

Development Practice

Pierre Aubert

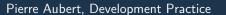














Change mind on **implementation**



Change mind on implementation



New **Idea**



Change mind on implementation



New Idea

- Learning:
- New Concept
- New **Language**



Change mind on implementation



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Learning:

- New Concept
- New **Language**

Better view of work to be done



Change mind on **implementation**



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Learning:

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Better view of work to be done **Good advice** of a collegue



Change mind on implementation



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So we change our way of implementing stuff



Change mind on implementation



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Better view of work to be done **Good advice** of a collegue

So we **change** our way of **implementing** stuff

Generaly: Nice Improvement



Change mind on implementation



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Better view of work to be done **Good advice** of a collegue

So we **change** our way of **implementing** stuff

Generaly: Nice Improvement

Sometimes: Break





Change mind on implementation



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Better view of work to be done **Good advice** of a collegue

So we change our way of implementing stuff

Generaly: Nice Improvement

Sometimes: Break



Why:

- Start with an idea
- Finish with another idea
- But not compatible







Documentation



Documentation

Versioning:

- **History** of modifications
- Restore previous versions
- **Prepare** future versions



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Unit Tests:

- Check if something is wrong
- Can be automatised



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Development Method:

- Simplify **new features**
- Ease bug fix
- Enhence reusability



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- Interfaces



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- Can be **automatised**

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- Enhence reusability

Software Architecture:

- Interfaces

Profiling:

- Time functions



Documentation

readme.md:

- Showcase
- Depedencies
- Installation / Compitation
- Use cases

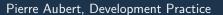
Development Documentation:

- Doxygen
- Sphinx











Save **all changes** in the project









Save **all changes** in the project





Save **all changes** in the project



Coherent save of the project

- As many local / remote saves you need



Save **all changes** in the project



Coherent save of the project

- As many local / remote saves you need

Prevent breaking projet with old modification



Save **all changes** in the project









- As many local / remote saves you need

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Coherent save of the project

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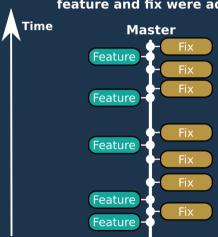


https://gitlab.in2p3.fr



Git History

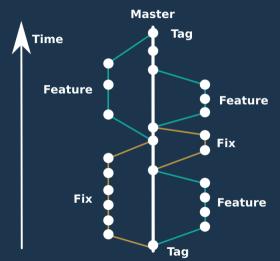
Tool to know when feature and fix were added





