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# Nonlinear neural network dynamics accounts for human confidence in a sequence of perceptual decisions

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**Fellowship:** CDSN Ecole Normale Supérieure Paris-Saclay

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## Perceptual Decision-Making

- ▶ Visual Discrimination

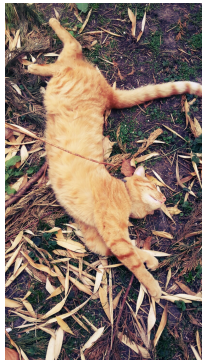
## Perceptual Decision-Making

- ▶ Visual Discrimination
- ▶ Choice between categories

## Cat or Dog ?

### Perceptual Decision-Making

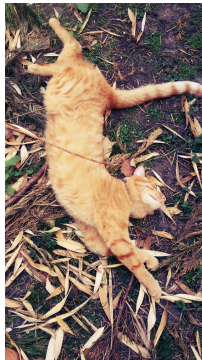
- ▶ Visual Discrimination
- ▶ Choice between categories



## Cat or Dog ?

### Perceptual Decision-Making

- ▶ Visual Discrimination
- ▶ Choice between categories
- ▶ Can be ambiguous



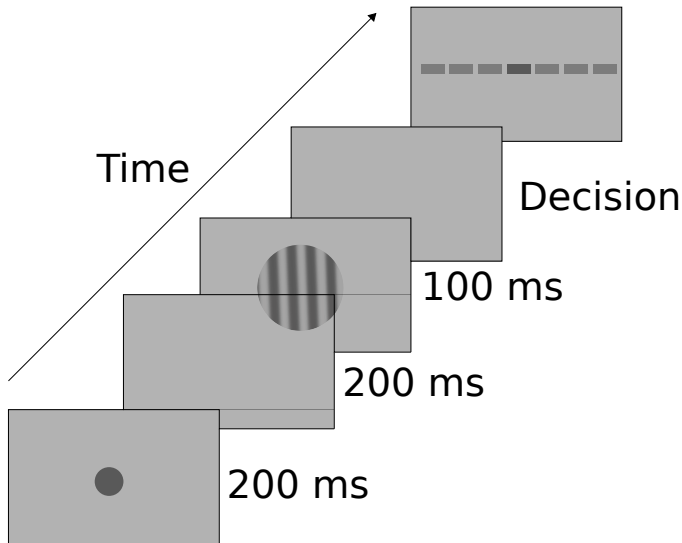
## Cat or Dog ?

