



Fast Parameter Estimation for Massive Black Hole Binaries with Normalising Flows

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Systèmes de Référence Temps-Espace

MASSIVE BLACK HOLE BINARIES EM COUNTERPARTS

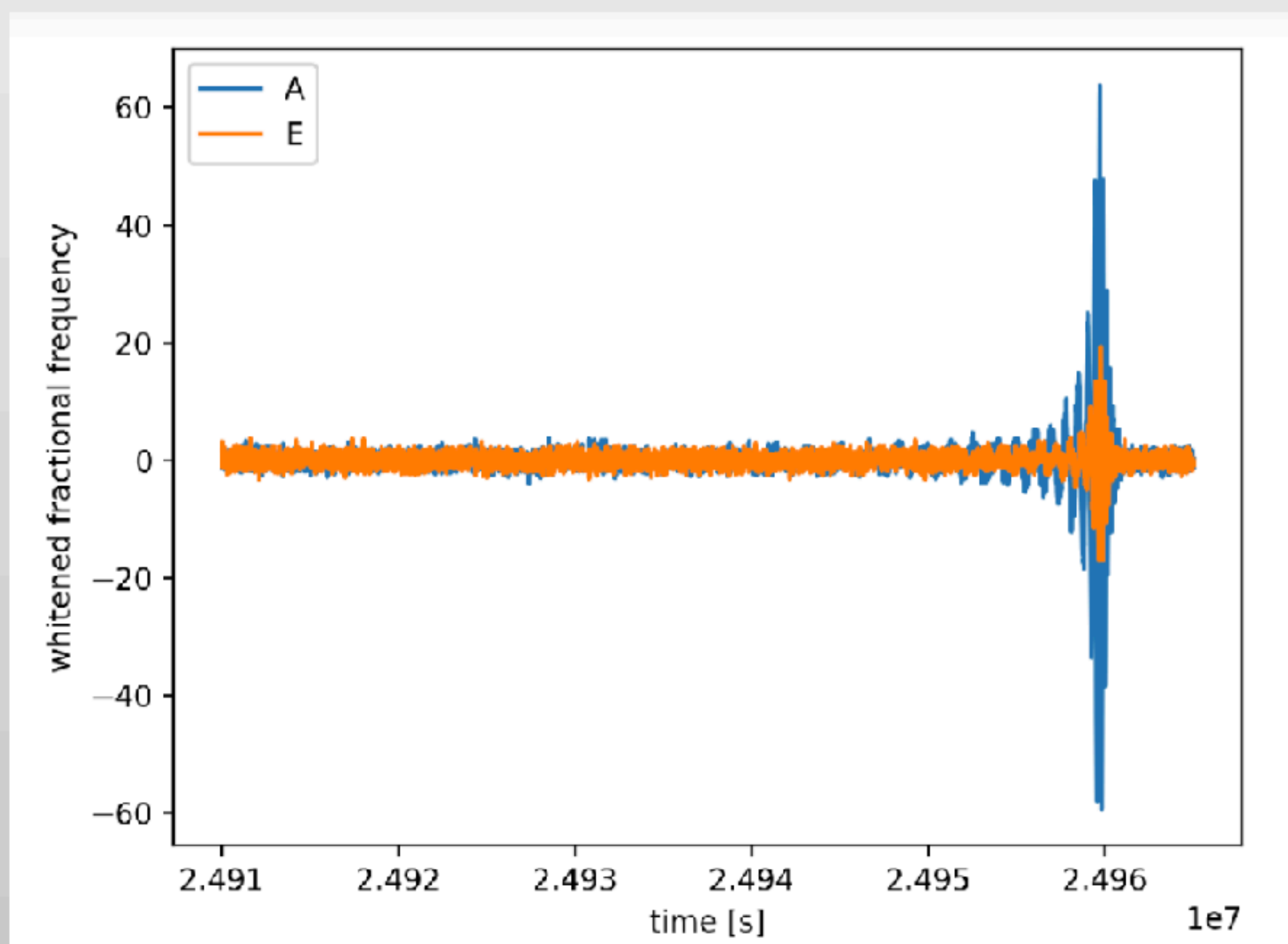
Multiple authors suggest that the electromagnetic counterparts will be observed as a transient during merger or also during inspiral and merger.

Electromagnetic counterparts will occur due to presence of

- matter or
- magnetic fields.

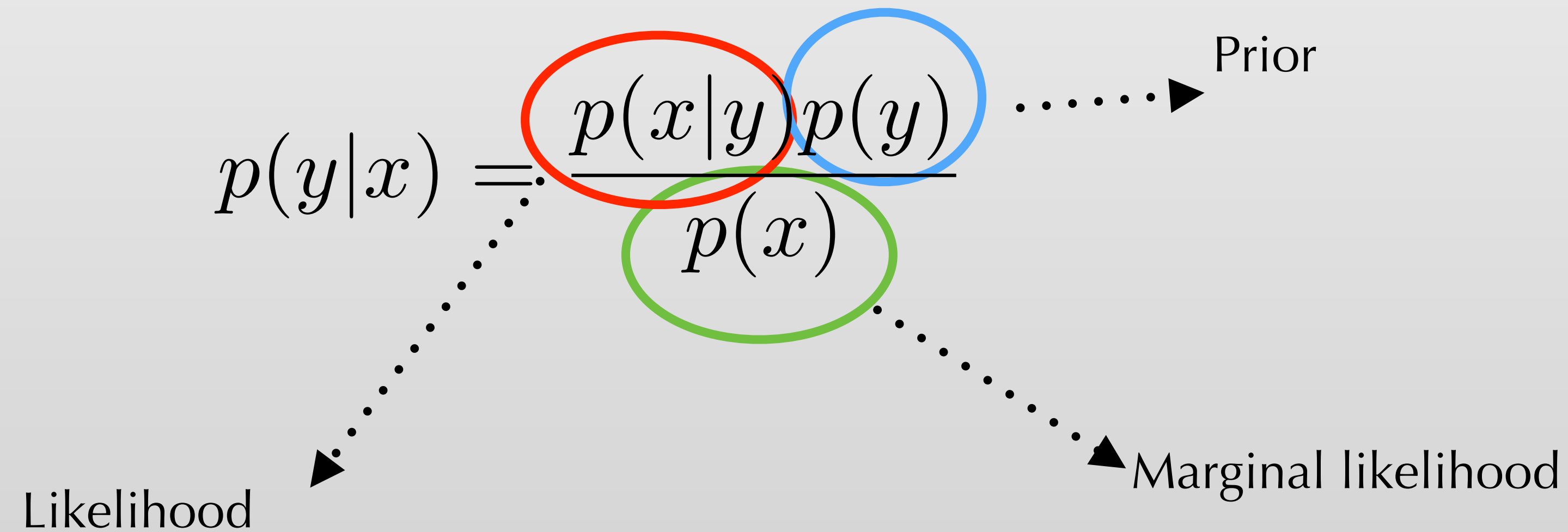
For example:

- Accretion during merger
- Jets produced by the external magnetic fields
- ...



INFERENCE

We can estimate the posterior probability distribution of the parameters using Bayes' theorem



INFERENCE

The problem is that we have to compute marginal likelihood for the observation:

$$p(\mathbf{x}) = \int p(\mathbf{x}, \mathbf{z}) d\mathbf{z}$$

That are the difference way to estimate marginal probability



INFERENCE

It is not possible to perform exact inference for the general problem.
We have to introduce some simplifications.

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We can use approximate inference:

- Sample from the exact posterior: MCMC or Nested sampling (slow)
- Variational Inference: approximate the posterior distribution with a tractable distribution

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There are some exceptions for the models with some simplifications:

- Gaussian mixture models (Very simplified)
- **Invertible models**



INVERTIBLE TRANSFORM

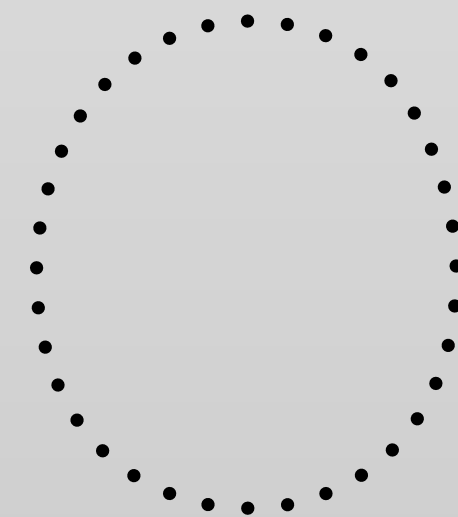
The basic idea:

INVERTIBLE TRANSFORM

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1. we have a simple random generator;

$$z \sim f_Z(z)$$



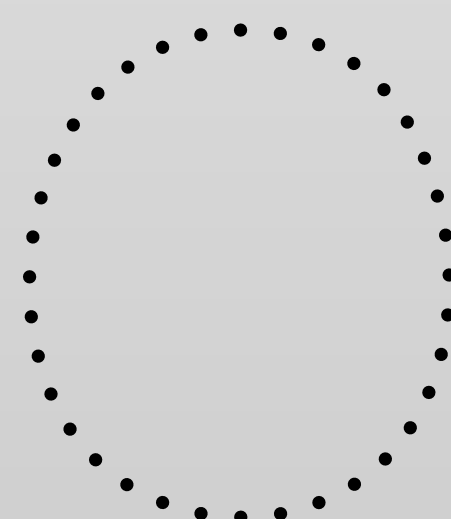
For example: $z \sim \mathcal{N}(0, 1)$

INVERTIBLE TRANSFORM

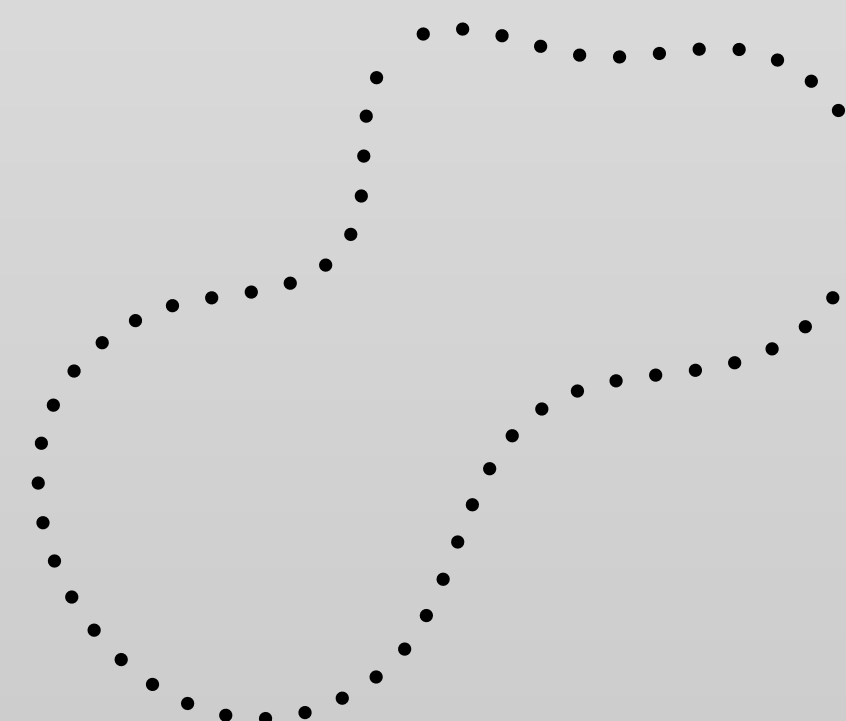
The basic idea:

