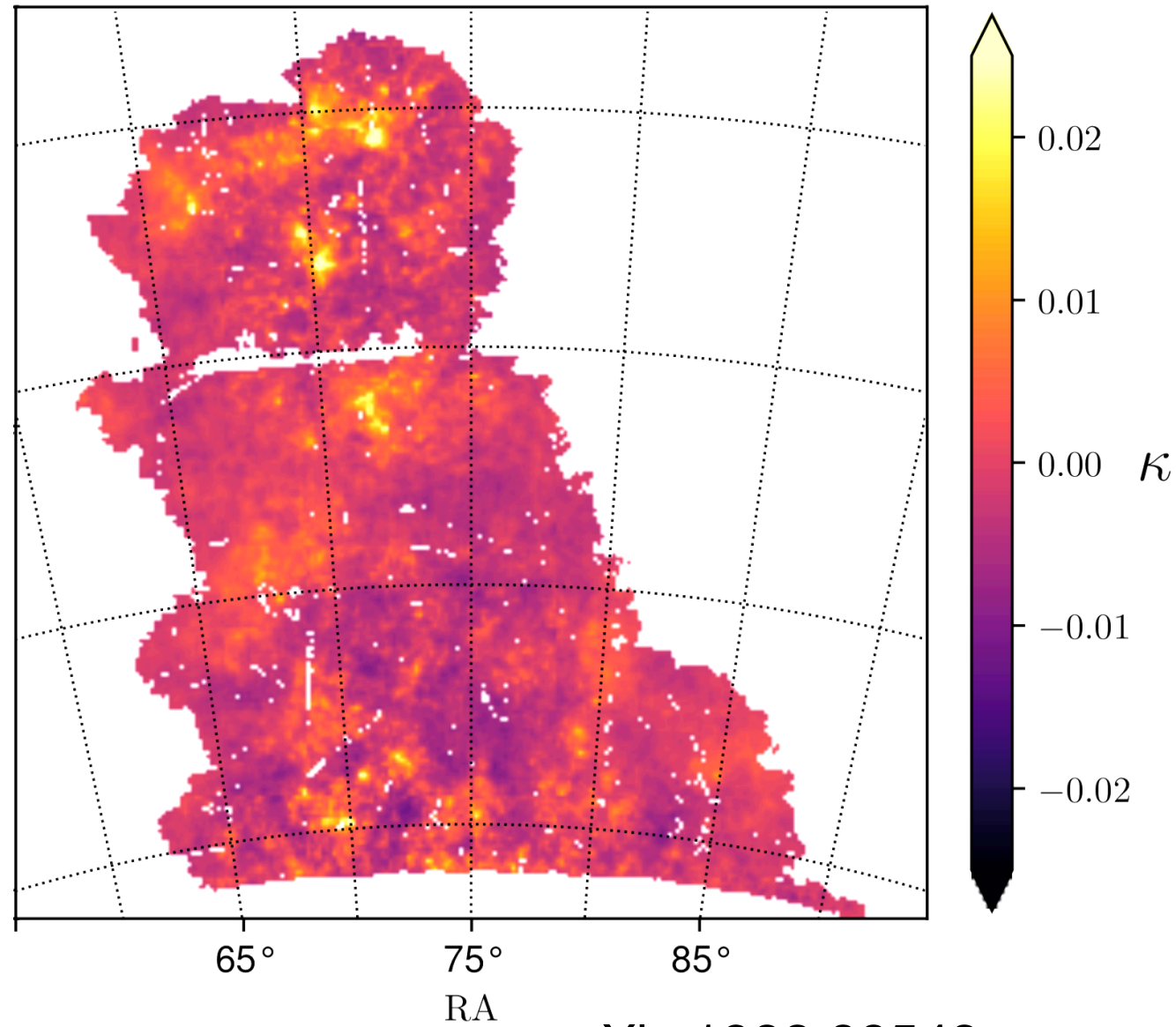


DeepMass

Deep learning dark matter map reconstructions from DES weak lensing data

Niall Jeffrey

DeepMass



Outline

1. Weak lensing map reconstruction
2. Deep learning a Bayesian estimate
3. Dark Energy Survey results
4. New results:
DeepMass and the CMB

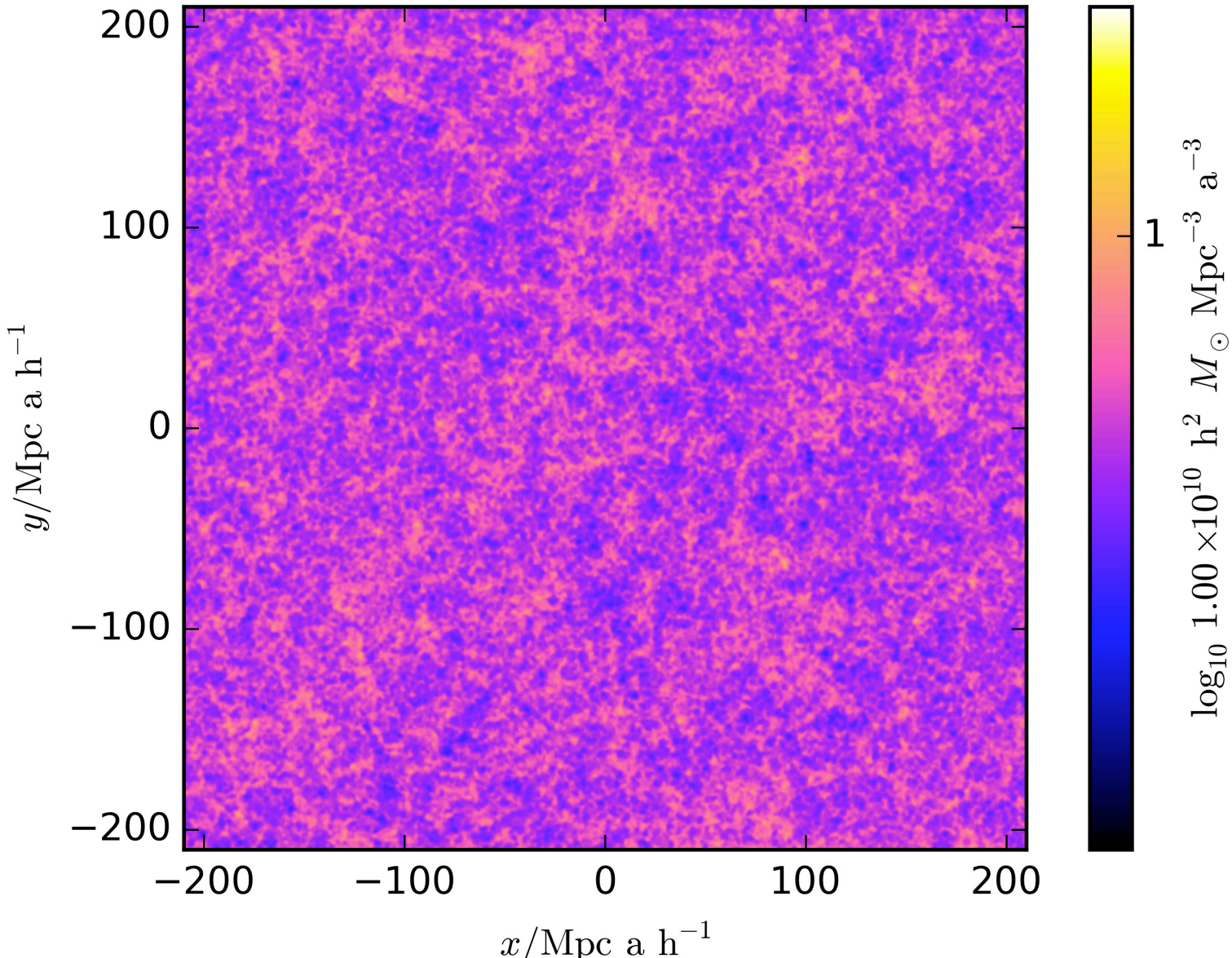
01

Weak lensing mass maps

Growth of structure

L-PICOLA simulation

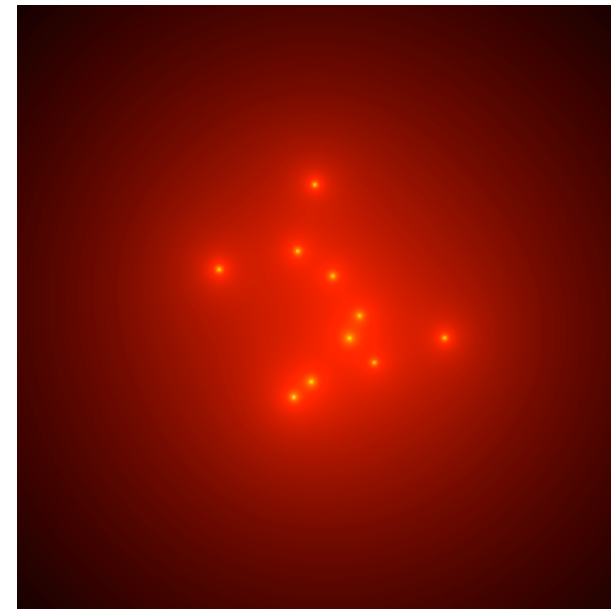
13.13 Billion Years Ago ($z = 35.000$)



