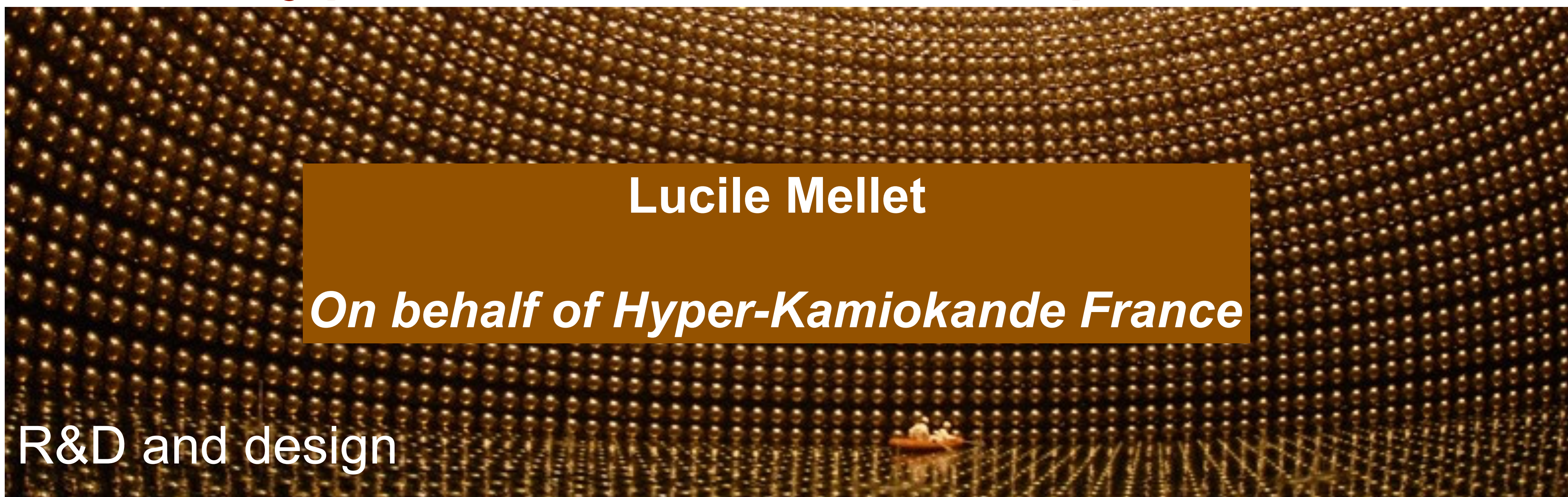


Precise time and charge digitization for the Hyper-Kamiokande experiment



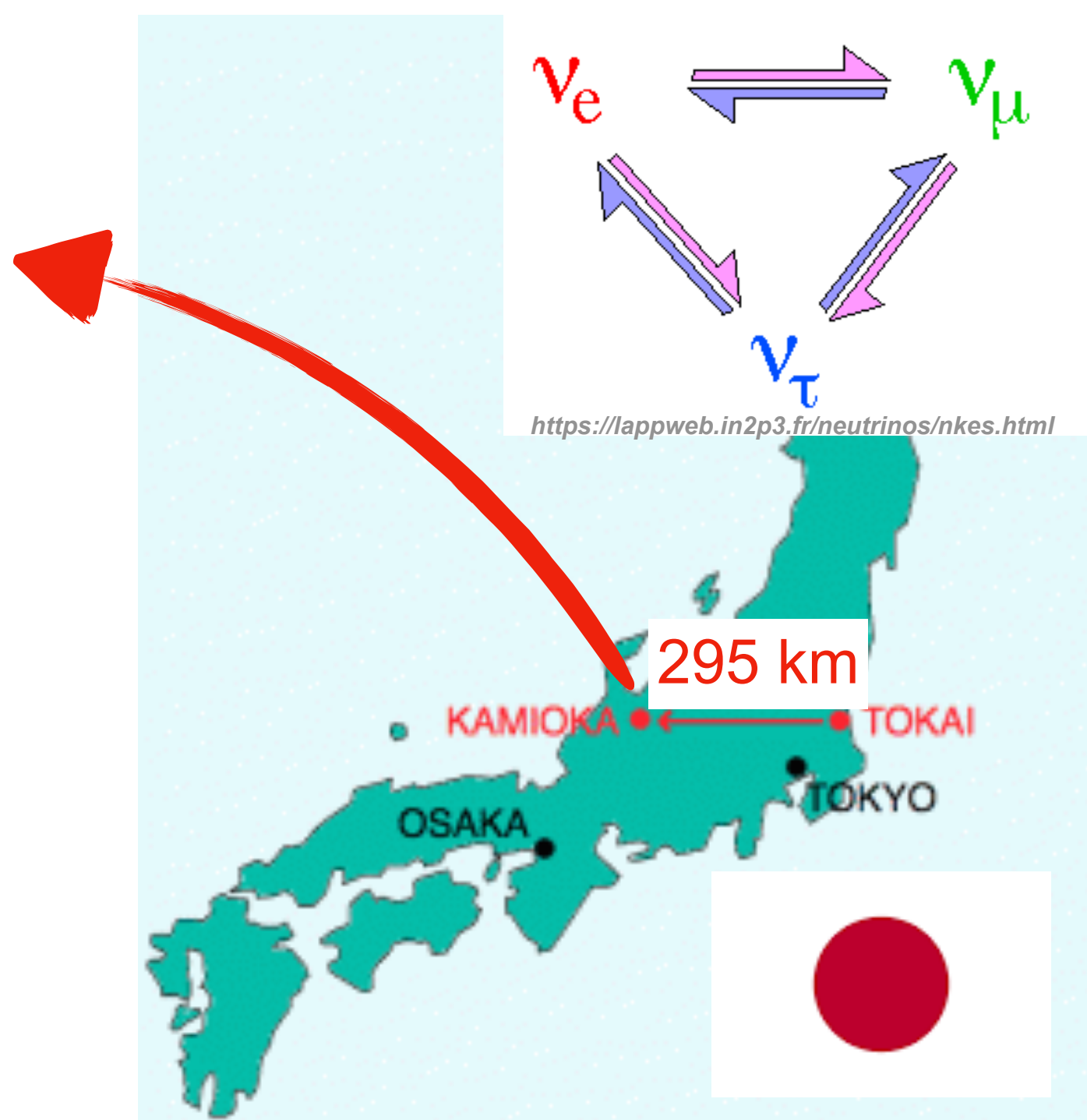
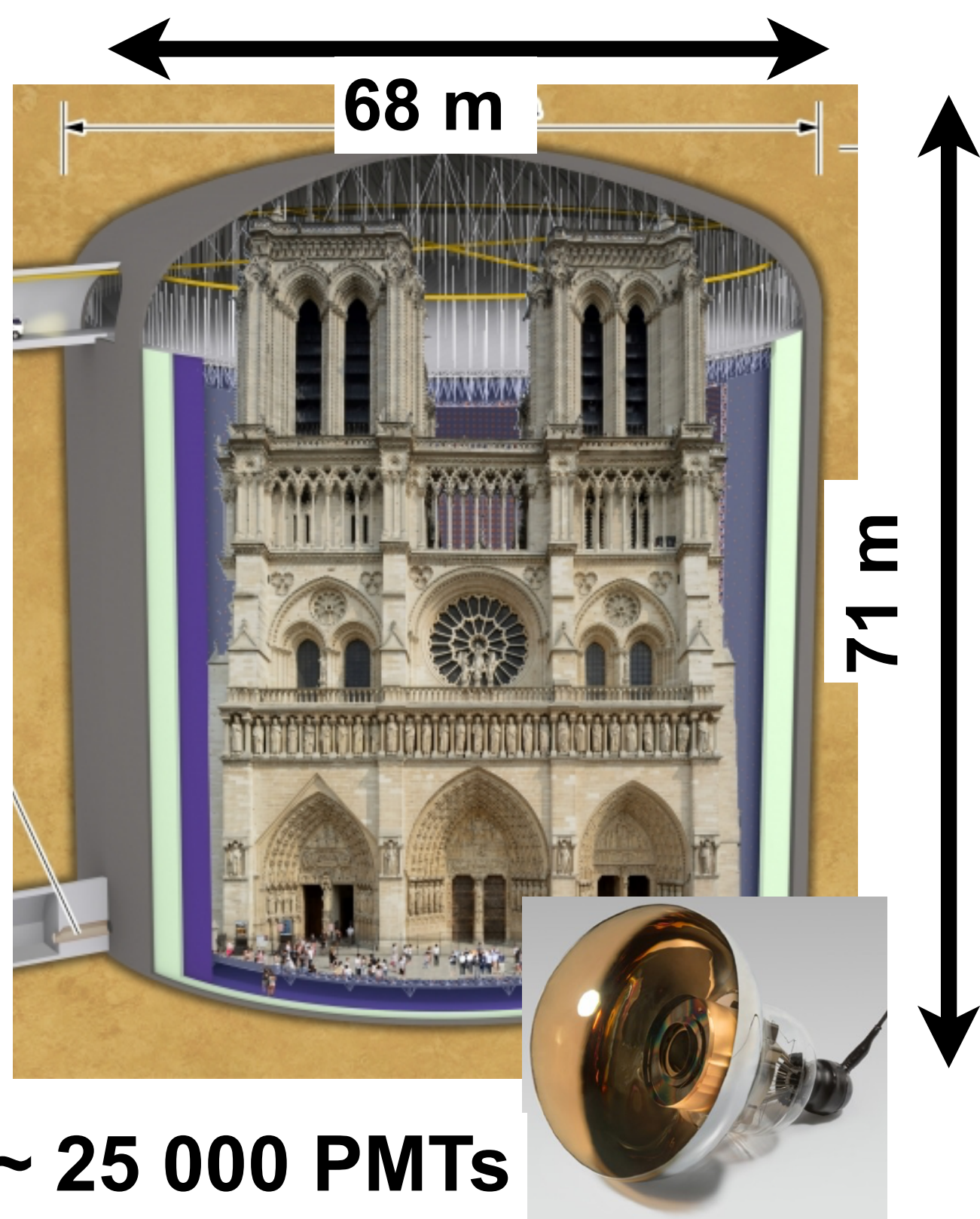
Lucile Mellet

On behalf of Hyper-Kamiokande France

R&D and design



HK in a nutshell

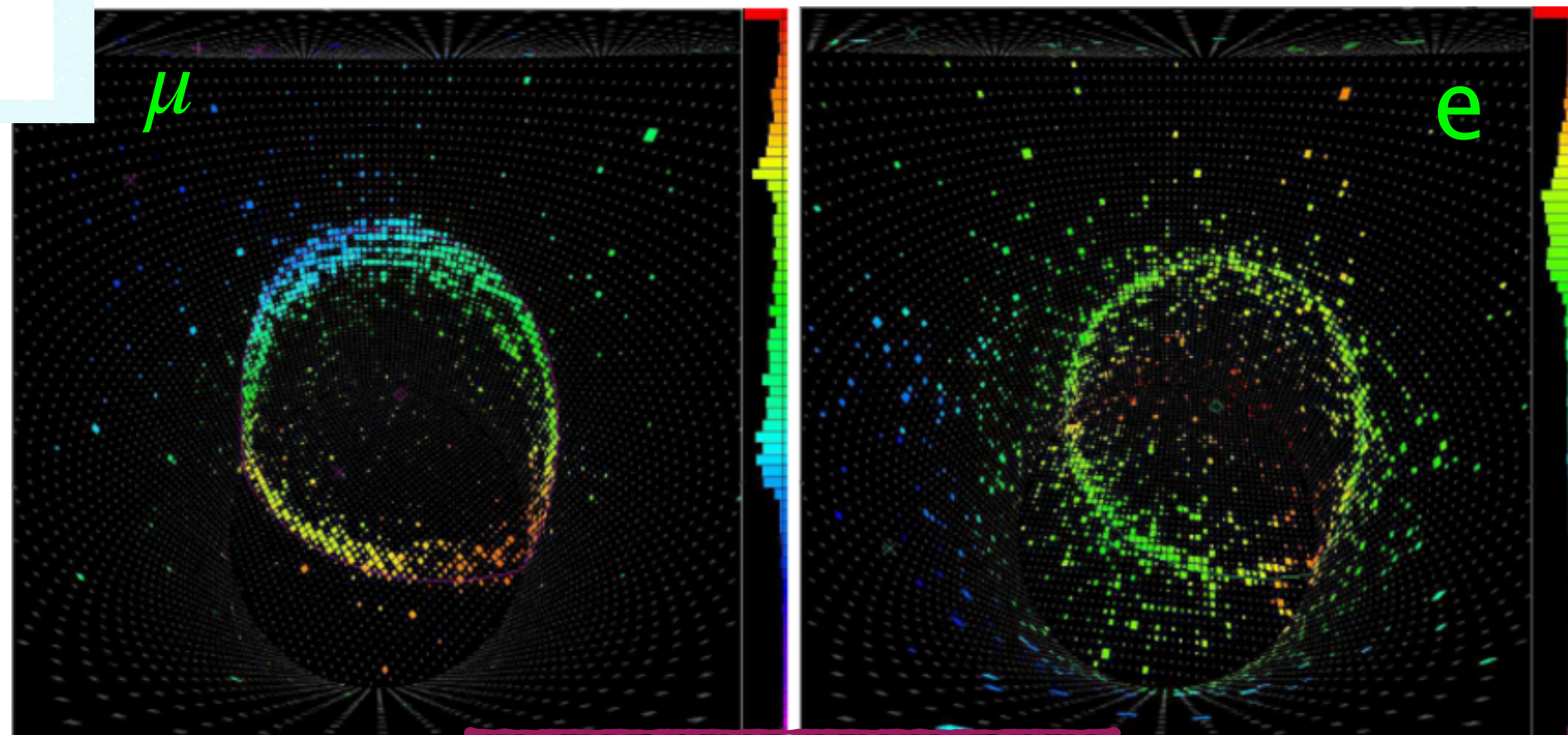
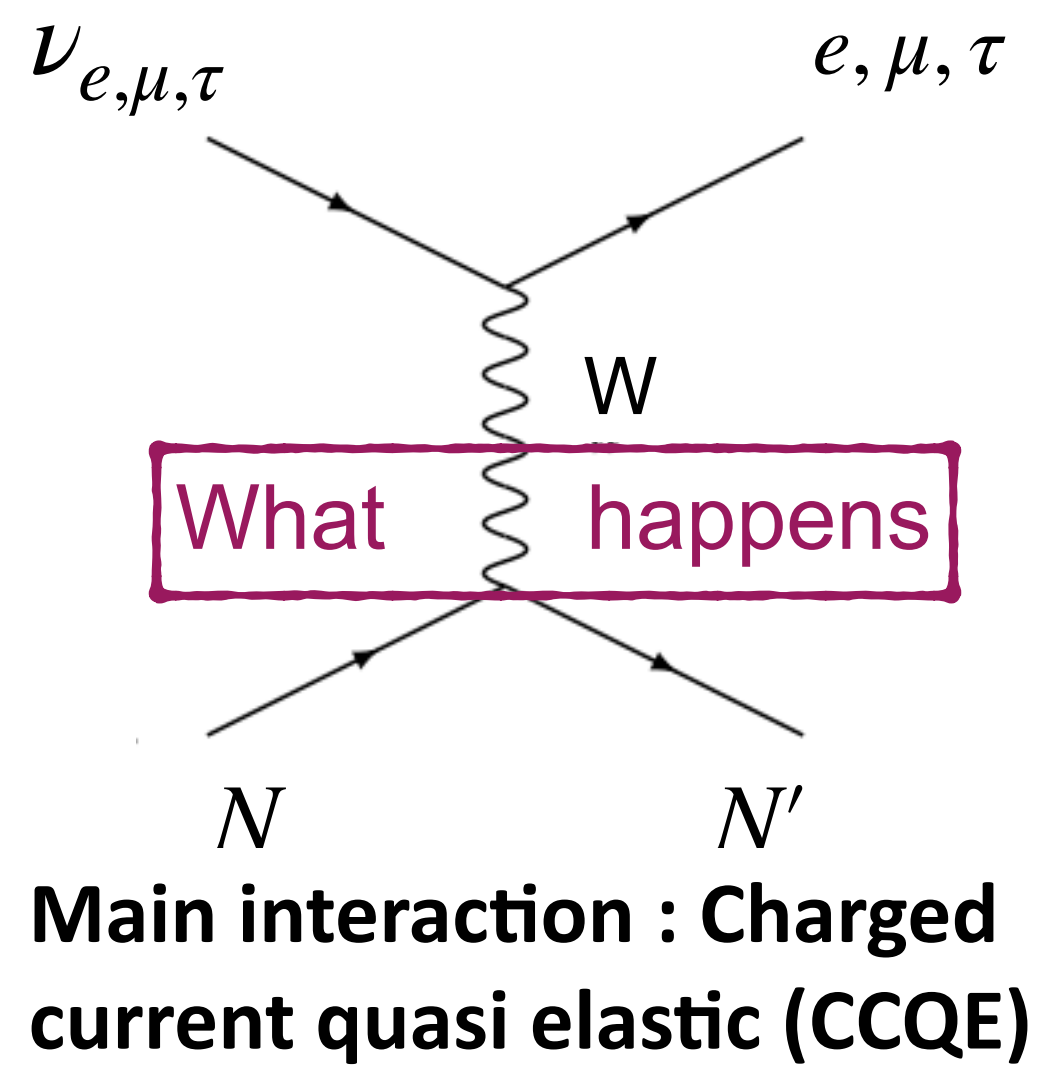


