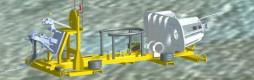
Online workshop on the evolution of advanced electronics and instrumentation for Water Cherenkov experiments - 11 April 2022

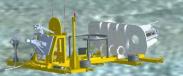
## Mechanical Design and Integration of KM3NeT

Marco Circella, INFN Bari for the KM3NeT Collaboration







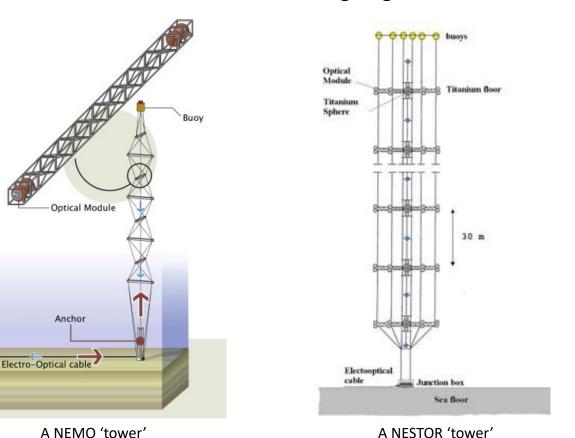


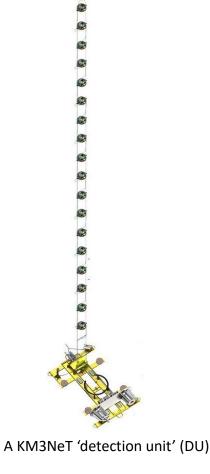
# Neutrino astronomy in the Mediterranean: the initiatives

ANTARES – first undersea neutrino telescope ever built – operated from 2006 to 2022 NEMO and NESTOR – extensive R&D programs carried out in Italy and Greece KM3NeT – construction of ARCA and ORCA ongoing



Assembly of one ANTARES 'storey'





# Neutrino astronomy in the Mediterranean: the challenges

ANTARES – first undersea neutrino telescope ever built – operated from 2006 to 2022 NEMO and NESTOR – extensive R&D programs carried out in Italy and Greece KM3NeT – construction of ARCA and ORCA ongoing



Assembly of one ANTARES 'storey'

#### Working in the (deep) sea implies:

- High pressure
- Salted water!
- Sea currents
- Optical background (<sup>40</sup>K decays and bioluminescence)
- Need to deploy and connect structures on the bottom of the sea

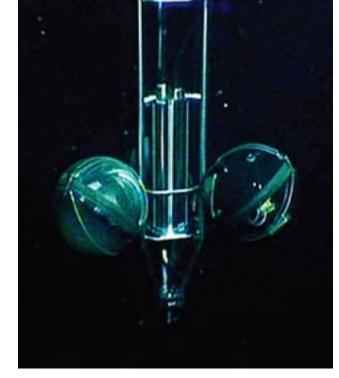


# The ANTARES 'storey'



- One electronic container
- A frame to keep all things together (including, when applicable, a hydrophone and/or a LED optical beacon)
- An electro-mechanical cable keeps the storeys (up to 25 in a line) together





One ANTARES 'storey' (in the deep sea)

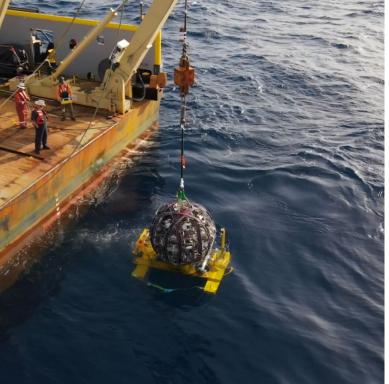
Deployment of one ANTARES line

# Principles of KM3NeT design

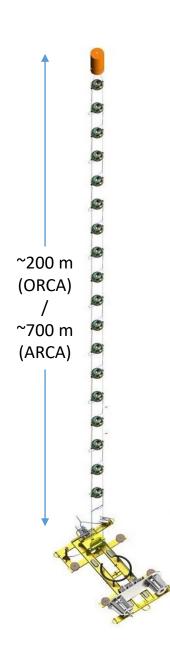


The multi-PMT Digital Optical Module (DOM) of KM3NeT • Push performance and reliability