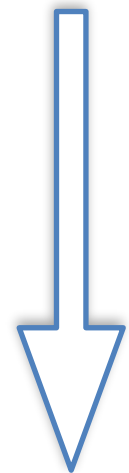
Mass mapping

Weak gravitational lensing

- I. Galaxy shape encoded in the shear: γ
- II. Weighted projected density is convergence: κ
- III. Objective: use observed γ from galaxies to reconstruct κ



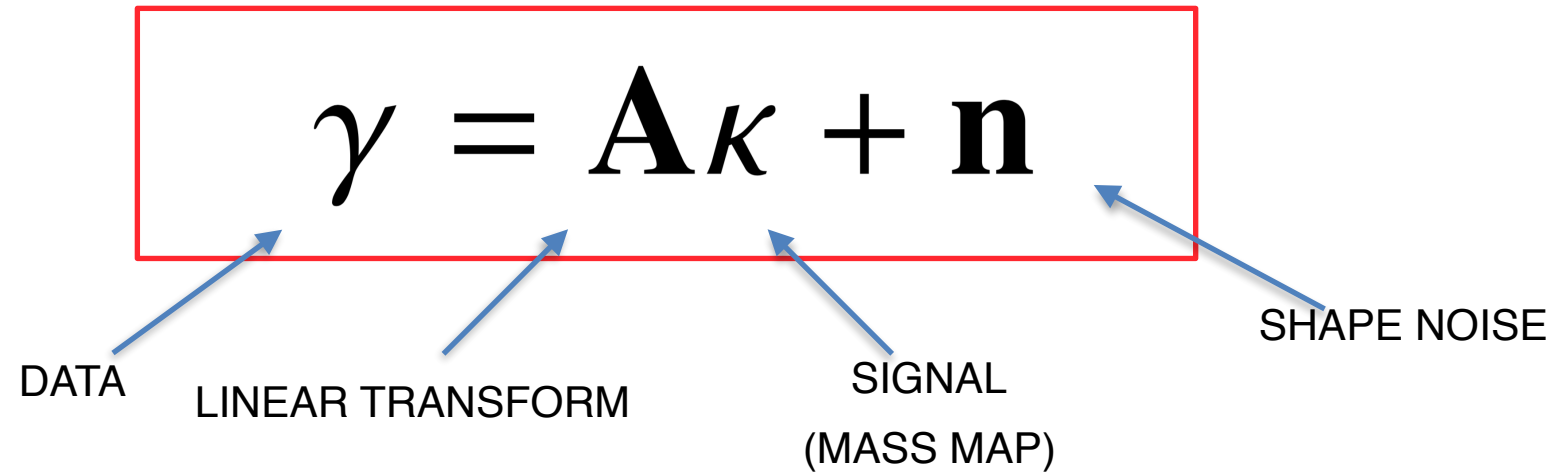
DATA



CONVERGENCE

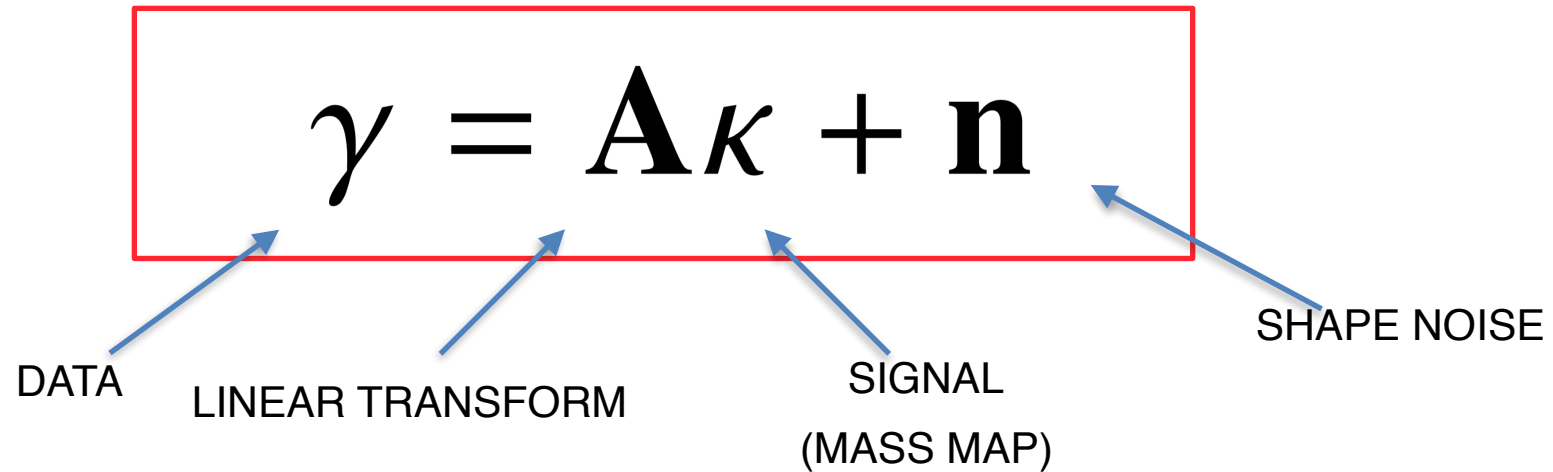
Mass mapping

Linear data model



Mass mapping

Linear data model



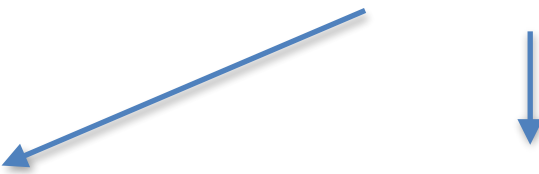
Kaiser-Squires 1993 Estimator

$$\hat{\gamma}(\vec{l}) = \pi^{-1} \hat{\mathcal{D}}(\vec{l}) \hat{\kappa}(\vec{l})$$

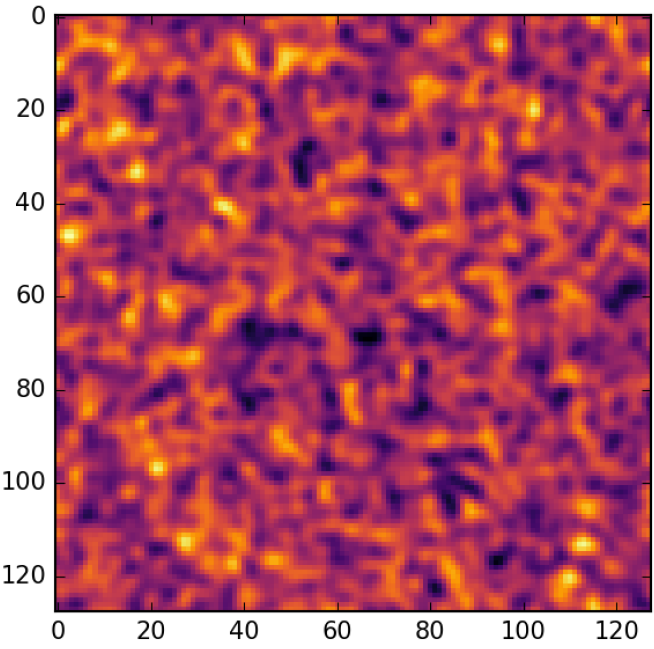
Mass mapping inference

Bayesian “*maximum a posteriori*”

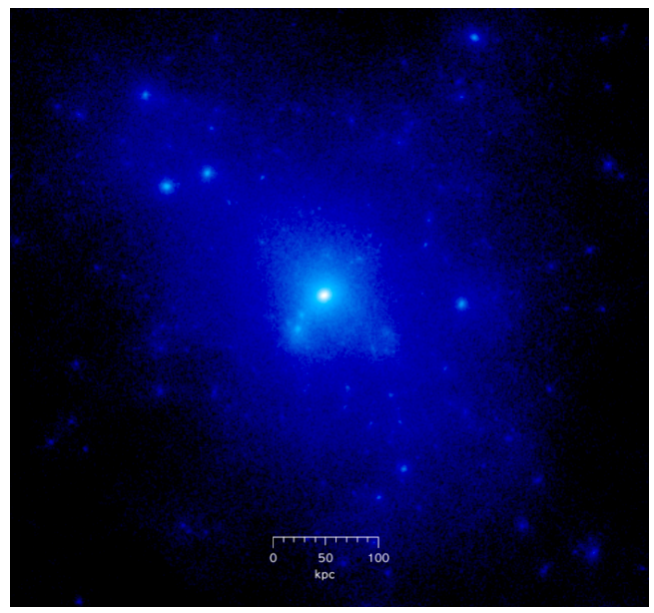
$$\hat{\kappa} = \arg \max_{\kappa} \log P(\gamma|\kappa, \mathcal{M}) + \log P(\kappa|\mathcal{M})$$



Gaussian Random Field?



