

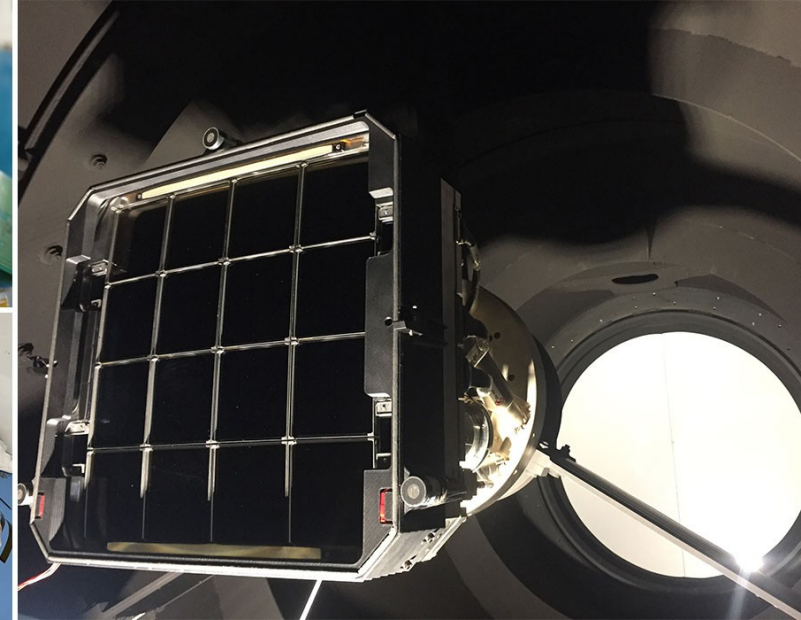
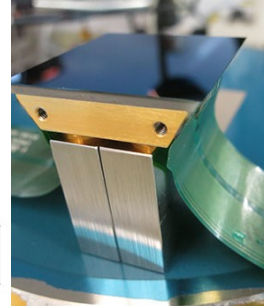
Precision supernova photometry with the Zwicky Transient Facility

Leander Lacroix for the ZTF participation group

The Samuel Oshin P48 telescope

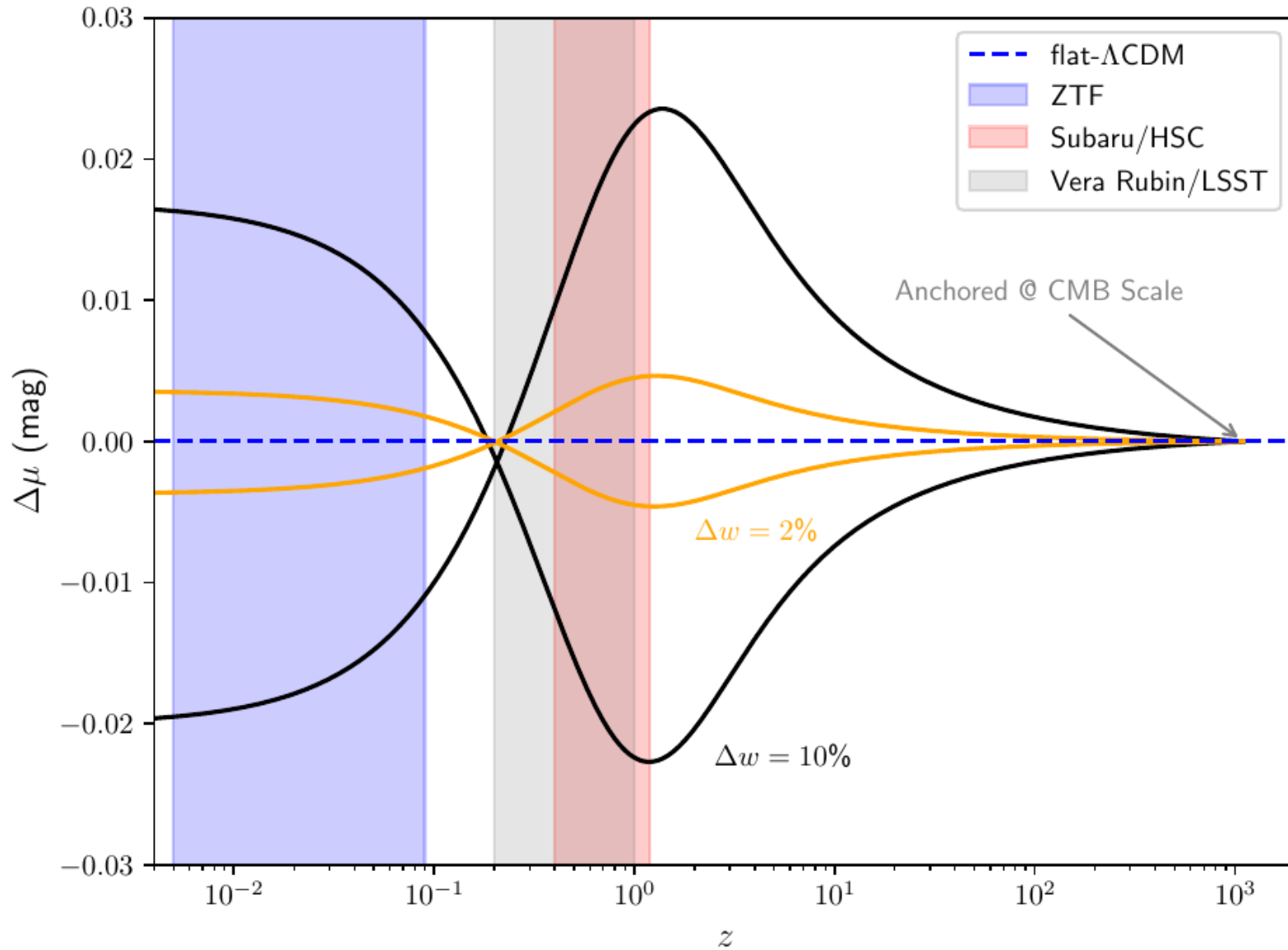
ZTF Camera Technical Specifications

Telescope	Samuel Oshin (48-inch Schmidt)
Field of View	47 square degrees
Detectors	16 e2v 6k x 6k CCD231-C6
Pixel size	15 micron
Pixel scale	1.0"/pixel
Median Delivered Image Quality	2.0" FWHM
Exposure Time	30 sec
Readout Time	10 sec
Median Time Between Exposures	15 sec
Median Single Visit Depth (5 σ , R band)	20.4 mag (all lunar phases)
Filters	ZTF g, ZTF r, ZTF i
Areal Survey Rate	3750 square degrees/hour



©Caltech

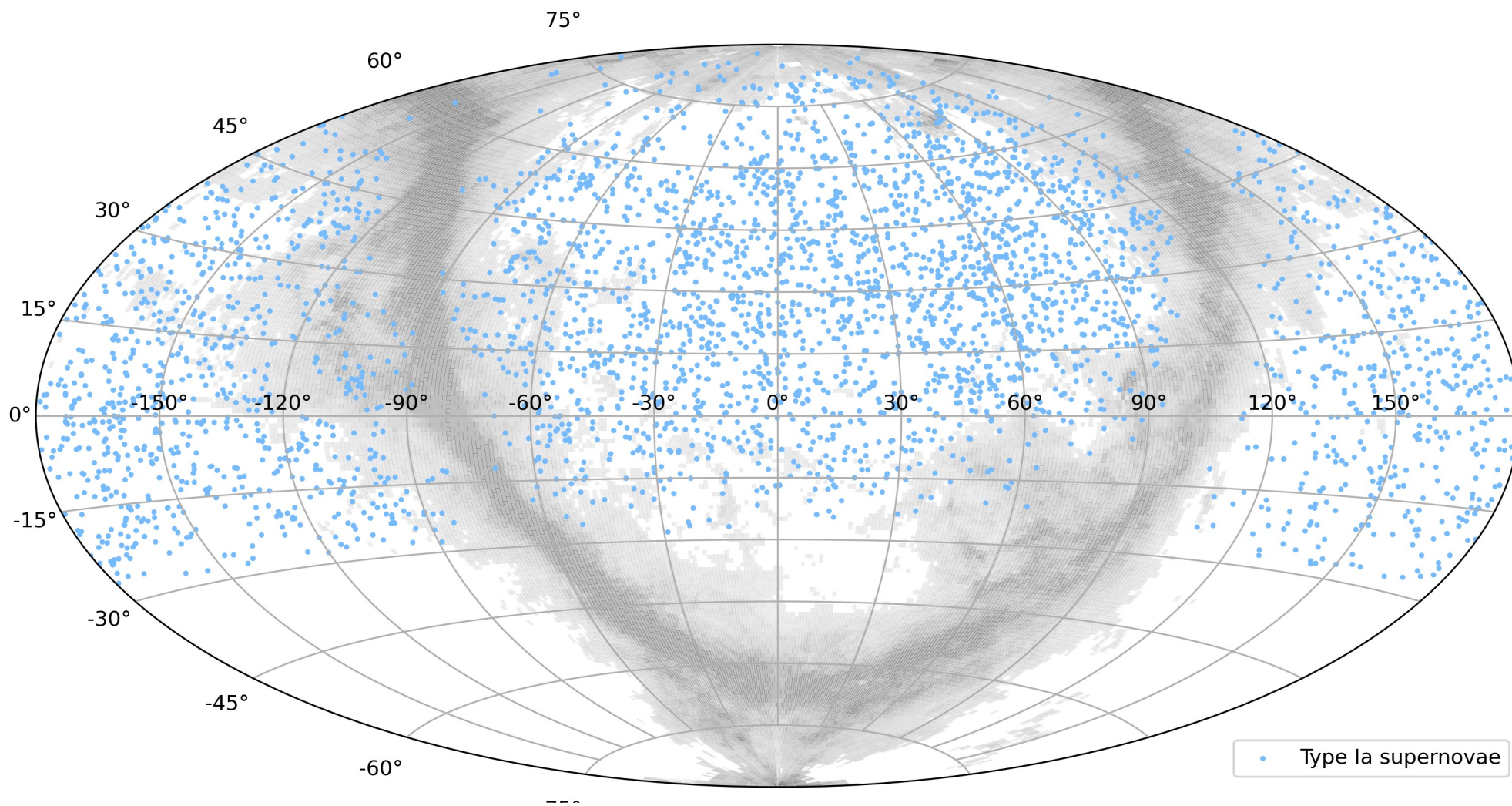
Photometry goals for precision w cosmology



