

Diluted spin glass models

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The Potts model

- ▶ a model of magnetism
- ▶ a model of assortative (ferromagnetic) or disassortative (antiferromagnetic) interaction
- ▶ complexity of counting/sampling

The Potts model

- ▶ G = a (sparse) graph
- ▶ $[q] = \{1, \dots, q\}$ = set of spins/colours
- ▶ for $\sigma : V(G) \rightarrow [q]$ define

$$H_G(\sigma) = \sum_{vw \in E(G)} \mathbf{1}\{\sigma_v = \sigma_w\} = \# \text{monochromatic edges}$$

- ▶ the special case $q = 2$ is called the **Ising model**
- ▶ in the Ising model, spins are labeled ± 1

The Potts model

- ▶ the Boltzmann distribution

$$\mu_{G,\beta}(\sigma) = \frac{\exp(\beta H_G(\sigma))}{Z_{G,\beta}}$$
$$Z_G(\beta) = \sum_{\sigma} \exp(\beta H_G(\sigma))$$

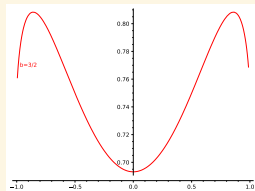
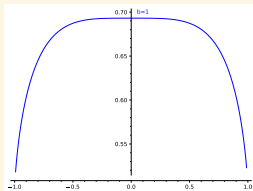
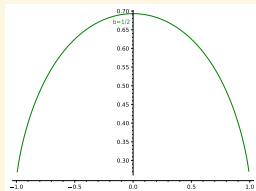
- ▶ ferromagnetic: $\beta > 0$
- ▶ anti-ferromagnetic: $\beta < 0$

The Curie-Weiss model

The Ising ferromagnet on the complete graph

- ▶ let $G = K_n$ be the complete graph
- ▶ let $q = 2$, $\beta = b/n$ with $b > 0$
- ▶ *even in this simple case, a phase transition occurs!*

The Curie-Weiss model



The partition function

We have

$$\lim_{n \rightarrow \infty} \frac{1}{n} \log Z_{K_n, \beta} = \max_{-1 \leq m \leq 1} \phi(b, m)$$

$$\phi(b, m) = \frac{bm^2}{2} - \frac{1+m}{2} \log \frac{1+m}{2} - \frac{1-m}{2} \log \frac{1-m}{2}$$

The Curie-Weiss model

Proof

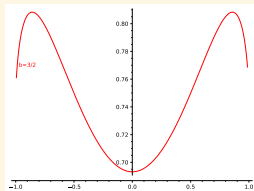
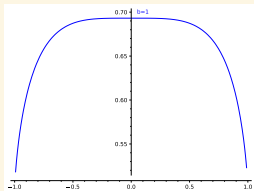
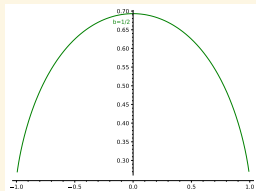
- ▶ for $\sigma \in \{\pm 1\}^n$ define $\lambda(\sigma) = \frac{1}{n} \sum_{i=1}^n \sigma(x_i)$
- ▶ then $\frac{1}{n} \sum_{i < j} \sigma(x_i) \sigma(x_j) = \frac{n}{2} - \frac{n}{2} \lambda(\sigma)^2$
- ▶ therefore,

$$Z = \exp(-\beta n/2) \sum_{\lambda} \binom{n}{n(1+\lambda)/2} \exp\left[\frac{\beta n}{2} \cdot \lambda^2\right].$$

- ▶ by Stirling's formula $\frac{1}{n} \ln \binom{n}{n(1+\lambda)/2} \sim h((1+\lambda)/2)$.
- ▶ hence,

$$Z = \exp(o(n)) \sum_{\lambda} \exp(n\phi_{\beta}(\lambda)) = \max_{\lambda} \exp(n\phi_{\beta}(\lambda) + o(n))$$

The Curie-Weiss model



The Boltzmann distribution

- ▶ for any spin i the Boltzmann distribution satisfies

$$\langle \sigma_i, \mu_{K_n, \beta} \rangle = 0$$

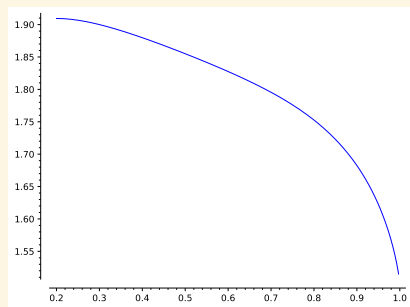
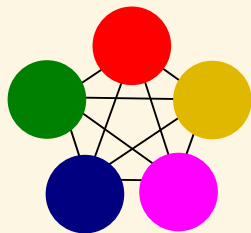
- ▶ if $b \leq 1$ then pairwise correlations disappear:

