

# Photometric Correction with Forward Global Calibration Model in the context of DM Rubin-LSST science pipeline

matter of discussion for the LSST France parallel session

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November 29, 2022





- Sources/Object standard magnitude estimation from instrumental magnitude → allowing coaddition of single epoch measurements
- use of time dependent epoch transmissions (instrument + atmosphere)
- photometric correction depending on poorly known objects SED
- to be implemented inside DM Rubin-LSST science pipelines
- participation of DESC technical groups (SAWG, PCWG, PSF), namely during commissioning phase,
- need participation of Science groups (PhotoZ, and objects groups like SN, and other astrophysical groups),



- 1 Key formula, definitions and notations
  - Instrumental Flux
  - Observed Magnitude
  - Standard Magnitude
  - Approximation for SED shape
  - Summary of definitions on interpretable standard magnitude
  - SED shape correction
  - Bias on Magnitude for SED shape correction
  - What is FGCM in DES&LSST ?
- 2 LSST Rubin science pipelines
- 3 Simulation of the photometric corrections
  - Atmospheric simulation and  $S_b^{obs}$
  - The zero's order of the photometric correction
  - The 1st and 2nd orders Integral differences



## Photometric flux of a source

$$ADU_b = \frac{A\Delta T}{gh} \int_0^\infty F_\nu(\lambda) \times S_b^{obs}(\lambda, x, y, az, alt, t) \frac{d\lambda}{\lambda} \quad (1)$$

- $ADU_b$  : ADU count of a source measured by photometry in band  $b$
- $F_\nu$  : SED in  $\text{erg}/\text{cm}^2/\text{Hz}/\text{s}$
- $S_b^{obs}$  : Observation transmission in band  $b$  (atmosphere + instrument)
- $A$  : Collection efficiency in  $\text{cm}^2$
- $g$  : Electronic gain in  $e^-/\text{ADU}$
- $\Delta T$  : Exposure time
- $h$  : Planck constant



## Observed Magnitude of a source

$$m_b^{obs} = -2.5 \log_{10} \left( \frac{\int_0^\infty F_\nu(\lambda) \times S_b^{obs}(\lambda, x, y, az, alt, t) \frac{d\lambda}{\lambda}}{\int_0^\infty F^{AB} \times S_b^{obs}(\lambda, x, y, az, alt, t) \frac{d\lambda}{\lambda}} \right) \quad (2)$$

- $m_b^{obs}$  : observed magnitude in band  $b$
- $F_\nu$  : SED in  $\text{erg}/\text{cm}^2/\text{Hz}/\text{s}$
- $F^{AB} = 3631 \text{ Jy}$  : Flat SED with  $1 \text{ Jy} = 10^{-23} \text{ erg}/\text{cm}^2/\text{Hz}/\text{s}$
- $S_b^{obs}$  : Observation transmission in band  $b$  (atmosphere + instrument)

In the above formula gives how the physics provides  $m_b^{obs}$ . However usually the  $F_\nu(\lambda)$  of an object is unknown. Note  $m_b^{obs}$  is defined independently of any reference to a standard magnitude.



# Natural magnitude in Rubin-LSST

Rubin-LSST usually use the concept of normalized passband

## normalized bandpass response function

$$\phi_b^{obs}(\lambda, t) = \frac{S_b^{obs}(\lambda, t) \frac{1}{\lambda}}{\int_0^\infty S_b^{obs}(\lambda, t) \frac{d\lambda}{\lambda}} \quad (3)$$

## Observed flux

$$F_b^{obs} = \int_0^\infty F_\nu(\lambda) \phi_b^{obs}(\lambda) d\lambda \quad (4)$$

## Natural magnitude

$$m_b^{nat} = -2.5 \log_{10} \left( \frac{F_b^{obs}}{F_{AB}} \right) \quad (5)$$

The natural magnitude  $m_b^{nat}$  is similar to the observed magnitude  $m_b^{obs}$



## Decomposition of observed Magnitude

The observed magnitude is estimated from the measured ADU counts rate  $C_b = ADU_b/\Delta T$  in filter  $b$

$$m_b^{obs} = -2.5 \log_{10}(C_b) + 2.5 \log_{10} \left( \mathbb{I}_0^{obs}(b) \right) + ZPT^{AB} \quad (6)$$

However the two following quantities which depend on atmospheric + detectors conditions must be estimated by calibration.

