

Accelerating cosmological inference from **Euclid** with Marginal **Neural** Ratio Estimation



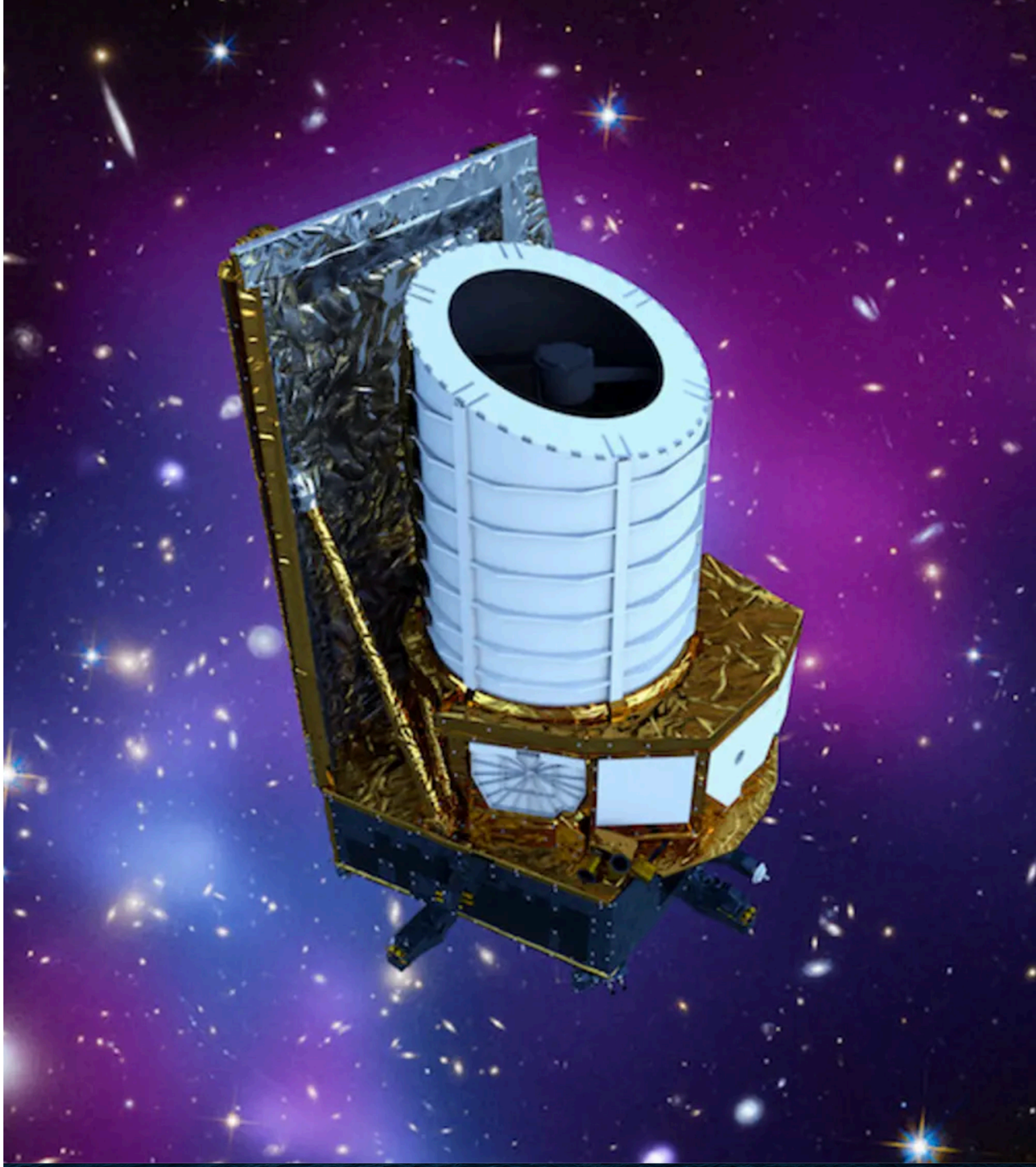
Guillermo Franco Abellán

TUG - 11/10/2023

Ongoing work with
Guadalupe C. Herrera,
Matteo Martinelli,
Christoph Weniger,
& others



[ESA's Euclid space satellite]



On July 1, **Euclid** was **launched** to L2

[ESA's Euclid space satellite]



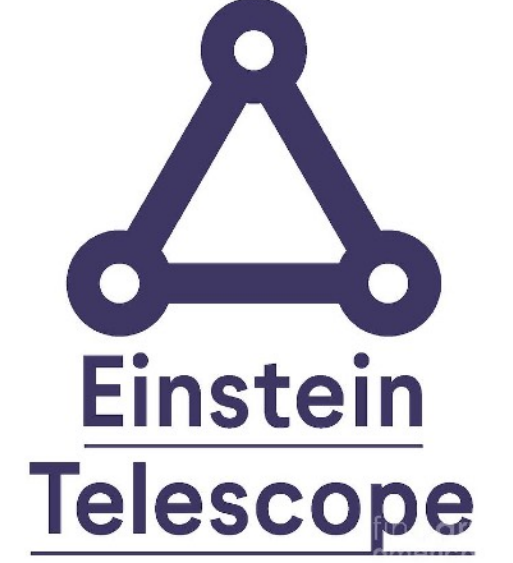
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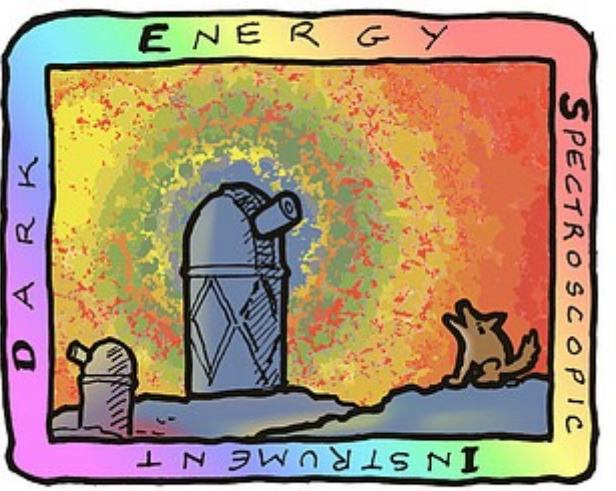
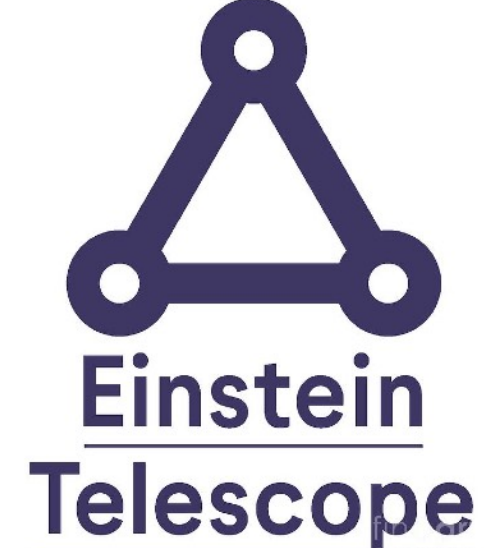
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- Over the next 6 years, Euclid will measure the **shapes, and redshifts of billions of galaxies**, across $\sim 1/3$ of the sky
- First **public data** release expected in **2025**

Many more astronomical data to come...



lisa

Many more astronomical data to come...



Analysing these high-quality data will be challenging with standard methods

The curse of dimensionality

- Traditional **likelihood-based** methods (MCMC, Nested Sampling,...)
→ compute **joint posterior** and then **marginalise**

