

Emil Gorm Dahlbæk Nielsen, Niels Bohr Institutet

Speed of sound and higher-order $[p_T]$ fluctuations in Pb–Pb collisions at $\sqrt{s_{NN}} = 5.02$ TeV

- on behalf of the ALICE Collaboration

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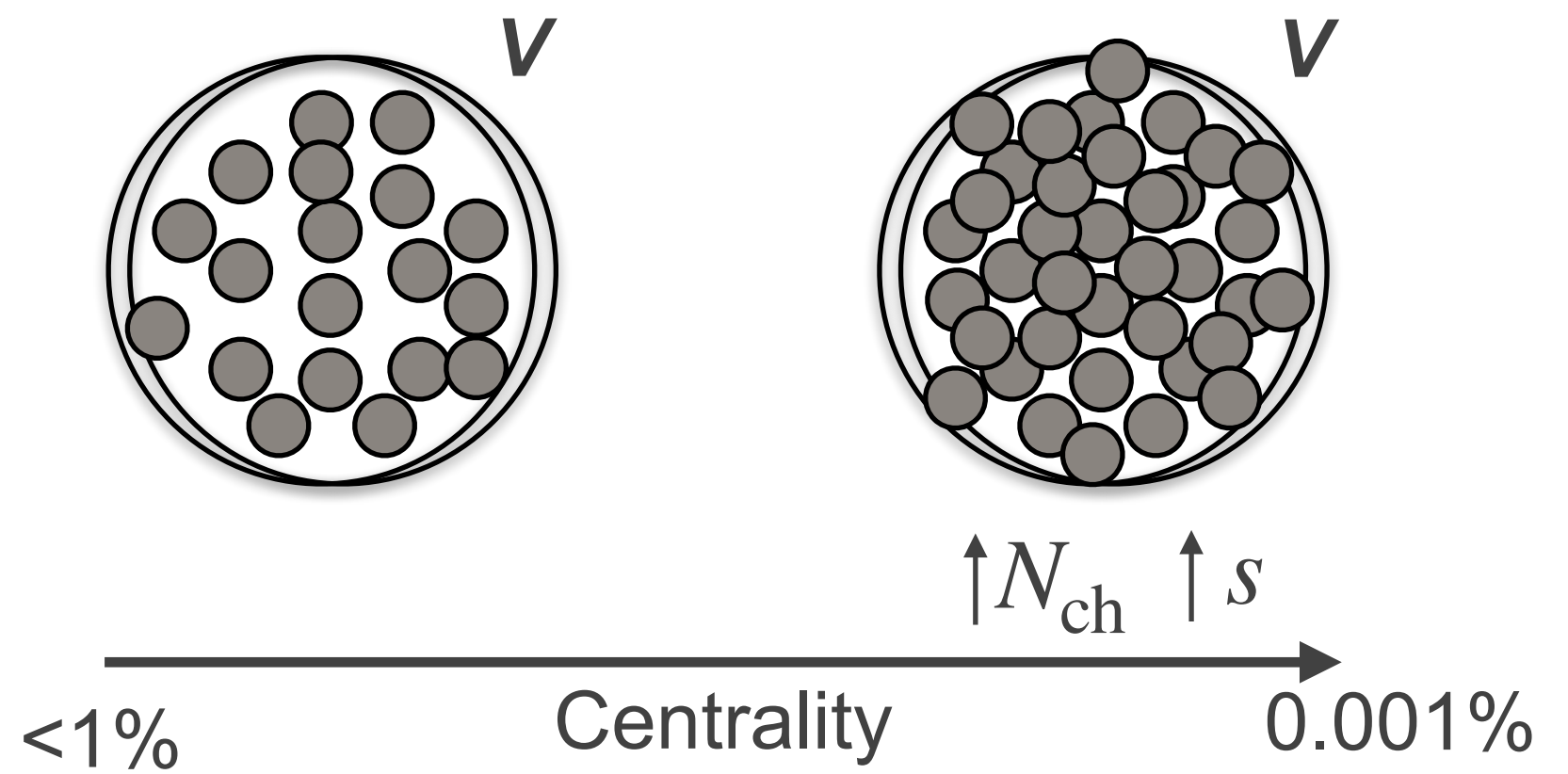


SOM 2024

The 21st International Conference on Strangeness in Quark Matter
3-7 June 2024, Strasbourg, France

QGP in ultra-central collisions

Ultra-central collisions: fixed volume V



[L. Van Howe, PLB 118 (1982) 138]

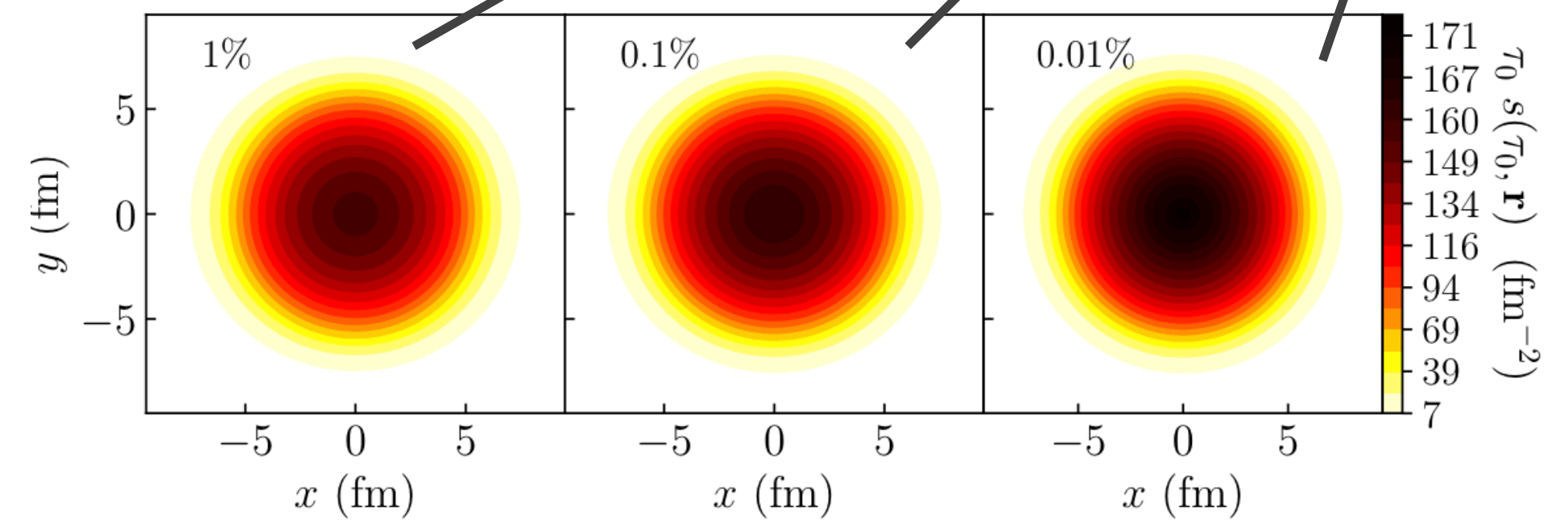
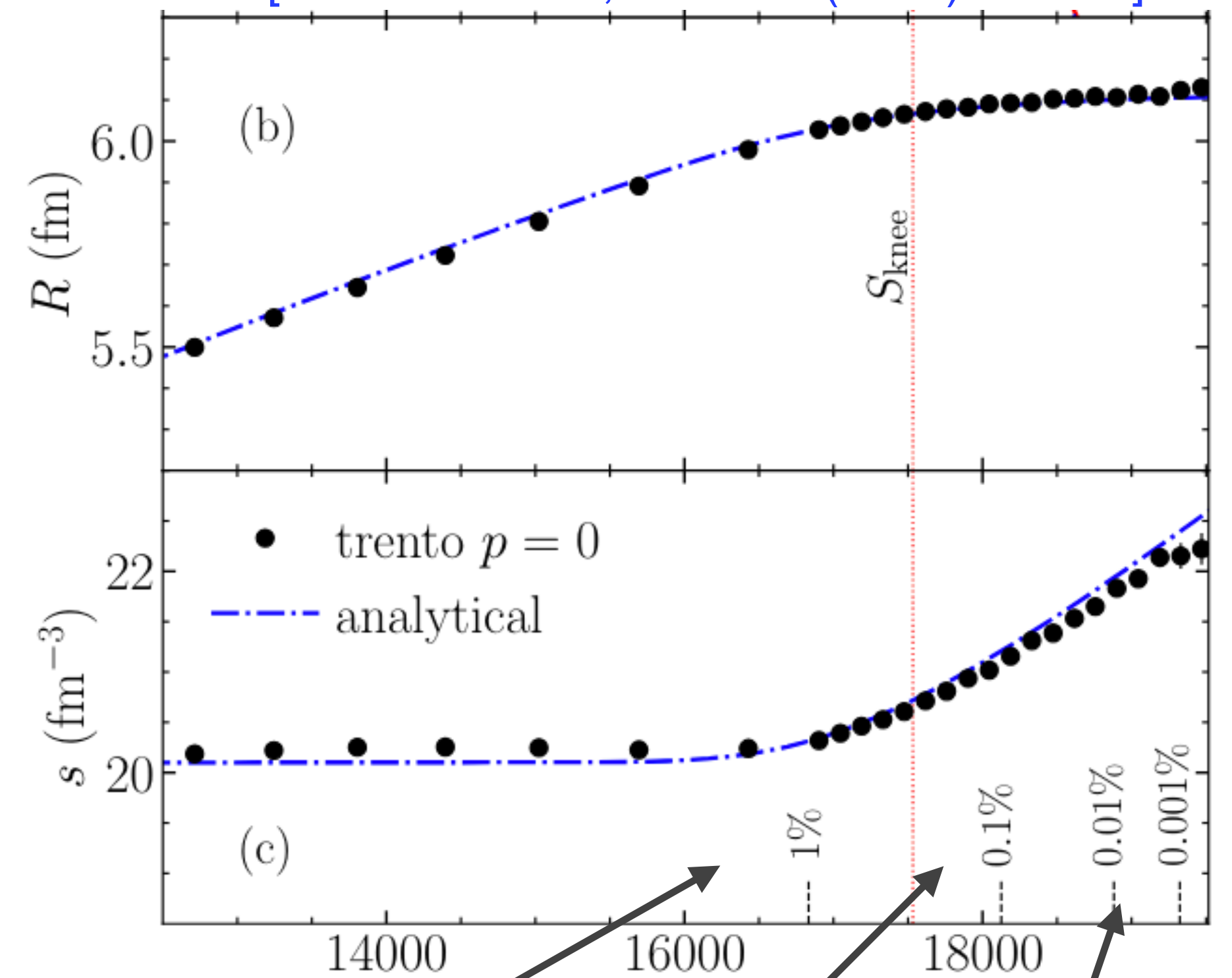
Thermalised system: $\uparrow s \Rightarrow \uparrow T \Rightarrow \uparrow \langle p_T \rangle$

$$\langle p_T \rangle \sim 3T_{\text{eff}}$$

Speed of sound, c_s^2 , from thermodynamic relations [F. Gardim et al., Nature Physics 16, 615-619 (2020)]

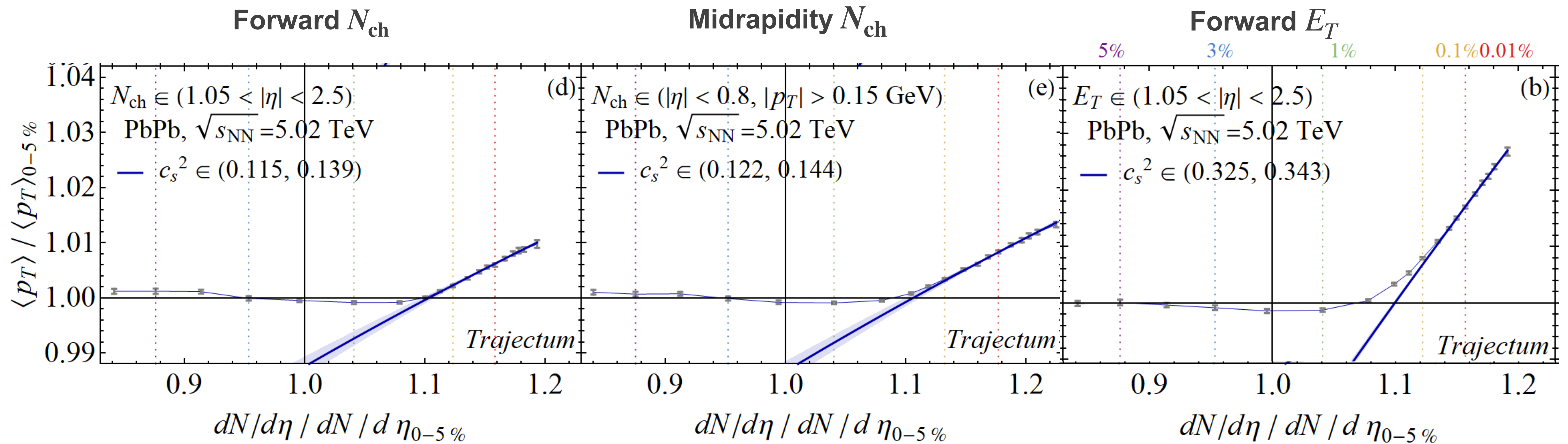
$$c_s^2 = \left. \frac{sdT}{Tds} \right|_{T_{\text{eff}}} = \frac{d \ln \langle p_T \rangle}{d \ln(N_{\text{ch}}/d\eta)}$$

[F. Gardim et al., PLB 809 (2020) 135749]



What determines the slope?

Recent theoretical studies suggest that the extraction of the speed of sound is heavily dependent on the centrality determination and associated η range.



[G. Nijs & W. van der Schee, PLB 853 (2024) 138636]

Transverse momentum fluctuations

The fluctuations of the event-by-event mean transverse momentum, $[p_T]$, arise from two sources:

[R. Samanta et al., PRC 108 (2023) 024908]
 [R. Samanta et al., PRC 109 (2024) L051902]

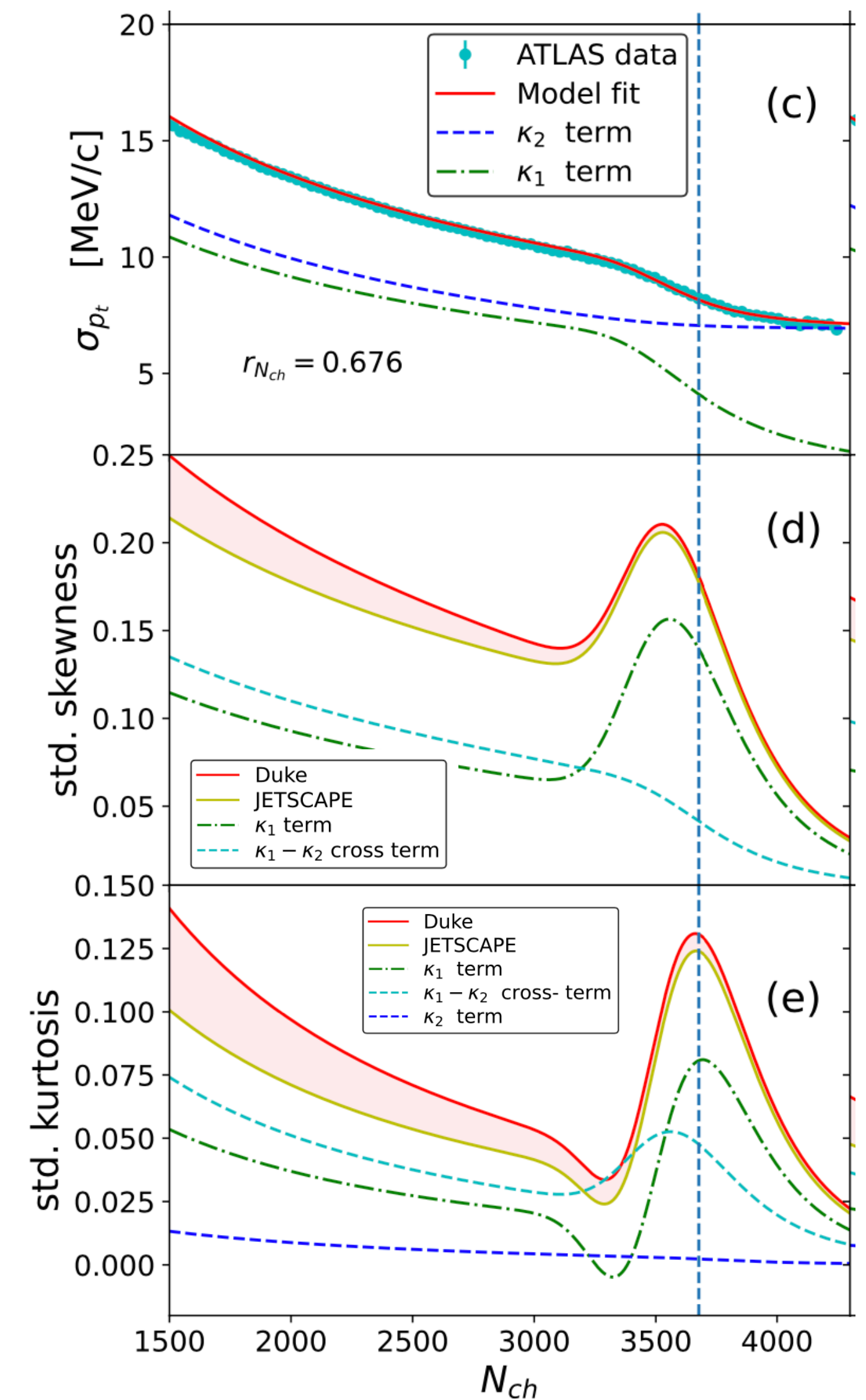
Geometrical fluctuations

- Radial flow: hydrodynamic response of $[p_T]$ to the inverse size $1/R$
- At fixed multiplicity \rightarrow radial flow fluctuations from fluctuations of inverse size

Intrinsic fluctuations

At fixed impact parameter b

- Quantum fluctuations in wave function of incoming nuclei
- Thermal fluctuations of the QGP



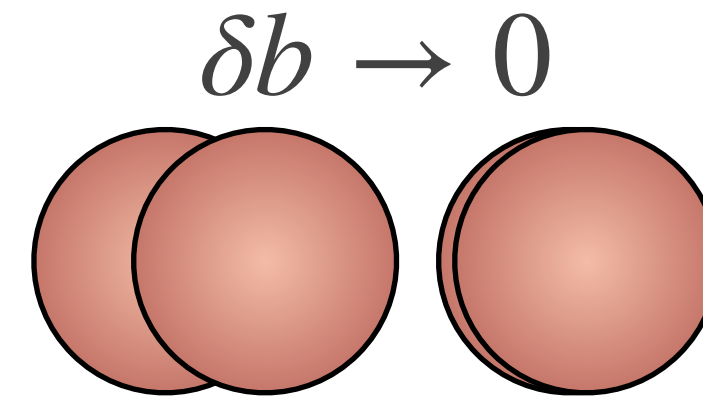
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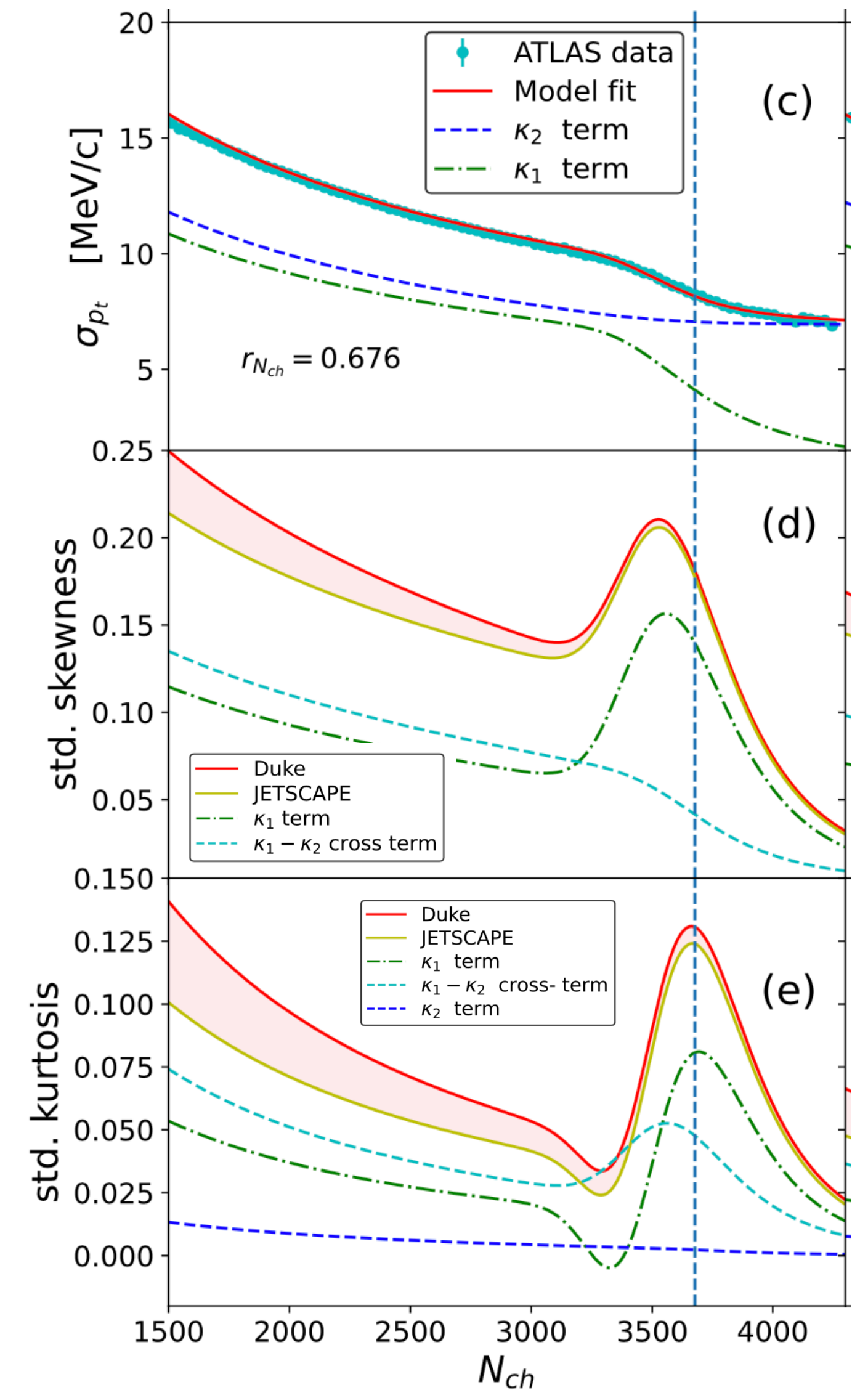


