

# Updates on DR2 sample simulations

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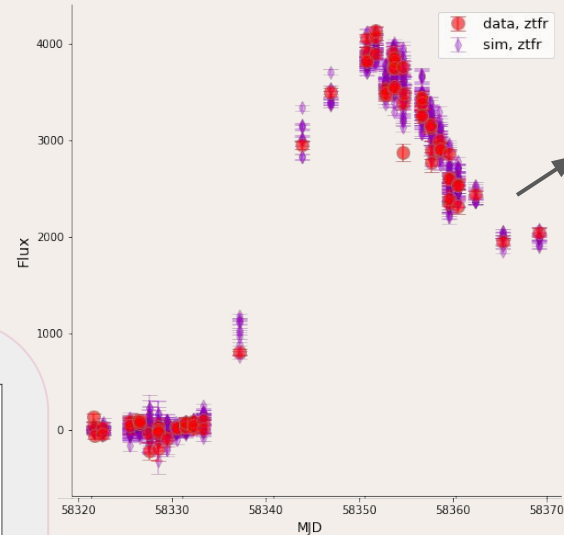
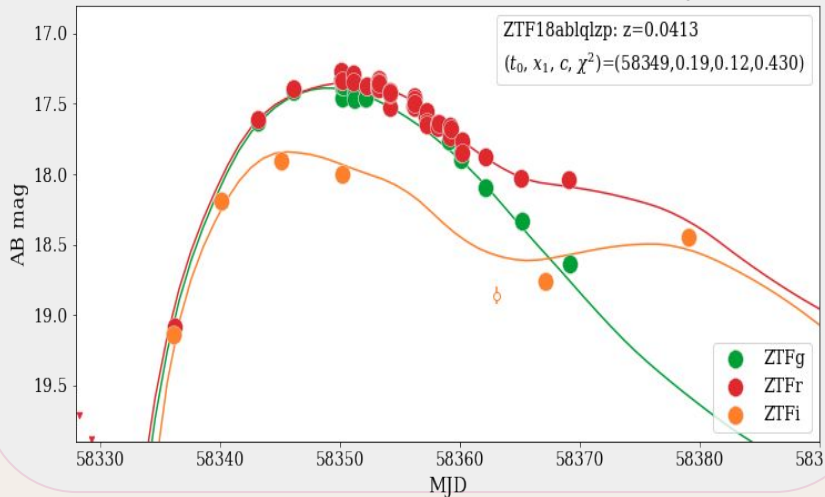


# ZTF realistic individual objects

simsurvey inputs

observing  
logs of ZTF  
DR2

DR2 measured  $z$ ,  $x_1$ ,  $c$  and  $t_0$



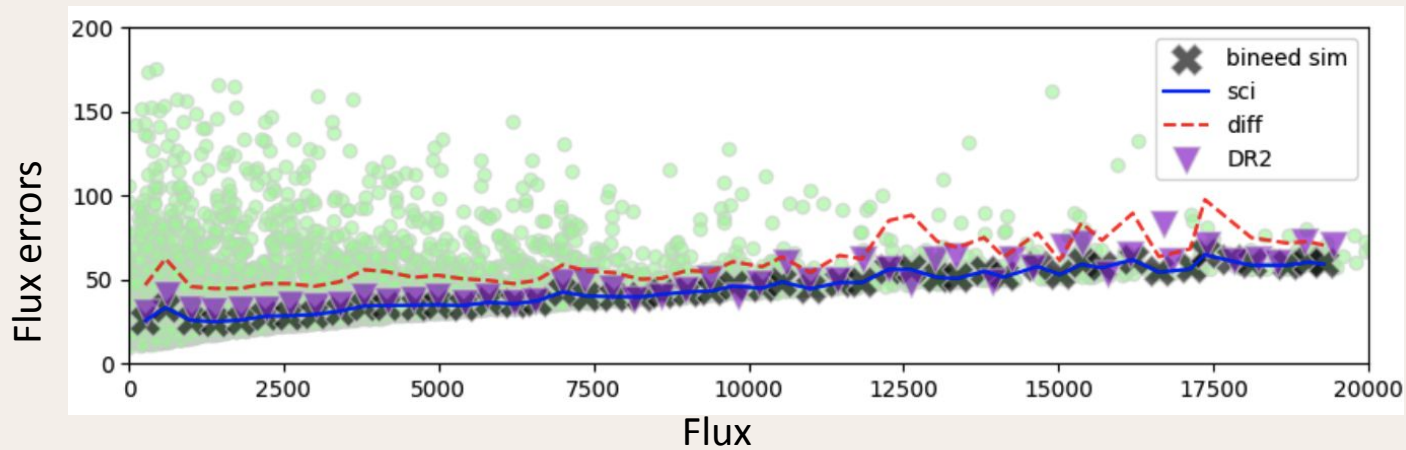
Compute  
Signal-to-Noise (SNR)