- Beam ν physics
- Astrophysics ν observatory

- Need for :**
- Efficient **collection of the charge** output of the Photo-multipliers
 - Precise **timing** for ring reconstruction

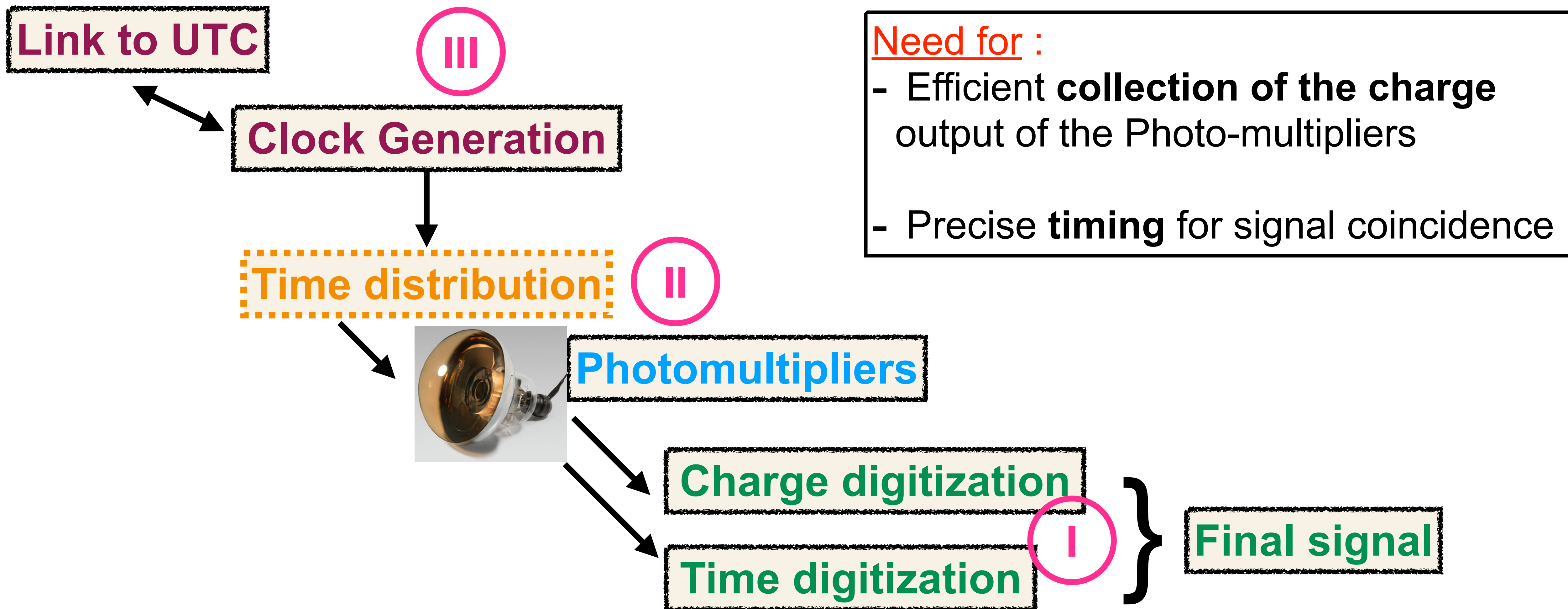
What we build

- Long baseline ν oscillation experiment
- Water Cerenkov detector



What we want to see

Global scheme of our participation to HK's electronics



Charge and time digitization for HK

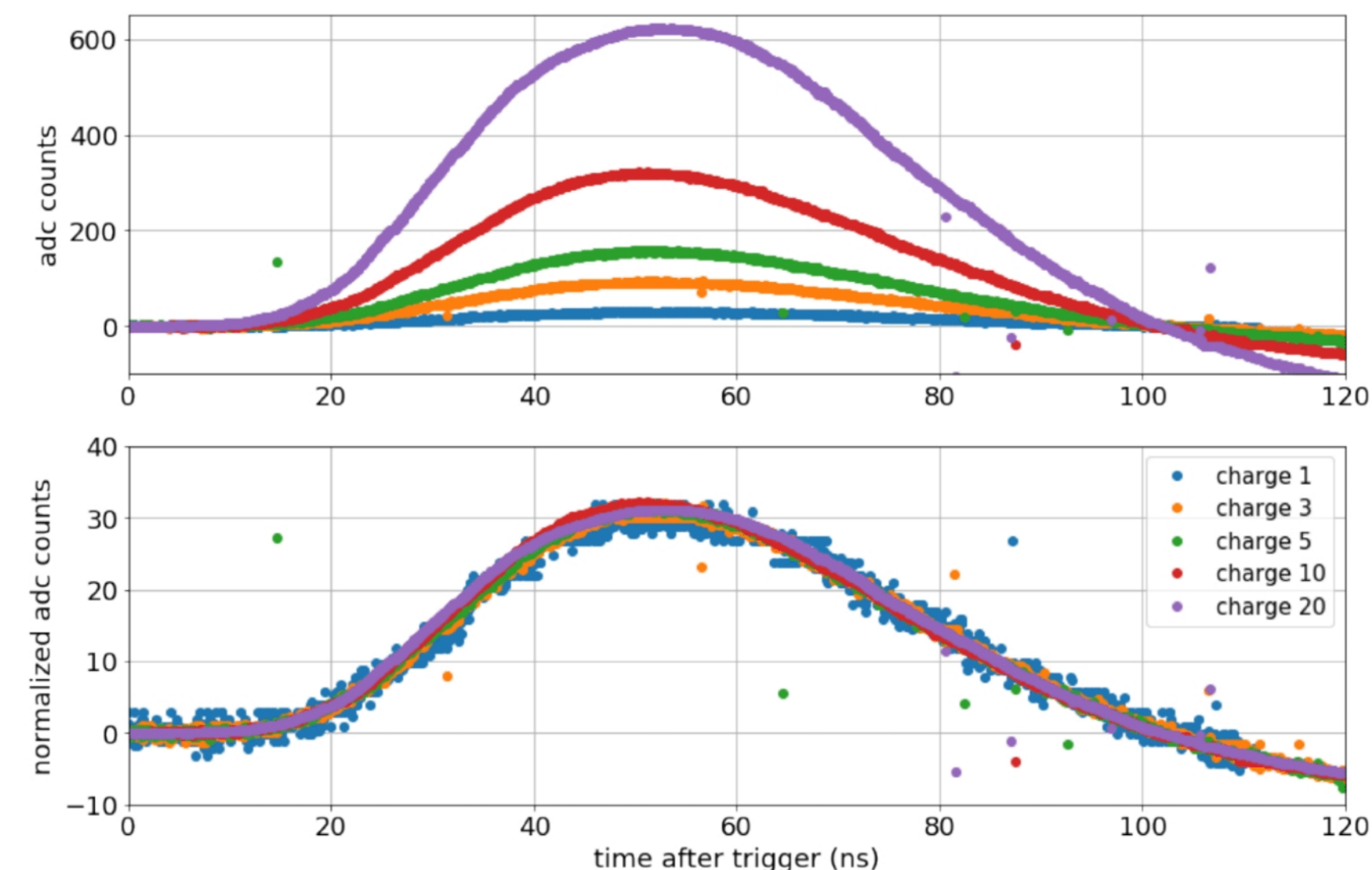
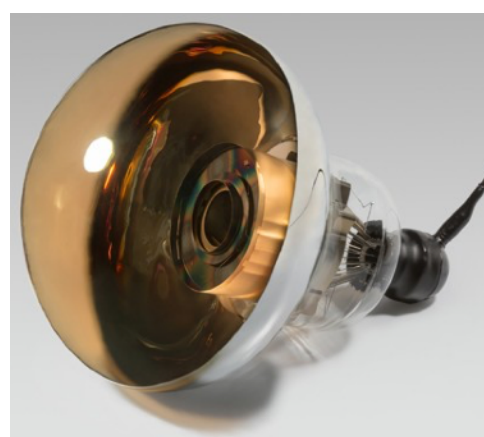
Some of the requirements

- Charge resolution :
 - Low energies : Solar ν
 - High energies : Atmospheric ν
- ➔ Large dynamic range
- Time resolution :
 - < 300 ps when > 1 p.e-
 - then < 200 ps above 10 p.e-
- Charge linearity : 1%
- Discriminator threshold : 1/6 p.e.

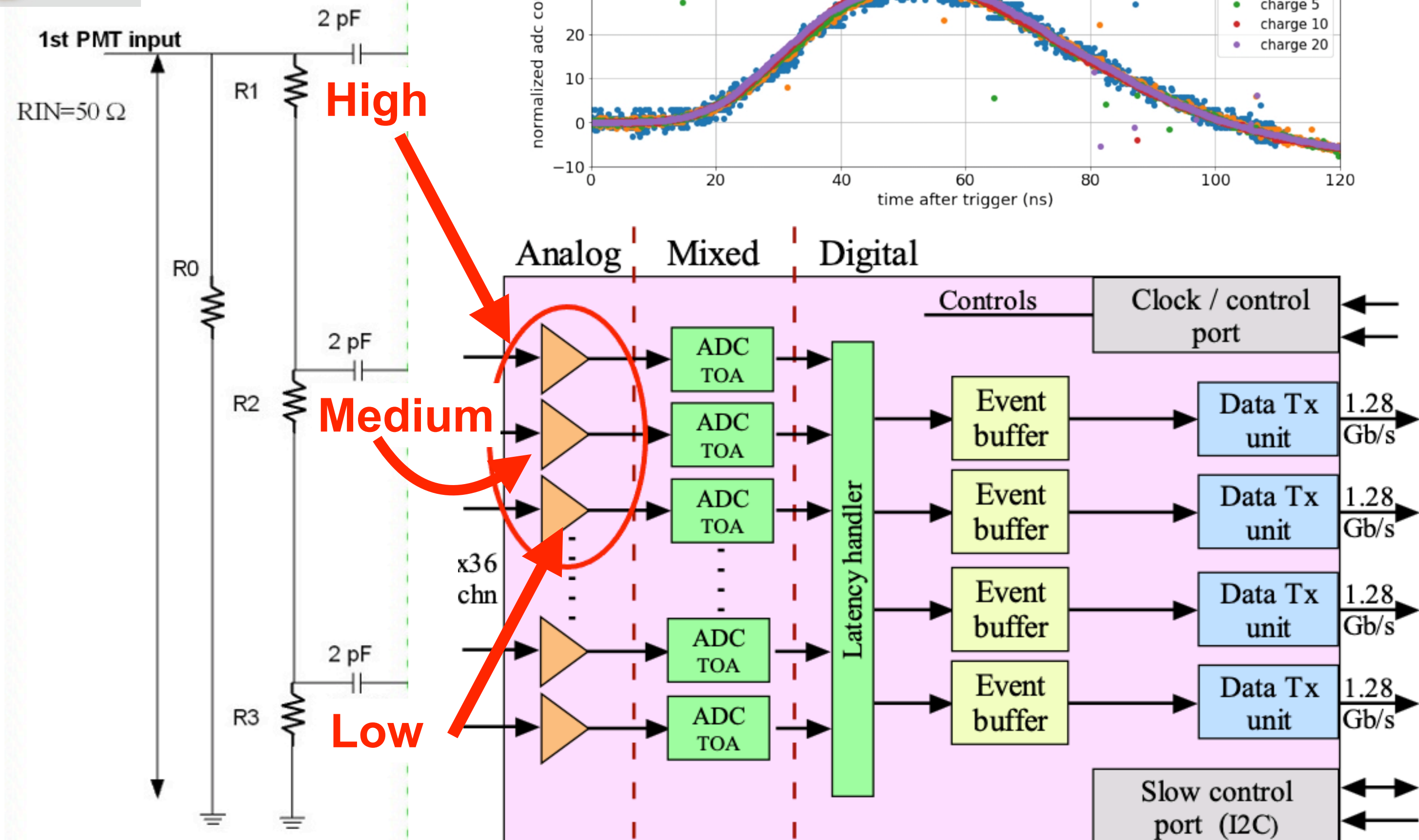
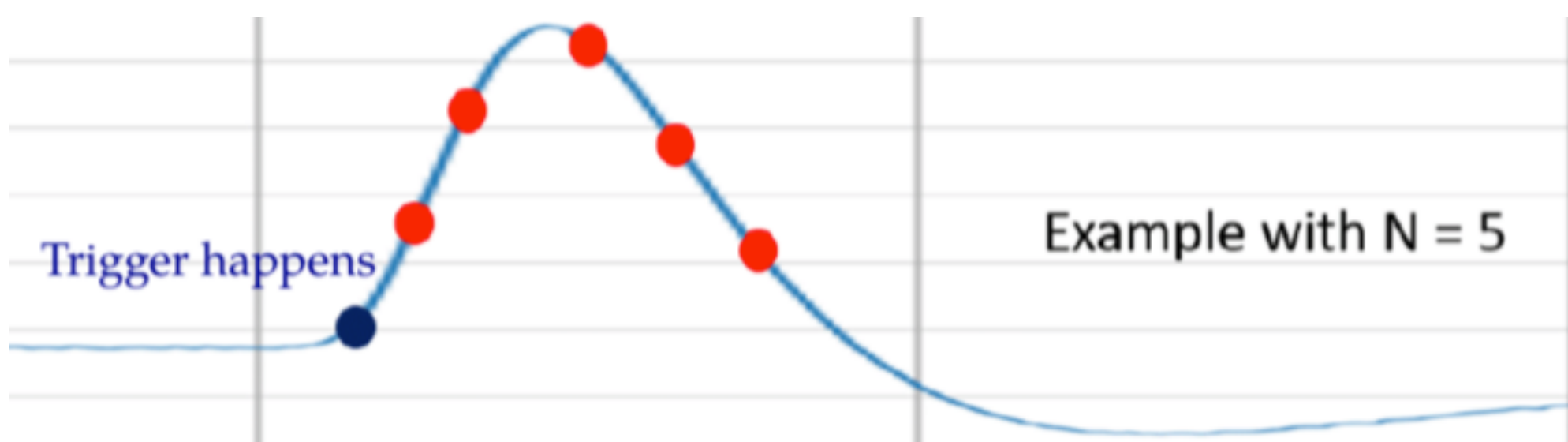
Charge and time digitization for HK