Branches

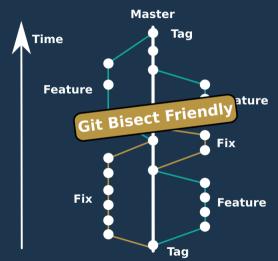
Classical Workflow





Branches

Classical Workflow







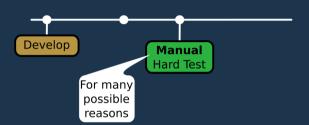




















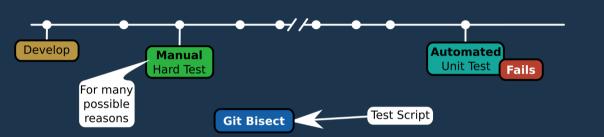




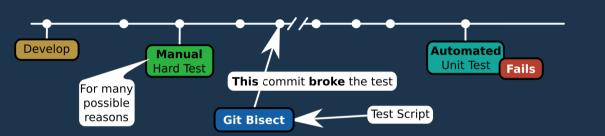




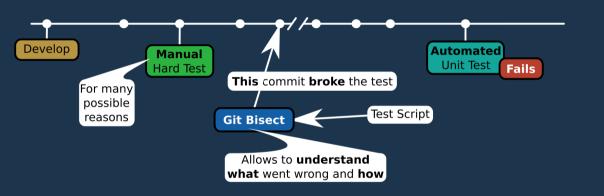




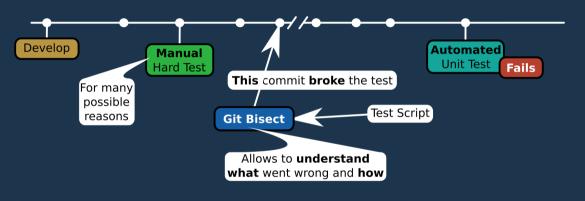








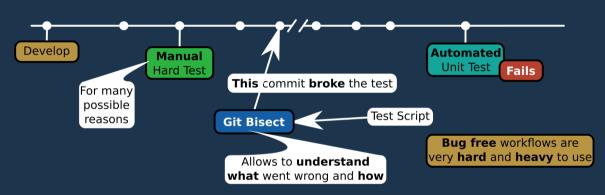




Development:

- Not only about adding features and finding bugs
- Understanding why a bug appeared and how to prevent it

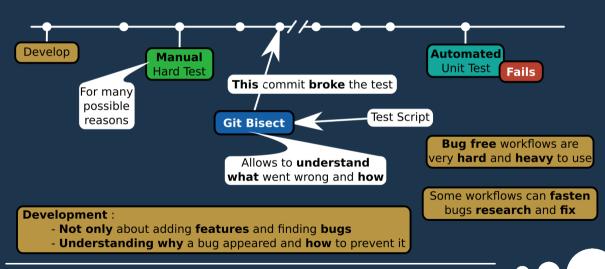




Development:

- Not only about adding features and finding bugs
- **Understanding why** a bug appeared and **how** to prevent it