### Perceptual Decision-Making

- ▶ Visual Discrimination
- ▶ Choice between categories
- ▶ Can be ambiguous

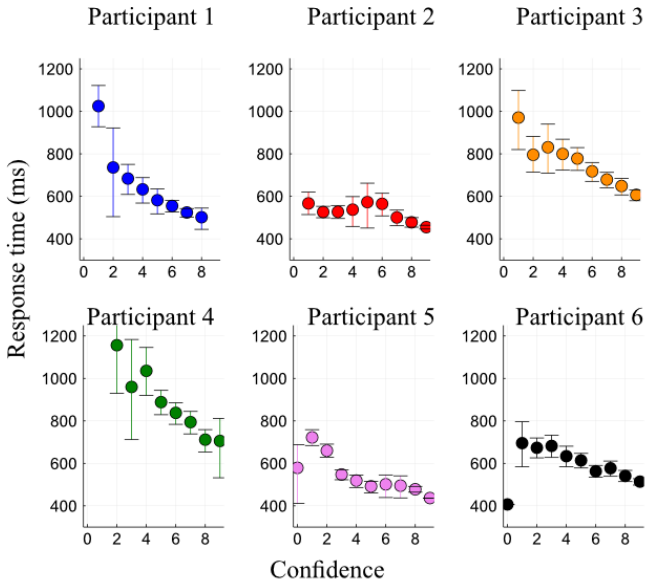


# Experimental setup

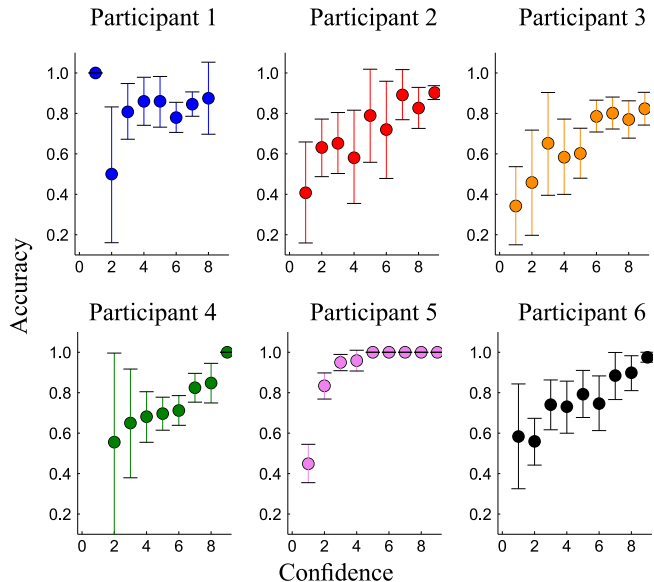




# Confidence and behavior



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# Attractor Model

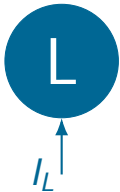


$$\frac{dS_i}{dt} = -\frac{S_i}{\tau_s} + (1 - S_i) \gamma f(I_{i,tot})$$

$$f(I_{i,tot}) = \frac{af(I_{i,tot}) - b}{1 - \exp[-d(af(I_{i,tot}) - b)]}$$

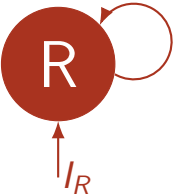
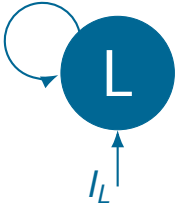
# Attractor Model

$$I_{L,tot} = I_0 + I_L + I_{noise,L}$$

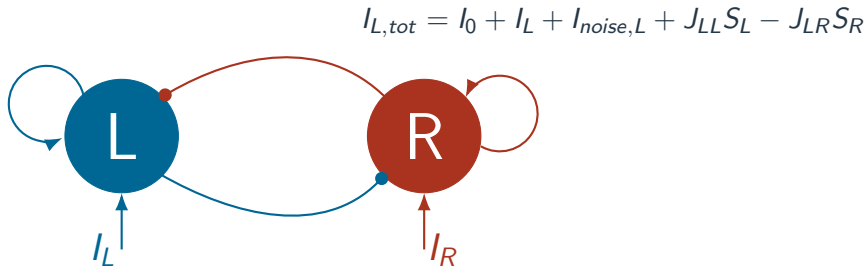


# Attractor Model

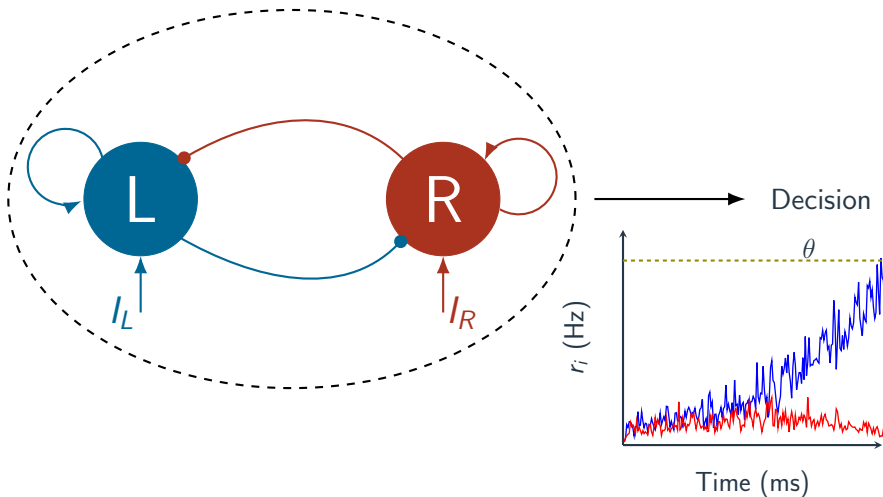
$$I_{L,tot} = I_0 + I_L + I_{noise,L} + J_{LL}S_L$$