Intrinsic fluctuations

At fixed impact parameter b

- Quantum fluctuations in wave function of incoming nuclei
- Thermal fluctuations of the QGP

2D Gaussian model of $[p_T]$ and N_{ch} fluctuations predicts abrupt changes of the higher-order $[p_T]$ fluctuations with vanishing impact parameter fluctuations



Mean

From fully corrected spectra

$\langle p_T \rangle$ extrapolated to $p_T = 0$ with Levy-Tsallis parametrisation

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Variance

Normalised

$$k_2 = \frac{c_2}{\langle [p_T^{(2)}] \rangle}$$

$c_n = n^{\text{th}}$ -order multi-particle
[p_T]-cumulant

$[p_T^{(n)}] = n^{\text{th}}$ -order multi-particle
[p_T]-moment

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Skewness

Normalised

$$k_3 = \frac{c_3}{\langle [p_T^{(3)}] \rangle}$$

Standardised

$$\gamma_{\langle [p_T] \rangle} = \frac{c_3}{c_2^{3/2}}$$

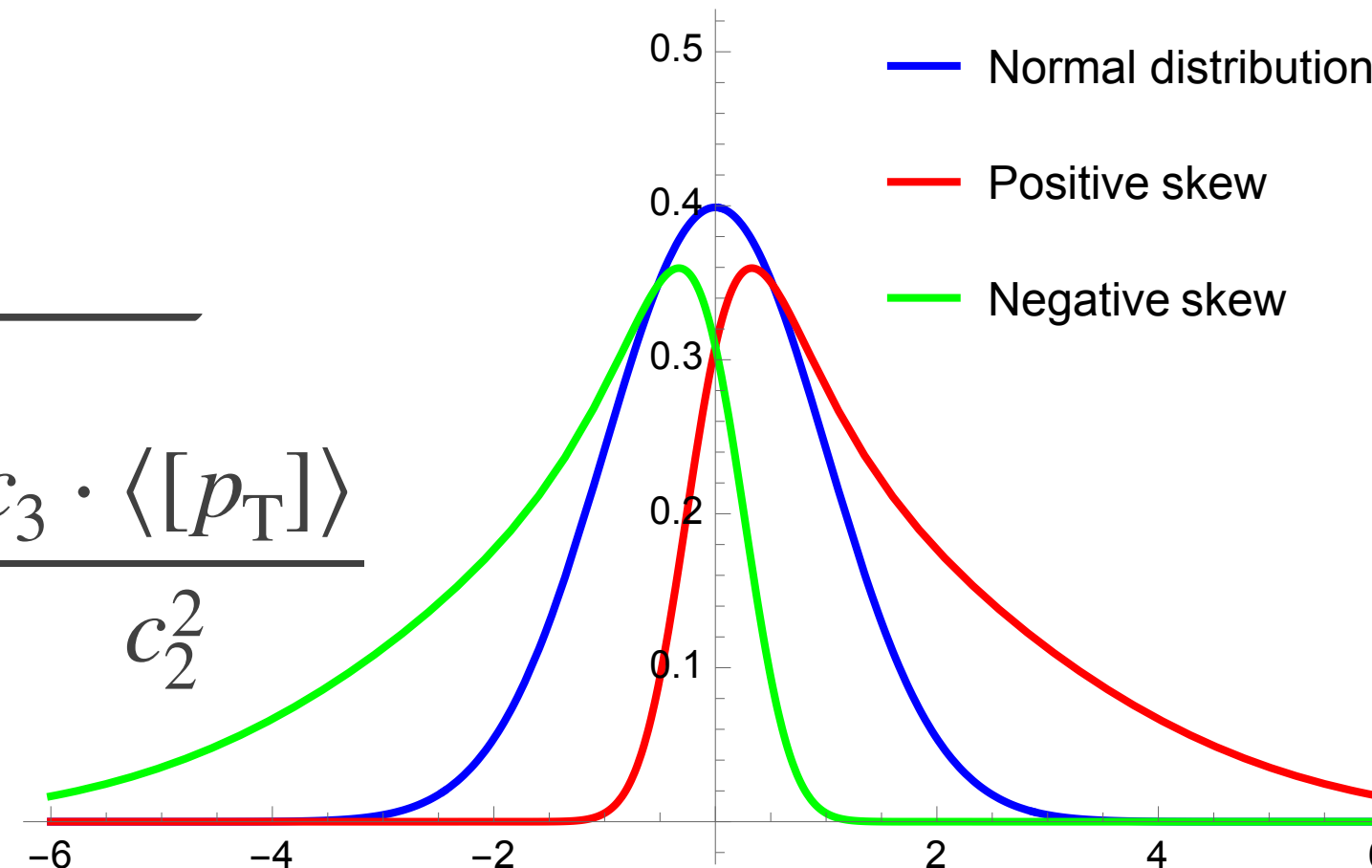
Intensive

$$\Gamma_{\langle [p_T] \rangle} = \frac{c_3 \cdot \langle [p_T] \rangle}{c_2^2}$$

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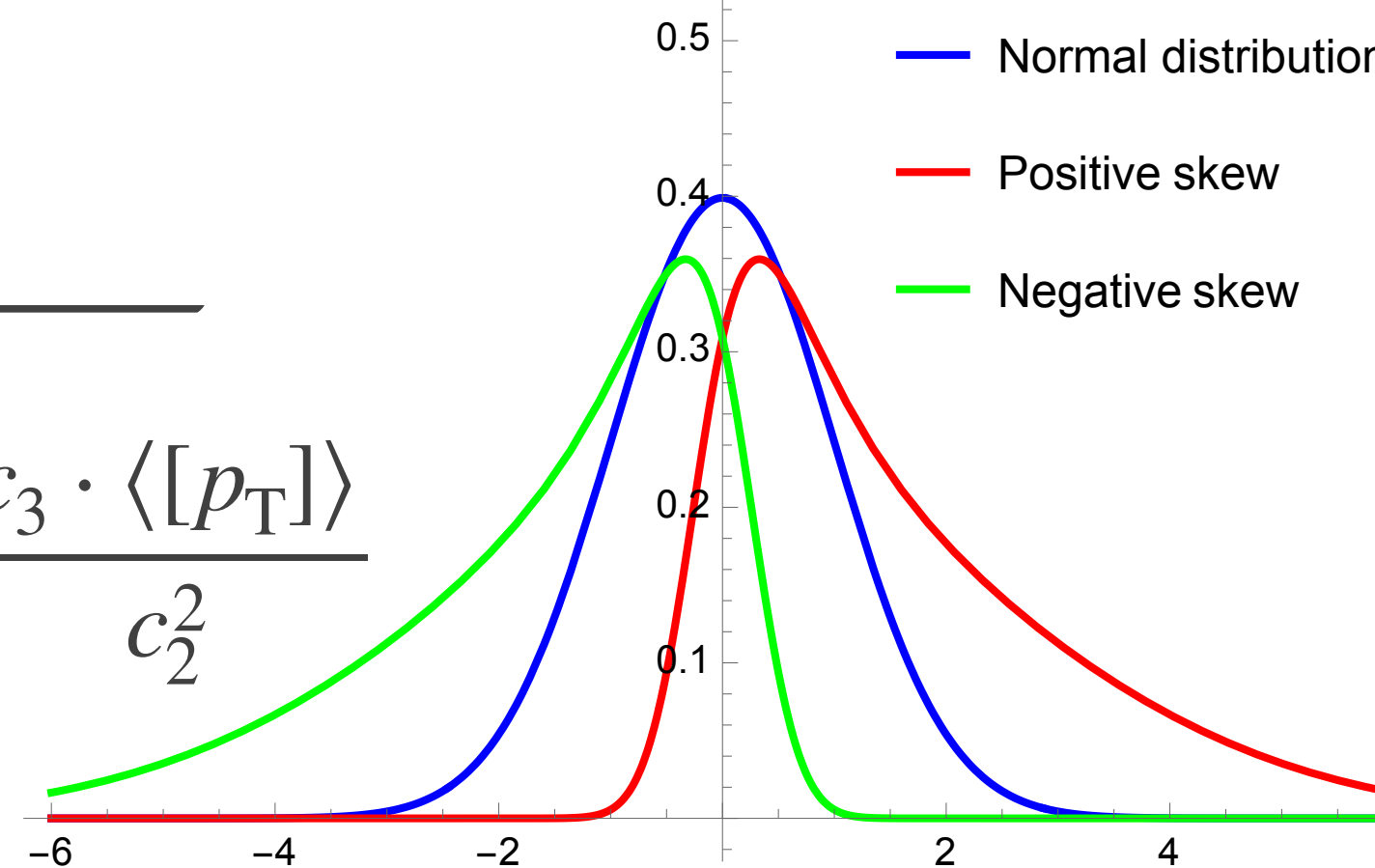
Kurtosis

$$K_{\langle [p_T] \rangle} = \frac{c_4 + 3c_2^2}{c_2^2}$$

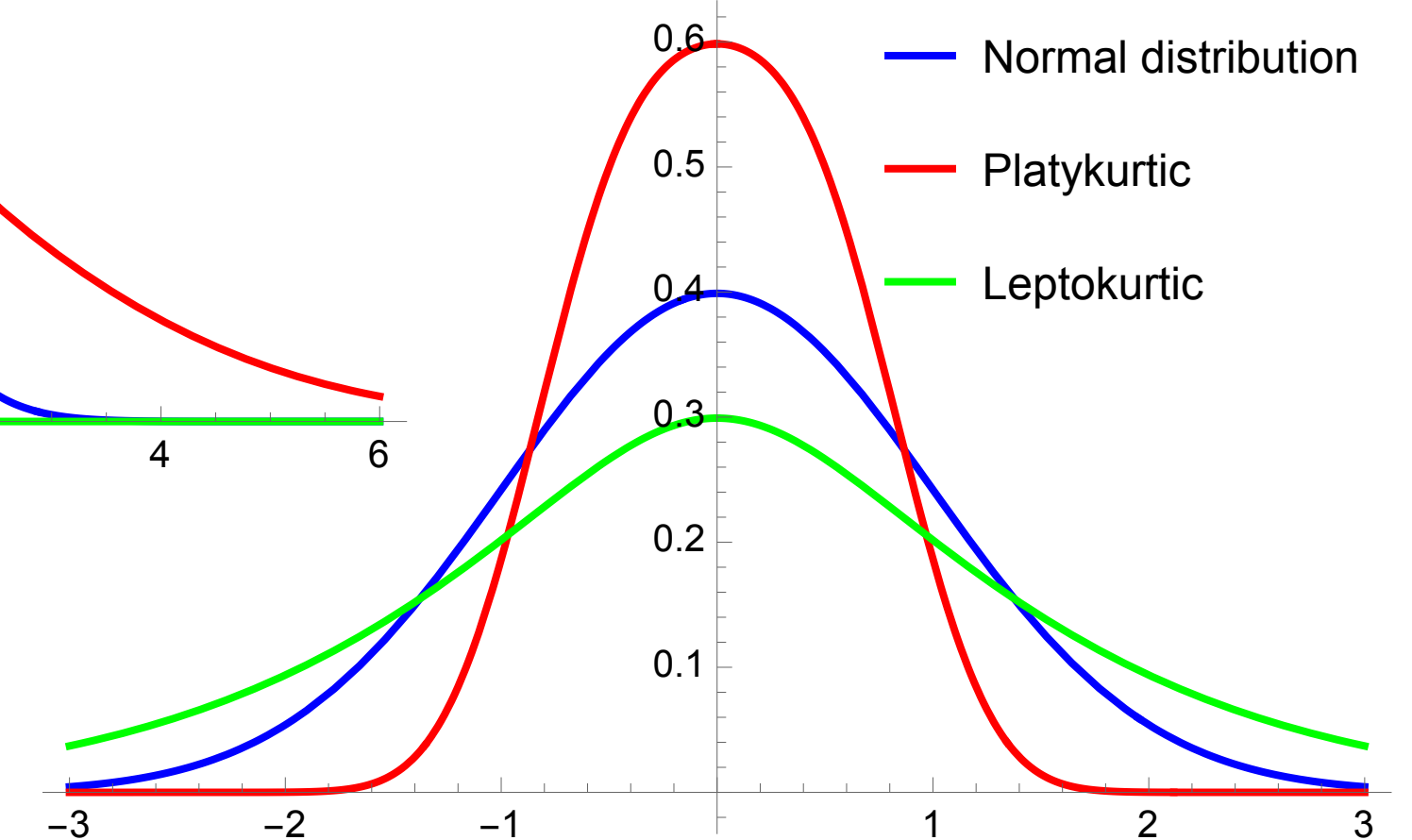
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Skewness



Kurtosis



Mean transverse momentum

Correlation between $\langle p_T \rangle$ and N_{ch} fitted with parametrisation

[F. Gardim et al., PLB 809 (2020) 135749]

$$\langle p_T \rangle / \langle p_T \rangle^{\text{ref}} = \left(\frac{N_{ch}^*}{f(N_{ch}^*, N_{ch, \text{knee}}^*, \sigma_0)} \right)^{c_s^2}$$

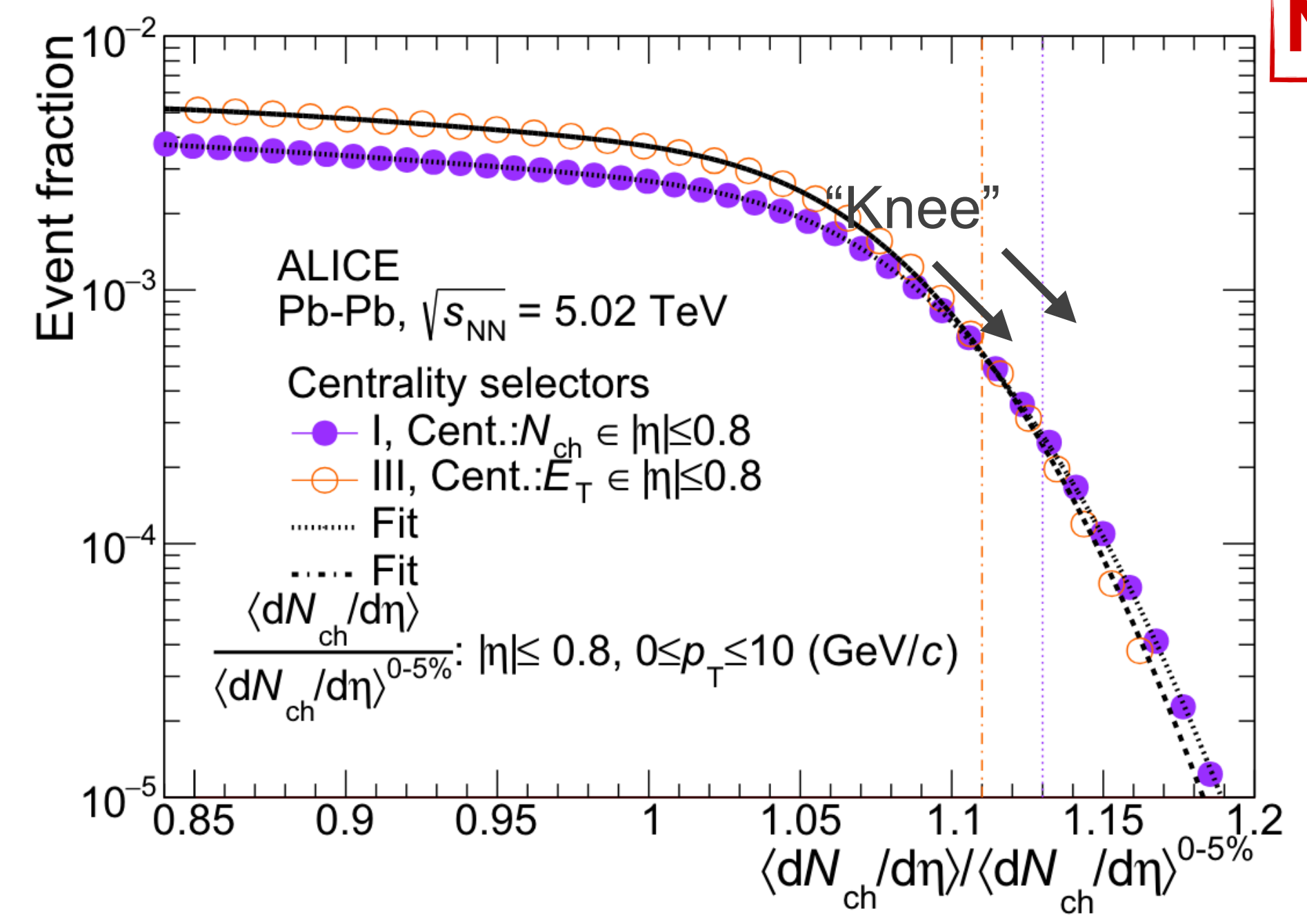
Gaussian fluctuations of N_{ch} as function of impact parameter

$N_{ch, \text{knee}}^*$ and σ_0 obtained from fit to multiplicity distribution

[S. J. Das et al., PRC 97, 014905 (2018)]

where $N_{ch}^* = \langle dN_{ch}/d\eta \rangle / \langle dN_{ch}/d\eta \rangle^{\text{ref}}$

