

The two-body potential in modified gravity

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Arxiv:1905.07340

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Dark energy meeting, IAP
20/05/2019

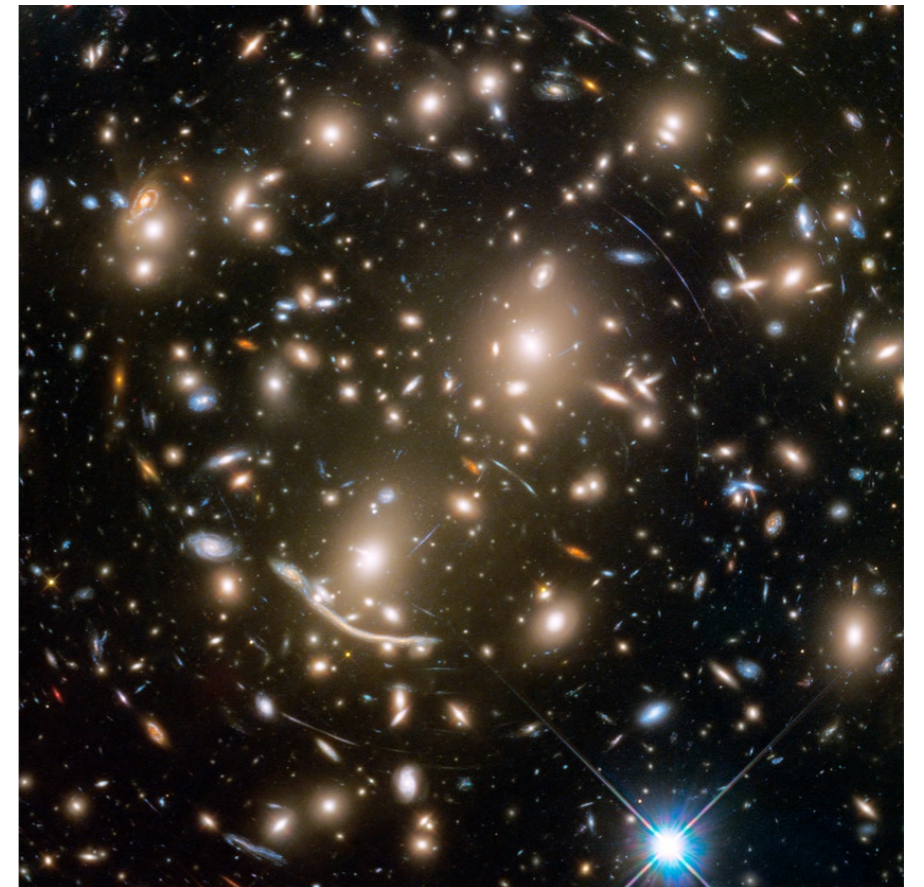
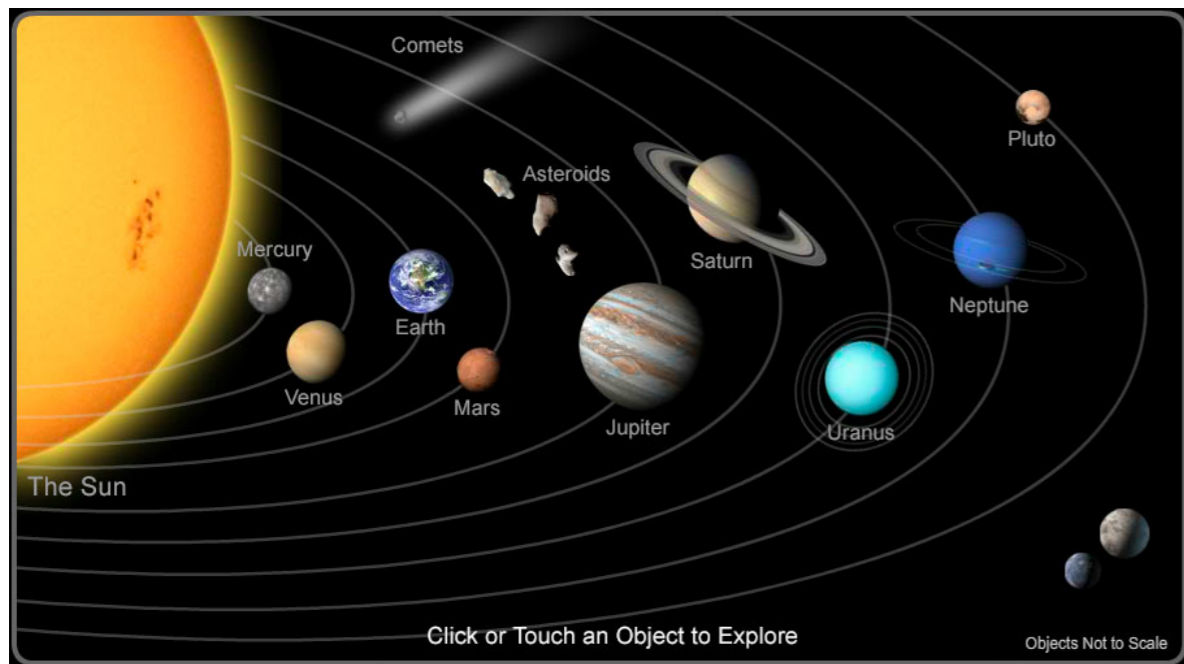
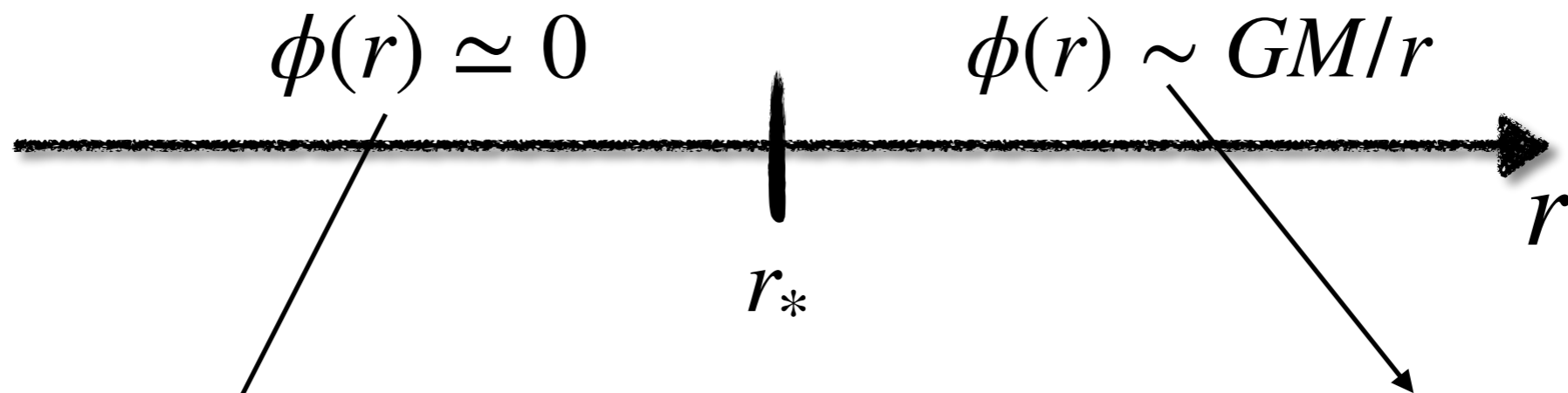
Motivation