1. we have a simple random generator;
2. we want want to transform it to be able to sample from a more complex distribution expression for which we do not know;

$$z \sim f_Z(z)$$



$$y \sim f_Y(y)$$



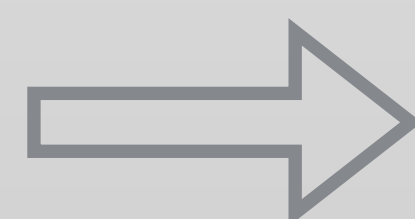
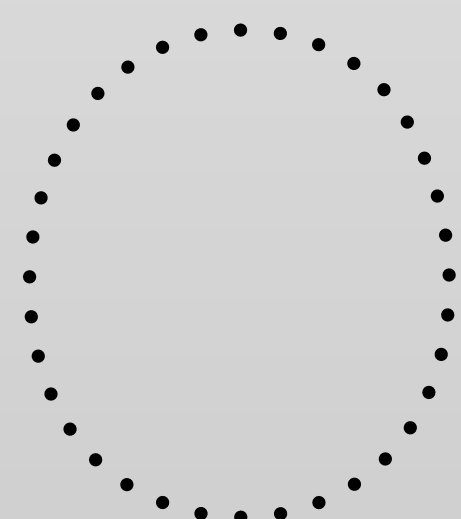
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INVERTIBLE TRANSFORM

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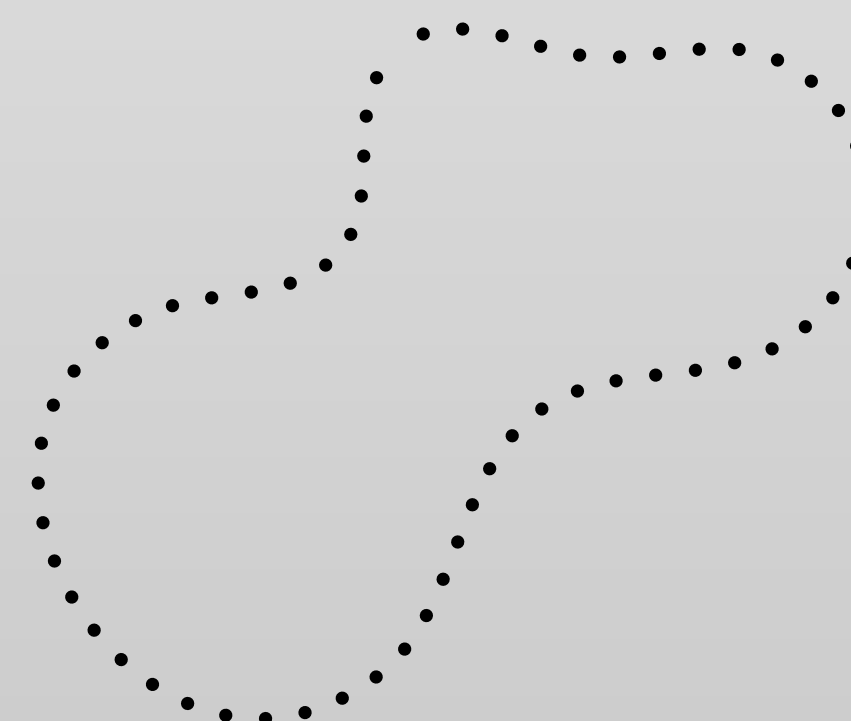
1. we have a simple random generator;
2. we want want to transform it to be able to sample from a more complex distribution expression for which we do not know;
3. we pass it through a *bijection* transformation to produce a more complex variable.

$$z \sim f_Z(z)$$



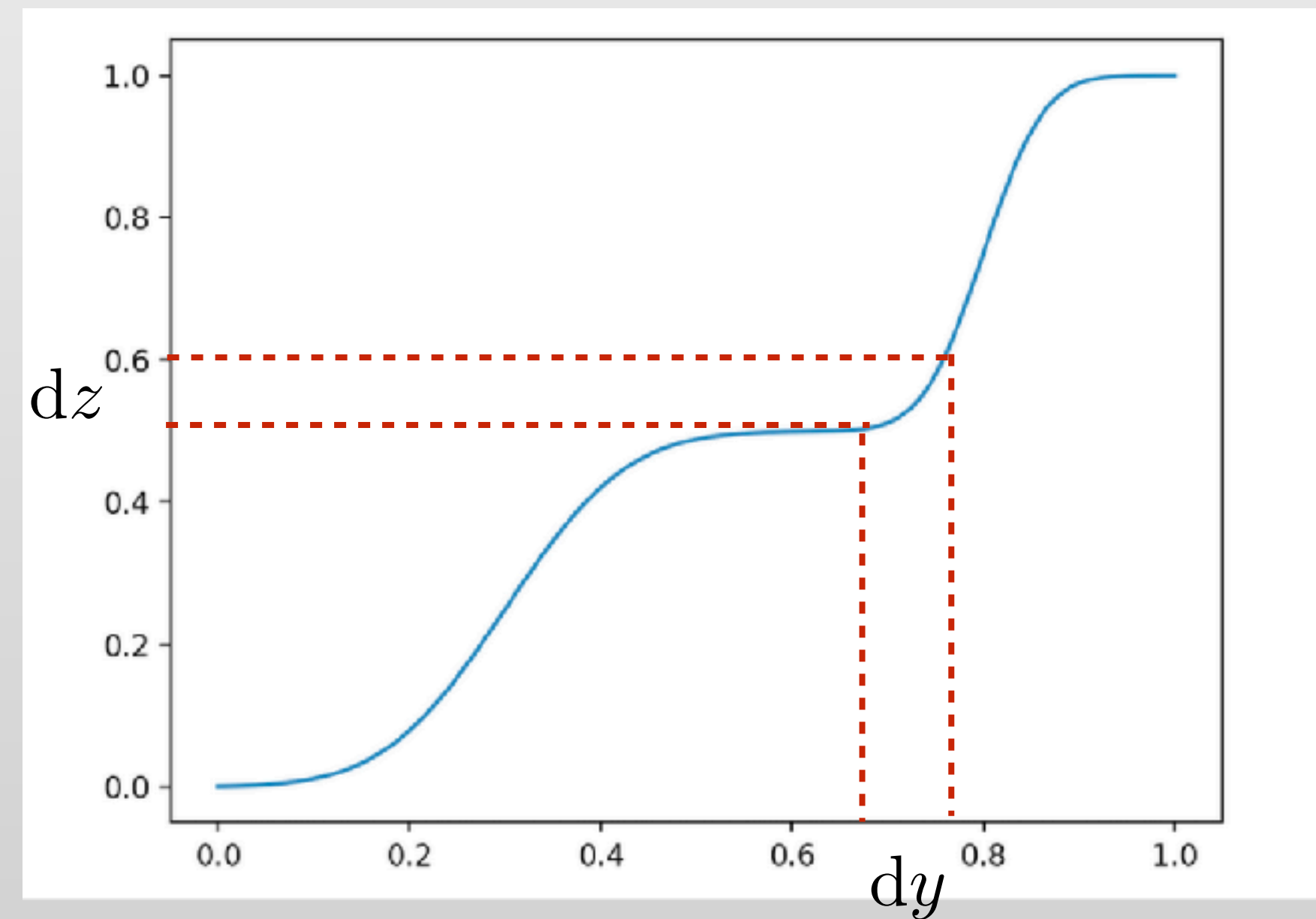
$$y = g(z)$$

$$y \sim f_Y(y)$$



For example: $z \sim \mathcal{N}(0, 1)$

CHANGE OF VARIABLE



$$f_Z(z)dz = f_Y(y)dy$$

$$f_Y(y) = f_Z(z) \left| \frac{dz}{dy} \right|$$

CHANGE OF VARIABLE

$$f_Y(y) = \frac{d}{dy} F_Y(y)$$

$$= \frac{d}{dy} F_Z(g^{-1}(y))$$

Chain rule

$$= f_Z(g^{-1}(y)) \left| \frac{d}{dy} g^{-1}(y) \right|$$

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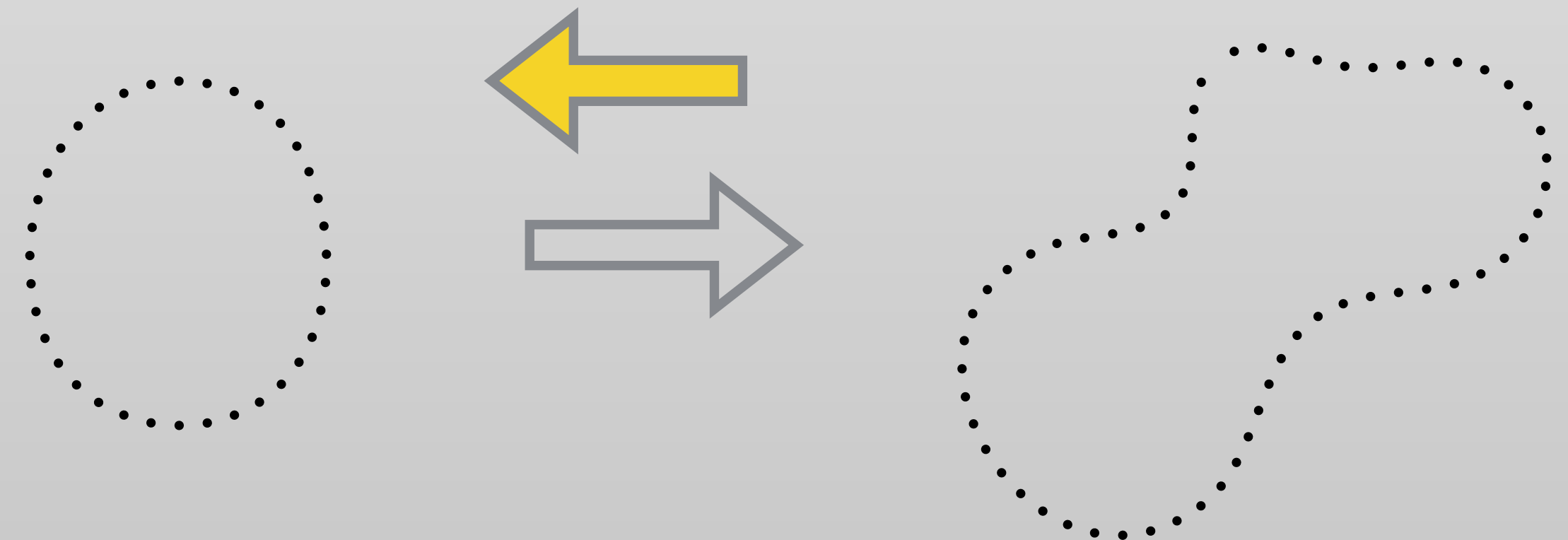
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$$= f_Z(g^{-1}(y)) \left| \frac{d}{dy} g^{-1}(y) \right|$$

Multidimensional case

$$f_Y(y) = f_Z(g^{-1}(y)) \left| \det \frac{\partial g^{-1}(y)}{\partial y} \right|$$