NEW



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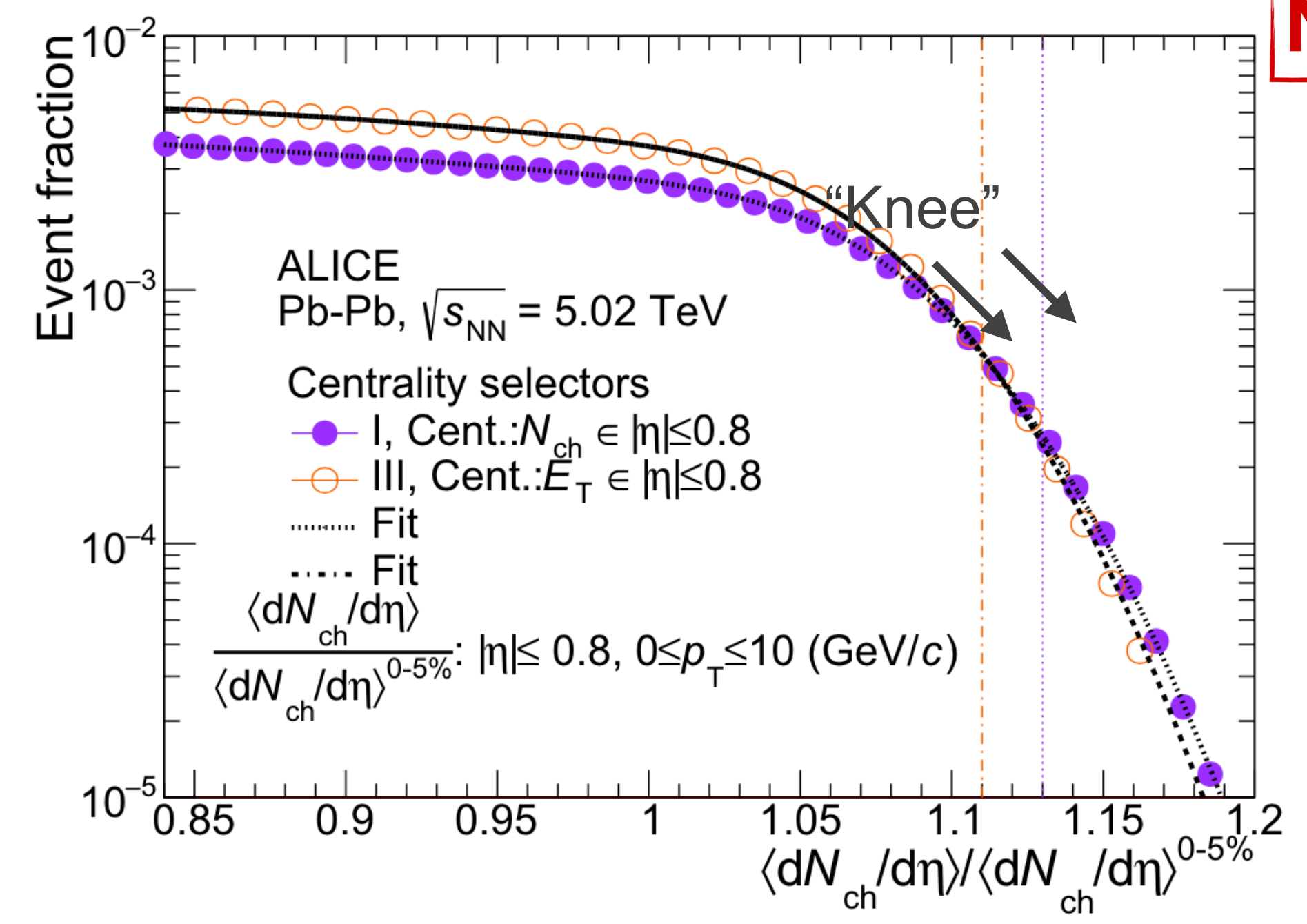
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Below the knee

$$\langle p_T \rangle / \langle p_T \rangle^{\text{ref}} \approx 1$$

distribution

NEW



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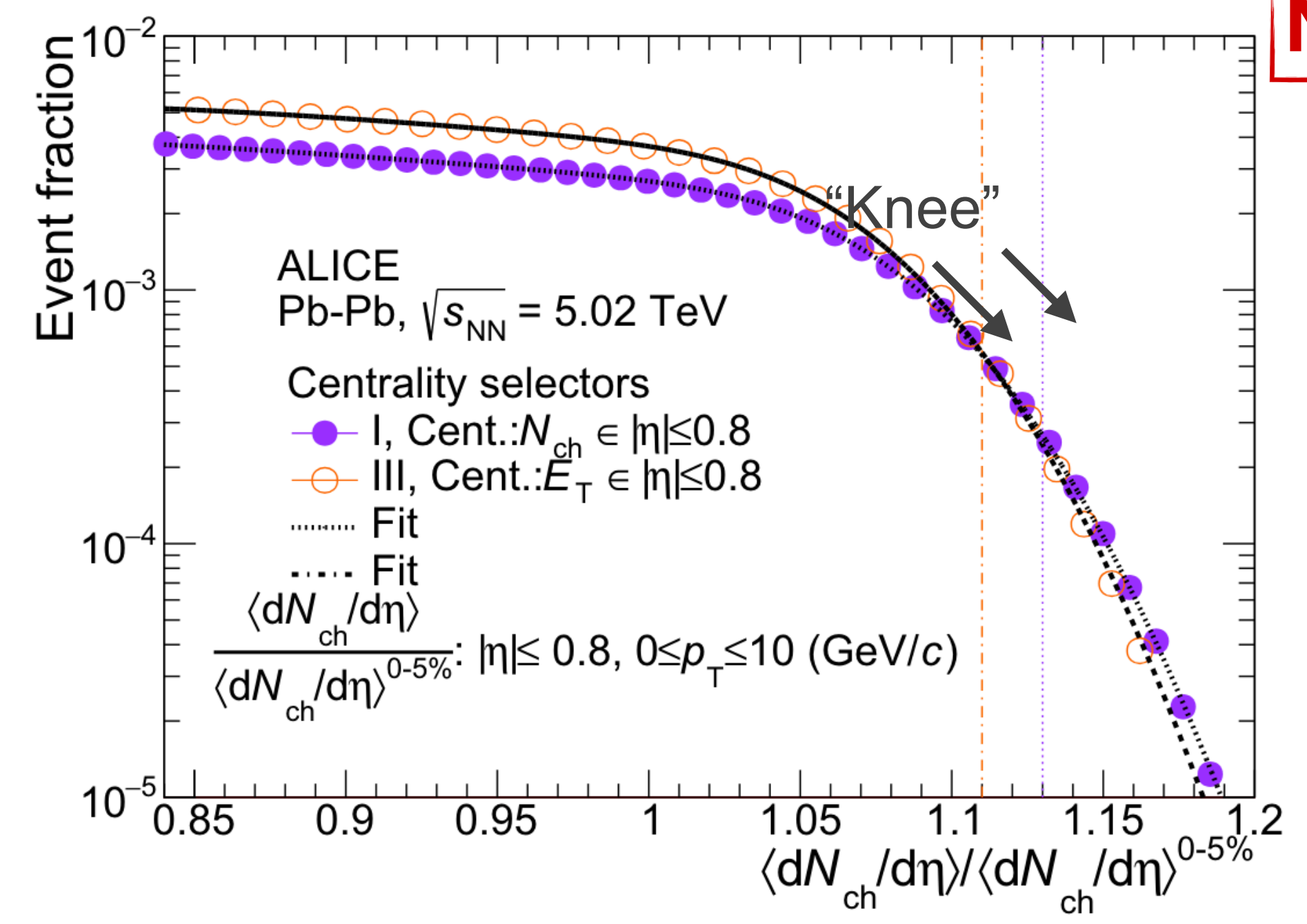
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Below the knee

$$\langle p_T \rangle / \langle p_T \rangle^{\text{ref}} \approx 1$$

Above the knee

$$\langle p_T \rangle / \langle p_T \rangle^{\text{ref}} \propto \left(\frac{N_{ch}^*}{N_{ch,knee}^*} \right)^{c_s^2}$$



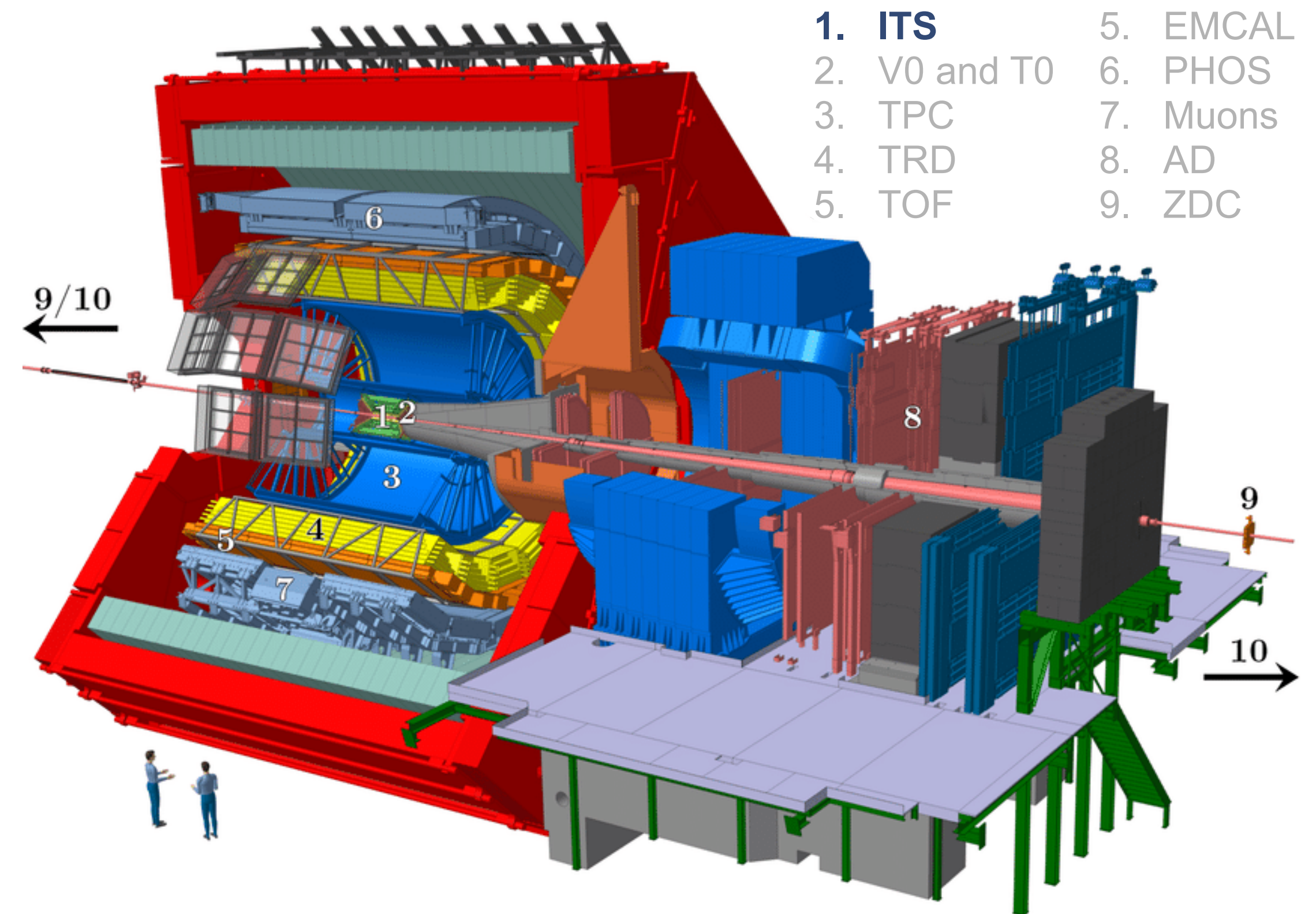
Relevant subdetectors:

Inner Tracking System (ITS)

Vertex identification, tracking

Collision system:

Pb–Pb at $\sqrt{s_{NN}} = 5.02$ TeV



Charged-particle **multiplicity** down to 30 MeV/c
with ITS tracklets in ALICE

Tracklet: track segments joining hits in two innermost ITS layers

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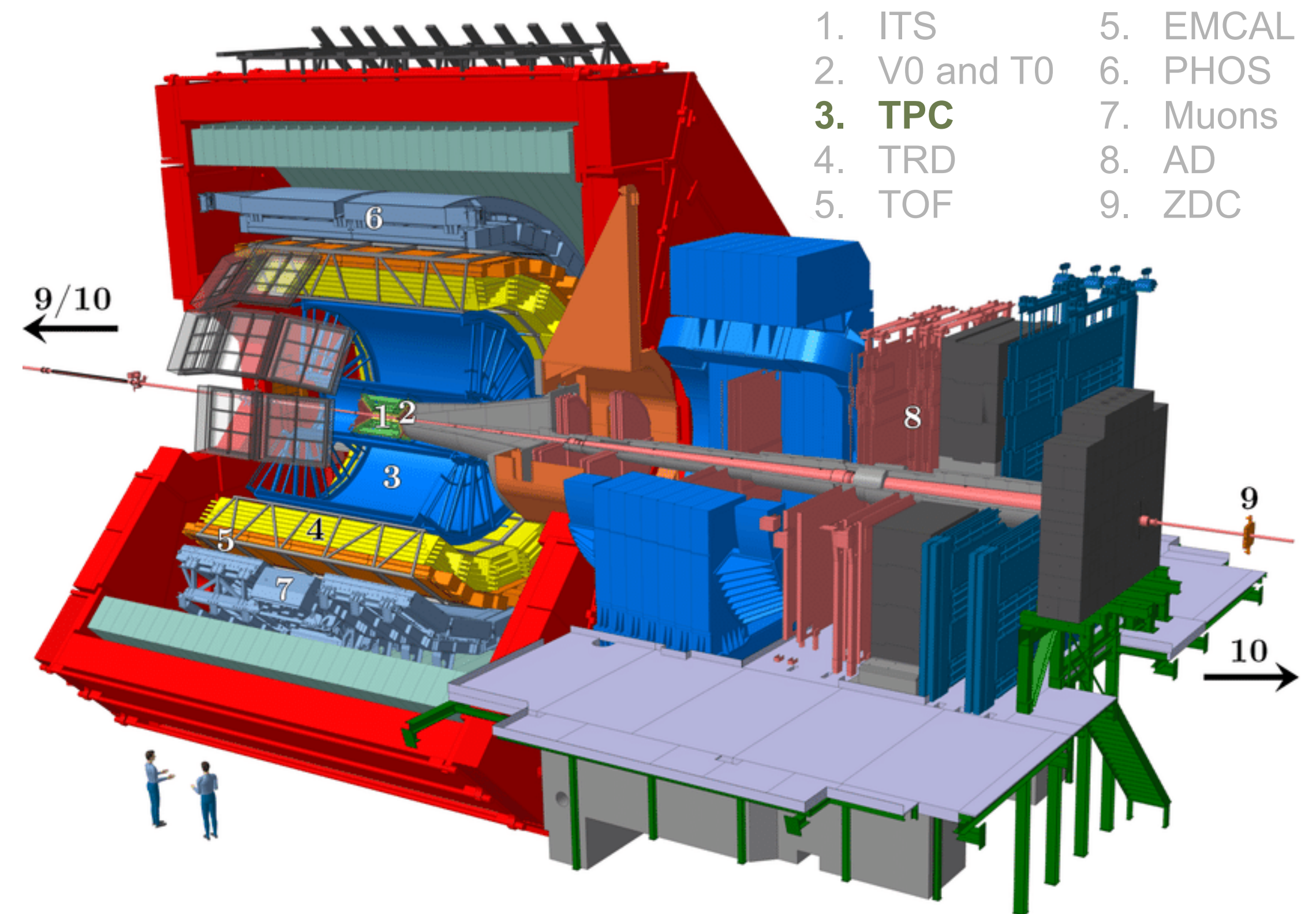
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Time-Projection Chamber (TPC)

Tracking, particle identification

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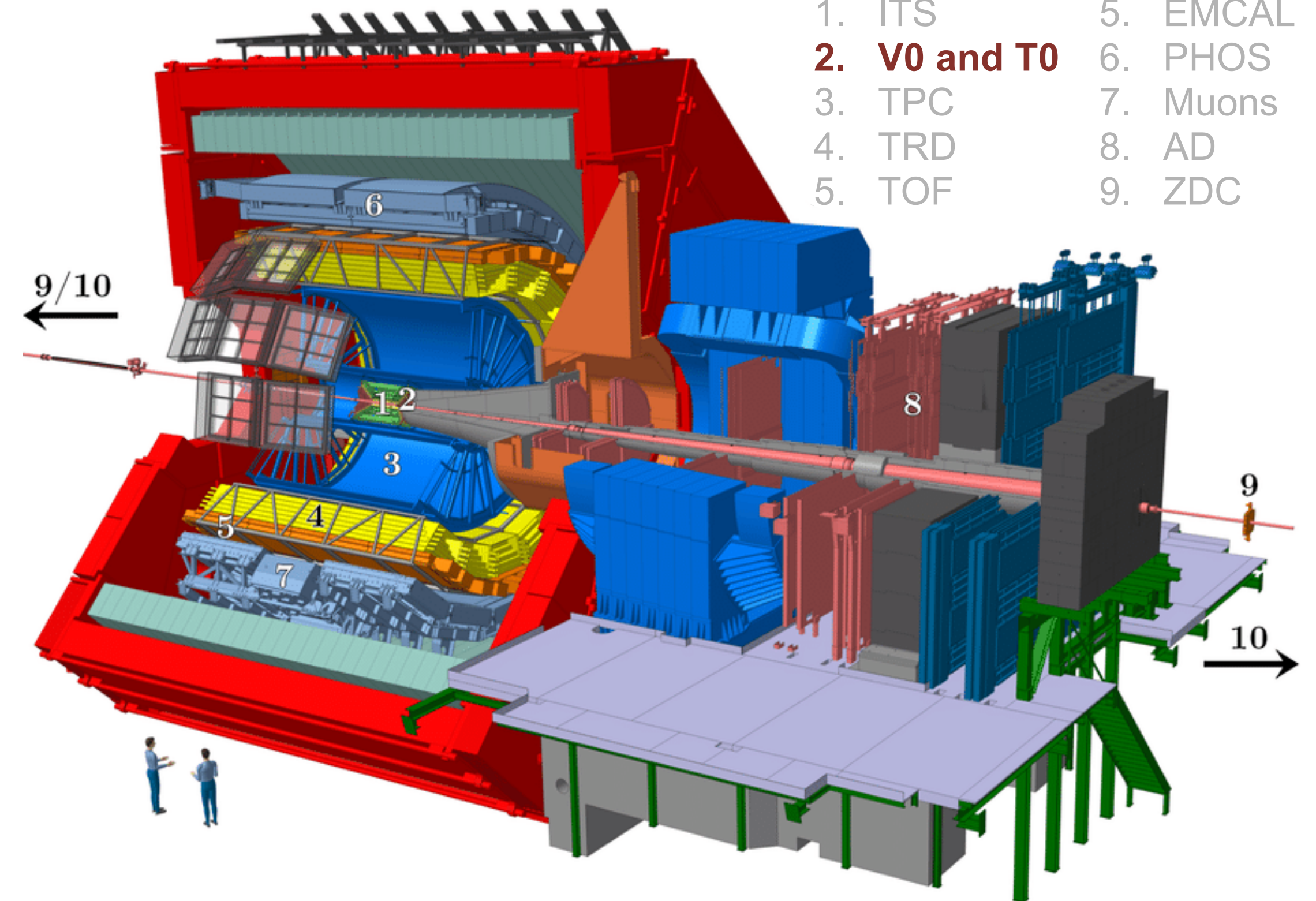
V0A ($2.8 < \eta < 5.1$) and V0C ($-3.7 < \eta < -1.7$)

Multiplicity and centrality estimation

Collision system:

Pb–Pb at $\sqrt{s_{NN}} = 5.02$ TeV

- | | |
|--------------|----------|
| 1. ITS | 5. EMCAL |
| 2. V0 and T0 | 6. PHOS |
| 3. TPC | 7. Muons |
| 4. TRD | 8. AD |
| 5. TOF | 9. ZDC |



Charged-particle **multiplicity** down to 30 MeV/c
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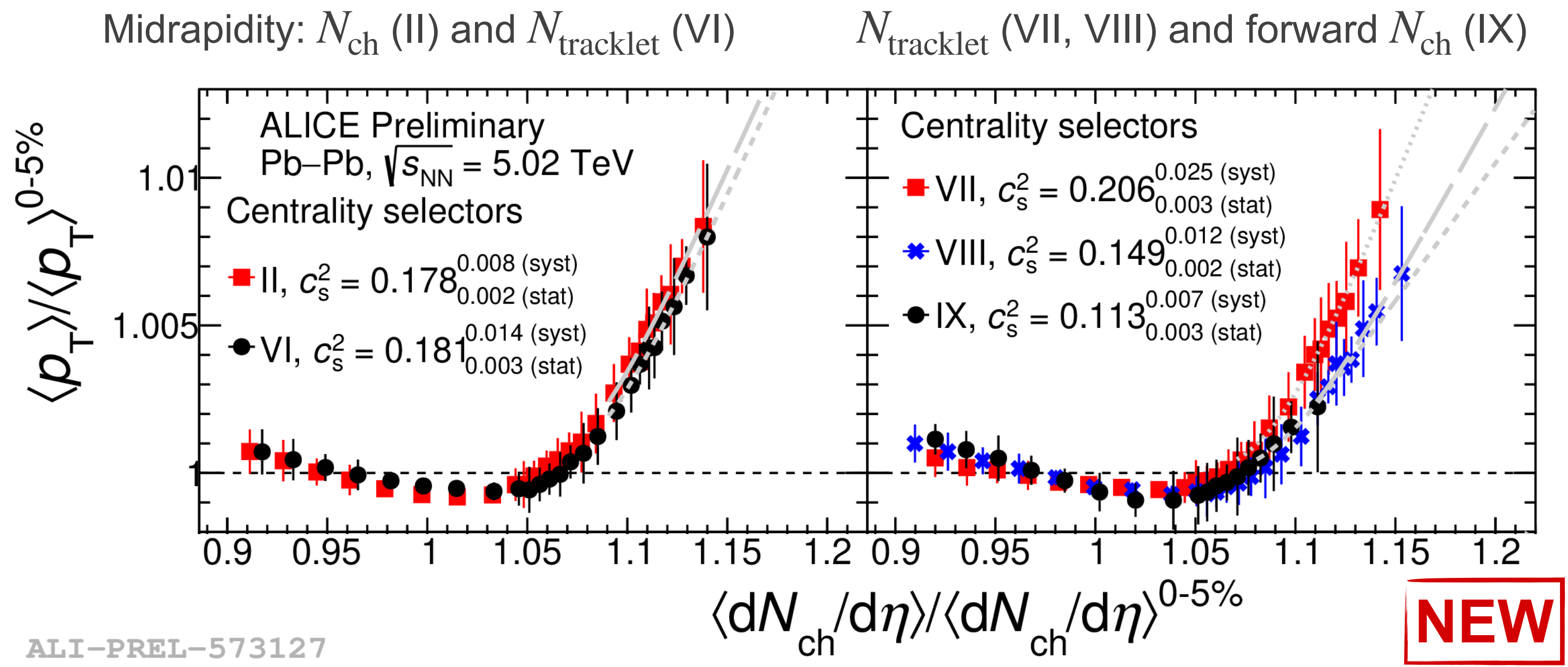
Tracklet: track segments joining hits in two innermost ITS layers

