Machine Learning Light Hypernuclei

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- I met Peter for the first time at the beginning of the 2000's in one of the SNNS meetings organized here in Orsay, maybe in the one of photo, and saw him for the last time in Catania in October/November 2019
- In these almost 20 years I had the chance to meet him in many other meetings but, unfortunately, not the one to work and collaborate with him

SNNS, IPN Orsay 2006

This work in few words

- We employ a feed-forward ANN to extrapolate at large model spaces the results of *abinitio* hypernuclear NCSM calculations for the Λ separation energy B_{Λ} of the lightest hypernuclei, obtained in accessible HO basis spaces using chiral NN, NNN & YN interactions
- Our results are in excellent agreement with those obtained using other extrapolation schemes of hypernuclear NCSM calculations, showing this that ANN is a reliable extrapolation method

Based on:



I.V. NPA 1032, 122625 (2023)

Machine Learning

Machine Learning is a branch of Artificial Intelligence whose scope is to devise algorithms able to recognize patterns in previously unseen data without any explicit instructions by an external party. Different types of ML include

Supervised Learning

Known input-output (feature-label) relations are given to the machine learning algorithm to trained it and infer a mapping therefrom. Once the model is trained based on the known data, one can use unknown data into the model to get predictions. Used for Classification & Regression problems

<u>Unsupervised Learning</u>

The output of the input training data is **unknown**. The input data is fed to the Machine Learning algorithm and is used to train the model which then is employed to search for patterns in the data. Used for Clustering & Generation problems

Reinforced learning

Given a framework of rules and goals, an agent (algorithm) learns in an interactive environment by trial and error using feedback from its own actions and experiences and it gets rewarded or punished depending on which strategy it uses. Each reward reinforces the current strategy, while punishment leads to an adaptation of its policy. Example: games such as Chess or Go







Machine Learning in Physics

Machine Learning has been applied in different areas of physics that include among others:

- Condense matter
- Statistical physics
- Cold atoms
- Quantum many-body theory
- Quantum computing
- Cosmology
- Particle physics
- Nuclear physics

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A **spectacular increase** of the number of publications related with AI or ML is observed in physical sciences in the last years

Machine Learning Applications in Nuclear Theory

Since the pioneering work of *Gazula et al., NPA 540 1 (1992)*, who employed a **feed forward neural network to study global nuclear properties across the nuclear landscape**, Machine Learning has been used to predict

- Nuclear masses & charge radii
- > α & β -decay half-lives
- Fission yields
- Fusion reaction cross sections
- Isotropic cross-sections in proton-induced spallation reactions
- > Ground and excited state energies
- Dripline locations
- > The deuteron properties
- Proton radius
- Liquid-gas phase transition
- Nuclear energy density functionals
- Neutron star EoS

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- > The nucleon axial form factor from neutrino scattering
- Extrapolation of A-body results with ANN



2003

Machine Learning Applications in Nuclear Theory

Recently, ANN have been employed to extrapolate the results of *ab-initio* nuclear structure calculations in finite **model spaces**. Particularly:

Negoita et al., PRC 99, 054308 (2019) have used a feed-forward ٠ ANN method for predicting the ground state energy and the ground state point proton root-mean-squared radius of ⁶Li training the network with NCSM results, obtained in accessible harmonic oscillator (HO) basis spaces. They showed that an ANN is able to predict correctly extrapolations of the NCSM results to very large model spaces of size $N_{max} \sim 100$.

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Similarly, Jiang et al., PRC 100, 054326 (2019) have also employed an ANN to extrapolate the ground state energy and radii of ⁴He, ⁶Li & ¹⁶O computed with the NCSM and the coupled-cluster (CC) methods.

⁴He with NCSM+NNLO_{opt}



Here we follow the work of these authors, to extrapolate at large model spaces the results of *ab-initio* hypernuclear NCSM calculations for the A separation energy B_{Λ} of the lightest hypernuclei

Machine Learning Process: General Scheme

The task of making a machine to learn is made of 2 phases



Feed-forward Artificial Neural Networks



Architecture of our ANN. The input data are the HO spacings $\hbar\omega$ and the maximum number of basis states N_{max} employed in hypernuclear NCSM calculations, whereas the output is the Λ separation energy

Numerical implementation with Python libraries Scikitlearn & Keras using a TensorFlow backend

