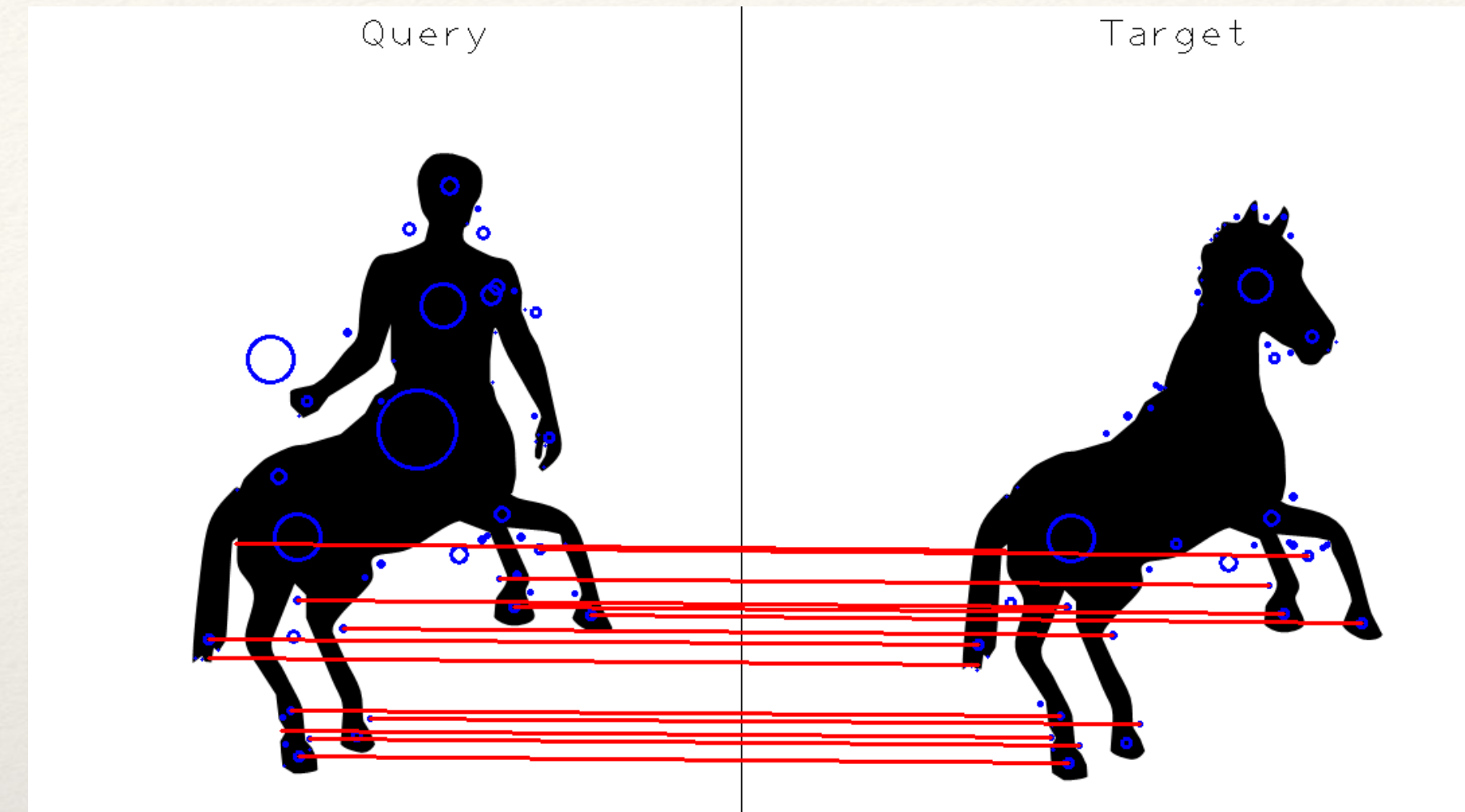


Image comparisons

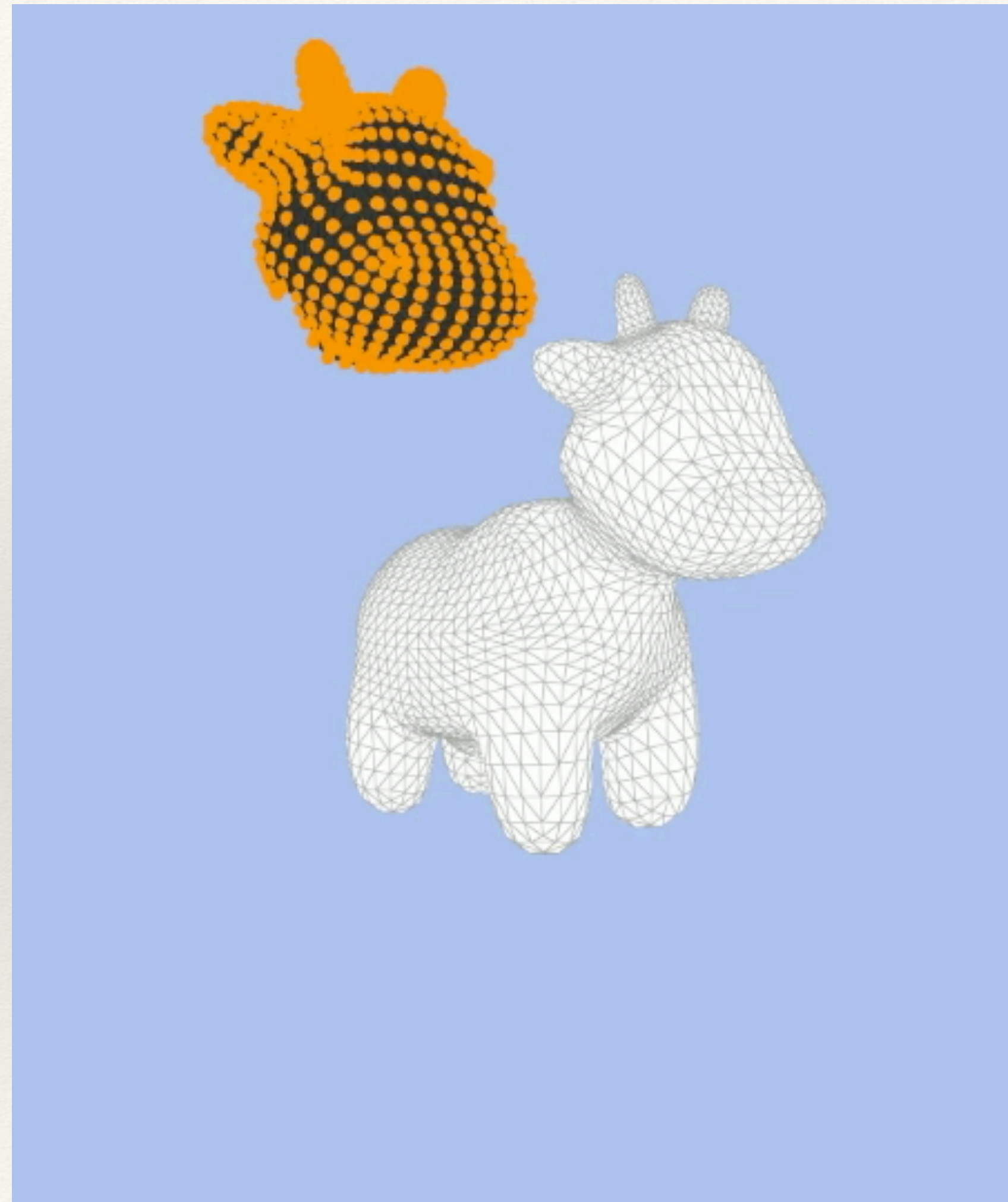
Fixed masses



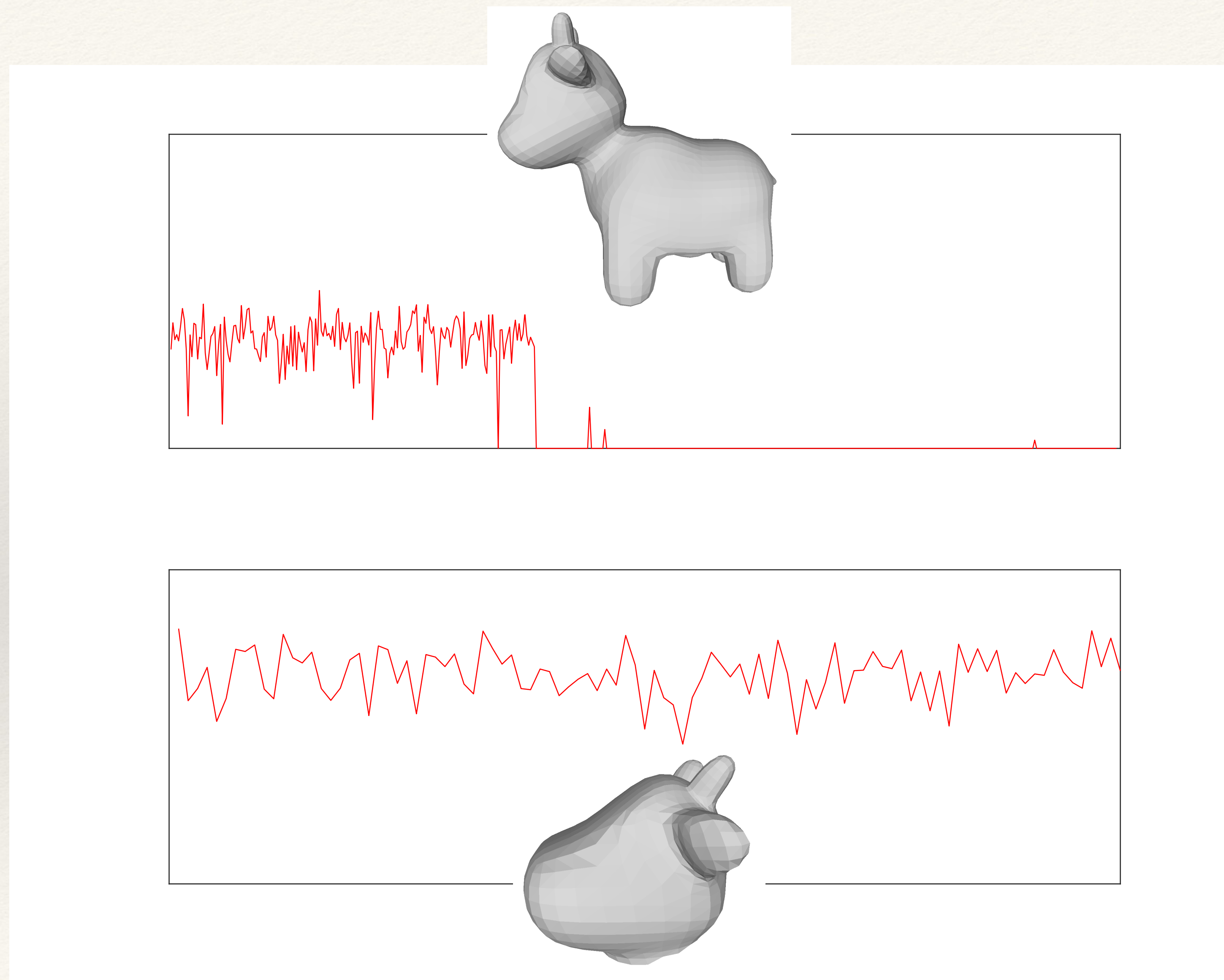
Variable masses



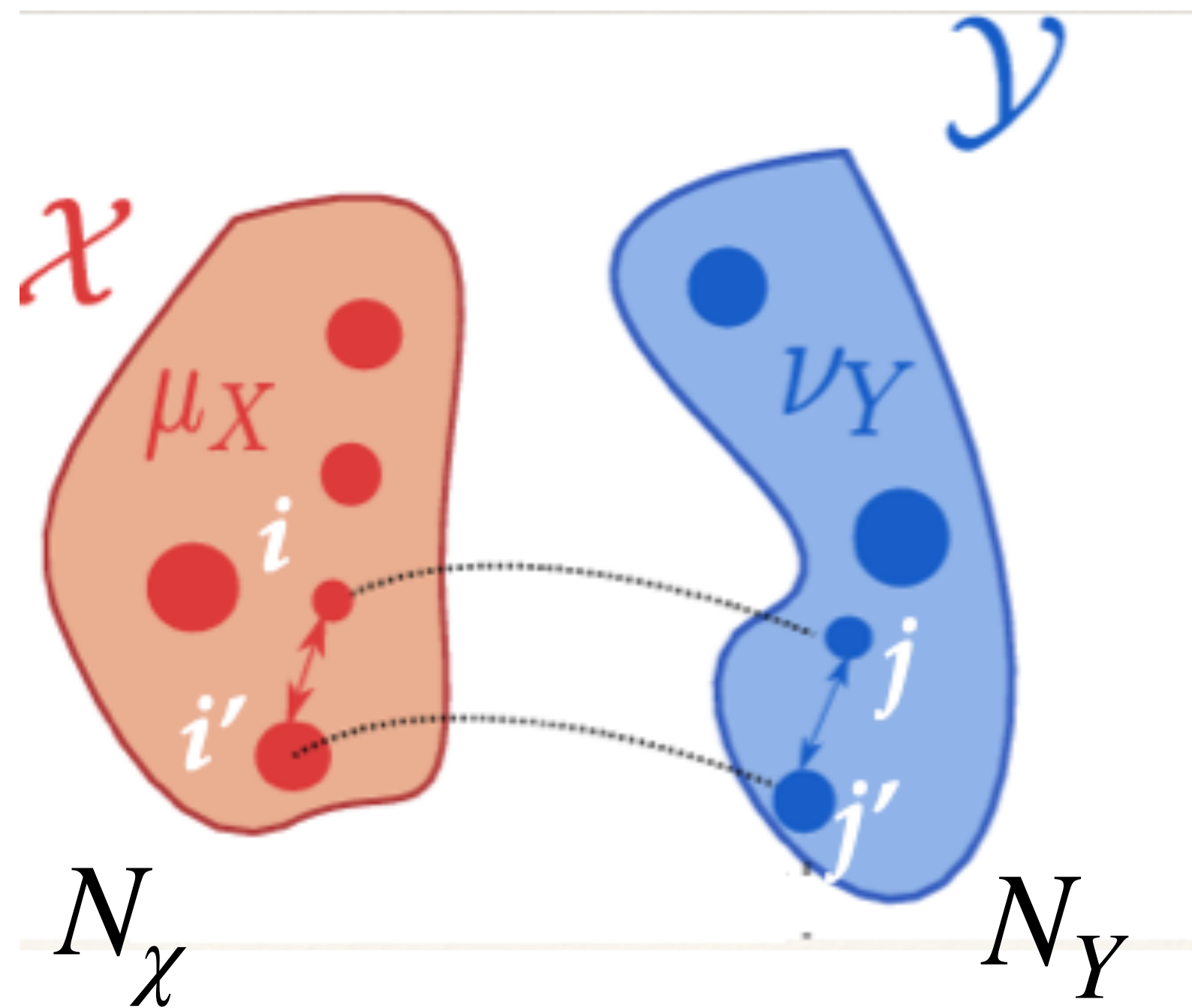
