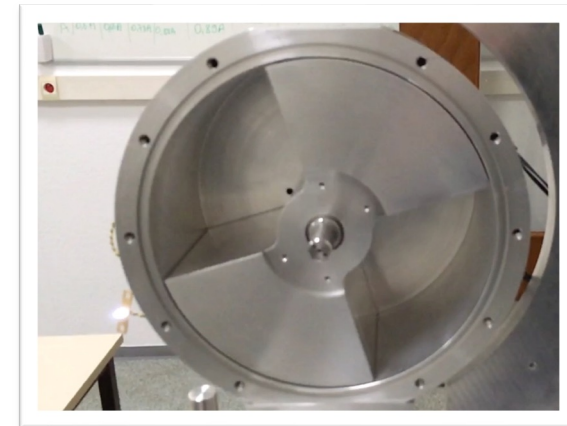


Newtonian Calibrator for Virgo (NCal)

Principle, first results, plans for O4,...

ILANCE workshop
April 15, 2022

Benoit Mours
IPHC-Strasbourg



Newtonian calibrator for Virgo



Calibration: move a mirror by a known amount to calibrate the interferometer output



NCal basic principle

▶ Rotor made of two masses

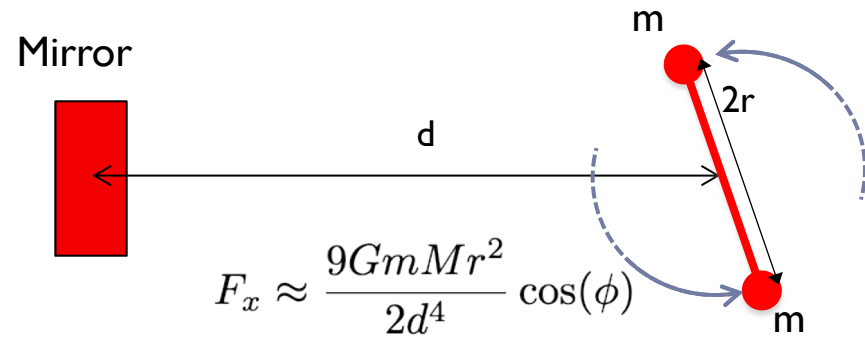
- Center of mass is not moving
- The non linear Newtonian force creates the signal
- Signal at twice the rotor frequency;
- Signal proportional to $1/d^4$ effect → Mirror to NCal distance is critical

▶ Expected benefits

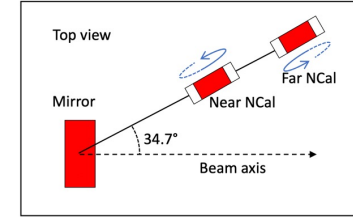
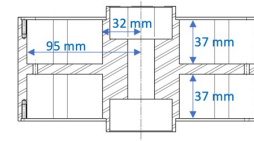
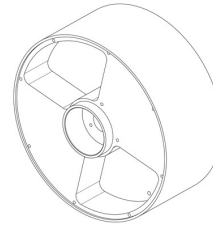
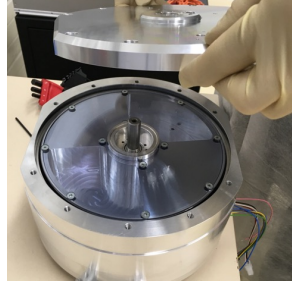
- Signal depends mainly on the rotor geometry, mass and position
 - ▶ Mass of the mirror cancels out
 - ▶ Correction for a real mirror geometry compared to point particle: around 1%
- No aging effect of the signal
- Simple interface with the detector
 - ▶ Could be moved from one mirror or ITF to another

▶ An old principle, tested during O2:

- “First test of a Newtonian calibrator on an interferometric gravitational wave detector”
CQG. 35, 235009, 2018