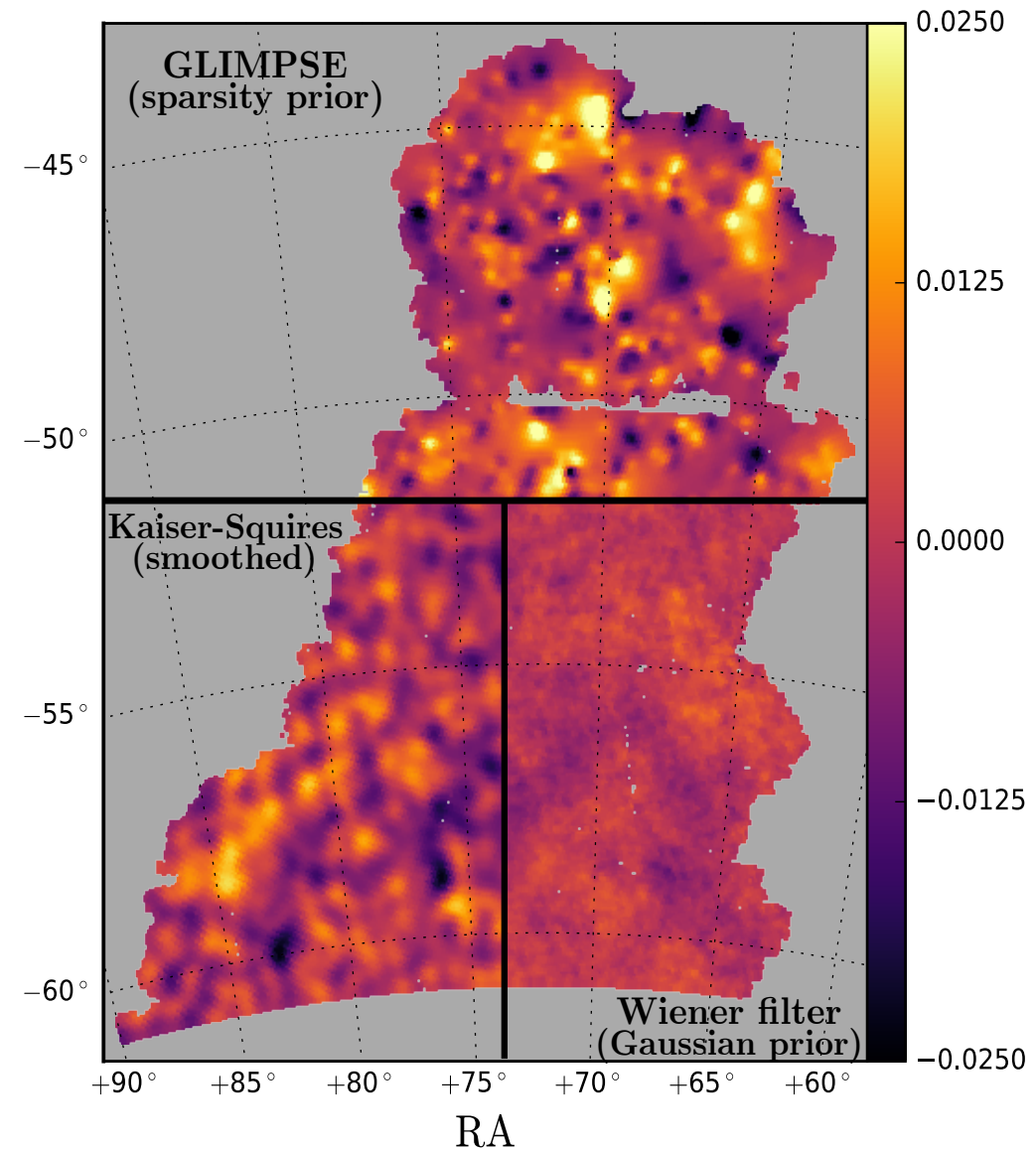
Dark Matter Halos?



Approximate priors

DES SV results

- I. Improved accuracy:
 - i. Gaussian prior (Wiener filter)
 - ii. "Halo-model" sparsity prior (GLIMPSE)
- II. Sparsity prior increases peaks statistic signal-to-noise (up to x9)



The perfect prior?

No closed-form probability distribution of the matter field for the late Universe...

$$P(\kappa | \theta, \mathcal{M})$$

Parameters

Cosmological model

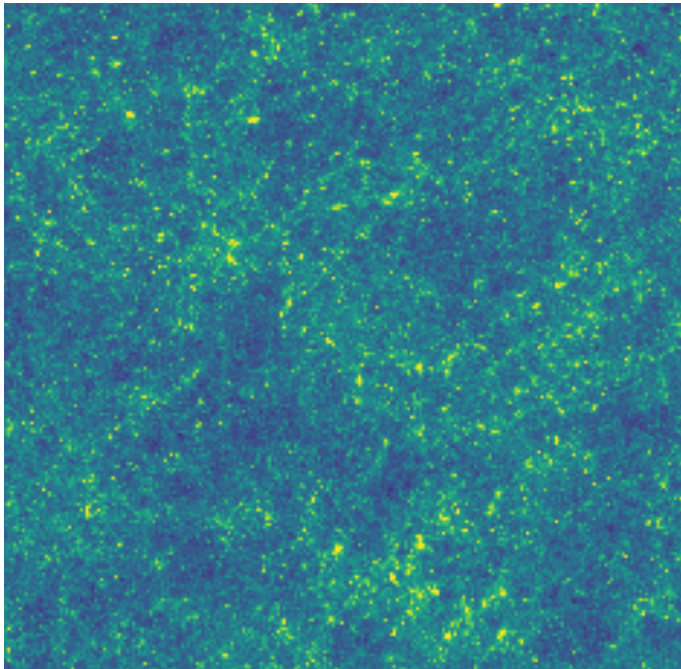
The perfect prior?

But, we can sample from the prior distribution...

$$\curvearrowright P(\kappa | \theta, \mathcal{M})$$

The perfect prior?

But, we can sample from the prior distribution...

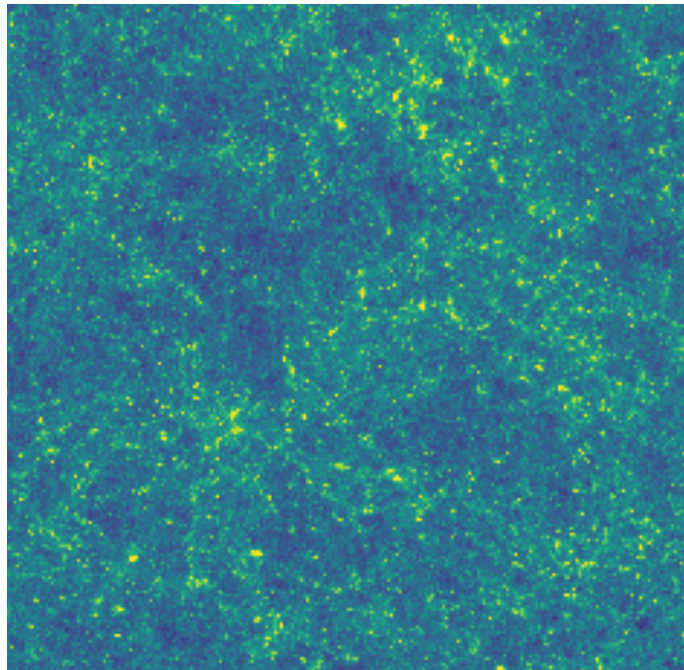


$$\curvearrowright P(\kappa | \theta, \mathcal{M})$$

simulated convergence map

The perfect prior?

But, we can sample from the prior distribution...

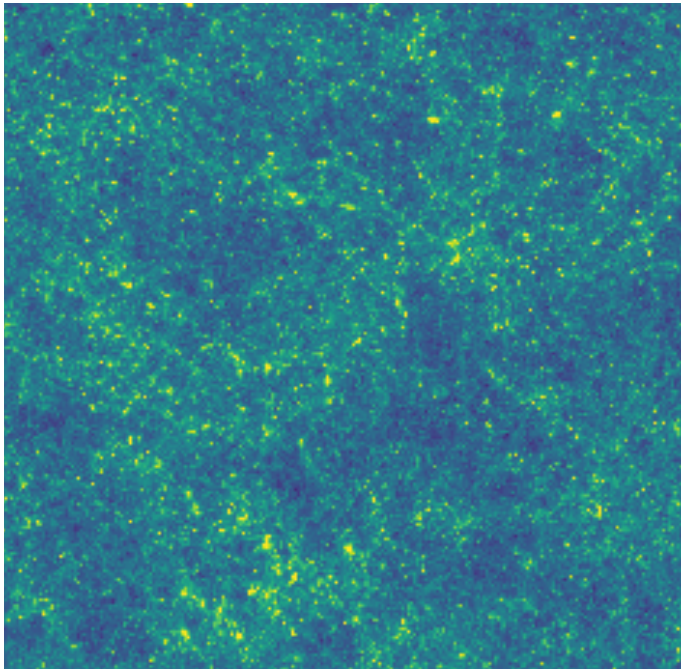


simulated convergence map

$$\curvearrowright P(\kappa|\theta, \mathcal{M})$$

The perfect prior?