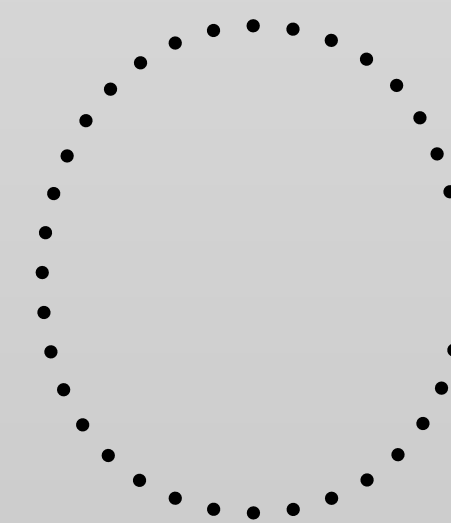
$g^{-1}(y)$



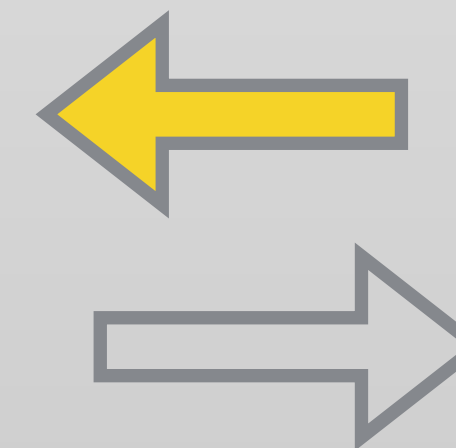
CHANGE OF VARIABLE

$$\log[f_Y(y)] = \log[f_Z(g^{-1}(y))] + \log \left[\left| \det \frac{\partial g^{-1}(y)}{\partial y} \right| \right]$$

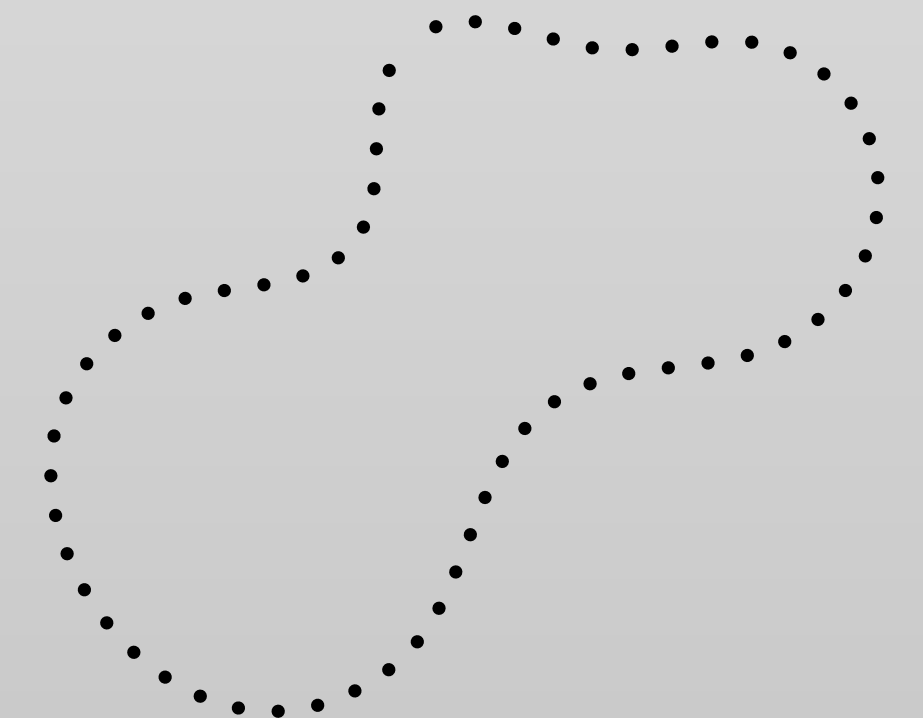
$z \sim f_Z(z)$



$g^{-1}(y)$



$y \sim f_Y(y)$

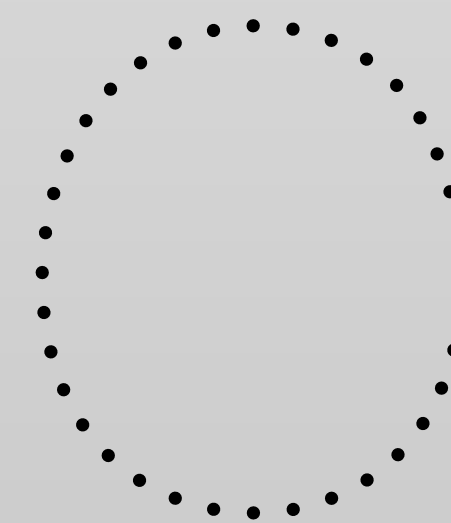


CHANGE OF VARIABLE

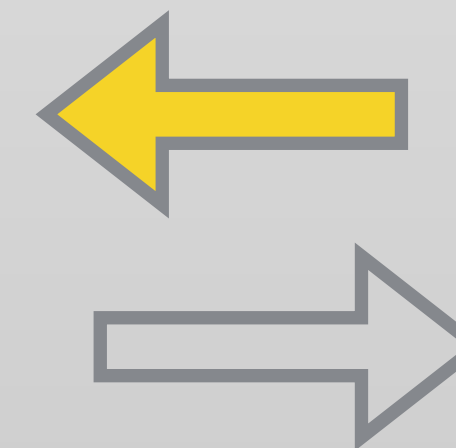
$$\log[f_Y(y)] = \log[f_Z(g^{-1}(y))] + \log \left[\left| \det \frac{\partial g^{-1}(y)}{\partial y} \right| \right]$$

1. $g(y)$ has to be a bijection

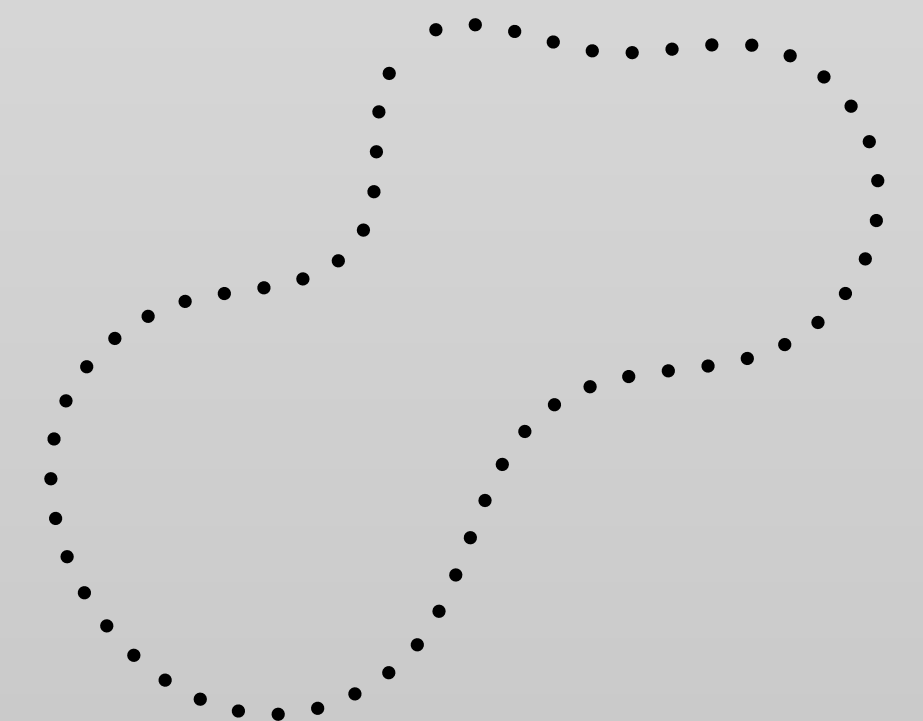
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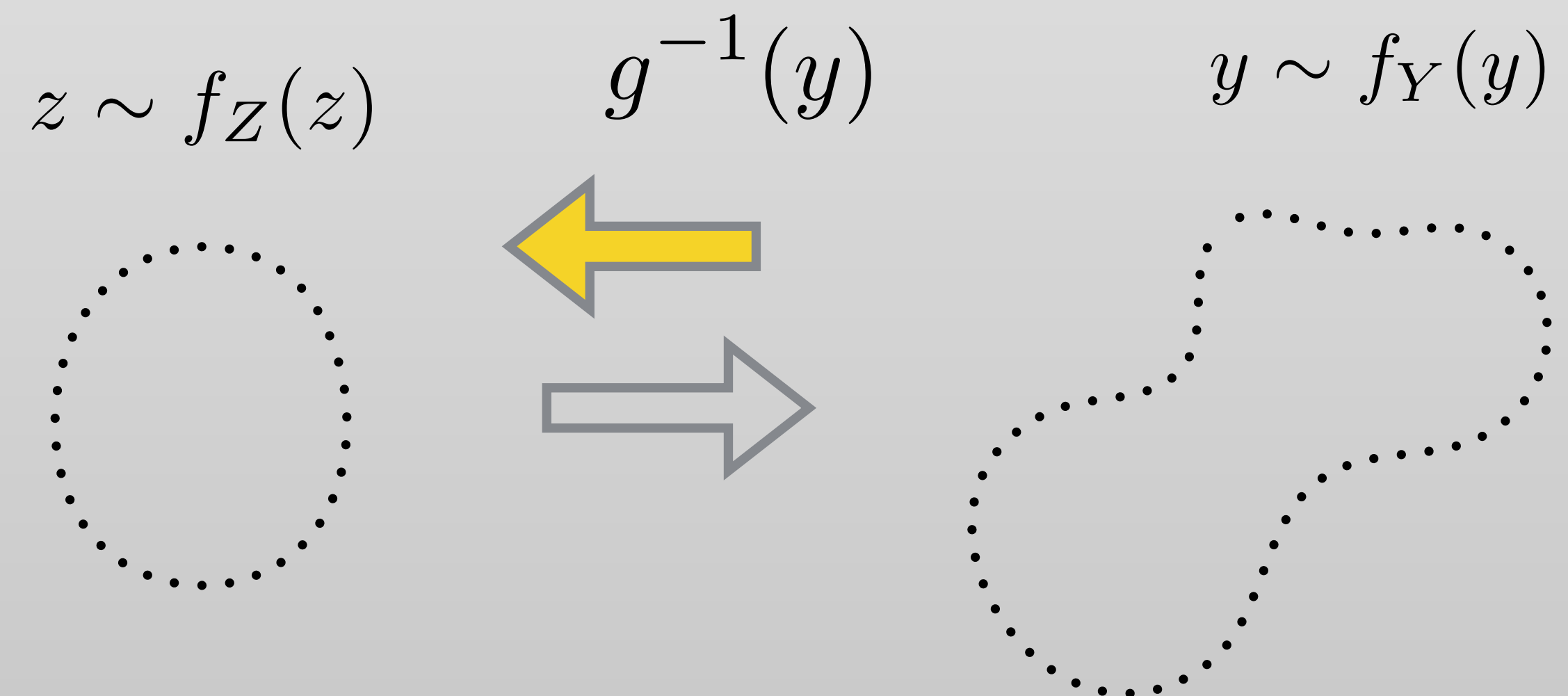
CHANGE OF VARIABLE

$$\log[f_Y(y)] = \log[f_Z(g^{-1}(y))] + \log \left[\left| \det \frac{\partial g^{-1}(y)}{\partial y} \right| \right]$$