- ANNs consist of a series of layers (input, hidden & output) each one contained a certain number of interconnected neurons
- In a feed-forward ANN, neurons do not form a cycle and the data propagates sequentially from the input to the output layer through all the hidden layers
- At each one of the N_k neurons *i* of a given layer *k*, the set of input data $\{a_i^{(k-1)}\}$ from the N_{k-1} neurons *j* of the layer *k-1* is transformed into

$$a_i^{(k)} = f\left(\sum_{j=1}^{N_{k-1}} \omega_{ij}^{(k)} a_j^{(k-1)} + b_i^{(k)}\right)$$

- ➤ f(z): activation function, introduces non-linearities on the neural network that enable it to capture complex non-linear relationships in the dataset. In this work we use a sigmoid activation function f(z)=(e^z + 1)⁻¹
 - $\omega_{ij}^{(k)}, b_i^{(k)}$: fitting parameters of the ANN. Are the *weights* of the connections between the neurons of the two adjacent layers *k*-1 & *k*, and the activation offset (*bias*) of each neuron of the layer *k*. The total number of fitting parameters n_p is

$$n_p = \sum_{k=0}^{L-2} (N_k + 1)N_{k+1}$$

The Learning Process of an ANN

The learning (or training) process of an ANN involves the minimization of a loss (also called cost or error) function (which compares the desired ouput (target) and the predicted one by the ANN) in order to obtain the optimal set of fitting parameters (weights and biases) $(W, b) \equiv \left\{\omega_{ij}^{(k)}, b_i^{(k)}\right\}$ of the network.

Choice of the loss function

In general, the **choice of the loss function depends on the type of problem** one is solving with a neural network. In this work we are solving a regression-type problem and we chose the *mean squared error* (MSE), a common choice for this kind of problems

$$L(\boldsymbol{W}, \boldsymbol{b}) = \frac{1}{N} \sum_{i=1}^{N} (\hat{y}_i(\boldsymbol{W}, \boldsymbol{b}) - y_i)^2$$

• N: number of points used in the minimization procedure

$$\hat{y}_i(\boldsymbol{W}, \boldsymbol{b}) \equiv \boldsymbol{a}_i^{(L-1)}$$
 : prediction of the ANN

• y_i : actual output oof the input data

Gradient Descent

Most of the **minimization algorithms** employed in ANN are based on the so-called **gradient descent algorithm**

<u>Idea</u>: Take repeated steps in the opposite direction of the gradient since the gradient of a multi-variable function $J(\vec{\theta})$ defines the direction of its maximum increase. One starts with a guess $\vec{\theta}_o$ and considers the sequence $\vec{\theta}_1, \vec{\theta}_2, \vec{\theta}_3, \cdots$ according to

$$\vec{\theta}_{n+1} = \vec{\theta}_n - \eta \vec{\nabla} J (\vec{\theta}_n)$$
, with $\eta > 0$



With this idea in mind the weights ω_{jk}^{l} & biases b_{j}^{l} of the network are updated at each iteration according to:

$$\omega_{jk}^l \to \omega_{jk}^l - \eta \frac{\partial L}{\partial \omega_{jk}^l}$$
, $b_j^l \to b_j^l - \eta \frac{\partial L}{\partial b_j^l}$

where η is the so-called **learning rate**, one of the **hyperparameters** of the newtwork, that controls how fast or how slow the network parameters are updated

The Backpropagation Algorithm

Backpropagation is a method used to calculate in an efficient way the gradient $\frac{\partial L}{\partial \omega_{jk}^l}$, $\frac{\partial L}{\partial b_j^l}$ of the loss function and adjust the connection weights & the biases to reduce the error during the learning process.



- Input x: set the corresponding activation $a_i^1 = x_i$ for each neuron *j*-th of the input layer
- Feedforward: for each layer $l = 2, 3, \dots, L$ compute $z_j^l = \sum_k \omega_{jk}^l a_k^{l-1} + b_j^l$ and $a_j^l = f(z_j^l)$
- Output error δ_j^L : compute the error of each neutron of the last layer L, $\delta_j^L = \frac{\partial L}{\partial a_i^L} f'(z_j^L) = \frac{\partial L}{\partial \hat{v}_i} f'(z_j^L)$
- Backpropagate the error: for each layer $l = L 1, L 2, \dots, 2$ compute $\delta_j^l = \sum_k \delta_k^{l+1} \omega_{kj}^{l+1} f'(z_j^l)$
- Gradient of the loss function: $\frac{\partial L}{\partial \omega_{ik}^l} = \delta_j^l a_k^{l-1}$, $\frac{\partial L}{\partial b_j^l} = \delta_j^l$
- Update the weights & biases: $\omega_{jk}^l \to \omega_{jk}^l \eta \frac{\partial L}{\partial \omega_{ik}^l}$, $b_j^l \to b_j^l \frac{\partial L}{\partial b_i^l}$
- Repeat till convergence is achieved