OT with variable masses



OT with variable masses



Gromov-Wasserstein OT



$$G_{ij} \in [0,1]$$

$$U_{GW} = \sum_{i,i'} \sum_{j,j'} G(i,j)(d_X(i,i') - d_Y(j,j'))^p G(i'j')$$

$$U_{GW} = \sum_{i,j} G(i,j)C_{GW}(i,j)$$

$$C_{GW}(i,j) = \sum_{i',j'} (d_X(i,i') - d_Y(j,j'))^p G(i'j')$$

Constraints

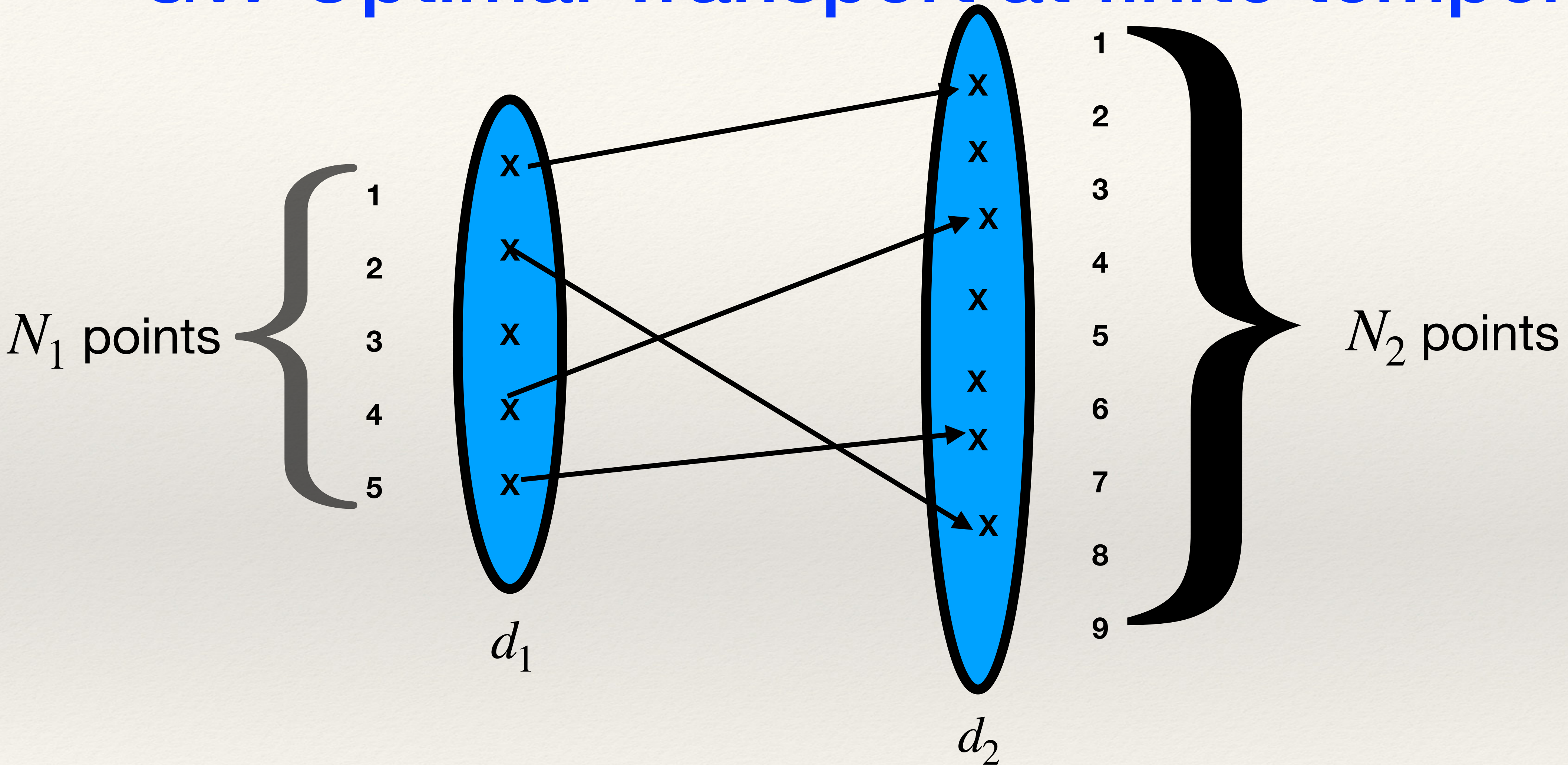
$$\forall i, \sum_j G_{ij} = m_1(i)$$