Modified gravity should incorporate screening in order to recover GR on solar system scales



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Spherically symmetric screening

Take the simplest screening : $S = \int d^4x \left[-\frac{(\partial\phi)^2}{2} - \frac{1}{4\Lambda^4}(\partial\phi)^4 + \frac{\phi T}{M_P} \right]$
(K-Mouflage)

Spherically symmetric screening

Take the simplest screening : $\tilde{S} = \int dt d^3x \left[-\frac{1}{2}(\nabla \tilde{\phi})^2 - \frac{1}{4}(\nabla \tilde{\phi})^4 + \tilde{\phi} \tilde{T} \right]$
(K-Mouflage)

$$\phi' + (\phi')^3 = \frac{M}{r^2}$$

Spherically symmetric screening

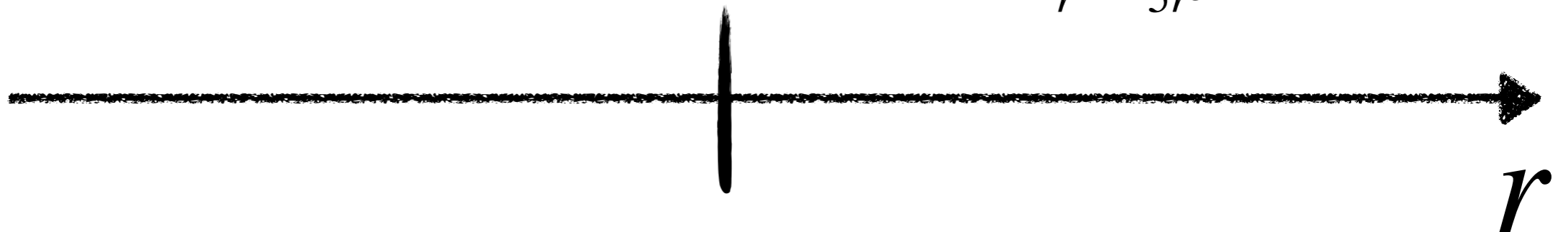
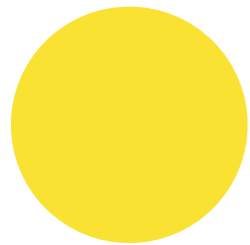
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(K-Mouflage)

$$\phi' + (\phi')^3 = \frac{M}{r^2}$$

$$\Rightarrow \phi(r) = -\frac{M}{r} {}_3F_2 \left(\frac{1}{4}, \frac{1}{3}, \frac{2}{3}; \frac{5}{4}, \frac{3}{2}; -\frac{27M^2}{4r^4} \right)$$

$$\phi(r) = 3(Mr)^{1/3} + \dots$$

$$\phi(r) = -\frac{M}{r} + \frac{M^3}{5r^5} + \dots$$

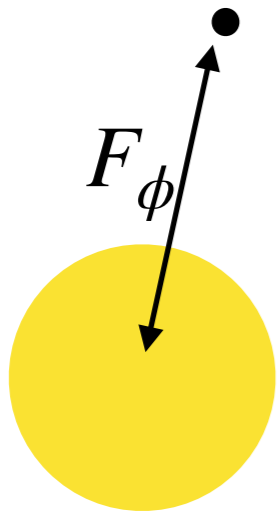


$$r_* = \sqrt{M}$$

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Modified gravity should incorporate screening in order to recover GR on solar system scales

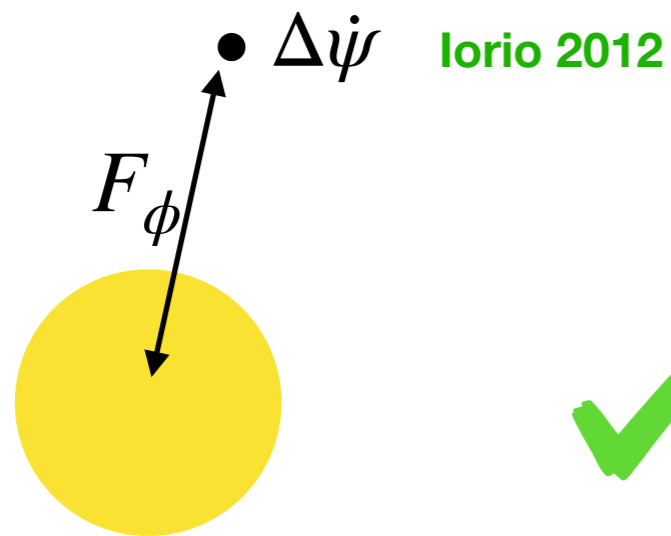
Still small-scale tests of GR are very precise !



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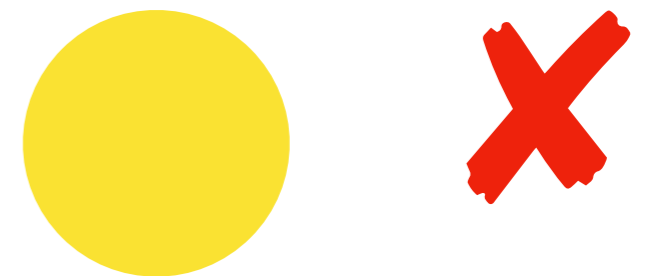
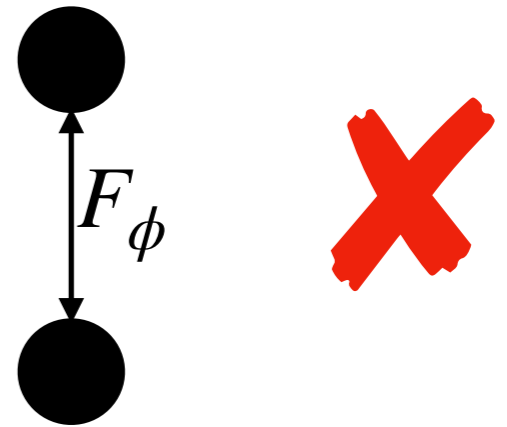
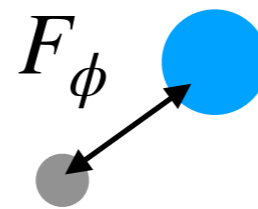
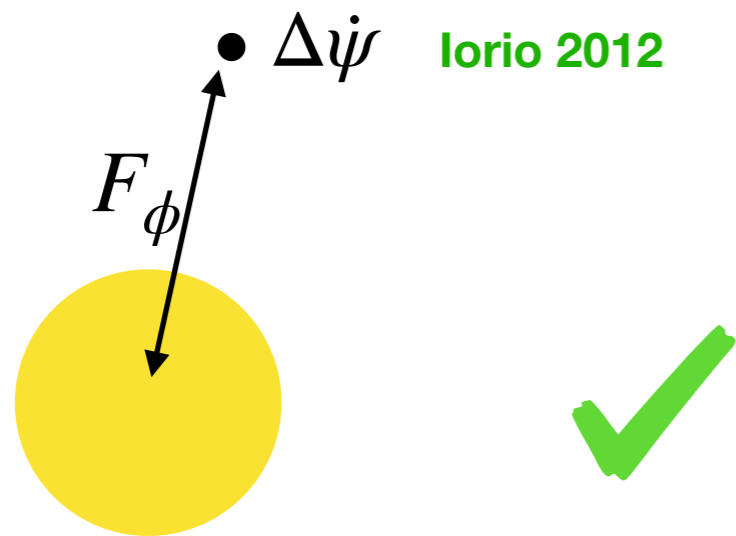
Still small-scale tests of GR are very precise !