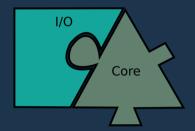




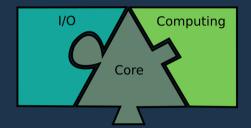




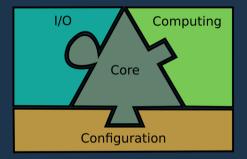




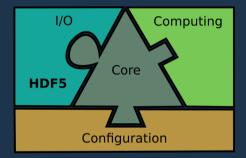






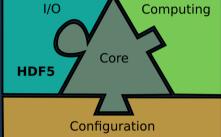




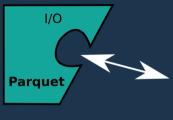


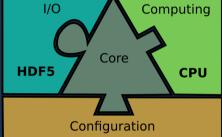




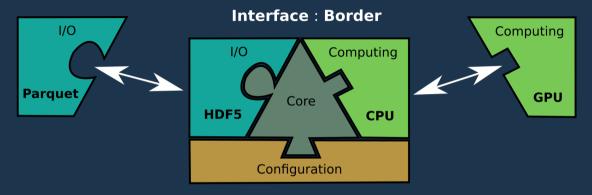




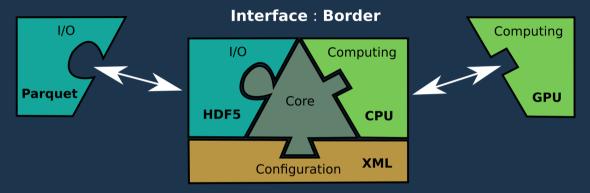




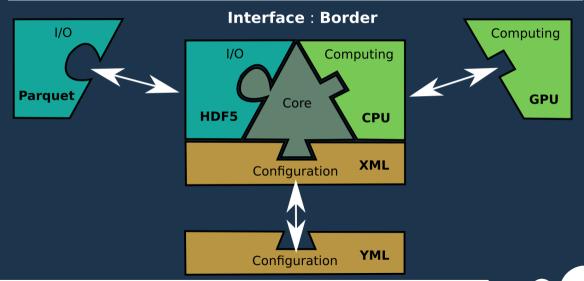




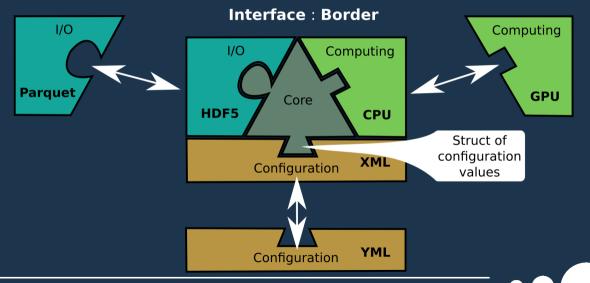




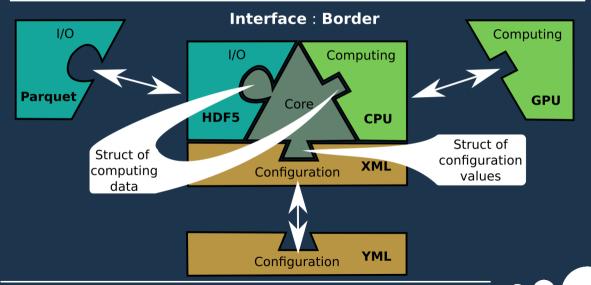






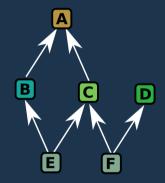




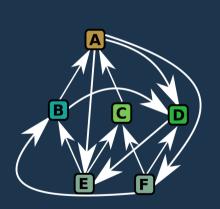


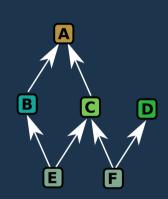




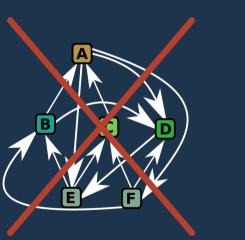


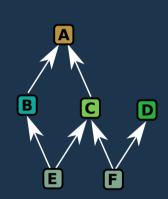






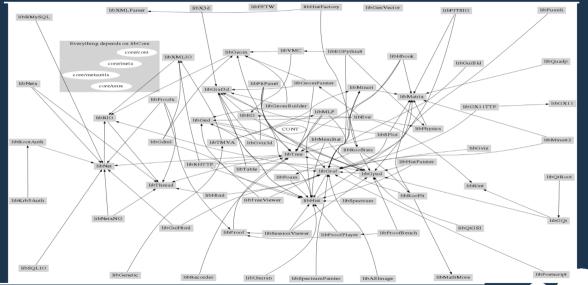








Do not do that !!!





```
float a, q, p, r, s;for(size_t _(0ul);_<m_;++_){a_[_]=0;b[_]=0;c[_]=0;d[_]=0;e[_]=0;f[_]=0;g[_]=0;h[_]=0;i[_]=0;j[_]=0:k[_]=0;l[_]=0;m[_]=0;n[_]=0;o[_]=0;for(size_t __(0ul);__<n;++__){a=w[_*n+__];a_[_]+=a;q=u[__],p=v[__];r=a*q;s=a*p;b[_]+=r;c[_]+=s;d[_]+=q*r;f[_]+=s*p;g[_]+=q*q*a*q;j[_]+=s*p*p;k[_]+=r*q*q*q;o[_]+=p*p*a*p*p;e[_]+=r*p;h[_]+=q*a*q*p;i[_]+=p*q*p*a;l[_]+=p*q*q*a*q;n[_]+=p*a*p*p;m[_]+=q*p*s*q;}}
```



```
float a, q, p, r, s; for(size_t _(0ul); _<m_; ++_){a_[_]=0; b[_]=0; c[_]=0; d[_]=0; e[_]=0; f[_]=0; g[_]=0; h[_]=0; i[_]=0; j[_]=0; k[_]=0; l[_]=0; n[_]=0; n[_]=0; o[_]=0; for(size_t __(0ul); __<n; ++__){a=w[_*n+__]; a_[_]+=a; q=u[__], p=v[__]; r=a*q; s=a*p; b[_]+=r; c[_]+=s; d[_]+=q*r; f[_]+=s*p; g[_]+=q*q*a*q; j[_]+=s*p*p; k[_]+=r*q*q*q; o[_]+=p*p*a*p*p; e[_]+=r*p; h[_]+=q*a*q*p; i[_]+=p*q*p*a; l[_]+=p*q*q*a*q; n[_]+=p*a*p*p; m[_]+=q*p*s*q; }}</pre>
```



```
<u>float a, q</u>, p, r, s;
for(size t (0ul); <m ;++ ){
       a [ ]=0:
       b[ ]=0;c[ ]=0;d[ ]=0;e[ ]=0;f[ ]=0;q[ ]=0;h[ ]=0;
       i[]=0;i[]=0:k[]=0;l[]=0;m[]=0;n[]=0;o[]=0;
       for(size t (0ul); <n;++ ){
               a=w[*n+];a[]+=a;q=u[],p=v[];r=a*q;s=a*p;
               b[]+=r;c[]+=s;d[]+=q*r;f[]+=s*p;
               q[]+=q*q*a*q;i[]+=s*p*p;
               k[]+=r*q*q*q;o[]+=p*p*a*p*p;
               e[]+=r*p;h[]+=q*a*q*p;
               i[]+=p*q*p*a:l[]+=p*q*q*a*q:
               n[]+=p*a*p*q*p;m[]+=q*p*s*q;
```



```
float a, q, p, r, s;
for(size t (0ul); <m ;++ ){
       b[]=0;c[]=0;d[]=0;e[]=0;f[]=0;g[]=0;h[]=0;
       i[]=0; i[]=0: k[]=0; l[]=0; m[]=0; n[]=0; o[]=0;
       for(size t (0ul): <n:++ ){
               a=w[ *n+ ]; a [ ]+=a; q=u[ ], p=v[ ]; r=a*q; s=a*p;
               b[]+=r;c[]+=s;d[]+=q*r;f[]+=s*p;
               q[]+=q*q*a*q;i[]+=s*p*p;
               k[]+=r*q*q*q;o[]+=p*p*a*p*p;
               e[]+=r*p;h[]+=q*a*q*p;
               i[]+=p*q*p*a;l[]+=p*q*q*a*q;
               n[]+=p*a*p*q*p;m[]+=q*p*s*q;
```



```
for(size t i(Oul); i < nbEvent; ++i){</pre>
        sumsig[i] = 0.0f;
        xm[i] = 0.0f; ym[i] = 0.0f; x2m[i] = 0.0f; xym[i] = 0.0f;
        v2m[i] = 0.0f; x3m[i] = 0.0f; x2vm[i] = 0.0f; xv2m[i] = 0.0f;