$$\forall j, \sum_i G_{ij} = m_2(j)$$

Balancing

$$\sum_i m_1(i) = \sum_j m_2(j)$$

GW Optimal Transport at finite temperature



Two different spaces with their own distances d_1 and d_2

GW Optimal Transport at finite temperature

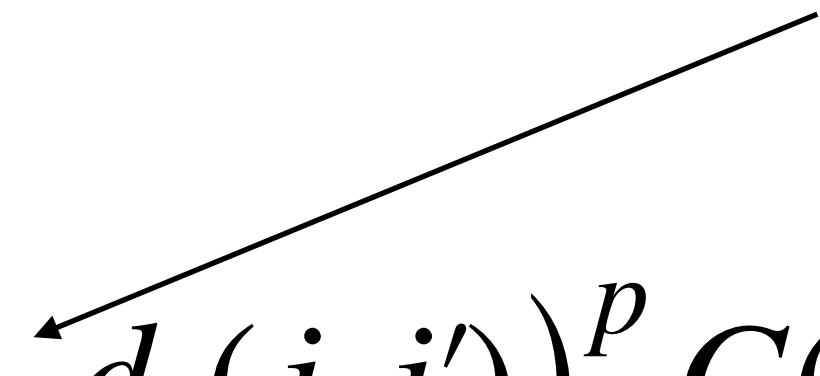
$$E = \sum_{i,j} G(i,j)C(i,j)$$

With

$$C(i,j) = \sum_{i',j'} (d_1(i,i') - d_2(j,j'))^p G(i',j')$$

Invariance with respect to translations and rotations.