1. $g(y)$ has to be a bijection

2. $g(y)$ and $g^{-1}(y)$ have to be differentiable

3. Jacobian determinant has to be tractably inverted



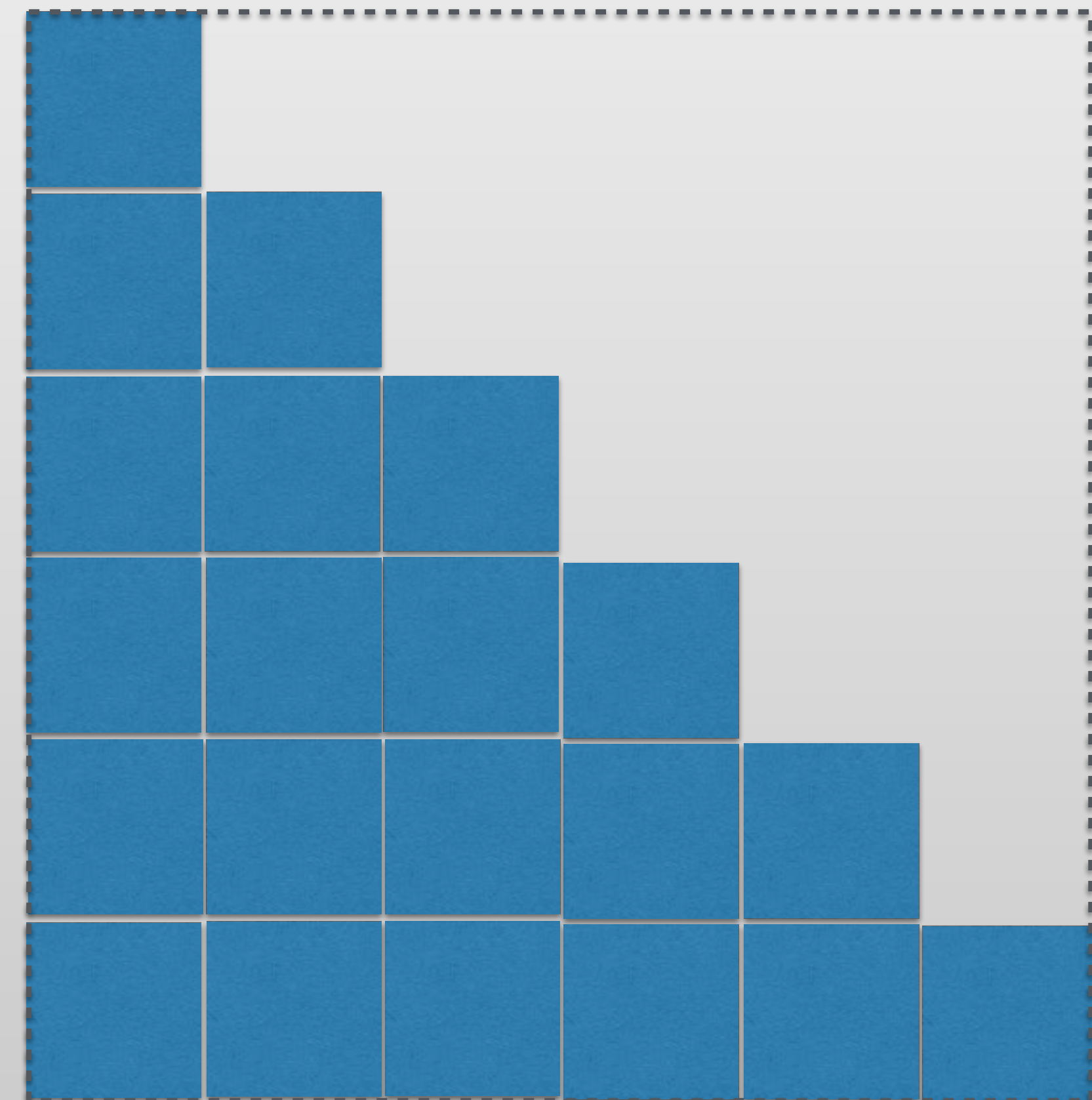
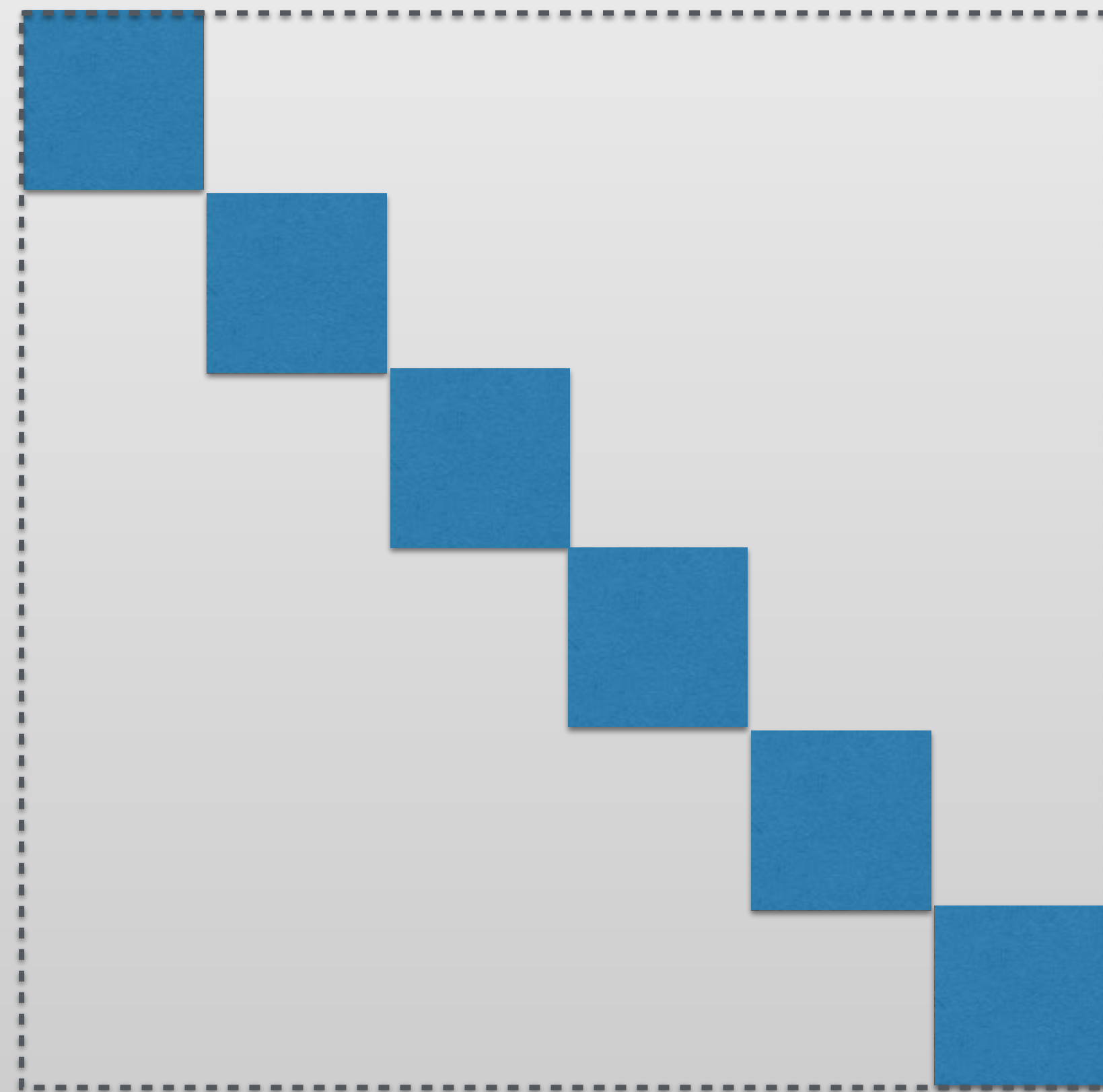
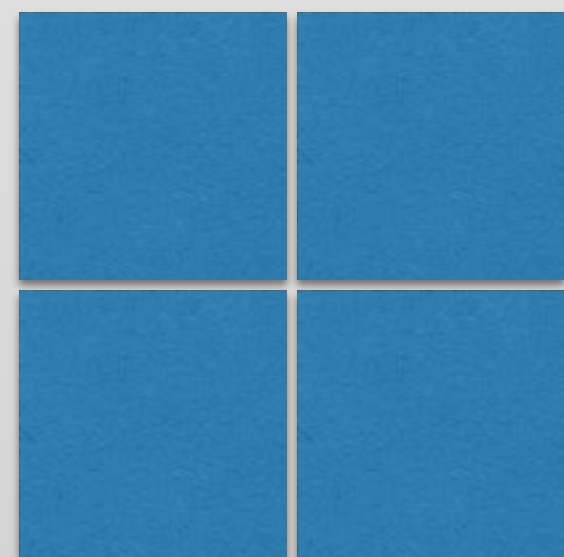
JACOBIAN

$$J_{g^{-1}} y = \begin{bmatrix} \frac{\partial g_1^{-1}}{\partial z_1} & \cdots & \frac{\partial g_1^{-1}}{\partial z_n} \\ \vdots & \ddots & \vdots \\ \frac{\partial g_n^{-1}}{\partial z_1} & \cdots & \frac{\partial g_n^{-1}}{\partial z_n} \end{bmatrix}$$

