

Time Synchronization Scheme for the Hyper-Kamiokande experiment

IN2P3-IRFU-INFN

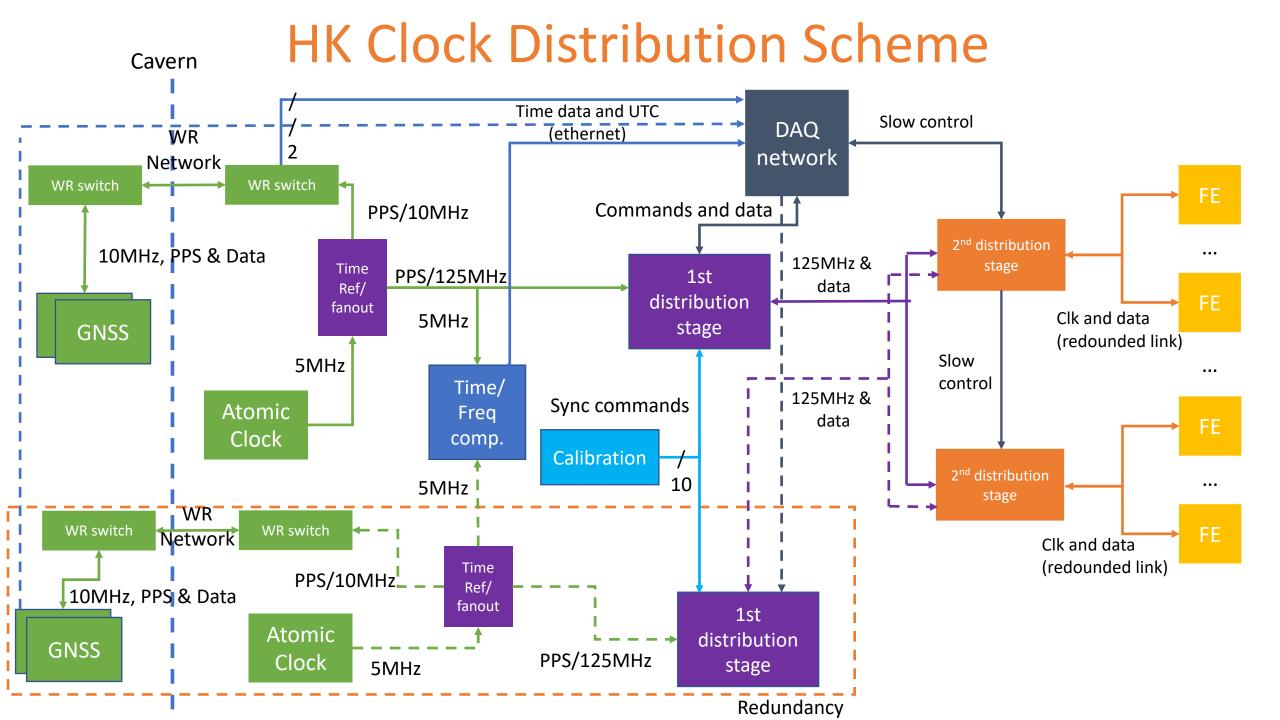
Context

LPNHE, CEA and INFN have joined forces to design a full time distribution scheme that has been submitted to the international collaboration in April 2022. The group will be in charge of its construction, commissioning and maintenance.

The proposal envisions to provide a system that fulfills the needs of the HK far detector. Possible synergies could be found with the time generation system at JPARC, the Intermediate Water Cherenkov detector and the future ND280 upgrades (when integrated in HK).

To conceive this proposal, an intense and fruitful R&D campaign has been carried out. The designed time distribution system meets all the far detector requirements.

This program takes advantage of the experience that group members have acquired in designing similar systems for other experiments and of a very fruitful collaboration with the SYRTE lab (Observatoire de Paris) responsible for the French UTC implementation.