Calibration quantities:

$$\mathbb{I}_0^{obs}(b) \equiv \int_0^\infty S_b^{obs}(\lambda) \frac{d\lambda}{\lambda} \quad (7)$$

$$ZPT^{AB} \equiv 2.5 \log_{10} \left( \frac{AF^{AB}}{gh} \right) \quad (8)$$



Note sometimes one defines the zero point as the magnitude  $m_b^{obs}$ , such  $ADU_b/\Delta T = 1$  count per sec, then

$$m_b^{obs}(ZP) \equiv 2.5 \log_{10} \left( \mathbb{I}_0^{obs}(b) \right) + ZPT^{AB} \quad (9)$$

- the zero point is common to all sources whatever their color is
- it has a time dependent and passband  $b$  dependent component :  $2.5 \log_{10} \left( \mathbb{I}_0^{obs}(b) \right)$
- it has a detector (CCD) dependent component :  $ZPT^{AB}$  through the relative electronic gain  $g$ , (independent of the passband  $b$  ?, long time-scale dependence (night) ?)





## Standard Magnitude

Standard magnitude is the magnitude to be published with the standard passband. It must be calculated from the observed magnitude.

### Standard magnitude in standard passband

$$m_b^{std} = -2.5 \log_{10} \left( \frac{\int_0^\infty F_\nu(\lambda) \times S_b^{std}(\lambda) \frac{d\lambda}{\lambda}}{\int_0^\infty F^{AB} \times S_b^{std}(\lambda) \frac{d\lambda}{\lambda}} \right) \quad (10)$$

$$\delta_b^{std} \equiv m_b^{std} - m_b^{obs} \quad (11)$$

$$\equiv 2.5 \log_{10} \left( \frac{\mathbb{I}_0^{std}(b)}{\mathbb{I}_0^{obs}(b)} \right) + 2.5 \log_{10} \left( \frac{\int_0^\infty F_\nu(\lambda) \times S_b^{obs}(\lambda) \frac{d\lambda}{\lambda}}{\int_0^\infty F_\nu(\lambda) \times S_b^{std}(\lambda) \frac{d\lambda}{\lambda}} \right) \quad (12)$$



## standard magnitude

$$m_b^{std} = m_b^{nat} + \Delta m_b^{obs} \quad (13)$$

$$\Delta m_b^{obs} = 2.5 \log_{10} \frac{\int_0^\infty F_\nu(\lambda) \phi_b^{obs}(\lambda) d\lambda}{\int_0^\infty F_\nu(\lambda) \phi_b^{std}(\lambda) d\lambda} \quad (14)$$

$$\begin{aligned} \Delta m_b^{obs} = \delta_b^{std} &= 2.5 \log_{10} \left( \frac{\mathbb{I}_0^{std}(b)}{\mathbb{I}_0^{obs}(b)} \right) + 2.5 \log_{10} \left( \frac{\int_0^\infty F_\nu(\lambda) \times S_b^{obs}(\lambda) \frac{d\lambda}{\lambda}}{\int_0^\infty F_\nu(\lambda) \times S_b^{std}(\lambda) \frac{d\lambda}{\lambda}} \right) \\ &= 2.5 \log_{10} \left( \frac{\int_0^\infty F_\nu(\lambda) \times \phi_b^{obs}(\lambda) d\lambda}{\int_0^\infty F_\nu(\lambda) \times \phi_b^{std}(\lambda) d\lambda} \right) \end{aligned}$$



## Zero point definition

$$m_b^{std} = -2.5 \log_{10}(C_b^{obs}) + \Delta m_b^{obs} + Z_b^{obs} \quad (15)$$

with  $C_b^{obs} = ADU_b / \Delta T$

## Correspondence of Zero point in Rubin-DES

$$Z_b^{obs} = 2.5 \log_{10} \left( \mathbb{I}_0^{obs}(b) \right) + ZPT^{AB} \quad (16)$$