        v3m[i] = 0.0f:x4m[i] = 0.0f:x3vm[i] = 0.0f:x2v2m[i] = 0.0f
        xy3m[i] = 0.0f; y4m[i] = 0.0f;
        for(size t j(@ul); j < nbPixel; ++j){</pre>
                float a = signal[i*nbPixel + i];
                sumsig[i] += a:
                float x = posPixelX[i], y = posPixelY[i];
                xm[i] += a*x;ym[i] += a*y;
                x2m[i] += a * x * x * v2m[i] += a * v * v
                x3m[i] += a * x * x * x; y3m[i] += a * y * y * y;
                x4m[i] += a * x * x * x * x * x; v4m[i] += a * v * v * v * v;
                xvm[i] += a * x * v:x2vm[i] += a * x * x * v:
                xy2m[i] += a * x * y * y;x3ym[i] += a * x * x * x * y;
                xy3m[i] += a * x * y * y * y; x2y2m[i] += a * x * x * y * y;
```



```
for(size t i(0ul); i < nbEvent; ++i){</pre>
        for(size t j(0ul); j < nbPixel; ++j){</pre>
                float a = signal[i*nbPixel + j];
                sumsig[i] += a;
                float x = posPixelX[j], y = posPixelY[j];
                xm[i] += a*x;
                ym[i] += a*y;
                x2m[i] += a * x * x;
                v2m[i] += a * v * v;
                x3m[i] += a * x * x * x;
                v3m[i] += a * v * v *
                x4m[i] += a * x * x *
                v4m[i] += a * v * v * v * v;
                xvm[i] += a * x * y;
                x2ym[i] += a * x * x * y;
                xy2m[i] += a * x * y *
                x3ym[i] += a * x * x *
                xv3m[i] += a * x * v *
                x2v2m[i] += a * x * x * v
```



```
for(size t i(0ul); i < nbEvent; ++i){</pre>
        for(size t j(0ul); j < nbPixel; ++j){</pre>
                 float a = signal[i*nbPixel + j];
                sumsig[i] += a
                                                               Constant
                           posPixelX[j],
                                              posPixelY[j]
                xm[i] += a*x;
                vm[i] += a*v:
                       += a * x * x;
                v2m[i]
                       += a * v *
                x3m[i] += a *
                v3m[i]
                x4m[i]
                 v4m[i]
                       += a * v * v * v * v;
                xvm[i] += a * x * v:
                x2vm[i]
                        += a * x * x * y;
                xv2m[i] += a * x *
                        += a * x *
                xv3m[i] += a * x * v
                x2v2m[i] += a * x * x *
```



```
for(size t i(0ul); i < nbEvent; ++i){</pre>
        for(size t j(0ul); j < nbPixel; ++j){</pre>
                 float a = signal[i*nbPixel + j];
                 sumsig[i] += a
                                                                Constant
                            posPixelX[i]
                                               posPixelY[j
                       += a*x;
                       += a*v:
                                                                 Useless computation
                 v2m[i]
                 x3m[i]
                 v3m[i]
                 x4m[i]
                 v4m[i]