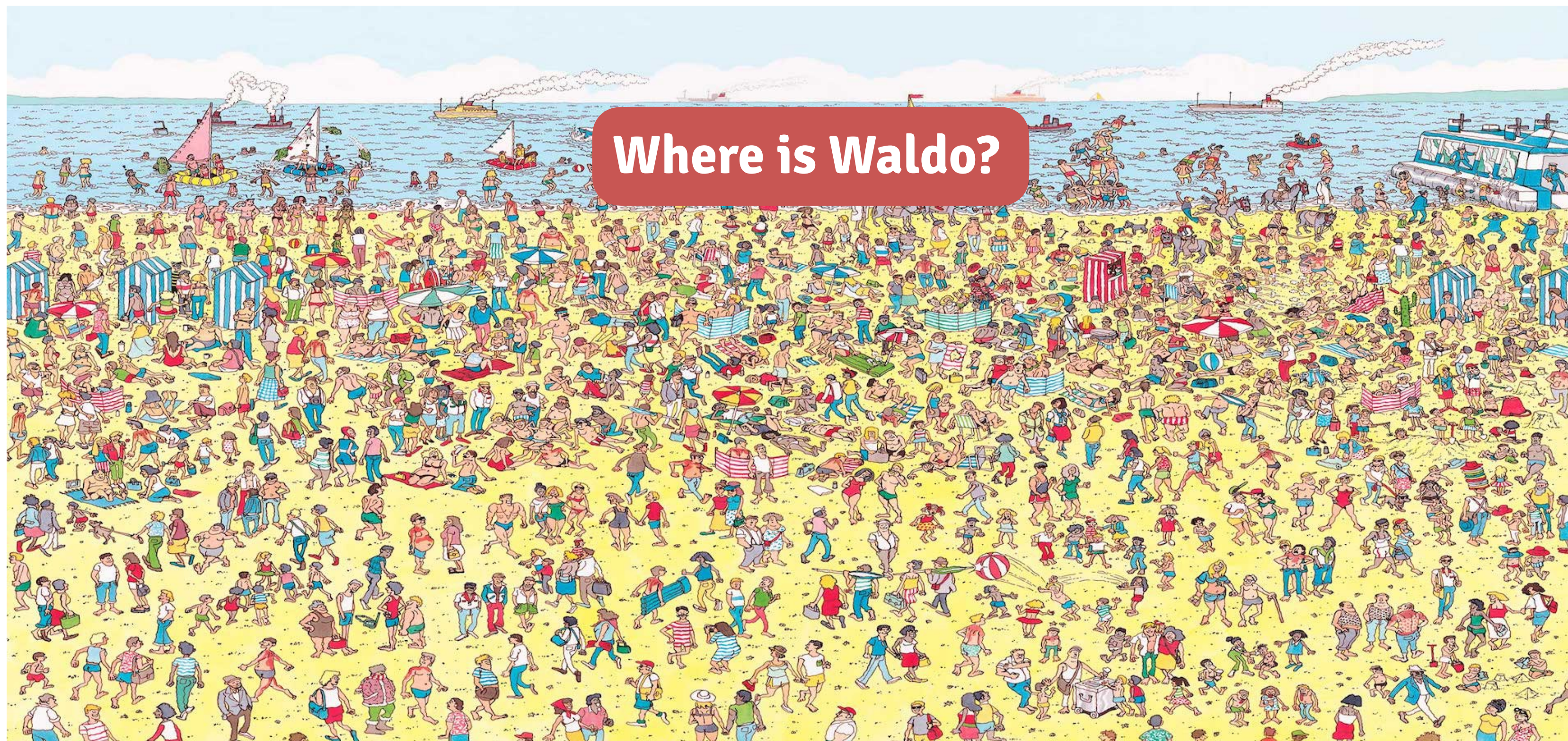
The curse of dimensionality

- Traditional **likelihood-based** methods (MCMC, Nested Sampling,...)
→ compute **joint posterior** and then **marginalise**
- Scale poorly** with **dimensionality** of parameter space

Ex: For Euclid, we expect to have
+50 nuisance parameters



The curse of dimensionality



Marginal posterior

$$P(z_{\text{waldo}} | x_0) = \int dz_{\text{Pierre}} dz_{\text{Thomas}} dz_{\text{Julien}} \cdots dz_{\text{Killian}} P(z_{\text{Waldo}}, z_{\text{Pierre}}, z_{\text{Thomas}}, z_{\text{Julien}}, \cdots, z_{\text{Killian}} | x_0)$$

Joint posterior

Are there methods to overcome this problem?

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Can machine learning be helpful?

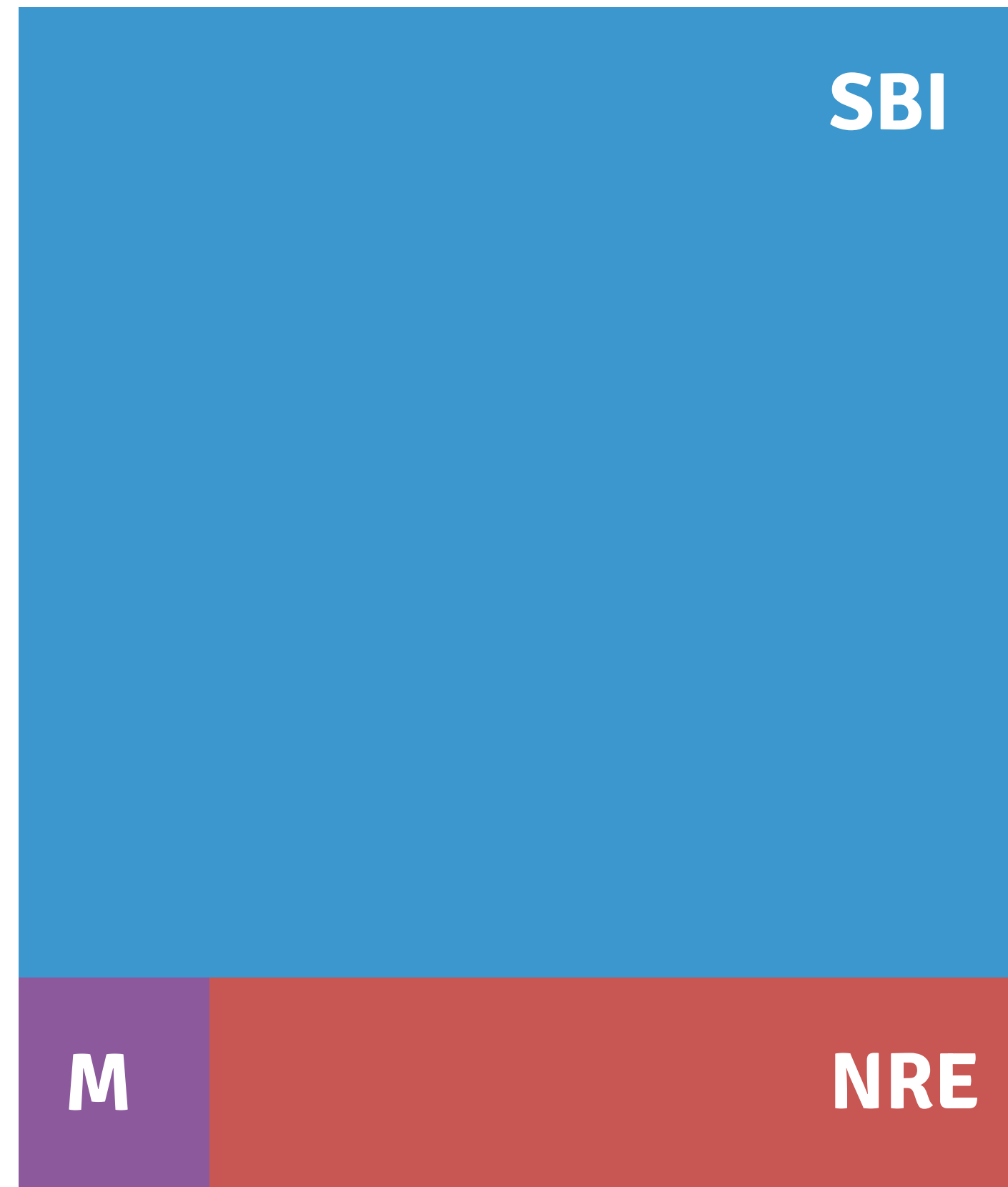
A NEW HOPE

MNRE = Marginal Neural Ratio Estimation

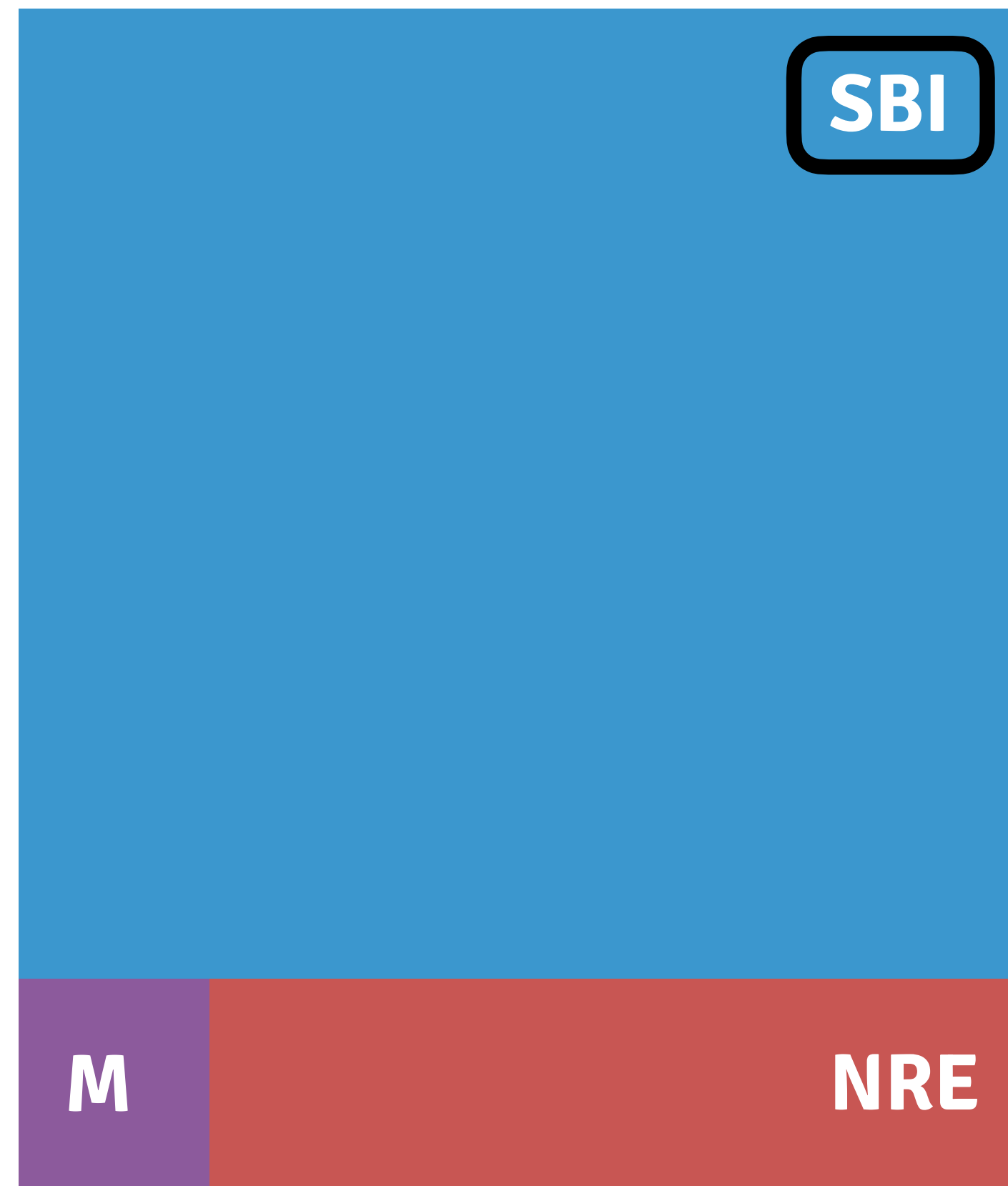
Implemented in [Swyft*](#) [[Miller+ 20](#)]