$$\langle \sigma_i \sigma_j, \mu_{K_n, \beta} \rangle = 0$$

- ▶ but for $b > 1$ pairwise correlations persist:

$$\langle \sigma_i \sigma_j, \mu_{K_n, \beta} \rangle > 0$$

The Curie-Weiss Potts model

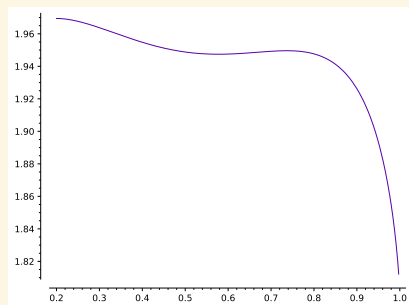
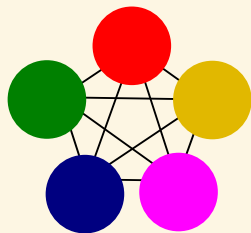


The Potts ferromagnet with $q = 5$ colours

[L21]

- ▶ unique paramagnetic
- ▶ non-unique paramagnetic
- ▶ non-unique ferromagnetic
- ▶ unique ferromagnetic

The Curie-Weiss Potts model

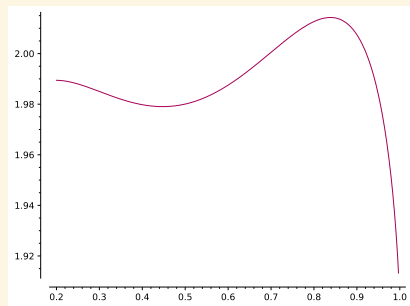
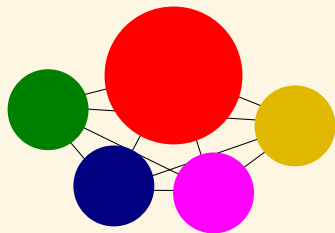


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The Curie-Weiss Potts model

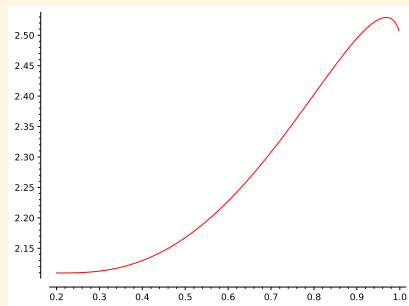
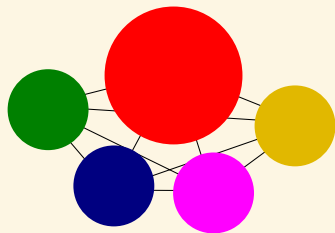


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The Curie-Weiss Potts model

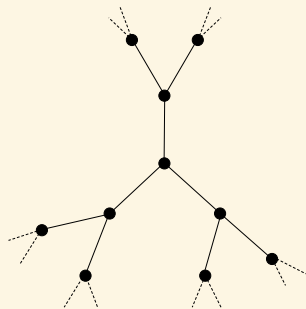


The Potts ferromagnet with $q = 5$ colours

[L21]

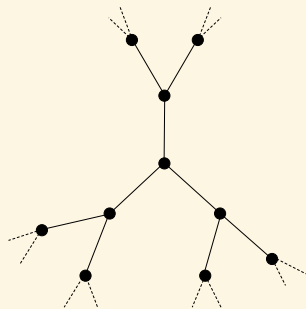
- ▶ unique paramagnetic
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The Potts model on sparse random graphs



- ▶ $\mathbb{G} = \mathbb{G}(n, d)$ = random d -regular graph
- ▶ $Z_{\mathbb{G}, \beta}$, $\mu_{\mathbb{G}, \beta}$ are random
- ▶ *what does $\mu_{\mathbb{G}, \beta}$ look like with high probability?*

The Potts model on sparse random graphs



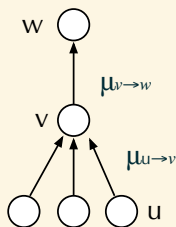
Global intuition

- ▶ the edges of \mathbb{G} are spread uniformly
- ▶ perhaps \mathbb{G} is not so different from the complete graph

Local geometry

- ▶ locally, \mathbb{G} converges to a d -regular tree
- ▶ short-range interactions matter!