                 xvm[i]
                 x2vm[i]
                 xv2m[i]
                         += a
                 x3vm[i]
                         += a
                 xv3m[i] += a
                 x2y2m[i] += a
```



```
for(size t i(0ul); i < nbEvent; ++i){</pre>
        for(size t j(0ul); j < nbPixel; ++j){</pre>
                 float a = signal[i*nbPixel + j];
                 sumsig[i] += a
                                                                Constant
                           posPixelX[i].
                                               posPixelY[j]
                       += a*x;
                       += a*v:
                                                                Useless computation
                 v4m[i
                                                We do not even use
                                                    these results
                 xv3m[i]
                 x2v2m[i]
```



```
for(size t i(0ul); i < nbEvent; ++i){</pre>
        for(size t j(0ul); j < nbPixel; ++j){</pre>
                 float a = signal[i*nbPixel + j];
                 sumsig[i] += a:
                 float x = posPixelX[j], y = posPixelY[j];
                 xm[i] += a*x:
                 vm[i] += a*v;
                 x2m[i] += a * x * x:
                 y2m[i] += a * y * y;
                 xym[i] += a * x * v:
```



```
for(size t i(0ul); i < nbEvent; ++i){</pre>
         for(size t j(0ul); j < nbPixel; ++j){</pre>
                  float a = signal[i*nbPixel + j];
                  sumsig[i] += a:
                  float x = posPixelX[j], y = posPixelY[j];
                  xm[i] += a*x:
                  vm[i] += a*v;
                  x2m[i] += a * (x * x)
                                         Table x<sup>2</sup>
                  v2m[i] += a * v * v;
                  xym[i] += a * x * v:
```



```
for(size t i(0ul); i < nbEvent; ++i){</pre>
         for(size t j(0ul); j < nbPixel; ++j){</pre>
                   float a = signal[i*nbPixel + j];
                   sumsig[i] += a:
                   float x = posPixelX[j], y = posPixelY[j];
                  xm[i] += a*x:
                  vm[i] += a*v;
                   x2m[i] += a * (x *)
                                            Table x<sup>2</sup>
                   v2m[i] += a * v
                                            Table v<sup>2</sup>
                   xym[i] += a * x *
```



```
for(size t i(0ul); i < nbEvent; ++i){</pre>
         for(size t j(0ul); j < nbPixel; ++j){</pre>
                   float a = signal[i*nbPixel + j];
                   sumsig[i] += a:
                   float x = posPixelX[j], y = posPixelY[j];
                   xm[i] += a*x:
                   vm[i] += a*v;
                   x2m[i] += a * (x)
                                            Table x<sup>2</sup>
                   v2m[i] += a *
                                            Table v<sup>2</sup>
                   xym[i] += a *
                                            Table xv
```