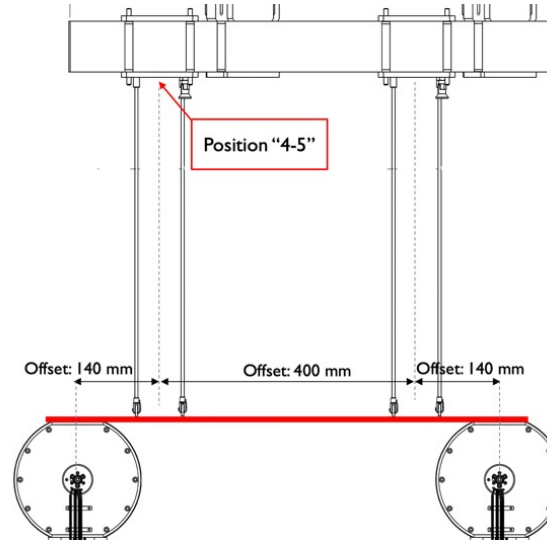
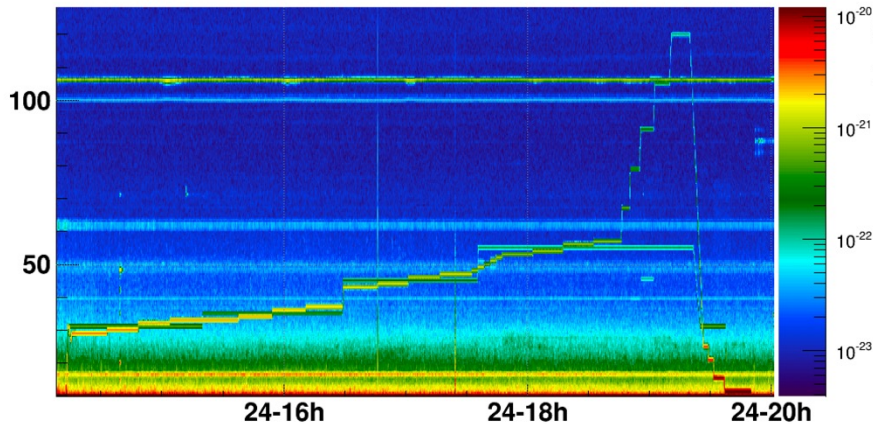


O3 setup



- ▶ Two NCals tested during O3 (build at LAPP)
 - At 1.27 and 1.95 m from the mirror → measure the NCal-mirror distance
- ▶ Most useful data set:
 - 6 hours on March 24, 2020

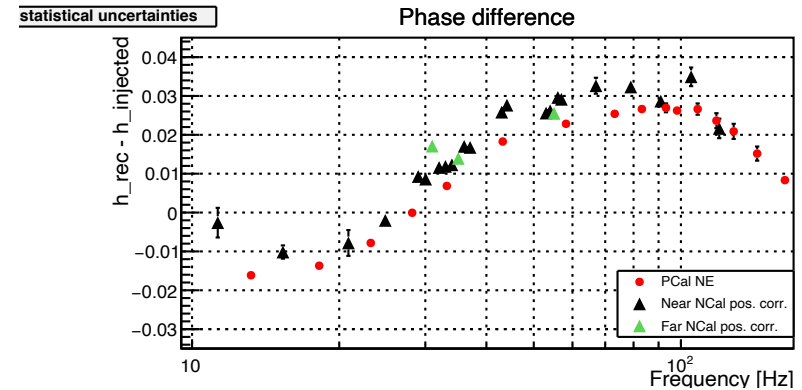
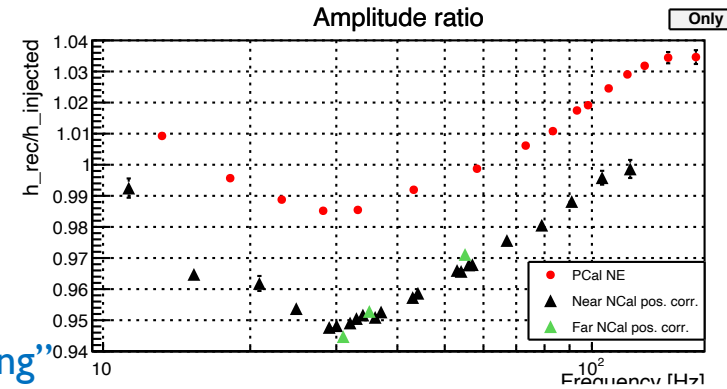
V1:Hrec_hoft_16384Hz__FFTIME