To account for the possibility of different scales, introduce a **scale factor** and minimize the energy w.r.t. this scale

$$C(i,j) = \sum_{i',j'} (d_1(i,i') - s \cdot d_2(j,j'))^p G(i',j')$$


Partition Function

$$Z_\beta = \int_0^1 \prod_{ij} dG_{ij} \prod_i \delta\left(\sum_j G_{ij} - m_1(i)\right) \prod_j \delta\left(\sum_i G_{ij} - m_2(j)\right) e^{-\beta \sum_{i,j} \sum_{i',j'} G(i,j) (d_1(i,i') - s \cdot d_2(j,j'))^p G(i',j')}$$

Introduce a cost variable

$$\begin{aligned} Z_\beta(s, S_1, S_2) = & \int_0^1 \prod_{k,l} dG(k,l) \int_{-\infty}^{+\infty} \prod_{k,l} dC(k,l) \\ & e^{-\beta \sum_{k,l} G(k,l) C(k,l)} \times \\ & \prod_k \delta\left(\sum_l G(k,l) - m_1(k)\right) \prod_l \delta\left(\sum_k G(k,l) - m_2(l)\right) \\ & \prod_{k,l} \delta\left(\sum_{k',l'} |d_1(k,k') - s \cdot d_2(l,l')|^p G(k',l') - C(k,l)\right). \end{aligned}$$

Use the Fourier representation of δ -functions

$$\begin{aligned}
 Z_\beta(s, S_1, S_2) = & \int_{-\infty}^{+\infty} \prod_{k,l} dC(k,l) \int_0^1 \prod_{k,l} dG(k,l) e^{-\beta \sum_{k,l} C(k,l)G(k,l)} \times \\
 & \int_{-\infty}^{+\infty} \prod_k d\lambda(k) e^{-i\beta \sum_{k,l} \lambda(k)G(k,l) + i\beta \sum_k \lambda(k)m_1(k)} \int_{-\infty}^{+\infty} \prod_l d\mu(l) e^{-i\beta \sum_{k,l} \mu(l)G(k,l) + i\beta \sum_l \mu(l)m_2(l)} \\
 & \int_{-\infty}^{+\infty} \prod_{k,l} dD(k,l) e^{i\beta \sum_{k,l} D(k,l)C(k,l) - i\beta \sum_{k,l} D(k,l) \sum_{k',l'} |d_1(k,k') - s \cdot d_2(l,l')|^p G(k',l')} .
 \end{aligned}$$

Do the G integrals

After some manipulations, the partition function can be written as

$$Z_\beta = \int dC dD d\lambda d\mu e^{-\beta F_\beta}$$

where

$$\begin{aligned} F_\beta &= - \sum_{k,l} D(k,l) C(k,l) - \left(\sum_k \lambda(k) m_1(k) + \sum_l \mu_l m_2(l) \right) \\ &+ \sum_{k,k'} \sum_{l,l'} D(k,l) |d_1(k,k') - s \cdot d_2(l,l')|^p D(k',l') \\ &- \frac{1}{\beta} \sum_{k,l} \ln \left(\frac{1 - e^{-\beta(C(k,l) + \lambda(k) + \mu(l))}}{\beta(C(k,l) + \lambda(k) + \mu(l))} \right). \end{aligned}$$

Saddle-Point Equations

Define average G_{ij} by $\bar{G}_{ij} = D_{ij}$

Standard Optimal Transport

$$\left\{ \begin{array}{l} \bar{G}_{ij} = \phi \left(\beta(C_{ij} + \lambda_i + \mu_j) \right) \\ \sum_j \bar{G}_{ij} = m_1(i) \\ \sum_i \bar{G}_{ij} = m_2(j) \end{array} \right. \quad \phi(x) = \frac{e^{-x}}{e^{-x} - 1} + \frac{1}{x}.$$

Self-consistency condition

$$C_{ij} = 2 \sum_{i'j'} \left(d_1(i, i') - s \cdot d_2(j, j') \right)^p \bar{G}_{i'j'}$$

The scaling factor is obtained by minimising the free energy w.r.t. s

$$\sum_{k,k'} \sum_{l,l'} D(k,l) d_2(l,l') |d_1(k,k') - s \cdot d_2(l,l')|^{p-2} (d_1(k,k') - s \cdot d_2(l,l')) D(k',l') = 0,$$

If $p = 2$

$$s = \frac{\sum_{k,k'} \sum_{l,l'} D(k,l) d_1(k,k') d_2(l,l') D(k',l')}{\sum_{k,k'} \sum_{l,l'} D(k,l) d_2(l,l')^2 D(k',l')}$$