But, we can sample from the prior distribution...



$$\leftarrow P(\kappa | \theta, \mathcal{M})$$

simulated convergence map

02

Deep learning a Bayesian estimate

Mean posterior estimate

Deep learning framework

I. We seek to approximate the mean posterior:

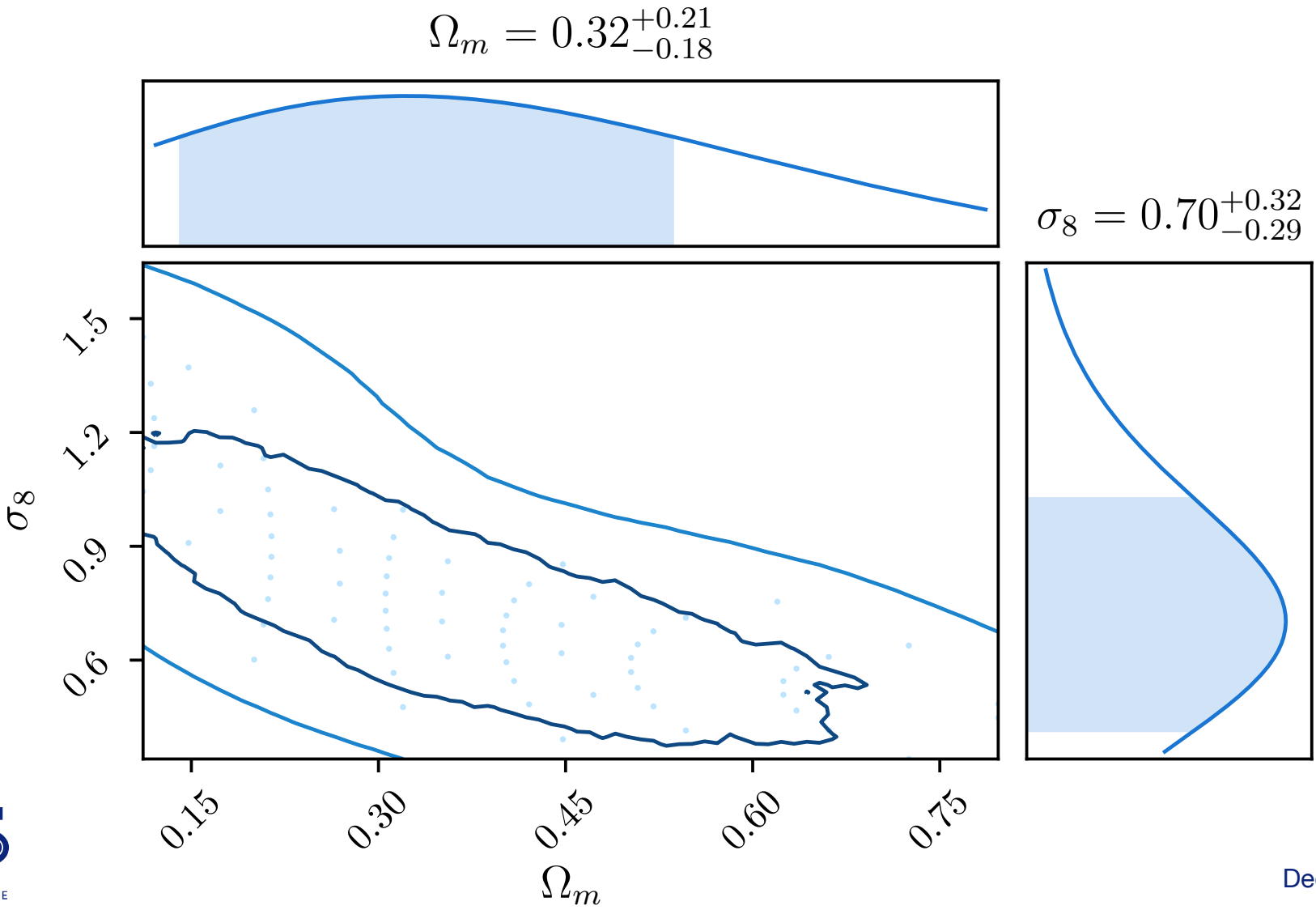
$$\hat{\kappa} = \mathcal{F}_{\Theta}(\gamma) = \int \kappa P(\kappa|\gamma) d\kappa$$

II. This is achieved by minimising:

$$J(\Theta) = \left\| \mathcal{F}_{\Theta}(\gamma) - \kappa_{\text{true}} \right\|_2^2$$

Step 1

Sample simulations from prior $P(\theta)$



Step 2

Learn the unknown function

$$\hat{\mathbf{K}} = \mathcal{F}_{\Theta}(\gamma)$$

- I. Approximate function as a Convolutional Neural Network (CNN)
- II. Unknown parameters Θ are mainly convolution filters
- III. Minimise $J(\Theta)$ using 3×10^5 {clean map, noisy data} realisations