## Interpretable standard magnitude expression

option A : with zero point as unit counting rate

$$\begin{aligned}
 m_b^{std} = & -2.5 \log_{10}(C_b^{obs}) + 2.5 \log_{10} \left( \frac{\mathbb{I}_0^{std}(b)}{\mathbb{I}_0^{obs}} \right) + m_b^{obs}(ZPT) \\
 & + 2.5 \log_{10} \left( \frac{\int_0^\infty F_\nu(\lambda) \times S_b^{obs}(\lambda) \frac{d\lambda}{\lambda}}{\int_0^\infty F_\nu(\lambda) \times S_b^{std}(\lambda) \frac{d\lambda}{\lambda}} \right) \quad (17)
 \end{aligned}$$

- $-2.5 \log_{10}(C_b^{obs})$  : measured instrumental aperture photometric term (ADU rate)
- $2.5 \log_{10} \left( \frac{\mathbb{I}_0^{std}(b)}{\mathbb{I}_0^{obs}} \right)$  : SED color free correction term for atmospheric transparency standard/observed
- $m_b^{obs}(ZPT)$  : SED color free observed magnitude Zero Point correction term at CCD level,
- $2.5 \log_{10} \left( \frac{\int_0^\infty F_\nu(\lambda) \times S_b^{obs}(\lambda) \frac{d\lambda}{\lambda}}{\int_0^\infty F_\nu(\lambda) \times S_b^{std}(\lambda) \frac{d\lambda}{\lambda}} \right)$  : SED color dependent term correction



## option B : with zero point as constants

$$m_b^{std} = -2.5 \log_{10}(C_b^{obs}) + 2.5 \log_{10} \left( \mathbb{I}_0^{std}(b) \right) + ZPT^{AB} + 2.5 \log_{10} \left( \frac{\int_0^\infty F_\nu(\lambda) \times S_b^{obs}(\lambda) \frac{d\lambda}{\lambda}}{\int_0^\infty F_\nu(\lambda) \times S_b^{std}(\lambda) \frac{d\lambda}{\lambda}} \right) \quad (18)$$

- $-2.5 \log_{10}(C_b^{obs})$  : measured instrumental aperture photometric term (ADU rate)
- $2.5 \log_{10}(\mathbb{I}_0^{std}(b))$  : Calculable constant
- $ZPT^{AB} = \frac{AF^{AB}}{gh}$  : SED color free observed magnitude Zero Point correction term at CCD level (electronic gain),
- $2.5 \log_{10} \left( \frac{\int_0^\infty F_\nu(\lambda) \times S_b^{obs}(\lambda) \frac{d\lambda}{\lambda}}{\int_0^\infty F_\nu(\lambda) \times S_b^{std}(\lambda) \frac{d\lambda}{\lambda}} \right)$  : SED color dependent term correction



## option C : using normalized passband

$$m_b^{std} = -2.5 \log_{10}(C_b^{obs}) + 2.5 \log_{10} \left( \mathbb{I}_0^{obs}(b) \right) + ZPT^{AB} + 2.5 \log_{10} \left( \frac{\int_0^\infty F_\nu(\lambda) \times \phi_b^{obs}(\lambda) d\lambda}{\int_0^\infty F_\nu(\lambda) \times \phi_b^{std}(\lambda) d\lambda} \right) \quad (19)$$

- $-2.5 \log_{10}(C_b^{obs})$  : measured instrumental aperture photometric term (ADU rate)
- $2.5 \log_{10}(\mathbb{I}_0^{obs}(b))$  : order 0 correction : measured variable absorption in the band  $b$  (compensate  $C_b^{obs}$ )
- $ZPT^{AB} = \frac{AF^{AB}}{gh}$  : SED color free observed magnitude Zero Point correction term at CCD level (electronic gain),
- $2.5 \log_{10} \left( \frac{\int_0^\infty F_\nu(\lambda) \times \phi_b^{obs}(\lambda) d\lambda}{\int_0^\infty F_\nu(\lambda) \times \phi_b^{std}(\lambda) d\lambda} \right)$  : SED color dependent term correction