Proposed solution

- Based on HKROC chip
 - **3 gains** per channel (low, medium, high)
 - Dynamic range from 0-2500 pC = 0-1250 p.e.
 - 1 readout for 3 PMTs → 1 trigger = read all 3 (hint for fake hit)



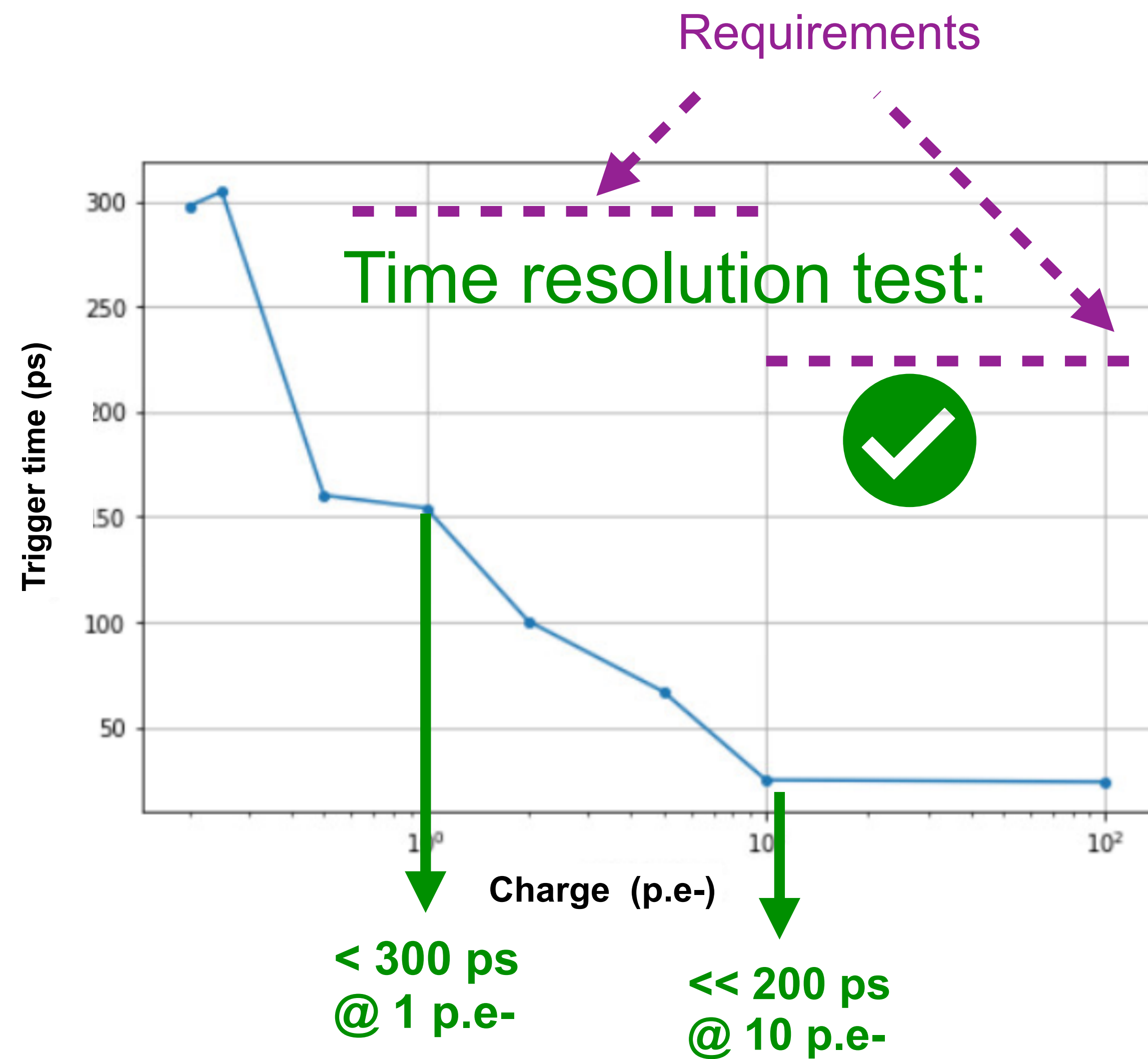
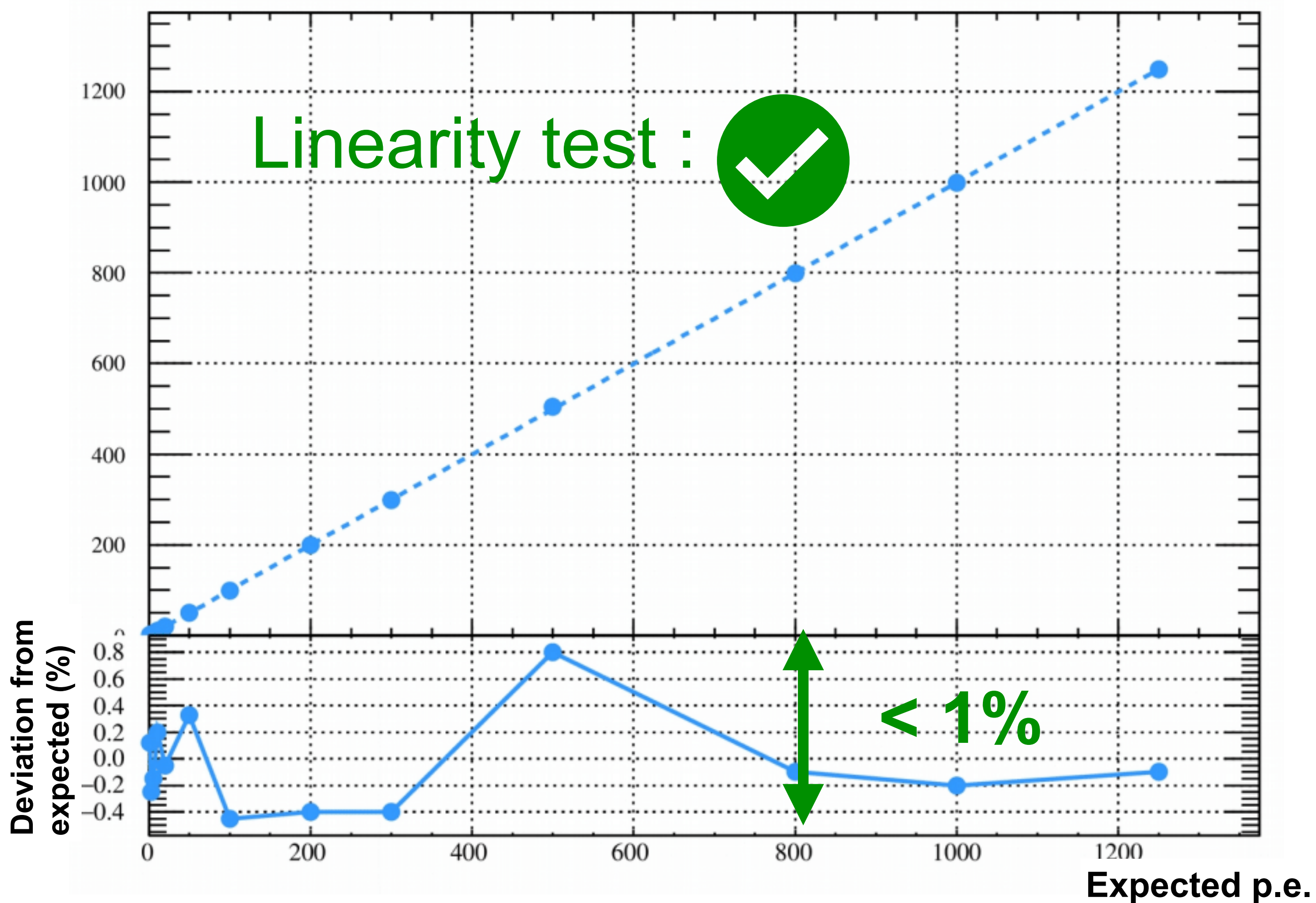
- Waveform-like **digitizer @40MHz**
: 1 point/25 ns



Charge and time digitization for HK

Some results

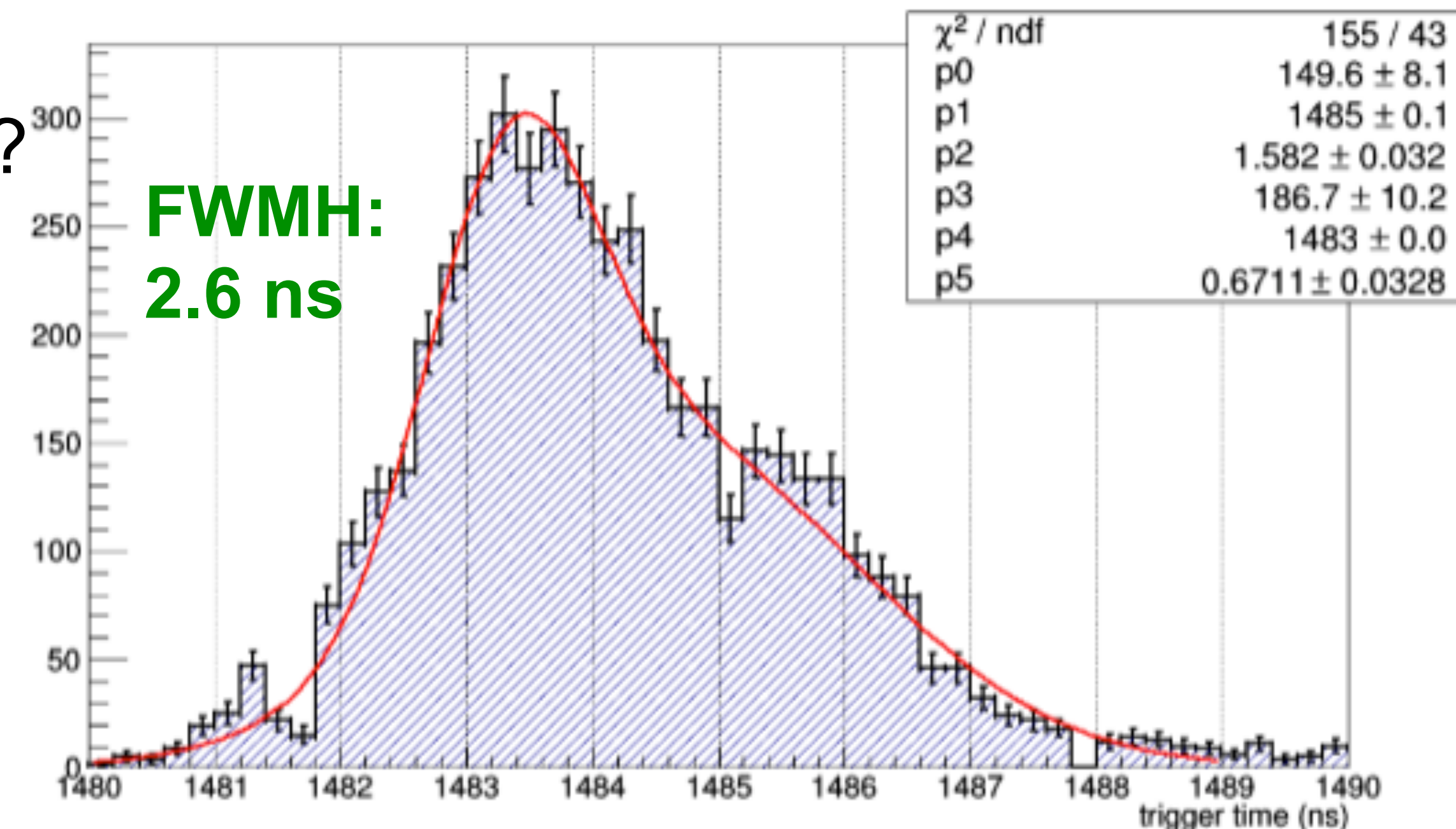
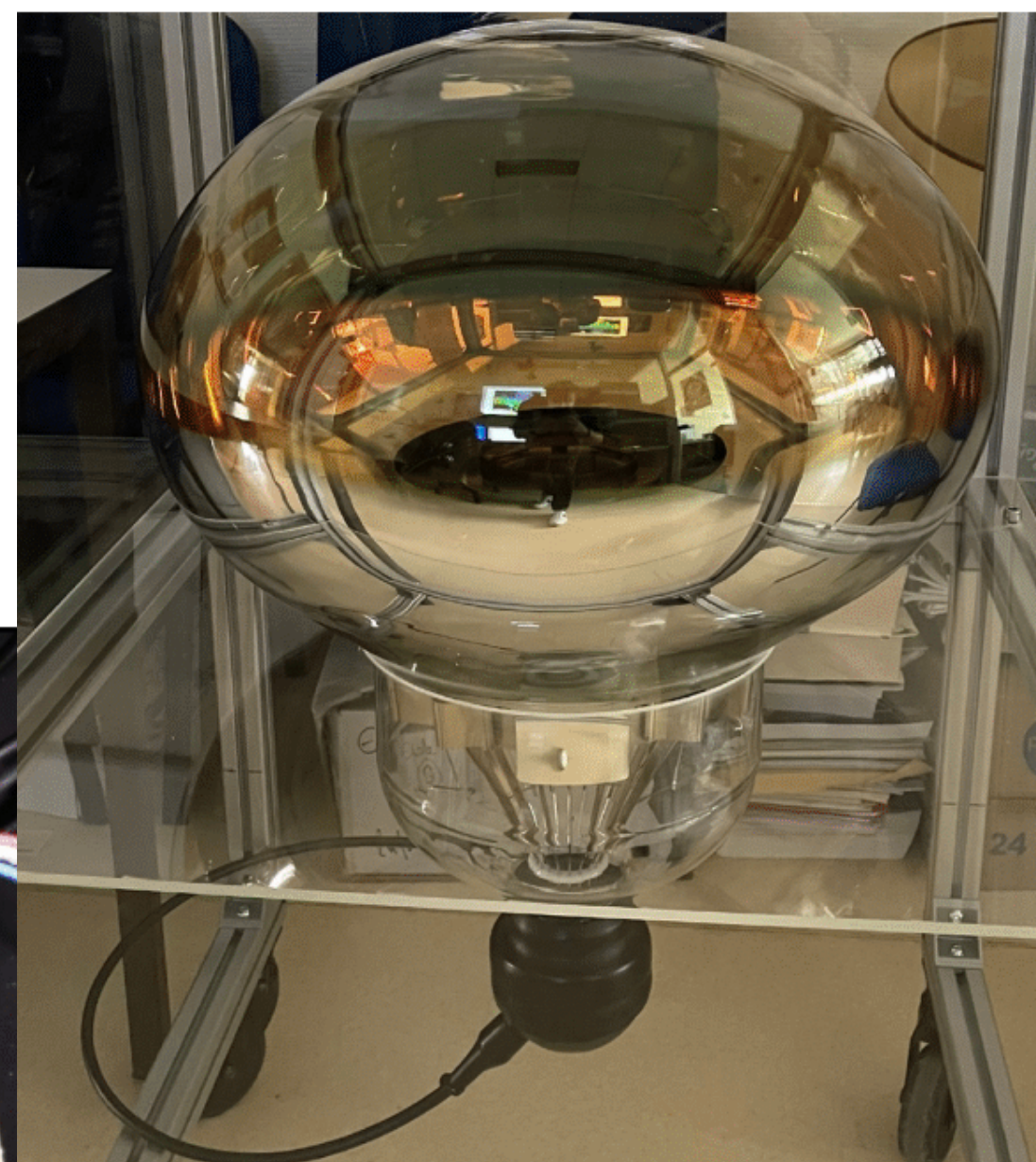
Mean p.e.