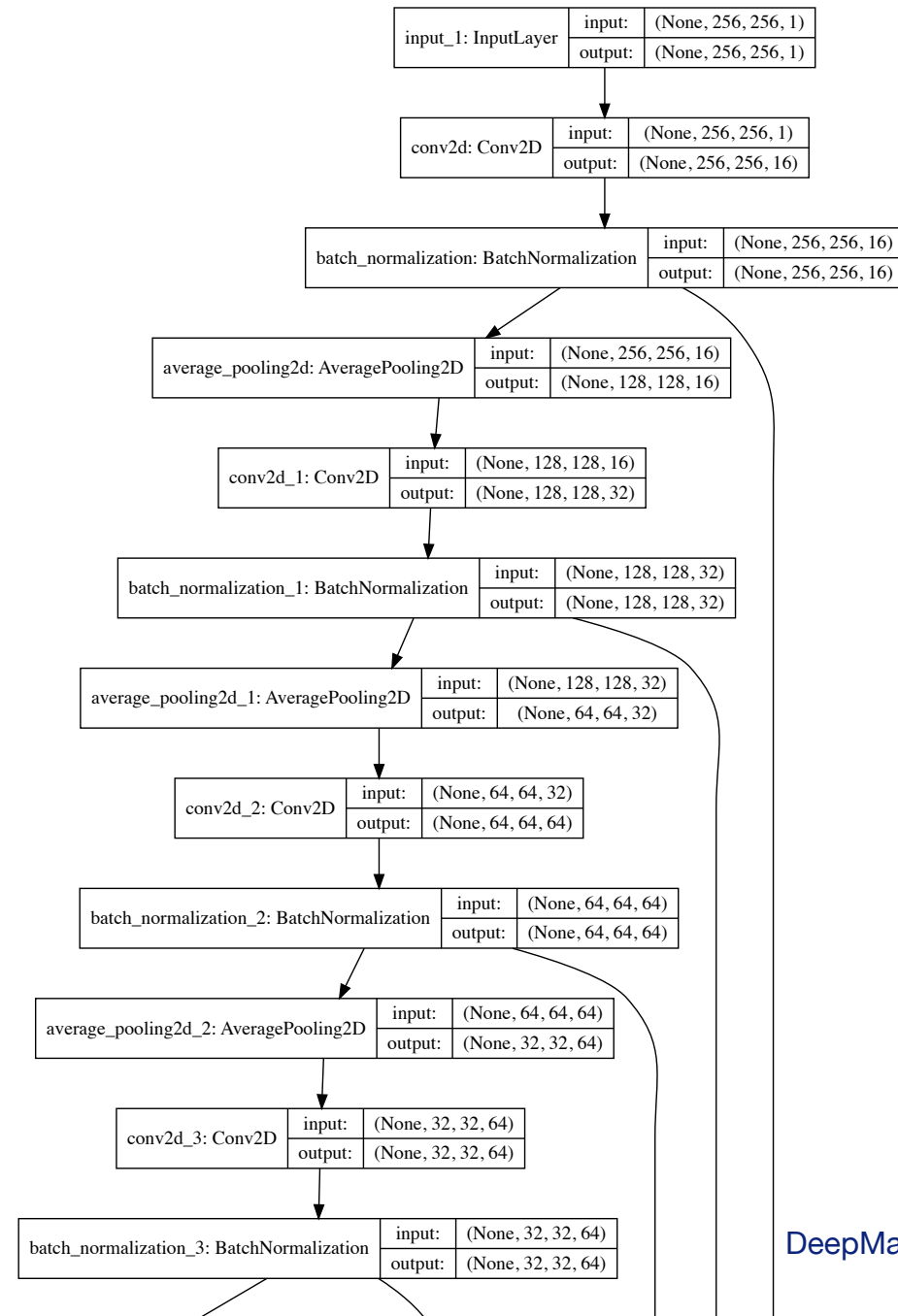
DeepMass architecture: U-Net

Expanding and contracting paths

I. Hierarchy of downsampling i.e. “pooling”

II. Increasing filter “receptive area”

III. Multiscale filters



03

Results with Dark Energy Survey data

Dark Energy Survey

SV weak lensing data

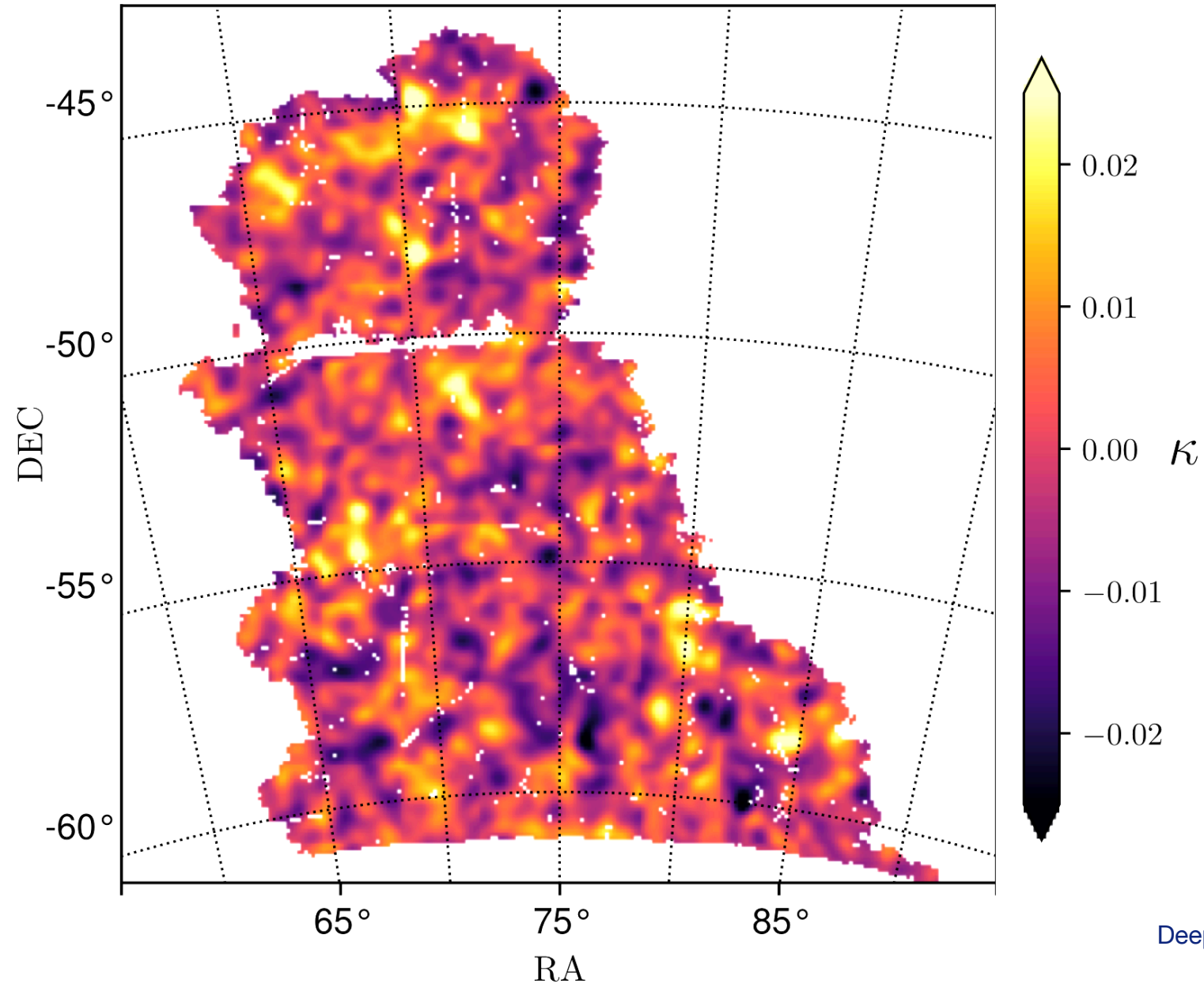


- I. Ground based 5-band photometric survey (just completed 6 years)
- II. Science Verification (SV) data are $<5\%$ of the final coverage, but to final depth
- III. 1.6 million background galaxies with $0.6 < z < 1.2$ in this sample