1269094100.00 : Mar 24 2020 14:08:02 UTC dt:2.00s nAv:10

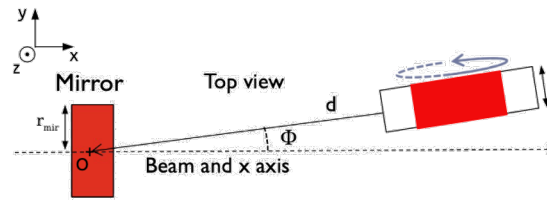
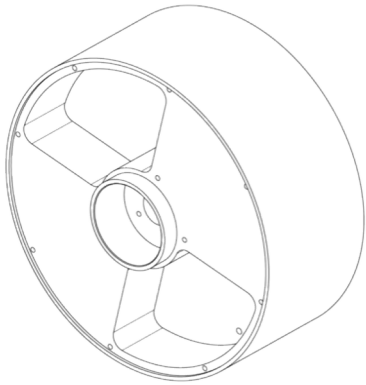
O3 results

- ▶ Accurate FEM simulation
- ▶ Results published: [CQG 38, 075012](#)
 - “Newtonian calibrator tests during the Virgo O3 data taking”
- ▶ Probing $h(t)$ up to 120 Hz (rotor @ 60 Hz)
- ▶ Same shape as PCal
- ▶ 3% amplitude offset between PCal and NCal
- ▶ Systematic uncertainties
 - At the level of the PCal uncertainties
 - Dominated by NCal-mirror distance

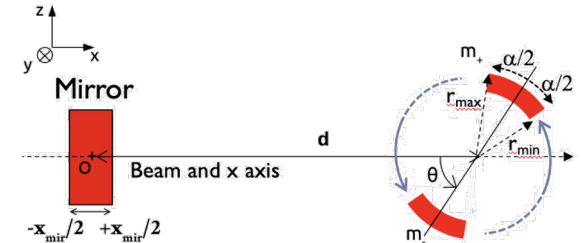


Parameter	uncertainty	formula	h_{rec}/h_{inj} near [%]	h_{rec}/h_{inj} far [%]
NCal to mirror distance d	6.4 mm	$4\delta d/d$	2.02	1.31
NCal to mirror angle Φ	5.0/3.3 mrad	$\delta\Phi \sin \Phi$	0.28	0.19
NCal vertical position z	1.3 mm	$5/2(z/d)^2$	0.03	0.01
Rotor geometry	see table 1		0.53	0.53
Modeling method	see end of section 4		0.018	0.017
Mirror torque from NCal	see end of section 4		0.05	0.03
Total	quadratic sum		2.1	1.4

Why this two 90° sector shape?



(a) Top view



(b) Side view

$$a(f_{2rot}) = \frac{9G\rho_{rot} b \sin(\alpha)(r_{max}^4 - r_{min}^4)}{32\pi^2 f_{2rot}^2 d^4} \cos(\phi) \left[1 + \frac{25}{54d^2} \frac{(r_{max}^6 - r_{min}^6)}{(r_{max}^4 - r_{min}^4)} + \left(\frac{45}{8} \sin^2(\phi) - \frac{5}{2} \right) \left(\frac{r_{mir}}{d} \right)^2 + \left(\frac{15}{8} \cos^2(\phi) - \frac{25}{24} \right) \left(\frac{x_{mir}}{d} \right)^2 - \frac{25}{72} \left(\frac{b}{d} \right)^2 \right] \quad (8)$$