* Stop Wasting Your Precious Time

Marginal Neural Ratio Estimation

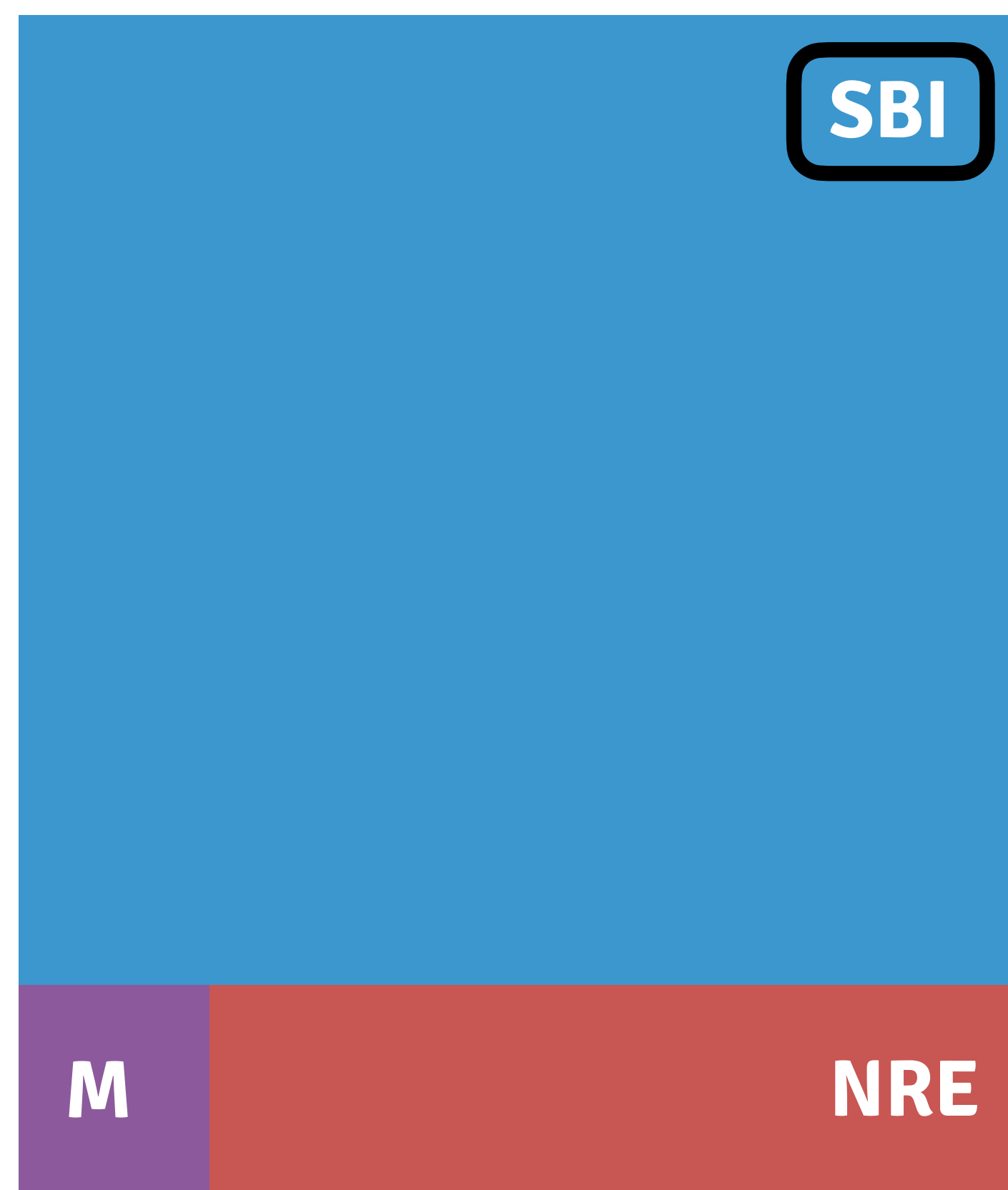


Marginal Neural Ratio Estimation



 **Simulation-based inference**
(or likelihood-free inference)

Marginal Neural Ratio Estimation



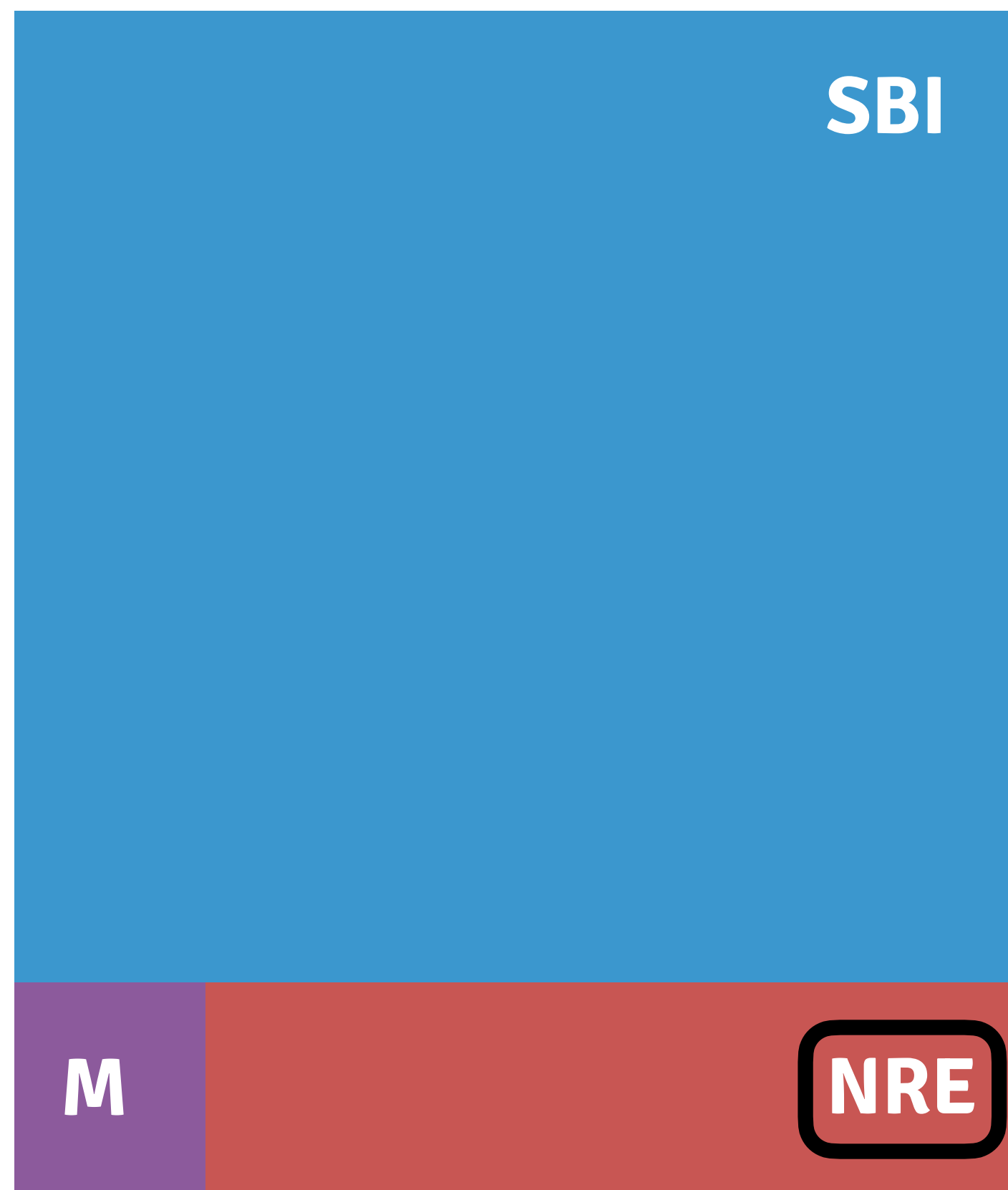
■ **Simulation-based inference**
(or likelihood-free inference)



Stochastic simulator that maps from
model parameters \mathbf{z} to data \mathbf{x}

$$\mathbf{x} \sim p(\mathbf{x} | \mathbf{z}) \quad (\text{implicit likelihood})$$