HK Clock Distribution Scheme Cavern Time data and UTC Slow control DAQ (ethernet) WR network Network WR switch Commands and data PPS/10MHz 10MHz, PPS & Data 125MHz & Time PPS/125MHz 1st Ref/ data distribution fanout Clk and data 5MHz stage **GNSS** (redounded link) Slow 5MHz Time/ 125MHz & Sync commands Atomic Freq data Clock comp. Calibration 10 5MHz WR Network Clk and data (redounded link) Time PPS/10MHz Ref/ 10MHz, PPS & Data fanout 1st Atomic distribution **GNSS** PPS/125MHz Clock stage 5MHz Redundancy

The Clock Generation & UTC Conceptual Scheme

- The local time is generated (by a precise atomic clock) in the form of 5MHz (HK local time).
- The time reference point custom board receives this frequency, generates a local PPS and distributes them to the GNSSs and the first distribution stage. It has extra ports to compare the main and spare base cadence.
- The first distribution stage produces the clock which is sent via the second stage to the FE.
- The events will be tagged with the HK local time and converted in UTC by the DAQ. A correction algorithm will be applied to compensate the atomic clock drift.

Time Base and UTC Characterization

All the main chain components have been purchased and an extensive test campaign has been performed to precisely characterize the

proposed scheme

At LPNHE we have:

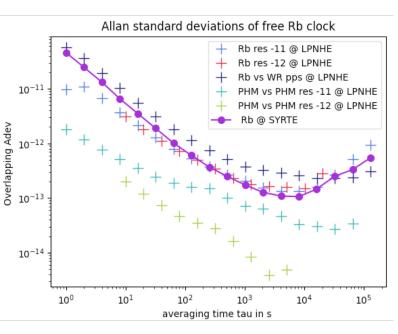
- 2 SRS SF725 Rubidium atomic clocks
- 2 Septentrio PolaRx5TR receivers + antennas
- 2 clock and Frequency counter Keysight 53220
- 1 PH1008 Passive Hydrogen Maser Atomic clock



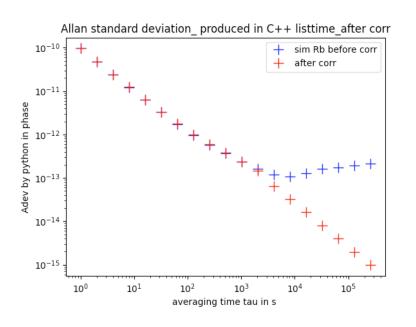


We have also a copy of the UTC(OP) PPS and 10MHz clock sent via white Rabbit link from the SYRTE laboratory (where it is produced). This is very important time reference for comparative analysis.

Time Base and UTC Characterization Results and correction studies



Measured performances of the atomic clocks and GNSS receivers

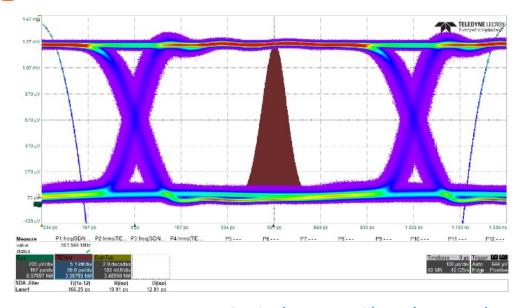


Simulated stability of the local time base after UTC conversion and correction

- The work on the correction algorithm is progressing and we are planning to test it on real data in the next 6 months.
- Tests at HK and JPARC site are under discussion. We hope to perform them by March 2023.
- The local time base to UTC and JPARC site expected uncertainty is about 10 ns (100 ns required).
- More detail in the L. Mellet talk https://hkdbweb.in2p3.fr/doc/meetingfiles/A00004681/Clockstudies_HKpremeeting.pdf

First Clock Distribution Stage Board Demonstrator





Principles

- Generic board for R&D on clock distribution based on Trenz SoC with Xilinx UltraScale+ FPGA
- Command interpreter on SoC (bare metal, Linux in final system) + Gbit Ethernet link to control PC
- Mezzanine card interfaces to external reference master clock

Optical out – 1 Gbps data mode

Rj = 11 ps and Dj < 13 ps

Current results

- 48 TX ports tested in pure clock distribution mode, modulated clock mode and classical serial data transmission. Runs up to 1 Gpbs and shows low jitter Rj typ. ~10 ps Dj typ. <20 ps
- Stability of input to output latency at level of 10 ps after board power cycling, and comparable stability of relative phase alignment between different optical outputs
- 48 RX ports tested for 125 MHz clock feed back reception. Logic based on DDMTD technique being implemented to measure stability of distributed clock via round-trip latency monitoring