- ▶ For 90° opening angle, the uncertainty goes to zero
- ▶ Rotor uncertainties are driven by:

O3 values

- Density
- Thickness
- Radius

Rotor parameter			NCal signal uncertainty	
name	value	uncertainty	formula	value (%)
Density ρ (kg/m ³)	2805	5	$\delta\rho/\rho$	0.18
Thickness b (mm)	74	0.2	$\delta b/b$	0.27
r_{max} (mm)	95	0.1	$4\delta r_{max}/r_{max}$	0.42
Total uncertainty from the rotor (quadratic sum)				0.53

NCal for O4

▶ O4 goals

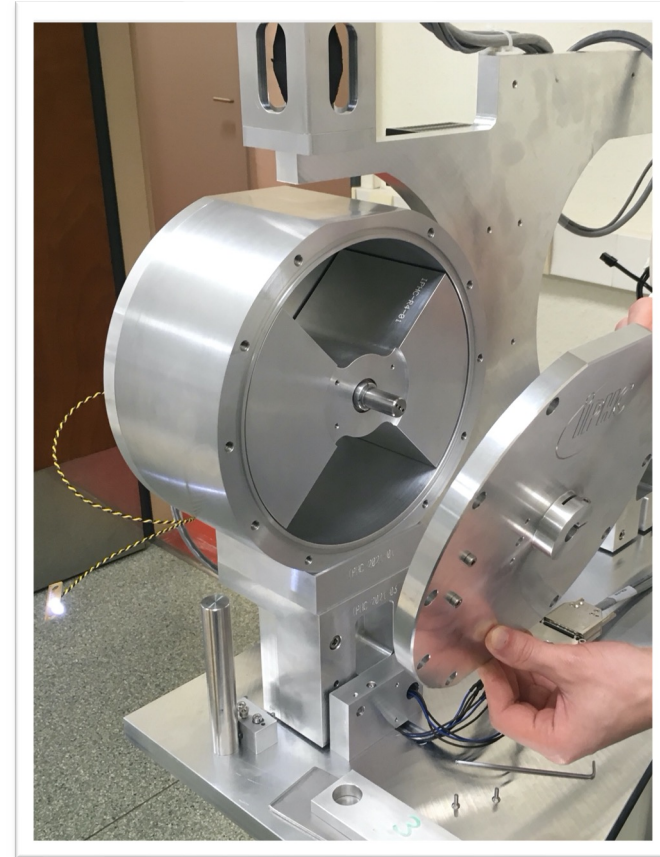
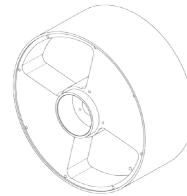
- Validate $h(t)$ within 1% in the 10-200 Hz frequency range
- Add a permanent NCal monitoring line

▶ Issues/challenges

- Accurate knowledge of the NCal geometry/material
 - ▶ → Metrology
 - ▶ → Be able to swap NCals to easily compare/crosscheck them
- Accurate knowledge of the mirror/NCal distance
 - ▶ Extract from measurements at several distances with known relative positions
 - ▶ → Several NCals,
 - ▶ → Know/survey of the relative NCal position
- Do not introduce vibrations that may shortcut the signal or spoiled the sensitivity
 - ▶ → Suspend the NCals
 - ▶ → Reduce the mechanical vibration induce by the rotors
- Reliability for long term operations