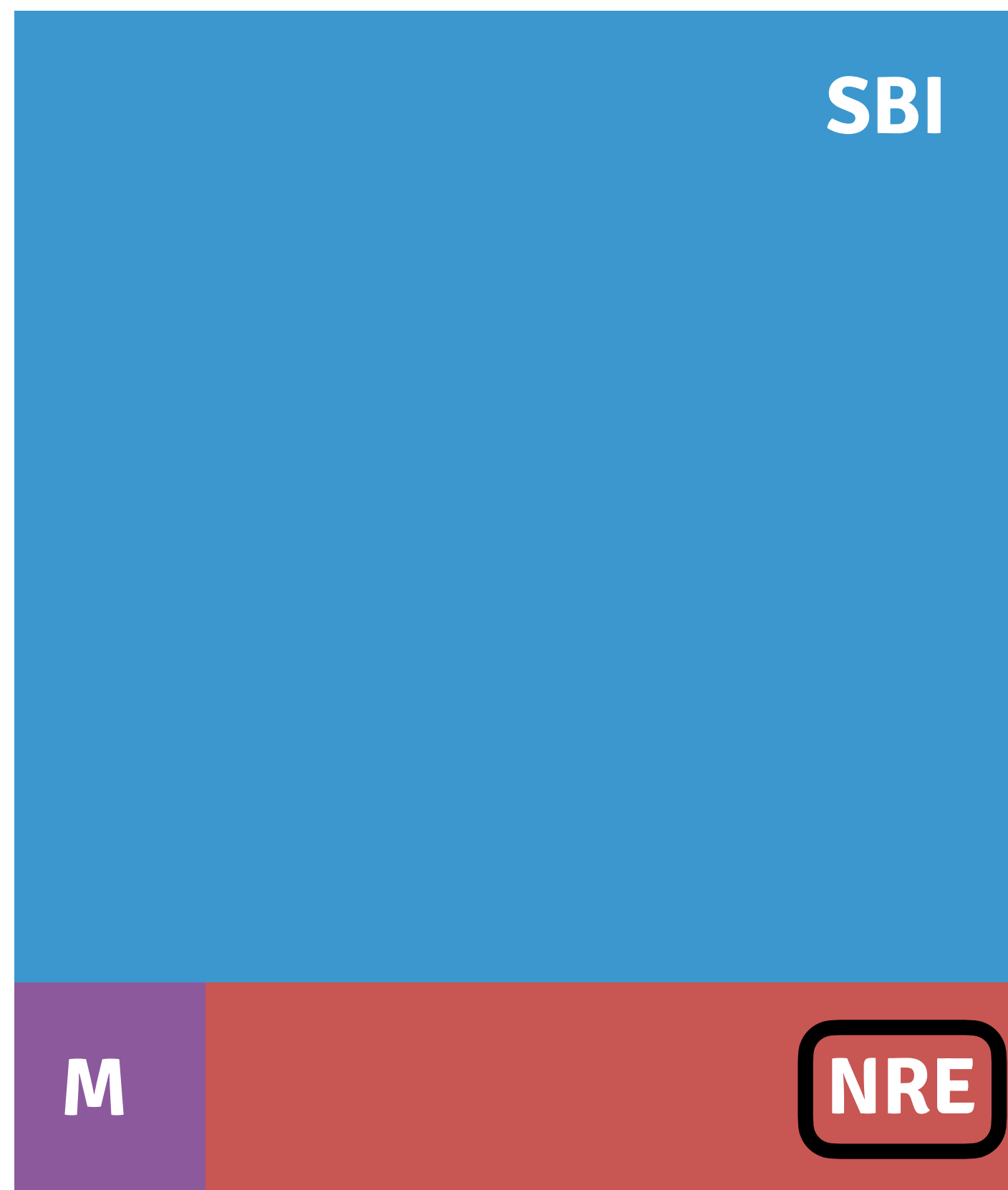
Marginal Neural Ratio Estimation



Neural Ratio Estimation

$$r(\mathbf{x}; \mathbf{z}) = \frac{p(\mathbf{x} | \mathbf{z})}{p(\mathbf{x})} = \frac{p(\mathbf{z} | \mathbf{x})}{p(\mathbf{z})} = \frac{p(\mathbf{x}, \mathbf{z})}{p(\mathbf{x})p(\mathbf{z})}$$

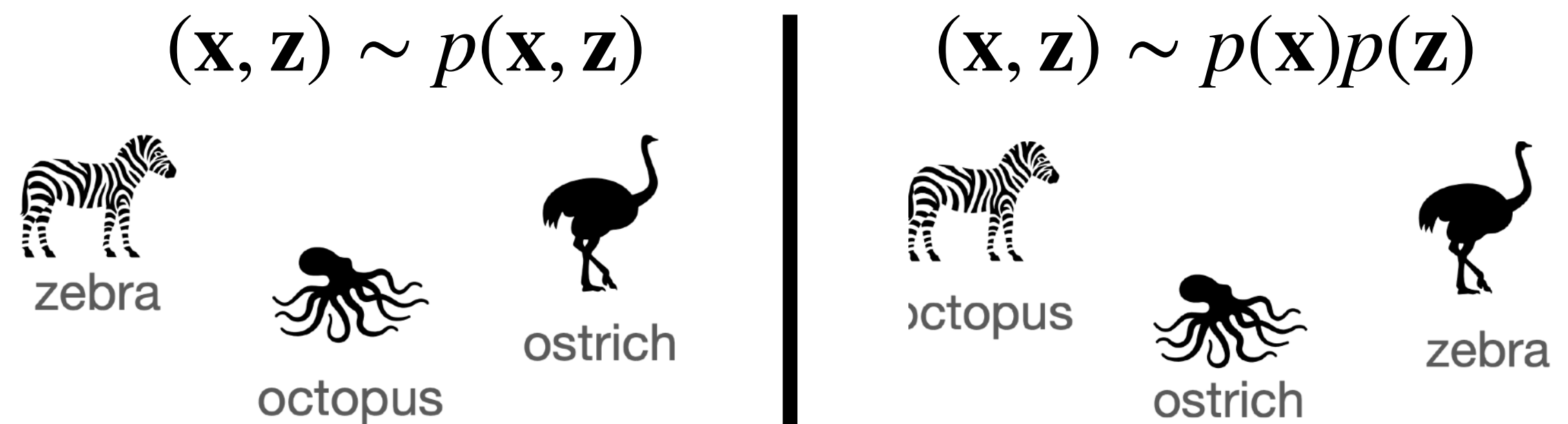
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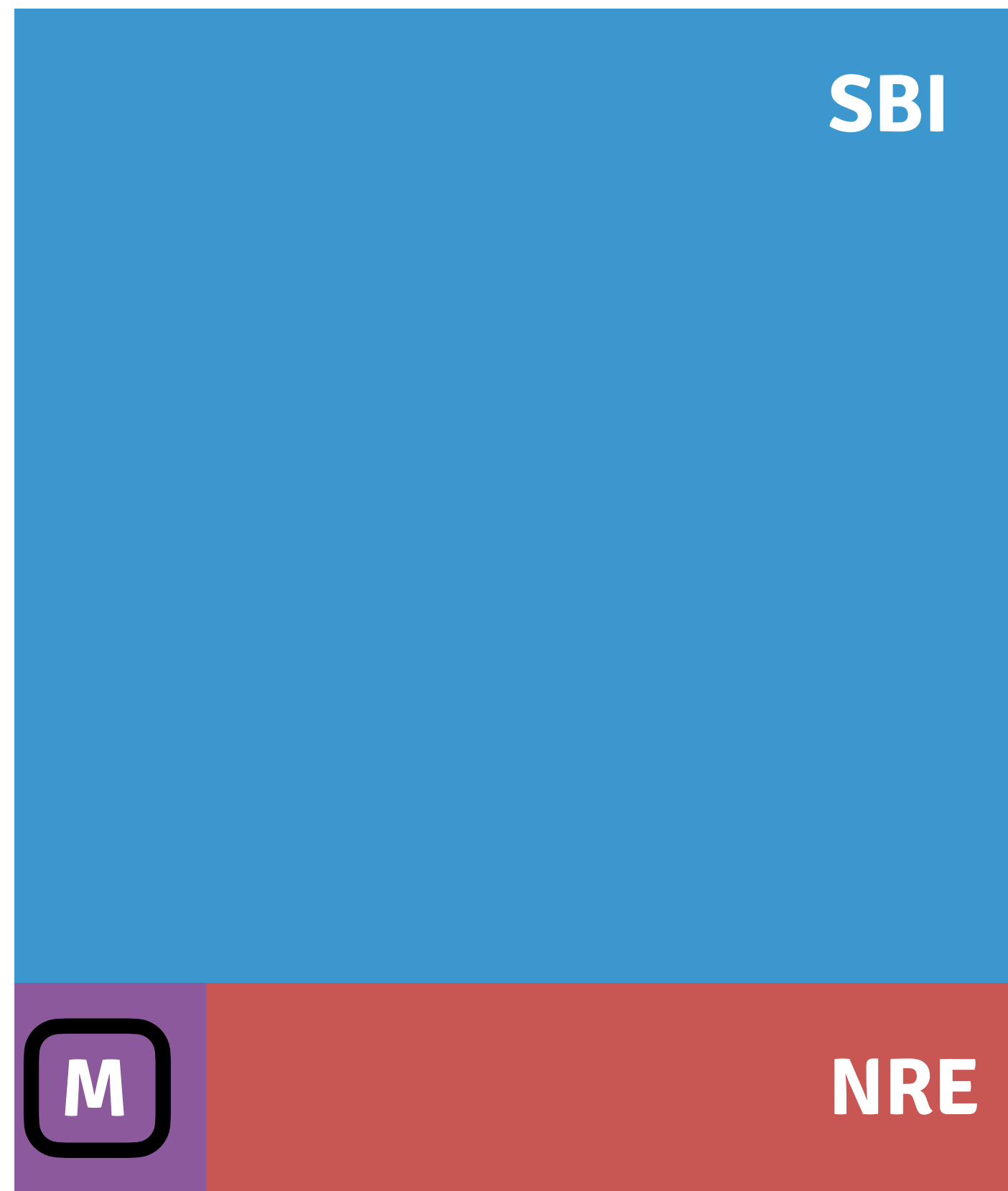
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Rephrase inference as a **binary classification problem**, and solve it by training a NN on simulated data