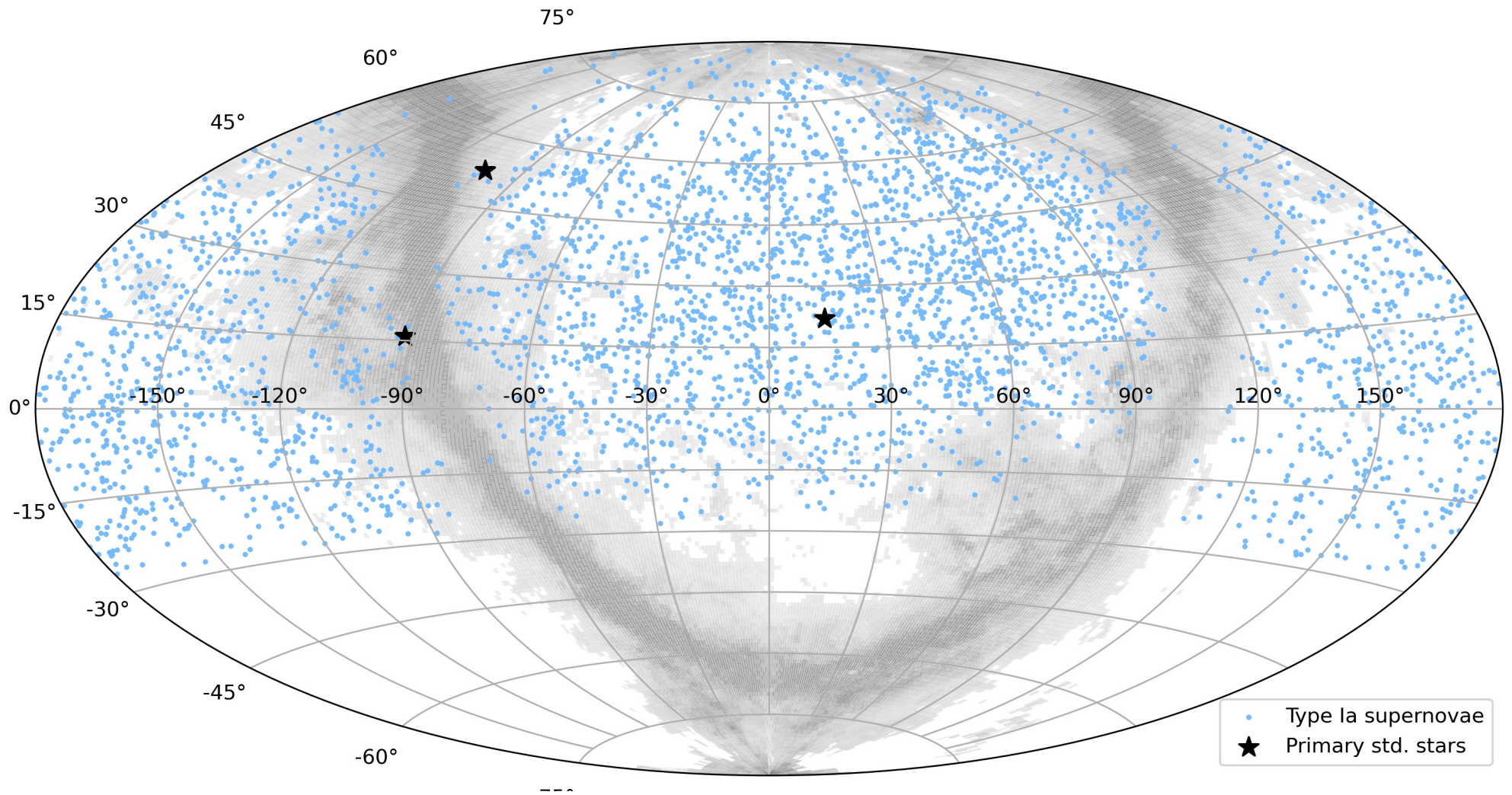
Ingredients for SN flux metrology

- Repeatability matters:
 - ZTF pipeline repeatability: 2%
 - Our goal: 0.1% (for $\Delta w = 1\%$ and $\sim 10\text{k}$ Ia SNe)
 - Work on systematical error at the ‰ level
- Ingredients:
 - Survey calibration → **UberCal**
 - Instrument non uniformity characterisation → **starflats**
 - Efficient SN lightcurve extraction → **scene modeling**
 - Instrument throughput model
 - Internal detrending pipeline
- Large french team coordinated effort for calibration