 Work performed by CEA-IRFU D. Calvet and E. Molina

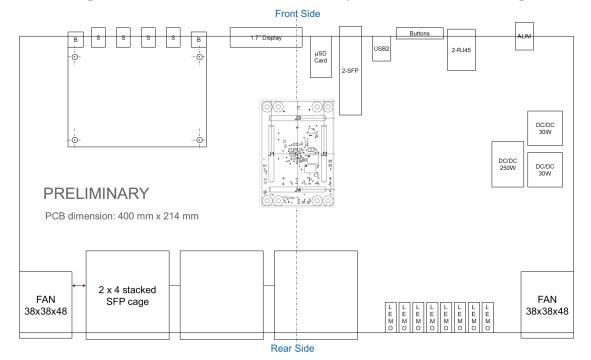
First Clock Distribution Stage Board Next Steps

48-port demonstrator – exploitation

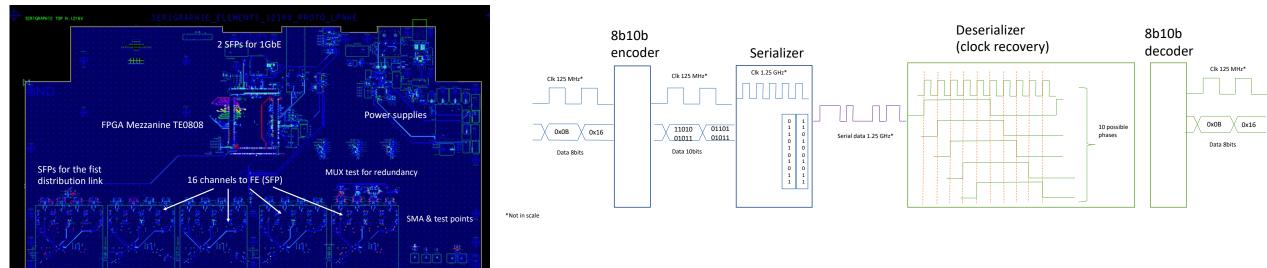
- Continue firmware/software functionality developments and device characterization
- Incorporate clock mezzanine card production suffered delays; board now expected mid-nov
- Validate specific blocks and various concepts as much as possible

1st stage clock distributor prototype – in design

- Same concept architecture as 48-port prototype and re-use of many of its validated parts.
- Lower density of 24-ports allowable by the use of passive optical splitter in the TX direction and because only a small fraction of 2nd stage distributors will have a return optical link to the 1st stage

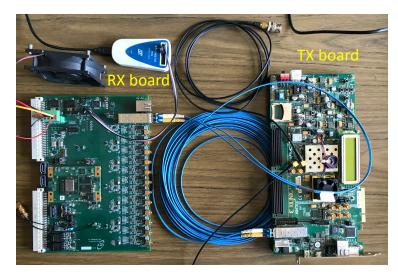


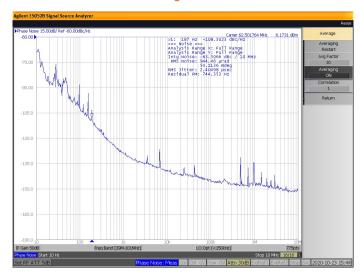
Second Clock Distribution Stage Board Concept



- The board receives the clock from the first stage and transmits the it to the time distribution endpoint in the front-end embedded into data via optical fiber.
- The main element is an FPGA with embedded processors mounted on Trenz module TE0808.
- It runs a custom firmware and software working under a Linux OS (Debian).

Second Clock Distribution Stage Board Tests and Next Steps





Jitter measured at the Endpoint = 2.4ps

- Clock and data distribution have been tested with EVBs and already available boards. The jitter at the endpoint has been measured at 2.4 ps (requirement 100 ps) after a PLL jitter cleaner.
- The firmware and software development continues on EVB and it will be ported on the first prototype as it arrives. The porting time will be very short due to the high compatibility of the two systems.
- Tests will be then performed against the DPB prototypes already in our possession (thanks to C. Toledo and M. Ziembicki)

• To absorb long delay on procurement a tender for the final production mezzanine purchase has been done. The process will be finalized by mid November.