Simplify the mechanics: reduce containers and interfaces Go for a lean detection unit structure (foldable!), easy to transport and deploy



Deployment of a KM3NeT DU



# KM3NeT: ARCA and ORCA

(Astroparticle/Oscillation Research with Cosmics in the Abyss)

**Same technology for the two detectors** – the main aim of KM3NET is:

- **ARCA**: detection of HE/VHE/UHE/etc. neutrinos from the cosmos
- ORCA: detection of «atmospheric neutrinos» with focus on neutrino mass ordering

The main differences in the ARCA and ORCA detectors are due to:

- Different size of the detectors (~9 m inter-DOM and ~20 m inter-DU distances in ORCA vs. ~36 m and ~90 m, resp., in ARCA)
- Different power systems (DC in ARCA vs. AC in ORCA, which is closer to shore)
- Different anchors and underwater connection systems (due to the different vehicles used at sea and the shorter inter-DU distance in ORCA)
- Slightly different optical communication systems (consequently)

# The DOM (Digital Optical Module)



A KM3NeT DOM (bottom view)

• 31 3" PMTs (by Hamamatsu)

- a fast LED pulser (for timing calibrations)
- an acoustic piezo-sensor + a compass/tiltmeter (for positioning)
- electronics and DAQ for data taking and communication with the shore station

All components are packed in a 17" pressure-resistant glass sphere (by Nautilus)

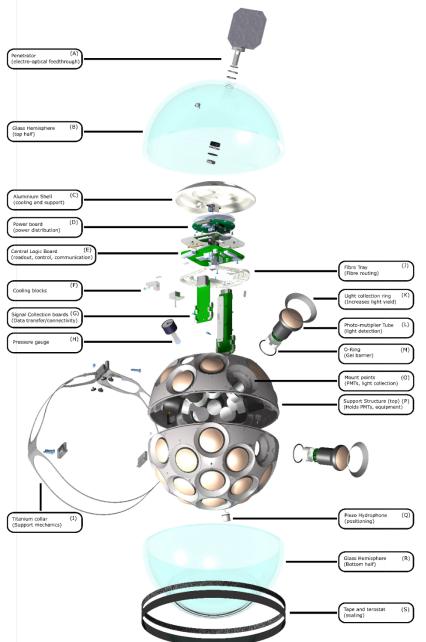
Each DOM requires: electrical power (~7W @12 VDC) and one optical fibre for communication (through a penetrator)

Advantages of the multi-PMT choice:

- large photocathode area
- large angular coverage
- sensitivity to photon direction
- improved photon counting capabilities
- possibility of local triggers
- simplified detector layout

For more details please check: <u>https://inspirehep.net/literature/2054872</u>

## The DOM structure and components





- . Section of a bottom
- support structure
- 2. Section of a top support structure
- 3. Glass hemisphere (bottom)
- 4. Bottom support structure with PMTs and light collection rings installed
- 5. Tray for routing of optical fibres
- Cooling and support mechanics (shell with rod mounted)
- 7. Power board
- 8. Central Logic Board
- 9. (Three) PMTs with base attached and light collection rings
- 10. Pressure gauge
- Signal collection boards

   (2)
- 12. Nanobeacon (led flasher) on driver board
- 13. Penetrator flange (left) and penetrator with temporary fibre/cable routing plate (right)
- 14. Piezo hydrophone
- 15. Laser transceiver