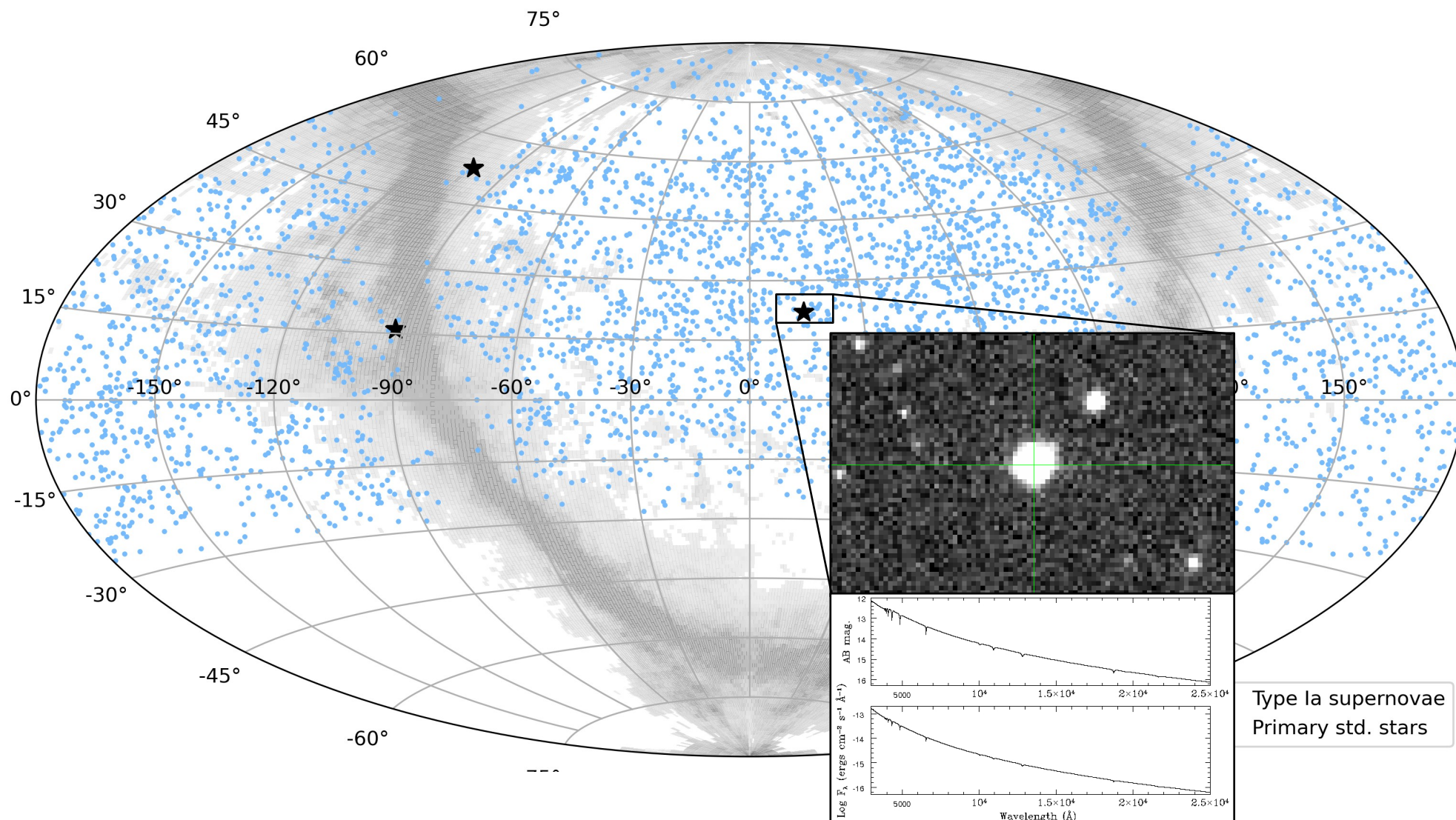
DR2 sample



DR2 sample & primary standard stars

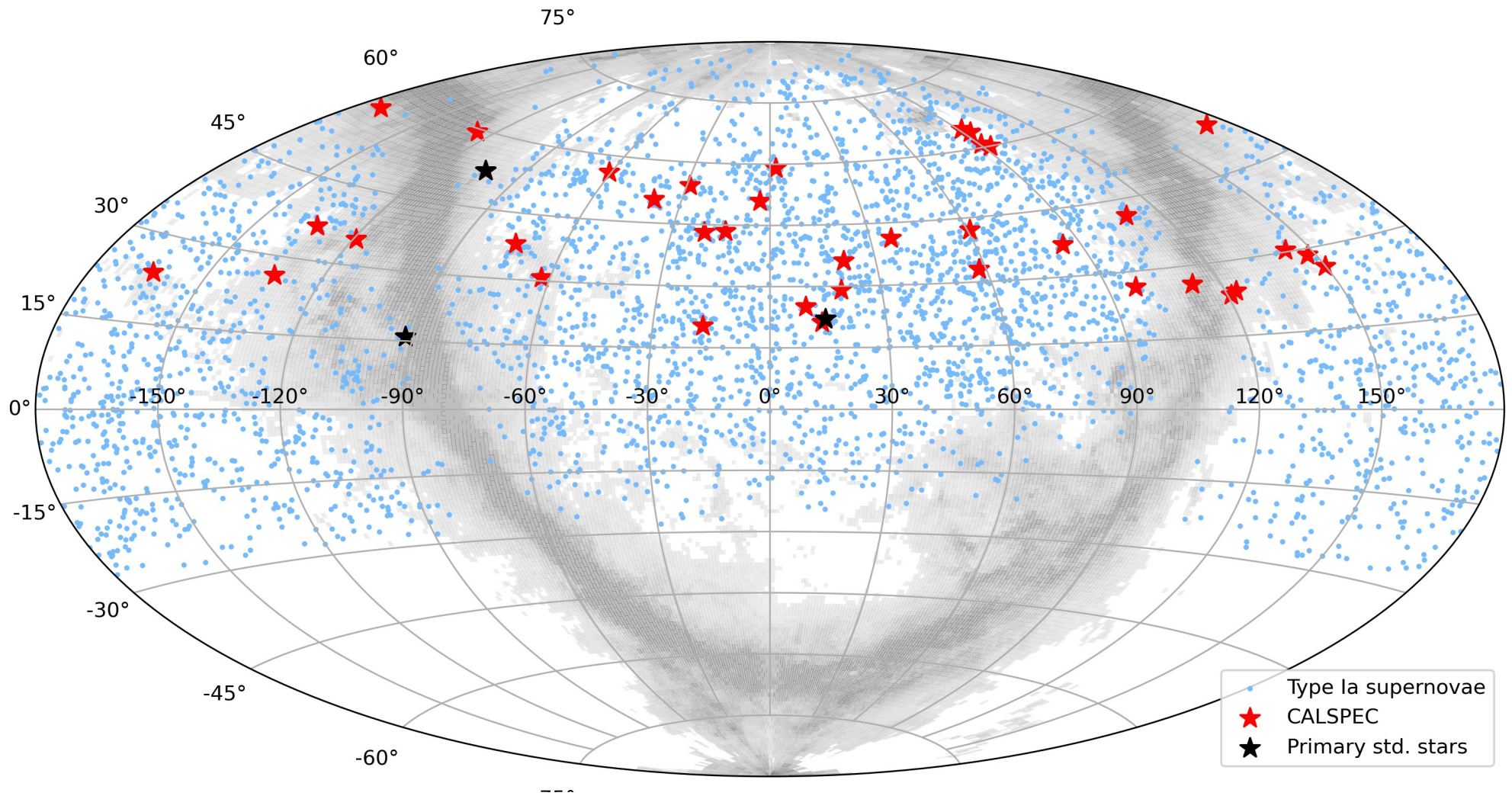


DR2 sample & primary standard stars



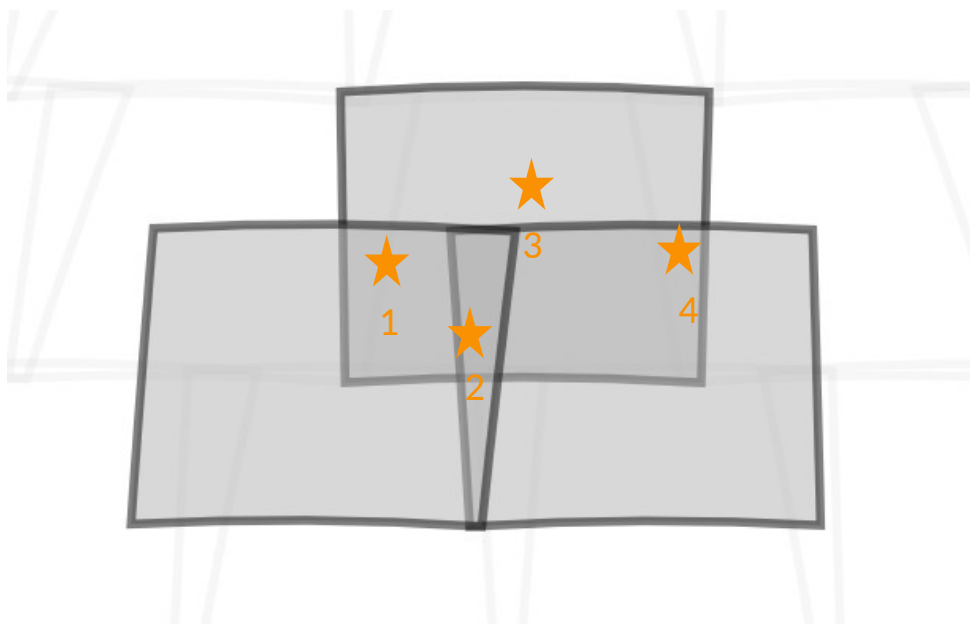
X-shooter ref. spectrum (Moehler et al. 2014a,b)

DR2 sample & primary std. & CALSPEC stars



Calibrating the field stars

The idea



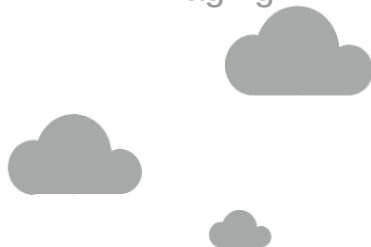
$$\begin{aligned}
 m_1 + 0 &= m_{11}^{obs} \\
 m_2 + 0 &= m_{21}^{obs} \\
 m_3 + \Delta ZP_2 &= m_{32}^{obs} \\
 m_4 + \Delta ZP_2 &= m_{42}^{obs} \\
 m_1 + \Delta ZP_3 &= m_{13}^{obs} \\
 m_2 + \Delta ZP_3 &= m_{23}^{obs} \\
 m_3 + \Delta ZP_3 &= m_{33}^{obs} \\
 m_4 + \Delta ZP_3 &= m_{43}^{obs}
 \end{aligned}$$

The fit (MLE)

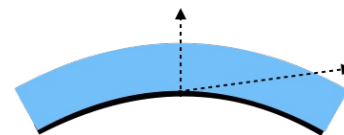
$$m_{obs} - m_{ps_g} = \alpha(m_{ps_g} - m_{ps_r}) + ZP(t_{exposure}) + k(t_{night}) * \text{airmass} + \delta ZP(u, v)$$

Color correction
vs PS1

Fast change from clouds
Slow change from mirror
aging?



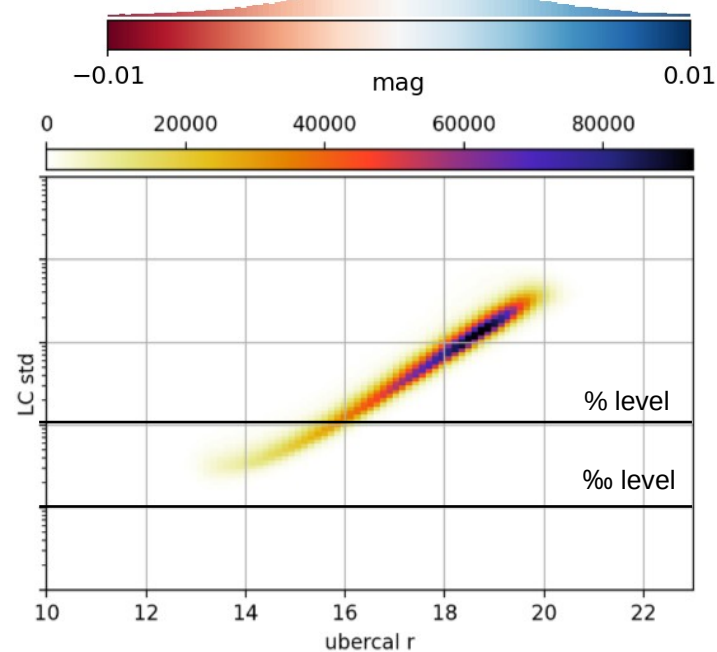
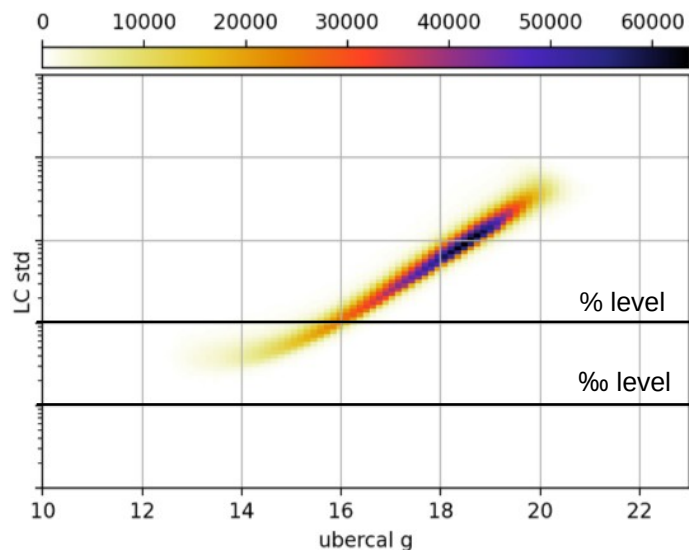
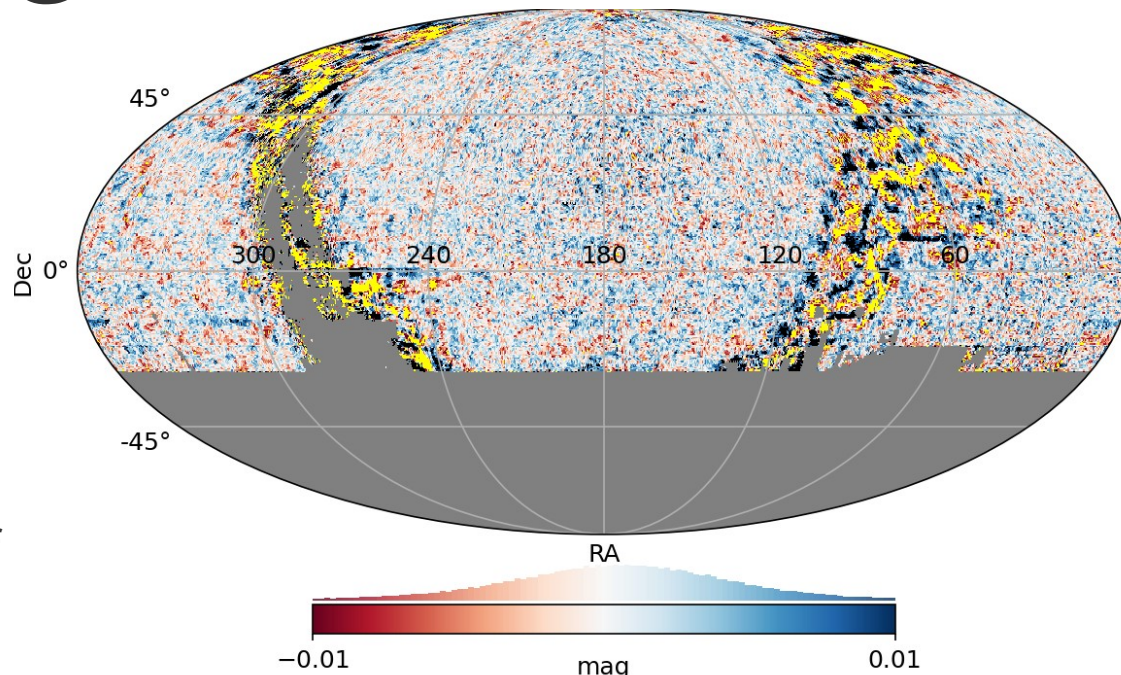
Low elevation
=
Observing through
high airmass