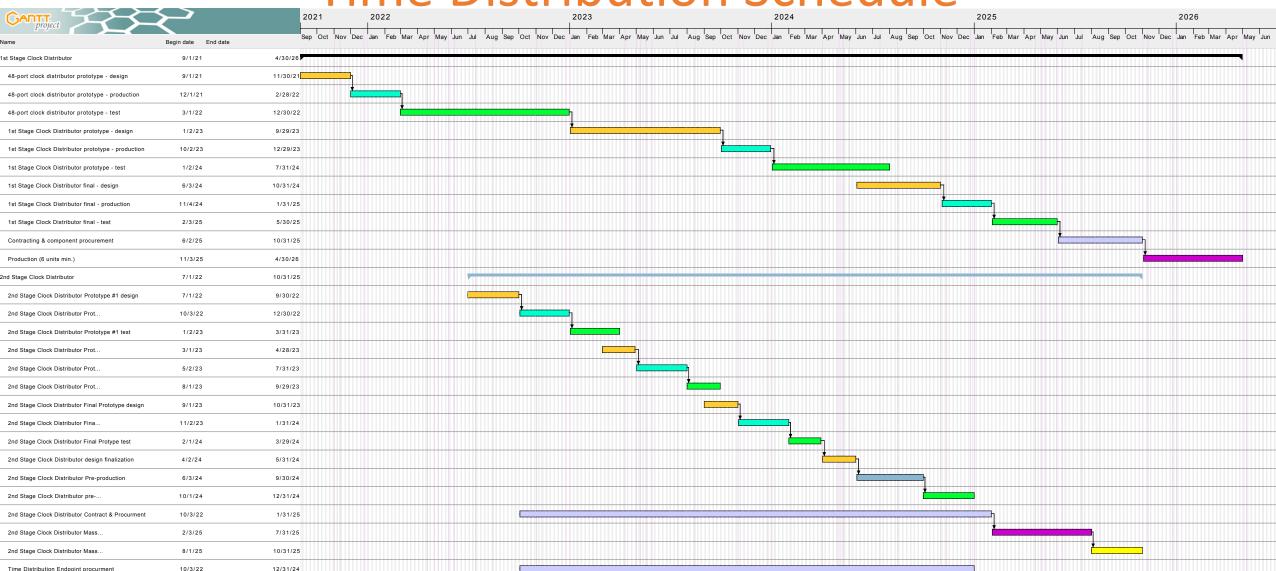
Work performed by LPNHE and INFN (s. russo and F. Ameli)

Time Distribution Endpoint

- The time distribution endpoint will be embedded in the Data Processing Board.
- We support the DPB development providing firmware/hardware IPs and components.
- A full chain composed from the second distribution stage, the DPB and digitizer
 will be installed at CERN as soon as a suitable space will be available
 (negotiations started).
- To absorb long delay on procurement a tender for the final production SFP transceivers purchase has been done. The process will be finalized by mid November.

 Work performed by LPNHE and INFN (s. russo and F. Ameli)

Time Distribution Schedule



The work is on schedule. The production is expected to be concluded in time for the assembly and commissioning in Japan

Summary

- A great synergy and collaboration has been established between IN2P3, CEA, INFN.
- The full time distribution scheme has been designed.
- Test and characterization campaigns on different subsystems have been carried out.
- First prototypes have been designed and are ready/fabricated now.
- The system will be tested together with the DPB and digitizer soon

Clock Generation & UTC - Connections

- The local time is generated (by a precise atomic clock) in the form of 5MHz in synch to each other (HK local time).
- The time reference point custom board receives the frequency, generate a local PPS and distributes them to the GNSSs and the first distribution stage. It has extra ports to compare the main and spare base cadence.
- GNSSs use the input cadence to sync the outputs and have a reference frequency more stable than the internal oscillator

Clock Generation & UTC - Connections

- 2 GNSSs receivers (connected to the same antenna) get information from the satellites and measure the time distance between the local PPS and UTC.
- The result of this measure is sent to DAQ and used to transform the local tag to UTC
- The DAQ monitors the status of the GNSSs and select which one to use

Clock Generation & UTC - Redundancy

- The full chain (atomic clock, GNSSs (x2), and first distribution stage) is replicated for redundancy
- Having a total of 4 GNSS receivers will allow the DAQ to identify if one is malfunctioning. Extra different brands receivers will be also used.
- The time distance between the 2 chains will be constantly measured and the result sent to DAQ. This info will be used in case of switch from one chain to the other