The Potts model on sparse random graphs



The replica symmetric ansatz

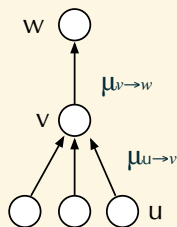
[MP00]

- ▶ assume the absence of long-range correlations
- ▶ we can write the Belief Propagation equations for **messages**

$$\mu_{v \rightarrow w}(c) \propto \prod_{u \in \partial \setminus \{w\}} \left(1 + (e^\beta - 1) \mu_{u \rightarrow v}(c) \right)$$

- ▶ these are exact on **acyclic** graphs

The Potts model on sparse random graphs



The replica symmetric ansatz

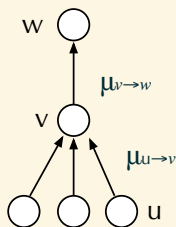
[MP00]

- ▶ the “correct” messages maximise the **Bethe free energy**

$$\mathcal{B}_{\mathbb{G}, \beta}(\boldsymbol{\mu}) = \frac{1}{n} \sum_{v \in V(\mathbb{G})} \log \sum_{c \in [q]} \prod_{u \in \partial v} \left(1 + (e^\beta - 1) \mu_{u \rightarrow v}(c) \right) - \frac{1}{n} \sum_{uv \in E(\mathbb{G})} \log \left(1 + (e^\beta - 1) \sum_{c \in [q]} \mu_{u \rightarrow v}(c) \mu_{v \rightarrow u}(c) \right)$$

- ▶ the max on $\boldsymbol{\mu}$ ought to approximate $\frac{1}{n} \log Z_{\mathbb{G}, \beta}$ w.h.p.

The Potts model on sparse random graphs



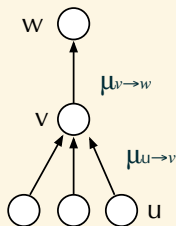
The replica symmetric ansatz

- ▶ due to regularity, we expect that all messages are *identical*

$$\mu(c) \propto (1 + (e^\beta - 1)\mu(c))^{d-1}$$

$$\mathcal{B}_{d,\beta}(\mu) = \log \sum_{c \in [q]} \left(1 + (e^\beta - 1)\mu(c)\right)^d - \frac{d}{2} \log \left(1 + (e^\beta - 1) \sum_{c \in [q]} \mu(c)^2\right)$$

The Potts model on sparse random graphs



[GSVY13]

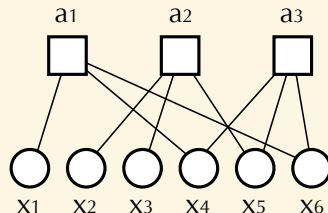
Theorem

For all $d \geq 3, q \geq 2, \beta > 0$ we have

$$\lim_{n \rightarrow \infty} \frac{1}{n} \log Z_{\mathbb{G}, \beta} = \max_{\mu} \mathcal{B}_{d, \beta}(\mu)$$

in probability.

Belief Propagation on factor graphs

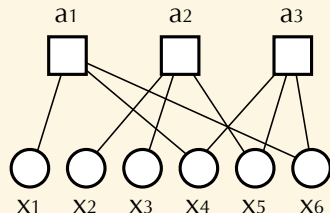


Factor graphs

A factor graph G comprises

- ▶ variable nodes $V(G)$ ranging over a finite $\Omega \neq \emptyset$
- ▶ factor nodes $F(G)$
- ▶ a **weight function** $\psi_a : \Omega^{\delta a} \rightarrow [0, \infty)$ for each $a \in F(G)$

Belief Propagation on factor graphs

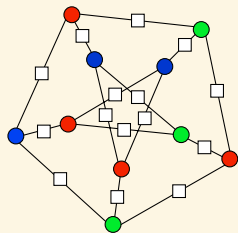


The Boltzmann distribution

$$\mu_G(\sigma) = \frac{1}{Z_G} \prod_{a \in F(G)} \psi_a(\sigma_{\partial a}) \quad (\sigma \in \Omega^{V(G)})$$

$$Z_G = \sum_{\sigma \in \Omega^{V(G)}} \prod_{a \in F(G)} \psi_a(\sigma_{\partial a}) \quad (\sigma \in \Omega^{V(G)})$$

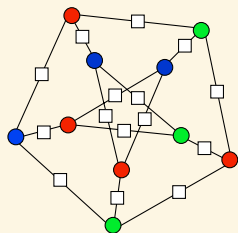
Belief Propagation on factor graphs



Example: Potts model

- ▶ $\Omega = [q] = \{1, \dots, q\}$
- ▶ $\psi_a(\sigma) = \exp(\beta \mathbf{1}\{\exists c \in [q] \forall x \in \partial a : \sigma_x = c\})$

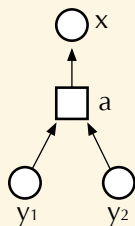
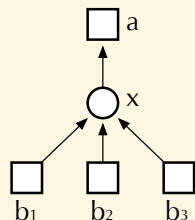
Belief Propagation on factor graphs



Random factor graphs

- ▶ a lot of the time we study sparse *random* factor graphs
- ▶ examples of this include binomial random graphs or random regular graphs
- ▶ “planted” models such as the stochastic block model