Extracting the speed of sound

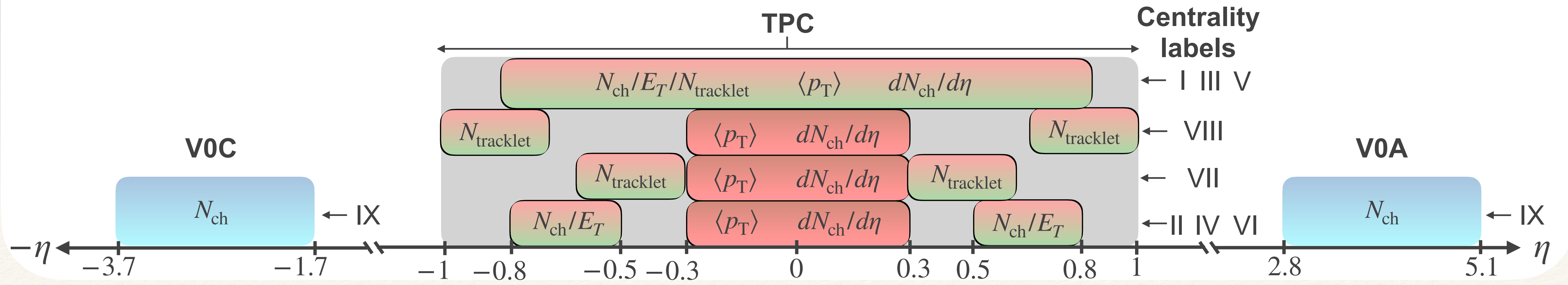
Extraction of c_s^2 depends on the centrality determination

- Forward vs. midrapidity
- ITS tracklets vs full tracks
- E_T vs N_{ch}

Decreased c_s^2 using forward centrality determination



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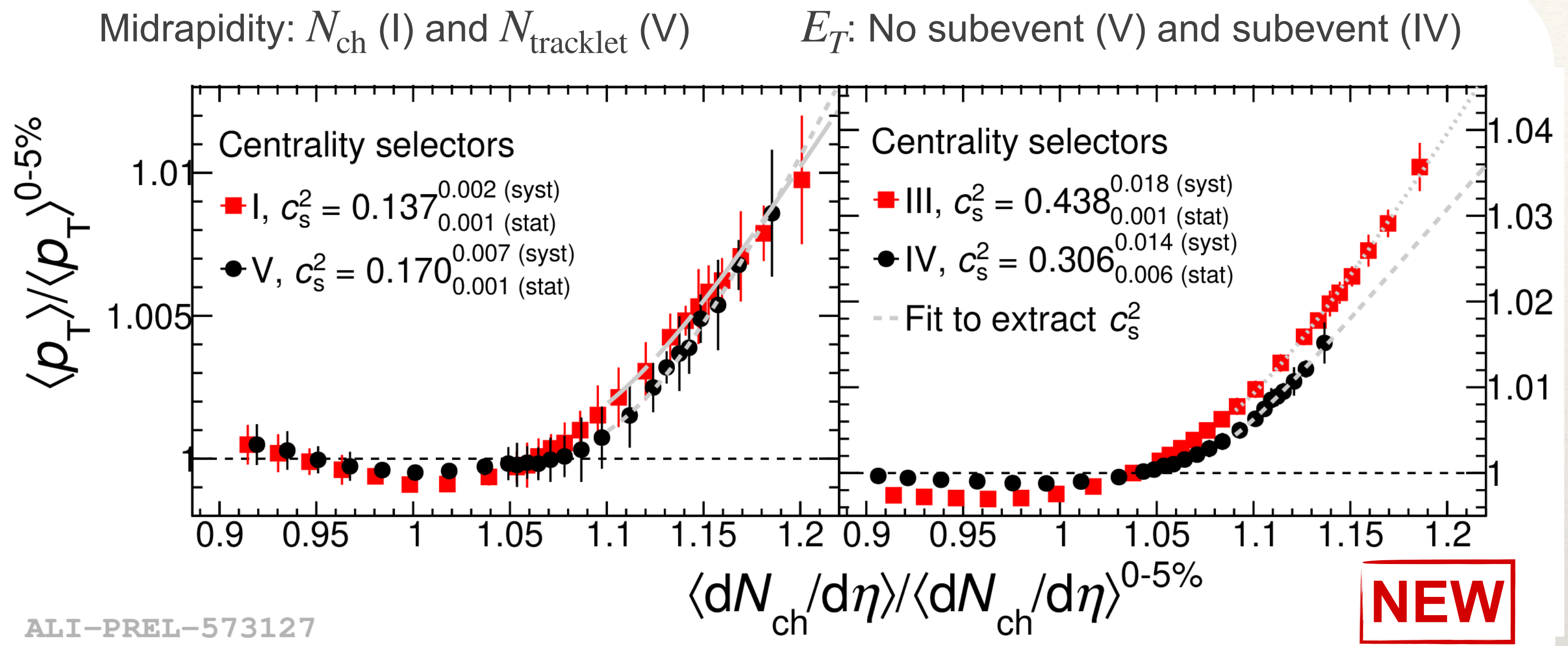
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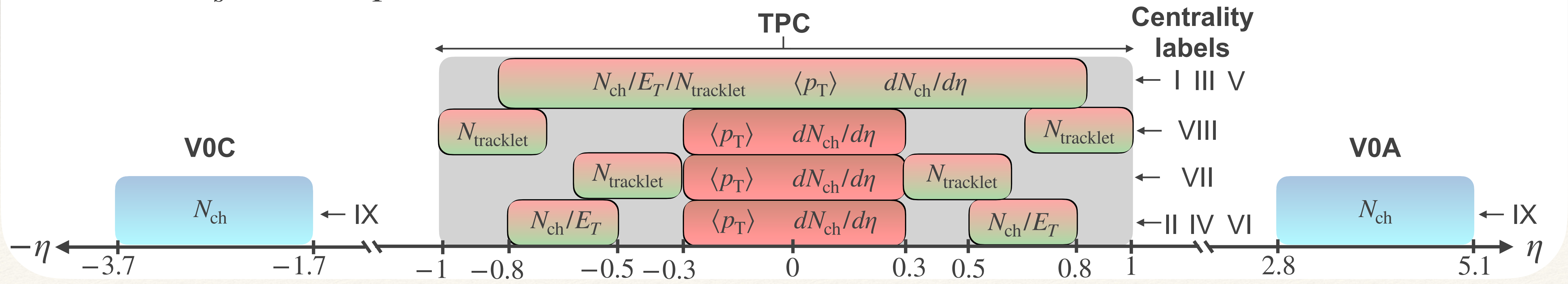
- Forward vs. midrapidity
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Decreased c_s^2 using forward centrality determination

Increased c_s^2 using E_T

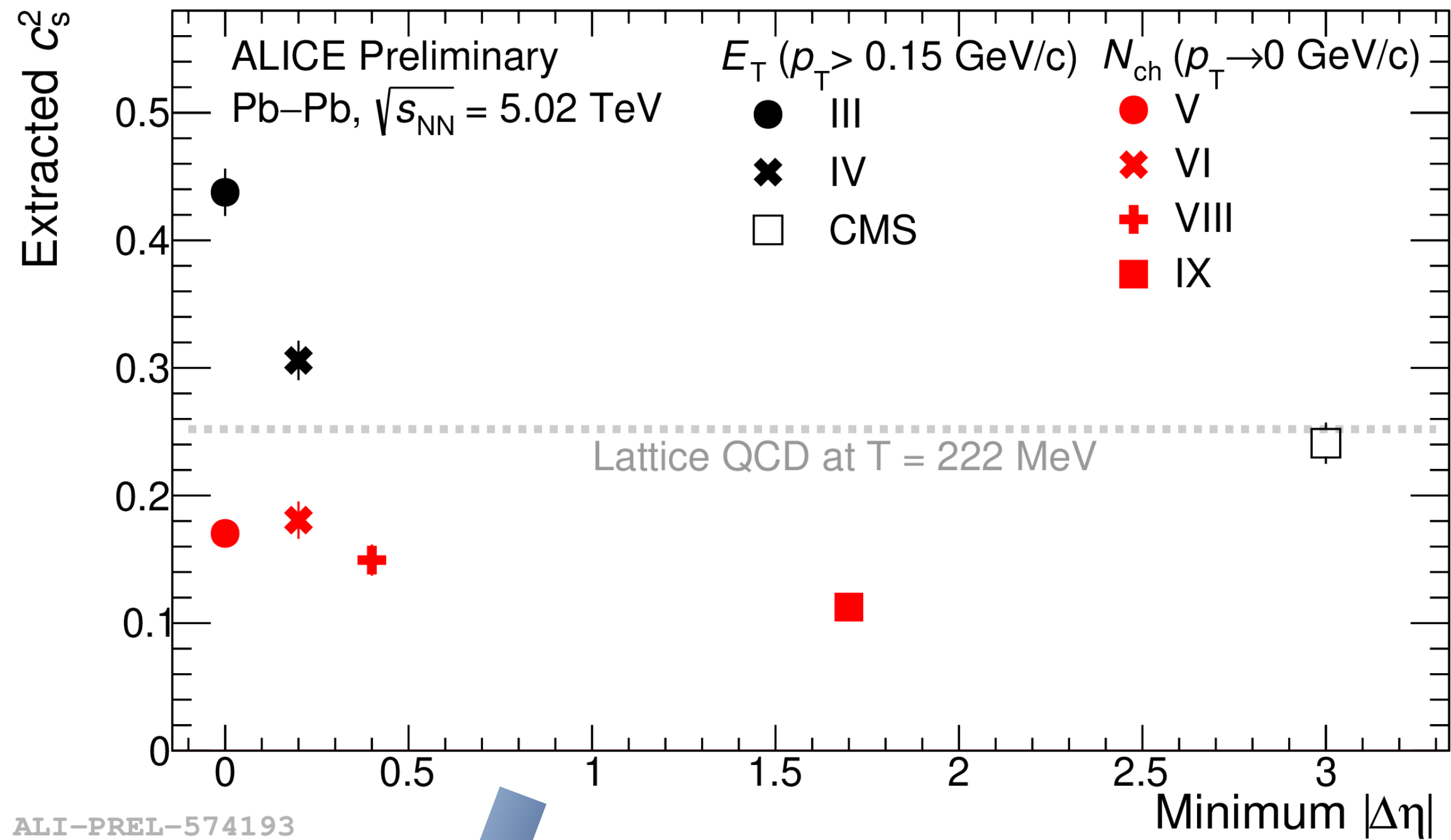


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Speed of sound as function of η -gap

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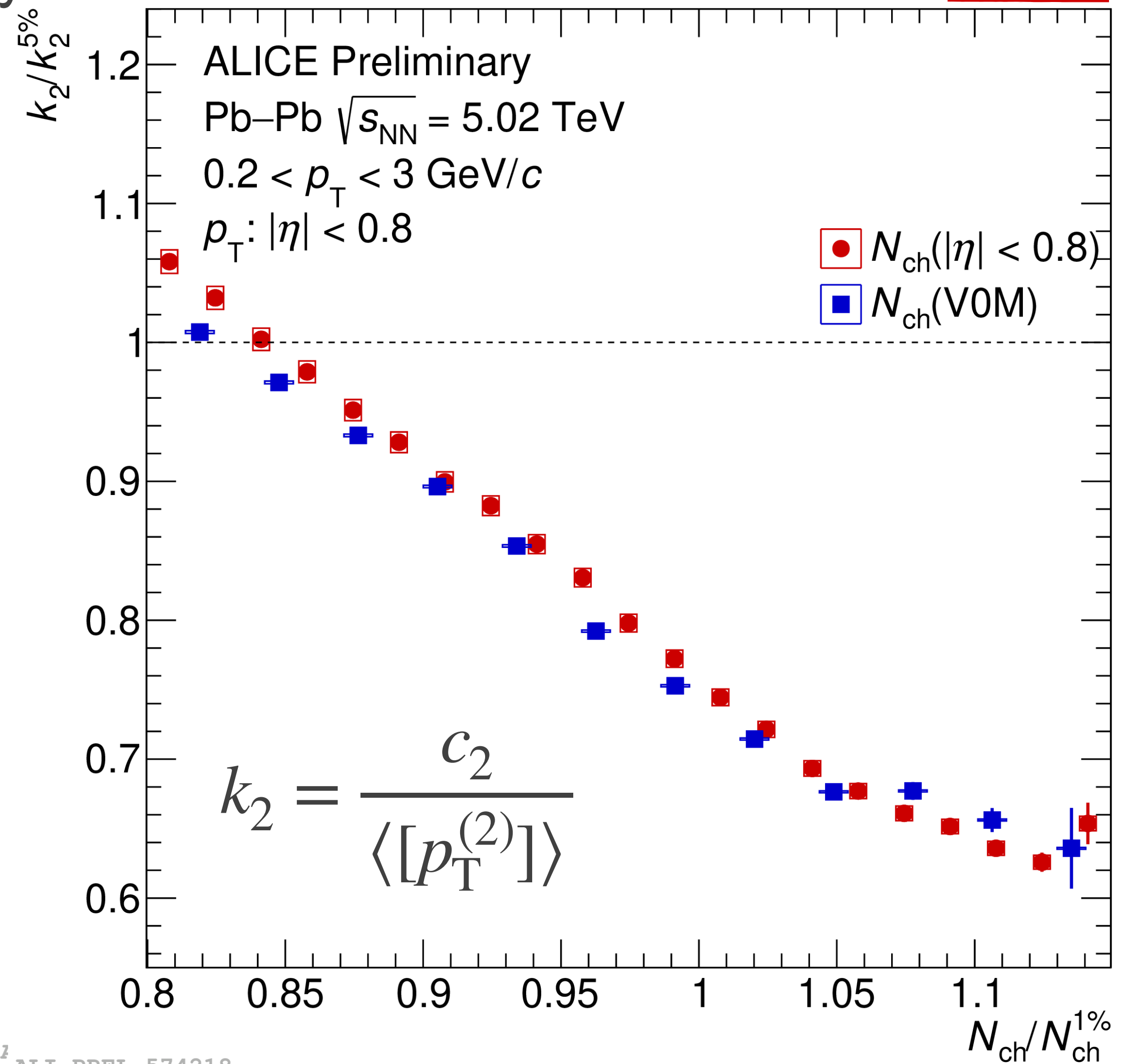
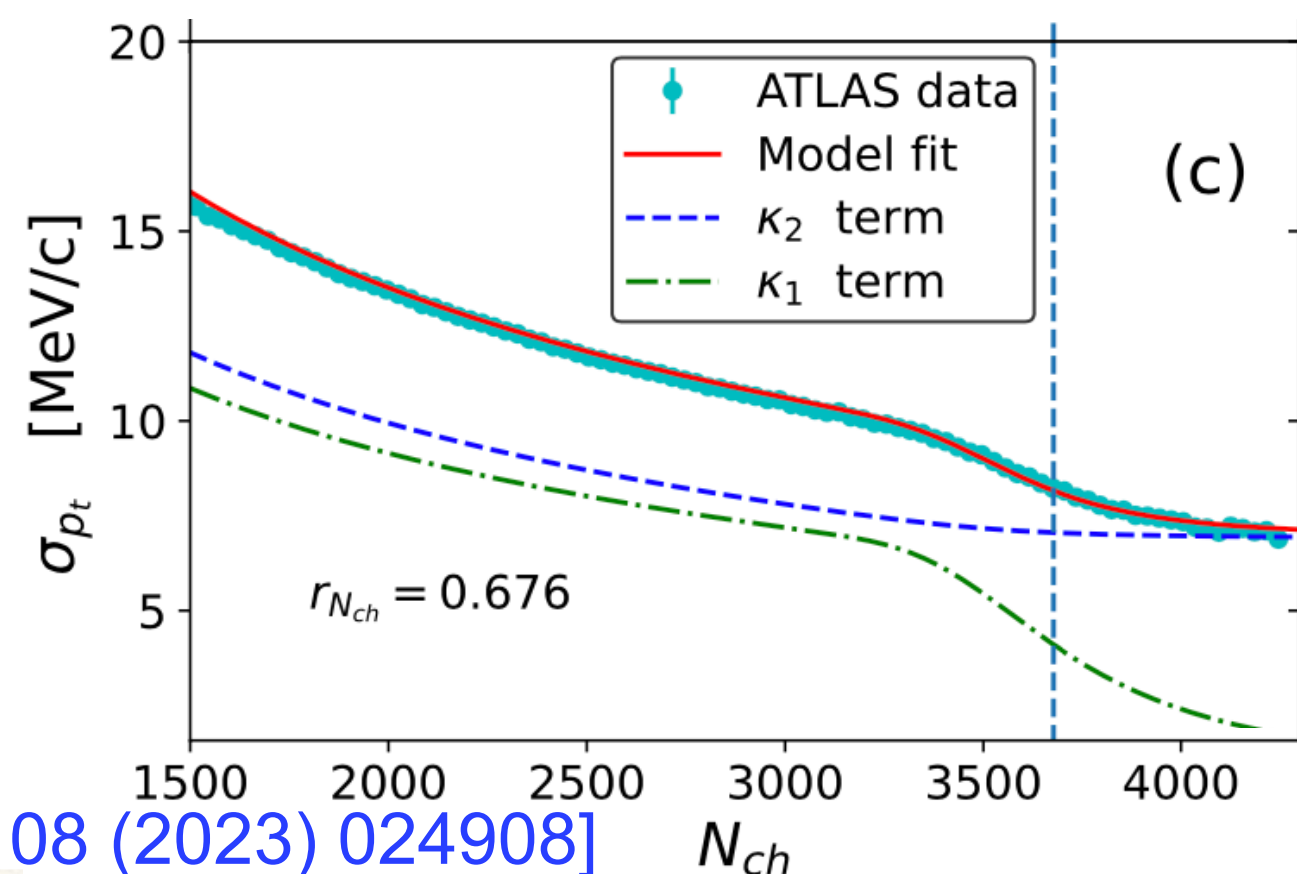
Observable	Label	Centrality estimation	$\langle p_T \rangle$ and $\langle dN_{ch}/d\eta \rangle$	η gap
N_{ch} in TPC	I	$ \eta \leq 0.8$	$ \eta \leq 0.8$	0
	II	$0.5 \leq \eta \leq 0.8$	$ \eta \leq 0.3$	0.3
E_T in TPC	III	$ \eta \leq 0.8$	$ \eta \leq 0.8$	0
	IV	$0.5 \leq \eta \leq 0.8$	$ \eta \leq 0.3$	0.3
$N_{tracklets}$ in SPD	V	$ \eta \leq 0.8$	$ \eta \leq 0.8$	0
	VI	$0.5 \leq \eta \leq 0.8$	$ \eta \leq 0.3$	0.3
	VII	$0.3 < \eta \leq 0.6$	$ \eta \leq 0.3$	0
	VIII	$0.7 \leq \eta \leq 1$	$ \eta \leq 0.3$	0.4
N_{ch} in V0	IX	$-3.7 < \eta < -1.7 + 2.8 < \eta < 5.1$	$ \eta \leq 0.8$	1.7

Summary plot of extracted c_s^2 with different centrality estimators and various η separations between particles used for $\langle p_T \rangle$ and centrality

Variance of $[p_T]$ in UCC

NEW

- Variations measured as a function of multiplicity determined from both midrapidity and forward rapidity