Gain variability
CCD width variation
Dust spots
Fringing
Laser annealing

Calibrating the field stars

- For now: anchored on PS1 as a large scale rigidifier
 - Needs slight modification of observing strategy (as for DES, SDSS...)
- Main product: uniform star catalog of the whole survey

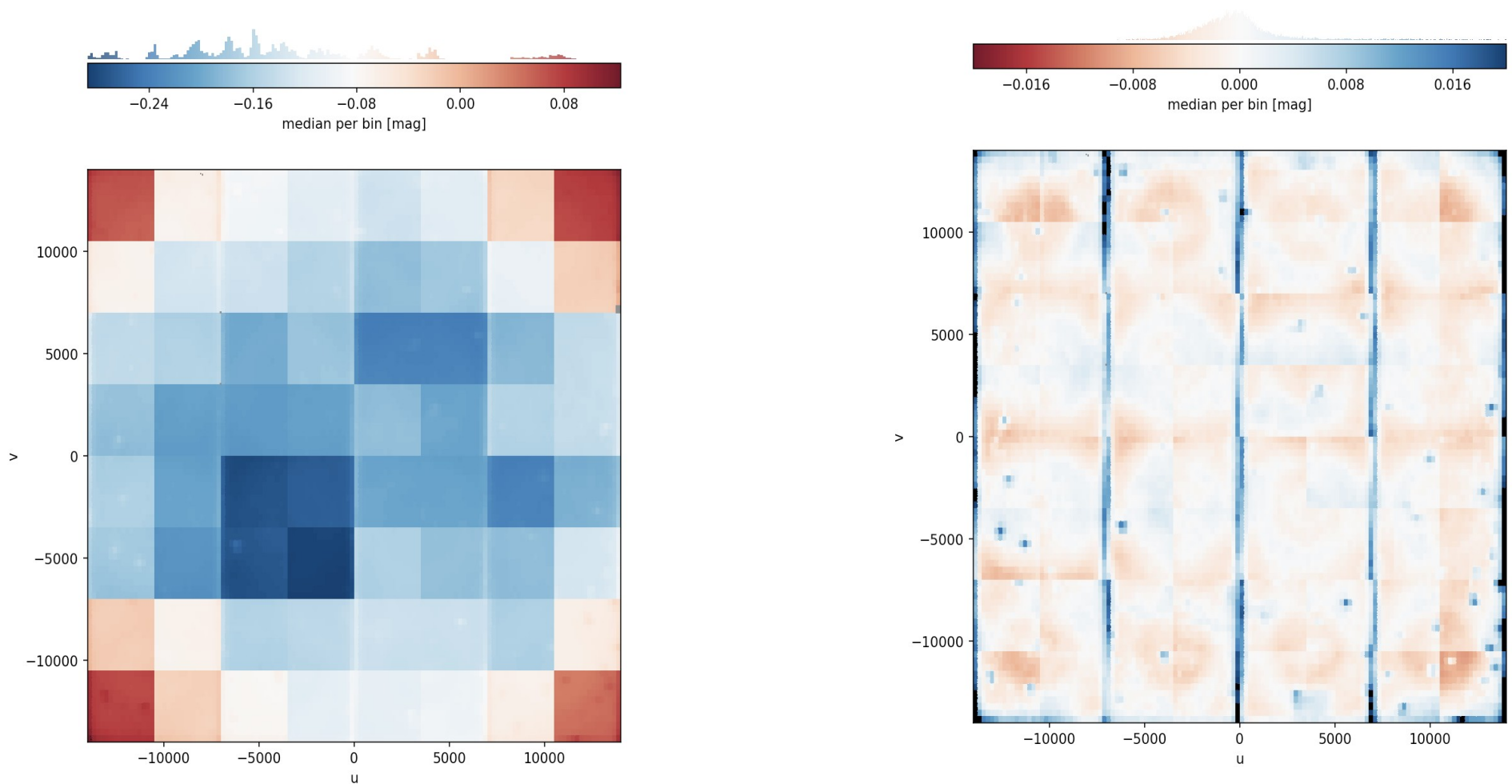


Conclusion:

- Good repetability for bright stars
- Anchored on PS1 as a large scale rigidifier

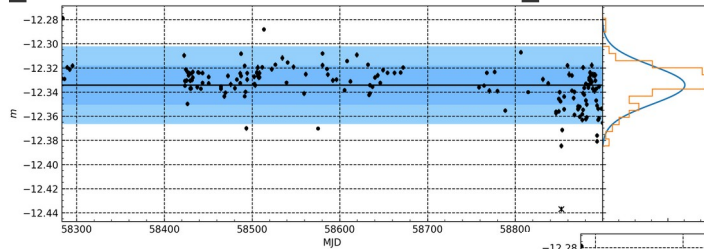
Camera non uniformities

- Map zero point variation on focal plane

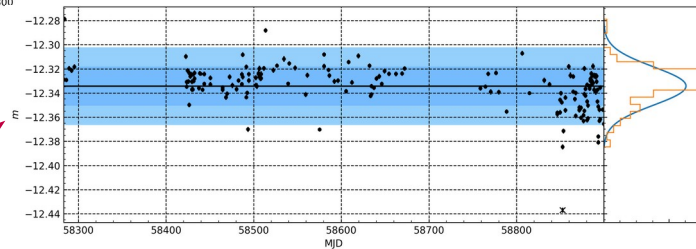


From UberCal fit

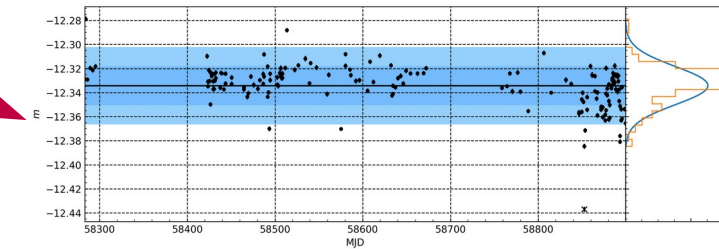
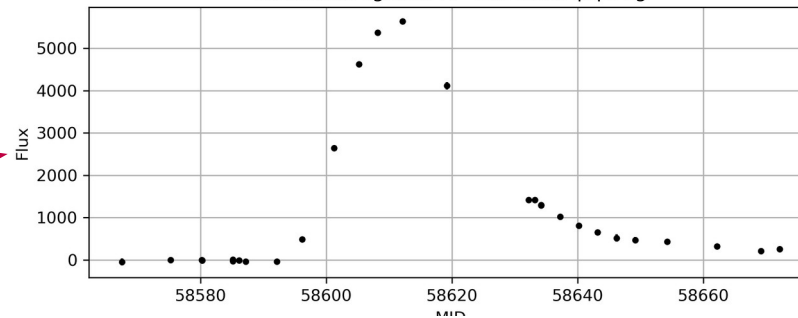
Supernova photometry