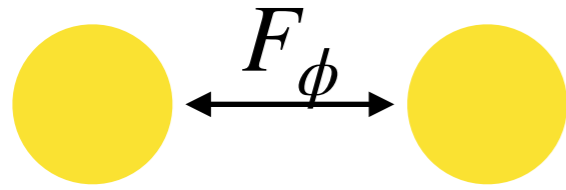
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Still small-scale tests of GR are very precise !



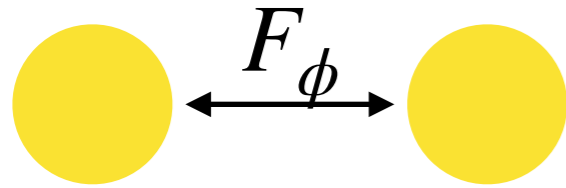
The two-body problem : outside



$$\tilde{S} = \int dt d^3x \left[-\frac{1}{2}(\nabla \tilde{\phi})^2 - \frac{1}{4}(\nabla \tilde{\phi})^4 + \tilde{\phi} \tilde{T} \right]$$

$$\tilde{T} = -m_1 \delta^3(\mathbf{x} - \mathbf{x}_1) - m_2 \delta^3(\mathbf{x} - \mathbf{x}_2)$$

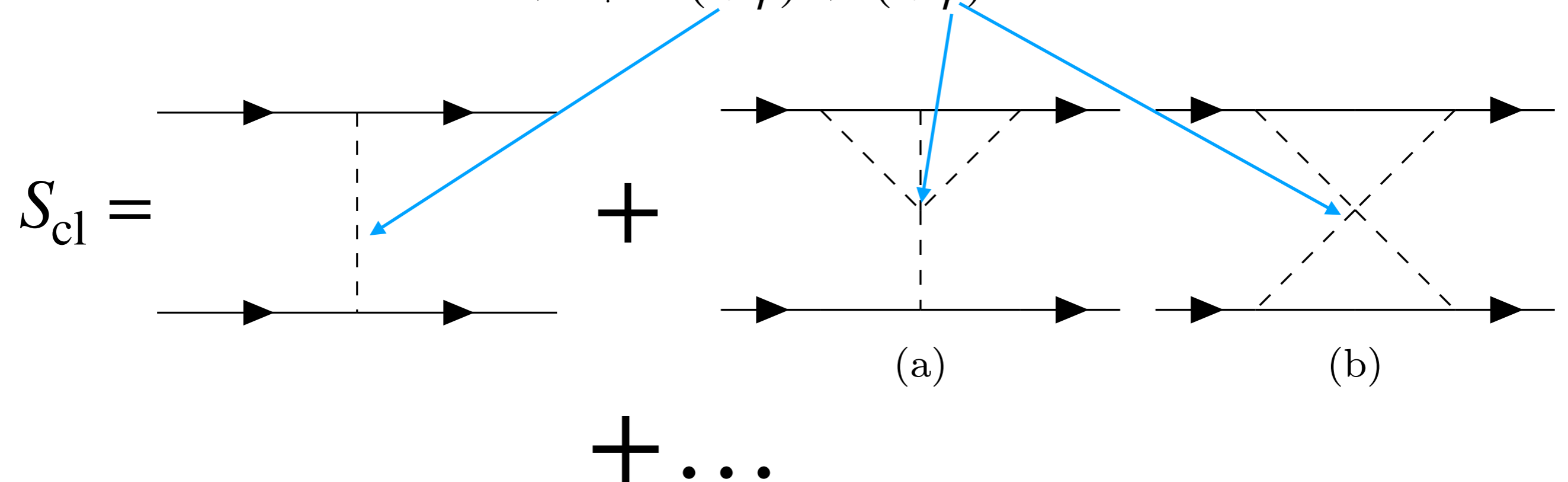
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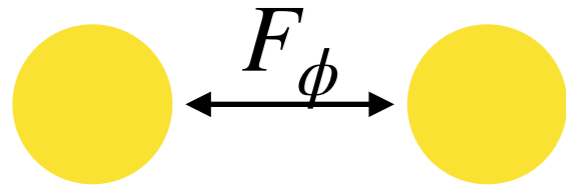
$$\tilde{S} = \int dt d^3x \left[-\frac{1}{2}(\nabla \tilde{\phi})^2 - \frac{1}{4}(\nabla \tilde{\phi})^4 + \tilde{\phi} \tilde{T} \right]$$

$$e^{iS_{\text{cl}}[\mathbf{x}_1, \mathbf{x}_2]} = \int \mathcal{D}[\phi] e^{iS[\mathbf{x}_1, \mathbf{x}_2, \phi]}$$

$$r > r_* \Leftrightarrow (\nabla \phi)^2 > (\nabla \phi)^4$$

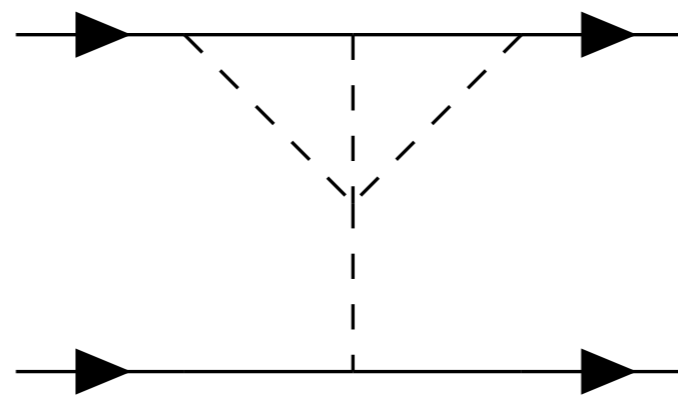
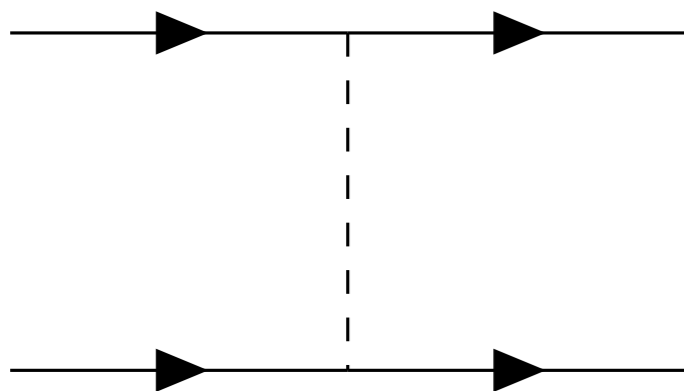


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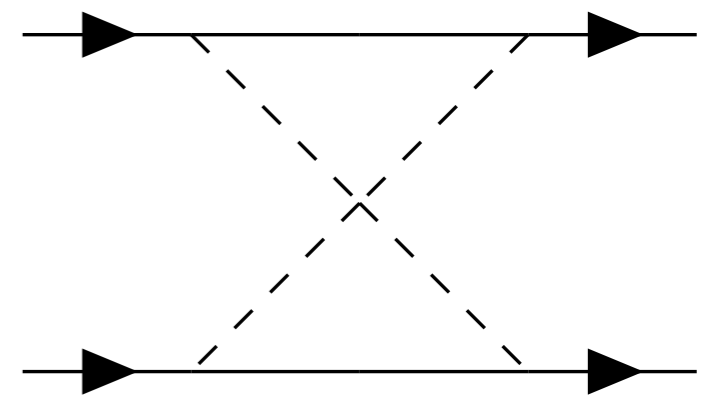


$$\tilde{S} = \int dt d^3x \left[-\frac{1}{2}(\nabla \tilde{\phi})^2 - \frac{1}{4}(\nabla \tilde{\phi})^4 + \tilde{\phi} \tilde{T} \right]$$

$$\int dt E = -S_{\text{cl}} \Rightarrow E = -\frac{m_1 m_2}{r} + \frac{m_1 m_2 (m_1^2 + m_2^2)}{5r^5} + \dots$$