Overfitting of an ANN



Strategies to avoid overfitting include among others:

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- <u>early stopping</u> of the training: stops the training process once the model performance stops improving on the validation dataset
- <u>dropout</u>: reduce overfitting by dropping randomly neurons from the neural network during training in each iteration
- In addition to these which can be used together, overfitting can be reduced by:
 - enlarging the input dataset (specially in those case where the input dataset is not large enough)
 - adding noise to the input dataset making the network less able to memorize data patterns since they change randomly during the training

- A major issue in the development of an ANN is overfitting (also known as overtraining), which basically means that the network, due to its high flexibility to approximate complex non-linear functions, tries to fit the data entirely and ends up memorizing all the data patterns.
- Due to overfitting the predictability of the network on testing data becomes questionable

Input Dataset

We employ as input dataset the hypernuclear NCSM results of Gazda *et al.* (PRC 97 (2018) 064315, Few-Body Syst. 62 (2021) 94) for the Λ separation energy of ${}^{3}_{\Lambda}$ H, ${}^{4}_{\Lambda}$ H & 4_{Λ} He obtained with chiral NN & NNN interactions at N³LO and N²LO, respectively both with a regulator cutoff of 500 MeV, and YN potentials at LO with a cutoff of 600 MeV



• Due to the small size of the original input dataset to avoid overfitting we have:

- \triangleright enlarged it by performing a cubic interpolation in the HO spacing $\hbar\omega$ at each given value of N_{max}
- > introduced a Gaussian noise in the enlarged input dataset during the training of the network
- We use the 80% (10 % of it used for validation) of the enlarged input dataset to train the network and leave the 20% of it for testing

Performance of the ANN



To illustrate the performance of the network we show the loss function L(W, b) of the training & test datasets as a function of the number of iterations in the calculation of the Λ separation energy of the ground state of ${}_{\Lambda}^{3}H$

- Very fast decrease during the first 500 iterations becoming (on average) essentially constant at about 1000 iterations and above it
- The loss function of the test dataset is smaller that that of the training one, indicating that overfitting has been substantially reduced
- Similar good performance for ${}^{4}_{\Lambda}$ H and ${}^{4}_{\Lambda}$ He

A General Comment



- A typical run of an ANN starts with random values of the weights & biases of the network.
- The random inizialization of the weights & biases is not accidental but an important feature of the network training that introduces a certain degree of stochasticity that reduces the risk that during the optimization process of the network parameters it gets stuck in a local minimum
- Consequently, different runs of the ANN lead to slightly different results as seen in the figure
- Because of this, for each hypernucleus, we have performed 100 independent runs of the ANN and taken the average and the standard deviation of all these runs ad the predictions of the network and their corresponding error, respectively

Statistical distribution of the results for the Λ separation energy B_{Λ} of the ground state of ${}^{3}_{\Lambda}H$ predicted by 100 independent runs of the ANN for an HO spacing $\hbar\omega = 10$ MeV and a model space size $N_{max} = 100$. The continuous line shows a Gaussian fit of the histogram.

A separation energy of the ground state of ${}^3_{\Lambda}$ H



Open circles in the right panel show the NCSM results used for the training of the ANN

- Slow convergence due to the extremely weak binding energy of $^{3}_{\Lambda}$ H
- Considerably reduction of the B_{Λ} dependence with $\hbar\omega$ with the increase of N_{max}
- Good extrapolation to the experimental result for large values of the model space size N_{max}

ANN prediction for $N_{max} = 100$

 $B_{\Lambda}({}^{3}_{\Lambda}H) = 0.16 \pm 0.02 \text{ MeV}$

A separation energy of the 0⁺ & 1⁺ states of ${}^{4}_{\Lambda}H$ & ${}^{4}_{\Lambda}He$

 $B_{\Lambda}(^{4}_{\Lambda}He(1^{+})) = 1.33 \pm 0.11 \text{ MeV}$



 $B_{\Lambda}(^{4}_{\Lambda}H(1^{+})) = 1.35 \pm 0.16 \text{ MeV}$

• Faster convergence than in the $^{3}_{\Lambda}H$ case. Good convergence already for $N_{max} \gtrsim 25$