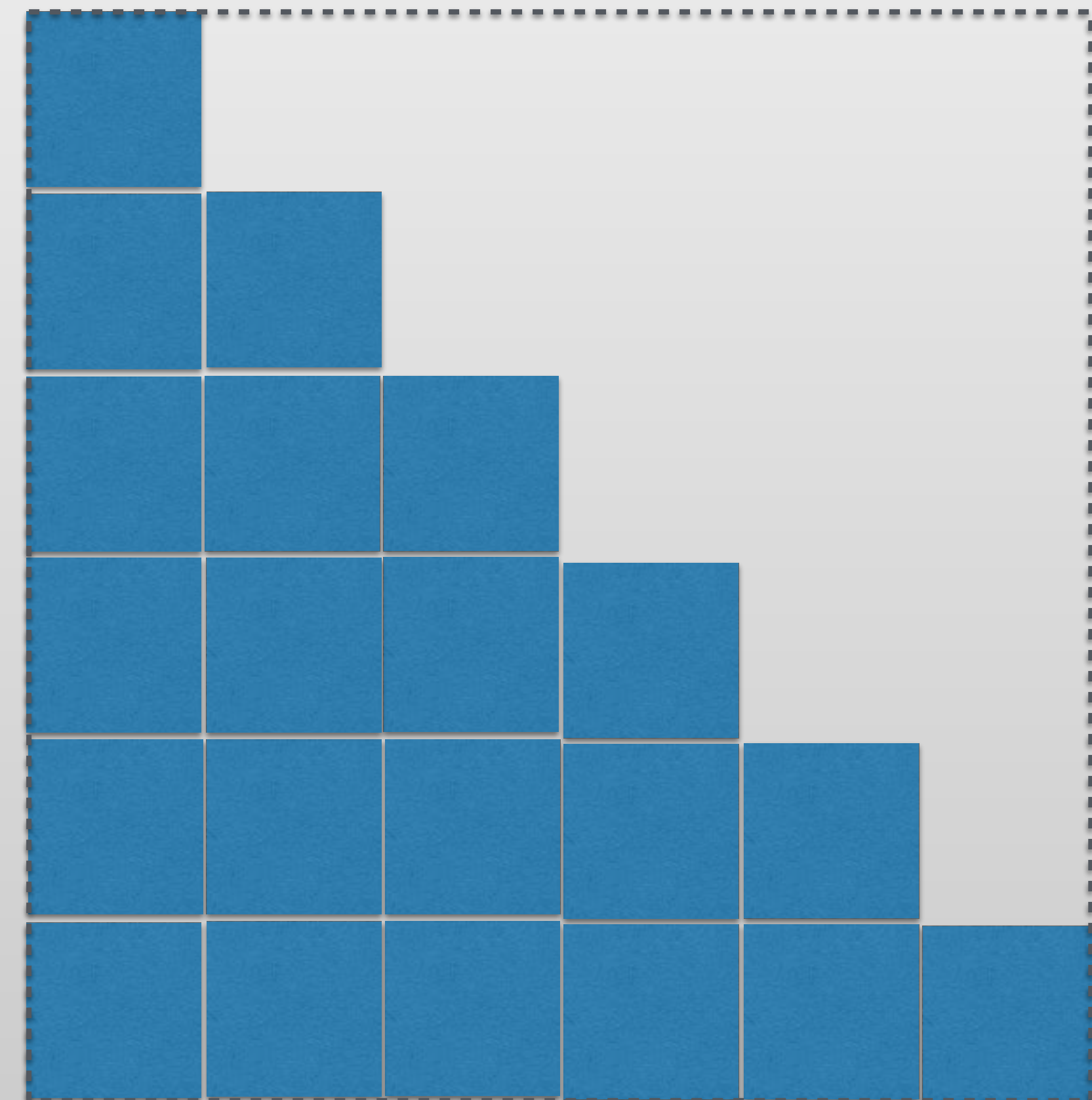
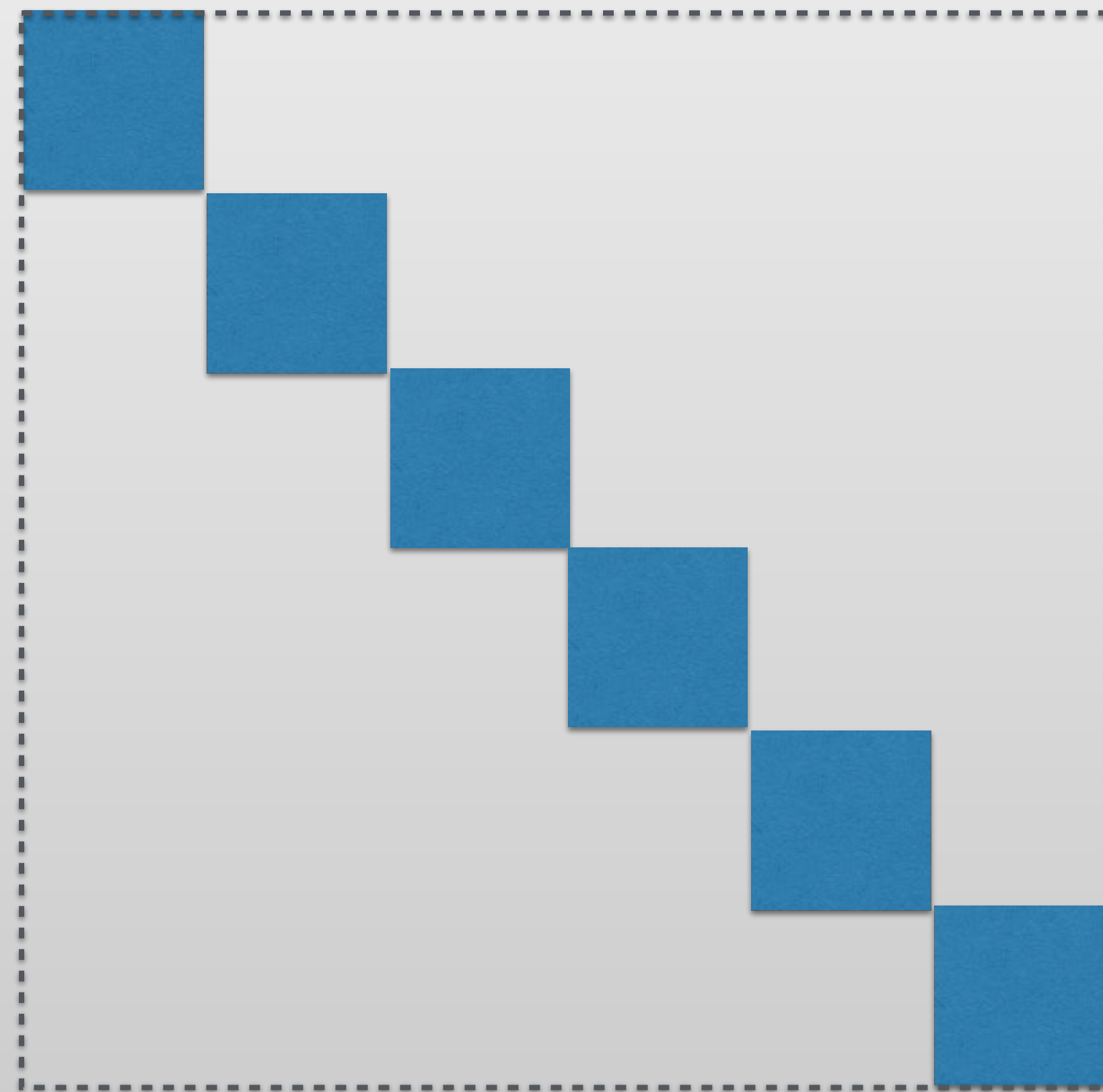
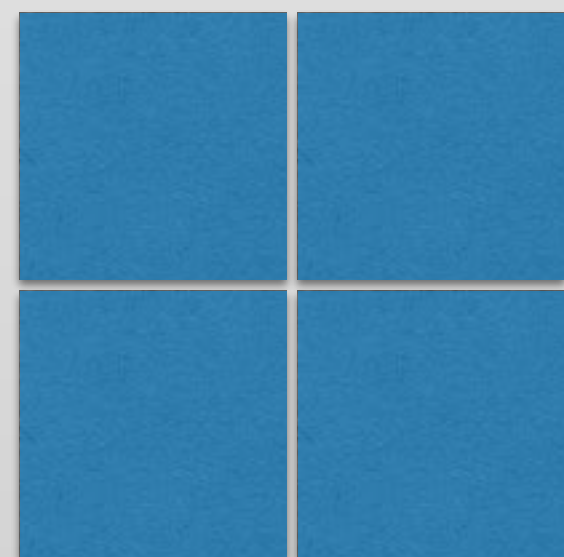
The calculation of determinant Jacobian will take $O(n^3)$

We have to find a way to make it faster

SIMPLIFYING JACOBIAN



SIMPLIFYING JACOBIAN



Determinant of triangular matrix is a product of the elements on its diagonal

AFFINE TRANSFORMATIONS

location-scale transformation:

$$\tau(z_i; \mathbf{h}_i) = \alpha_i z_i + \beta_i \quad \mathbf{h}_i = \{\alpha_i, \beta_i\}$$