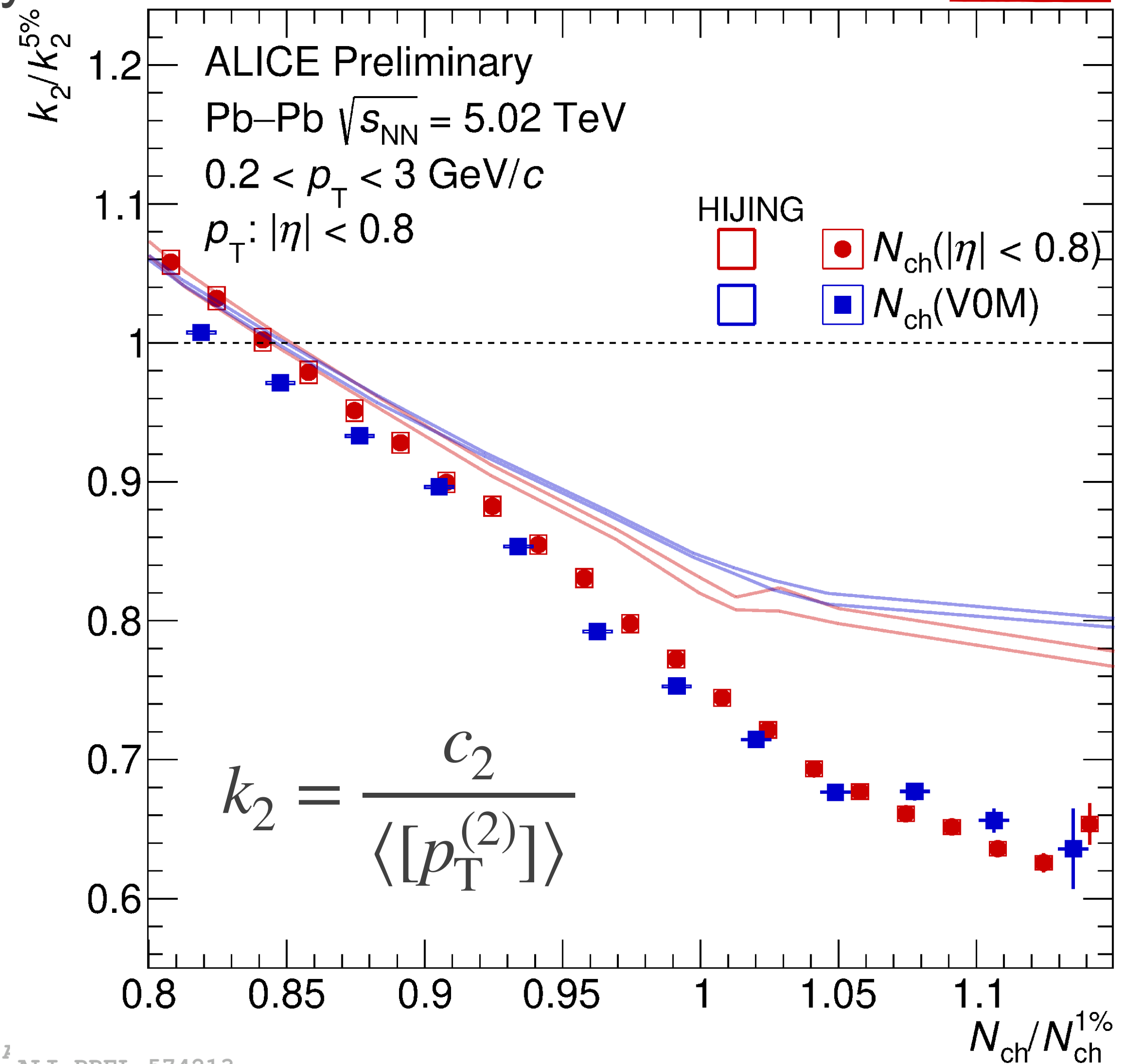
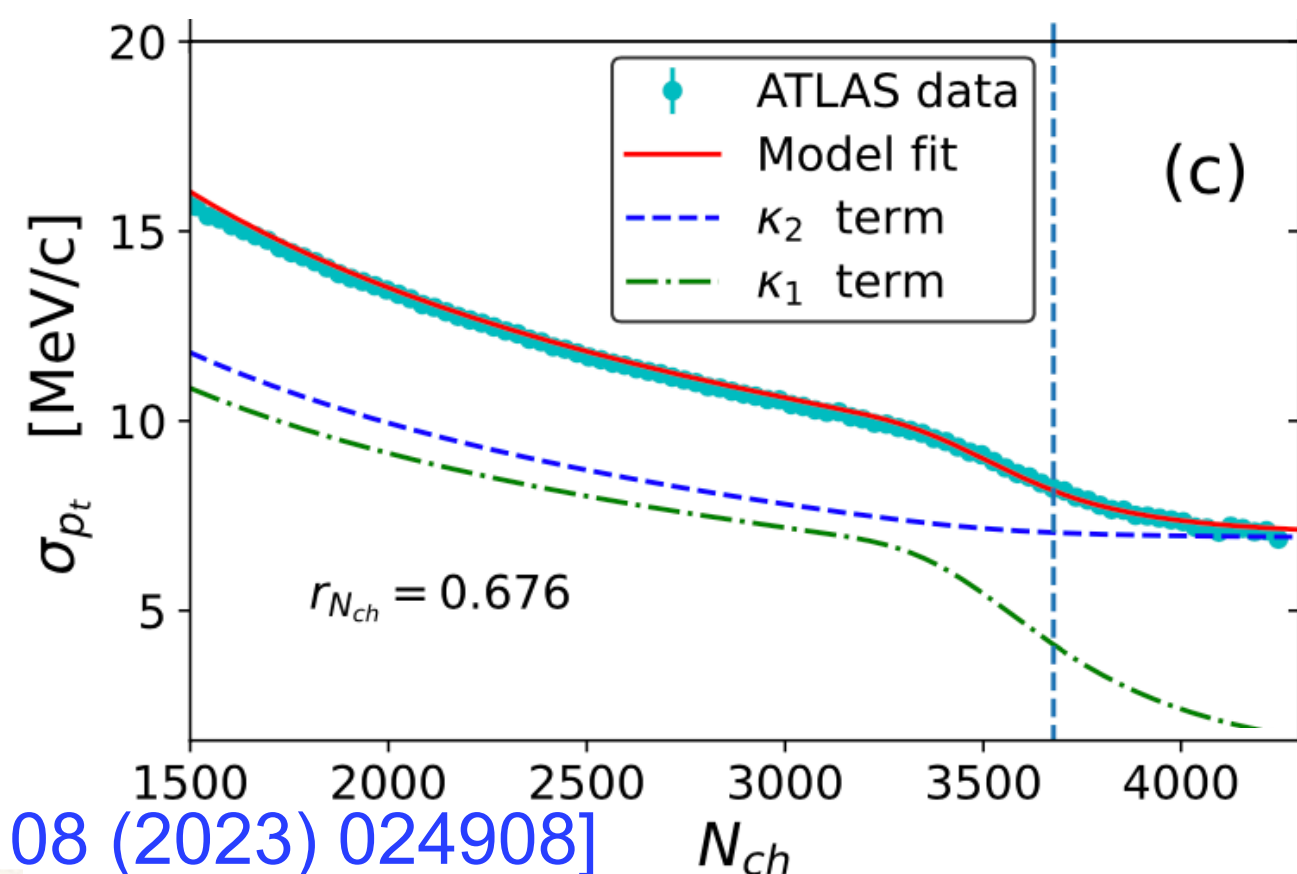


[R. Samanta et al., PRC 108 (2023) 024908]

² ALI-PREL-574218

NEW

- Variances measured as a function of multiplicity determined from both midrapidity and forward rapidity
- Independent sources picture (HIJING) :
 $\rightarrow k_2 \propto N_{ch}^{-1}$
- Decrease of variance in UCC evidence of thermalisation of the medium

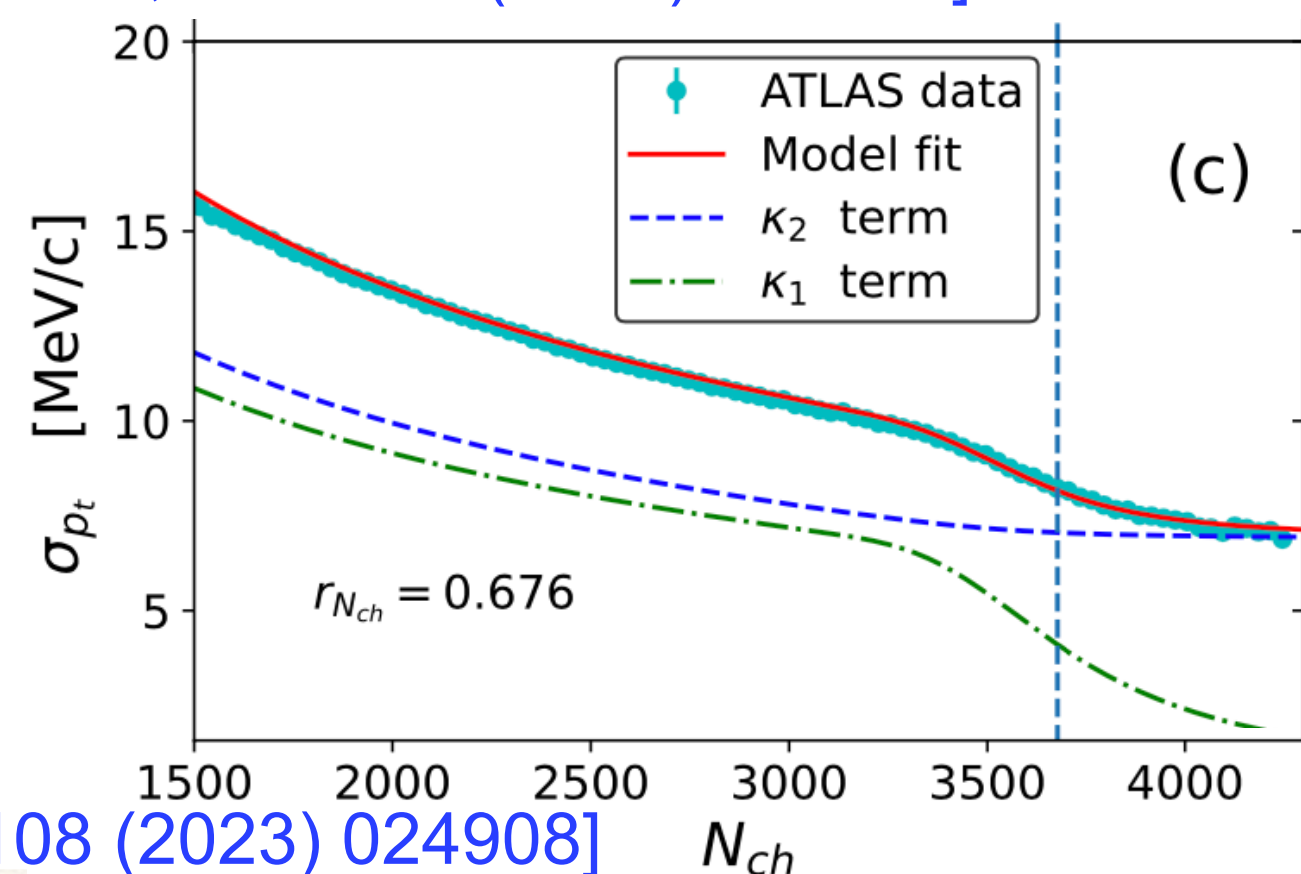


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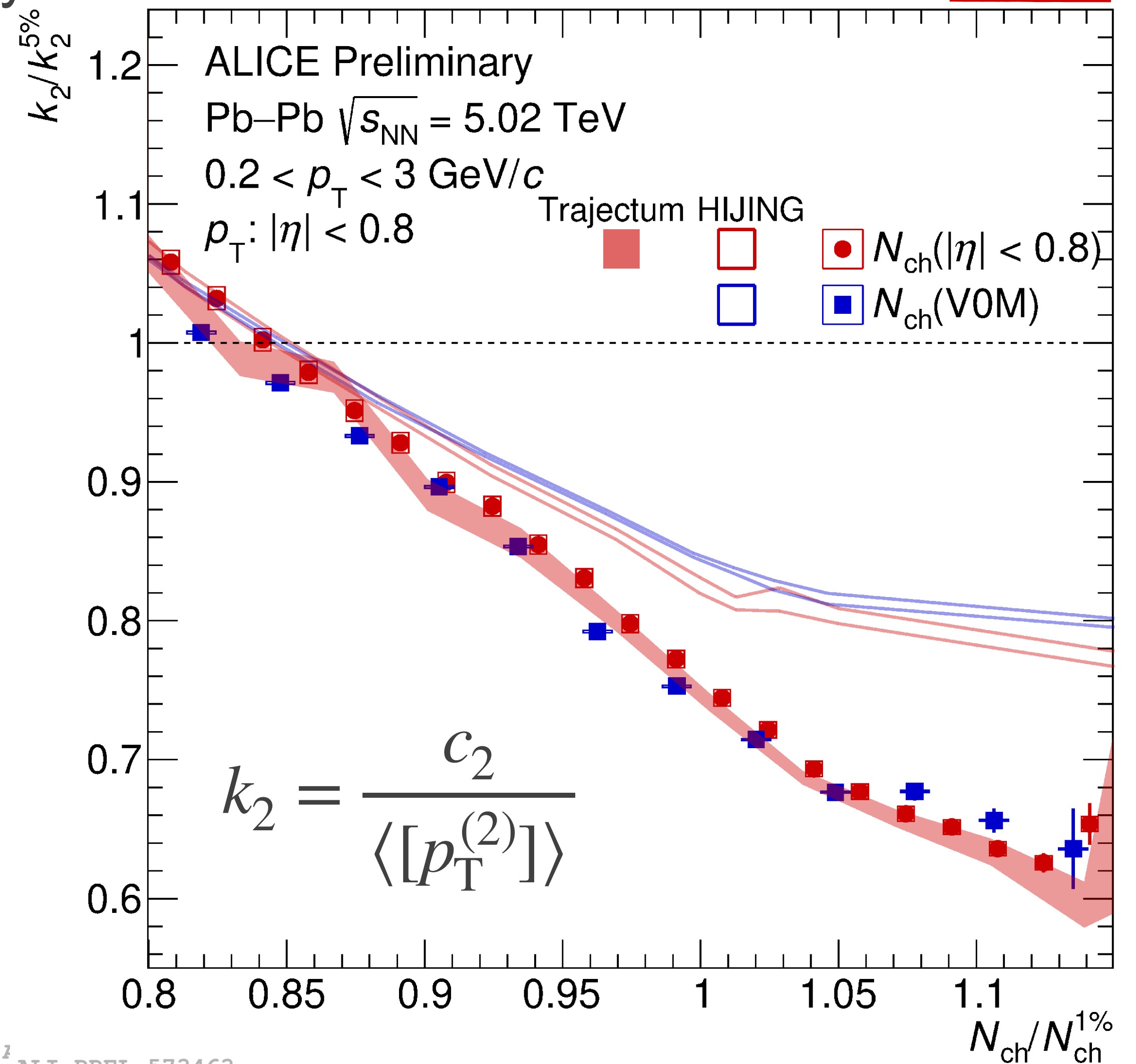
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- Trajectum: good agreement with data
[\[G. Nijs and W. van der Schee, PLB 853 \(2024\) 138636\]](#)

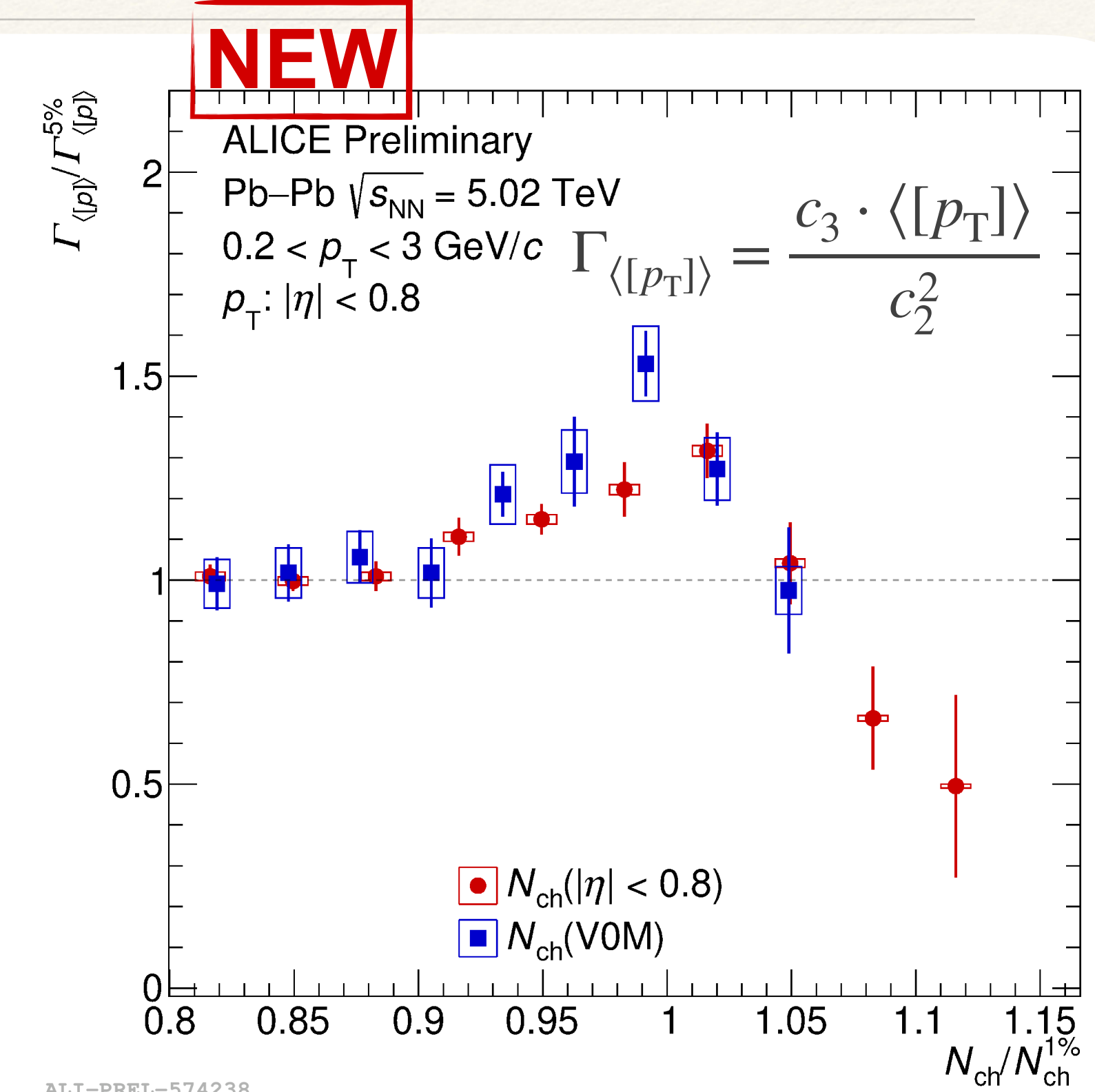
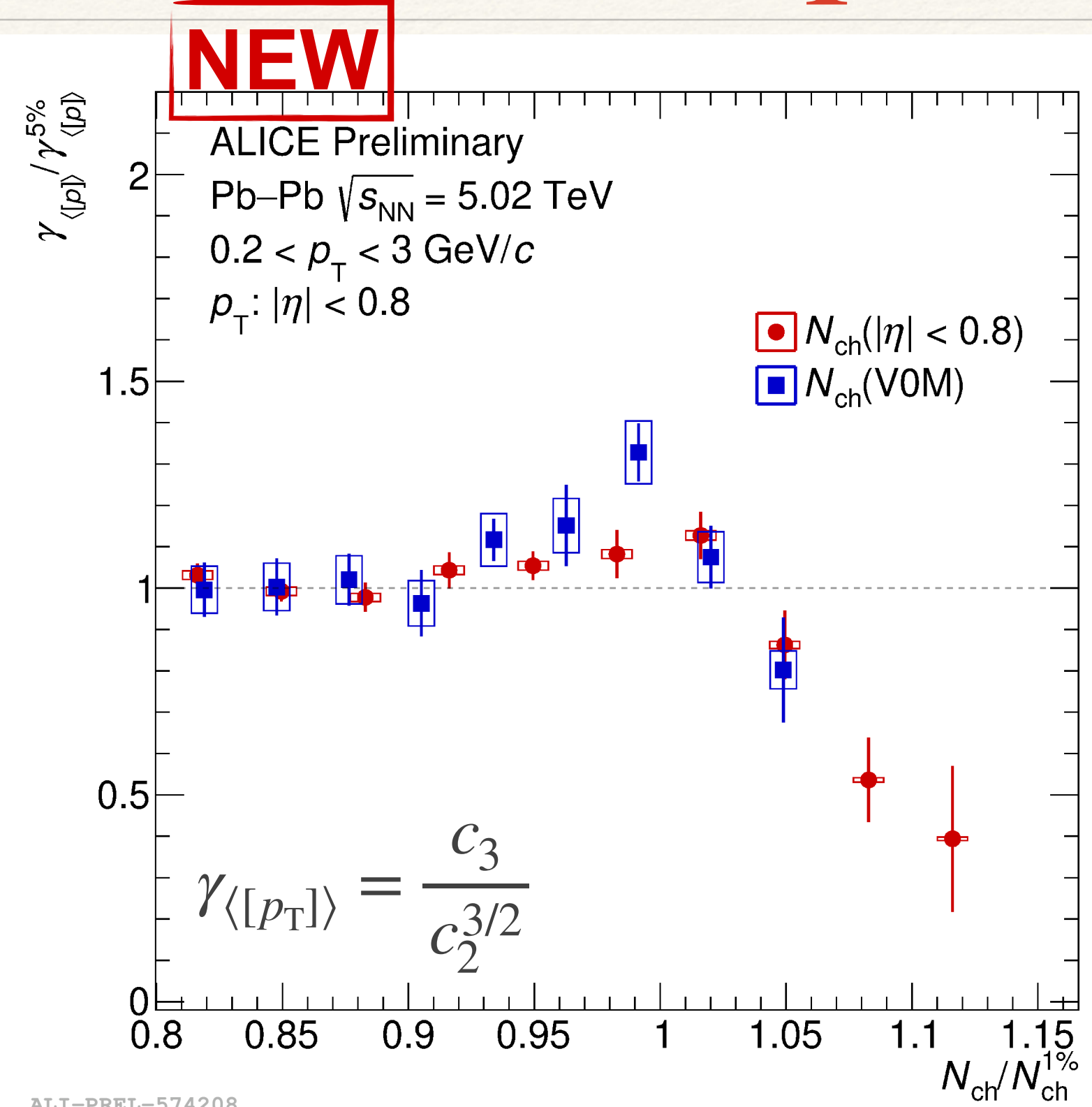
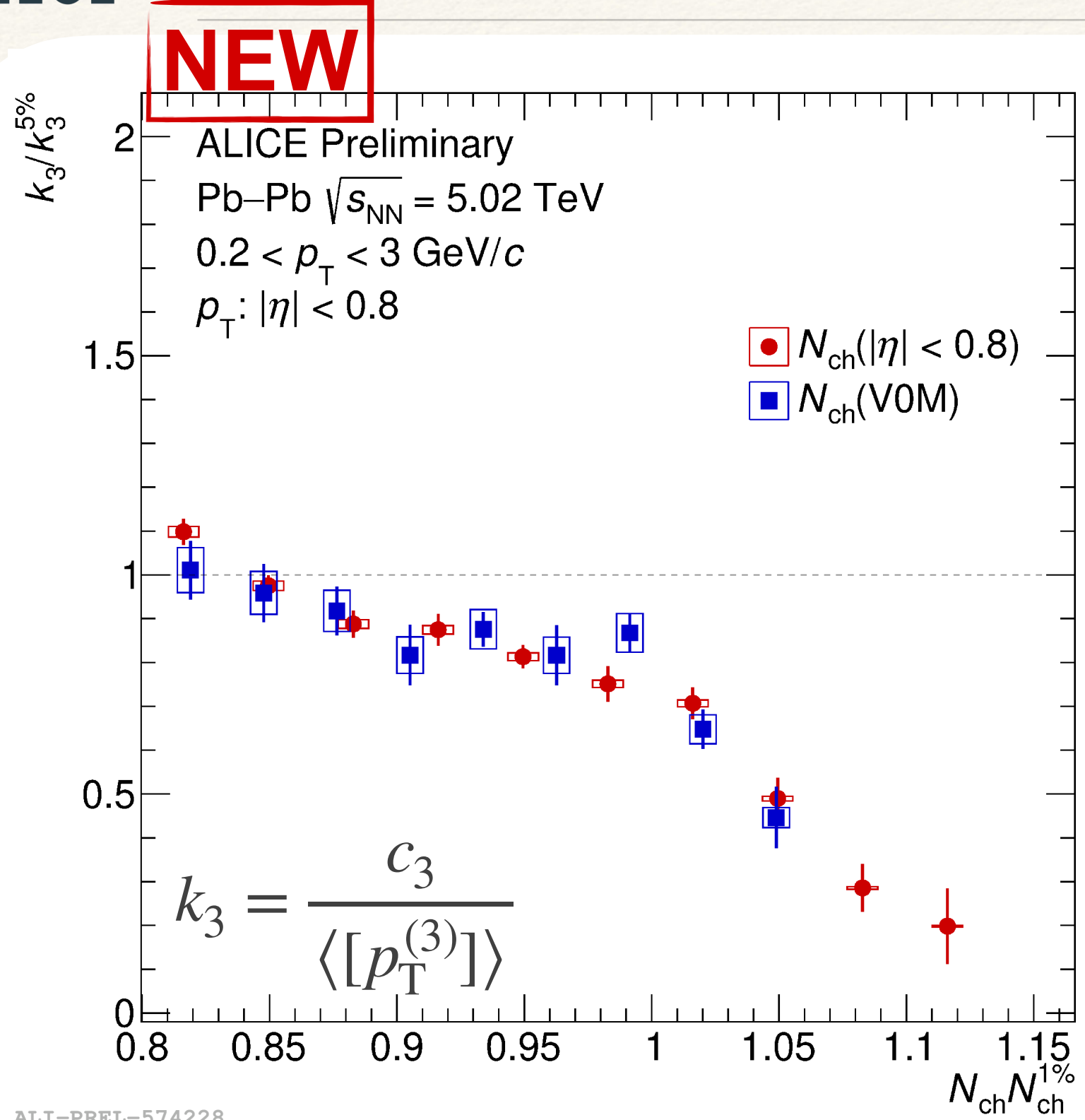