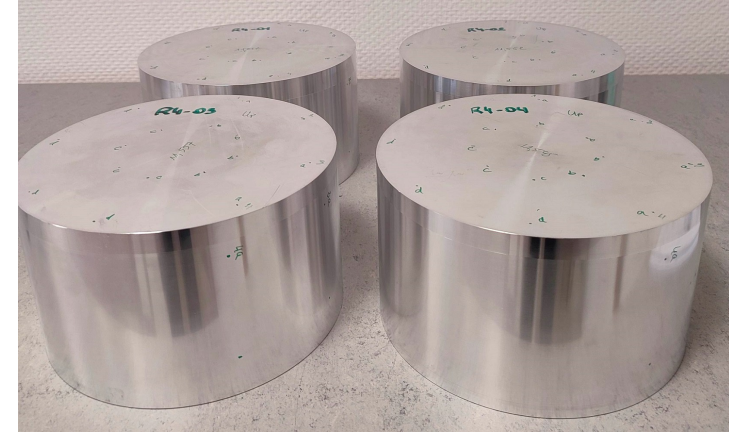
Improving the NCal rotor for O4

- ▶ Simpler geometry
 - Remove: the O3 external ring and central disk
- ▶ Make it thicker
- ▶ Benefit
 - Force x 2 compared to O3
 - Simplify the metrology and prediction
- ▶ Challenge: air motion → friction
 - Go to 70W motor
- ▶ Current test: 80 Hz rotor speed achieved
 - Will be building a three sectors rotor to probe $h(t)$ up to 200 Hz

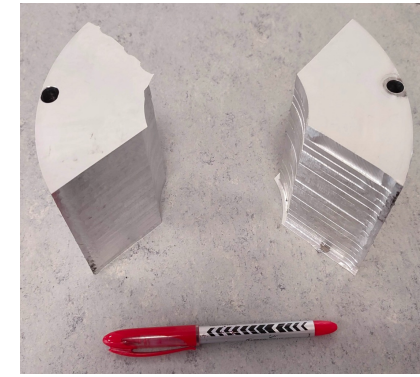
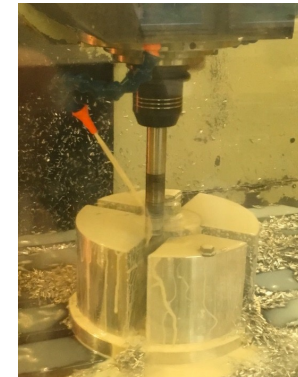
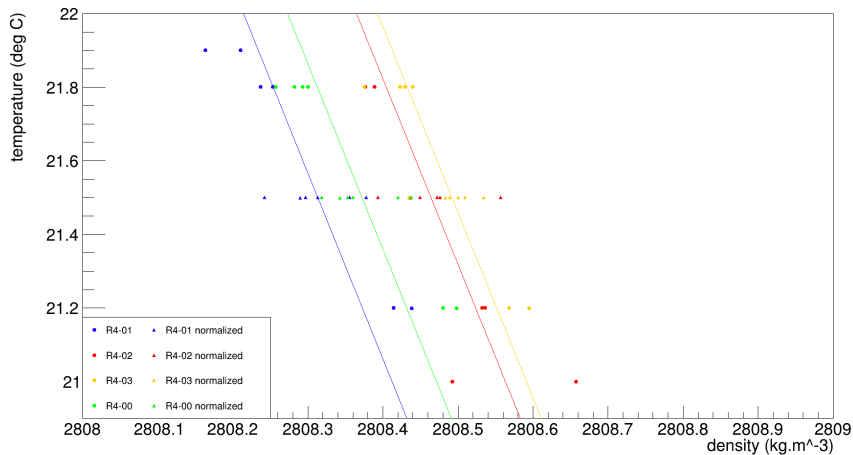