Charge and time digitization for HK

Time resolution of the PMT : ~2.8 ns

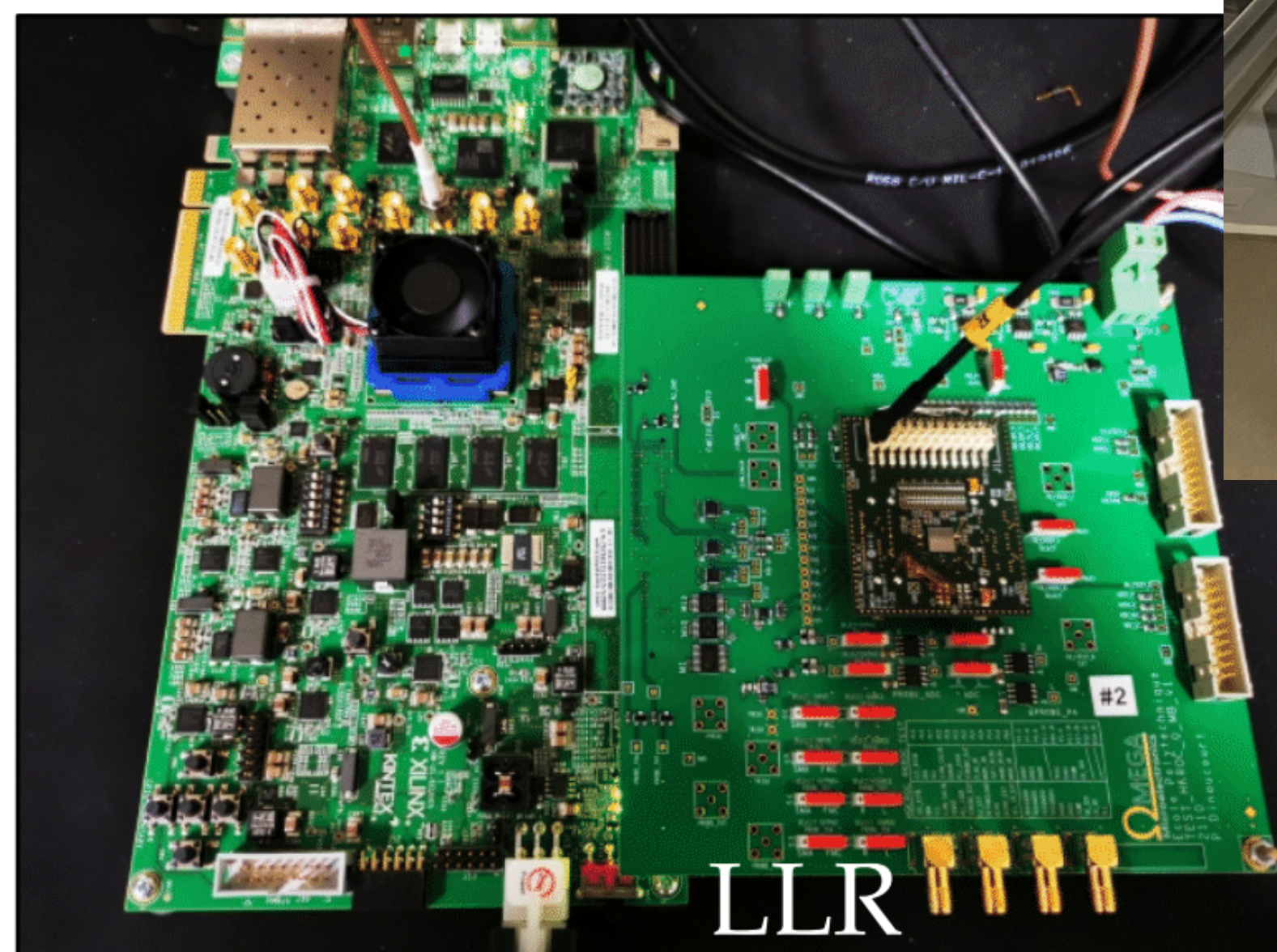
Does the digitizer degrade the PMT performance ?



Time resolution with PMT :



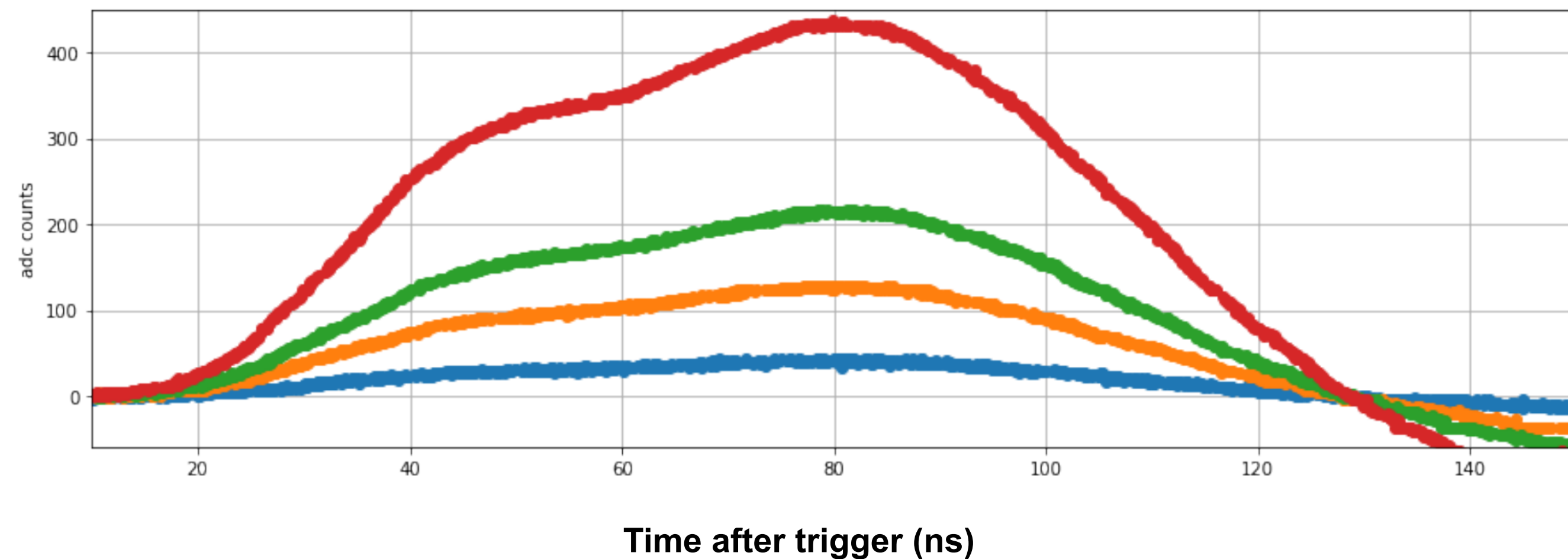
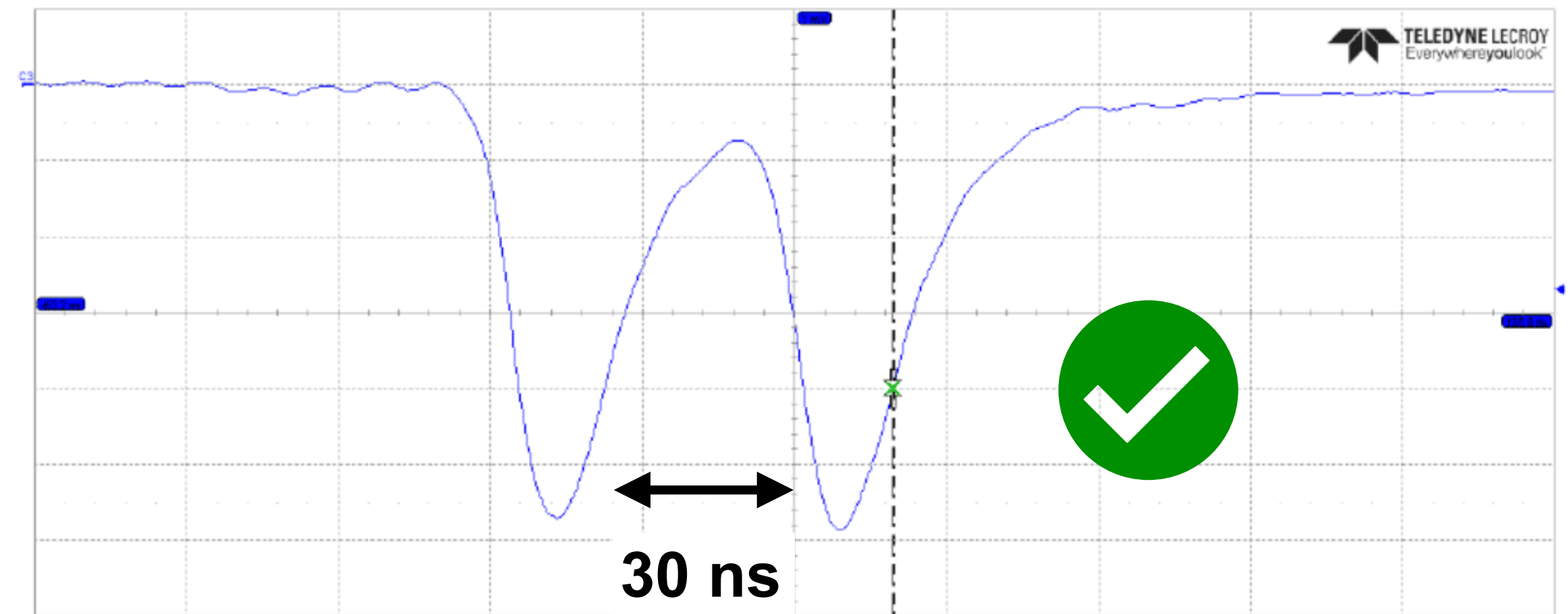
All tests on time and charge have been performed with PMT in real conditions



