

# Data Challenges for the SKA

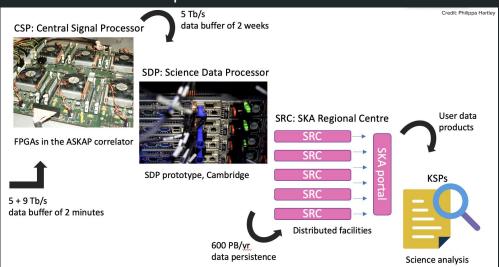
Alex Clarke (SKAO)

a.clarke@skatelescope.org

On behalf of the team: Anna Bonaldi, Phillipa Hartley, Rosie Bolton, James Collinson, Rob Barnsley, Rohini Joshi

### Preparing users for SKA data access

- Users will get data products via regional centres in their part of the world through a single portal
- They will do most of the processing and analysis at these centres, rather than downloading data to their own computers

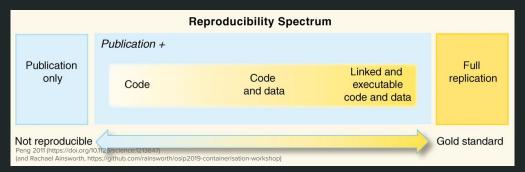


 Data challenges are designed to represent the workflow of users interacting with SKA data products

# Open science and reproducibility

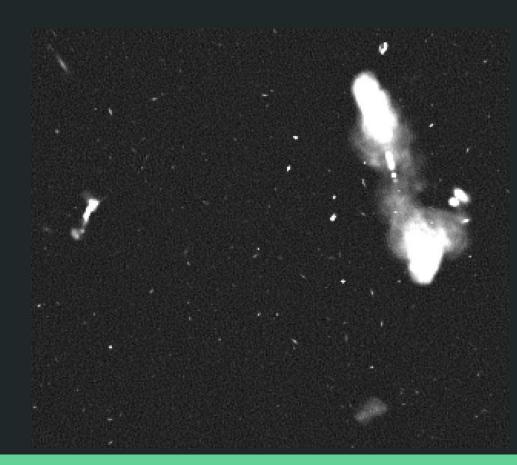
Data challenges are being aimed at motivating users to follow best practices in their workflows

- Coding standards
  - Style guide, documentation, comments, functions, classes, modular, version control
- Publishing their code, data and workflow alongside the results
  - Zenodo/Github
- Ensuring their workflow is reproducible
  - Documenting software dependencies, using containers



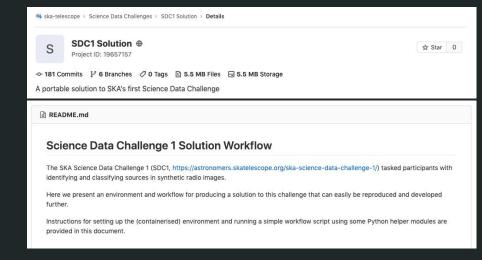
#### Source finding in images

- 32000 by 32000 pixel images were provided at 560, 1400, 9200 MHz, at resolutions of 2.4, 1.2 and 0.6 arcseconds, respectively.
- A truth catalogue is provided for a small area of sky, but when the challenge ran in 2019 the full truth catalogue was not provided.
- Participants submitted a catalogue of sources and were scored on how many they found and what they classified them as (star-forming galaxy, or steep/flat spectrum active galactic nuclei).
- There was no requirement for participants to show their workflow, code, or demonstrate it was reproducible.



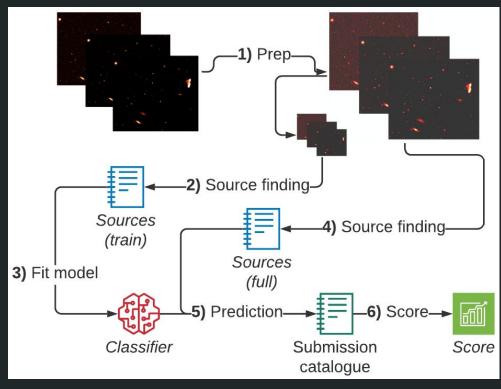
#### Developing an example solution

- We made a containerised example solution after the challenge to demonstrate a variety of best practices in research and software development
- Code is available on Github/Gitlab https://gitlab.com/ska-telescope/sdc/sdc1-solution
- Data is available on Zenodo
  <a href="https://doi.org/10.5281/zenodo.4328029">https://doi.org/10.5281/zenodo.4328029</a>
- Modular code structure, rather than one long script, means it's easier to read, document, collaborate on, test, and reuse parts for other projects.



