



Search for New Physics using un-supervised ML techniques

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IN2P3/IRFU ML workshop, CC-IN2P3, 22-23 janvier 2020

Direct Searches for New Physics



B. Nachman, D. Shih, arxiv:2001.04990

Bump hunt use-case





Direct search for New Physics at the LHC using **Autoencoders**

Two use-cases with **dijet** simulated samples

- LHC Olympics challenge → AE (jet substructure variables)
- Simulated **dijet data** \rightarrow GAN-AE (Event variables)

Conclusion and outlook

Why Autoencoders ?

An **Autoencoder** is a network trained to copy it input to its output

$$x \to h = f(x) \to \hat{x} = g(h)$$



Reproducing the **identity** is not useful → Restricted to **copy imperfectly**: forces the AE to **prioritize** information to **learn useful features**

Undercomplete or regularized AE

Usage: dimensionality reduction, representation learning, manifold learning, generative network, **anomaly detection**, ...

Autoencoders

Train AE on background samples: reconstructed error $|\ell| = ||x - \hat{x}||^2$



The idea being that the network will **learn** to main background features and **fail** to reconstruct **anomalous** sample \rightarrow **larger reconstruction error**

LHC Olympic challenge

Anomaly detection challenge for ML4Jets2020 conference (15-17/01/20)

- Simulated Background (dijet data) + Signal
 - **Benchmark** samples to develop method
 - Three LHCO 2020 Black Boxes "data" with unknown signal
- Datasets
 - Event selection: >=1 anti-kT R = 1.0 jet, $|\eta| < 2.5$ and pT > 1.2 TeV.
 - Data consists of [pt,eta,phi] for of up to 700 hadrons
- What was asked
 - **p-value** of dataset (for null hypothesis)
 - As complete as possible **description** of NP process
 - Number of signal events in the data (with uncertainties
- Challenge ran until Jan 12th, **10 team** submitted their results

High level features

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Pre-processing was necessary to extract jet features from raw data

- Jet Features (× two jets)
 - (*p*_T, η, φ, m), E
 - *nsj_{inclusive}*, *nsj_{exclusive}* (based on *d_{cut}*), *n_{constit}*
 - τ_1 , τ_2 , τ_3 , τ_3/τ_2 , τ_2/τ_1 (subjettinesses)
 - Energy rings $E_i = (\sum E_{constit})/E_{jet}$, where $\Delta R(jet, constit) \in [R_{jet}(i/n); R_{jet}((i+1)/n)]$, n=10

Event Features

• m_{jj} , $n_{jets}(p_T \ge 20 \, GeV)$

High level features

Correlation



Importance I. Dinu

(ranked with Gradient BDT)



HLF-AE: High Level Feature AE

Hyperparameter space scan

- Learning rate: 0.01, 0.005, 0.001, 0.0005, 0.0001
- Features used: 44
- 1st hidden layer nodes: 30,25
- 2nd hidden layer nodes: 20, 15
- Encoding dimension: 10,7,5
- Activations: ReLU, Leaky ReLU, ELU
- Batch size: 32, 64, 128, 256, 512, 1024

Grid Task on Manchester GPU Test Site

- 1180 configurations spread among 10 jobs
- custom Docker container for this architecture
 - \rightarrow gitlab link to code



Hyper Parameter Optimization



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Hyper Parameter Optimization

AUC distribution 5.85 % of configs 400 50.17 % of configs 43.98 % of configs 350 300 No. of configurations 250 200 150 100 50 0 0.3 0.4 0.5 0.6 0.8 0.7 AUC

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Results

Mean square error returned by AE

 \rightarrow training dataset (background) and black box samples 1-3:



A threshold value is applied and feature distributions are compared.

Results on Bbox-1 dataset

Invariant mass distribution after threshold on MSE error:

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Possible signal around 5.2 TeV ?

Challenge (sad) truth

LHC Olympics outcome: these slides



Challenge (sad) truth

LHC Olympics outcome: these slides



Team results: number of events 834 Signal Events



\rightarrow Our approach finds something but clearly biased ...

Simulated samples: dijet events

Dijet events (Madgraph+Pythia+Delphes):

- Background: 500k QCD dijets ($H_{T} > 400 \text{ GeV}$)
- Signal: 500k RPV-MSSM stop (615 GeV, 1 TeV)

10 input variables (selected using supervised BDT ranking)



GAN-AE architecture

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Network architecture



- → Discriminant objective : learn AE's weaknesses
- \rightarrow AE objective : correct these weaknesses

GAN-AE architecture

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Dropout rate: up to 20% or 40% depending on the layer

Training

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Training of discriminant



Loss function: binary cross-entropy

$$\ell = -\sum_{j} y_{j} \log(p_{j}) + (1 - y_{j}) \log(1 - p_{j})$$

Training

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Training of AE



Loss function: binary cross-entropy + ε x mean distance [ε =2%]

$$\ell = -\sum_{j=1}^{N} y_j \log(p_j) + (1 - y_j) \log(1 - p_j) + \frac{\epsilon}{N} ||\mathbf{x}_j^{\text{in}} - \mathbf{x}_j^{\text{out}}||$$

Training

Training cycle: 10 epochs on D, 4 epochs on AE (asymmetric training) **Stopping criterion:** evaluation of AE performance (validation sample)



FOM = Mean distance + (1- mean D output)

Testing

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Application: only the AE is used on test events



Trained AE is applied on both background and signal test samples

Preliminary results

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Double peaks in distance calculation: to be understood AUC ~ 0.7 for both signal masses

Comparison with standalone AE



GAN-AE performs better for low mass signal (most difficult)

Issues with unstability

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Results (AUC) show high variance: here for 60 GAN-AE (signal m=615 GeV)



Conclusion and Outlook

AE seem a good idea for unsupervised searches

However simple use case are not conclusive

- Appearance of spurious signal ? (LHC Olympics dataset)
- Instabilities (dijet sample)

More work needed on NN architectures (GAN-AE could be promizing)

Try to generalize to more complex signatures

Model independent methods

General searches in CMS & ATLAS

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Model independent methods

Autoencoders approaches

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Bump hunt approaches

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backup





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Loss curve of the discriminant



Loss evaluated at each cycle after D training phase

Spiky behavior : AE as changed between each evaluations => Performence of D varies at each cycle