## SED approximation as Taylor expansion

$$F_\nu(\lambda) = F_\nu(\lambda_b) \left( 1 + f'(\lambda_b)(\lambda - \lambda_b) + \frac{f''(\lambda_b)}{2}(\lambda - \lambda_b)^2 + \dots \right) \quad (20)$$

$$f'_\nu(\lambda) \equiv \frac{1}{F_\nu(\lambda)} \frac{dF_\nu(\lambda)}{d\lambda} \qquad f''_\nu(\lambda) \equiv \frac{1}{F_\nu(\lambda)} \frac{d^2F_\nu(\lambda)}{d\lambda^2}$$

$$\lambda_b \equiv \frac{\int_0^\infty \lambda \times S_b^{inst}(\lambda) \frac{d\lambda}{\lambda}}{\int_0^\infty S_b^{inst}(\lambda) \frac{d\lambda}{\lambda}} \quad (21)$$

- $S_b^{obs}(\lambda) = S_b^{inst}(\lambda, t, x, y) \times S^{atm}(\lambda, t, alt, az)$



### Decomposition of standard magnitude

$$\begin{aligned} m_b^{std} = & -2.5 \log_{10}(C_b) \\ & + 2.5 \log_{10}(\mathbb{I}_0^{obs}(b)) + ZPT^{AB} \\ & + 2.5 \log_{10} \left( \frac{1 + f'_\nu(\lambda_b) \mathbb{I}_{10}^{obs}(b) + \frac{f''_\nu(\lambda_b)}{2} \mathbb{I}_{20}^{obs}(b)}{1 + f'_\nu(\lambda_b) \mathbb{I}_{10}^{std}(b) + \frac{f''_\nu(\lambda_b)}{2} \mathbb{I}_{20}^{std}(b)} \right) \end{aligned} \quad (22)$$





## Transmission moments definitions

$$\mathbb{I}_0^i(b) = \int_0^\infty S_b^i(\lambda) \frac{d\lambda}{\lambda} \quad (23)$$

$$\mathbb{I}_1^i(b) = \int_0^\infty (\lambda - \lambda_b) S_b^i(\lambda) \frac{d\lambda}{\lambda} \quad (24)$$

$$\mathbb{I}_2^i(b) = \int_0^\infty (\lambda - \lambda_b)^2 S_b^i(\lambda) \frac{d\lambda}{\lambda} \quad (25)$$

$$\mathbb{I}_{10}^i(b) = \frac{\mathbb{I}_1^i(b)}{\mathbb{I}_0^i(b)} \quad (26)$$

$$\mathbb{I}_{20}^i(b) = \frac{\mathbb{I}_2^i(b)}{\mathbb{I}_0^i(b)} \quad (27)$$

with  $i = obs$  or  $i = std$



## SED shape ( $f'_\nu, f''_\nu$ ) color correction

$$\begin{aligned} m_b^{std} = & -2.5 \log_{10}(C_b) \\ & + 2.5 \log_{10}(\mathbb{I}_0^{obs}(b)) + ZPT^{AB} \\ & + 1.087 \left( f'_\nu(\lambda_b) \Delta \mathbb{I}_{10}(b) + \frac{f''_\nu(\lambda_b)}{2} \Delta \mathbb{I}_{20}(b) \right. \\ & \left. - \frac{1}{2} (f'_\nu(\lambda_b) \Delta \mathbb{I}_{10}(b))^2 \right) \end{aligned} \quad (28)$$

## Moments difference definition

$$\Delta \mathbb{I}_{10}(b) = \mathbb{I}_{10}^{obs}(b) - \mathbb{I}_{10}^{std}(b) \quad (29)$$

$$\Delta \mathbb{I}_{20}(b) = \mathbb{I}_{20}^{obs}(b) - \mathbb{I}_{20}^{std}(b) \quad (30)$$