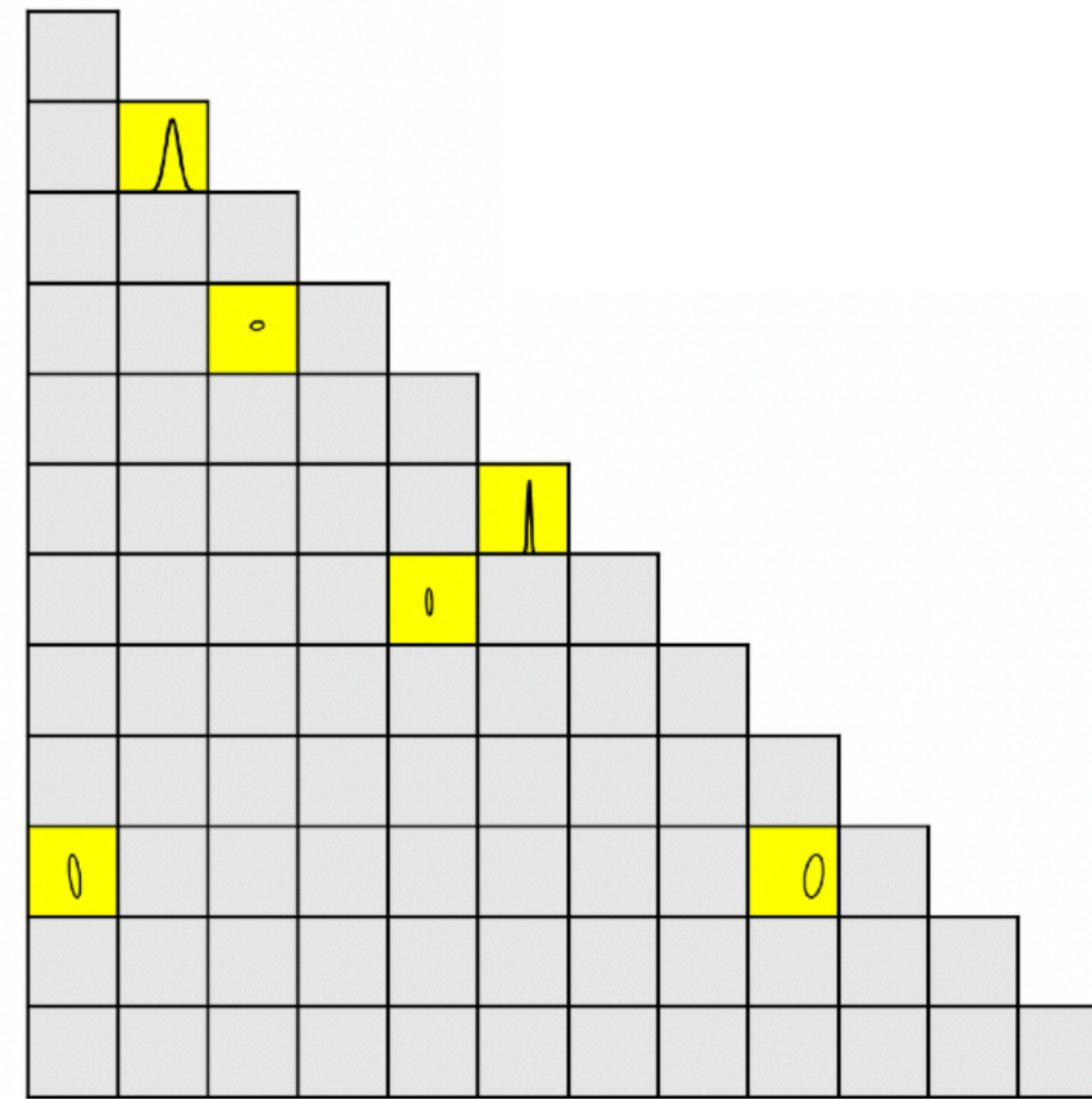


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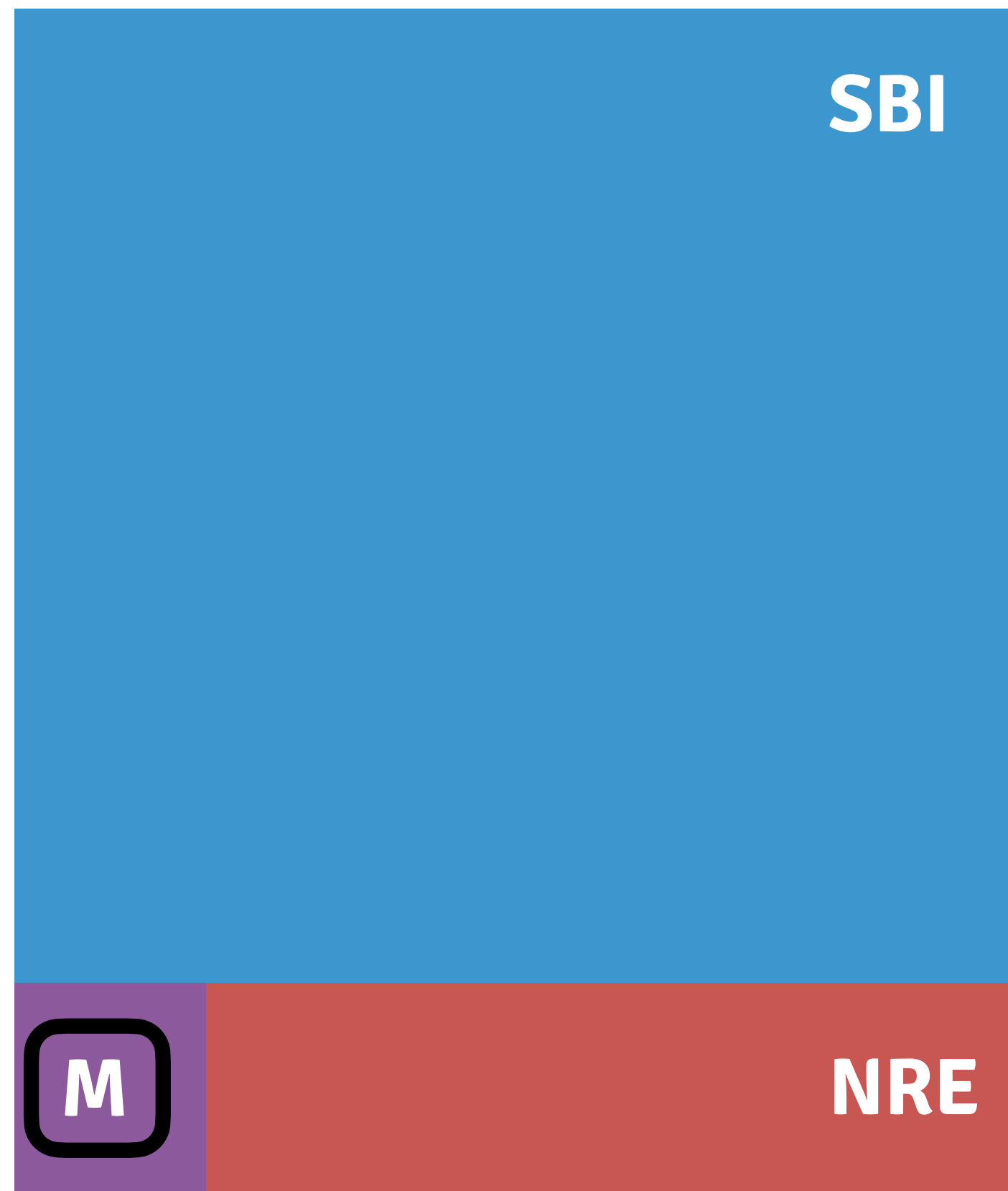