$$SNR_{sim} = \frac{\Phi_{sim}}{\sigma_{\Phi, sim}}$$

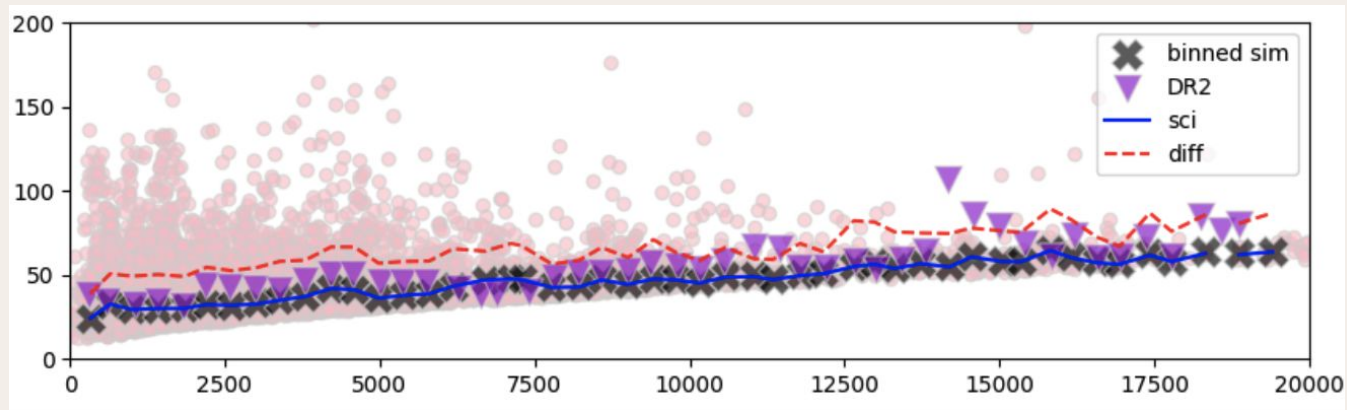
$$SNR_{DR2} = \frac{\Phi_{DR2}}{\sigma_{\Phi, DR2}}$$