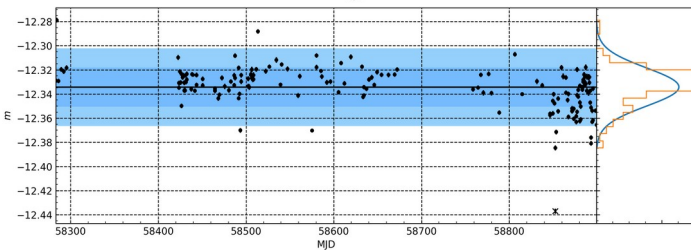
→ Star magnitude m_i



→ Star magnitude m_{i+1}

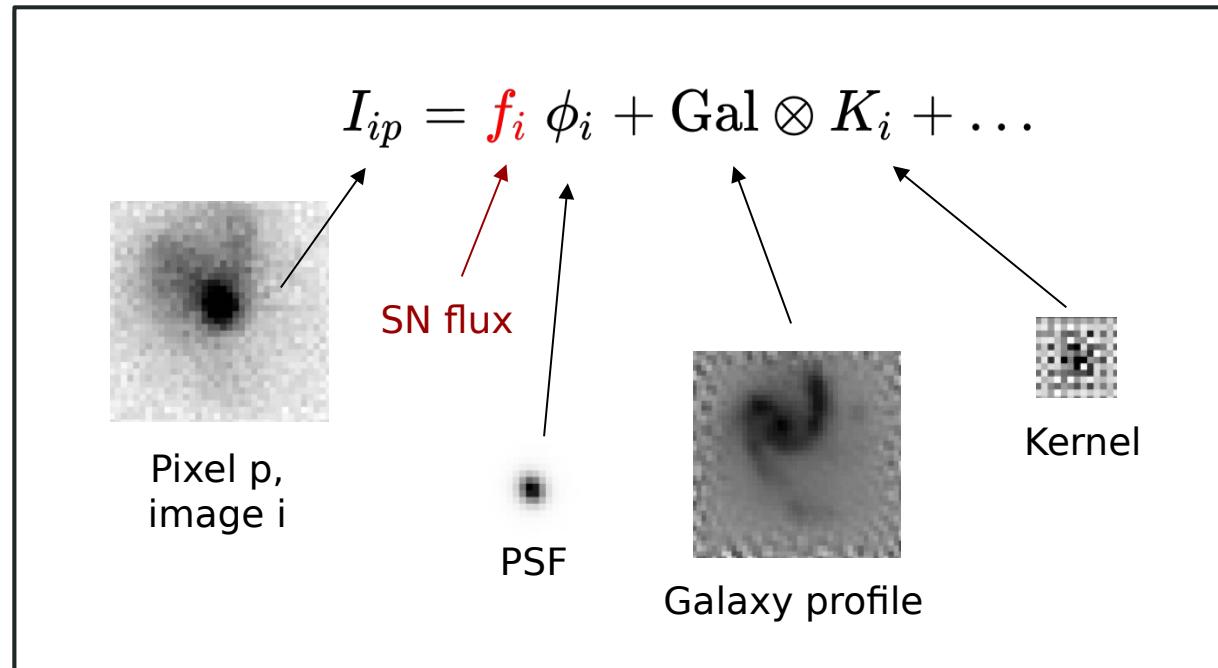


→ Star magnitude m_{i+2}



→ Star magnitude m_{i+3}

Scene Modeling Photometry (SMP)



- Statistically optimal maximum likelihood flux estimator
- Directly work at the pixel level
- Models the “scene” (SN flux and background galaxy)
- Same flux estimator for SN and field stars → auto cancellation of systematics

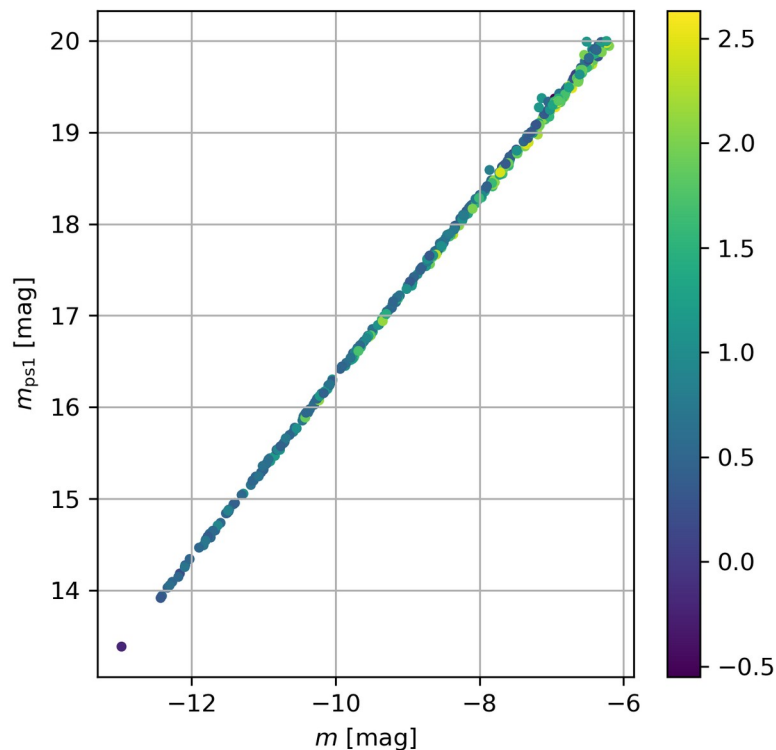
Simultaneously fits

- SN position
- Galaxy profile
- Fluxes ← lightcurve!

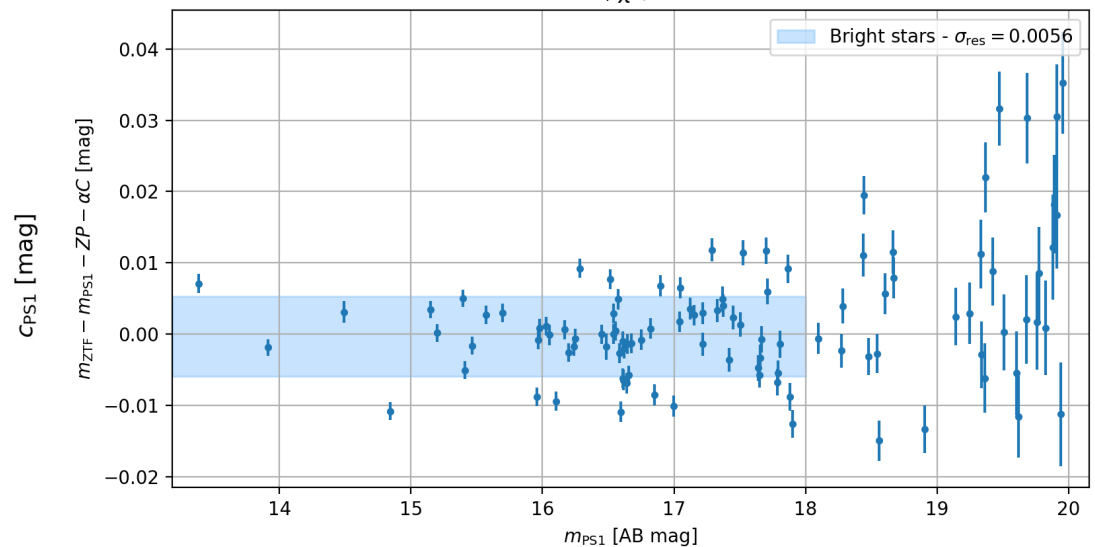
Lightcurve calibration

- For each star lightcurve, fit constant magnitude model
 - High $\chi^2 \rightarrow$ variable stars – removed
- Find Zero Point (ZP) \rightarrow compare with calibrated catalog

Fitted star magnitude vs external catalog (ps1)



ZTF19aaripqw-zg
Residual plot for the calibration fit onto PS1
 $ZP = -26.3563$, $\chi^2/\text{ndof} = 0.9807$