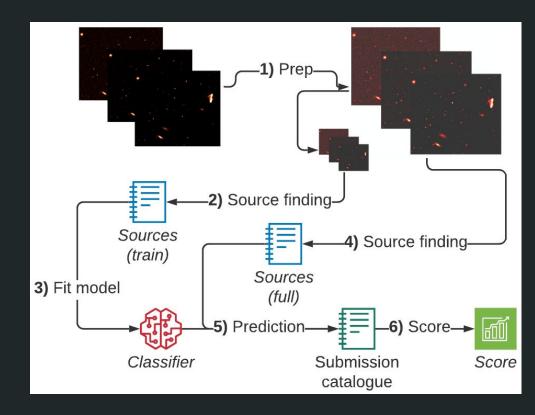
#### Running the example solution

- Get Docker
- Environment variable and aliases
- Download data
- Make the Docker image
- Start the Container
- In the Container, run sdc1\_solution.py,
   which reproduces the entire workflow,
   producing output catalogues and scores,
   taking 3 hours

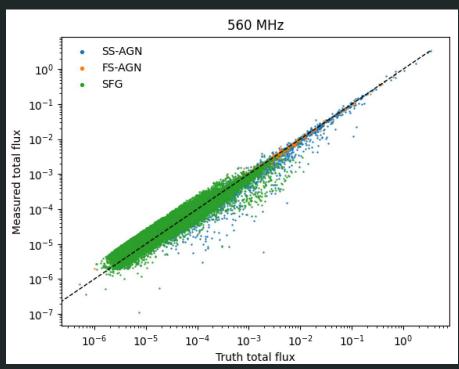


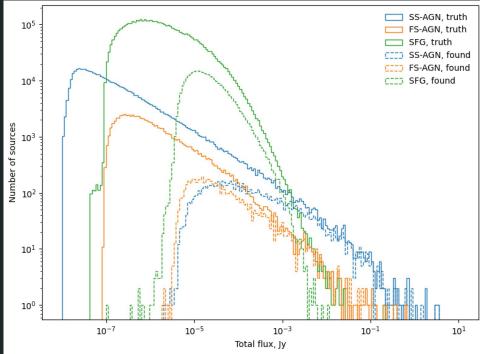
#### Running the example solution

- 1. Image preprocessing
  - Primary beam correction
  - Split out training sub-image
  - o (Chunk images)
- Source finding (training)
- 3. Model fitting (training)
- 4. Source finding (full)
- 5. Model prediction (full)
- 6. Score results



Running the example solution





### Precision, recall, F1 score for the Random Forest (RF) - 560 MHz

Fit RF to half of the sources in the training area, test on other half:

	precision	recall	f1-score	support
FSAGN	0.8250	0.2426	0.3750	136
SFG	0.9801	0.9984	0.9892	10424
SSAGN	0.5926	0.1280	0.2105	125

Apply this model to classify the rest of the sources in the field:

	precision	recall	f1-score	support
FSAGN	0.8453	0.2383	0.3718	5342
SFG	0.9714	0.9964	0.9838	328561
SSAGN	0.4993	0.1575	0.2395	6736

Run the scoring code with these class labels:

Score was 231607.00169231306
Number of detections 343272
Number of matches 340639
Number of matches too far from truth 1433
Number of false detections 2633
Score for all matches 234240.00169231306
Accuracy percentage 68.7648806191637

The F1 score is the harmonic mean of precision and recall, interpreting true positives (TP), false positives (FP) and false negatives (FN):

$$F_1 = \frac{2\text{TP}}{2\text{TP} + \text{FP} + \text{FN}}$$

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This is a hugely imbalanced classification problem. Let's compare scores for guessing against the RF model:

Model	SDC Score	Average F1-score
RF:	231 607	0.53
Guess all SFG:	231 475	0.33
Guess all SS-AGN:	188 275	0.01

Guessing they are all SFG will result in much worse precision, recall and F1 scores:

	precision	recall	f1-score	support
FSAGN	0.0000	0.0000	0.0000	5342
SFG	0.9645	1.0000	0.9820	328561
SSAGN	0.0000	0.0000	0.0000	6736

The inclusion of the class label in the scoring package gives a score biased towards finding star-forming galaxies. Thus the score from the scoring package is not a fair representation of overall performance, it is only fair at assessing the identification of sources, not their class.