- Well extrapolation of the ANN prediction for the 0^+ state of ${}^4_{\Lambda}$ He to the experimental value
- ANN prediction for the 0^+ & 1^+ states of ${}^{4}_{\Lambda}H$ & 1^+ of ${}^{4}_{\Lambda}He$ off of the experiment by about 0.3 MeV. This should not be attributed to the performance of the ANN but to the Hamiltonian used & the symmetries assumed in the NCSM calculations
- Charge symmetry breaking (CSB) in these two A=4 mirror hypernuclei not explained because CSB effects are not included in the NCSM calculations used to train the ANN. Therefore, the ANN cannot account for them

Convergence of the extrapolated results of the 0^+ & 1^+ states at N_{max}=100



To further check the convergence of the extrapolated value of B_{Λ} for the 0⁺ & 1⁺ states of $^{4}_{\Lambda}H & ^{4}_{\Lambda}He$ at N_{max} =100 we show the statistical distributions of the results of 100 independent runs of the ANN for several choices of the maximal value of N_{max} taken into account in the training dataset

We observe that:

- The dispersion of the ANN predictions becomes narrower & narrower when the maximal value of N_{max} included in the training dataset increases
- Successive extrapolates are consistent consistent with the previous ones within the given uncertainties

From this one can conclude that the extrapolated values of B_{Λ} for the two states of both hypernuclei show a rather well convergence in terms of the maximal value of N_{max} included in the training dataset, being this an indication that ANN are a reliable method to extrapolate the results of hypernuclear NCSM calculations to large model spaces

Comparison with other extrapolation schemes

The main goal of this work is mainly focused on discerning whether ANN is a reliable scheme to extrapolate NCSM results at larger model spaces rather than its accuracy on reproducing the experimental results. To such end we compare our results with the extrapolated ones of Htun *et al.*, FBS 62 (2021) 94 [1] & Wirth *et al.*, PRC 97 (2018) 064315 [2]

| Hypernucleus | ANN Prediction | Extrapolated results of [1] & [2] | Experimental Vaue |
|--------------------------------------|-----------------------|--------------------------------------|--------------------------|
| $^{3}_{\Lambda}$ H (g.s.) | 0.16 ± 0.02 | 0.158 [1] | 0.13 ± 0.05 |
| $^4_{\Lambda}\text{H}(0^+)$ | 2.49 ± 0.05 | 2.48 ± 0.04 [2] | 2.157 ± 0.077 |
| $^4_{\Lambda}\text{H}(1^+)$ | 1.35 ± 0.16 | 1.40 ± 0.28 [2] | 1.067 ± 0.08 |
| $^{4}_{\Lambda}$ He(0 ⁺) | 2.43 ± 0.06 | 2.45 ± 0.04 [2] | 2.39 ± 0.05 |
| $^{4}_{\Lambda}$ He(1 ⁺) | 1.33 ± 0.11 | 1.34 ± 0.28 [2] | 0.984 ± 0.05 |

As it is seen our results are in excellent agreement with those of Htun *et al.* & With *et al.*, confirming this that ANN is a reliable method to extrapolate results of hypernuclear NCSM calculations to large model spaces

Summary & Conclusions

- We employ a feed-forward ANN to extrapolate at large model spaces the results of *ab-initio* hypernuclear NCSM calculations for the Λ separation energy B_{Λ} of the lightest hypernuclei, obtained in accessible HO basis spaces using chiral NN, NNN & YN interactions
- The overfitting problem is avoided by enlarging the size of the input dataset & by introducing a Gaussian noise during the training process of the neural network
- We find that a network with a single hidden layer of eight neurons is enough to extrapolate correctly the value of B_{Λ} to model spaces of size $N_{max}=100$
- Our results are in excellent agreement with those obtained using other extrapolation schemes of hypernuclear NCSM calculations, showing this that ANN is a reliable extrapolation method

Future Perspectives

- Compare the ANN results with those obtained with other extrapolation schemes such that of infrared extrapolation (IR) where the model space parameter $\hbar\omega \& N_{max}$ are translated into an IR length scale L_{eff} and an ultraviolet (UV) cutoff scale Λ_{UV}
- Analyze the ANN performance, particularly the convergence of the ANN results, on heavier hypernuclei

 \diamond You for your time & attention

Daniel Gazda for providing me with the NCSM results used to train the ANN

♦ Specially, Peter for his tremendous scientific legacy