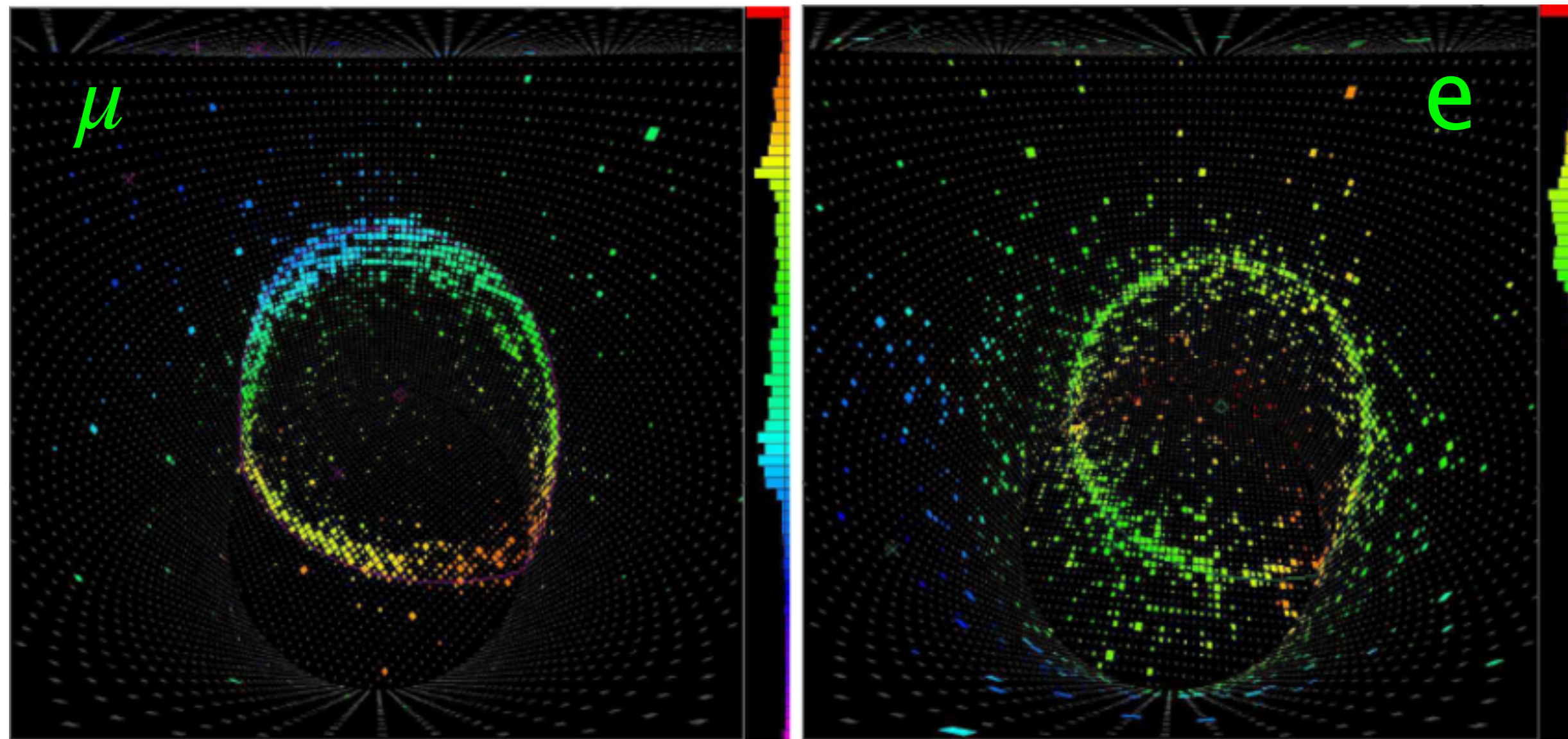
Charge and time digitization for HK

By the way, why a waveform digitizer ?

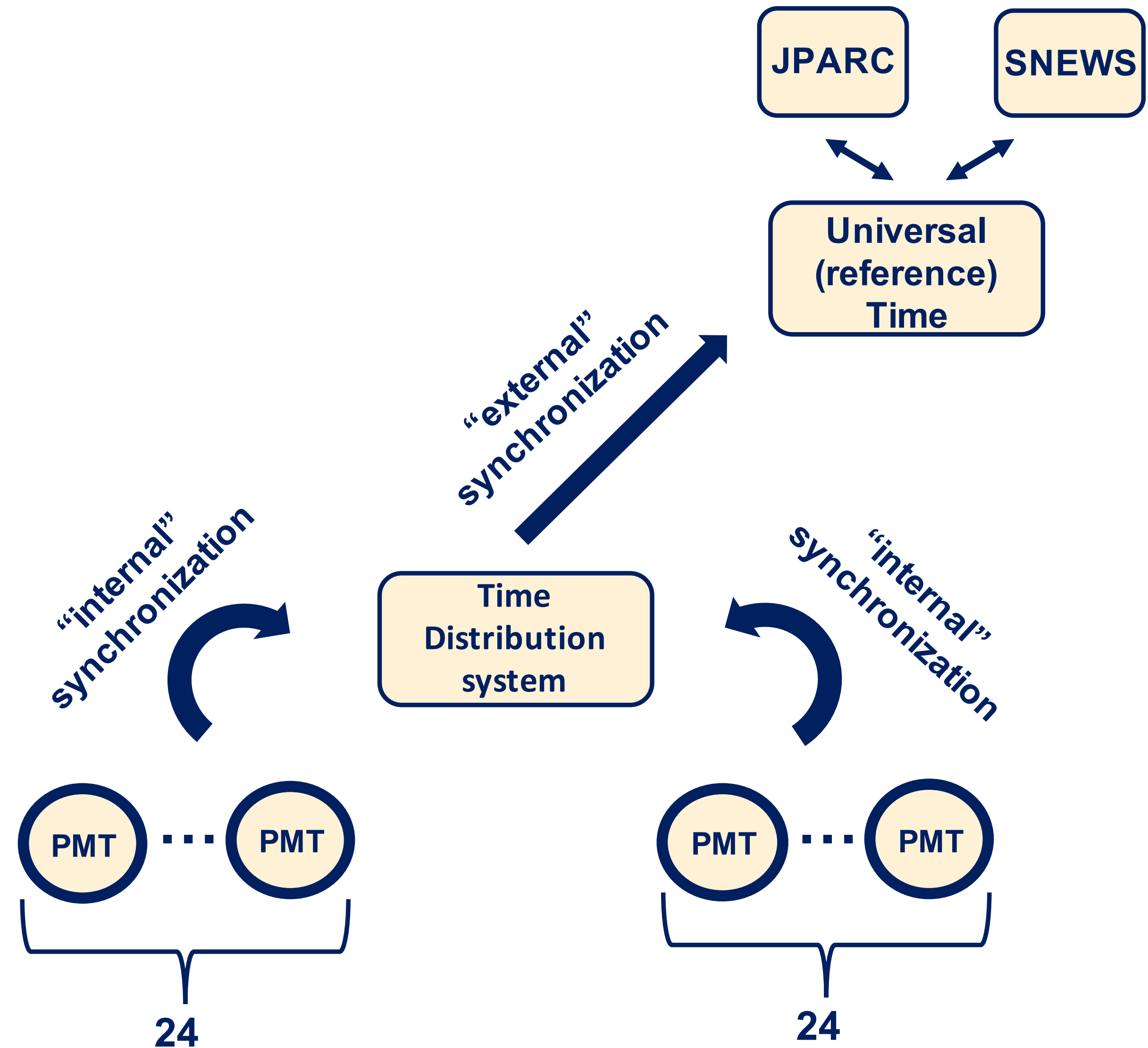
- Reduces dead time (requirement $< 1 \mu s$) up to 30ns
- Allows for separation between close events in time (pile-up) :
 - ➡ Software reconstruction
 - ➡ Delayed signals (decay e^- , direct/indirect light, ...)
 - ➡ High rate of SN explosion signal



Precise timing for Hyper-Kamiokande



- ▶ **Internal sync : ring reconstruction by coincidence**
 - ▶ **Stability of less than 100 ps**
- ▶ **External sync : beam bunches + astrophysical observatory (SN) + other studies**
 - ▶ **At least 100 ns wrt UTC**



Detailed scheme of our solution

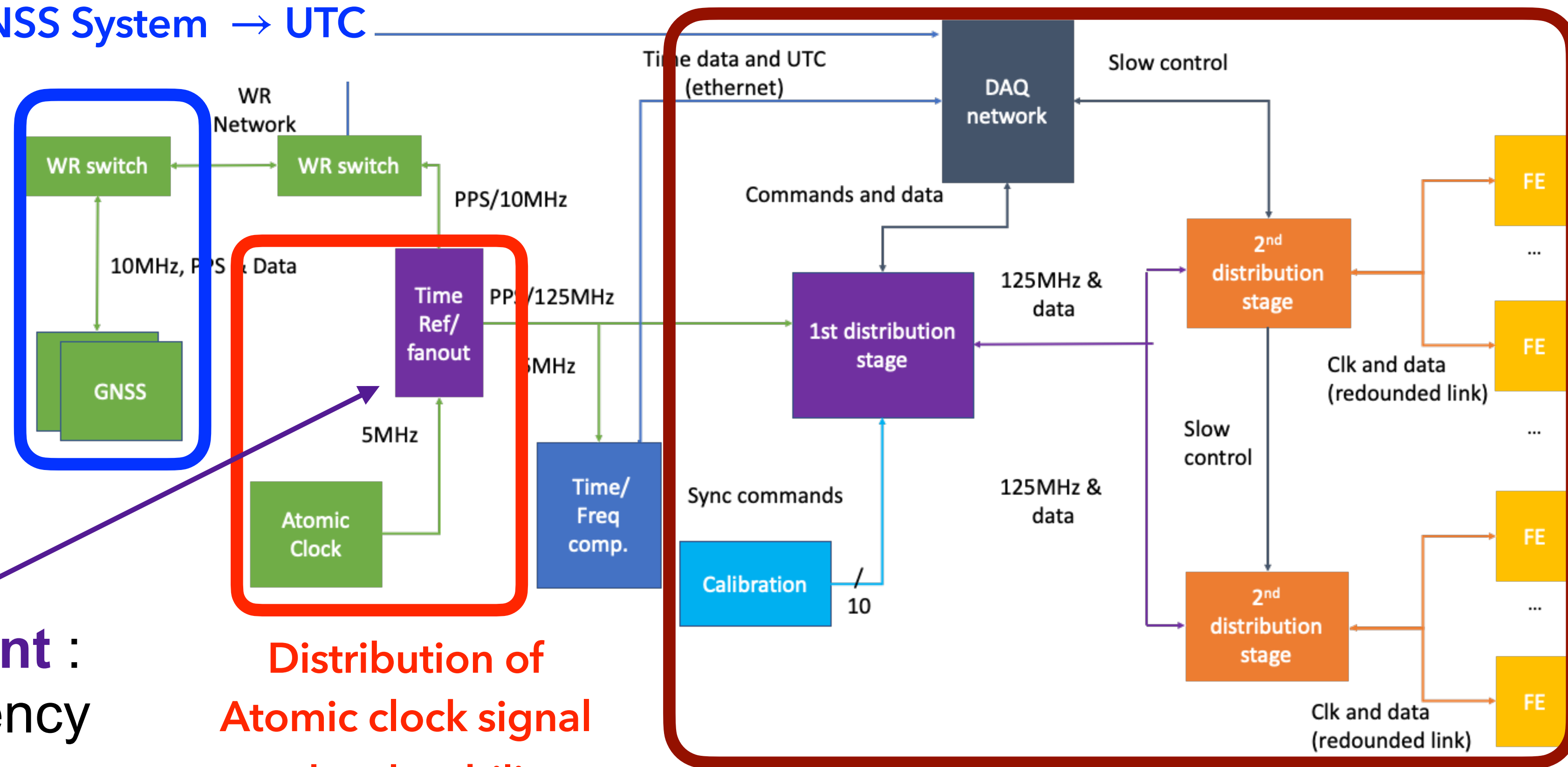
GNSS System → UTC

Currently in an R&D phase

Our proposed system :
What ?

- One local **time reference point** :
 - distributes a high-frequency clock signal
 - built from an **atomic clock**

- A **GNSS** antenna + receiver : link to universal time (UTC)