## Error on Magnitude for SED-shape correction

$$\Delta m = \left| 2.5 \log_{10} \left( \frac{\mathbb{I}_0^{std}(b)}{\mathbb{I}_0^{obs}(b)} \right) + 2.5 \log_{10} \left( \frac{\int_0^\infty F_\nu(\lambda) \times S_b^{obs}(\lambda) \frac{d\lambda}{\lambda}}{\int_0^\infty F_\nu(\lambda) \times S_b^{std}(\lambda) \frac{d\lambda}{\lambda}} \right) \right.$$
$$\left. - 1.087 \left( f'_\nu(\lambda_b) \Delta \mathbb{I}_{10}(b) + \frac{f''_\nu(\lambda_b)}{2} \Delta \mathbb{I}_{20}(b) - \frac{1}{2} (f'_\nu(\lambda_b) \Delta \mathbb{I}_{10}(b))^2 \right) \right|$$
$$\Delta m = \left| 2.5 \log_{10} \left( \frac{\int_0^\infty F_\nu(\lambda) \times \phi_b^{obs}(\lambda) d\lambda}{\int_0^\infty F_\nu(\lambda) \times \phi_b^{std}(\lambda) d\lambda} \right) \right.$$
$$\left. - 1.087 \left( f'_\nu(\lambda_b) \Delta \mathbb{I}_{10}(b) + \frac{f''_\nu(\lambda_b)}{2} \Delta \mathbb{I}_{20}(b) - \frac{1}{2} (f'_\nu(\lambda_b) \Delta \mathbb{I}_{10}(b))^2 \right) \right|$$



## Error on Magnitude for SED-shape correction

$$\begin{aligned}\Delta I_{i0}(b) &= I_{i0}^{obs}(b, z_{obs}, aer_{obs}, pwv_{obs}) - I_{i0}^{std}(b, z_{std}, aer_{std}, pwv_{std}) \\ &= \left( I_{i0}^{obs}(b, z_{obs}, aer_{obs}, pwv_{obs}) - I_{i0}^{std}(b, z_{obs}, aer_{std}, pwv_{std}) \right) + \\ &\quad \left( I_{i0}^{std}(b, z_{obs}, aer_{std}, pwv_{std}) - I_{i0}^{std}(b, z_{std}, aer_{std}, pwv_{std}) \right)\end{aligned}$$

## Linearity of corrections - standard atmosphere at different airmass

$$\Delta I_{i0}(b) = \left( I_{i0}^{obs}(b, z_{obs}) - I_{i0}^{std}(b, z_{obs}) \right) + \frac{\partial}{\partial z} I_{i0}^{std}(b, z_{std})(z_{obs} - z_{std}) + \dots$$

- $I_{i0}^{obs}(b, z_{obs})$  : measured
- $I_{i0}^{std}(b, z_{obs})$  and  $\frac{\partial}{\partial z} I_{i0}^{std}(b, z_{std})$ : from standard atmospheric model



- From a reference catalog of calibration stars  $j$  with known  $\overline{m_b^{std}(j)}$
- Optimize the following  $\chi^2$  in band  $b$  ( $i$  exposure,  $j$  star-object,  $\sigma_{phot}(i,j)$ , photometric error):

$$\chi_b^2 = \sum_{(i,j)} \frac{\left(m_b^{std}(i,j) - \overline{m_b^{std}(j)}\right)^2}{\sigma_{phot}^2(i,j)} \quad (31)$$

- With the measured magnitude in LSST is :

$$\begin{aligned} m_b^{std}(i,j) &= -2.5 \log_{10}(C_b^{i,j}) + 2.5 \log_{10}(\mathbb{I}_0^{obs,i}(b)) + ZPT^{AB}(i) \\ &+ 2.5 \log_{10} \left( \frac{1 + f'_v(\lambda_b)(b)\mathbb{I}_{10}^{obs,i}(b)}{1 + f'_v(\lambda_b)(b)\mathbb{I}_{10}^{std}(b)} \right) \end{aligned} \quad (32)$$