Improving the knowledge of the rotor: density

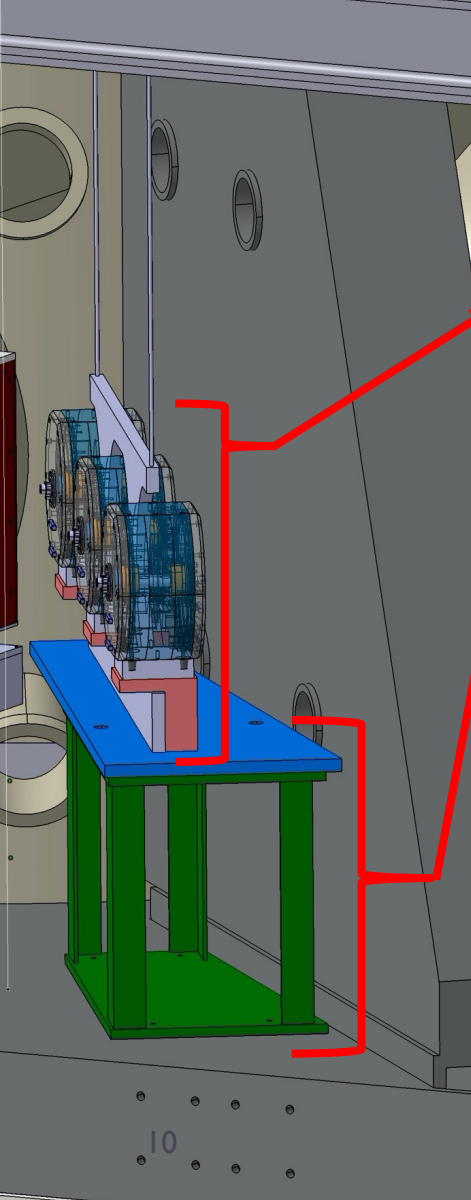
- ▶ Careful measurement of the material density
- ▶ Machine multiple blocs
- ▶ Mean density of $2808.41 \pm 0.2 \text{ kg.m}^{-3}$
 - for aluminum 7075 at $21.5 \text{ }^\circ\text{C}$
- ▶ Relative uncertainty: 0.007% (0.18 % for O3)
- ▶ Value is batch specific: could change by 10^{-3}
- ▶ Homogeneity check to better than 10^{-4}



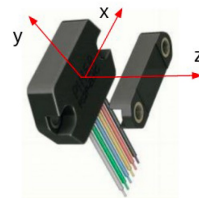
Weighted density per temperature and density normalized at 21.5 deg C