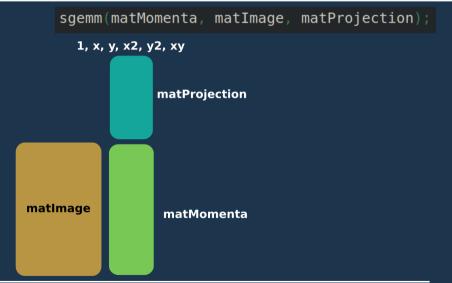


```
for(size t i(0ul); i < nbEvent; ++i){</pre>
          for(size t i(0ul); i < nbPixel; ++i);</pre>
                   float a = signal[i*nbPixel + j];
                   sumsig[i] += a;
                   float x = posPixelX[j], y = posPixelY[j];
                   xm[i] += a*x:
                   vm[i] += a*v:
                   x2m[i] += a *
                                              Table x<sup>2</sup>
                   v2m[i] += a *
                                              Table v<sup>2</sup>
                                                             These are
                                             Table xy
                                                            dot products
```



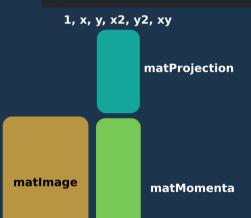
```
for(size t i(0ul); i < nbEvent; ++i){</pre>
          for(size t i(0ul): i < nbPixel: ++i)</pre>
                    float a = signal[i*nbPixel + j];
                    sumsiq[i] += a:
                    float x = posPixelX[j], y = posPixelY[j]
                    xm[i] += a*x:
                    vm[i] += a*v:
                    x2m[i] += a *
                                               Table x<sup>2</sup>
                    v2m[i] += a *
                                               Table v<sup>2</sup>
                                                               These are
                                               Table xy
                                                              dot products
                               This is a
                          Matrix Multiplication
```







sgemm(matMomenta, matImage, matProjection);

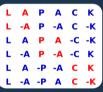






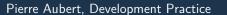














- Valgrind:
 - Dynamic binary **Profiler**
 - Memory binary Checker





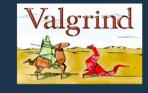
- Valgrind :
 - Dynamic binary **Profiler**
 - Memory binary Checker
- Maqao:
 - **Static** binary profiler
 - **Dynamic** binary profiler







- Valgrind:
 - Dynamic binary **Profiler**
 - Memory binary Checker



- Maqao :
 - **Static** binary profiler
 - **Dynamic** binary profiler



- Auto profiling library :
 - Only selected functions
 - But has to be part of the software



- Valgrind:
 - Dynamic binary **Profiler**
 - Memory binary Checker



- Maqao:
 - **Static** binary profiler
 - **Dynamic** binary profiler

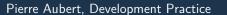


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 - Only selected functions
 - But has to be part of the software



Nsight























Project builder Unit tests









Project builder Unit tests



readme.md:

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- Installation / Compitation
- Use cases

Development Documentation:

- Doxygen
- Sphynx











Project builder Unit tests

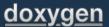


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Profiling













Project builder Unit tests



readme.md:

- Showcase
- Depedencies
- Installation / Compitation
- Use cases

Development Documentation:

- Doxygen
- Sphynx





Profiling