# The DU (Detection Unit)

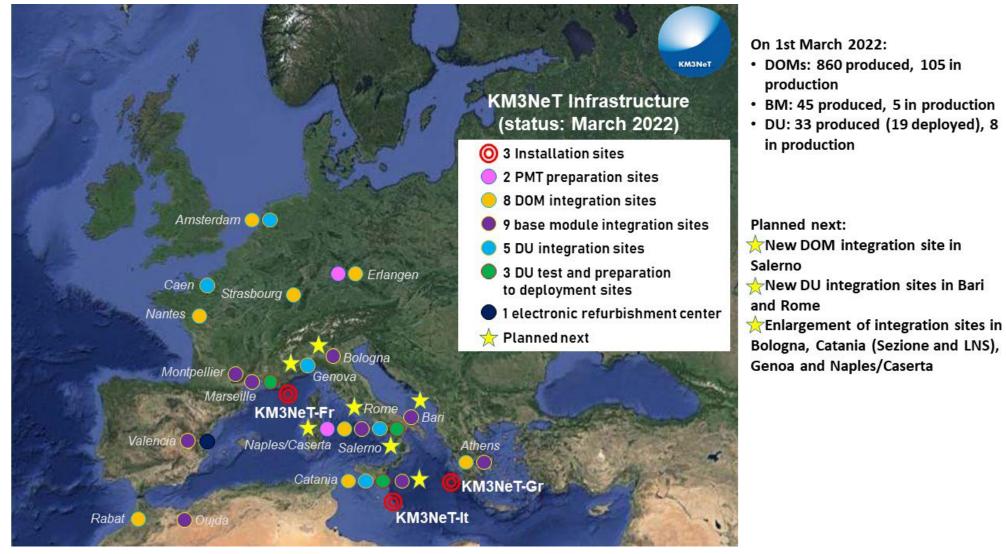
Slender, yet robust, design:

- Two ropes connect the DOMs to an anchor and a top (submersed) buoy
- The DOMs are attached to the ropes by means of a slim titanium 'collar'
- An electro-optical backbone provides each DOM with power and an optical fibre for data communication (through a break-out box connected to the penetator mounted on the DOM)
- A base module is installed on the anchor to interface the DU with the submarine cabling network

The DU can be packed on a launcher vehicle (spherical, 2 m diameter) placed on the anchor for installation

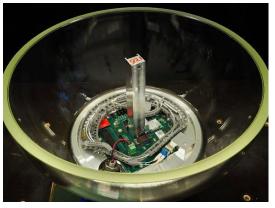


### Detector integration organization

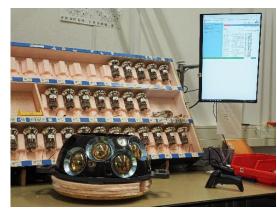


- Organization defined so as to optimize construction schedule and simplify logistics
- Flexible organization: the activities in each site can be adjusted so as to better serve the needs of ARCA and ORCA

## Integration and preparation to deployment



Mounting of DOM electronics



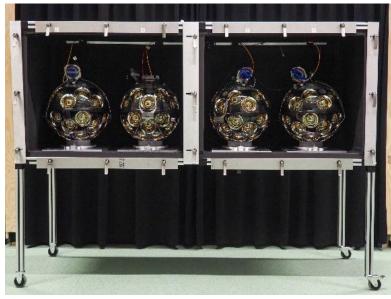
Installing the PMTs on their support structures



Pouring gel into the spheres



Sealing the sphere



Tests of integrated DOMs



Integration of a base module



#### A DU ready for deployment

# Thank you very much for your attention!

### Interested in any further details? Please don't hesitate to contact me: marco.circella@ba.infn.it

Note: you can please check our <u>Youtube channel</u> for illustration of detector construction! In particular:

- DOM and DU integration (at Nikhef, Amsterdam): <u>https://www.youtube.com/watch?v=tzxHlLgAahE</u>
- loading of launcher vehicle (for ORCA): <u>https://www.youtube.com/watch?v=TMjEQKshOqw</u>
- integration and installation of first ARCA DUs: <u>https://www.youtube.com/watch?v=tR8jwgG6uzk</u>
- installation of first ORCA DU: <u>https://www.youtube.com/watch?v=dMjN93H7Nvo</u>