Compare SNR of  
measured and  
simulated LC points

# Flux uncertainties comparison

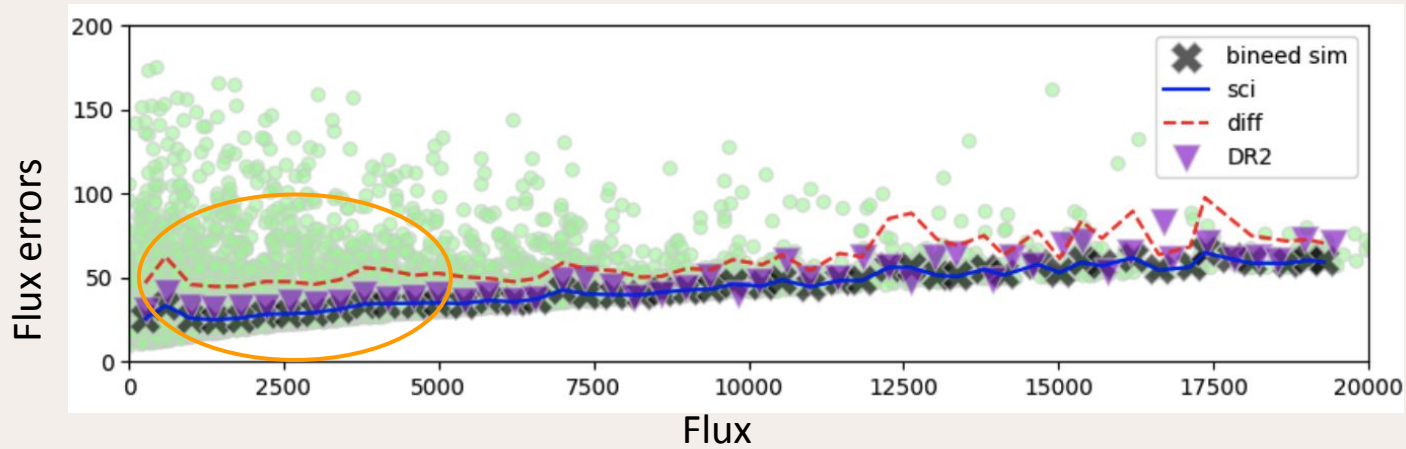


ztfg

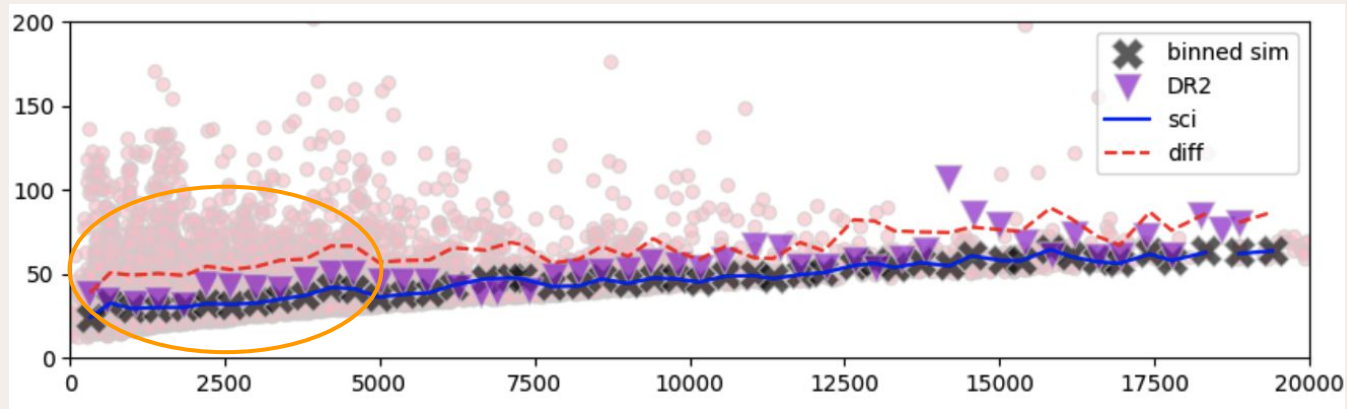


ztfr

# Which skynoise should we use ?



ztfg

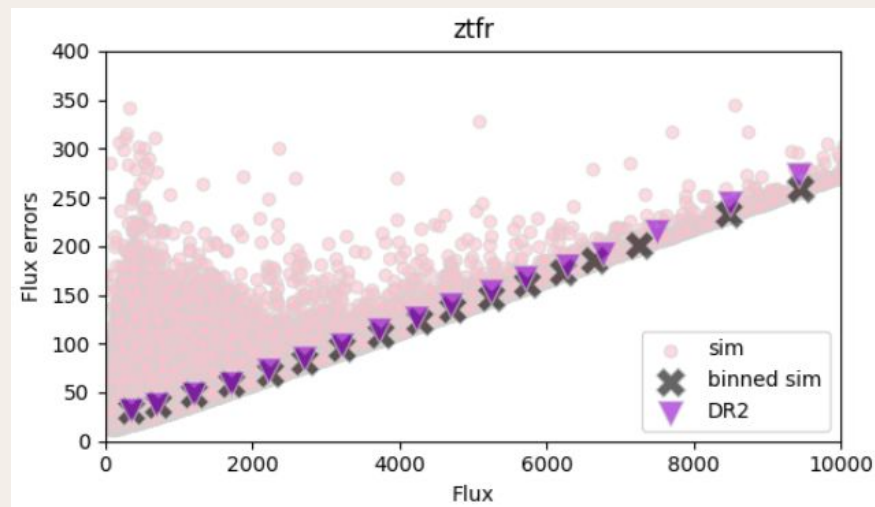
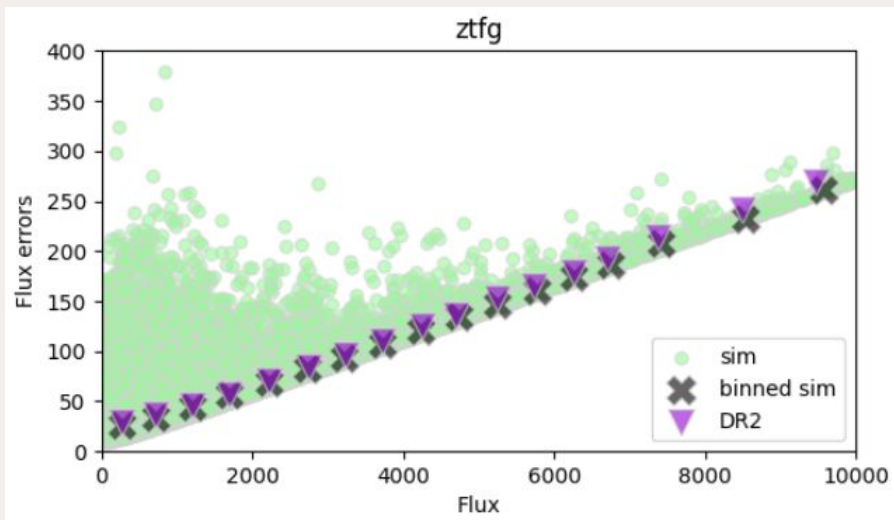