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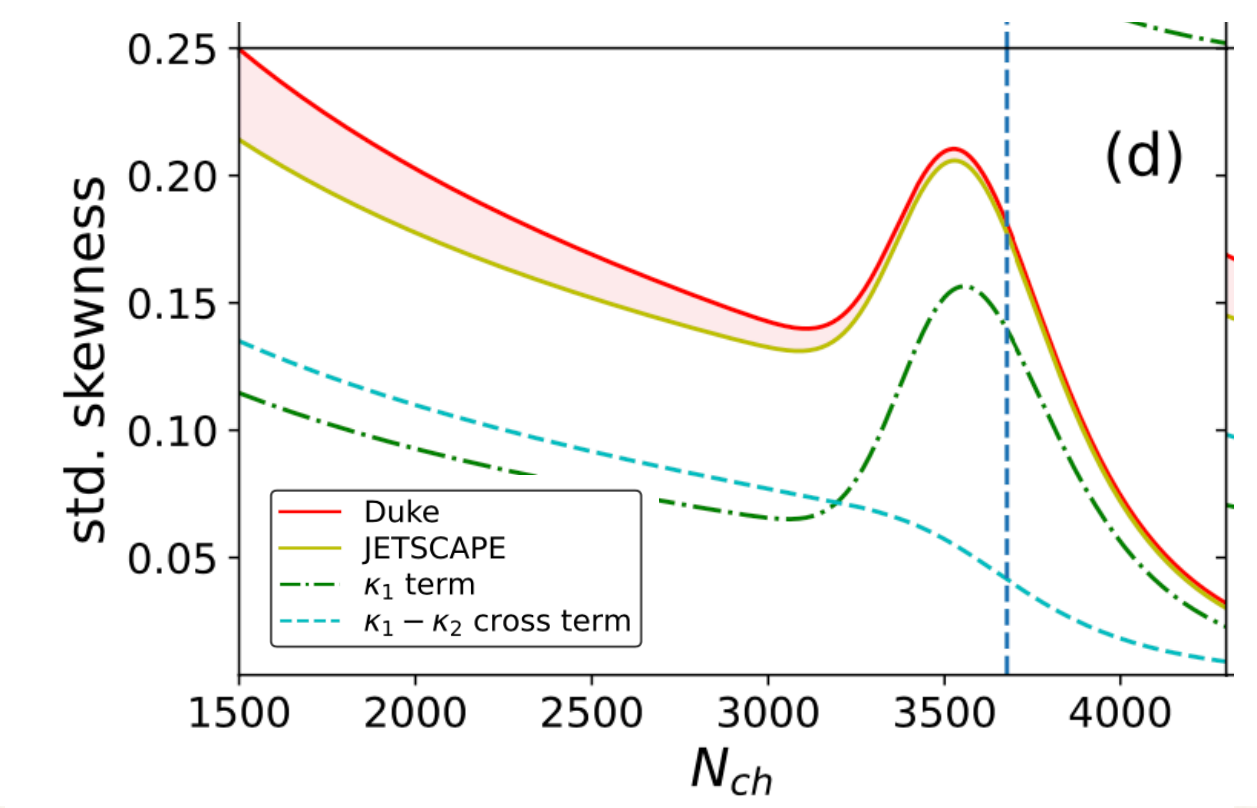


² ALI-PREL-573463

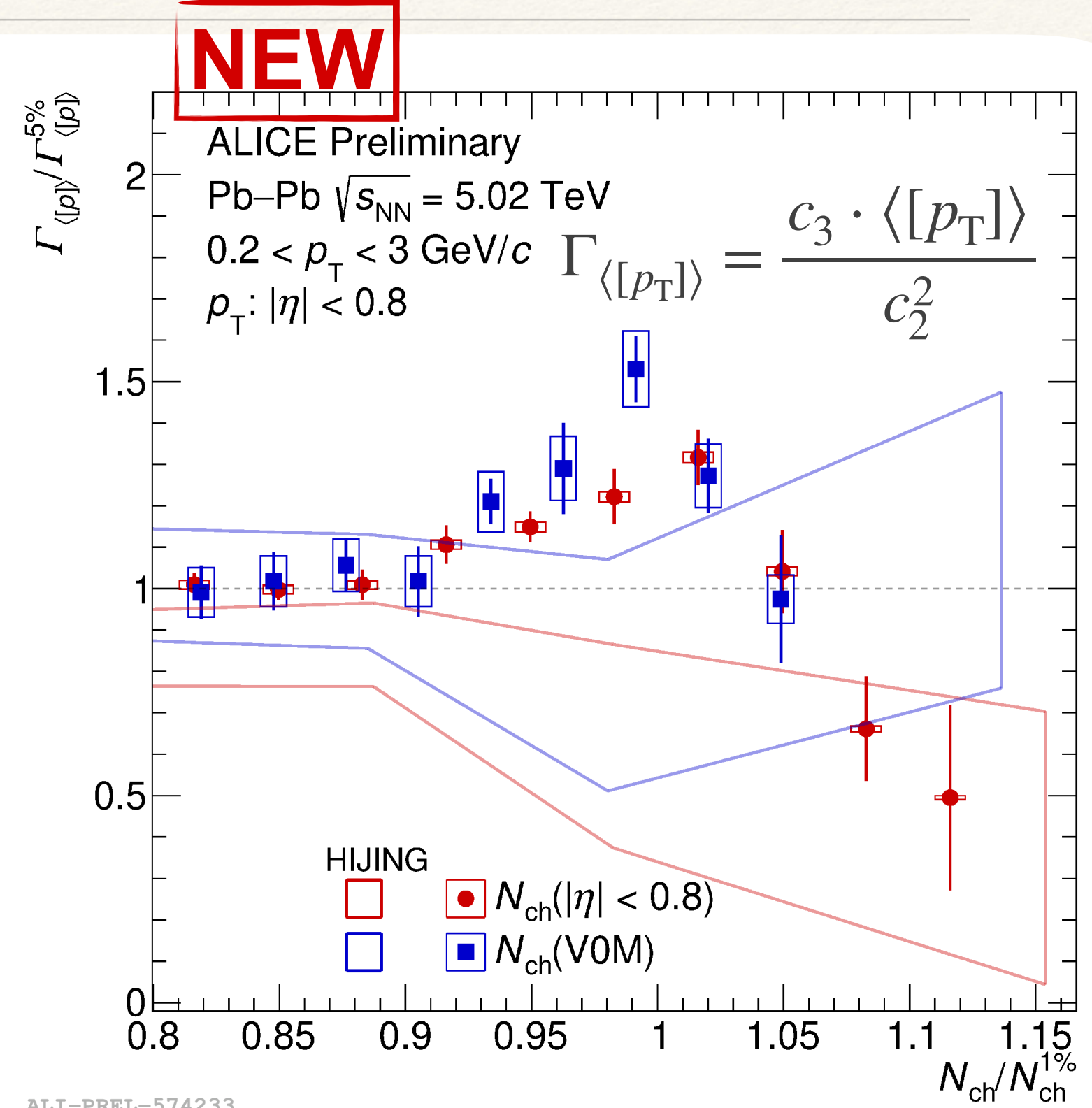
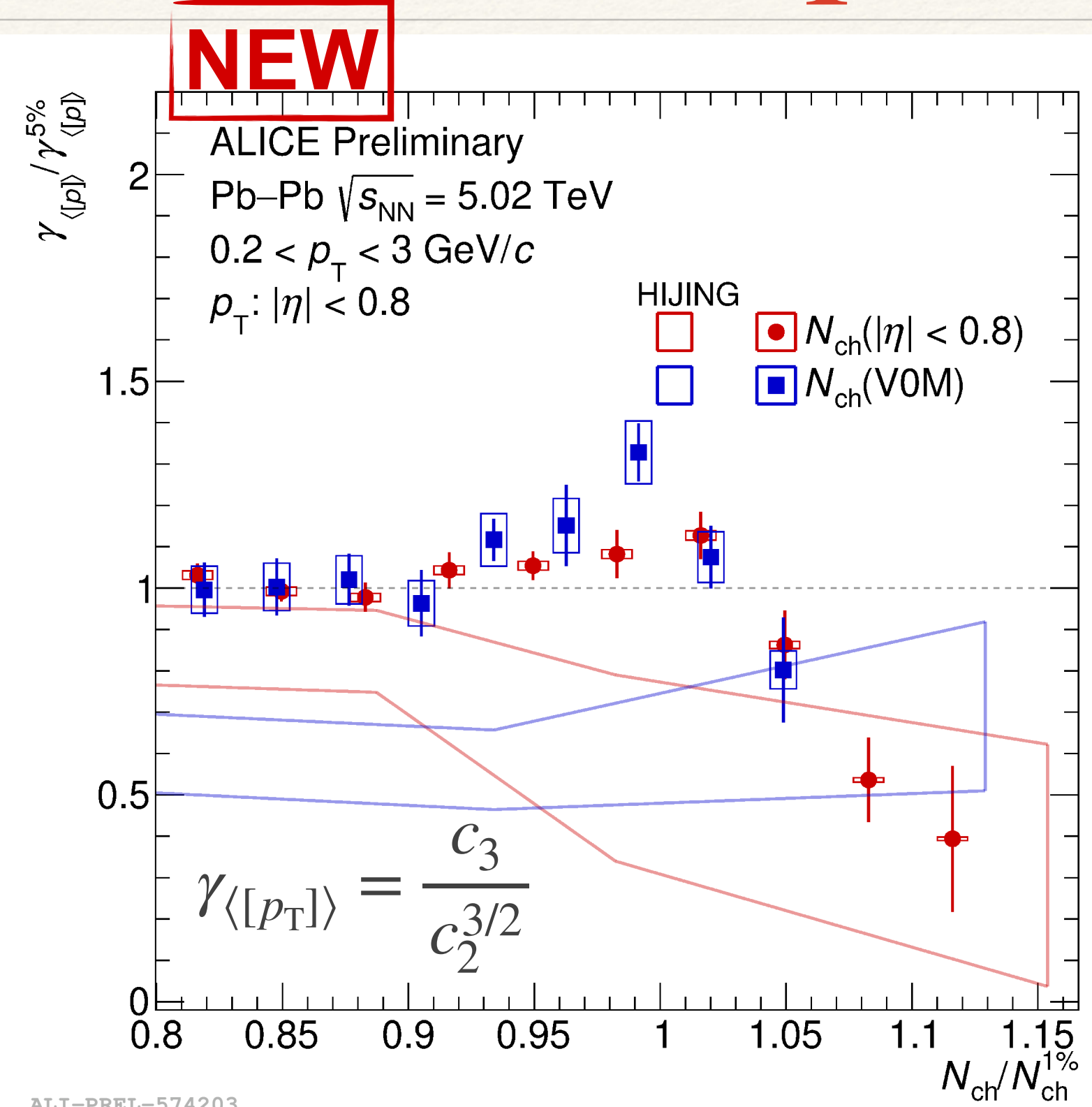
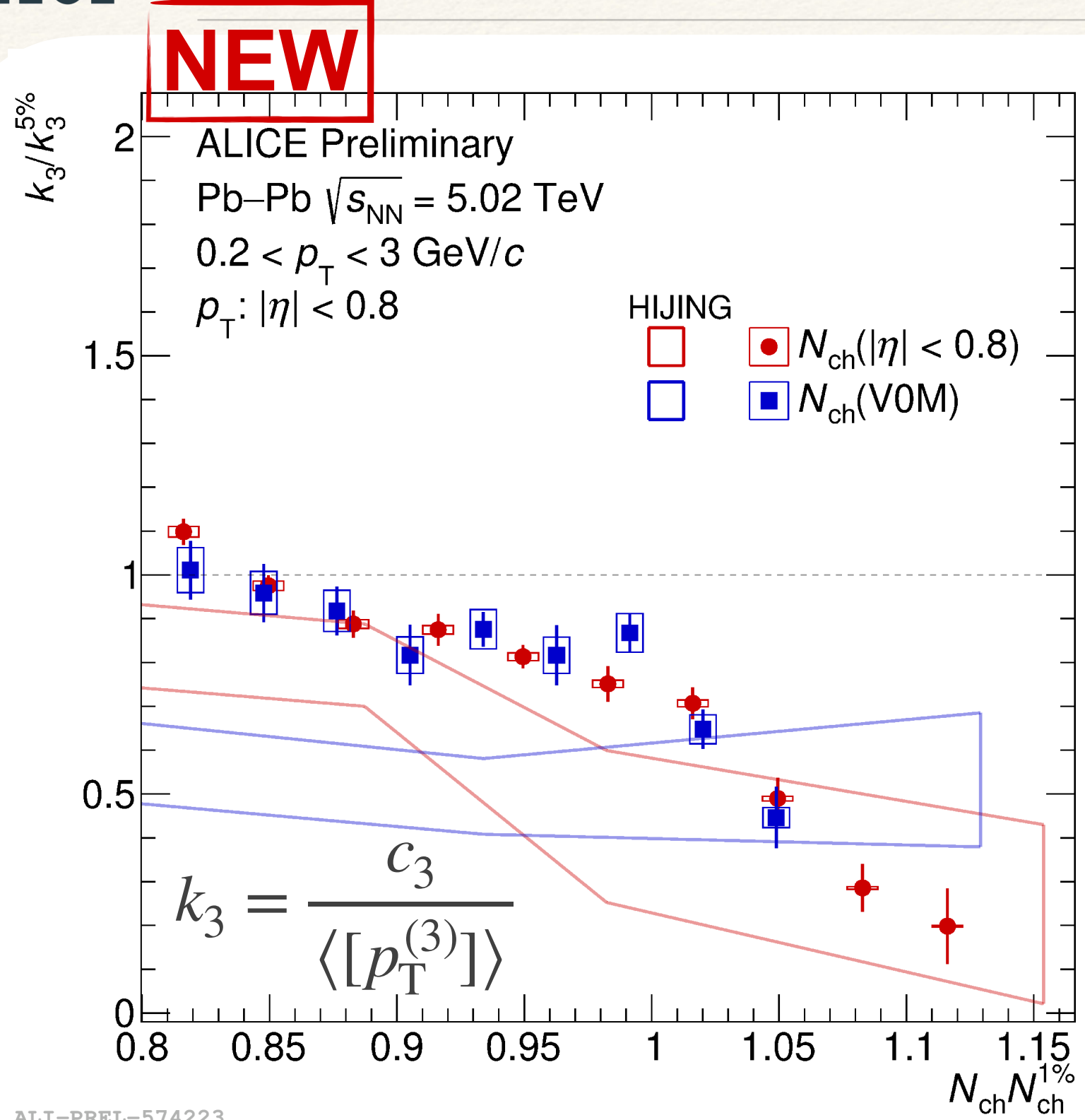
Skewness of $[p_T]$ in UCC



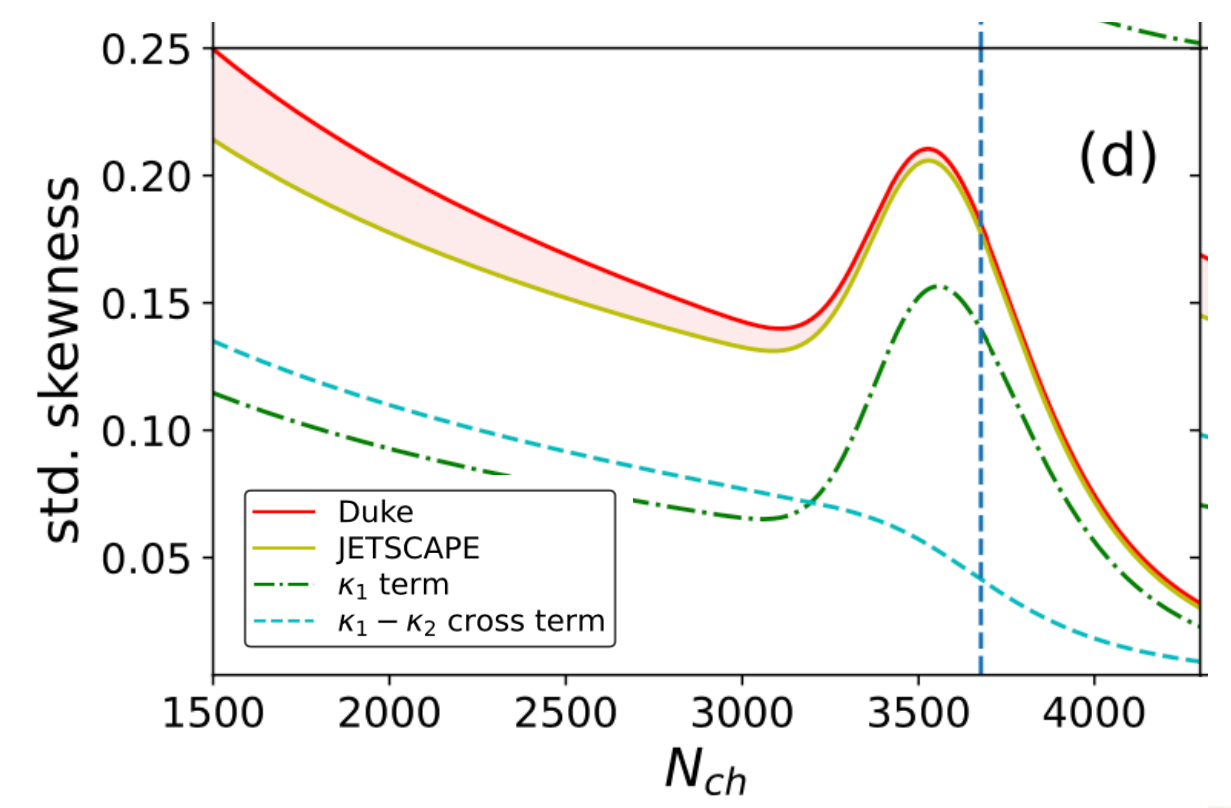
- Skewness behaviour depends on normalisation
- Interplay between skewness and variance in $\gamma_{\langle [p_T] \rangle}$ and $\Gamma_{\langle [p_T] \rangle}$
- Bump driven by geometrical fluctuations