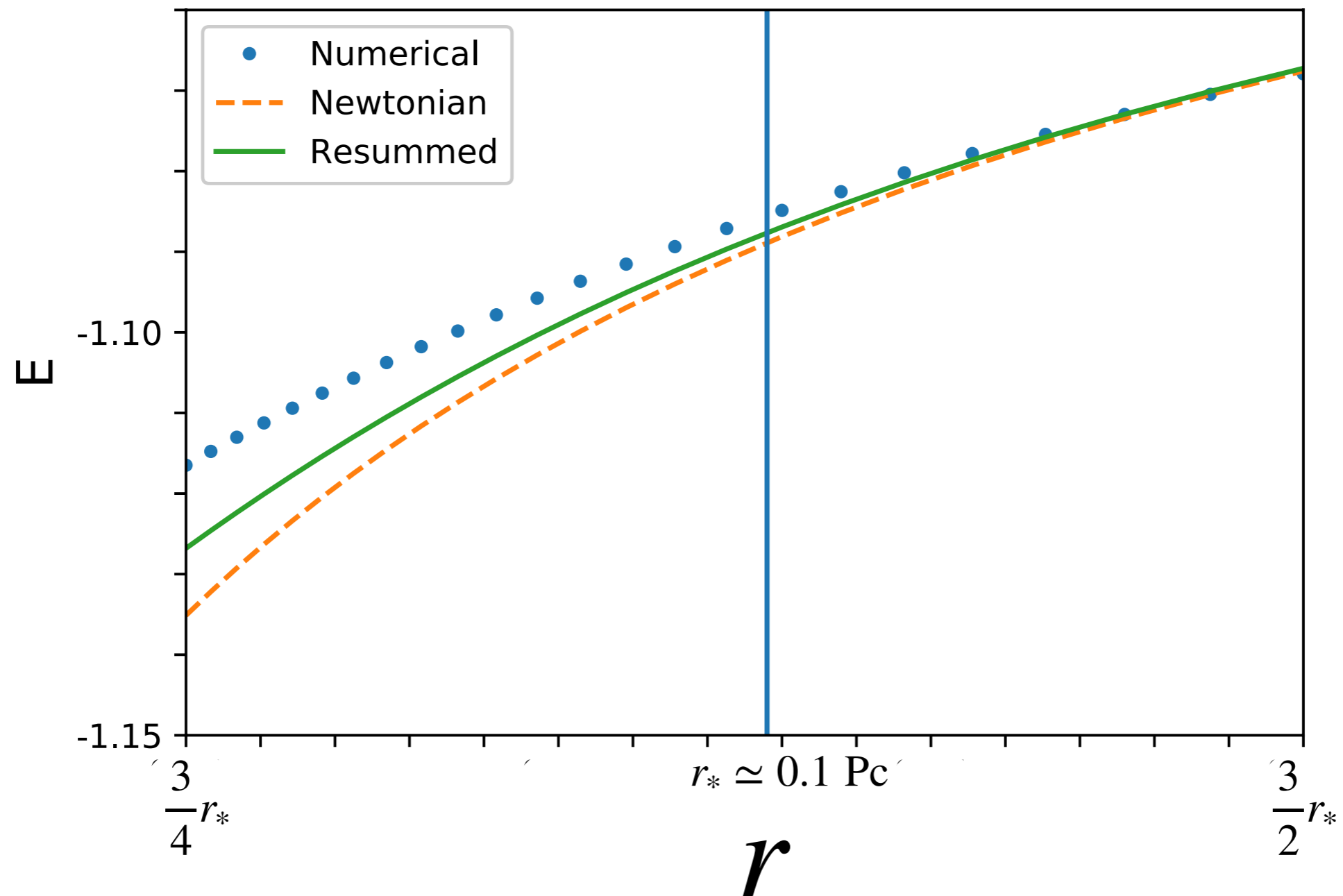
(a)



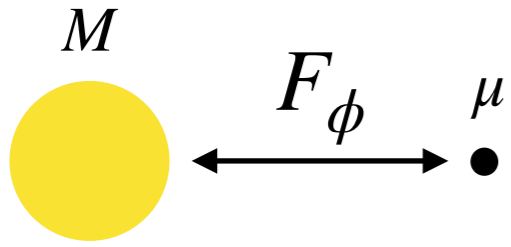
(b)