# Attractor Model



# Attractor Model

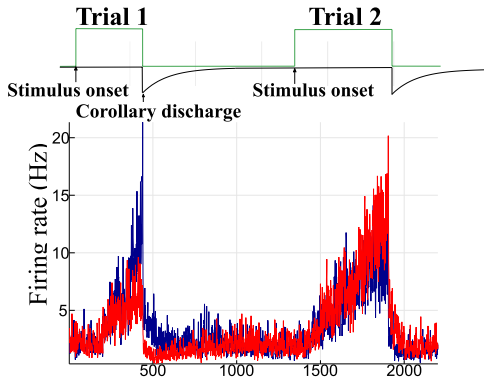


# Typical timecourse



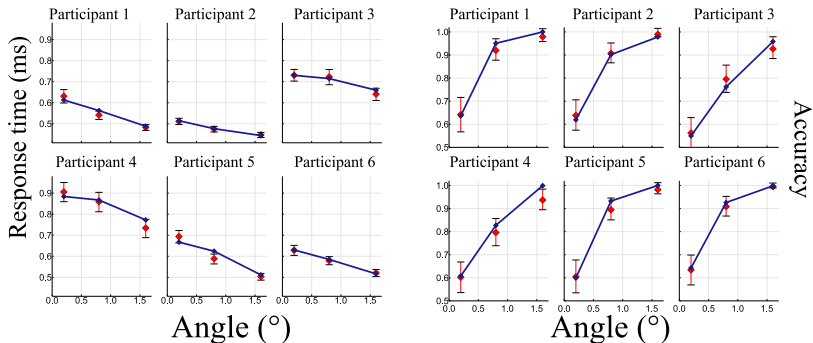


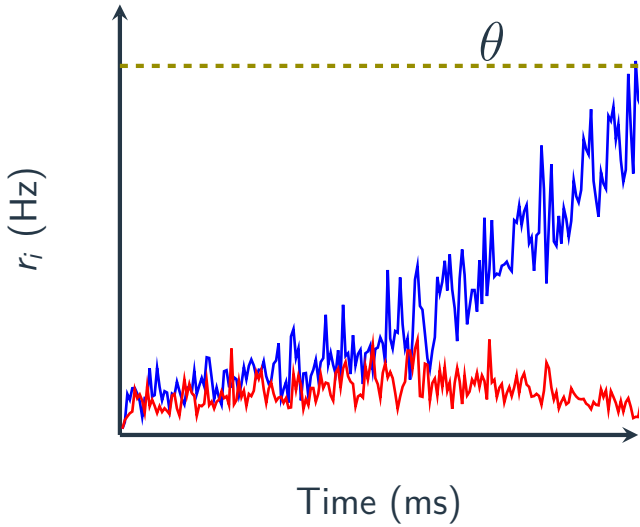
# Typical timecourse

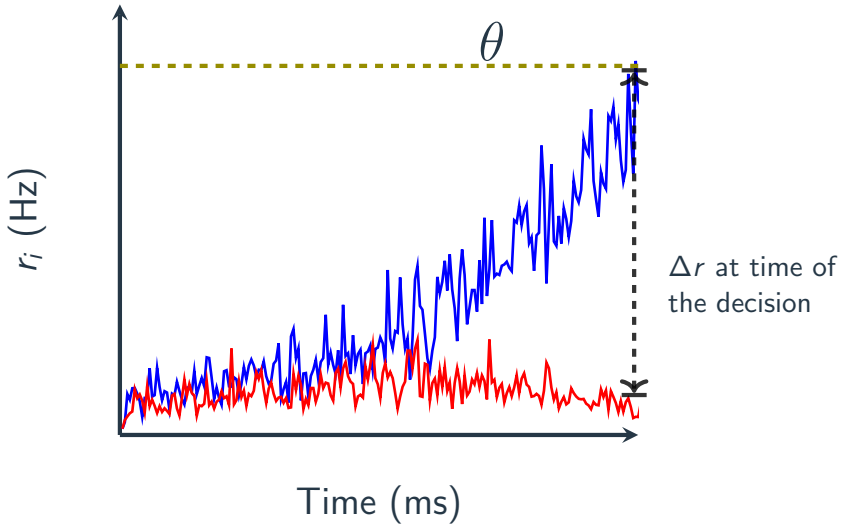


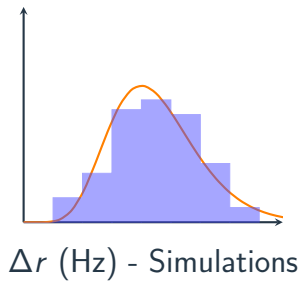
# Behavioral results

## Confidence block

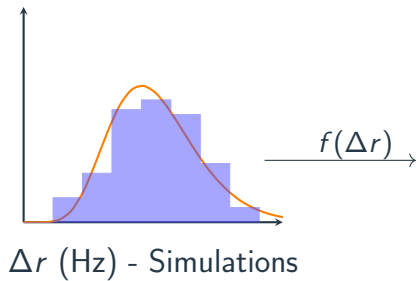