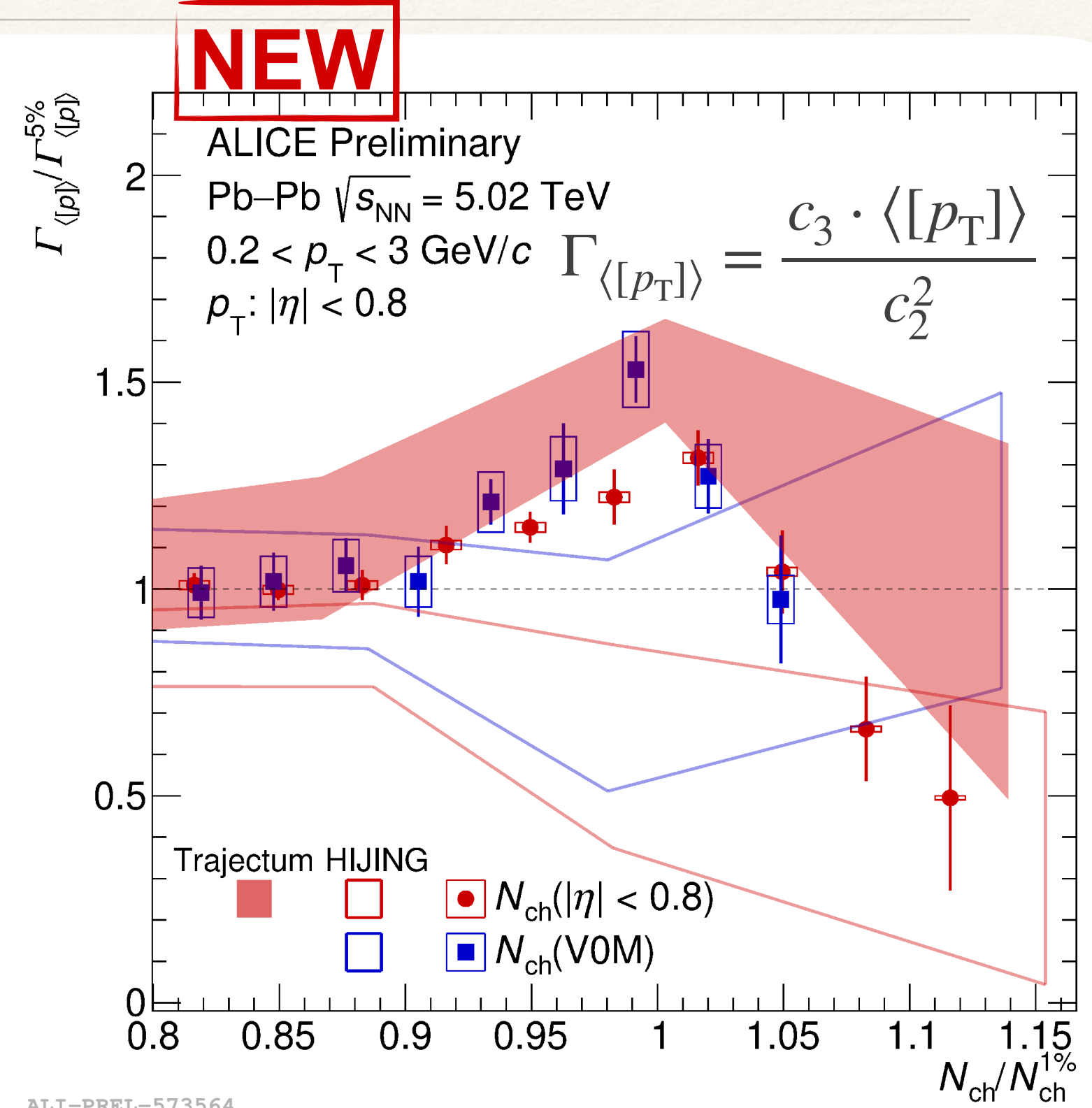
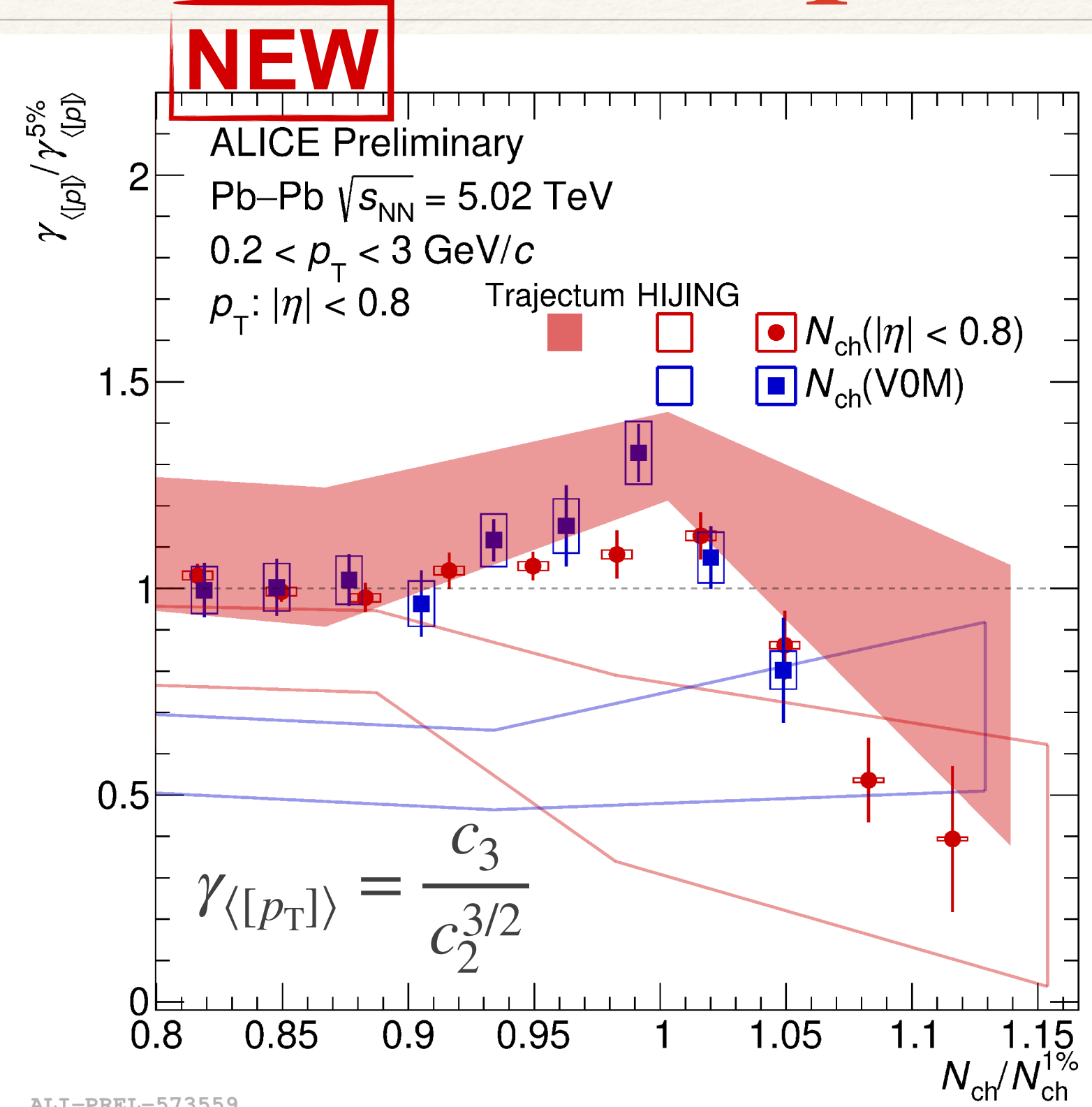
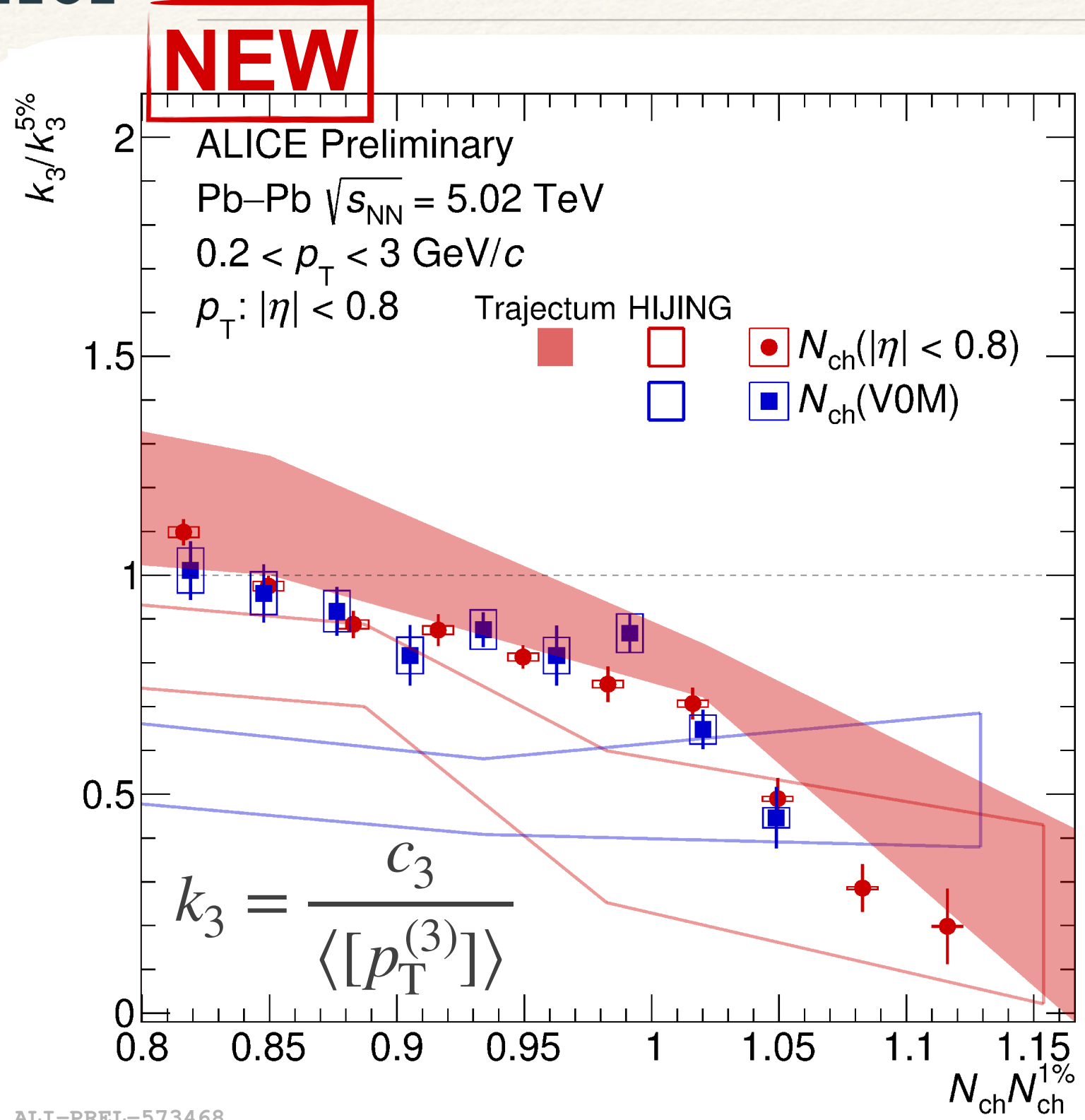
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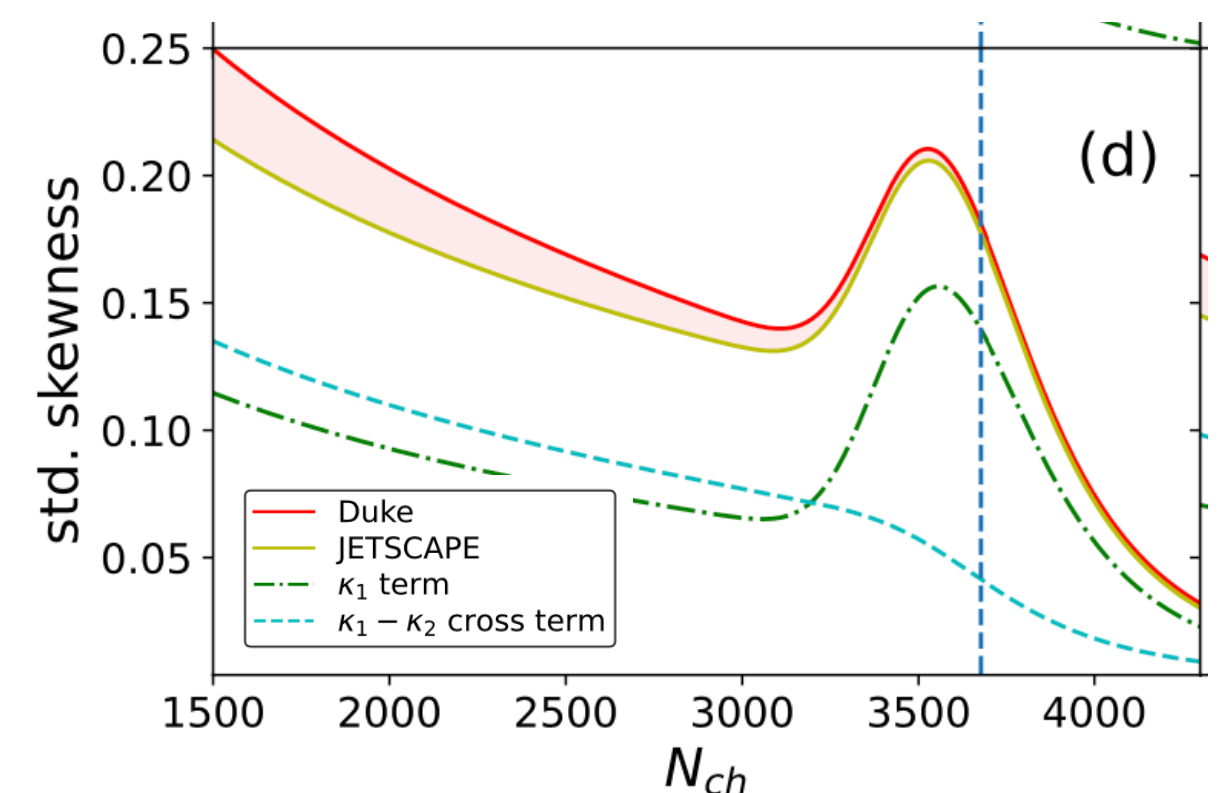
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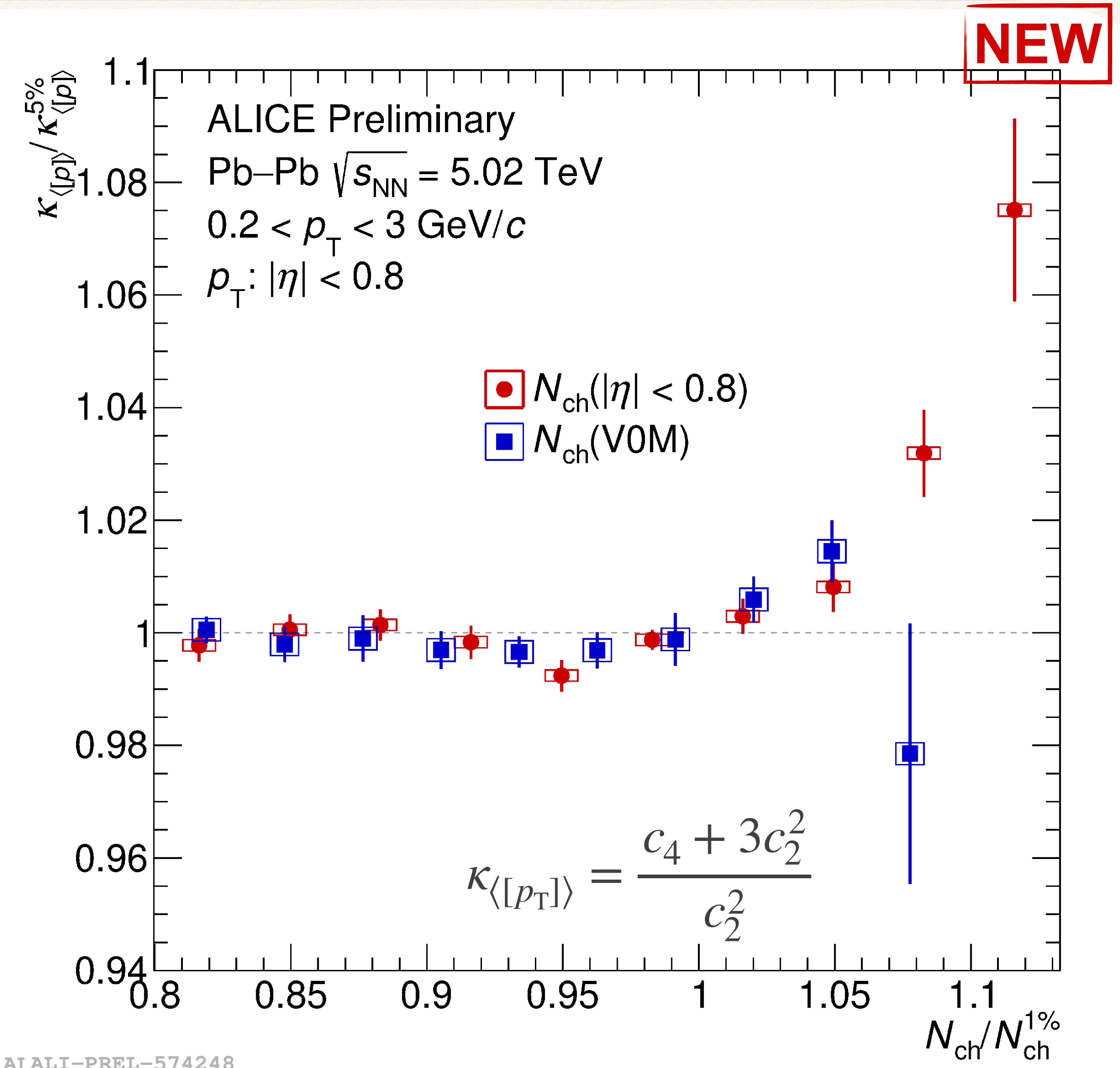
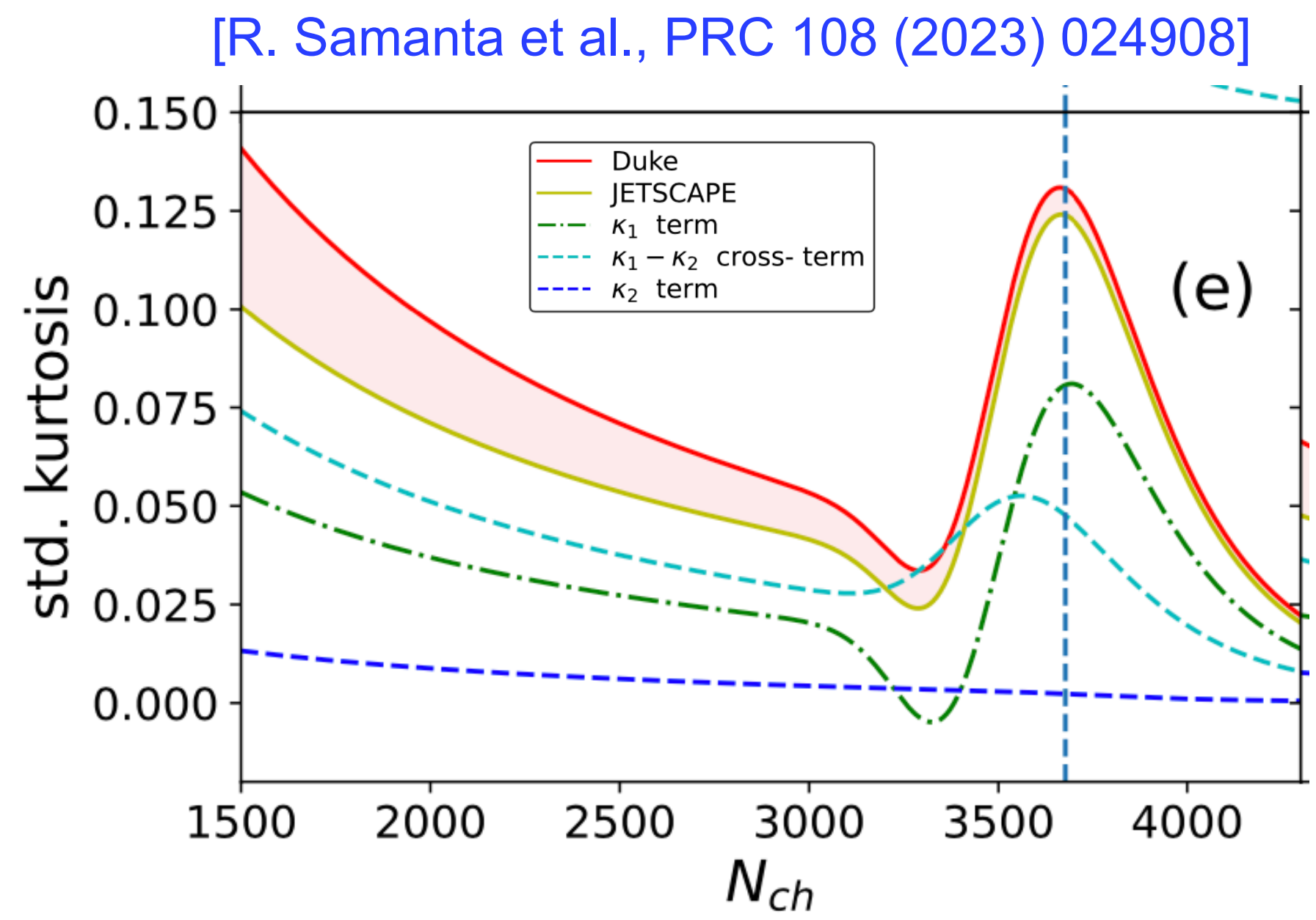