Marginal inference

Instead of estimating all parameters, we can **cherry-pick what we care about**

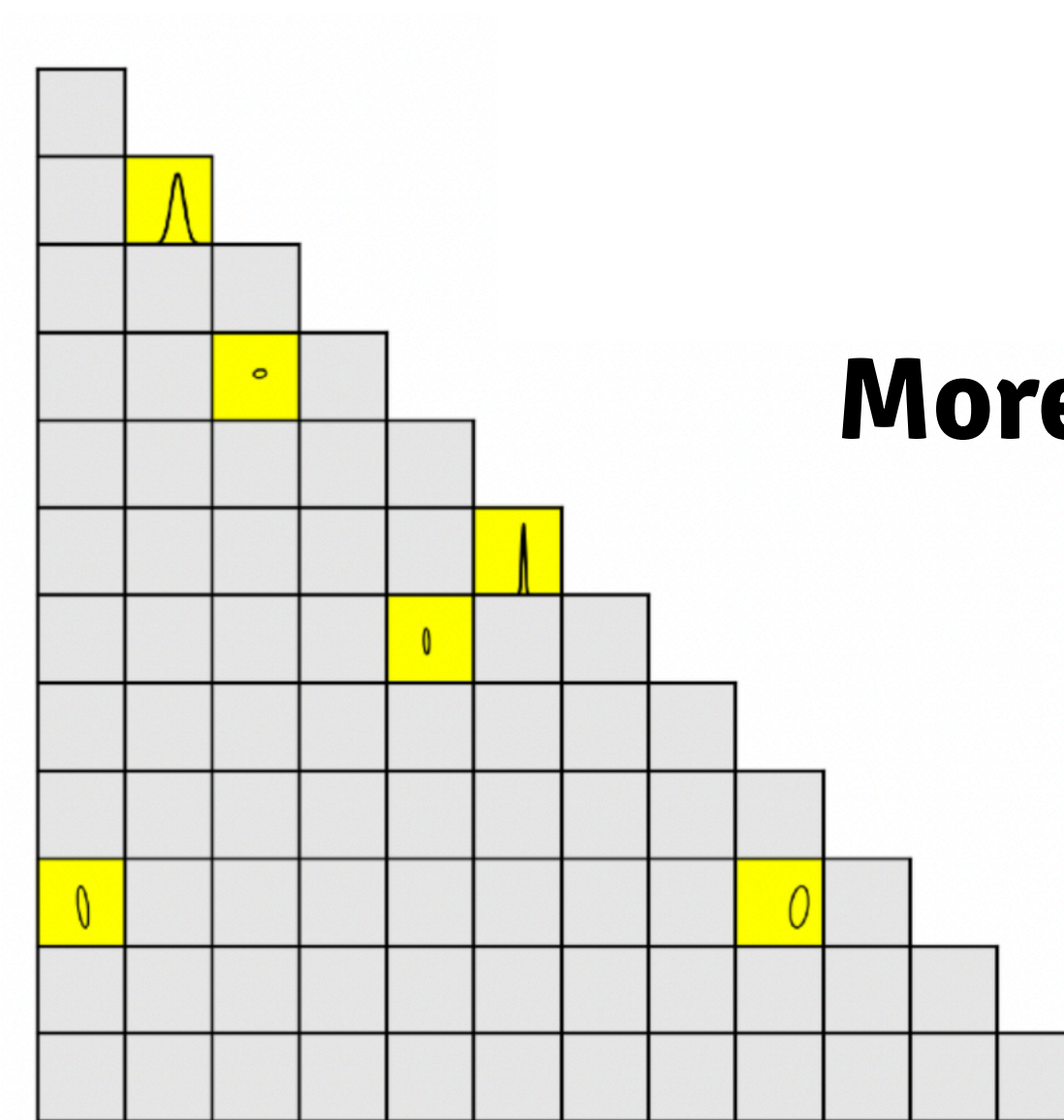


Marginal Neural Ratio Estimation



Marginal inference

Instead of estimating all parameters, we can **cherry-pick what we care about**



↓
More flexible & efficient

MNRE has been successfully applied in many contexts:

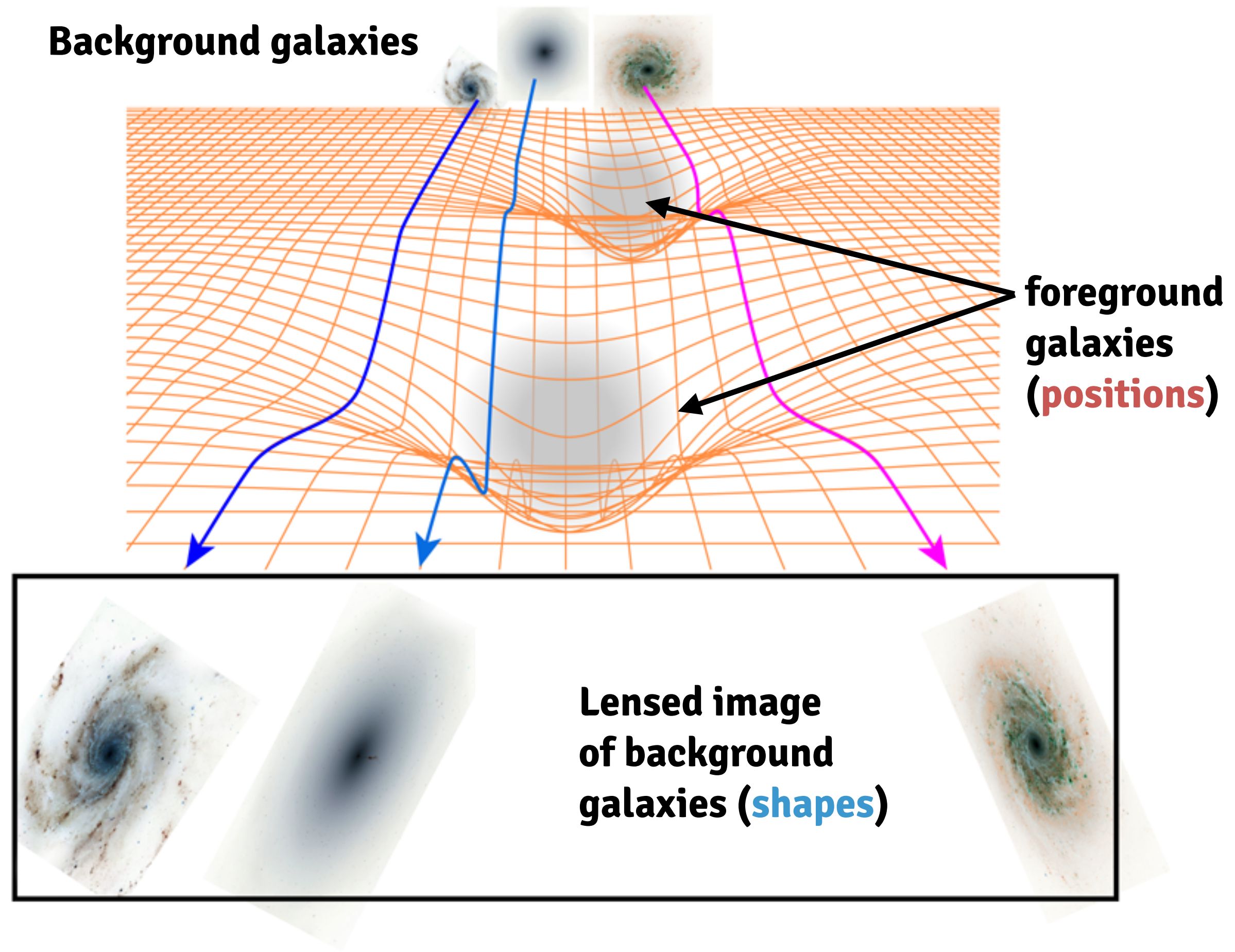
- **Strong lensing** [[Montel+ 22](#)]
- **Stellar Streams** [[Alvey+ 23](#)]
- **Gravitational Waves** [[Bhardwaj+ 23](#)] [[Alvey+ 23](#)]
- **CMB** [[Cole+ 22](#)]
- **21-cm** [[Saxena+ 23](#)]

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Our goal: apply MNRE to Euclid primary observables

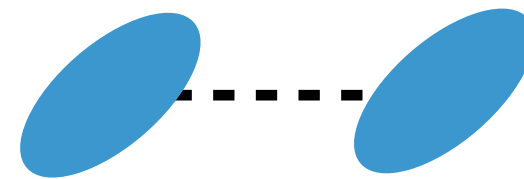
Which are the Euclid primary observables?



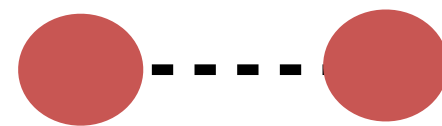
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Summarise maps of **positions/shapes**
using three 2-point statistics (**3x2pt**):

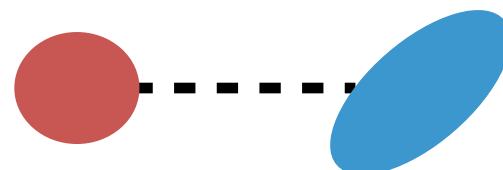
 **Cosmic Shear**



 **Galaxy clustering**



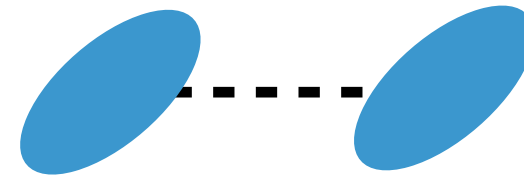
 **Galaxy-Galaxy lensing**



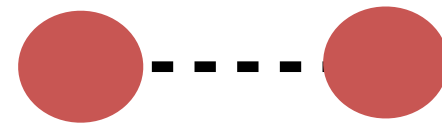
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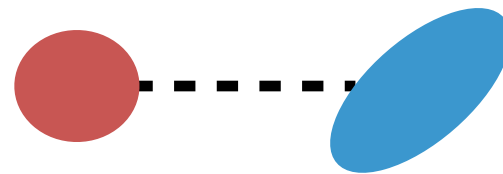
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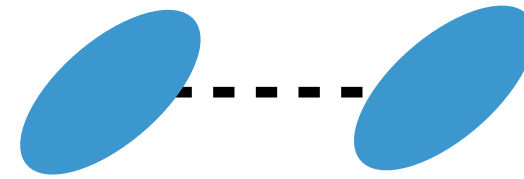


... measured for different
tomographic redshift bins*

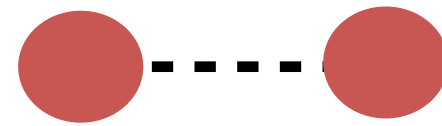
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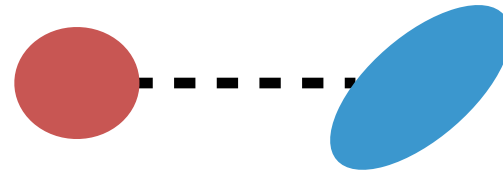
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... measured for different
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* We consider only photometric redshifts, but Euclid will also create a spectroscopic survey

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- 3x2pt statistics described by a series of **power spectra**:

$$C_{ij}^{XY}(\ell) = \int dz W_i^X(z) W_j^Y(z) P_m(k_\ell, z)$$

Window functions Matter power spectrum

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- For 10 redshift bins up to $z = 3$
 → **+200 power spectra!**