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# Low and high flux correction

For the simulation, we need:

- Low flux: new skynoise
- Higher flux: calibration uncertainties

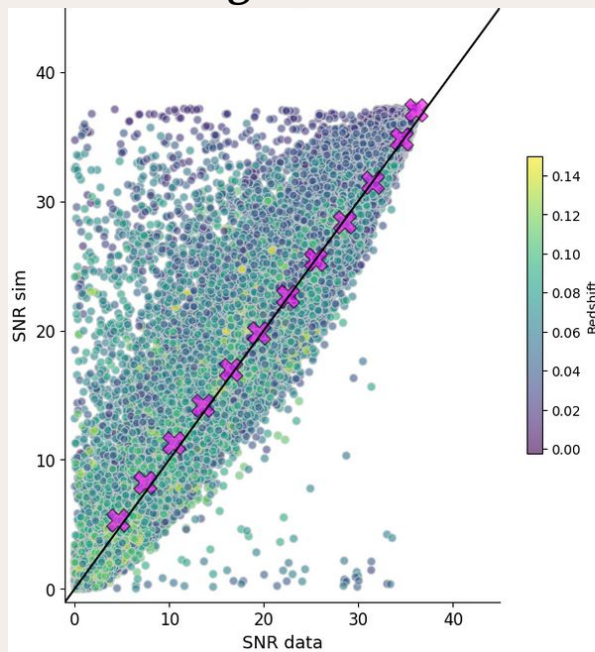


# Individual objects simulations: all DR2 sample

Amenouche et al. (in prep)

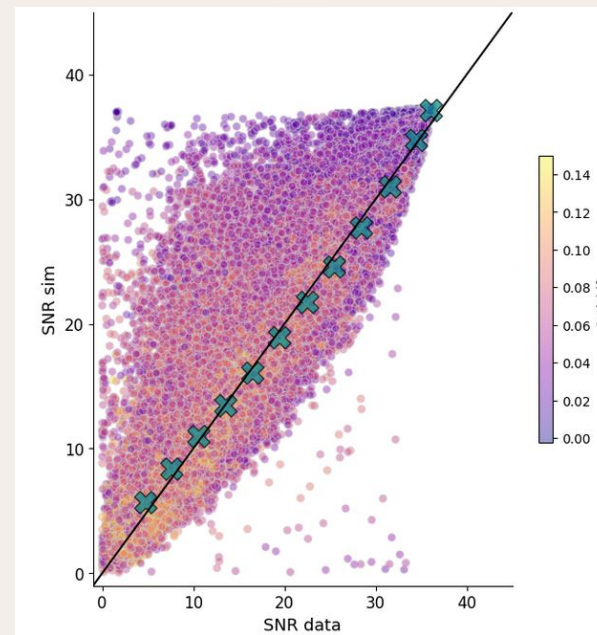
- We need calibration uncertainties in the DR2 light-curves
- We need extra 2.9% in the simulation uncertainties