- Variations are features of a thermalised system
- Sensitive to early thermodynamic properties at highest QGP temperatures



Kurtosis of $[p_T]$ in UCC

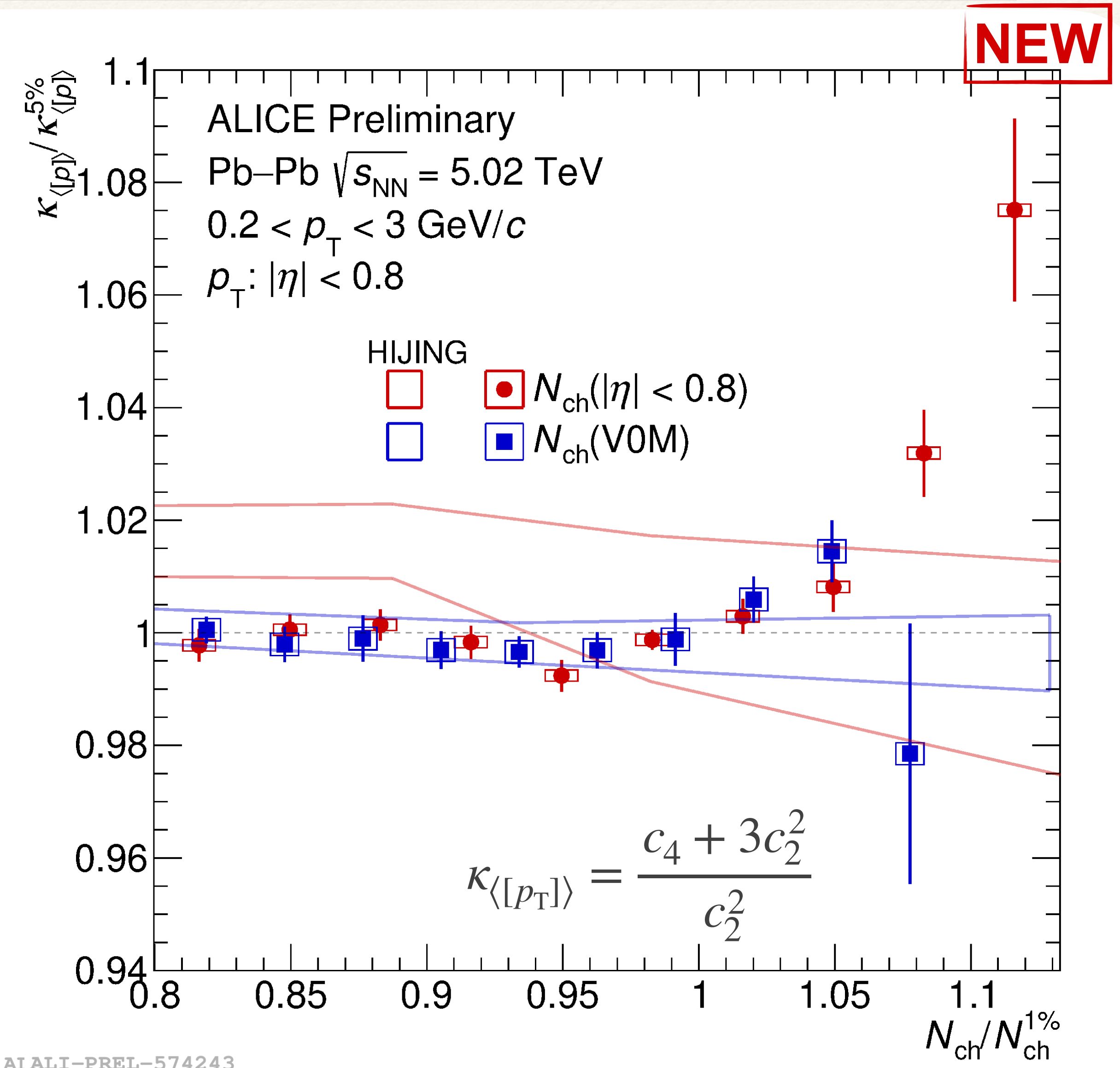
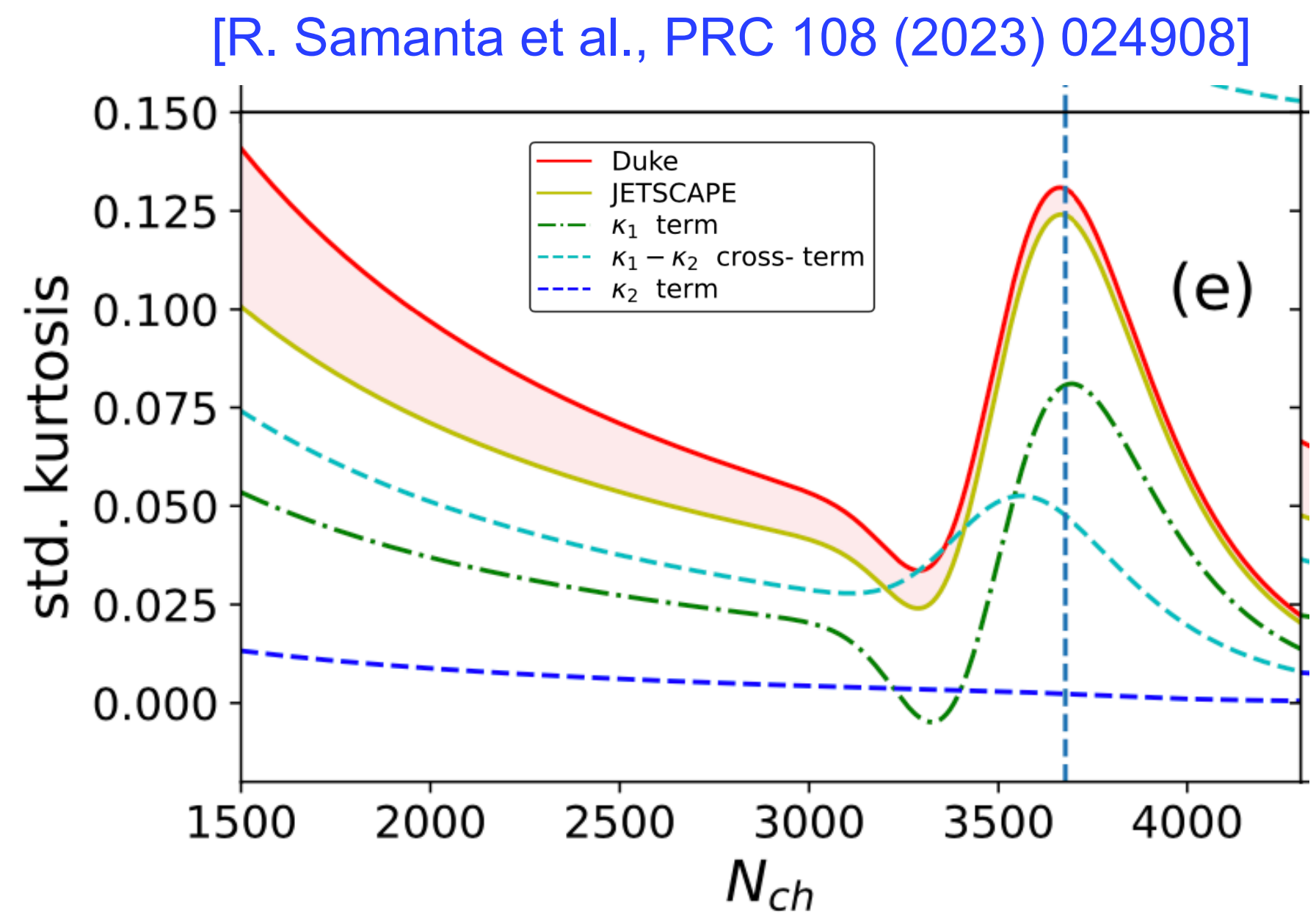
- Decrease of the kurtosis followed by significant increase
- Effect is lessened when determined as function of forward N_{ch}



ALICE-PREL-574248

Kurtosis of $[p_T]$ in UCC

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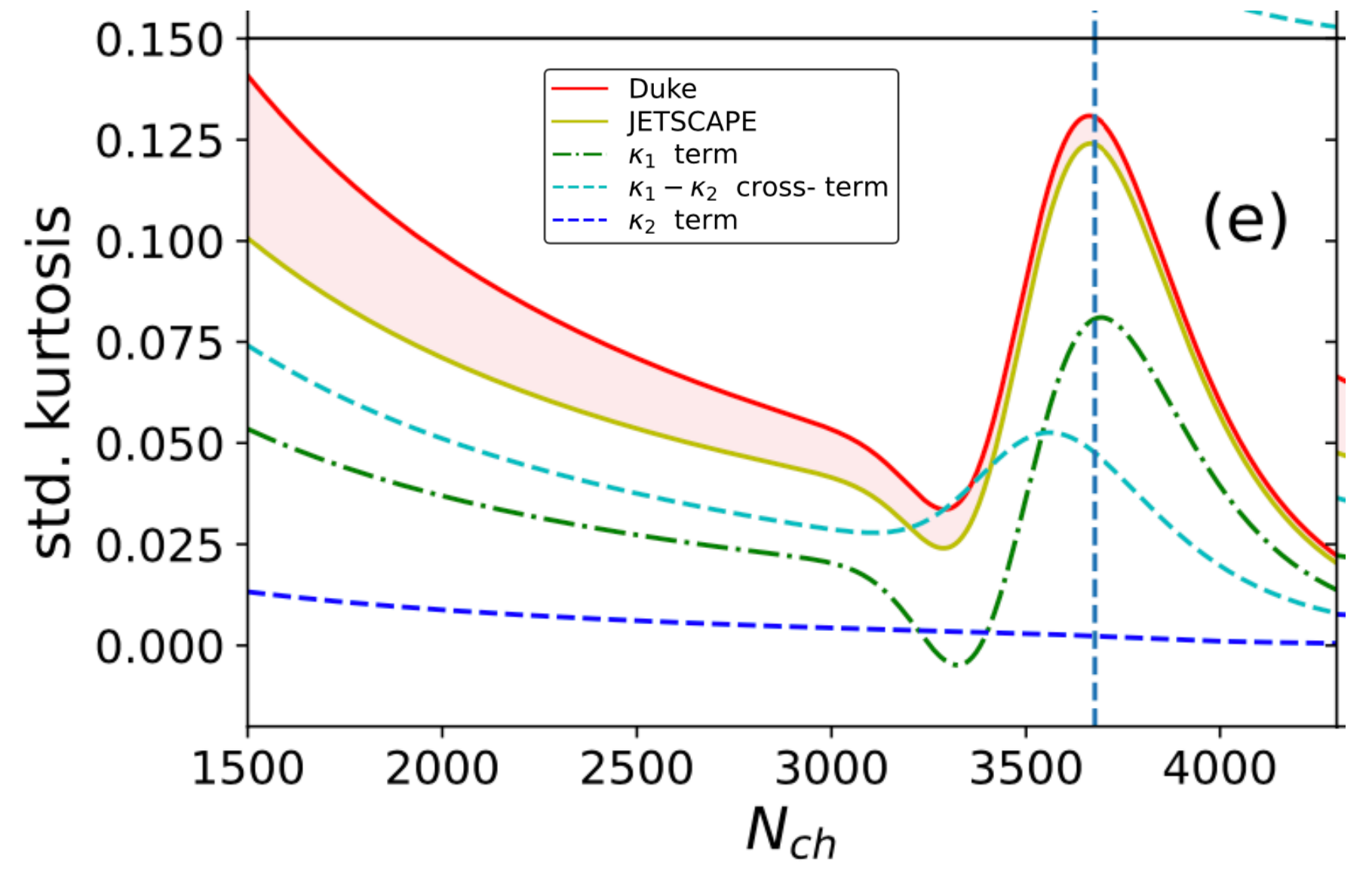


ALICE-PREL-574243

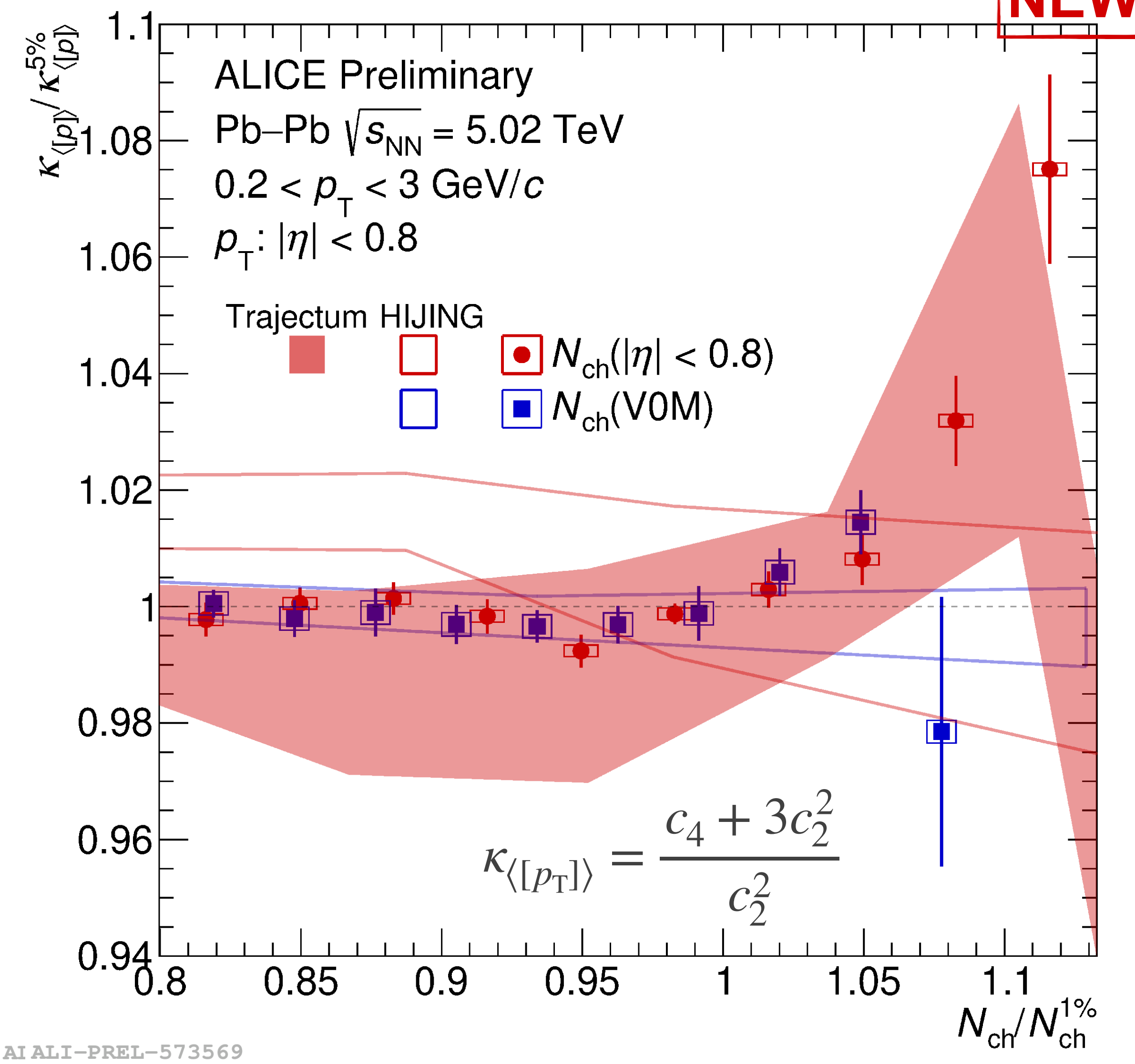
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[R. Samanta et al., PRC 108 (2023) 024908]



NEW



ALICE PREL-573569

The correlation between $\langle p_T \rangle$ and N_{ch} in ultra-central collisions - a **feature of a thermalised system** - can be used to extract the speed of sound in the QGP

The extraction is heavily **dependent on the choice of centrality estimator**

A significant difference in forward versus midrapidity centrality determination and from the bias of the centrality estimator

The measurements of the fluctuations of event-by-event mean transverse momentum exhibit **significant changes in ultra-central collisions**

In Gaussian model: driven by the changes in geometrical fluctuations and the remaining intrinsic fluctuations

In hydrodynamic models: Further contributions from the non-gaussian fluctuations of the initial state of the QGP

The data is **well described by a state-of-art hydrodynamic model** from which a consistent speed of sound can be extracted

Further constraints on the hydrodynamic models related to the determination of the speed of sound in QGP

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Thank you for your attention!

Backup

$[p_T]$ cumulants

$$c_2 = \langle [p_T^{(2)}] \rangle - \langle [p_T] \rangle^2$$

$$c_3 = \langle [p_T^{(3)}] \rangle - 3\langle [p_T^2] \rangle \langle [p_T] \rangle + 2\langle [p_T^3] \rangle$$

$$c_4 = \langle [p_T^{(4)}] \rangle - 4\langle [p_T^{(3)}] \rangle \langle [p_T] \rangle - 3\langle [p_T^{(2)}] \rangle^2 + 12\langle [p_T^{(2)}] \rangle \langle [p_T] \rangle^2 - 6\langle [p_T^{(4)}] \rangle$$

Recursive moments

$$\langle [p_T^{(k)}] \rangle = \frac{N\langle k \rangle_{p_T}}{D\langle k \rangle_{p_T}}$$

$$N\langle m \rangle_{p_T} = \sum_{k=1}^m (-1)^{k-1} N\langle m-k \rangle_{p_T} \frac{(m-1)!}{(m-k)!} \sum_i^M P_{k,k}$$

$$D\langle m \rangle_{p_T} = \sum_{k=1}^m (-1)^{k-1} D\langle m-k \rangle_{p_T} \frac{(m-1)!}{(m-k)!} \sum_i^M P_{k,0}$$

$[p_T]$ moments

$$P_{n,k} = \sum_i^M w_i^n p_{T,i}^k$$

$$\langle [p_T] \rangle = \frac{P_{1,1}}{P_{1,0}}$$

$$\langle [p_T^{(2)}] \rangle = \frac{P_{1,1}^2 - P_{2,2}}{P_{1,0}^2 - P_{2,0}}$$

$$\langle [p_T^{(3)}] \rangle = \frac{P_{1,1}^3 - 3P_{2,2}P_{1,1} + 2P_{3,3}}{P_{1,0}^3 - 3P_{2,0}P_{1,0} + 2P_{3,0}}$$

$$\langle [p_T^{(4)}] \rangle = \frac{P_{1,1}^4 + 8P_{3,3}P_{1,1} - 6P_{2,2}P_{1,1}^2 + 3P_{2,2}^2 - 6P_{4,4}}{P_{1,0}^4 + 8P_{3,0}P_{1,0} - 6P_{2,0}P_{1,0}^2 + 3P_{2,0}^2 - 6P_{4,0}}$$

Fitting the $\langle p_T \rangle$

Correlation between $\langle p_T \rangle$ and N_{ch} fitted with parametrisation based on [PLB 809 \(2020\) 135749](#)

$$\langle p_T \rangle / \langle p_T \rangle^{\text{ref}} = \left(\frac{N_{ch}^*}{f(N_{ch}^*, N_{ch,knee}^*, \sigma_0)} \right)^{c_s^2} \quad \text{where}$$

$$f(N_{ch}^*, N_{ch,knee}^*, \sigma_0) = N_{ch}^* - \sigma_0 \sqrt{\frac{2}{\pi}} \frac{\exp\left(-\left[\frac{N_{ch}^* - N_{ch,knee}^*}{\sqrt{2}\sigma_0}\right]^2\right)}{\text{erfc}\left(\frac{N_{ch}^* - N_{ch,knee}^*}{\sqrt{2}\sigma_0}\right)}$$

and $N_{ch}^* = \langle dN_{ch}/d\eta \rangle / \langle dN_{ch}/d\eta \rangle^{\text{ref}}$

$N_{ch,knee}^*$ and σ_0 obtained from fit to model proposed in [PRC 97, 014905 \(2018\)](#)

Below the knee ($N_{ch}^* \ll N_{ch,knee}^*$):

$$f(N_{ch}^*, N_{ch,knee}^*, \sigma_0) \approx N_{ch}^* \rightarrow \langle p_T \rangle / \langle p_T \rangle^{\text{ref}} \approx 1$$

Above the knee ($N_{ch}^* \gg N_{ch,knee}^*$):

$$f(N_{ch}^*, N_{ch,knee}^*, \sigma_0) \approx N_{ch,knee}^* \rightarrow \langle p_T \rangle / \langle p_T \rangle^{\text{ref}} \propto \left(\frac{N_{ch}^*}{N_{ch,knee}^*} \right)^{c_s^2}$$