# Rubin-LSST science pipeline

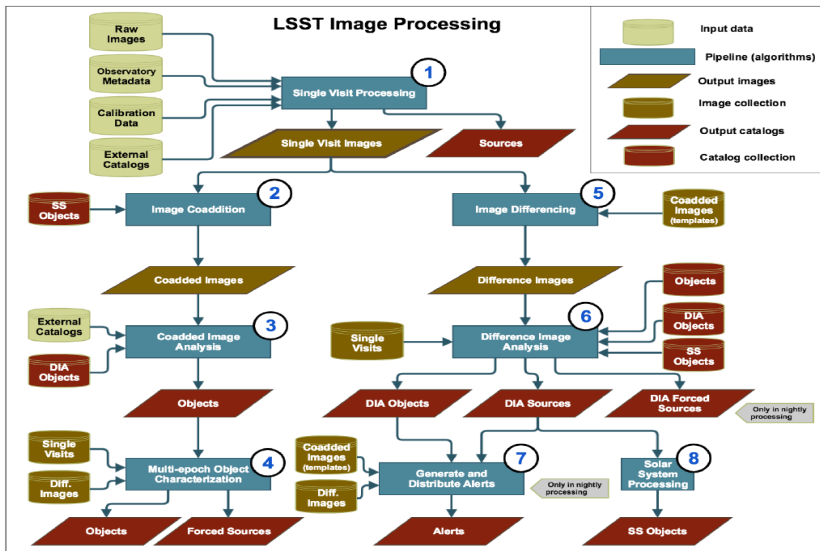


FIGURE 2: Illustration of the conceptual design of LSST science pipelines for imaging processing.



## 1 Single Visit Processing

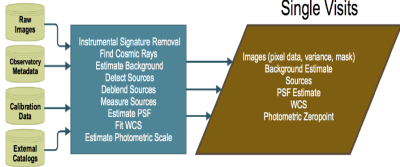


FIGURE 3: Illustration of the conceptual algorithm design for Single Visit Processing pipeline.

## 2 Image Coaddition



## 3 Coadd Image Analysis



## 4 Multi-Epoch Object Characterization

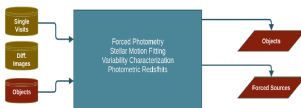
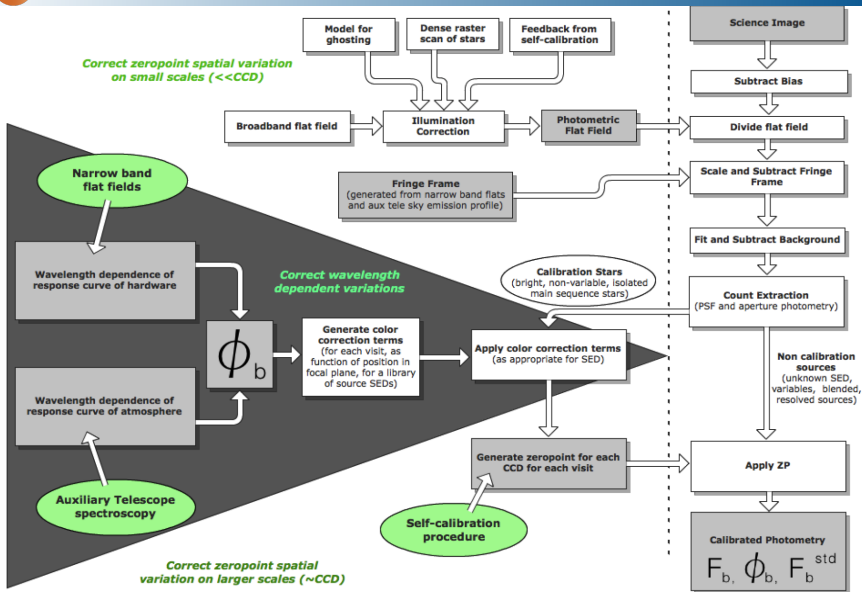


FIGURE 4: Illustration of the conceptual algorithm design for Image Coaddition, Coadded Image Analysis, and Multi-epoch Object Characterization pipelines.