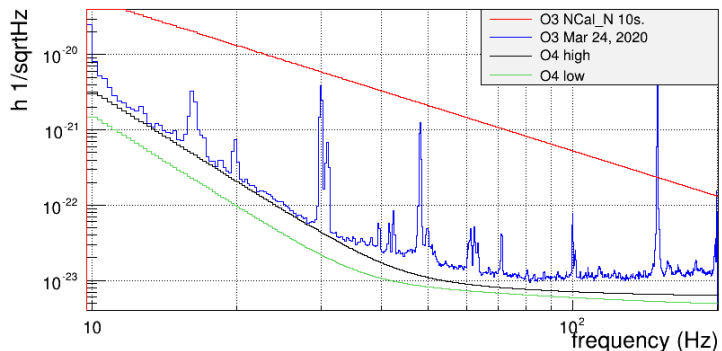


New NCal supports



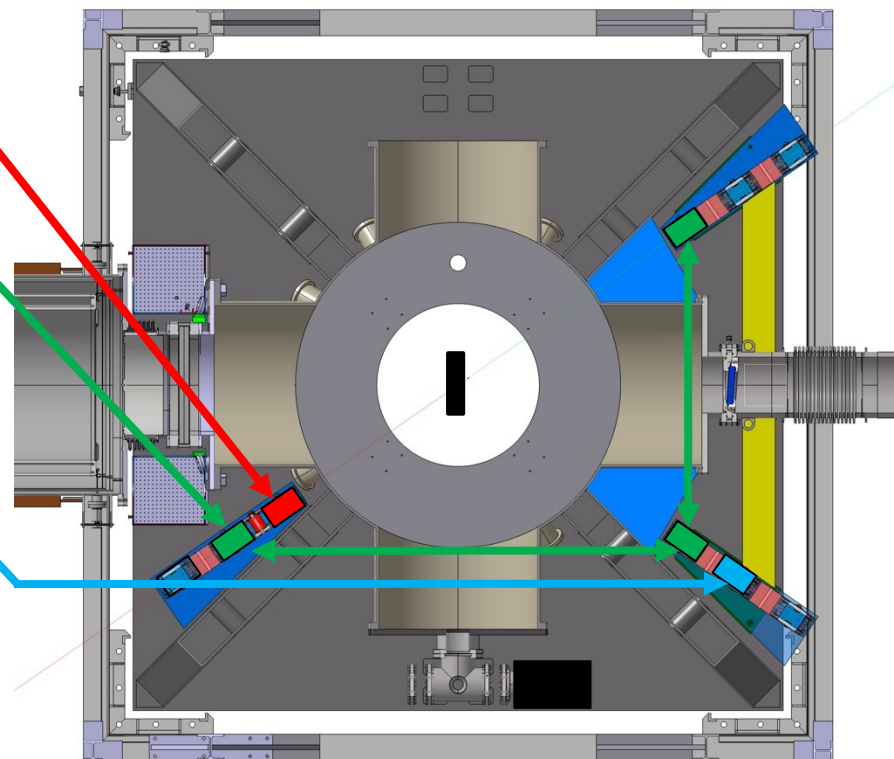
- ▶ **Suspended NCal blocs**
 - **Three slots, only one or two slots used**
 - ▶ Accurate relative positioning
 - **Simple suspension:**
 - ▶ rough filtering of NCal vibrations
- ▶ **Bottom reference**
 - **Fixed to the tower base**
- ▶ **Relative position measurement**
 - **Using linear sensors:**
 - ▶ PS2PLIN-CE-M002-I-A0-L0000-ELSI20-05.
 - **Preliminary test results:**
 - ▶ ± 6 mm range along x
 - ▶ Could tolerate ± 3 to 4 mm offsets along y and z