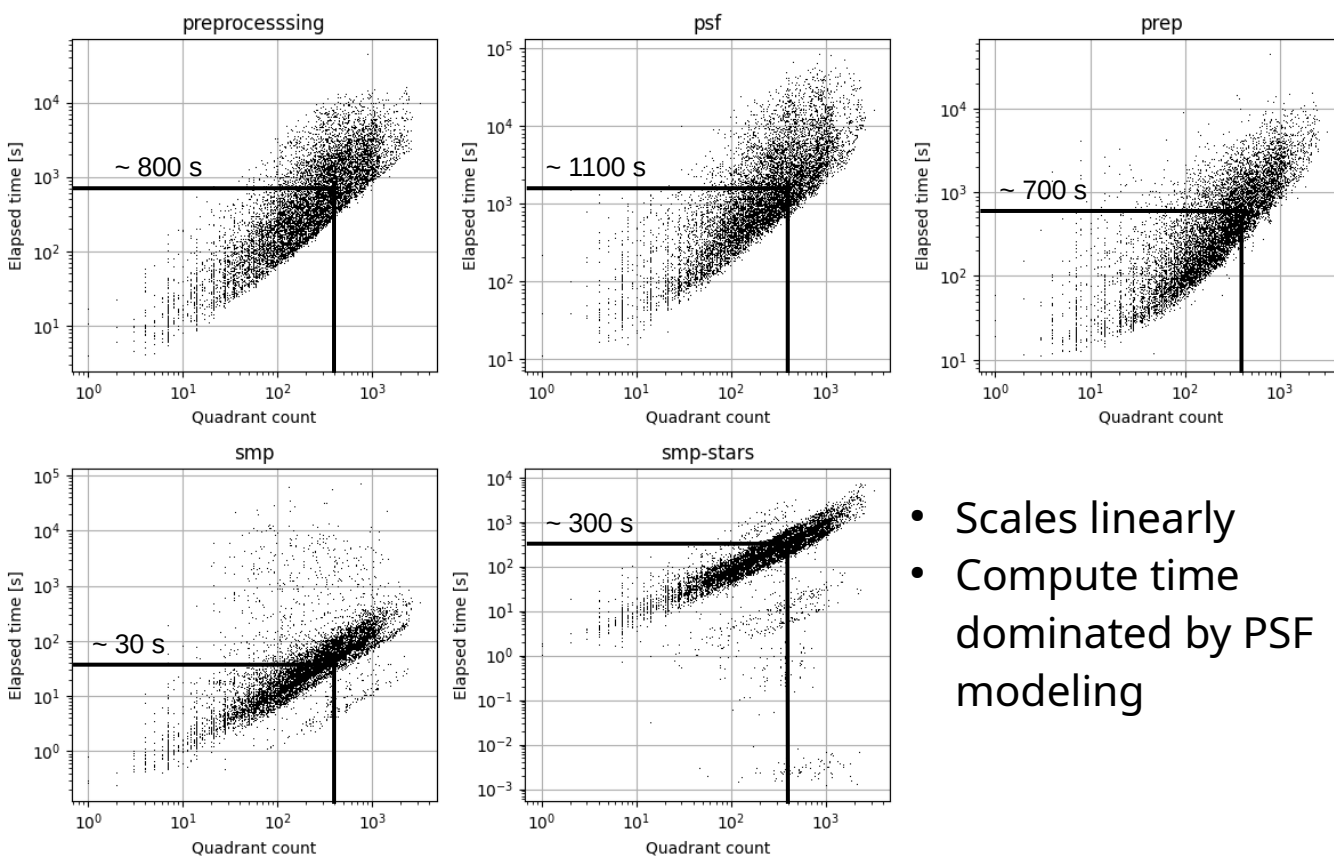


- Here: 0.5% dispersion for field stars
- With ~ 50 stars \rightarrow % level

Scene modeling pipeline

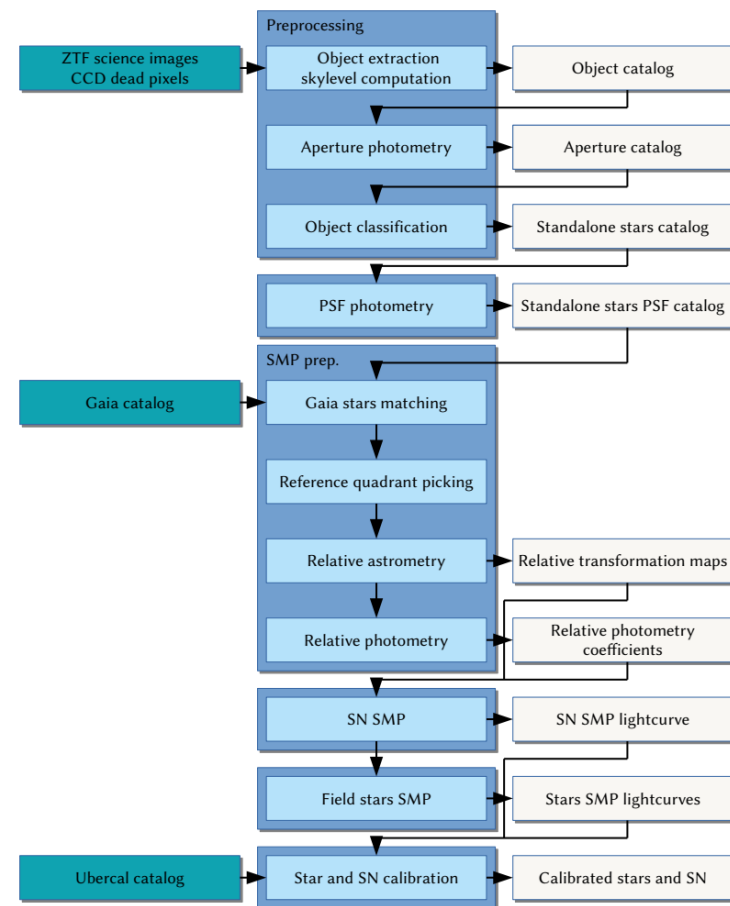
- 180 TB dataset - 3.6M quadrants
 - ~ 3600 SNe → ~10k lightcurves
 - ~ 1 week processing for whole DR2

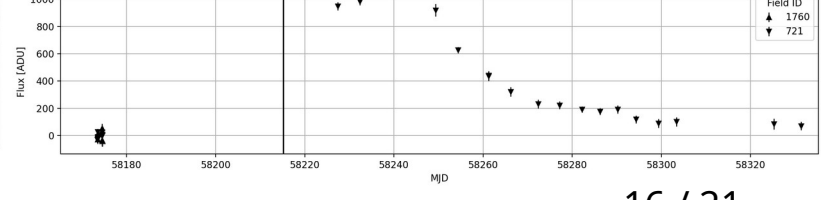
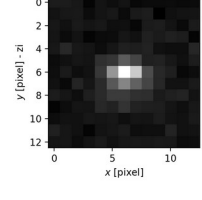
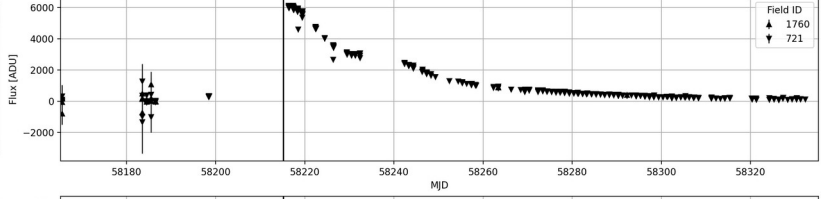
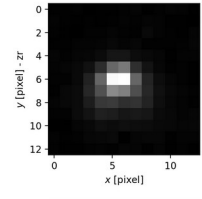
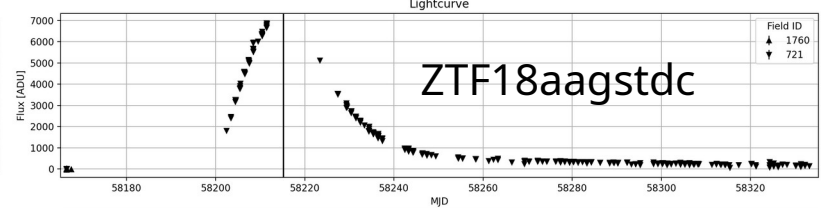
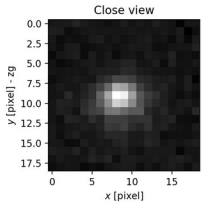
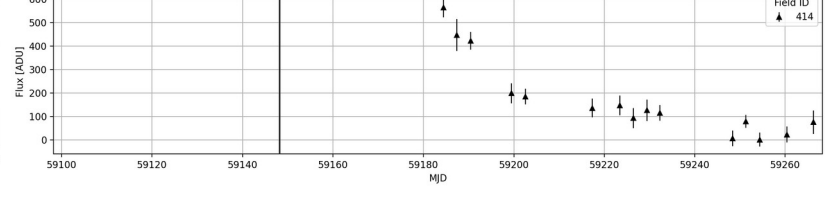
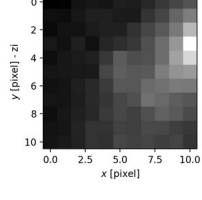
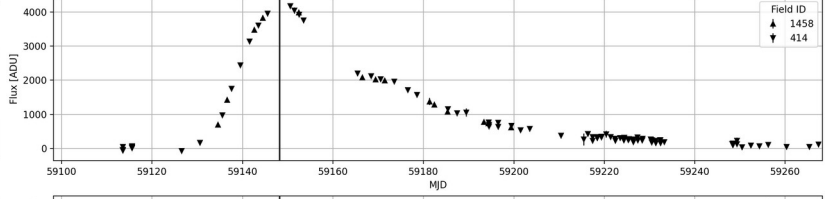
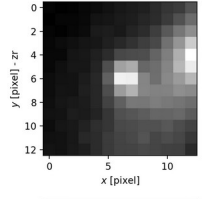
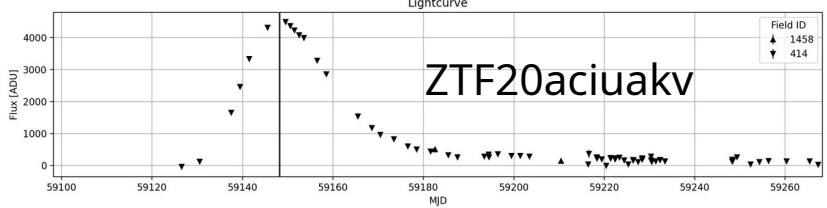
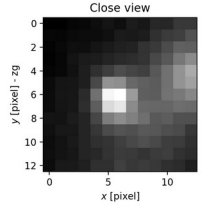
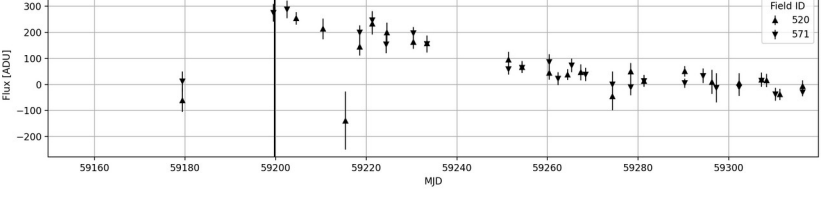
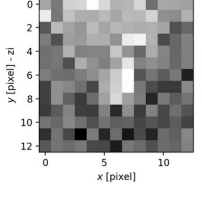
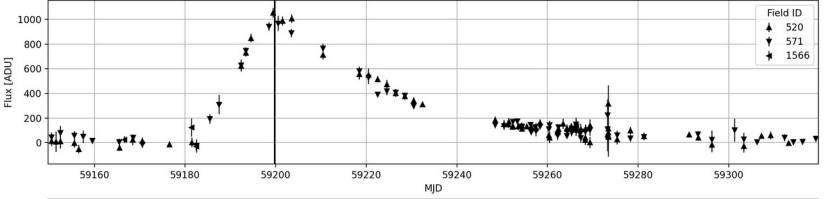
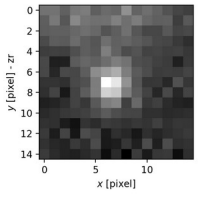
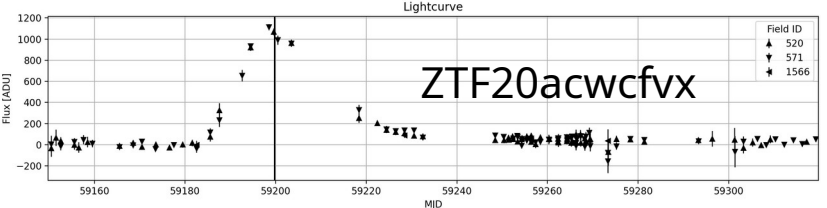
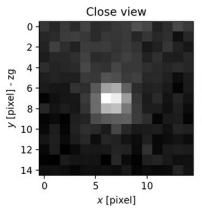
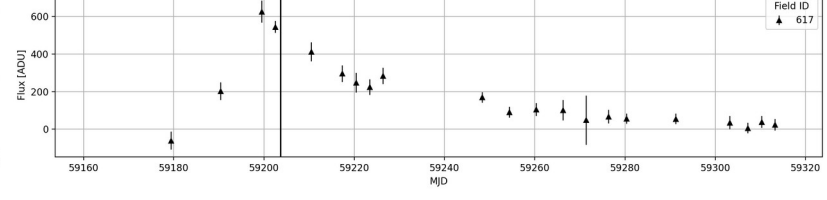
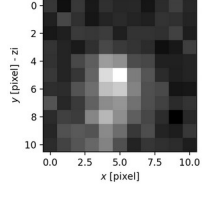
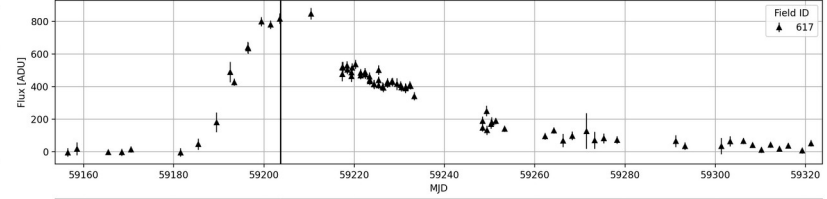
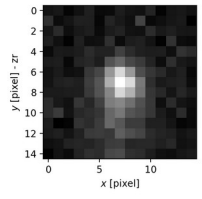
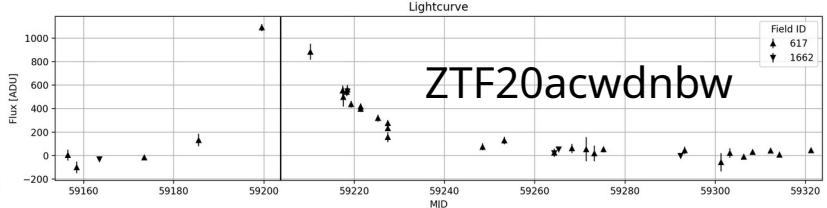
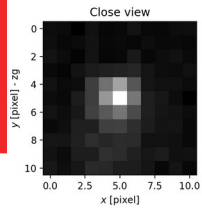
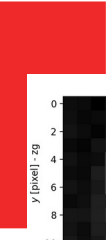
Time versus number of quadrants scatter plot