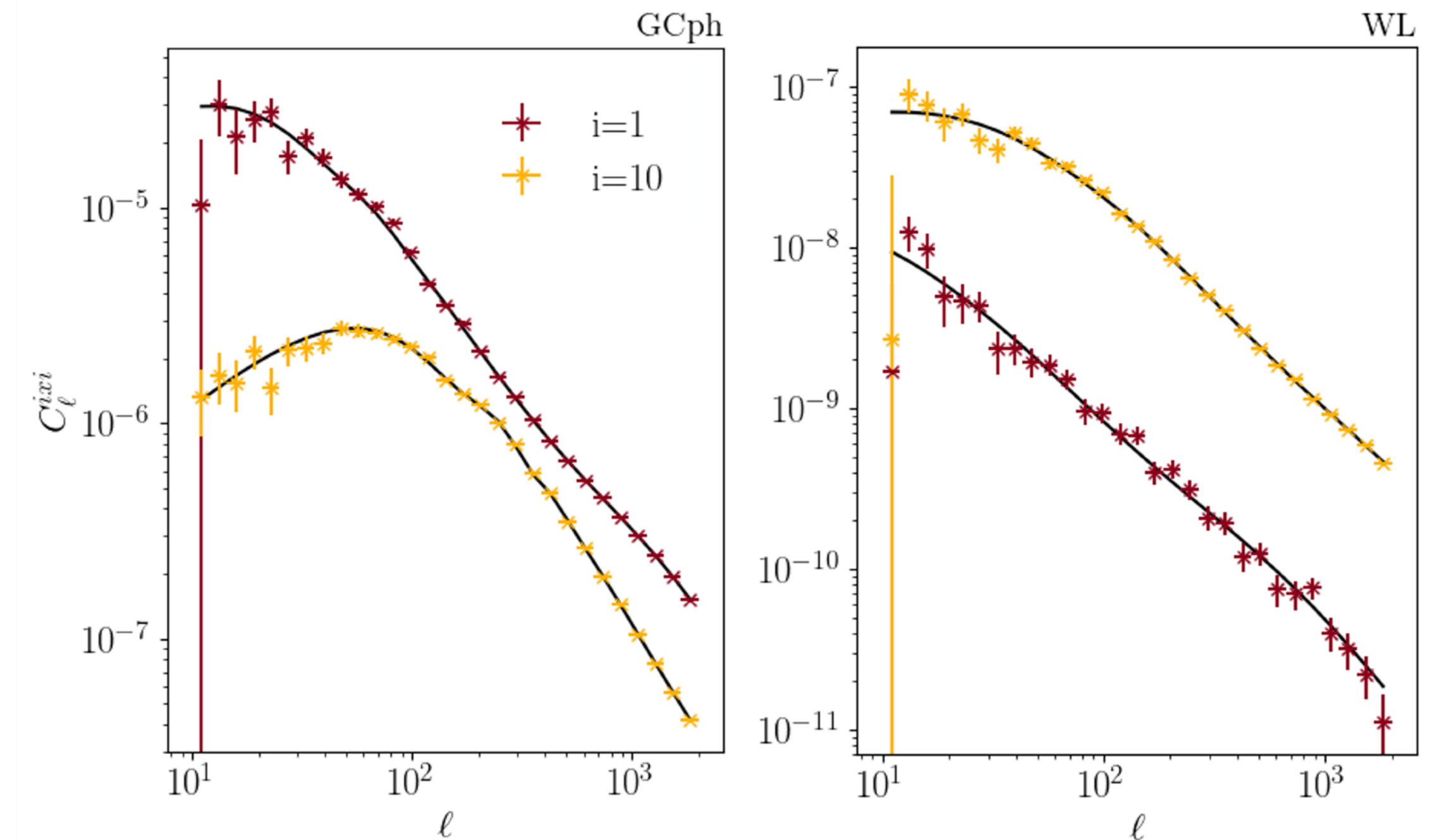
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Ex:



Preliminary results

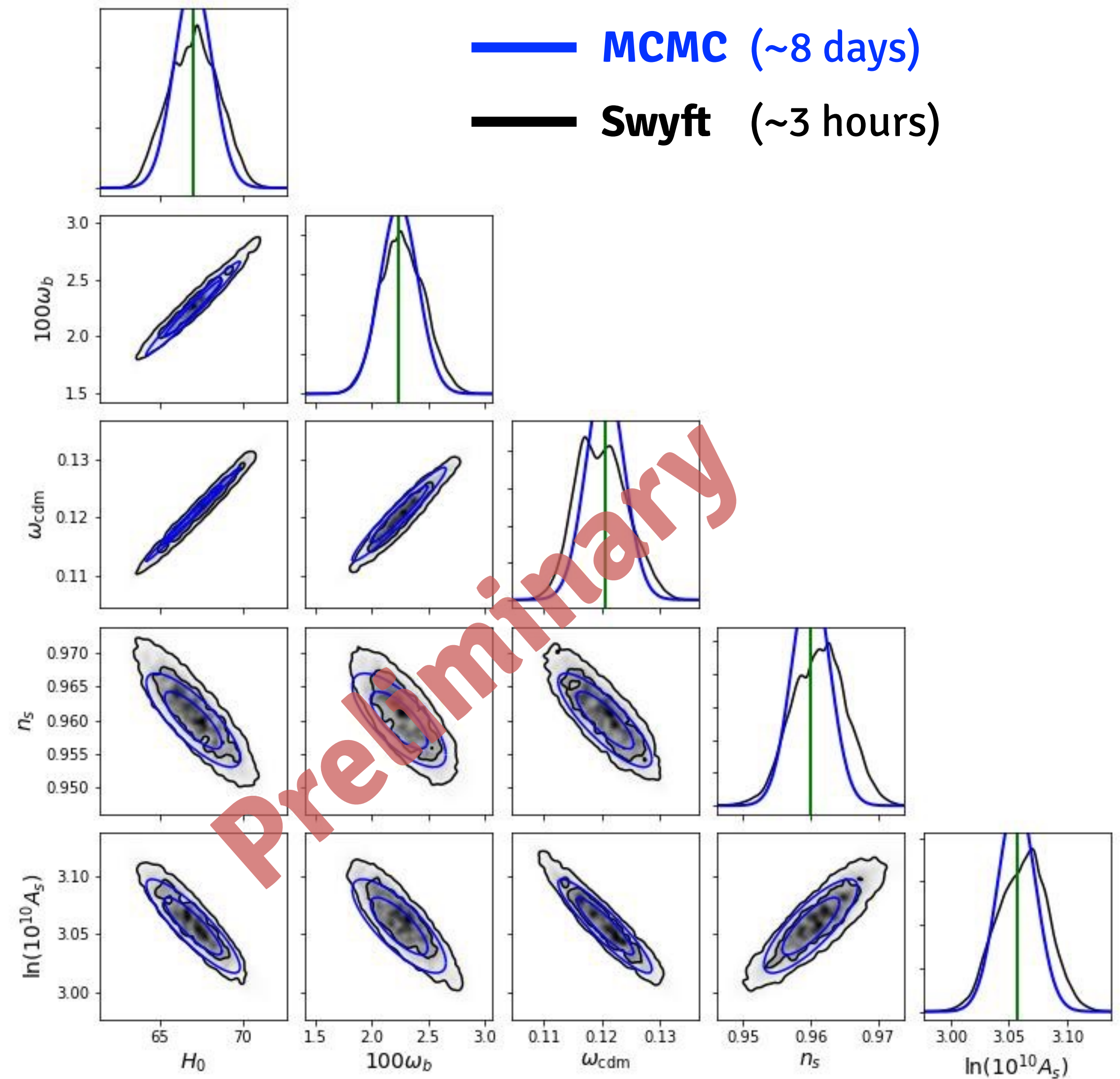
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Conclusions

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- **MNRE** provides a **highly efficient and flexible** framework to analyse Euclid data