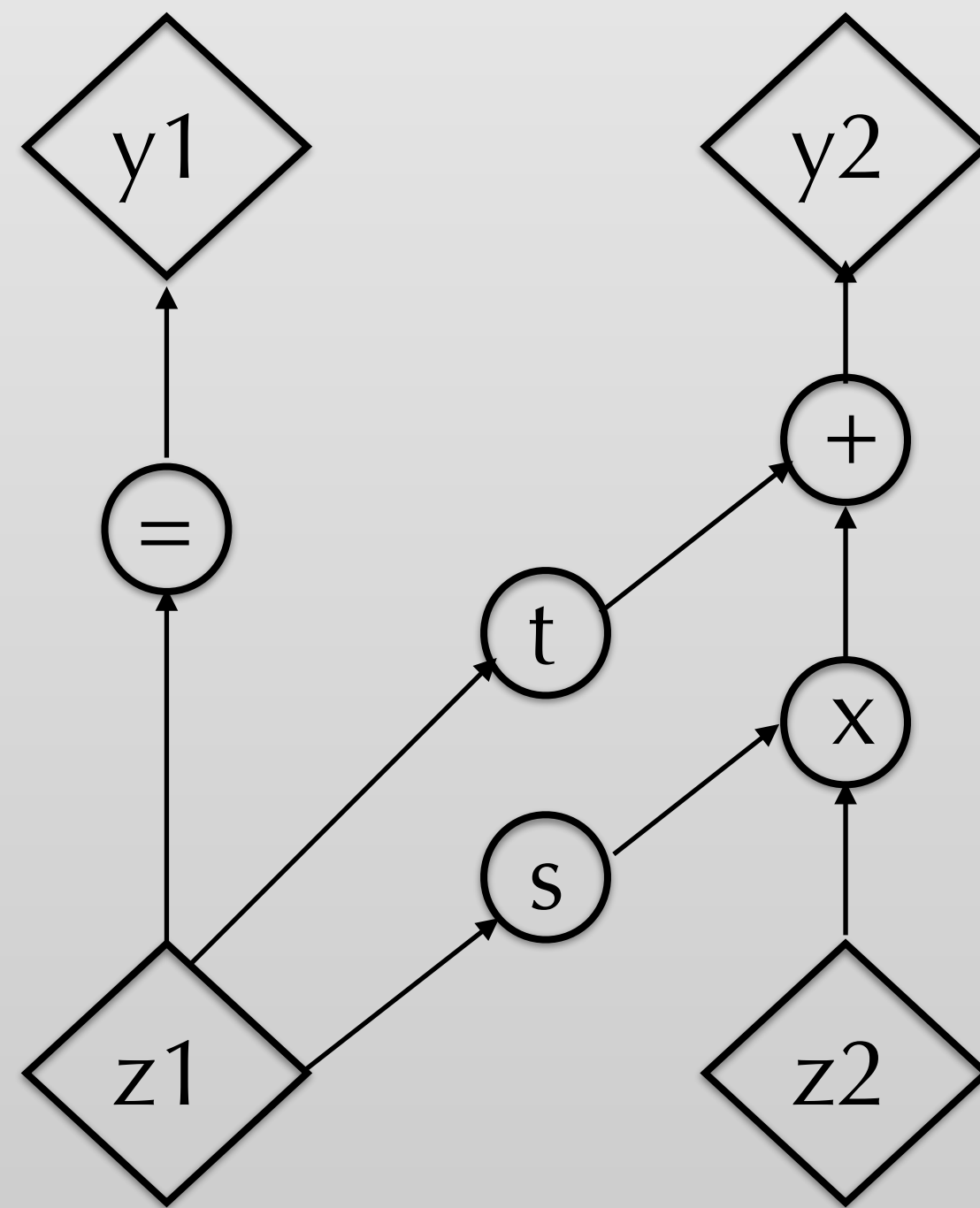
Invertibility for $\alpha_i \neq 0$

log-Jacobian becomes

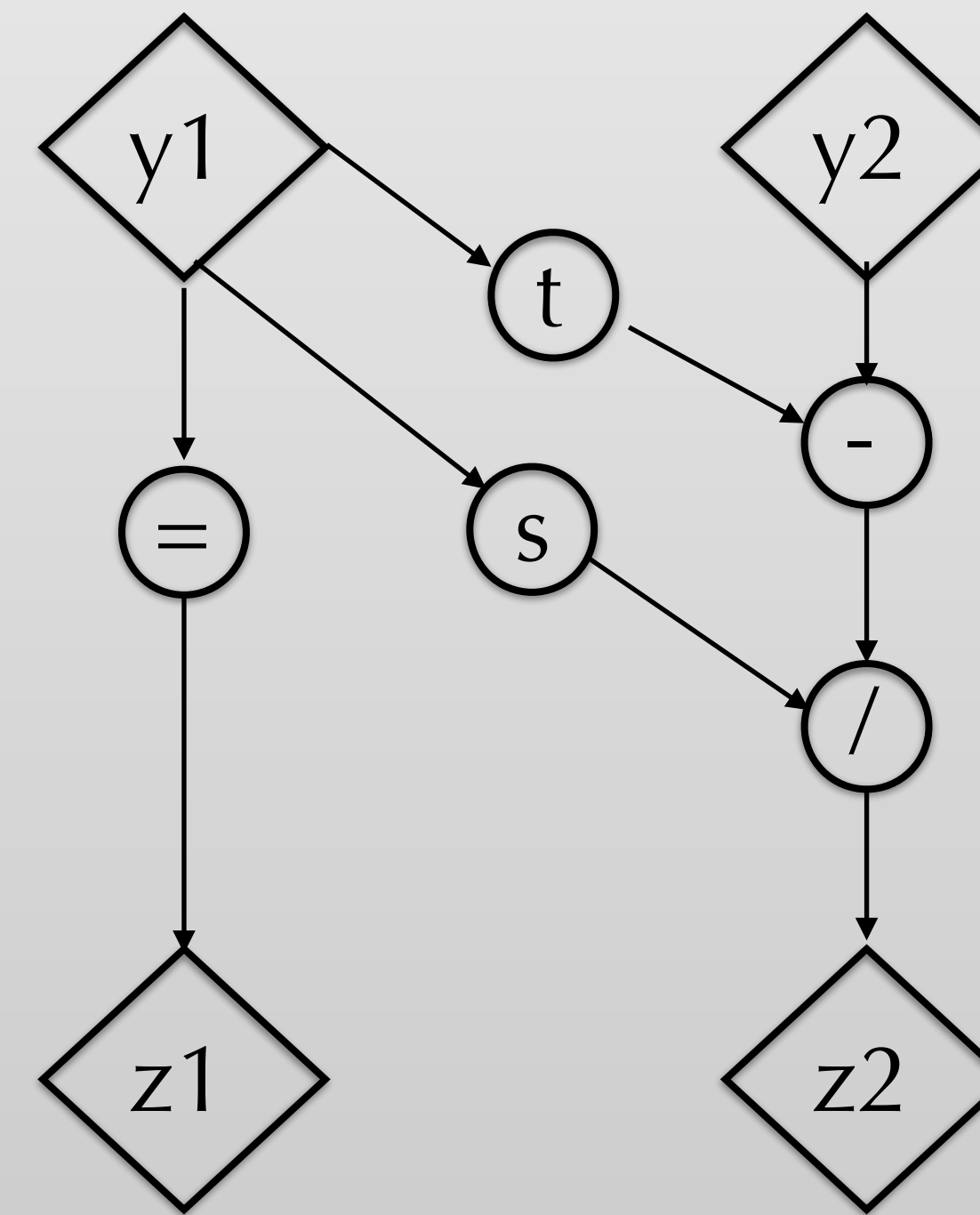
$$\log|\det J_{g^{-1}}(\mathbf{z})| = \sum_{i=1}^N \log|\alpha_i|$$

COUPLING TRANSFORM

Split input into two parts: z_1 and z_2



Forward propagation



Inverse propagation

REAL NVP

Coupling transform combined with affine transformation:

$$y_{1:d} = z_{1:d}$$

$$y_{d+1:D} = z_{d+1:D} \cdot \exp(s(z_{1:d})) + t(z_{1:d})$$

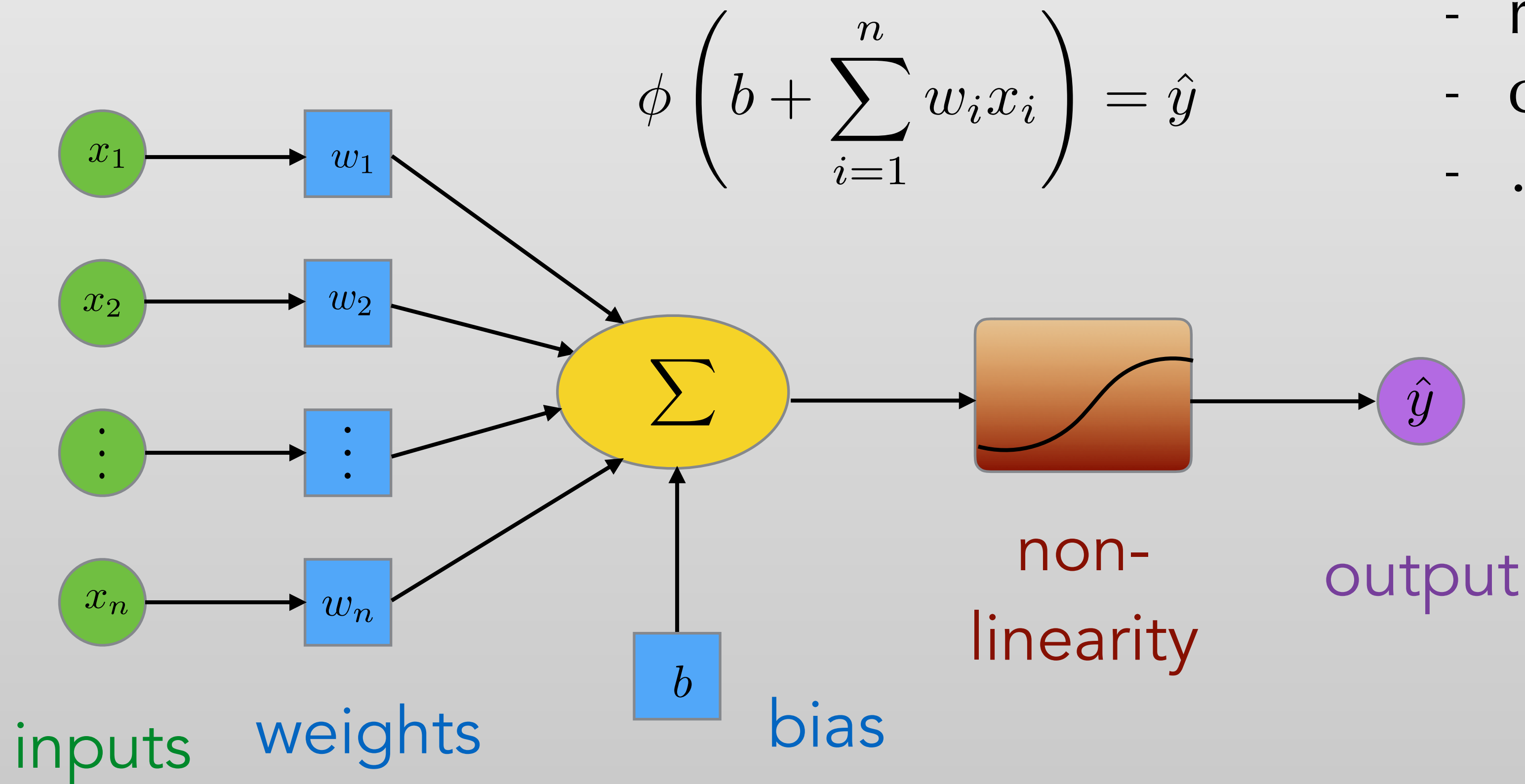
Jacobian of this transformation

$$\frac{\partial y}{\partial z} = \begin{bmatrix} \mathbf{I}_d & 0 \\ \frac{\partial y_{d+1:D}}{\partial z_{1:d}} & \text{diag}(\exp[s(z_{1:d})]) \end{bmatrix}$$

What is functions t and s?

PARAMETERISATION WITH THE NN

Neuron



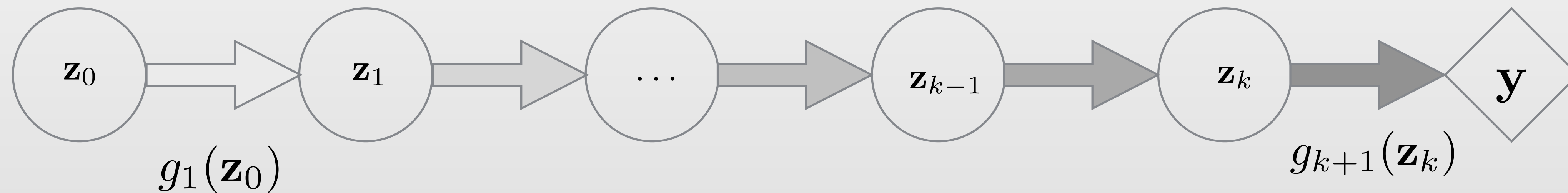
$$\phi \left(b + \sum_{i=1}^n w_i x_i \right) = \hat{y}$$

The architecture can be any:

- fully connected
- residual network
- convolutional network
- ...