The two-body problem : outside

$$E = -\frac{m_1 m_2}{r} + \frac{m_1 m_2 (m_1^2 + m_2^2)}{5r^5} + \dots$$

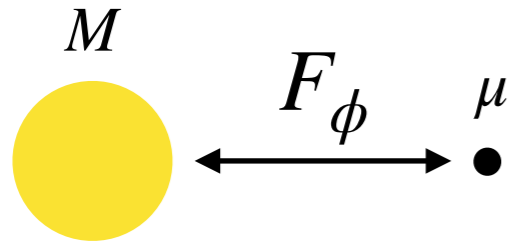


Effective One-Body (EOB) : outside



$$E_{\text{tm}} = \mu \left(-\frac{M}{r} + \frac{M^3}{5r^5} + \dots \right)$$

Effective One-Body (EOB) : outside

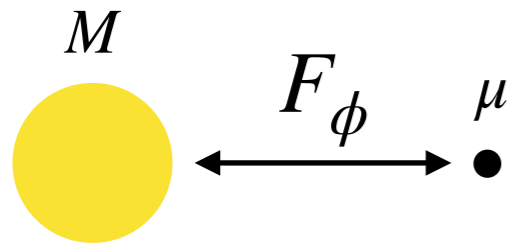


$$E_{\text{tm}} = \mu \left(-\frac{M}{r} + \frac{M^3}{5r^5} + \dots \right)$$

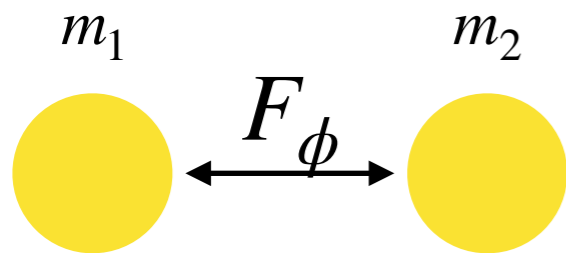
$$E_N = -\mu \frac{M}{r}$$

$$\frac{E_{\text{tm}}}{E_N} - 1 = -\frac{M^2}{5r^4} + \dots \ll 1$$

Effective One-Body (EOB) : outside

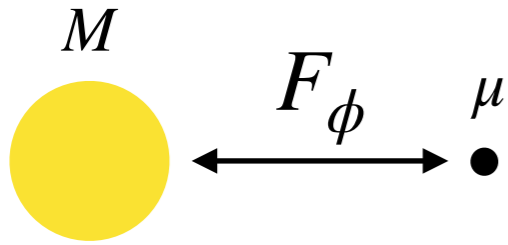


$$E_{\text{tm}} = \mu \left(-\frac{M}{r} + \frac{M^3}{5r^5} + \dots \right)$$

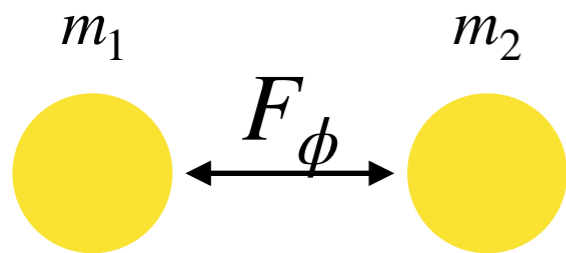


$$E = -\frac{m_1 m_2}{r} + \frac{m_1 m_2 (m_1^2 + m_2^2)}{5r^5} + \dots$$

Effective One-Body (EOB) : outside



$$E_{\text{tm}} = \mu \left(-\frac{M}{r} + \frac{M^3}{5r^5} + \dots \right)$$



$$E = -\frac{m_1 m_2}{r} + \frac{m_1 m_2 (m_1^2 + m_2^2)}{5r^5} + \dots$$

$$\mu = \frac{m_1 m_2}{m_1 + m_2}$$

$$M = m_1 + m_2$$

$$x = \frac{m_1}{m_1 + m_2}$$

$$= \mu \left(-\frac{M}{r} + \frac{M^3}{5r^5} (x^2 + (1-x)^2) + \dots \right)$$

The two-body energy is a deformation of the test-mass energy

Energy map outside

Idea : resum nonlinearities by using only E_{tm}

$$E_{tm} = \mu \left(-\frac{M}{r} + \frac{M^3}{5r^5} + \dots \right) \quad E = \mu \left(-\frac{M}{r} + \frac{M^3}{5r^5} (x^2 + (1-x)^2) + \dots \right)$$

Energy map outside

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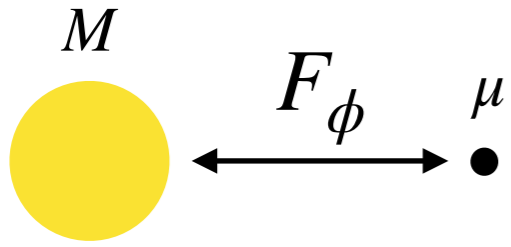
$$E_{tm} = \mu \left(-\frac{M}{r} + \frac{M^3}{5r^5} + \dots \right) \quad E = \mu \left(-\frac{M}{r} + \frac{M^3}{5r^5} (x^2 + (1-x)^2) + \dots \right)$$

$$\frac{E}{E_{tm}} = 1 + \frac{M^2}{5r^4} (1 - x^2 - (1-x)^2) + \dots$$

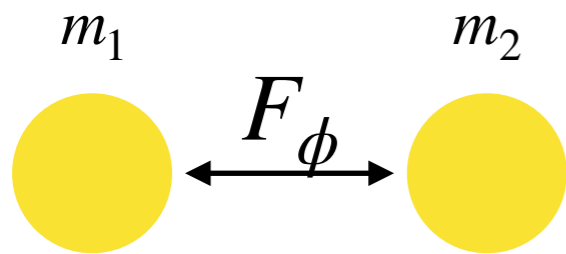
$$\frac{E}{E_{tm}} = a_0 + a_1 \left(\frac{E_{tm}}{E_N} - 1 \right) + a_2 \left(\frac{E_{tm}}{E_N} - 1 \right)^2 + \dots$$

$\frac{E_{tm}}{E_N} - 1 = -\frac{M^2}{5r^4} + \dots \ll 1$ is itself a resummed expansion in $\frac{1}{r}$

Inside the nonlinear radius

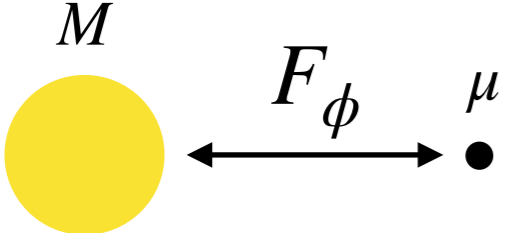


$$E_{\text{tm}} = 3\mu (Mr)^{1/3} + \dots$$

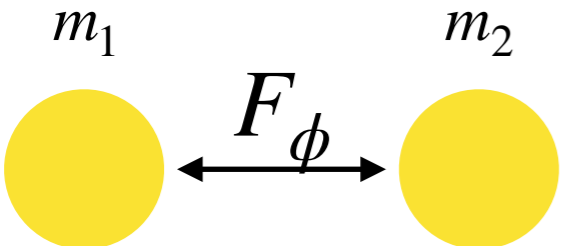


?

Inside the nonlinear radius



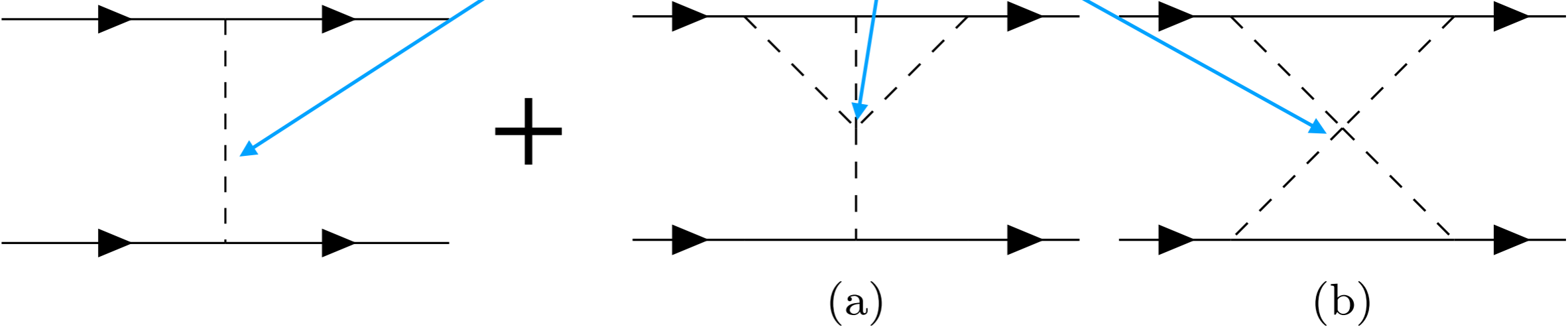
$$E_{\text{tm}} = 3\mu (Mr)^{1/3} + \dots$$



?