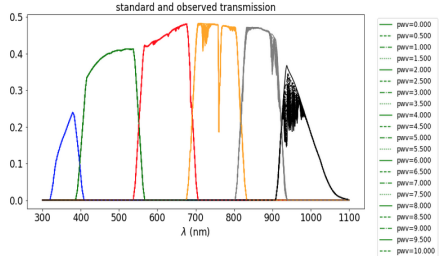
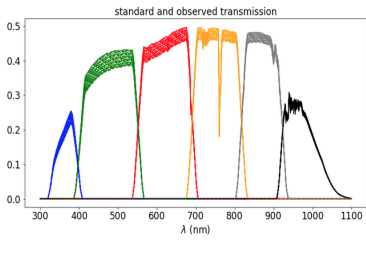
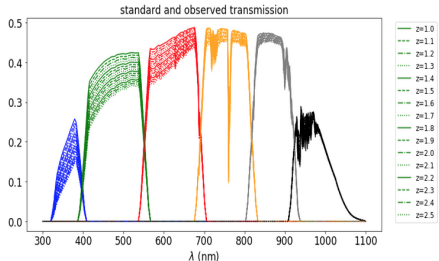
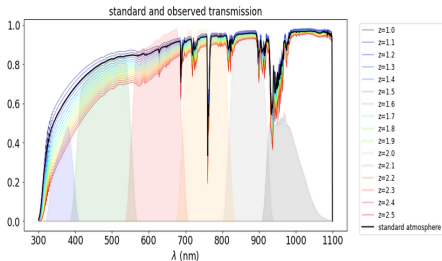
# Rubin-LSST calibration plan







# Atmospheric simulation and $S_b^{obs}$

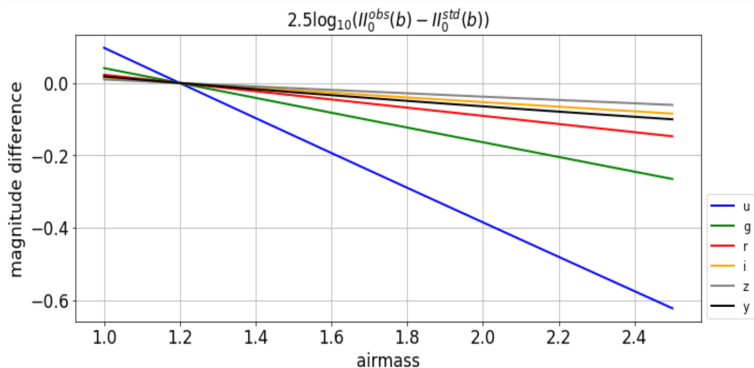




# The 0<sup>th</sup> order of the photometric correction

vs airmass, relative to the standard transmission

$$\mathbb{I}_0^{obs}(b, z) - \mathbb{I}_0^{std}(b, z_{std}) \quad (33)$$

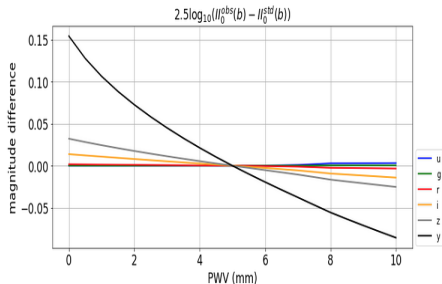
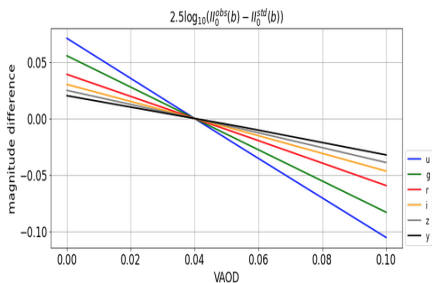




# The 0<sup>th</sup> order of the photometric correction

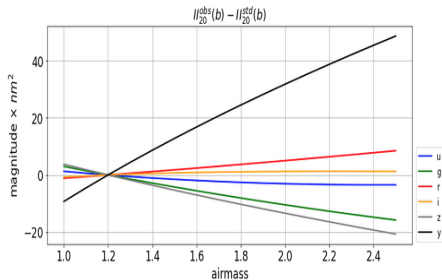
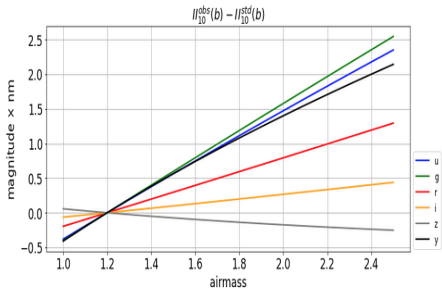
vs aeolols or PWV, relative to the standard transmission

$$\mathbb{I}_0^{obs}(b, z_{std}) - \mathbb{I}_0^{std}(b, z_{std}) \quad (34)$$





# The 1<sup>st</sup> & 2<sup>nd</sup> orders Integral differences



End of part 1