Distribution of Atomic clock signal → local stability

Distribution to PMTs

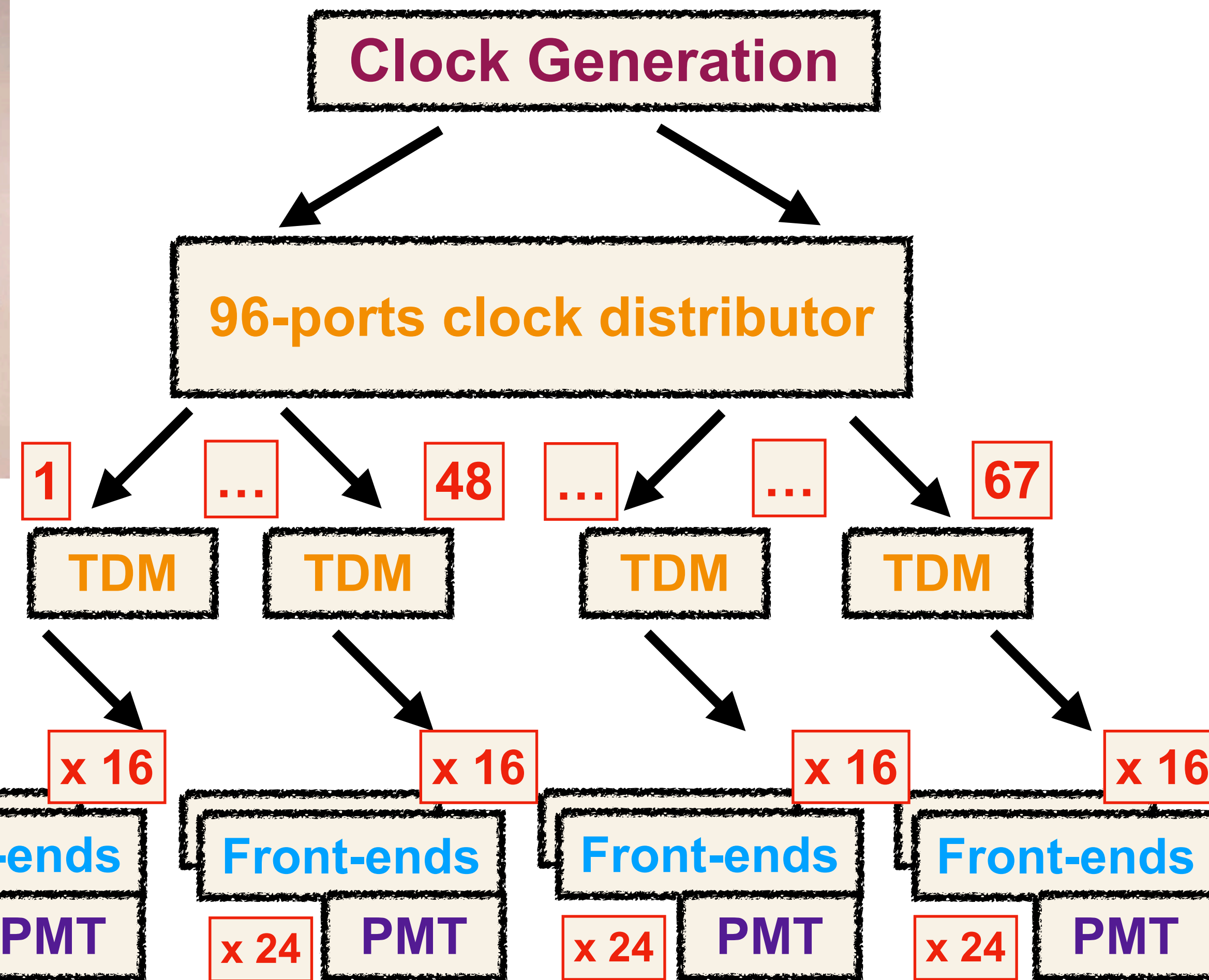
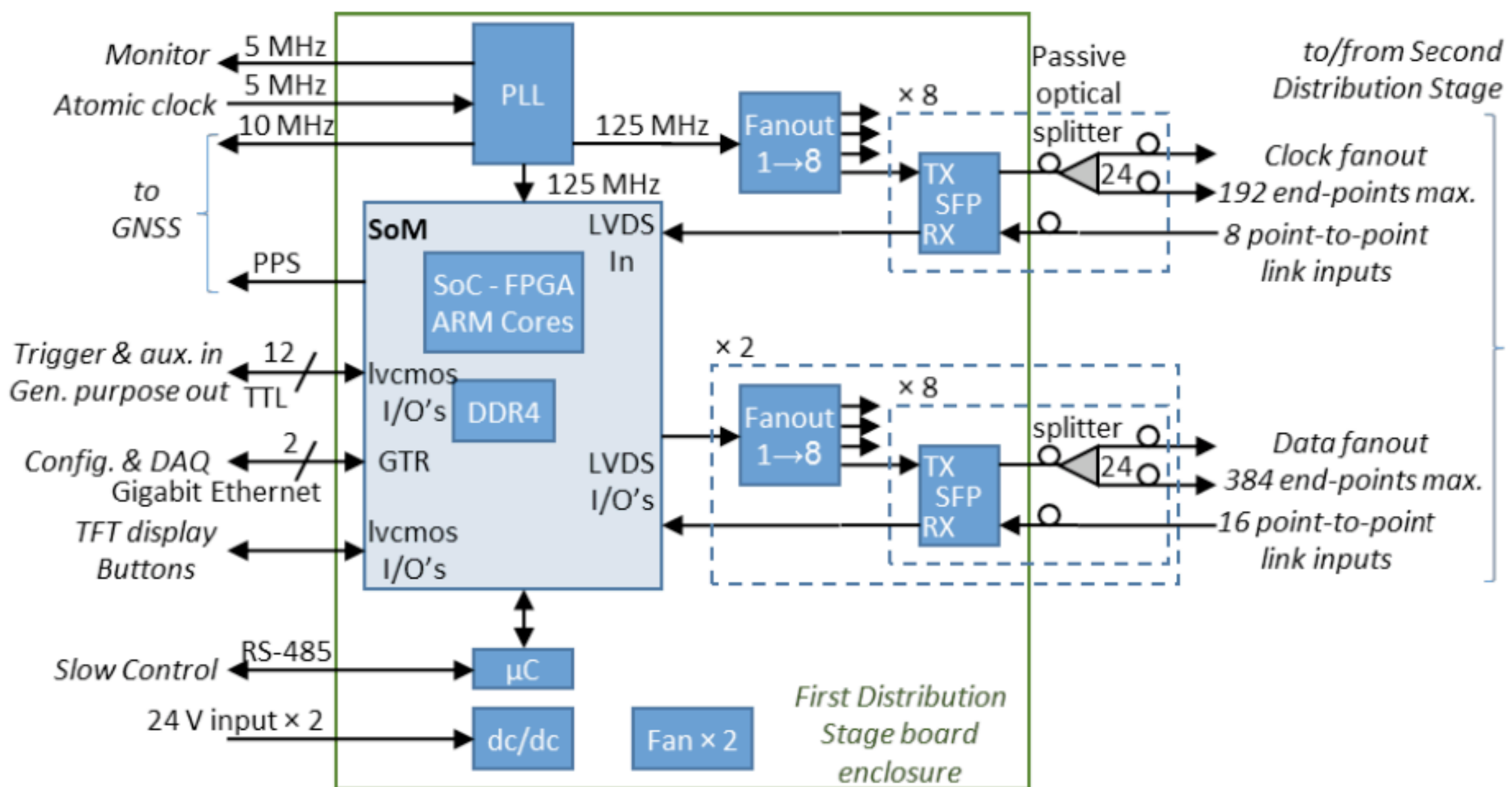
- Two-stages distribution
- + Redundancy

Two-stages distribution

1st stage distribution prototype



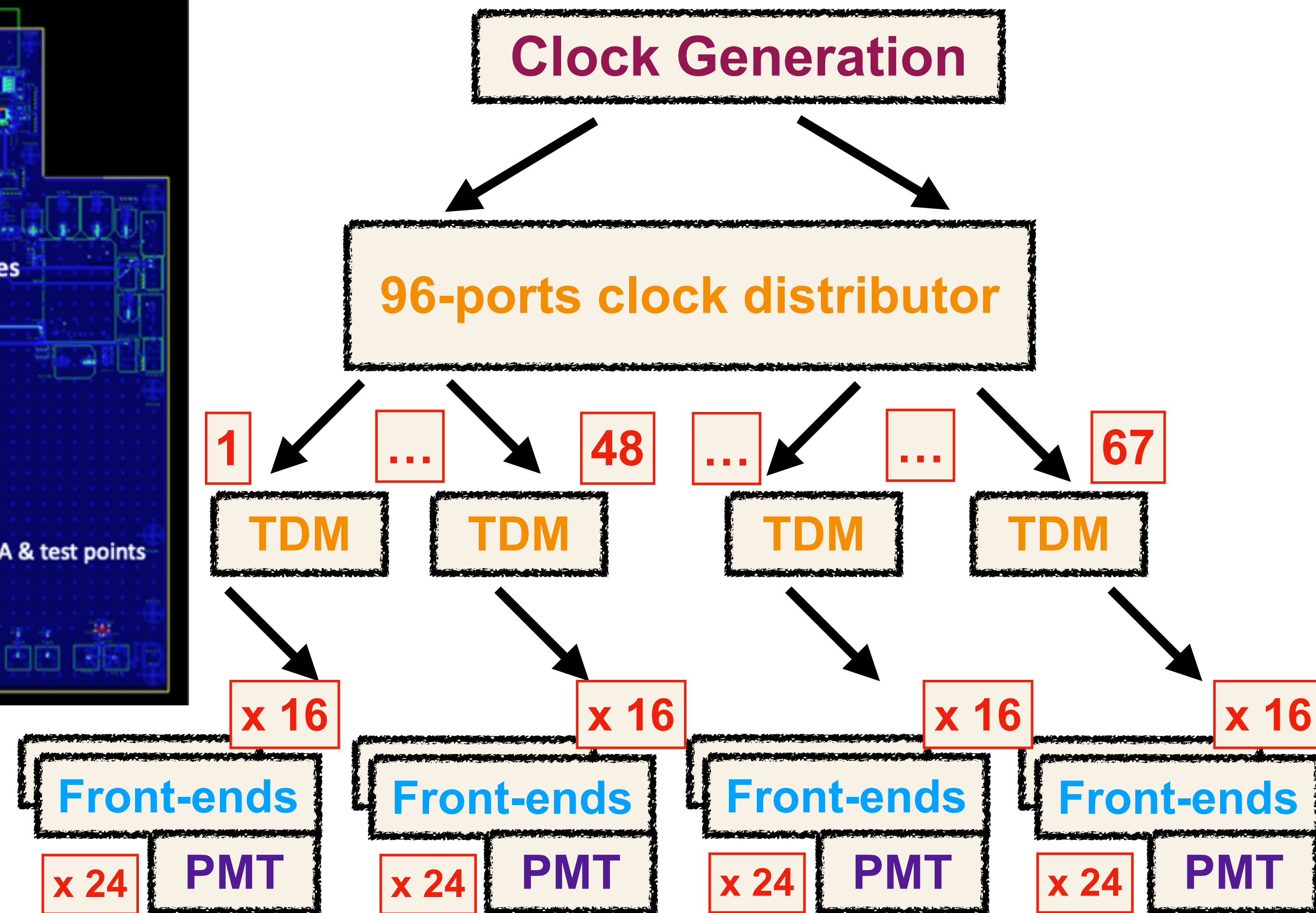
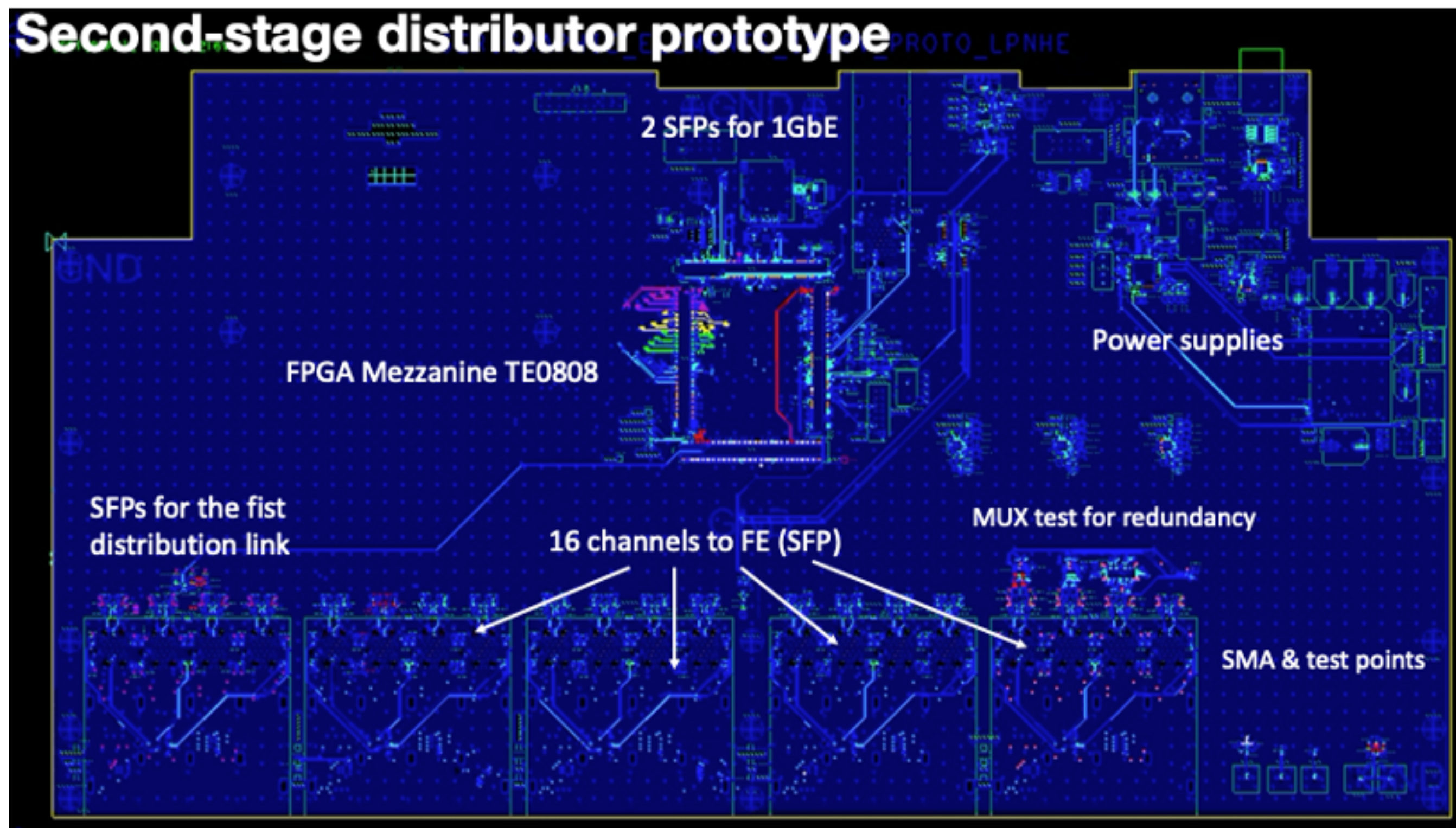
@Denis Calvet



- 2 stages

- Electronic boards and cards are being designed and prototype

Two-stages distribution



- 2 stages
- Electronic boards and cards are being designed and prototype

Undergoing tests in collaboration between French and Italian groups

Characterization of the proposed generation system

Our proposed system : Why ?

Atomic clock : the most stable at short term

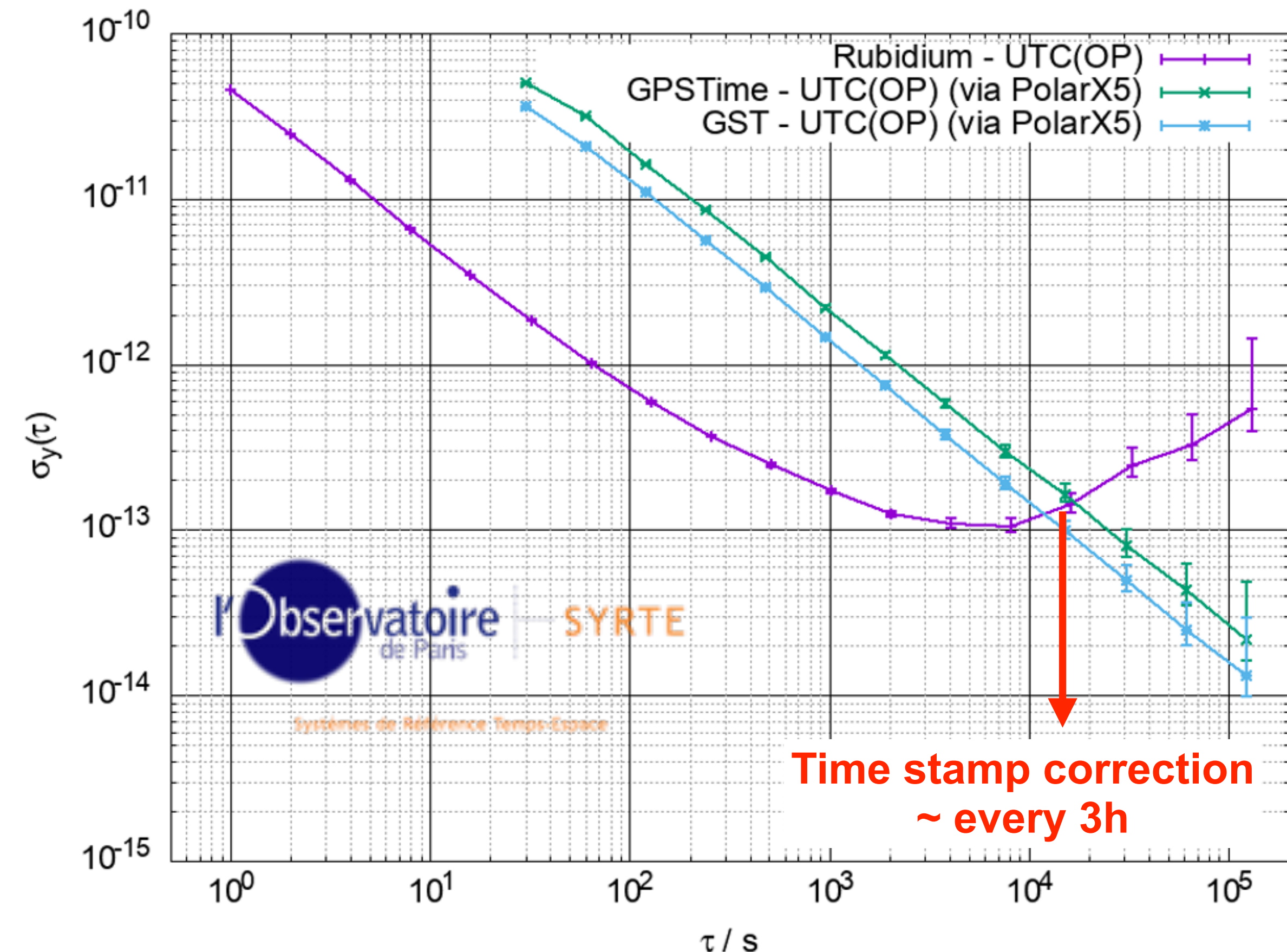
- Tested a Rubidium clock
- Will test Passive Hydrogen Maser