$$r < r_* \Leftrightarrow (\nabla\phi)^2 < (\nabla\phi)^4$$

$S_{\text{cl}} =$



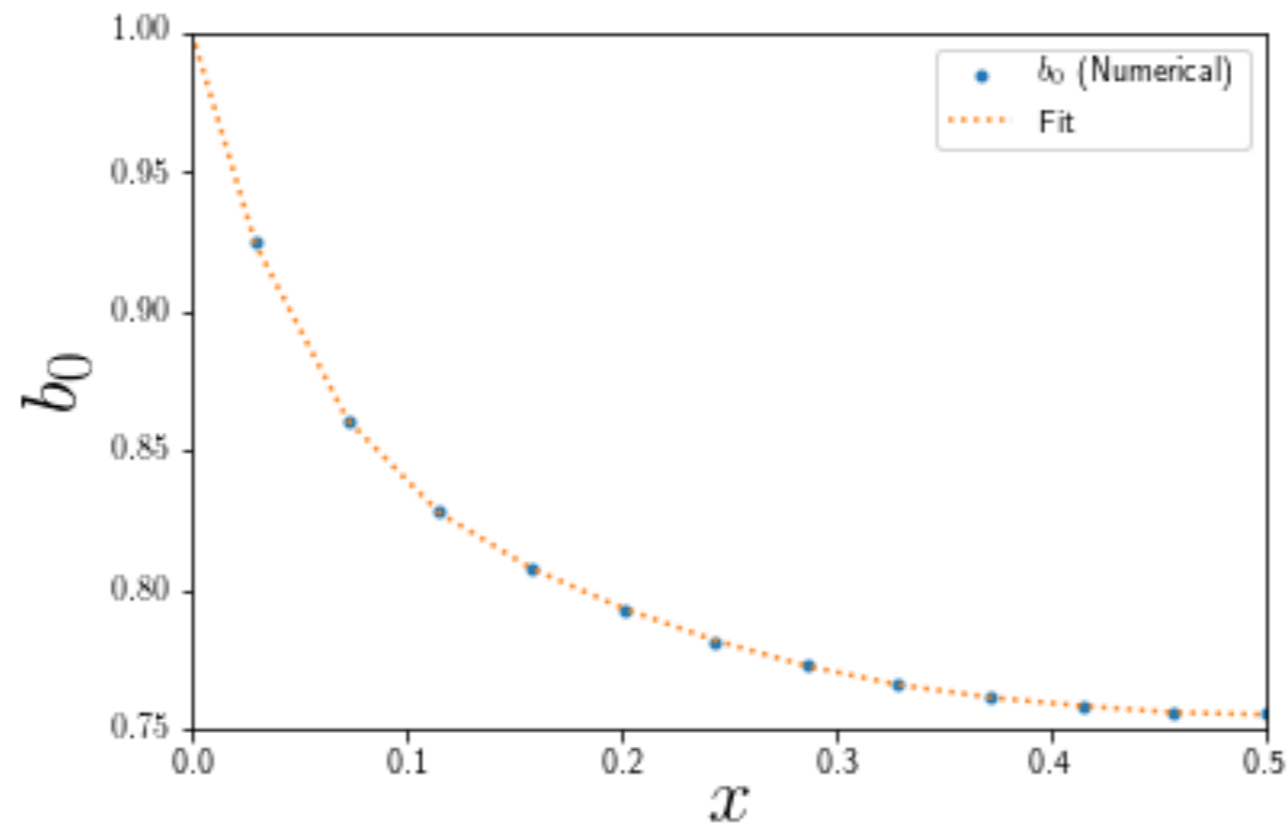
+ ... **Diverges**

Inside the nonlinear radius

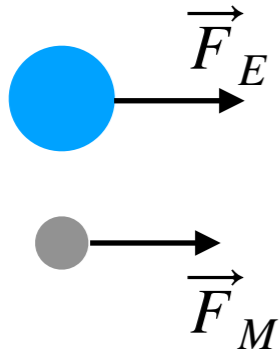
Idea: Postulate that the energy map is valid inside

$$\frac{E}{E_{\text{tm}}} = b_0 + b_1 \left(\frac{E_{\text{tm}}}{E_{\text{ref}}} - 1 \right) + b_2 \left(\frac{E_{\text{tm}}}{E_{\text{ref}}} - 1 \right)^2 + \dots$$

One cannot compute the b_i 's, but one can get them with a numerical simulation !



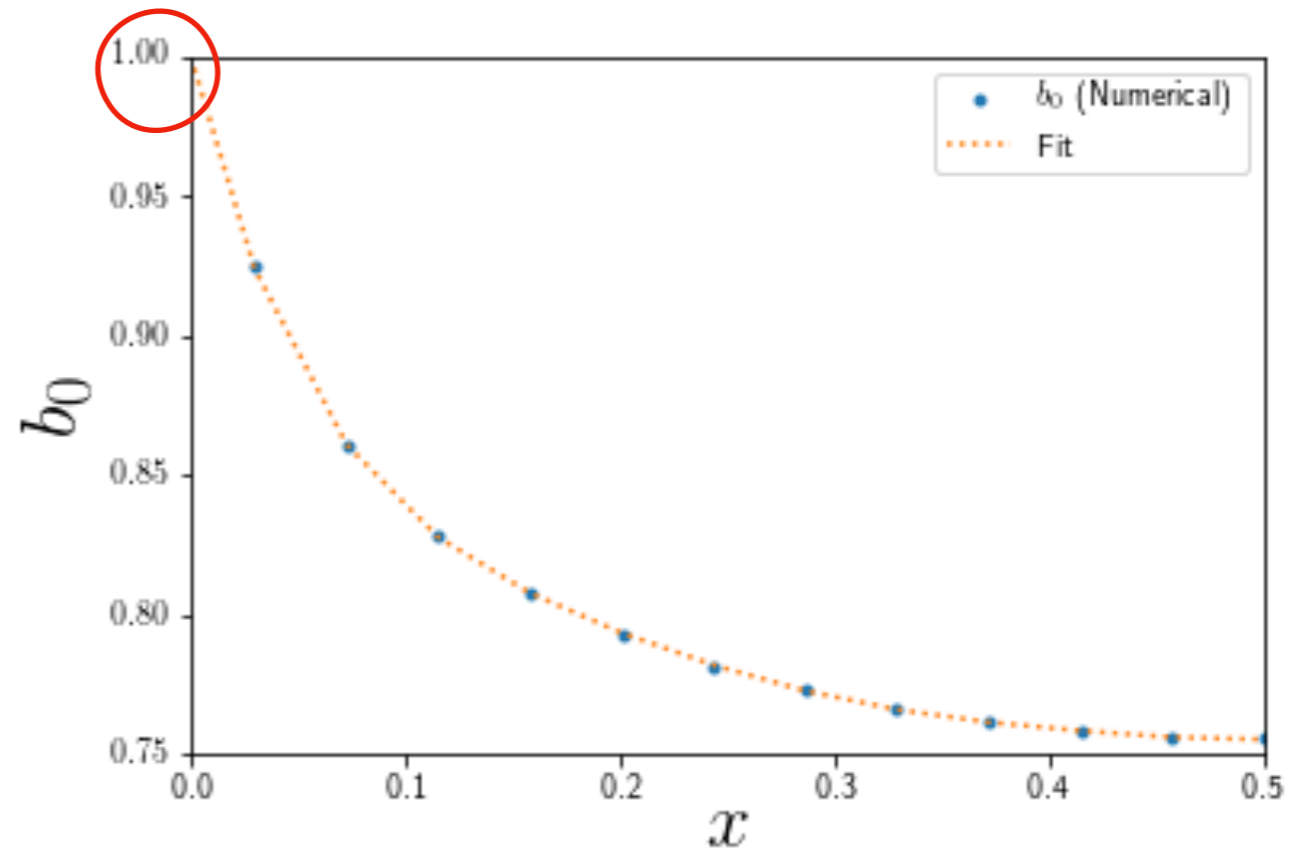
EP violation



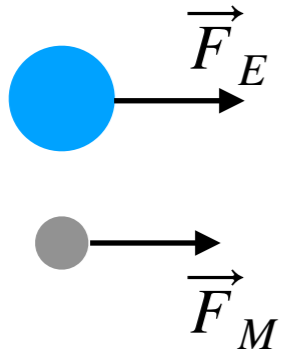
The Moon is a test-mass :

$$\vec{F}_M \simeq m_M \vec{\nabla} \phi_S(r) \quad \text{and} \quad \vec{F}_M = m_M \vec{a}_M$$