g band



✕ binned SNR values  
✕ binned SNR values

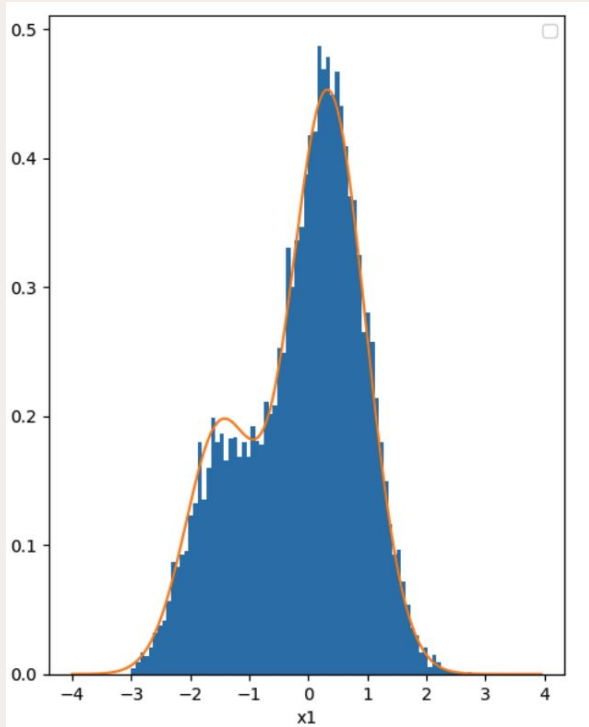
r band



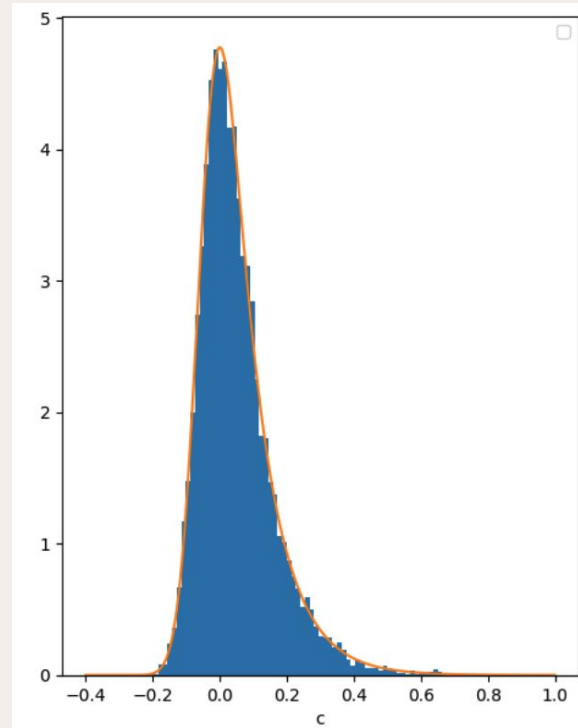
# Free simulations: input distributions

100,000 objects simulated

Stretch (Nicolas et al 2021)