Clock Generation & UTC - Reliability

- Scheduled interventions on components will be performed to reduce the risk of failures
- A third atomic clock will be available at far detector site and periodically turned on. It will serve as cold spare used if the main or the hot spare needs maintenance
- All the atomic clocks will be measured against the so-called travelling station every 3 / 4 years.
- The GNSS receivers will be changed before the end of life.
- The maintenance cost needs to be included in the budget request

Septentrio PolaRx5TR calibration

Our receiver (RINEX name: LPN1) was calibrated against one at Observatoire de Paris (OP73) in turn calibrated against a travelling station from Bureau International de Poids et de Mesures (BIPM, responsible of defining UTC). OP73 is then a so-called level 1 receiver and LPN1 has been calibrated as a level 2.

The receiver internal delays were measured for both GPS and Galileo constellations.

The combined uncertainty of the LPN1 station hardware delays calibration is 4 ns. This is the conventional uncertainty applied after a "direct calibration" in the TAI system.

Septentrio PolaRx5TR calibration

The two tables correspond to GPS (P1 and P2 codes) and Galileo (E1 and E2a) codes.

Receiver	Reference	MJD of Measurement	REFDLY	CABDLY	P1 DLY	TDEV	P2 DLY	TDEV
OP73	Ref	59508 – 59514	85.2	129.6	29.500	NC	26.300	NC
LPN1	OP73	59508 – 59514	88.3	127.1	25.832	0.024	22.871	0.022

Receiver	Reference	MJD of Measurement	REFDLY	CABDLY	E1 DLY	TDEV	E5a DLY	TDEV
OP73	Ref	59508 – 59514	85.2	129.6	31.700	NC	31.300	NC
LPN1	OP73	59508 – 59514	88.3	127.1	28.242	0.040	25.431	0.034

The values will be configured in the receiver and a correction will be applied to the UTC time. Mixing the two constellations' data will be done to provide the UTC time.

Time Base and UTC Characterization

The work on the time base characterization continues and an extensive test campaign is ongoing (thanks mainly to Lucille Mellet, Vincent Voisin and Mathieu Guige).

Most of the results are summarized here:

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https://indico-sk.icrr.u-tokyo.ac.jp/event/7332/contributions/22011/attachments/20557/26254/LPNHE_timingsystem_R%26D.pdf
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I give just a quick recap:

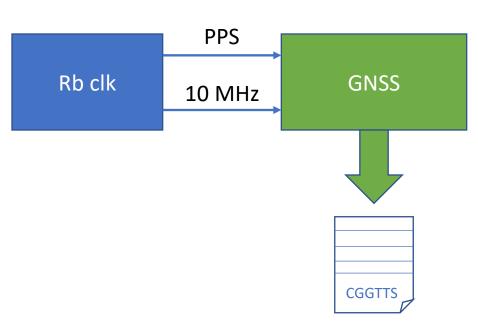
Kind of Test Performed

We basically perform 2 kind of tests:

- Local time base characterization. Test our proposed concept on real hardware
- Time transfer via common view: a method to measure two local time bases using the GNSS data. This method is implemented using the files published regularly by UTC(k) labs (Syrte in our case).

Local Time Base Characterization

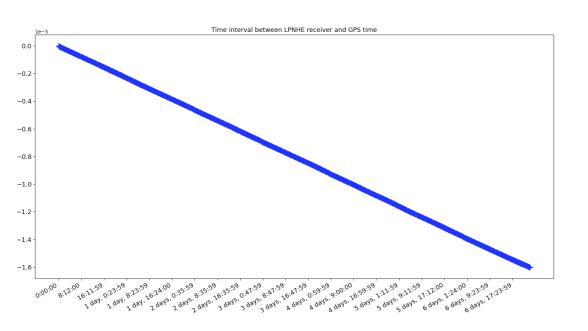
For this test we use 1Rb clock sending 1 PPS and 10 MHz clock to the Spetentrio receiver. Thanks to the time transfer algorithm, we can estimate the drift of our local time base with respect to GNSS time (only GPS in this case)