1. Do a temperature annealing from high to low temperature
2. Start with an initial \bar{G}_{ij} , for instance $\bar{G}_{ij} = m_1(i)m_2(j)$ and scaling factor $s = 1$
3. Calculate C_{ij}
4. Solve optimal transport with C_{ij} and get new \bar{G}_{ij} and new s
5. Back to 3 till convergence
6. Decrease temperature till low enough temperature.
7. Back to 3 till convergence

TOSCA Dataset: 11 classes, 133 shapes of 3400 vertices and 6600 faces

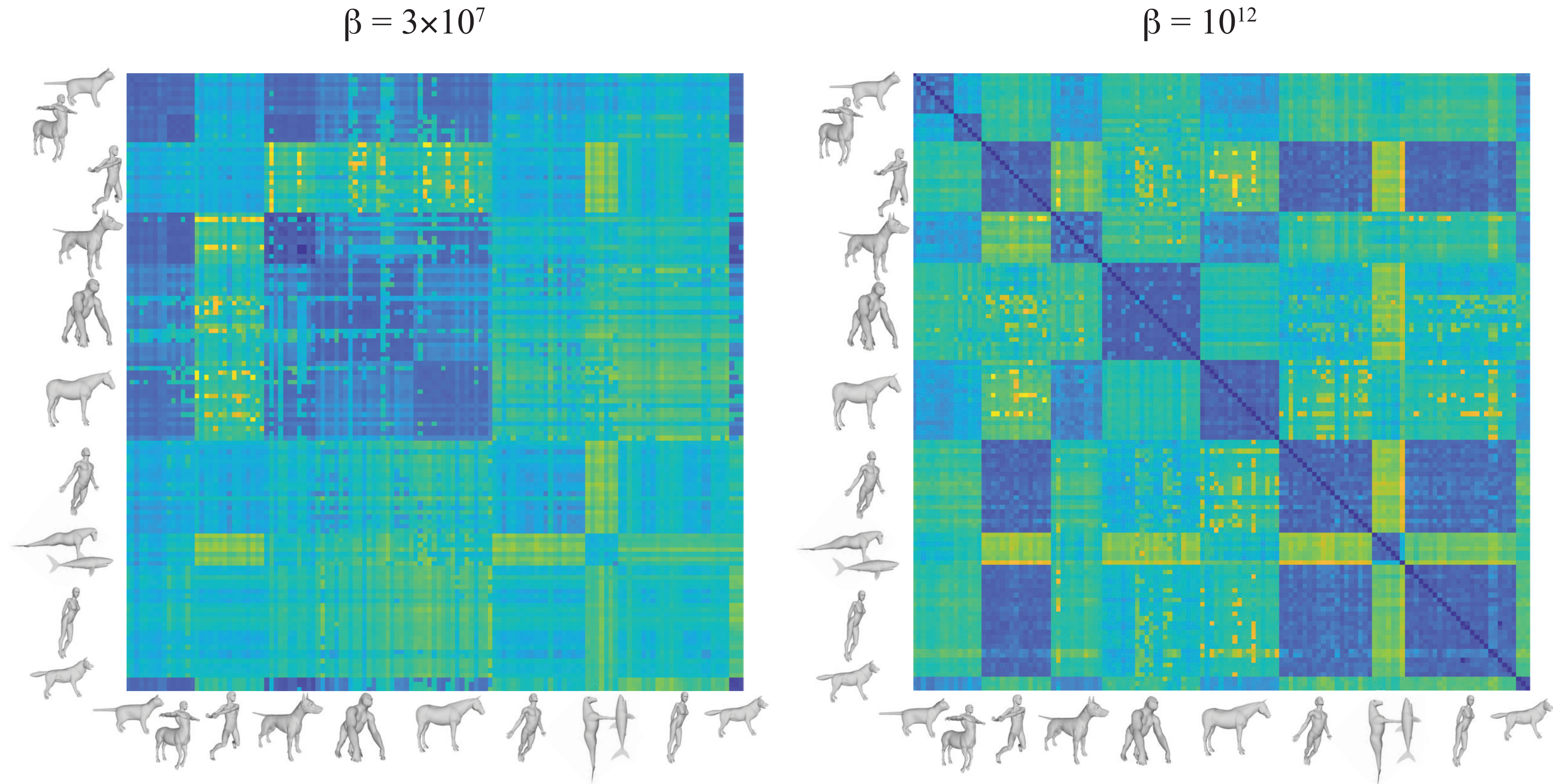
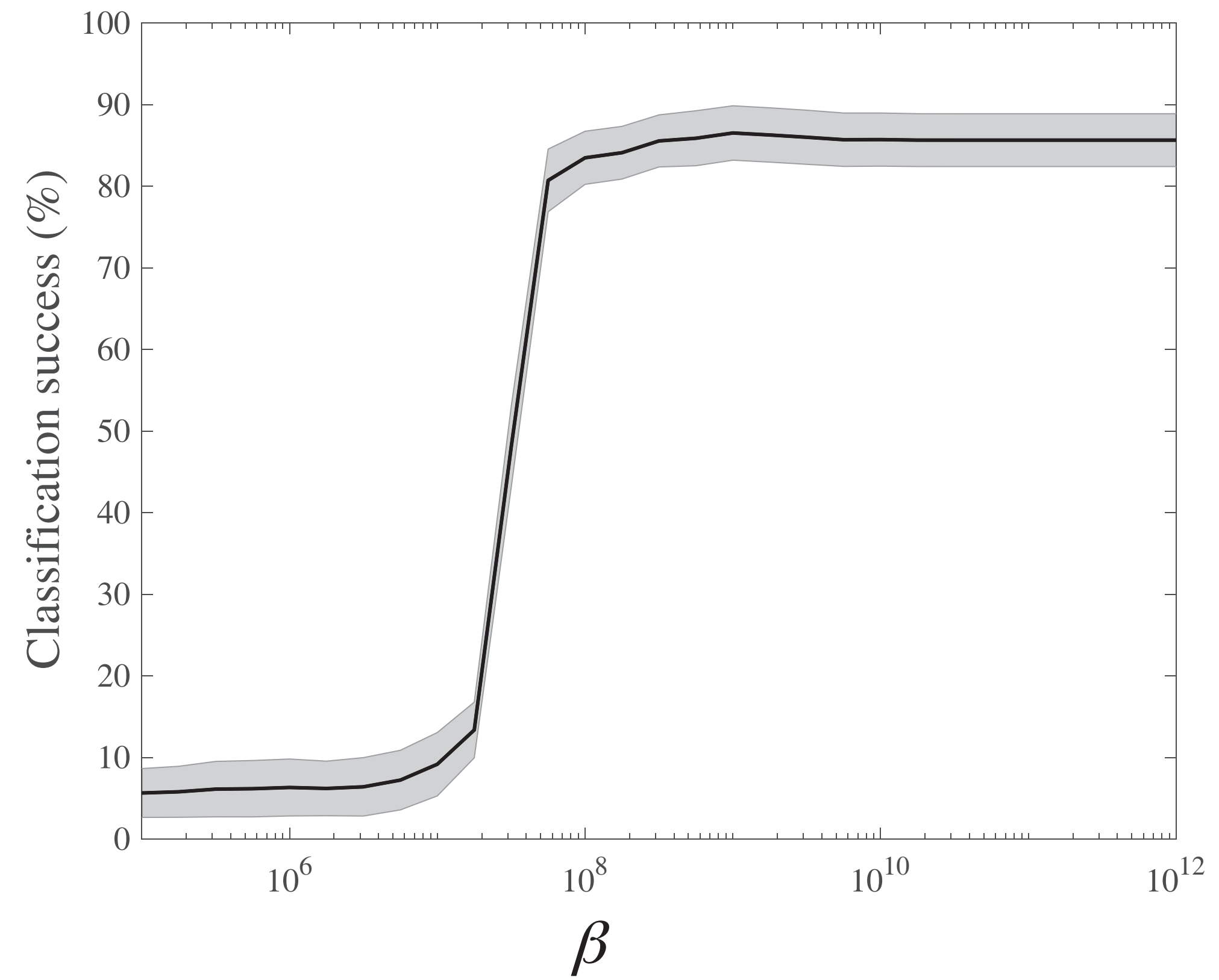


Figure 1. Distance matrices for shape similarity within the TOSCA dataset using the Gromov-Wassertein framework at two different “temperatures”, $\beta = 3 \times 10^7$ (**left**) and $\beta = 10^{12}$ (**right**). Blue colors represent small distances (high similarity), while yellow colors represent large distances



Quality of 3d shape recognition (10000 experiments)

Conclusion

- Statistical mechanics is a natural framework to study assignment and optimal transport problems.
- Numerical methods are more stable than standard entropy regularisation
- Possible to do local matching by using variable masses
- GW OT very powerful tool but requires large computational resources