GNSS signal : more stable at long term + link to UTC

Allan Standard Deviation (ASD) statistical tool :

$$\sigma_y^2(\tau) = \frac{1}{2} \langle (y_{n+1}^- - y_n^-)^2 \rangle$$

Variance of Δt as a function of interval length :
allows to separate noise types = visualize stability at various time scales



Purple curve : Rubidium clock stability (OP71 as reference)

Green curve : Received GPS time stability (OP71 as reference)

Blue curve : Received Galileo time stability (OP71 as reference)

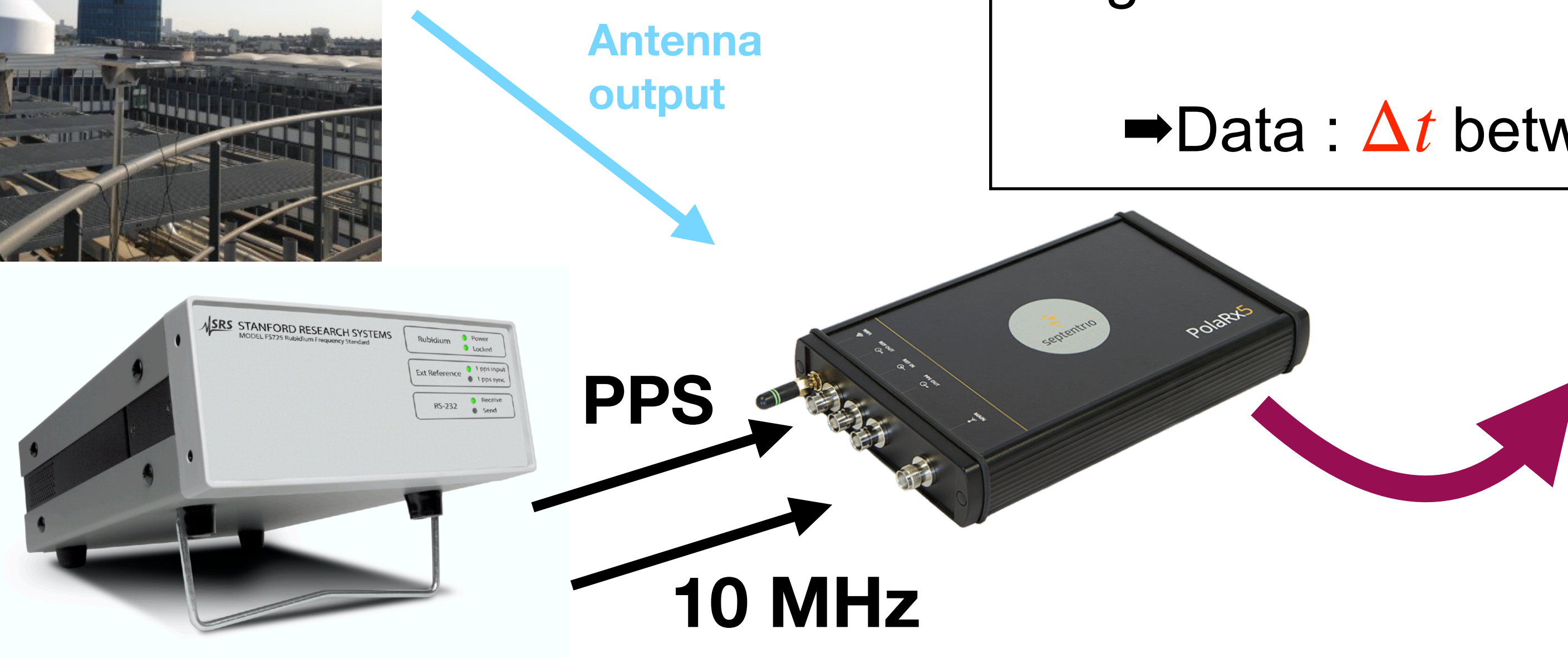
Set-up for tests @ LPNHE



How to test the stability of a frequency ?

➔ Against a much more stable reference signal

➔ Data : Δt between each signal at each pulse

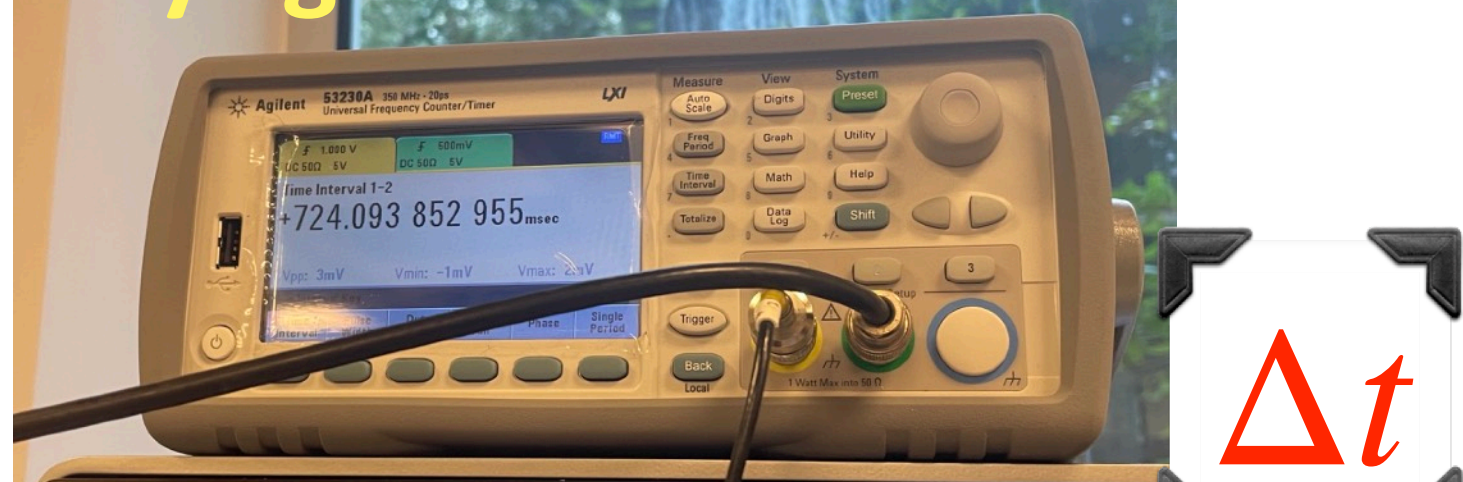


CGGTTS files :

- Infos on satellites
- All info on applied corrections
- ...
- Time difference between input and GPS time in 0.1 ns



Keysight 53220 counter

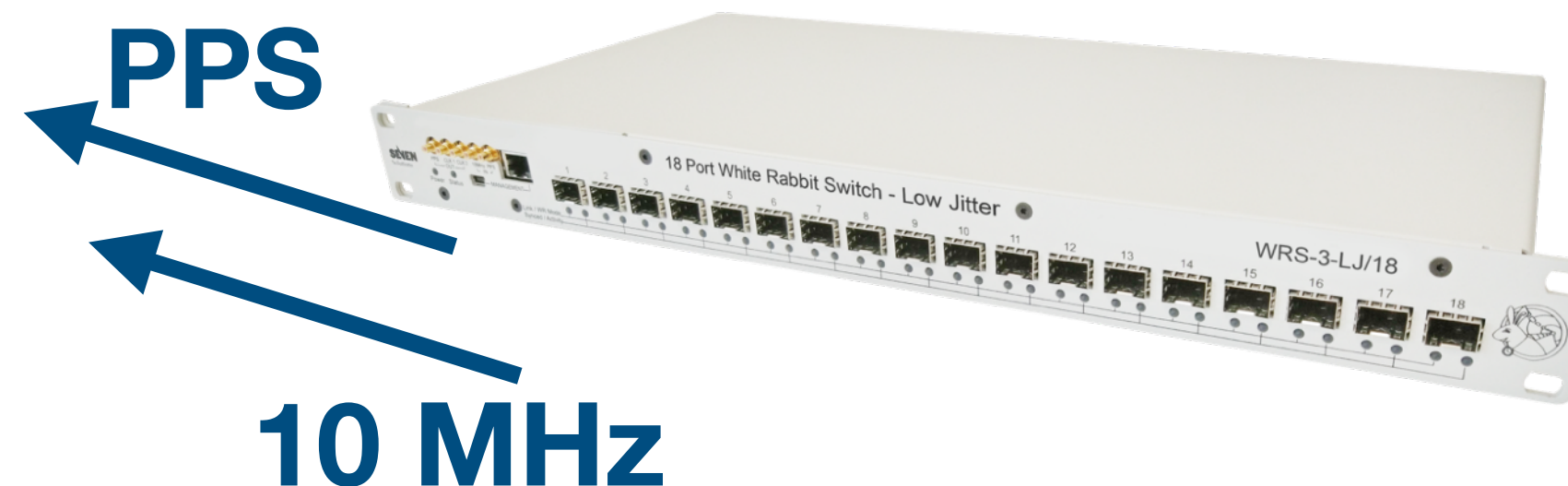


For other comparison



IRN Annecy

One or the other

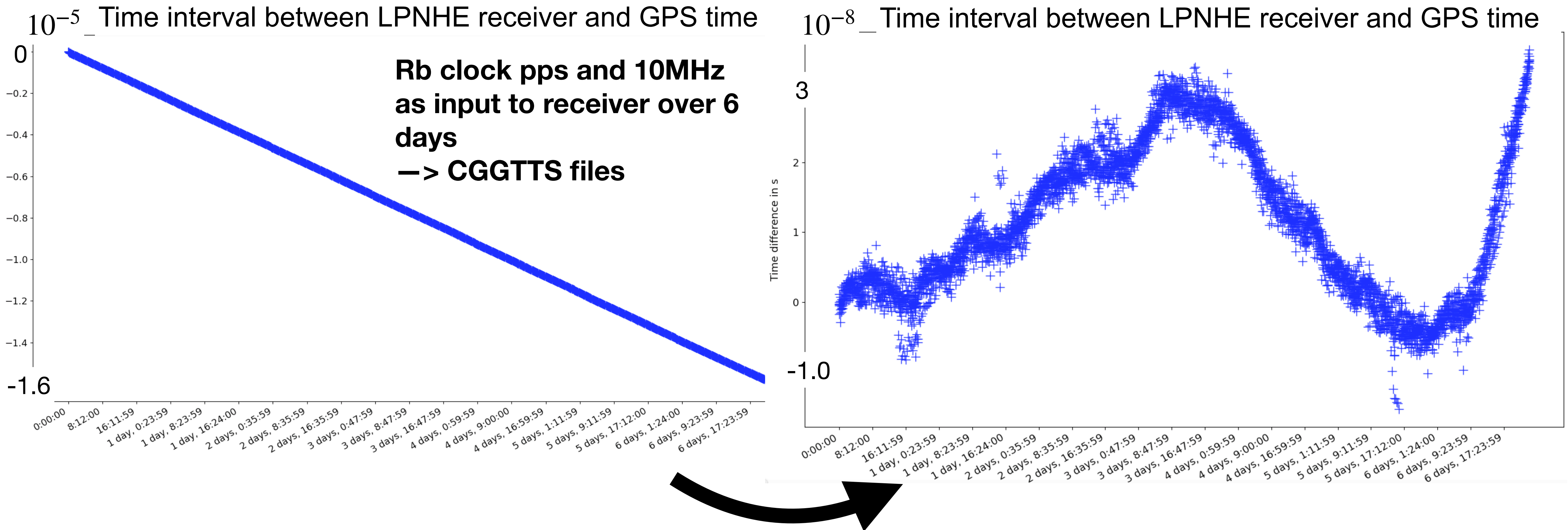


OP71 calibrated signal through optical fiber from :