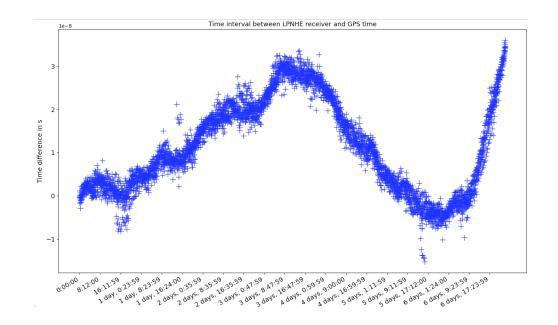


CGGTTS file with time distance Between local time and GPS time

```
GENERIC DATA FORMAT VERSION = 2E
REV DATE = 00-00-000
RCVR = PolaRx5TR (5.3.2)
                              SN3222543
CH = 80
IMS = PolaRx5TR
LAB = LPNHE
X = 4201670.132 m
Y = 172825.507 m
Z = 4779558.436 \text{ m}
FRAME = ITRF
COMMENTS = LS=18; ElMask=Odeg;
INT DLY = 25.8 \text{ ns} (GPS P1), 22.9 \text{ ns} (GPS P2)
                                                    CAL_ID = Calibration at OP vs OP73
CAB DLY = 505.0 ns
REF DLY = 0.0 \text{ ns}
REF = SRS
CKSUM = Ob
                                      REFSV
                                                 SRSV
                                                           REFSYS
                                                                            DSG IOE MDTR SMDT MDIO SMDI MSIO SMSI ISG FR HC FRC CK
                                       .1ns
                                                 .1ps/s
                                                                     1ps/s .1ns
                                                                                      .1ns.1ps/s.1ns.1ps/s.1ns.1ps/s.1ns
                                                            .1ns
                                       6018322
                                                  -271
                                                            -513936
G02 FF 59693 001800
                     780 452 2678
                                                                                                      13 102
                     780 166 700
                                        1219828
                                                  -282
                                                            -513956
                                        279947
                                                  -180
                                                            -513955
                                                                                                139
G05 FF 59693 001800
                     780 183 3026
                                       -3291323
                                                  -407
                                                            -513924
                     780 625 1419
                                       -3723689
                                                  -282
                                                            -513929
G09 FF 59693 001800
                     780 505 677
                                        2902993
                                                  -274