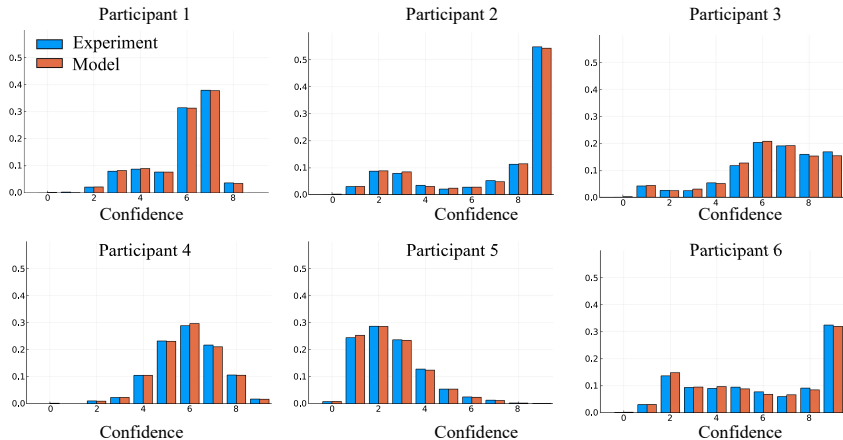




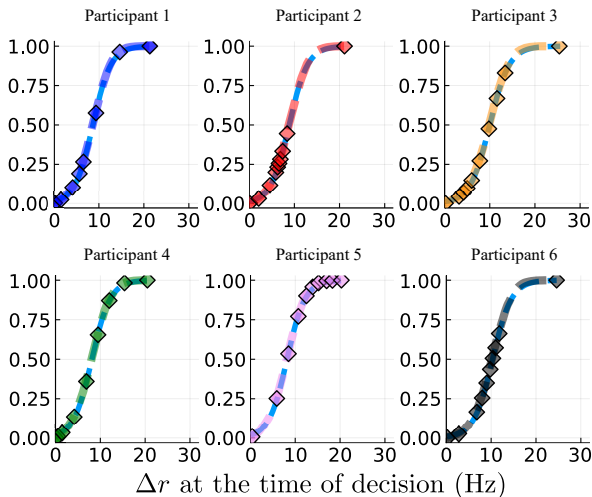
# Confidence modelisation



# Histogram matching

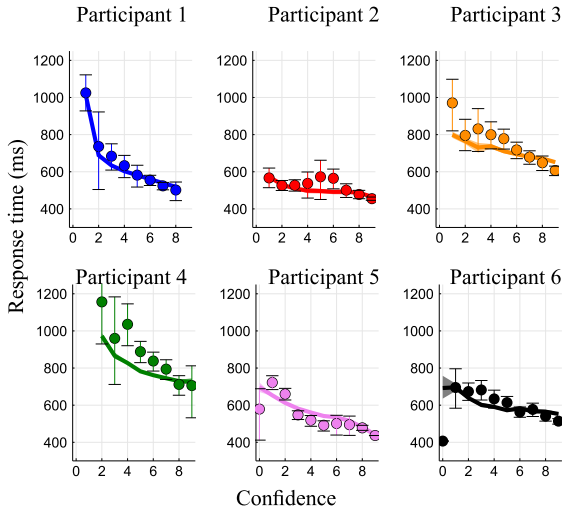


# Histogram matching

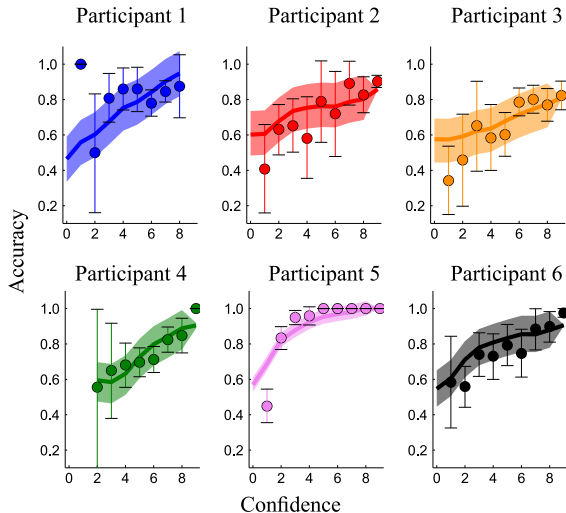




# Matching with data



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- ▶ Non-linearity explains various effects observed in decision-making experiments.