Early commissioning test image, Euclid VIS instrument



THANKS FOR YOUR ATTENTION

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BACK-UP

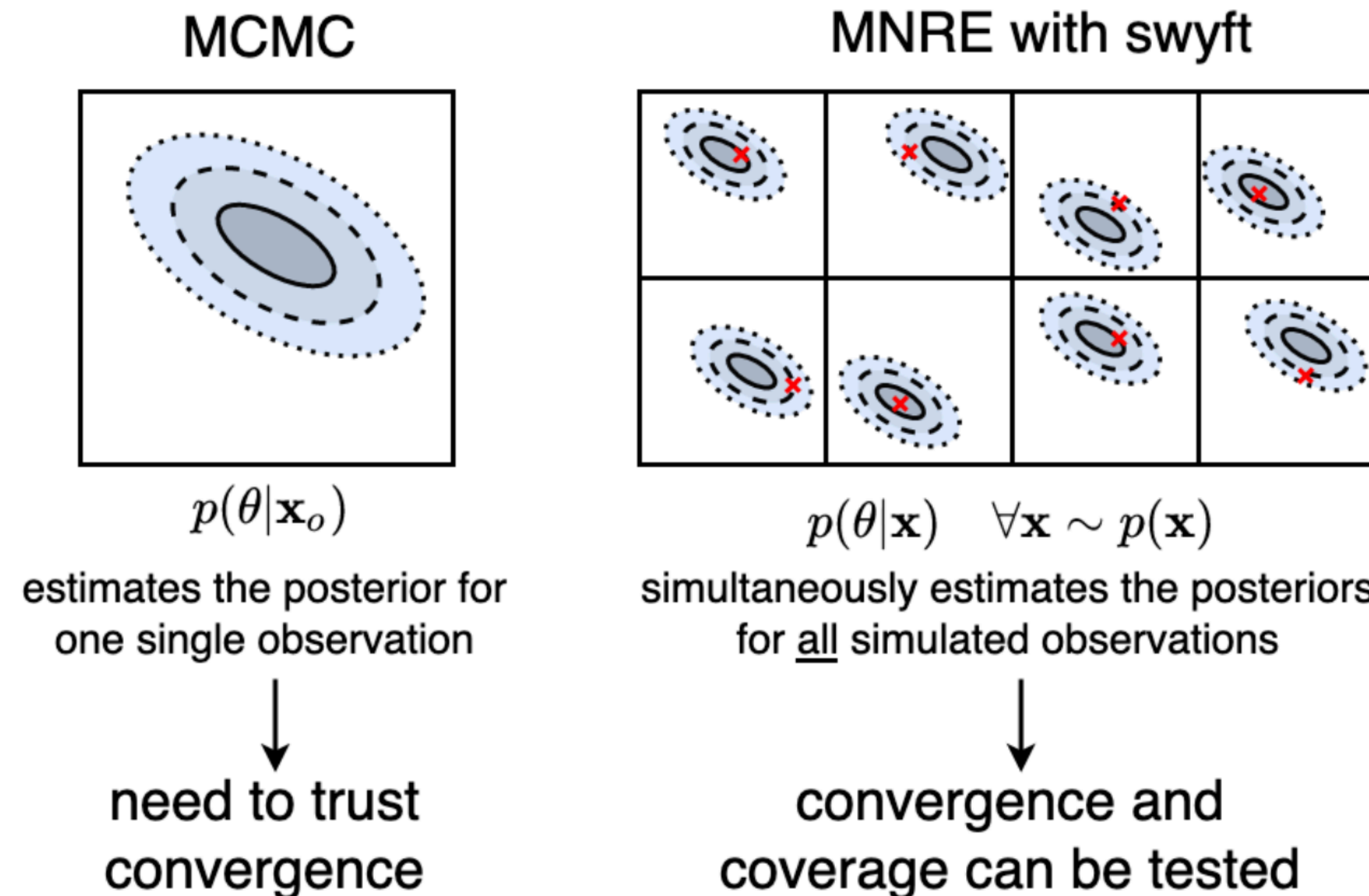
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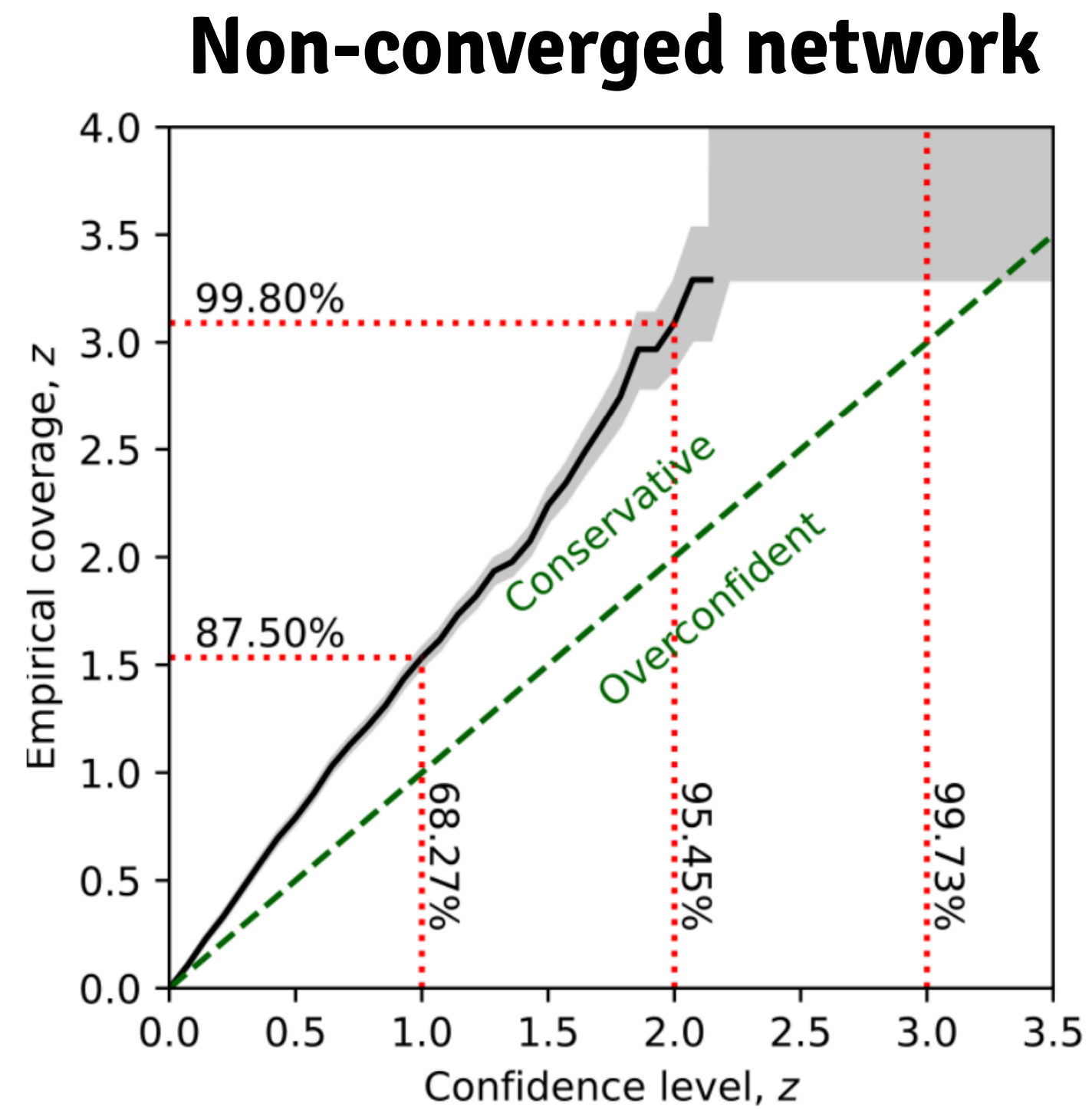
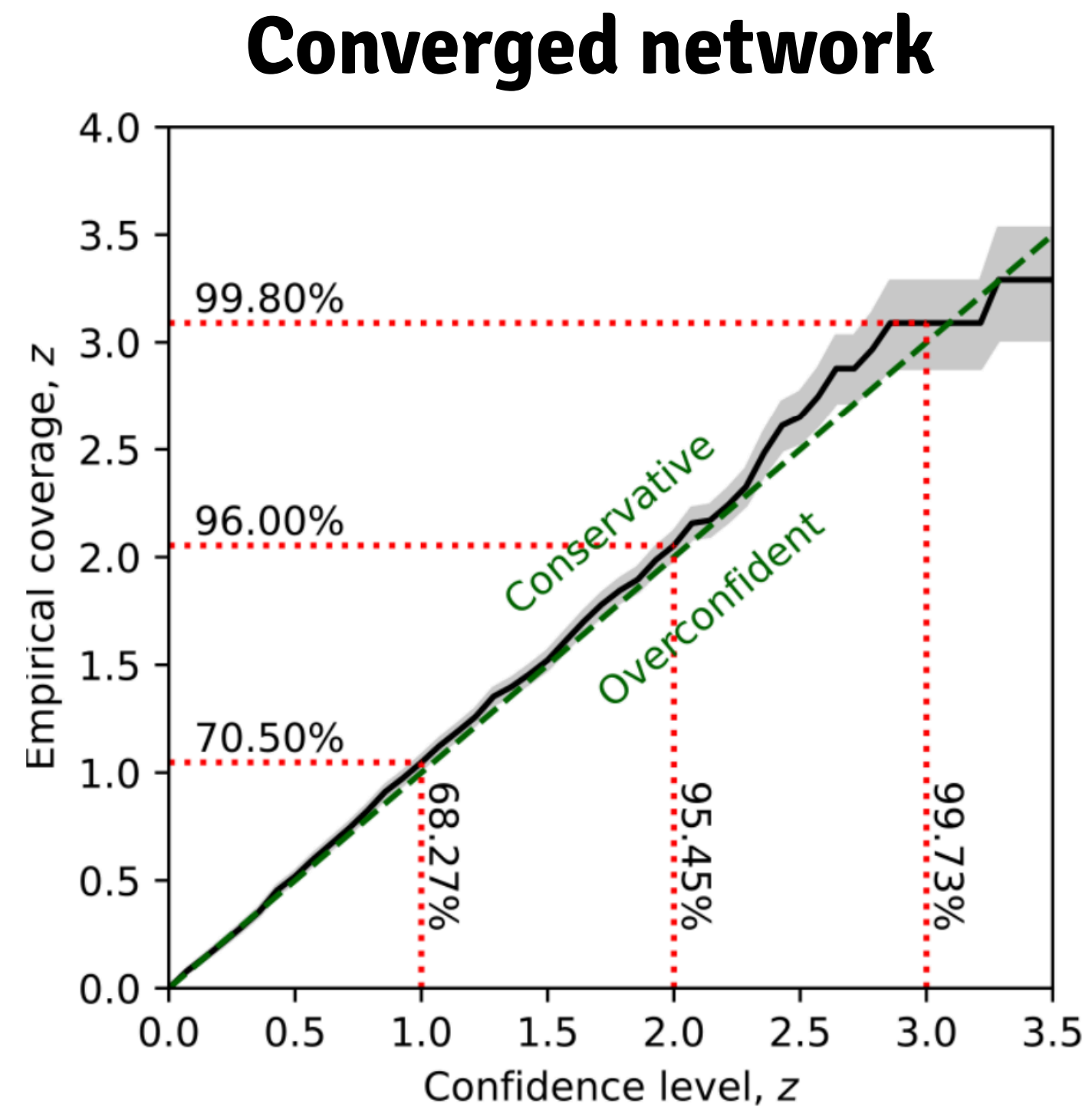
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- Exploit MNRE's **local amortization**:



Can we trust our results?

- We can empirically estimate the **Bayesian coverage**



[Cole+ 22](#)