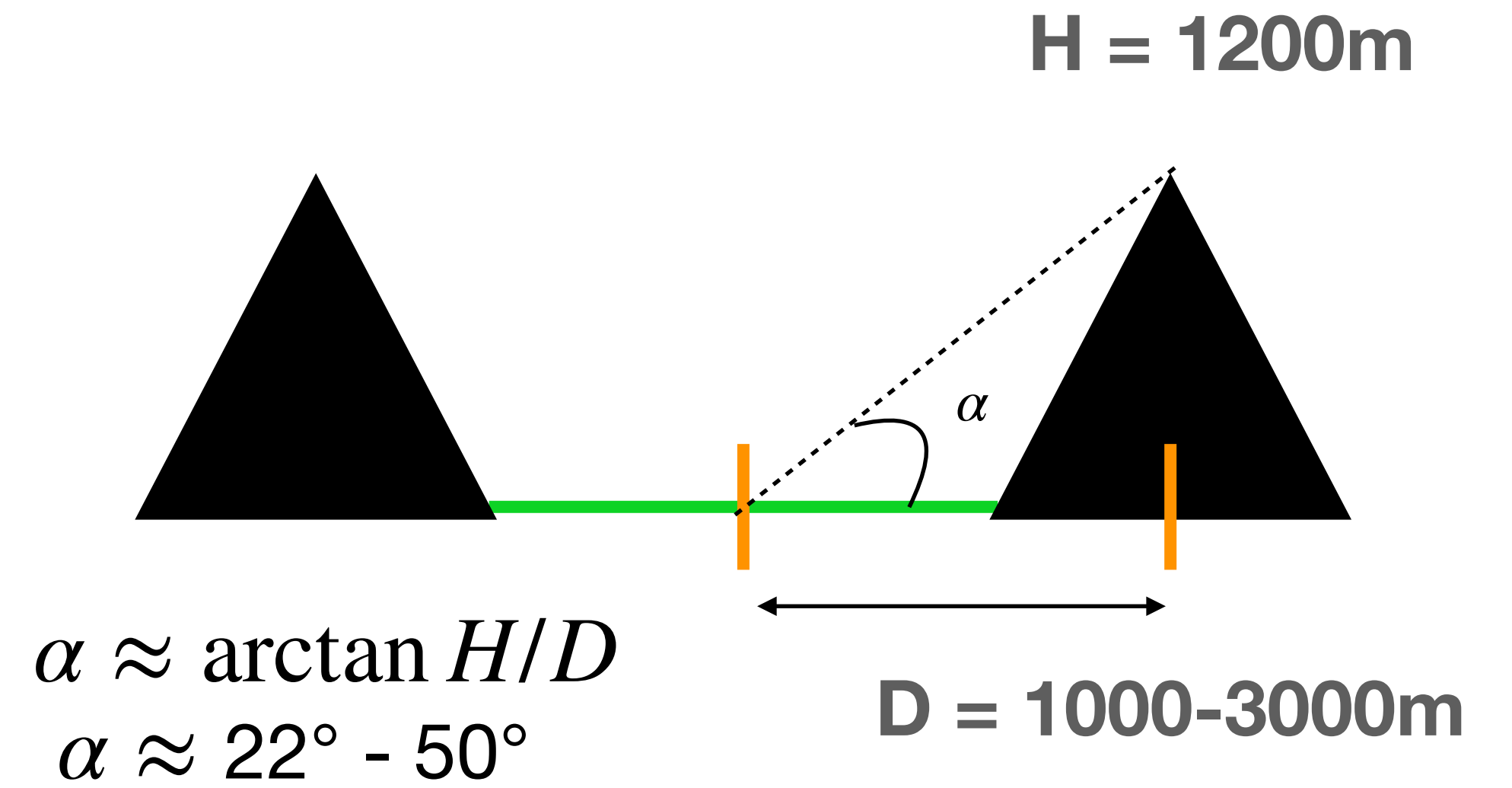
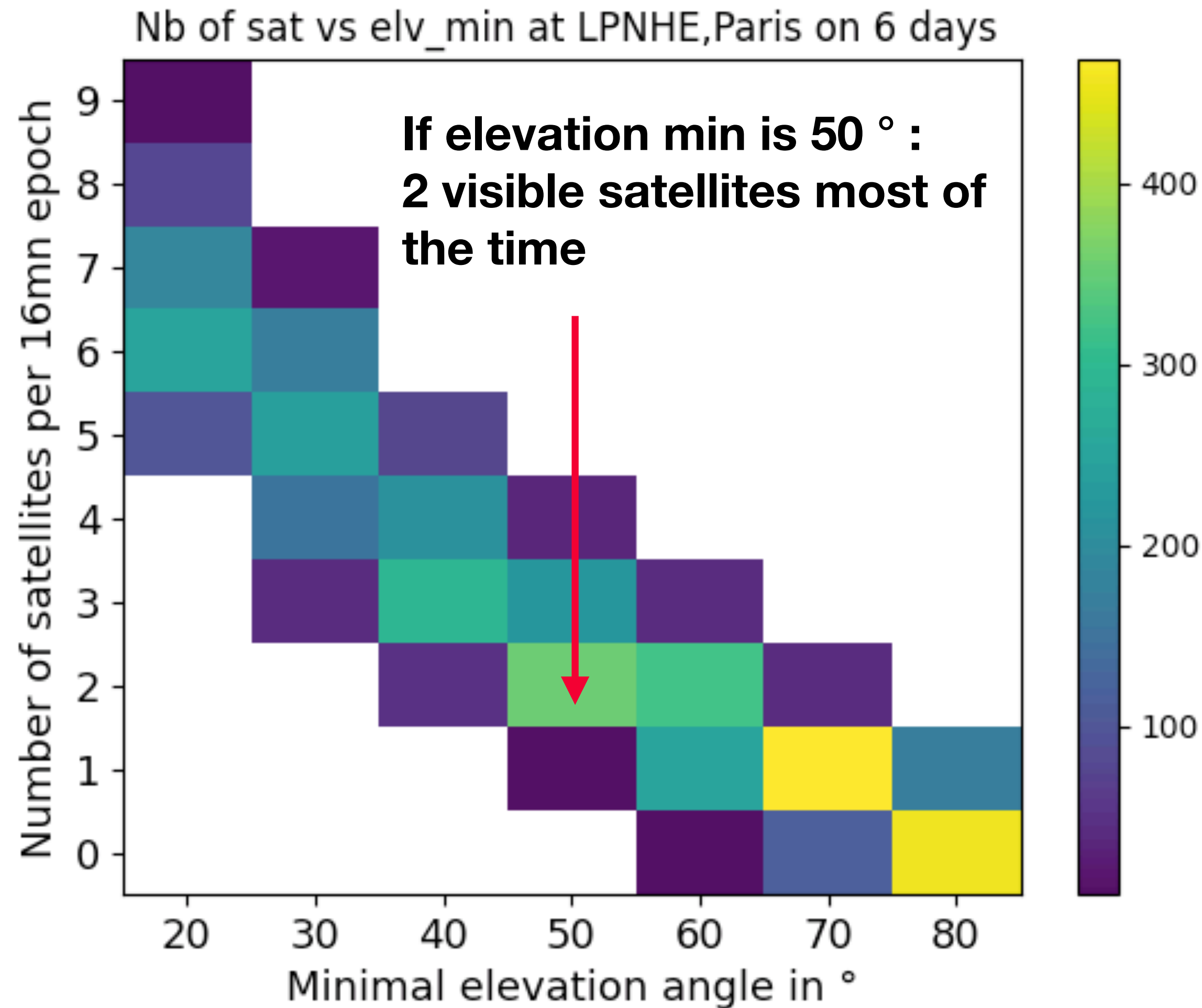
Characterization of our solution

- Cross checks to find same performances as @ SYRTE
- Test of the proposed set-up : Rb clock as an input to the receiver



Remove linear drift over time = deterministic noise of the clock

Characterization of our solution



The system has to be robust against :

- Power outage → reboot procedure + calibration
- Limited nb of visible satellites (mountain area)

Common view Time transfer technique

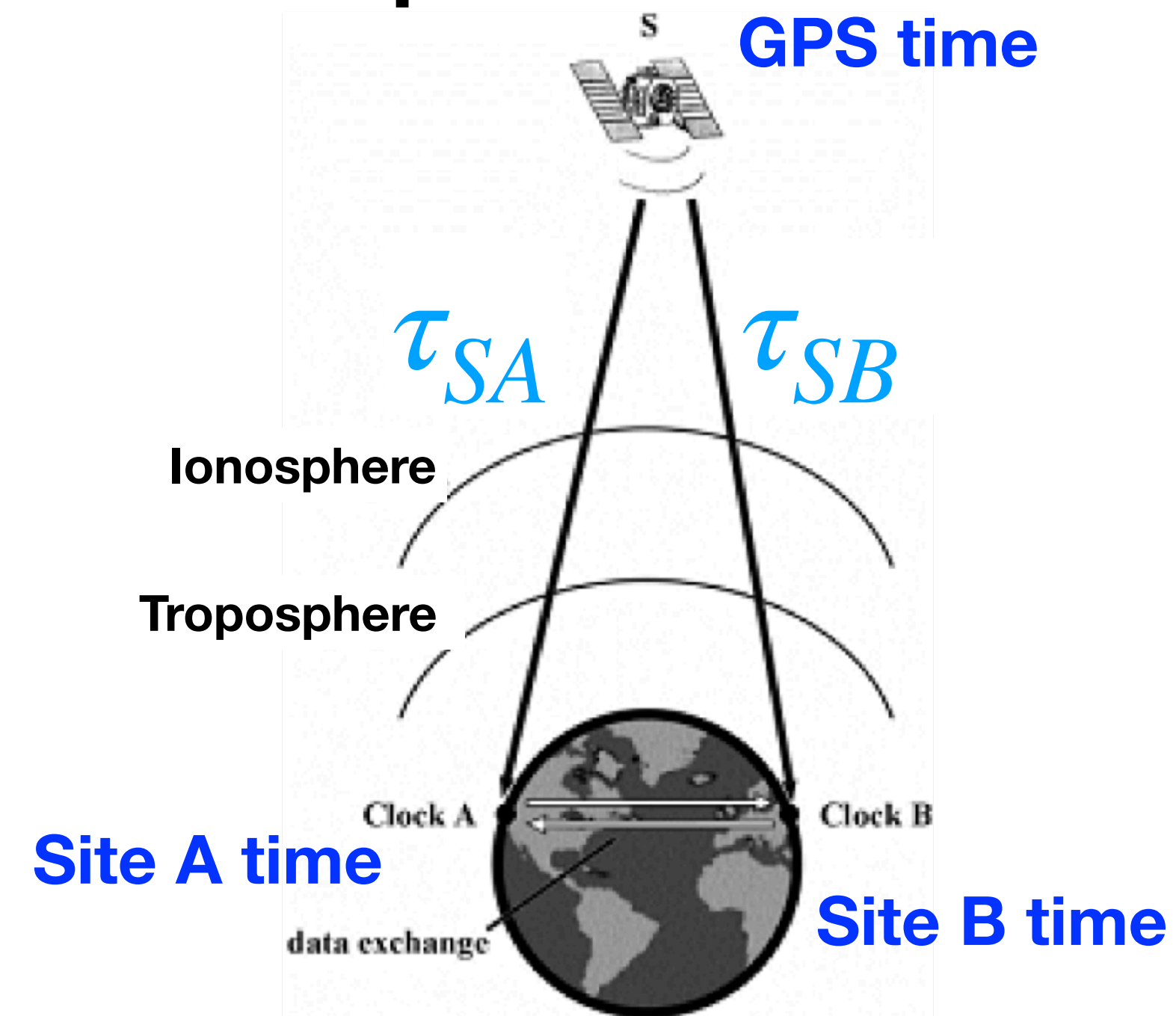
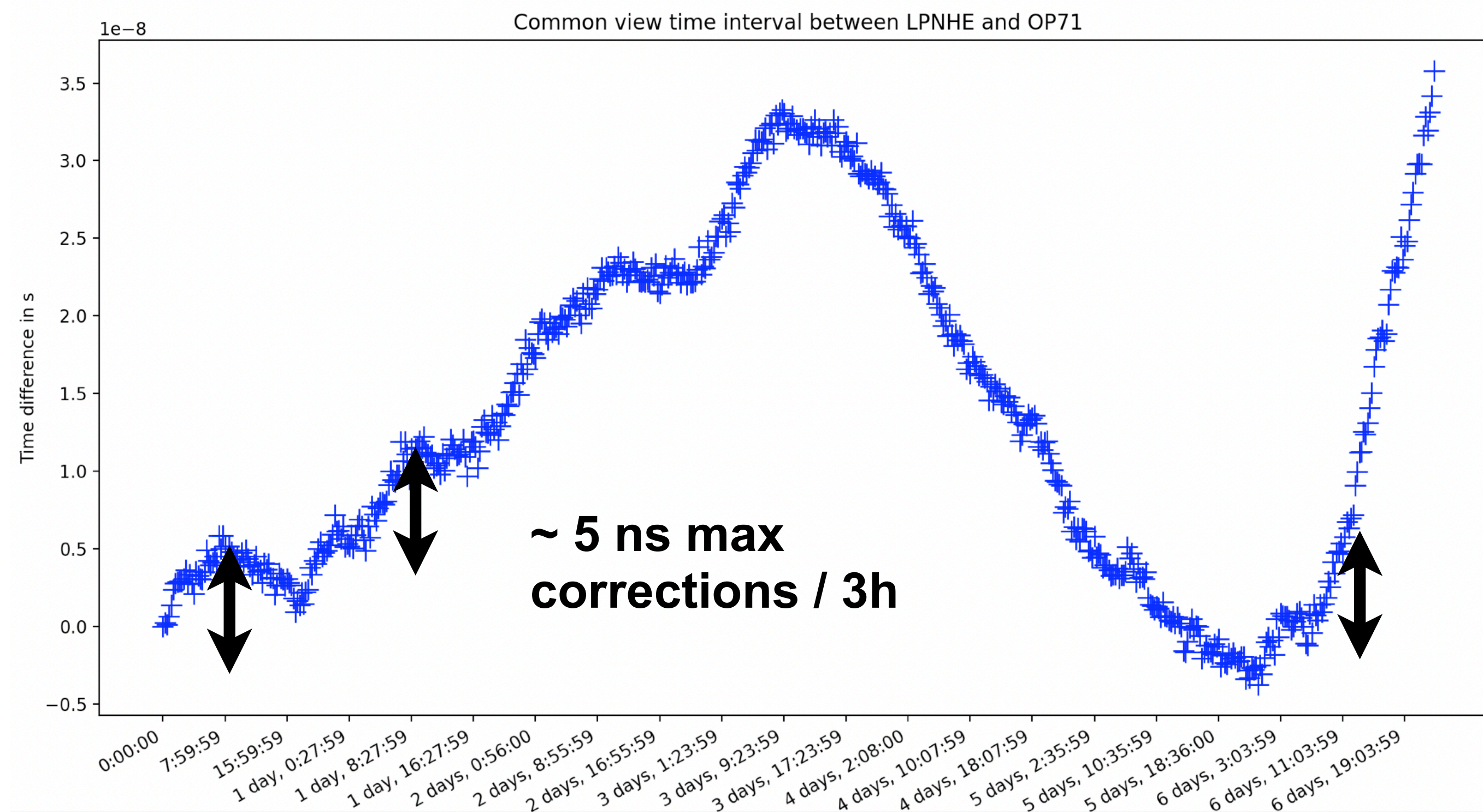
How to obtain UTC time tags / corrections ?

Site A CGGTTS data : GPS Time – SiteA Time = $\Delta t_{GPS-A} = \tau_{SA}$

Site B CGGTTS data : GPS Time – SiteB Time = $\Delta t_{GPS-B} = \tau_{SB}$

Time transfer software computes $\tau_{SA} - \tau_{SB}$

If site B is the reference time keeper : $\rightarrow \tau_{SA} - \tau_{SB} = \Delta t_{siteA}$ wrt UTC (local)



Last step of the process

Need tests and simulation to optimize the applied correction

Conclusion

- R&D has been happening for 2.5 years, almost final
- Internal HK reviews ongoing, choice this year
- Collaboration between at least 4 different groups
- Great synergy between the 2 items : digitizer and time distribution
- So far, everything seems to meet and exceed HK's requirements
 - ▶ Increase physics possibilities