Layout for O4 at North End

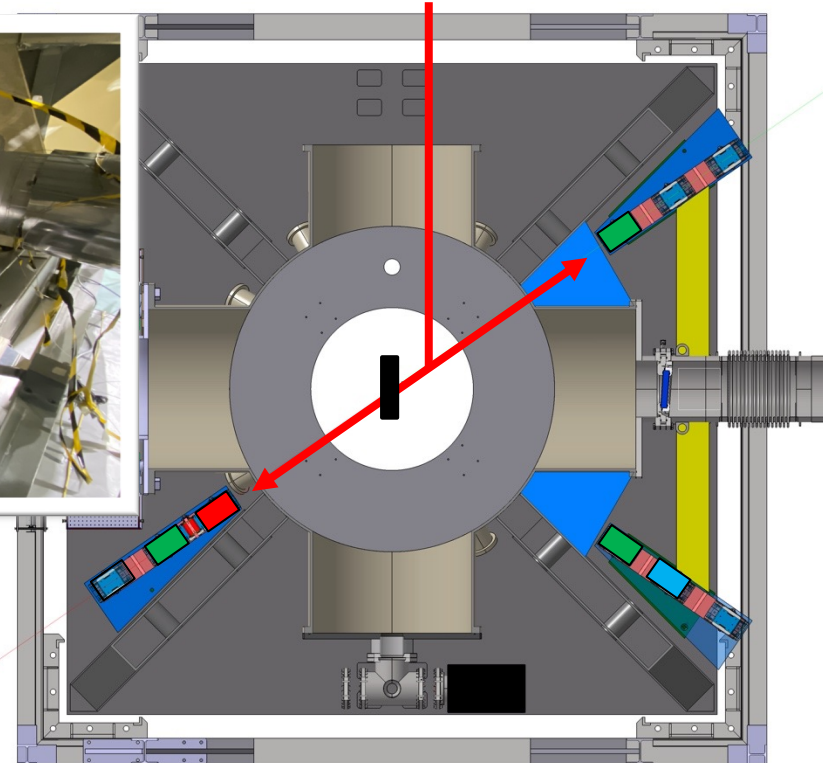
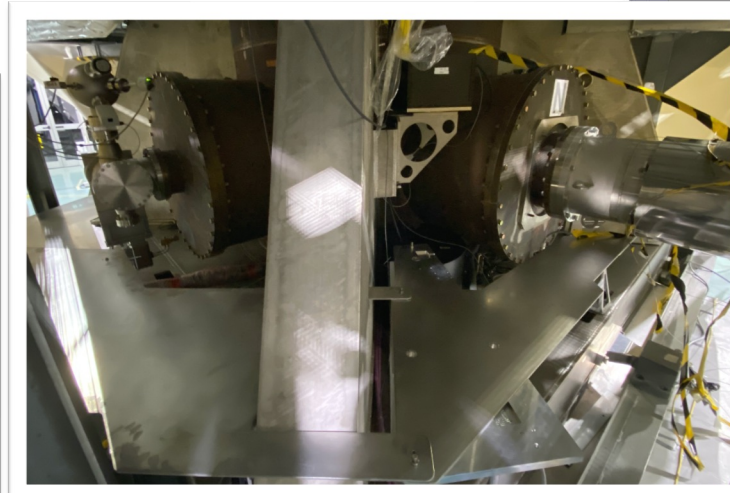
- ▶ 1 close NCal (red) for high frequency check
 - At 1.3 m from the mirror
 - ▶ Same distance as O3 NCal_N
- ▶ 3 NCals (green) for mirror position control
 - Same mirror distance to reduce model uncertainties
 - At 1.7 m from the mirror
 - ▶ Attenuation factor vs O3 NCal_N: 2.9
- ▶ 1 Far NCal (blue) for permanent line
 - At 2.1 or 2.5 m from the mirror
 - ▶ Attenuation factor vs O3 NCal_N: 6.8/13.7
 - Could be installed on any side;
 - Around 30 Hz (in $h(t)$) ?
- ▶ → Build 5+1 new NCals + positioning system



Knowing the NCal relative distance

- ▶ Use a mechanical template for installing the NCal support
- ▶ Survey their positions

North-South distance known to ± 1.3 mm



NCal foreseen operations during O4

- ▶ **Dedicated commissioning shifts to:**
 - Compare NCals strength by swapping NCals,
 - Extract mirror-NCal relative position by comparing NCal amplitudes
 - Check vertical position by moving the NCal along the vertical axis
 - Search for induced NCal noises, ...
- ▶ **Weekly, calibration period:**
 - Frequency scan and check of the mirror-NCal position
 - Should not take too much time (less than half an hour)
- ▶ **Permanent line(s) for $h(t)$ monitoring**
 - Strong enough to get a meaningful result
 - Not too strong to avoid sidebands



O5 NCal plans

- ▶ Improve the accuracy from less than 1 % (O4 goal) to less than 0.5 %.
 - Improve the knowledge (and stability) of the NCal position
- ▶ Install an NCal system on the West End tower,
 - To be able to inject accurate calibration signals on both arms.
- ▶ Extend the frequency band cover up to at least 250 Hz (in $h(t)$).
 - This corresponds roughly to the frequency where 95 % of the BNS SNR is accumulated.
 - ▶ → Work on new rotor
 - May need
 - ▶ To use denser material (could gain a factor 2.85 with stainless steel)
 - ▶ More powerful motor
 - ▶ Go to (partial vacuum)
 - ▶ Use magnetic bearing (also good to reduce the mechanical vibration)
- ▶ Fix any issue that may be observed during O4

Summary

- ▶ We will have more and better NCals for O4
- ▶ The NCal systematic uncertainties might be smaller than for PCal
... could be our absolute calibration reference for O4
- ▶ Will keep improving it for O5