COMPOSING FLOWS

$$\mathbf{z}_0 \sim f_{z_0}(\mathbf{z}_0)$$



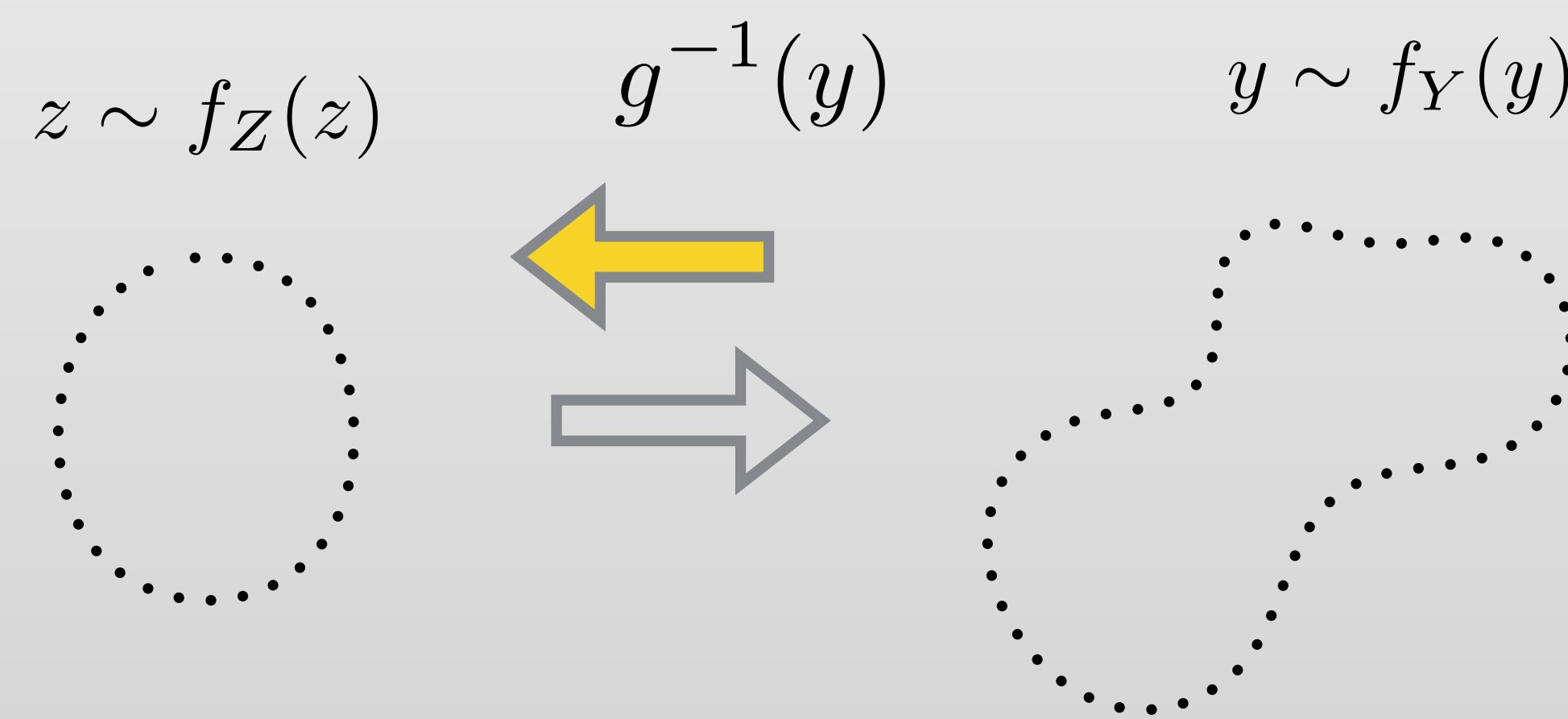
Function composition

$$(g_1 \circ g_2)^{-1} = g_1^{-1} \circ g_2^{-1}$$

Jacobian composition

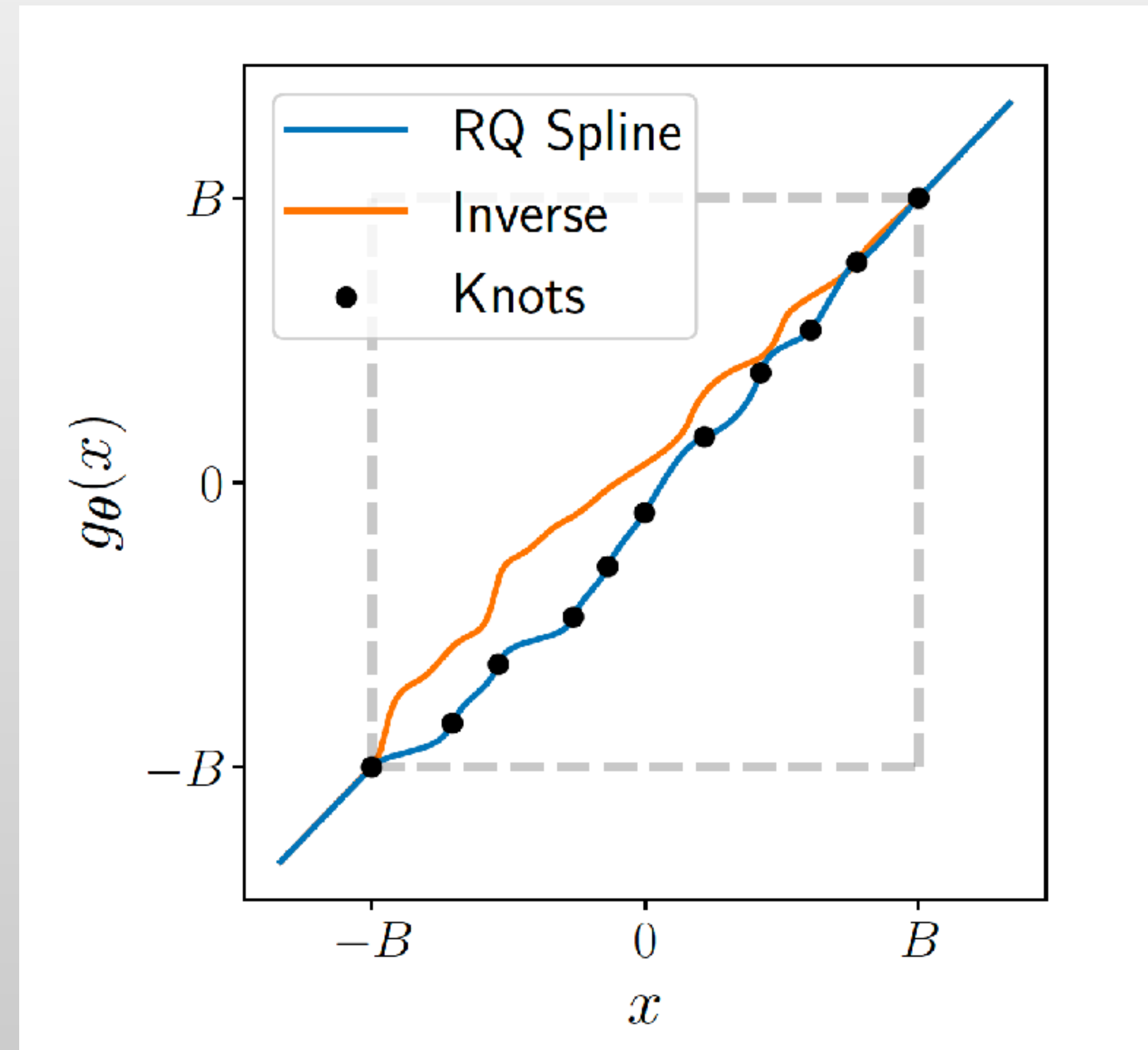
$$\det(J_1 \cdot J_2) = \det(J_1) \cdot \det(J_2)$$

SAMPLE GENERATION



SPLINE NEURAL FLOW

Replace affine transform
with tractable piecewise function.
For example,
Rational Quadratic Splines



OPTIMISATION

The flow is trained by maximising the total log likelihood of the data with respect to the parameters of the transformation:

$$\log p(\mathcal{D}|\theta) = \sum_{i=1}^N \log[f_Y(y_i|\theta)]$$

θ — parameters of the Neural Network with we use to parameterise our transform

OPTIMISATION

The flow is trained by maximising the total log likelihood of the data with respect to the parameters of the transformation:

$$\log p(\mathcal{D}|\theta) = \sum_{i=1}^N \log[f_Y(y_i|\theta)]$$

Use change of variable equation:

$$\log[f_Y(y)] = \log[f_Z(g^{-1}(y))] + \log \left[\left| \det \frac{\partial g^{-1}(y)}{\partial y} \right| \right]$$



CONDITIONING ON THE WAVEFORM

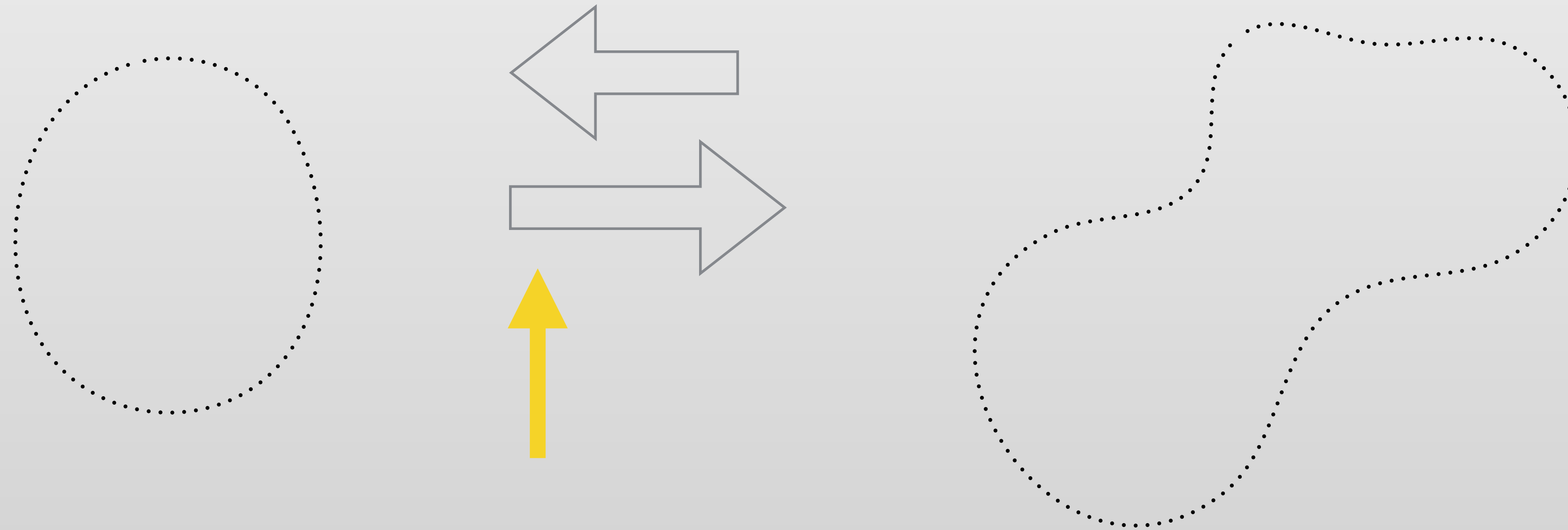
We do not have access to the samples from the posterior, as in the examples that we have just considered.

But we have access to the samples from the prior and the simulations of the data.

LIKELIHOOD FREE INFERENCE

Samples from a prior of a physical parameter

$$y \sim f_Y(y)$$



Condition map on the simulated data:

$$\mathbf{x} = h(\mathbf{y}) + \mathbf{n}$$

Therefore we have access to the joint sample:

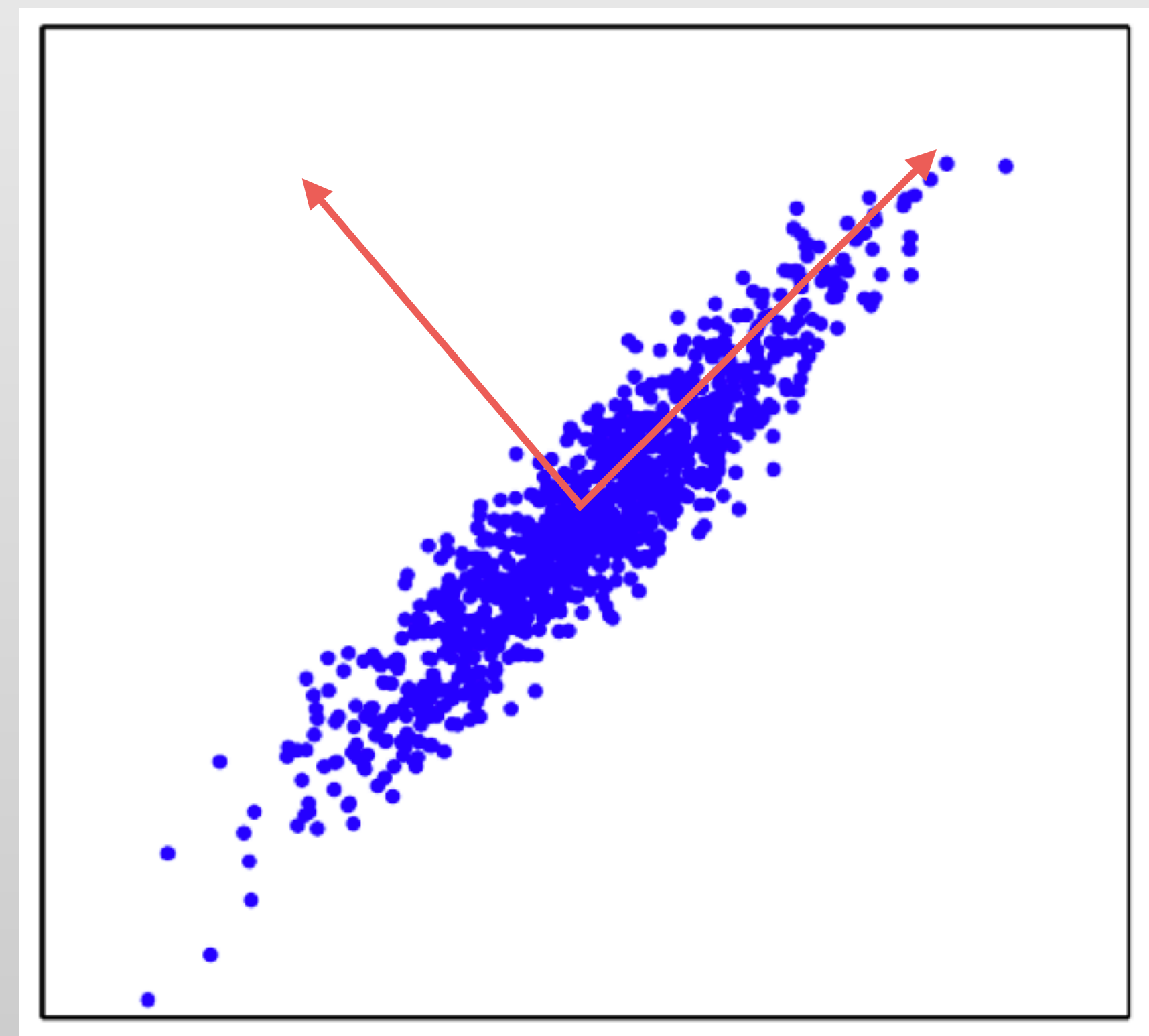
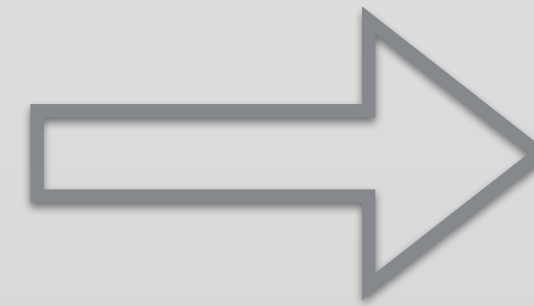
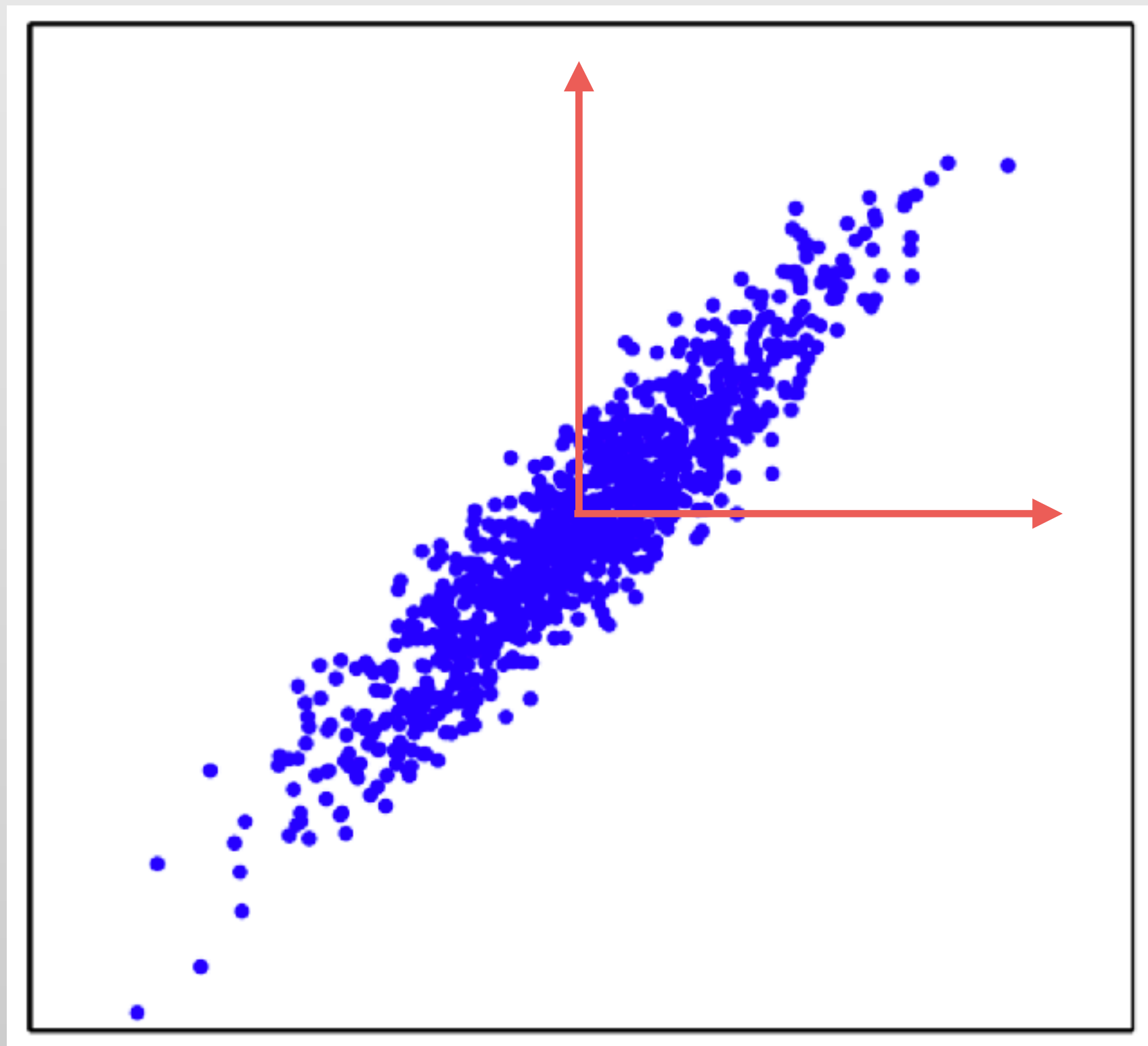
$$p(\mathbf{x}, \mathbf{y}) = p(\mathbf{x})p(\mathbf{x}|\mathbf{y})$$



WAVEFORM EMBEDDING

- LISA observes signals in low frequency, therefore the waveforms are long.
- Conditioning does not work well with the long waveform, have to find a way to reduce it.
- It can be done, for example, by constructing new orthogonal basis which maximises variance in the space of the waveforms.
- And using the coefficients of the projection of the waveforms to the new basis.
- We implement it with Singular Value Decomposition.

WAVEFORM EMBEDDING



WAVEFORM EMBEDDING

Decompose a matrix constructed of the waveforms

$$\mathbf{H} = \mathbf{V}\Sigma\mathbf{U}^T$$

matrix composed of reconstruction coefficients

matrix composed of basis vectors

matrix containing the singular values

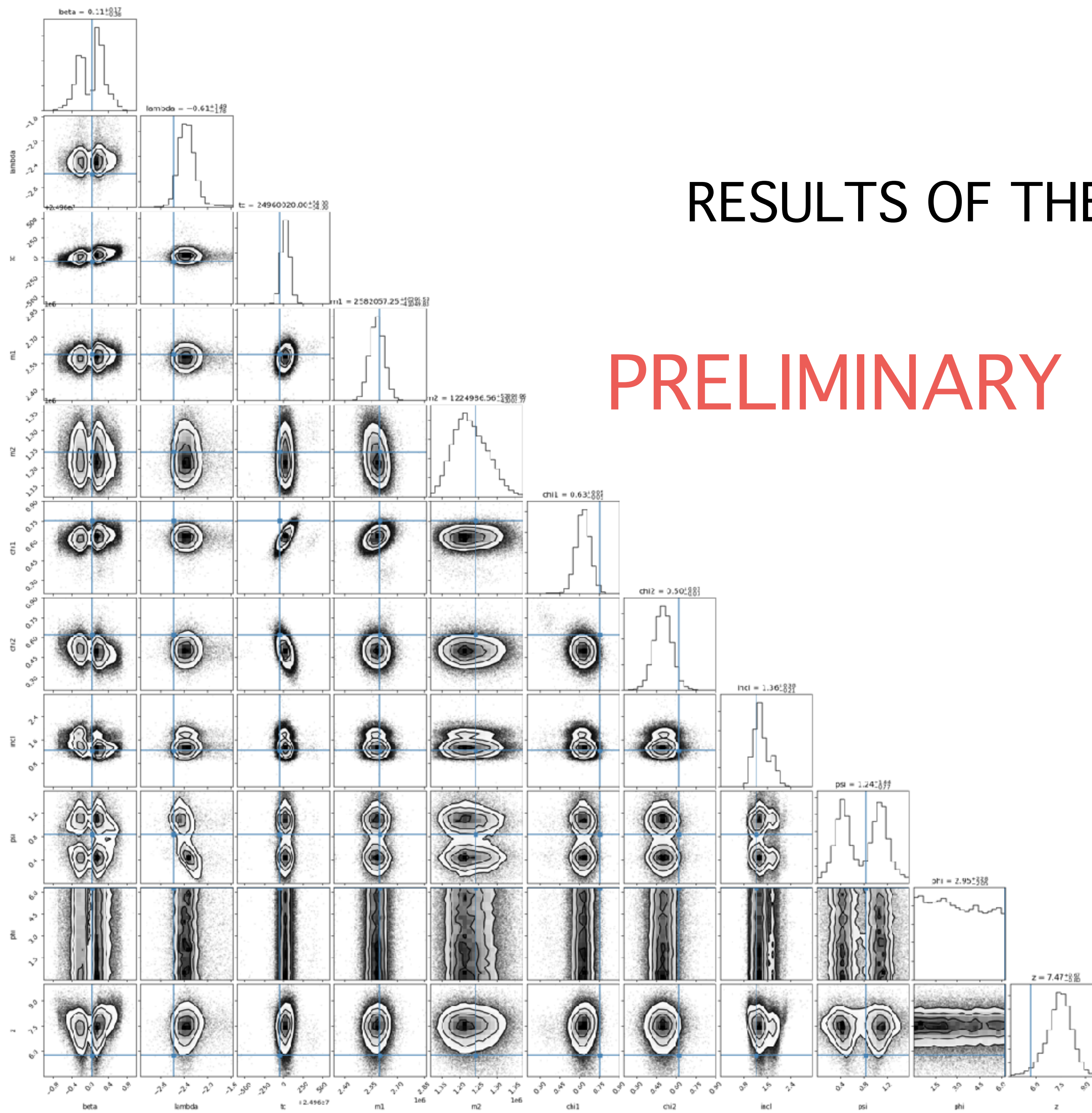
WAVEFORM EMBEDDING

Project the waveform onto the reduced basis in the following way:

$$v'_{\alpha\mu} = \frac{1}{\sigma_{\mu}} \sum_{j=1}^N h_{\alpha j} u_{\mu j}$$

RESULTS OF THE PARAMETER ESTIMATION

PRELIMINARY





Questions?