F1 scores are a fair representation of the performance of a multiclass, imbalanced classification scheme.

### Dimension reduction

- High dimensional data can often be represented extremely well in a lower dimensional space

- High dimensional data opens the door for complex models to fail or have undetected inconsistencies/biases

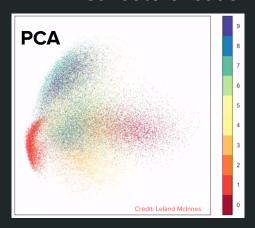
 Our existence is based in three dimensions. It is unnatural to expect us to have any significant intuition beyond this

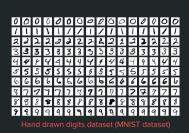
 Visualisation is everything. You will reap the rewards of being able explain your data and models to other people intuitively

### Dimension reduction

#### Matrix Factorisation

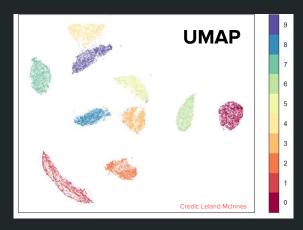
- Principal Component Analysis
- Latent Dirichlet Allocation
- Linear auto-encoder





### Neighbour Graphs

- Isomap
- t-SNE
- UMAP



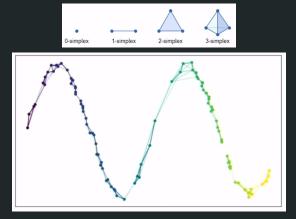
I would highly recommend Leland McInnes' talk which goes over the basic mathematical concepts behind matrix factorisation and neighbour graphs: <a href="https://www.youtube.com/watch?v=9iol3Lk6kyU">https://www.youtube.com/watch?v=9iol3Lk6kyU</a>

### Dimension reduction

### Neighbour Graphs: Uniform Manifold Approximation and Projection

UMAP: McInnes et al https://arxiv.org/abs/1802.03426

- 1) Compute a graphical representation of a dataset (Topology: fuzzy simplicial complex)
- 2) Through stochastic gradient descent, optimise a low-dimensional embedding of the graph.



Parametric UMAP: replace step 2 with a neural network that learns a parametric embedding

PARAMETRIC UMAP: LEARNING EMBEDDINGS WITH DEEP NEURAL NETWORKS FOR REPRESENTATION AND SEMI-SUPERVISED LEARNING

#### Tim Sainburg UC San Diego tsainbur@ucsd.edu

Leland McInnes
Tutte Institute for Mathematics
and Computing
leland.mcinnes@gmail.com

Timothy Q Gentner UC San Diego

tgentner@ucsd.edu

#### ABSTRACT

We propose Parametric UMAP, a parametric variation of the UMAP (Uniform Manifold Approximation and Projection) algorithm. UMAP is a non-parametric graph-based dimensionality reduction algorithm using applied Riemannian geometry and algebraic topology to find low-dimensional embeddings of structured data. The UMAP algorithm consists of two steps: (1) Compute a graphical representation of a dataset (fuzzy simplicial complex), and (2) Through stochastic gradient descent, optimize a low-dimensional embedding of the graph. Here, we replace the second step of UMAP with a deep neural network that learns a parametric relationship between data and embedding. We demonstrate that our method performs similarly to its non-parametric counterpart while conferring the benefit of a learned parametric mapping (e.g. fast online embeddings for new data). We then show that UMAP loss can be extended to arbitrary deep learning applications, for example constraining the latent distribution of autoencoders, and improving classifier accuracy for semi-supervised learning by capturing structure in unlabeled data.

See this talk for an overview:

https://jbca-machinelearning.github.io/journalclub.html#6

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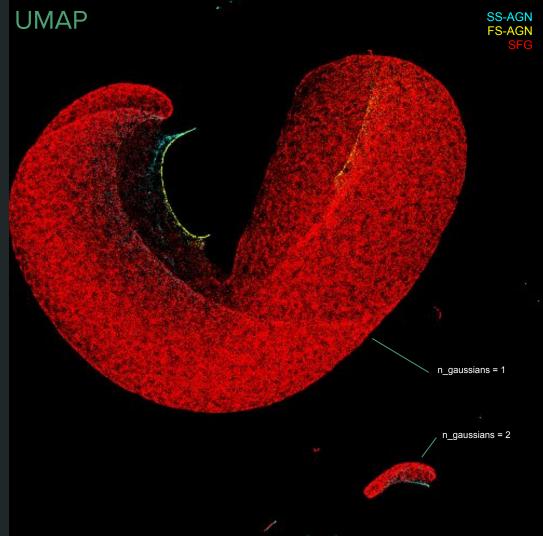
### Visualising the classifications with UMAP

Uniform Manifold Approximation and Learning (UMAP) is a non-linear dimension reduction algorithm.