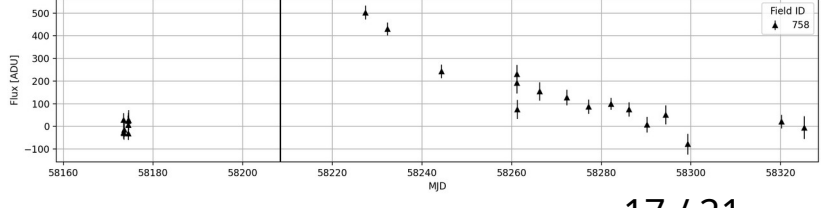
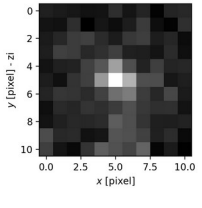
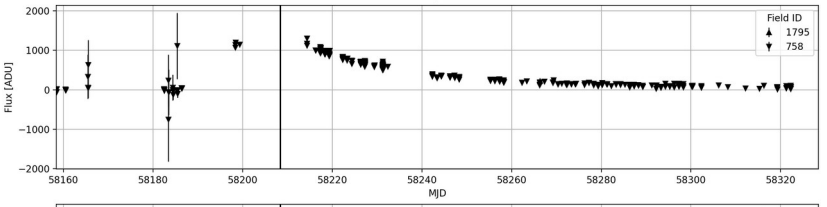
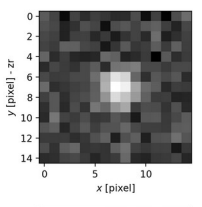
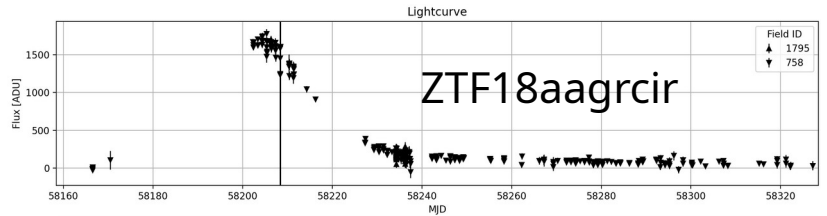
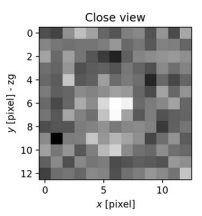
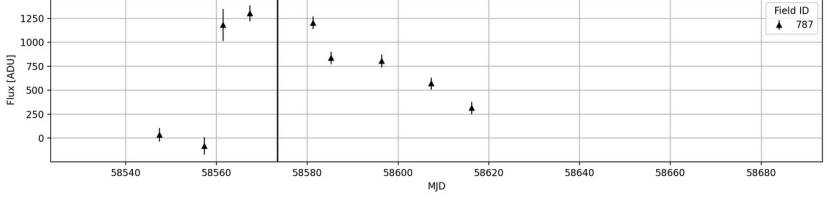
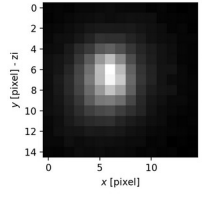
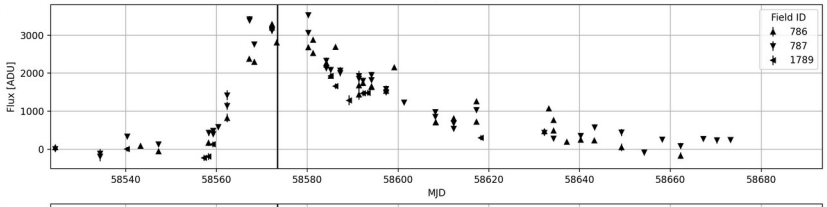
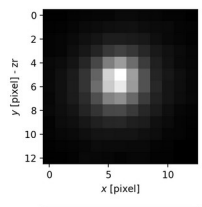
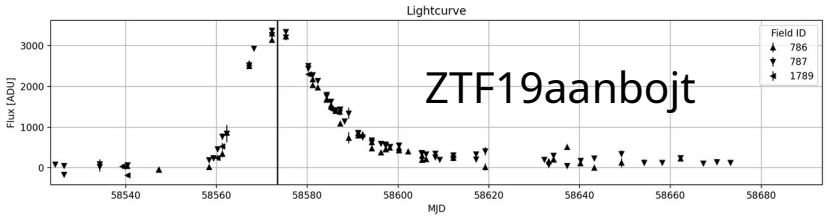
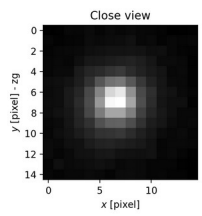
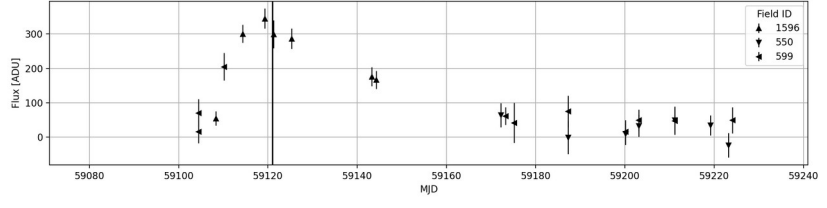
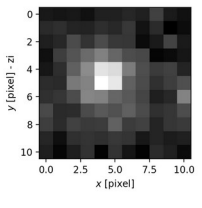
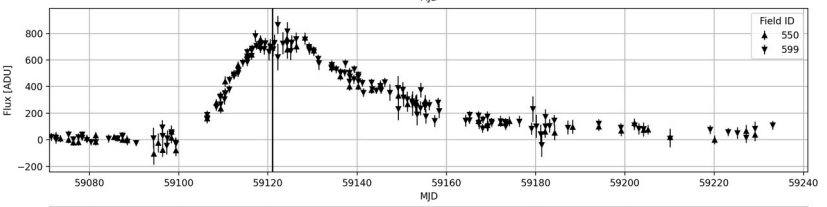
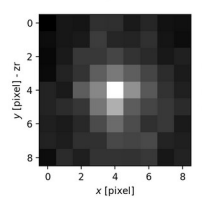
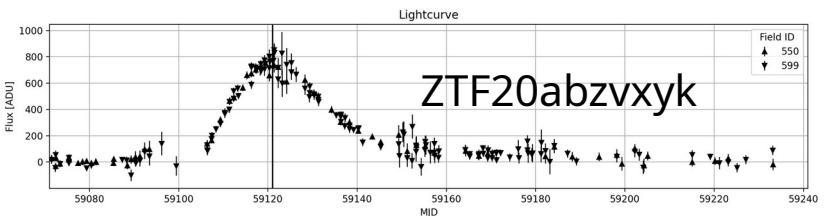
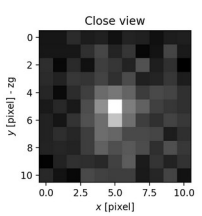
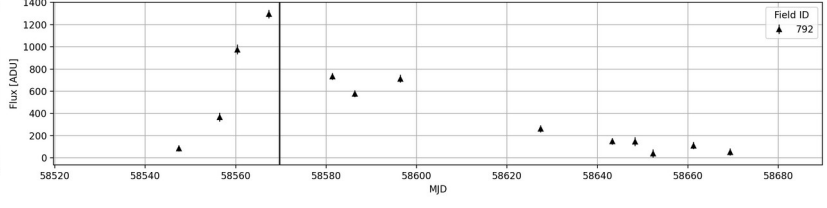
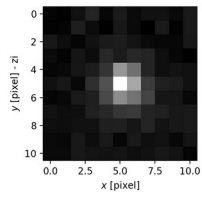
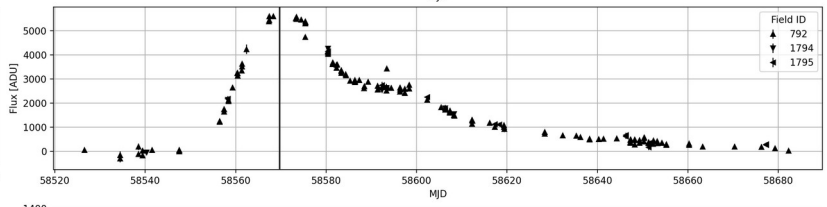
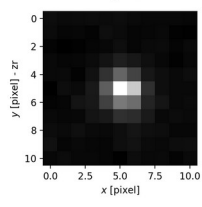
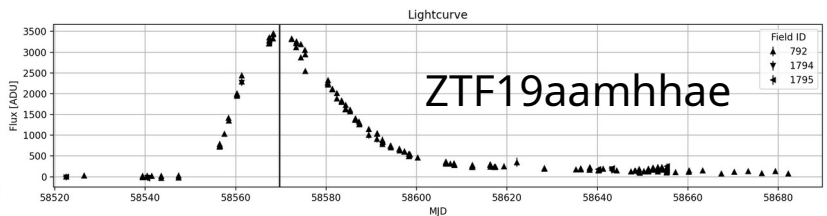
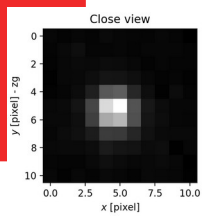