$\Rightarrow \vec{a}_M = \vec{\nabla} \phi_S(r)$ does not depend
on m_M



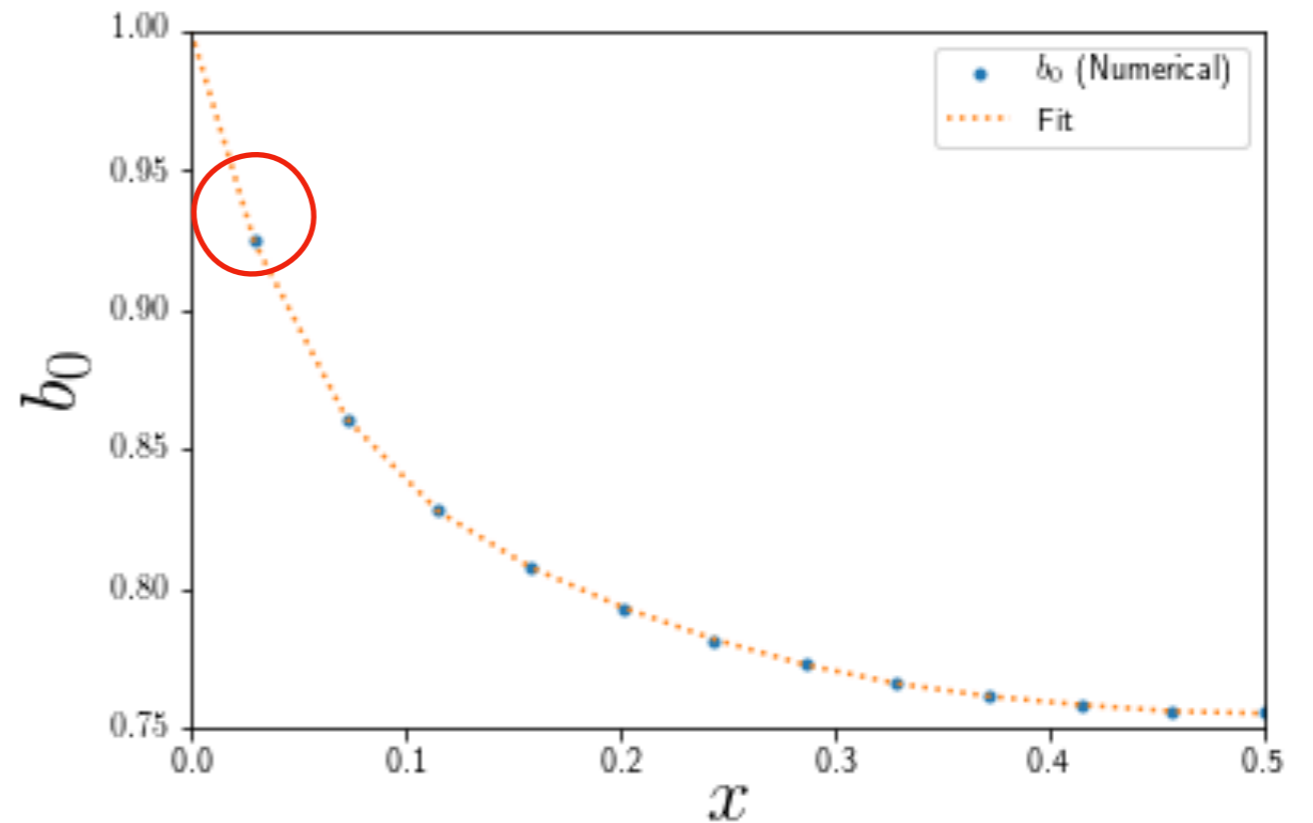
EP violation



The Earth is **not** a test-mass :

$$\vec{F}_E \simeq m_E b_0(x_{SE}) \vec{\nabla} \phi_S(r) \quad \text{and} \quad \vec{F}_E = m_E \vec{a}_E$$

$$\Rightarrow \vec{a}_E = b_0(x_{SE}) \vec{\nabla} \phi_S(r) \quad \text{depends on } x_{SE} !!$$



The Sun-Earth-Moon system

$$\delta r_{EM} \simeq 3 \times 10^{12} \left| (b_0(x_{SE}) - 1) \left(\frac{r}{r_*} \right)^n \right| \text{ cm}$$

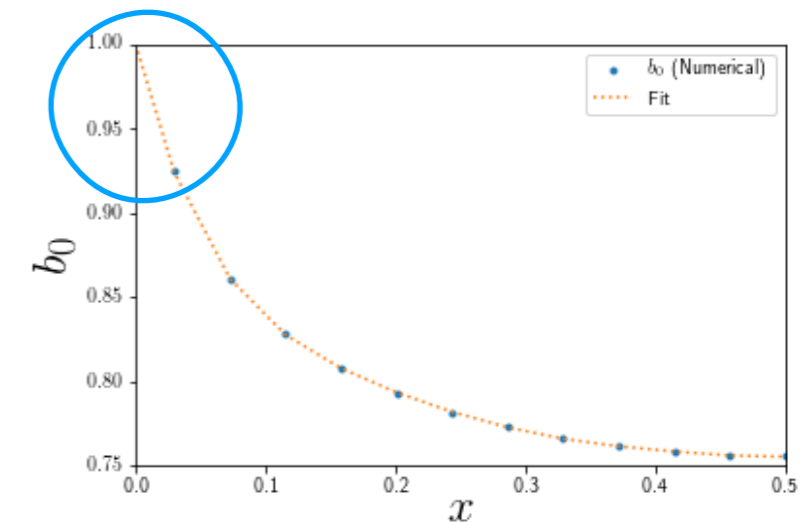
This gives a constraint :

$$b_0(x) \simeq 1 - \kappa x$$

$$\kappa x_{SE} \left(\frac{r}{r_*} \right)^n \lesssim 10^{-13}$$

Since $x_{SE} \simeq 10^{-6}$, the perihelion constraint is better :