Results

Dark Energy Survey SV data

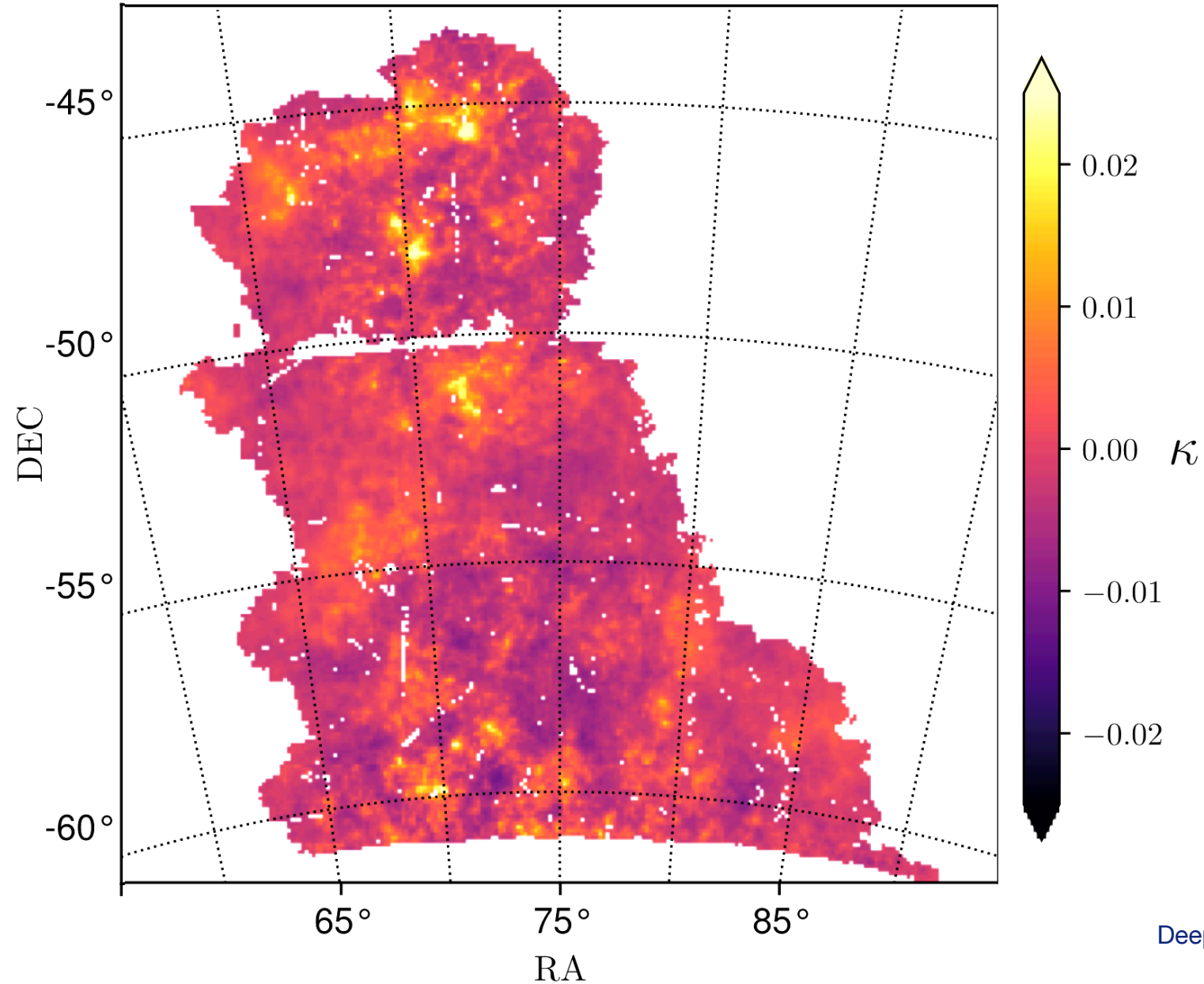
Kaiser-Squires



Results

Dark Energy Survey SV data

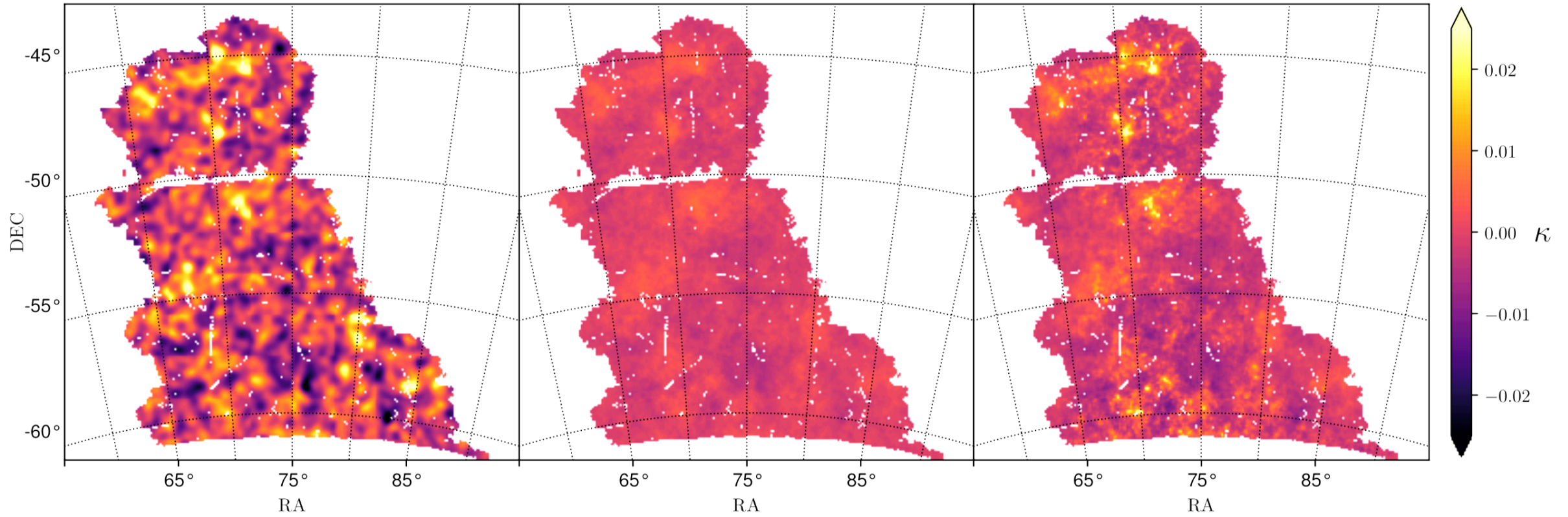
DeepMass

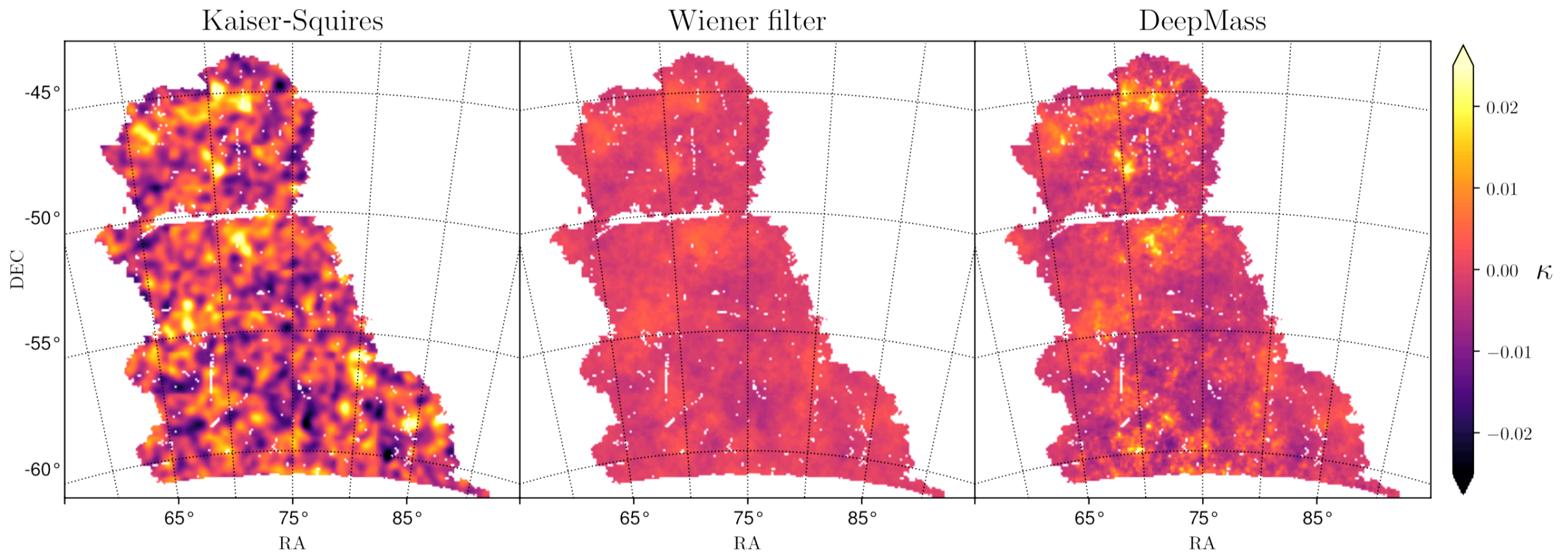


Kaiser-Squires

Wiener filter

DeepMass





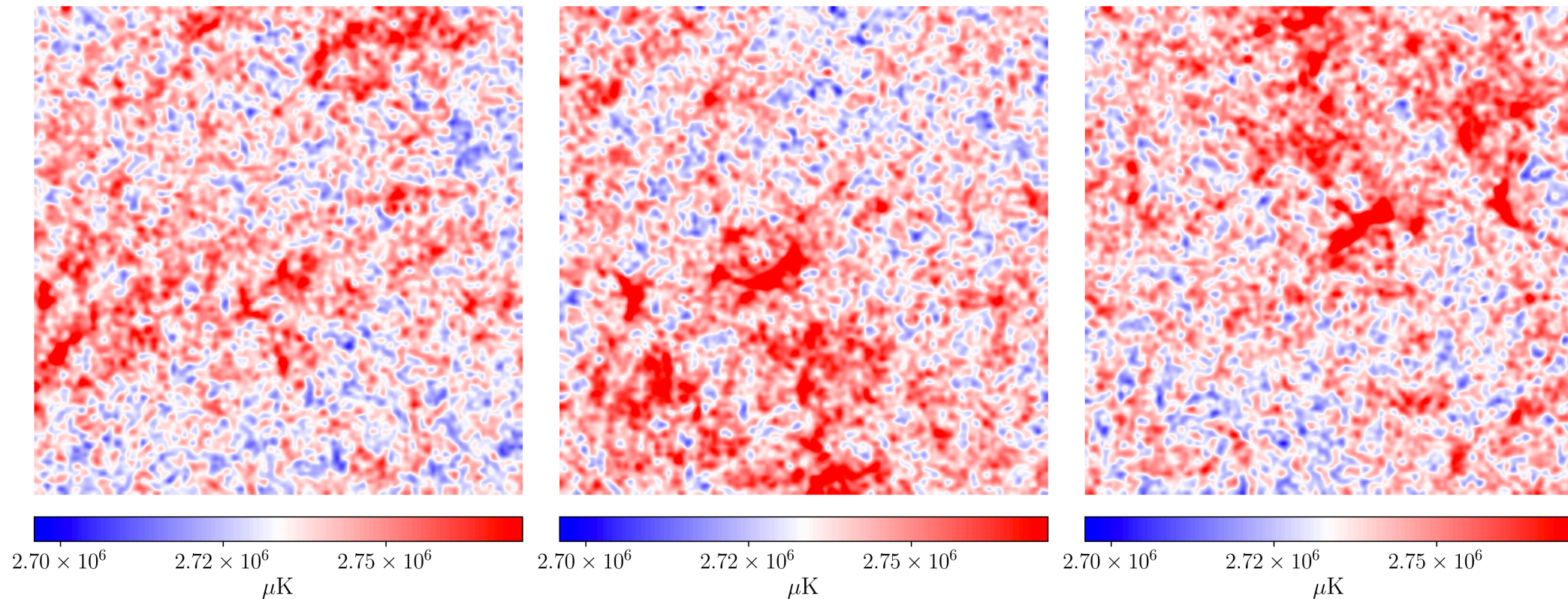
- I. Wiener filter is optimal linear MSE filter
- II. 8000 sample maps not used for training
- III. DeepMass improves MSE by 11% compared to Wiener

04

DeepMass and the CMB
(Preliminary)