- Scales linearly
- Compute time dominated by PSF modeling

Typical SN: 300 exposures



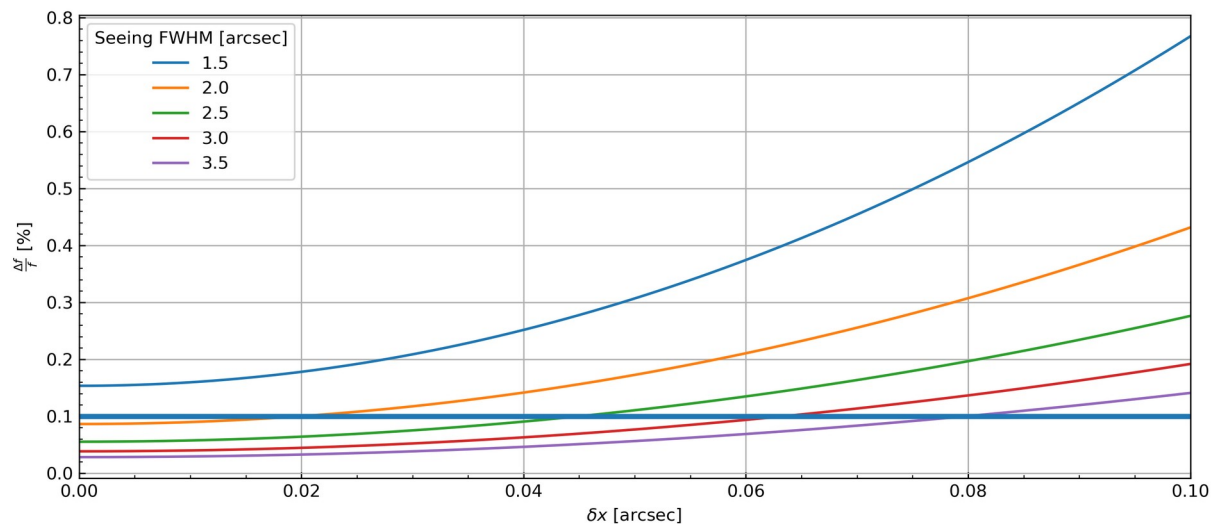




Scene modeling requirements

- Are we done? Not yet!
 - Still dominated by systematics
- Indeed: SMP has strict requirements
 - Robust and precise relative astrometry maps
 - PSF linearity → independent of flux

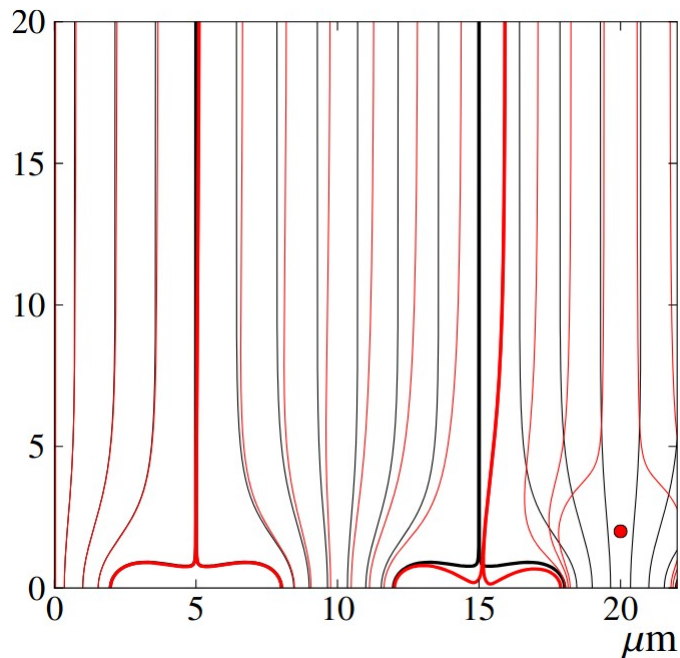
Gaussian PSF photometry bias due to position error
(setting $\delta y = 0.05$ [arcsec])



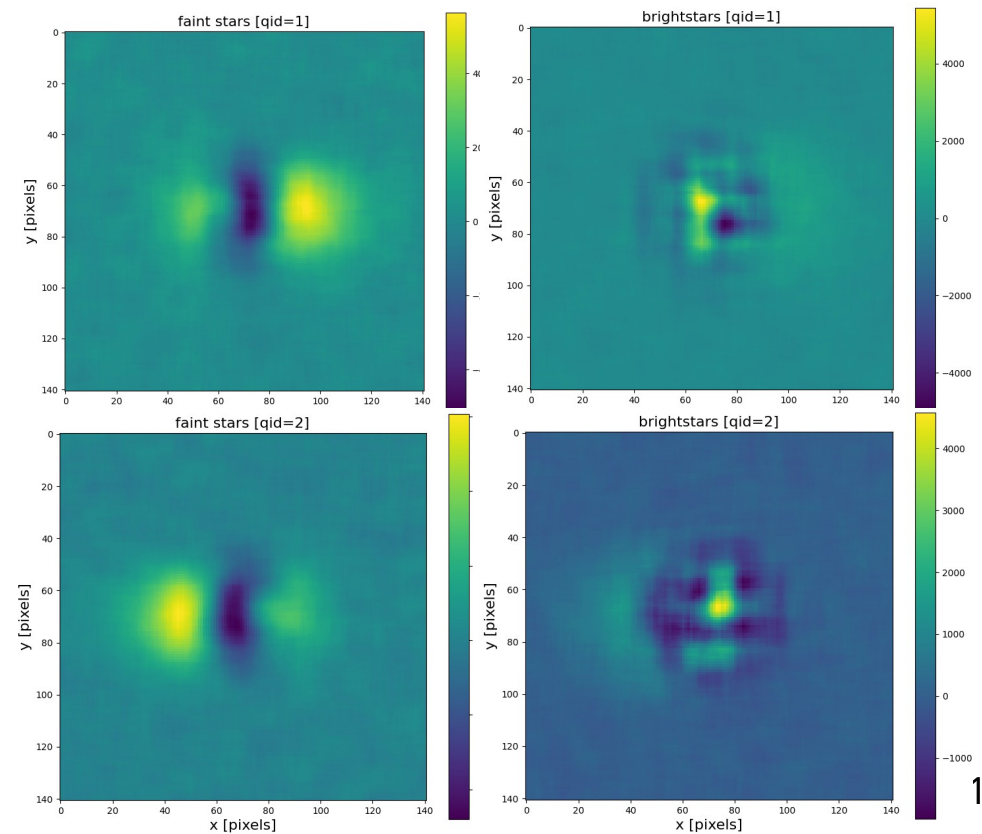
$$\frac{\Delta f}{f} = \frac{1}{4} \frac{\delta x^2 + \delta y^2}{\sigma_{\text{IQ}}^2}$$

Sensor effects affecting PSF linearity

- Brighter-fatter
 - High flux
 - Expected
 - 1-2% effect (p-to-p)
- “Pocket effect”
 - Low flux – low background
 - Unexpected
 - 5-10% effect (p-to-p)



(Guyonnet et al, 15, Astier '19, Astier & Regnault, '23)



Toward DR 2.5

- Current state
 - Fast pipeline able to process full dataset
 - ‰ statistical precision
- However
 - Challenging instrumental effects need to be fully corrected (from raw pixels) → control of systematics at the ‰ level

These corrections implies full data processing

Conclusion

- Full pipeline: from raw pixels to calibrated lightcurves
- Scales well, suitable for spectroscopic ZTF III → ~10k SNe
 - Also enables photometric sample processing, i.e. ~40k SNe
- 10k low z Ia SNe → will be unmatched for years
- Prepares the LSST era

Thank you