We use it to reduce the number of features from 5 to 2

Total flux
Peak flux
Maj
Min
Number of gaussians
UMAP x
UMAP y

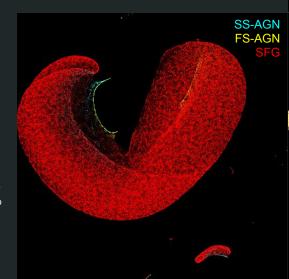
Colour code this plot by truth class label to see if the spatial separation is correlated with class

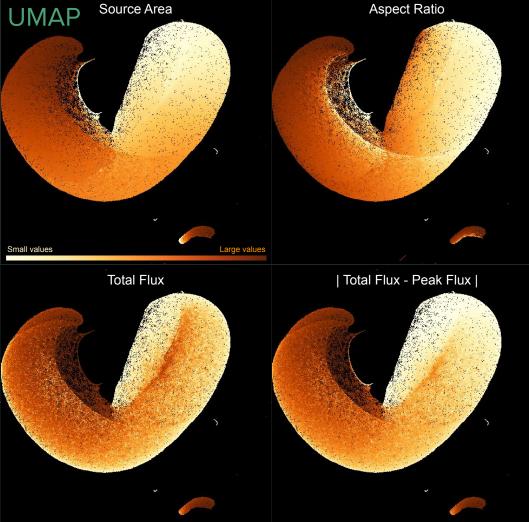


### Visualising the classifications with UMAP

Can colour the plot by features or other parameters to investigate their distribution or correlations with class label or beyond

Akin to looking at histograms over all parameters





Thanks to the datashader package for visualising so many sources - the pixel brightness is proportional to number of sources counted in that pixel (log scale)

Learning from the example solution

- Hopefully this helps share knowledge about technologies and techniques that enable more reproducible results, and people can use this example for future data challenges

- Future science data challenges will test the reproducibility of results

- Technologies like containers will become essential for future SKA data challenges, where you bring your software pipelines to the data at regional centres

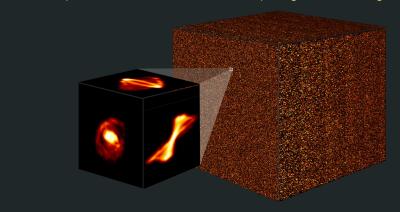
#### Source finding in a 1TB image cube

- A simulated 3D image cube of the neutral hydrogen line, where participants must find sources.
- Each team is given access to a <u>computational</u> <u>resource provider</u> acting as a regional centre

(IRIS, INAF ICT, IAA-CSIC proto-SRC, GENCI-IDRIS, EngageSKA-UCLCA, CSCS-Piz Daint, China SKA proto-SRC, AusSRC-Pawsey)

- The cube is hosted at these facilities and teams bring their pipelines to the data.
- 40 teams, 276 participants, representing 80 institutes and 23 countries
- Awards will be given out for <u>demonstrating</u>
   reproducible results:

https://sdc2.astronomers.skatelescope.org/sdc2-challenge/reproducibility-awards





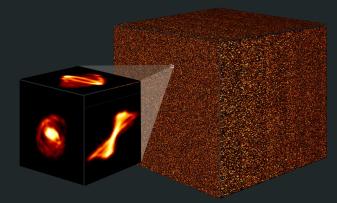
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		Reproducibility of the solution  Can the software pipeline be re-run easily to produce the same results? Is it:  Well-documented Research software documentation best practice Easy to install Top into for accidants software Easy to use Top this for documentation		
	Well-documented	High-level description of what/who the software is for is available	Ш	
ı		High-level description of what the software does is available	H	Open lie
ı		High-level description of how the software works is available	Ш	
ı		Documentation consists of clear, step-by-step instructions	Ш	
		Documentation gives examples of what the user can see at each step e.g. screenshots or command-line excerpt	ı	
		Documentation uses monospace fonts for command-line inputs and outputs, source code fragments, function names, class names etc	ı	Accessi
ı		Documentation is held under version control alongside the code	Ш	
	Easy to install	Full instructions provided for building and installing any software	I	
		All dependencies are listed, along with web addresses, suitable versions, licences and whether they are mandatory or optional	ı	Code st
ı		All dependencies are available	Ш	
		Tests are provided to verify that the installation has succeeded	I	
		A containerised package is available, containing the code together with all of the related configuration files, libraries, and dependencies required. Using .e.g. Docker/Singularity	ı	
	Easy to use	A getting started guide is provided outlining a basic example of using the software e.g. a README file		Testing
ı		Instructions are provided for many basic use cases	ı	resting
		Reference guides are provided for all command-line, GUI and configuration options		

Reusability of the pipeline Can the code be reused easily by other people to develop new projects? Does it: · Have an open licence Choosing an open source licence Have easily accessible source code <u>Choosing a repository for your project</u> · Adhere to coding standards Writing readable source code Utilise tests Testing your software Software has an open source licence e.g. GNU General Public License (GPL), BSD 3-Clause Licence is stated in source code repository Each source code file has a licence header Access to source code repository is available online Repository is hosted externally in a sustainable third-party repository e.g. SourceForge, LaunchPad, GitHub: Introduction to GitHub Documentation is provided for developers Source code is laid out and indented well Source code is commented There is no commented out code Source code is structured into modules or packages Source code uses sensible class, package and variable names Source code structure relates clearly to the architecture or design Source code has unit tests Software recommends tools to check conformance to coding standards

Reproducibility Awards

Reproducibility of the solution Can the software pipeline be re-run easily to produce the same results? Is it: Well-documented Research software documentation best practice Easy to install Top tips for packaging software · Easy to use Top tips for documentation Well-documented High-level description of what/who the software is for is available High-level description of what the software does is available High-level description of how the software works is available Documentation consists of clear, step-by-step instructions Documentation gives examples of what the user can see at each step e.g. screenshots or command-line excerpt Documentation uses monospace fonts for command-line inputs and outputs, source code fragments, function names, class names etc Documentation is held under version control alongside the code Easy to install Full instructions provided for building and installing any software All dependencies are listed, along with web addresses, suitable versions, licences and whether they are mandatory or optional All dependencies are available Tests are provided to verify that the installation has succeeded A containerised package is available, containing the code together with all of the related configuration files, libraries, and dependencies required. Using .e.a. Docker/Singularity Easy to use A getting started guide is provided outlining a basic example of using the software e.a. a README file Instructions are provided for many basic use cases Reference guides are provided for all command-line, GUI and configuration

	١,				
	Reusability of the pipeline  Can the code be reused easily by other people to develop new projects? If  Have an open licence <u>Choosing an open source licence</u> Have easily accessible source code <u>Choosing a repository for your</u> Adhere to coding standards <u>Writing readable source code</u> Utilise tests <u>Testing your software</u>				
		Open licence	Software has an open source licence e.g. GNU General Public License (GPL), BSD 3-Clause		
			Licence is stated in source code repository		
ı			Each source code file has a licence header		
Ī		Accessible code	Access to source code repository is available online		
			Repository is hosted externally in a sustainable third-party repository e.g. SourceForge, LaunchPad, GitHub: Introduction to GitHub		
Ц			Documentation is provided for developers		
ı		Code standards	Source code is laid out and indented well		
			Source code is commented		
			There is no commented out code		
			Source code is structured into modules or packages		
			Source code uses sensible class, package and variable names		
			Source code structure relates clearly to the architecture or design		
		Testing	Source code has unit tests		
			Software recommends tools to check conformance to coding standards e.g. A 'linter' such as PyLint for Python		
	40				

### Conclusions

- Data challenge 1 was a successful starting point, 9 teams competed, we developed an example solution afterwards to help guide the community
- Data challenge 2 is running now (Feb-July) with 40 teams, stepping up data size and workflow expectations
- We hope these data challenges will help prepare people for the kind of workflows that will be necessary with SKA data (but also relevant for any scientific data analysis)
- A great platform for spreading the word amongst the community about relevant technologies, efficient workflows, best practices in coding, publishing data and code, reproducibility
- Also helping a lot with our work on prototyping and developing technologies for the SKA regional centres