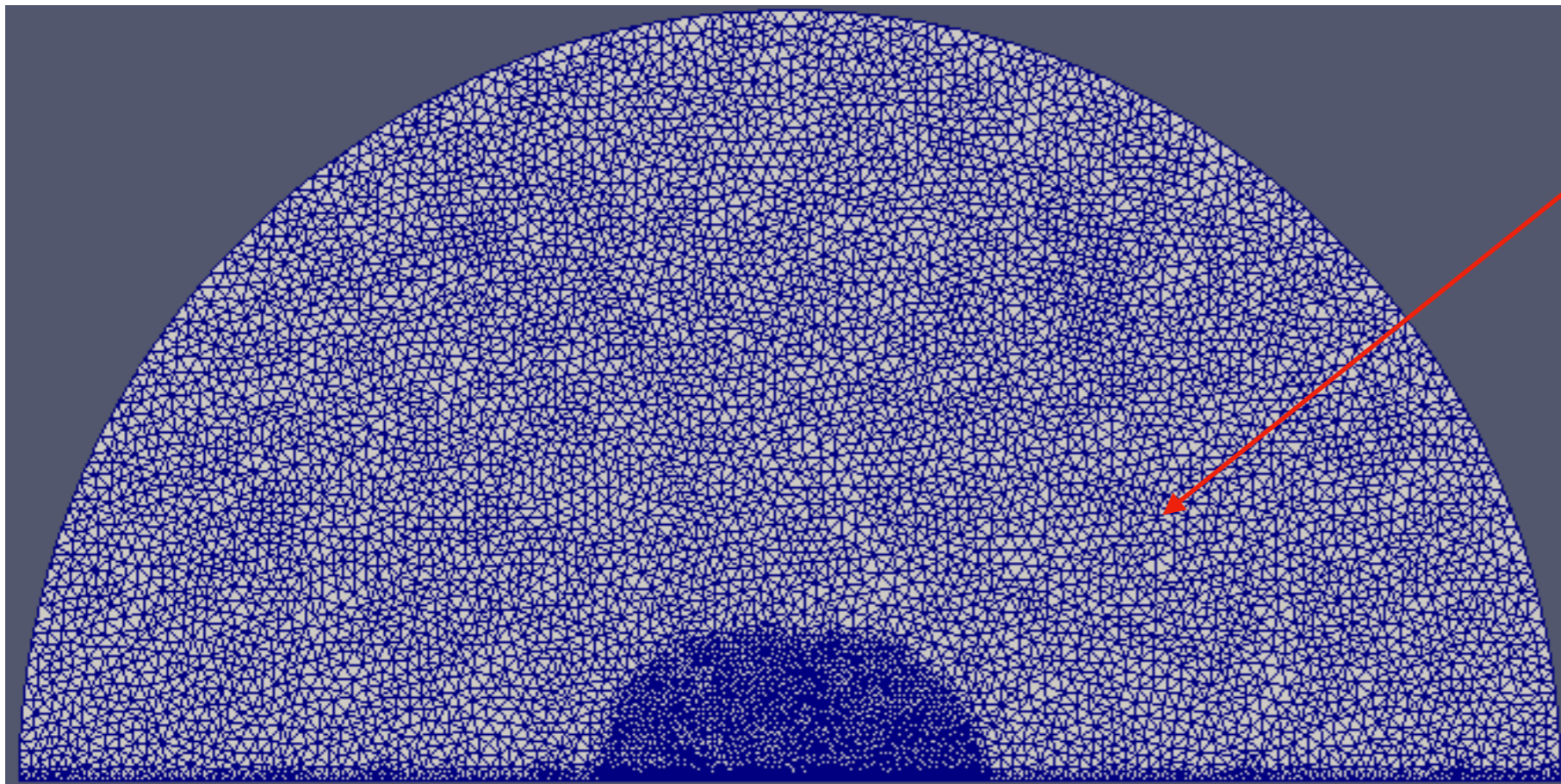
$$\left(\frac{r}{r_*} \right)^n \lesssim 10^{-11}$$



Conclusions

- The two-body potential is easily expressed in the EOB formalism
- EP violation in the Sun-Earth-Moon system is weaker than anomalous perihelion precession in the $P(X)$ model
- Future direction : conservative and dissipative dynamics of inspiralling compact objects

Finite Elements simulation



Basis function on
the grid

$$\phi = \sum_j c_j \psi_j$$

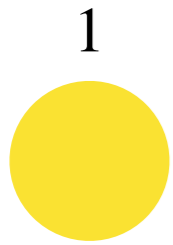
$$\nabla \cdot (\nabla \phi + (\nabla \phi)^2 \nabla \phi) = -T \quad \Leftrightarrow \quad \int d^3x \left((1 + (\nabla \phi)^2) \nabla \phi \cdot \nabla \psi_j - T \psi_j \right) = 0$$

Solve this matrix equation by LU decomposition

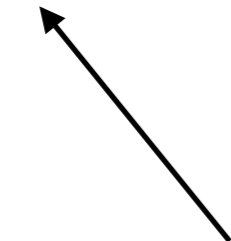
Then

$$E = \int d^3x \left(\frac{(\nabla \phi)^2}{2} + \frac{(\nabla \phi)^4}{4} \right) + 4\pi m_1 \phi(\mathbf{x}_1) + 4\pi m_2 \phi(\mathbf{x}_2)$$

Superposing nonlinear solutions



2

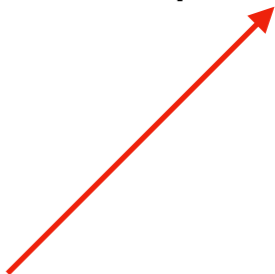
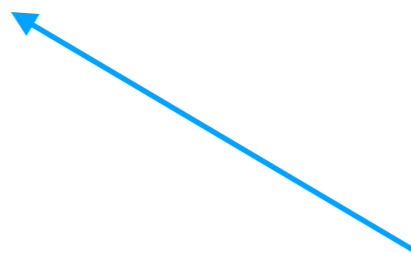


$$\phi = \phi_1(\mathbf{x} - \mathbf{x}_1) + \psi \quad \text{with} \quad \phi_1(r) = 3(m_1 r)^{1/3}$$

Sufficiently close to 2, we should expect : $\psi(\mathbf{x}) \simeq 3(m_2 |\mathbf{x} - \mathbf{x}_2|)^{1/3}$

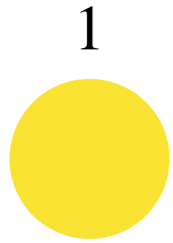
Expand the action $S = \int dt d^3x \left[-\frac{1}{2}(\nabla \phi)^2 - \frac{1}{4}(\nabla \phi)^4 + \phi T \right]$

$$\Rightarrow S = S[\phi_1] + \int dt d^3x \left[-\frac{1}{2}(\nabla \phi_1)^2 (\nabla \psi)^2 - (\nabla \phi_1 \cdot \nabla \psi)^2 - (\nabla \psi)^2 \nabla \phi_1 \cdot \nabla \psi - \frac{1}{4}(\nabla \psi)^4 + \psi T_1 \right]$$



If the last term dominates over the other, we recover the original action !

Superposing nonlinear solutions



2

• $\phi = \phi_1(\mathbf{x} - \mathbf{x}_1) + \psi$ with $\phi_1(r) = 3(m_1 r)^{1/3}$
 $\psi(\mathbf{x}) \simeq 3(m_2 |\mathbf{x} - \mathbf{x}_2|)^{1/3}$

$$S = S[\phi_1] + \int dt d^3x \left[-\frac{1}{2}(\nabla \phi_1)^2 (\nabla \psi)^2 - (\nabla \phi_1 \cdot \nabla \psi)^2 - (\nabla \psi)^2 \nabla \phi_1 \cdot \nabla \psi - \frac{1}{4}(\nabla \psi)^4 + \psi T_1 \right]$$

Ratio of the cubic and quartic terms :

$$\frac{(\nabla \psi)^2 \nabla \phi_1 \cdot \nabla \psi}{(\nabla \psi)^4} \leq \frac{|\nabla \phi_1|}{|\nabla \psi|} \simeq \left(\frac{m_1}{m_2} \left(\frac{r_2}{r_1} \right)^2 \right)^{1/3} \quad \text{(Recall that } r_* = \sqrt{M} \text{)}$$

Condition to superpose the nonlinear solutions :

$$\frac{r_2}{r_{*,2}} \ll \frac{r_1}{r_{*,1}}$$