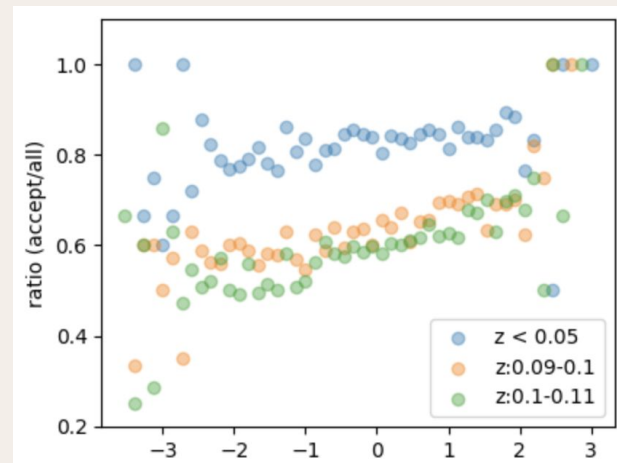
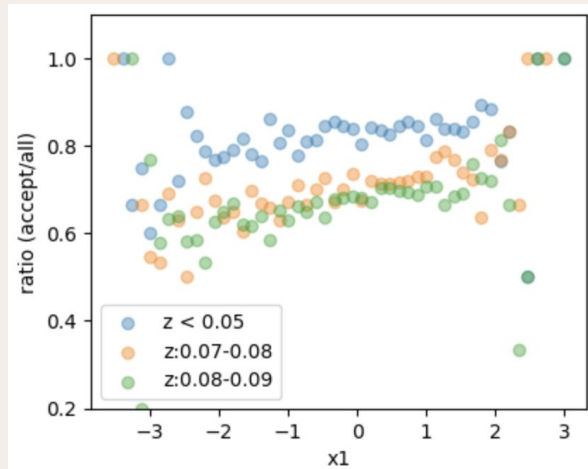
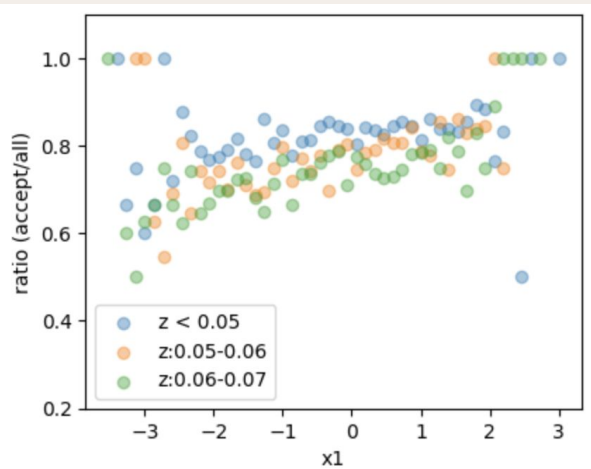
exponential decay



# Free simulations: x1

Preliminary  
y

- 100,000 objects simulated
- Requirement: at least 4 detections to accept an object

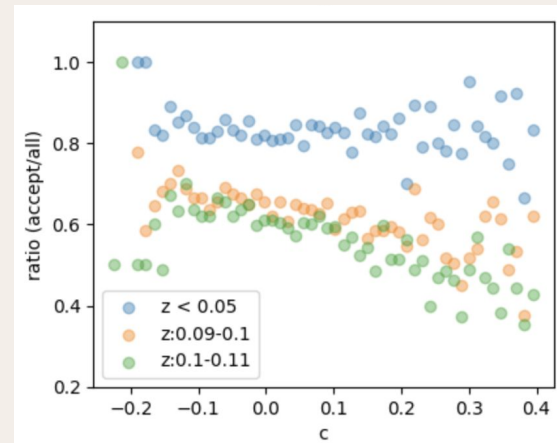
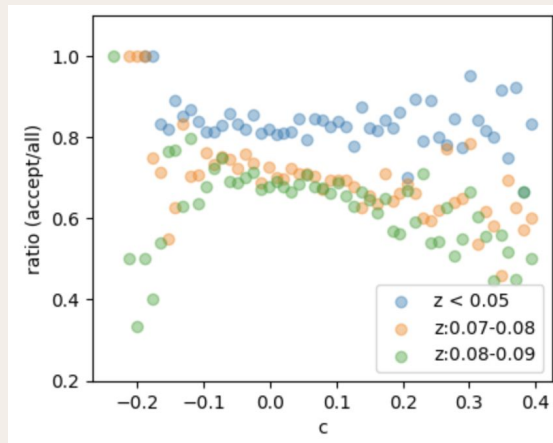
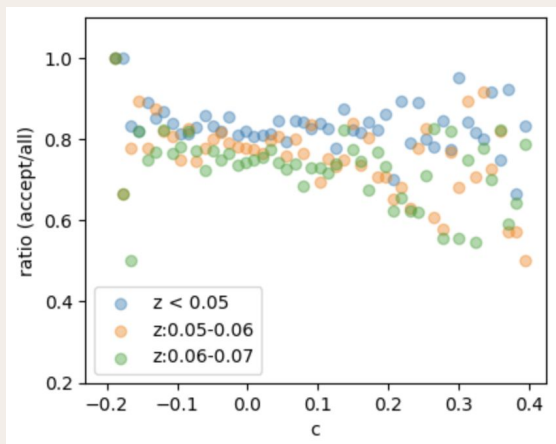




# Free simulations: c

Preliminary  
y

- 100,000 objects simulated
- Requirement: at least 4 detections to accept an object



# What is next ?

- Individual objects: explore i band simulations
- Continue biases study with the free simulations: comparison after SALT2 fit and estimation of the bias in the distance measurement