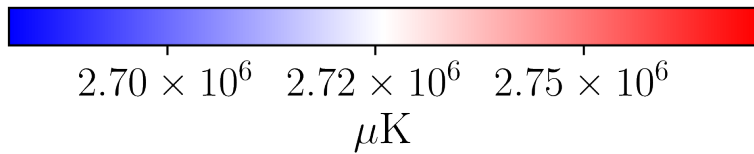
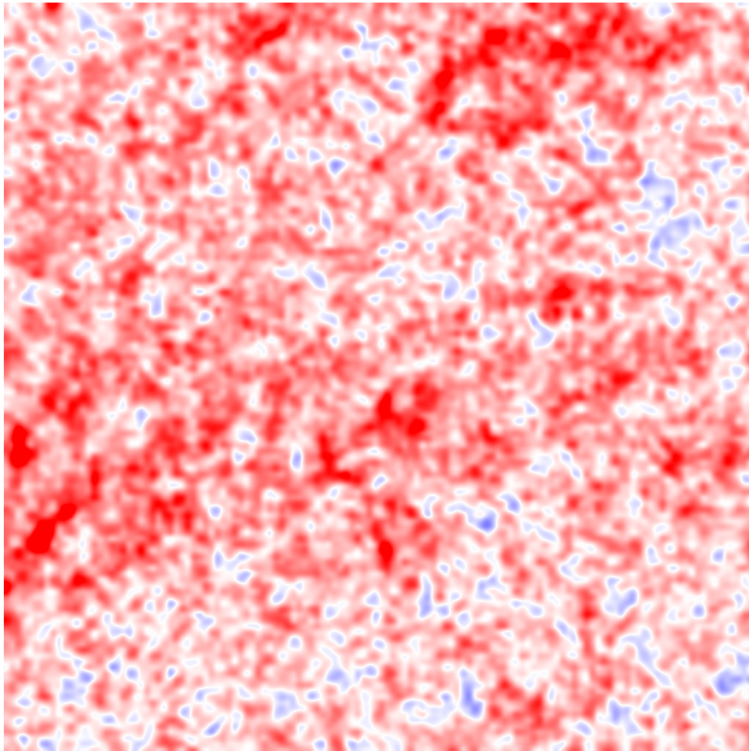
DeepMass as general tool

- I. If observations can be modelled, DeepMass recovers the signal
- II. Example, synthesise CMB foreground data: *(See Francois Boulanger's talk)*



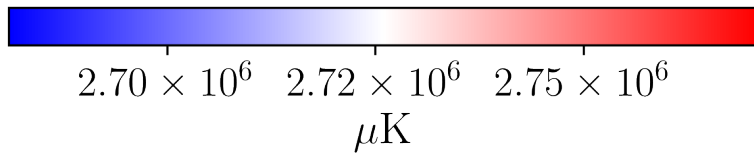
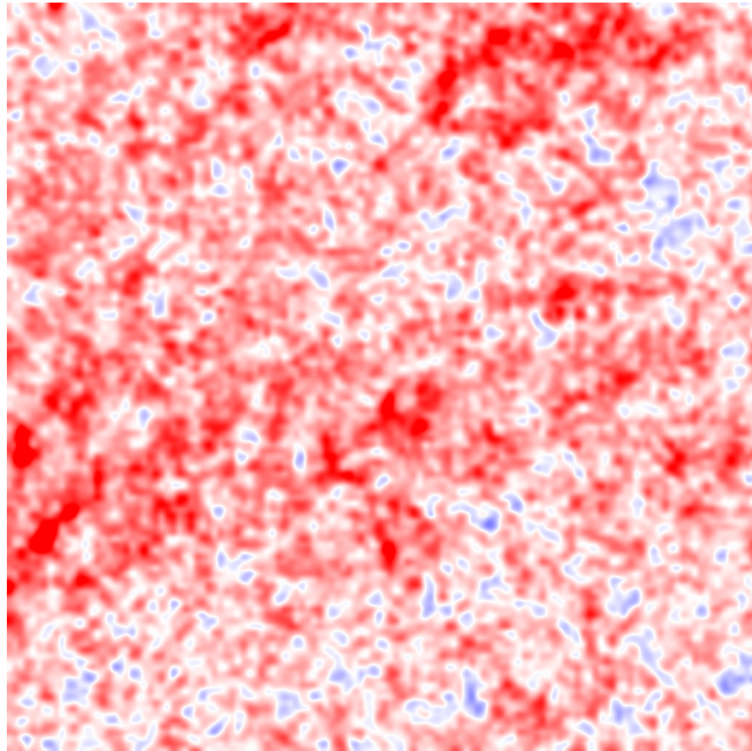
DeepMass: CMB T foreground removal (preliminary)

Simulated observed data

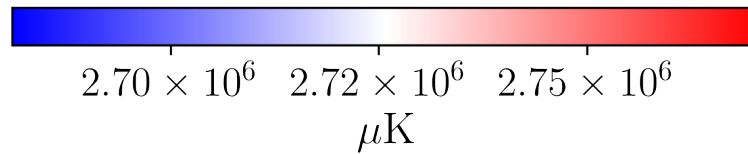
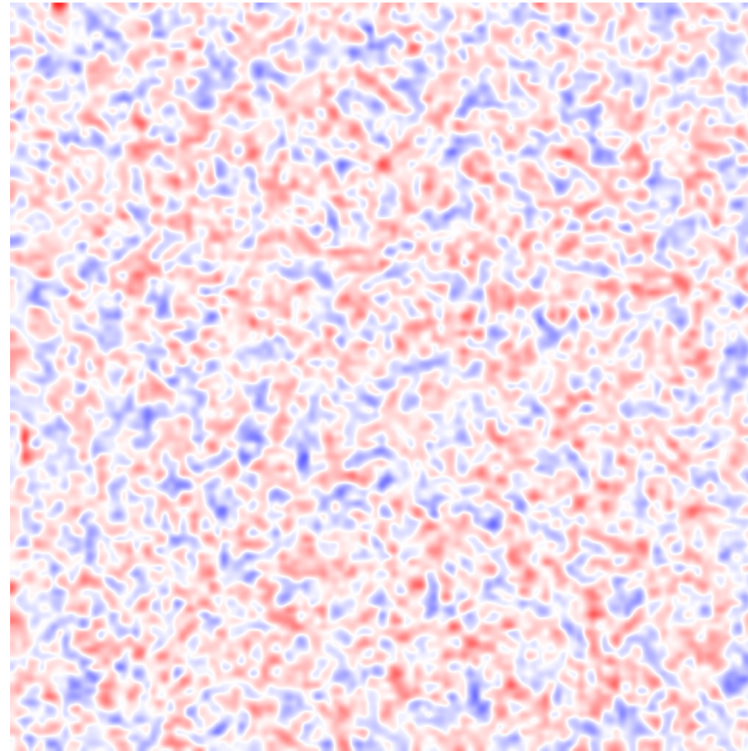


DeepMass: CMB T foreground removal (preliminary)

Simulated observed data

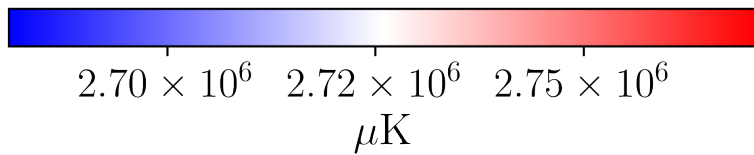
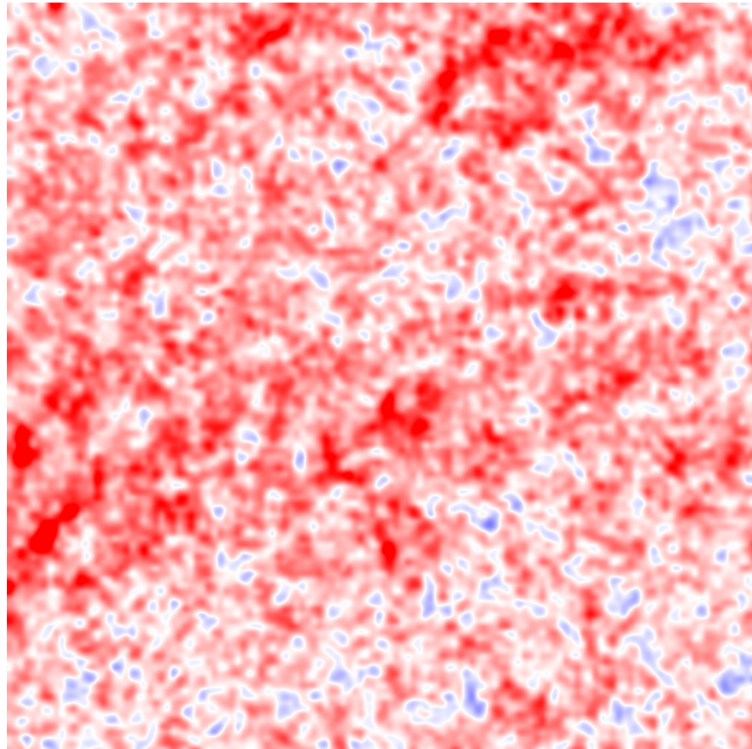