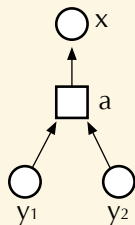
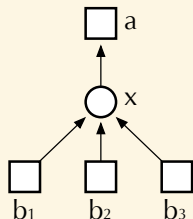
Belief Propagation on factor graphs



Belief Propagation

- ▶ associate messages $\mu_{G,x \rightarrow a}(\cdot)$, $\mu_{G,a \rightarrow x}(\cdot)$ with the edges
- ▶ each message is a probability distribution on Ω

Belief Propagation on factor graphs

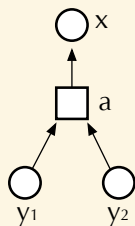
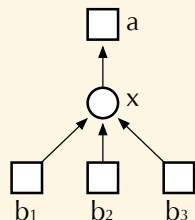


Belief Propagation

$$\mu_{G,x \rightarrow a}(s) \propto \prod_{b \in \partial x \setminus a} \mu_{G,b \rightarrow x}(s)$$

$$\mu_{G,a \rightarrow x}(s) \propto \sum_{\sigma \in \Omega^{\partial a}} \mathbf{1}\{\sigma_x = s\} \psi_a(\sigma) \prod_{y \in \partial a \setminus x} \mu_{G,y \rightarrow a}(\sigma_y)$$

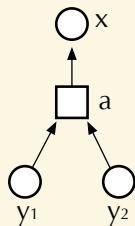
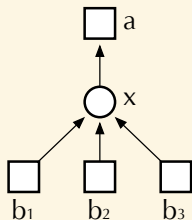
Belief Propagation on factor graphs



The Bethe free entropy

$$\begin{aligned}\mathcal{B}_G &= \sum_{x \in V(G)} \log \sum_{s \in \Omega} \prod_{a \in \partial x} \mu_{G, a \rightarrow x}(s) \\ &+ \sum_{a \in F(G)} \log \sum_{\sigma \in \Omega^{\partial a}} \psi_a(\sigma) \prod_{y \in \partial a} \mu_{G, y \rightarrow a}(\sigma_y) \\ &- \sum_{a \sim x} \log \sum_{s \in \Omega} \mu_{G, a \rightarrow x}(s) \mu_{G, x \rightarrow a}(s)\end{aligned}$$

Belief Propagation on factor graphs



The replica symmetric “solution”

$$\log Z_G = \mathcal{B}_G + o(n)$$

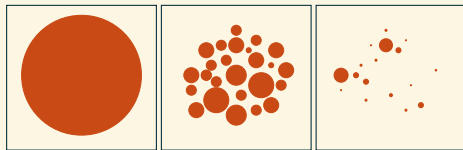
Bethe states and replica symmetry breaking

Replica symmetry breaking

[MP00,KMRTSZ07]

- ▶ the replica symmetric “solution” sometimes turns out to be correct
- ▶ **Example:** the Potts ferromagnet on $\mathbb{G}(n, d)$
- ▶ but not *always*
- ▶ **Example:** the Potts anti-ferromagnet on $\mathbb{G}(n, d)$ at low temperature

Bethe states and replica symmetry breaking

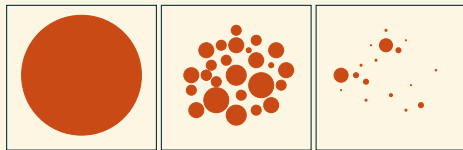


Replica symmetry breaking

[MP00,KMRTSZ07]

- ▶ replica symmetry
- ▶ dynamic replica symmetry breaking
- ▶ (static) replica symmetry breaking

Bethe states and replica symmetry breaking

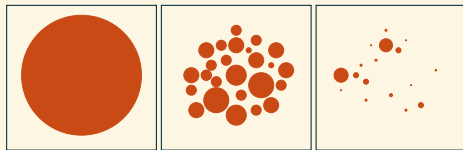


Replica symmetry

[MP00,KMRTSZ07]

$$\mu_{\mathbb{G},\beta}(\{\sigma_{x_1} = s, \sigma_{x_2} = t\}) \sim \mu_{\mathbb{G},\beta}(\{\sigma_{x_1} = s\})\mu_{\mathbb{G},\beta}(\{\sigma_{x_2} = t\})$$

Bethe states and replica symmetry breaking



Bethe states

[MPRTRLZ99,MP00,KMRTSZ07]

- ▶ the phase space decomposes into **pure states**
- ▶ in disordered system their locations are “unpredictable”
- ▶ each of them induces a BP fixed point (but not vice versa)
- ▶ in the presence of hard constraints, freezing may occur

Summary

- ▶ ferromagnetic models possess the “obvious” pure states
- ▶ these can be captured cleanly by BP
- ▶ replica symmetry breaking in disordered systems
- ▶ **prediction:** non-trivial decomposition into Bethe states