                                                            -513932
G16 FF 59693 001800
                     780 118 411
                                        4432147
                                                  -121
                                                            -513927
G20 FF 59693 001800
                     780 460 3001
                                       -5670792
                                                            -513930
                     780 76 3256
                                        4549643
                                                  -265
                                                            -513933
G30 FF 59693 001800 780 430 1808
                                        4737062
                                                  -227
                                                            -513927
                                                                                           -17 108
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Local Time Base Characterization

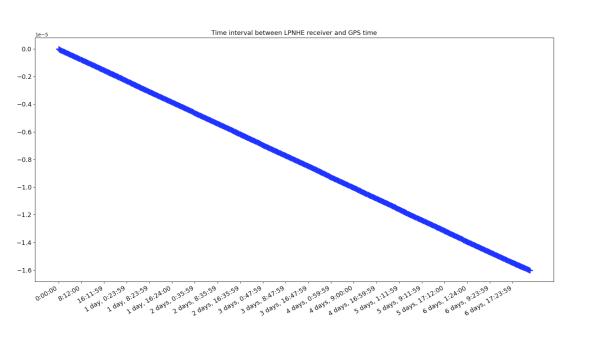


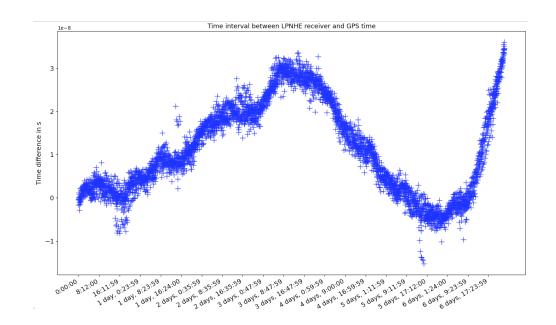


The "raw" plot (left), as produced from the receiver, shows a liner drift, as expected for the Rb clock. Once removed we can see that the clock "noise".

(from Lucille's talk cited before)

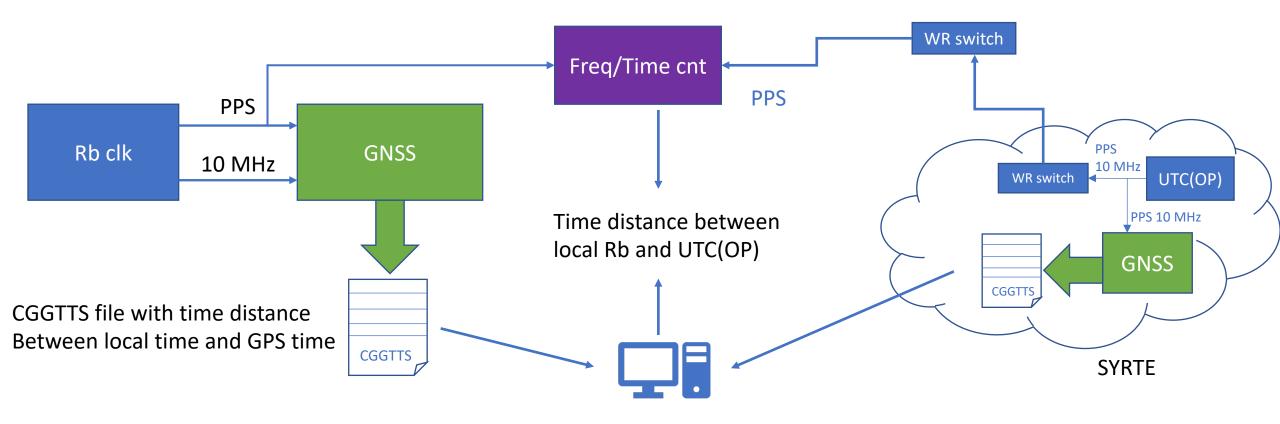
What Do We Do With It?





Extracting the drift from the left plot will allow us to precisely correlate the local time base (used to time tag the events) to GNSS time. Once done we can calculate the uncertainty on it (right plot). In this case is about 4 ns over 6 days (random walk).

How Accurate Is This Method?

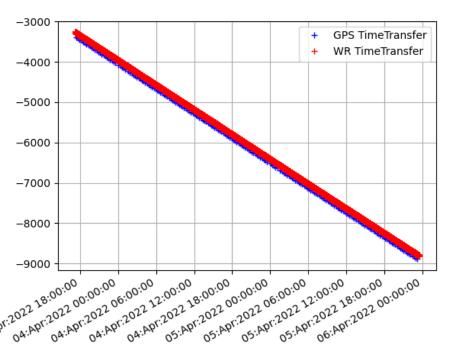


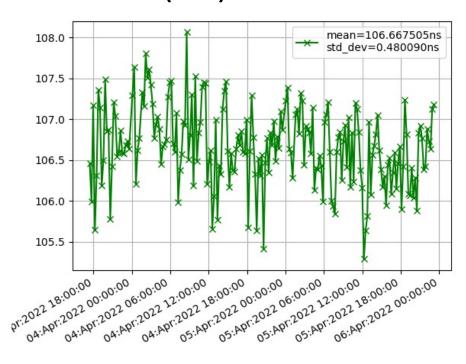
To evaluate our drift estimation method, we have done the following measure:

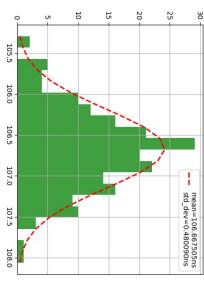
- We have created a CGGTTS form the GNSS steered by Rb clock (as before).
- Then we have used the time transfer technique to measure the time distance between our Rb clock to SYRTE UTC(OP) via common view method.
- Finally, we have compared this time distance with the one measured via the counter.

How Accurate Is This Method?

Time distance between local Rb and UTC(OP): Common view vs White Rabbit







Local time base/ UTC(OP) Via common mode (blue)

Local time base/ UTC(OP) Via white rabbit (red)

Common view method/WR method difference +/- 3 ns max

Histogram of the difference Sigma = 0.48 ns

(same slope as before)

3 days of data. X axis: local time Y axis: ns

Vincent Voisin work