DeepMass recovered map

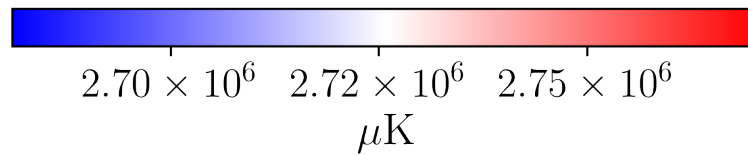
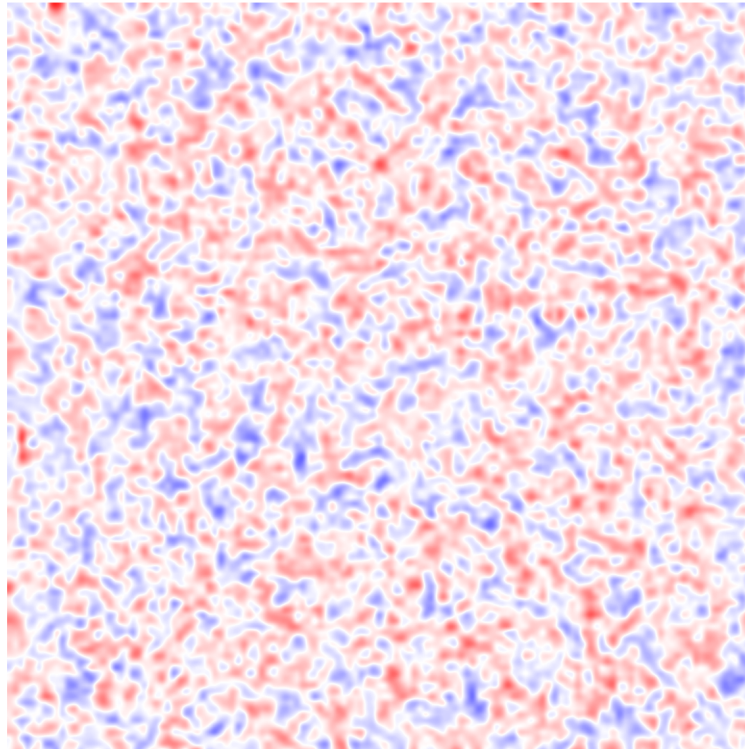


DeepMass: CMB T foreground removal (preliminary)

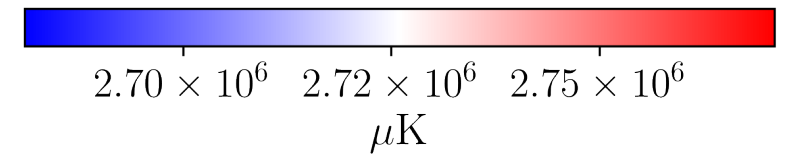
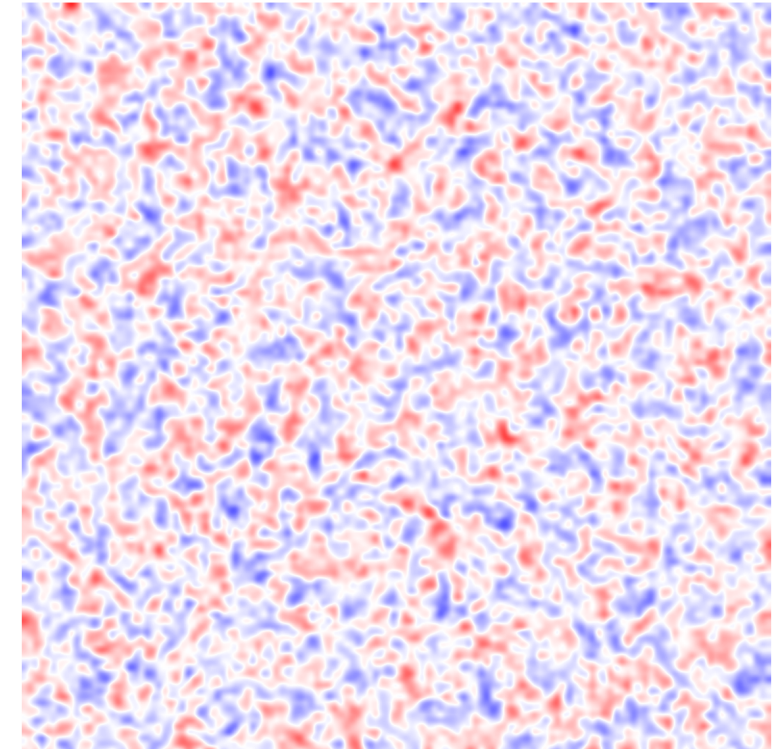
Simulated observed data

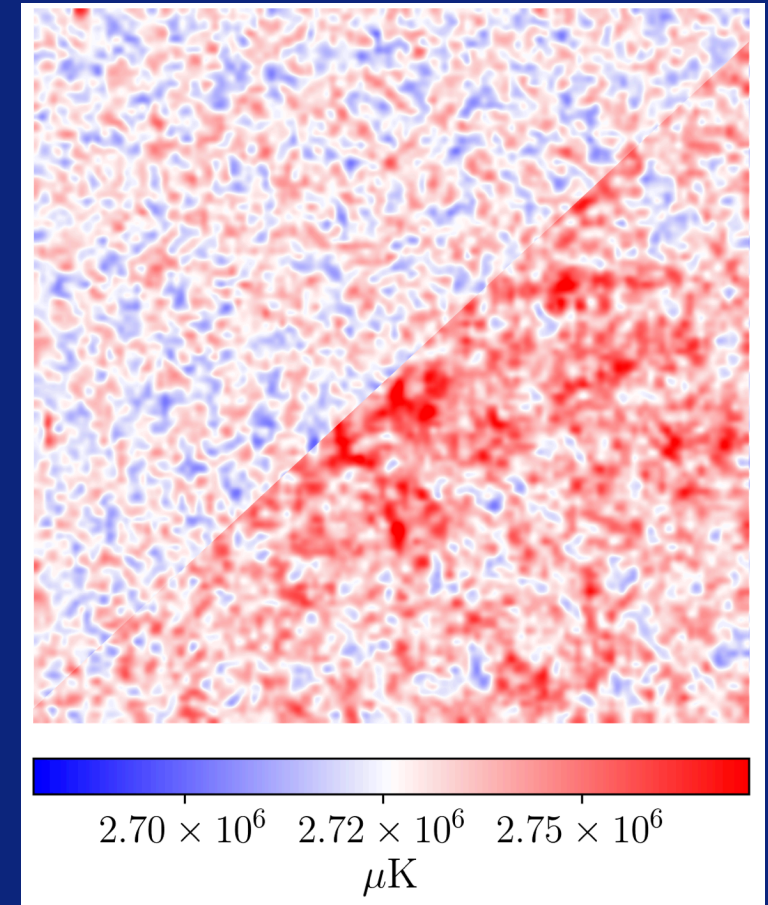
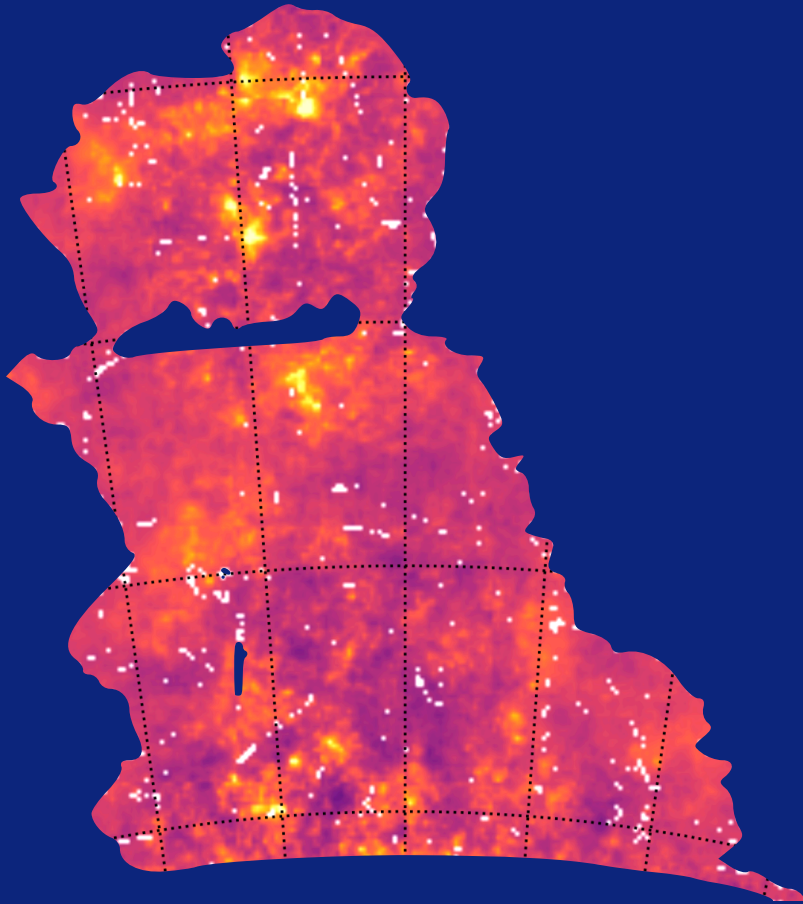


DeepMass recovered map



Simulated CMB T





Merci !